

Title: AMATH 875/PHYS 786 - Fall 2015 - Lecture 19

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Abstract:

# GR for Cosmology, Achim Kempf, Fall 2015, Lecture 19

Note Title

## Classification of solutions of GR

(and along the way we will introduce some generally useful methods of group theory)

### Recall:

- The task is to solve the equations of motion of matter, jointly with the Einstein equation:

$$G_{\mu\nu} = 8\pi G T_{\mu\nu}$$

- In practice, this problem must be simplified, i.e., the number of to-be-determined functions must be reduced.



Question: How much can we weaken the symmetry assumptions of Friedmann-Lemaître and still get exact solutions?

Strategy:

- 1 Classify cosmological models  $(M, g), T_{\mu\nu}$  by the amount and type of symmetry assumed.
- 2 For each amount and type of symmetry assumed, try to find exact solutions or at least (asymptotic) properties of exact solutions.

Remark: Among the high symmetry models, some come arbitrarily close to F.L. at finite times!

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See, e.g., text by Wainwright & Ellis.

## Recall: Symmetries & Killing vector fields

□ Two spacetimes  $(M, g)$ ,  $(\tilde{M}, \tilde{g})$  are isometric (and therefore of exactly identical shape) if there is a diffeomorphism  $\phi: M \rightarrow \tilde{M}$  so that the image of the metric  $g$  in  $\tilde{M}$  is  $\tilde{g}$ :  $Tg = \tilde{g}$ .

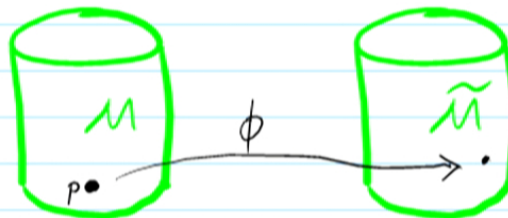
□ A spacetime has a symmetry if and only if it has a Killing vector field

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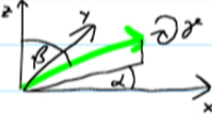
□ <sup>hand</sup> A space-time has a symmetry, if we find such a  $\phi$  for  $\tilde{M} = M$ .

□ Example:



$\phi$  performs a rotation of  $M$  about a symmetry axis, to obtain  $\tilde{M} = M$

Definition: A group  $G$  is called a Lie group if  $G$  is also a finite-dimensional smooth manifold.

Example: The sets of rotations in  $\mathbb{R}^3$  forms a 3-dimensional Lie group,  $SO(3)$ .  
The angles   $\alpha, \beta, \gamma$  are coordinates for elements  $g \in SO(3)$ .

Remarks:

- The symmetries of a manifold  $(M, g)$  can be discrete, such as reflections.
- But often, the symmetry group of a manifold  $(M, g)$  is actually a Lie group.

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□ But often, the symmetry group of a manifold  $(M, g)$  is actually a Lie group.

Note: □ Each  $h \in G$  yields an isometric diffeomorphism, by assumption.

$$h: M \rightarrow M, \text{ namely } h: p \rightarrow h(p) \quad \forall p \in M$$

□ Consider the set  $\mathcal{O}_p \subset M$  defined by:  $\mathcal{O}_p := \{q \in M \mid \exists h \in G: h(p) = q\}$

Definition: The set  $\mathcal{O}_p$  is called the *Orbit* of  $p$  under the action of the group  $G$ .

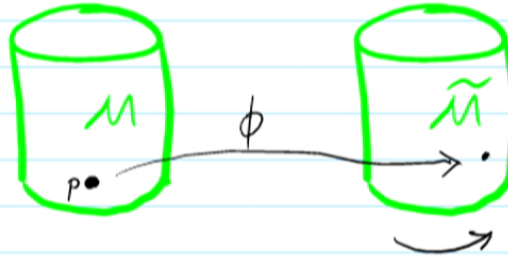
Note: If  $G$  is a Lie group then each orbit  $\mathcal{O}_p$  is  $p$  or a submanifold of  $(M, g)$ .

Question: What are the *infinitesimal* isometric diffeomorphisms?



such a  $\phi$  for  $\tilde{M} = M$ .

□ Example:



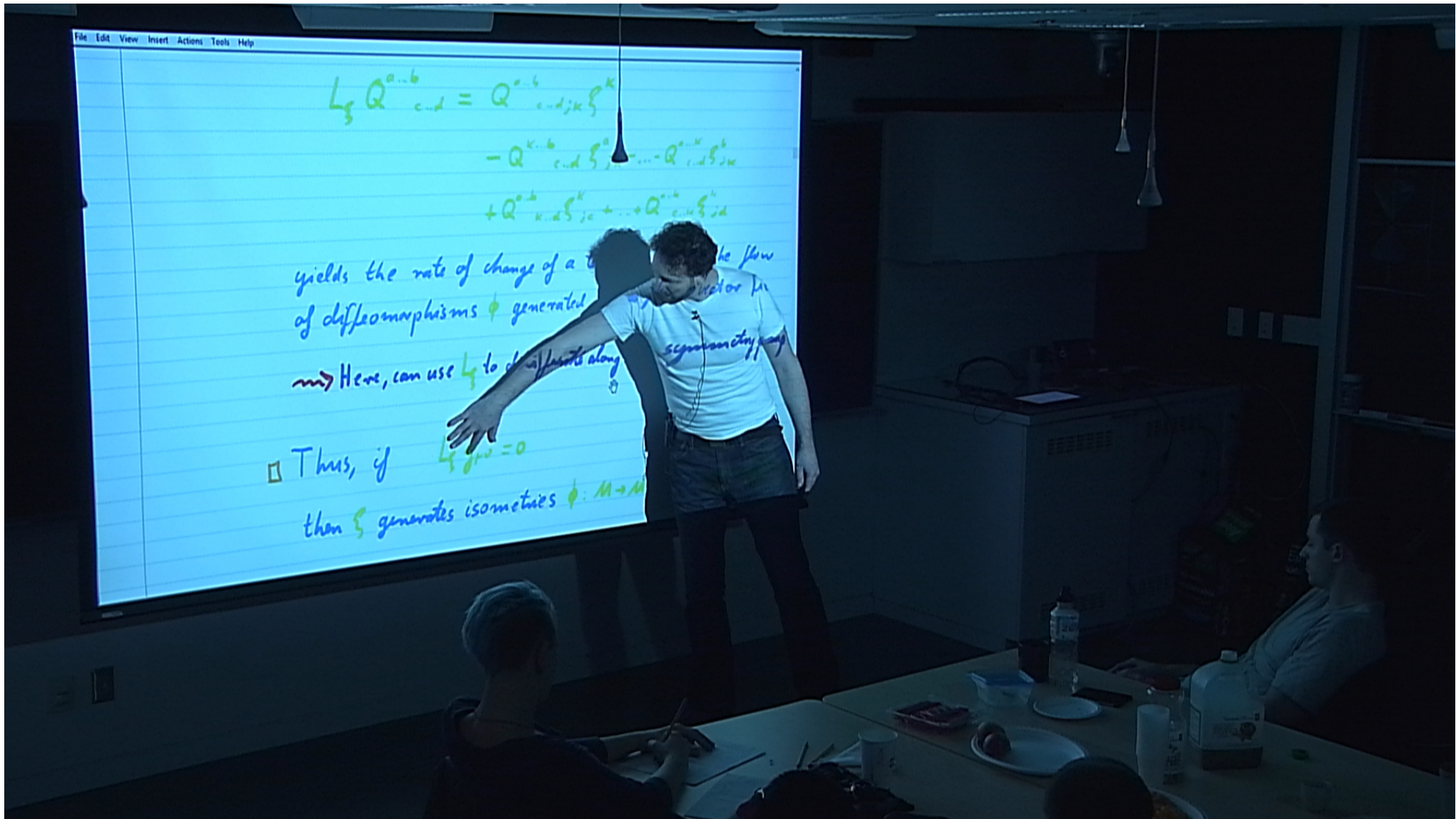
$\phi$  performs a rotation of  $M$  about a symmetry axis, to obtain  $\tilde{M} = M$  with  $T_g = \tilde{g}$ .

Note: The set of all symmetries of a manifold  $(M, g)$  forms a "group":

Definition: A "group"  $G$  is a set, with an operation, say " $\circ$ ",

$$\circ : G \times G \rightarrow G$$

and a "neutral element", say " $e$ ",  $e \in G$ , such that



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$$L_{\xi} Q^{a...b}_{c...d} = Q^{a...b}_{c...d} \xi^k$$

$$- Q^{a...b}_{c...d} \xi^k_{;c} + \dots - Q^{a...b}_{c...d} \xi^k_{;d}$$

$$+ Q^{a...b}_{c...d} \xi^k_{;c} + \dots + Q^{a...b}_{c...d} \xi^k_{;d}$$

yields the rate of change of a tensor along the flow of diffeomorphisms  $\phi$  generated by vector field  $\xi$ .

$\Rightarrow$  Here, can use  $L_{\xi}$  to differentiate along  $\xi$ .


□ Thus, if  $L_{\xi} g_{\mu\nu} = 0$  then  $\xi$  generates isometries  $\phi: M \rightarrow M$ .

$\Rightarrow$  A vector field  $\xi$  generates a symmetry of spacetime if it is a Killing vector field:

$$\xi_{\mu;\nu} + \xi_{\nu;\mu} = 0 \quad (X)$$

Q: Maximum number,  $d$ , of Killing vector fields in  $n$  dims.?

A:  $d = n(n+1)/2$  To see this, note that there are 2 ways to obey Eq. (X):

a)  $\xi_{\mu;\nu} = 0 \quad \forall \nu$ , i.e.  $\nabla \xi = 0$  

(can have maximally  $n$  such indep. vectors)

b)  $\nabla \xi \neq 0$ , but then  $K_{\mu\nu} := \xi_{\mu;\nu}$  is antisymmetric

(can have at most  $n(n-1)/2$  indep. such cases.)

$$\Rightarrow d = n + \frac{n(n-1)}{2} = \frac{n(n+1)}{2}$$




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## From a symmetry Lie group to a "symmetry Lie algebra":

### General idea:

Normally the points of a manifold cannot be multiplied!

- ▢ A Lie group is a smooth manifold with extra structure: the multiplication.
- ▢ Note: Product of group elements close to  $1 \in G$  yields a group element close to  $1$ .
- ▢ Consider the tangent space  $T_1(G)$  to the point  $1 \in G$  of the Lie group manifold  $G$ .
- ▢  $T_1(G)$  is a vector space and it has extra structure, inherited from the group's multiplication.
- ▢ Define the Lie algebra of a group  $G$  to be  $T_1(G)$ , equipped with the inherited "multiplication".

The identity element of the group,  $p = 1$  is also a point of the group's manifold.  $T_1(G)$  is the tangent space to this point.

Crucial fact: From knowledge of only the Lie algebra, i.e., only  $T_1(G)$  and

- Let us collect the properties that the inherited multiplications of all Lie algebras share.
- Then, let us define Lie algebras as anything with these properties:

Definition:

A Lie algebra is a vector space  $A$ , with an operation  $\{ \cdot \}$

$$\{ \cdot \} : A \times A \rightarrow A$$

obeying  $\{v, s\} = -\{s, v\} \quad \forall v, s \in A$

and  $\{\{v, s\}, t\} + \{\{t, v\}, s\} + \{\{s, t\}, v\} = 0$

Lie bracket  
"Jacobi identity"

Theorem: Every vector space  $A$  with a "multiplication"  $\{ \cdot \}$  is a Lie algebra.



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Theorem: Every vector space  $A$  with a "multiplication"  $\{\cdot, \cdot\}$  that obeys these axioms is isomorphic to  $\mathfrak{t}_2(6)$  of a Lie group  $G$ .



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**Exercise:** Prove this, i. e., show the following:

Assume  $\xi^{(1)}, \xi^{(2)}$  are Killing vector fields of  $(M, g)$  and  $\alpha, \beta \in \mathbb{R}$ .

Then:  $\alpha \xi^{(1)} + \beta \xi^{(2)}$  (i.e., they form a vector space)

and  $\{\xi^{(1)}, \xi^{(2)}\} := \xi^{(1)}\xi^{(2)} - \xi^{(2)}\xi^{(1)}$

are also Killing vector fields, 

and the  $\xi^{(i)}$  obey the Jacobi identity.

## Summary of the big picture:

1. The symmetries of any  $(M, g)$  form a group: they can be concatenated associatively, and all possess an inverse. Some symmetries are differentiable, parametrized by the flow  $\Rightarrow$  the symmetries form a Lie group.  
↓ Recall: there can be discrete symmetries too.
2. Each Killing vector field is the infinitesimal generator of a flow of isometric diffeomorphisms, i.e., of a symmetry.
3. We see here that the Killing vector fields indeed form a Lie algebra.



Concretely:

$$K^{(1)} := \frac{\partial}{\partial x}, \quad K^{(2)} := \frac{\partial}{\partial y}$$

$$K^{(3)} := y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y}$$

(Group elements generated by these are  $e^{tK^{(1)}}$  and  $e^{tK^{(2)}}$  and they act as  $e^{tK^{(3)}}(x,y) = (x+ty, y-tx)$  by Taylor expansion)

Orbit of  $p = (0,0)$ :

$O(p) = \mathbb{R}^2$  because generators  $\frac{\partial}{\partial x}$  and  $\frac{\partial}{\partial y}$  generate flow to every where.

Def: The surface of homogeneity has dimension  $s = 2 - r$  (generated by the Killing vectors (here  $K^{(1)}, K^{(2)}$ ) which do not have fixed orbits)

Notice: Since  $n=2$ , at any given point  $p$ , only



□ comprehensive list.

Wainwright & Ellis, *Dyn. systems in cosmology*,  
 Cambridge Univ. Press (1997)

□ Examples:

	homogeneity ↓	isotropy ↓	
□	<u>5</u>	<u>d</u>	
	4	3	Einstein's static model
	4	1	Gödel's model
	4	0	Oscvath-Kerr models
	3	3	Friedmann Lemaitre models
	3	1	spatially hom & locally one rot. sym axis
	3	0	Bianchi models
	⋮	⋮	

Powerful alternative classification approach:

□ Classification possibilities

Idea: Classify the possible  $T_{\mu\nu}$ , then use Einstein equation to obtain classification of curvature.

Proposition:

For every physical energy momentum tensor  $T_{\mu\nu}$  there exists a unique timelike vector field  $u$  so that  $T_{\mu\nu}$  takes this standard form:

$$T_{ab} = \overset{\text{scalar}}{\rho} u_a u_b + \overset{\text{vector}}{q_a} u_b + \overset{\text{vector}}{q_b} u_a + \overset{\text{scalar}}{p} (g_{ab} + u_a u_b) + \overset{\text{tensor}}{\pi_{ab}}$$

where  $q$  and  $\pi$  are a vector field and a tensor field obeying:

$$q_a u^a = 0, \quad \pi_{ab} u^b = 0, \quad \pi_a^a = 0, \quad \pi_{ab} = \pi_{ba}$$

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Definition:  $u$  is called the "fundamental 4-velocity field"

$u^a u_a = -1$

$T_{ab} u^a u^b = -\rho + p$

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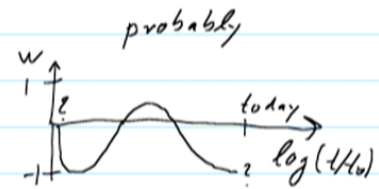
Note: E.g., for a perfect fluid this is the fluid velocity:

$$T_{ab} = \mu u_a u_b + p(g_{ab} + u_a u_b), \quad u_a u^a = -1 \quad \text{✎}$$

Recall: equation of state is

$$p = \overbrace{(ze - 1)}^w \mu$$

$$\left\{ \begin{array}{l} 1 \\ 4/3 \\ 0 \end{array} \right. \begin{array}{l} \text{dust} \\ \text{radiation} \\ \text{cosmological constant} \end{array}$$



□ Definition:

If  $(M, g)$  possesses spacelike  $s=3$  homogeneity but the fundamental velocity is not orthogonal

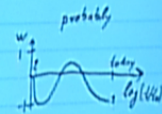


$$T_{ab} = \rho u_a u_b + p(g_{ab} + u_a u_b), \quad u_a u^a = -1$$

Recall: equation of state is

$$p = (\gamma - 1)\rho$$

$$\gamma = \begin{cases} 1 & \text{dust} \\ 4/3 & \text{radiation} \\ 0 & \text{cosmological constant} \end{cases}$$



Definition:

$\mathcal{M}, g$  possesses spacelike  $s=3$  homogeneity but the fundamental velocity is not orthogonal to the homogeneity surfaces, then we say that this cosmology is "tilted".



⇒ The Segré classification of possible  $T_{\mu\nu}$  yields, via the Einstein equation also classification of possible Ricci tensors  $R_{\mu\nu}$ .

Q: Does this yield also a classification of the possible Riemann tensors  $R^{\mu\nu\rho\sigma}$ ?

A: No! The Ricci tensor contains only 10 of the 20 degrees of freedom of the Riemann tensor! (In 5+1 dim)

Prop.: The information in  $R^{\mu\nu\rho\sigma}$  is shared among the Ricci tensor  $R_{\mu\nu}$  and the so-called Weyl tensor,  $C^{\mu\nu\rho\sigma}$ .

## The Weyl tensor, $C^{am}_{sq}$ :

$$C^{am}_{sq} := R^{am}_{sq} - \frac{1}{2} (g^a_s R^m_q + g^m_q R^a_s - g^m_s R^a_q - g^a_q R^m_s) + \frac{1}{6} (g^a_s g^m_q - g^a_q g^m_s) R$$

Notice: If  $R^a_b$  and  $C^{am}_{sq}$  are given, they determine  $R^{am}_{sq}$  fully:

$$R^{am}_{sq} = C^{am}_{sq} + \frac{1}{2} (g^a_s R^m_q + g^m_q R^a_s - g^m_s R^a_q - g^a_q R^m_s) - \frac{1}{6} (g^a_s g^m_q - g^a_q g^m_s) R$$


 $R^{am}_{sq}$  is expressed through  $C^{am}_{sq}$  and  $R^{ab}$   
 ↑ 20 indep. components                      ↑ 10 indep. comp.                      ↑ 10 indep. comp.

⇒ The Weyl tensor  $C^{am}_{sq}$  indeed contains all that information



$C^{\infty}$  describes all that curvature which can exist even where there is no matter! (e.g.: gravity waves)

also e.g. sun's gravity away from the sun in empty space

## Proposition

- Assume  $(M, g)$  is a 3+1 dimensional Lorentzian manifold.
- Choose any smooth positive scalar function  $\phi$  on  $M$ .
- Define  $(M, \tilde{g})$  with the new metric  $\tilde{g}$  obtained through the "conformal transformation":

$$g_{\mu\nu}(x) \rightarrow \tilde{g}_{\mu\nu}(x) := \phi(x) g_{\mu\nu}(x)$$

Then:  $\tilde{C}^{\nu\alpha\beta}(x) = C^{\nu\alpha\beta}(x) \quad \forall x \in M$  (Exercise: what would be a proof strategy?)

Intuition:

Weyl curvature distorts (000)

but only Ricci curvature

shrinks or expands overall: (000)



- Consider the equivalence class of spacetimes  $(M, \tilde{g})$  that are conformally equivalent to Minkowski space:

$$g_{\mu\nu}(x) = \phi^2(x) \eta_{\mu\nu}$$

- Einstein and Fokker initially considered a theory in which the metric possesses only this conformal degree of freedom  $\phi$  (to play role of Newton's gravitational potential).

Newton gravity does come out correctly as a limiting case!

- Then,  $S = \int_M R \sqrt{g} d^4x + \int_M \mathcal{L}_{matter} \sqrt{g} d^4x$  and  $\frac{\delta S}{\delta \phi} = 0$  yield:

$$R = 8\pi G T^\mu{}_\mu$$

In electromagnetism  $T^{(EM)\mu}{}_\mu = 0$  i.e. EM fields would not gravitate.

No gravity waves here because  $C^{ab}{}_{cd} = C^{ab}{}_{cd}(\text{Minkowski}) = 0$

- Equivalence principle ok.
- Light bending & Mercury perihelion shift wrong

skype  
John Klauder is online

Recall: via the Einstein equation the Segré classification implies a classification of properties of the Ricci tensor  $R_{\mu\nu}$ .

It remains to classify the Weyl tensor:

Petrov classification:

This is a classification of the Weyl tensor  $C^{\mu\nu}_{\sigma\epsilon}$  which possesses the 10 remaining degrees of freedom of  $R^{\alpha\beta\gamma\delta}$ .

□  $C^{\mu\nu}_{\sigma\epsilon}$ , just like the Riemann tensor, is antisymmetric in  $\mu \leftrightarrow \nu$  and in  $\sigma \leftrightarrow \epsilon$ , and symmetric in  $\mu\nu \leftrightarrow \sigma\epsilon$ .

Type I: Longitudinal gravitational waves

These waves cause a shear effect.

However, they decay fast:  $\sim \frac{1}{r^2}$

Why? Gravitational waves, when small enough, travel with speed of light. Like light, they then cannot oscillate longitudinally.

Types II, III: Mixtures of the above.

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(E.g. recall that flatness in FL spacetimes is unstable)

□ The so-obtained highly symmetric solutions, e.g. Friedman-Lemaître, may possess properties that are peculiar to high symmetry.

(E.g.:  
In Newtonian gravity, a slightly non-symmetric collapse of a star would not lead to a singularity but to a bounce - think figure skater.)

□ E.g.: When a Friedmann-Lemaître solution, or a Schwarzschild solution exhibits a singularity: Is it due to symmetry, or realistic?

□ Singularity theorems (see later) confirm the robustness under certain conditions (such as strong energy condition).

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→ More confidence in significance of the properties of highly symmetric solutions.