

Title: Advanced General Relativity - Lecture 10

Date: Feb 21, 2013 05:00 PM

URL: <http://pirsa.org/13020021>

Abstract:

$$|g_{00}| \equiv -g_{00} \approx c^2 + 2\Phi \quad \leftarrow \text{grav. potential}$$

$g_{\mu\nu}$  stationary,  $x^0 \equiv t$  ('time')



$$|g_{00}| \equiv -g_{00} \approx c^2 + 2\Phi$$

$g_{\mu\nu}$  stationary,  $x^0 \equiv t$  ("Killing time")

$$d\tau^2 \equiv -ds^2 = -g_{00} dt^2 = |g_{00}| dt^2$$

$$d\tau = \sqrt{\frac{|g_{00}|}{c^2}} dt$$

P, Q spatial locations

• Q

• P



earth



$$|g_{00}| \equiv -g_{00} \approx c^2 + 2\Phi$$

$g_{\mu\nu}$  stationary,  $x^0 \equiv t$  ("Killing time")

$$\equiv -ds^2 = -g_{00} dt^2 = |g_{00}| dt^2$$

$$\sqrt{\frac{|g_{00}|}{c^2}} dt$$

$$\left(1 + \frac{\Phi}{c^2}\right) dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

P, Q spatial locations

$\leftrightarrow \Phi$

$\bullet P$



Earth



$$|g_{00}| \equiv -g_{00} \approx c^2 + 2\Phi$$

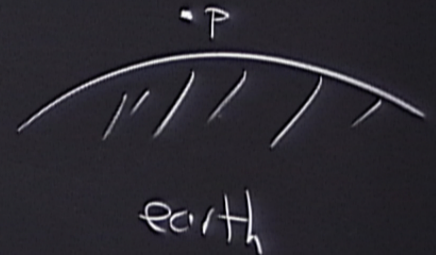
$g_{\mu\nu}$  stationary,  $x^0 \equiv t$  ("Killing time")

$$c^2 d\tau^2 \equiv dt^2 = -g_{00} dt^2 = |g_{00}| dt^2$$

$$\boxed{d\tau} = \boxed{dt}$$

$$d\tau \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

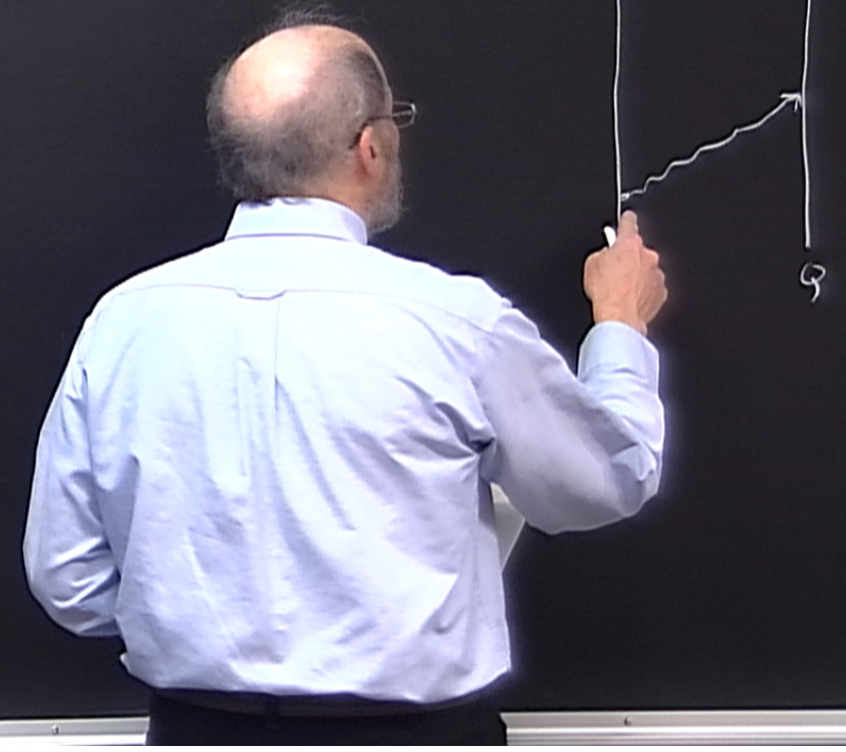
P, Q spatial locations  
 $\rightarrow \Phi$





$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

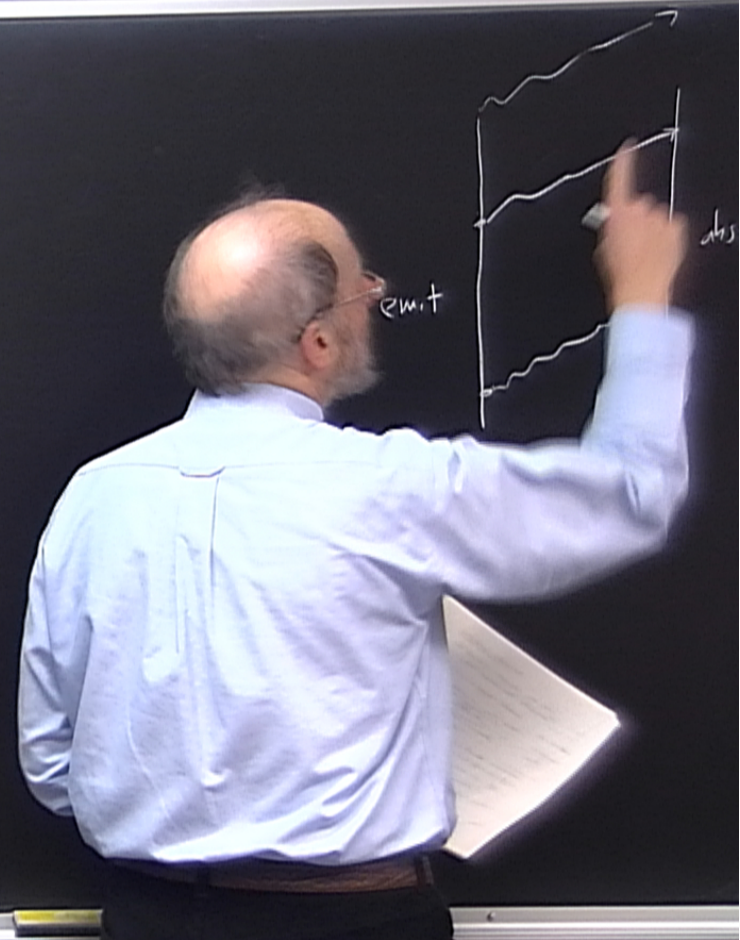
Red shift





$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

Red shift



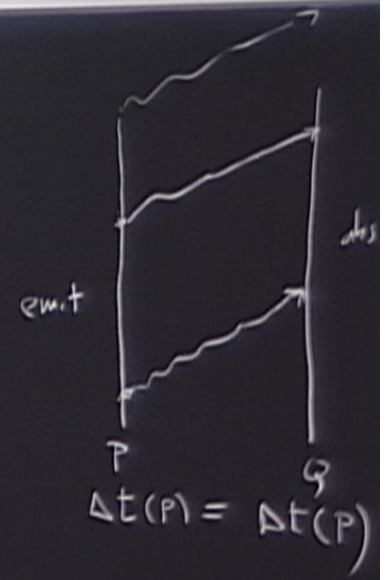
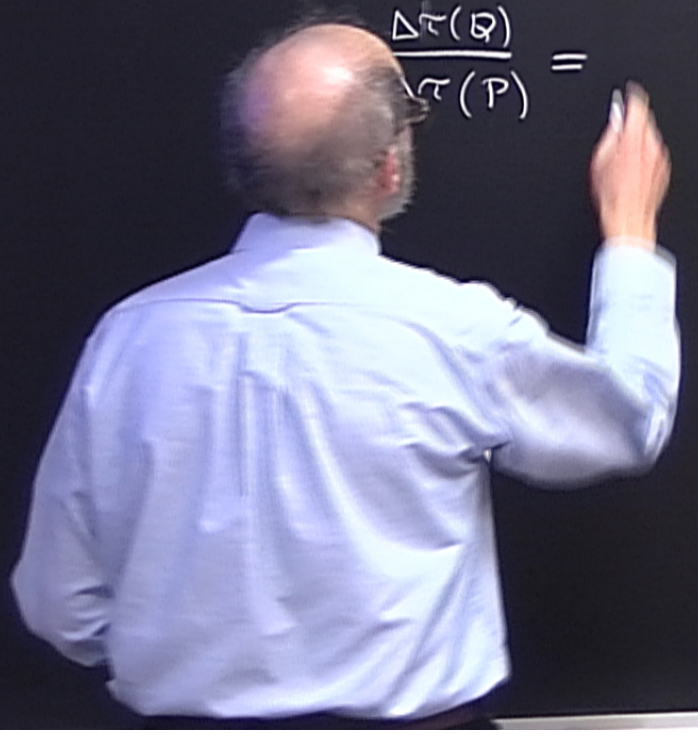


$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

Red shift

$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta \tau(Q)}{\Delta \tau(P)} =$$





$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

Red shift

$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$





$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

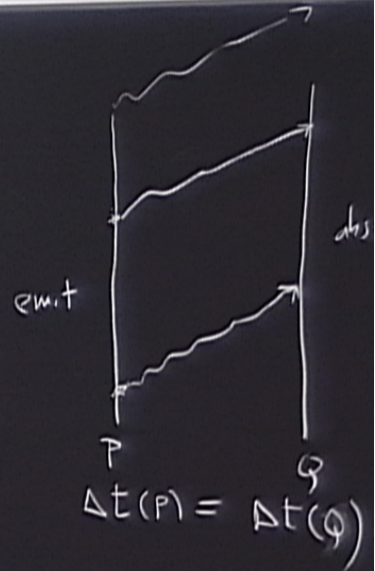
Red shift

$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta \tau(Q)}{\Delta \tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \frac{1 + \frac{\delta\Phi}{c^2}}{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

$\delta \equiv \text{change } \Phi$

$$\frac{\delta\omega}{\omega} = \frac{\delta\Phi}{c^2}$$





$$\sqrt{1 + \frac{2\Phi}{c^2}} dt \approx (1 + \Phi/c^2) dt$$

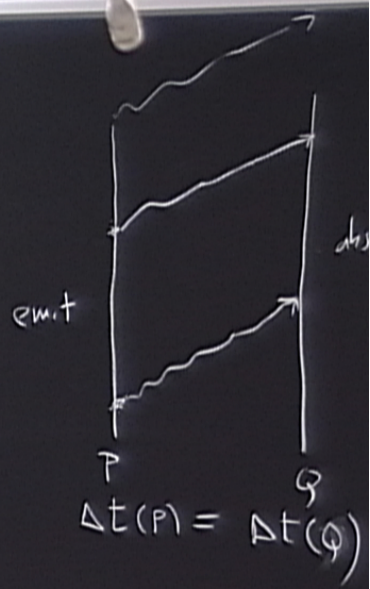
Red shift

$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta \tau(Q)}{\Delta \tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\delta\Phi}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\boxed{\frac{\delta W}{W} = -\frac{\delta\Phi}{c^2}}$$





Red shift

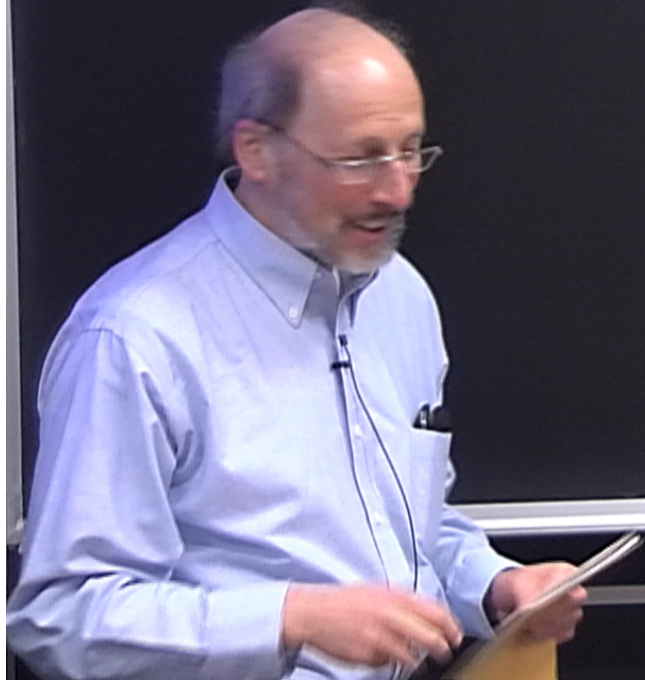
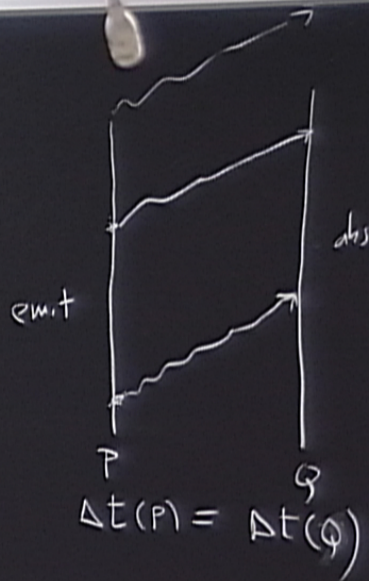
$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\boxed{\frac{\delta\omega}{\omega} = -\frac{\delta\Phi}{c^2}}$$

ascending light  
redshift





Red shift

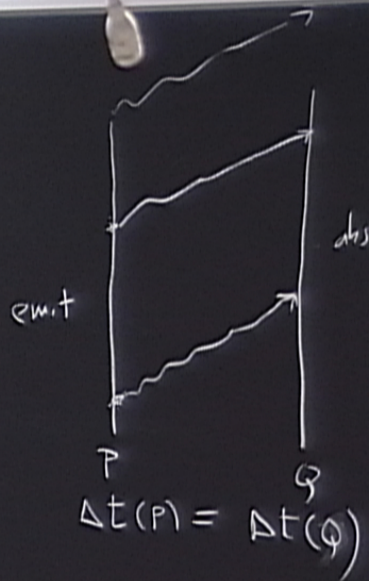
$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \frac{1 + \frac{\delta\Phi}{c^2}}{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\frac{\delta\omega}{\omega} = -\frac{\delta\Phi}{c^2}$$

ascending light  
red shift





Red shift

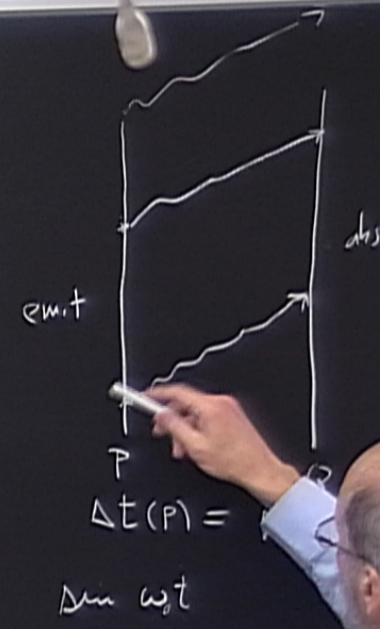
$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\boxed{\frac{\delta\omega}{\omega} = -\frac{\delta\Phi}{c^2}}$$

ascending light  
red shift





Red shift

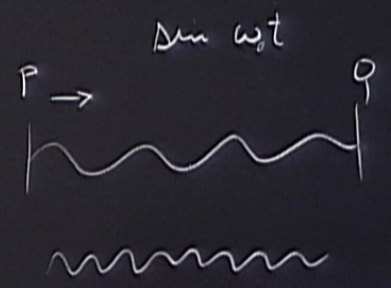
$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \frac{1 + \frac{\delta\Phi}{c^2}}{1 + \frac{\Phi(P) - \Phi(Q)}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\frac{\delta W}{W} = -\frac{\delta\Phi}{c^2}$$

ascending light  
red shift





# Red shift

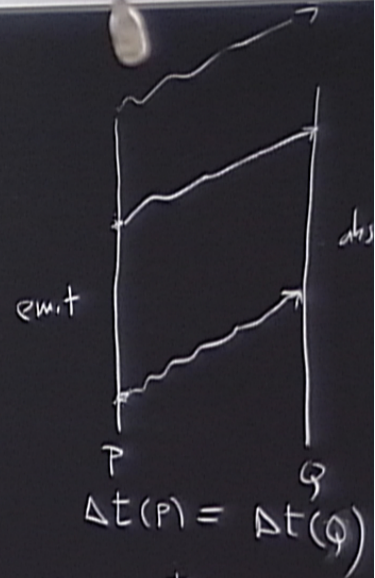
$$\Delta t(Q) = \Delta t(P)$$

$$\frac{\Delta \tau(Q)}{\Delta \tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

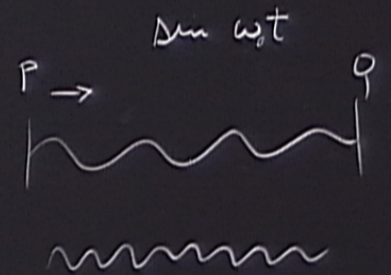
$\delta \equiv$  change from P to Q

$$\boxed{\frac{\delta W}{W} = -\frac{\delta \Phi}{c^2}}$$

ascending light  
red shift



$$\square \phi = 0 \quad e^{-i\omega t}$$





# Red shift

$$\Delta t(Q) = \Delta t(P)$$

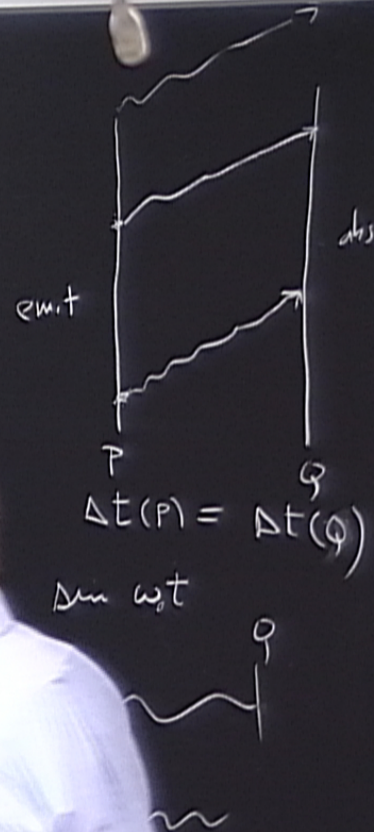
$$\frac{\Delta\tau(Q)}{\Delta\tau(P)} = \left| \frac{g_{00}(Q)}{g_{00}(P)} \right|^{1/2} \approx \frac{1 + \Phi(Q)/c^2}{1 + \Phi(P)/c^2} \approx \boxed{1 + \frac{\Phi(Q) - \Phi(P)}{c^2}}$$

$\delta \equiv$  change from P to Q

$$\boxed{\frac{\delta W}{W} = -\frac{\delta\Phi}{c^2}}$$

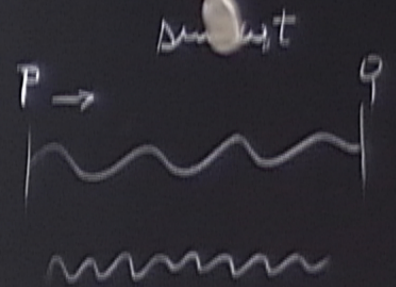
ascending light  
red shift

$$\left( \square\phi = 0 \quad e^{-i\omega t} \right)$$





$$\left( \square \phi = 0 \quad e^{-i\omega t} \right)$$





$g_{\mu\nu}$  stationary,  $x^0 \equiv t$  ("Killing time")

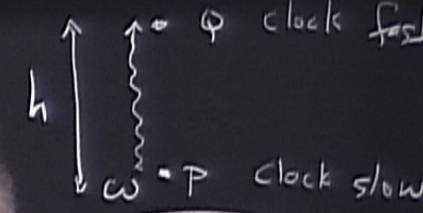
$$c^2 d\tau^2 \equiv -ds^2 = -g_{00} dt^2 = |g_{00}| dt^2$$

$$d\tau = \sqrt{\frac{|g_{00}|}{c^2}} dt$$

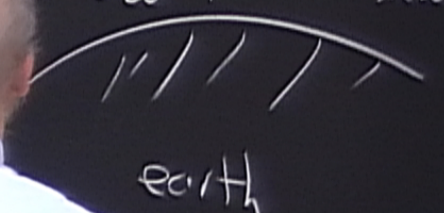
$$d\tau \approx \sqrt{1 + \frac{2\Phi}{c^2}} dt \approx \left(1 + \frac{\Phi}{c^2}\right) dt$$

$P, Q$  spatial locations

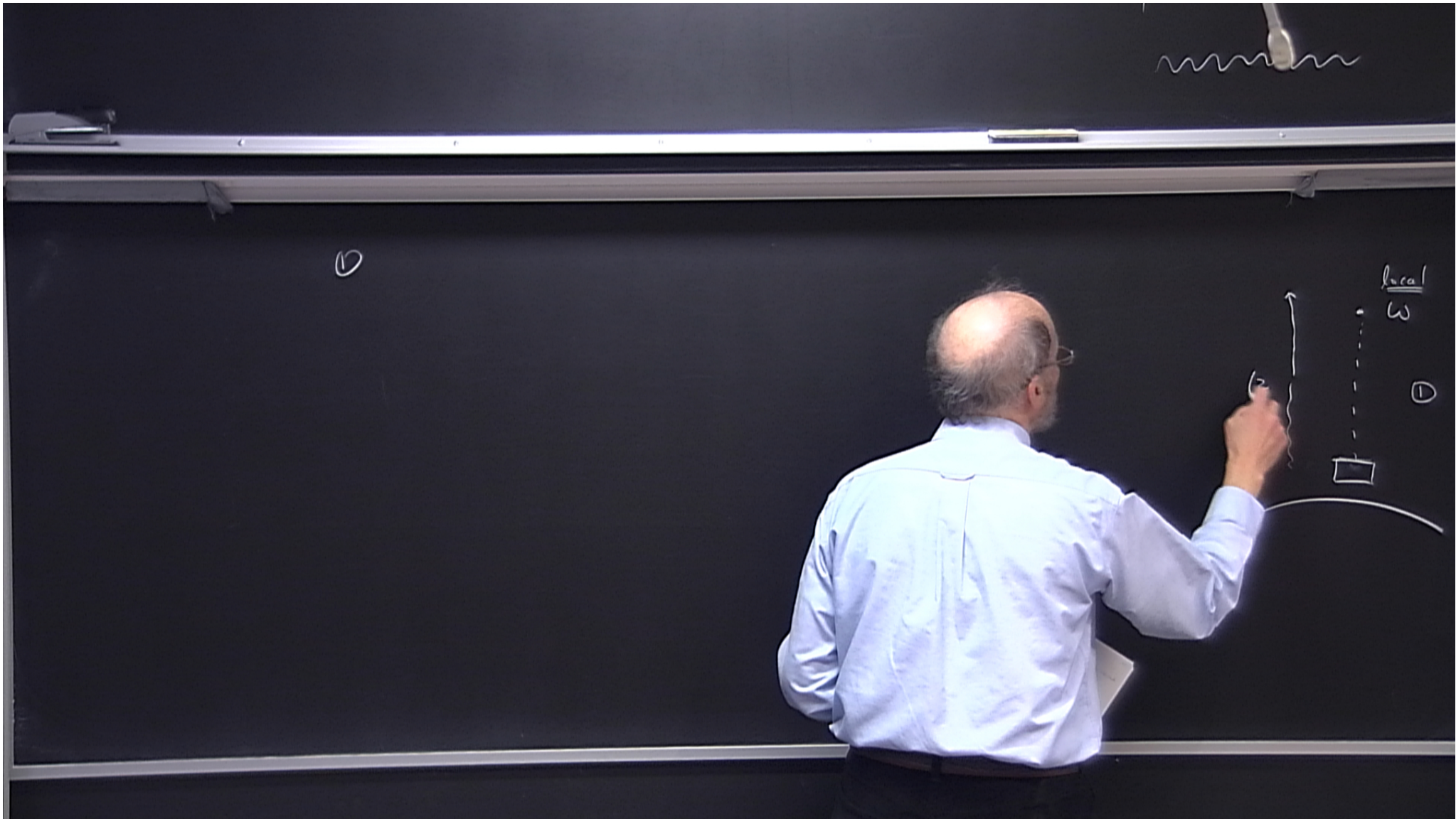
$$E = h\omega$$



$$\left(\Phi = \frac{-GM}{r} = \dots\right)$$







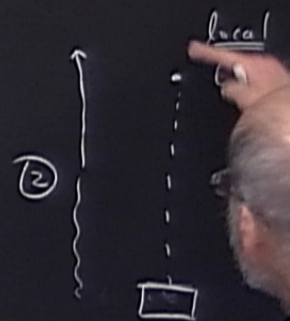


① locally  $\omega = \text{const}$       ① adiabatically

②  $\omega \rightarrow \omega - \delta\omega$

work extracted  $\stackrel{?}{=} \text{reduction in } \gamma \text{ energy}$

$m \delta\Phi = \delta(\hbar\omega)$





① adiabatically

① locally  $\omega = \text{const}$

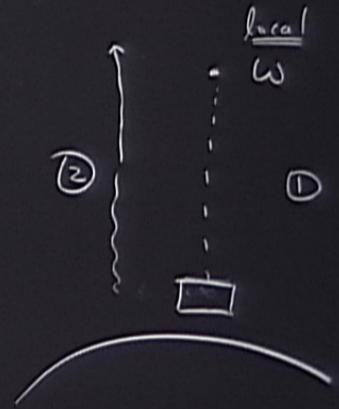
②  $\omega \rightarrow \omega - \delta\omega$

work extracted  $\stackrel{?}{=} \text{reduction in } \gamma \text{ energy}$

$-m \delta\Phi \stackrel{?}{=} \delta(\hbar\omega)$

$-\frac{\hbar\omega}{c^2} \delta\Phi \approx \hbar \delta\omega$

$\frac{\hbar\omega}{c^2} \approx \frac{\hbar\omega}{c^2}$





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks



Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )



Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )

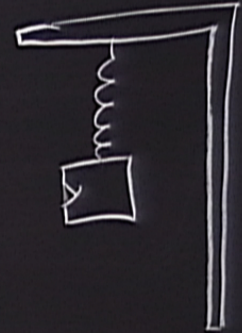
$$\Delta E \Delta t$$





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )

$$\Delta E \Delta t \approx \hbar$$





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks

spread (gravity  $\leftrightarrow$  geometry)

$$\Delta E \Delta t \approx \hbar$$

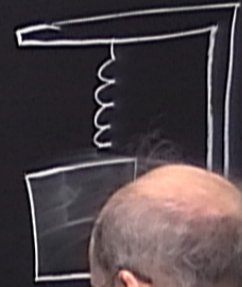




Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks

spread (gravity  $\leftrightarrow$  geometry)

$$\downarrow$$
$$\Delta E \Delta t \approx \hbar$$

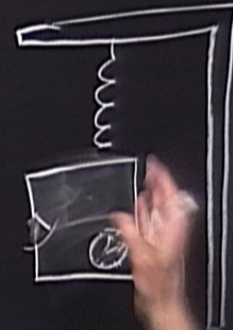




Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks

spread (gravity  $\leftrightarrow$  geometry)

$$\downarrow$$
$$\Delta E \Delta t \approx \hbar$$

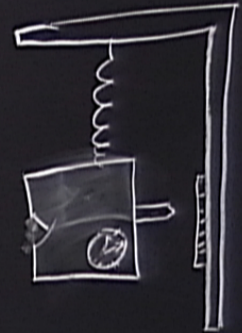




Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )

line-width  
spread

$$\Delta E \Delta t \approx \hbar$$





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )

line-width  
spread

$$\downarrow \Delta E \Delta t \approx \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (clock)





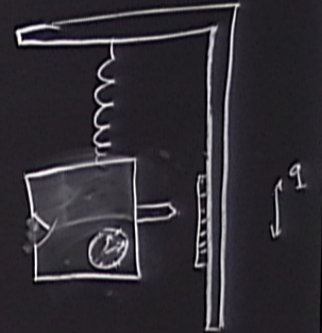
Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks  
( gravity  $\leftrightarrow$  geometry )

line-width spread

$$\Delta E \Delta t \approx \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (clock)

height  $g$   
 $T =$  time to weigh





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks

line-width spread

(gravity  $\leftrightarrow$  geometry)

height  $q$

$T =$  time to weigh

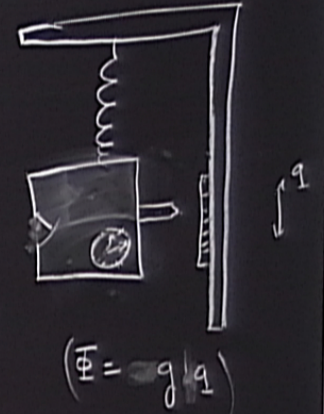
$\downarrow$

$$\Delta E \Delta t \approx \hbar$$

Challenge  $\Delta E = 0$  ( $\dots$ )  
 $\Delta t = 0$  ( $\dots$ )

$$\Delta t = T$$

$$\text{rate} \propto 1 + \frac{\Phi}{c^2}$$





Energy conservation  $\Rightarrow$  red shift  $\Rightarrow$  slowing clocks

live-with spread (gravity  $\leftrightarrow$  geometry)

$$\Delta E \Delta t \approx \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (clock)

$m, m + \Delta m$   
accuracy  $\Delta m$

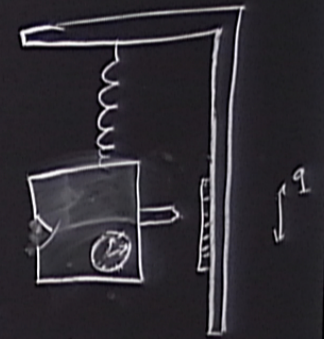
claim  $g m T$

height  $q$   
 $T =$  time to weigh

$$\Delta t = T \frac{\Delta \Phi}{c^2} =$$
  
$$\Delta t = \frac{g}{c^2} T \Delta q$$

$$\text{rate} \propto 1 + \frac{\Phi}{c^2}$$

$$1 = \frac{T}{c^2} g \Delta q$$



$$(\Phi = -g q)$$

accel grav



$m, m + \Delta m$   
 accuracy  $\Delta m$

Claim  $g \Delta m T \gtrsim \Delta p$

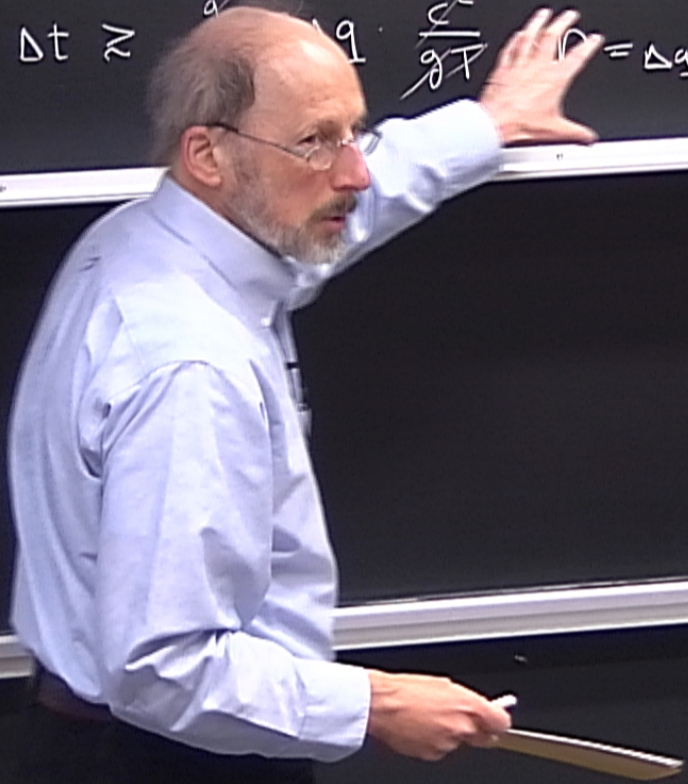
$\Rightarrow \Delta E = (\Delta m) c^2 \gtrsim \frac{c^2}{g T} \Delta p$

$\Delta E \Delta t \gtrsim \frac{c^2}{g T} \Delta p$

$\Delta t = \frac{g}{c^2} T \Delta q$

$\frac{\partial \Delta q}{\partial q} = \frac{T}{c^2} g \Delta q$

accel  $g$





line-width spread

( gravity ↔ geometry )

$$\Delta E \Delta t \gtrsim \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (click)

$m, m + \Delta m$   
accuracy  $\Delta m$

claim  $g \Delta m T \gtrsim \Delta p$

$$\Delta E \Delta t \gtrsim \frac{g}{c^2} T \Delta q \quad \frac{c^2}{gT} \Delta p = \Delta q \Delta p \gtrsim \hbar$$

height  $q$

$T =$  time to weigh

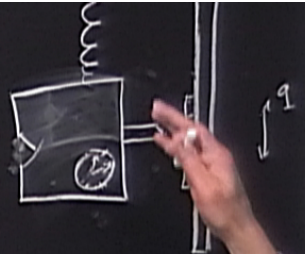
$$\Delta t = T \frac{\Delta \Phi}{c^2} = \frac{T}{c^2} \frac{\partial \Phi}{\partial q}$$

$$\Delta t = \frac{g}{c^2} T \Delta q \quad \textcircled{1}$$

$$\text{rate} \propto 1 + \frac{\Phi}{c^2}$$

$$\Delta q = \frac{T}{c^2} g \Delta q$$

$$(\Phi = g q)$$



accel grav



line-width spread

(gravity ↔ geometry)

$$\Delta E \Delta t \gtrsim \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (click)

$m, m + \Delta m$   
accuracy  $\Delta m$

claim

height  $q$   
 $T =$  time to weigh

$$\Delta t = T \frac{\Delta \Phi}{c^2} = \frac{T}{c^2} \frac{\partial \Phi}{\partial q} \Delta q = \frac{T}{c^2} g \Delta q$$

$$\Delta t = \frac{g}{c^2} T \Delta q \quad (1)$$

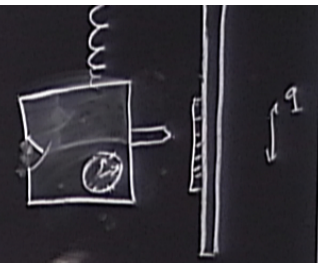
$$g \Delta m T \gtrsim \Delta p$$

$$\Rightarrow \Delta E = (\Delta m) c^2 \gtrsim \frac{c^2}{gT} \Delta p$$

$$\Delta E \Delta t \gtrsim \frac{g}{c^2} T \Delta q$$

$$\frac{c^2}{gT} \Delta p = \Delta q \Delta p \gtrsim \hbar$$

$$\text{rate} \propto 1 + \frac{\Phi}{c^2}$$



actual grav



line-width spread

(gravity ↔ geometry)

$$\Delta E \Delta t \gtrsim \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (click)

$m, m + \Delta m$   
accuracy  $\Delta m$

claim

$$\Delta t = \frac{g}{c^2} T \Delta q \quad (1)$$

$$g \Delta m T \gtrsim \Delta p$$

$$\Rightarrow \Delta E = (\Delta m) c^2 \gtrsim \frac{c^2}{g T} \Delta p \quad (2)$$

$$\Delta E \Delta t \gtrsim \frac{g}{c^2} T \Delta q$$

$$\frac{c^2}{g T} \Delta p = \Delta q \Delta p \gtrsim \hbar$$

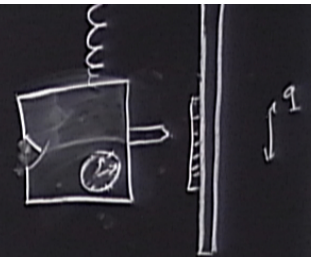
height  $q$

$T =$  time to weigh

$$\text{rate} \propto 1 + \frac{\Phi}{c^2}$$

$$\Delta q = \frac{T}{c^2} g \Delta q$$

$$(\Phi = g q)$$



accel grav



line-width spread

( gravity ↔ geometry )

$$\Delta E \Delta t \gtrsim \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (click)

$m, m + \Delta m$   
accuracy  $\Delta m$

claim

$$\Delta t = \frac{g}{c^2} T \Delta q \quad ①$$

$$g \Delta m T \gtrsim \Delta p$$

$$\Rightarrow \Delta E = (\Delta m) c^2 \gtrsim \frac{c^2}{g T} \Delta p \quad ②$$

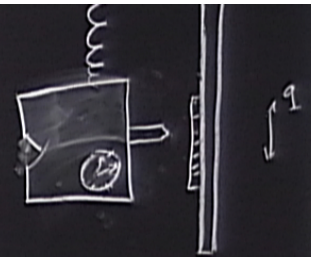
$$\Delta E \Delta t \gtrsim \frac{g}{c^2} T \Delta q \cdot \frac{c^2}{g T} \Delta p = \Delta q \Delta p \gtrsim \hbar$$

height  $q$   
 $T =$  time to weigh

$$rate \propto 1 + \frac{\Phi}{c^2}$$

$$\Delta q = \frac{T}{c^2} g \Delta q$$

$$(\Phi = g q)$$



accel grav



line-width spread

( gravity ↔ geometry )

$$\Delta E \Delta t \gtrsim \hbar$$

Challenge  $\Delta E = 0$  (weigh box)  
 $\Delta t = 0$  (click)

$m, m + \Delta m$   
accuracy  $\Delta m$

claim

$$\Delta t = \frac{g}{c^2} T \Delta q \quad ①$$

$$g \Delta m T \gtrsim \Delta p$$

$$\Rightarrow \Delta E = (\Delta m) c^2 \gtrsim \frac{c^2}{g T} \Delta p \quad ②$$

$$\Delta E \Delta t \gtrsim \frac{g}{c^2} T \Delta q$$

$$\frac{c^2}{g T} \Delta p = \Delta q \Delta p \gtrsim \hbar$$

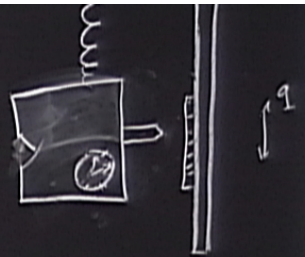
height  $q$

$T =$  time to weigh

$$rate \propto 1 + \frac{\Phi}{c^2}$$

$$\Delta q = \frac{T}{c^2} g \Delta q$$

$$(\Phi = g q)$$



accel grav

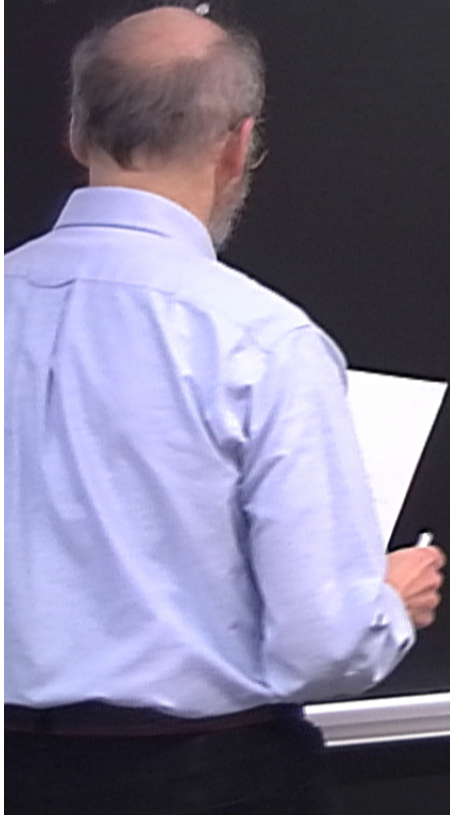


Diff. geom ("tensor analysis")

CAUTION  
DO NOT TOUCH THE BOARD  
IF IT IS DAMAGED BY YOU  
PLEASE REPORT TO THE  
RELEVANT OFFICE



Diff geom ("tensor analysis")



CAUTION  
DO NOT TOUCH THE BOARD  
IF IT IS NECESSARY TO CLEAN  
THE BOARD PLEASE CONTACT THE  
TECHNICAL SUPPORT



## Diff geom ("tensor analysis")

- Sum of products of vectors (& covectors):  $\sum u \otimes v$
- linear op. from one space of tensor to another
- multilinear form from vectors & covectors to scalars
- certain types of geom. object



## Diff geom ("tensor analysis")

- • Sum of products of vectors (& covectors):  $\otimes$
- linear op. from one space of tensor to another
  - multilinear form from vectors & covectors to scalars
  - certain type of geom. object
  - a array of numbers (components) that transform



## Diff geom ("tensor analysis")

⇒ • Sum of products of vectors (& covectors)  $\sum u \otimes v$

→ • linear op. from one space of tensor to another

• multilinear form from vectors & covectors to

• certain type of geom. object

• a array of numbers (components) that transforms in a certain way under change of basis (coordinate)

• elt of  $V_1 \otimes V_2$  that arises as sol'n of "UM"

→ • Symbol with some indices



# Diff geom ("tensor analysis")

⇒ • Sum of products of vectors (& covectors):

$$\sum u \otimes v \otimes w$$

tensor product  
"outer product"

→ • linear op. from one space of tensor to another

• multilinear form from vectors & covectors to scalars

• certain type of geom. object

• a array of numbers (components) that transforms in a certain way under change of basis

• elt of  $V_1 \otimes V_2$  that arises as sol'n of "U.M.P."

→ • Symbol with some indices



# Diff geom ("tensor analysis")

⇒ • Sum of products of vectors (& covectors):

$$\sum u \otimes v \otimes w \otimes \dots$$

tensor product  
"outer product"

$$V \otimes V^* \otimes \dots$$

→ • linear op. from one space of tensor to another

• multilinear form from vectors & covectors to scalars

• certain type of geom. object

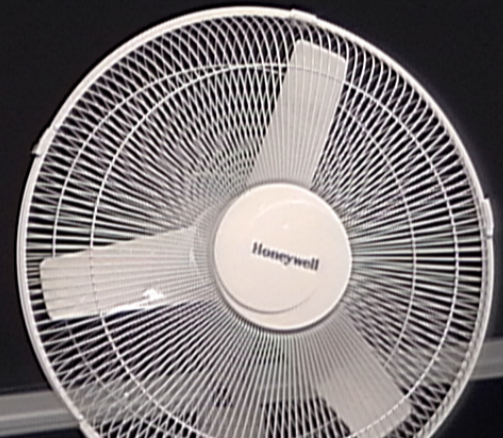
• a array of numbers (components) that transform in a certain way under change of basis (coordinate)

• elt of  $V_1 \otimes V_2$  that arises as sol'n of "U.M.P."

→ • Symbol with some indices



Dual vectorspace





# Diff geom ("tensor analysis")

⇒ • Sum of products of vectors (& covectors)

→ • linear op. from one space of tensor to another

• multilinear form from vectors & covectors to scalars

• certain type of geom. object

• a array of numbers (components) that transforms in a certain way under change of basis (coordinate)

• elt of  $V_1 \otimes V_2$  that arises as sol'n of "U.M.P"

→ • Symbol with some indices

tensor product  
"outer product"

$$\sum u \otimes v \otimes w \otimes \dots$$

$$V \otimes V^* \otimes \dots$$

$$V = T_p M$$

$$V^*$$



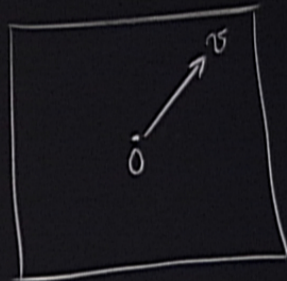
Dual vectorspace      covector

$$V^* = \mathcal{L}(V, \mathbb{R}) = \{ \omega : V \rightarrow \mathbb{R} \mid \omega \text{ linear} \}$$

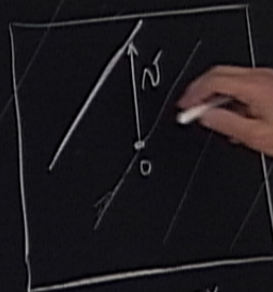
inner-product  $V^* \times V \rightarrow \mathbb{R}$

$$\omega, v \rightarrow (\omega, v) \equiv \omega(v) = \omega \cdot v = (v, \omega)$$

picture



$$v \in V = T_p M$$



$$\omega \in V^*$$



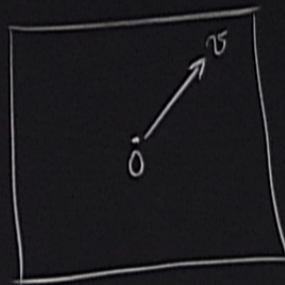
Dual vectorspace      covector

$$V^* = \mathcal{L}(V, \mathbb{R}) = \{ \omega : V \rightarrow \mathbb{R} \mid \omega \text{ linear} \}$$

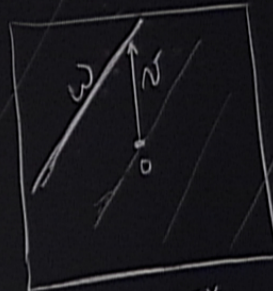
inner-product  $V^* \times V \rightarrow \mathbb{R}$

$$\omega, v \rightarrow (\omega, v) \equiv \omega(v) = \omega \cdot v = (v, \omega)$$

picture

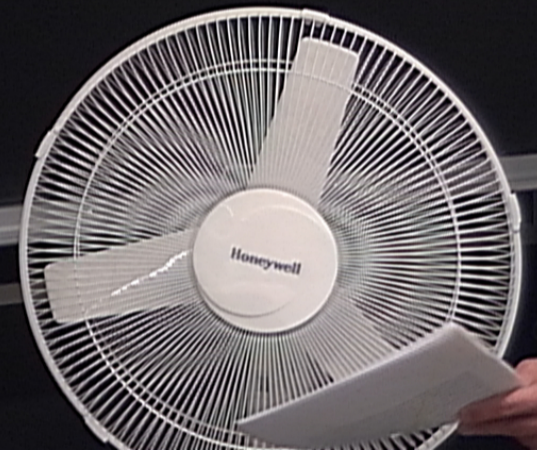


$$v \in V = T_p M$$



$$\omega \in V^*$$

$(\omega, v) = 1 \Leftrightarrow$  head  $v$  falls on (head) of  $\omega$   
 $(\omega, v)$  is number of planes "pierced" by  $v$

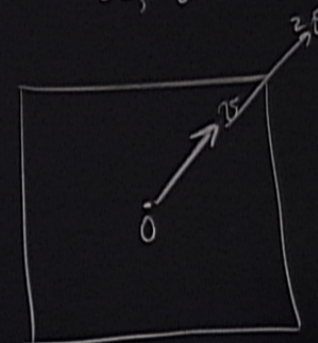




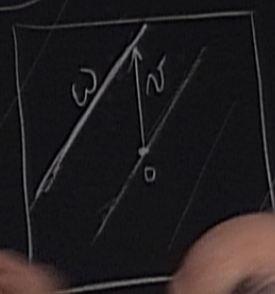
inner product

$$\omega, \nu \rightarrow (\omega, \nu) = \omega(\nu) = \omega \cdot \nu = (\nu, \omega)$$

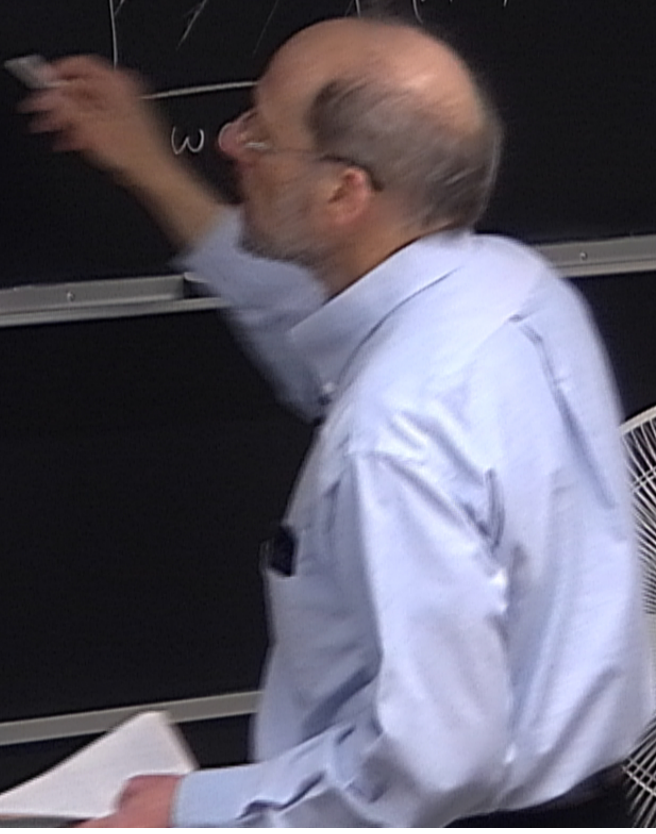
Picture



$$\nu \in V = T_p M$$



$(\omega, \nu) = 1 \Leftrightarrow$  head  $\nu$  falls on (head) of  $\omega$   
 $(\omega, \nu)$  is number of planes "pierced" by  $\nu$





inner product

$\omega, \nu \rightarrow (\omega, \nu) = \omega(\nu) = \omega \cdot \nu = (\nu, \omega)$

Picture  $\omega$

$\nu \in V = T_p M$

$\omega \in V^*$

$(\omega, \nu) = 1 \Leftrightarrow$  head  $\nu$  falls on (head) of  $\omega$

$(\omega, \nu)$  is number of planes "pierced" by  $\nu$