

Title: Entanglement and Edge Modes in Gauge Theory and Gravity

Date: May 21, 2014 04:10 PM

URL: <http://pirsa.org/14050122>

Abstract:

Entanglement entropy

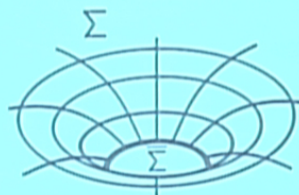
Given a state $|\psi\rangle$ in a product Hilbert space,

$$|\psi\rangle \in \mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$$

Take the partial trace $\rho_\Sigma = \text{Tr}_{\bar{\Sigma}} |\psi\rangle \langle \psi|$.

The resulting entropy is the *entanglement entropy*

$$S = -\text{Tr} \rho_\Sigma \log \rho_\Sigma.$$



This quantity has a number of uses:

- In gravity, as a proposed explanation of black hole entropy,
- In condensed matter theory, as a probe of topological phases,
- In string theory, as part of the AdS/CFT dictionary.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

ep, lower indices

$$L_k + cL = \gamma^A \gamma_A$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} \gamma_B = \gamma_A \gamma^{AB} \gamma_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\alpha\beta\gamma\delta} \rightarrow \int e^{\mu\nu} \eta e^{\alpha\beta} F^{\gamma\delta} \epsilon_{\alpha\beta\gamma\delta}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} \omega^b & -\omega^b \end{pmatrix}$$

$$\times \quad \times$$

Entanglement entropy

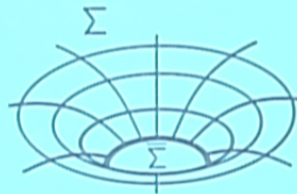
Given a state $|\psi\rangle$ in a product Hilbert space,

$$|\psi\rangle \in \mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$$

Take the partial trace $\rho_\Sigma = \text{Tr}_{\bar{\Sigma}} |\psi\rangle \langle \psi|$.

The resulting entropy is the *entanglement entropy*

$$S = -\text{Tr} \rho_\Sigma \log \rho_\Sigma.$$



This quantity has a number of uses:

- In gravity, as a proposed explanation of black hole entropy,
- In condensed matter theory, as a probe of topological phases,
- In string theory, as part of the AdS/CFT dictionary.

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma^A{}_\mu V_A^\mu$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{\mu\nu} y_B = \gamma_A^\mu \gamma^{\nu\lambda} y_B^\lambda$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a F^a \epsilon_{abcd} \rightarrow \int e^a \eta e^b F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B{}_C = \begin{pmatrix} \omega^B \\ \omega^C \end{pmatrix}$$

$$\times \quad \times$$

Gauge symmetry

Many interesting examples have local gauge symmetry:

Topological phases Emergent gauge symmetry

AdS/CFT $SU(N)$ gauge symmetry, N large

Gravity Diffeomorphism symmetry

For gauge fields the factorization $\mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$ doesn't hold!

Main question:

- What replaces this factorization in a gauge theory?
- Is there a sensible notion of entanglement entropy?

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + c_L = \gamma^{A'} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma^{A'} \gamma^{B'} y_{B'}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a \wedge F^a \epsilon_{\text{edge}} \rightarrow \int e^a \wedge e^b \wedge F^{cd} \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\times \quad \times$$

Gauge symmetry

Many interesting examples have local gauge symmetry.

Topological phases Emergent gauge symmetry

AdS/CFT $SU(N)$ gauge symmetry, N large

Gravity Diffeomorphism symmetry

For gauge fields the factorization $\mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$ doesn't hold!

Main question:

- What replaces this factorization in a gauge theory?
- Is there a sensible notion of entanglement entropy?

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

eg, lower indices

$$L_A + c L = \gamma^{A'} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_A \gamma^{AB} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta} \rightarrow \int e^{\mu\nu\alpha\beta} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B{}_C = \begin{pmatrix} \omega \\ \end{pmatrix}$$

$$\times \quad \times$$

Gauge symmetry

Many interesting examples have local gauge symmetry:

- Topological phases Emergent gauge symmetry
- AdS/CFT $SU(N)$ gauge symmetry, N large
- Gravity Diffeomorphism symmetry

For gauge fields the factorization $\mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$ doesn't hold!

Main question:

- What replaces this factorization in a gauge theory?
- Is there a sensible notion of entanglement entropy?

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

eg, lower indices

$$L_A + C_A = \gamma^{AB} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \gamma_A \gamma^{AB} y_B = \gamma'_A \gamma'^{AB} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\eta(D\epsilon)^{\mu\nu} F^{\alpha\beta} \epsilon_{\alpha\beta\gamma\delta} \rightarrow \int e^{\mu\nu} e^{\alpha\beta} F^{\gamma\delta} \epsilon_{\alpha\beta\gamma\delta}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^B_C & \epsilon^B_C \\ 0 & 0 \end{pmatrix} \quad \times \quad \times$$

Gauge symmetry

Many interesting examples have local gauge symmetry:

- Topological phases Emergent gauge symmetry
- AdS/CFT $SU(N)$ gauge symmetry, N large
- Gravity Diffeomorphism symmetry

For gauge fields the factorization $\mathcal{H} = \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}}$ doesn't hold!

Main question:

- What replaces this factorization in a gauge theory?
- Is there a sensible notion of entanglement entropy?

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + c L = \gamma^{A'} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_A \gamma^{AB} y_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a F^a \epsilon_{abcde} \rightarrow \int e^a e^b F^{cd} \epsilon_{abcd}$$

$$\rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} w & e \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Why no factorization?

States of a gauge theory must be gauge invariant!

On a closed manifold, we have gauge-invariant observables: Wilson loops.

If $\partial\Sigma \neq \emptyset$, we allow Wilson lines to end on the boundary.

New degrees of freedom, *edge modes*, act like charges.

We then have an embedding:

$$\mathcal{H} \subset \mathcal{H}_\Sigma \otimes \mathcal{H}_\Sigma.$$

Only \subset (not $=$) because the endpoints must match.

This construction can be made completely precise on the lattice, and allows us to define an entanglement entropy.

But what if we don't know a complete set of gauge-invariant observables?



$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma_A^{\mu\nu} V_A$$

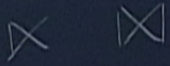
$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A^{\mu\nu} y_B = \gamma_A^{\mu\nu} y_B'$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta} \rightarrow \int e^{\mu\nu\alpha\beta} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} \omega^B_C \\ 0 \end{pmatrix}$$



Why no factorization?

States of a gauge theory must be gauge invariant!

On a closed manifold, we have gauge-invariant observables: Wilson loops.

If $\partial\Sigma \neq \emptyset$, we allow Wilson lines to end on the boundary.

New degrees of freedom, *edge modes*, act like charges.

We then have an embedding:

$$\mathcal{H} \subset \mathcal{H}_\Sigma \otimes \mathcal{H}_\Sigma.$$

Only \subset (not $=$) because the endpoints must match.

This construction can be made completely precise on the lattice, and allows us to define an entanglement entropy.

But what if we don't know a complete set of gauge-invariant observables?



$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma_A^{\mu\nu} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{\mu\nu} y_B = \gamma_A^{\mu\nu} y_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta} \rightarrow (e^{\mu\nu} e^{\alpha\beta} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta})$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^B_C & e^B_C \\ 0 & 0 \end{pmatrix} \quad \times \quad \times$$

Why no factorization?

States of a gauge theory must be gauge invariant!

On a closed manifold, we have gauge-invariant observables: Wilson loops.

If $\partial\Sigma \neq 0$, we allow Wilson lines to end on the boundary.

New degrees of freedom, *edge modes*, act like charges.

We then have an embedding:

$$\mathcal{H} \subset \mathcal{H}_\Sigma \otimes \mathcal{H}_{\bar{\Sigma}},$$

Only \subset (not $=$) because the endpoints must match.



This construction can be made completely precise on the lattice, and allows us to define an entanglement entropy.

But what if we don't know a complete set of gauge-invariant observables?

Why no factorization?

States of a gauge theory must be gauge invariant!

On a closed manifold, we have gauge-invariant observables: Wilson loops.

If $\partial\Sigma \neq \emptyset$, we allow Wilson lines to end on the boundary.

New degrees of freedom, *edge modes*, act like charges.

We then have an embedding:

$$\mathcal{H} \subset \mathcal{H}_\Sigma \otimes \mathcal{H}_\Sigma.$$

Only \subset (not $=$) because the endpoints must match.

This construction can be made completely precise on the lattice, and allows us to define an entanglement entropy.

But what if we don't know a complete set of gauge-invariant observables?



$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma_A^{\mu\nu} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A^{\mu\nu} y_B = \gamma_A^{\mu\nu} y_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\int (D\phi)^n F^{\mu\nu} \epsilon_{\mu\nu\rho\sigma} \rightarrow \int e^{\mu\nu\rho\sigma} F^{\mu\nu} \epsilon_{\rho\sigma\lambda}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} \omega^B_C & 0 \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Classical version

Instead consider a related classical problem

What is the *phase space* Γ_Σ associated to an region Σ with boundary?

Follow the covariant canonical formalism. Given a Lagrangian density L ,

$$\delta L[\phi] = E[\phi] \cdot \delta\phi + d\theta[\phi, \delta\phi].$$

Phase space Γ is solutions of $E[\phi] = 0$.

The phase space has a symplectic potential:

$$\Theta_\Sigma[\phi, \delta\phi] = \int_\Sigma \theta[\phi, \delta\phi]$$

In particle mechanics we would have $\theta = p_i dq^i$ - encodes Poisson brackets.

For closed surface this defines a phase space (Γ, Θ) .

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} \nu \\ \mu \end{pmatrix}$$

ν, μ , lower indices

$$L_A + c_L = \gamma_A^{\mu\nu} \gamma_{\mu\nu}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A^{\mu\nu} \gamma_{\mu\nu} = \gamma_A^{\mu\nu} \gamma_{\mu\nu}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a F^b \epsilon_{abcd} \rightarrow \int e^a \eta e^b F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} \omega^b_c & e^b_c \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Classical version

Instead consider a related classical problem:

What is the *phase space* Γ_Σ associated to a region Σ with boundary?

Follow the covariant canonical formalism. Given a Lagrangian density L ,

$$\delta L[\phi] = E[\phi] \cdot \delta\phi + d\theta[\phi, \delta\phi].$$

Phase space Γ is solutions of $E[\phi] = 0$.

The phase space has a symplectic potential:

$$\Theta_\Sigma[\phi, \delta\phi] = \int_\Sigma \theta[\phi, \delta\phi]$$

In particle mechanics we would have $\theta = p_i dq^i$ - encodes Poisson brackets.

For closed surface this defines a phase space (Γ, Θ) .

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} \nu \\ \mu \end{pmatrix}$$

μ, ν , lower indices

$$L_A + c_L = \gamma_A^{\mu\nu} \gamma_{\mu\nu}^A$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{\mu\nu} \gamma_B = \gamma_A^{\mu\nu} \gamma_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a \eta F^a \epsilon_{abcd} \rightarrow \int e^a \eta e^b \eta F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$A^B_C = \begin{pmatrix} \omega^B_C & 0 \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Yang-Mills

For Yang-Mills, we find the symplectic potential

$$\theta[A, \delta A] = -E \cdot \delta A.$$

This is not gauge invariant. But θ changes only by a total derivative:

$$\Theta_\Sigma[A, \delta A] \rightarrow \Theta_\Sigma[A, \delta A] + \int_S E_\perp \cdot (g^{-1} \delta g)$$

To make Θ gauge-invariant we add a boundary term Θ_S where $S = \partial\Sigma$.
Phase space is (A, g) with symplectic potential $\Theta_\Sigma + \Theta_S$.

Leads to nontrivial Poisson brackets

$$\{E_\perp^a(x), E_\perp^b(y)\} = f_{abc} E_\perp^c \delta(x, y)$$

E_\perp are the edge modes - they commute like surface charges.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} l \\ k \end{pmatrix}$$

ep, lower indices

$$L_A + CL = \gamma^{A'} \gamma_{A'}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} \gamma_B = \gamma_A \gamma^{AB} \gamma_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a \eta F^a \epsilon_{\text{target}} \rightarrow \int e^a \eta e^b \eta F^a \epsilon_{abc,d}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B C = \begin{pmatrix} \omega^b \\ \end{pmatrix}$$

$$\times \quad \times$$

Yang-Mills

For Yang-Mills, we find the symplectic potential

$$\theta[A, \delta A] = -E \cdot \delta A.$$

This is not gauge invariant. But θ changes only by a total derivative:

$$\Theta_\Sigma[A, \delta A] \rightarrow \Theta_\Sigma[A, \delta A] + \int_S E_\perp \cdot (g^{-1} \delta g)$$

To make Θ gauge-invariant we add a boundary term Θ_S where $S = \partial\Sigma$.
Phase space is (A, g) with symplectic potential $\Theta_\Sigma + \Theta_S$.

Leads to nontrivial Poisson brackets

$$\{E_\perp^a(x), E_\perp^b(y)\} = f_{abc} E_\perp^c \delta(x, y)$$

E_\perp are the edge modes - they commute like surface charges.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

eg, lower indices

$$L_A + cL = \gamma^{A\alpha} V'_\alpha$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma'_A \gamma'^{AB} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\eta(D\phi)^a \wedge F^b \epsilon_{abcd} \rightarrow \int e^a e^b \wedge F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B{}_C = \begin{pmatrix} \omega^b{}_c & e^b \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Yang-Mills

For Yang-Mills, we find the symplectic potential

$$\theta[A, \delta A] = -E \cdot \delta A.$$

This is not gauge invariant. But θ changes only by a total derivative:

$$\Theta_\Sigma[A, \delta A] \rightarrow \Theta_\Sigma[A, \delta A] + \int_S E_\perp \cdot (g^{-1} \delta g)$$

To make Θ gauge-invariant we add a boundary term Θ_S where $S = \partial\Sigma$.
Phase space is (A, g) with symplectic potential $\Theta_\Sigma + \Theta_S$.

Leads to nontrivial Poisson brackets

$$\{E_\perp^a(x), E_\perp^b(y)\} = f_{abc} E_\perp^c \delta(x, y)$$

E_\perp are the edge modes - they commute like surface charges.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} l \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma^{A'} \gamma_{A'}^A$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} \gamma_B = \gamma_A \gamma^{AB} \gamma_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a \eta F^a \epsilon_{abcd} \rightarrow \int e^a \eta e^b \eta F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^B_C & e^B_C \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

General relativity

We would like to extend the Yang-Mills result to gravity

- 1 What are the boundary degrees of freedom (analogs of g)?
- 2 What is the symplectic structure?
- 3 What are the generators (analogs of E_\perp)?
- 4 What algebra do they generate?

There is a new issue in general relativity: diffeomorphisms that move S .

For now we focus on diffeomorphisms that preserve S .

Locally split V into tangent part \tilde{V}^A and normal part \hat{V}^i , with $\hat{V}^i|_S = 0$:

- \tilde{V}^A are infinitesimal diffeomorphisms of S ,
- $\partial_i \hat{V}^j$ are deformations of the plane normal to S .

How much of the diffeomorphism group becomes physical?

$$\Rightarrow \begin{pmatrix} M & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \nu \\ \lambda \end{pmatrix}$$

ep, lower indices

$$L_A + cL = \gamma^{A'} V_A$$

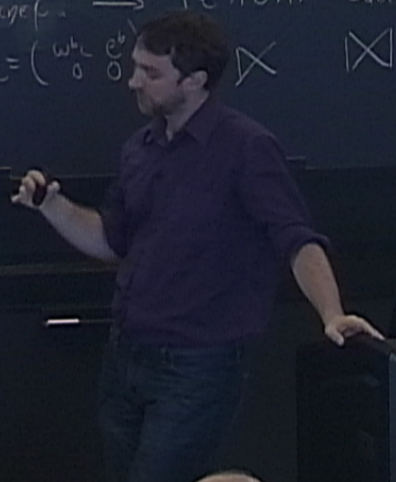
$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_{A'} \gamma^{A'B'} y_{B'}$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a{}_b F^c{}_d \epsilon_{abc} \rightarrow (e^a{}_\mu e^b{}_\nu F^{\mu\nu}) \epsilon_{abc}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B{}_C = \begin{pmatrix} \omega^b{}_c & e^b{}_c \\ 0 & 0 \end{pmatrix}$$



General relativity

We would like to extend the Yang-Mills result to gravity

- 1 What are the boundary degrees of freedom (analogs of g)?
- 2 What is the symplectic structure?
- 3 What are the generators (analogs of E_\perp)?
- 4 What algebra do they generate?

There is a new issue in general relativity: diffeomorphisms that move S .

For now we focus on diffeomorphisms that preserve S .

Locally split V into tangent part \tilde{V}^A and normal part \hat{V}^i , with $\hat{V}^i|_S = 0$:

- \tilde{V}^A are infinitesimal diffeomorphisms of S ,
- $\partial_i \hat{V}^j$ are deformations of the plane normal to S .

How much of the diffeomorphism group becomes physical?

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} \nu \\ \mu \end{pmatrix}$$

ep, lower indices

$$L_A + c_L = \gamma^{A'} \gamma_{A'}^A$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} \gamma_B = \gamma_A \gamma^{AB} \gamma_B$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\int (D\phi)^a \wedge F^a \epsilon_{\text{target}} \rightarrow \int e^a \wedge e^b \wedge F^c \epsilon_{abc,d}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^B_C \\ 0 \end{pmatrix}$$

$$\times \quad \times$$

General relativity

1 What are the boundary degrees of freedom?

- $g_{\mu\nu}$ - a metric on Σ .
- $K_{\mu\nu}$ - extrinsic curvature of Σ .
- X^μ - a diffeomorphism in a neighbourhood of the boundary.

2 What is the symplectic structure?

Following the same procedure as in Yang-Mills, we find

$$\Theta_S[g, X, \delta X] = \frac{1}{2} \int_{X(S)} \sqrt{q} n^{ab} \nabla_a \delta X_b$$

n^{ab} is the unit binormal to S , and q the induced metric on S .

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} \nu \\ \lambda \end{pmatrix}$$

ep, lower indices

$$L_k + cL = \gamma^{A'} V'_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \gamma_A \gamma^{AB} y_B = \gamma'_A \gamma'^{AB} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\alpha\beta\gamma\delta} \rightarrow \int e^\mu n^\nu F^{\alpha\beta} \epsilon_{\alpha\beta\gamma\delta}$$

$$\Rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^b_c & e^b_c \\ 0 & 0 \end{pmatrix} < \quad \times$$

General relativity

- What are the generators (analogs of E_\perp)?

For a vector field V , define

$$H_V \equiv \frac{1}{2} \int_{X(S)} \sqrt{q} n^{ab} \nabla_a V_b$$

These generate diffeomorphisms and satisfy $\{H_V, H_W\} = H_{[V, W]}$.

For a surface-preserving diffeomorphism,

$$H_V = \frac{1}{2} \int_{X(S)} \left(H_{ij} (\epsilon^{ik} \partial_k \hat{V}^j) + \tilde{V}^A A_A \right).$$

$H_{ij} = \frac{\sqrt{\det q}}{\sqrt{-\det h}} h_{ij}$, the (densitized) unimodular normal metric.

$A_A = \sqrt{\det q} [n^0, n^1]_A$, the (densitized) extrinsic twist.

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} v \\ w \end{pmatrix}$$

eg, lower indices

$$L_A + C_A = \gamma^{A'} V_{A'}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_{A'} \gamma^{A'B'} y_{B'}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a F^b \epsilon_{abcd} \rightarrow \int e^a e^b F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} w & 0 \\ 0 & 0 \end{pmatrix} \quad \times \quad \times$$



General relativity

- What are the generators (analogs of E_\perp)?

For a vector field V , define

$$H_V \equiv \frac{1}{2} \int_{X(S)} \sqrt{q} n^{ab} \nabla_a V_b$$

These generate diffeomorphisms and satisfy $\{H_V, H_W\} = H_{[V, W]}$.

For a surface-preserving diffeomorphism,

$$H_V = \frac{1}{2} \int_{X(S)} \left(H_{ij} (\epsilon^{ik} \partial_k \hat{V}^j) + \tilde{V}^A A_A \right).$$

$H_{ij} = \frac{\sqrt{\det q}}{\sqrt{-\det h}} h_{ij}$, the (densitized) unimodular normal metric.

$A_A = \sqrt{\det q} [n^0, n^1]_A$, the (densitized) extrinsic twist.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma^{A'} V_{A'}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

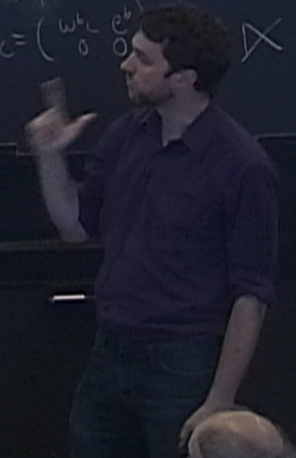
$$\gamma_A \gamma^{AB} y_B = \gamma_{A'} \gamma^{A'B'} y_{B'}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\eta(D\phi)^a F^a \epsilon_{abcd} \rightarrow \int e^a \eta e^b F^c \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} w^B_C & e^B_C \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$



General relativity

- What are the generators (analogs of E_\perp)?

For a vector field V , define

$$H_V \equiv \frac{1}{2} \int_{\mathcal{X}(S)} \sqrt{q} n^{ab} \nabla_a V_b$$

These generate diffeomorphisms and satisfy $\{H_V, H_W\} = H_{[V, W]}$.

For a surface-preserving diffeomorphism,

$$H_V = \frac{1}{2} \int_{\mathcal{X}(S)} \left(H_{ij} (\epsilon^{ik} \partial_k \hat{V}^j) + \tilde{V}^A A_A \right).$$

$H_{ij} = \frac{\sqrt{\det q}}{\sqrt{-\det h}} h_{ij}$, the (densitized) unimodular normal metric.

$A_A = \sqrt{\det q} [n^0, n^1]_A$, the (densitized) extrinsic twist.

$$\Rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma^{A'} V_{A'}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_{A'} \gamma^{A'B} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\int_S X^{\star}(\dots)$$

$$\eta(D\phi)^0 \wedge F^0 \epsilon_{\text{target}} \xrightarrow{c} \int e^{\nu} n^b \wedge F^{cd} \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B$$

$$\begin{pmatrix} e^a & e^b \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

General relativity

What algebra do they generate?

Can read off commutators between geometric quantities from $\{H_V, H_W\}$:

$$\begin{aligned}\{H_{ij}(x), H_{kl}(y)\} &= (\epsilon_{jk} H_{il} + \epsilon_{il} H_{jk})(x) \delta(x, y), \\ \{A_A(x), A_B(y)\} &= A_A(y) \partial_B \delta(x, y) - A_B(x) \partial'_A \delta(x, y), \\ \{H_{ij}(x), A_A(y)\} &= H_{ij}(y) \partial_A \delta(x, y).\end{aligned}$$

- A_A generate diffeomorphisms of S .
- H_{ij} generate normal-plane deformations.
- Together they generate $\text{Diff}(S) \ltimes \text{SL}(2, \mathbb{R})^S$.

The area form is $\sqrt{\det q} = \sqrt{\det H}$, and $\det H$ is the Casimir of $\text{SL}(2, \mathbb{R})$.

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

ep, lower indices

$$L_k + cL = \gamma^{\mu\nu} \partial_\mu \partial_\nu$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{\mu\nu} y_B = \gamma'_A \gamma^{\mu\nu} y'_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\int_S x^{\mu}(\dots)$$

$$\eta(D\phi)^{\mu\nu} F^{\alpha\beta} \epsilon_{\mu\nu\alpha\beta} \rightarrow \int e^{\mu\nu} e^{\alpha\beta} F^{\mu\nu} \epsilon_{\alpha\beta\mu\nu}$$

$$\Rightarrow \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$A^B_C = \begin{pmatrix} \omega^{\mu\nu} & e^{\mu} \\ 0 & 0 \end{pmatrix}$$

$$\times \quad \times$$

Summary

Conclusions

- In a gauge theory, the Hilbert space doesn't factor in the usual way.
- There are new degrees of freedom on S - edge modes.
- Gravity is no exception!
- Boundary degrees of freedom generate gauge transformations - in gravity these are diffeomorphisms of a neighbourhood of S .

Future work

- Surface-moving diffeomorphisms
- Quantization (representations of the diffeomorphism algebra)

Thank you!

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma^{A'} V_A$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{AB} y_B = \gamma_{A'} \gamma^{A'B'} y_{B'}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\int_S X^*(\dots)$$

$$\eta(D\phi)^a \wedge F^a \epsilon_{\text{edge}} \rightarrow \int e^a \wedge e^b \wedge F^{cd} \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad A^B_C = \begin{pmatrix} \omega^b_c & e^b \\ 0 & 0 \end{pmatrix}$$



Summary

Conclusions

- In a gauge theory, the Hilbert space doesn't factor in the usual way.
- There are new degrees of freedom on S - edge modes.
- Gravity is no exception!
- Boundary degrees of freedom generate gauge transformations - in gravity these are diffeomorphisms of a neighbourhood of S .

Future work

- Surface-moving diffeomorphisms
- Quantization (representations of the diffeomorphism algebra)

Thank you!

Summary

Conclusions

- In a gauge theory, the Hilbert space doesn't factor in the usual way.
- There are new degrees of freedom on S - edge modes.
- Gravity is no exception!
- Boundary degrees of freedom generate gauge transformations - in gravity these are diffeomorphisms of a neighbourhood of S .

Future work

- Surface-moving diffeomorphisms
- Quantization (representations of the diffeomorphism algebra)

Thank you!

Summary

Conclusions

- In a gauge theory, the Hilbert space doesn't factor in the usual way.
- There are new degrees of freedom on S - edge modes.
- Gravity is no exception!
- Boundary degrees of freedom generate gauge transformations - in gravity these are diffeomorphisms of a neighbourhood of S .

Future work

- Surface-moving diffeomorphisms
- Quantization (representations of the diffeomorphism algebra)

Thank you!

$$\rightarrow \begin{pmatrix} m & 0 \\ n & 1 \end{pmatrix} \begin{pmatrix} 1 \\ n \end{pmatrix}$$

ep, lower indices

$$L_A + C_A = \gamma_A^{\alpha\beta} V_A$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\gamma_A \gamma^{\alpha\beta} y_B = \gamma_A^{\alpha\beta} \gamma_B^{\alpha\beta} y_B$$

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\int_S X^*(\dots)$$

$$\eta(D\phi)^a \wedge F^a \epsilon_{\text{tough}} \rightarrow \int e^a \wedge e^b \wedge F^{cd} \epsilon_{abcd}$$

$$\Rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} A^B_C = \begin{pmatrix} w^b_c & e^b \\ 0 & 0 \end{pmatrix}$$

