

Title: Mathematica, tensor networks, MERA and entanglement

Date: Aug 28, 2015 09:15 AM

URL: <http://pirsa.org/15080052>

Abstract: TBA

# OUTLINE

## MERA, entanglement and AdS/MERA

- Tensor networks and contractions
- Entanglement on a slice of AdS?
- Goal: do MERA computations, and make AdS/MERA quantitative
  - → get simple MERA example + routines and do exercises

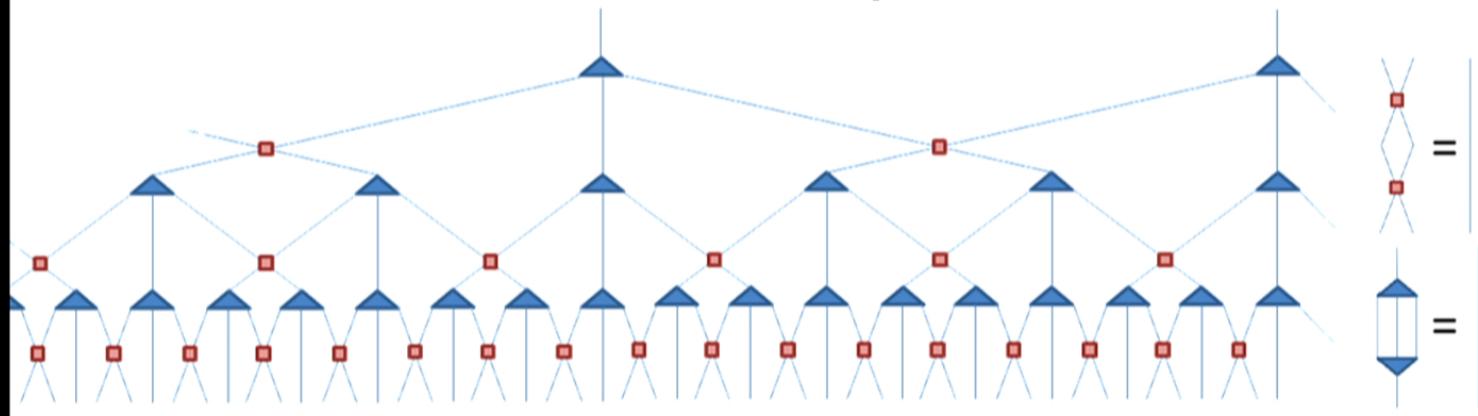
## Frequently used *Mathematica*

- Making and using packages
- NDSolve and/or spectral methods
- Transforming functions/coordinate transformations

## MULTISCALE ENTANGLEMENT RENORMALISATION ANSATZ (MERA)

MPS correlations/entanglement requires larger  $\chi$

Choose different *ansatz* to incorporate RG flow:



Disentanglers and coarse grainers (ternary)

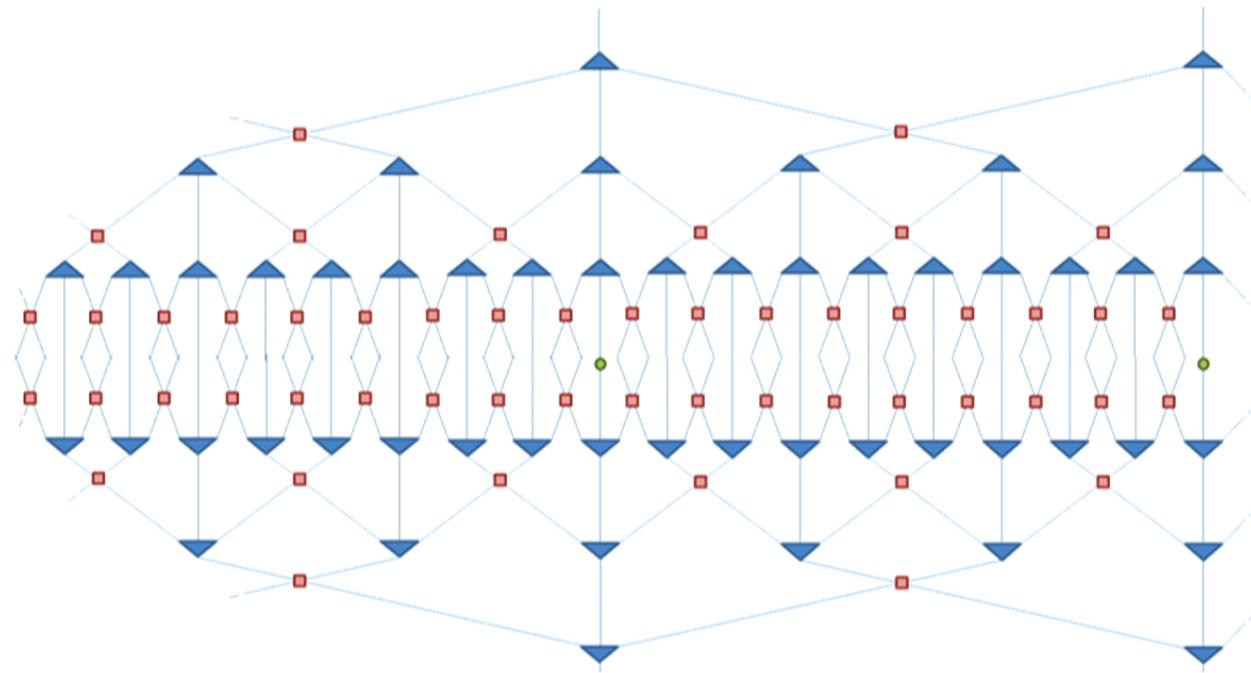
Extra advantage: scale invariance is very natural!

G. Vidal, Entanglement Renormalization (2007)

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## EXAMPLE: CORRELATORS IN MERA

Choose operators at smart locations



Simplify ☺

R.N.C. Pfeifer, G. Evenbly and G. Vidal, Entanglement renormalization, scale invariance, and quantum criticality (2009)

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## ENTANGLEMENT ENTROPY

**Reduced density matrix:**  $\rho_{red,L} = \text{tr}(\rho)$

**Obtain mixed state with probabilities:**  $p_\rho = \text{eig}(\rho_{red,L})$

- **Has entropy:**  $S_{EE} = -\sum_i p_{\rho,i} \log(p_{\rho,i}) = \frac{c}{3} \log(L) + \mathcal{O}(1)$
- **I.e. ground state → excited state!**

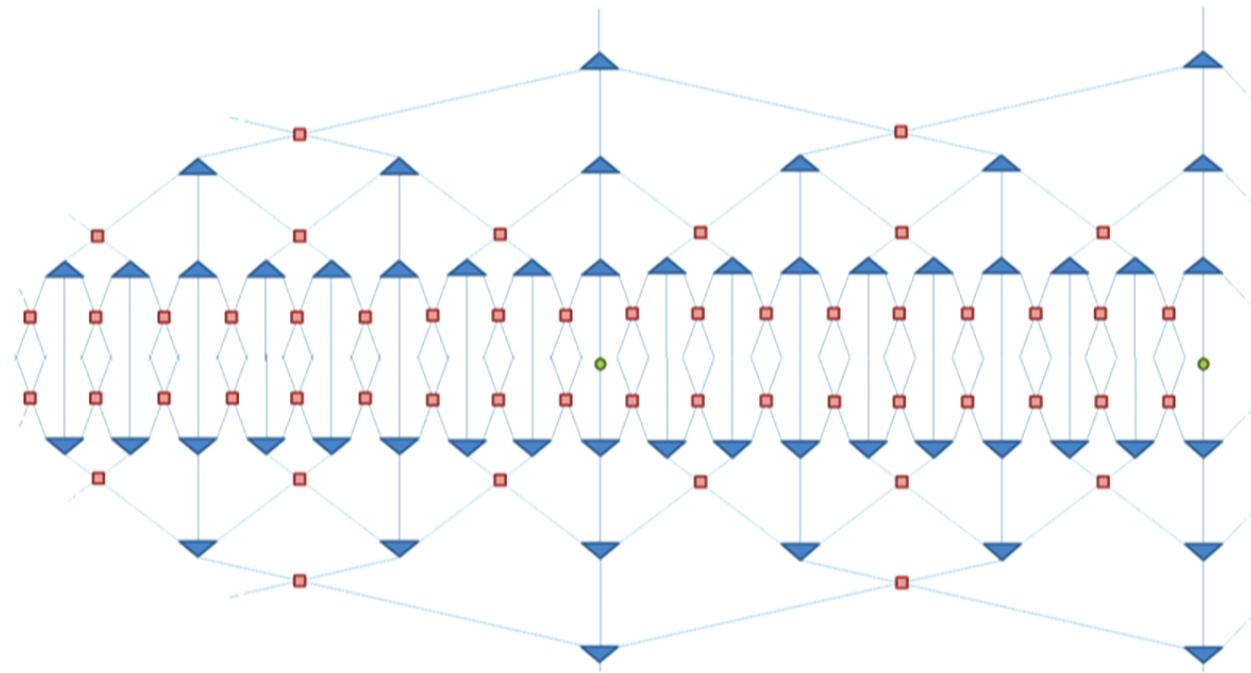
**Ising model:**  $H_{\text{Ising}} = -\sum_r \left( \lambda \sigma_z^{[r]} + \sigma_x^{[r]} \sigma_x^{[r+1]} \right)$

- **Energy:**  $e_0 = -\frac{2}{L \sin(\pi/2L)} \approx -\frac{4}{\pi} - \frac{\pi}{6L^2}$
- **Central charge 1/2**

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## EXAMPLE: CORRELATORS IN MERA

Choose operators at smart locations



$$\begin{array}{c} \text{Diagram 1} \\ = \\ \text{Diagram 2} \end{array}$$

Simplify ☺

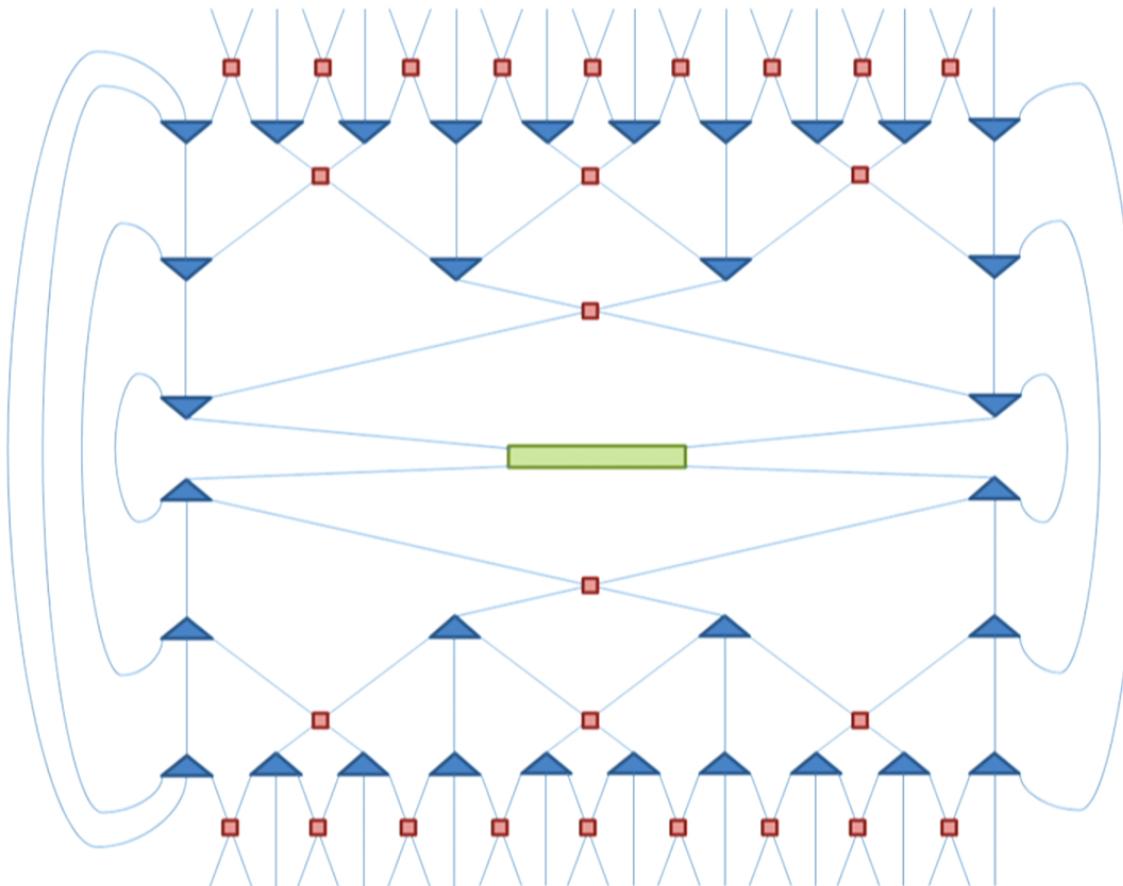
R.N.C. Pfeifer, G. Evenbly and G. Vidal, Entanglement renormalization, scale invariance, and quantum criticality (2009)

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$$\rho_{red,L} = \text{tr}(\rho)$$

Wilke van der Schee, MIT

## REDUCED DENSITY MATRIX IN MERA

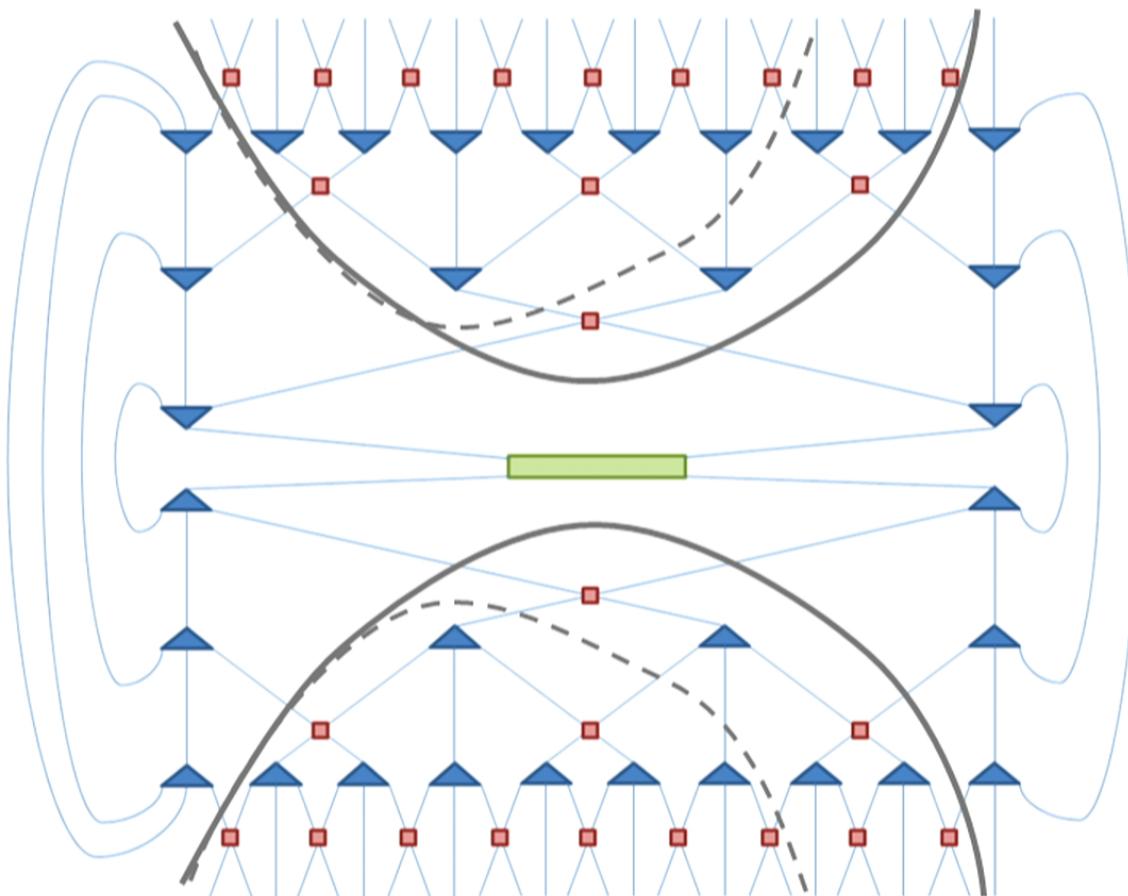


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$$\rho_{red,L} = \text{tr}(\rho)$$

Wilke van der Schee, MIT

## 'GEODESIC' IN ADS SPACETIME (SWINGLE)



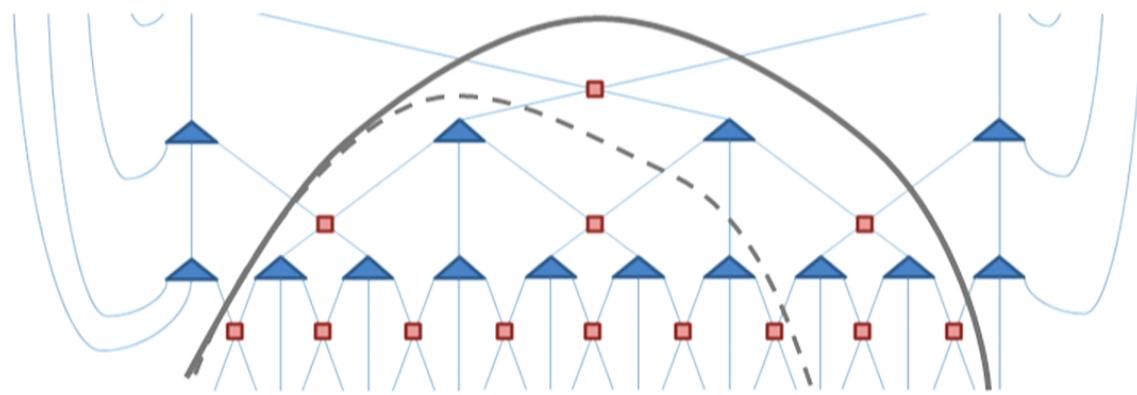
Brian Swingle, Entanglement Renormalization and Holography (2009)

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$$\rho_{red,L} = \text{tr}(\rho)$$

Wilke van der Schee, MIT

## LOG(L) SCALING

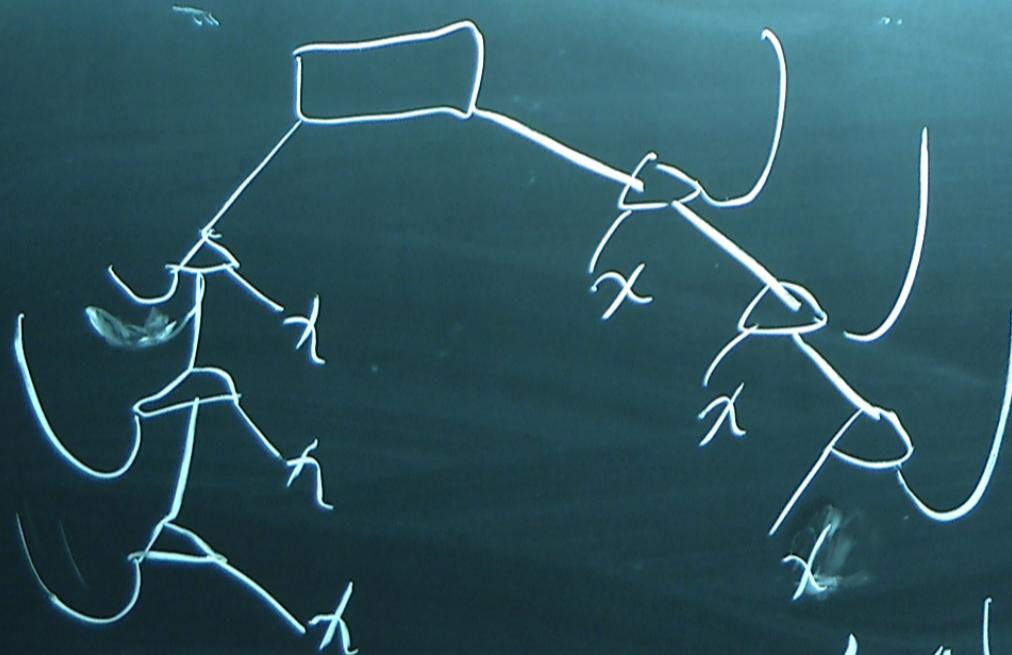


**Important: MERA has  $S_{EE} \lesssim \log(\chi) \log(L)$**

**Most local Hamiltonians obey this (but  $S_{EE} \sim \sqrt{L}$  possible)**

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R. Movassagh, P.W. Shor, Power law violation of the area law in quantum spin chains (2014)



$$P_L = \begin{pmatrix} m_1 \\ m_2 \\ \vdots \\ m_n \end{pmatrix}$$

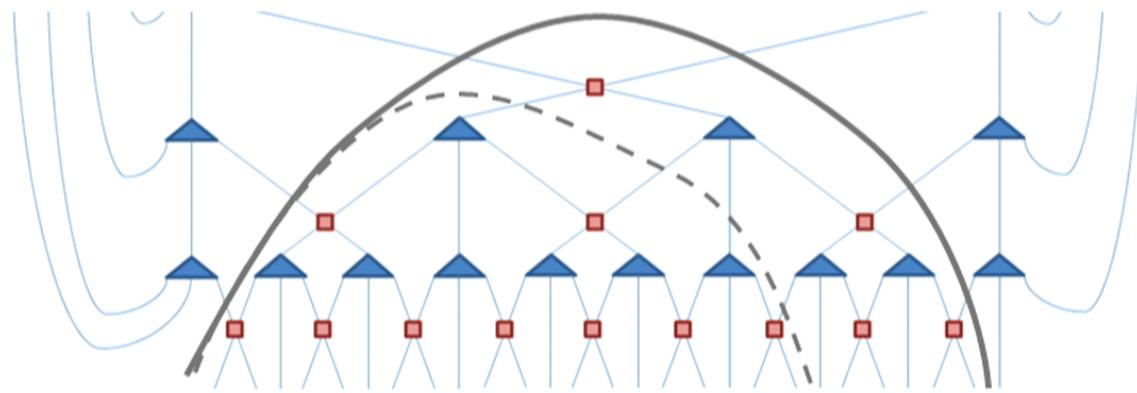
$$M = \chi^{\log L}$$

$$\log L S_{\text{ext}} = -P_i \log P_i$$

$$\rho_{red,L} = \text{tr}(\rho)$$

Wilke van der Schee, MIT

## LOG(L) SCALING



**Important: MERA has  $S_{EE} \lesssim \log(\chi) \log(L)$**

**Most local Hamiltonians obey this (but  $S_{EE} \sim \sqrt{L}$  possible)**

11/16

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## GRAVITY AS AN EMERGENT FORCE, ADS/MERA

Field theory without gravity  $\leftrightarrow$  string theory with gravity

Holographic: gravity has one extra dimension, RG scale

→ Propose connection between MERA and gravity

Caveat: gravity ‘emerges’ only for specific field theories  
(large N, strong coupling)

12/16

Brian Swingle, Entanglement Renormalization and Holography (2009)

## GRAVITY AS AN EMERGENT FORCE, ADS/MERA

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12/16

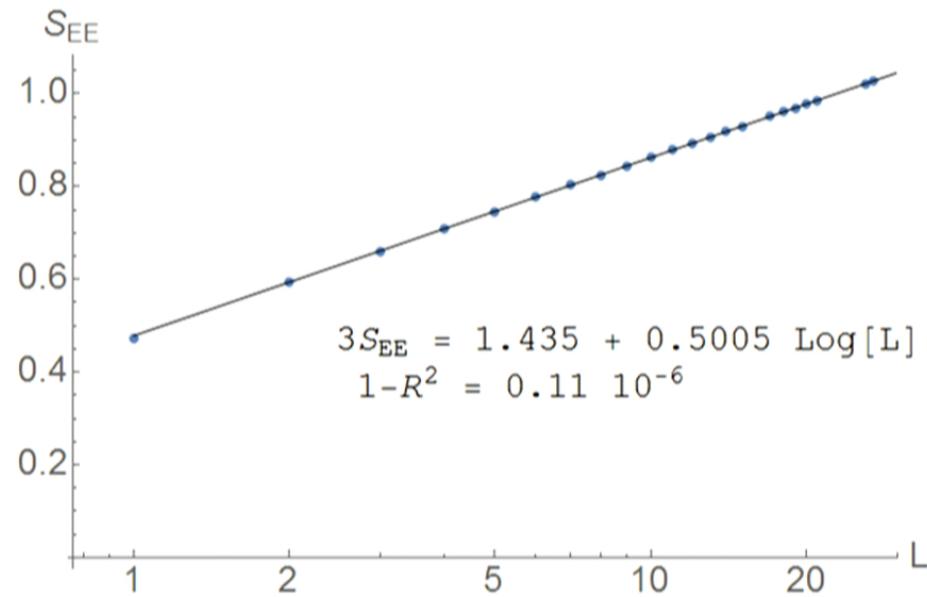
Brian Swingle, Entanglement Renormalization and Holography (2009)

$$S_{EE} = \frac{c}{3} \log(L) + \mathcal{O}(1)$$

Wilke van der Schee, MIT

## EQUIVALENT REDUCED DENSITY MATRIX

Resulting entanglement entropies:



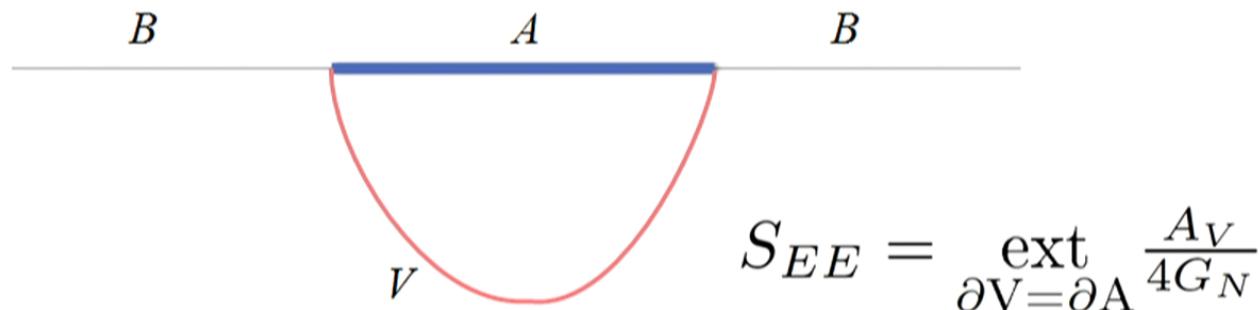
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## ENTANGLEMENT = GEOMETRY (PICTURE)

Entanglement: trace out part of space → mixed state (entropy!)

Remarkable statement (Ryu+Takayanagi):

entanglement entropy = area extremal surface in AdS



S. Ryu, T. Takayanagi, Holographic derivation of entanglement entropy from the anti-de sitter space/conformal field theory correspondence (2006)

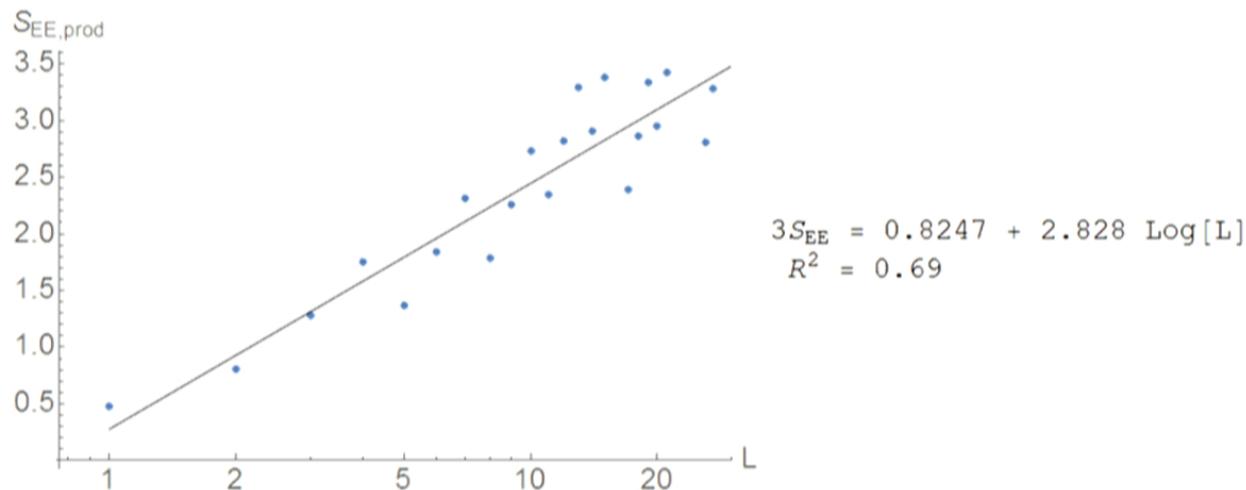
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## QUESTION: WHAT GIVES A GEOMETRIC PICTURE?

Reduced density matrix gives a local ‘slice’ in ‘AdS’

Hard to formalise: legs do not in general decouple

- Do they decouple with large  $c$ ?
- If so, then entanglement entropy = sum over entropy/leg
- What about dual of Ising model?



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## ^ Packages

- Almost always useful: different notebooks for different parameters/options, simulations versus analysing
- Easy to make: convert initialisation cells to package  
Trick: Edit --> Preferences --> Advanced --> Option Inspector --> Notebook options -->  
File Options --> Autogenerated package --> Manual
- Either put parameters/options before loading package or after

Example:

```
In[1]:= SetDirectory[NotebookDirectory[]];  
<< MERA`  
  
domodel[initIsing, 6]
```

## Hydrodynamics

### Load and display

### Standard values

Below are all standard values used. They are evaluated at the very last, so when using the notebook one can just change them and use ones own values; of particular interest are the gridsize (longitudinal), ngridpoints (AdS, longitudinal), the input function h, and the regulator energy density a4reg.

#### ■ Standard values for grid

```
gridsize = 10 \pi;
ngridpoints = {40, 500};
horloc = -1;
gridtypeset := {{"spectral", 2.0 / (1 + Cos[(-horloc - 1) \pi / ngridpoints[[1]] - 1])}, {"fourier", gridsize}};
derivativeorder = {"spectral", 41};
periodicity = {False, True};
dt := Min[0.00007 45^2 / ngridpoints[[1]]^2, 0.001];
```

#### ■ Standard values for computing EF B

```
startzFG = 3 / 100;
rFGmax = 1 / 0.005^{1/4};
charge = 0;
orderRKiny = 6;
stepsizeFGy = 1 / 1000;
orderRKinz = 8;
stepsizeFGz = 1 / 500;
```

100%



## ^ CUDA

```
cuda = False;
usecuda := (
    Needs["CUDALink`"];
    cuda = True;
)
CUDADot2[a_, b_] := (
    dima = Dimensions[a];
    dimb = Dimensions[b];
    If[Length[dim] > 2 || Length[dimb] > 2,
        ArrayReshape[CUDALink`CUDADot[Flatten[a, Length[dim] - 2] // N,
            Flatten/@b // N], dima[[;; -2]]~Join~dimb[[2 ;;]]],
        CUDALink`CUDADot[a // N, b // N]]
    )
dot[a_, b_] := If[cuda && Dimensions[a][[-1]] < 2500, CUDA2[a, b], a.b];
usecuda
```

```
If[Length[legs1[[1]]] > 0, Transpose[tens1[[1]], -legs1[[1]]], tens1[[1]]]
)
ncon[tensors_, legs_] := ncon[tensors, legs, Union[Select[Flatten[legs], # > 0 &]]]
```

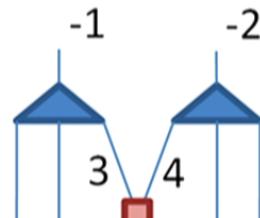
IdentityMatrix, change order, translational operator

```
In[3]:= x = 18;
{w, u, operator} = Table[Random[], {3}, {x}, {x}, {x}, {x}];
```

```
In[5]:= AbsoluteTiming[
nconp[{w, w^*, w, w^*, u, u^*, operator},
{{-1, 1, 2, 3}, {-3, 1, 2, 9}, {-2, 4, 11, 12}, {-4, 10, 11, 12},
{3, 4, 5, 6}, {7, 8, 9, 10}, {5, 6, 7, 8}},
{5, 6, 7, 8, 1, 2, 3, 9, 11, 12, 4, 10}] // Dimensions]
```

total cost is  $6x^6$  total: 204 073 344 (old: 204 073 344)

```
Out[5]= {0.157110, {18, 18, 18, 18}}
```



```
ncon[{w,w^*,w,w^*,u,u^*,o},
{{-1,1,2,3},
{-3,1,2,9},
{-2,4,11,12},
{-4,10,11,12},
```

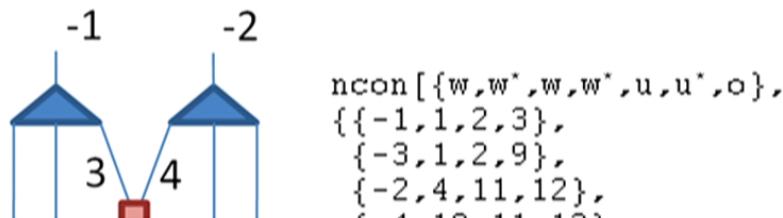
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```
In[3]:= x = 18;
{w, u, operator} = Table[Random[], {3}, {x}, {x}, {x}, {x}];

In[5]:= AbsoluteTiming[
ncomp[{w, w^*, w, w^*, u, u^*, operator},
{{{-1, 1, 2, 3}, {-3, 1, 2, 9}, {-2, 4, 11, 12}, {-4, 10, 11, 12},
{3, 4, 5, 6}, {7, 8, 9, 10}, {5, 6, 7, 8}},,
{5, 6, 7, 8, 1, 2, 3, 9, 11, 12, 4, 10}] // Dimensions]
total cost is  $6x^6$  total: 204 073 344 (old: 204 073 344)

Out[5]= {0.157110, {18, 18, 18, 18}}
```

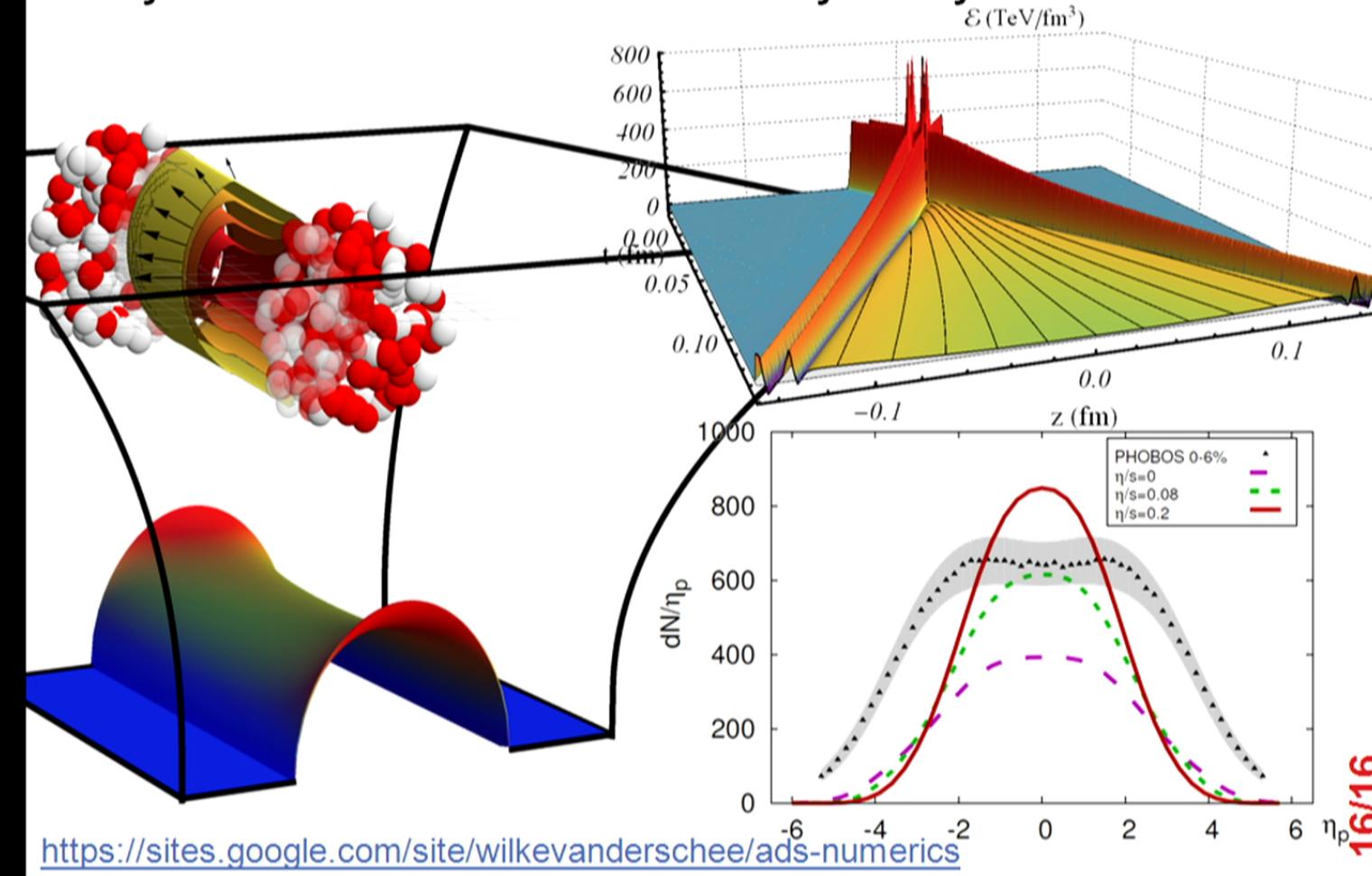
```
In[5]:= AbsoluteTiming[
ncomp[{w, |w^*, w, w^*, u, u^*, operator},
{{{-1, 1, 2, 3}, {-3, 1, 2, 9}, {-2, 4, 11, 12}, {-4, 10, 11, 12}, {3, 4, 5, 6},
{7, 8, 9, 10}, {5, 6, 7, 8}},, {5, 6, 7, 8, 1, 2, 3, 9, 11, 12, 4, 10}] // Dimensions]
```

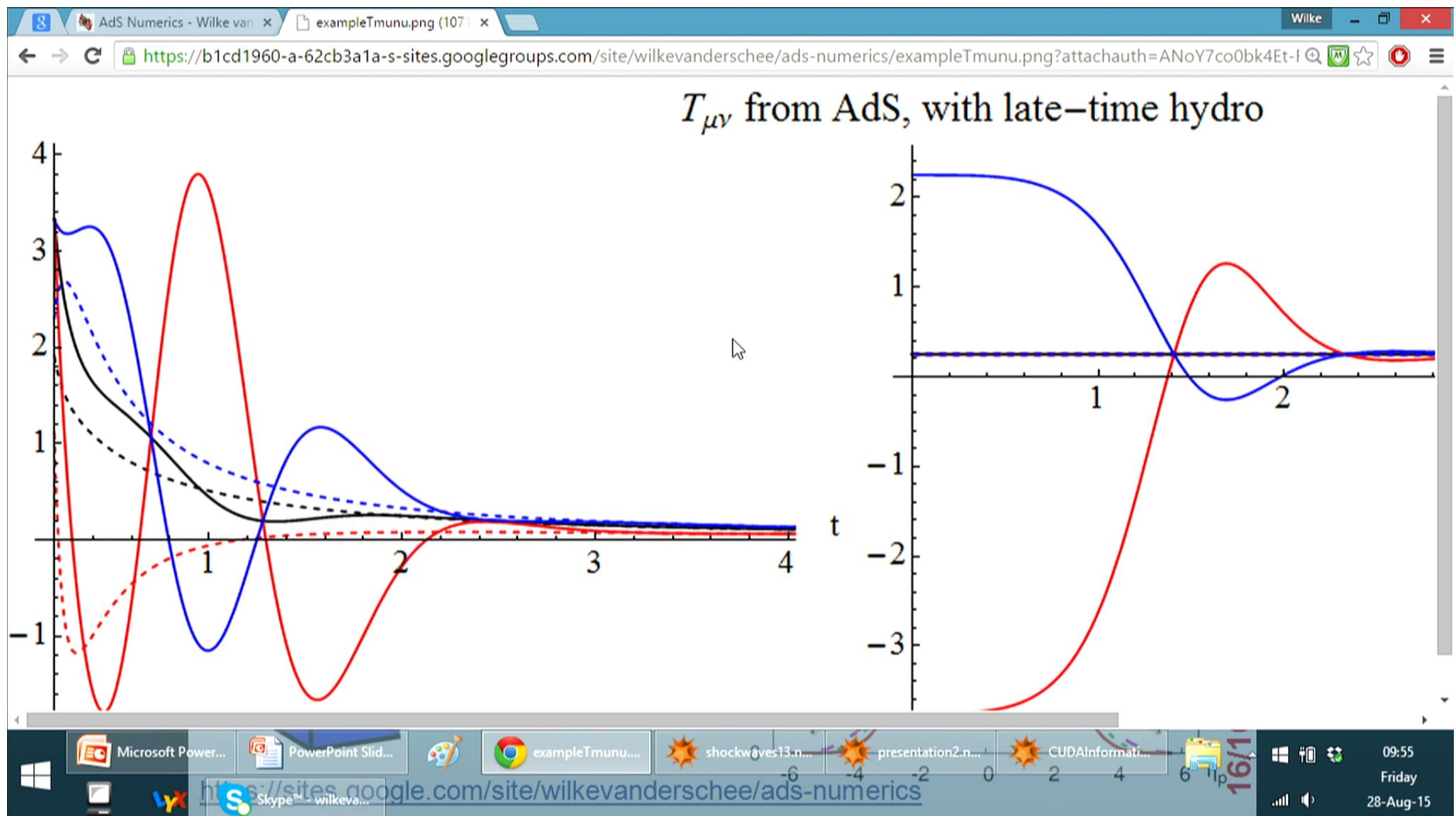


```
ncon[{w,w^*,w,w^*,u,u^*,o},
{{{-1,1,2,3},
{-3,1,2,9},
{-2,4,11,12},
{3,4,5,6},
{7,8,9,10},
{5,6,7,8}}}, {5,6,7,8,1,2,3,9,11,12,4,10}] // Dimensions]
```

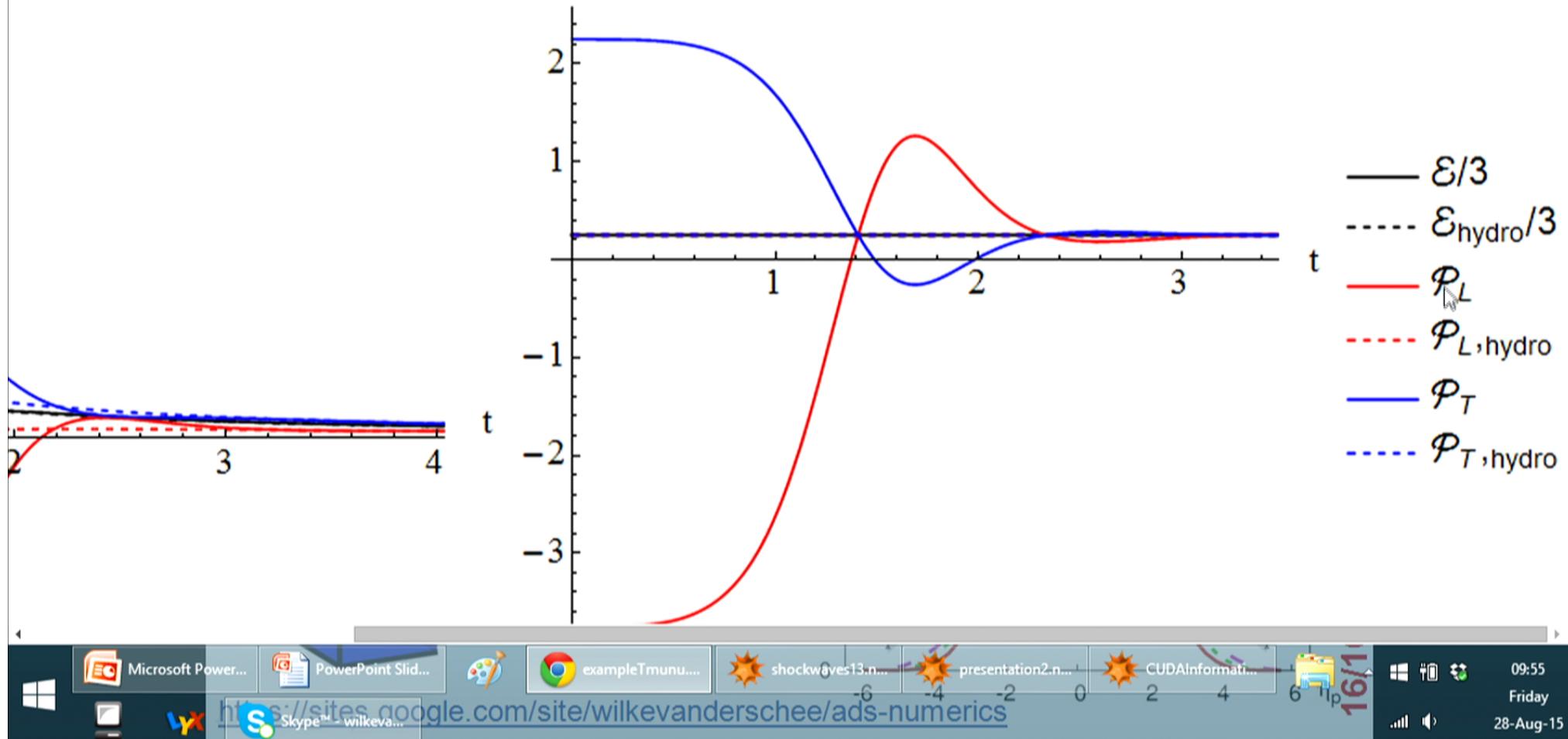
## SOME OTHER WORK

### Dynamics in Anti-de Sitter to study heavy ion collisions





## $T_{\mu\nu}$ from AdS, with late-time hydro



## ^ NDSolve and/or spectral methods

Solve linear ODE:

```
LDE = (2 + x) y''[x] + y'[x] - 20 x y[x];  
LDEboundary = {y[-1] == 5, y[1] == -1};  
  
dsollDE = y /. DSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]  
ndsolLDE = y /. NDSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]  
  
pl = Plot[dsollDE[x] // Re, {x, -1, 1.}]  
  
initGrid[points_] := (  
    nx = points;  
    x = N[Table[-Cos[(r \[Pi])/nx], {r, 0, nx - 1}]];
```



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```
In[12]:= LDE = (2 + x) y''[x] + y'[x] - 20 x y[x];
LDEboundary = {y[-1] == 5, y[1] == -1};
```

```
In[14]:= LDE
```

```
Out[14]= -20 x y[x] + y'[x] + (2 + x) y''[x]
```

```
In[15]:= dsollDE = y /. DSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]
ndsollDE = y /. NDSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]
```

```
Out[15]= Function[{x}, \left(e^{-2 \sqrt{5} (1+x)} \left(-\text{HypergeometricU}\left[\frac{1}{2}-2 \sqrt{5}, 1, 4 \sqrt{5} (2+x)\right]\right.\right.
\left.\left.(e^{4 \sqrt{5}} \text{LaguerreL}\left[-\frac{1}{2}+2 \sqrt{5}, 4 \sqrt{5}\right]+5 \text{LaguerreL}\left[-\frac{1}{2}+2 \sqrt{5}, 12 \sqrt{5}\right]\right)+\right.
\left.\left.(e^{4 \sqrt{5}} \text{HypergeometricU}\left[\frac{1}{2}-2 \sqrt{5}, 1, 4 \sqrt{5}\right]+5 \text{HypergeometricU}\left[\frac{1}{2}-2 \sqrt{5}, 1, 12 \sqrt{5}\right]\right) \text{LaguerreL}\left[-\frac{1}{2}+2 \sqrt{5}, 4 \sqrt{5} (2+x)\right]\right)\right)/
\left(\text{HypergeometricU}\left[1-2 \sqrt{5}, 1, 12 \sqrt{5}\right] \text{LaguerreL}\left[1-2 \sqrt{5}, 4 \sqrt{5}\right]\right)]
```

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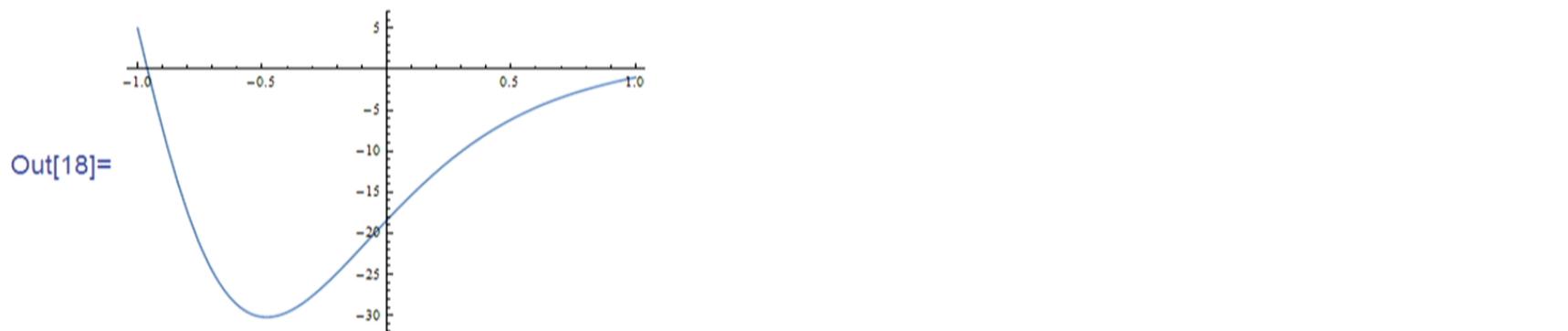
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$$\left( \text{HypergeometricU}\left[\frac{1}{2} - 2\sqrt{5}, 1, 12\sqrt{5}\right] \text{LaguerreL}\left[-\frac{1}{2} + 2\sqrt{5}, 4\sqrt{5}(2+x)\right]\right) / \\ \left( \text{HypergeometricU}\left[\frac{1}{2} - 2\sqrt{5}, 1, 12\sqrt{5}\right] \text{LaguerreL}\left[-\frac{1}{2} + 2\sqrt{5}, 4\sqrt{5}\right] - \\ \text{HypergeometricU}\left[\frac{1}{2} - 2\sqrt{5}, 1, 4\sqrt{5}\right] \text{LaguerreL}\left[-\frac{1}{2} + 2\sqrt{5}, 12\sqrt{5}\right]\right)$$

In[18]:= pl = Plot[dsollDE[x] // Re, {x, -1, 1.}]



initGrid[points\_]:=

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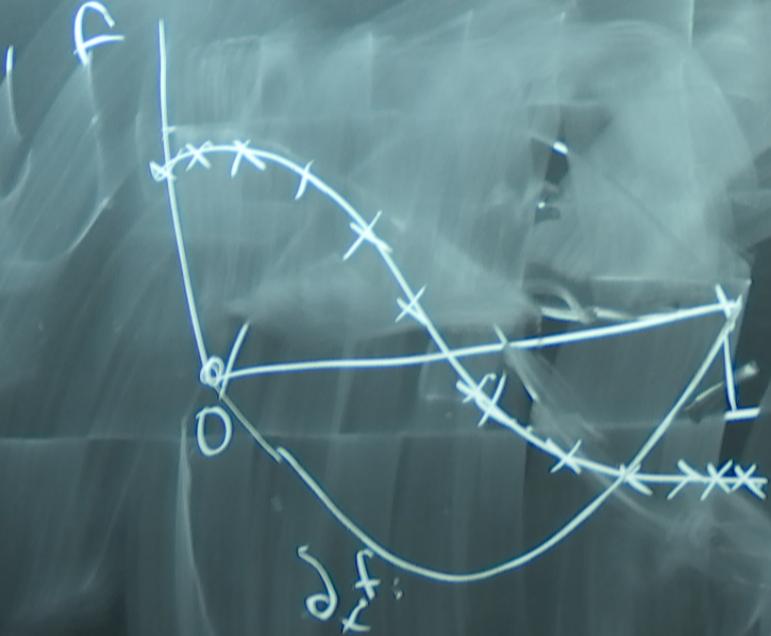


$$f_{\text{approx}} = \sum_{i=0}^N f_{\text{chob}}$$

$$f_i =$$

$$\partial_x f_i =$$

$f$



$$f_{\text{approx}} = \sum_{i=0}^N f_{\text{chob}}$$

$$f_i =$$

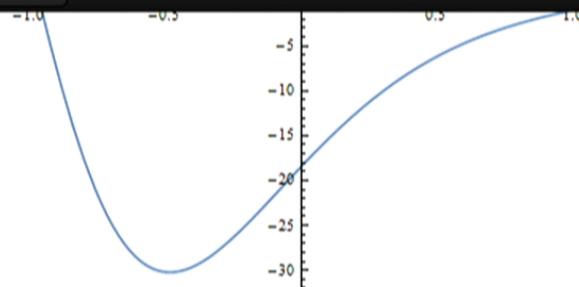
$$\begin{matrix} \text{Ospan} \\ \downarrow \\ \partial_x f_i = \end{matrix}$$

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Out[18]=



```
initGrid[points_] := (
  nx = points;
  x = N[Table[-Cos[(r \[Pi])/(nx - 1)], {r, 0, nx - 1}]];
  DSpec = NDSolve`FiniteDifferenceDerivative[1, x, DifferenceOrder \[Rule] points - 1][
    "DifferentiationMatrix"];
  D2Spec = DSpec.DSpec;
  x)
```

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```
In[19]:= initGrid[points_] := (
  nx = points;
  x = N[Table[-Cos[(r \pi)/(nx - 1)], {r, 0, nx - 1}]];
  DSpec = NDSolve`FiniteDifferenceDerivative[1, x, DifferenceOrder \rightarrow points - 1][
    "DifferentiationMatrix"];
  D2Spec = DSpec.DSpec;
  x)

eqm = DiagonalMatrix[D[LDE, y''[x]]].D2Spec +
  DiagonalMatrix[D[LDE, y'[x]]].DSpec + DiagonalMatrix[D[LDE, y[x]]];
source = LDE /. y \rightarrow (0 &);

LinearSolve[eqm, -source]
```

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## presentation2.nb \* - Wolfram Mathematica 10.0 (New Kernel)

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```
x = N[Table[-Cos[ $\frac{\pi r}{nx - 1}$ ], {r, 0, nx - 1}]];  
DSpec = NDSolve`FiniteDifferenceDerivative[1, x, DifferenceOrder -> points - 1][  
    "DifferentiationMatrix"];  
D2Spec = DSpec.DSpec;  
x]
```

In[20]:= initGrid[25]

Out[20]= {-1., -0.991445, -0.965926, -0.92388, -0.866025, -0.793353, -0.707107, -0.608761,  
-0.5, -0.382683, -0.258819, -0.130526, 0., 0.130526, 0.258819, 0.382683,  
0.5, 0.608761, 0.707107, 0.793353, 0.866025, 0.92388, 0.965926, 0.991445, 1.}

```
eqm = DiagonalMatrix[D[LDE, y''[x]]].D2Spec +  
    DiagonalMatrix[D[LDE, y'[x]]].DSpec + DiagonalMatrix[D[LDE, y[x]]];  
source = LDE /. y -> (0 &);
```

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## ^ NDSolve and/or spectral methods

Solve linear ODE:

```
In[12]:= LDE = (2 + x) y''[x] + y'[x] - 20 x y[x];
LDEboundary = {y[-1] == 5, y[1] == -1};
```

```
In[14]:= LDE
```

```
Out[14]= -20 x y[x] + y'[x] + (2 + x) y''[x]
```

```
In[15]:= dsollDE = y /. DSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]
nd sollDE = y /. NDSolve[{LDE == 0, LDEboundary} // Flatten, y, {x, -1, 1}] [[1]]
```

```
Out[15]= Function[{x}, \!\!\! (e^(-2 \sqrt{5} (1+x)) \!\!\! (-HypergeometricU[\!\!\! \frac{1}{2} - 2 \sqrt{5}, 1, 4 \sqrt{5} (2 + x)]\!\!\!) )/ \!\!\! A \!\!\! \sqrt{5}
```

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```
Out[21]= {1., 1.00856, 1.03407, 1.07612, 1.13397, 1.20665, 1.29289, 1.39124,
1.5, 1.61732, 1.74118, 1.86947, 2., 2.13053, 2.25882, 2.38268, 2.5,
2.60876, 2.70711, 2.79335, 2.86603, 2.92388, 2.96593, 2.99144, 3.}

In[24]:= DSpec // Normal // MatrixForm;

DiagonalMatrix[D[LDE, y''[x]]].D2Spec

In[25]:= eqm = DiagonalMatrix[D[LDE, y''[x]]].D2Spec +
DiagonalMatrix[D[LDE, y'[x]]].DSpec + DiagonalMatrix[D[LDE, y[x]]];
source = LDE /. y → (0 &);

In[30]:= LinearSolve[eqm, -source];
```

LinearSolve::luc : Result for LinearSolve of badly conditioned matrix {<<1>>} may contain significant numerical errors. >>

```
eqm[[1, ;;]] = Table[If[i == 1, 1, 0], {i, nx}];
eqm[[-1, ;;]] = Table[If[i == nx, 1, 0], {i, nx}];
```

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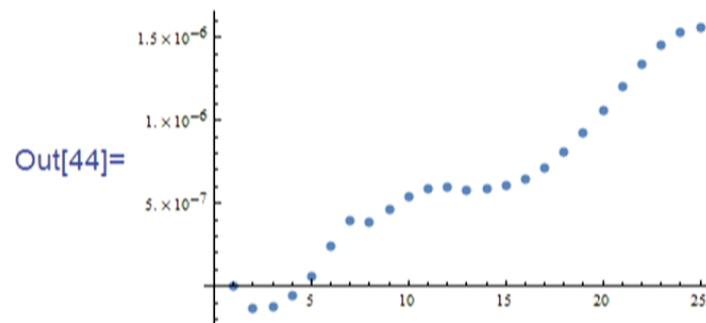
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```
-24.1764, -28.4537, -30.1825, -29.3739, -26.5942, -22.6775,  
-18.4271, -14.4284, -11.0015, -8.24794, -6.13099, -4.54953,  
-3.388, -2.54316, -1.93452, -1.50526, -1.21881, -1.05392, -1.}
```

In[44]:= function = ndsolLDE[x] // ListPlot



```
grid = x;  
x = .
```

```
ndsolLDE2 =
```

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10:17

Friday

28-Aug-15

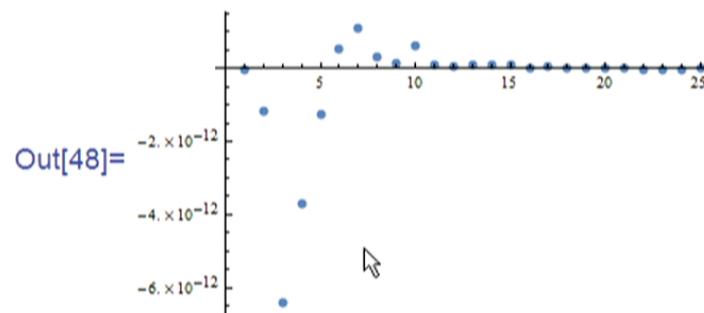
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```
y /. NDSolve[{lde == 0, ldeBoundary} // Flatten, y, {x, -1, 1},  
StartingStepSize -> 10^-2,  
Method -> {"FixedStep",  
Method -> {"ExplicitRungeKutta", "DifferenceOrder" -> 8,  
"StiffnessTest" -> False}]][[1]]
```

Out[47]= InterpolatingFunction[ Domain: {{-1., 1.}}]  
Output: scalar

In[48]:= function = ndsolLDE2[grid] // ListPlot[#, PlotRange -> All] &



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## ^ Transforming functions/coordinate transformation

```

metric = 
$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & -A[t, r] & 0 & 0 & 0 \\ 0 & 0 & S[t, r]^2 \text{Exp}[-2B[t, r]] & 0 & 0 \\ 0 & 0 & 0 & S[t, r]^2 \text{Exp}[B[t, r]] & 0 \\ 0 & 0 & 0 & 0 & S[t, r]^2 \text{Exp}[B[t, r]] \end{pmatrix}$$


coord = {r, t, x1, x2, x3};

SetDirectory[NotebookDirectory[]];
<< "diffgeo.m";

```

SetDelayed::write: Tag Laplacian in Laplacian[scalar\_?scalarQ] is Protected. >>

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Method →

```
{"FixedStep",
  Method → {"ExplicitRungeKutta", "DifferenceOrder" → 8,
  "StiffnessTest" → False} } ]
```

For a time dependent problem:

```
NDSolve[ ..., StartingStepSize → 10-2,
  Method → {"MethodOfLines",
  "SpatialDiscretization" → {"TensorProductGrid", "MinPoints" → 50,
  "MaxPoints" → 50, "DifferenceOrder" → 4}} ]
```

## ■ One could compute entanglement entropy (1506.02658)

u = .

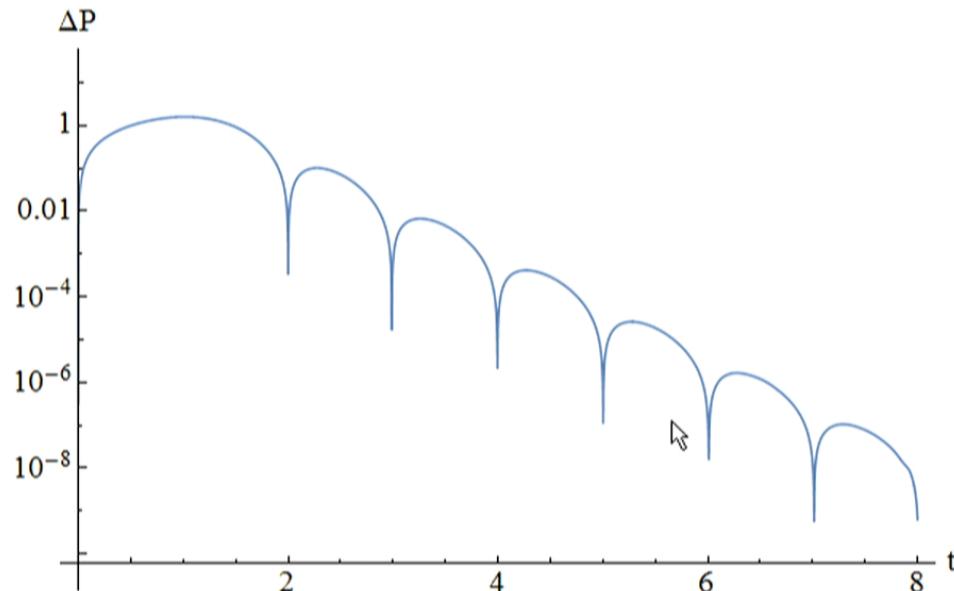
$\sigma = \{\lambda, \lambda_2, \lambda_3\};$

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```
LogPlot[bi3d[t, 0] // Abs, {t, 0, 8}, BaseStyle → 20, ImageSize → 600,  
AxesLabel → {"t", "ΔP"}]
```



My other favourite NDSolve methods :



$$\frac{1}{2} S[t, r] (A[t, r] (3 A^{(0,1)}[t, r] S^{(0,1)}[t, r] + S[t, r] (-8 + A^{(0,2)}[t, r])) - 3 (S^{(0,1)}[t, r] A^{(1,0)}[t, r] + S[t, r] B^{(1,0)}[t, r]^2 - A^{(0,1)}[t, r] S^{(1,0)}[t, r] + 2 S^{(2,0)}[t, r])) \}$$

- Do a linearized approximations (look up black brane, or solve by near boundary analysis)

```

 funcs = {A, B, S};

 linear =
 (f ↦
 (f → (ToExpression[ToString[f] <> "0"] [#1, #2] +
   ε ToExpression["δ" <> ToString[f]] [#1, #2] &))) /@ funcs
 D[A[t, r], t] /. linear

 {A → (ToExpression[ToString[A] <> 0] [#1, #2] +

```

## ^ Transforming functions/coordinate transformation

In[53]:= metric =

$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & -A[t, r] & 0 & 0 & 0 \\ 0 & 0 & s[t, r]^2 \text{Exp}[-2 B[t, r]] & 0 & 0 \\ 0 & 0 & 0 & s[t, r]^2 \text{Exp}[B[t, r]] & 0 \\ 0 & 0 & 0 & 0 & s[t, r]^2 \text{Exp}[B[t, r]] \end{pmatrix}$$

coord = {r, t, x1, x2, x3};

In[55]:= SetDirectory[NotebookDirectory[]];  
 << "diffgeo.m";

SetDelayed::write : Tag Laplacian in Laplacian[scalar\_?scalarQ] is Protected. >>



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$$\text{In[75]:= } \text{EE1}[[4]] \\ \text{Out[75]= } \frac{1}{r} \left( (-1 + r^4) \delta B^{(0,1)}[t, r] + r ((-1 + r^4) \delta B^{(0,2)}[t, r] + r (3 \delta B^{(1,0)}[t, r] + 2 r \delta B^{(1,1)}[t, r])) \right)$$

■ Change coordinates to  $1/r$  and  $B$  to  $B/z^4$ , which makes  $B$  regular at the boundary:

In[75]:= EE1[[4]]

$$\text{Out[75]= } \frac{1}{r} \left( (-1 + r^4) \delta B^{(0,1)}[t, r] + r ((-1 + r^4) \delta B^{(0,2)}[t, r] + r (3 \delta B^{(1,0)}[t, r] + 2 r \delta B^{(1,1)}[t, r])) \right)$$

In[72]:= replrtou =  $\{f_{-}^{(a-, b-)}[t, r] \rightarrow D[f^{(a, 0)}[t, \frac{1}{r}], \{r, b\}], f_{-}[t, r] \rightarrow f[t, u], r \rightarrow 1/u\}$

Out[72]=  $\{f_{-}^{(a-, b-)}[t, r] \rightarrow \partial_{\{r, b\}} f^{(a, 0)}[t, \frac{1}{r}], \dots, r \rightarrow \{\{\dots, \{\dots, \dots, 14\dots, \{\{\dots, \dots, 16\dots, \{\{2.87775, 2.05096, 116.219, \dots, 13\dots, 5.38225, 2.15256}, \dots, 17\dots\}\}, \{\{\dots, \dots, 17\dots\}\}\}$

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$$\text{Out}[75]= \frac{1}{r} \left( (-1 + 5 r^4) \delta B^{(0,1)}[t, r] + r ((-1 + r^4) \delta B^{(0,2)}[t, r] + r (3 \delta B^{(1,0)}[t, r] + 2 r \delta B^{(1,1)}[t, r])) \right)$$

$$u = 1/r$$

In[76]:= D[f[t, 1/r], t]

$$\text{Out}[76]= f^{(1,0)}\left[t, \frac{1}{r}\right]$$

In[77]:=  $\delta B^{(0,1)}[t, r] / . f^{(a_, b_)}[t, r] \rightarrow D[f^{(a,0)}[t, \frac{1}{r}], \{r, b\}]$

$$\text{Out}[77]= -\frac{\delta B^{(0,1)}[t, \frac{1}{r}]}{r^2}$$

In[72]:= replrtou = { $f^{(a_, b_)}[t, r] \rightarrow D[f^{(a,0)}[t, \frac{1}{r}], \{r, b\}]$ ,  $f_[t, r] \rightarrow f[t, u]$ ,  $r \rightarrow 1/u$ }

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## presentation2.nb \* - Wolfram Mathematica 10.0 (New Kernel)

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$$\text{Out}[76]= f^{(1,0)} \left[ t, \frac{1}{r} \right]$$

In[78]:= u = .

$$\text{In}[81]:= \delta B^{(0,5)} [t, r] /. f_{-}^{(a_, b_)} [t, r] \rightarrow D[f^{(a,0)} \left[ t, \frac{1}{r} \right], \{r, b\}]$$

% /. r → 1/u

$$\text{Out}[81]= -\frac{120 \delta B^{(0,1)} \left[ t, \frac{1}{r} \right]}{r^6} - \frac{240 \delta B^{(0,2)} \left[ t, \frac{1}{r} \right]}{r^7} -$$

$$\frac{120 \delta B^{(0,3)} \left[ t, \frac{1}{r} \right]}{r^8} - \frac{20 \delta B^{(0,4)} \left[ t, \frac{1}{r} \right]}{r^9} - \frac{\delta B^{(0,5)} \left[ t, \frac{1}{r} \right]}{r^{10}}$$

$$\text{Out}[82]= -120 u^6 \delta B^{(0,1)} [t, u] - 240 u^7 \delta B^{(0,2)} [t, u] -$$

$$120 u^8 \delta B^{(0,3)} [t, u] - 20 u^9 \delta B^{(0,4)} [t, u] - u^{10} \delta B^{(0,5)} [t, u]$$

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$$\text{Out}[82] = -120 u^6 \delta B^{(0,1)}[t, u] - 240 u^7 \delta B^{(0,2)}[t, u] - \\ 120 u^8 \delta B^{(0,3)}[t, u] - 20 u^9 \delta B^{(0,4)}[t, u] - u^{10} \delta B^{(0,5)}[t, u]$$

$$\text{In}[83]:= \text{replrtou} = \left\{ f_{-}^{(a-, b-)}[t, r] \rightarrow D[f^{(a, 0)}[t, \frac{1}{r}], \{r, b\}], f_{-}[t, r] \rightarrow f[t, u], r \rightarrow 1/u \right\}$$

$$\text{Out}[83] = \left\{ f_{-}^{(a-, b-)}[t, r] \rightarrow \partial_{\{r, b\}} f^{(a, 0)}[t, \frac{1}{r}], f_{-}[t, r] \rightarrow f[t, u], r \rightarrow \frac{1}{u} \right\}$$

$$\text{EElreg} = -\frac{1}{u^3} \text{EEl}[4] // . \text{replrtou} /. \delta B \rightarrow (\delta B \text{reg}[\#1, \#2] \#2^4 \&) // \text{FullSimplify}$$

$$16 u^3 \delta B \text{reg}[t, u] + (-5 + 9 u^4) \delta B \text{reg}^{(0,1)}[t, u] + \\ u (-1 + u^4) \delta B \text{reg}^{(0,2)}[t, u] + 5 \delta B \text{reg}^{(1,0)}[t, u] + 2 u \delta B \text{reg}^{(1,1)}[t, u]$$

- Now write time derivative equation numerically, as  $B_c \partial_z (\partial_t B) + C_c (\partial_t B) + S_c = 0$ , which is easy to solve spectrally

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1.726, 1.79609, 1.85686, 1.90758, 1.94765, 1.97662, 1.99414, 2.}

```
dBregdt[Bnum_List] :=
  LinearSolve[DiagonalMatrix[Bc].DSpec + DiagonalMatrix[Cc + 0 u], -Snum[Bnum]]
```

- Time stepping with NDSolve and/or ones favorite method (Runge-Kutta, Adams-Basforth, implicit/explicit etc)

`Timing[`

```
ndsol = NDSolve[{D[b[t], t] == dBregdt[b[t]], b[0] == Bnum}, b, {t, 0, 8}][[1]];
bi = b /. ndsol
{0.140625, Null}
```

InterpolatingFunction[ Domain: {{0., 8.}}  
Output dimensions: {30}]

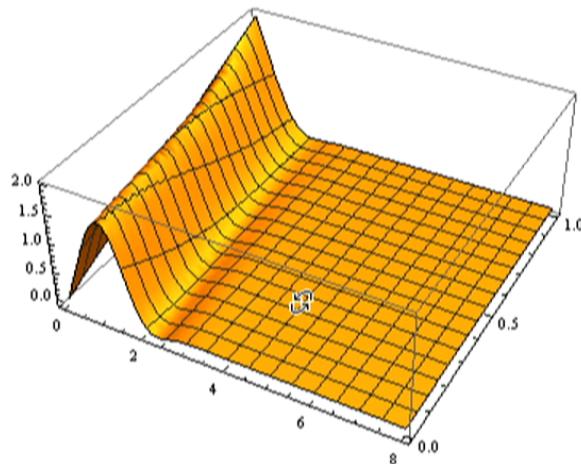
`tgrid = bi["Grid"][[;; , 1]]`

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```
Plot3D[bi3d[x, y], {x, 0., 8.}, {y, 0., 1.}, PlotRange -> All]
```



■ One clearly sees the lowest QNM:

```
LogPlot[bi3d[t, 0] // Abs, {t, 0, 8}, BaseStyle -> 20, ImageSize -> 600,  
AxesLabel -> {"t", "ΔP"}]
```