

Title: 14/15 PSI - Statistical Mechanics - Lecture 9

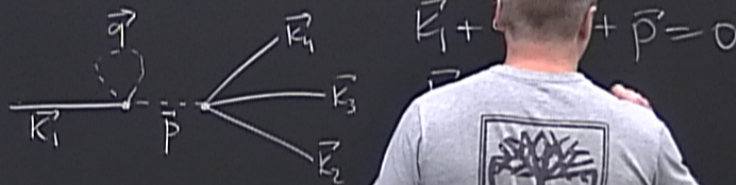
Date: Oct 17, 2014 10:45 AM

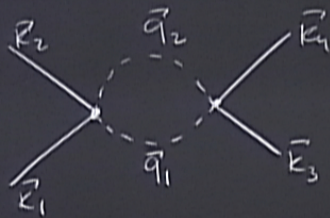
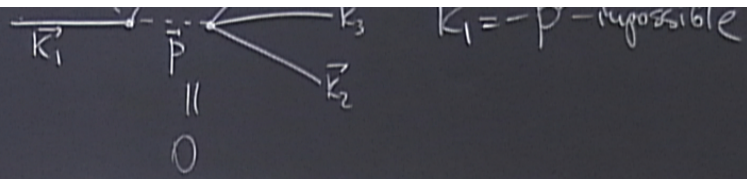
URL: <http://pirsa.org/14100095>

Abstract:

Contribution of the second cumulant to RG equations:

$$\frac{1}{2} \left[\langle S_{int}^2 \rangle_0 - \langle S_{int} \rangle_0^2 \right] = 26 \text{ (loop diagram)} + 48 \text{ (loop diagram)}$$





$$k_1 + k_2 + q_1 + q_2 = 0$$


$$k_3 + k_4 - q_1 - q_2 = 0$$

$\Rightarrow k_1$

$k_1 = -p$ - impossible
 k_2

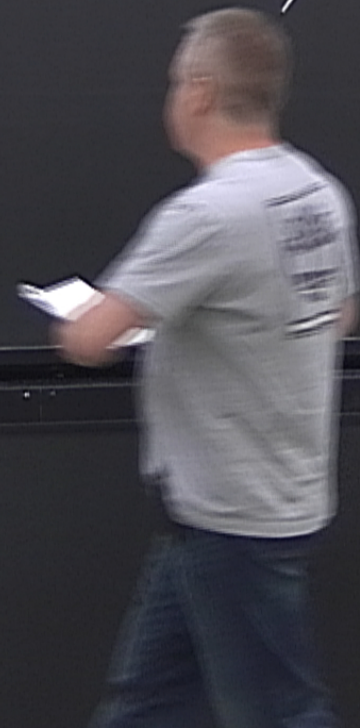
$$\begin{aligned} E_1 + E_2 + q_1 + q_2 &= 0 \\ E_3 + E_4 - q_1 - q_2 &= 0 \end{aligned} \Rightarrow E_1 + E_2 + E_3 + E_4 = 0$$

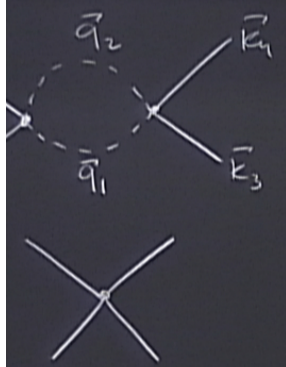
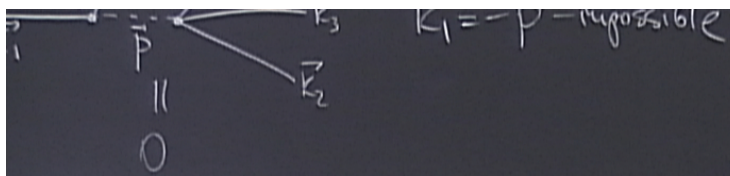
let $q_1 = q$, $q_2 = -E_1 - E_2 - q$



$$= \left(\frac{4}{4!}\right)^2 \int_{k_1, k_4} (2\pi)^d \delta(E_1 + E_2 + E_3 + E_4) \psi_c(E_1) \psi_c(E_2) \psi_c(E_3) \psi_c(E_4)$$

↑
N/6





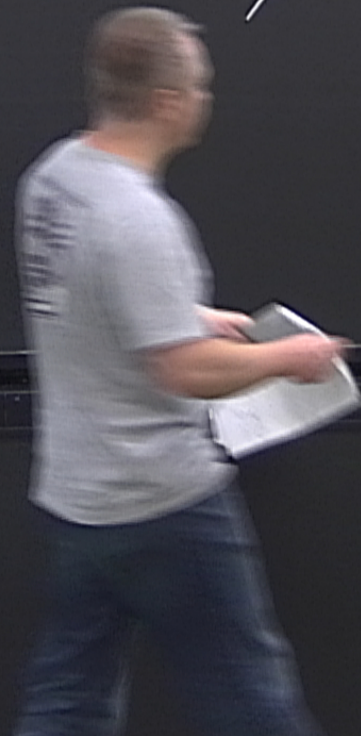
$$k_1 + k_2 + q_1 + q_2 = 0 \Rightarrow k_1 + k_2 + k_3 + k_4 = 0$$

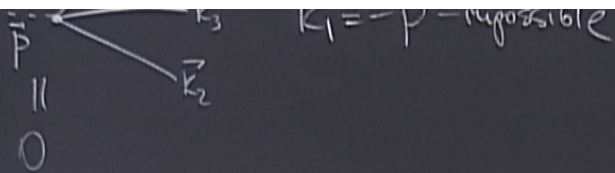
$$k_3 + k_4 - q_1 - q_2 = 0$$

let $q_1 = q$, $q_2 = -k_1 - k_2 - q$

$$= \left(\frac{u}{4!} \right)^2 \int_{k_1, k_4} (2\pi)^d \delta(k_1 + k_2 + k_3 + k_4) \psi_2(k_1) \psi_2(k_4)$$

\uparrow
 $N/6$





\vec{k}_4
 \vec{k}_3
 $\vec{k}_1 + \vec{k}_2 + \vec{q}_1 + \vec{q}_2 = 0 \Rightarrow \vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4 = 0$
 $\vec{k}_3 + \vec{k}_4 - \vec{q}_1 - \vec{q}_2 = 0$
 let $\vec{q}_1 = \vec{q}$, $\vec{q}_2 = -\vec{k}_1 - \vec{k}_2 - \vec{q}$

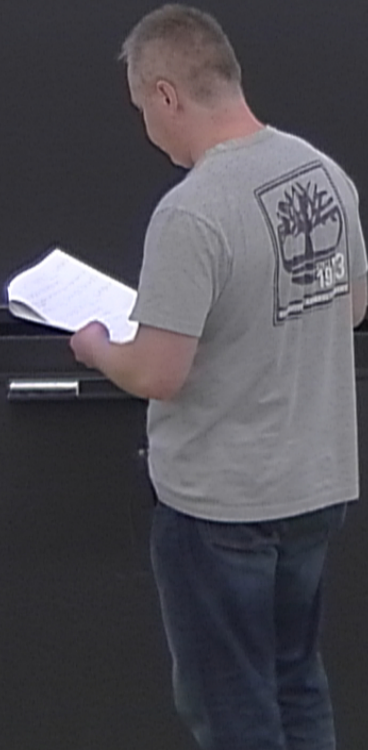
$\times \times = \left(\frac{u}{4!}\right)^2 \int_{k_1, k_4} (2\pi)^d \delta(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \varphi_c(\vec{k}_1) \varphi_c(\vec{k}_2) \varphi_c(\vec{k}_3)$
 $\int_{N/6} \frac{d^d q}{(2\pi)^d} \underbrace{G_0(\vec{q}) G_0(-\vec{k}_1 - \vec{k}_2 - \vec{q})}_{I_2}$

$(E) \psi_c(E) \psi_c(E) \psi_c(E)$

$$I_2 = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} G_0(\vec{q}) G_0(-E-E_i, \vec{q})$$



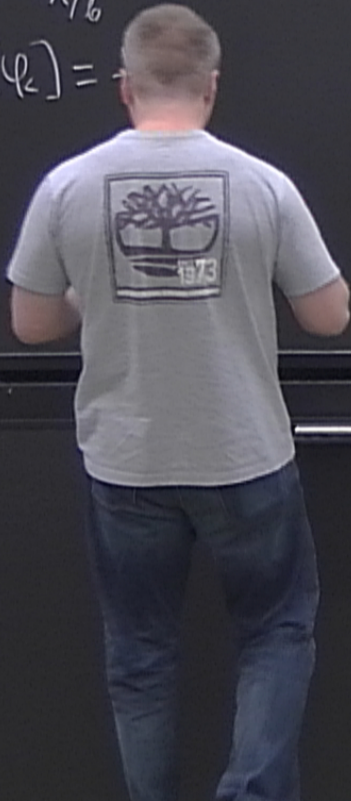
$$I_2 = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \zeta_0(\vec{q}) \zeta_0(-\vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \zeta_0^2(\vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \frac{1}{(\Gamma + q^2)^2} = \frac{S_d}{(2\pi)^d} \frac{\Lambda^d \Delta l}{(\Gamma + \Lambda^2)^2}$$



b) $\psi_2(\vec{r})$

$$I_2 = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \zeta_0(\vec{q}) \zeta_0(-\vec{E}_1 - \vec{E}_2 - \vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \zeta_0^2(\vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \frac{1}{(r+q^2)^2} = \frac{S_d}{(2\pi)^d} \frac{\Lambda^d \Delta \ell}{(r+\Lambda^2)^2}$$

$$S'[\psi_2] =$$



b) $\psi_k(\vec{r})$

$$I_2 = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} G_0(\vec{q}) G_0(-\vec{r}_1 - \vec{r}_2 - \vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} G_0^2(\vec{q}) = \int_{\Lambda/b}^{\Lambda} \frac{d^d q}{(2\pi)^d} \frac{1}{(r+q^2)^2} = \frac{S_d}{(2\pi)^d} \frac{\Lambda^d \Delta \ell}{(r+\Lambda^2)^2}$$
$$S'[\psi_k] = \frac{1}{2} \int_k \left(k^2 + r + \frac{u}{2} I_1 \right) |\psi_k(\vec{r})|^2 + \left[\frac{u}{4!} \right]$$

$$\psi'(\vec{r}) = b^{-\frac{d-1}{2}} \psi_c(\vec{r})$$

$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{dl} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ \frac{du}{dl} = (4-d)u - \frac{3u^2}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2} \end{cases}$$

-one-loop RG equations

$$\frac{du}{dl} = 0$$

$$\psi'(\vec{r}) = b^{-\frac{d-1}{2}} \psi_c(\vec{r})$$

$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{d\ell} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ = \underbrace{(4-d)}_{\varepsilon} r - \frac{3u^2}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2} \end{cases}$$

-one-loop RG equations

$$\frac{dr}{d\ell} = \frac{du}{d\ell} = 0 \quad ; \quad u^* = \varepsilon^2$$



$$\psi'(\vec{r}) = b^{-\frac{d-2}{2}} \psi_c(\vec{r})$$

$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{dl} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ \frac{du}{dl} = \left(4 - \frac{3u^2}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2}\right) u \end{cases}$$

-one-loop RG equations

$$\frac{dr}{dl} = \frac{du}{dl} = 0 \quad ; \quad u^* = \varepsilon \frac{2}{3} \frac{(2\pi)^d}{S_d}$$

$$\psi'(\vec{r}) = b^{-\frac{d-2}{2}} \psi_c(\vec{r})$$

$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{dl} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ \frac{du}{dl} = \left(\frac{u}{2} - \frac{3u^2}{2}\right) \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2} \end{cases}$$

-one-loop RG equations

$$\frac{dr}{dl} = \frac{du}{dl} = 0 \quad ; \quad u^* = \frac{2}{3} \frac{(2\pi)^d}{S_d}$$

$$\psi'(\vec{R}) = b^{-\frac{d-2}{2}} \psi_c(\vec{R})$$

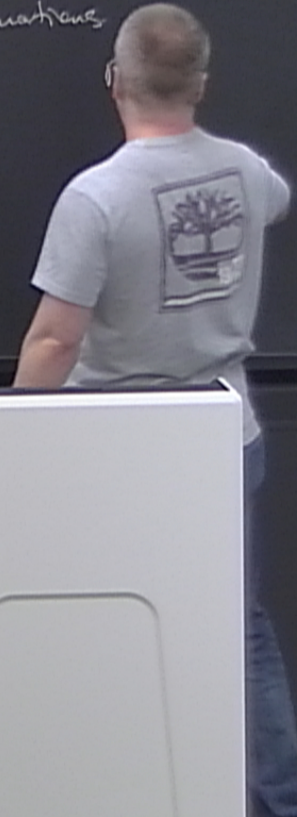
$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{dl} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ \frac{du}{dl} = \left(\frac{d-2}{2} - \frac{3u^2}{2}\right) \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2} \end{cases}$$

-one-loop RG equations

$$\frac{dr}{dl} = \frac{du}{dl} = 0 \quad ; \quad u^* = \varepsilon \frac{2}{3} \frac{(2\pi)^d}{S_d}$$

$$\begin{cases}
 \frac{dr}{dl} = 2r + \frac{y}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\
 \frac{d\mu}{dl} = \underbrace{(4-d)}_{\varepsilon} \mu - \frac{3\mu^2}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2}
 \end{cases}$$
 - one-loop RG equations

$$\mu^* = \varepsilon \frac{2}{3} \frac{(2\pi)^d}{S_d} ; S_d = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 ; \mu^* = \frac{16\pi^2 \varepsilon}{3} ; r^* = -\frac{\varepsilon}{6} \Lambda^2$$

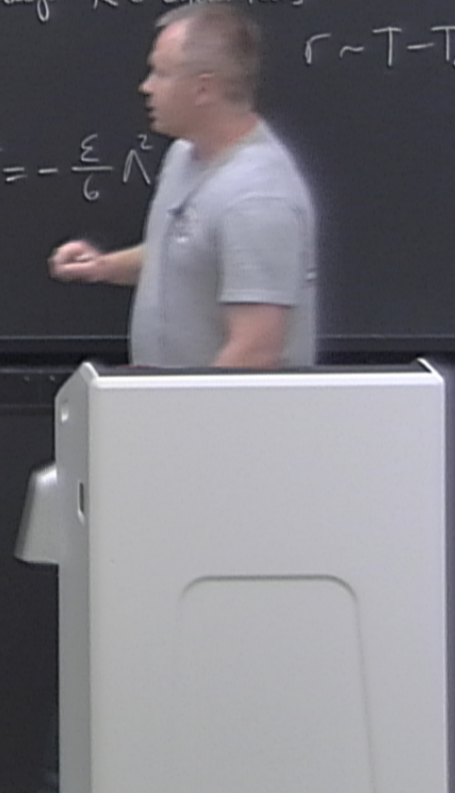


$$\psi'(R) = b^{-\frac{d-1}{2}} \psi_c(R)$$

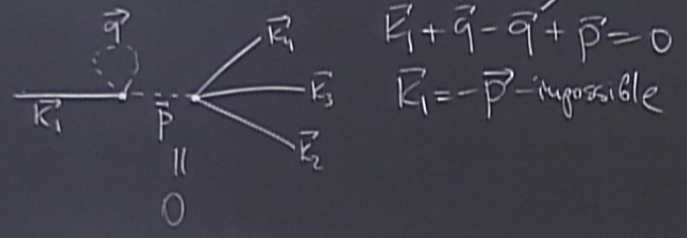
$$\begin{cases} r' = \left(r + \frac{u}{2} I_1\right) b^2 \\ u' = \left(u - \frac{3}{2} u^2 I_2\right) b^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{dl} = 2r + \frac{u}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{r + \Lambda^2} \\ \frac{du}{dl} = \underbrace{(4-d)}_{\varepsilon} u - \frac{3u^2}{2} \frac{S_d}{(2\pi)^d} \frac{\Lambda^d}{(r + \Lambda^2)^2} \end{cases}$$

- one-loop RG equations $r \sim T - T_c$

$$\frac{dr}{dl} = \frac{du}{dl} = 0 \quad ; \quad u^* = \varepsilon \frac{2}{3} \frac{(2\pi)^d}{S_d} \quad ; \quad S_d = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 \quad ; \quad u^* = \frac{16\pi^2 \varepsilon}{3} \quad ; \quad r^* = -\frac{\varepsilon}{6} \Lambda^2$$



$$[\langle S_{int} \rangle_0 - \langle S_{int} \rangle^2] = 36 \times \text{diagram} + 48 \times \text{diagram}$$



Linearize the RG flow equations near the Gaussian fixed point $r^* = u^* = 0$

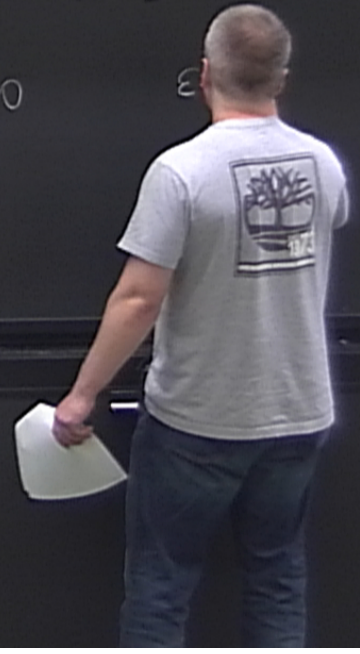
$$\delta r = r - r^*, \quad \delta u = u - u^*$$

$$\begin{cases} \frac{d\delta r}{dl} = 2\delta r + \frac{\delta u}{2} K_d \Lambda^2 \\ \frac{d\delta u}{dl} = \epsilon \delta u \end{cases}$$

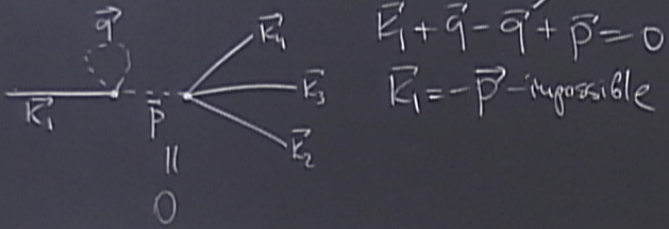
$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$\lambda_r = 2, \quad \lambda_u = \epsilon$$

$$\begin{pmatrix} 2 - \lambda_t & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon \end{pmatrix}$$



$$[\langle S_{int} \rangle_0 - \langle S_{int} \rangle^2] = 36 \times \text{diagram} + 48 \times \text{diagram}$$



Linearize the RG flow equations near the Gaussian fixed point $r^* = u^* = 0$

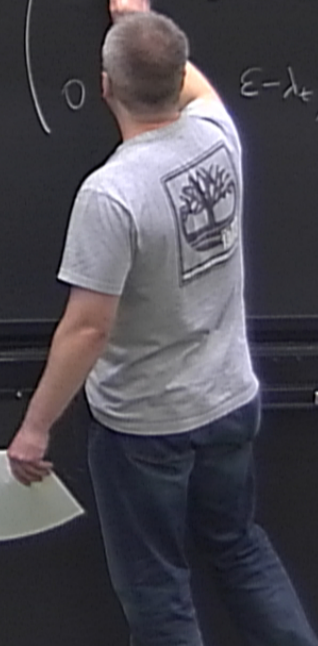
$$\delta r = r - r^*, \quad \delta u = u - u^*$$

$$\begin{cases} \frac{d\delta r}{dl} = 2\delta r + \frac{\delta u}{2} K_d \Lambda^2 \\ \frac{d\delta u}{dl} = \epsilon \delta u \end{cases}$$

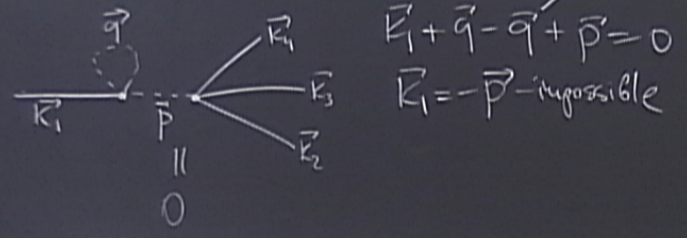
$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$\lambda_r = 2, \quad \lambda_u = \epsilon$$

$$\begin{pmatrix} -\frac{1}{2} K_d \Lambda^2 & \\ 0 & \epsilon - \lambda_t \end{pmatrix} \begin{pmatrix} v_{t1} \\ v_{t2} \end{pmatrix} = 0$$



$$[\langle S_{int} \rangle_0 - \langle S_{int} \rangle^2] = 36 \times \text{diagram} + 48 \times \text{diagram}$$



Linearize the RG flow equations near the Gaussian fixed point $r^* = u^* = 0$

$$\delta r = r - r^*, \quad \delta u = u - u^*$$

$$\begin{cases} \frac{d\delta r}{dl} = 2\delta r + \frac{\delta u}{2} K_d \Lambda^2 \\ \frac{d\delta u}{dl} = \epsilon \delta u \end{cases}$$

$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

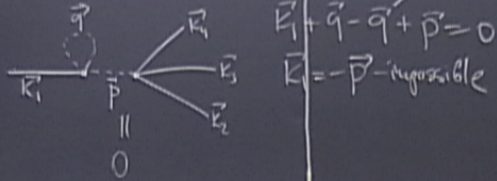
$$\lambda_r = 2, \quad \lambda_u = \epsilon$$

$$\begin{pmatrix} 0 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon - \lambda_t \end{pmatrix} \begin{pmatrix} v_{t1} \\ v_{t2} \end{pmatrix} = 0$$

$$\frac{1}{2} K_d \Lambda^2 v_{t2} = 0 \Rightarrow v_{t2} = 0, \quad v_{t1} = 1$$

Contribution of the second invariant to RG equations.

$$\frac{1}{2} [\langle S_{int}^2 \rangle_0 - \langle S_{int} \rangle^2] = 36 \text{ (diagram)} + 48 \text{ (diagram)}$$



Linearize the RG flow equations near the Gaussian fixed point $r^* = u^* = 0$

$$\delta r = r - r^*, \quad \delta u = u - u^*$$

$$\begin{cases} \frac{d\delta r}{dl} = 2\delta r + \frac{\delta u}{2} K_d \Lambda^2 \\ \frac{d\delta u}{dl} = \varepsilon \delta u \end{cases}$$

$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \varepsilon \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$\lambda_r = 2, \quad \lambda_u = \varepsilon$$

$$\begin{pmatrix} 0 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \varepsilon - \lambda_r \end{pmatrix} \begin{pmatrix} v_{t1} \\ v_{t2} \end{pmatrix} = 0$$

$$K_d \Lambda^2 v_{t2} = 0 \Rightarrow v_{t2} = 0, \quad v_{t1} = 1$$

$$S'[\psi_k] = \frac{1}{2} \int_k \left(k^2 + r + \frac{\mu}{2} I_1 \right) |\psi_k(\vec{R})|^2 + \left[\frac{\mu}{4!} - 36 \left(\frac{\mu}{4!} \right)^2 I_2 \right] \int_{k_1, \dots, k_n} (\dots)^d \delta(E_1 + \dots + E_n) \psi_k(E_1) \dots$$

$\vec{R}' = \vec{R} b$ $\leftarrow \eta = 0$
 $\psi'(\vec{R}') = b^{-\frac{d+2}{2}} \psi_k(\vec{R})$

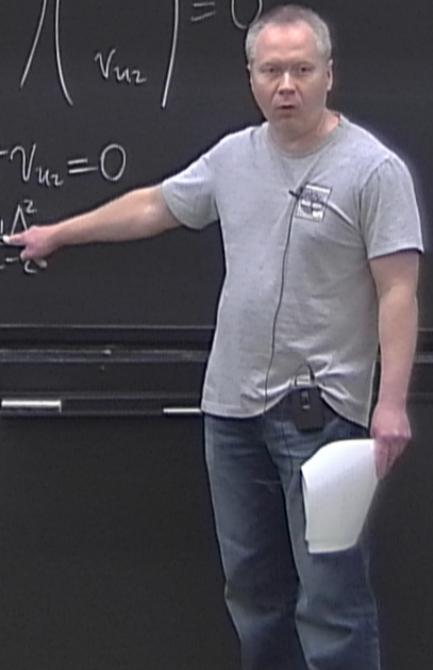
$$\begin{pmatrix} \lambda_2 \\ \lambda_t \end{pmatrix} \begin{pmatrix} v_{t1} \\ v_{t2} \end{pmatrix} = 0$$

$v_{t2} = 0, v_{t1} = 1$

$$\begin{pmatrix} 2-\xi & \frac{1}{2} K_d \Lambda^2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

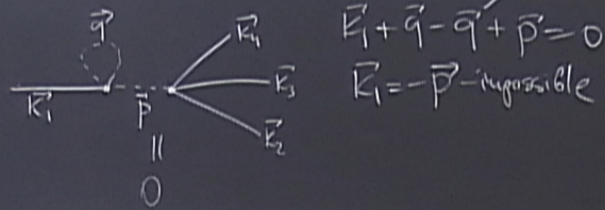
$$(2-\xi)v_{u1} + \frac{1}{2} K_d \Lambda^2 v_{u2} = 0$$

$$\frac{v_{u1}}{v_{u2}} = -\frac{1}{2} \frac{K_d \Lambda^2}{2-\xi}$$



Contribution of the second cumulant to RG equations:

$$\frac{1}{2} [\langle S_{int}^2 \rangle_0 - \langle S_{int} \rangle^2] = 36 \text{ (diagram)} + 48 \text{ (diagram)}$$



Linearize the RG flow equations near the Gaussian fixed point $r^* = u^* = 0$

$$\delta r = r - r^*, \quad \delta u = u - u^*$$

$$\frac{d\delta r}{d\ell} = \dots + \frac{\delta u}{2} K_d \Lambda^2$$

$$\frac{d}{d\ell} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$\lambda_r = 2, \quad \lambda_u = \epsilon$$

$$\vec{v}_u = \begin{pmatrix} -\frac{\Lambda^2}{32\epsilon} \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & \frac{1}{2} K_d \Lambda^2 \\ 0 & \epsilon - \lambda_r \end{pmatrix} \begin{pmatrix} v_{r1} \\ v_{r2} \end{pmatrix} = 0$$

$$\frac{1}{2} K_d \Lambda^2 v_{r2} = 0 \Rightarrow v_{r2} = 0, \quad v_{r1} = 1$$

$$\vec{v}_r = (1, 0)$$

$$S'[\psi_c] = \frac{1}{2} \int_K \left(k^2 + r + \frac{\eta}{2} I_1 \right) |\psi_c(\mathbf{R})|^2 + \left[\frac{\eta}{4!} - 36 \left(\frac{\eta}{4!} \right)^2 I_2 \right] \int_{k_1 \dots k_n} (\pi)^d \delta(\mathbf{R}_1 + \dots + \mathbf{R}_n) \psi_c(\mathbf{R}_1) \dots \psi_c(\mathbf{R}_n)$$

$$\vec{k}' = \vec{k} b$$

$$\psi'(\mathbf{R}') = b^{-\frac{d+2}{2}} \psi_c(\mathbf{R}) \quad \leftarrow \eta = 0$$

$$\begin{pmatrix} 2-\xi & \frac{1}{2} K_d \Lambda^2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

$$(2-\xi)v_{u1} + \frac{1}{2} K_d \Lambda^2 v_{u2} = 0$$

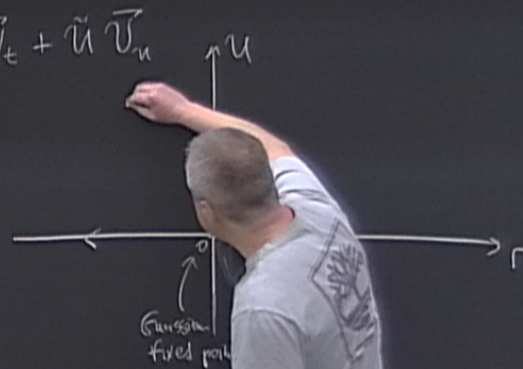
$$\frac{v_{u1}}{v_{u2}} = -\frac{1}{2} \frac{K_d \Lambda^2}{2-\xi}$$

$$(\delta r, \delta u) = t \vec{v}_t + \tilde{u} \vec{v}_u$$

$$\frac{dt}{dl} = \lambda t$$

$$\frac{d\tilde{u}}{dl} = \lambda_{\tilde{u}} \tilde{u}$$

$$\xi = 4-d$$



$$S'[\psi_c] = \frac{1}{2} \int_k (k^2 + r + \frac{\eta}{2} I_1) |\psi_c(\mathbf{R})|^2 + \left[\frac{\eta}{4!} - 36 \left(\frac{\eta}{4!} \right)^2 I_2 \right] \int_{k_1 \dots k_n} (\frac{\eta}{4!})^d \delta(\mathbf{R}_1 + \dots + \mathbf{R}_n) \psi_c(\mathbf{R}_1) \dots \psi_c(\mathbf{R}_n)$$

$$\vec{k}' = \vec{k} \beta \quad \leftarrow \eta = 0$$

$$\psi'(\mathbf{R}') = \beta^{-\frac{d+2}{2}} \psi_c(\mathbf{R})$$

$$\begin{pmatrix} 2-\xi & \frac{1}{2} K_d \Lambda^2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

$$(2-\xi)v_{u1} + \frac{1}{2} K_d \Lambda^2 v_{u2} = 0$$

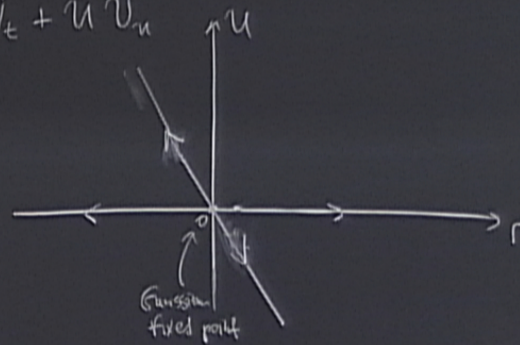
$$\frac{v_{u1}}{v_{u2}} = -\frac{1}{2} \frac{K_d \Lambda^2}{2-\xi}$$

$$(\delta r, \delta u) = t \vec{v}_t + \tilde{u} \vec{v}_u$$

$$\frac{dt}{dl} = \lambda t$$

$$\frac{d\tilde{u}}{dl} = \lambda_{\tilde{u}} \tilde{u}$$

$$\xi = 4-d$$



$$S[\psi_c] = \frac{1}{2} \int_k (k^2 + r + \frac{\eta}{2} I_1) |\psi_c(\mathbf{R})|^2 + \left[\frac{\eta}{4!} - 36 \left(\frac{\eta}{4!} \right)^2 I_2 \right] \int_{k_1, \dots, k_n} (\frac{\eta}{4!})^d \delta(\mathbf{R}_1 + \dots + \mathbf{R}_n) \psi_c(\mathbf{R}_1) \dots \psi_c(\mathbf{R}_n)$$

$$\vec{k}' = \vec{k} b$$

$$\psi'(\mathbf{R}') = b^{-\frac{d+2}{2}} \psi_c(\mathbf{R})$$

$\leftarrow \eta = 0$

$$\begin{pmatrix} 2-\xi & \frac{1}{2} K_d \Lambda^2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

$$(2-\xi)v_{u1} + \frac{1}{2} K_d \Lambda^2 v_{u2} = 0$$

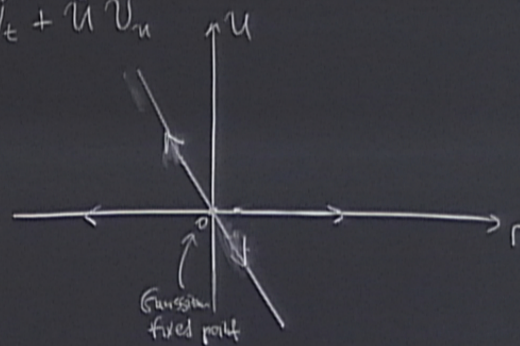
$$\frac{v_{u1}}{v_{u2}} = -\frac{1}{2} \frac{K_d \Lambda^2}{2-\xi}$$

$$(\delta r, \delta u) = t \vec{v}_t + \tilde{u} \vec{v}_u$$

$$\frac{dt}{dl} = \lambda + t$$

$$\frac{d\tilde{u}}{dl} = \lambda_u \tilde{u}$$

$$\xi = 4-d$$



$$S[\psi_c] = \frac{1}{2} \int_K (k^2 + r + \frac{\eta}{2} I_1) |\psi_c(\mathbf{R})|^2 + \left[\frac{\eta}{4!} - 36 \left(\frac{\eta}{4!} \right)^2 I_2 \right] \int_{k_1 \dots k_n} (\frac{\eta}{4!})^d \delta(\mathbf{R}_1 + \dots + \mathbf{R}_4) \psi_c(\mathbf{R}_1) \dots \psi_c(\mathbf{R}_4)$$

$$\vec{k}' = \vec{k} \beta \quad \leftarrow \eta = 0$$

$$\psi'(\mathbf{R}') = \beta^{-\frac{d+2}{2}} \psi_c(\mathbf{R})$$

$$\begin{pmatrix} 2-\xi & \frac{1}{2} K_d \Lambda^2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

$$(2-\xi)v_{u1} + \frac{1}{2} K_d \Lambda^2 v_{u2} = 0$$

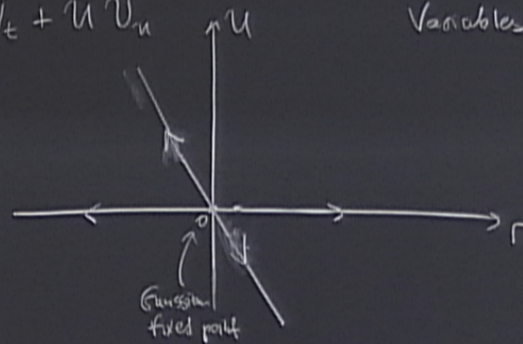
$$\frac{v_{u1}}{v_{u2}} = -\frac{1}{2} \frac{K_d \Lambda^2}{2-\xi}$$

$$(\delta r, \delta u) = t \vec{v}_t + \tilde{u} \vec{v}_u$$

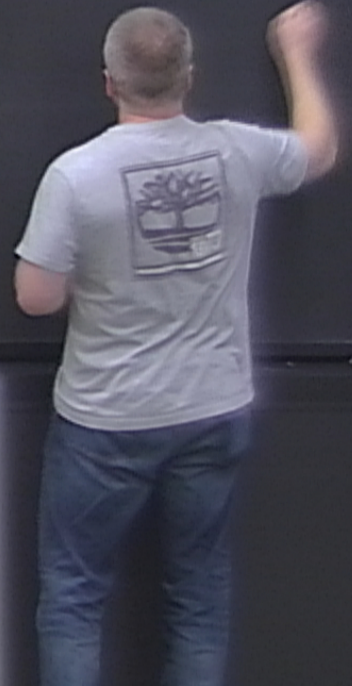
$$\frac{dt}{dl} = \lambda t$$

$$\frac{d\tilde{u}}{dl} = \lambda_{\tilde{u}} \tilde{u}$$

$$\xi = 4-d$$



Variables for which small deviations from



$(y_1, \dots, y_n) = (y_1, \dots, y_n)$
 $(k_1, \dots, k_n) \psi_c(k_1) \dots \psi_c(k_n)$

$\begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$

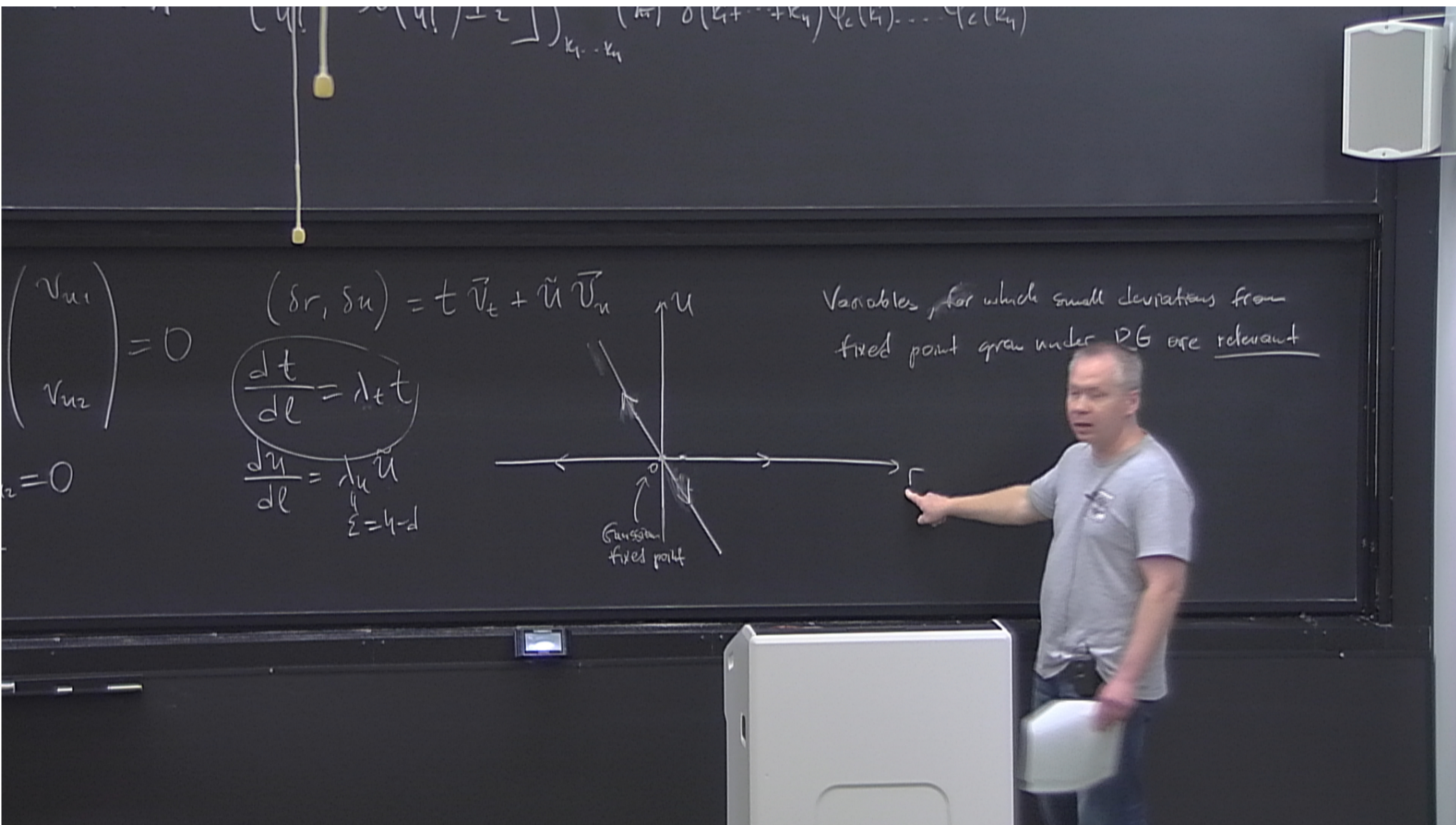
$(\delta r, \delta u) = t \vec{V}_t + \tilde{u} \vec{V}_u$

$\frac{dt}{dl} = \lambda + t$

$\frac{du}{dl} = \lambda u \tilde{u}$
 $\Sigma = 4 - d$

$z = 0$

Variables, for which small deviations from fixed point grow under RG relevant



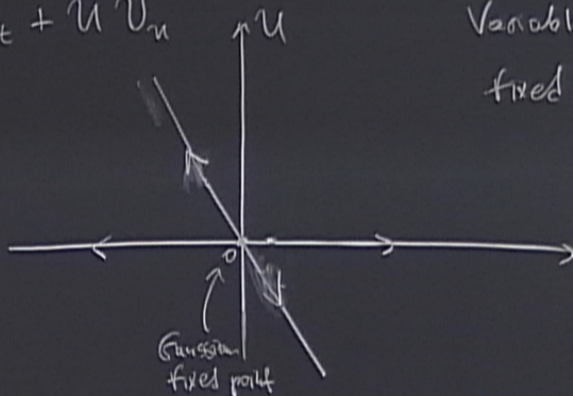
$$\begin{pmatrix} v_{u1} \\ v_{u2} \end{pmatrix} = 0$$

$$(\delta r, \delta u) = t \vec{V}_t + \tilde{u} \vec{V}_u$$

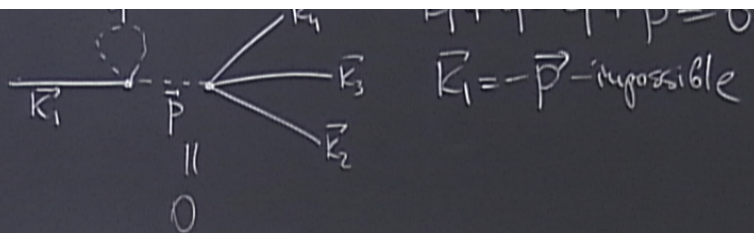
$$\frac{dt}{dl} = \lambda_t t$$

$$\frac{du}{dl} = \lambda_u \tilde{u}$$

$\lambda_u = 4-d$



Variables, for which small deviations from fixed point grow under RG are relevant

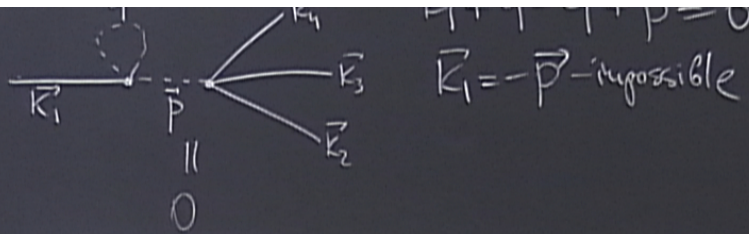


RG flows near the Wilson-Fisher fixed point

beta-function:

d



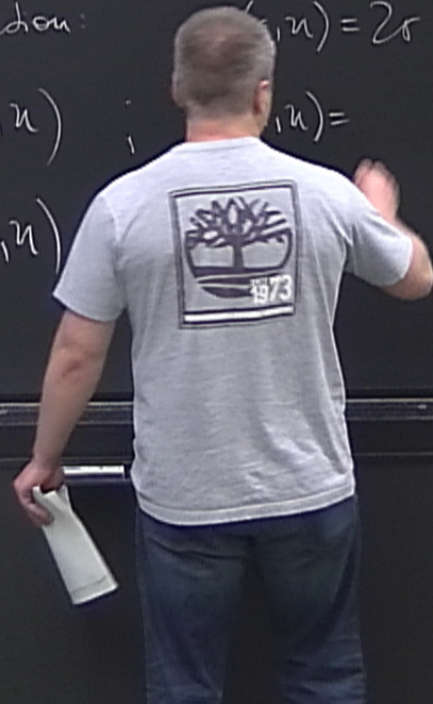


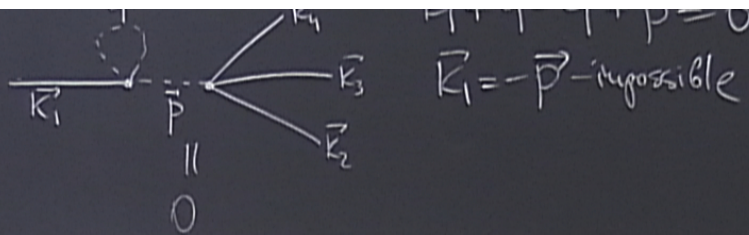
RG flows near the Wilson-Fisher fixed point

Beta-function: $\beta(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + K^2}$

$\frac{dr}{dl} = \beta_r(r, u)$; $\beta_u(r, u) =$

$\frac{du}{dl} = \beta_u(r, u)$



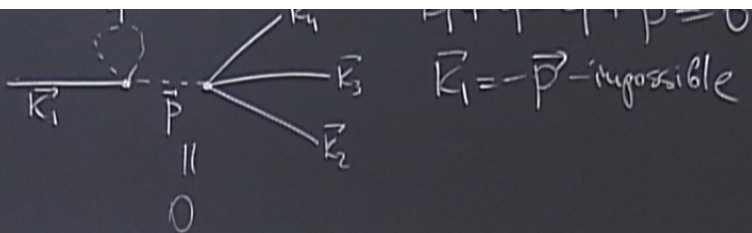


RG flows near the Wilson-Fisher fixed point

beta-function: $\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$

$\frac{dr}{dl} = \beta_r(r, u)$; $\beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$

$\frac{du}{dl} = \beta_u(r, u)$



RG flows near the Wilson-Fisher fixed point

Beta-function:

$$\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$$

$$\frac{dr}{dl} = \beta_r(r, u) ; \quad \beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$$

$$\frac{du}{dl} = \beta_u(r, u)$$

$$r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$u^* = \frac{16\pi^2}{3} \varepsilon$$

- WF fixed point

$$\frac{d}{dl} \left(\frac{dr}{r} \right)$$



$K_1 = -\bar{p}$ - impossible

Wilson-Fisher fixed point

$$\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$$

$$\beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$$

$$r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$u^* = \frac{16\pi^2}{3} \varepsilon$$

- WF fixed point

$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} \partial \beta_r \\ \partial \beta_u \end{pmatrix}$$



$K_1 = -\bar{p}$ - impossible

Nelson-Fisher fixed point

$$\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$$

$$\beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$$

$$r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$u^* = \frac{16\pi^2}{3} \varepsilon$$

- WF fixed point

$$\frac{d}{dt} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} \frac{\partial \beta_r}{\partial r} & \frac{\partial \beta_r}{\partial u} \\ \frac{\partial \beta_u}{\partial r} & \frac{\partial \beta_u}{\partial u} \end{pmatrix}_{r^*, u^*} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$K_1 = -\bar{p}$ - impossible

Nelson-Fisher fixed point

$$\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$$

$$\beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$$

$$r^* = -\frac{\varepsilon}{6} \Lambda^2 \quad \text{WF fixed point}$$

$$u^* = \frac{16\pi^2}{3} \varepsilon$$

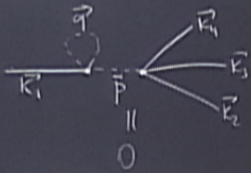
$$\left. \frac{\partial \beta_r}{\partial r} \right|_{r^*, u^*} = 2 - \frac{u^*}{2} \frac{K_d}{\Lambda^4} = 2 - \frac{\varepsilon}{3}$$

$$\frac{d}{dt} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} \frac{\partial \beta_r}{\partial r} & \frac{\partial \beta_r}{\partial u} \\ \frac{\partial \beta_u}{\partial r} & \frac{\partial \beta_u}{\partial u} \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$\left. \frac{\partial \beta_u}{\partial u} \right|_{r^*, u^*} = \frac{1}{2} \frac{K_d}{\Lambda^2} = \frac{\Lambda^2}{16\pi^2}$$

Contribution of the second cumulant to RG equations.

$$\frac{1}{2} \left[\langle S_{int}^2 \rangle_0 - \langle S_{int} \rangle^2 \right] = 36 \left[\text{diagram} \right] + 48 \left[\text{diagram} \right]$$



$$K_1 + q - q + p = 0$$

$$K_1 = -p \text{ - impossible}$$

RG flows near the Wilson-Fisher fixed point

Beta-function:

$$\frac{dr}{dl} = \beta_r(r, u)$$

$$\frac{du}{dl} = \beta_u(r, u)$$

$$\beta_r(r, u) = 2r + \frac{u}{2} \frac{K_d}{r + \Lambda^2}$$

$$\beta_u(r, u) = \varepsilon u - \frac{3u^2}{2} \frac{K_d}{(r + \Lambda^2)^2}$$

$$r^* = -\frac{\varepsilon}{2} \Lambda^2$$

$$u^* = \frac{16r^2}{3} \varepsilon$$

- WF fixed point

$$\left. \frac{\partial \beta_r}{\partial r} \right|_{r^*, u^*} = 2 - \frac{u^*}{2} \frac{K_d}{\Lambda^4} = 2 - \frac{\varepsilon}{3}$$

$$\frac{d}{dl} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix} = \begin{pmatrix} \frac{\partial \beta_r}{\partial r} & \frac{\partial \beta_r}{\partial u} \\ \frac{\partial \beta_u}{\partial r} & \frac{\partial \beta_u}{\partial u} \end{pmatrix} \begin{pmatrix} \delta r \\ \delta u \end{pmatrix}$$

$$K_d = \frac{\Lambda^2}{16r^2}$$

$$\begin{cases} r' = (r + \frac{u}{2} I) \ell^2 \\ u' = (u - \frac{3}{2} u^2 \frac{I}{\Lambda^2}) \ell^{4-d} \end{cases} \Rightarrow \begin{cases} \frac{dr}{d\ell} \\ \frac{du}{d\ell} \end{cases}$$

$$\frac{dr}{d\ell} = \frac{du}{d\ell} = 0 \Rightarrow u^* = \varepsilon \frac{2}{3} \frac{(\Lambda^2)^2}{S_4}$$

$$\left. \frac{\partial \beta_u}{\partial r} \right|_{r^*, u^*} =$$

$$\frac{d\beta}{dl} = \frac{d\alpha}{dl} = 0 \quad ; \quad u^* = \varepsilon \frac{c}{3} \frac{(m)}{S_y} \quad ; \quad S_y = \frac{d\alpha}{\Gamma(z)} = 2u^2 \quad ; \quad u^* = \frac{10\pi \varepsilon}{3}$$

$$\left. \frac{\partial \beta_u}{\partial r} \right|_{r^*, u^*} = 3u^{*2} \frac{K_d}{(r^* + \Lambda^2)^2} = O(\varepsilon^2) \rightarrow 0$$

$$\left. \frac{\partial \beta_u}{\partial u} \right|_{r^*, u^*} = \varepsilon - 3u^* \frac{K_d}{(r^* + \Lambda^2)^2} =$$

$$\frac{dL}{dL} = \frac{dL}{dL} = 0 \quad ; \quad U^* = \varepsilon \frac{2}{3} \frac{(m)}{S_y} \quad ; \quad S_y = \frac{m}{\Gamma(z)} = 2u^2 \quad ; \quad U^* = \frac{10\pi \varepsilon}{3}$$

$$\left. \frac{\partial \beta u}{\partial r} \right|_{r^*, u^*} = 3u^{*2} \frac{K_d}{(r^* + \Lambda^2)^2} = O(\varepsilon^2) \rightarrow 0$$

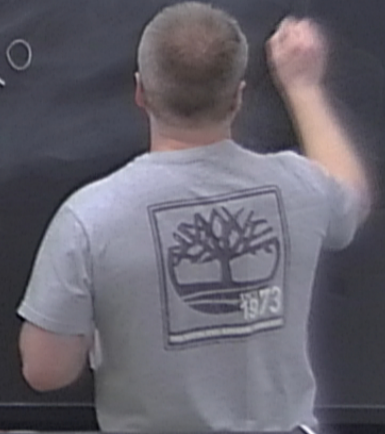
$$\left. \frac{\partial \beta u}{\partial u} \right|_{r^*, u^*} = \varepsilon - 3u^* \frac{K_d}{(r^* + \Lambda^2)^2} = \varepsilon - 3u^* \frac{K_y}{\Lambda^4} = \varepsilon - 3 \frac{16\pi^2 \varepsilon}{3} \frac{1}{8\pi^2} = \varepsilon - 2\varepsilon = -\varepsilon$$

$$\frac{dL}{d\ell} = \frac{du}{d\ell} = 0 \quad ; \quad u^* = \varepsilon \frac{2}{3} \frac{(2\pi)^4}{S_4} \quad ; \quad S_{u^*} = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 \quad ; \quad u^* = \frac{16\pi^2 \varepsilon}{3} \quad ; \quad r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$\left. \frac{\partial u}{\partial r} \right|_{r^*, u^*} = 3u^{*2} \frac{K_d}{(r^* + \Lambda^2)^2} = O(\varepsilon^2) \rightarrow 0$$

$$\left. \frac{\partial u}{\partial u} \right|_{r^*, u^*} = \varepsilon - 3u^* \frac{K_d}{(r^* + \Lambda^2)^2} = \varepsilon - 3u^* \frac{K_d}{\Lambda^4} = \varepsilon - 3 \frac{16\pi^2 \varepsilon}{3} \frac{1}{8\pi^2} = \varepsilon - 2\varepsilon = -\varepsilon$$

$$M = \begin{pmatrix} 2 - \frac{\varepsilon}{2} & \frac{\Lambda^2}{16\pi^2} \\ 0 & \end{pmatrix}$$



$$U^* = \epsilon \frac{2}{3} \frac{(2\pi)^4}{S_4} ; S_4 = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 ; U^* = \frac{16\pi^2 \epsilon}{3} ; r^* = -\frac{\epsilon}{6} \Lambda^2$$

$$\frac{K_d}{(r^* + \Lambda^2)^2} = O(\epsilon^2) \rightarrow 0$$

$$3U^* \frac{K_d}{(r^* + \Lambda^2)^2} = \epsilon - 3U^* \frac{K_4}{\Lambda^4} = \epsilon - 3 \frac{16\pi^2 \epsilon}{3} \frac{1}{8\pi^2} = \epsilon - 2\epsilon = -\epsilon$$

$$M = \begin{pmatrix} 2 - \frac{\epsilon}{2} & \frac{\Lambda^2}{16\pi^2} \\ 0 & -\epsilon \end{pmatrix}$$



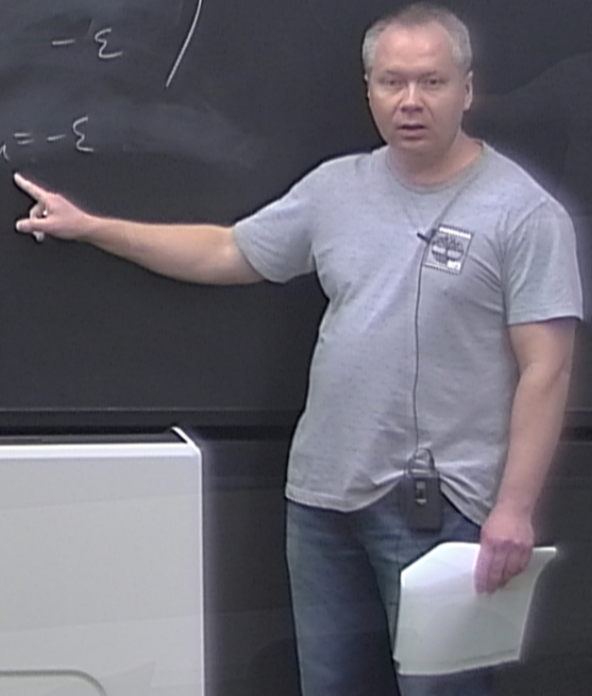
$$U^* = \varepsilon \frac{2}{3} \frac{(2\pi)^4}{S_4} ; S_4 = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 ; U^* = \frac{16\pi^2 \varepsilon}{3} ; r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$\frac{K_d}{(r^* + \Lambda^2)^2} = O(\varepsilon^2) \rightarrow 0$$

$$3U^* \frac{K_d}{(r^* + \Lambda^2)^2} = \varepsilon - 3U^* \frac{K_4}{\Lambda^4} = \varepsilon - 3 \frac{16\pi^2 \varepsilon}{3} \frac{1}{8\pi^2} = \varepsilon - 2\varepsilon = -\varepsilon$$

$$M = \begin{pmatrix} 2 - \frac{\varepsilon}{3} & \frac{\Lambda^2}{16\pi^2} \\ 0 & -\varepsilon \end{pmatrix}$$

$$\lambda_+ = 2 - \frac{\varepsilon}{3} ; \lambda_- = -\varepsilon$$



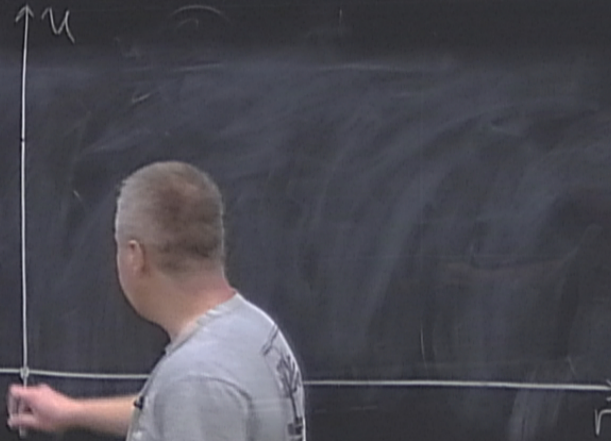
$$\vec{v}_t = (1, 0), \quad \vec{v}_u = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$

$$\left(\frac{dr}{dl} = 2r + \frac{4}{2} \left(\frac{S_d}{(2\pi)^d} \right) \frac{\Lambda^d}{r + \Lambda^2} \right. \rightarrow K_d \text{ - one-loop RG equations}$$

$$\left. \frac{du}{dl} = \underbrace{(4-d)}_{\varepsilon} u - \frac{3u^2}{2} \left(\frac{S_d}{(2\pi)^d} \right) \frac{\Lambda^d}{(r + \Lambda^2)^2} \right. \quad r \sim T$$

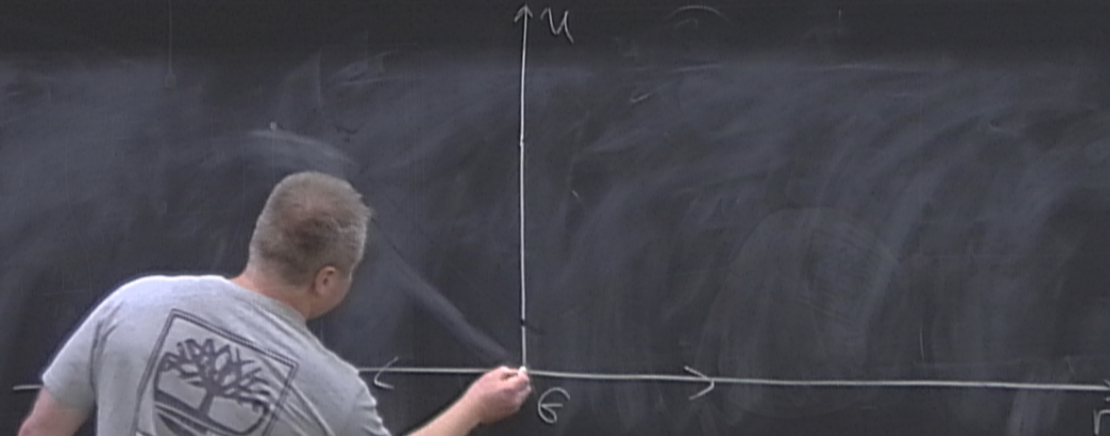
$$\frac{(2\pi)^d}{S_d} ; S_d = \frac{2\pi^2}{\Gamma(2)} = 2\pi^2 ; u^* = \frac{16\pi^2 \varepsilon}{3} ; r^* = -\frac{\varepsilon}{6} \Lambda^2$$

$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$



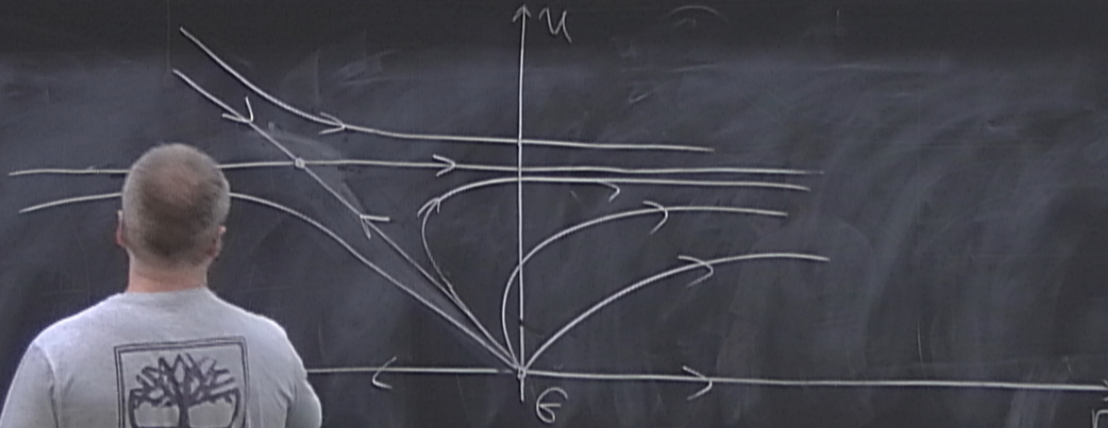
$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$

$d < 4$



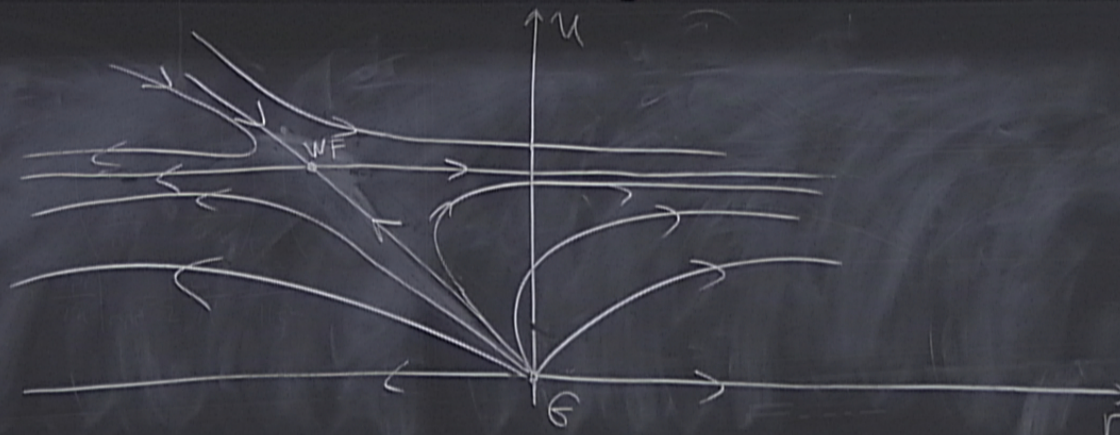
$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$

$d < 4$



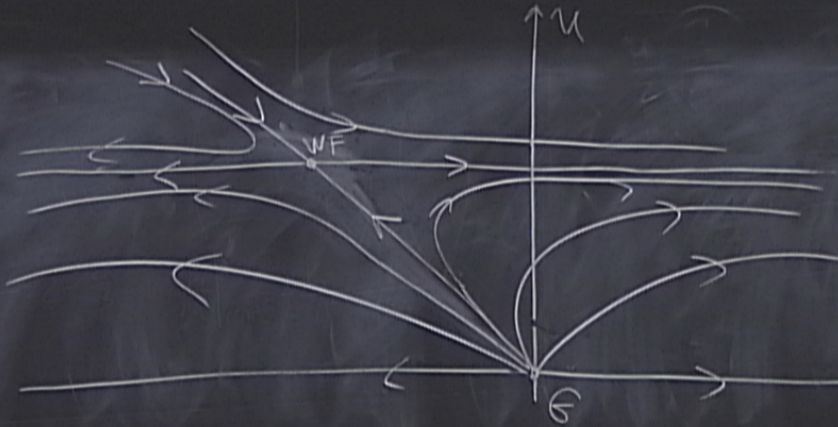
$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$

$d < 4$



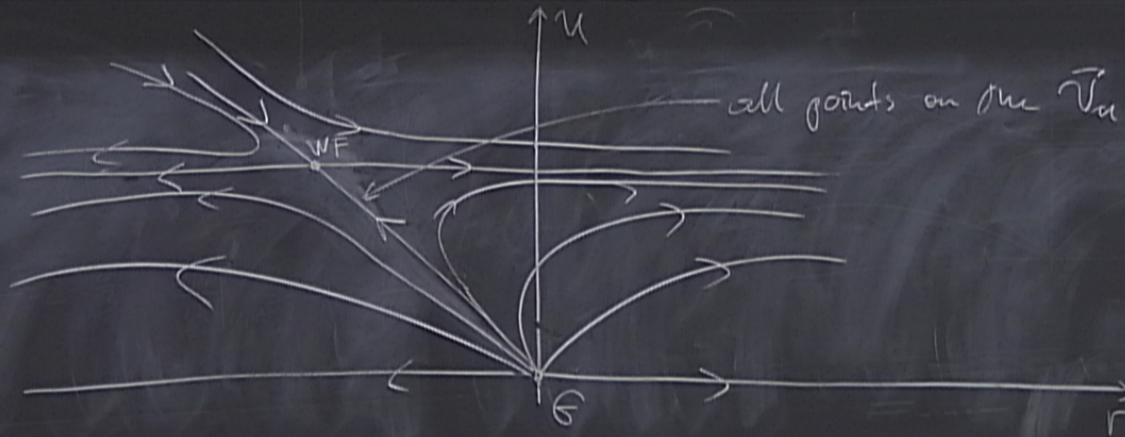
$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\eta^2}, 1 \right)$$

dc 4

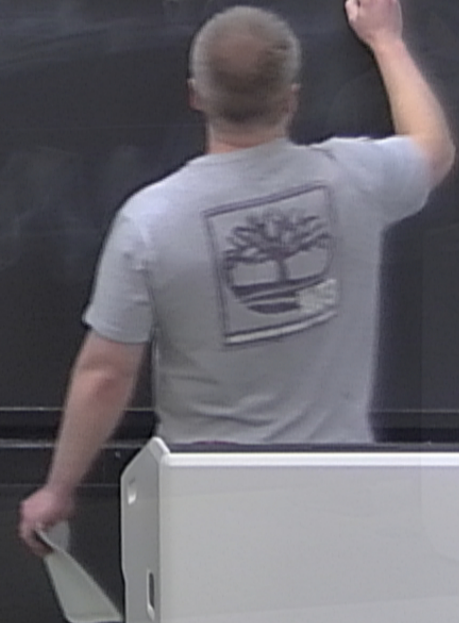


$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32\eta^2}, 1\right)$$

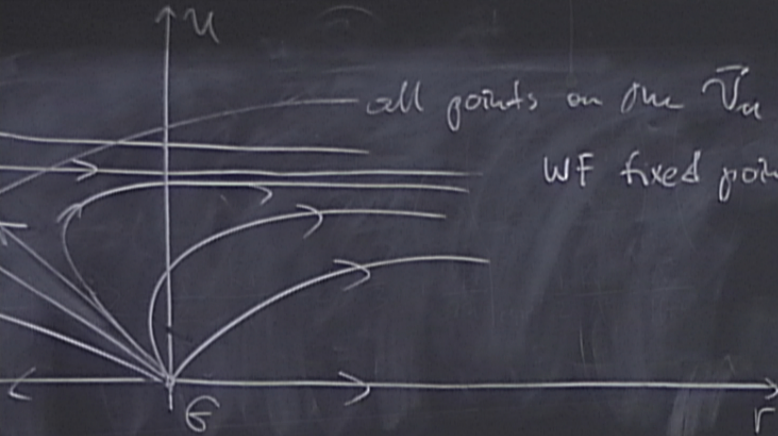
dc 4



all points on the \vec{v}_n line are critical



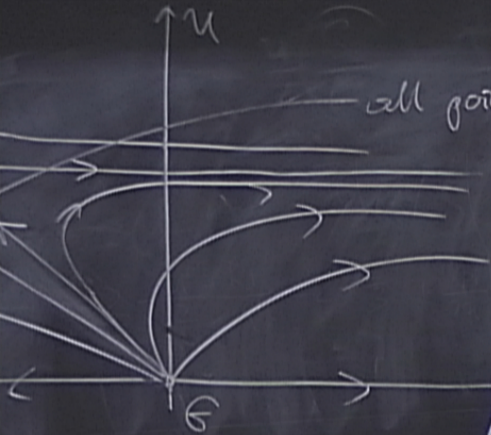
$$\vec{V}_t = (1, 0), \quad \vec{V}_u = \left(-\frac{\Lambda^2}{32u^2}, 1 \right)$$



all points on the \vec{V}_u line are critical points.

WF fixed point describes FM - PM transitions in the Ising model

$$\vec{v}_t = (1, 0), \quad \vec{v}_n = \left(-\frac{\Lambda^2}{32v^2}, 1 \right)$$

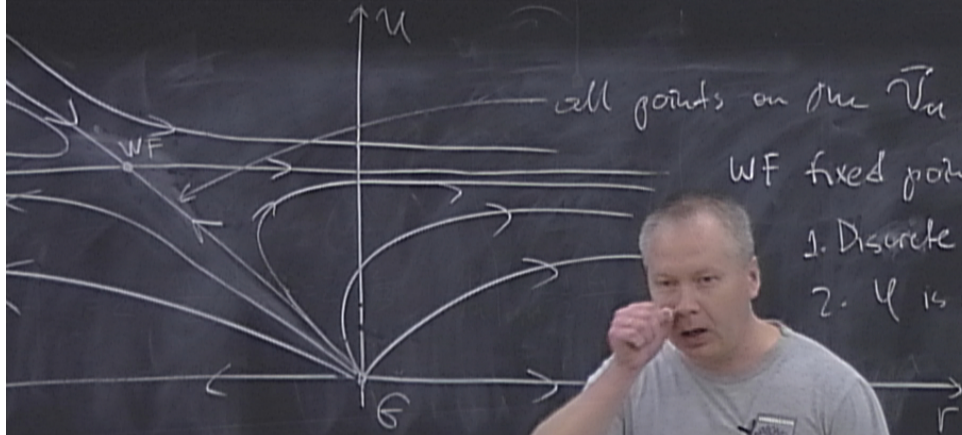


all points on the \vec{v}_n line are critical points.

WF fixed point describes FM-PM transitions in the Ising universality class



$$\vec{V}_t = (1, 0), \quad \vec{V}_n = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$

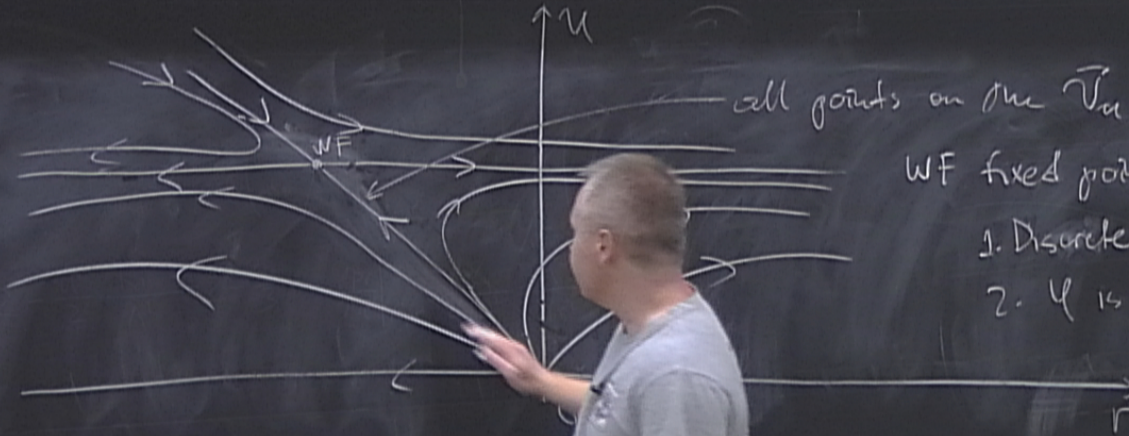


all points on the \vec{V}_n line are critical points.

WF fixed point describes FM-PM transitions in the Ising universality class

1. Discrete $\psi \rightarrow -\psi$ symmetry
2. ψ is a real scalar field

$$\vec{V}_t = (1, 0), \quad \vec{V}_u = \left(-\frac{\Lambda^2}{32\pi^2}, 1 \right)$$



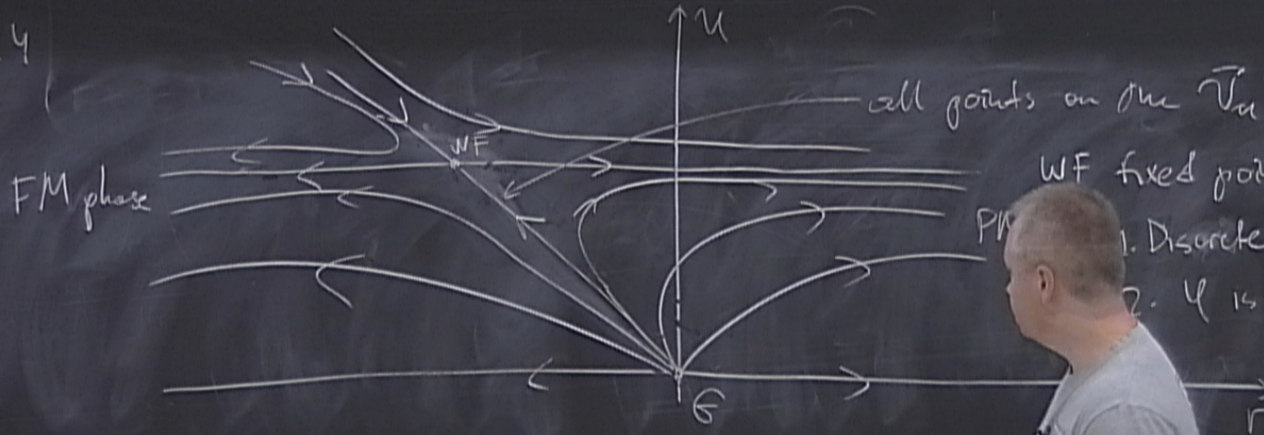
all points on the \vec{V}_u line are critical points.

WF fixed point describes FM - PM transitions in the Ising

1. Discrete $\phi \rightarrow -\phi$ symmetry
2. ϕ is a real scalar field

$$\vec{V}_t = (1, 0), \quad \vec{V}_u = \left(-\frac{\Lambda^2}{32u^2}, 1 \right)$$

dc ψ



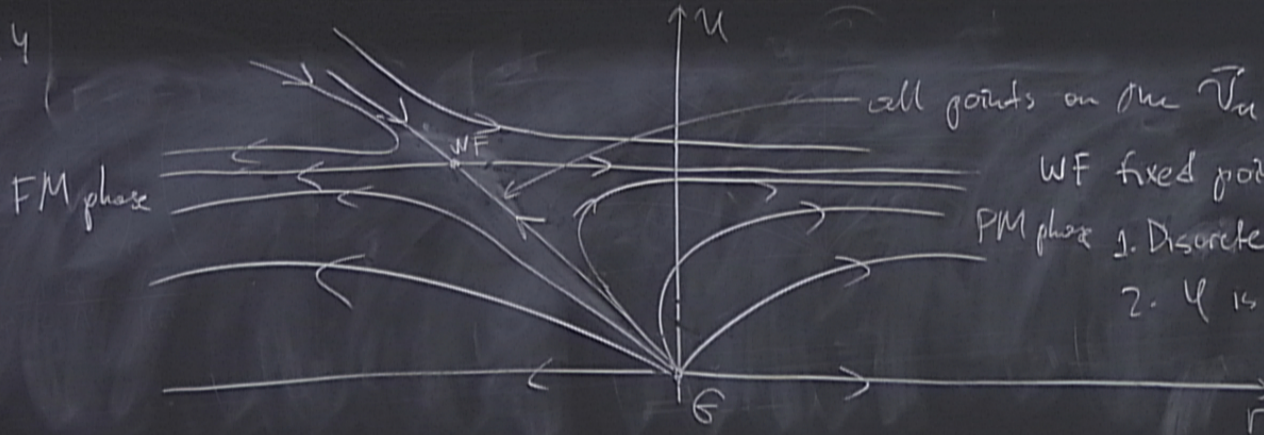
all points on the \vec{V}_u line are critical points.

WF fixed point describes FM-PM transitions in

1. Discrete $\psi \rightarrow -\psi$ symmetry
2. ψ is a real scalar field

$$\vec{V}_t = (1, 0), \quad \vec{V}_n = \left(-\frac{\Lambda^2}{32\mu^2}, 1 \right)$$

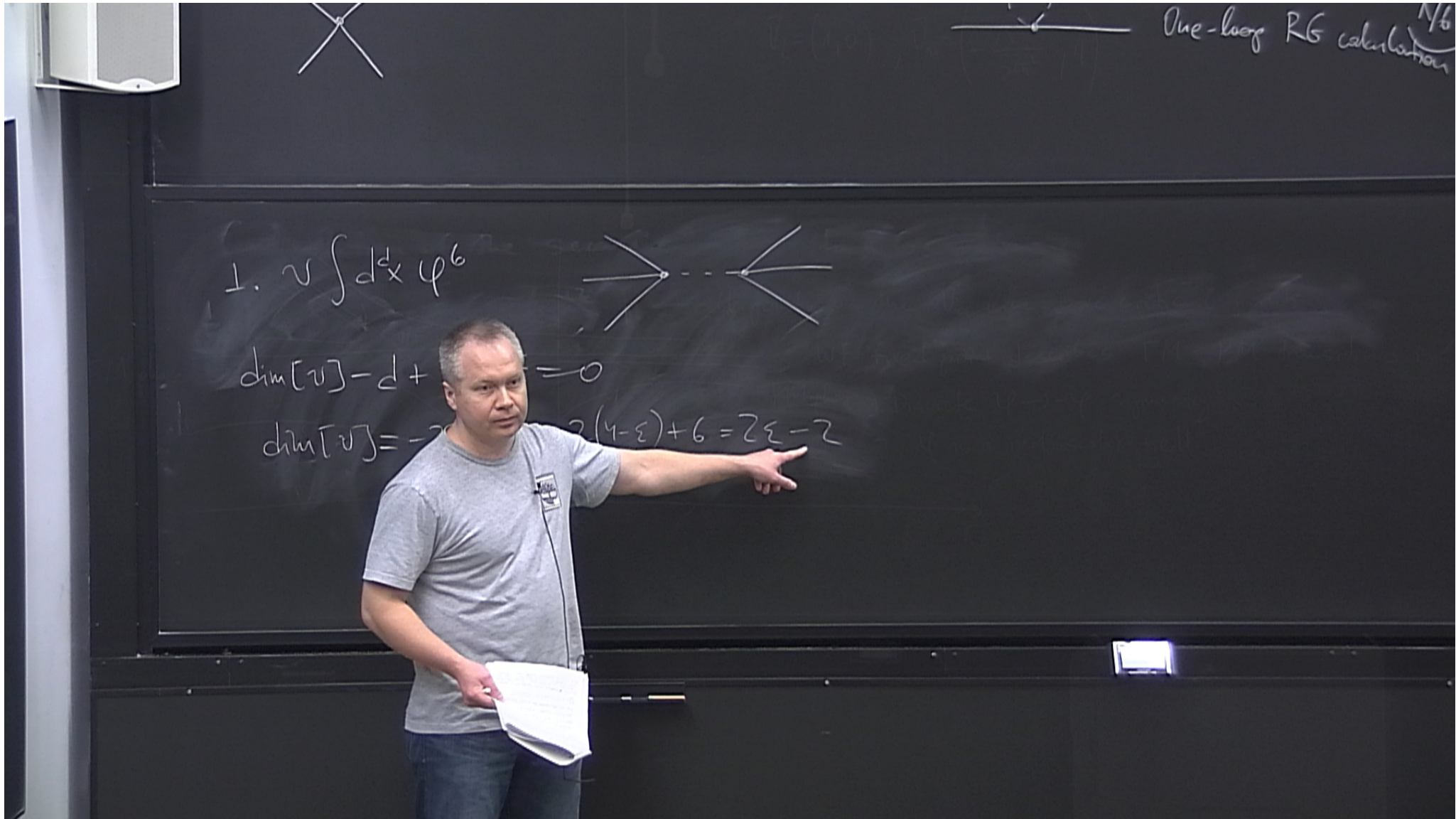
dc ψ

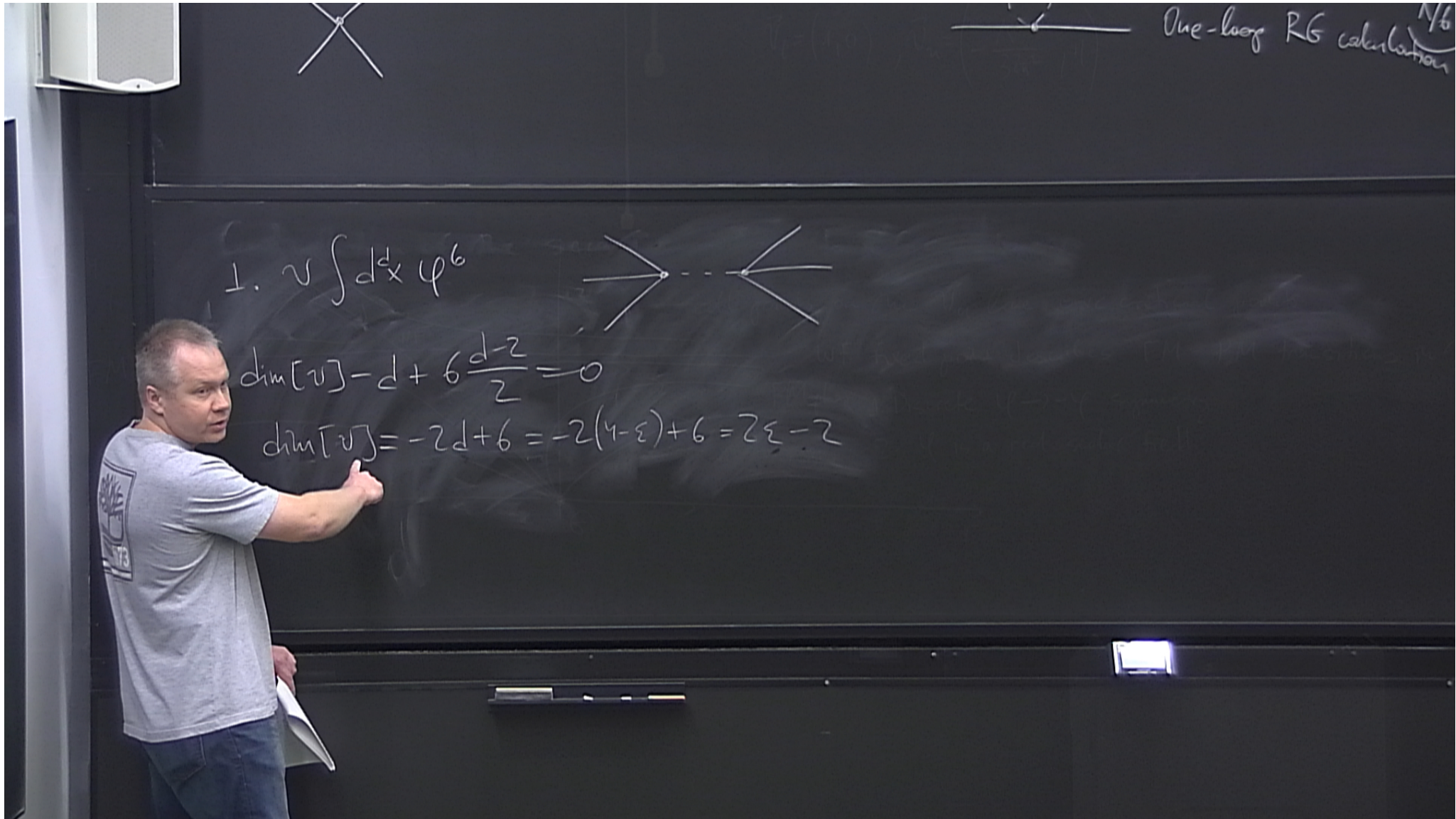


all points on the \vec{V}_n line are critical points.

WF fixed point describes FM-PM transitions in

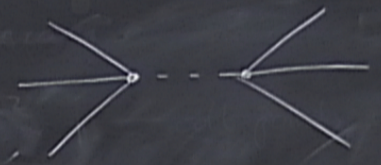
- PM phase
1. Discrete $\psi \rightarrow -\psi$ symmetry
 2. ψ is a real scalar field





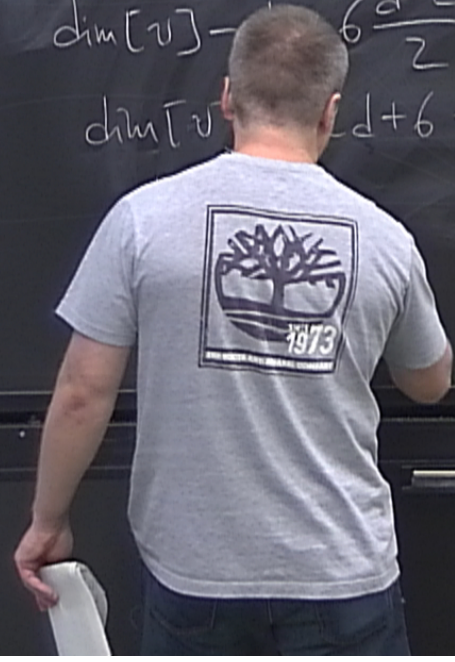
One-loop RG calculation ^{N/b}

1. $\int d^d x \varphi^6$



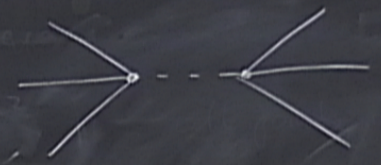
$$\dim[v] = 6 \frac{d-2}{2} = 0$$

$$\dim[v] = d+6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$



One-loop RG calculation ^{N/b}

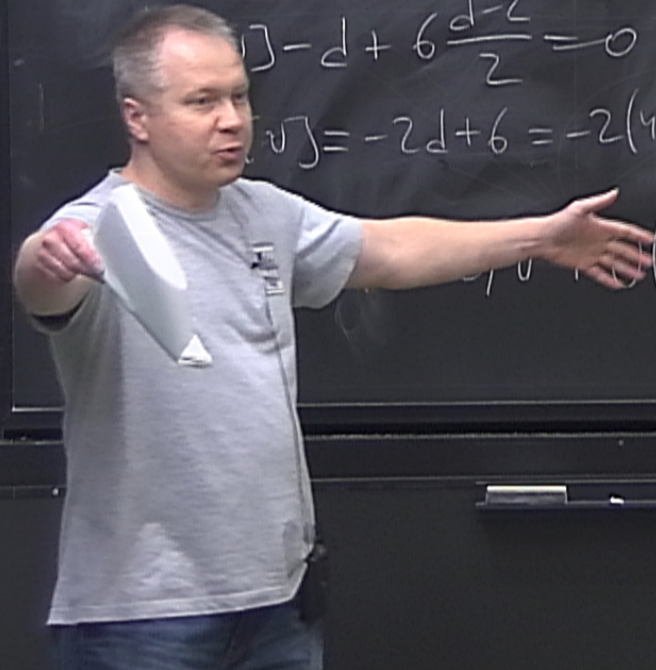
1. $\int d^d x \varphi^6$



$$[d] - d + 6 \frac{d-2}{2} = 0$$

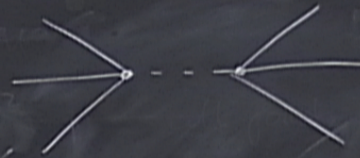
$$[u] = -2d + 6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$

$$[v] = 2 - 2\epsilon$$



One-loop RG calculation ^{N/b}

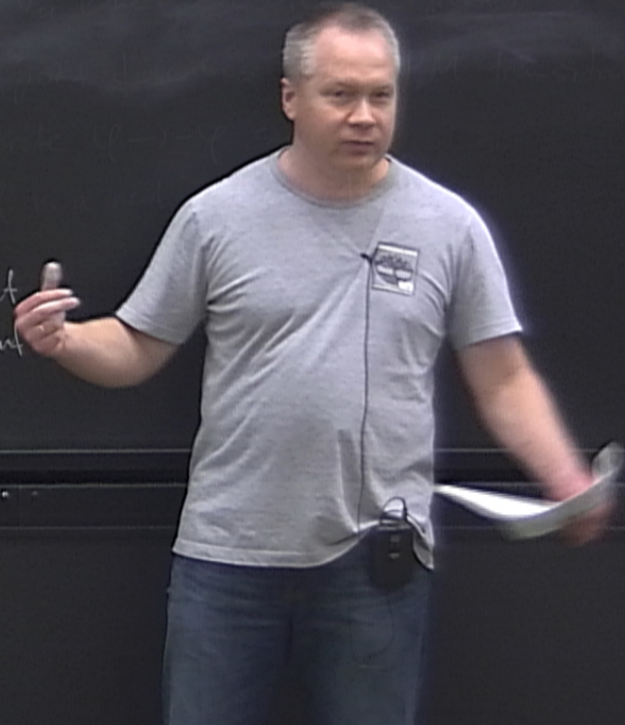
1. $v \int d^d x \phi^6$



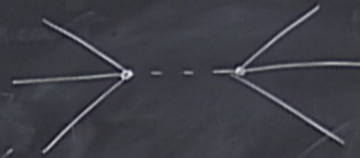
$$\dim[v] - d + 6 \frac{d-2}{2} = 0$$

$$\dim[v] = -2d + 6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$

$$\frac{dv}{d\ell} = (2\epsilon - 2)v + O(v^2, v^2) ; \quad v \text{ is irrelevant at WF fixed point}$$



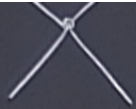
1. $v \int d^d x \phi^6$



$$\dim[v] - d + 6 \frac{d-2}{2} = 0$$

$$\dim[v] = -2d + 6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$

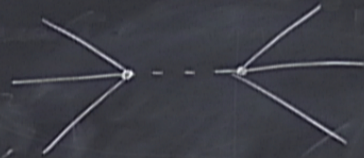
$$\frac{dv}{d\ell} = (2\epsilon - 2)v + O(v^2, v^2) ; \quad \begin{array}{l} v \text{ is irrelevant at} \\ \text{WF fixed point} \end{array}$$



One-loop RG calculation ^{N/b}

I_2

$$1. \nu \int d^d x \varphi^6$$



$$\dim[\nu] - d + 6 \frac{d-2}{2} = 0$$

$$\dim[\nu] = -2d + 6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$

$$\frac{d\nu}{d\ell} = (2\epsilon - 2)\nu + O(\nu^2, \nu^2) \quad \nu \text{ is irrelevant at WF fixed point}$$



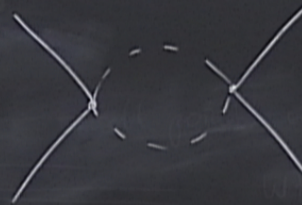
One-loop RG calculation $N/6$
 I_2



$$1 + 6 \frac{d-2}{2} = 0$$

$$-2d + 6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$

$(2\epsilon - 2)U + O(u^2, v^2)$ | U is irrelevant at WF fixed point



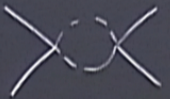
$$I_2 = \int_{N/6}^{\Lambda} \frac{d^d q}{(2\pi)^d} G_0(\vec{q})$$



$$E_1 + E_2 + \bar{q}_1 + \bar{q}_2 = 0$$

$$E_3 + E_4 - \bar{q}_1 - \bar{q}_2 = 0 \Rightarrow E_1 + E_2 + E_3 + E_4 = 0$$


let $\bar{q}_1 = \bar{q}$, $\bar{q}_2 = -E_1 - E_2 - \bar{q}$



$$= \left(\frac{u}{u_1}\right)^2 \int_{k_1, k_4} (2\pi)^d \delta(E_1 + E_2 + E_3 + E_4) \psi_c(E_1) \psi_c(E_2) \psi_c(E_3) \psi_c(E_4)$$

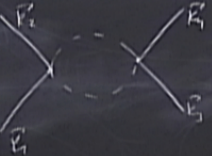
$$\int \frac{d^d q}{(2\pi)^d} G_0(\bar{q}) G_0(-E_1 - E_2 - \bar{q})$$

One-loop RG calculation $\int \frac{d^d q}{(2\pi)^d} G_0(\bar{q}) G_0(-E_1 - E_2 - \bar{q})$



$$\frac{d-2}{2} = 0$$

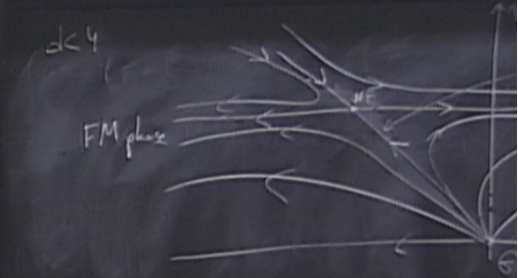
$$+6 = -2(4-\epsilon) + 6 = 2\epsilon - 2$$



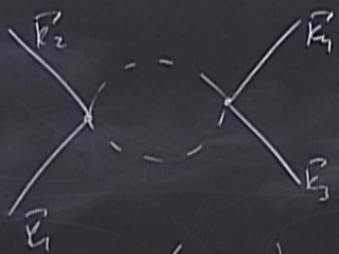
$$I_2 = \int \frac{d^d q}{(2\pi)^d} G_0(\bar{q}) G_0(-E_1 - E_2 - \bar{q})$$

2) $V + O(u^2, v^2)$ \cup is irrelevant at WF fixed point

$$\frac{\partial \beta u}{\partial u} \Big|_{r^*} = \epsilon - 3u \frac{K_d}{(r^* + K)^2} = \epsilon - 3u$$



One-loop RG calculation $\frac{N}{6}$ I_2

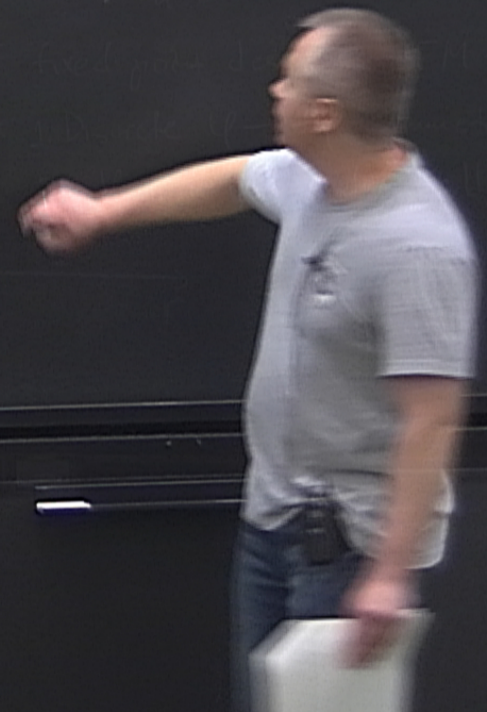


$$I_2 = \int_{\frac{N}{6}}^{\Lambda} \frac{d^d q}{(2\pi)^d} G_0(\vec{q}) G_0(-E_1 - E_2 - \vec{q})$$

$$U(E_1, E_2) \approx U_0 +$$

$$= 2\epsilon - 2$$

U is irrelevant at WF fixed point



One-loop RG calculation $\frac{N}{6}$
 I_2



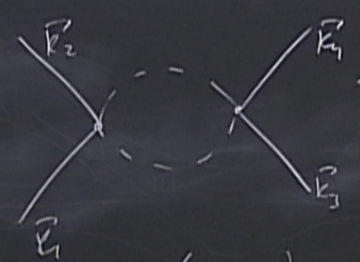
$$I_2 = \int \frac{d^d q}{(2\pi)^d} G_0(\vec{q}) G_0(-\vec{k}_1 - \vec{k}_2 - \vec{q})$$

$$U(\vec{k}_1, \vec{k}_2) \approx U_0 + W(\vec{k}_1 \cdot \vec{k}_2)$$

$= 2\epsilon - 2$

U is irrelevant at
 WF fixed point

One-loop RG calculation $\frac{N}{6}$ I_2



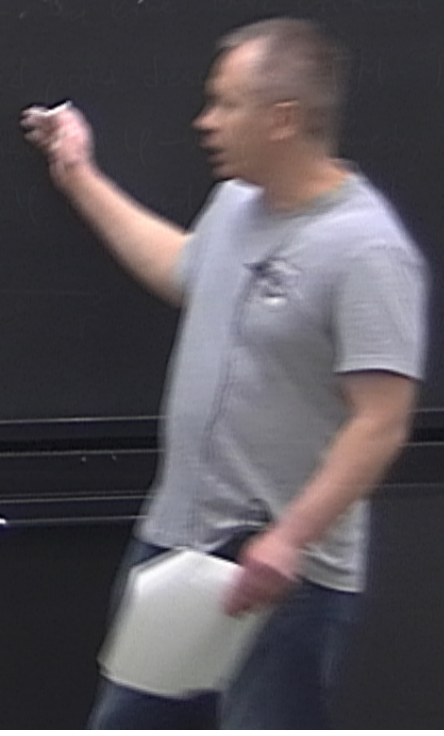
$$I_2 = \int \frac{d^d q}{(2\pi)^d} G_0(\vec{q}) G_0(-E_1 - E_2 - \vec{q})$$

$$U(\vec{E}_1, \vec{E}_2) \approx U_0 + W(\vec{E}_1 \cdot \vec{E}_2) + \dots$$

$$W \int dx (\nabla \psi)^2 \psi^2$$

$$= 2\xi - 2$$

U is irrelevant at WF fixed point



$$\int_{k_1, k_2} (2\pi)^d \delta(E_1 + E_2 + E_3 + E_4) \psi_c(E_1) \psi_c(E_2) \psi_c(E_3) \psi_c(E_4)$$

$$\underbrace{\frac{d^4 q}{(2\pi)^4} G_0(\vec{q}) G_0(-E_1 - E_2 - \vec{q})}_{I_2}$$

$$G_0(\vec{q}) G_0(-E_1 - E_2 - \vec{q})$$

$$\dim[w] = d + 4 \frac{d-2}{2} + 2 = 0$$

$$\dim[w] = \epsilon - 2 - \text{irrelevant}$$

$$\frac{\partial \beta u}{\partial r} \Big|_{r^*, u^*} = 3u^{*2} \frac{K_d}{(r^* + \Lambda^2)^2} = O(\epsilon^2) \rightarrow 0$$

$$\frac{\partial \beta u}{\partial u} \Big|_{r^*, u^*} = \epsilon - 3u^* \frac{K_d}{(r^* + \Lambda^2)^2} = \epsilon - 3u^* \frac{K_4}{\Lambda^4} = \epsilon - 3 \frac{16\pi^2 \epsilon}{3} \frac{1}{8\pi^2} = \epsilon - 2\epsilon = -\epsilon$$

$$M = \begin{pmatrix} 2 - \frac{\epsilon}{3} & \frac{\Lambda^2}{16\pi^2} \\ 0 & -\epsilon \end{pmatrix}$$

$$\lambda_t = 2 - \frac{\epsilon}{3}, \lambda_u = -\epsilon$$

$$\vec{v}_t = (1, 0), \vec{v}_u = \left(-\frac{\Lambda^2}{32\pi^2}, 1\right)$$

