

Title: 12/13 PSI - Quantum Gravity Review Lecture 3

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URL: <http://pirsa.org/13010091>

Abstract:



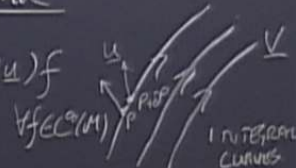
ω_μ^l, e_μ^k $\omega_{\mu\nu} = \epsilon_{j\mu k} \omega_\mu^l$
 curvature: $F_{\mu\nu}^l = \partial_\mu \omega_\nu^l - \partial_\nu \omega_\mu^l + \epsilon^{ljk} \omega_\mu^j \omega_\nu^k$

torsion: $T_{\mu\nu}^l = \partial_\mu e_\nu^l - \partial_\nu e_\mu^l + \epsilon^{ljk} \omega_\mu^j e_\nu^k$

$\text{if } T_{\mu\nu}^l = 0 \Rightarrow \Gamma_{\mu\nu}^\sigma = e_\mu^a e_\nu^b \partial_a e_b^\sigma$

Lie Derivative

$[U, V]f = (UV - VU)f$



$$L_V Q_{b_1 \dots b_m}^{a_1 \dots a_n} = V^c \partial_c Q_{b_1 \dots b_m}^{a_1 \dots a_n} - \sum_{i=1}^n Q_{b_1 \dots b_m}^{a_1 \dots a_{i-1} c a_{i+1} \dots a_n} \partial_c V^{a_i}$$

$$+ \sum_{j=1}^m Q_{b_1 \dots b_m}^{a_1 \dots a_n} \partial_{b_j} V^{b_j}$$

$$+ \textcircled{W} \partial_a V^a Q_{b_1 \dots b_m}^{a_1 \dots a_n}$$
 density weight

ω_μ^l, e_μ^k $\omega_{\mu\nu} = \epsilon_{j\mu k} \omega_\mu^l$

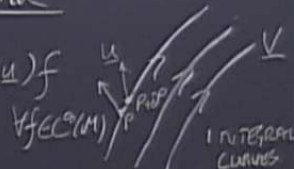
curvature: $F_{\mu\nu}^l = \partial_\mu \omega_\nu^l - \partial_\nu \omega_\mu^l + \epsilon^{ljk} \omega_\mu^j \omega_\nu^k$

torsion: $T_{\mu\nu}^l = \partial_\mu e_\nu^l - \partial_\nu e_\mu^l + \epsilon^{ljk} \omega_\mu^j e_{\nu k} - \epsilon^{ljk} \omega_\nu^j e_{\mu k}$

$\text{if } T_{\mu\nu}^l = 0 \Rightarrow \Gamma_{\mu\nu}^s = e_\nu^k \omega_{\mu k}^s + e_\mu^s \partial_\nu e_\mu^s$
is Levi-Civita

Lie Derivative

$[U, V]f = (UV - VU)f$



$L_V Q_{b_1 \dots b_m}^{a_1 \dots a_n} = V^c \partial_c Q_{b_1 \dots b_m}^{a_1 \dots a_n} - \sum_{i=1}^n Q_{b_1 \dots b_m}^{a_1 \dots a_{i-1} a_{i+1} \dots a_n} \partial_c V^{a_i} + \sum_{j=1}^m Q_{b_1 \dots b_m}^{a_1 \dots a_n} \partial_{b_j} V^c + \textcircled{W} \partial_a V^a Q_{b_1 \dots b_m}^{a_1 \dots a_n}$
density weight

3D first

$$S = \int_R \sqrt{g} d^3x = - \int e_{\sigma\ell} F_{\mu\nu}^e \tilde{E}^{\sigma\mu\nu} d^3x$$
$$= - \int e_{\sigma\ell} [2\mathcal{D}_\mu \omega_\nu^\ell + \epsilon^{ljk} \omega_{\mu j} \omega_{\nu k}^\ell] \tilde{E}^{\sigma\mu\nu} d^3x$$

3D first order action

$$S = \int R \sqrt{g} d^3x = - \int e_{\sigma\ell} F_{\mu\nu}^{\ell} \tilde{E}^{\sigma\mu\nu} d^3x$$
$$= - \int e_{\sigma\ell} [2\partial_{\mu} \omega_{\nu}^{\ell} + \epsilon^{\ell jk} \omega_{\mu j} \omega_{\nu k}] \tilde{E}^{\sigma\mu\nu} d^3x$$

3D first order action

$$S = \int R \sqrt{g} d^3x = - \int e_{\sigma\ell} F_{\mu\nu}^e \tilde{E}^{\sigma\mu\nu} d^3x$$
$$= - \int e_{\sigma\ell} [2\gamma_{\mu\nu}^{\ell} \omega_{\nu}^{\ell} + \epsilon^{\ell jk} \omega_{\mu j} \omega_{\nu k}] \tilde{E}^{\sigma\mu\nu} d^3x$$

2 order formalism. $\omega(e)$

1 order — : e, ω independent

Equatio

d^3x $\epsilon^{ijk} \omega_{\mu j} \omega_{\nu k}] \tilde{E}^{\sigma\mu\nu} d^3x$

Equations of Motion

 $\delta e_{\alpha\beta}:$

$$F_{\mu\nu}^l = 0$$

 $\delta \omega_\alpha^l:$

d^3x

$$[\epsilon^{ljk} \omega_{\mu j} \omega_{\nu k}] \tilde{E}^{\sigma\mu\nu} d^3x$$

$$[\epsilon^{ljk} \omega_{\mu j} \omega_{\nu k}] \tilde{E}^{\sigma\mu\nu} d^3x$$

Equations of Motion:

$$\delta e_{\alpha\beta}: F_{\mu\nu}^l = 0$$

$$\delta \omega_\alpha^e: T_{\mu\nu}^l = 0$$

d^3x

$\epsilon^{ijk} \omega_{\mu j} \omega_{\nu k}$

$\rightarrow \mu\nu d^3x$

$\epsilon^{ijk} \omega_{\mu j} \omega_{\nu k}$

d^3x

Equations of Motion

$\delta e_{\mu\nu}: F_{\mu\nu}^I = 0$

$\delta \omega_\nu^e: T_{\mu\nu}^I = 0$

$\Rightarrow \omega(e)$

3D first order action

$$S = \int R \sqrt{g} d^3x = - \int e_{\sigma\ell} F_{\mu\nu}^{e\ell} \tilde{E}^{\sigma\mu\nu} d^3x$$

$$= \int e_{\sigma\ell} [2\partial_\mu \omega_\nu^\ell + \epsilon^{ljk} \omega_{\mu j} \omega_{\nu k}^\ell] \tilde{E}^{\sigma\mu\nu} d^3x$$

$$= \int (2\partial_\mu e_{\sigma\ell}) \omega_\nu^\ell + e_{\sigma\ell} \epsilon^{ljk} \omega_{\mu j} \omega_{\nu k}^\ell] \tilde{E}^{\sigma\mu\nu} d^3x$$



Symmetries

Symmetries of the action

Symmetries of the action

* rotations in internal index

Symmetries of the action

* rotations in internal index

Symmetries of the action

* rotations in internal index

Rotations

$$(e^i)_{\mu}^{j'} = R^{j'}_i, e_{\mu}^j$$

$$\omega_{\mu}^{j'k}$$

$$\omega_{\mu jk} = -e_k^{\nu} \partial_{\mu} e_{\nu}^j + e_{\nu}^j \partial_{\mu} e_k^{\nu}$$

Rotations

$$(e^i)_{\mu}^{j'} = R^{j'}_{i\mu} ; e_{\mu}^j$$

$$\omega_{\mu}^{j'k}$$

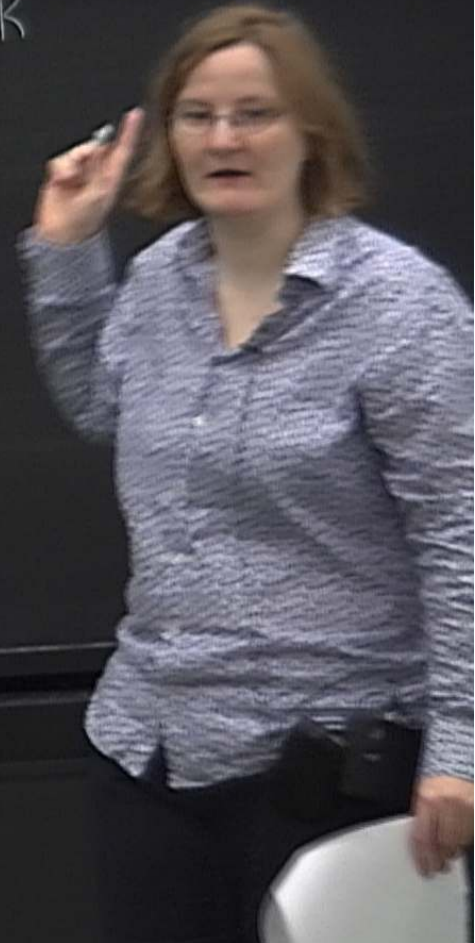
$$\omega_{\mu}^{j'k} = -e_{\mu}^{j'} \partial_{\nu} e^k_{\nu} + e_{\mu}^{j'} \Gamma_{\mu\nu}^k e^i_{\nu}$$

Rotations

$$(e^i)_{\mu}^{j'} = R^{j'}_{i'} e_{\mu}^{i'}$$

$$\omega_{\mu}^{j'k}$$

$$\omega_{\mu}^{j'k} = -\underset{\uparrow R}{e^{\nu}_{k'}} \underset{\uparrow R}{d_{\mu}} \underset{\uparrow R}{e^j_{\nu}} + \underset{\uparrow R}{e^{\nu}_{k'}} \underset{\uparrow R}{\Gamma^j_{\mu\nu}} \underset{\uparrow R}{e^i_{\nu}}$$



Rotations

$$(e^i)_{\mu}^{j'} = R^{j'}_{\mu} ; e_{\mu}^j$$

$$\omega_{\mu}^{j'k} = R_{\mu}^m \omega_{\mu ml} (R^{-1})^l_k + R_{\mu}^m \partial_{\mu} (R^{-1})$$

$$\omega_{\mu}^{j'k} = -\underset{\uparrow R}{e^j}_k \partial_{\mu} \underset{\uparrow R}{e^i}_j + \underset{\uparrow R}{e^j}_k \overset{\uparrow R}{\omega_{\mu}^{ij}} \underset{\uparrow R}{e^i}_j$$

Rotations

$$(e^i)_\mu^{j'} = R^{j'}_i, e_\mu^j$$

$$\omega_{\mu j k}^i = R^{i m} \omega_{\mu m l} (R^{-1})^l_k + R^{i m} \partial_\mu (R^{-1})_{m k}$$

Exercise
=>

$$F'_{\mu\nu j k} =$$

$$\omega_{\mu j k} = -\underset{\uparrow R}{e^i_k} \partial_\mu \underset{\uparrow R}{e^j_i} + \underset{\uparrow R}{e^i_k} \underset{\uparrow R}{\Gamma^s_{\mu\nu} e^j_s}$$



Rotations.

$$(e^i)_{\mu}^{j'} = R^{j'}_{\mu}{}^i, e_{\mu}^{j'}$$

$$\omega_{\mu}^{j'k'} = R_{\mu}{}^m \omega_{mnl} (R^{-1})^{nl}{}_{jk}$$

Exercise
 \Rightarrow

$$F'_{\mu\nu jk} = R_{\mu\nu}{}^{\alpha\beta} F_{\alpha\beta jk}$$

$$\omega_{\mu jk} = -\underset{\uparrow R}{e^{\nu}}_{\mu} \partial_{\mu} \underset{\uparrow R}{e^{\nu}}_{\mu} + \underset{\uparrow R}{e^{\nu}}_{\mu} \underset{\uparrow R}{\Gamma^{\nu}}_{\mu\sigma} e^{\sigma}{}_{\mu}$$

$$+ R_{\mu}{}^m \partial_{\mu} (R^{-1})^{nl}{}_{jk}$$

Rotations.

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu} + \underset{\uparrow R}{e_\rho^\nu} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\nu^\rho}$$

$$(e^i)_\mu^{j'} = R^{j'}_i, \quad e_\mu^j$$

$$\omega_{\mu\nu\rho}^{j'} = R^{j'}_m \omega_{\mu\nu\rho} (R^{-1})^m_k + R^{j'}_m \partial_\mu (R^{-1})_{mk}$$

Exercise
 \Rightarrow

$$F'_{\mu\nu\rho} = R^{j'}_m F_{\mu\nu\rho} (R^{-1})^m_k$$

$+e_k^v \sum_{nu} e_{sj}$
 $\uparrow R \quad \uparrow R$

infinitesimal rotations.

$$\left. \frac{d}{d\theta} R_z(\theta) \right|_{\theta=0} = \left. \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \right|_{\theta=0} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$



$$+ e_k^v \sum_{n \nu} e_{\nu j}^s$$

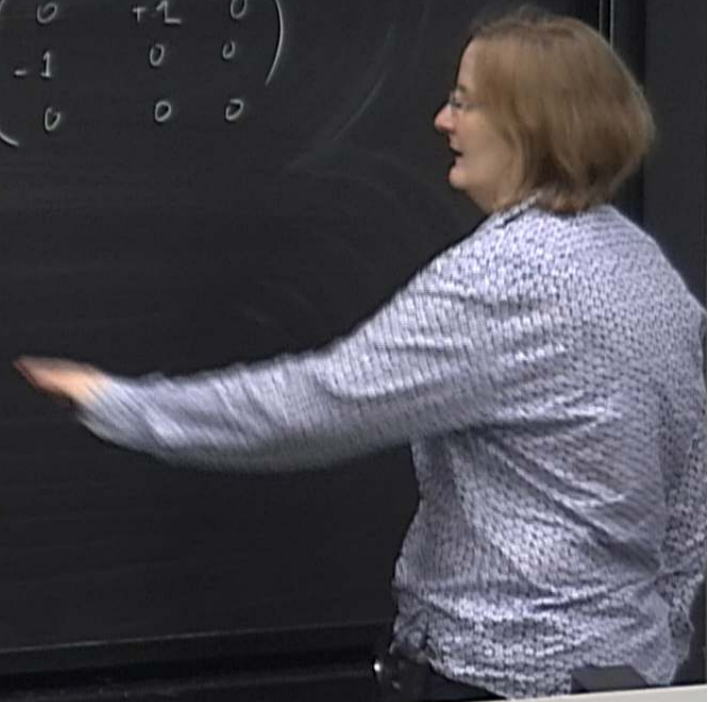
$$\uparrow \quad \uparrow$$

$$R \quad R$$

infinitesimal rotations.

$$\left. \frac{d}{d\theta} R_z(\theta) \right|_{\theta=0} = \left. \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \right|_{\theta=0} = \begin{pmatrix} 0 & +1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^3$$



$$+ e_{\mathbb{R}}^{\nu} \uparrow \mathbb{R} \quad \mathbb{R}^3 \quad \uparrow \mathbb{R} \quad e_{\mathbb{R}}^{\nu} \uparrow \mathbb{R} \quad e_{\mathbb{R}}^{\nu} \uparrow \mathbb{R}$$

infinitesimal rotations.

$$\frac{d}{d\theta} R_z(\theta) \Big|_{\theta=0} = \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \Big|_{\theta=0} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^k \leftarrow \text{parameters}$$

SO(3)



$$+ e_k^v \sum_{nu} e_{sj}$$

↑ R ↑ R

infinitesimal notations.

$$\left. \frac{d}{d\theta} R_z(\theta) \right|_{\theta=0} = \left. \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \right|_{\theta=0} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^k$$

SO(3)

parameters
basis of Lie algebra

$$so(3) = \mathfrak{so}(3)$$

$$(T^k)_{ij} = \epsilon_{ijk}$$

Rotations

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu} + \underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu}$$

$$(e^i)_{\mu'} = R^{j'}_{\mu} ; e_{\mu'}^j$$

$$\omega_{\mu'jk} = R_{\mu'}^m \omega_{mjkl} (R^{-1})^l_k + R_{\mu'}^m \partial_\mu (R^{-1})_{mk}$$

Exercise
=>

$$F'_{\mu\nu jk} = R_{\mu}^m F_{m\nu jk} (R^{-1})^k_l$$

$$\frac{d}{d\varepsilon} \omega_{\mu}^m = \partial_\mu \Lambda^m + \epsilon^m_{li} \omega_{\mu}^l \Lambda^i = D_\mu$$

Rotations

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu} + \underset{\uparrow R}{e_\rho^\nu} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\nu^\rho}$$

$$(e^i)_{\mu}^{j'} = R^{j'}_i ; e_\mu^j$$

$$\omega_{\mu\nu\rho}^{j'} = R^{j'}_m \omega_{\mu\nu\rho}^m (R^{-1})^k_l + R^{j'}_m \partial_\mu (R^{-1})_{mk}$$

Exercise
=>

$$F'_{\mu\nu\rho} = R^{j'}_m F_{\mu\nu\rho}^m (R^{-1})^k_l$$

$$\frac{d}{d\varepsilon} \omega_{\mu}^m = \partial_\mu \Lambda^m + \epsilon^m_{li} \omega_{\mu}^l \Lambda^i = D_\mu \Lambda^m = \delta^R$$

infinitesimal
 $\frac{d}{d\varepsilon} R_{ij}(\varepsilon)$
 R_{ij}

Rotations.

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu} + \underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\omega_{\mu\nu}^\rho} e_\rho^\sigma$$

$$(e^i)_{\mu}^{j'} = R^{j'}{}^i{}_{\mu}$$

$$\omega_{\mu}^{j'k} = R^{j'}{}^m \omega_{\mu ml} (R^{-1})^l{}_k + R^{j'}{}^m \partial_\mu (R^{-1})_{mk}$$

Exercise
=>

$$F'_{\mu\nu jk} = R^{j'}{}^m F_{\mu\nu ml} (R^{-1})^l{}_k$$

$$\frac{d}{d\varepsilon} \omega_{\mu}^{j'm} = \partial_\mu \Lambda^m + \epsilon^m{}_{li} \omega_{\mu}^l \Lambda^i = D_{\mu\nu} \Lambda_m = \delta_{\mu\nu}^R \omega_{\mu}^m$$

infinitesimal
 $\frac{d}{d\varepsilon} R_{ij}$
 R_{ij}

$$\omega_{\mu\nu R} = -\underset{\uparrow R}{e_\nu^j} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_{Rj}} + \underset{\uparrow R}{e_\nu^j} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_{Rj}}$$

e_μ^j

$$\partial_{\mu\nu\lambda} (R^{-1})^e_k + R_{,m}^{\nu} \partial_\mu (R^{-1})_{mk}$$

$$R_{,m}^{\nu} \Gamma_{\mu\nu\lambda} (R^{-1})^k$$

$$\Lambda^m + \epsilon^m_{li} \omega_{\mu}^l \Lambda^i$$

$$D_{\mu\nu} \Lambda^m = \delta_{\mu\nu}^R \omega_{\mu}^m$$

infinitesimal rotations.

$$\left. \frac{d}{d\theta} R_3(\theta) \right|_{\theta=0} = \left. \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix} \right|_{\theta=0}$$

$$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^k$$

SO(3)

basis of Lie algebra

$$(\Gamma^k)_{ij} = \epsilon_{ijk}$$

Rotations

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\sigma} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_{\rho\sigma}} + \underset{\uparrow R}{e_\rho^\sigma} \underset{\uparrow R}{\partial_\nu} \underset{\uparrow R}{e_{\sigma\mu}}$$

$$(e^i)_\mu^{j'} = R^{j'}_i ; e_\mu^j$$

$$\omega_{\mu\nu\rho}^{j'} = R^{j'}_m \omega_{\mu\nu\rho}^m (R^{-1})^k_l + R^{j'}_m \partial_\mu (R^{-1})_{mk}$$

Exercise
=>

$$F'_{\mu\nu\rho} = R^{j'}_m F_{\mu\nu\rho}^m (R^{-1})^k_l$$

$$L^m = \partial_\mu L^m + \epsilon^m_{li} \omega_\mu^l \Lambda^i$$

$$D_\mu L^m = \delta_\mu^R \omega_\mu^m$$

$d\epsilon|_{\epsilon=0}$

Rotations

$$\omega_{\mu\nu\rho} = -\underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu} + \underset{\uparrow R}{e_\nu^\rho} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\rho^\nu}$$

$$(e^i)_{\mu'} = R^{j'}_{\mu'} ; e_{\mu'}^j$$

$$\omega_{\mu'j'k'} = R^{m'}_{\mu'} \omega_{\mu m l} (R^{-1})^l_{k'} + R^{m'}_{\mu'} \partial_{\mu'} (R^{-1})_{mk}$$

Exercise
=>

$$F'_{\mu\nu jk} = R^{m'}_{\mu'} F_{\mu m l} (R^{-1})^l_{k'}$$

$$\frac{d}{d\varepsilon} \omega'_{\mu}{}^m \Big|_{\varepsilon=0} = \partial_\mu \Lambda^m + \epsilon^m_{\ell} \omega_{\mu}^{\ell} \Lambda^i = \boxed{D_{\mu} \Lambda^m = \delta_{\ell}^m \omega_{\mu}^{\ell}}$$

Diffeomorphism

$$y^M = \phi^M(x^N), \quad \text{infinitesimally}$$

Diffeomorphism

$$y^M = \phi^M(x^N), \quad \text{infinitesimally: } \phi^M(x) = x^M + \varepsilon$$

Diffeomorphism

$$y^M = \phi^M(x^N), \quad \text{infinitesimally: } \phi^M(x) = x^M + \varepsilon$$

$$(\mathcal{L}_\sigma f)(x) = \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} f(x + \varepsilon \sigma)$$

orphism

$$y^M = \phi^M(x^N), \quad \text{infinitesimally: } \phi^M(x) = x^M + \varepsilon \sigma^M(x)$$

$$(L_\sigma f)(x) = \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} f(x + \varepsilon \sigma) = \sigma^M \partial_M f(x)$$

$$(L_\sigma \omega)_\mu(x) = \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} \left[\omega_\nu(x + \varepsilon \sigma) \frac{\partial \phi^\nu}{\partial x^\mu} \right] = \sigma^\rho \partial_\rho \omega_\mu +$$

infinitesimally: $\phi^\mu(x) = x^\mu + \varepsilon \psi^\mu(x)$

$$\left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} f(x + \varepsilon \psi) = \psi^\mu \partial_\mu f(x)$$

$$= \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} \left[\omega_\nu(x + \varepsilon \psi) \frac{\partial \phi^\nu}{\partial x^\mu} \right] = \psi^\mu \partial_\mu \omega_\nu + \omega_\nu \partial_\mu \psi^\nu$$

$\mu(x)$

$$\partial_\nu \omega_\mu + \omega_\nu \partial_\mu \sigma^\nu$$

$$\delta_\sigma^D e_\mu^j = \sigma^\nu \partial_\nu e_\mu^j + e_\nu^j \partial_\mu \sigma^\nu$$

$$\delta_\sigma^D \omega_\mu^j =$$

Rotatio

$$(e^j)_\mu^{j'} =$$

$$\omega_{\mu}^{jk} =$$

Exercise $\Rightarrow F'_{\mu\nu}$

$$\frac{d}{d\varepsilon} \omega'_{\mu}{}^m \Big|_{\varepsilon=0}$$

R^j , e_μ^j

$$\omega_{\mu j k} = -\underset{\uparrow R}{e_k^\nu} \underset{\uparrow R}{\partial_\mu} \underset{\uparrow R}{e_\nu^j} + \underset{\uparrow R}{e_k^\nu} \underset{\uparrow R}{F_{\nu\sigma}^j} e_\sigma^i$$

$${}^m \omega_{\mu m l} (R^{-1})^l_k + R,{}^m \partial_\mu (R^{-1})_{mk}$$

$$= R,{}^m F_{\mu\nu ml} (R^{-1})^l_k$$

$$\partial_\mu \Lambda^m + \epsilon^m_{li} \omega_\mu^l \Lambda^i =$$

$$\delta_{\perp}^R e_\mu^j = \epsilon^j_{kl} e_\mu^k \Lambda^l$$

$$D_{\perp} \Lambda^m = \delta_{\perp}^R \omega_\mu^m$$

infinitesimal rotations

$$\left. \frac{d}{d\theta} R_3(\theta) \right|_{\theta=0} = \frac{d}{d\theta} \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \\ 0 & 0 \end{pmatrix}_{\theta=0}$$

$$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^k$$

SO(3)

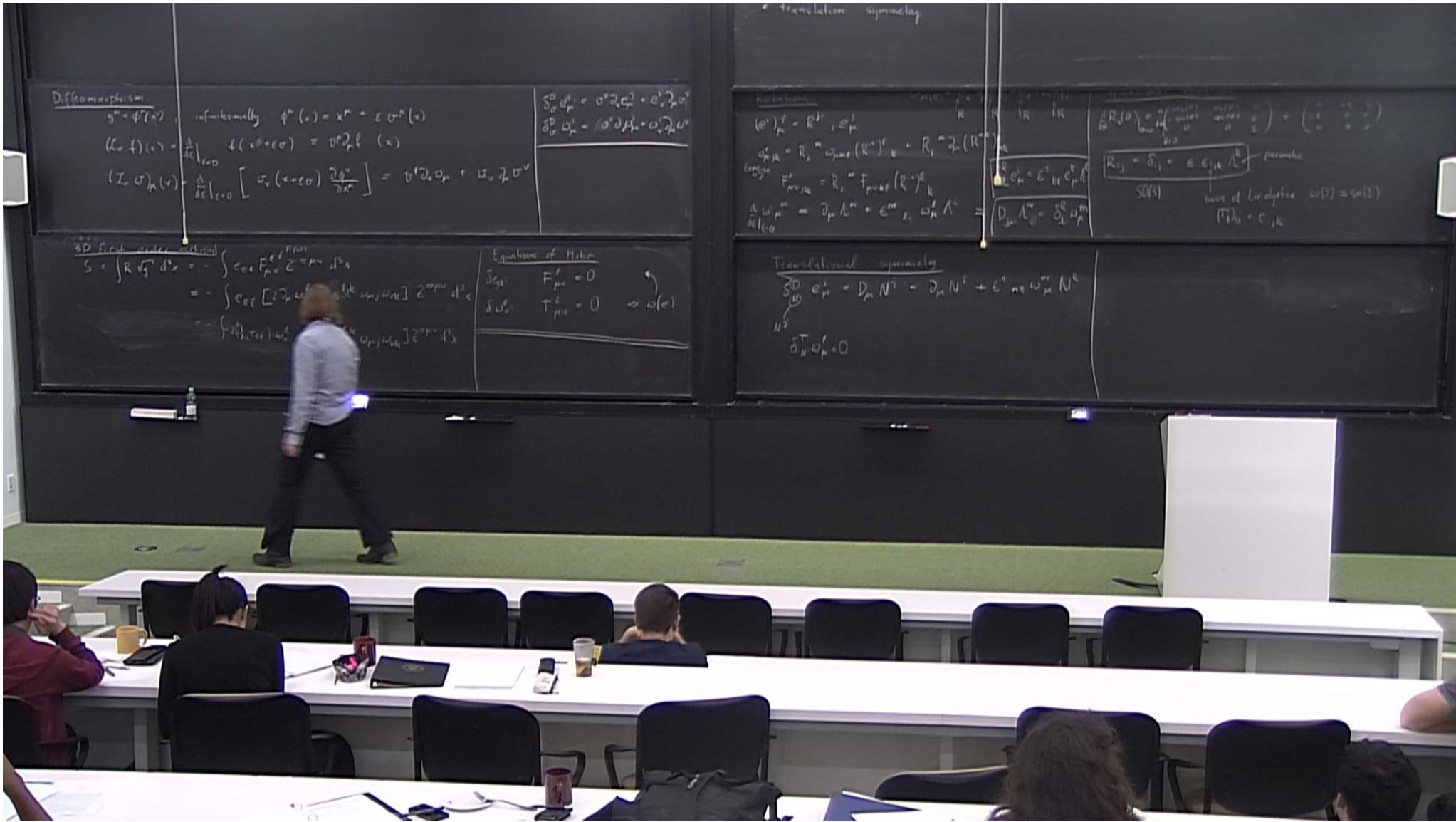
basis of (T^*_k)

Translational symmetry



$$e_{\mu}^i = D_{\mu} N^i = \partial_{\mu} N^i + \epsilon^i{}_{mk} \omega_{\mu}^m N^k$$

$$\delta_N^T \omega_{\mu}^l = 0$$



Diffeomorphism

infinitesimally $\phi^x(x) = x^x + \epsilon \sigma^x(x)$
 $(L \circ \phi)_\mu(x) = \frac{d}{dt} \Big|_{t=0} L(x + \epsilon \sigma) = \sigma^\mu \partial_\mu L(x)$
 $(L \circ \phi)_\mu(x) \stackrel{\Delta}{=} \frac{d}{dt} \Big|_{t=0} \left[\omega_\nu(x + \epsilon \sigma) \frac{\partial \phi^\nu}{\partial x^\mu} \right] = \sigma^\nu \partial_\nu \omega_\mu + \omega_\nu \partial_\mu \sigma^\nu$

$\delta_\sigma^\mu \omega_\mu = \sigma^\nu \partial_\nu \omega^\mu + \omega_\nu \partial_\mu \sigma^\nu$
 $\delta_\sigma^\mu \omega_\mu = \sigma^\nu \partial_\nu \omega^\mu + \omega_\nu \partial_\mu \sigma^\nu$

3D first order action

$S = \int R \sqrt{g} d^3x = - \int \epsilon_{\mu\nu\rho} F_{\mu\nu}^\sigma \tilde{E}^{\rho\sigma} d^3x$
 $= - \int \epsilon_{\mu\nu\rho} [2\partial_\mu \omega_\nu - \partial_\nu \omega_\mu + \omega_\mu \omega_\nu] \tilde{E}^{\rho\sigma} d^3x$
 $= - \int 2\partial_\mu \omega_\nu \tilde{E}^{\rho\sigma} d^3x + \dots$

Equations of Motion

$\frac{\delta S}{\delta \omega_\mu} = F_{\mu\nu}^\sigma = 0$
 $\frac{\delta S}{\delta \tilde{E}^\mu} = T_{\mu\nu}^\sigma = 0 \rightarrow \omega(\epsilon)$

translation symmetry

$(\omega^i)_\mu = R^i_j \omega_\mu^j$
 $\frac{d}{dt} \Big|_{t=0} F_{\mu\nu}^\sigma = R^i_j \omega_\mu^i \omega_\nu^j (R^k_l)^{\sigma} - R^i_j \omega_\nu^i (R^k_l)^{\sigma} \omega_\mu^j$
 $\frac{d}{dt} \Big|_{t=0} \omega_\mu^m = \partial_\mu \Lambda^m + \epsilon^m_{\nu\lambda} \omega_\mu^\nu \Lambda^\lambda = D_\mu \Lambda^m = \delta_\mu^m \omega_\mu^m$

$R_{ij} = \delta_{ij} + \epsilon \epsilon_{ijk} \Lambda^k$ (parameters)
 $SO(3)$ Lie algebra $\omega(D) = \omega(L)$
 $(F_{ij})_k = C_{ijk}$

Translational symmetry

$\frac{d}{dt} \Big|_{t=0} \omega_\mu^i = D_\mu N^i = \partial_\mu N^i + \epsilon^i_{\nu\lambda} \omega_\mu^\nu N^\lambda$
 $\delta_H^\mu \omega_\mu^i = 0$

Translational symmetry

$$\delta_{N^i}^{\text{T}} e_{\mu}^j = D_{\mu} N^i = \partial_{\mu} N^i + \epsilon^i{}_{mk} \omega_{\mu}^m N^k$$

(due to Bianchi identity)

$$\delta_N^{\text{T}} \omega_{\mu}^p = 0$$

3D first order action

$$S = \int R \sqrt{g} d^3x = -$$

$$\int e_{\sigma\ell} F_{\mu\nu}^{\ell} \tilde{E}^{\sigma\mu\nu} d^3x$$

$$0 = N_{\ell} D_{\sigma} F_{\mu\nu}^{\ell} \tilde{E}^{\sigma\mu\nu}$$

⊗ Bianchi identity

$$\int e_{\sigma\ell} [2 \partial_{\mu} \omega_{\nu}^{\ell} + \epsilon^{\ell jk} \omega_{\mu j} \omega_{\nu k}]$$

$$= - \int -2(\partial_{\mu} e_{\sigma\ell}) \omega_{\nu}^{\ell} + e_{\sigma\ell} \epsilon^{\ell jk}$$

Translational symmetry

$$\delta_{N^i}^{\text{T}} e_{\mu}^j = D_{\mu} N^i = \partial_{\mu} N^i + \epsilon^i{}_{mk} \omega_{\mu}^m N^k$$

(due to Bianchi identity)

$$\delta_N^{\text{T}} \omega_{\mu}^{\rho} = 0$$

$$\int \underbrace{R}_{\omega(\sigma)} e^i{}_{\mu} + \int \underbrace{T}_{e(\sigma)} e^j{}_{\mu} = \int \delta^D_{\sigma} e^j{}_{\mu} + T^i{}_{\mu\nu} \sigma^{\nu}$$

$$\Lambda^i = \int \omega^i{}_{\mu} \sigma^{\mu}$$

$$N^R = e^R{}_{\mu} \sigma^{\mu}$$

$$\int \underbrace{R}_{\omega(\sigma)} \omega^i{}_{\mu} + \int \underbrace{T}_{e(\sigma)} \omega^j{}_{\mu} = \int \delta^D_{\sigma} \omega^i{}_{\mu} + T^j{}_{\mu\nu} \sigma^{\nu}$$