

Title: AMATH 875/PHYS 786 - Fall 2015 - Lecture 13

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Abstract:

# GR for Cosmology, Achim Kempf, Fall 15, Lecture 13

Note Title

## II Energy and momentum of matter in curved spacetime.

Recall: In flat spacetime, i.e., in Minkowski space, the invariance of the action,  $S$ , under

$$t \rightarrow t + \epsilon \quad \text{and} \quad \vec{x} \rightarrow \vec{x}_0 + \vec{\epsilon}$$

implies the conservation of energy and momentum,  $E, p$ , via Noether's theorem.

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For fields  $\psi_{(i)b\dots b_s}$ : Physical fields imply that at every point in space and time there are flows of energy and flows of momentum, that are conserved if spacetime is flat.

## In curved spacetime:

A generic curved spacetime has no translation invariance.

⇒ The flows of energy and momentum will generally not be conserved! How then to identify these flows?

### Idea:

Whatever plays the role of energy and momentum flows in curved spacetimes must be very sensitive to any changes in the spacetime geometry. Therefore, to study energy and momentum flows in curved spacetime, study:

$$T^{\mu\nu} = -\frac{2}{\sqrt{-g}} \delta S(\text{matter})$$

convention

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Def:  $g_{\mu\nu}(\lambda, x)$  is called a deformation of  $g_{\mu\nu}(x)$  for  $x \in B$  if:

a.)  $g_{\mu\nu}(\lambda=0, x) = g_{\mu\nu}(x)$

b.)  $g_{\mu\nu}(\lambda, x) = g_{\mu\nu}(x)$  if  $x \in M - B$

We then write:  $\delta g_{\mu\nu}(x) := \left. \frac{dg_{\mu\nu}(\lambda, x)}{d\lambda} \right|_{\lambda=0}$ .

or variation  
 Notice: not all these variations of  $g$  vary the Riemannian structure!

Def:  $S$  is called functionally differentiable w. resp. to  $g_{\mu\nu}$  in  $B$  if

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exists for all smooth deformations and is of the form:

$$\left. \frac{dS}{d\lambda} \right|_{\lambda=0} = \frac{1}{2} \int_B T^{\mu\nu}(x) \delta g_{\mu\nu}(x) d^4x$$

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$$= \frac{1}{2} \int_B \underbrace{\frac{1}{\sqrt{g}}}_{\text{tensor}} T^{\mu\nu}(x) \underbrace{\delta g_{\mu\nu}(x)}_{\text{tensor}} \underbrace{\sqrt{g} d^4x}_{\text{volume form}}$$

Def: If  $M^{\mu_1, \dots, \mu_n}_{\nu_1, \dots, \nu_s}$  is a tensor, then  $\mathcal{M}^{\mu_1, \dots, \mu_n}_{\nu_1, \dots, \nu_s} := M^{\mu_1, \dots, \mu_n}_{\nu_1, \dots, \nu_s} \sqrt{g}$  is called a "Tensor Density".

Thus:  $\square$   $T^{\mu\nu}$  is a tensor density and

$\square$   $T^{\mu\nu} := \frac{1}{\sqrt{g}} T^{\mu\nu} = \frac{2}{\sqrt{g}} \delta S$  is a tensor.

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$$\square T^{\mu\nu} := \frac{1}{\sqrt{g}} J^{\mu\nu} = \frac{2}{\sqrt{g}} \frac{\delta}{\delta g_{\mu\nu}} \rho$$

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Proposition:  $T^{\mu\nu}(x)$  obeys:

$$T^{\mu\nu}{}_{; \nu}(x) = 0$$

Proof: later



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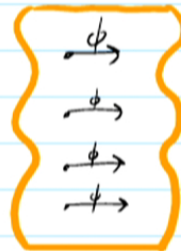
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Strategy:

We need to identify how  $T^{\mu\nu}(x)$  relates to the flows of energy and momentum associated with the matter fields:

→ Consider the cases where spacetime has a symmetry:



$\exists$  diffeomorphism  $\phi: \mathcal{M} \rightarrow \mathcal{M}$   
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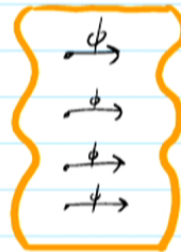
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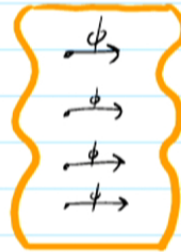


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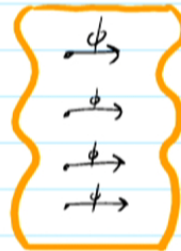
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Infinitesimal symmetry diffeomorphisms suffice (to build up finite ones)

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7. Killing vectors + diffeomorphisms suffice (to be discussed)

On a spacetime  $(M, g)$ , consider the infinitesimal flow induced by a vector field  $\xi$ .

(notice that e.g. any upwards  $\uparrow$  diffeomorphism would not be isometric)



$\uparrow$  a rotationally symmetric body

$$\phi: M \rightarrow M \quad \phi: x^\mu \rightarrow x^\mu + \xi^\mu$$

Then,  $\phi^*g = g$  means  $L_\xi g = 0$ .

Definition:

Any vector field  $\xi$  which, in a region  $B \subset M$ , obeys

$$L_\xi g = 0$$

is called a "Killing vector field in  $B$ ".

## How to find Killing vector fields?

**Proposition:** For metric connections, the Lie derivative is also:

$$\begin{aligned}
 L_{\xi} Q^{a\dots b}_{c\dots d} &= Q^{a\dots b}_{c\dots d;jk} \xi^k \\
 &\quad - Q^{k\dots b}_{c\dots d} \xi^a_{;jk} - \dots - Q^{a\dots k}_{c\dots d} \xi^b_{;jk} \\
 &\quad + Q^{a\dots b}_{k\dots d} \xi^k_{;jc} + \dots + Q^{a\dots b}_{c\dots k} \xi^k_{;jd}
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**Proof:** We know it is true with commas, instead of semicolons;  
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Apply to  $L_{\xi}g$ :

$$L_{\xi}g_{\mu\nu} = g_{\mu\nu;jk}\xi^k + g_{\kappa\nu}\xi^{\kappa}_{;i\mu} + g_{\mu\kappa}\xi^{\kappa}_{;j\nu}$$

Using  $\nabla g = 0$  i.e.:  $g_{\mu\nu;jk} = 0$  we find:

$$L_{\xi}g = 0 \text{ means } g_{\kappa\nu}\xi^{\kappa}_{;i\mu} + g_{\mu\kappa}\xi^{\kappa}_{;j\nu} = 0$$

$\Rightarrow$  To search for Killing vector fields, i.e., to find out if  $(M, g)$  has symmetries, is to search for vector fields  $\xi$  that obey:



Assume the spacetime  $(M, g)$  has a symmetry, described by some Killing vector field  $\xi$ .

Can we then identify flows that are conserved?

Prop.: For every symmetry, i.e., for every Killing vector field  $\xi$  that a spacetime  $(M, g)$  possesses, its matter fields possess a conserved quantity which flows according to the vector field  $P^\mu(x)$ :

$$P^\mu := T^{\mu\nu} \xi_\nu$$



Proof:

$$P^\mu{}_{;\nu} = (T^{\mu\nu} \xi_\nu)_{;\mu} = \overset{0}{T^{\mu\nu}{}_{;\mu} \xi_\nu} + \underbrace{T^{\mu\nu}}_{\text{symmetric}} \underbrace{\xi_{\nu;\mu}}_{\text{anti-symmetric}}$$

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 &= 0
 \end{aligned}$$

In integral form:

$$0 = \int_B P^\mu{}_{j\nu} \nabla_j^\mu d^4x = \int_B \text{div}_x P = \int_{\partial B} i_\rho \Omega$$

Note:  $T^{\mu\nu}{}_{; \nu} = 0$  is not a conservation law because  $T^{\mu\nu}{}_{; \nu}$  is not a divergence!

Thus: As much of  $P^\mu$  flows into a volume  $B$ , that much also flows out of it.

In integral form:

$$0 = \int_B P^{\mu\nu}{}_{;\nu} \sqrt{g} d^4x = \int_B \text{div}_\nu P^{\mu\nu} = \int_{\partial B} i_\mu \Omega$$

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Def: If the Killing vector field is time-like, i.e., if it generates a time-like translation, then the flow described by the conserved vector field  $K^\mu(x) = T^{\mu\nu}(x) \xi_\nu(x)$  is called the flow of energy. If spacelike, momentum.



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→ Def:  $T^{\mu\nu}(x)$  is called the energy-momentum tensor of fields. <sup>hand</sup>  
(with and without Killing fields)

## Energy and momentum of point particles?

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Then:

The quantity  $Q := \xi^\mu \dot{\gamma}_\mu$  is conserved on the trip  $\gamma$ :

It is called an energy or momentum etc, depending on  $\xi$ .

(In Minkowski space  $\xi^\mu = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$  and  $\tilde{\xi}^\mu = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$  are Killing fields and  $\dot{\gamma}_0, \dot{\gamma}_i$  are energy & momentum)

Proof: Denote the geodesic's tangent vector field by  $u$ . Then:

$$\nabla_u(\xi^\mu u_\mu) = u^\nu (\xi^\mu u_\mu)_{;\nu} = \underbrace{u^\nu \xi^\mu_{;\nu} u_\mu}_{=0 \text{ anti-sym}} + \underbrace{u^\nu \xi^\mu u_{\mu;\nu}}_{=0 \text{ because}} = 0 \quad \checkmark$$

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Proof: Denote the geodesic's tangent vector field by  $u$ . Then:

$$\underbrace{\nabla_u(\xi^\mu u_\mu)}_{\text{rate of change of } \xi^\mu u_\mu \text{ along the geodesic } \gamma} = u^k (\xi^\mu u_\mu)_{;k} = \underbrace{u^k \xi^\mu_{;jk} u_\mu}_{\substack{\text{anti-symmetric} \\ \text{symmetric}}} + \underbrace{u^k \xi^\mu u_{\mu;jk}}_{\substack{\text{because} \\ u^k u_{\mu;jk} = \nabla_u u = 0 \text{ because} \\ \text{geodesic.}}} = 0 \quad \checkmark$$

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(In Minkowski space  $\xi^\mu = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$  and  $\tilde{\xi}^\mu = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$  are Killing fields and  $\dot{\gamma}_0, \dot{\gamma}_i$  are energy & momentum)

Proof: Denote the geodesic's tangent vector field by  $u$ . Then:

$$\underbrace{\nabla_u(\xi^\mu u_\mu)}_{\text{rate of change of } \xi^\mu u_\mu \text{ along the geodesic } \gamma} = u^k (\xi^\mu u_\mu)_{;k} = \underbrace{u^k \xi^\mu}_{=0} \underbrace{_{;k} u_\mu}_{\substack{\text{anti-symmetric} \\ \text{symmetric}}} + \underbrace{u^k \xi^\mu}_{=0} \underbrace{u_{\mu;k}}_{\substack{\text{because} \\ u^k u_{\mu;k} = \nabla_u u = 0 \text{ because} \\ \text{geodesic.}}} = 0 \quad \checkmark$$

Assume the spacetime  $(M, g)$  possesses a Killing field  $\xi$ .

Assume a point-like particle travels on a geodesic  $\gamma$ .

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Why is  $T^{\mu\nu}_{;\nu} = 0$ ?

Intuition: Many variations

$$g_{\mu\nu}(x) \rightarrow \tilde{g}_{\mu\nu}(x) = g_{\mu\nu}(x) + \delta g_{\mu\nu}(x)$$

do not change the shape of the manifold because  $(M, g)$  and  $(\tilde{M}, \tilde{g})$  describe the same Riemannian structure, i.e., because there is an isometric diffeomorphism, i.e., a coordinate change that relates them.

But 
$$T^{\mu\nu}(x) = \frac{1}{2} \frac{1}{\sqrt{g}} \frac{\delta S}{\delta g_{\mu\nu}(x)}$$

depends on all  $\delta g_{\mu\nu}$ , even the trivial ones!

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depends on all  $\delta g_{\mu\nu}$ , even the trivial ones!

$\Rightarrow$  Expect  $T^{\mu\nu}$  to contain redundant information.

How much redundant information is in  $T^{\mu\nu}(x)$ ? 

□ Diffeomorphism invariance, i.e., re-labeling points,

$$\bar{X}^{\mu} = \bar{X}^{\mu}(x^0, x^1, x^2, x^3)$$

has 4 freely choosable functions. Thus, expect 4 equations

that express redundancy in  $T^{\mu\nu}(x)$ . They turn out to be  $T^{\mu\nu}_{;\nu} = 0$



## Proof of $T^{\mu\nu}_{; \nu} = 0$ :

$\leftarrow t$  is the flow parameter, i.e.:  $\phi_0 = \text{id}$   
 Assume  $\phi_t: M \rightarrow M$  is a diffeomorphism that is generated by the flow of a vector field,  $\xi$ , that vanishes outside the region  $B \subset M$ , i.e.

$$\phi_t(p) = p \text{ if } p \in M - B$$

(i.e. only the points in  $B$  get re-labeled)

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Every integral, including the action integral, is invariant under the change of variable, i.e., here under the diffeomorphism  $\phi_t$ , including when the diffeomorphism is infinitesimal. Thus:

$$\int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4x = \int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4\bar{x}$$

short for all matter fields  
↓  
Lagrangian density

$$\Rightarrow 0 = \frac{1}{t} \int_B [\mathcal{L} - \phi_t^{x^{-1}}(\mathcal{L})] d^4x$$

$$\approx \frac{1}{t} \int_B \left[ \sum_i \frac{\delta \mathcal{L}}{\delta \Psi^{(i) a \dots b} c \dots d} (\Psi_{(i) a \dots b c \dots d} - \phi_t^{x^{-1}}(\Psi)_{a \dots b c \dots d}) \right] d^4x = 0$$

for small t

(total dependence on  $\Psi$  and  $\nabla\Psi$  vanishes because of eqn of motion for the matter fields  $\Psi$ .)

including when the diffeomorphism is infinitesimal. Thus:

$$\int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4x = \int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4\bar{x}$$

short for all matter fields  
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$$\Rightarrow 0 = \frac{1}{\epsilon} \int_B [\mathcal{L} - \phi_\epsilon^{*-1}(\mathcal{L})] d^4x$$

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$$\approx \frac{1}{\epsilon} \int_B \left[ \sum_i \frac{\delta \mathcal{L}}{\delta \Psi_{(i)}^{a\dots b} \dots} (\Psi_{(i)}^{a\dots b} \dots - \phi_\epsilon^{*-1}(\Psi)_{a\dots b} \dots) \right] d^4x = 0$$

for small  $\epsilon$

$$+ \frac{\delta \mathcal{L}}{\delta g_{\mu\nu}} (g_{\mu\nu} - \phi_\epsilon^{*-1}(g)_{\mu\nu}) d^4x$$

recognize:  $\frac{1}{2} T^{ab} \sqrt{g} =$   $\rightarrow$  becomes  $\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} (g - \phi_\epsilon^{*-1}(g)) = L_g(g)$

$$\int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4x = \int_B \mathcal{L}(\Psi, \partial\Psi, g) d^4\bar{x}$$

$\mathcal{L}$  ← Lagrangian density

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$$\approx \frac{1}{\epsilon} \int_B \left[ \sum_i \frac{\delta \mathcal{L}}{\delta \Psi^{(i) a \dots b} c \dots d} (\Psi_{(i) c \dots d}^{a \dots b} - \phi_{\epsilon}^{\Psi^{-1}}(\Psi)_{c \dots d}^{a \dots b}) \right] d^4x = 0$$

for small  $\epsilon$

recognize:  $\frac{1}{2} T^{ab} \sqrt{g} = \rightarrow \frac{\delta \mathcal{L}}{\delta g_{\mu\nu}}$

$$+ \frac{\delta \mathcal{L}}{\delta g_{\mu\nu}} (g_{\mu\nu} - \phi_{\epsilon}^g(g)_{\mu\nu}) d^4x$$

becomes  $\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} (g - \phi_{\epsilon}^g(g)) = L_g(g)$

Take  $\lim_{\epsilon \rightarrow 0} \Rightarrow$  obtain Lie derivative:

$$0 = \left( \frac{1}{2} T^{ab} \sqrt{g} \right) L_{\xi} g_{ab} d^4x$$

Take  $\lim_{\epsilon \rightarrow 0} \Rightarrow$  obtain Lie derivative:

$$0 = \int_B \frac{1}{2} T^{ab} \sqrt{g} L_{\xi}(g_{ab}) d^4x$$

Notice:  $L_{\xi}(g_{ab}) = \overbrace{g_{ab;k}}^{=0} \xi^k + g_{kb} \xi^k{}_{;a} + g_{ak} \xi^k{}_{;b}$

$$\begin{aligned} \text{Thus: } 0 &= \int_B T^{ab} (g_{kb} \xi^k{}_{;a} + g_{ak} \xi^k{}_{;b}) \sqrt{g} d^4x \\ &= \int_B T^{ab} \underbrace{(\xi_{b;a} + \xi_{a;b})}_{\text{symmetric}} \sqrt{g} d^4x \\ &= 2 \int_B T^{ab} \xi_{b;a} + \underbrace{(\xi_{a;b} - \xi_{b;a})}_{\text{anti-symmetric}} \sqrt{g} d^4x \end{aligned}$$

$$\Rightarrow 0 = \frac{1}{t} \int_B [\mathcal{L} - \phi_t^{*-1}(\mathcal{L})] d^4x$$

(total dependence on  $\psi$  and  $\nabla\psi$  vanishes because of eqn of motion for the matter fields  $\psi$ ;

$$\stackrel{\text{for small } t}{\approx} \frac{1}{t} \int_B \left[ \sum_i \frac{\delta \mathcal{L}}{\delta \psi_{(i)}^{a\dots b} \dots} (\psi_{(i)}^{a\dots b} \dots - \phi_t^{*-1}(\psi)_{a\dots b}) \right] d^4x = 0$$

$$\text{recognize: } \frac{1}{2} T^{ab} \sqrt{g} = \rightarrow + \frac{\delta \mathcal{L}}{\delta g_{\mu\nu}} (g_{\mu\nu} - \phi_t^{*-1}(g)_{\mu\nu}) d^4x$$

becomes  $\lim_{t \rightarrow 0} \frac{1}{t} (g - \phi_t^{*-1}(g)) = L_{\xi}(g)$

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□ Thus:  $0 = \int_B T^{ab} (g_{kb} \xi^k{}_{;a} + g_{ak} \xi^k{}_{;b}) \sqrt{g} d^4x$

$$= \int_B \overbrace{T^{ab}}^{\text{symmetric}} (\xi_{b;a} + \xi_{a;b}) \sqrt{g} d^4x$$

$$= 2 \xi_{b;a} + \underbrace{(\xi_{a;b} - \xi_{b;a})}_{\text{anti-symmetric}}$$

$$= \int_B 2 T^{ab} \xi_{b;a} \sqrt{g} d^4x$$

$$= 2 \int_B \left( T^{ab} \xi_{b;a} + T^{ak} \xi_{jk} \xi_a - T^{ak} \xi_{jk} \xi_a \right) \sqrt{g} d^4x$$

$$= 2 \int_B \left[ \underbrace{(T^{ab} \xi_b)_{;a}}_{=0} \sqrt{g} - T^{ak} \xi_{jk} \xi_a \sqrt{g} \right] d^4x$$

Why? define  $r^a := T^{ab} \xi_b$ , then:

$$\int_B \overbrace{r^a_{;a}}^{= \text{div}_r \Omega} \sqrt{g} d^4x = \int_{\partial B} i_r \Omega = 0$$

because  $\xi = 0$   
on  $\partial B$  by assumption,  
i.e. also  $r^a = T^{ab} \xi_b = 0$   
there.

□ T/...



15

Why? define  $r^a := T^{ab} \xi_b$ , then:

$$\int_B \overbrace{r^a{}_{;a} V^a} = \text{div}_r \Omega d^4x = \int_{\partial B} i_r \Omega = 0$$

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□ Thus:

$$\int_B T^{ak}{}_{;k} \xi_a V^a d^4x = 0 \text{ for all } \xi$$

$\Rightarrow$

$$T^{ak}{}_{;k} = 0$$

Consequence of  $\checkmark$   
diffeomorphism invariance.

But: How to calculate  $T^{\mu\nu}(x) = \frac{2}{\sqrt{-g}} \frac{\delta S^{(\text{matter})}}{\delta g_{\mu\nu}}$ ?

But: How to calculate  $T^{\mu\nu}(x) = \frac{2}{\sqrt{|g(x)|}} \frac{\delta S^{(\text{matter})}}{\delta g_{\mu\nu}(x)}$  ?

Recall:  $S = \int L(\Psi, \nabla\Psi) \sqrt{g} d^4x$

$$\frac{\partial S}{\partial \lambda} \Big|_{\lambda=0} = \int_B \left( \frac{\partial L}{\partial g_{ab}} \delta g_{ab} + \sum_i \frac{\partial L}{\partial \Psi_{(i)}^{a\dots b\dots c\dots d}} \underbrace{\delta \Psi_{(i)}^{a\dots b\dots c\dots d}}_{=0 \text{ because } \delta\Psi=0} + \int_B L \frac{\partial \sqrt{g}}{\partial g_{ab}} \delta g_{ab} \right. \\ \left. + \sum_i \frac{\partial L}{\partial \Psi_{(i)}^{a\dots b\dots c\dots d;e}} \delta(\Psi_{(i)}^{a\dots b\dots c\dots d;e}) \right) \sqrt{g} d^4x$$

$\frac{\partial \sqrt{g}}{\partial g_{ab}} = \frac{1}{2} g^{ab} \sqrt{g}$   
 Exercise: prove this.

(\*) Notice:  $\delta(\Psi_{(i)}^{a\dots b\dots c\dots d;e}) \neq 0$  even though  $\delta\Psi = 0$ , because ; contains  $\Gamma$  and if  $\delta g \neq 0$  then  $\delta\Gamma \neq 0$ :

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$= \frac{1}{2} g^{ab} \sqrt{g}$   
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(\*) Notice:  $\delta(\Psi_{(i)}^{a\dots b\dots c\dots d;e}) \neq 0$  even though  $\delta\Psi = 0$ , because ; contains  $\Gamma$  and if  $\delta g \neq 0$  then  $\delta\Gamma \neq 0$ :

$$\delta(\Psi_{(i)}^{a\dots b\dots c\dots d;e}) = \sum_{k,m,n} \frac{\partial \Psi_{(i)}^{a\dots b\dots c\dots d;e}}{\partial \Gamma_{mn}^k} \delta \Gamma_{mn}^k$$

(\*) Notice:  $\delta(\Psi_{(i)}^{a\dots b}{}_{c\dots d;j|e}) \neq 0$  even though  $\delta\psi = 0$ , because  $\Psi$  contains  $\Gamma$  and if  $\delta g \neq 0$  then  $\delta\Gamma \neq 0$ :

$$\delta(\Psi_{(i)}^{a\dots b}{}_{c\dots d;j|e}) = \sum_{k,m,n} \frac{\partial \Psi_{(i)}^{a\dots b}{}_{c\dots d;j|e}}{\partial \Gamma^k{}_{mn}} \delta \Gamma^k{}_{mn}$$

Recall:  $\delta\Gamma^k{}_{mn}$  is a tensor. It is:

$$\delta\Gamma^a{}_{bc} = \frac{1}{2} g^{ad} (\delta g_{db;c} + \delta g_{dc;ib} - \delta g_{bc;d})$$

(easiest to prove in geodesic or normal cds)

$$\Rightarrow \delta(\Psi_{(i)}^{a\dots b}{}_{c\dots d;j|e}) = \sum \frac{\partial \Psi}{\partial \Gamma} \frac{1}{2} g^{ad} (\delta g_{db;c} + \delta g_{dc;ib} - \delta g_{bc;d})$$

Recall:  $\delta \Gamma_{mn}^k$  is a tensor. It is:

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(easiest to prove in geodesic i.e. normal cds)

$$\Rightarrow \delta(\Psi_{(i_1}^{a \dots b} \dots d; e)) = \sum_{kmn} \frac{\partial \Psi}{\partial \Gamma} \frac{1}{2} g^{ad} (\delta g_{db;c} + \delta g_{dc;b} - \delta g_{bc;d})$$

Integrate again "by parts"

Exercise: work this out

$$\Rightarrow \delta(\Psi_{(i_1}^{a \dots b} \dots d; e)) \sim \# \delta g_{\mu\nu}$$

$$\Rightarrow \left. \frac{dS}{d\lambda} \right|_{\lambda=0} = \int T^{\mu\nu}(x) \delta g_{\mu\nu}(x) \sqrt{g} d^4x$$

$$\Rightarrow \delta(\psi_{(i} \dots \delta_{j)e}) = \sum_{k=1}^n \frac{\partial}{\partial \lambda} \frac{1}{2} g^{ab} (\delta g_{1b;c} + \delta g_{d-;b} - \delta g_{bc;d})$$

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$\Rightarrow$  One can read off  $T^{\mu\nu}(x)$  for any  $L$ .

Example:

$\psi$  is scalar, i.e.  $\psi_{;j\mu} = \psi_{;\mu j}$  e.g.  $V(\psi) = \frac{m^2}{2\lambda^2} \psi^2 + \frac{\lambda}{4!} \psi^4$

$$S' := -\frac{1}{2} \int (\psi_{;a} \psi_{;b} g^{ab} + 2V(\psi)) \sqrt{g} d^4x$$

$$\Rightarrow \delta(\psi_{(i_1}^{a \dots b} \dots d; e)) = \sum_{k=mn} \frac{\partial \psi}{\partial \Gamma^k} \frac{1}{2} g^{ad} (\delta g_{db; c} + \delta g_{dc; b} - \delta g_{bc; d})$$

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Then:

(Klein Gordon field, e.g. inflaton field)

$$\frac{\partial S}{\partial \lambda} \Big|_{\lambda=0} = -\frac{1}{2} \int (\psi_{,a} \psi_{,b} (\delta g^{ab}) \sqrt{g} + \psi_{,a} \psi_{,b} g^{ab} \frac{\partial \sqrt{g}}{\partial g^{ij}} \delta g^{ij} + 2V(\psi) \frac{\partial \sqrt{g}}{\partial g^{ij}} \delta g^{ij}) d^4x$$

$$\left( \delta g_{\mu\nu} = \frac{dg(\lambda)_{\mu\nu}}{d\lambda} \Big|_{\lambda=0} \right)$$

Recall:  $\frac{\partial \sqrt{g}}{\partial g^{ij}} = \frac{1}{2} g^{ij} \sqrt{g}$

i.e.  $\delta g^{ab} = -g^{ai} g^{bj} \delta g_{ij}$

We also notice:  $\delta(g_{ab} g^{bc}) = 0 = g_{ab} \delta g^{bc} + (\delta g_{ab}) g^{bc}$

Thus:



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$$\frac{\partial S'}{\partial \lambda} \Big|_{\lambda=0} = -\frac{1}{2} \int \left( \psi_{,a} \psi_{,b} (\delta g^{ab}) \sqrt{g} + \psi_{,a} \psi_{,b} g^{ab} \frac{\partial \sqrt{g}}{\partial g^{ij}} \delta g^{ij} + 2V(\psi) \frac{\partial \sqrt{g}}{\partial g^{ij}} \delta g^{ij} \right) d^4x$$

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Then:

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$$\frac{\partial S'}{\partial \lambda}|_{\lambda=0} = -\frac{1}{2} \int \left( \psi_{,a} \psi_{,b} (\delta g^{ab}) \sqrt{g} + \psi_{,a} \psi_{,b} g^{ab} \frac{\partial \sqrt{g}}{\partial g_{ij}} \delta g_{ij} + 2V(\psi) \frac{\partial \sqrt{g}}{\partial g_{ij}} \delta g_{ij} \right) d^4x$$

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$$\Rightarrow \frac{\delta S'}{\delta g_{\mu\nu}} = \frac{1}{2} T^{\mu\nu} \quad \text{with:}$$

$$T^{\mu\nu} = \left( \underbrace{\Psi_{,i\mu} \Psi_{,i\nu}}_{= \Psi_{,i a} g^{a\mu} \Psi_{,i a} g^{a\nu}} - \frac{1}{2} \Psi_{,i a} \Psi_{,i a} g^{\mu\nu} - V(\psi) g^{\mu\nu} \right) \sqrt{g}$$

$$\frac{\partial S'}{\partial \lambda} \Big|_{\lambda=0} = -\frac{1}{2} \int \left( \psi_{,a} \psi_{,b} \sqrt{g} (-g^{ai} g^{bj} \delta g_{ij}) + \psi_{,a} \psi_{,b} g^{ab} \frac{1}{2} g^{ij} \sqrt{g} \delta g_{ij} + 2 V(\psi) \frac{1}{2} g^{ij} \sqrt{g} \delta g_{ij} \right) d^4x$$

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i.e. the energy-momentum tensor reads:

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Exercise: Show that for the electromagnetic <sup>hand</sup> field:

$$T_{\mu\nu}^{\text{E.M.}} = \frac{1}{4\pi} (F_{\mu i} F_{\nu j} g^{ij} - \frac{1}{4} g_{\mu\nu} F_{ij} F^{ij})$$

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(traditional sense: thermodynamically reversible dynamics)

$$V^{\mu} V_{\mu} = -1$$

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□ A perfect (classical) fluid has at every point a unique time-like flux direction vector  $v^\mu$ , the flux is conserved, and the fluid is completely characterized by its local energy density  $\rho$  and pressure  $p$  (i.e., e.g. no shear, no viscosity).

as measured by a co-moving observer:  
Then,  $v_\mu = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ , so  $T_{\mu\nu} = \begin{pmatrix} \rho & 0 \\ 0 & p \delta_{ij} \end{pmatrix}$ .



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□ Terminology: (Hawking & Ellis) Any fluid with this  $T_{\mu\nu}$  is called perfect.

Definition:

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The "equation of state" of a perfect fluid is the relation between its energy density,  $\rho$  and its pressure,  $p$ . It depends on the fluid and so one can characterize the fluids by this parameter:

$$w := \frac{p}{\rho}$$

Important later for cosmology:

The two tensors

← applies to the inflaton field.

$$T_{\mu\nu}^{\text{K.G.}} = \psi_{,i\mu} \psi_{,i\nu} - \frac{1}{2} g_{\mu\nu} (\psi_{,i\alpha} \psi^{,i\alpha} + 2V(\psi))$$

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$$T_{\mu\nu}^{KG} = \Psi_{;\mu} \Psi_{;\nu} - \frac{1}{2} g_{\mu\nu} (\Psi_{;\alpha} \Psi^{;\alpha})$$

and  $T_{\mu\nu}^{IF} = (\rho + p) v_{\mu} v_{\nu} + g_{\mu\nu} p$

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$$T_{\mu\nu}^{\text{K.G.}} = \Psi_{,i\mu} \Psi_{,i\nu} - \frac{1}{2} g_{\mu\nu} (\Psi_{,ia} \Psi^{,ia} + 2V(\Psi))$$

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$$T_{\mu\nu}^{\text{P.F.}} = (\rho + p) v_{\mu} v_{\nu} + g_{\mu\nu} p$$

are of similar form (unlike e.g.  $T_{\mu\nu}^{\text{EM}}$ )

if  $\Psi$  is almost homogeneous, i.e.  $\Psi_{,i} \approx 0$ :  
 $i=1, 2, 3$

Then, define:  $v_{\mu} := \frac{\Psi_{,i\mu}}{\sqrt{|g^{ab} \Psi_{,a} \Psi_{,b}|}}$  (so that  $v_{\mu} v^{\mu} = -1$ )

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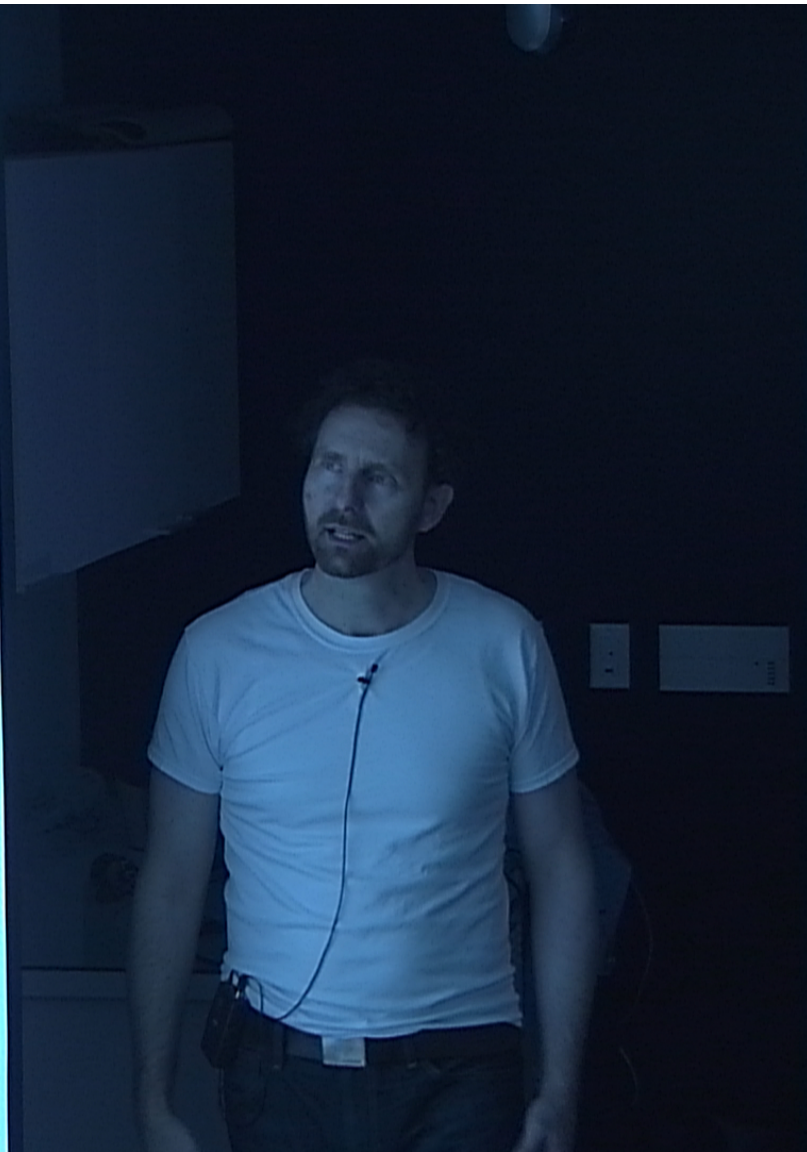
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$\dots$   
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 (so that  $V_{\mu\nu} \dots$ )



de Rham Geometric  
 from SUSY

↑ TIME  
 ↓ SPACE

- 1 Introduction
- 2 Twists of  $N=4$
- 3 Compactification

HOP EOM  $\lambda_{\pm}(p_{\pm}) = \dots$

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□ Compare with  $T^{\text{PF}}$ :

$$\frac{K+P}{P} = \frac{1}{w} + 1 = \frac{\dot{\psi}^2}{\frac{1}{2} \dot{\psi}^2 - V(\psi)}$$

$$\Rightarrow \frac{1}{w} = \frac{\dot{\psi}^2}{\frac{1}{2} \dot{\psi}^2 - V(\psi)} - \frac{\dot{\psi}^2/2 - V(\psi)}{\frac{1}{2} \dot{\psi}^2 - V(\psi)} = \frac{\dot{\psi}^2/2 + V(\psi)}{\dot{\psi}^2/2 - V(\psi)}$$

□ Thus:  $w = \frac{\dot{\psi}^2/2 - V(\psi)}{\dot{\psi}^2/2 + V(\psi)}$

$\in (-1, 1)$   
 potential dominated, i.e.  $V(\psi) \gg \dot{\psi}^2$  (see inflation later)  
 no potential:  $V(\psi) = 0$

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