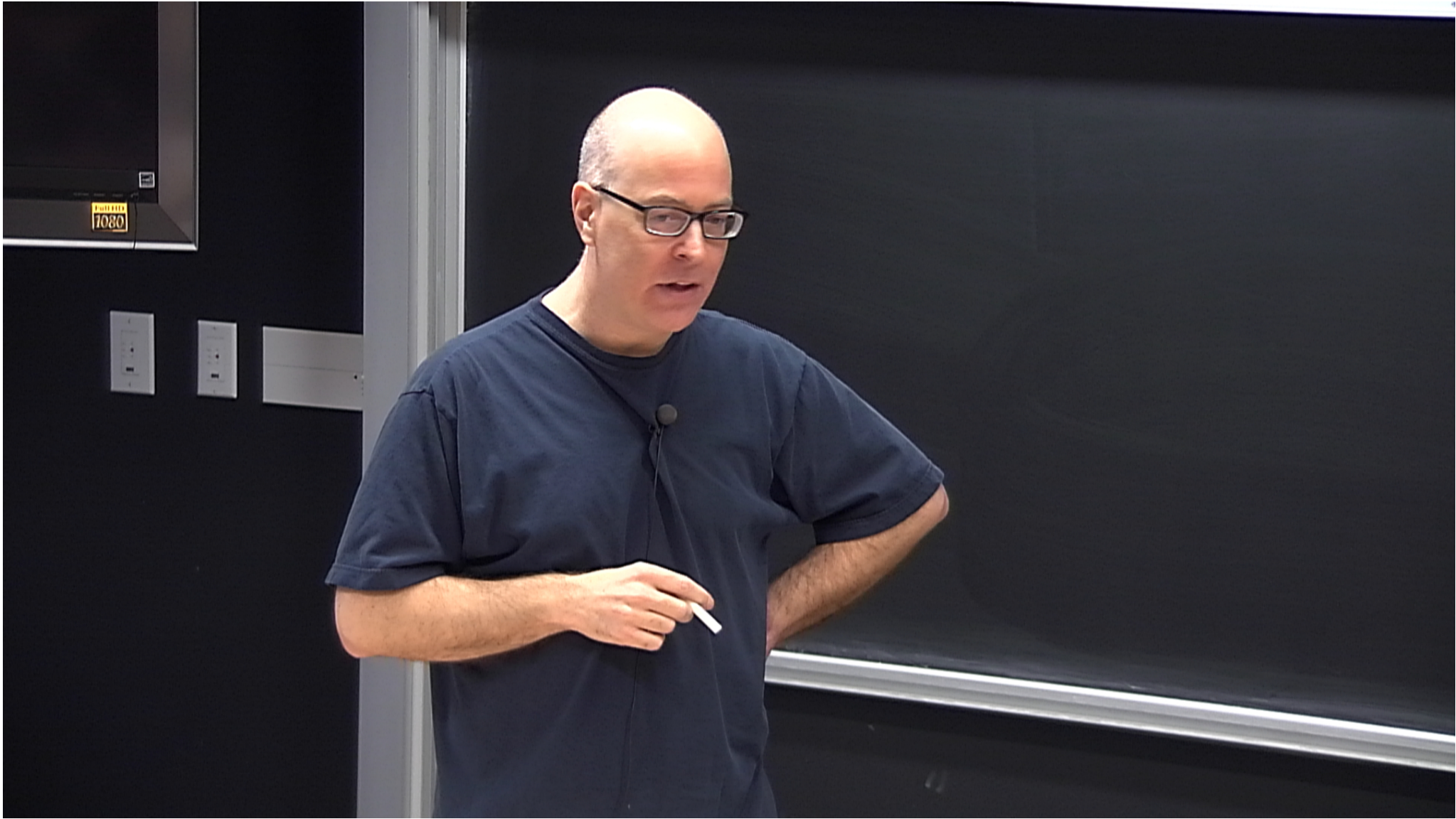


Title: Advanced General Relativity - Lecture 15

Date: Mar 07, 2012 10:00 AM

URL: <http://pirsa.org/12030068>

Abstract:



HAMILTONIAN FORMULATION

mechanics:

$$L(q, \dot{q}) \rightarrow p = \frac{\partial L}{\partial \dot{q}}$$

HAMILTONIAN FORMULATION

mechanics:

$$L(q, \dot{q}) \rightarrow p = \frac{\partial L}{\partial \dot{q}}$$

$$H = p\dot{q} - L$$

HAMILTONIAN FORMULATION

mechanics:

$$L(q, \dot{q}) \rightarrow p = \frac{\partial L}{\partial \dot{q}}$$

$$H = p\dot{q} - L$$

field theory in flat spacetime:

$$\mathcal{L}(\varphi, \partial_\alpha \varphi) \rightarrow \pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \varphi)}$$

HAMILTONIAN FORMULATION

mechanics: $L(q, \dot{q}) \rightarrow p = \frac{\partial L}{\partial \dot{q}}$

$$H = p\dot{q} - L$$

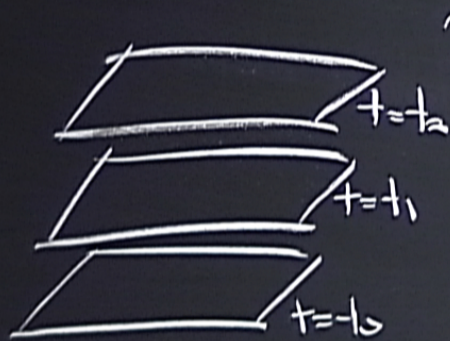
field theory in flat spacetime:

$$\mathcal{L}(\psi, \partial_\alpha \psi) \rightarrow \pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \psi)}$$

$$\partial \mathcal{L} = \pi \partial_t \psi - \mathcal{L} = T_{00}$$

$$H = \int \mathcal{H} d^3x = \text{total field energy}$$

field theory in flat spacetime:



$$\mathcal{L}(\varphi, \partial_\alpha \varphi)$$

$$H = p \dot{q} - L$$

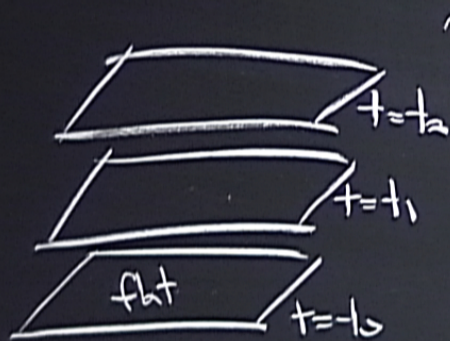
$$\pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \varphi)}$$

$$\mathcal{H} = \pi \partial_t \varphi - \mathcal{L} = T_{00}$$

$$H = \int \mathcal{H} d^3x = \text{total field energy}$$

field theory in curved spacetime:

field theory in flat spacetime:



$$\mathcal{L}(\varphi, \partial_\alpha \varphi)$$

$$H = p \dot{q} - \overline{L}$$

$$\pi = \frac{\partial \mathcal{L}}{\partial (\partial_t \varphi)}$$

$$\mathcal{H} = \pi \partial_t \varphi - \mathcal{L} = T_{00}$$

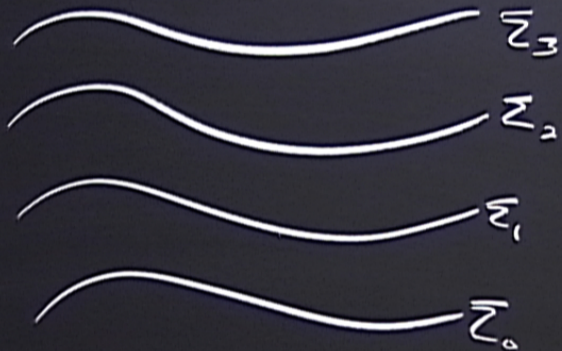
$$H = \int \mathcal{H} d^3x = \text{total field energy}$$

field theory in curved

foliated

$$H = \int \mathcal{H} \delta X = \text{total field energy}$$

field theory in curved spacetime: foliate spacetime with arbitrary spacelike hypersurfaces.



$$\partial \psi \rightarrow n^\alpha \partial_\alpha \psi$$

3+1 decomposition



time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

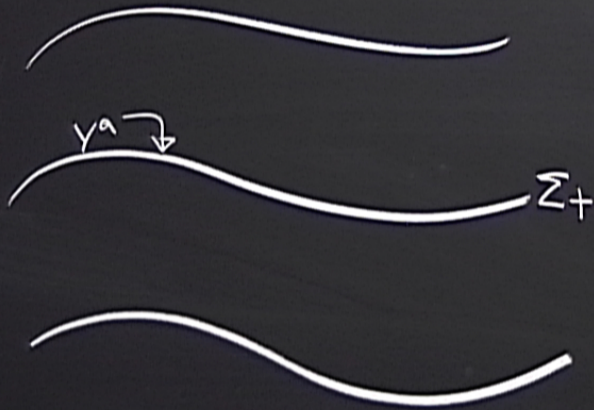
3+1 decomposition



time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

3+1 decomposition



time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

3+1 decomposition



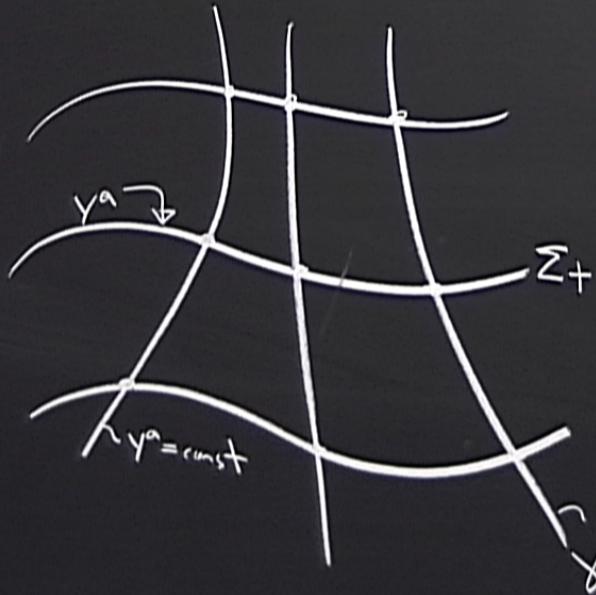
time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t$$

$$n_\alpha n^\alpha = -1$$

γ congruence of curves; $y^a = \text{const}$

3+1 decomposition

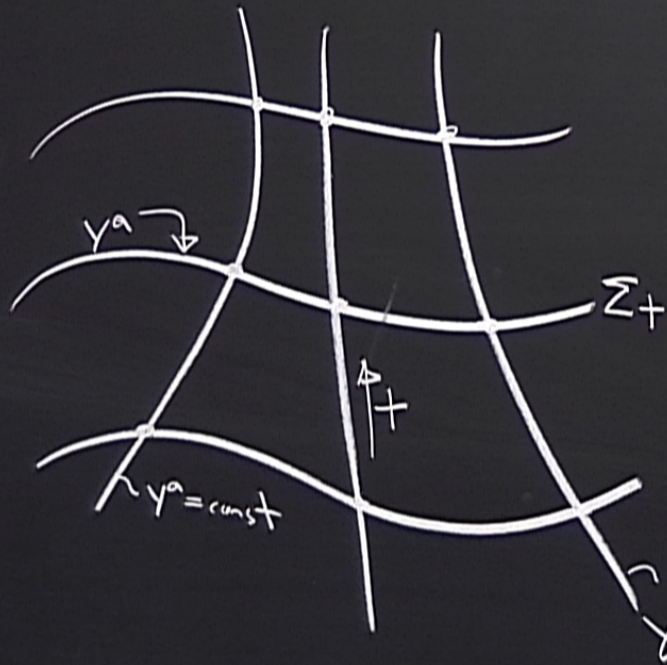


time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

ring curve of curves, $y^\alpha = \text{const}$

3+1 decomposition

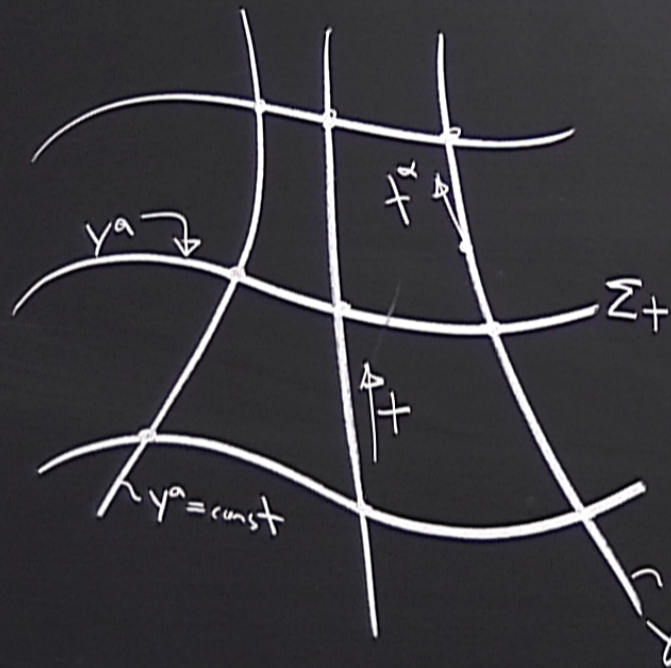


time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

γ congruence of curves $y^a = \text{const}$; parameterized by t .

3+1 decomposition

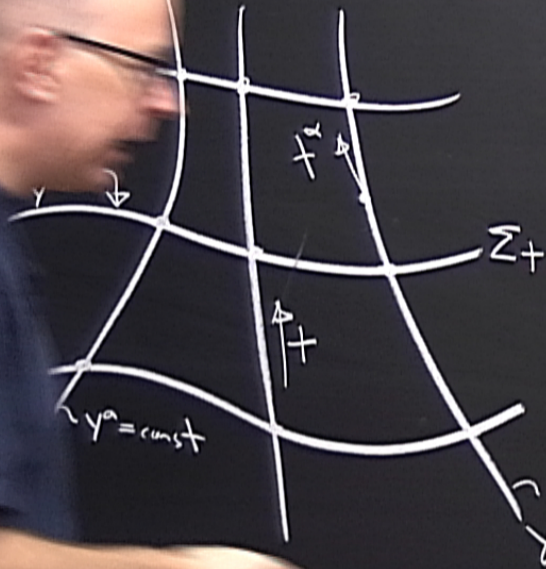


time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

congruence of curves $y^a = \text{const}$; parameterized by t .
 Displacement along curve: $dx^\alpha =$

3+1 decomposition



time function $t(x^\alpha)$, such that
 $t = \text{const}$ on each Σ_t

$$n_\alpha \propto \partial_\alpha t \quad n_\alpha n^\alpha = -1$$

in a curve of curves; $y^a = \text{const}$; parameterized by t ; tangent vector t^α

Displacement along curve: $dx^\alpha = t^\alpha dt$

Change in t will be given by

$$dt = \frac{\partial t}{\partial x^\alpha} dx^\alpha = \left(\frac{\partial t}{\partial x^\alpha} t^\alpha \right) dt$$

magnitude of curves; $y^a = \text{const}$; parameterized by t ; tangent v

Displacement along curve: $dx^\alpha = \dot{x}^\alpha dt$

Change in t will be given by

$$dt = \frac{\partial t}{\partial x^\alpha} dx^\alpha = \left(\frac{\partial t}{\partial x^\alpha} \dot{x}^\alpha \right) dt$$

Original coordinate system X^α

Alternative: (t, y^a)

Relation $X^\alpha = X^\alpha(t, y^a)$: parametric relations for γ

$$\boxed{t^\alpha \partial_\alpha t = 1}$$

Original
Alternative
Relation

$$\left(\frac{\partial X^\alpha}{\partial t} \right)_{y^a} = t^\alpha$$

$$\left(\frac{\partial X^\alpha}{\partial y^a} \right)_t = e_a^\alpha$$

$$\boxed{t^\alpha \partial_\alpha t = 1}$$

Original coordinate sys

Alternative: $(t$

Relation $\boxed{x^\alpha = x^\alpha$

$$\left(\frac{\partial x^\alpha}{\partial t} \right)_{y^a} = t^\alpha \quad (\text{tangent to congruence})$$

$$\left(\frac{\partial x^\alpha}{\partial y^a} \right)_t = e_a^\alpha \quad (\text{tangent to } \Sigma_t)$$

$$\boxed{t^\alpha \partial_\alpha t = 1}$$

Original coordinate system x^α

Alternative: (t, y^a)

Relation $\boxed{x^\alpha = x^\alpha(t, y^a)}$ parametric relations for

$$\left(\frac{\partial x^\alpha}{\partial t} \right)_{y^a} = t^\alpha \quad (\text{tangent to congruence})$$

$$\left(\frac{\partial x^\alpha}{\partial y^a} \right)_t = e_a^\alpha \quad (\text{tangent to } \Sigma_t)$$

$$\mathcal{L}_t e_a^\alpha = 0$$

$$\boxed{t^\alpha \partial_\alpha t = 1}$$

Original coordinate system x^α

Alternative: (t, y^a)

Relation $\boxed{x^\alpha = x^\alpha(t, y^a)}$ parametric relations for γ

$$\left(\frac{\partial x^\alpha}{\partial t} \right)_{y^a} = t^\alpha \quad (\text{tangent to congruence})$$

$$\left(\frac{\partial x^\alpha}{\partial y^a} \right)_t = e_a^\alpha \quad (\text{tangent to } \Sigma_t)$$

$$\boxed{y^\alpha + e_a^\alpha = 0}$$

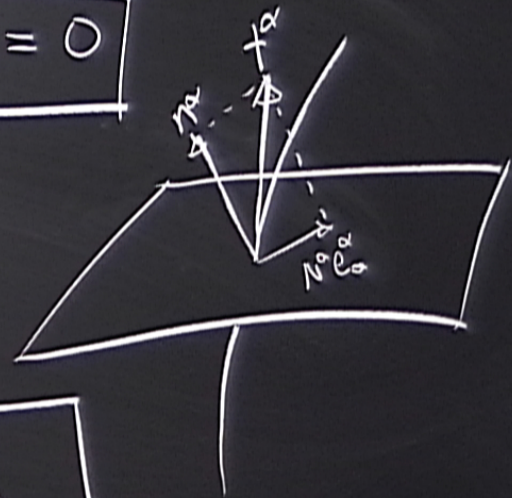
$$\boxed{n_\alpha = -N \partial_\alpha t}$$

↳ lapse function.

$$\boxed{n_\alpha e_a^\alpha = 0}$$

$$\boxed{t^\alpha = N n^\alpha + N^a e_a^\alpha}$$

↳ shift vector



$$t^\alpha = A n^\alpha + N^\alpha e_\alpha$$
$$1 = t^\alpha \partial_\alpha t = t^\alpha \left(-\frac{1}{N} n_\alpha \right) = (A n^\alpha + \dots) \left(-\frac{1}{N} n_\alpha \right) = \frac{A}{N}$$

$$t^\alpha = A n^\alpha + N^\alpha e_\alpha$$

$$1 = t^\alpha \partial_\alpha t = t^\alpha \left(-\frac{1}{N} n_\alpha \right) = (A n^\alpha + \dots) \left(-\frac{1}{N} n_\alpha \right) = \frac{A}{N}$$

metric in coordinates (t, y^a) :

$$dx^\alpha = t^\alpha dt + e_a^\alpha dy^a$$

$$= (Nn^\alpha + N^a e_a^\alpha) dt + e_a^\alpha dy^a$$

$$= (Ndt) n^\alpha + (N^a dt + dy^a) e_a^\alpha$$

metric in coordinates (t, y^a) :

$$\begin{aligned} dx^\alpha &= t^\alpha dt + e_a^\alpha dy^a \\ &= (Nn^\alpha + N^a e_a^\alpha) dt + e_a^\alpha dy^a \\ &= (Ndt) n^\alpha + (N^a dt + dy^a) e_a^\alpha \end{aligned}$$

$$\begin{aligned} ds^2 &= g_{\alpha\beta} dx^\alpha dx^\beta = g_{\alpha\beta} [Ndt n^\alpha + (dy^a + N^a dt) e_a^\alpha] [Ndt n^\beta + (dy^b + N^b dt) e_b^\beta] \\ &= -N^2 dt^2 \end{aligned}$$

metric in coordinates (t, y^a) :

$$\begin{aligned} dx^\alpha &= t^\alpha dt + e_a^\alpha dy^a \\ &= (Nn^\alpha + N^a e_a^\alpha) dt + e_a^\alpha dy^a \\ &= (Ndt) n^\alpha + (N^a dt + dy^a) e_a^\alpha \end{aligned}$$

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta = g_{\alpha\beta} [Ndt n^\alpha + (dy^a + N^a dt) e_a^\alpha] [Ndt n^\beta + (dy^b + N^b dt) e_b^\beta]$$

$$\boxed{ds^2 = -N^2 dt^2 + h_{ab} (dy^a + N^a dt) (dy^b + N^b dt)}$$
$$h_{ab} = g_{\alpha\beta} e_a^\alpha e_b^\beta$$

3+1 decomposition.

Metric in coordinates (t, y) :

$$\begin{aligned} dx^\alpha &= t^\alpha dt + e_a^\alpha dy^a \\ &= (N n^\alpha + N^a e_a^\alpha) dt + e_a^\alpha dy^a \\ &= (N dt) n^\alpha + (N^a dt + dy^a) e_a^\alpha \end{aligned}$$

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta = g_{\alpha\beta} [N dt n^\alpha + (dy^a + N^a dt) e_a^\alpha] [N dt n^\beta + (dy^b + N^b dt) e_b^\beta]$$

$$\boxed{ds^2 = -N^2 dt^2 + h_{ab} (dy^a + N^a dt) (dy^b + N^b dt)} \quad \text{3+1 decomposition.}$$
$$h_{ab} = g_{\alpha\beta} e_a^\alpha e_b^\beta$$

For a displacement along σ , $dy^a = 0$

$$\begin{aligned} ds^2 &= -N^2 dt^2 + h_{ab} N^a N^b dt^2 \\ &= -(N^2 - h_{ab} N^a N^b) dt^2 \end{aligned}$$

$$= (N dt | n + (N dt + dy^a | e_a$$

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta = g_{\alpha\beta} [N dt + n^\alpha + (\partial y^a + N^a dt) e_a^\alpha] [N dt + n^\beta + (\partial y^b + N^b dt) e_b^\beta]$$

$$ds^2 = -N^2 dt^2 + h_{ab} (\partial y^a + N^a dt) (\partial y^b + N^b dt)$$

$$h_{ab} = g_{\alpha\beta} e_a^\alpha e_b^\beta$$

3+1 decomposition.

For a displacement along ∂_t , $\partial y^a = 0$

$$ds^2 = -N^2 dt^2 + h_{ab} N^a N^b dt^2$$

$$= -(N^2 - h_{ab} N^a N^b) dt^2$$

$$\sqrt{-g} = N \sqrt{h}$$

Hamiltonian of a field theory

$$\mathcal{L}(\psi, \partial_\mu \psi)$$

Hamiltonian of a field theory

$$\mathcal{L}(\psi, \partial_\mu \psi)$$

$$\partial_\mu \psi \rightarrow \dot{\psi} \equiv \mathcal{L}_+ \psi$$

For a displacement $\delta y = 0$, $\delta S = -N \delta t + \hbar \delta N^a N^b \delta t$

$$\boxed{\sqrt{-g} = N \sqrt{h}}$$

$$= - (N^a \hbar \delta N^a N^b) \delta t^2$$

$$\mathcal{L}(\psi, \partial_\alpha \psi)$$

$$\partial_\alpha \psi \rightarrow \boxed{\dot{\psi} \equiv \mathcal{L}_+ \psi} \quad (\text{derivative along } t^\alpha, \text{ not } n^\alpha)$$

$$\boxed{\pi \equiv \frac{\partial}{\partial \dot{\psi}} (\sqrt{-g} \mathcal{L})}$$

canonical momentum.

↳ not a scalar.

Hamiltonian density

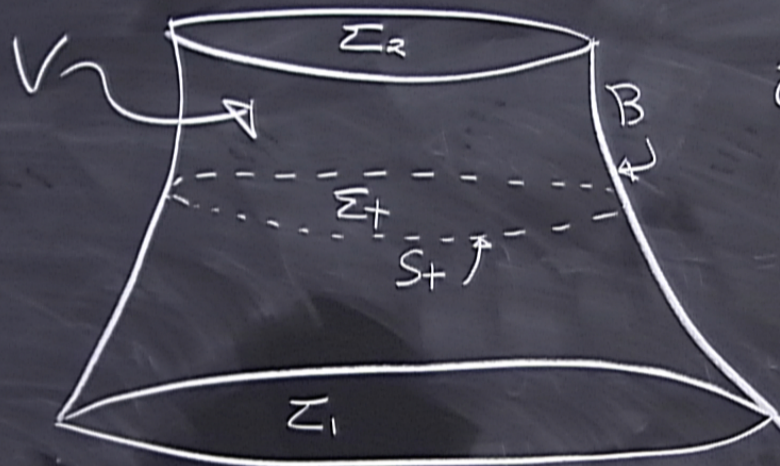
$$\boxed{\mathcal{H} \equiv \pi \dot{\psi} - \sqrt{-g} \mathcal{L}}$$

$$\boxed{H = \int \mathcal{H} d^3 y}$$

Hamiltonian.

Hamiltonian formulation of GR:

$$16\pi S_G = \int_V {}^4R \sqrt{-g} d^4x + 2 \oint_{\partial V} \varepsilon K \sqrt{|h|} d^3y$$



$$\partial V = B + \Sigma_1 + \Sigma_2$$

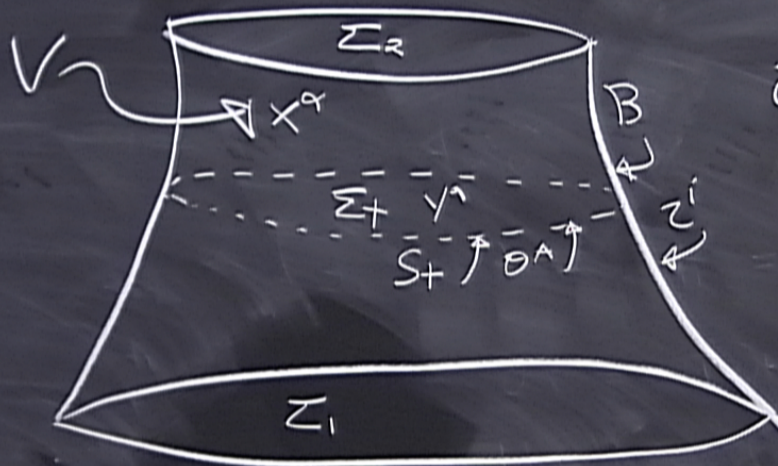
V is foliated by Σ_+

Σ_+ is bounded by S_+

B is foliated by S_+

Hamiltonian Formulation of GR:

$$16\pi S_G = \int_V 4R \sqrt{-g} d^4x + 2 \oint_{\partial V} \epsilon K \sqrt{|h|} d^3y$$



$$\partial V = B + \Sigma_1 + \Sigma_2$$

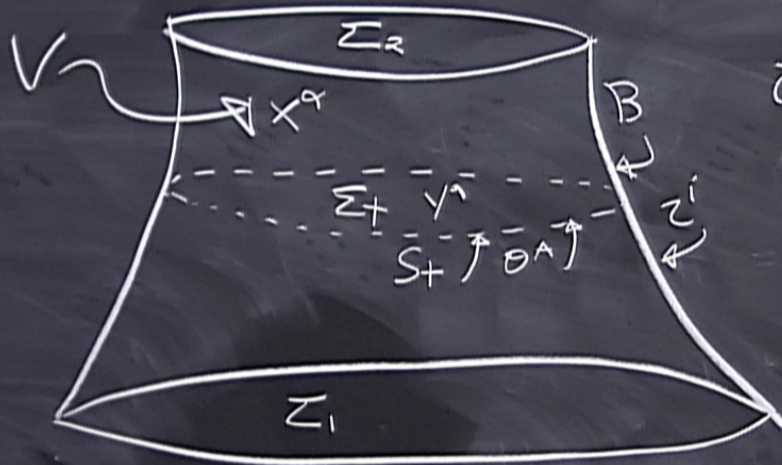
V is foliated by Σ_+

Σ_+ is bounded by S_+

B is foliated by S_+

Hamiltonian Formulation of GR:

$$16\pi S_G = \int_V {}^4R \sqrt{-g} d^4x + 2 \oint_{\partial V} \epsilon K \sqrt{|h|} d^3y$$



$\partial V = B + \Sigma_1 + \Sigma_2$
 V is foliated by Σ_+
 Σ_+ is bounded by S_+
 B is foliated by S_+