

Title: Explorations in Quantum Gravity - Lecture 6

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Abstract:

LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN GR

3d e, ω

$$S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F$$

LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN GR

3d

e, ω

$$S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F$$

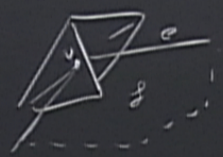
LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN QF

3d e, ω

$$S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F \quad \underline{F=0}$$

- DISCRET.
- HILB. SP., OP.
- TRANS. AMPL



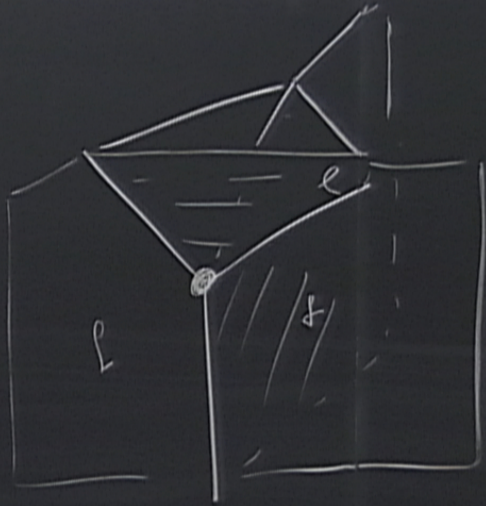
\mathcal{D} { Tetrahedra
Triangles
bones
; } $\Rightarrow \mathcal{D}^k$ { vertex v
edge e
face f

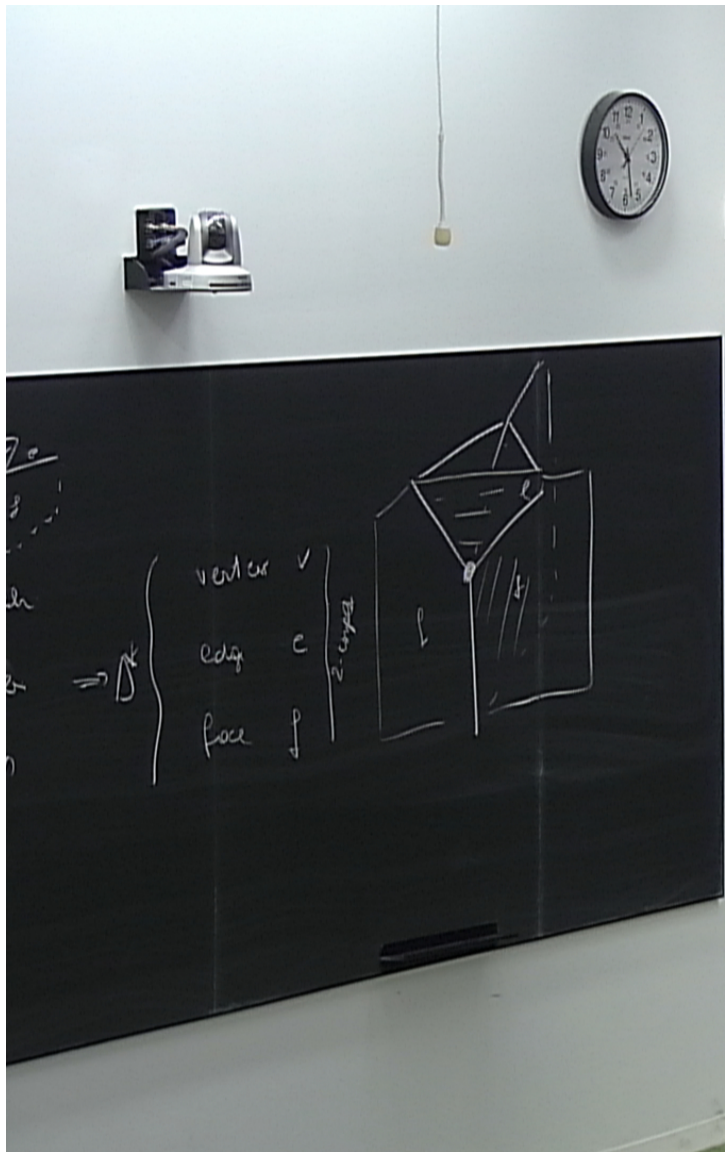


\mathcal{D}

| | | | | | | |
|---|------------|---|--------|-----|---|----------------------------|
| } | Tetrahedra | } | vertex | v | } | $2 \cdot \text{faces} - 2$ |
| | Triangles | | edge | e | | |
| | bones | | face | f | | |
| | ; | | | | | |

$\Rightarrow \mathcal{D}^k$





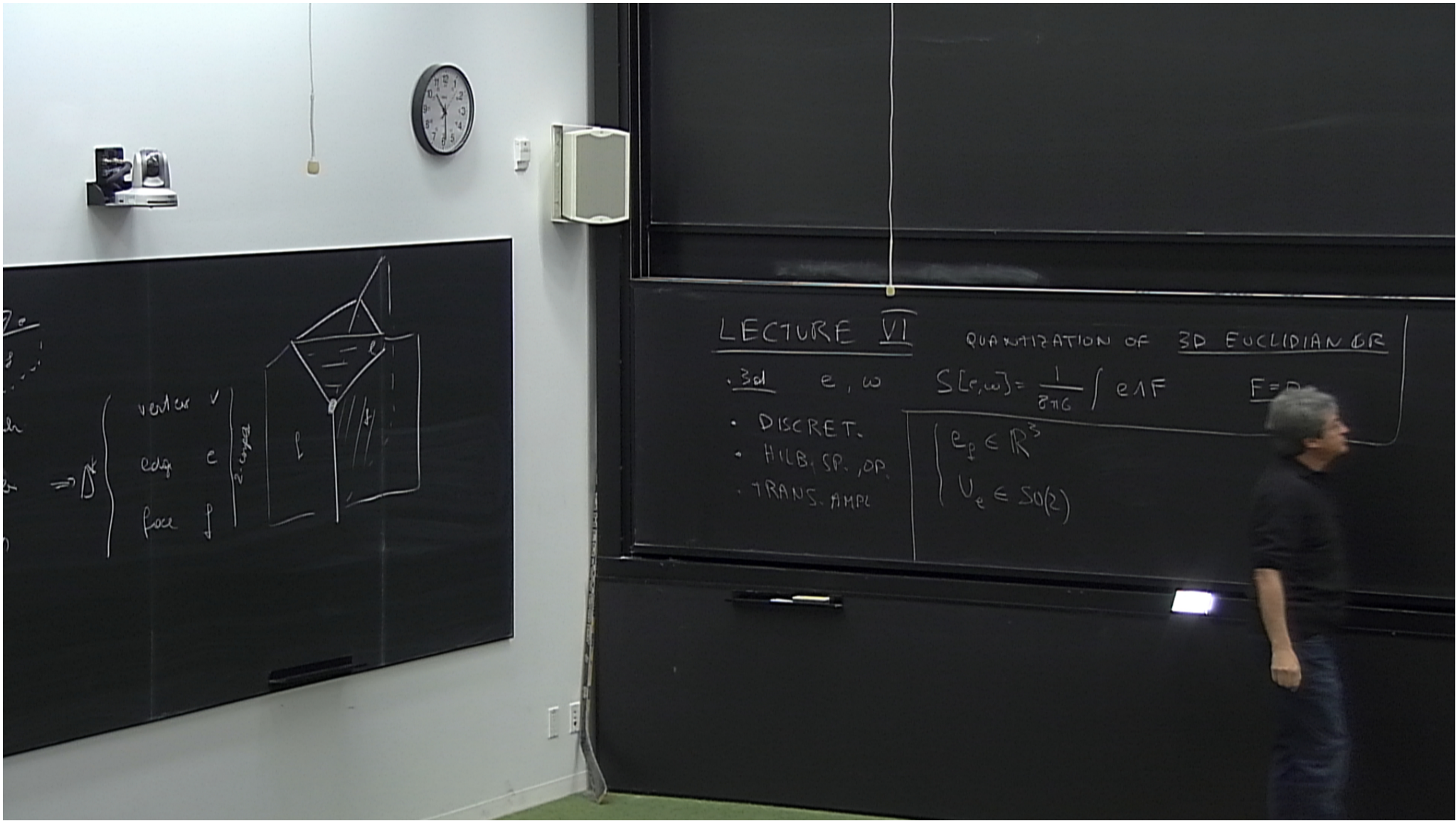
LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN GR

3d e, ω $S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F$ $F = D$

- DISCRET.
- HILB, SP., OP.
- TRANS. AMPL

$$\begin{cases} e_f \in \mathbb{R}^3 \\ U_e \in SO(2) \end{cases}$$



LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN GR

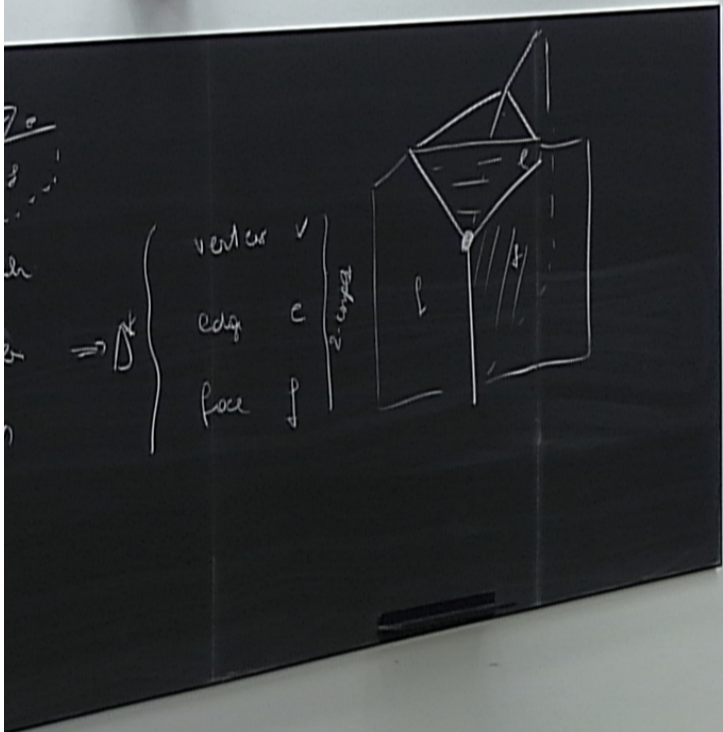
3d e, ω

$$S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F$$

$F = D$

- DISCRET.
- HILB. SP., OP.
- TRANS. AMPL

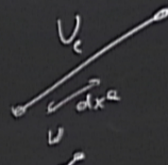
$$\begin{cases} e_p \in \mathbb{R}^3 \\ U_e \in SO(2) \end{cases}$$



PARAMETERIZATION OF 3D EUCLIDIAN DR

$$= \frac{1}{8\pi G} \int e \wedge F$$

$$\underline{F=0}$$

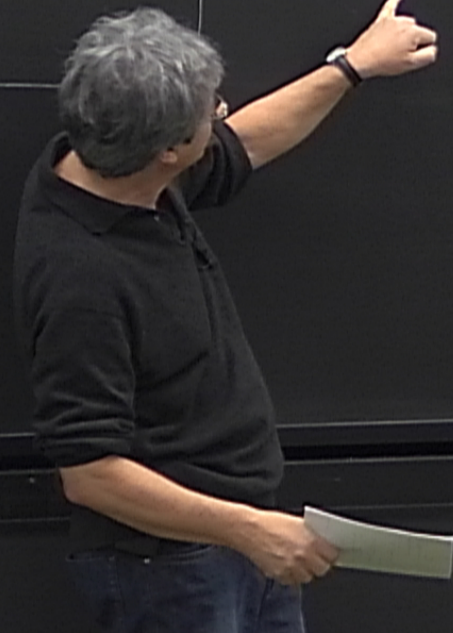


$$U_e \perp \mathbb{1}$$

$$U_e = \mathbb{1} + \omega_e dx^e$$

$$\omega_e = \omega_e^i \sigma_i$$

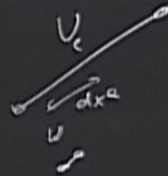
SO(2)



PARAMETERIZATION OF 3D EUCLIDIAN DR

$$= \frac{1}{8\pi G} \int e \wedge F$$

$$\underline{F=0}$$



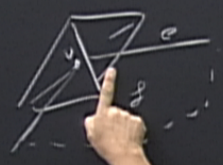
$$U_e \perp \mathbb{1}$$

$$U_e = \mathbb{1} + \omega_e dx^e$$

$$\omega_e = \omega_e^i \sigma_i$$

$$\omega_e^i(x)$$

SO(2)



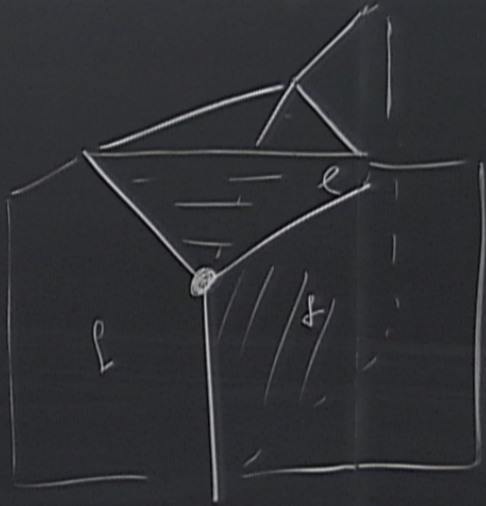
\mathcal{D}

- Tetrahedron
- Triangle
- border
- ;

 \mathcal{D}^k

vertex v
 edge e
 face f

\mathcal{D}^{k-2}



PARAMETERIZATION OF 3D EUCLIDIAN DR

$$\frac{1}{8\pi G} \int e \wedge F$$

$$\underline{F=0}$$



$$U_e \perp \mathbb{1}$$

$$U_e = \mathbb{1} + \omega_e dx^e$$

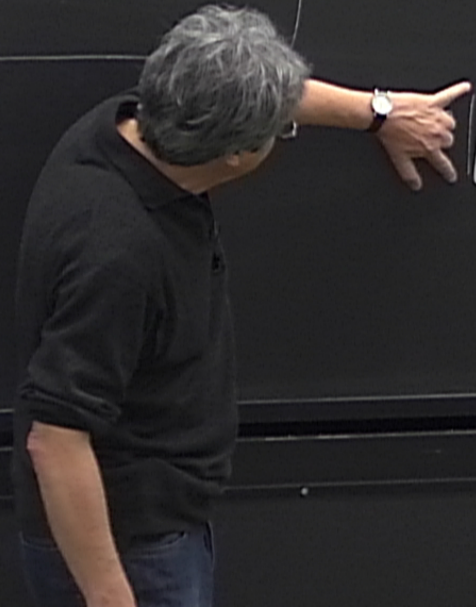
$$\omega_e = \omega_e^i \sigma_i$$

$$\omega_e^i(x)$$

$$\dot{e} = \dot{e}_e^i dx^e$$

e is

$SU(2)$

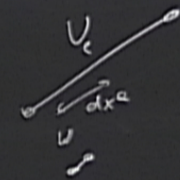


PARAMETERIZATION OF 3D EUCLIDIAN DR

$$\frac{1}{8\pi G} \int e \wedge F$$

$$F=0$$

$$|\vec{e}_a|_{f_b}$$



$$U_e \perp \mathbb{1}$$

$$U_e = \mathbb{1} + \omega_e dx^e$$

$$\omega_e = \omega_e^i \sigma_i$$

$$dx^e \parallel e_a$$

$$\omega_e^i(x)$$

$$\vec{e} = e^i_e dx^e$$

LECTURE VI

QUANTIZATION OF 3D EUCLIDIAN DR

3d e, ω

$$S[e, \omega] = \frac{1}{8\pi G} \int e \wedge F \quad \underline{F=0}$$

- DISCRET.
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- TRANS. AMPL

$e_f \in \mathbb{R}^3$

$U_e \in SU(2)$

L^2

f_6

$\frac{U_e}{\int e \wedge \omega}$

$\omega^a \parallel e^a$

TRANS. AMPL

$$U_e \in SO(2)$$

$$U_f = U_e \cdot U_n$$
$$S = \frac{1}{\sigma} \sum_{\mathbf{p}} T_2(e_f U_f)$$
$$= \cos|\mathbf{a}| \mathbb{1} + i \sin|\mathbf{a}| \frac{a_i}{|\mathbf{a}|} \sigma_i$$

$\mathbb{R}^3 \xrightarrow{\downarrow} \mathfrak{so}(2)$

$$\delta e = U_f = \mathbb{1}$$

TRANS. AMPL

$$U_e \in SO(2)$$

$$U_F = U_e$$
$$S = \frac{1}{\hbar} \sum_F T_2(e_F U_F)$$

$\mathbb{R}^3 \xrightarrow{\downarrow} \mathfrak{so}(2)$

$$e^{i \sum_j a_j \sigma_j} = \cos|a| \mathbb{1} + i \sin|a| \frac{a_i}{|a|} \sigma_i$$

$$\delta e = U_F = \mathbb{1}$$

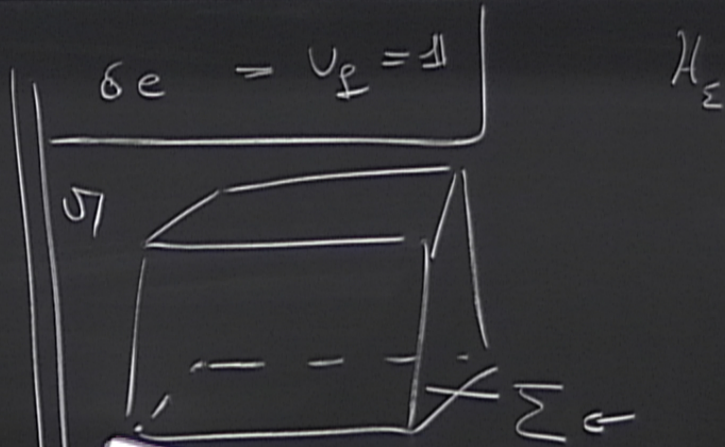
TRANS. AMPL

$$U_e \in SO(2)$$

$$U_F = U_{e_1} \dots U_{e_n}$$

$$S = \frac{1}{8\pi G} \sum_{\pm p} T_2(e)$$

$$e_e = e^{i \int_{\pm p} \sigma_i}$$
$$U_F = e^{i \int_{\pm p} \sigma_i} = 1$$

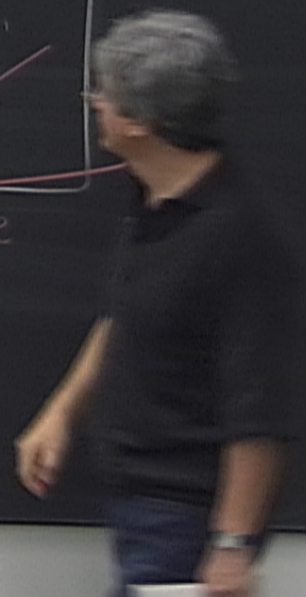
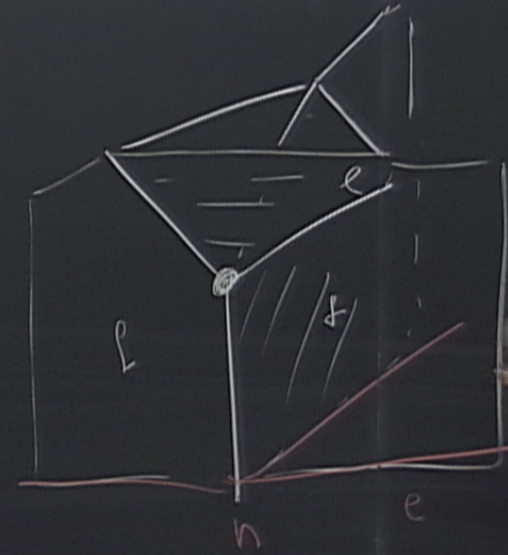




\mathcal{D}

| | | | | | | |
|---|------------|---|--------|-----|---|------------------------|
| } | Tetrahedra | } | vertex | v | } | $2 \cdot \text{edges}$ |
| | Triangles | | edge | e | | |
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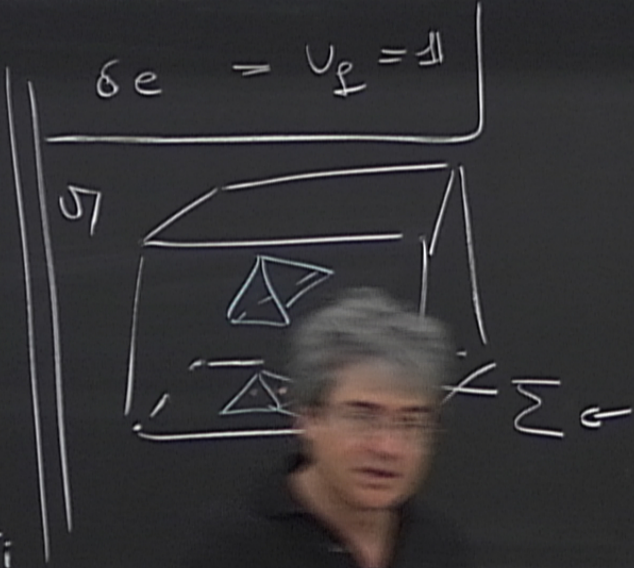
$\Rightarrow \mathcal{D}^k$



MPL $U_e \in SO(2)$

$$U_{en} \xrightarrow{\mathbb{R}^3} \text{SO}(2) \\ \downarrow \quad \downarrow \\ T_2(e_f, U_f)$$

$$\delta e = U_f = \mathbb{1}$$



H_Σ

Graph $\Gamma = \{\text{nodes}, \text{links}\}$
 boundary variable: $\underline{U_e}, \underline{e_e}$

$$= \cos|\alpha| \mathbb{1} + i \sin|\alpha| \frac{\alpha^i}{|\alpha|} \sigma_i$$

$$\| U_P = e^{i \alpha \sigma_i} = \cos|\alpha| \mathbb{1} + i \sin|\alpha| \frac{\alpha_i}{|\alpha|} \sigma_i \|$$

$$\chi(\Gamma) = \psi(U_e) \quad L = \# \text{ of links in the boundary graph}$$

$$\chi(\Gamma) = L_2 [SU(2)^L]$$

\vec{e}

$$\| U_P = e^{i \alpha \sigma_i} = \cos|\alpha| \mathbb{1} + i \sin|\alpha| \frac{\sigma_i}{|\alpha|} \|$$

$$\chi(\Gamma) \geq \psi(U_e) \quad L = \# \text{ of links in the boundary graph}$$

$$\chi(\Gamma) = L_2 [SU(2)^L]$$

\vec{e}_e

$$\| U_P = e^{i \alpha \sigma_i} = \cos|\alpha| \mathbb{1} + i \sin|\alpha| \frac{\alpha_i}{|\alpha|} \sigma_i \|$$

$$\chi(\Gamma) = \psi(U_e)$$

$L = \#$ of links in the boundary graph

$$\chi(\Gamma) = L_2[SU(2)^L]$$

$$\dot{\chi}^i(\Gamma) = \frac{d}{dt} \psi(U e^{it \tau_{i, \Gamma}})$$

$$\vec{\chi}_e = \vec{L}_e$$

$$U_P = e^{i\alpha \sigma_i} = \cos|\alpha| \mathbb{1} + i \sin|\alpha| \frac{\sigma_i}{|\alpha|}$$

$$\chi(\Gamma) = \psi(U_e)$$

$L = \#$ of links in the boundary graph

$$H_\Gamma = L_2[SU(2)^L]$$

$$\psi(t) = \frac{d}{dt} \psi(U e^{it \frac{\sigma_i}{|\alpha|}})$$

$$\vec{E}_e = 8\pi\hbar G \vec{L}_e$$

in the band graph

$$\psi(t) = \frac{d}{dt} \psi(U e^{it \frac{J_i}{2}})$$

$$J_i = \frac{\sigma_i}{2}$$

+ $\frac{U_1 U_2}{e}$

$$\left\{ \frac{e}{8\pi G}, U_i \right\} \sim \delta_{ij} \gamma U$$

$$\sum e, U \sim 8\pi G$$

$$[\hat{e}, \hat{U}] = i\pi \{e, U\} \\ = i\pi 8\pi G$$

$$\{e^A, \omega^i_B(\gamma)\} = \delta(x, y) \delta^0_\gamma \delta^i_B$$

$$\{e^A, U_i\} = \{e^A, p^e\} = \gamma U \\ = U \gamma U^2$$

in the band graph

$$\psi(t) = \frac{d}{dt} \psi(U e^{it \frac{J_i}{2}})$$

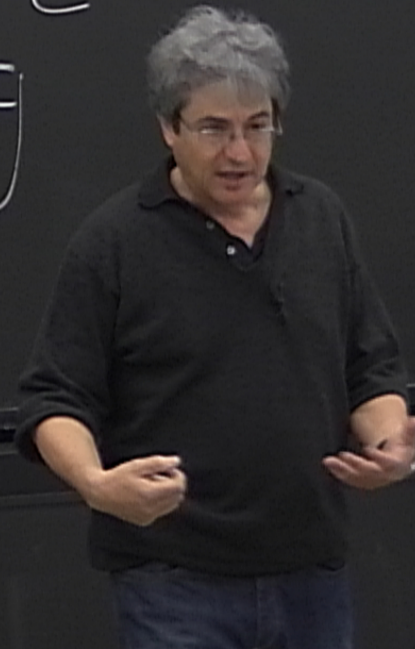
$$J_i = \frac{\sigma_i}{2}$$

$$\left(\begin{array}{l} \{ \frac{e_i}{8\pi G}, U_i \} \sim \delta_{ij} \text{ } \gamma U \\ \sum e_i, U_i \sim 8\pi G \\ [\hat{e}_i, \hat{U}_i] = i\hbar \{e_i, U_i\} \\ = i\hbar 8\pi G \\ \{ e_i^A, \omega_j^B(\gamma) \} = \delta(x, y) \delta_{ij}^0 \delta_{ij}^1 \\ \{ e_i^A, U_j^B \} = \{ e_i^A, p_j^B \} = \delta_{ij}^0 \delta_{ij}^1 \\ = U_j^B \end{array} \right)$$

$$L_B = L_e$$

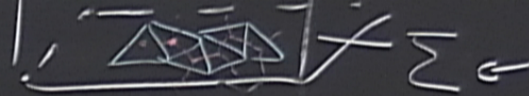
$$L_e^2 = (8\pi G\hbar)^2 \vec{L}_s \cdot \vec{L}_s = (8\pi G\hbar)^2 C$$

$$L_e = \underline{8\pi G\hbar} \sqrt{j(j+1)}$$



$$e_e = e^{i\theta_i \sigma_i}$$

$$U_f = e^{i\theta_i \sigma_i} = \cos|\theta| \mathbb{1} + i \sin|\theta| \frac{\theta_i}{|\theta|} \sigma_i$$



$$\chi(\Gamma) \geq \psi(U_e)$$

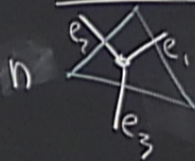
$L = \#$ of links in the boundary graph

$$J_i = \frac{g_i}{2}$$

$$\mathcal{H}_\Gamma = L_2[SU(2)^L]$$

$$\vec{e}_e = 8\pi h G \vec{L}_e$$

$$\vec{L}^i \psi(t) = \frac{d}{dt} \psi(U e^{it \frac{J_i}{n}})$$



$$\vec{C}_n = \vec{L}_{e_1} + \vec{L}_{e_2} + \vec{L}_{e_3} = 0$$