

Title: 14/15 PSI - Conformal Field Theory - Lecture 8

Date: Oct 16, 2014 03:30 PM

URL: <http://pirsa.org/14100018>

Abstract:

Comments/Summary

$$1) \mathcal{O}_1(0) \mathcal{O}_2(x) = \sum_{\text{primaries } k} C_k(x) [1 + b^\mu(x) \partial_\mu + b^{\mu\nu}(x) \partial_\mu \partial_\nu + \dots] \mathcal{O}_k$$

more and more subleading

$$b^{\mu_1 \dots \mu_n}(x) \sim x^{-n}$$

Similarly

$$\mathcal{F}_{\Delta, \ell}(\bar{z}, \bar{z}) = (\bar{z}\bar{z})^{\Delta/2} \left(\frac{\bar{z}}{\bar{z}}\right)^\ell (1 + \dots)$$

subleading from disc that re- the t

Comments/Summary

$$1) \mathcal{O}_1(0)\mathcal{O}_2(x) = \sum_{\text{primaries } k} C_k(x) [1 + b^\mu(x)\partial_\mu + b^{\mu\nu}(x)\partial_\mu\partial_\nu + \dots] \mathcal{O}_k$$

more and more
subleading

$$b^{\mu_1 \dots \mu_n}(x) \sim x^n \ll 1$$

Similarly

$$\tilde{\mathcal{F}}_{\Delta, \ell}(\bar{z}, \bar{z}) = (\bar{z}\bar{z})^{\Delta/2} \left(\frac{\bar{z}}{\bar{z}}\right)^\ell (1 + \dots)$$

subleading terms
from descendants
that re-sum into
the hyperg.

PP-2R2
208/DOV, 3-phase, 4-wire
fed from TX-6

Comments / Summary

$$1) \mathcal{O}_1(0) \mathcal{O}_2(x) = \sum_{\text{primaries } k} C_k(x) \left[1 + b^{\mu}(x) \partial_{\mu} + b^{\mu\nu}(x) \partial_{\mu} \partial_{\nu} + \dots \right] \mathcal{O}_k$$


more and more subleading
 $b^{\mu_1 \dots \mu_n}(x)$ $n \ll 1$

Similarly

$$\mathcal{F}_{\Delta, \ell}(\bar{z}, \bar{z}) = (\bar{z} \bar{z})^{\Delta/2} \left(\frac{\bar{z}}{\bar{z}} \right)^{\ell} \left(1 + \dots \right)$$

sublo

that re-
the h

3) 3.A)  = $\frac{1}{(x_{12})^4 (x_{34})^4} \left[z\bar{z} \left(1 + \frac{1}{(1-z)(1-\bar{z})} \right) = \sum_{\Delta=l+2} 2 \frac{l!}{(2l)!} \mathcal{F}_{\Delta, l}(z, \bar{z}) \right]$

3.B) and indeed, with

$\mathcal{O}_l \equiv \mathcal{N} \sum_{k=0}^l \binom{l}{k}^2 (-1)^k \partial_{\phi}^{2k} \phi$ we had found

such that zpt fn is normalized to 1

$\langle \mathcal{O}_l \mathcal{O}_0 \rangle = \langle \text{diagram} \rangle = \sqrt{2} \frac{l!}{\sqrt{(2l)!}} \frac{\left(\frac{\vec{x}_{12} \cdot \vec{n}}{x_{12}^2} - \frac{\vec{x}_{13} \cdot \vec{n}}{x_{13}^2} \right)^l}{x_{12}^2 x_{13}^2 x_{23}^2}$

! for more complicated composite ops B might be much harder than A!

2)



could be identity in general! (not in our scalar examples due to charge conservation)

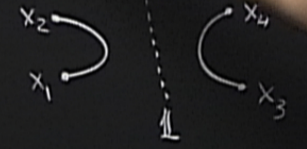
$$\tilde{F}_{0,0} = 1$$

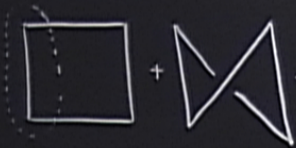
and indeed

$$\langle 0000 \rangle = \frac{1}{x_{12}^{2\Delta} x_{34}^{2\Delta}} (1 + \dots)$$

identity

$$\langle O(x_1) O(x_2) O(x_3) O(x_4) \rangle$$





3) 3.A)  = $\frac{1}{(x_{12})^4 (x_{34})^4} \left[z\bar{z} \left(1 + \frac{1}{(1-z)(1-\bar{z})} \right) \right] = \sum_{\Delta=l+2} 2 \frac{l!}{(2l)!} \mathcal{F}_{\Delta, l}^z(z, \bar{z})$

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$\langle \mathcal{O}_l \mathcal{O}_0 \rangle = \langle \left(\frac{\vec{x}_k \cdot \vec{n}}{x_k^2} - \frac{\vec{x}_l \cdot \vec{n}}{x_l^2} \right)^l \rangle = \sqrt{2} \frac{l!}{\sqrt{(2l)!}} \frac{\left(\frac{\vec{x}_k \cdot \vec{n}}{x_k^2} - \frac{\vec{x}_l \cdot \vec{n}}{x_l^2} \right)^l}{x_{12}^2 x_{13}^2 x_{23}^2}$

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3) 3.A)  +  = $\frac{1}{(x_{12})^4 (x_{34})^4} \left[z\bar{z} \left(1 + \frac{1}{(1-z)(1-\bar{z})} \right) \right] = \sum_{\Delta=l+2} 2 \frac{l!}{(2l)!} \mathcal{F}_{\Delta, l}(z, \bar{z}) = \sum \langle \text{diagram} \rangle$



3.B) and indeed, with

$U_l \equiv e^{\int \sum_{k=0}^l \binom{l}{k}^2 (-1)^k \partial^k \phi \partial^k \phi}$ we had found

such that zpt fn is normalized to 1

$\langle U_l \rangle = \langle \text{diagram} \rangle = \sqrt{2} \frac{l!}{\sqrt{(2l)!}} \frac{\left(\frac{\vec{x}_{12} \cdot \vec{n}}{x_{12}^2} - \frac{\vec{x}_{13} \cdot \vec{n}}{x_{13}^2} \right)^l}{x_{12}^2 x_{13}^2 x_{23}^2}$



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$\langle U_l 000 \rangle = \langle \text{diagram} \rangle = \sqrt{2} \frac{l!}{\sqrt{(2l)!}} \frac{\left(\frac{\vec{x}_k \cdot \vec{n}}{x_k^2} - \frac{\vec{x}_l \cdot \vec{n}}{x_l^2} \right)^l}{x_{12}^2 x_{13}^2 x_{23}^2}$

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AdS/CFT toy model

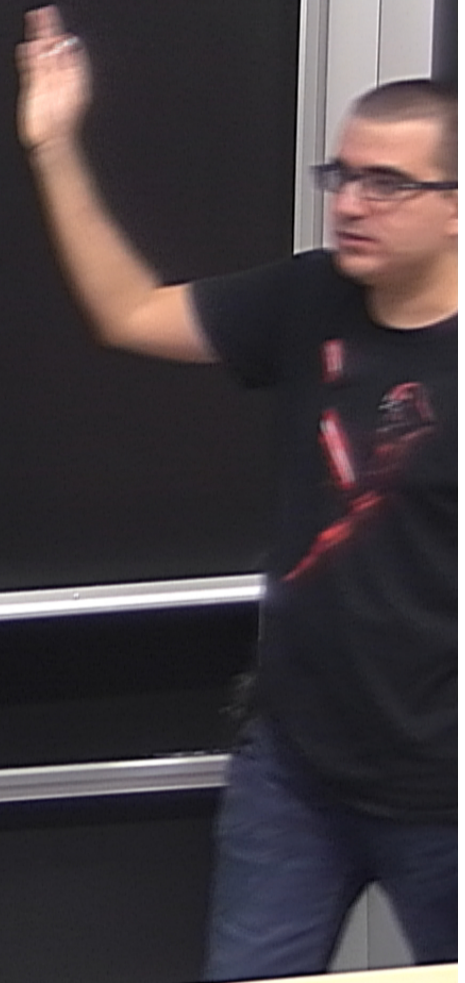
CAUTION
DO NOT TOUCH THE BOARD SURFACE
OR THE BOARD OR THE BOARD OR THE BOARD
OR THE BOARD OR THE BOARD OR THE BOARD
OR THE BOARD OR THE BOARD OR THE BOARD
OR THE BOARD OR THE BOARD OR THE BOARD

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AdS/CFT toy model

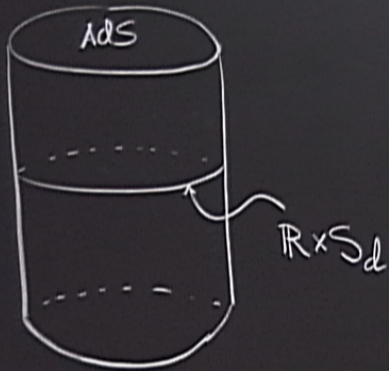


AdS/CFT toy model



CAUTION
DO NOT STAND ON THE BOARD OR ON THE EDGE OF THE BOARD.
IT IS ESSENTIAL TO KEEP THE BOARD CLEAN AND FREE OF CLUTTER.
PLEASE CLEAN UP AFTER YOURSELF.

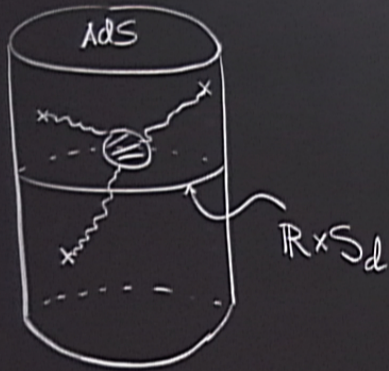
Ads/CFT toy model



CAUTION
DO NOT USE UNLESS THE INSTRUCTIONS ARE
READ CAREFULLY AT ALL TIMES.
IF AT ANY TIME YOU ARE
UNSURE OF THE SAFETY OF THE
EQUIPMENT, STOP IMMEDIATELY.
PLEASE CONTACT US AT
1-800-368-7000

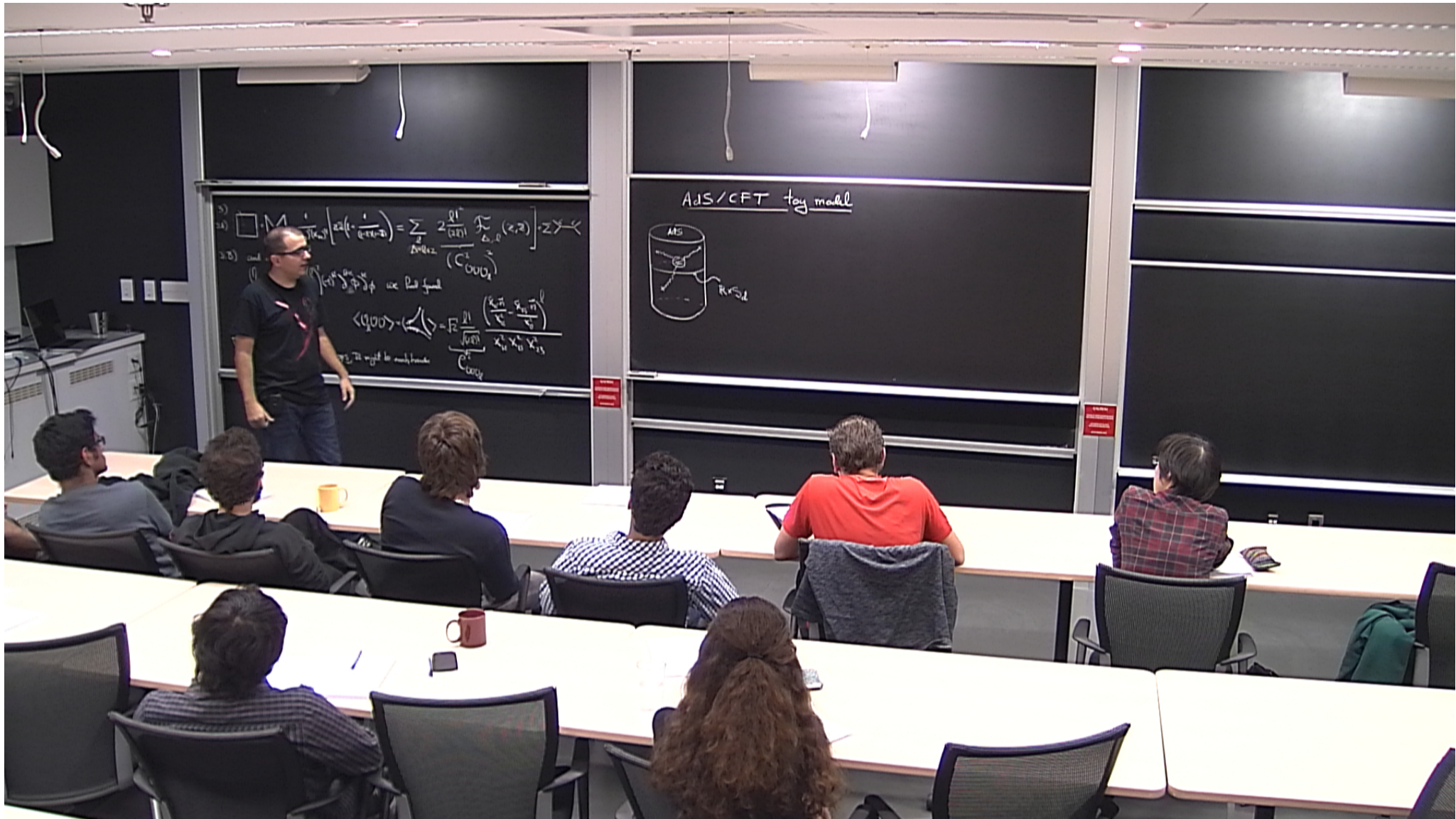
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AdS/CFT toy model

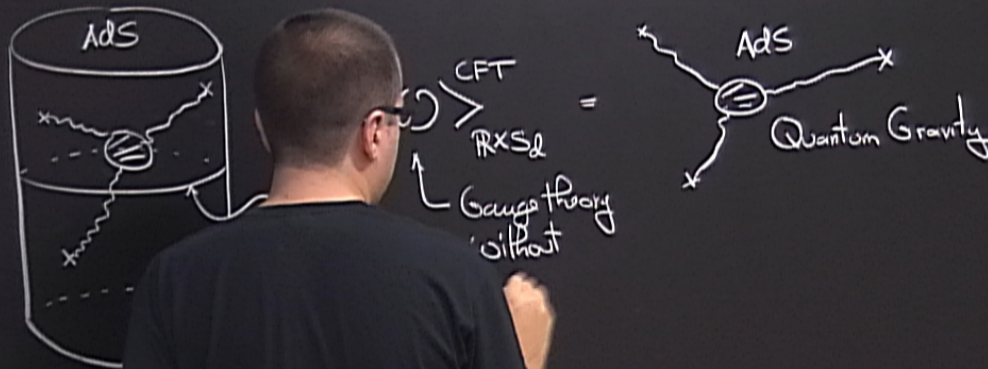


CAUTION
DO NOT USE THIS BOARD IN THE PRESENCE OF
OPEN FLAMES OR OTHER SOURCES OF
HEAT. ALWAYS WEAR YOUR SAFETY GOGGLES.
KEEP YOUR HANDS OFF THE BOARD.

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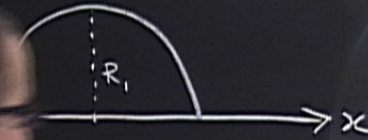
AdS/CFT toy model



CAUTION
DO NOT TOUCH THE BOARD OR THE SURFACE OF THE BOARD.
IT IS PROHIBITED TO SMILE
WITH YOUR MOUTH OPEN.
PLEASE REMAIN SEATED.

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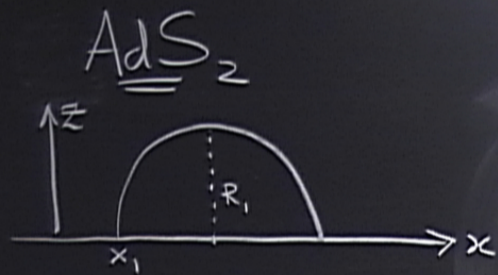
AdS₂



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$

geodesics are

$$z^2 = R_1^2 - (x - x_1 - R_1)^2$$



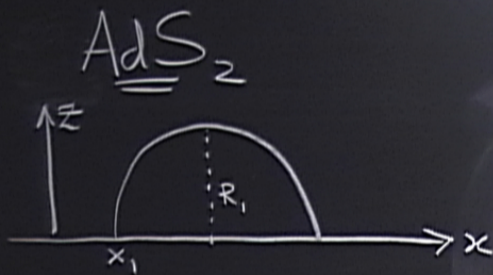
$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$

geodesics are

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\downarrow \uparrow var
 $z(x)$

$$\mathcal{L}_{NG} = \int dz \sqrt{g_{\mu\nu}(x) \dot{x}^\mu \dot{x}^\nu}$$



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$

geodesics are

$$z^2 = R_1^2 - (x - x_1 - R_1)^2$$

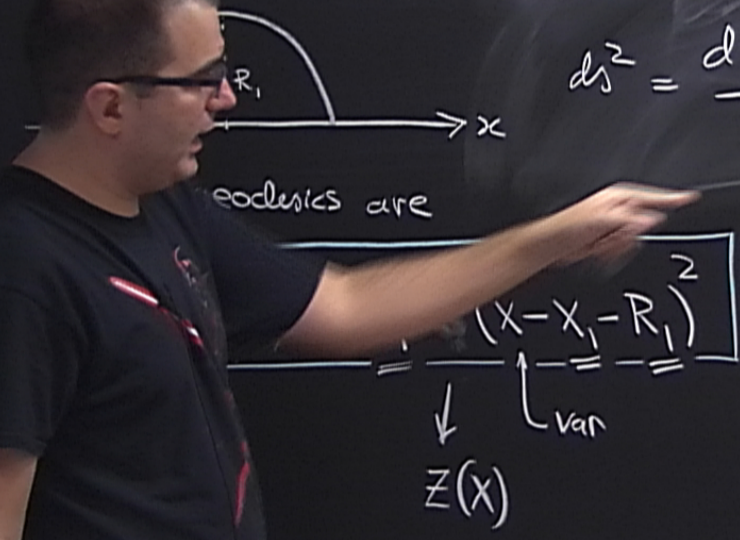
\downarrow \uparrow var
 $z(x)$

$$\mathcal{L}_{NG} = \int dz \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} = \int dz \sqrt{\frac{\dot{z}^2 + \dot{x}^2}{z^2}}$$

⚠ for more complicated composite sps, B might be much harder than A. ⚠

∫
∞

AdS₂



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$

$$\mathcal{L}_{NG} = \int dz \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} = \int dz \sqrt{\frac{\dot{z}^2 + \dot{x}^2}{z}}$$

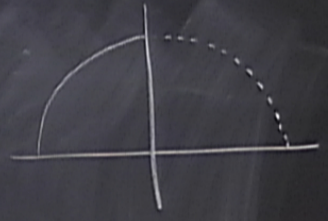
! for more complicated composite sps, B might be much harder than A!

∫
∞∞

AdS



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$



ics are

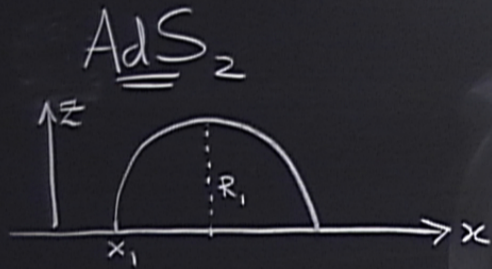
$$R_1^2 - (x - x_1 - R_1)^2$$

↓ ↗
z(x) var

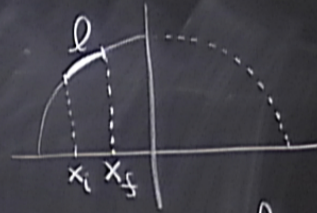
$$\mathcal{L}_{NG} = \int dz \sqrt{g_{mn} \dot{x}^m \dot{x}^n} = \int dz \sqrt{\frac{\dot{z}^2 + \dot{x}^2}{z}}$$

! for more complicated composite sps, B might be much harder than A!

\int
000e



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$



$$l = \frac{1}{z} \log \left(\frac{x_2 - x_1 - 2R_1}{x_2 - x_1} \frac{x_1 - x_1}{x_1 - x_1 - 2R_1} \right)$$

geodesics are

$$z^2 = R_1^2 - (x - x_1 - R_1)^2$$

\downarrow \uparrow var
 $z(x)$

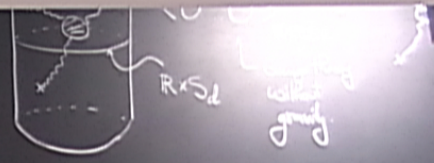
$$\mathcal{L}_{NG} = \int dz \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} = \int dz \sqrt{\frac{\dot{z}^2 + \dot{x}^2}{z}}$$

$$Q_2 \equiv \int \psi^\dagger \sum_{k=0}^{\infty} \binom{Q_2}{k} (-1)^k \psi^k \psi \quad \text{we find found}$$

such that zpt fn is normalized to 1

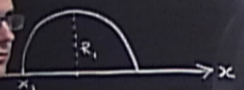
$$\langle Q_2 00 \rangle = \langle \psi^\dagger \psi \rangle = \sqrt{2} \frac{l_1}{\sqrt{(2l_1)}} \frac{\left(\frac{x_1^2}{x_1^2} - \frac{x_1}{x_1} \right)}{x_1^2 x_1^2 x_1^2}$$

▽ for more complicated composite ops, B might be much harder than A

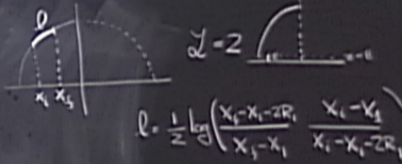


$$d_1^2 = \frac{d_1^2 + \dots}{z^2}$$

AdS₂



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$



$$l = \frac{1}{z} \ln \left(\frac{x_1 - x_2 - 2R_1}{x_1 - x_1} \frac{x_1 - x_2}{x_1 - x_1 - 2R_1} \right)$$

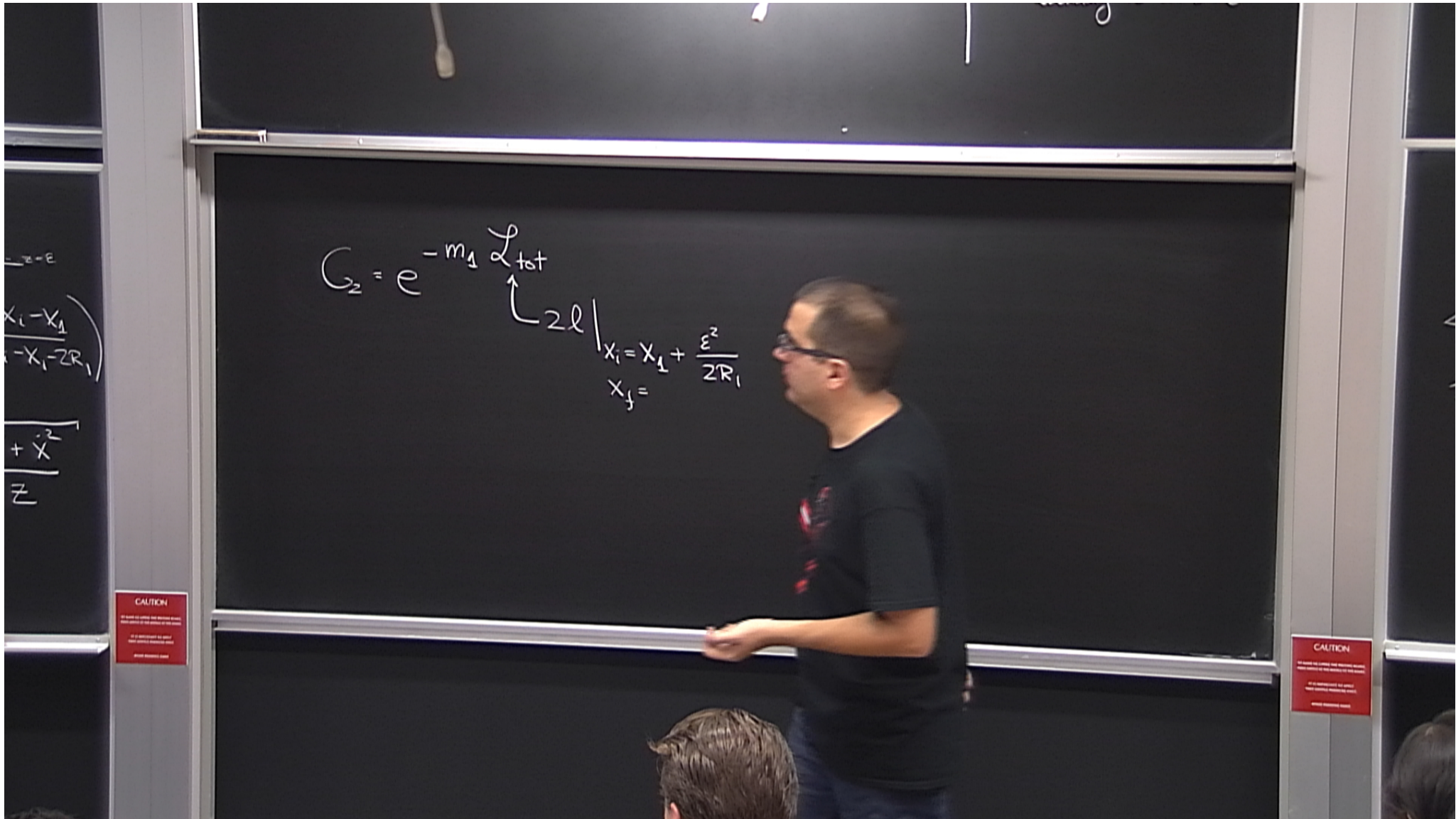
geodesics are

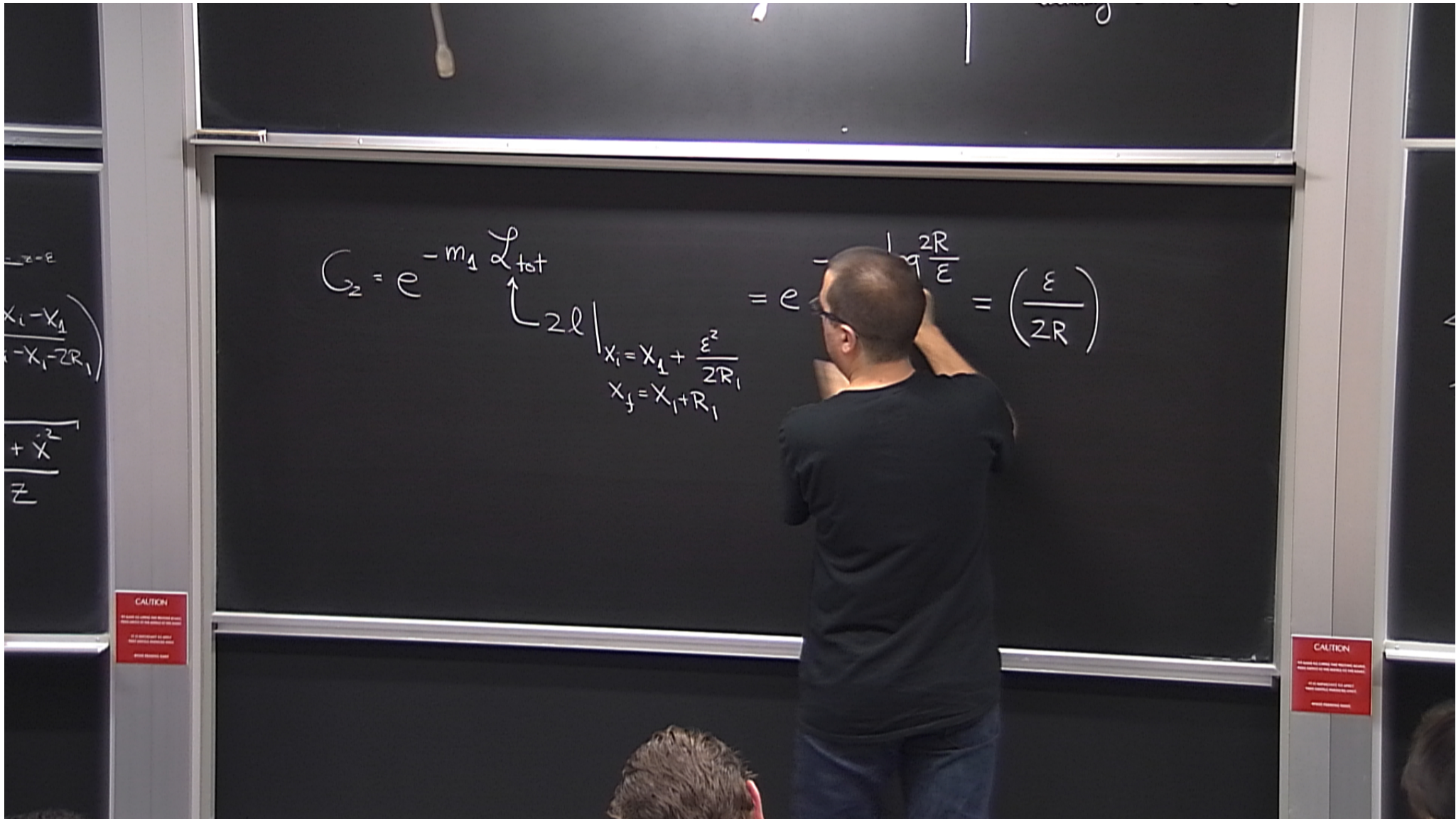
$$z^2 = R_1^2 - (x - x_1 - R_1)^2$$

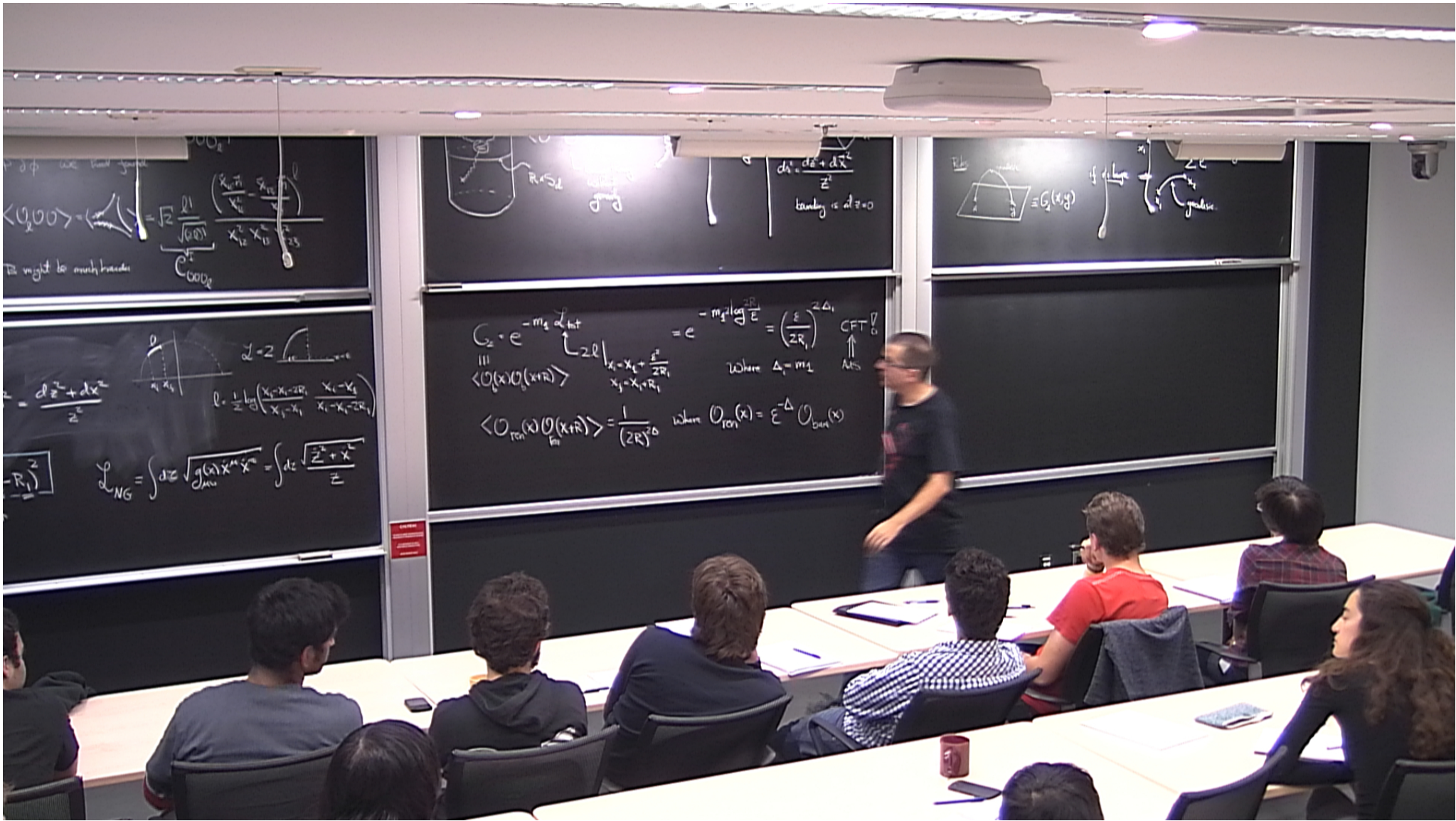
↓
z(x)

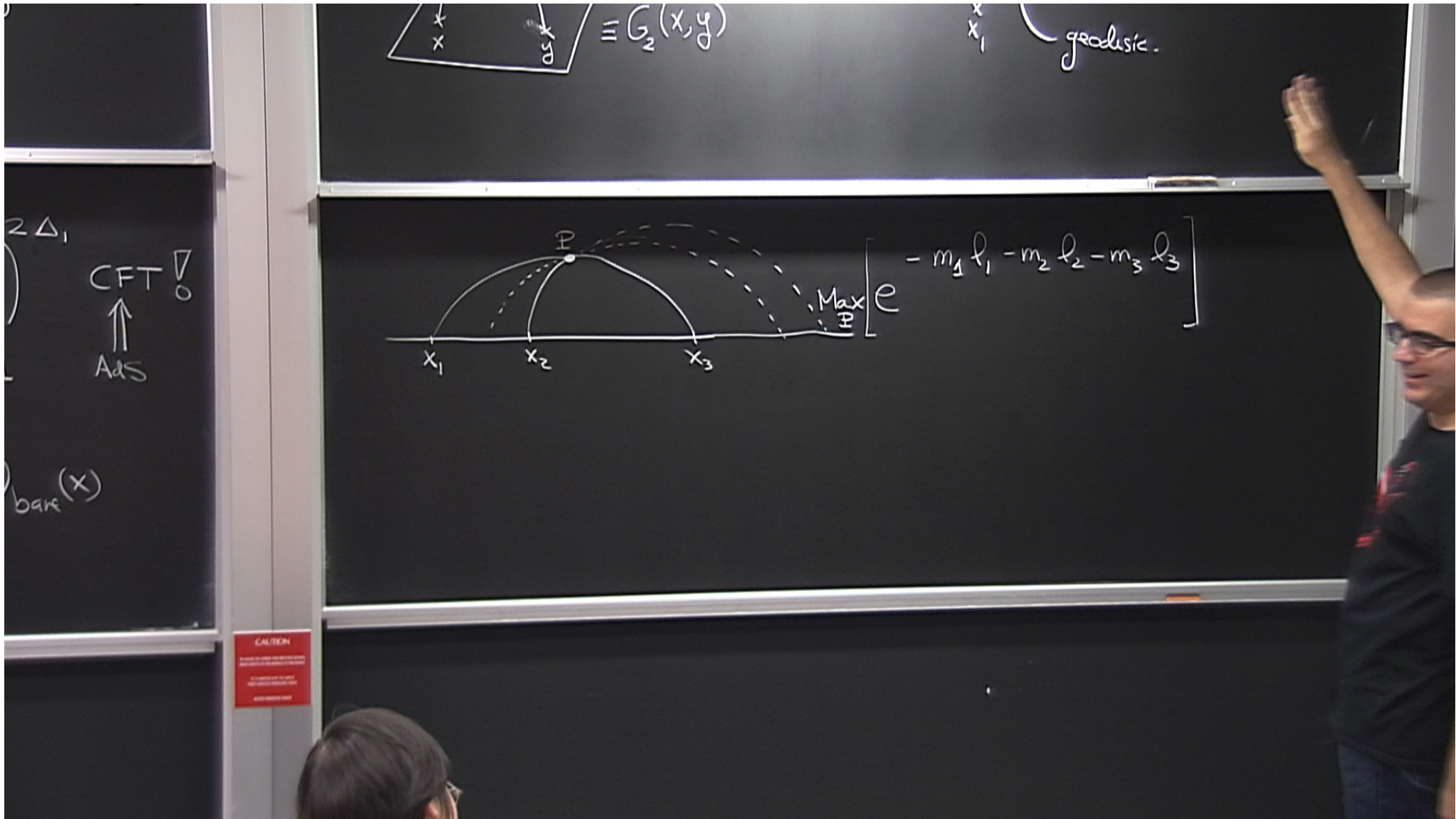
$$\mathcal{L}_{NG} = \int dz \sqrt{g(x) \dot{x}^\mu \dot{x}^\nu} = \int dz \sqrt{\frac{z^2 + \dot{x}^2}{z}}$$

$$G_2 = e^{-m_4 \mathcal{L}_{tot}} \quad \mathcal{L}_{tot} = \int dz \left| x_1 - x_2 + \frac{z^2}{2R_1} \right|$$







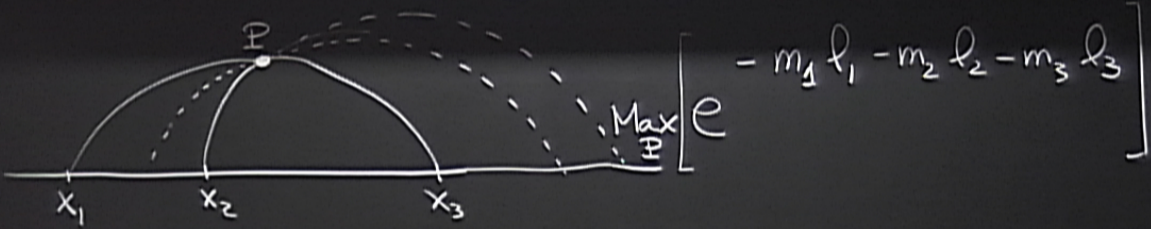


$$\begin{matrix} x \\ x \end{matrix} \begin{matrix} x_1 \\ x_1 \end{matrix} \equiv G_2(x, y)$$

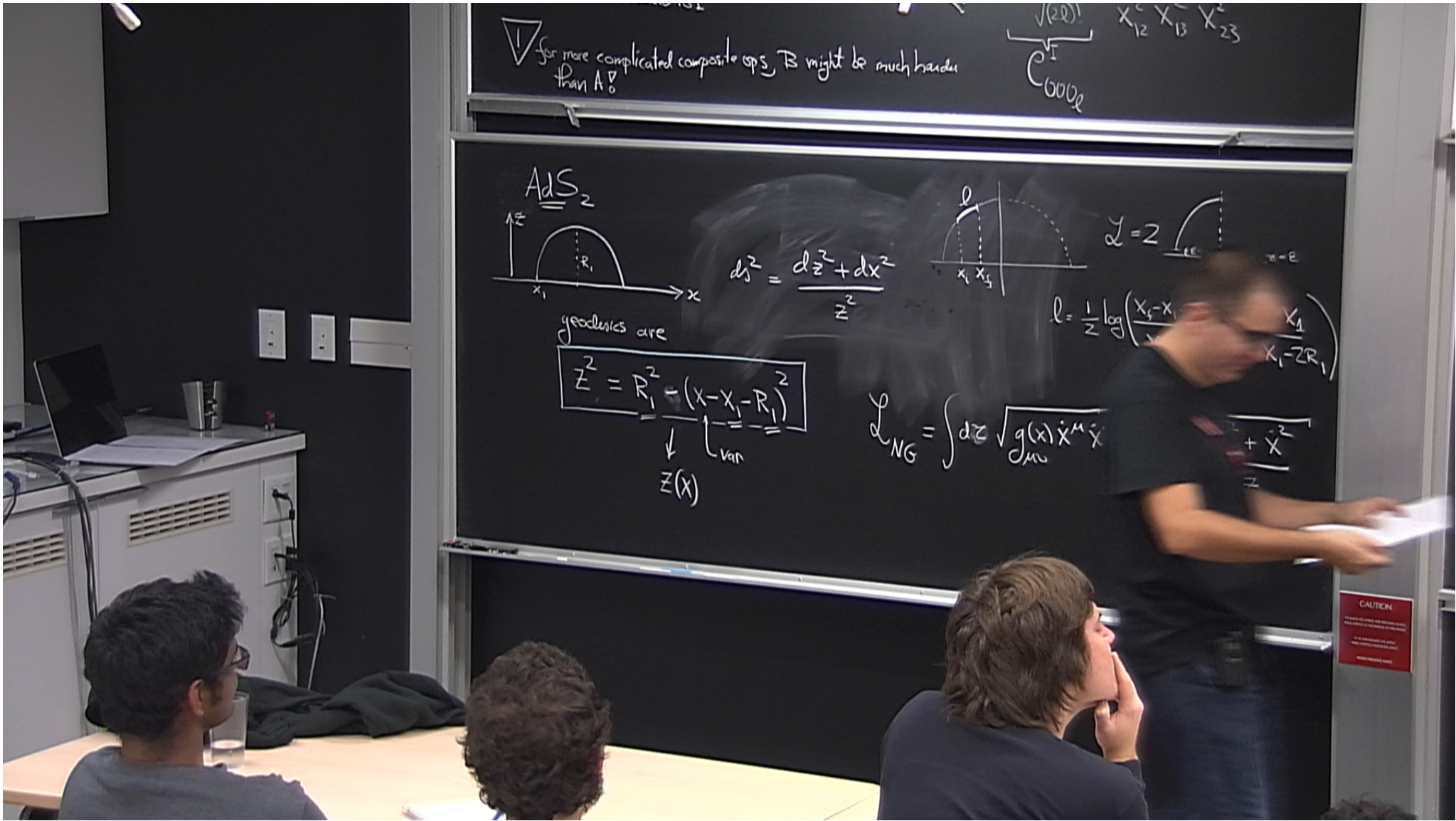
geodesic.

$z \Delta_1$
CFT ∇_0
 \uparrow
Ads

$bare(x)$

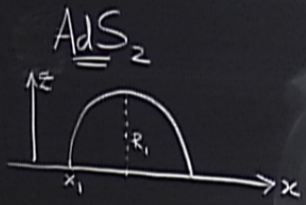


CAUTION



for more complicated composite ops, B might be much harder than A!

$$\sqrt{(2R)^2} \quad X_{12}^2 \quad X_{13}^2 \quad X_{23}^2$$



$$ds^2 = \frac{dz^2 + dx^2}{z^2}$$



$$L = 2 \int_{x_1}^{x_2} \frac{dx}{z}$$

geodesics are

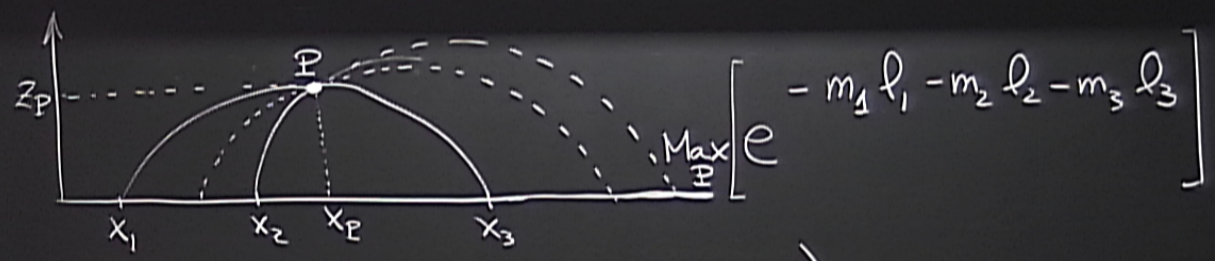
$$Z^2 = R_1^2 - \underbrace{(x - x_1 - R_1)^2}_{\text{var}} = Z(x)$$

$$L_{NG} = \int dz \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}$$

$$l = \frac{1}{2} \log \left(\frac{x_2 - x_1}{x_1 - 2R_1} \right)$$

$\left(\frac{\varepsilon}{2R_1}\right)^{2\Delta_1}$
 CFT ∇_0
 \uparrow
 AdS
 $= m_1$

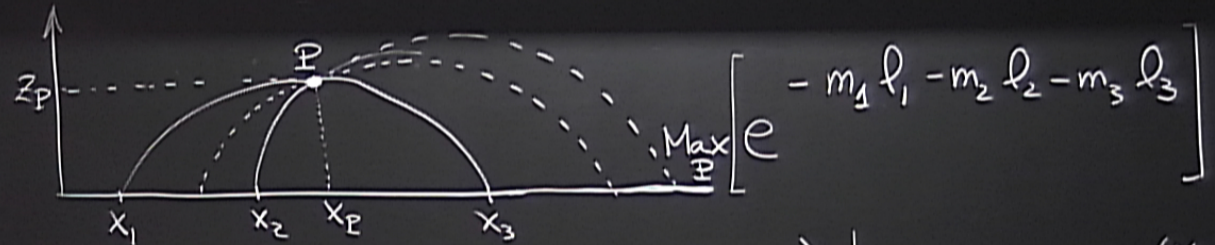
$\Delta \circlearrowleft_{\text{bare}}(x)$



$$l_1 = \frac{1}{2} \log \left(\frac{x_f - x_1}{x_f - x_1 - 2R_1} \frac{x_i - x_1 - 2R_1}{x_i - x_1} \right)$$

CAUTION
 ALL AREAS TO THE LEFT AND RIGHT OF THIS BOARD ARE RESERVED FOR THE USE OF THE BOARD.
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$\left(\frac{\varepsilon}{2R_1}\right)^{2\Delta_1}$
 $= m_1$
 $\Delta_1 \circlearrowleft_{\text{bare}}(x)$
 CFT ∇_0
 ↑
 AdS

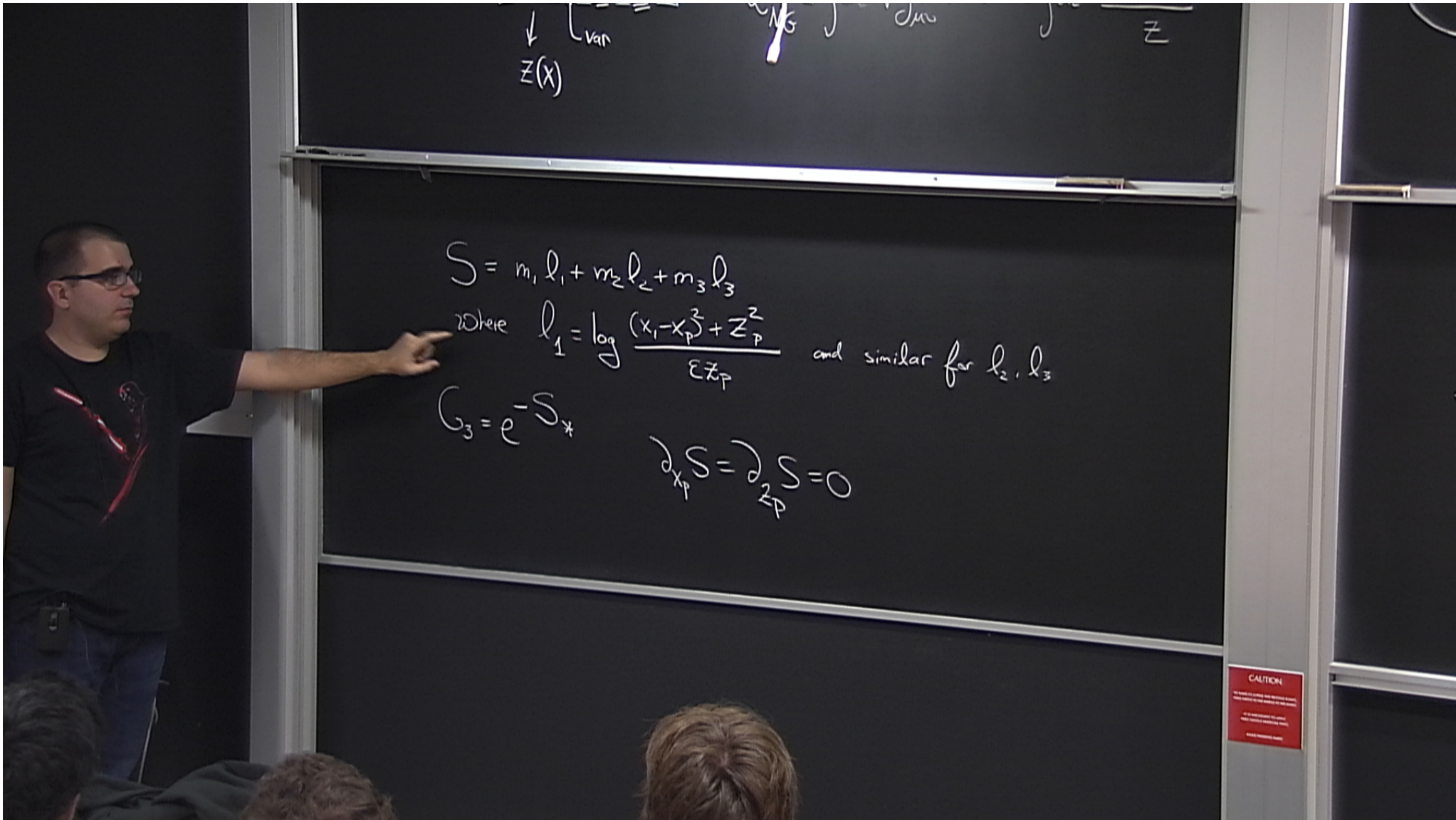


$$l_1 = \frac{1}{2} \log \left(\frac{x_f - x_i}{x_f - x_i - 2R_1} \frac{x_i - x_i - 2R_1}{x_i - x_i} \right) \quad \text{with } R_1 = \frac{(x_i - x_f)^2}{2\varepsilon}$$

$$x_i = x_1 + \frac{\varepsilon^2}{2R_1}$$

$$x_f = x_P$$

CAUTION



In[324]:=

```
PowerExpand@FullSimplify[
$$\frac{\sqrt{D[\sqrt{R1^2 - (x - x1 - R1)^2}, x]^2 + 1}}{\sqrt{R1^2 - (x - x1 - R1)^2}}$$
] //
Integrate[#, {x, xi, xf}, GenerateConditions -> False] &
```

Out[324]=

$$\frac{1}{2} (\text{Log}[-x1 + xf] - \text{Log}[-2 R1 - x1 + xf] - \text{Log}[-x1 + xi] + \text{Log}[-2 R1 - x1 + xi])$$

$$\text{action} = m[1] \text{Log}\left[\frac{(x1 - xp)^2 + zp^2}{zp \epsilon}\right] + m[2] \text{Log}\left[\frac{(x2 - xp)^2 + zp^2}{zp \epsilon}\right] +$$

$$m[3] \text{Log}\left[\frac{(x3 - xp)^2 + zp^2}{zp \epsilon}\right]$$

In[324]:=

```
PowerExpand@FullSimplify[
$$\frac{\sqrt{D[\sqrt{R1^2 - (x - x1 - R1)^2}, x]^2 + 1}}{\sqrt{R1^2 - (x - x1 - R1)^2}}$$
] //
Integrate[#, {x, xi, xf}, GenerateConditions -> False] &
```

Out[324]=

$$\frac{1}{2} (\text{Log}[-x1 + xf] - \text{Log}[-2 R1 - x1 + xf] - \text{Log}[-x1 + xi] + \text{Log}[-2 R1 - x1 + xi])$$

In[326]:=

```
action = m[1] Log[
$$\frac{(x1 - xp)^2 + zp^2}{zp \epsilon}$$
] + m[2] Log[
$$\frac{(x2 - xp)^2 + zp^2}{zp \epsilon}$$
] +
m[3] Log[
$$\frac{(x3 - xp)^2 + zp^2}{zp \epsilon}$$
];
```

In[327]:=

$$\text{action} = m[1] \text{Log} \left[\frac{(x1 - xp)^2 + zp^2}{zp \epsilon} \right] + m[2] \text{Log} \left[\frac{(x2 - xp)^2 + zp^2}{zp \epsilon} \right] + m[3] \text{Log} \left[\frac{(x3 - xp)^2 + zp^2}{zp \epsilon} \right];$$

$$\text{action} = m[1] \text{Log} \left[\frac{(x1 - xp)^2 + zp^2}{zp^2} \right] + m[2] \text{Log} \left[\frac{(x2 - xp)^2 + zp^2}{zp^2} \right] +$$

$$m[3] \text{Log} \left[\frac{(x3 - xp)^2 + zp^2}{zp^2} \right];$$

In[331]:=

```
eqs = {∂zp action, ∂xp action} // FullSimplify;
```

```
Solve[eqs
```

Out[332]=

$$\left\{ -\frac{\frac{(x1-xp)^2 - zp^2}{(x1-xp)^2 + zp^2} m[1]}{zp} + \frac{\frac{(x2-xp)^2 - zp^2}{(x2-xp)^2 + zp^2} m[2]}{zp} + \frac{\frac{(x3-xp)^2 - zp^2}{(x3-xp)^2 + zp^2} m[3]}{zp}, \right.$$

$$\left. 2 \left(\frac{(-x1 + xp) m[1]}{(x1 - xp)^2 + zp^2} + \frac{(-x2 + xp) m[2]}{(x2 - xp)^2 + zp^2} + \frac{(-x3 + xp) m[3]}{(x3 - xp)^2 + zp^2} \right) \right\}$$

300%

$$\text{action} = m[1] \text{Log} \left[\frac{(x1 - xp)^2 + zp^2}{zp^2} \right] + m[2] \text{Log} \left[\frac{(x2 - xp)^2 + zp^2}{zp^2} \right] +$$

$$m[3] \text{Log} \left[\frac{(x3 - xp)^2 + zp^2}{zp^2} \right];$$

In[331]:=

```
eqs = {∂zp action, ∂xp action} // FullSimplify;
```

```
eqs /. {m[2] → α m[1], m[3]}
```

Out[334]=

$$\left\{ -\frac{\frac{(x1-xp)^2 - zp^2}{(x1-xp)^2 + zp^2} m[1]}{zp} + \frac{\frac{(x2-xp)^2 - zp^2}{(x2-xp)^2 + zp^2} m[2]}{zp} + \frac{\frac{(x3-xp)^2 - zp^2}{(x3-xp)^2 + zp^2} m[3]}{zp}, \right.$$

$$\left. 2 \left(\frac{(-x1 + xp) m[1]}{(x1 - xp)^2 + zp^2} + \frac{(-x2 + xp) m[2]}{(x2 - xp)^2 + zp^2} + \frac{(-x3 + xp) m[3]}{(x3 - xp)^2 + zp^2} \right) \right\}$$

300%

```
sol = Solve[0 == eqs2, {xp, zp}] // First // Simplify // PowerExpand // Simplify
```

Out[338]=

$$\left\{ \begin{aligned} \mathbf{x}_p \rightarrow & \left(-\mathbf{x}_2 \mathbf{x}_3 (-1 + \alpha + \beta) (\mathbf{x}_2 (-1 + \alpha - \beta) + \mathbf{x}_3 (-1 - \alpha + \beta)) + \right. \\ & \mathbf{x}_1^2 (-1 + \alpha + \beta) (\mathbf{x}_2 (1 + \alpha - \beta) + \mathbf{x}_3 (1 - \alpha + \beta)) + \\ & \mathbf{x}_1 \left(-\mathbf{x}_2^2 (-1 + \alpha^2 - 2\alpha\beta + \beta^2) - \mathbf{x}_3^2 (-1 + \alpha^2 - 2\alpha\beta + \beta^2) + \right. \\ & \left. \left. 2\mathbf{x}_2 \mathbf{x}_3 (\alpha^2 + (-1 + \beta)^2 - 2\alpha(1 + \beta)) \right) \right) / \\ & \left(2 (\mathbf{x}_3^2 (1 + \alpha - \beta) \beta + \mathbf{x}_2^2 \alpha (1 - \alpha + \beta) + \mathbf{x}_1^2 (-1 + \alpha + \beta) + \right. \\ & \left. \mathbf{x}_2 \mathbf{x}_3 (-1 + \alpha^2 - 2\alpha\beta + \beta^2) + \right. \\ & \left. \mathbf{x}_1 (-1 + \alpha + \beta) (\mathbf{x}_2 (-1 + \alpha - \beta) + \mathbf{x}_3 (-1 - \alpha + \beta)) \right) \Big), \\ \mathbf{z}_p \rightarrow & - \left(i (\mathbf{x}_1 - \mathbf{x}_2) (\mathbf{x}_1 - \mathbf{x}_3) (\mathbf{x}_2 - \mathbf{x}_3) \sqrt{\alpha^4 + (-1 + \beta^2)^2 - 2\alpha^2 (1 + \beta^2)} \right) / \\ & \left(2 (\mathbf{x}_3^2 (1 + \alpha - \beta) \beta + \mathbf{x}_2^2 \alpha (1 - \alpha + \beta) + \mathbf{x}_1^2 (-1 + \alpha + \beta) + \mathbf{x}_2 \mathbf{x}_3 (-1 + \alpha^2 - \right. \\ & \left. 2\alpha\beta + \beta^2) + \mathbf{x}_1 (-1 + \alpha + \beta) (\mathbf{x}_2 (-1 + \alpha - \beta) + \mathbf{x}_3 (-1 - \alpha + \beta)) \right) \Big) \end{aligned} \right\}$$

$$2 \left(\frac{-x_1 + x_p}{(x_1 - x_p)^2 + z_p^2} + \frac{(-x_2 + x_p) \alpha}{(x_2 - x_p)^2 + z_p^2} + \frac{(-x_3 + x_p) \beta}{(x_3 - x_p)^2 + z_p^2} \right) m[1] \}$$

```
sol = Solve[0 == eqs2, {xp, zp}] // First // Simplify // PowerExpand // Simplify;
```

```
action /. sol /. {alpha -> m[2] / m[1], beta -> m[3] /
```

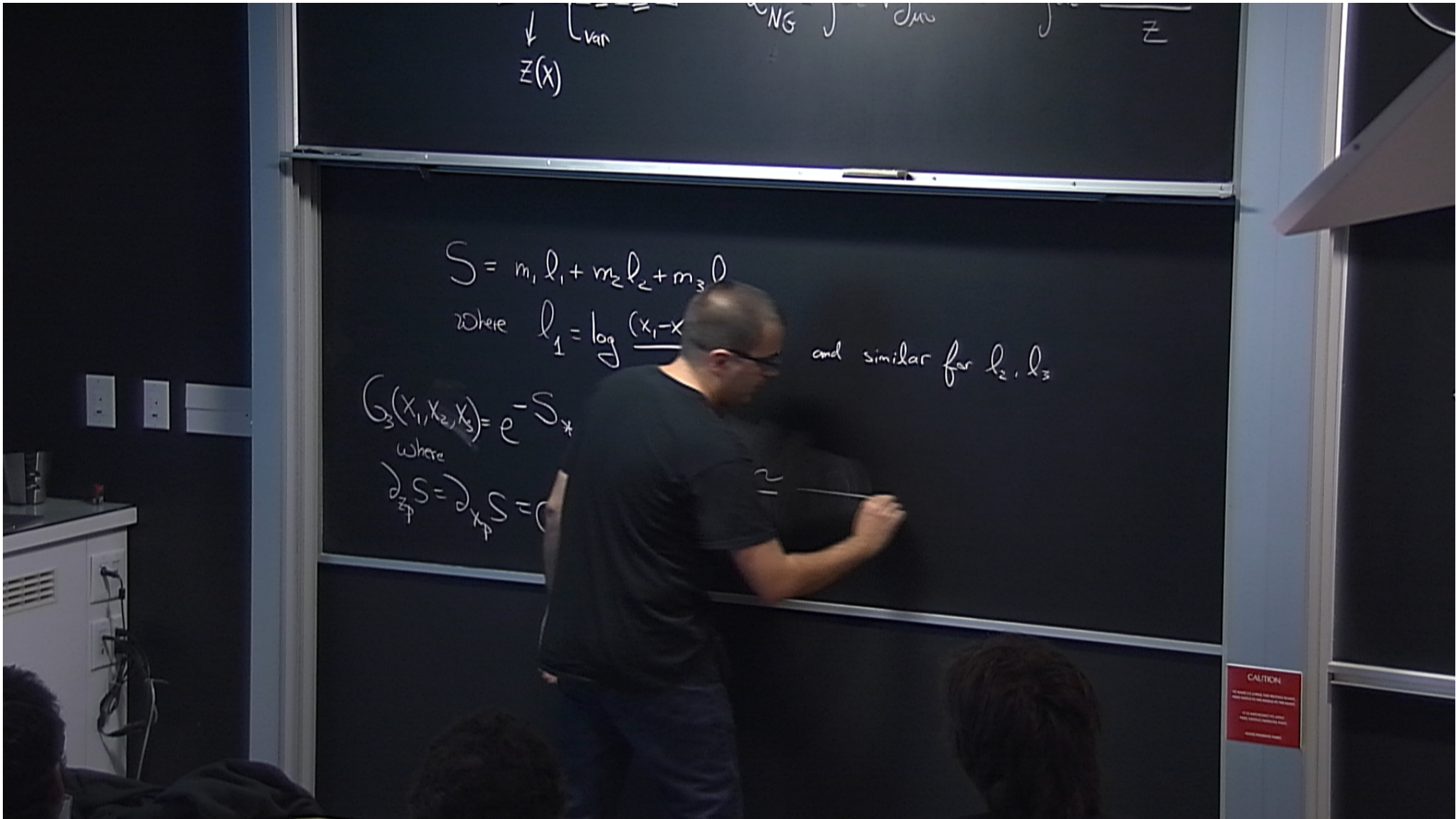
Out[340]=

$$\text{Log} \left[\frac{2 i \left(x_3^2 (1 + \alpha - \beta) \beta + x_2^2 \alpha (1 - \alpha + \beta) + x_1^2 (-1 + \alpha + \beta) + x_2 x_3 (-1 + \alpha^2 - 2 \alpha \beta + \beta^2) + x_1 (-1 + \alpha + \beta) (x_2 (-1 + \alpha - \beta) + x_3 (-1 - \alpha + \beta)) \right)}{\left(- \left((x_1 - x_2)^2 (x_1 - x_3)^2 (x_2 - x_3)^2 (\alpha^4 + (-1 + \beta^2)^2 - 2 \alpha^2 (1 + \beta^2)) \right) \right) / \left(4 \left(x_3^2 (1 + \alpha - \beta) \beta + x_2^2 \alpha (1 - \alpha + \beta) + x_1^2 (-1 + \alpha + \beta) + x_2 x_3 (-1 + \alpha^2 - 2 \alpha \beta + \beta^2) + x_1 (-1 + \alpha + \beta) (x_2 (-1 + \alpha - \beta) + x_3 (-1 - \alpha + \beta)) \right)^2 \right) +$$

actionCrit

Out[344]=

$$\begin{aligned} & \left(-\frac{i\pi}{2} + \text{Log}[2] + \text{Log}[x1 - x2] + \text{Log}[x1 - x3] - \right. \\ & \quad \left. \text{Log}[x2 - x3] - \text{Log}[\epsilon] - \text{Log}[m[1]] + \text{Log}[m[1] - m[2] - m[3]] + \frac{1}{2} \right. \\ & \quad \left. \left(4 \text{Log}[m[1]] - \text{Log}[m[1]^4 + (m[2]^2 - m[3]^2)^2 - 2m[1]^2(m[2]^2 + m[3]^2)] \right) \right) \\ m[1] & + \left(\frac{i\pi}{2} + \text{Log}[2] + \text{Log}[x1 - x2] - \text{Log}[x1 - x3] + \text{Log}[x2 - x3] - \right. \\ & \quad \left. \text{Log}[\epsilon] - 2 \text{Log}[m[1]] + \text{Log}[m[2]] + \text{Log}[m[1] - m[2] + m[3]] + \frac{1}{2} \right. \\ & \quad \left. \left(4 \text{Log}[m[1]] - \text{Log}[m[1]^4 + (m[2]^2 - m[3]^2)^2 - 2m[1]^2(m[2]^2 + m[3]^2)] \right) \right) \\ m[2] & + \left(\frac{i\pi}{2} + \text{Log}[2] - \text{Log}[x1 - x2] + \text{Log}[x1 - x3] + \text{Log}[x2 - x3] - \text{Log}[\epsilon] - \right. \\ & \quad \left. 2 \text{Log}[m[1]] + \text{Log}[m[1] + m[2] - m[3]] + \text{Log}[m[3]] + \frac{1}{2} \left(4 \text{Log}[m[1]] - \right. \right. \\ & \quad \left. \left. \text{Log}[m[1]^4 + (m[2]^2 - m[3]^2)^2 - 2m[1]^2(m[2]^2 + m[3]^2)] \right) \right) m[3] \end{aligned}$$



$$\downarrow \text{var} \\ Z(x)$$

$$S = m_1 l_1 + m_2 l_2 + m_3 l_3$$

where $l_1 = \log \frac{(x_1 - x_p)^2 + z_p^2}{\epsilon z_p}$ and similar for l_2, l_3

$$G_3(x_1, x_2, x_3) = e^{-S}$$

where

$$\frac{\partial S}{\partial z_p} = \frac{\partial S}{\partial x_p} = 0$$

\Rightarrow

$$G_3 \approx \frac{C(m_1, m_2, m_3)}{\epsilon}$$

Full result is $D[\text{with}\alpha, \alpha] + (\text{with}\alpha / . \alpha \rightarrow 0)$

In[349]:=

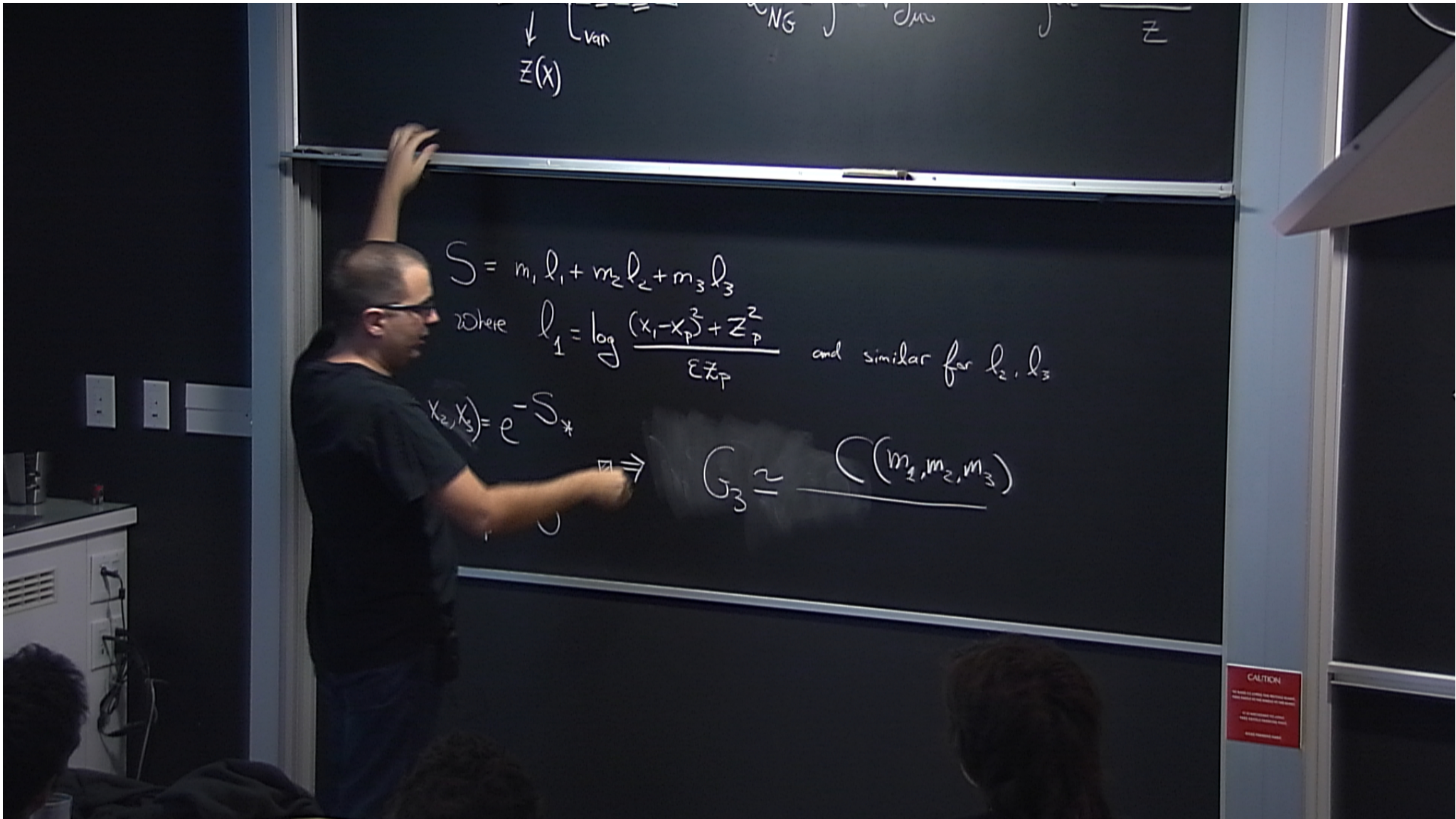
```
with $\alpha$  /.  $\alpha \rightarrow 0$  // Simplify;
```

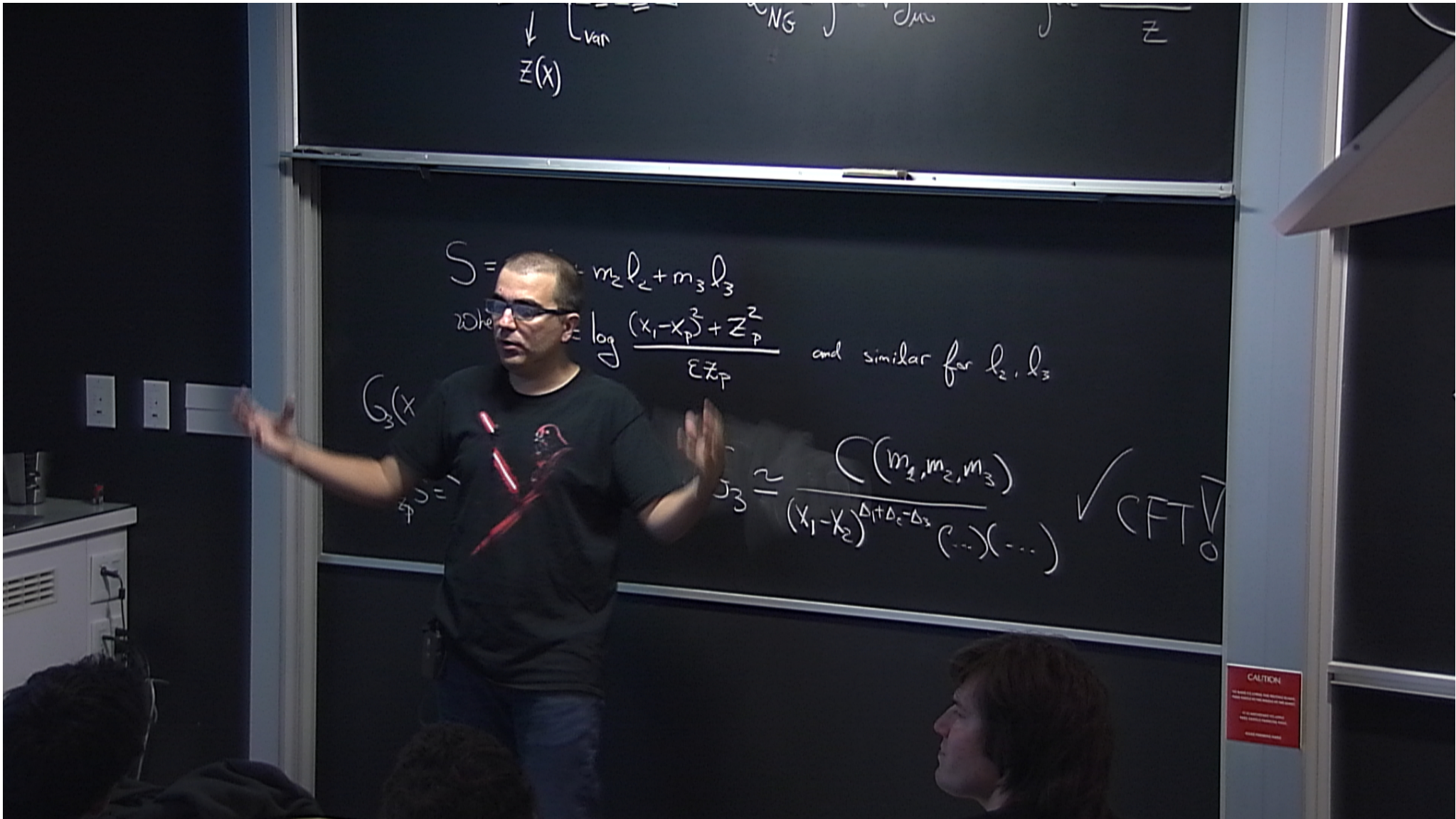
In[350]:=

```
D[with $\alpha$ ,  $\alpha$ ]
```

Out[350]=

```
(Log[x1 - x2] + Log[x1 - x3] - Log[x2 - x3]) m[1] +  
(Log[x1 - x2] - Log[x1 - x3] + Log[x2 - x3]) m[2] +  
(-Log[x1 - x2] + Log[x1 - x3] + Log[x2 - x3]) m[3]
```





\downarrow var $\left[\frac{1}{\epsilon} \int_{\mathcal{N}_S} \dots \right]$ Z
 $Z(x)$

$$S = m_1 l_1 + m_2 l_2 + m_3 l_3$$

where $l_1 = \log \frac{(x_1 - x_p)^2 + z_p^2}{\epsilon z_p}$ and similar for l_2, l_3

$$G_3(x_1, x_2, x_3) = e^{-S}$$

where

$$\frac{\partial S}{\partial z_p} = \frac{\partial S}{\partial x_p} = 0$$

\Rightarrow

$$G_3 \approx \frac{\binom{m_1, m_2, m_3}{(\dots)(\dots)}}{(x_1 - x_2)^{\Delta + \Delta_c - \Delta_s}}$$

✓ CFT ✓

CAUTION

z

gravity.

boundary is at $z=0$

AdS/CFT

Def of QG.

✓ CFT!

CAUTION
DO NOT TOUCH THE BOARD WHEN
IN USE OR WHEN IT IS HOT
IF IT IS HOT TO TOUCH
DO NOT TOUCH IT
UNLESS YOU ARE
WARRANTED TO DO SO

z

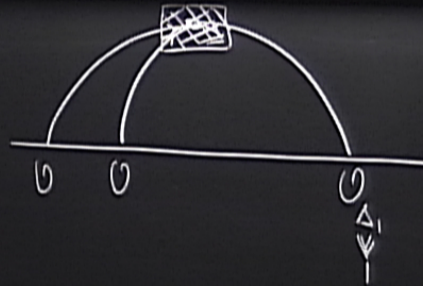
gravity.

boundary is at $z=0$

AdS/CFT

Def of QG

More "re"



CFT

G_3 / geodesics

✓ CFT ✓

z

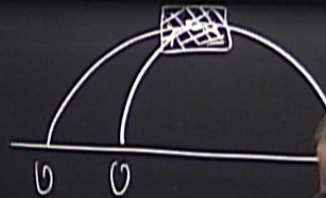
gravity.

boundary is at $z=0$

AdS/CFT

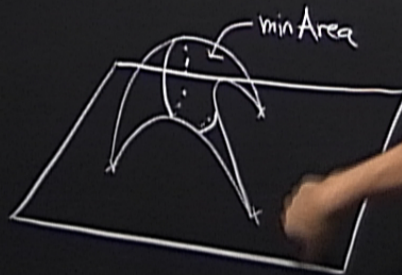
Def of QG

More "realistic"



S^3 / geodesics

CFT



$e^{-m \text{ Length}}$

CAUTION

z

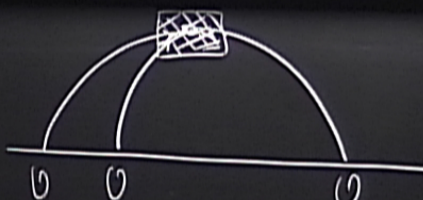
gravity.

boundary is at $z=0$

AdS/CFT

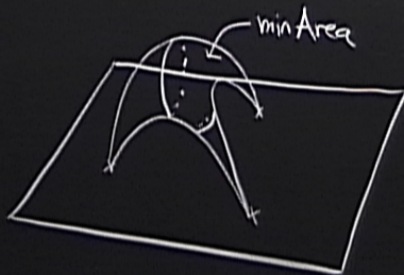
Def of QG

More "realistic"



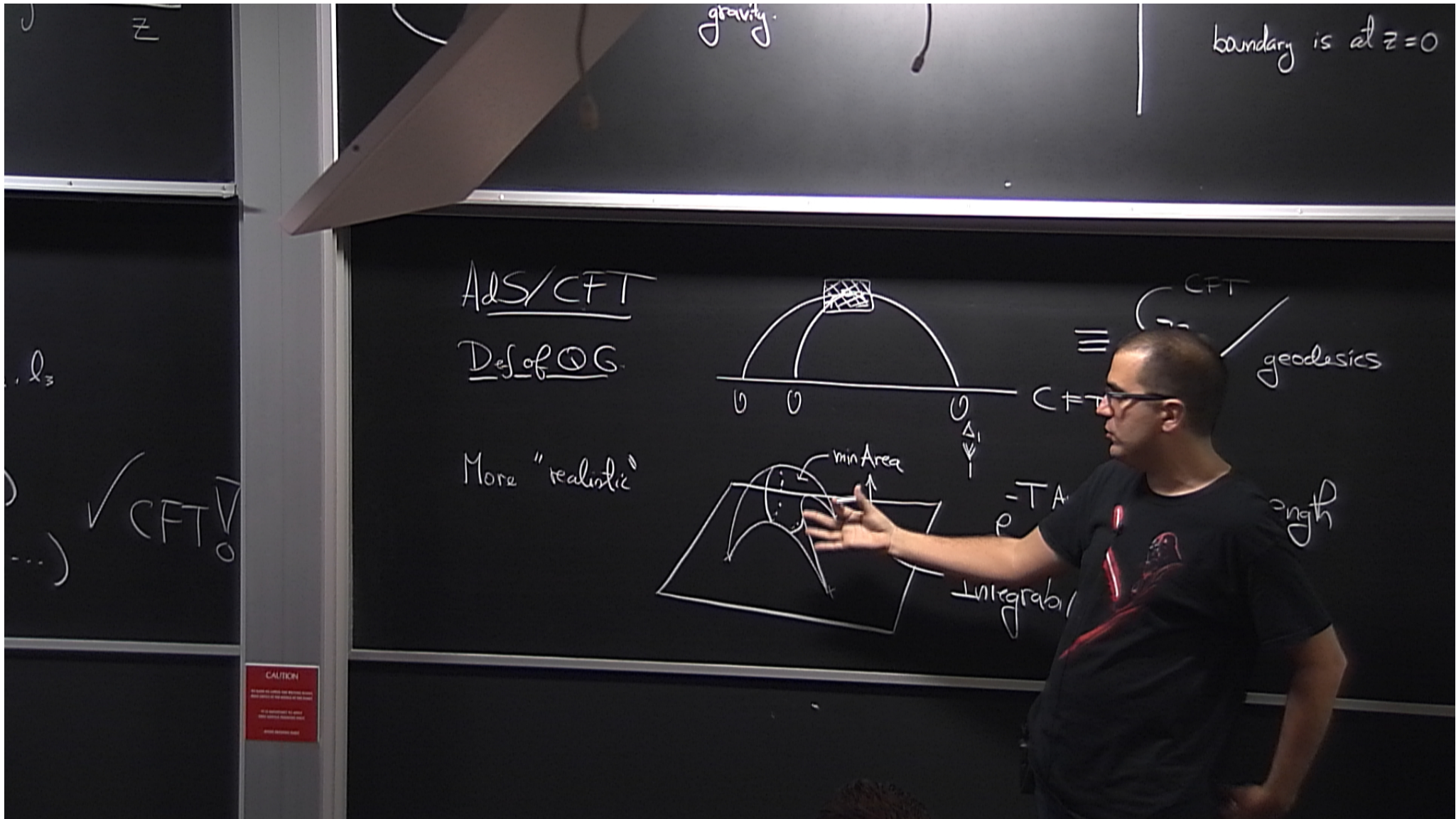
CFT

\mathcal{G}_3 / geodesics



$e^{-T \text{ Area}}$ ← $e^{-m \text{ Length}}$

CAUTION
DO NOT TOUCH THE BOARD WHEN THE BOARD IS BEING USED BY OTHERS
IF A MESSAGE IS SHOWN ON THE BOARD PLEASE REPORT IT TO THE BOARD MANAGER



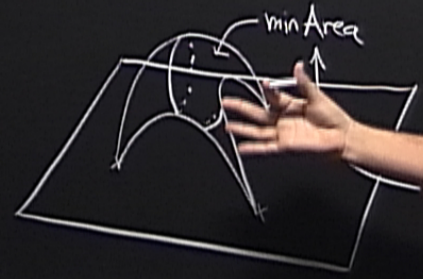
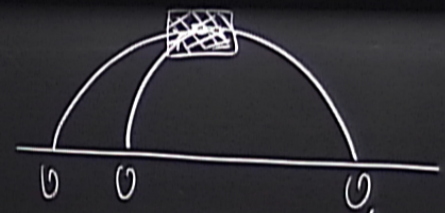
gravity.

boundary is at $z=0$

AdS/CFT

Def of QG

More "realistic"

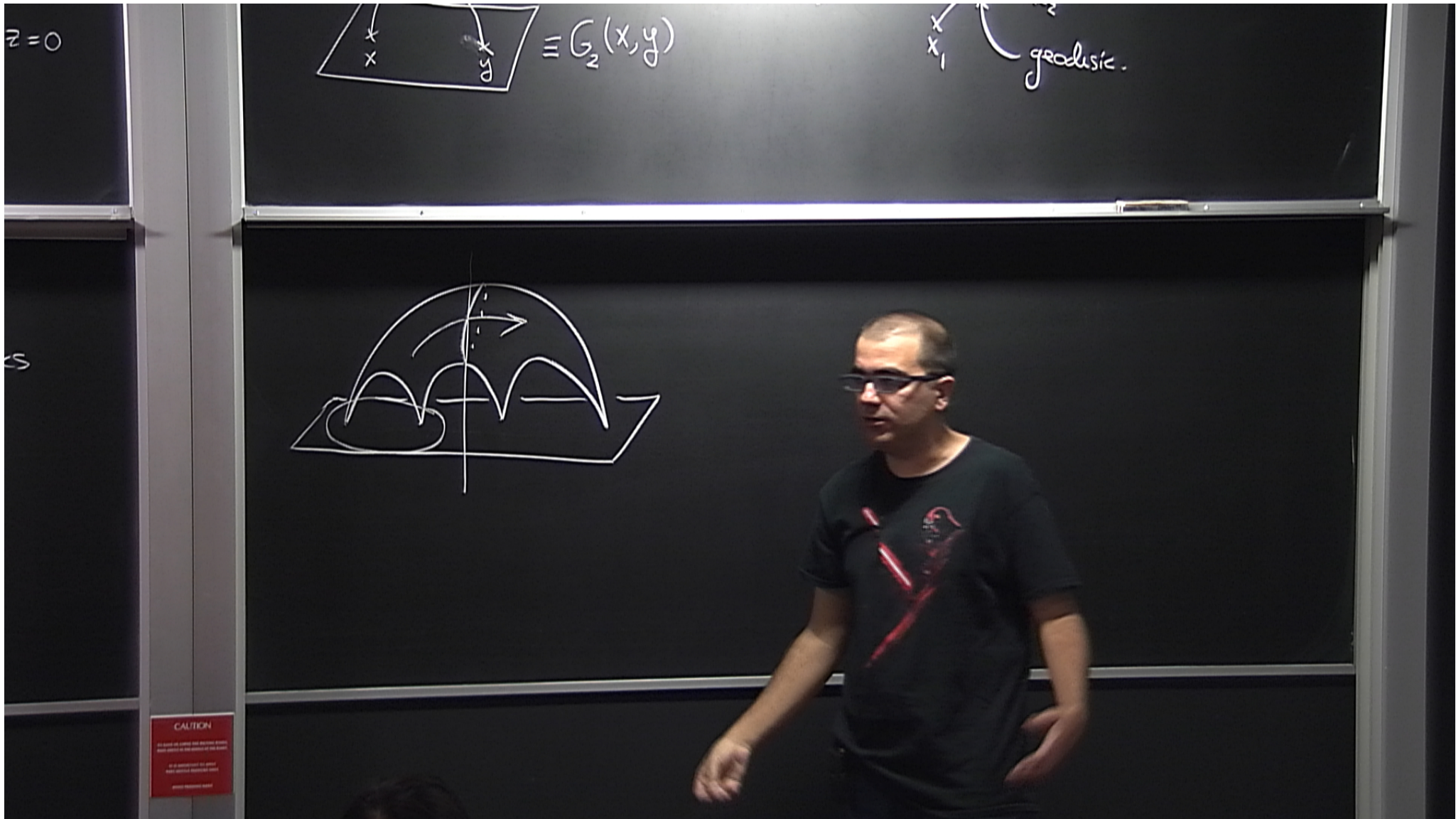


CFT
≡
geodesics

-TA
Integrability

length

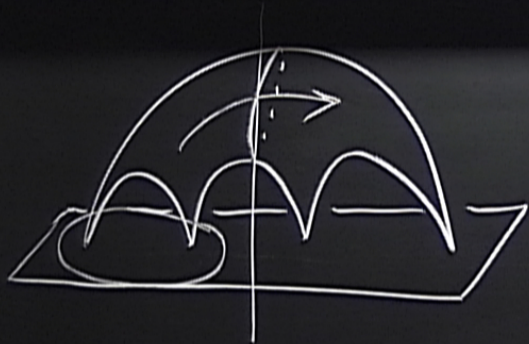
CAUTION
DO NOT TOUCH THE BOARD
OR THE SURFACE OF THE BOARD
OR THE SURFACE OF THE BOARD
OR THE SURFACE OF THE BOARD



$z=0$



x_1 geodesic.



CAUTION
DO NOT TOUCH THE SURFACE
BECAUSE IT IS HOT
OR IN OTHERWISE BE DAMAGED
BY YOUR HANDS