

Title: Resonant Detection of Short-Range Gravitational Forces

Date: Jun 17, 2014 12:00 PM

URL: <http://pirsa.org/14060046>

Abstract: Some theories predict a short-range component to the gravitational force, typically modeled as a Yukawa modification of the gravitational potential. This force is usually detected by measuring the motion of a mechanical oscillator driven by an external mass. In this talk I will discuss such an apparatus optimized for use in the 10-100 micron distance range. The setup consists of a cantilever-style silicon nitride oscillator suspended above a rotating drive mass. Periodic density variations in the drive mass cause an oscillatory gravitational force on the cantilever, whose position is read out using optical interferometry. In order to drive the cantilever precisely on resonance, it must have a broad resonant peak; however, lower quality factors reduce force sensitivity by reducing the amplitude of oscillation for a given drive force. We solve this problem by implementing an effective damping on the oscillator by use of optical feedback. I will discuss further applications of this feedback technique, as well as improvements to the apparatus and future experiments.

Resonant Detection of Short-Range Gravitational Forces

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New Ideas in Low-Energy Tests of
Fundamental Physics
Perimeter Institute
June 17, 2014

Acknowledgements

A. Kapitulnik

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Stanford

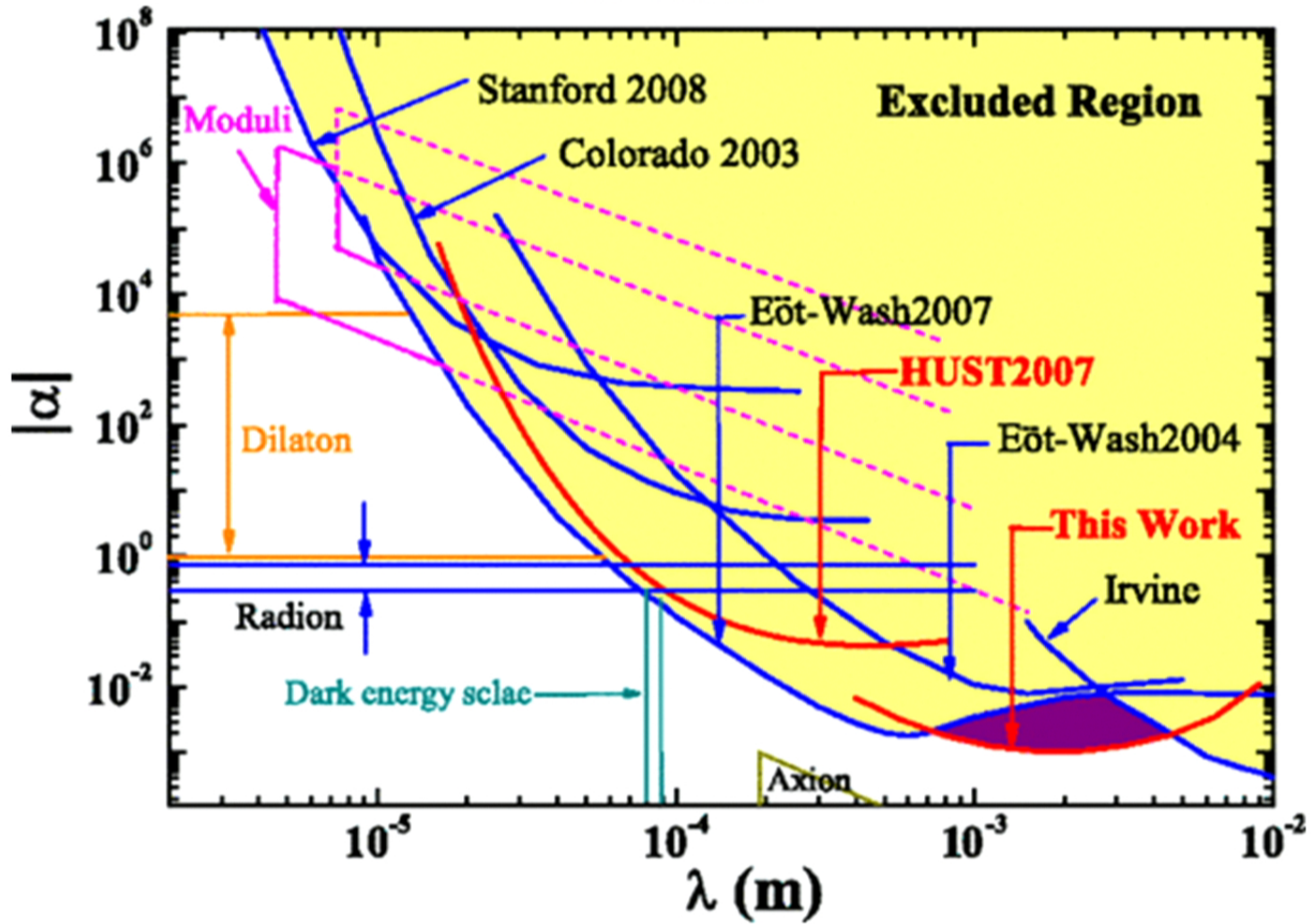
D. Weld

UCSB

Jing Xia

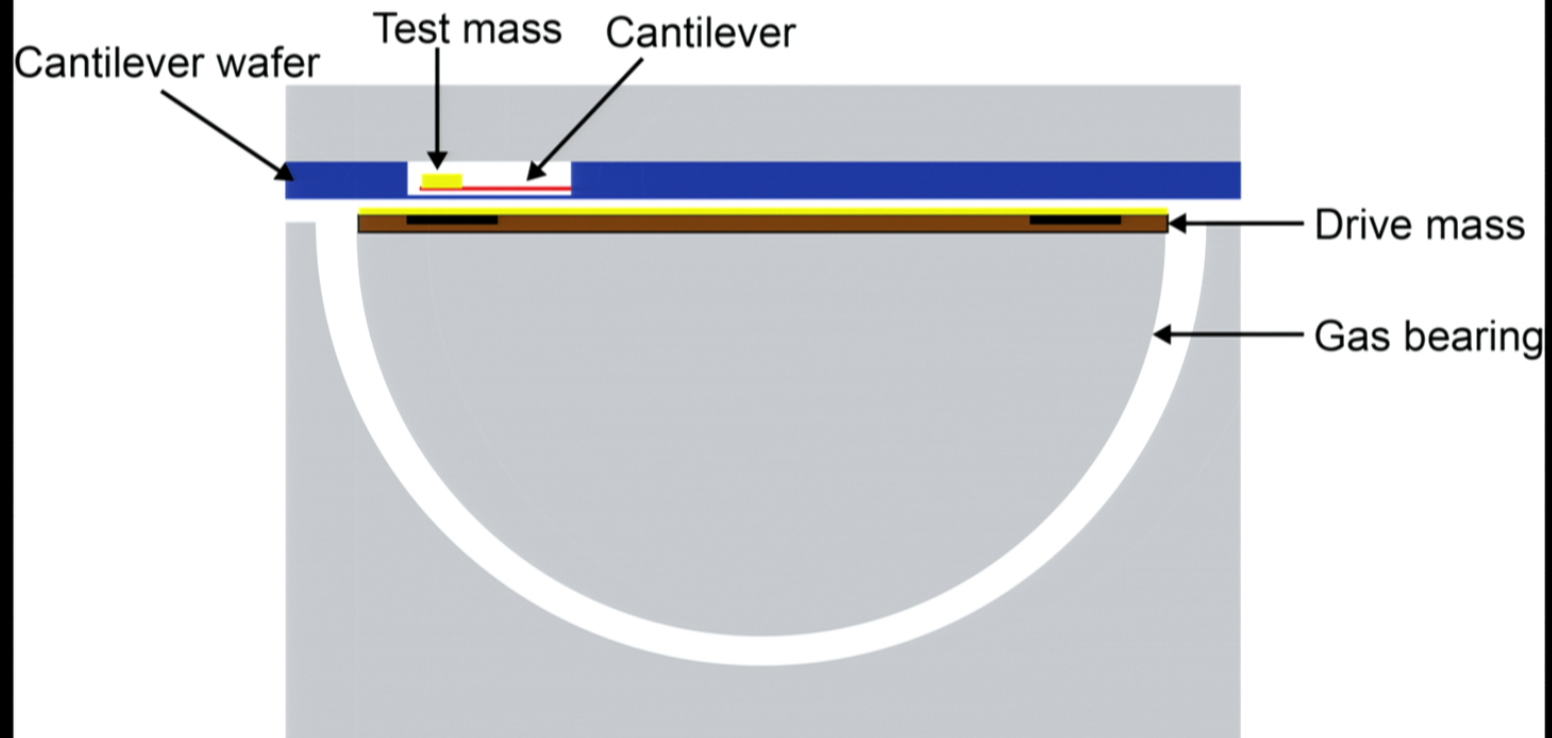
UCI

So far...



Shan-Qing Yang et al., *Phys. Rev. Lett.* **108**, 081101

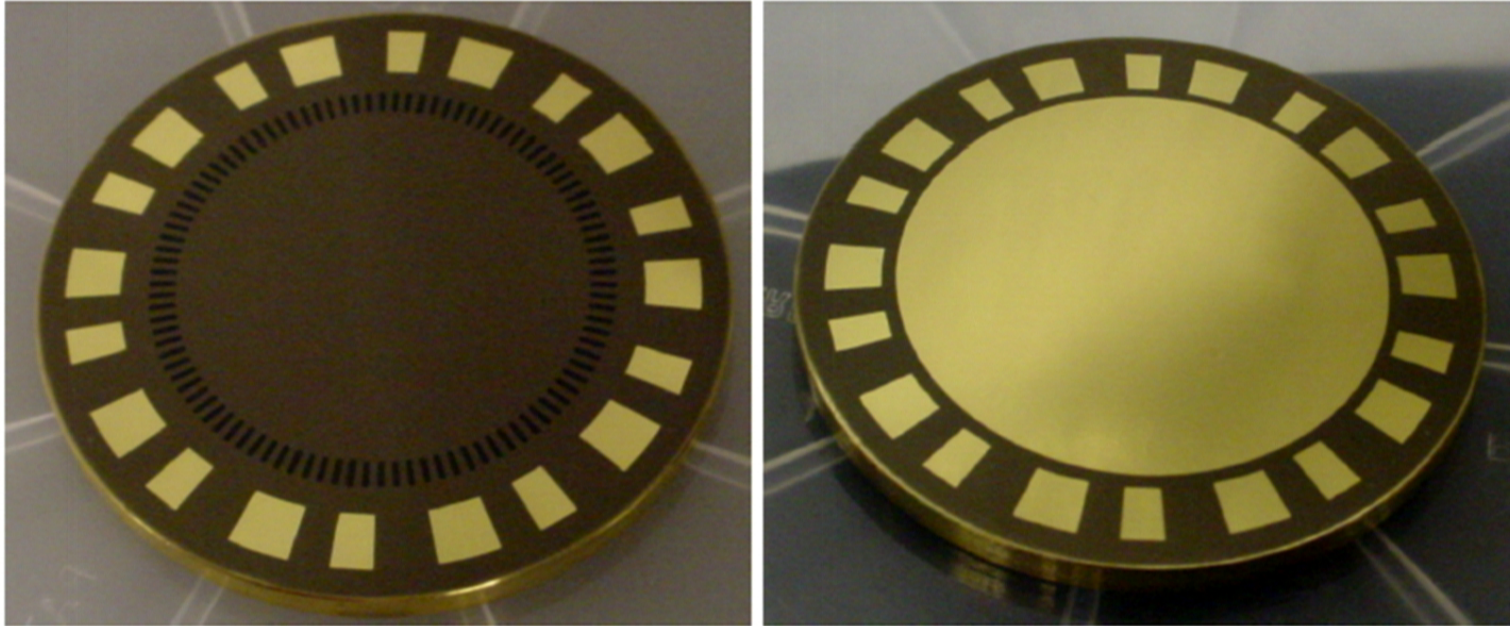
The Basics



Spin gas bearing → alternating metal/epoxy grooves in drive mass → oscillatory force

Drive cantilever on resonance, optically detect position

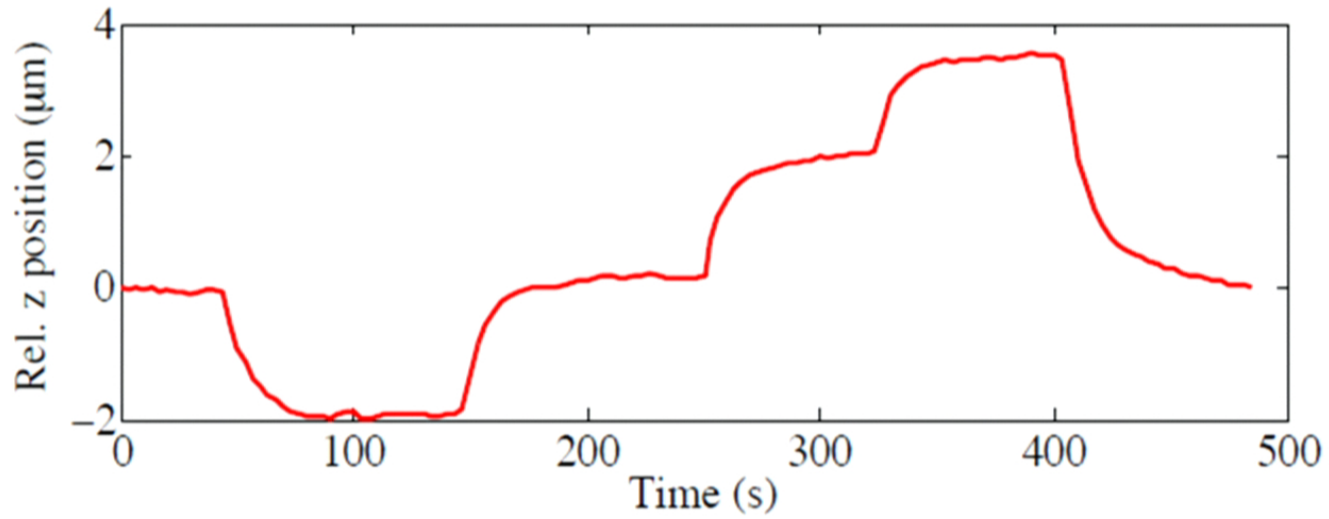
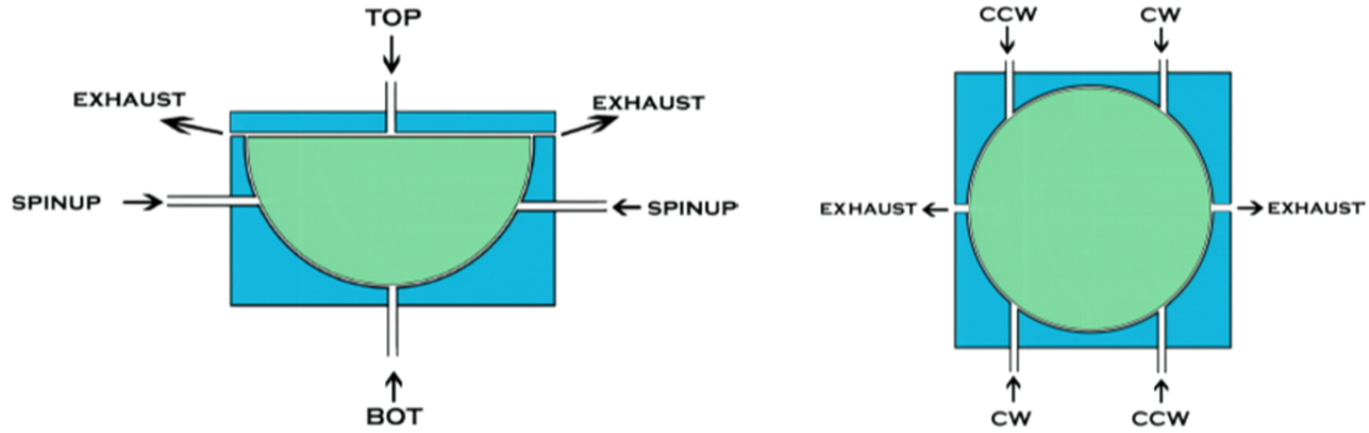
Drive Mass



Copper or brass

Grooves filled with epoxy (lower density)

Helium Gas Bearing



Resonant Drive

Rotation speed control: 0.5 mHz

Mass oscillation control: 50 mHz

Intrinsic resonance linewidth ($Q = 80,000$): ~ 4 mHz

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Need broader resonance!

$$\text{But } F_{min} = \sqrt{\frac{4kk_B T b}{Q \omega_0}}$$

Feedback Cooling

$$x(t) = A \cos(\omega t + \phi)$$

$$v(t) = -\omega A \sin(\omega t + \phi)$$

$$= -\omega A \cos\left(\omega t + \phi - \frac{\pi}{2}\right)$$

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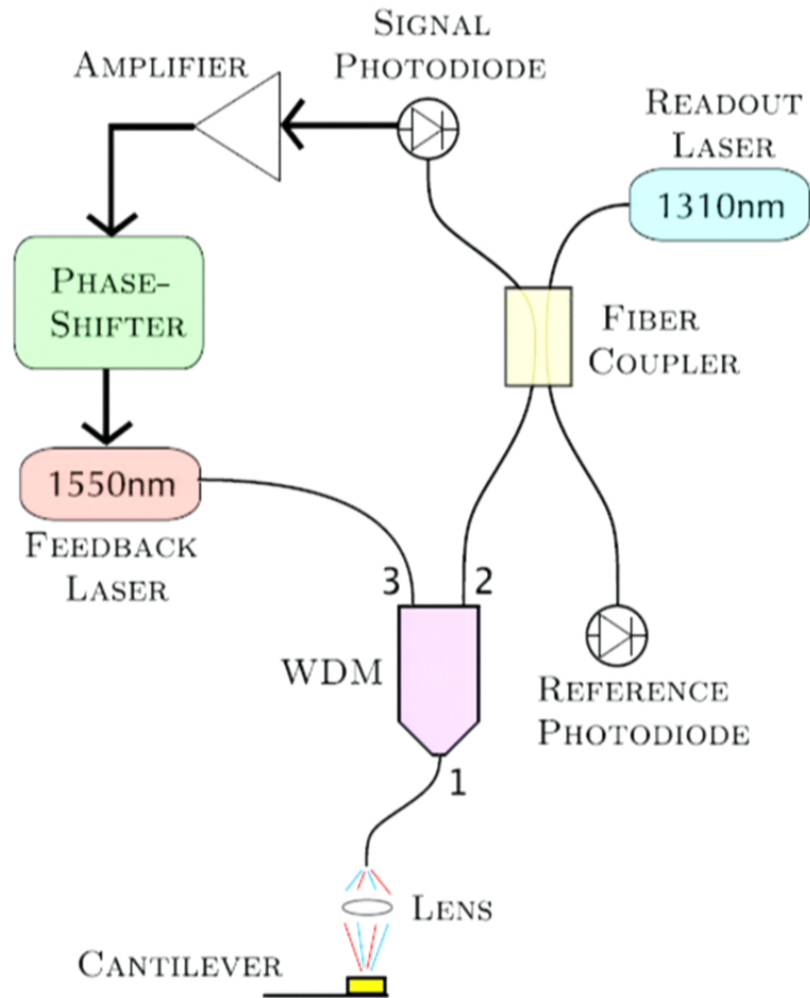
Phase shifted force \rightarrow velocity dependent force \rightarrow damping

Damping is “cold”, eliminates fluctuations \rightarrow lowers T

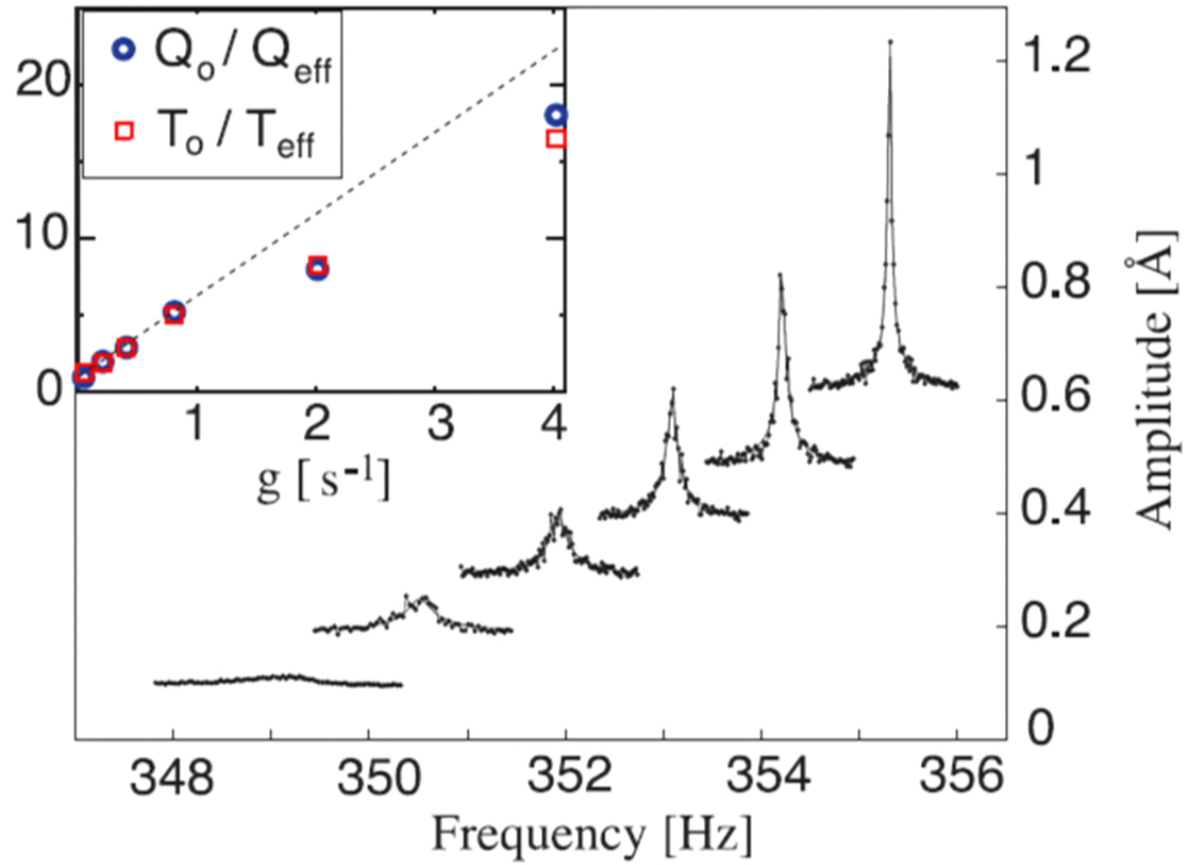
$$Q \rightarrow Q_0 \frac{\Gamma}{\Gamma + g}$$

$$T \rightarrow T_0 \frac{\Gamma}{\Gamma + g}$$

Feedback Cooling



Feedback Cooling



“Recent” Improvements

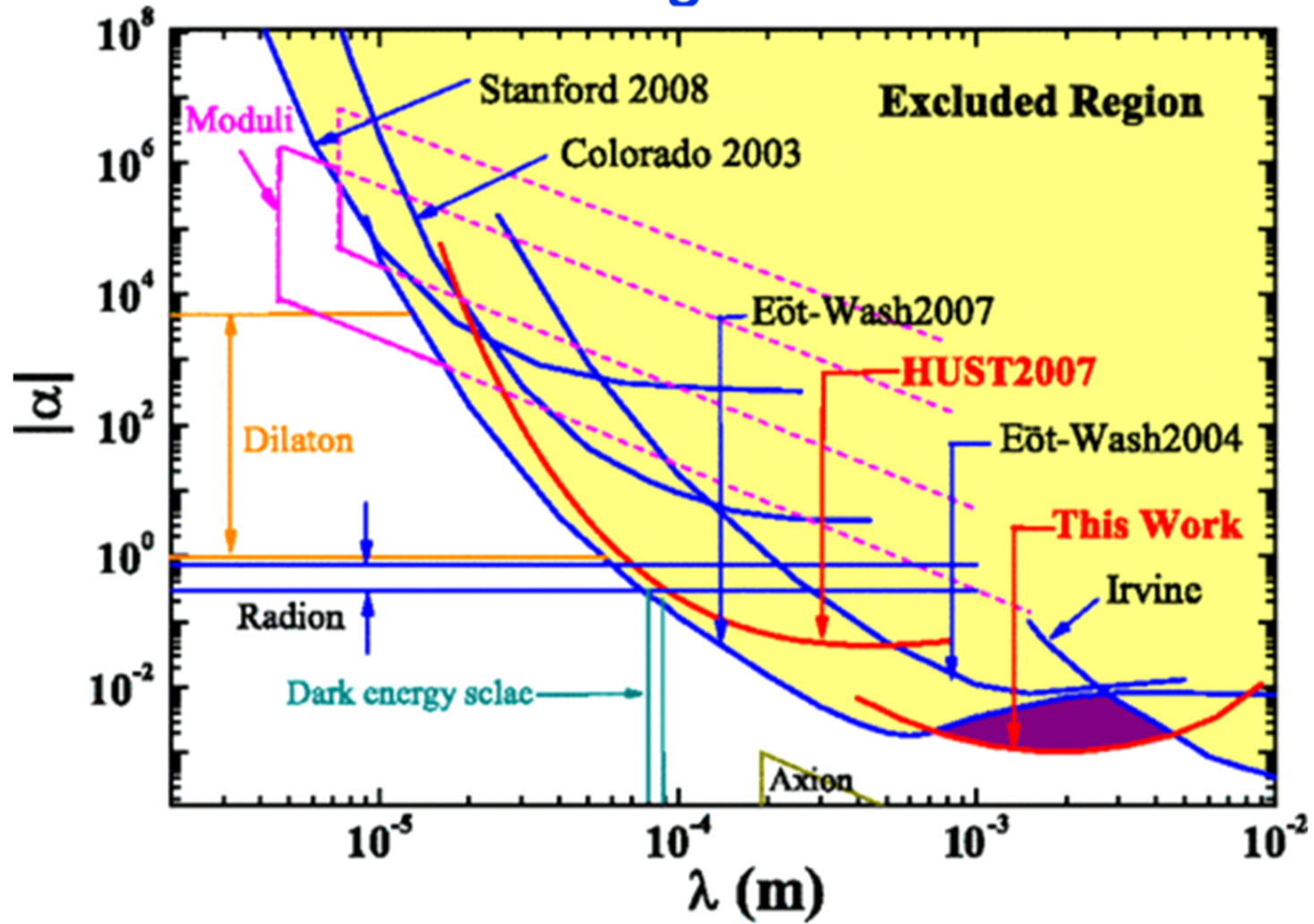


“Recent” Improvements



Improved drive mass → ~1.5x more force
Lower environmental vibrations + additional shielding
Computer-controlled gas flow optimization

The goal



Shan-Qing Yang et al., *Phys. Rev. Lett.* **108**, 081101

In the Future...

How strong can feedback cooling be?

- Optomechanics
- Scanning probe measurements

Neutrinos

Neutrino-neutrino interactions (or new particle) cause β decay with preferential direction

Peter Sturrock

Neutrinos

Neutrino-neutrino interactions (or new particle) cause β decay with preferential direction

Anisotropic decay \rightarrow net force \rightarrow detectable by cantilevers

Big, yellow, oscillatory neutrino source (period \sim 24 hours)

First calculation: $\sim 10^{-13}$ N force for 1 Curie (~ 125 μ g)

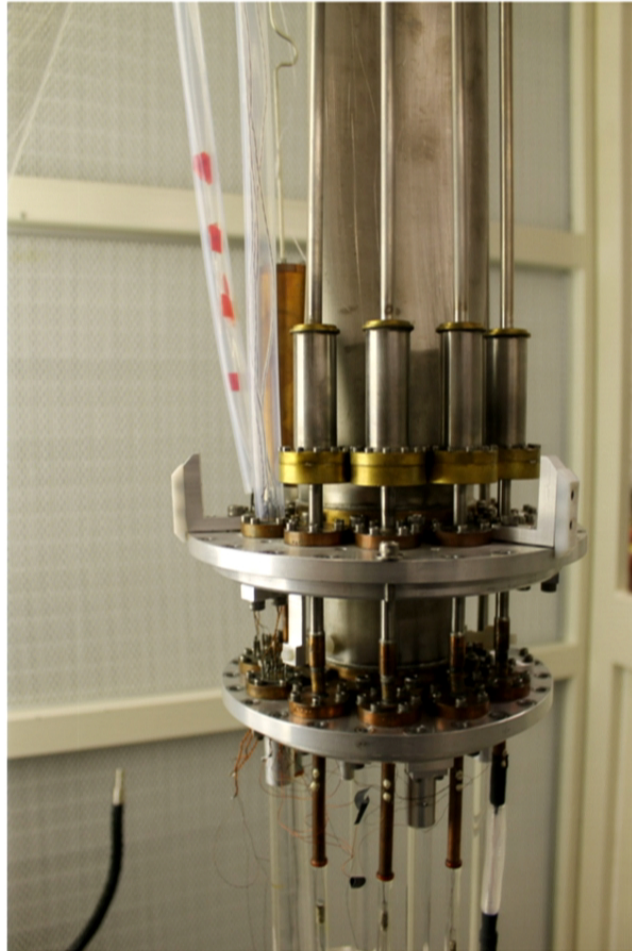
Detectable by our setup!

(Pay no attention to that 1/f noise behind the curtain \rightarrow turntable?)

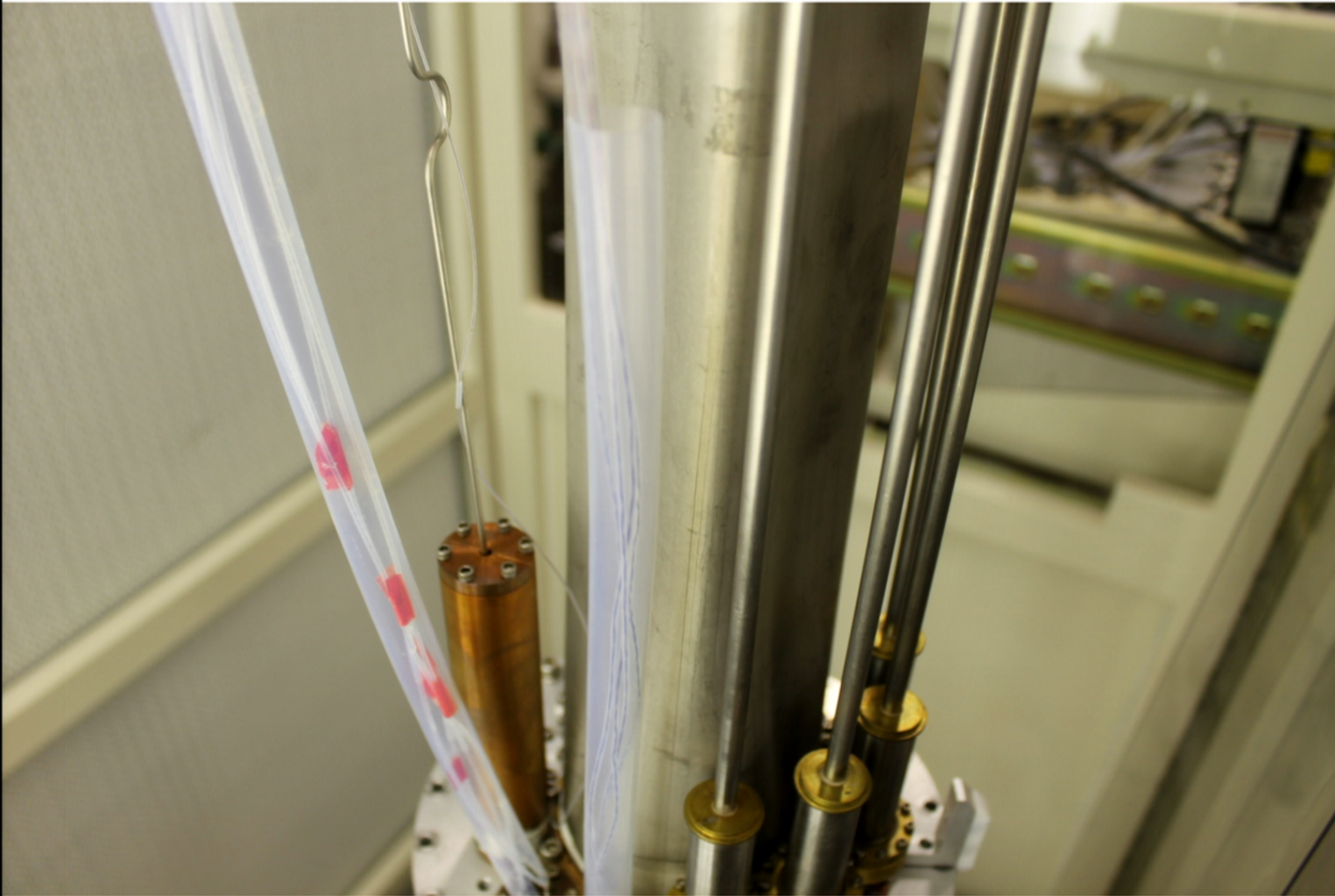
Learn about solar dynamics!

Peter Sturrock

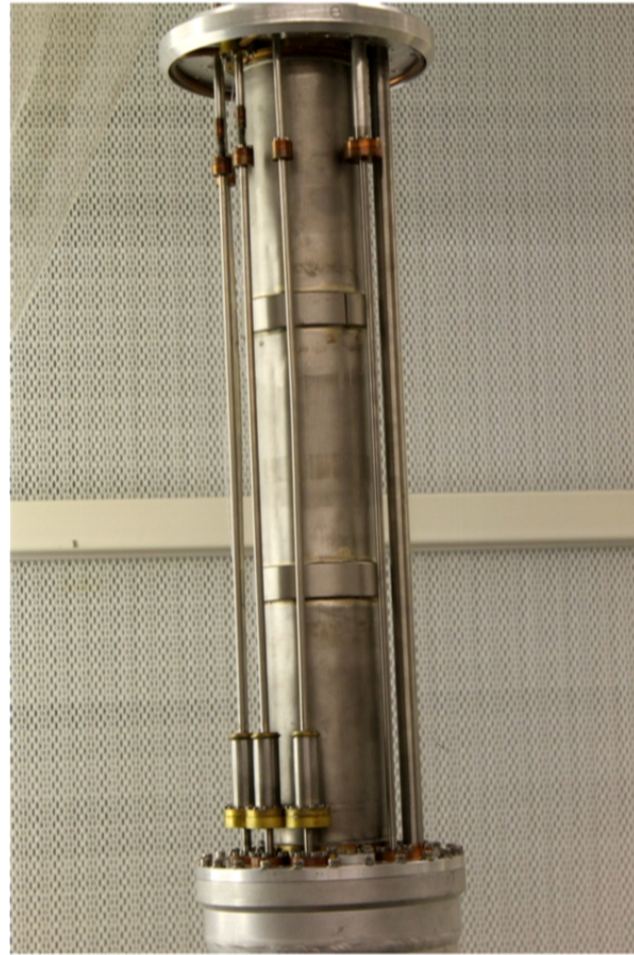
Crunch



Crunch



Fix

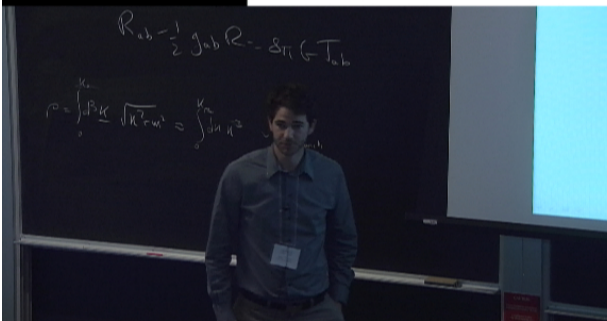


Possibilities

- Drive mass density contrast ($\sim 2x$ improvement possible)
- Lower temperatures \rightarrow probably can't use gas bearing
 - Local cooling?

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- Lower temperatures \rightarrow probably can't use gas bearing
 - Local cooling?
- Raise Q of cantilevers (HARD!)
- Increase mass overlap area (hard, but not quite as bad)
- Multiple cantilevers (CM and DM rejection)
- Parametric modulation?
- Genius ideas from the audience?