Title: Dynamic Force Patterns of an Undulatory Microswimmer

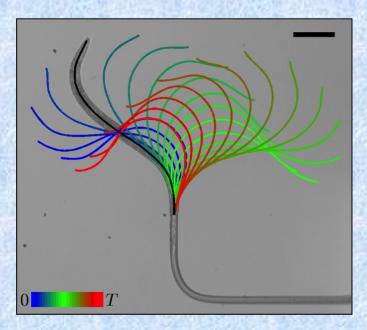
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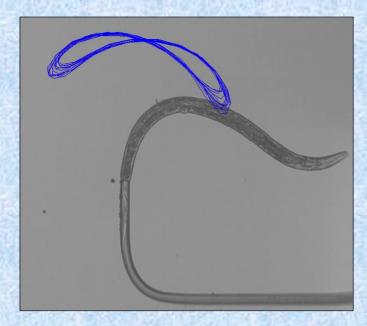
URL: http://pirsa.org/13120038

Abstract: C. elegans is a millimeter-sized nematode which has served as a model organism in biology for several decades primarily due to its simple anatomy. Using an undulatory form of locomotion this worm is capable of propelling itself through various media. Due to the small length scales involved swimming in this regime is qualitatively different from macroscopic locomotion because the swimmers can be considered to have no inertia. In order to understand the microswimming that this worm exhibits it is crucial to determine the viscous forces experienced during its motion. Using a micropipette deflection technique in conjunction with high speed imaging we have directly measured the time-varying forces generated by C elegans during swimming. Furthermore by analyzing the bodys kinematics over time and applying a simple model of locomotion we can compute the theoretical force curves. We observe excellent agreement between the measured and calculated forces. The success of this simple model has important implications in the understanding of microswimming in general.

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The Dynamic Force Measurements on the Nematode *C. elegans*





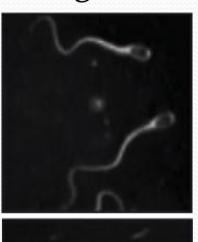
Rafael Schulman, Matilda Backholm, and Kari Dalnoki-Veress

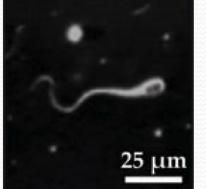
Department of Physics and Astronomy, McMaster University

William S. Ryu

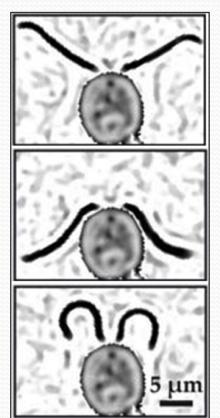
Microswimmers

Helical beating of flagellum

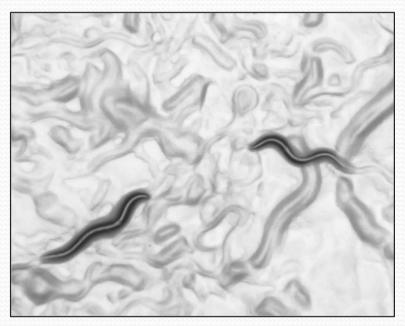




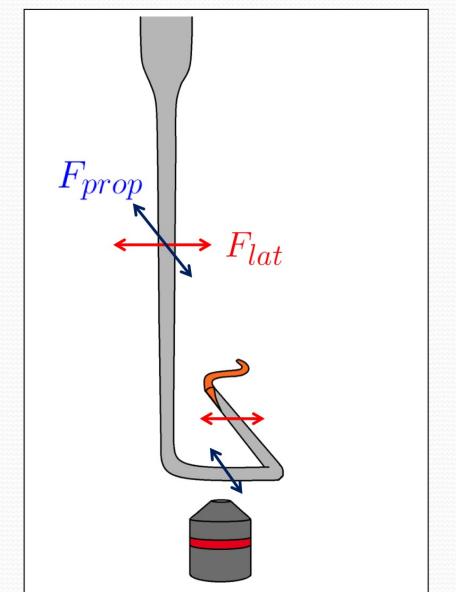
"Breast stroke"

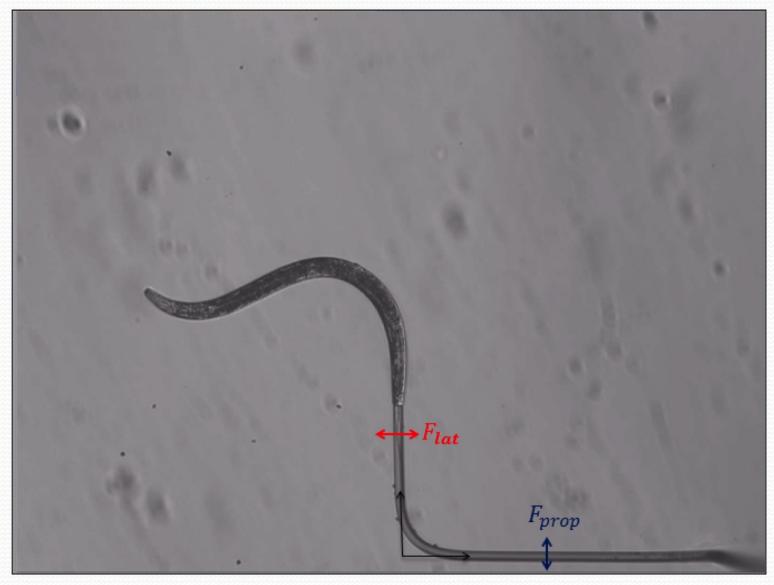


Undulatory



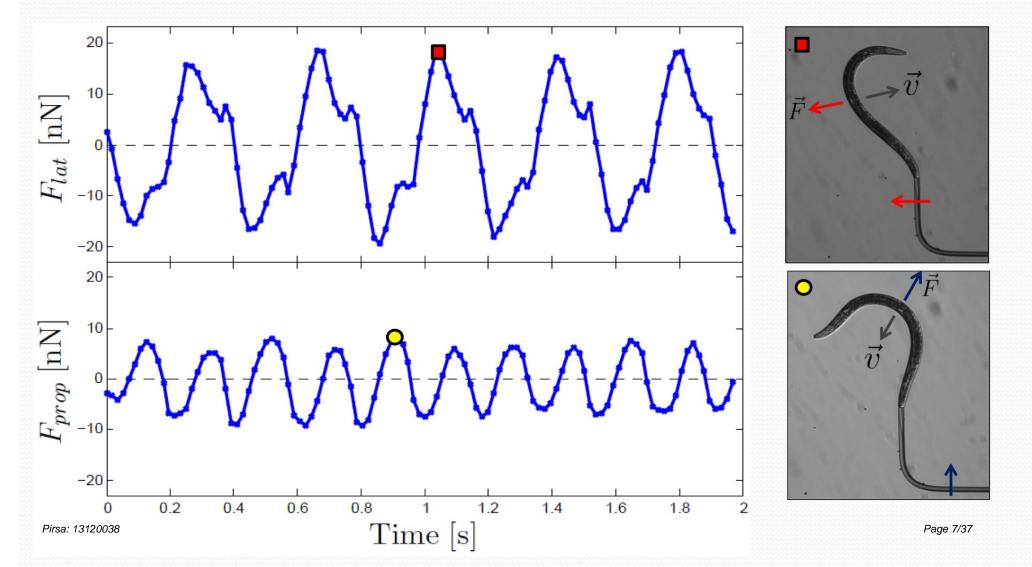
Lateral and Propulsive Forces



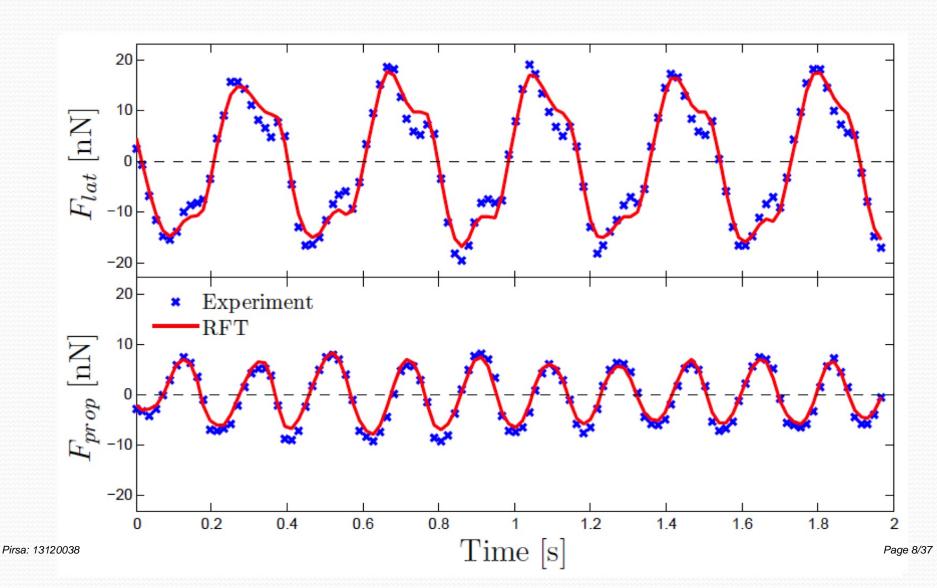




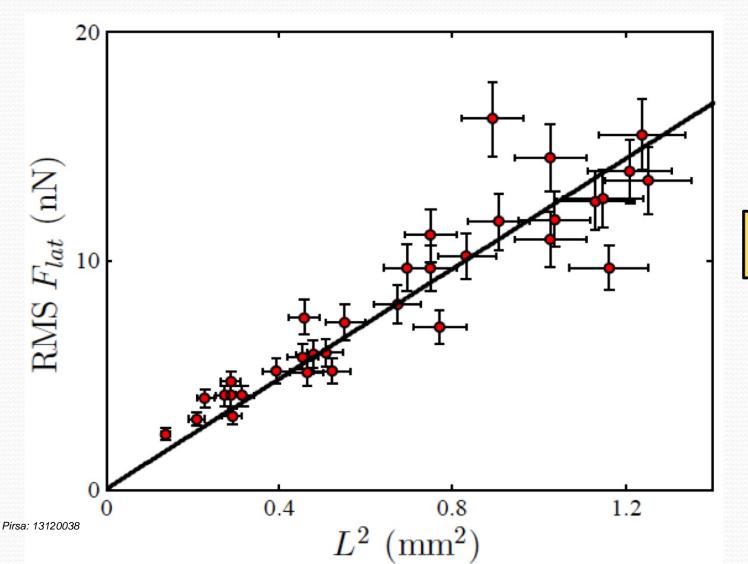
Lateral and Propulsive Forces



Resistive Force Theory (RFT)



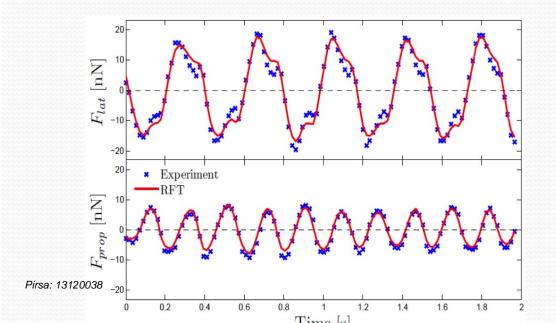
Size Dependence: Lateral



 $|F| \propto L^2$

Conclusions

- Measured forces felt by *C. elegans* during swimming using micropipette deflection
- Resistive Force Theory describes force pattern well
- Forces scale as L^2





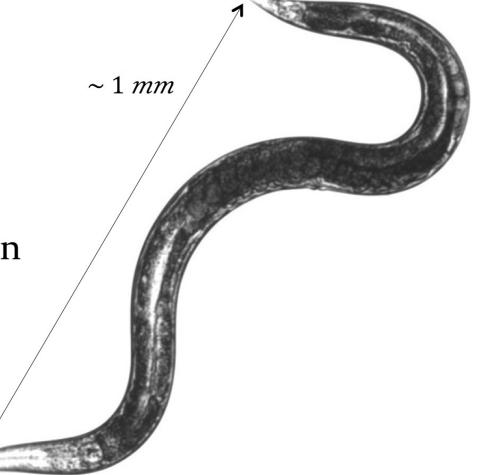
C. elegans

 Hermaphroditic, transparent nematode

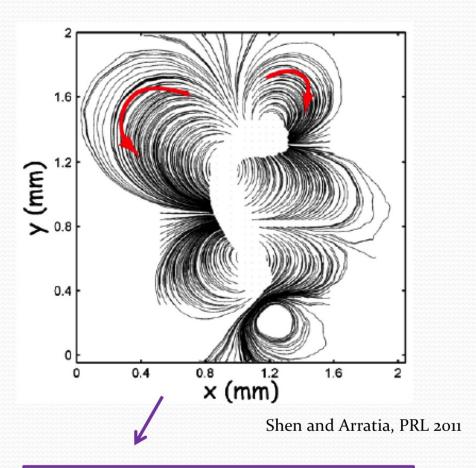
• 959 cells, 302 neurons

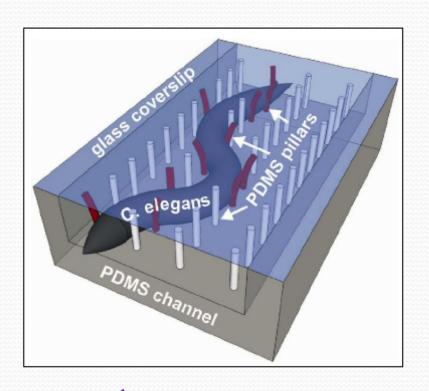
Undulatory locomotion

Swimming and crawling gaits



Measuring Forces





1

Ghanbari, et al., M2VIP08 2008

Fluid velocities \rightarrow Calculate forces

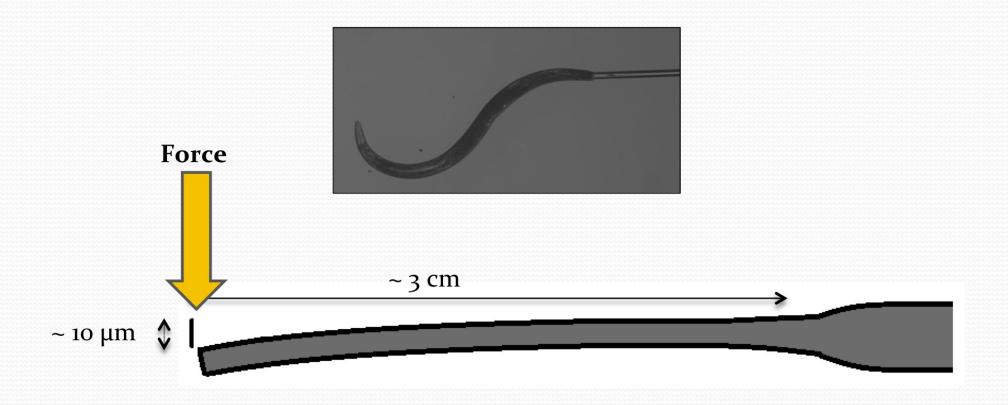
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Pillar → Calculate forces

INDIRECT

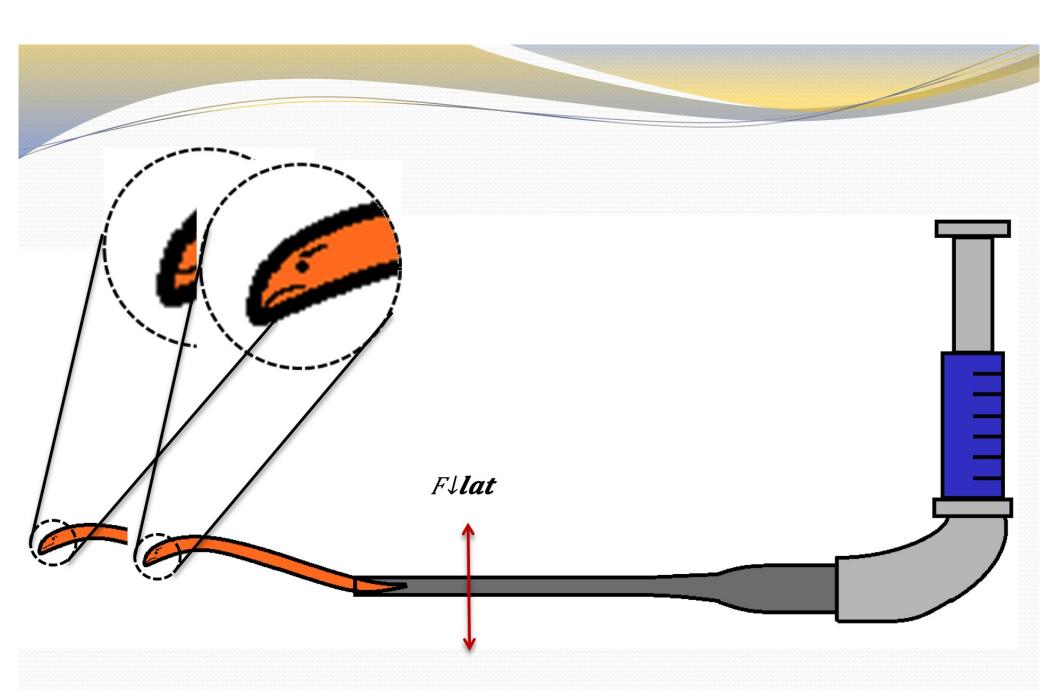
DIRECT

Micropipette Deflection (MD)

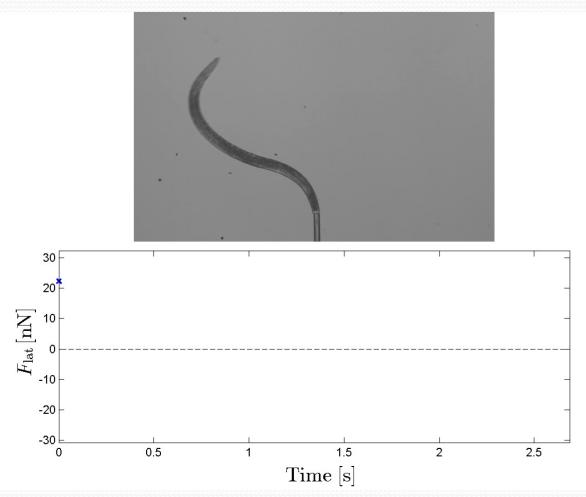


 $k \downarrow b \sim 3 \text{ nN/}\mu\text{m}$

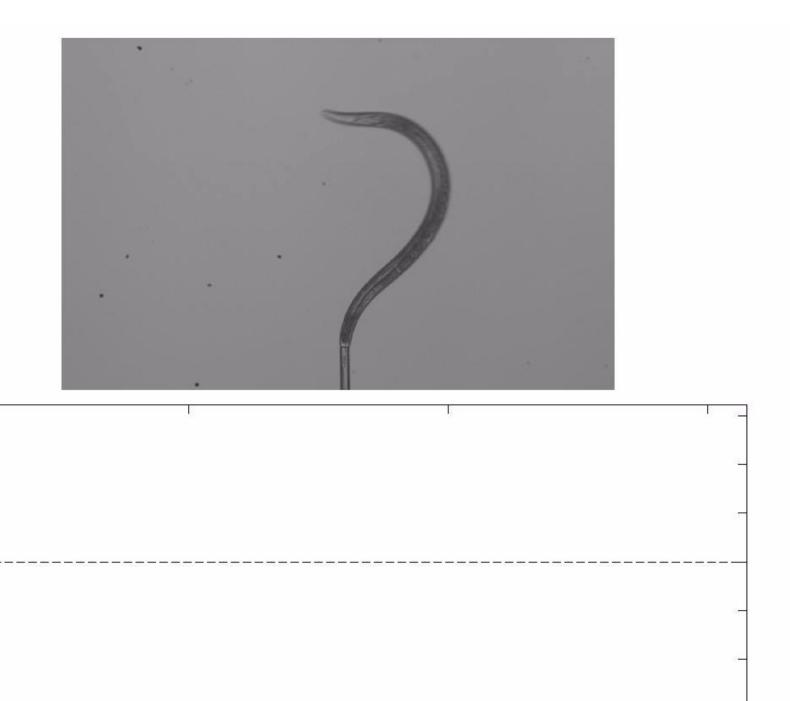
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30 -

20

 $F_{lat}[\mathrm{nN}]$

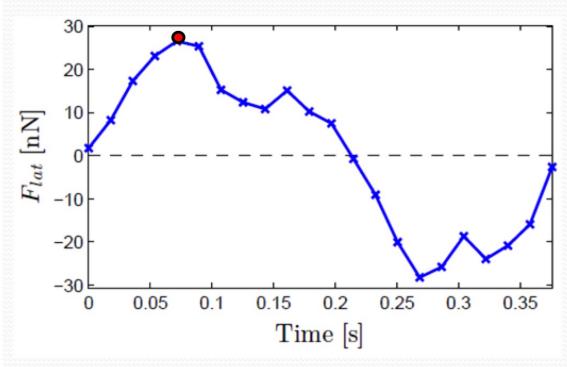
-20

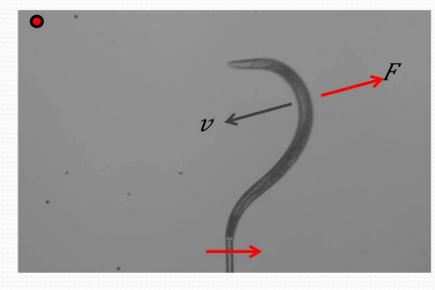
-30 = Pirsa: 1312003**8**0

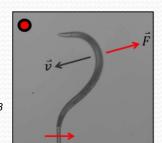
T:--- [-]

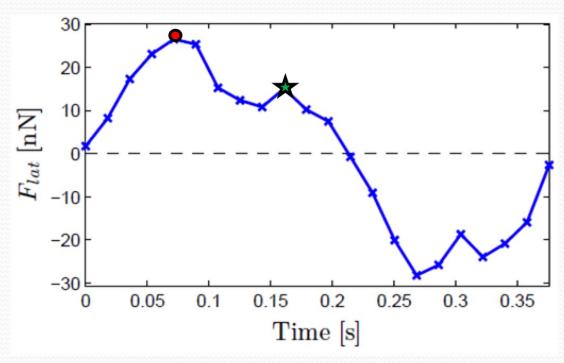
0.5

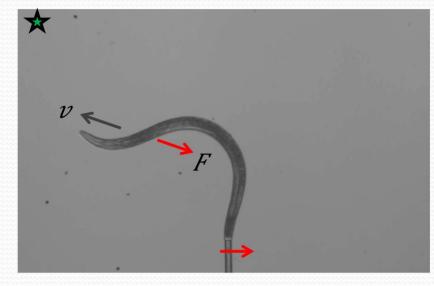
1.5 Page 16/37

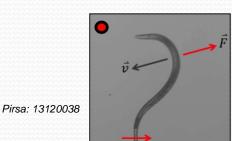


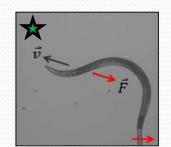


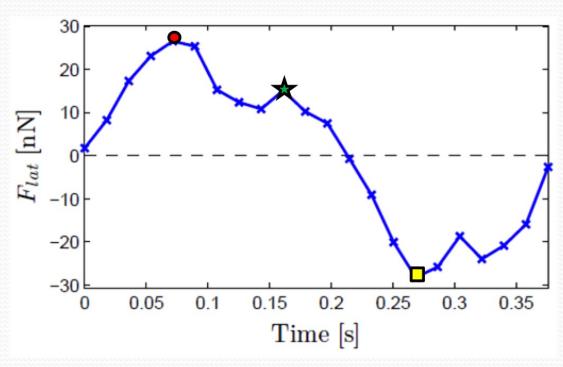


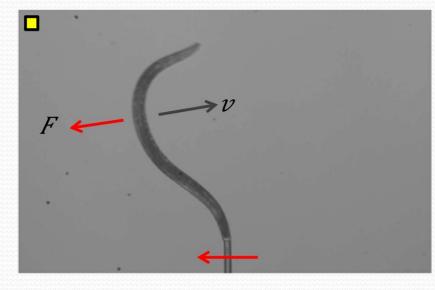


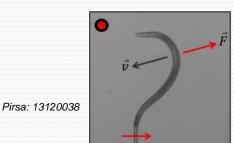


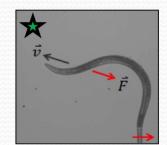


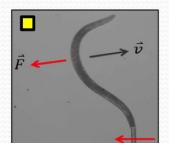


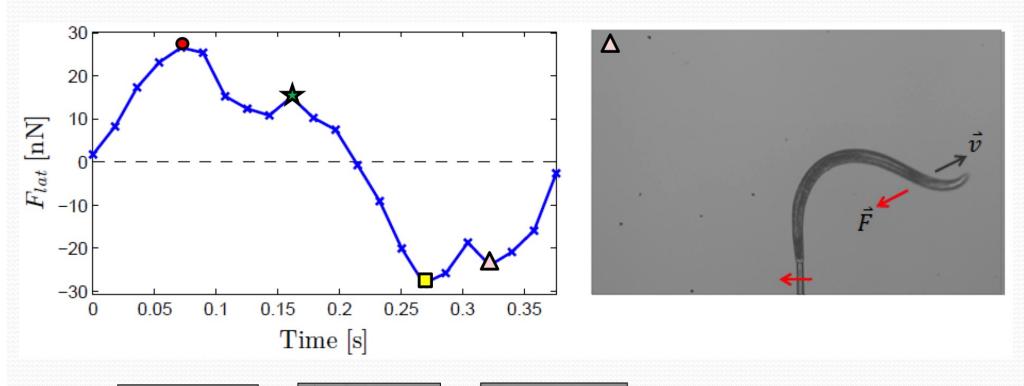


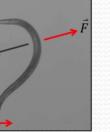


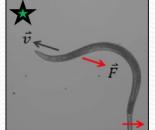


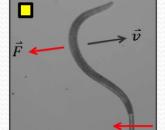




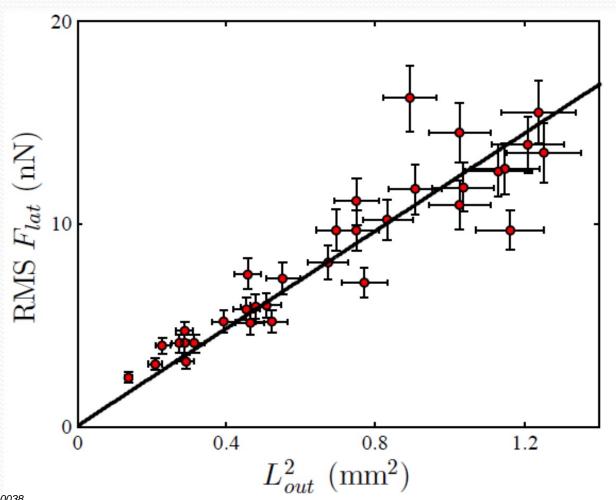








Size Dependence: Lateral



 $|dF| \sim cv \, dL$ c independent of L $|F| \propto vL$ $v \sim A/T/2 \, |F| \propto AL/T$ $A \propto L$ T independent of L

*|F|∝L1*2

Size Dependence: Lateral

 $|F| \sim cvL$

c independent of L

 $|F| \propto vL$

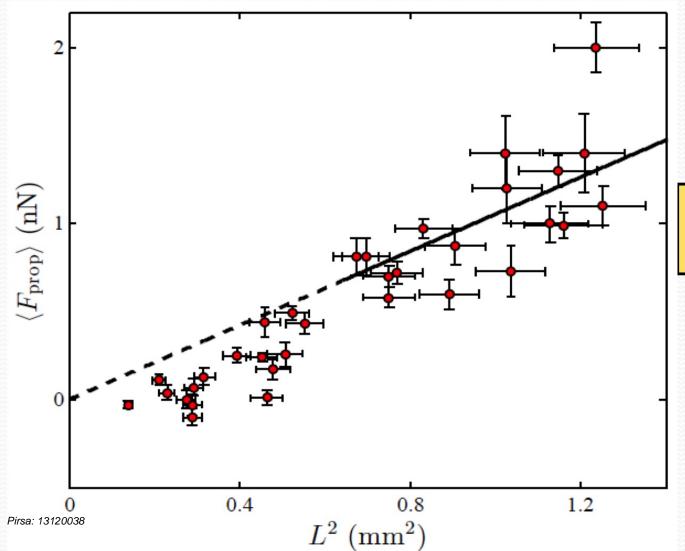
 $v\sim A/T/2$, $|F|\propto AL/T$

 $A \propto L$

T independent of L

*|F|∝L1*2

Size Dependence: Propulsive



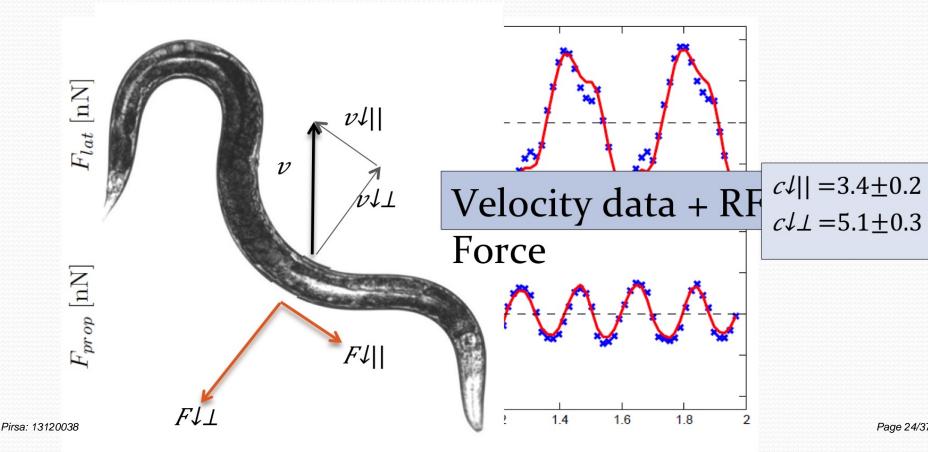
 $\langle F_{prop} \rangle \propto L^2$

Resistive Force Theory (RFT)

 $F \downarrow || \propto -c \downarrow || v \downarrow ||$

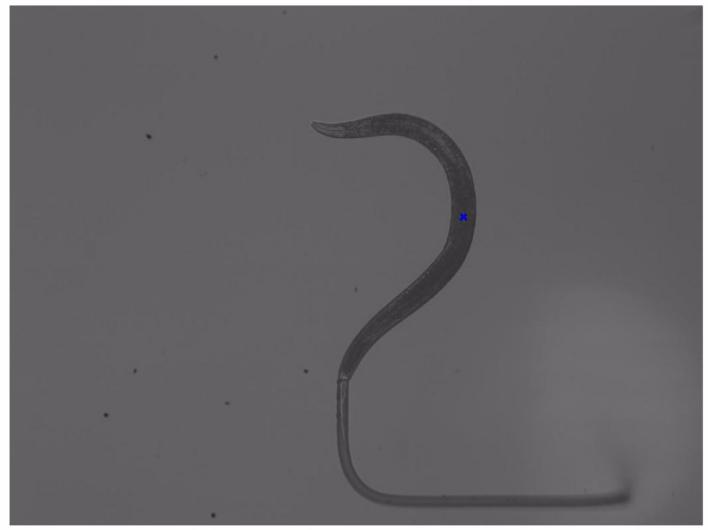
 $F \downarrow \perp \propto -c \downarrow \perp v \downarrow \perp$

 $K=c\downarrow\perp /c\downarrow||\approx 1.5$



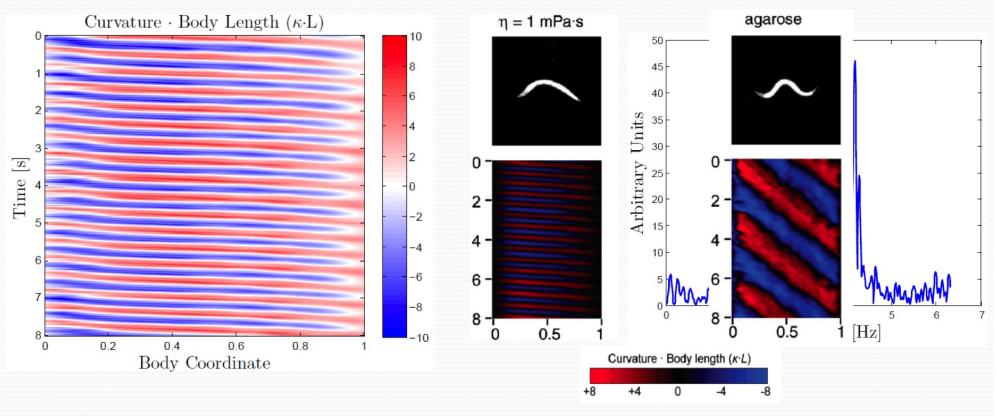
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Trajectory



Swimming?

Forcing a node at tail

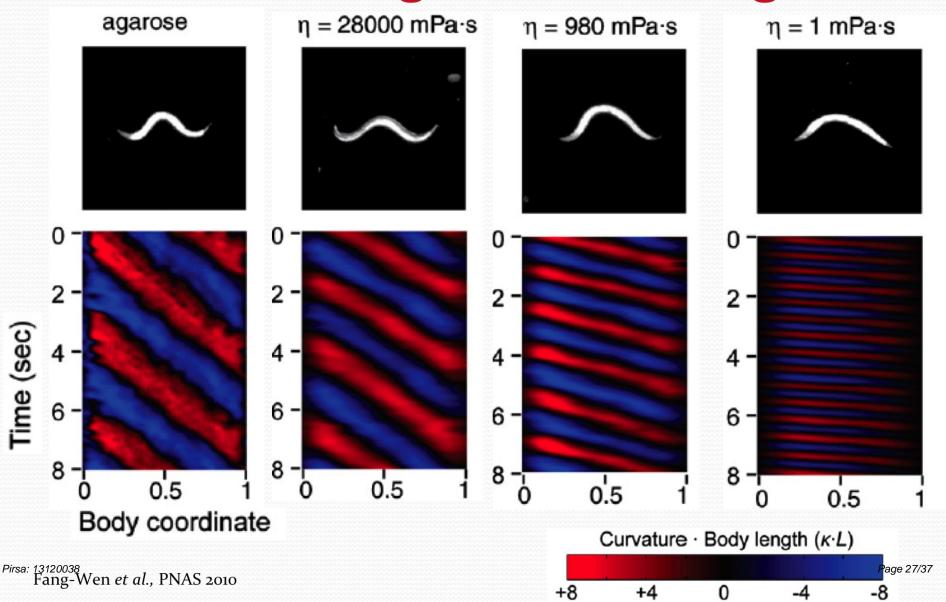


Fang-Yen et al., PNAS 2010

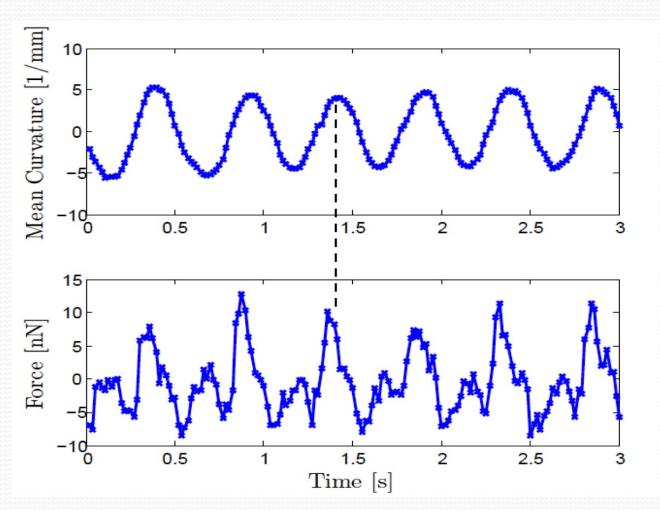
Similar curvature pattern and frequency <



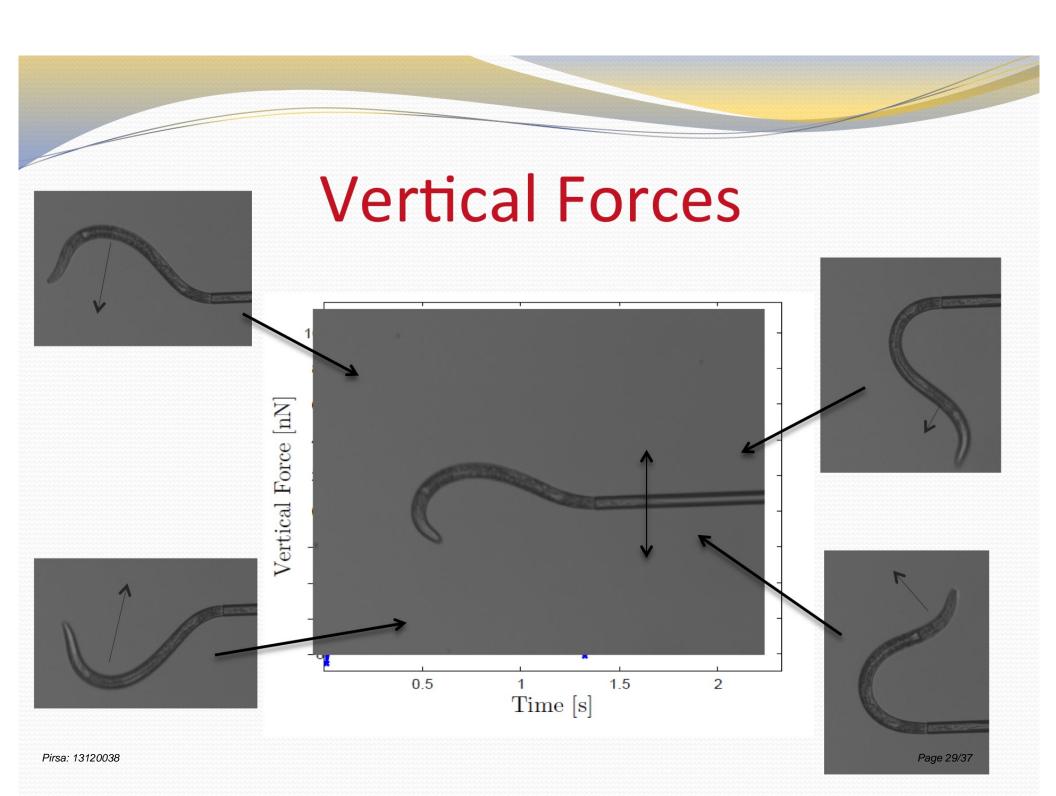
Crawling to Swimming

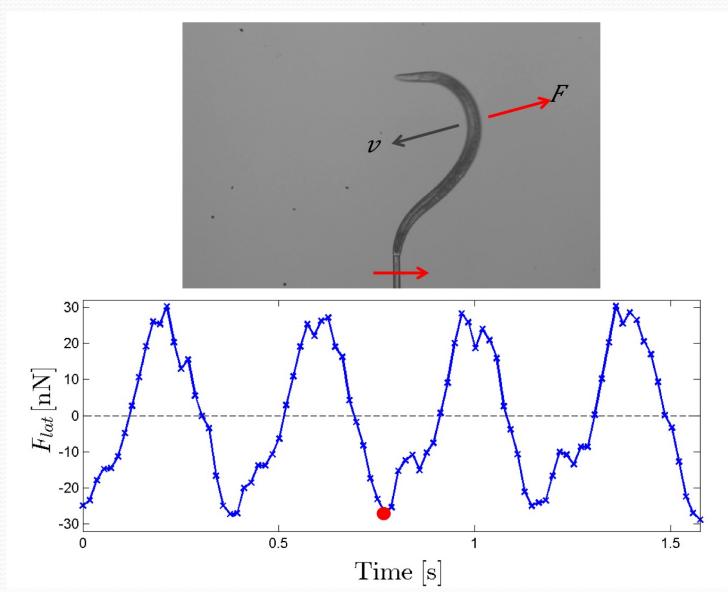


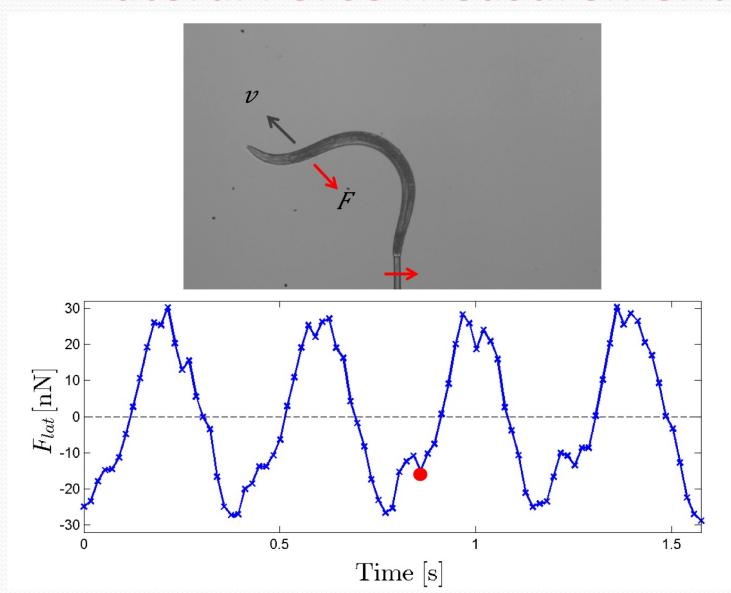
Curvature and Force

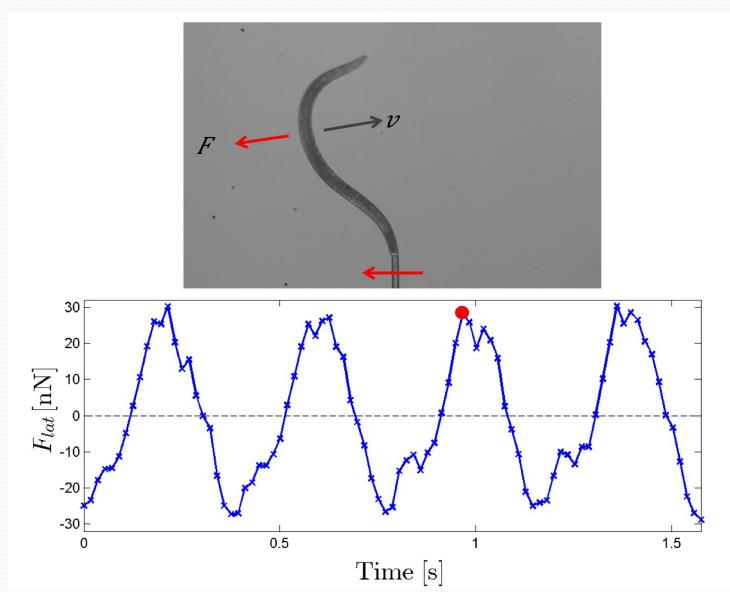


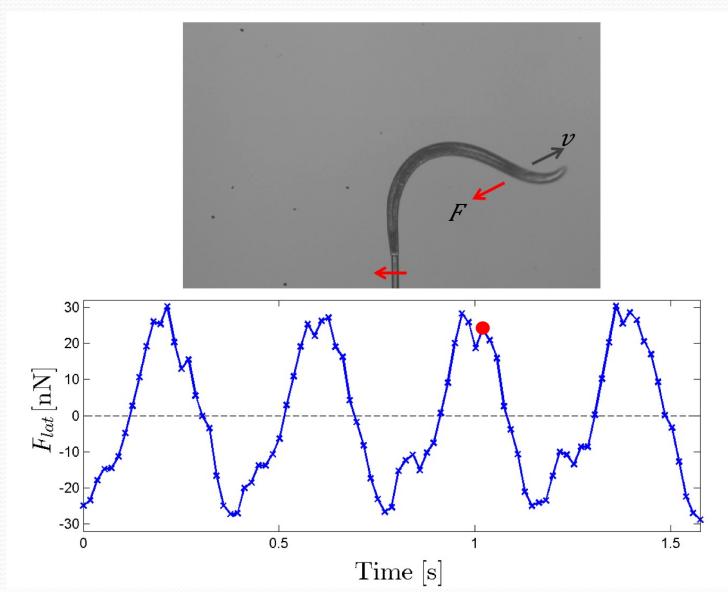
- Asymmetry in force but not curvature
 - → Pipette interaction?

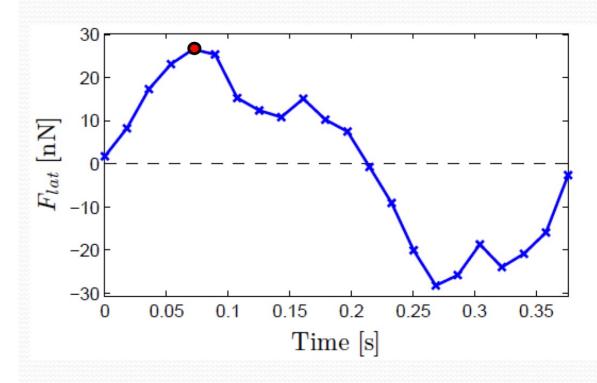


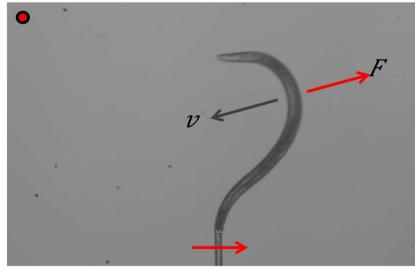












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