

Title: Quantum correlations with no causal order

Date: May 10, 2011 02:50 PM

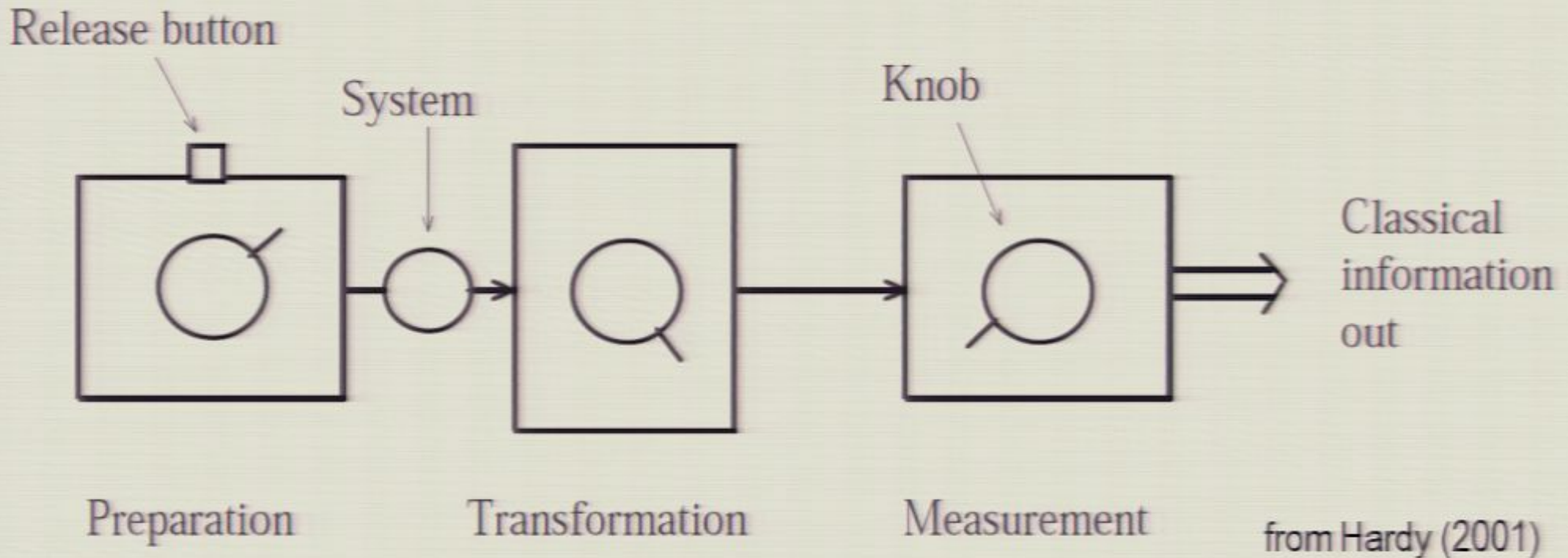
URL: <http://pirsa.org/11050039>

Abstract: Much of the recent progress in understanding quantum theory has been achieved within an operational approach. Within this context quantum mechanics is viewed as a theory for making probabilistic predictions for measurement outcomes following specified preparations. However, thus far some of the essential elements of the theory – space, time and causal structure – elude such an operational formulation and are assumed to be fixed. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying spacetime or causal structure are not assumed? What new phenomenology can follow from such an approach? We develop a framework for multipartite quantum correlations that does not presume these notions, but simply that experimenters in their local laboratories are free to perform arbitrary quantum operations. All known situations that respect definite causal order, including signalling and no-signalling correlations between space-like and time-like separated experiments, as well as probabilistic mixtures of these, can be expressed in this framework. Remarkably, we find quantum correlations which are neither causally ordered nor in a probabilistic mixture of definite causal orders. These correlations are shown to enable performing a communication task that is impossible if a fixed background time is assumed and the events are sufficiently localized in the time.

# Quantum correlations with no causal order

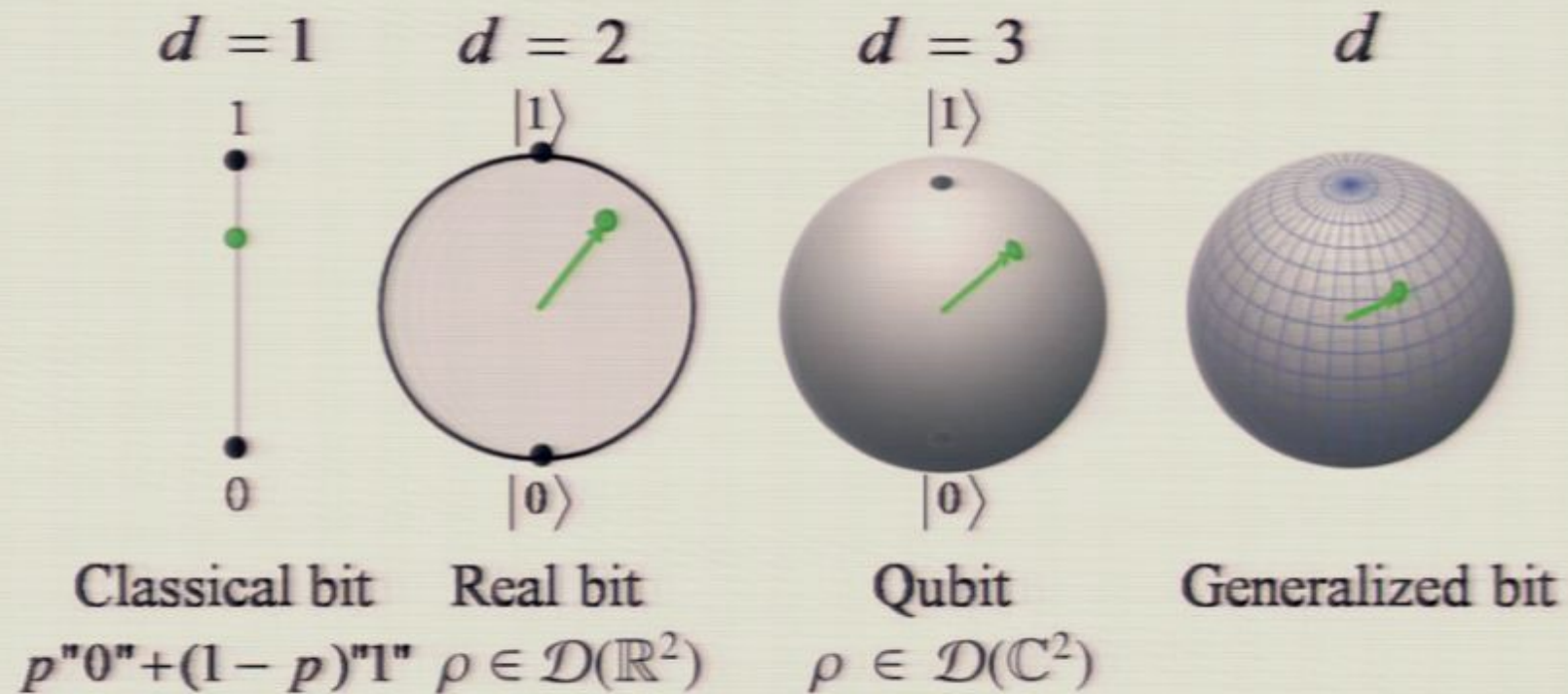
Ognyan Oreshkov, Fabio Costa, Časlav Brukner\*

# Operational Approach



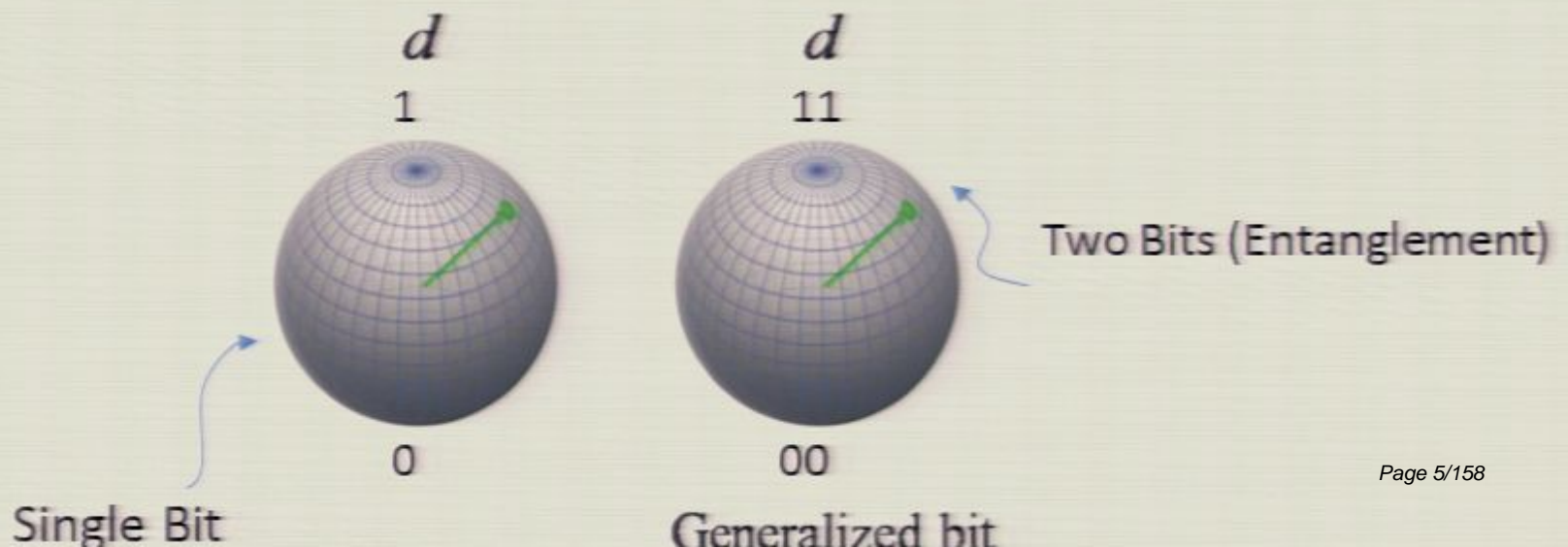
Last 10 years significant progress in understanding quantum theory within **operationalism** with primitive laboratory procedures as basic ingredients.

# 1 Bit Systems

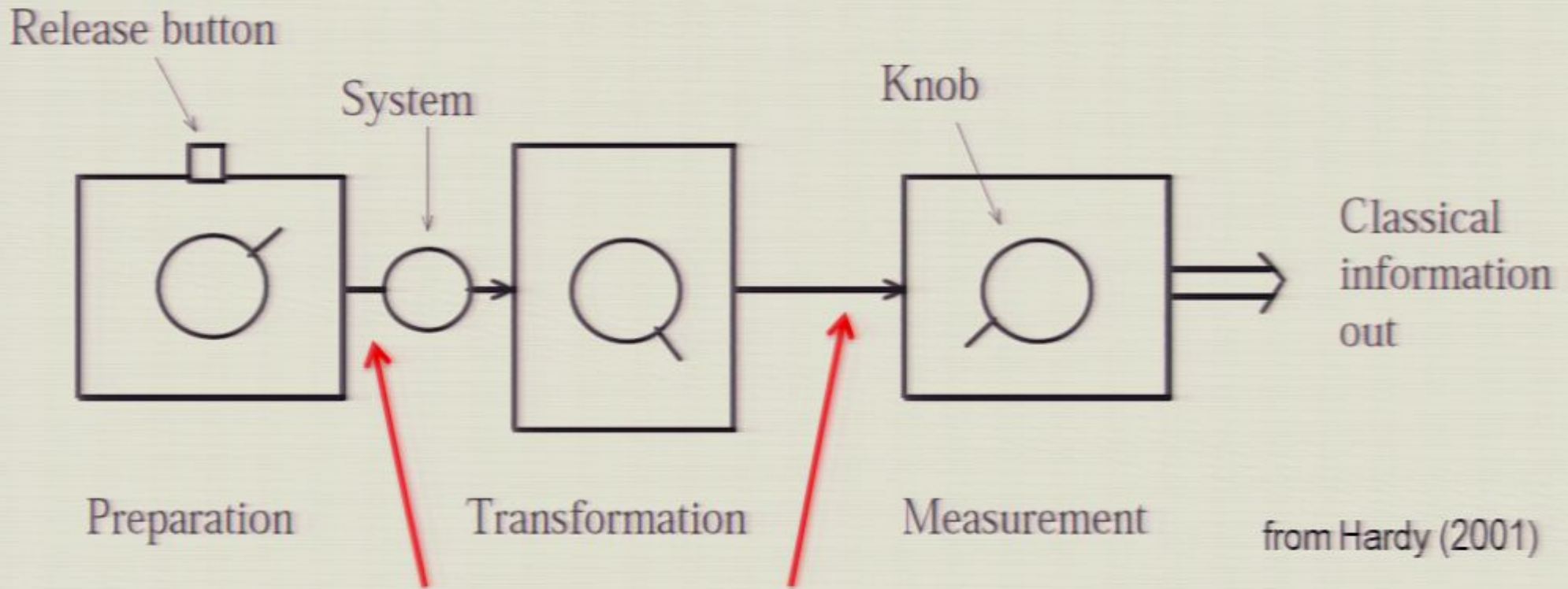


**➔ d=1 or d=3**

1. **Orthogonal Decomposition:** Any state of 1-bit system can be prepared by mixing two perfectly distinguishable states.
2. **Reversibility:** Between any two pure states there exists a reversible transformation
3. **Local Tomography:** The state of a composite system is completely determined by local measurements on its subsystems and their correlations.
4. **Subspace Axiom:** All 1-bit systems are equivalent **irrespectively of our (classical) notion of localizability**

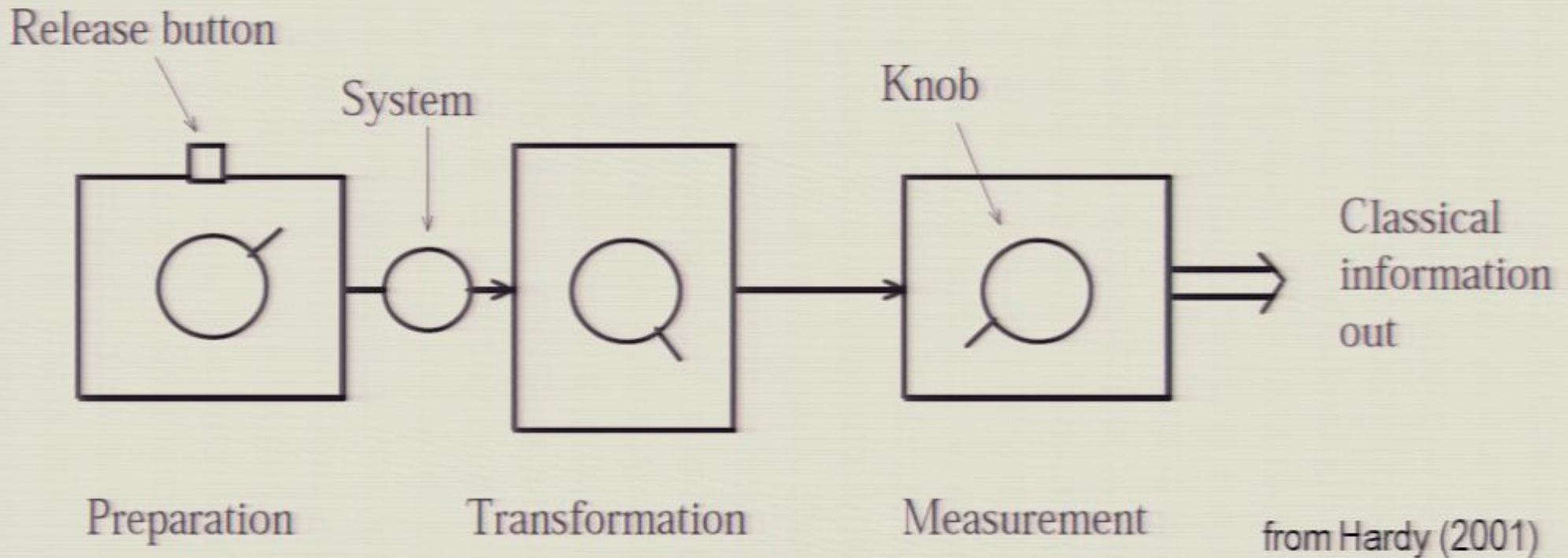


# Operational Approach

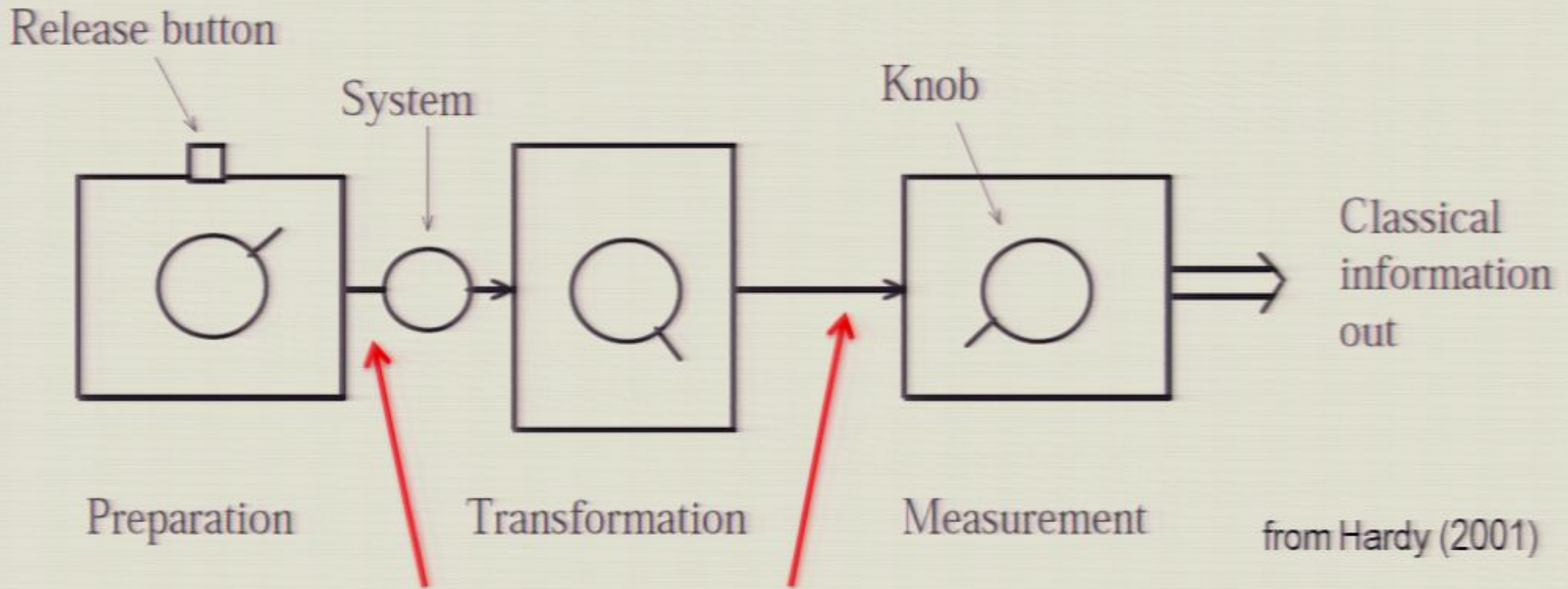


**Presupposes definite causal order**

# Operational Approach



# Operational Approach



**Presupposes definite causal order**



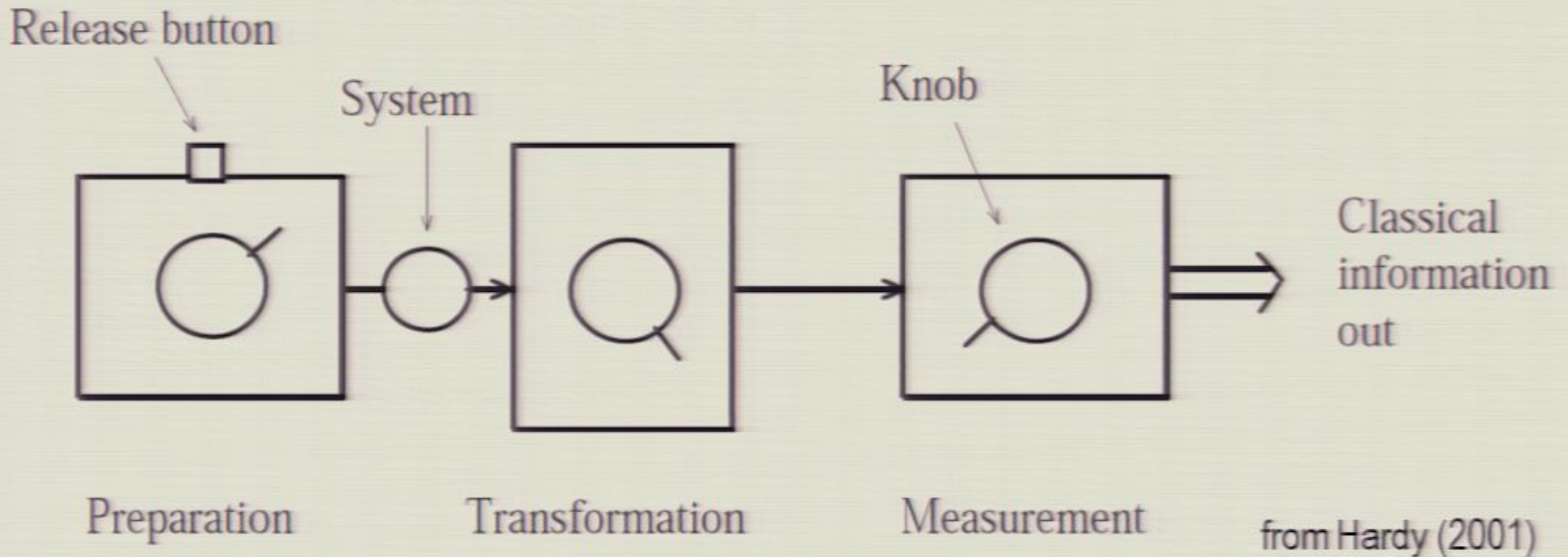
# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?
3. What new phenomenology can follow from such an approach?

Find a general framework for probabilistic theories with no pre-existing causal structure.

L. Hardy arXiv:gr-qc/0509120,  
Probability Theories with Dynamic Causal Structure:  
A New Framework for Quantum Gravity

# Operational Approach



# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?
3. What new phenomenology can follow from such an approach?

Find a general framework for probabilistic theories with no pre-existing causal structure.

L. Hardy arXiv:gr-qc/0509120,  
Probability Theories with Dynamic Causal Structure:  
A New Framework for Quantum Gravity

# Questions

# Questions

# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?

# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?

# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?
3. What new phenomenology can follow from such an approach?



# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?
3. What new phenomenology can follow from such an approach?

Find a general framework for probabilistic theories with no pre-existing causal structure.

# Questions

1. Is definite causal structure a necessary pre-assumption or does it follow from more primitive concepts?
2. Is it possible to extend the operational approach to quantum mechanics such that the notions of an underlying space-time or causal structure are not assumed?
3. What new phenomenology can follow from such an approach?

Find a general framework for probabilistic theories with no pre-existing causal structure.

L. Hardy arXiv:gr-qc/0509120,  
Probability Theories with Dynamic Causal Structure:  
A New Framework for Quantum Gravity

# Outline

# Outline

- Operational Approach

# Outline

- Operational Approach
- Definite causal structures  $\rightarrow$  causally ordered (spatial and temporal) correlations: joint state, channel, channel with memory

# Outline

- Operational Approach
- Definite causal structures  $\rightarrow$  causally ordered (spatial and temporal) correlations: joint state, channel, channel with memory
- Framework for correlations without assuming definite causal structures

# Outline

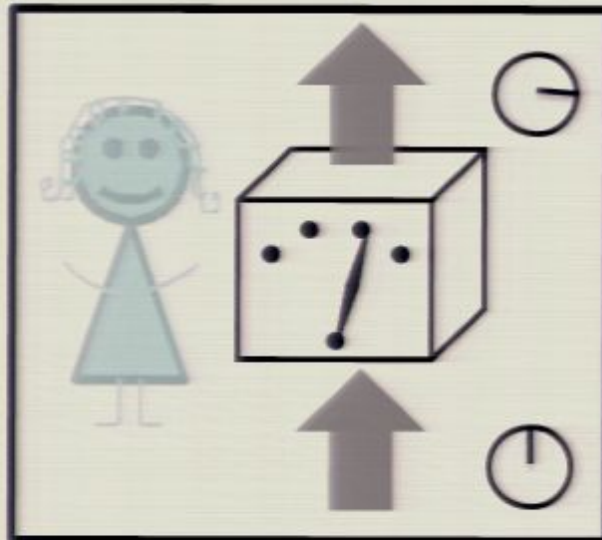
- Operational Approach
- Definite causal structures  $\rightarrow$  causally ordered (spatial and temporal) correlations: joint state, channel, channel with memory
- Framework for correlations without assuming definite causal structures
- Causal game  $\rightarrow$  winning strategy with “non-causal” correlations

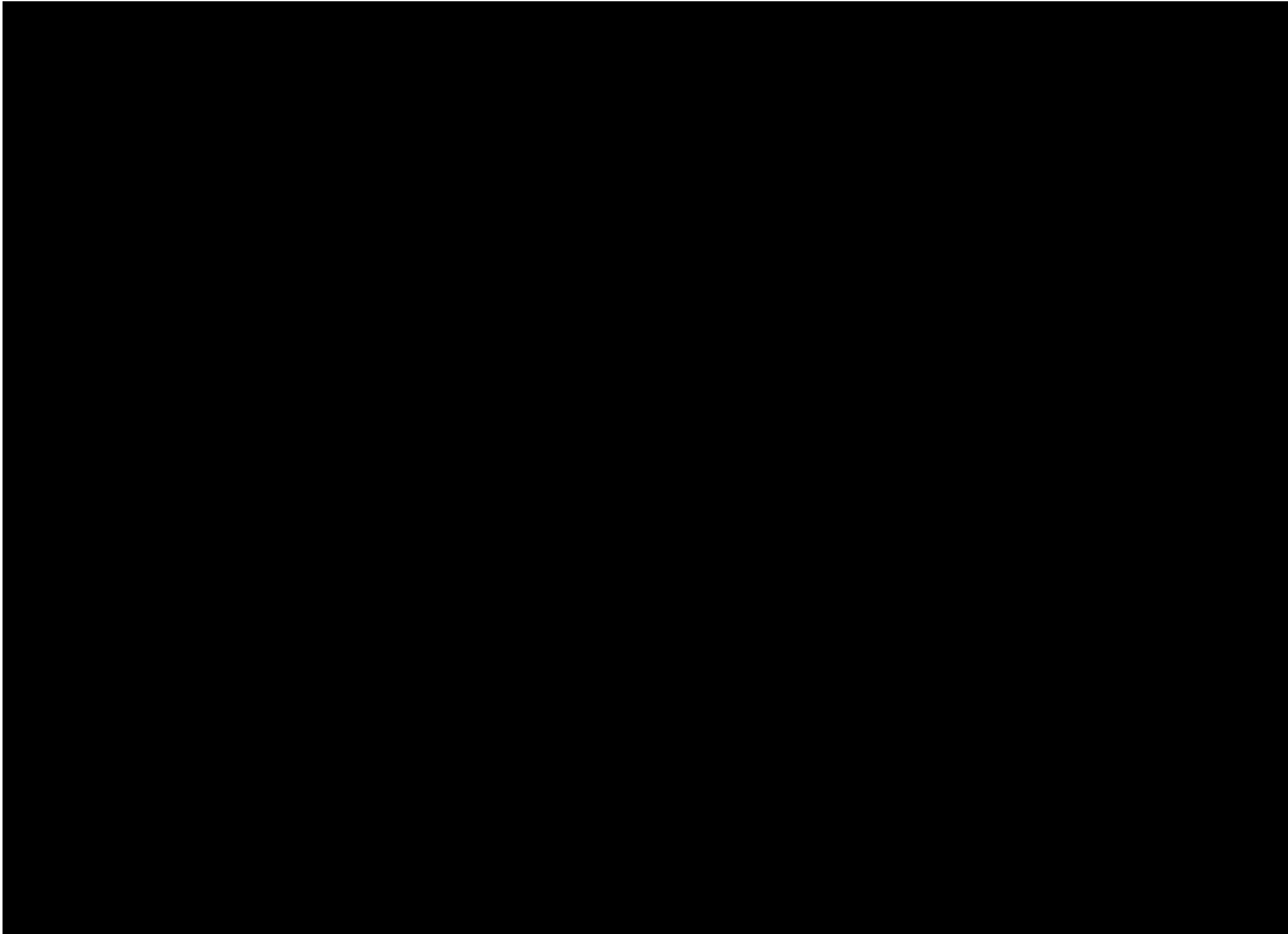
# Outline

- Operational Approach
- Definite causal structures  $\rightarrow$  causally ordered (spatial and temporal) correlations: joint state, channel, channel with memory
- Framework for correlations without assuming definite causal structures
- Causal game  $\rightarrow$  winning strategy with “non-causal” correlations
- Conclusions

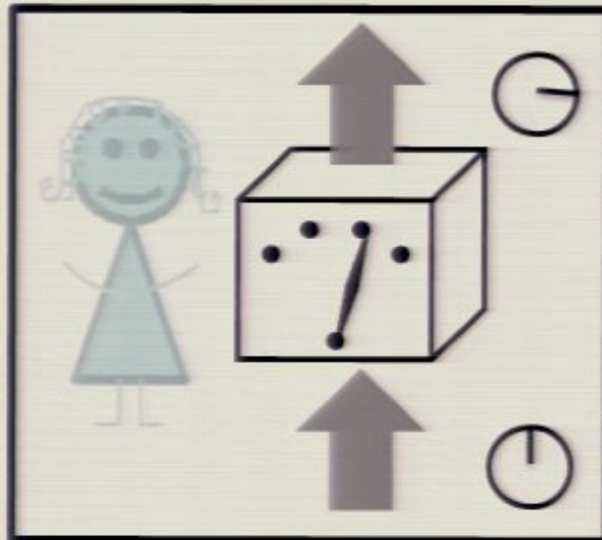


# Operational approach

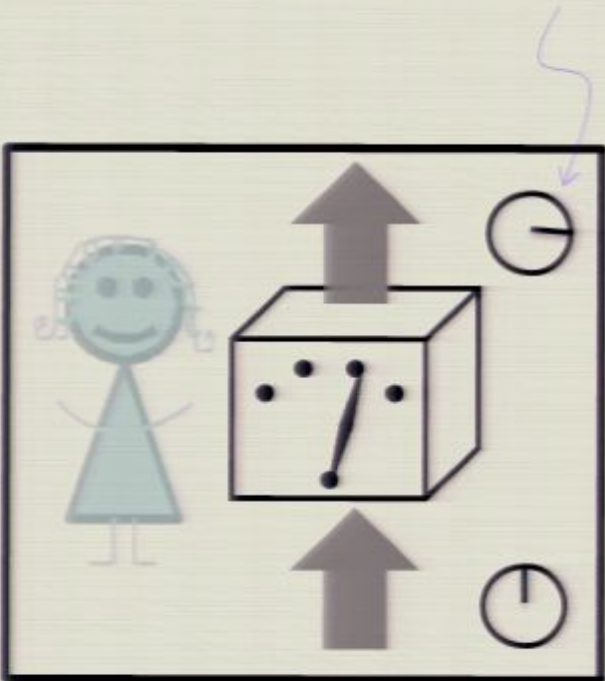




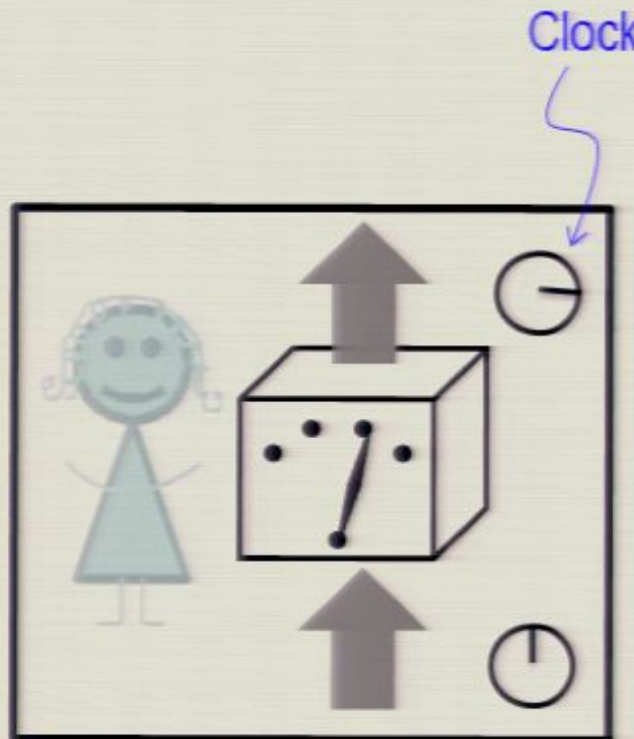
# Operational approach



# Operational approach



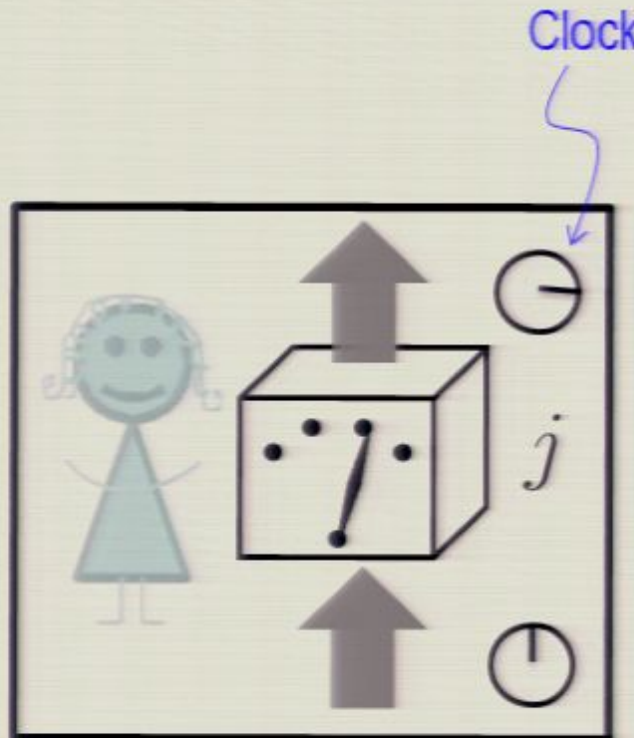
# Operational approach



Input

A system enters the lab.

# Operational approach

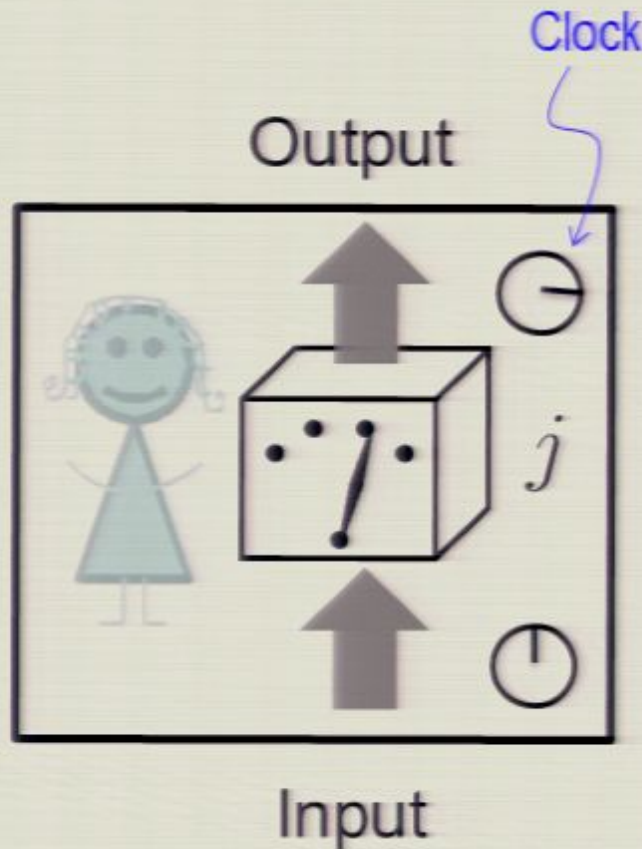


Input

One out of a set of possible transformations is performed.

A system enters the lab.

# Operational approach

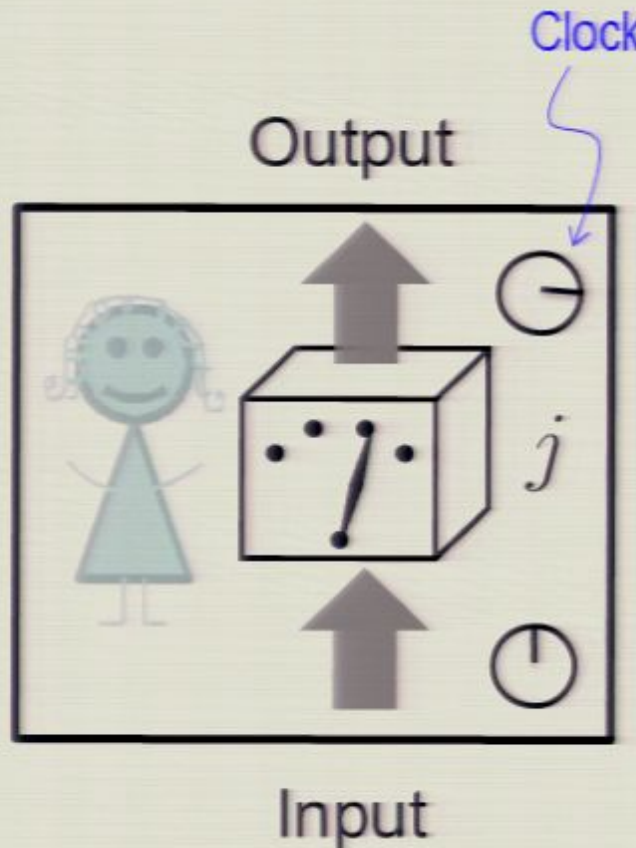


The system exits the lab.

One out of a set of possible transformations is performed.

A system enters the lab.

# Operational approach



The system exits the lab.

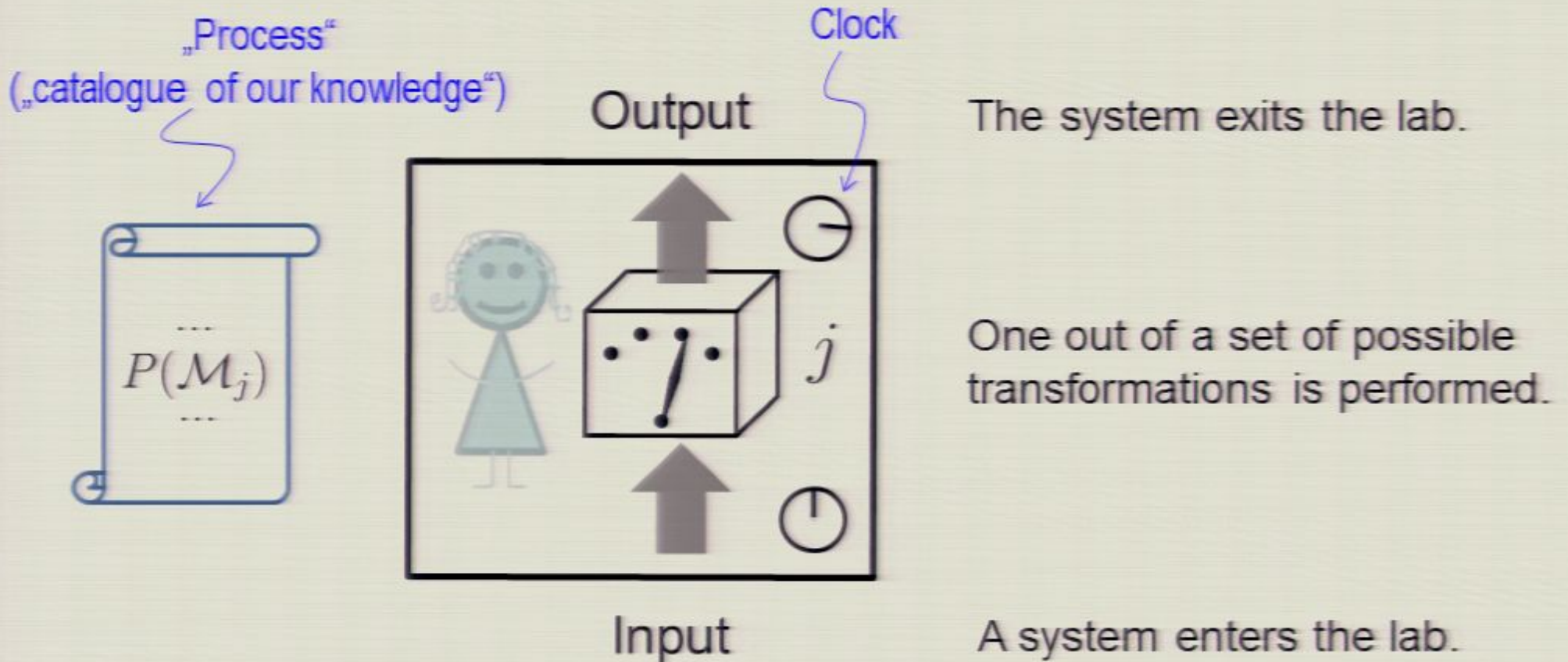
One out of a set of possible transformations is performed.

A system enters the lab.

This is the **only** way how the labs interact with the “outside world”

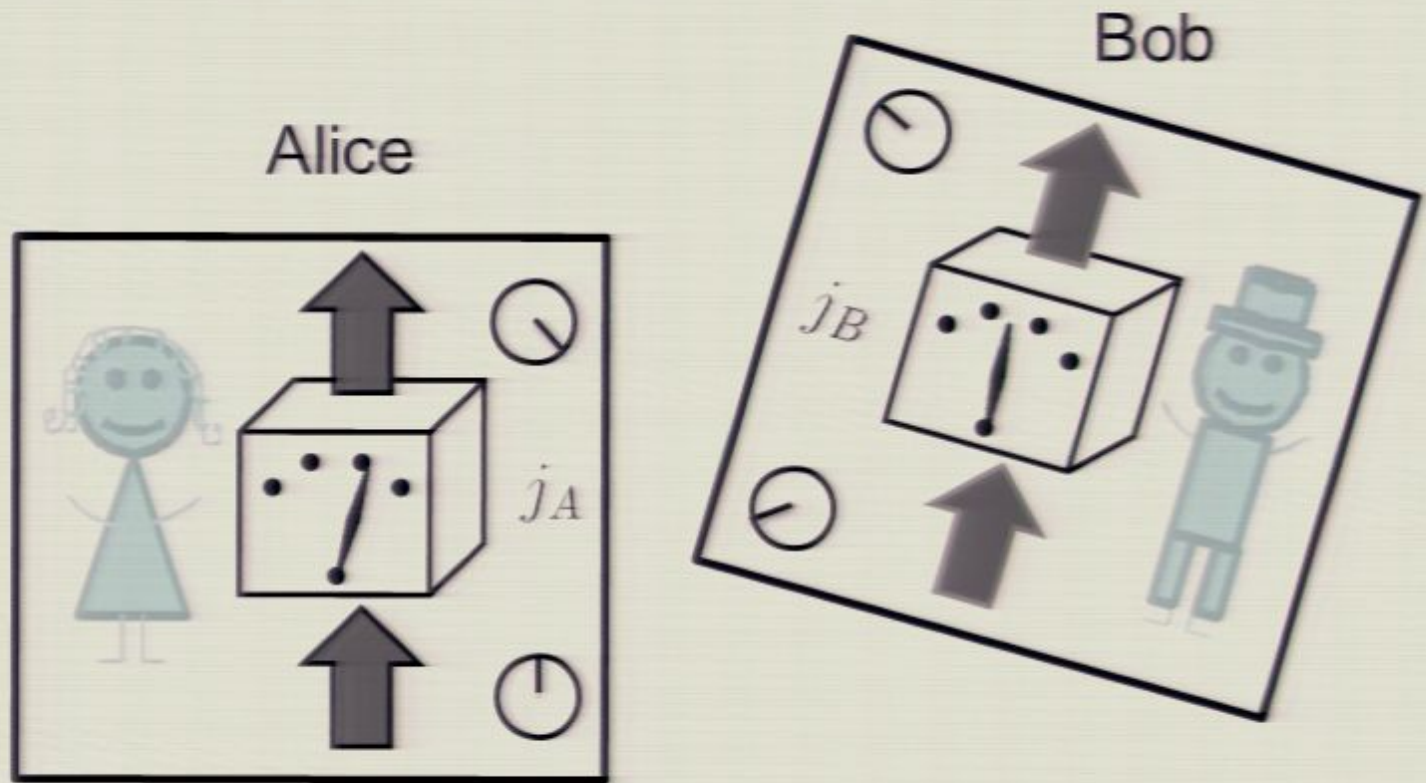


# Operational approach

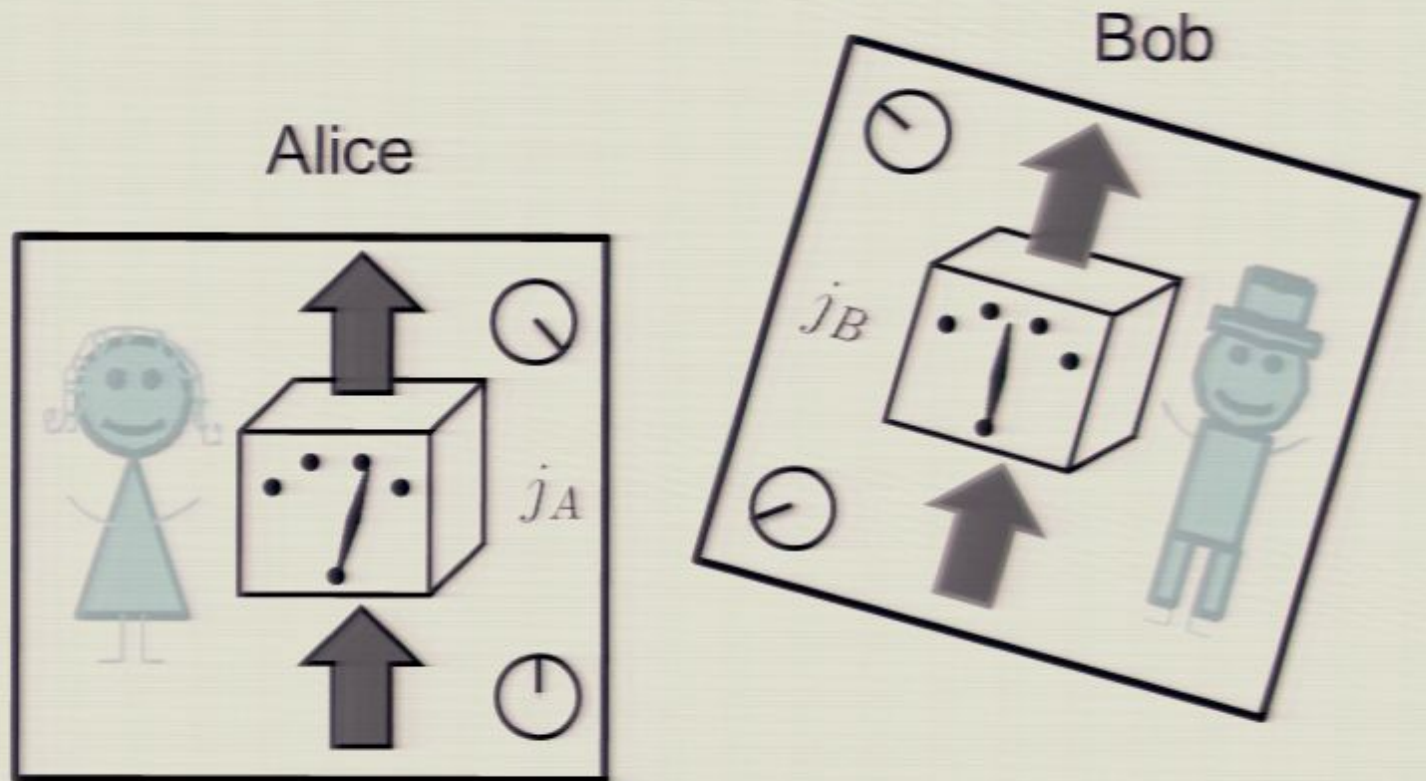


This is the **only** way how the labs interact with the “outside world”

# Operational approach

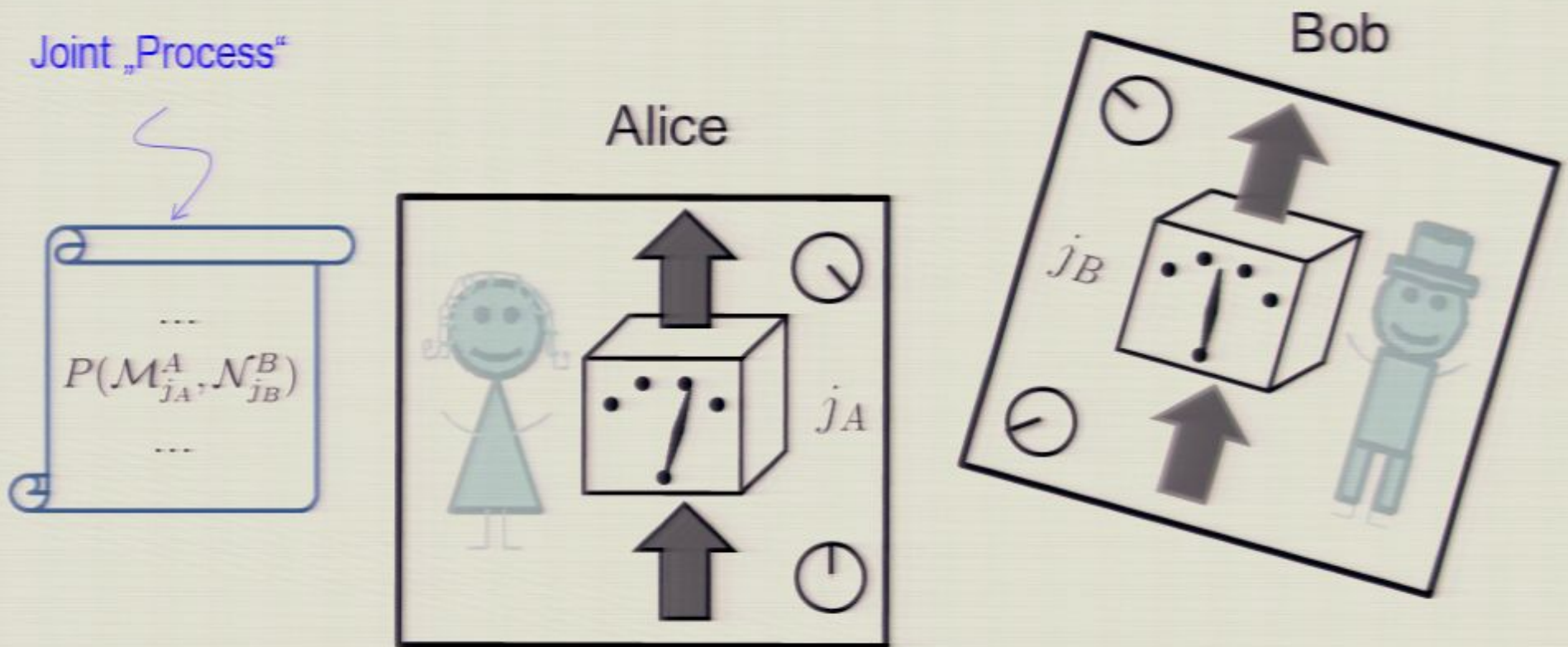


# Operational approach



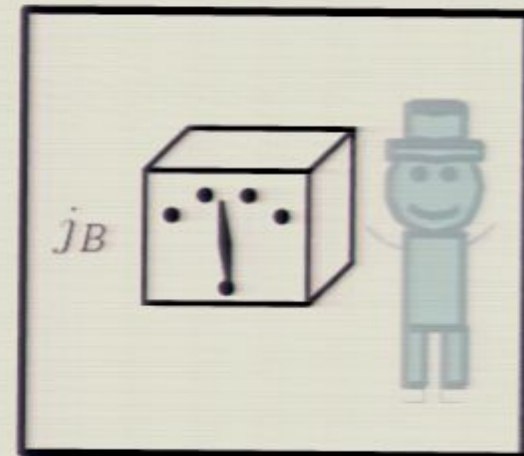
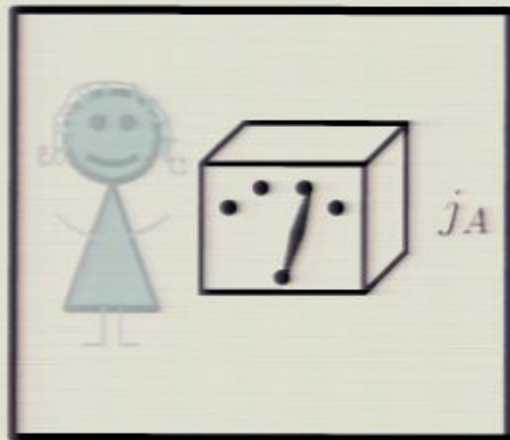
No prior assumption of pre-existing causal structure, in particular of the pre-existing background time.

# Operational approach

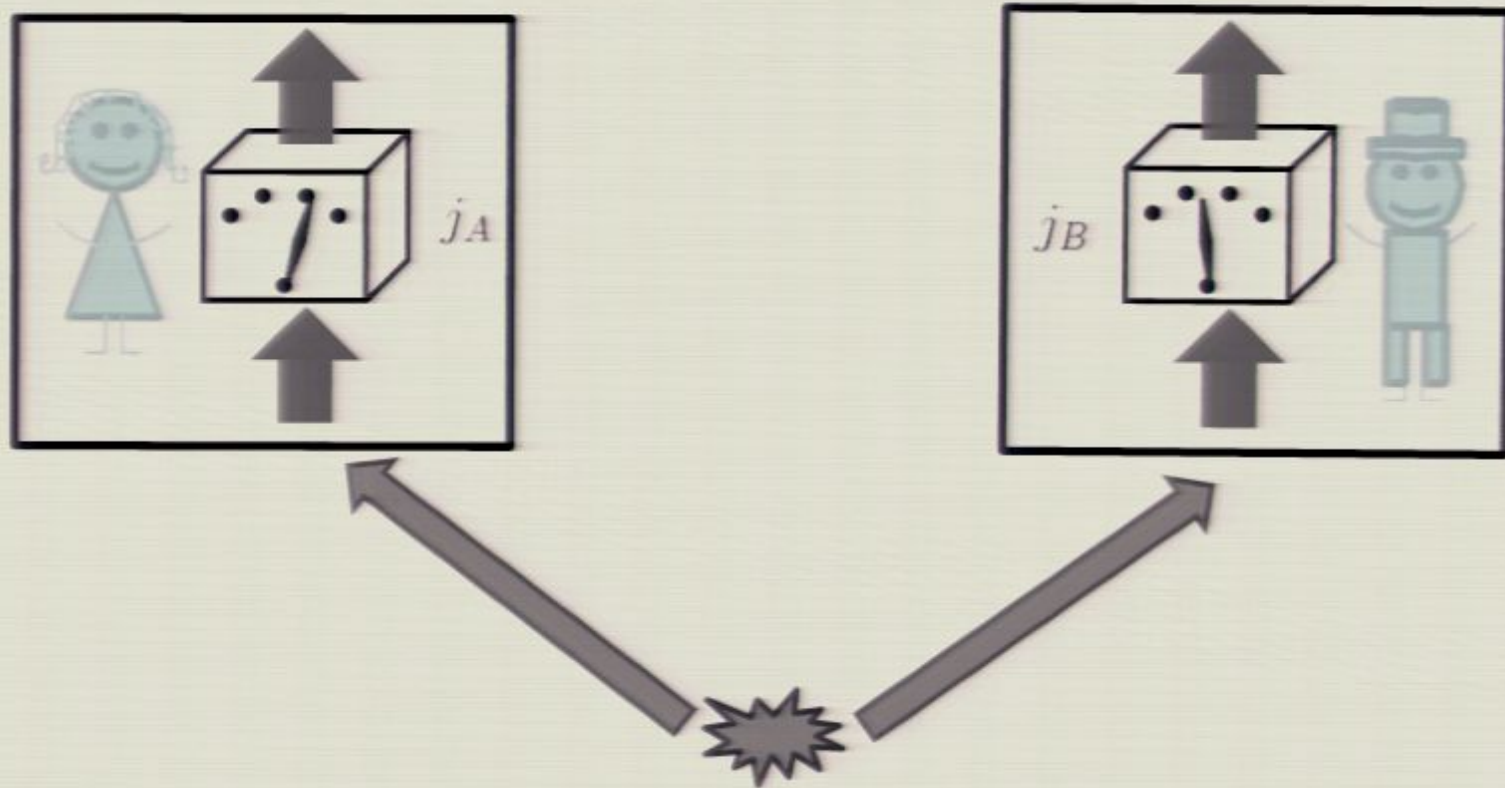


No prior assumption of pre-existing causal structure, in particular of the pre-existing background time.

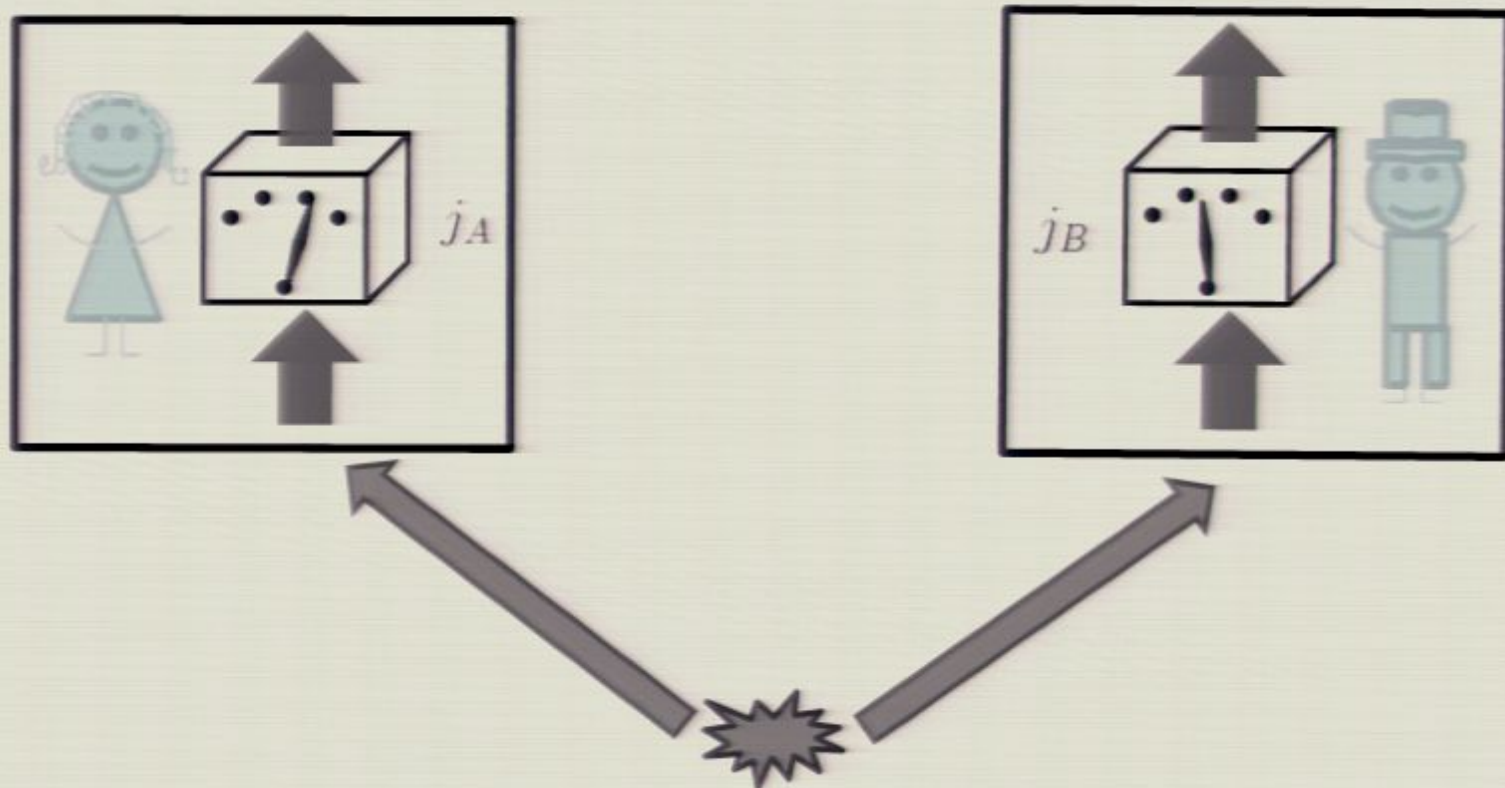
# Bipartite state



# Bipartite state

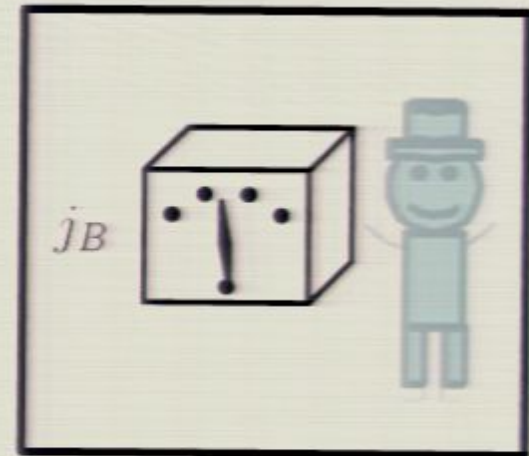
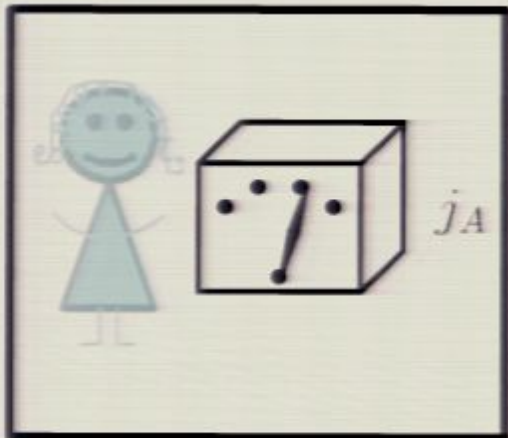


# Bipartite state



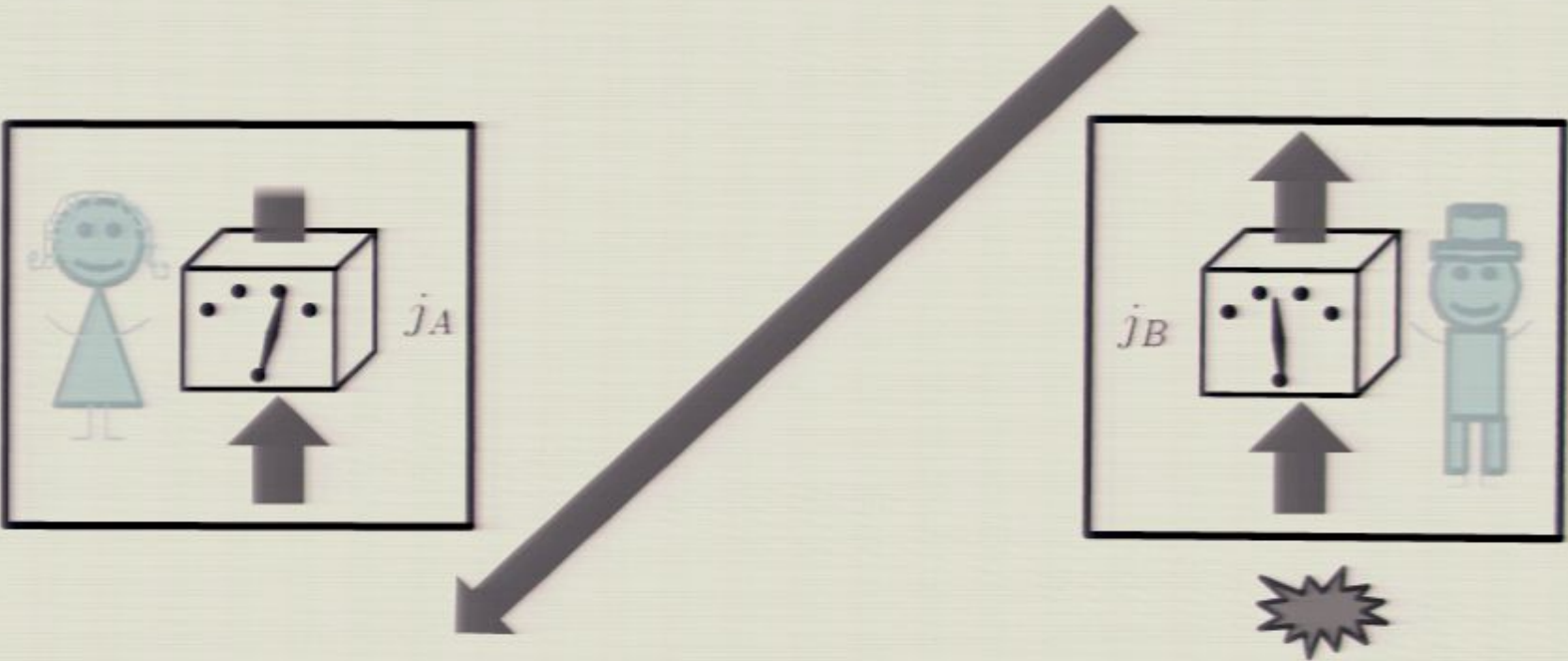
Sharing a joint state; No signalling

# Channel $B \rightarrow A$

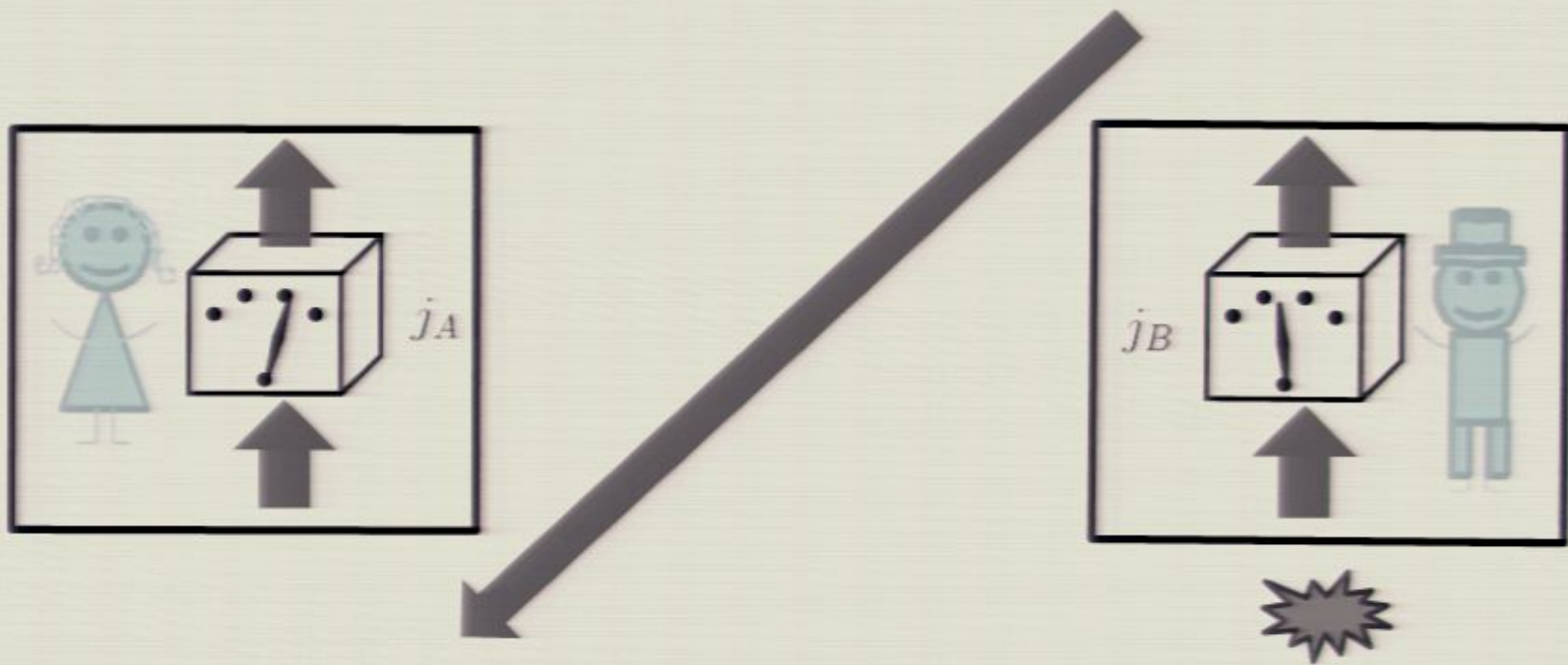




# Channel B→A

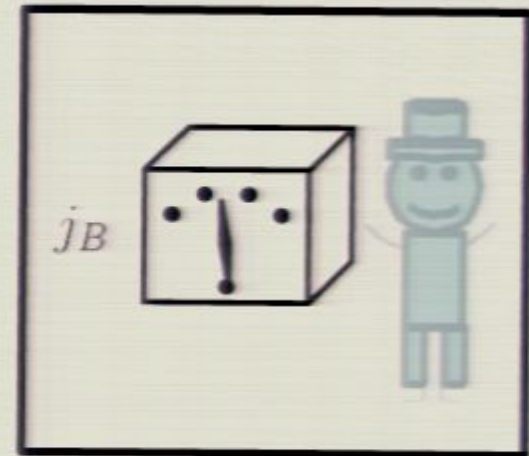
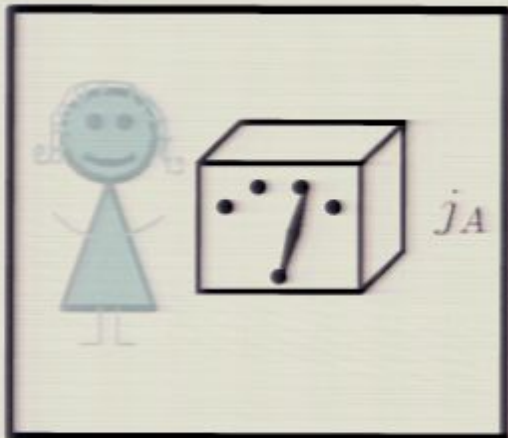


# Channel $B \rightarrow A$

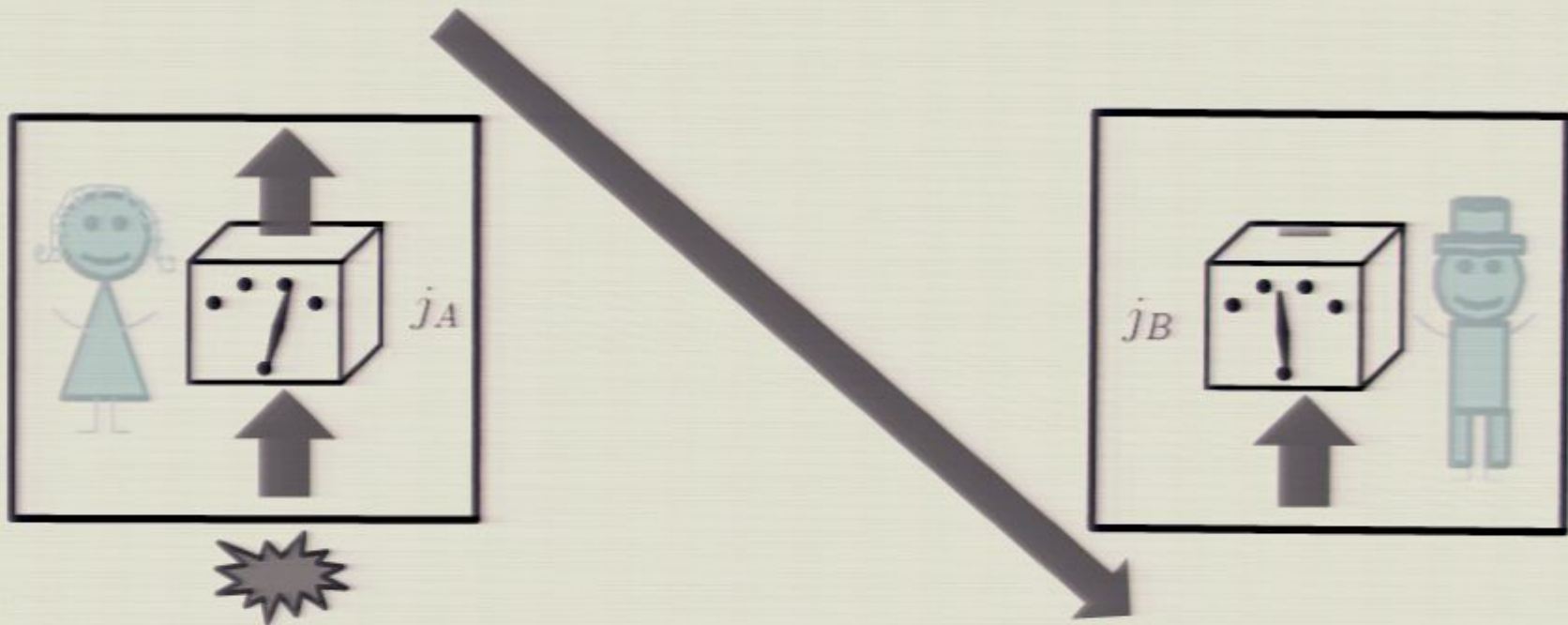


Sending a state from B to A; Possibility of signalling

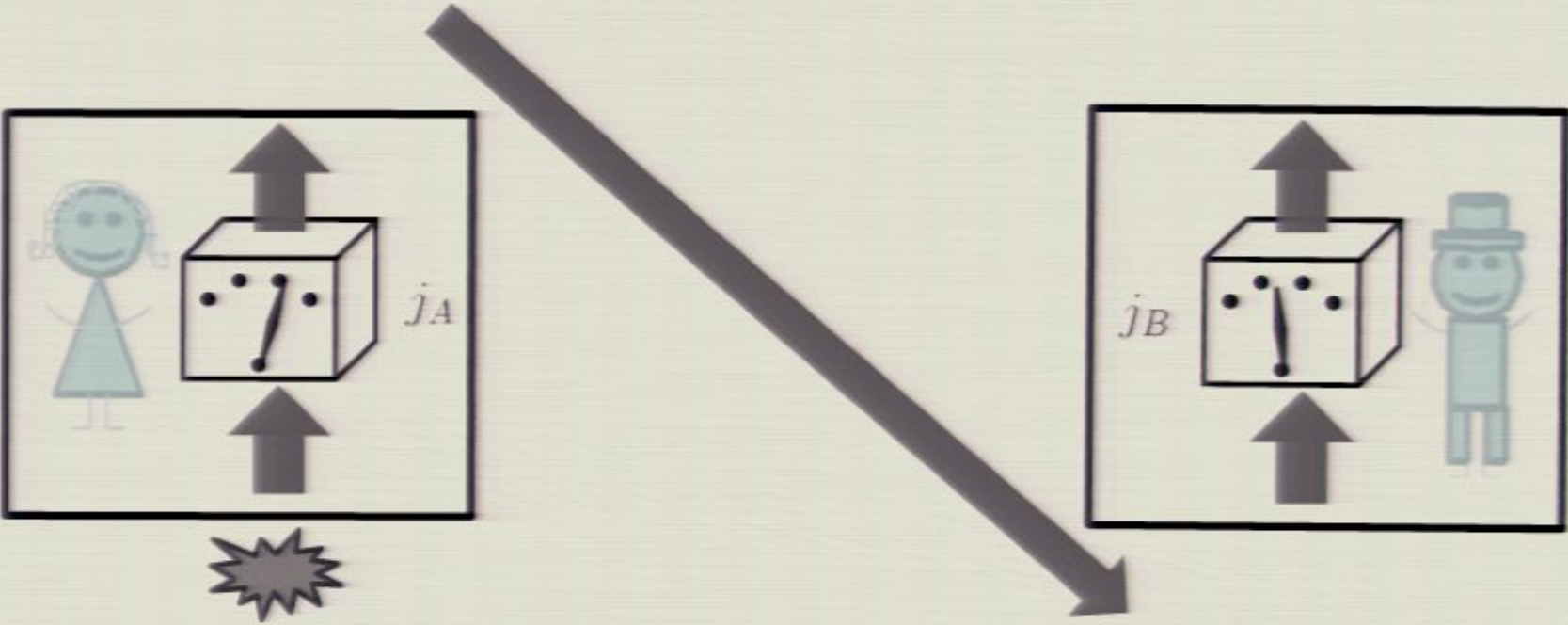
# Channel $A \rightarrow B$



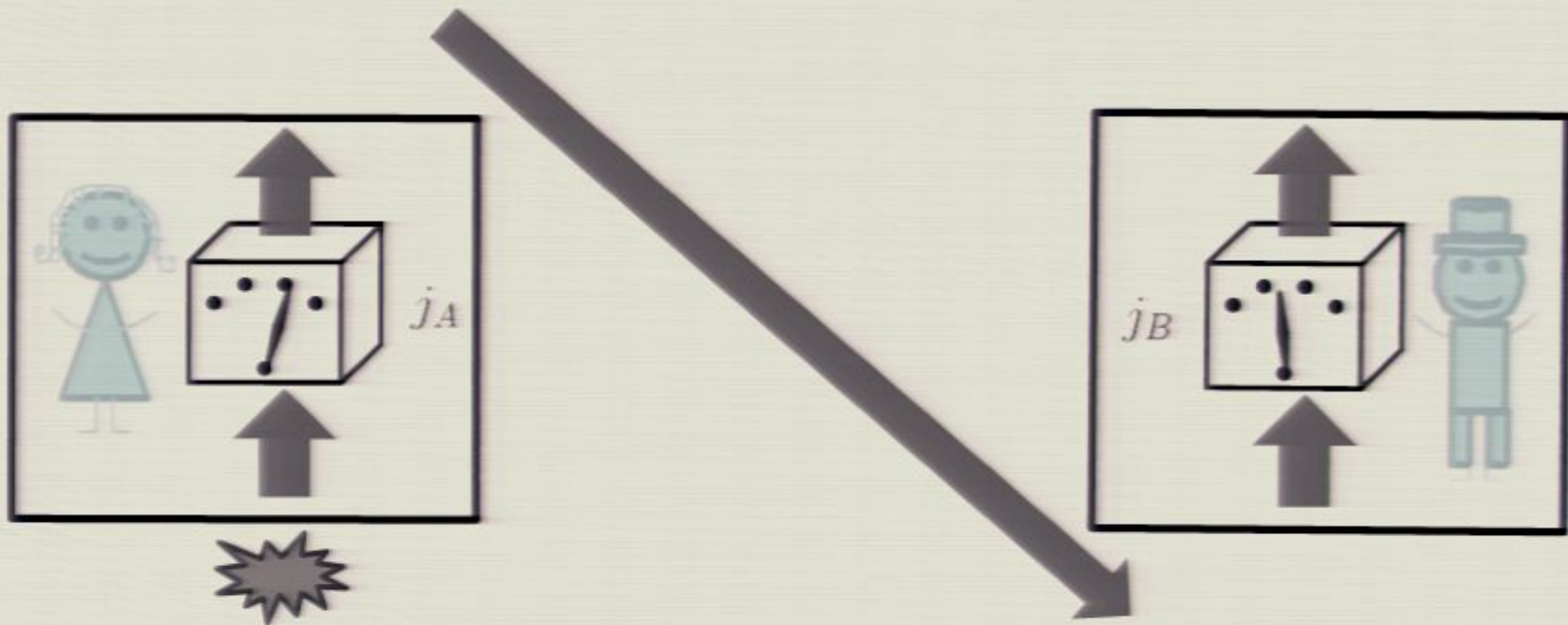
# Channel A → B



# Channel A $\rightarrow$ B

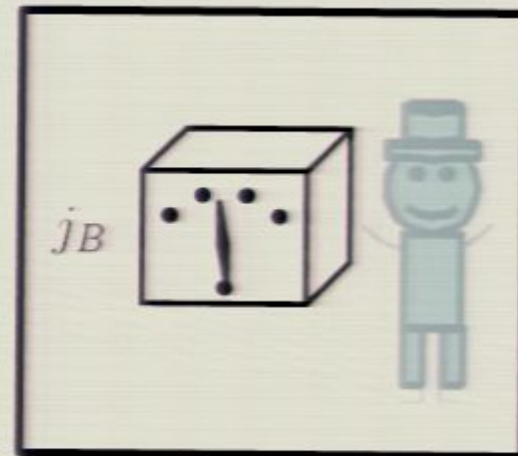
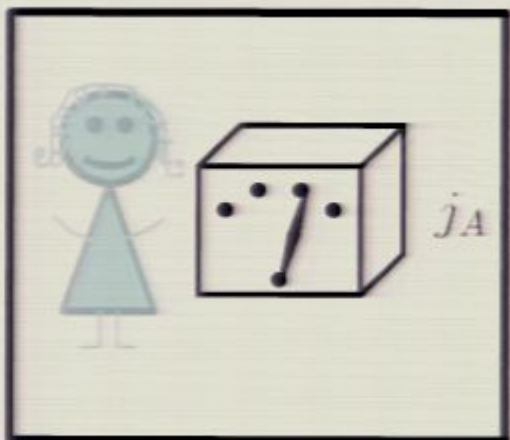


# Channel $A \rightarrow B$

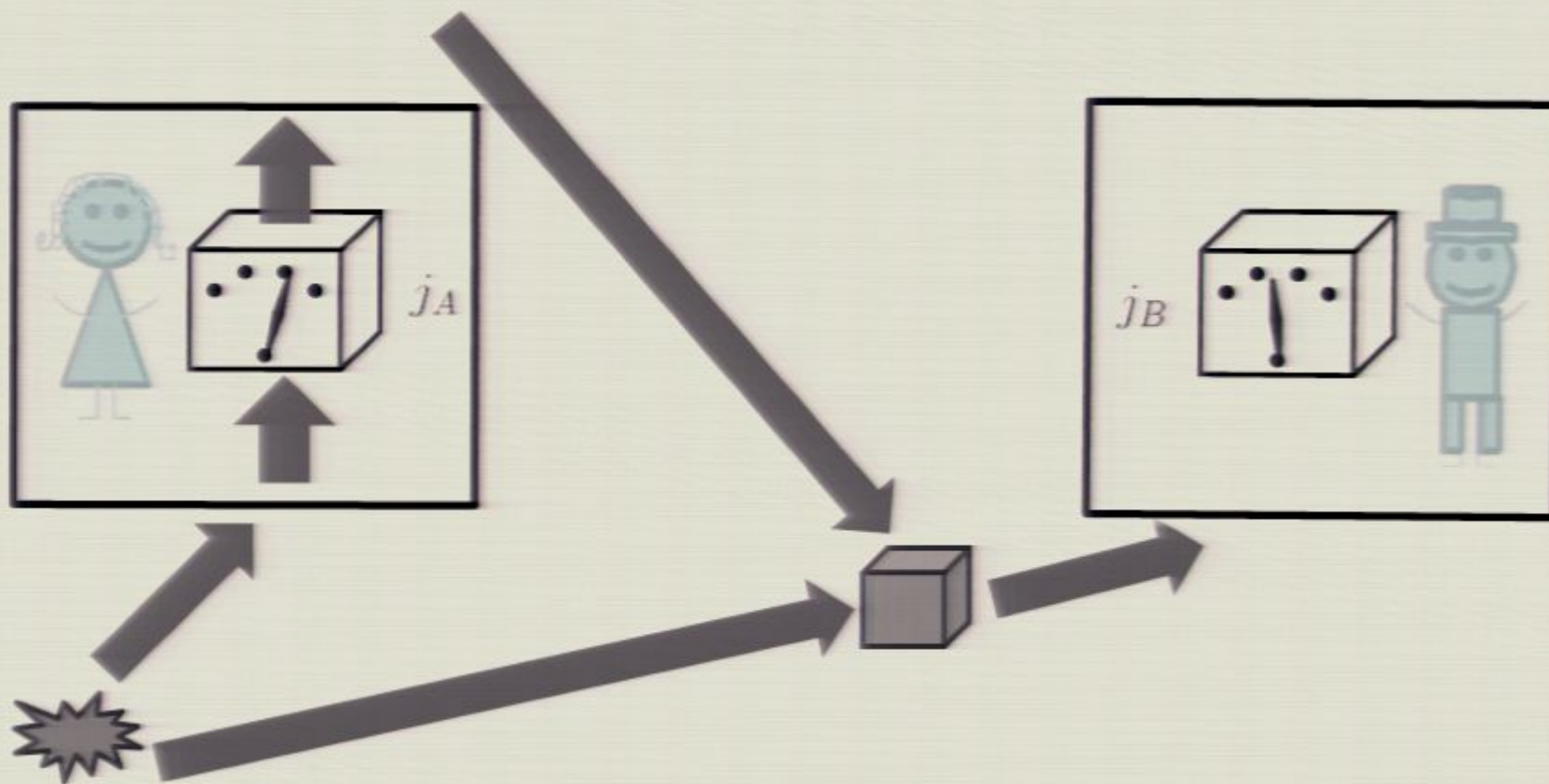


Sending a state from A to B; Possibility of signalling

# Channel with memory

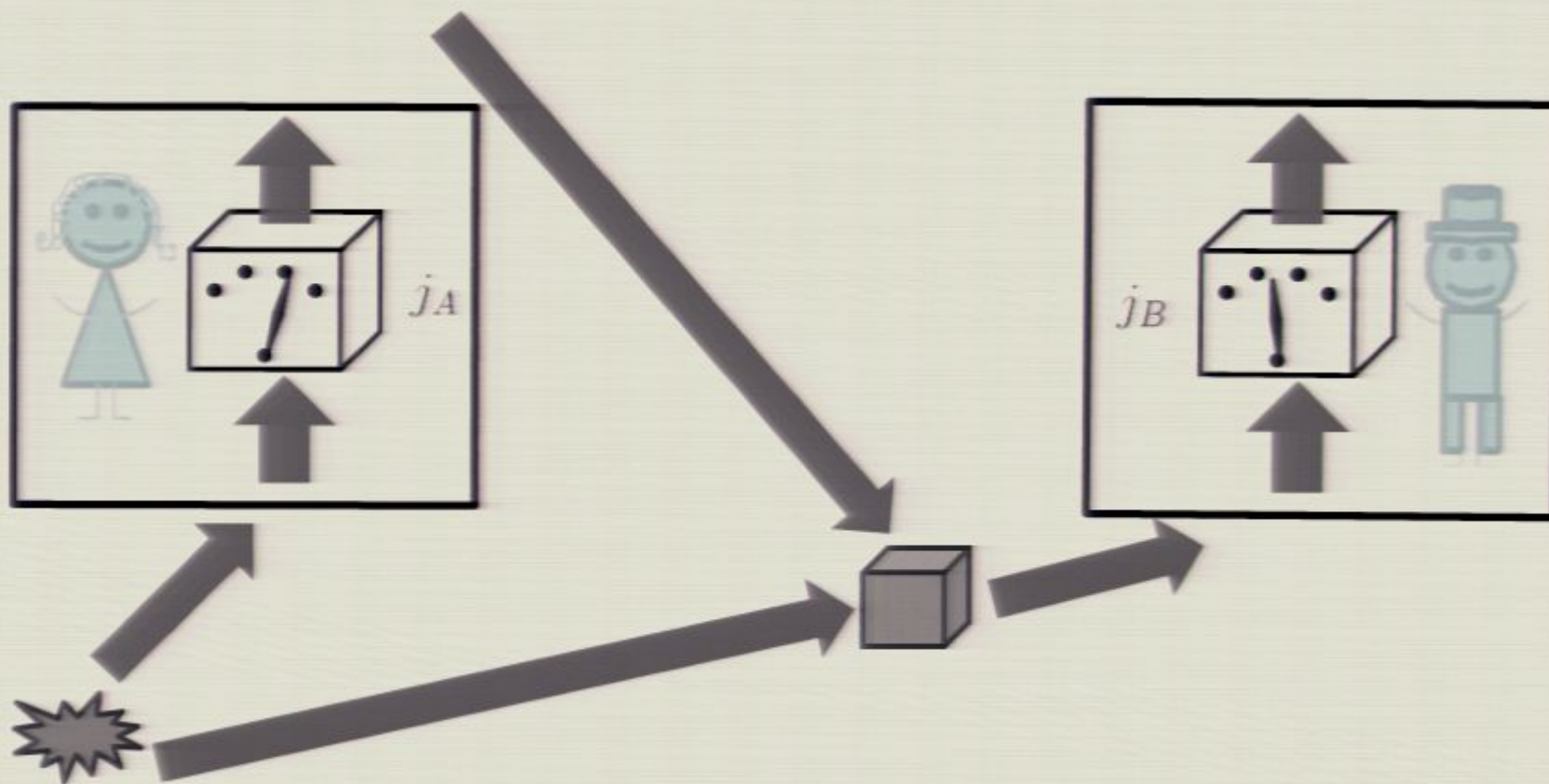


# Channel with memory

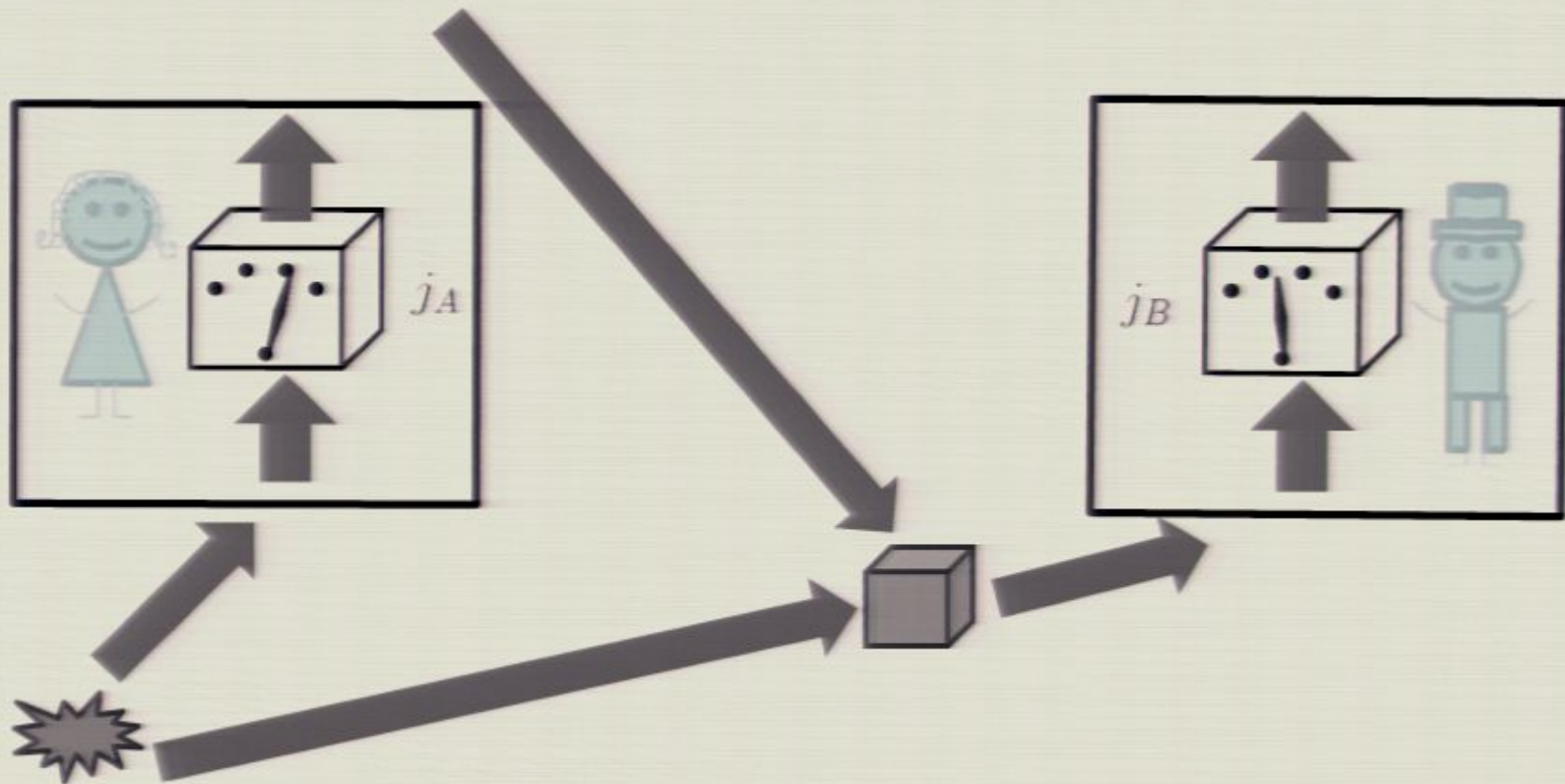




# Channel with memory

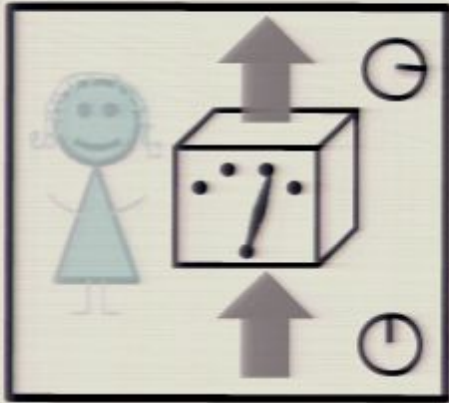


# Channel with memory



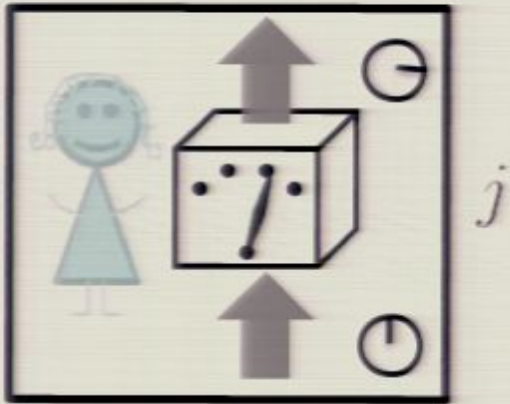
Most general causally ordered situation; Signaling possible  
Mixtures of different orders also possible

# Main premise



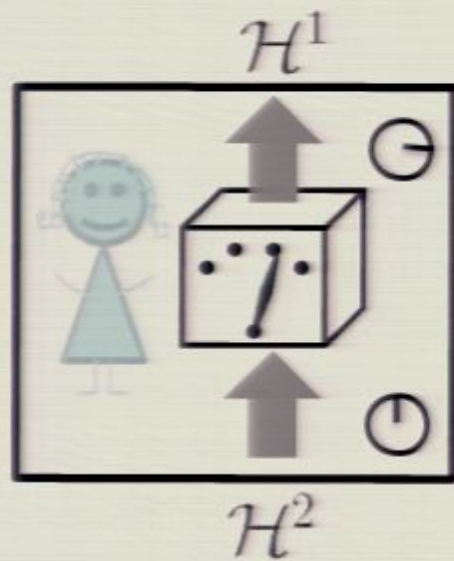
# Main premise

**Local descriptions agree with quantum mechanics**



# Main premise

## Local descriptions agree with quantum mechanics



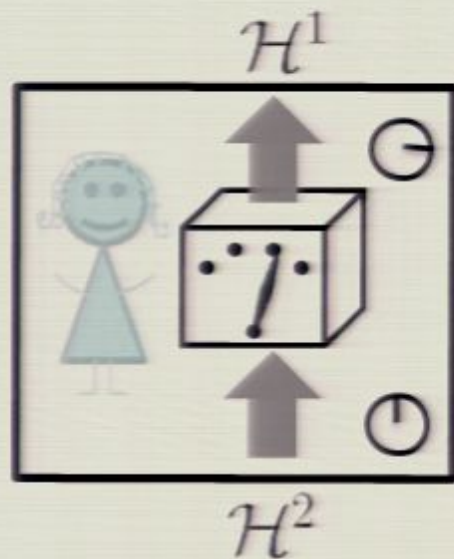
$j \rightarrow$

Transformations = **completely positive** (CP)  
trace non increasing maps

$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

# Main premise

## Local descriptions agree with quantum mechanics



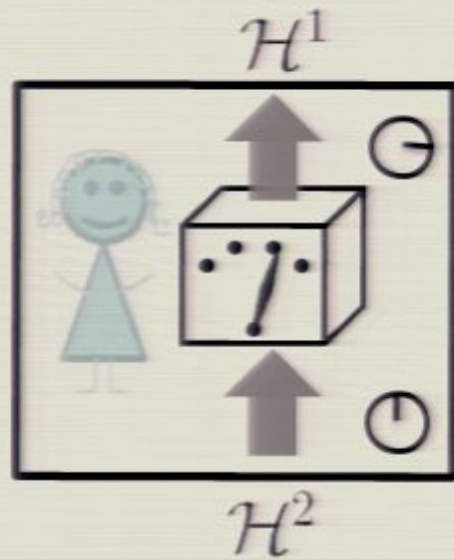
Transformations = **completely positive** (CP)  
trace non increasing maps

$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Local algebra in both labs

# Main premise

## Local descriptions agree with quantum mechanics



Transformations = **completely positive** (CP)  
trace non increasing maps

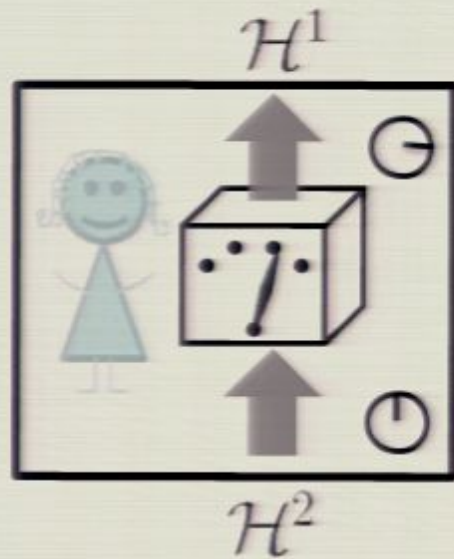
$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Local algebra in both labs

Convex Mixtures

# Main premise

## Local descriptions agree with quantum mechanics



Transformations = **completely positive** (CP)  
trace non increasing maps

$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

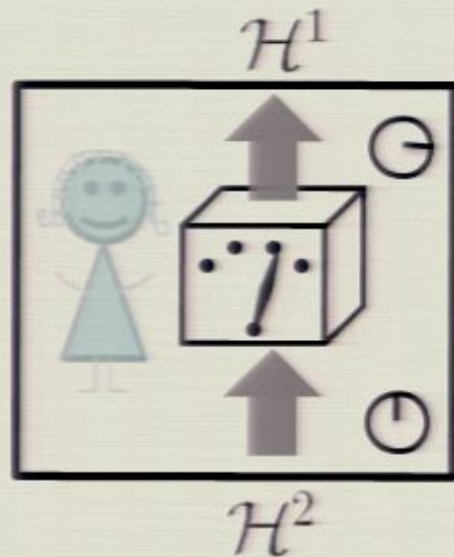
Local algebra in both labs

Convex Mixtures  $P(q\mathcal{M} + (1 - q)\mathcal{N}) = qP(\mathcal{M}) + (1 - q)P(\mathcal{N})$



# Main premise

## Local descriptions agree with quantum mechanics



$j \rightarrow$

Transformations = **completely positive (CP)**  
trace non increasing maps

$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

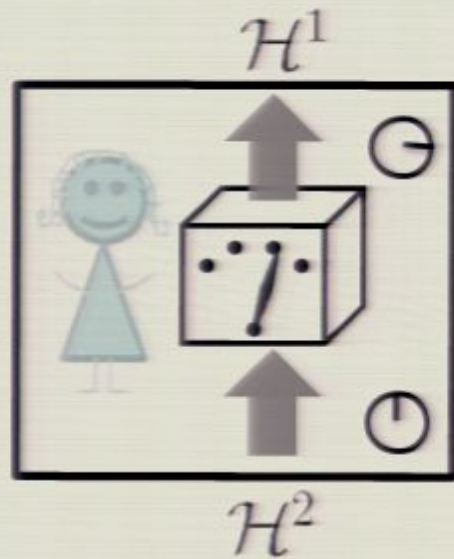
## Local algebra in both labs

Convex Mixtures  $P(q\mathcal{M} + (1 - q)\mathcal{N}) = qP(\mathcal{M}) + (1 - q)P(\mathcal{N})$

Distributivity  $P(\mathcal{M} + \mathcal{N}) = P(\mathcal{M}) + P(\mathcal{N})$

# Main premise

## Local descriptions agree with quantum mechanics



$j \rightarrow$

Transformations = **completely positive (CP)**  
trace non increasing maps

$$\mathcal{M}_j: \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

## Local algebra in both labs

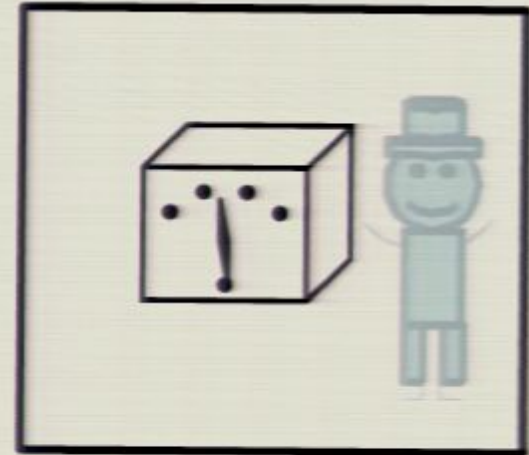
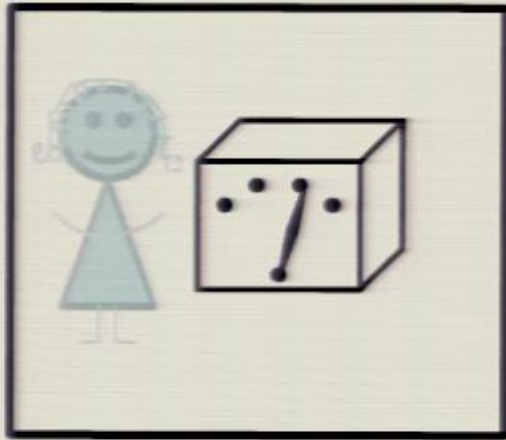
Convex Mixtures  $P(q\mathcal{M} + (1 - q)\mathcal{N}) = qP(\mathcal{M}) + (1 - q)P(\mathcal{N})$

Distributivity  $P(\mathcal{M} + \mathcal{N}) = P(\mathcal{M}) + P(\mathcal{N})$

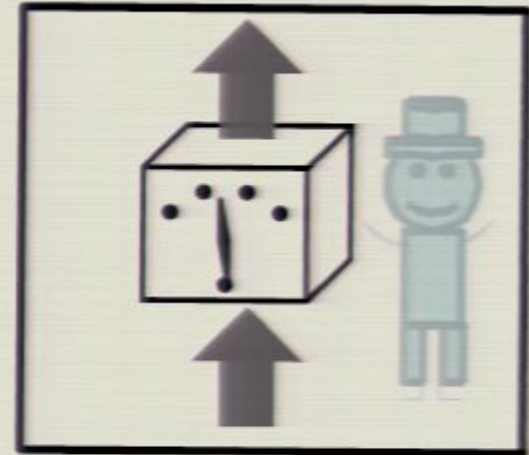
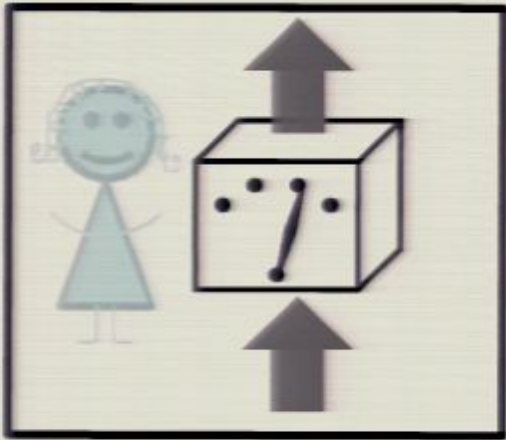


Probabilities are **linear** functions of CP maps

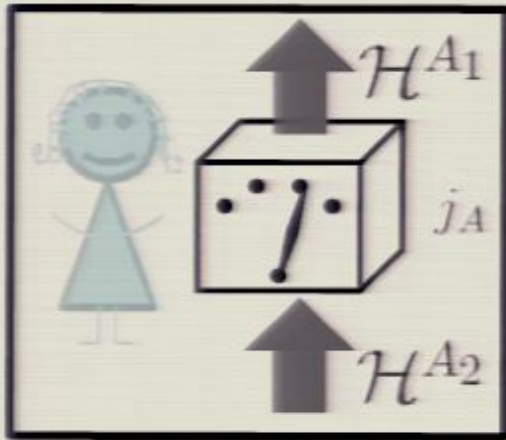
# Two parties



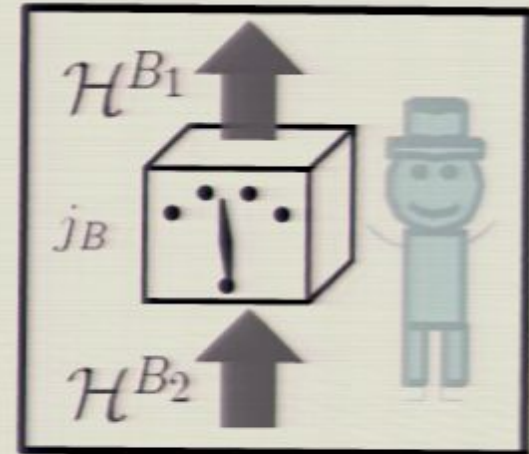
# Two parties



# Two parties

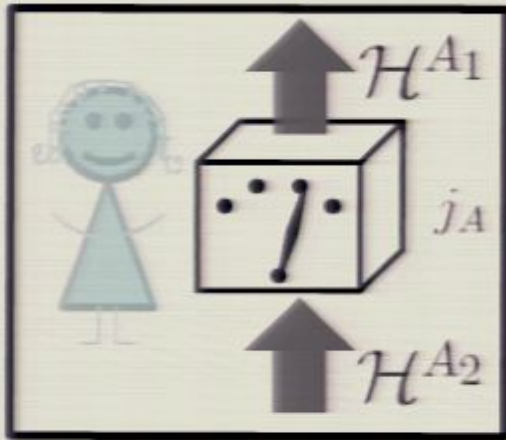


$$\mathcal{M}_{j_A}^A : \mathcal{L}(\mathcal{H}^{A_2}) \rightarrow \mathcal{L}(\mathcal{H}^{A_1})$$

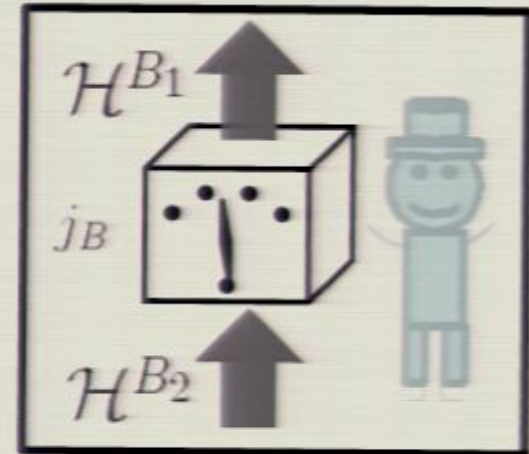


$$\mathcal{M}_{j_B}^B : \mathcal{L}(\mathcal{H}^{B_2}) \rightarrow \mathcal{L}(\mathcal{H}^{B_1})$$

# Two parties



$$\mathcal{M}_{j_A}^A : \mathcal{L}(\mathcal{H}^{A_2}) \rightarrow \mathcal{L}(\mathcal{H}^{A_1})$$

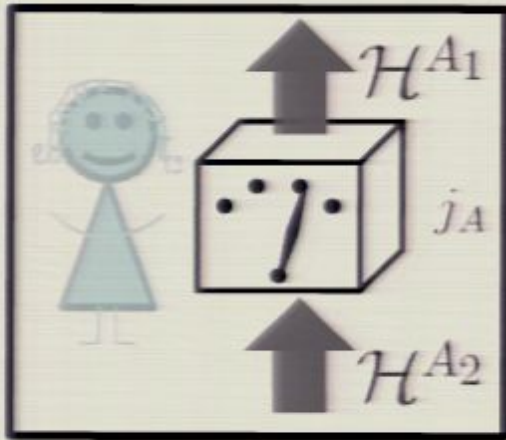


$$\mathcal{M}_{j_B}^B : \mathcal{L}(\mathcal{H}^{B_2}) \rightarrow \mathcal{L}(\mathcal{H}^{B_1})$$

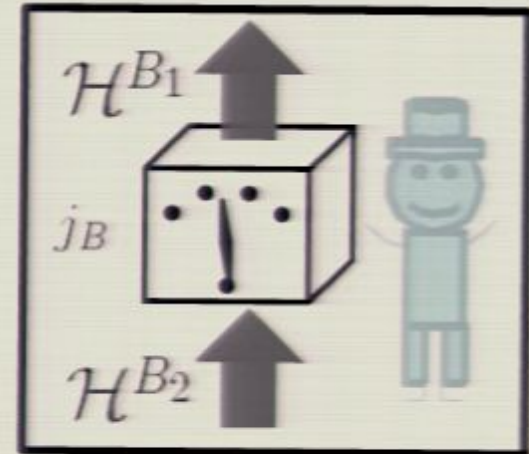
Probabilities are **bilinear** functions of the CP maps

$$P(\mathcal{M}^A, \mathcal{M}^B) = \omega(\mathcal{M}^A, \mathcal{M}^B)$$

# Two parties



$$\mathcal{M}_{j_A}^A : \mathcal{L}(\mathcal{H}^{A_2}) \rightarrow \mathcal{L}(\mathcal{H}^{A_1})$$



$$\mathcal{M}_{j_B}^B : \mathcal{L}(\mathcal{H}^{B_2}) \rightarrow \mathcal{L}(\mathcal{H}^{B_1})$$

Probabilities are **bilinear** functions of the CP maps

$$P(\mathcal{M}^A, \mathcal{M}^B) = \omega(\mathcal{M}^A, \mathcal{M}^B)$$

**Question:** how to characterize the most general probability distributions?

# Choi-Jamiołkowski isomorphism



# Choi-Jamiołkowski isomorphism

CP maps

$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$



Bipartite positive operators

$$\rho_M^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$

# Choi-Jamiołkowski isomorphism

CP maps

$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Bipartite positive operators

$$\rho_{\mathcal{M}}^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$



Maximally entangled state

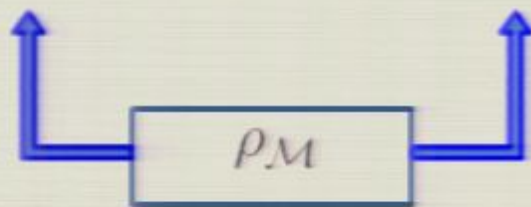
# Choi-Jamiołkowski isomorphism

CP maps

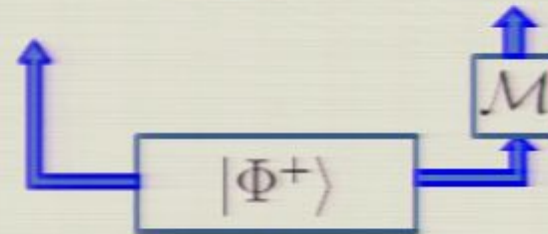
$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Bipartite positive operators

$$\rho_{\mathcal{M}}^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$



=



Maximally entangled state

$$\rho_{\mathcal{M}}^{12} = \mathcal{M} \otimes \mathcal{I}(|\Phi^+\rangle\langle\Phi^+|)$$

$$|\Phi^+\rangle = \sum_i |i\rangle|i\rangle$$

$$|i\rangle \in \mathcal{H}^1$$

# Choi-Jamiołkowski isomorphism

CP maps

$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Bipartite positive operators

$$\rho_{\mathcal{M}}^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$



$$\rho_{\mathcal{M}}^{12} = \mathcal{M} \otimes \mathcal{I}(|\Phi^+\rangle\langle\Phi^+|)$$

$$|\Phi^+\rangle = \sum_i |i\rangle|i\rangle$$

$$|i\rangle \in \mathcal{H}^1$$

Maximally entangled state

Examples

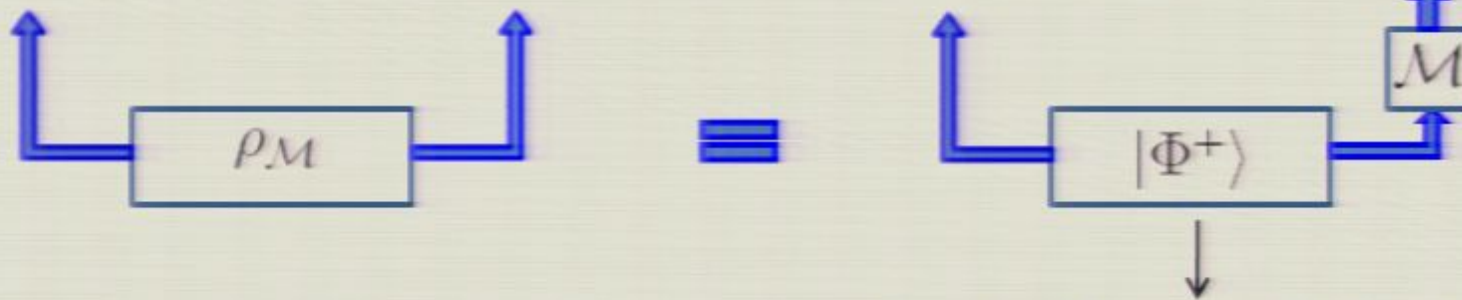
# Choi-Jamiołkowski isomorphism

CP maps

$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Bipartite positive operators

$$\rho_{\mathcal{M}}^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$



$$\rho_{\mathcal{M}}^{12} = \mathcal{M} \otimes \mathcal{I}(|\Phi^+\rangle\langle\Phi^+|)$$

$$|\Phi^+\rangle = \sum_i |i\rangle|i\rangle$$

$$|i\rangle \in \mathcal{H}^1$$

Maximally entangled state

## Examples

Projection on a pure state  $|\psi\rangle$   
and its reparation

$$\rho^{12} = |\psi\rangle\langle\psi|^1 \otimes |\psi\rangle\langle\psi|^2$$

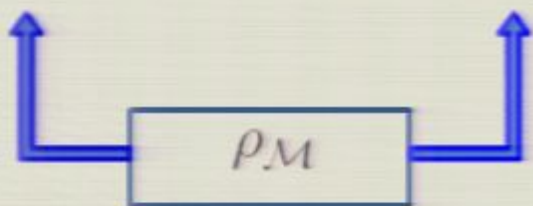
# Choi-Jamiołkowski isomorphism

CP maps

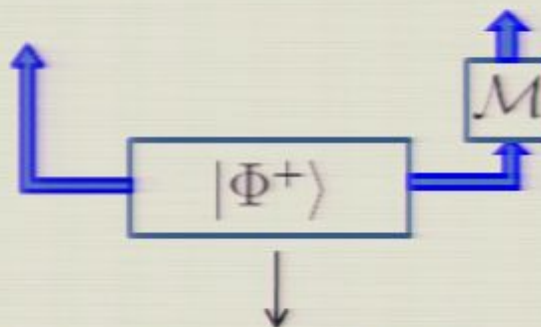
$$\mathcal{M} : \mathcal{L}(\mathcal{H}^2) \rightarrow \mathcal{L}(\mathcal{H}^1)$$

Bipartite positive operators

$$\rho_{\mathcal{M}}^{12} \in \mathcal{L}(\mathcal{H}^1) \otimes \mathcal{L}(\mathcal{H}^2)$$



=



$$\rho_{\mathcal{M}}^{12} = \mathcal{M} \otimes \mathcal{I}(|\Phi^+\rangle\langle\Phi^+|)$$

$$|\Phi^+\rangle = \sum_i |i\rangle|i\rangle$$

$$|i\rangle \in \mathcal{H}^1$$

Maximally entangled state

## Examples

Projection on a pure state  $|\psi\rangle$   
and its reparation

$$\rho^{12} = |\psi\rangle\langle\psi|^1 \otimes |\psi\rangle\langle\psi|^2$$

Preparation of a new state  $\sigma$

$$\rho^{12} = \sigma^1 \otimes \mathbb{1}^2$$

# Bipartite probabilities

# Bipartite probabilities

Bilinear functions of CP maps



Bilinear functions of  
positive operators

$$P(\mathcal{M}^A, \mathcal{M}^B) = \omega(\mathcal{M}^A, \mathcal{M}^B)$$

$$P(\mathcal{M}^A, \mathcal{N}^B) = \omega(\rho_{\mathcal{M}_A}^{A_1 A_2}, \rho_{\mathcal{M}_B}^{B_1, B_2})$$



# Bipartite probabilities

Bilinear functions of CP maps



Bilinear functions of  
positive operators

$$P(\mathcal{M}^A, \mathcal{M}^B) = \omega(\mathcal{M}^A, \mathcal{M}^B)$$

$$P(\mathcal{M}^A, \mathcal{N}^B) = \omega(\rho_{\mathcal{M}^A}^{A_1 A_2}, \rho_{\mathcal{M}^B}^{B_1, B_2})$$

## Representation

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

# Bipartite probabilities

Bilinear functions of CP maps



Bilinear functions of positive operators

$$P(\mathcal{M}^A, \mathcal{M}^B) = \omega(\mathcal{M}^A, \mathcal{M}^B)$$

$$P(\mathcal{M}^A, \mathcal{N}^B) = \omega(\rho_{\mathcal{M}^A}^{A_1 A_2}, \rho_{\mathcal{M}^B}^{B_1, B_2})$$

## Representation

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$



„Process“ Matrix

# Bipartite probabilities

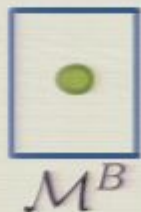
$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

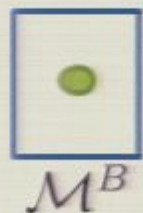
$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$



# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

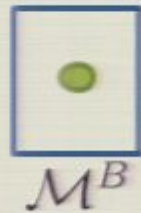


$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \quad \rightarrow \quad W^{A_1 A_2 B_1 B_2} \text{ POPT}$$

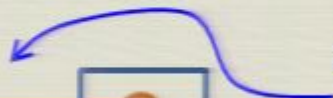
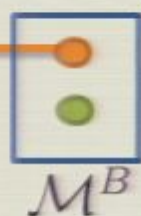
# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$



$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \quad \Rightarrow \quad W^{A_1 A_2 B_1 B_2} \text{ POPT}$$



ancillary entangled state do not fix the causal order

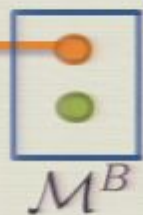
# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$



$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \quad \Rightarrow \quad W^{A_1 A_2 B_1 B_2} \text{ POPT}$$



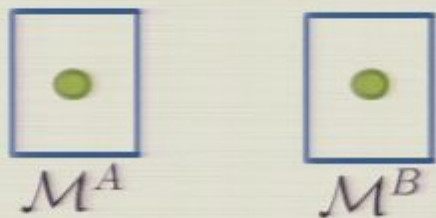
ancillary entangled state do not fix the causal order



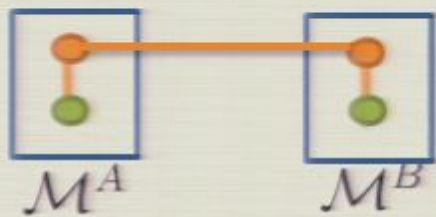
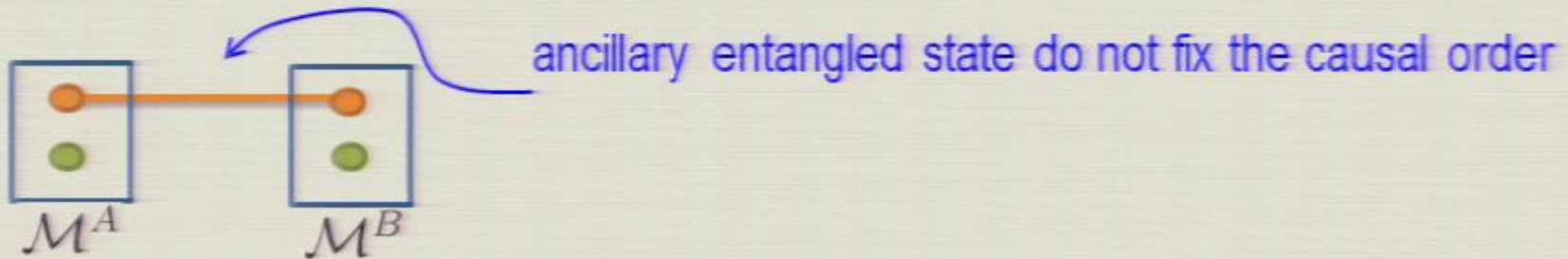
# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$



$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \Rightarrow W^{A_1 A_2 B_1 B_2} \text{ POPT}$$

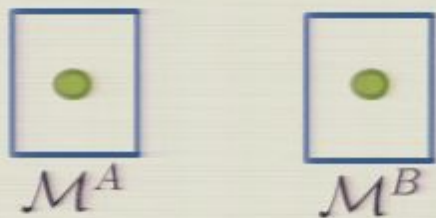




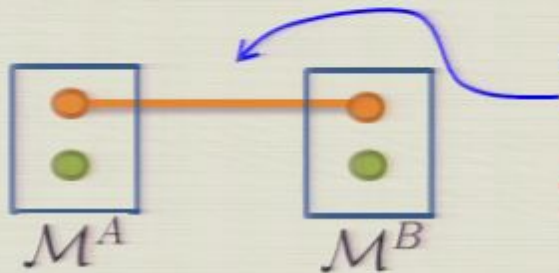
# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

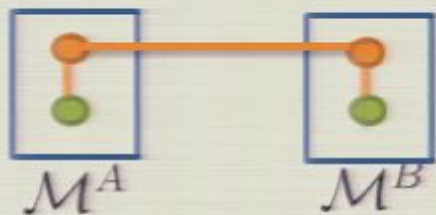


$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \Rightarrow W^{A_1 A_2 B_1 B_2} \text{ POPT}$$



ancillary entangled state do not fix the causal order

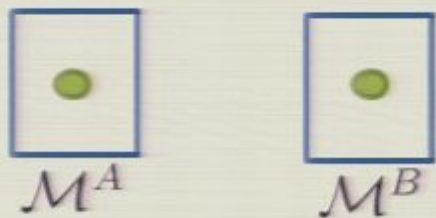
1. Probability positive:  $W^{A_1 A_2 B_1 B_2} \geq 0$



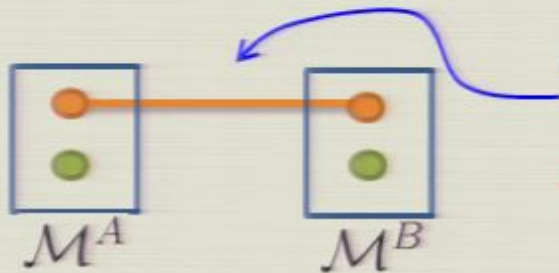
# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

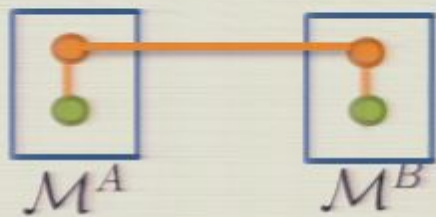


$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \quad \Rightarrow \quad W^{A_1 A_2 B_1 B_2} \text{ POPT}$$



ancillary entangled state do not fix the causal order

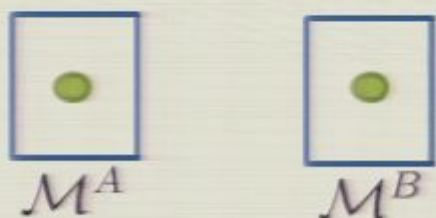
1. Probability positive:  $W^{A_1 A_2 B_1 B_2} \geq 0$



# Bipartite probabilities

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{M}^A}^{A_1 A_2} \otimes \rho_{\mathcal{M}^B}^{B_1 B_2} \right) \right]$$

$$W^{A_1 A_2 B_1 B_2} \in \mathcal{L}(\mathcal{H}^{A_1} \otimes \mathcal{H}^{A_2} \otimes \mathcal{H}^{B_1} \otimes \mathcal{H}^{B_2})$$

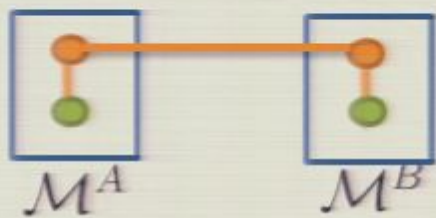


$$P(\mathcal{M}^A, \mathcal{N}^B) \geq 0 \quad \Rightarrow \quad W^{A_1 A_2 B_1 B_2} \text{ POPT}$$



ancillary entangled state do not fix the causal order

1. Probability positive:  $W^{A_1 A_2 B_1 B_2} \geq 0$

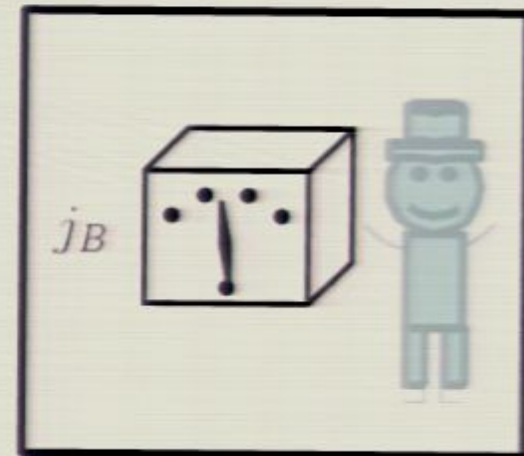
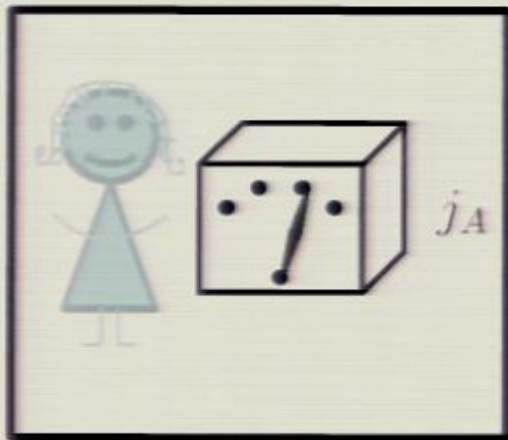


2. Probability 1 on all CPTP maps:

$$\text{Tr} \left[ W^{A_1 A_2 B_1 B_2} \left( \rho_{\mathcal{E}^A}^{A_1 A_2} \rho_{\mathcal{E}^B}^{B_1 B_2} \right) \right] = 1$$

$$\forall \rho^{A_1 A_2}, \rho^{B_1 B_2} > 0, \text{Tr}_1 \rho^{A_1 A_2} = \mathbb{1}^{A_2}, \text{Tr}_1 \rho^{B_1 B_2} = \mathbb{1}^{B_2}$$

# Example: Bipartite state

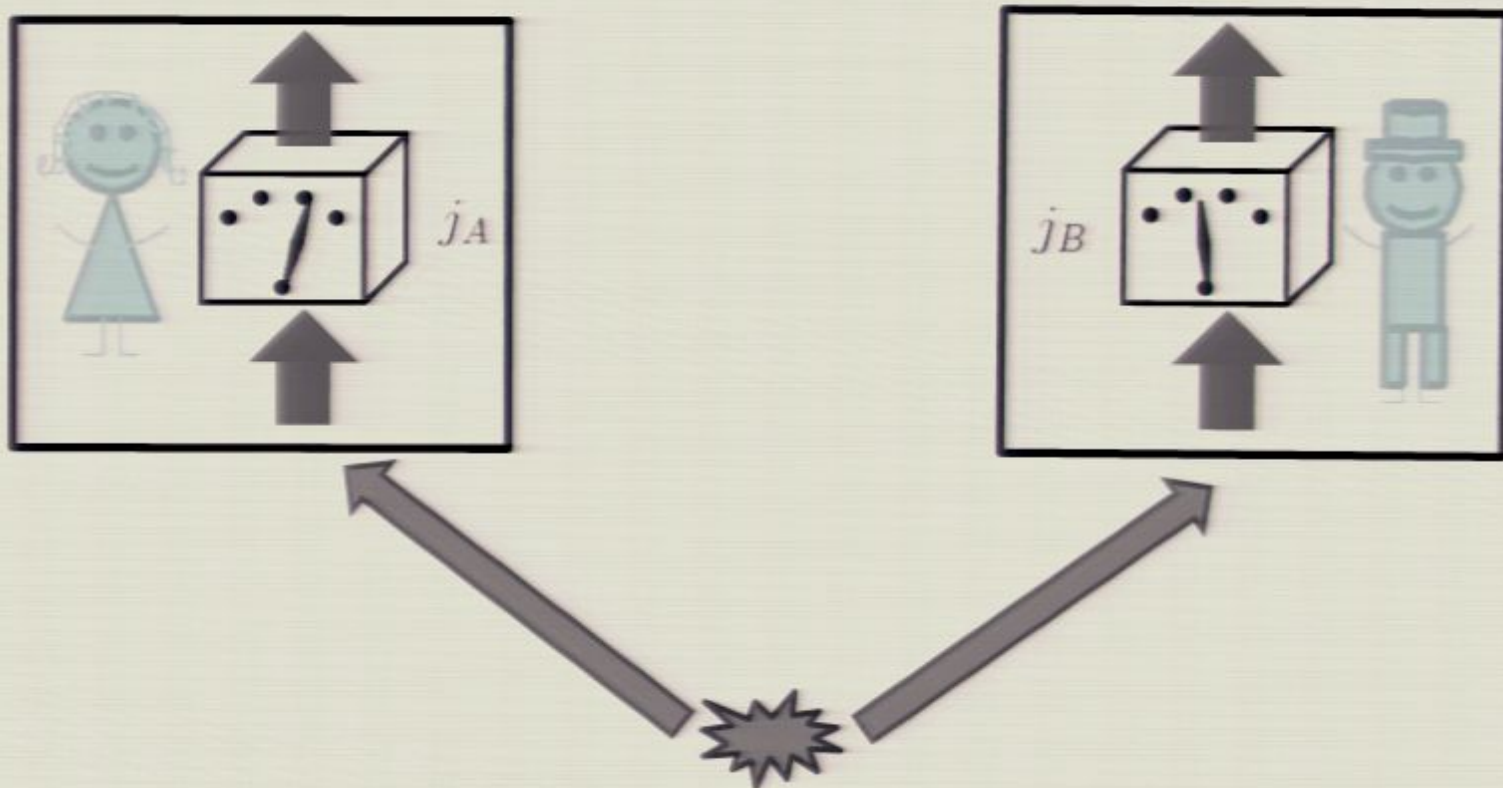


Sharing a joint state,  
No signalling

$$W^{A_1 A_2 B_1 B_2} = \mathbb{1}^{A_1 B_1} \otimes (\rho^{A_2 B_2})^T$$

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} [\mathcal{M}^A \otimes \mathcal{M}^B (\rho^{A_2 B_2})]$$

# Example: Bipartite state

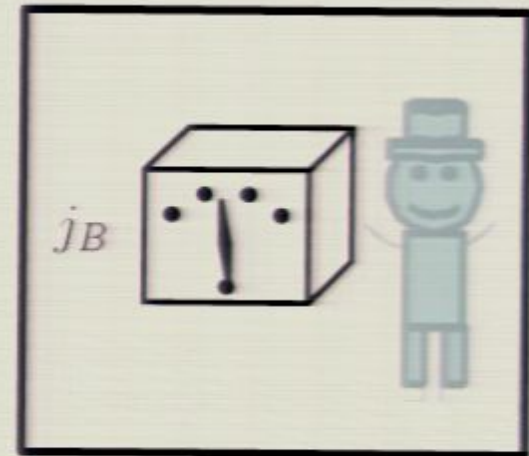
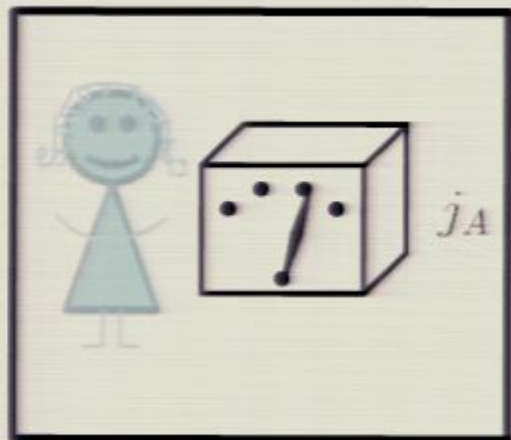


Sharing a joint state,  
No signalling

$$W^{A_1 A_2 B_1 B_2} = \mathbb{1}^{A_1 B_1} \otimes (\rho^{A_2 B_2})^T$$

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} [\mathcal{M}^A \otimes \mathcal{M}^B (\rho^{A_2 B_2})]$$

# Example: Channel $B \rightarrow A$

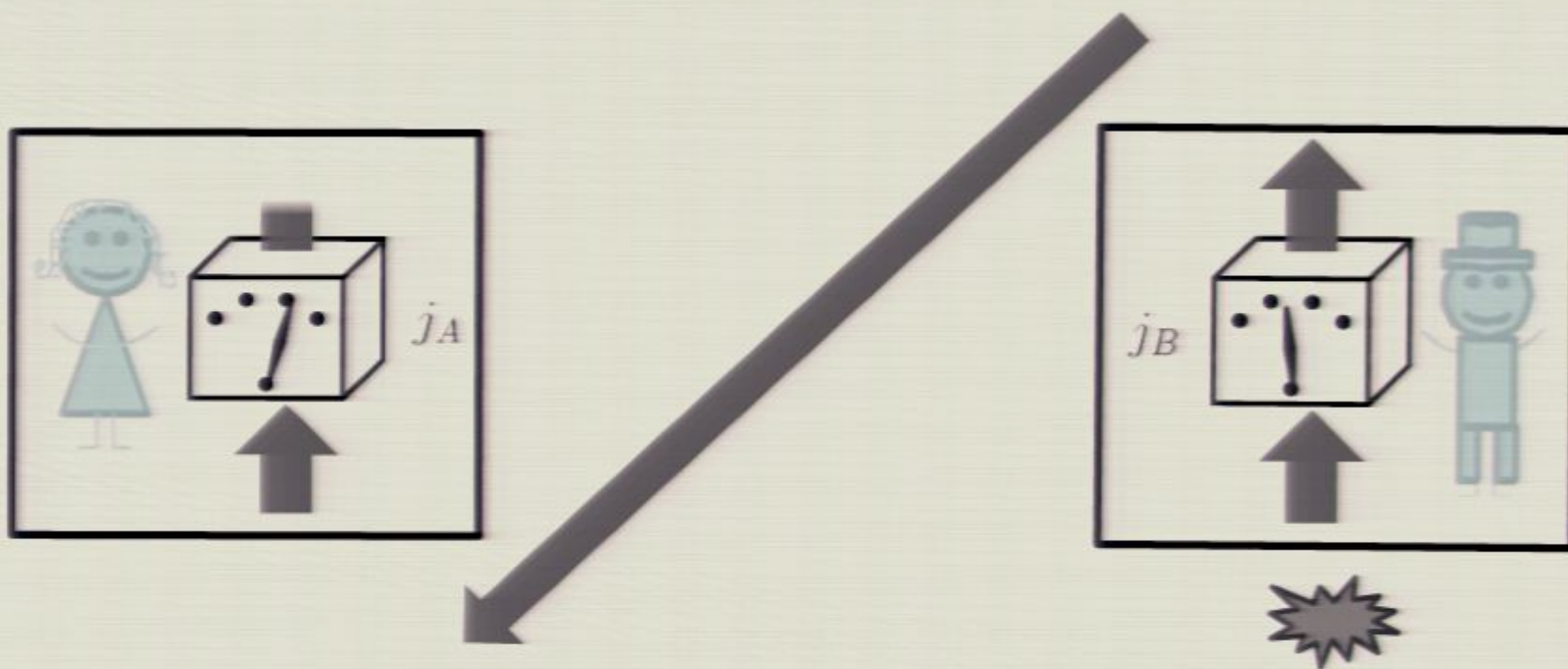


Sending a state from B to A, Possibility of signalling

$$W^{A_1 A_2 B_1 B_2} = \mathbb{1}^{A_1} \otimes \left( \rho_{\mathcal{E}}^{A_2 B_1} \right)^T \rho_0^{B_2 T}$$

$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ \mathcal{M}^A \circ \mathcal{E} \circ \mathcal{M}^B \left( \rho_0^{B_2} \right) \right]$$

# Example: Channel $B \rightarrow A$



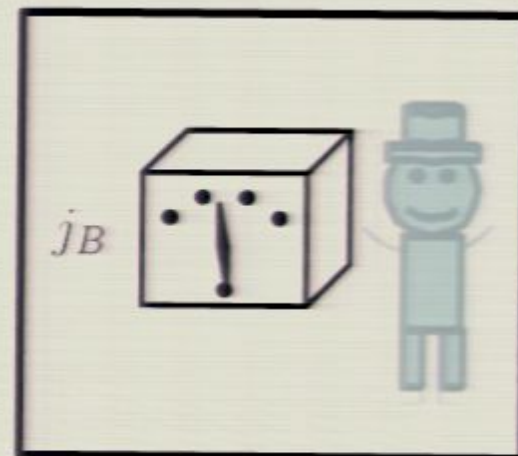
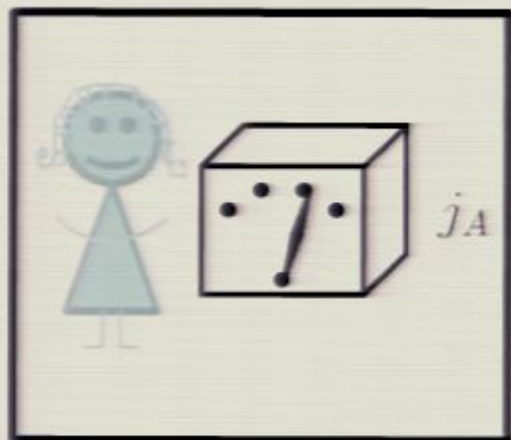
Sending a state from B to A,

$$W^{A_1 A_2 B_1 B_2} = \mathbb{1}^{A_1} \otimes \left( \rho_{\mathcal{E}}^{A_2 B_1} \right)^T \rho_0^{B_2 T}$$

Possibility of signalling

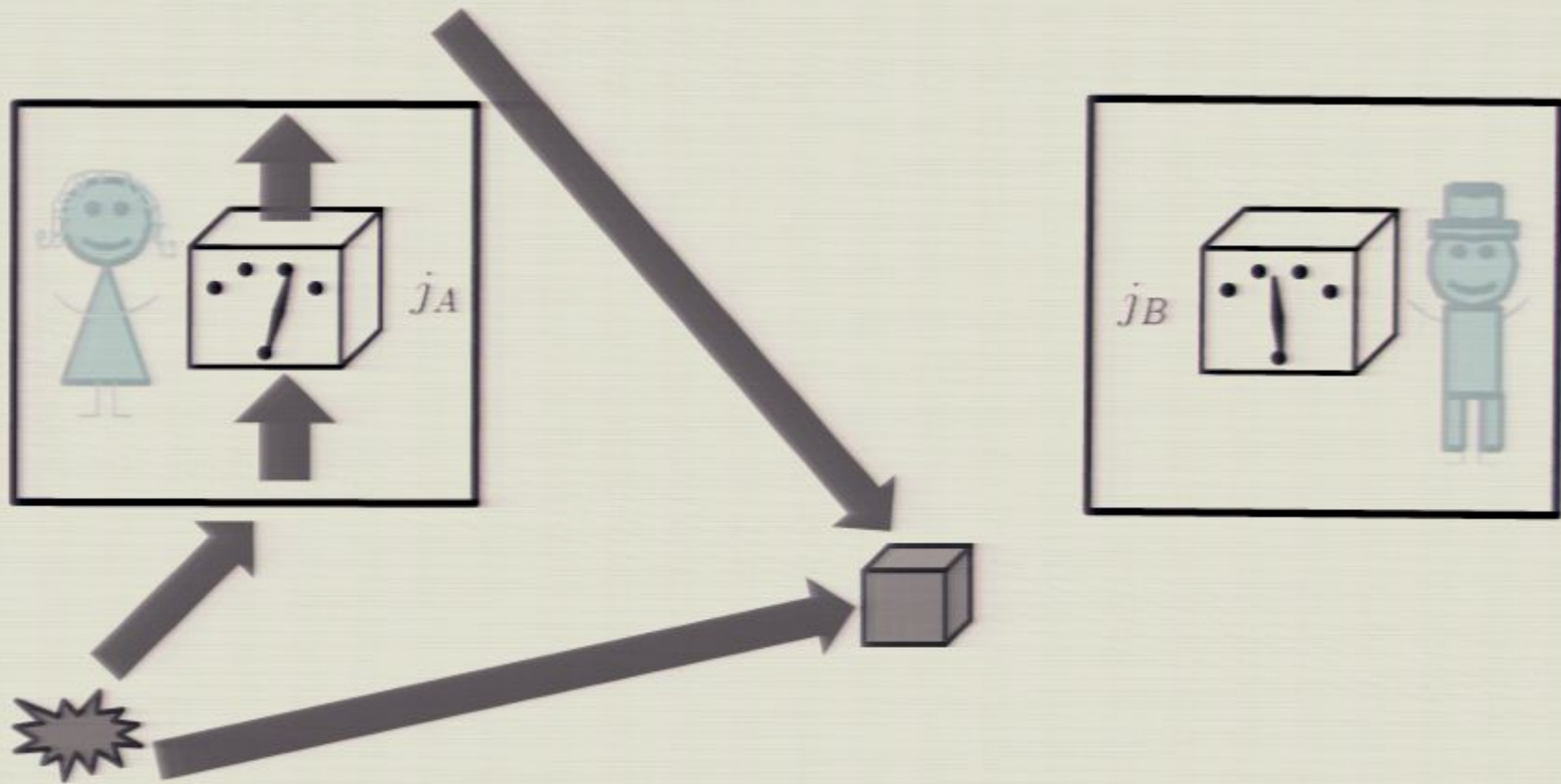
$$P(\mathcal{M}^A, \mathcal{M}^B) = \text{Tr} \left[ \mathcal{M}^A \circ \mathcal{E} \circ \mathcal{M}^B \left( \rho_0^{B_2} \right) \right]$$

# Channel with memory

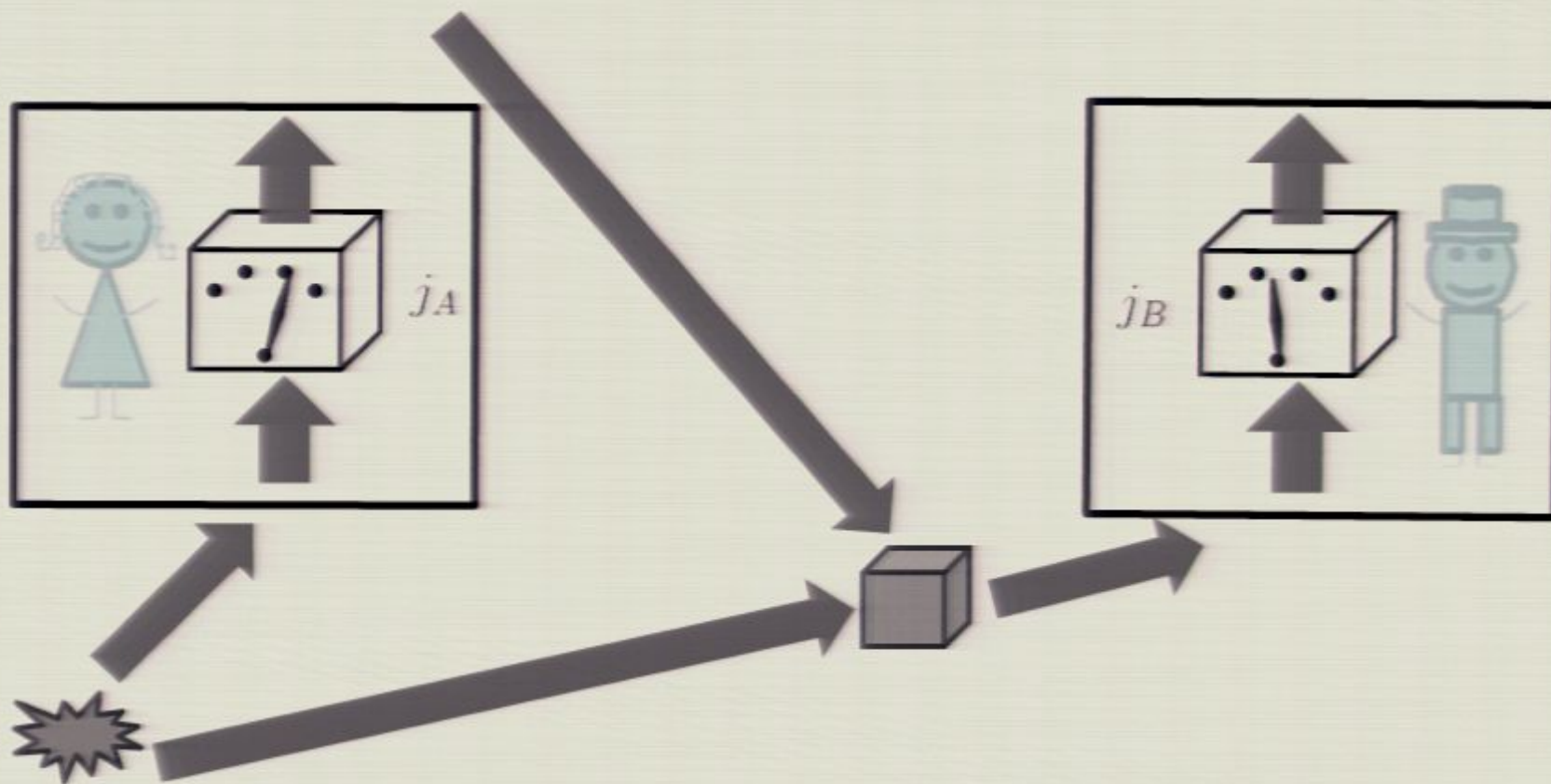




# Channel with memory



# Channel with memory



# Causal order - notation

# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B

# Causal order - notation

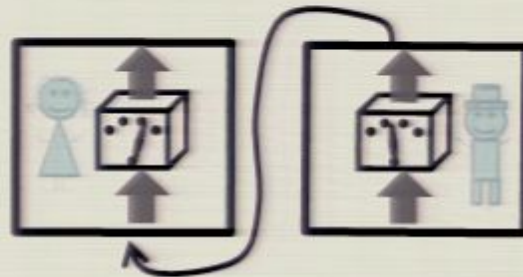
- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A

# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B

# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B



# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B





# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B



- $B \not\preceq A$ : "B is not in the causal past of A"      B cannot signal to A

# Causal order - notation

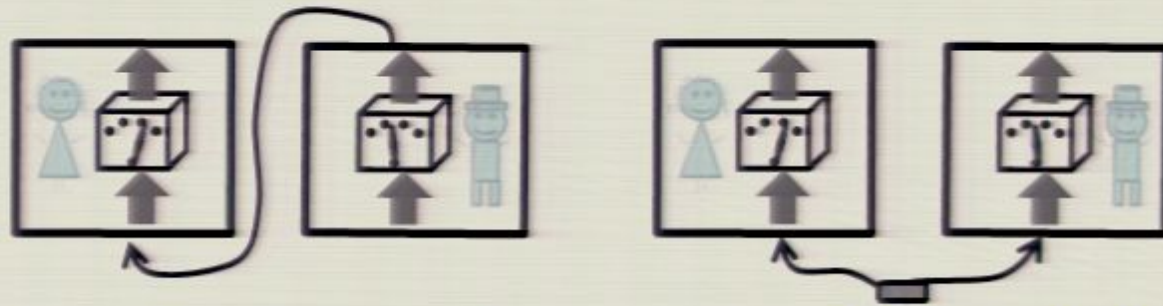
- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B



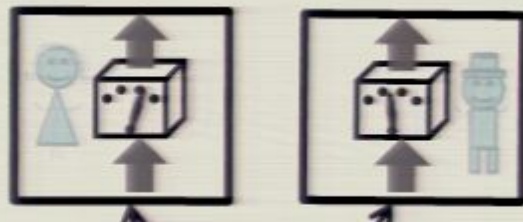
- $B \not\preceq A$ : "B is not in the causal past of A"      B cannot signal to A
- $A \not\preceq B \ \& \ B \not\preceq A$ : "A and B causally independent"

# Causal order - notation

- $A \preceq B$ : "A is in the causal past of B"      A can signal to B
- $B \preceq A$ : "B is in the causal past of A"      B can signal to A
- $A \not\preceq B$ : "A is in not the causal past of B"      A cannot signal to B



- $B \not\preceq A$ : "B is not in the causal past of A"      B cannot signal to A
- $A \not\preceq B \ \& \ B \not\preceq A$ : "A and B causally independent"



# Terms appearing in process matrix

$$W^{A_1 A_2 B_1 B_2} = \sum_{\mu_1, \dots, \mu_4} a_{\mu_1 \dots \mu_4} \sigma_{\mu_1}^{A_1} \otimes \dots \otimes \sigma_{\mu_4}^{B_2}$$

$\sigma_i^{A_1} \otimes \mathbb{1}^{rest}$	type $A_1$
$\sigma_i^{A_1} \otimes \sigma_j^{A_2} \otimes \mathbb{1}^{rest}$	type $A_1 A_2$
...	

# Terms appearing in process matrix

$$W^{A_1 A_2 B_1 B_2} = \sum_{\mu_1, \dots, \mu_4} a_{\mu_1 \dots \mu_4} \sigma_{\mu_1}^{A_1} \otimes \dots \otimes \sigma_{\mu_4}^{B_2}$$

$\sigma_i^{A_1} \otimes \mathbb{1}^{rest}$	type $A_1$
$\sigma_i^{A_1} \otimes \sigma_j^{A_2} \otimes \mathbb{1}^{rest}$	type $A_1 A_2$
...	

1. Probability positive & 2. Probability 1 on all CPTP maps

# Terms appearing in process matrix

$$W^{A_1 A_2 B_1 B_2} = \sum_{\mu_1, \dots, \mu_4} a_{\mu_1 \dots \mu_4} \sigma_{\mu_1}^{A_1} \otimes \dots \otimes \sigma_{\mu_4}^{B_2}$$

$\sigma_i^{A_1} \otimes \mathbb{1}^{rest}$                       type  $A_1$   
 $\sigma_i^{A_1} \otimes \sigma_j^{A_2} \otimes \mathbb{1}^{rest}$                       type  $A_1 A_2$   
 ...

1. Probability positive & 2. Probability 1 on all CPTP maps




$B \not\ll A$	$A_2, B_2, A_2 B_2$	$A_1 B_2$	$A_1 A_2 B_2$
$A \not\ll B$		$A_2 B_1$	$A_2 B_1 B_2$
Causal order	States	Channels	Channels with memory

Most general causally separable situation:  
probabilistic mixture of ordered ones:

$$W^{A_1 A_2 B_1 B_2} = q W^{B \not\prec A} + (1 - q) W^{A \not\prec B}$$

Most general causally separable situation:  
probabilistic mixture of ordered ones:

$$W^{A_1 A_2 B_1 B_2} = q W^{B \not\leftarrow A} + (1 - q) W^{A \not\leftarrow B}$$




Signalling only from  
A to B or causally  
independent




Most general causally separable situation:  
probabilistic mixture of ordered ones:

$$W^{A_1 A_2 B_1 B_2} = q W^{B \not\prec A} + (1 - q) W^{A \not\prec B}$$



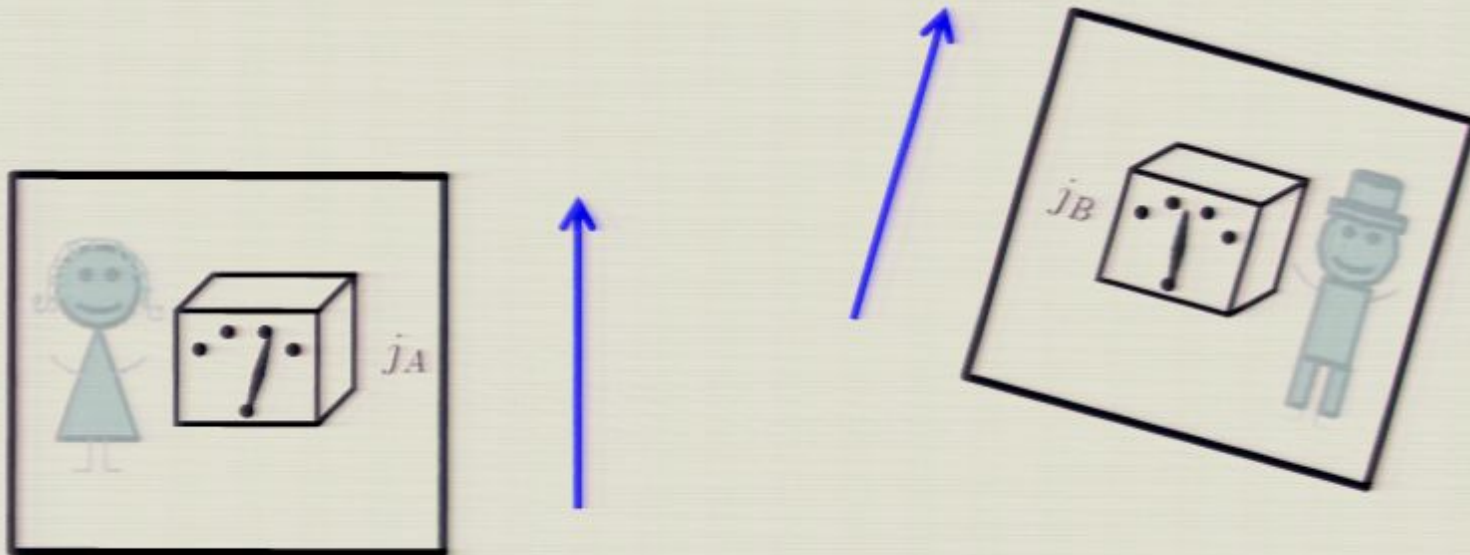
Signalling only from  
A to B or causally  
independent



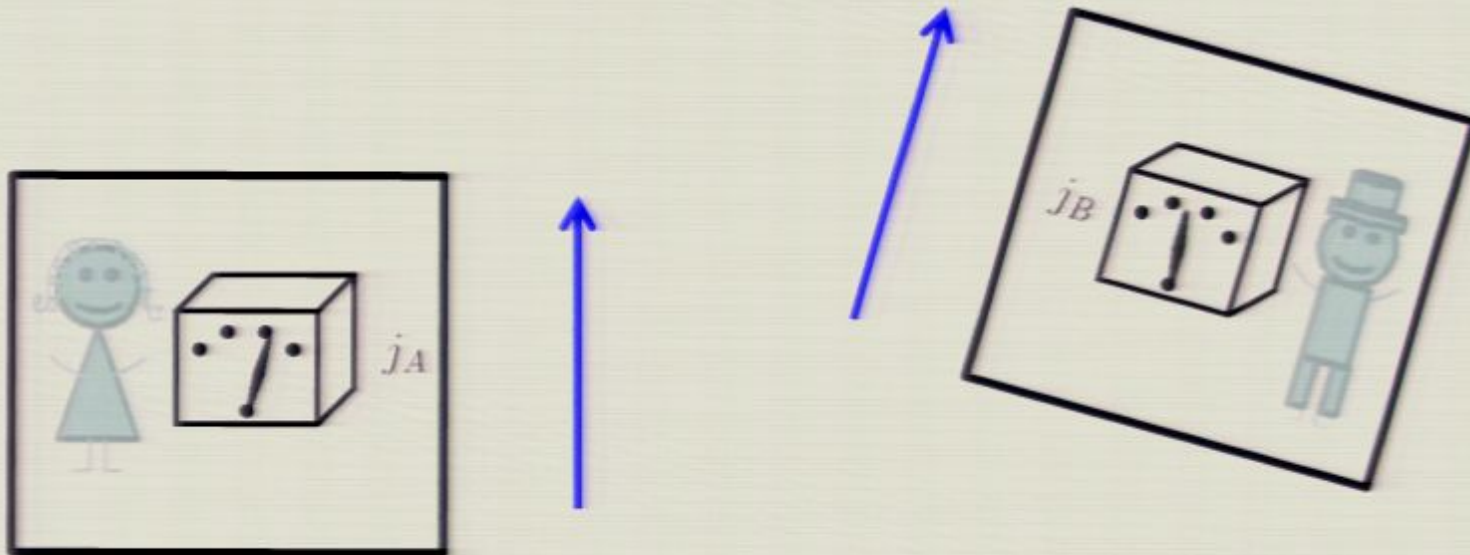
Signalling only from  
B to A or causally  
independent

Do all possible processes  $W$  respect  
definite causal order?

# Causal Game

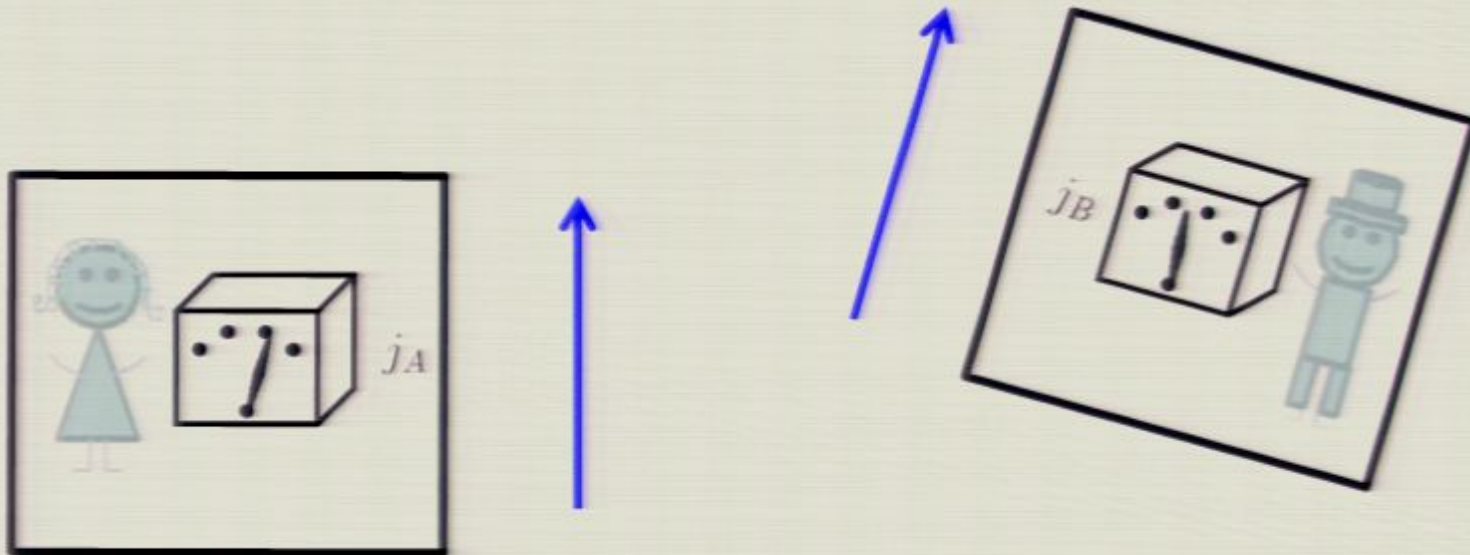


# Causal Game



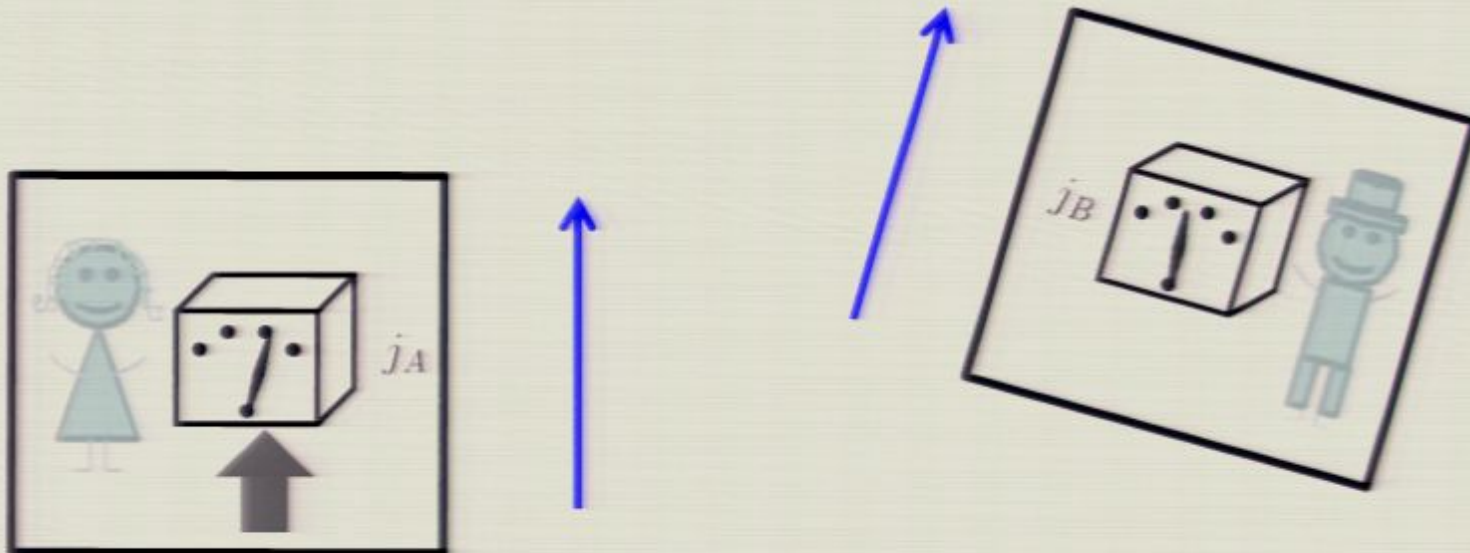
- Alice is given bit **a** and Bob bit **b**.

# Causal Game



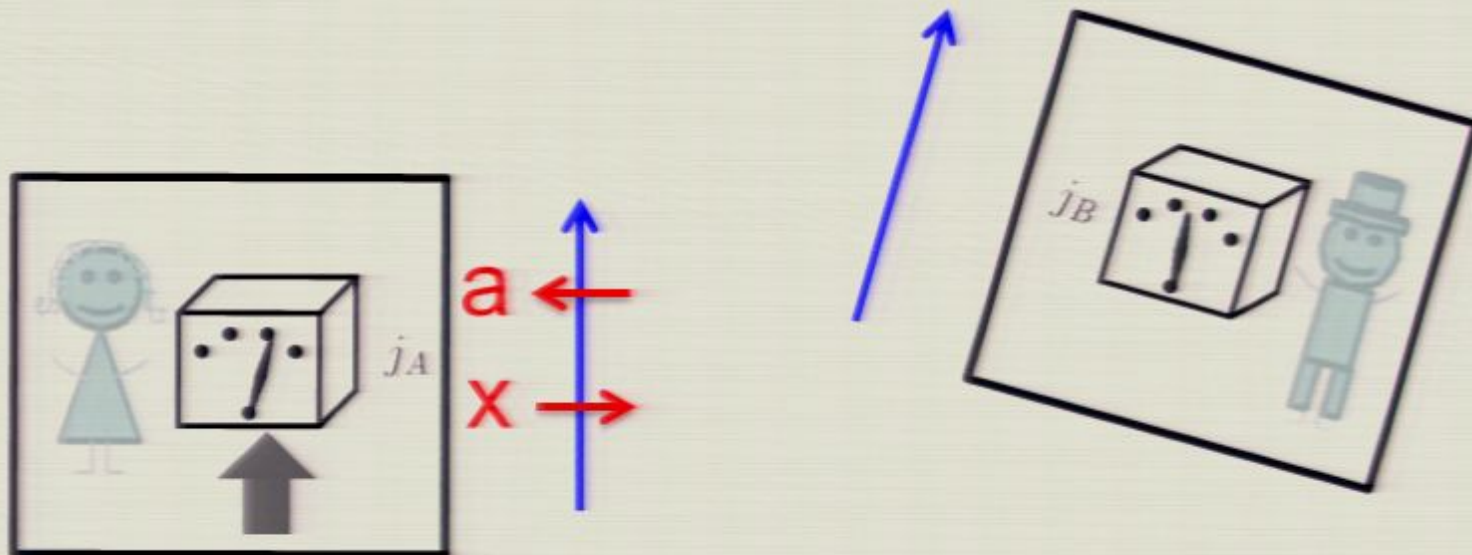
- Alice is given bit **a** and Bob bit **b**.
- Alice produces **x** and Bob **y**, which are their best guesses for the value of the bit given to the other.

# Causal Game



- Alice is given bit **a** and Bob bit **b**.
- Alice produces **x** and Bob **y**, which are their best guesses for the value of the bit given to the other.

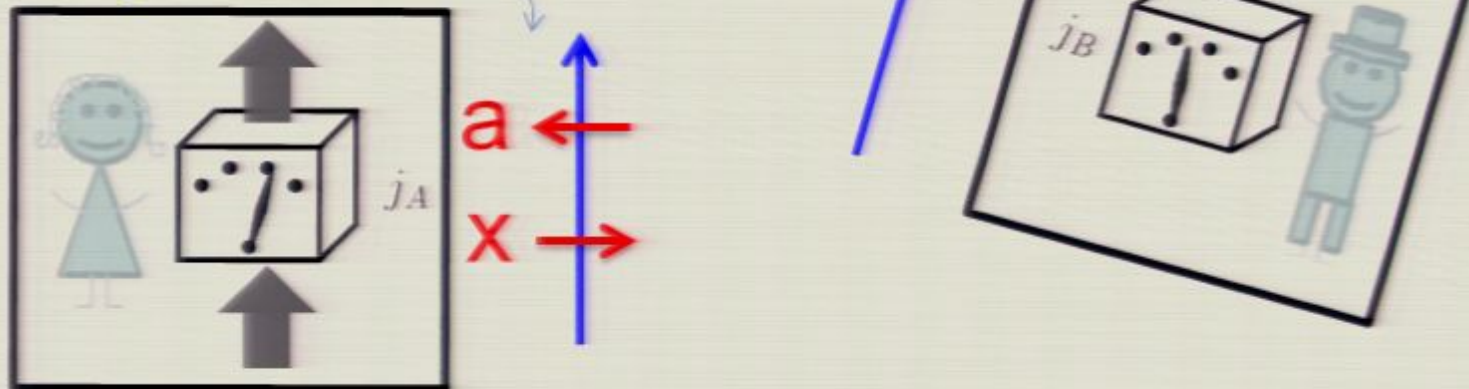
# Causal Game



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.

# Causal Game

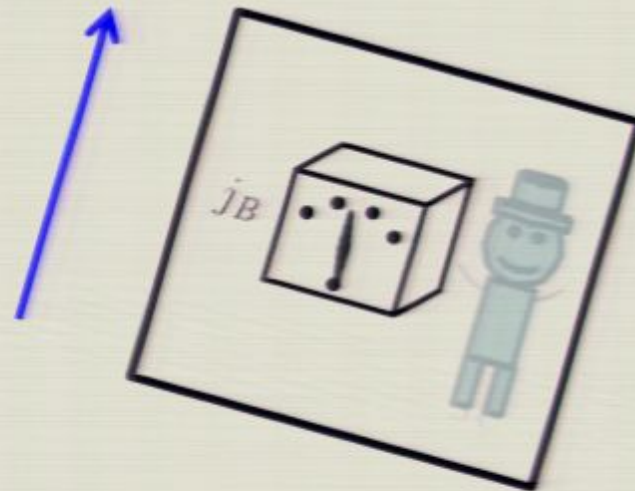
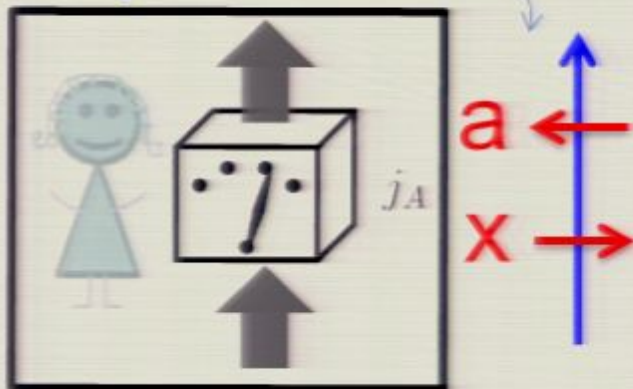
Guess  $x$  is produced  
in local time before  
bit  $a$  is given



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.

# Causal Game

Guess  $x$  is produced  
in local time before  
bit  $a$  is given

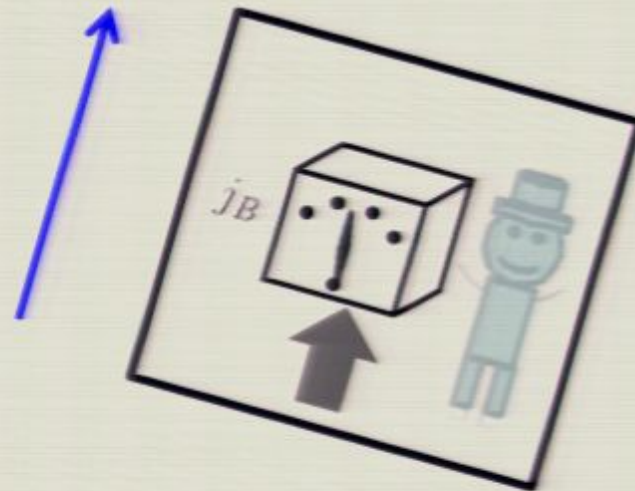
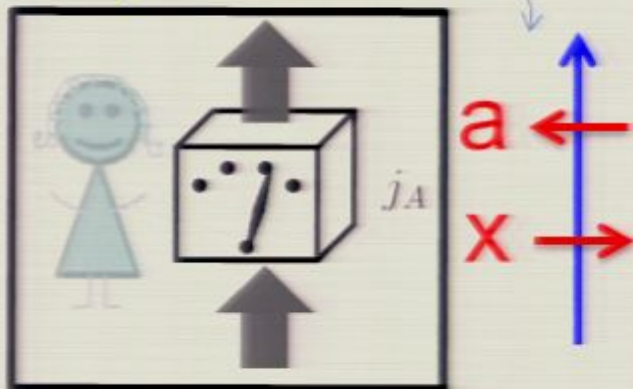


- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).



# Causal Game

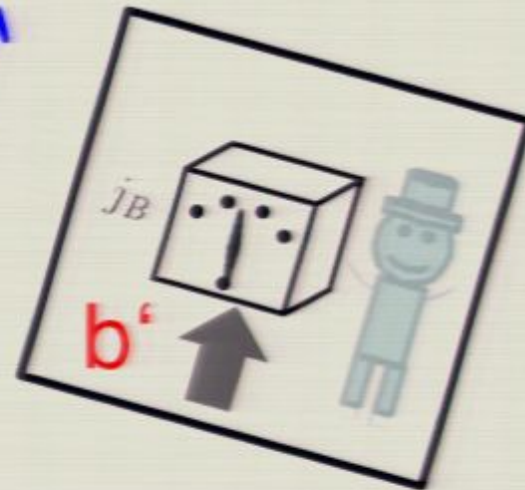
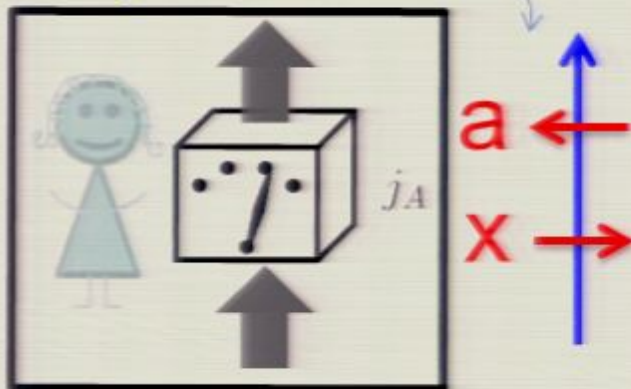
Guess  $x$  is produced  
in local time before  
bit  $a$  is given



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).

# Causal Game

Guess  $x$  is produced  
in local time before  
bit  $a$  is given



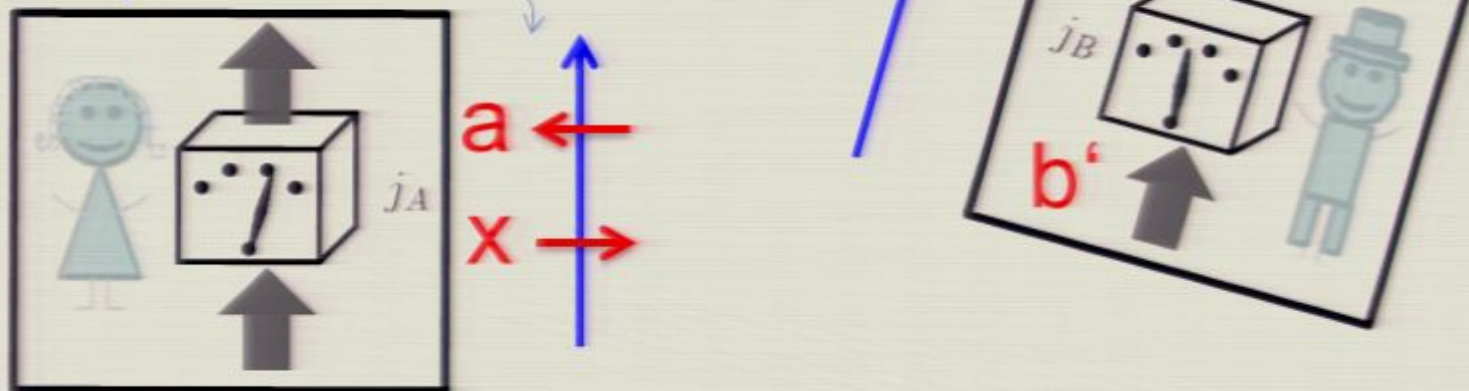
- Alice is given bit  $a$  and Bob  $b$
- Alice produces  $x$  and Bob  $y$ ,  
the value of the bit given to th
- Bob is given an additional bit  
should guess her bit ( $b'=1$ ) o

st guesses for  
whether he  
his bit ( $b'=0$ ).

- Weiter
- Zurück
- Zuletzt angesehen
- Gehe zu Folie
- Gehe zu Abschnitt
- Zielgruppenorientierte Präsentation
- Bildschirm
- Zeigeroptionen
- Hilfe
- Anhalten
- Präsentation beenden

# Causal Game

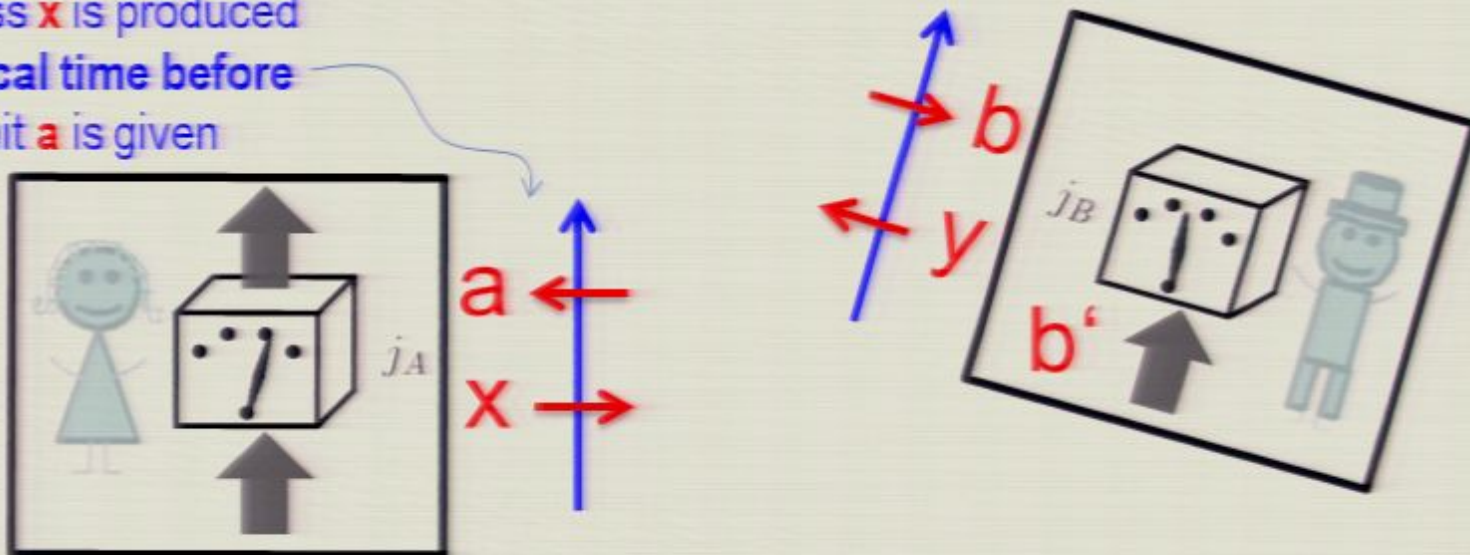
Guess  $x$  is produced  
in local time before  
bit  $a$  is given



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).

# Causal Game

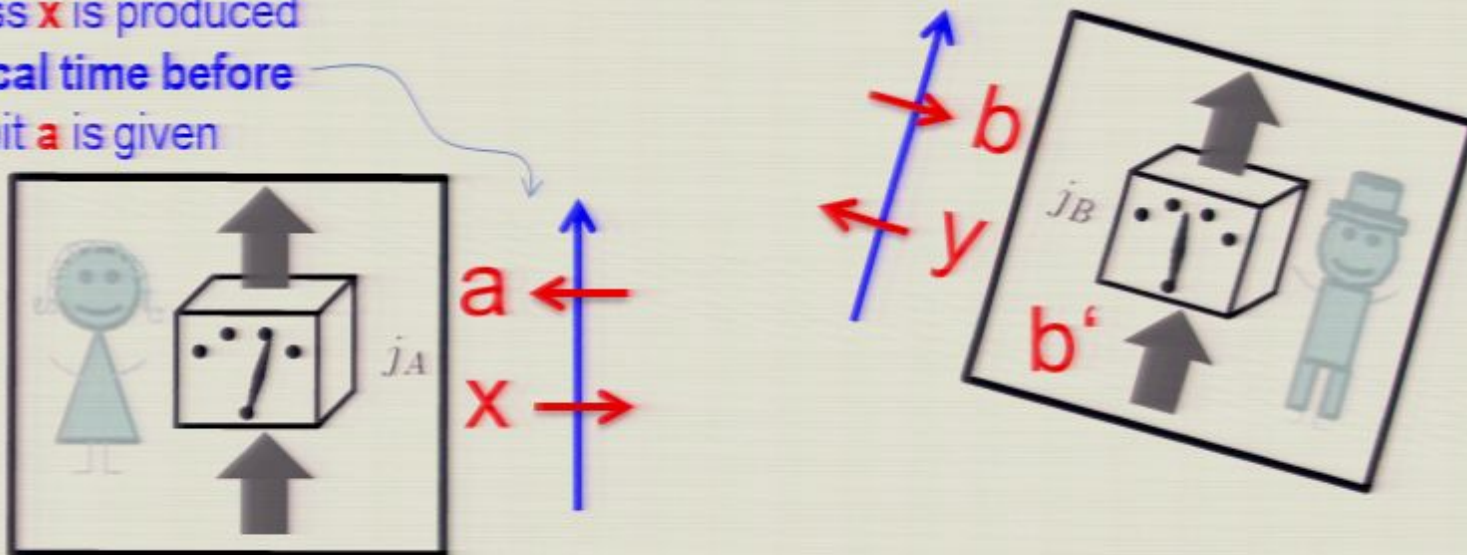
Guess  $x$  is produced  
in local time before  
bit  $a$  is given



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).

# Causal Game

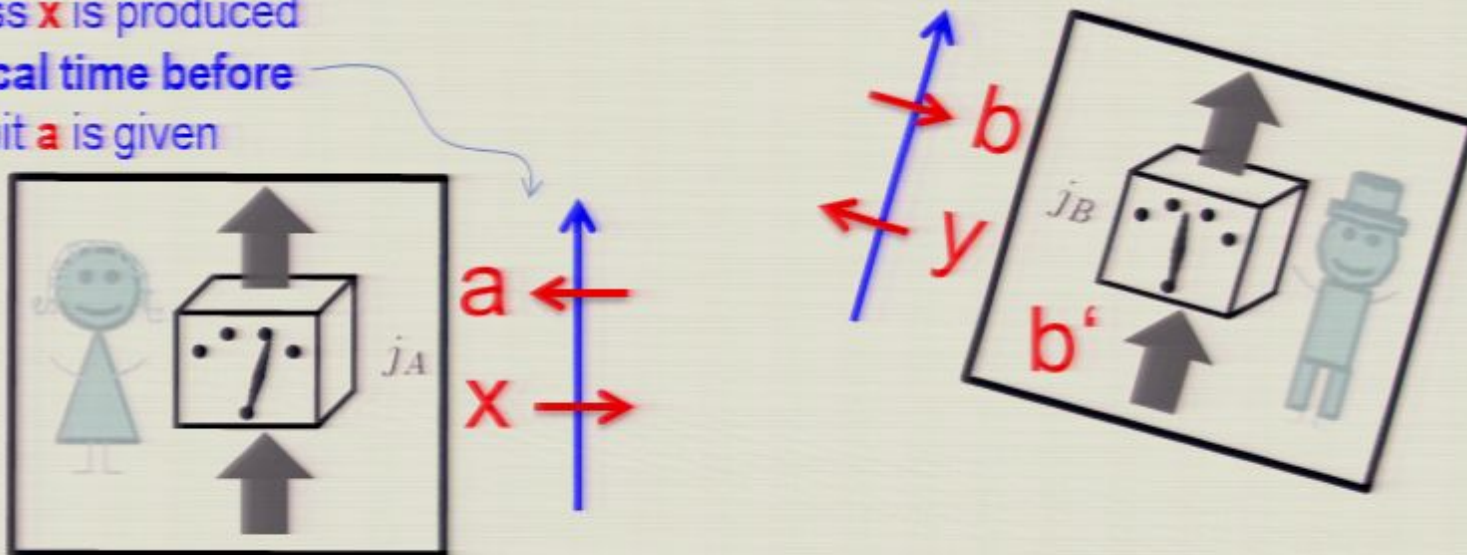
Guess  $x$  is produced  
in local time before  
bit  $a$  is given



- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).

# Causal Game

Guess  $x$  is produced  
in local time before  
bit  $a$  is given



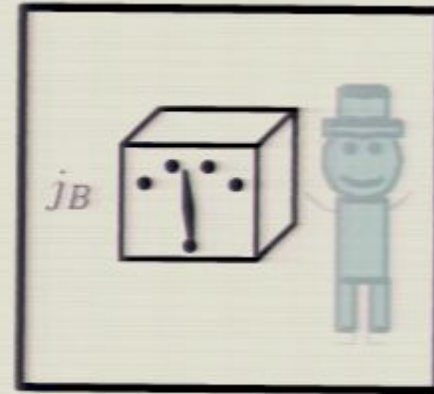
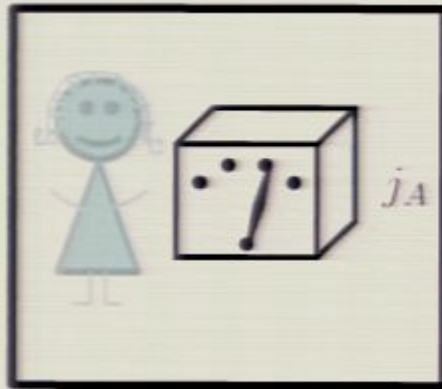
- Alice is given bit  $a$  and Bob bit  $b$ .
- Alice produces  $x$  and Bob  $y$ , which are their best guesses for the value of the bit given to the other.
- Bob is given an additional bit  $b'$  that tells him whether he should guess her bit ( $b'=1$ ) or she should guess his bit ( $b'=0$ ).
- The goal is to maximize the probability for correct guess:

$$P_{succ} := \frac{1}{2} [P(x = b | b' = 0) + P(y = a | b' = 1)]$$

# Causally ordered situation

Case:  $B \not\prec A$

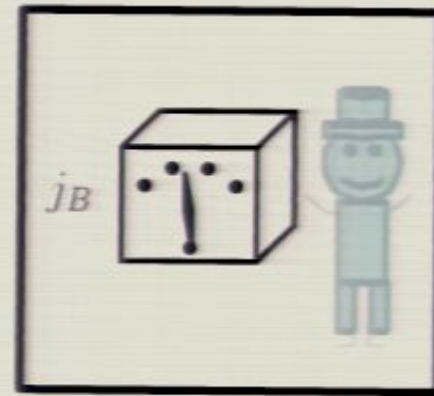
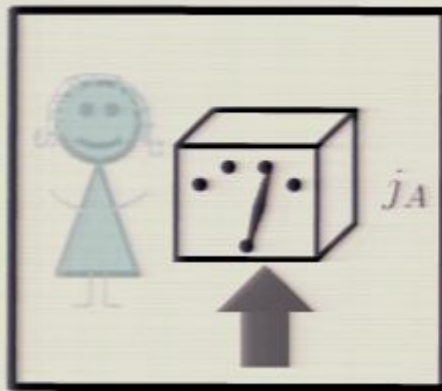
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

Global Time

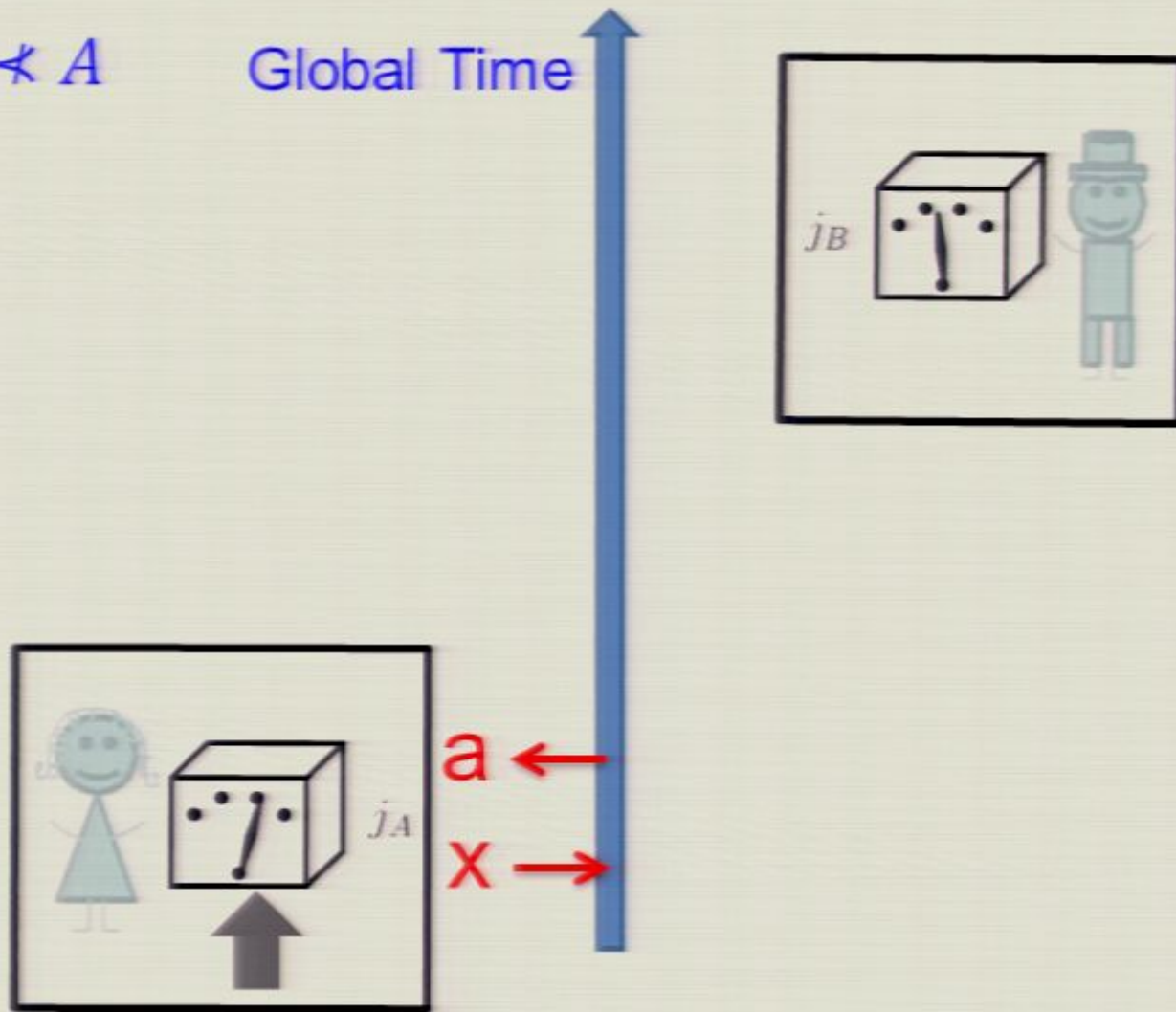




# Causally ordered situation

Case:  $B \not\prec A$

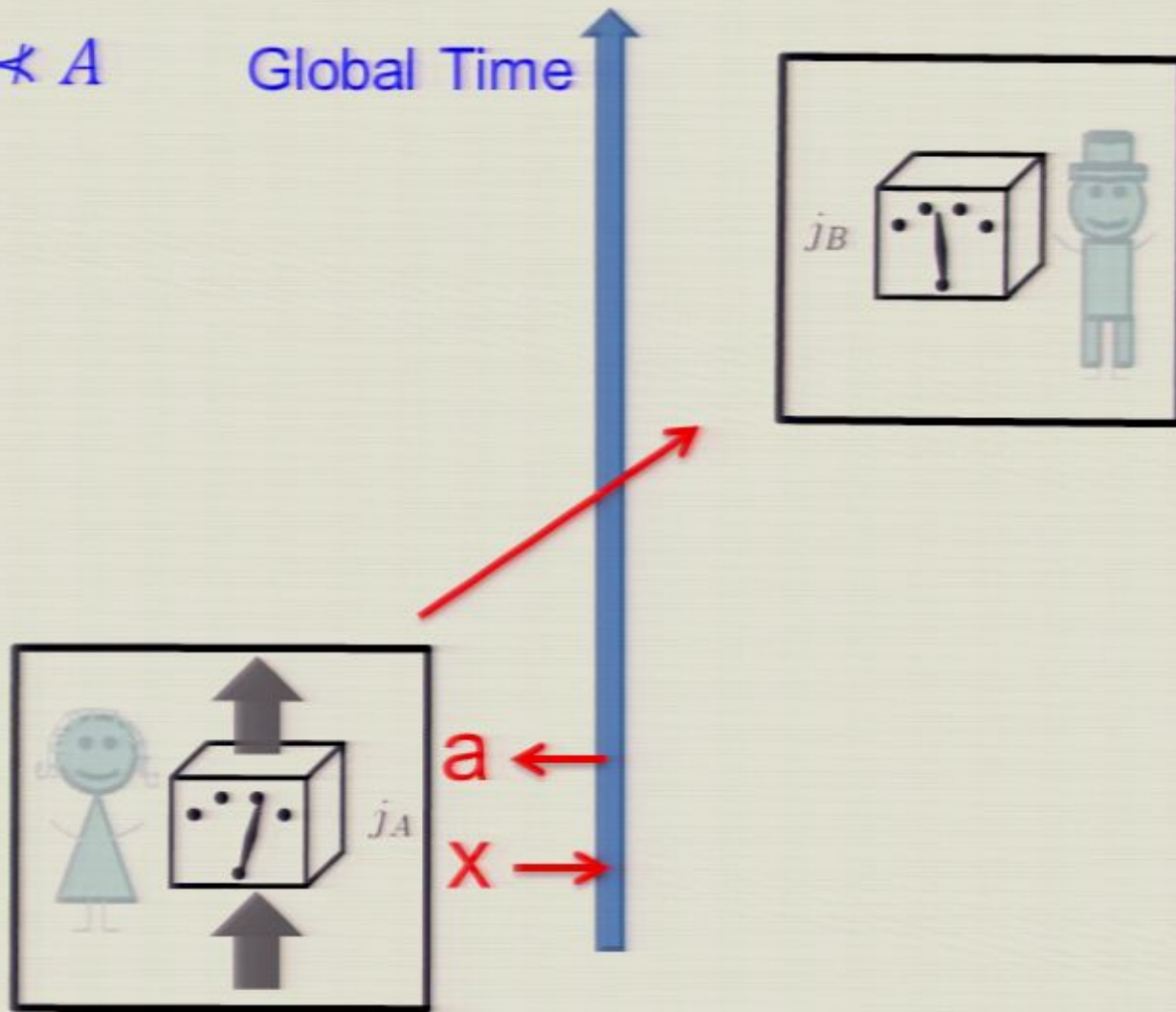
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

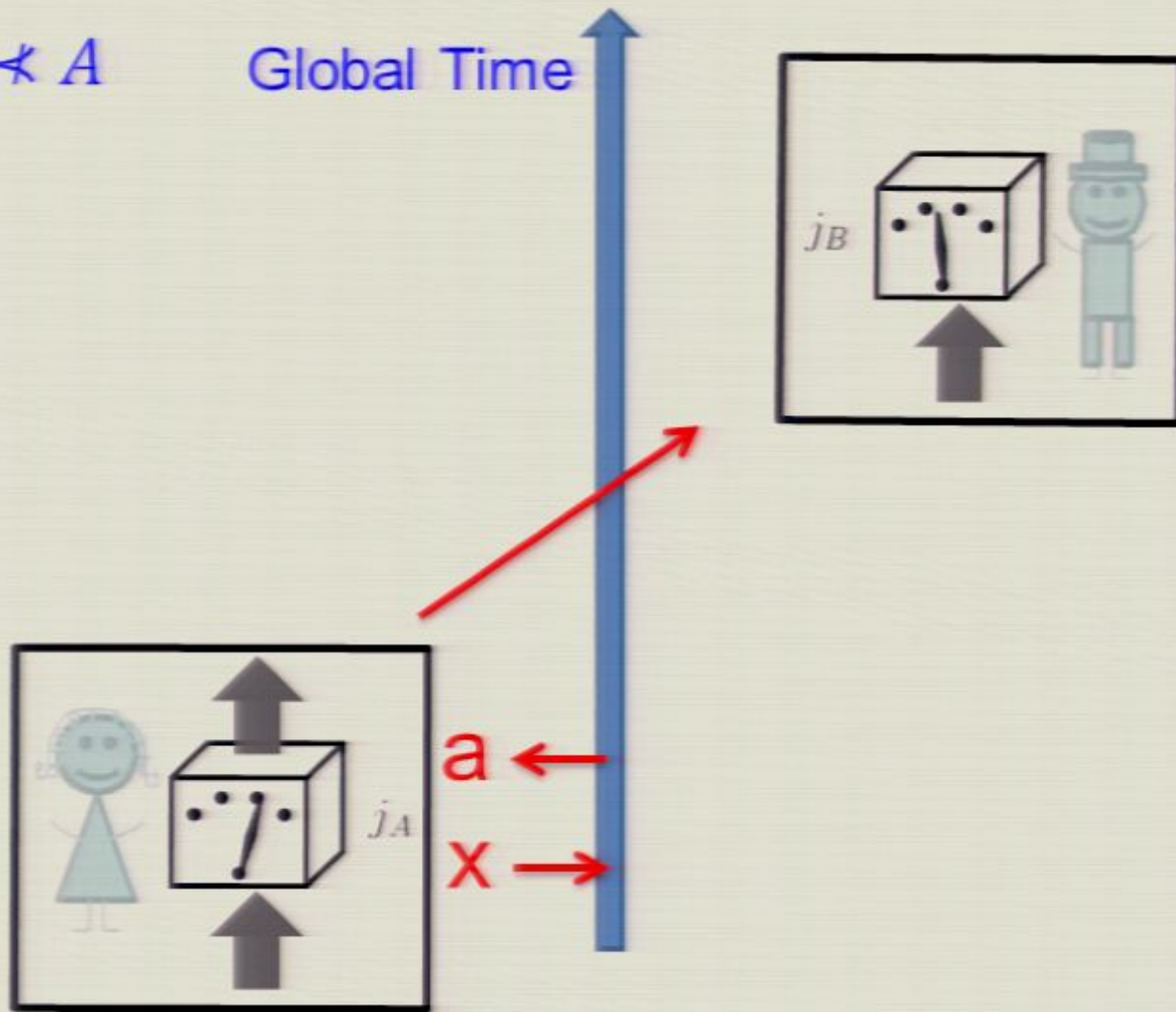
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

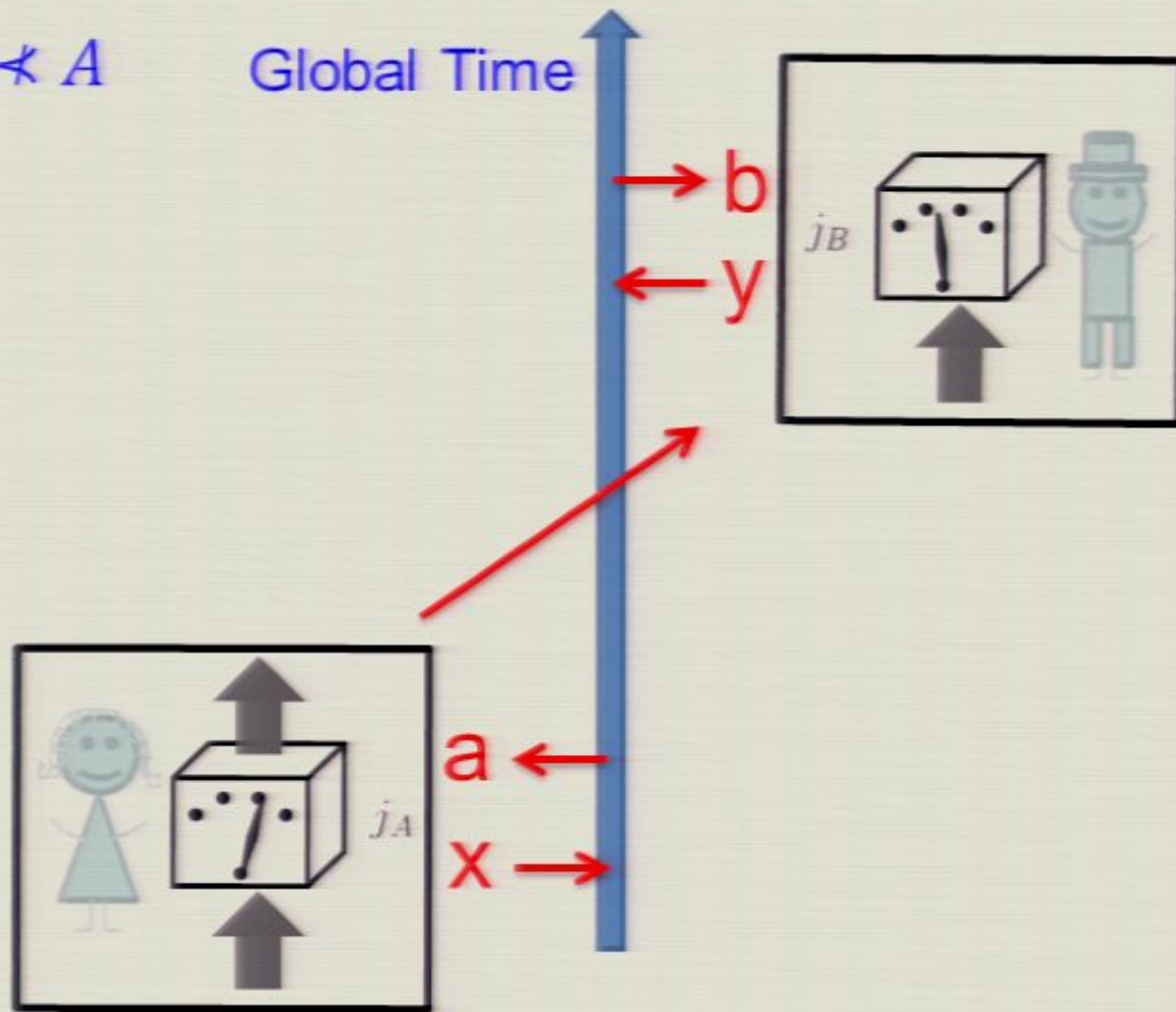
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

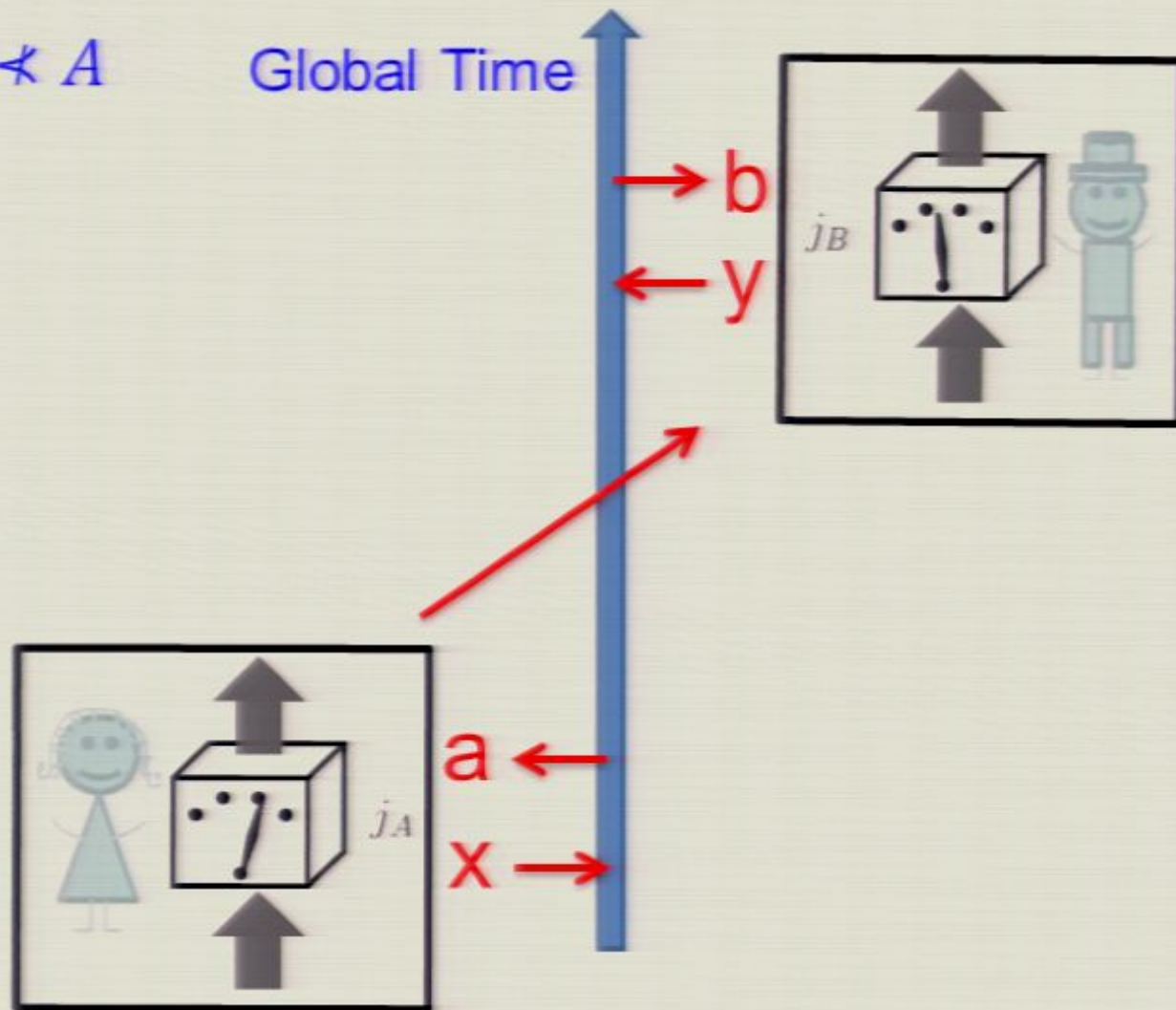
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

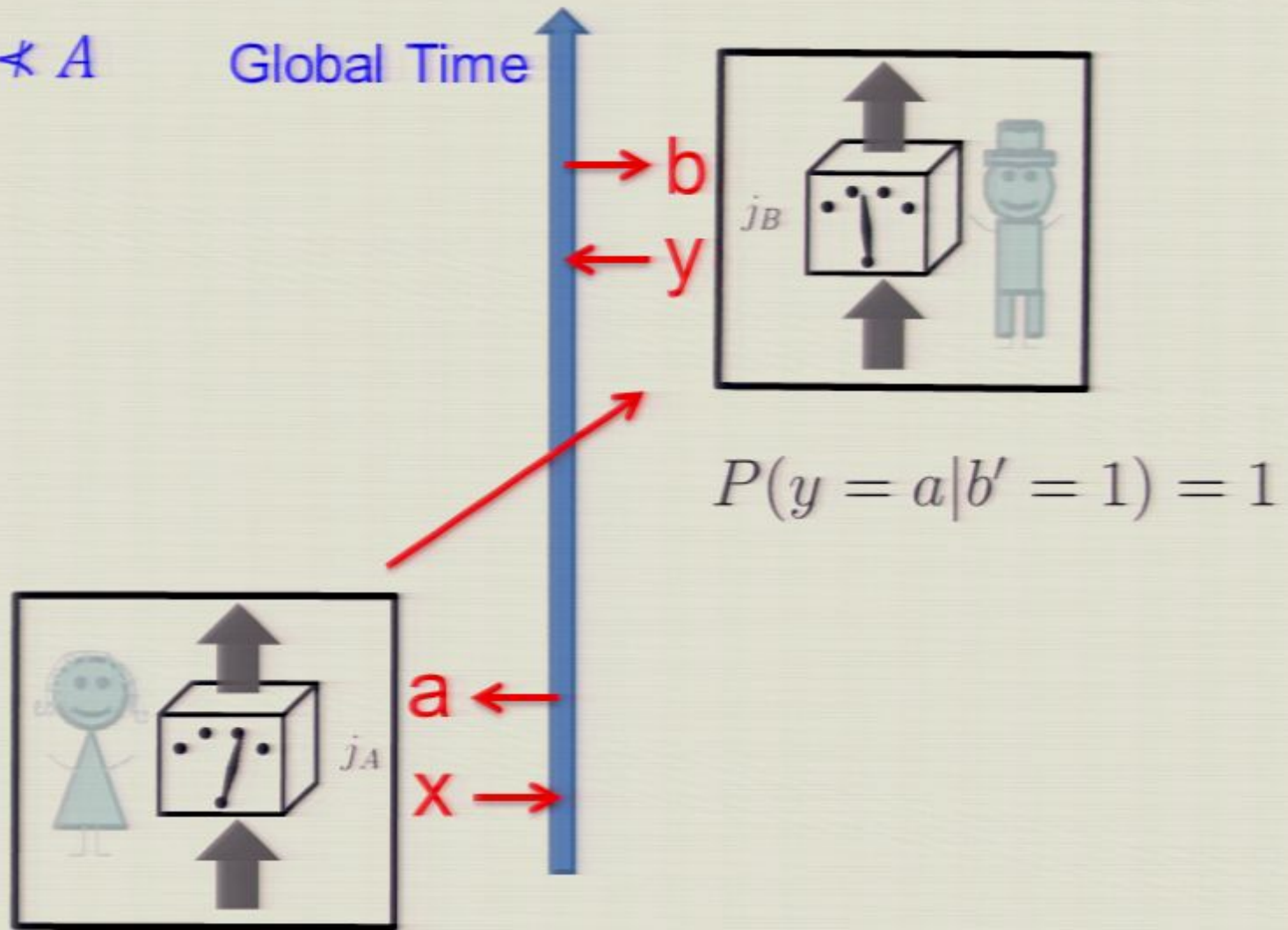
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

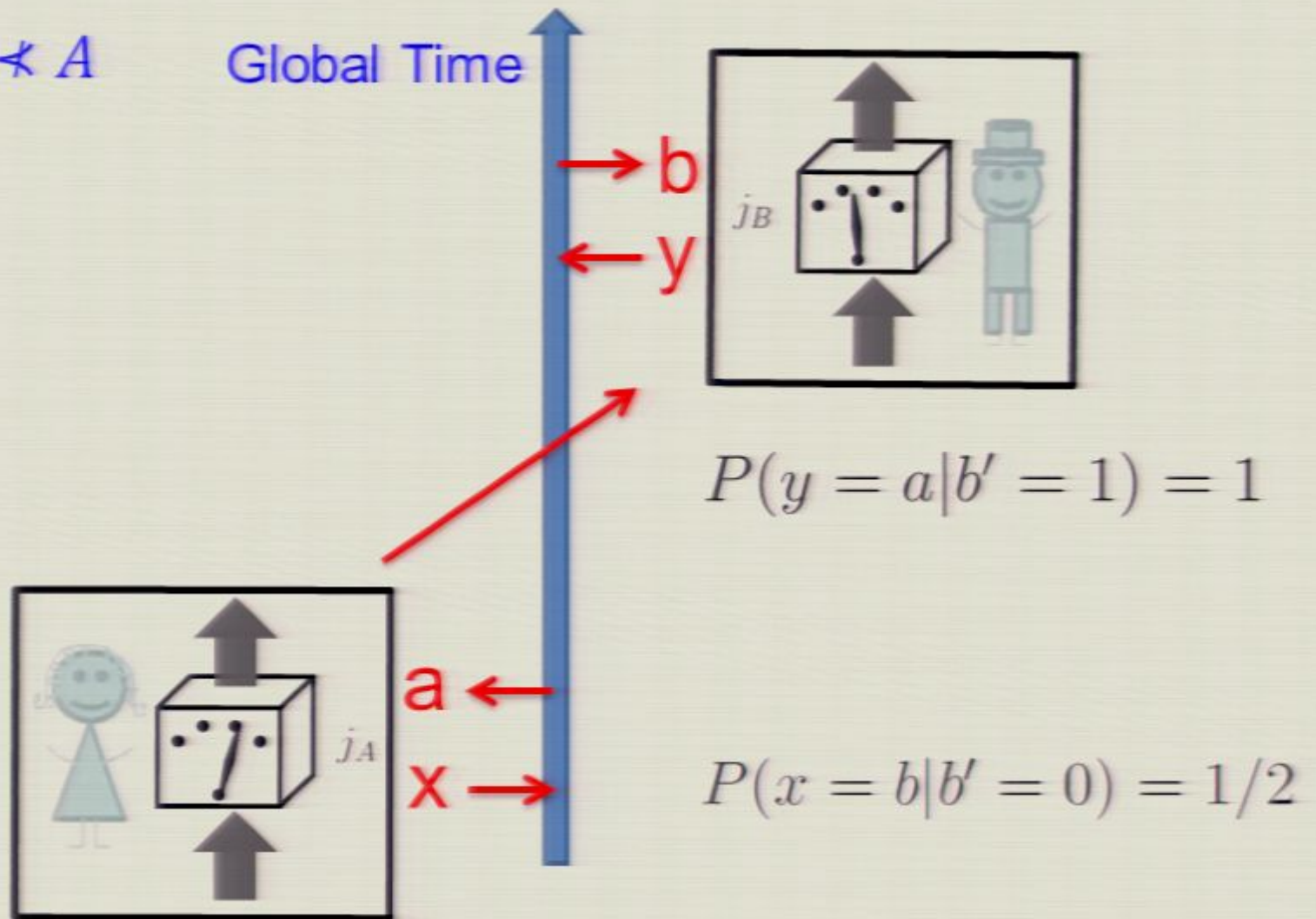
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

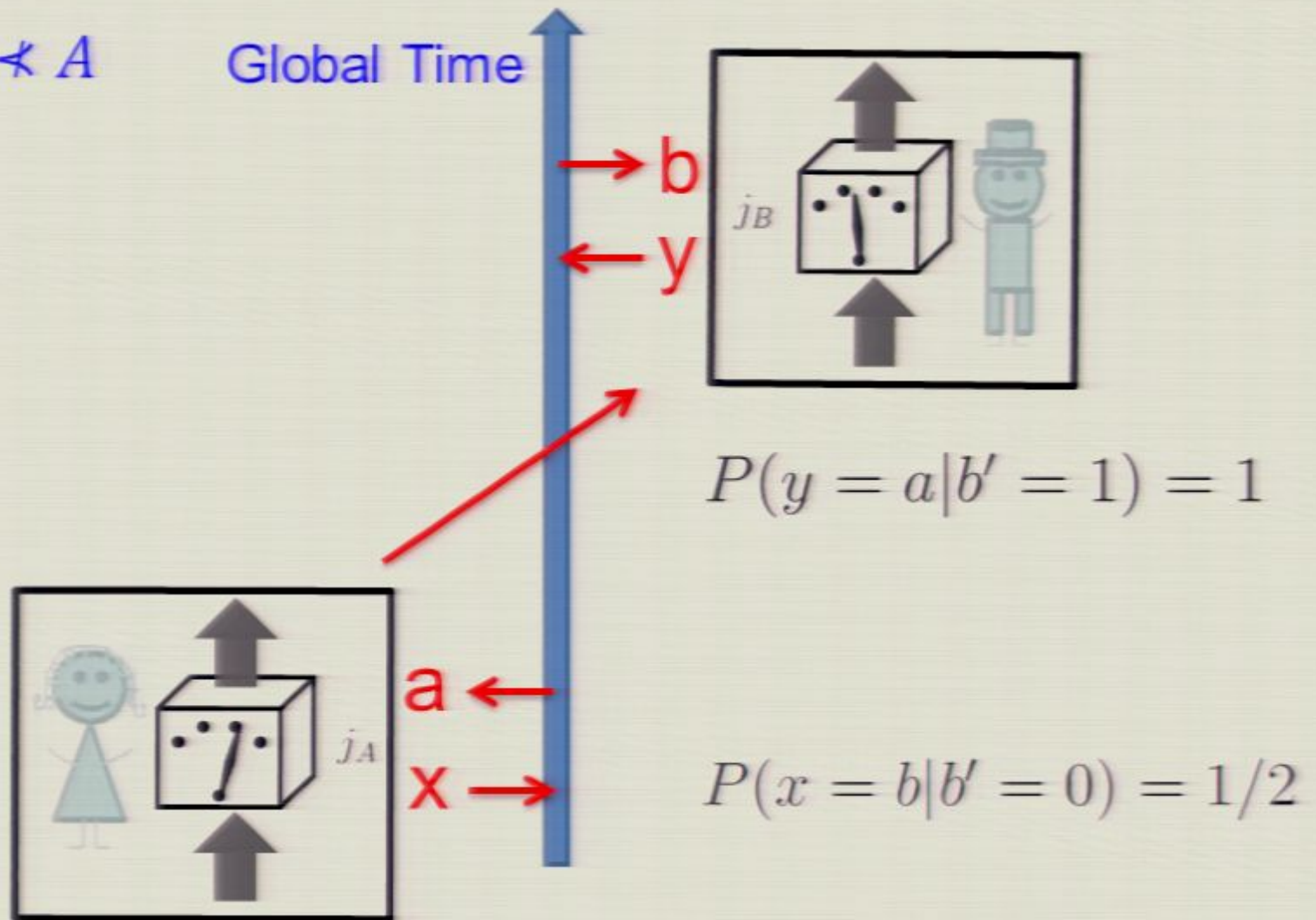
Global Time



# Causally ordered situation

Case:  $B \not\prec A$

Global Time



$$P(y = a|b' = 1) = 1$$

$$P(x = b|b' = 0) = 1/2$$

$$p_{\text{succ}} = P(x = b|b' = 0) + P(y = a|b' = 1) \leq \frac{3}{4}$$



# Causally non-separable situation

# Causally non-separable situation

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} (\sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2}) \right]$$

# Causally non-separable situation

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} (\sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2}) \right]$$

The probability of success is

$$p_{succ} = \frac{2 + \sqrt{2}}{4} > \frac{3}{4}$$

# Causally non-separable situation

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} (\sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2}) \right]$$

The probability of success is

$$p_{succ} = \frac{2+\sqrt{2}}{4} > \frac{3}{4}$$

This process cannot be realized as a probabilistic mixture of causally ordered situations!

# Causally non-separable situation

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} (\sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2}) \right]$$

The probability of success is

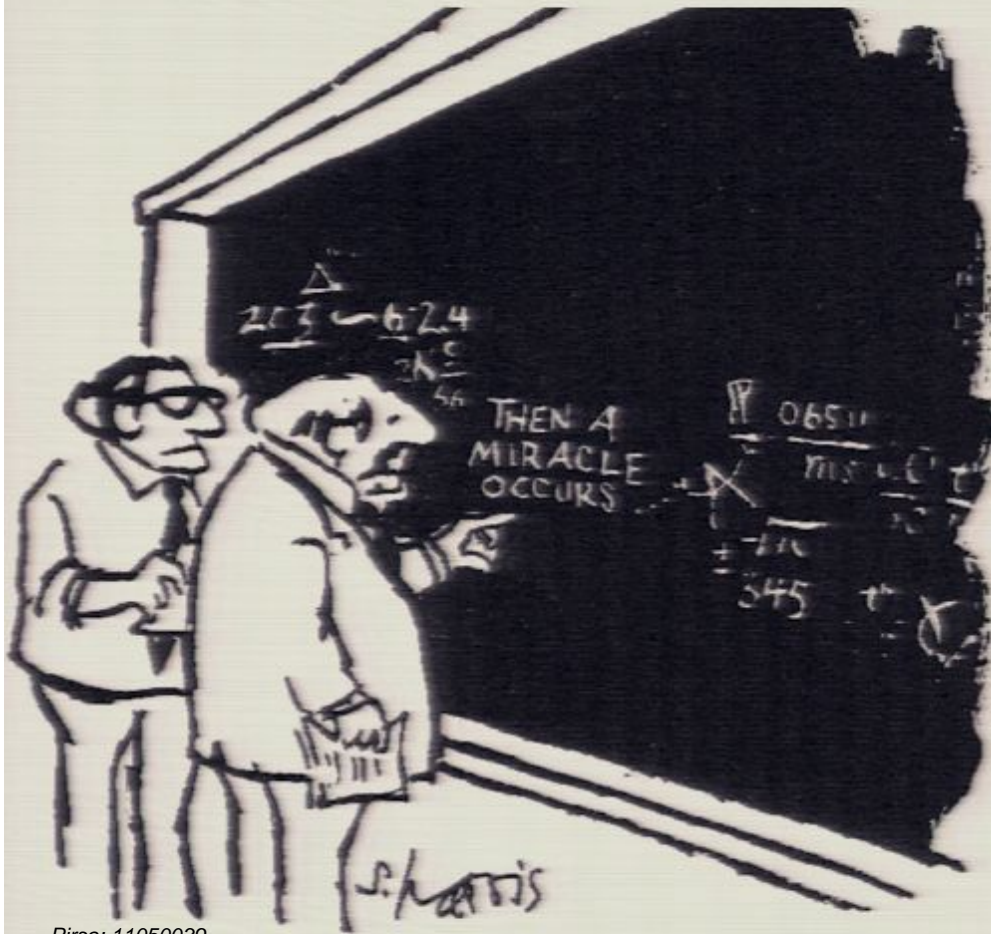
$$p_{succ} = \frac{2 + \sqrt{2}}{4} > \frac{3}{4}$$

“Tsirlason bound for non-causal correlations” ??

This process cannot be realized as a probabilistic mixture of causally ordered situations!

# Causally non-separable situation

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} (\sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2}) \right]$$



The probability of success is

$$p_{succ} = \frac{2 + \sqrt{2}}{4} > \frac{3}{4}$$

“Tsirlason bound for non-causal correlations” ??

This process cannot be realized as a probabilistic mixture of causally ordered situations!

# A causally non-separable example



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



# A causally non-separable example

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2} \quad x, a = \pm 1$

Repreparation      Measurement  
    ↓                      ↓



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$





# A causally non-separable example

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2}$   $x, a = \pm 1$

Repreparation
Measurement

↙
↘

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} \left[ W^{A_1 A_2 B_1 B_2} \left( |z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2} \right) \right]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



# A causally non-separable example

Repreparation      Measurement

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2} \quad x, a = \pm 1$

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} [W^{A_1 A_2 B_1 B_2} (|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2})]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_x^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



$\langle z_{\pm} | \sigma_z | z_{\pm} \rangle = \pm 1$

Not seen by Bob

# A causally non-separable example

Repreparation      Measurement

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2}$        $x, a = \pm 1$

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} [W^{A_1 A_2 B_1 B_2} (|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2})]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_x^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$$\langle z_a | \sigma_z | z_a \rangle = a$$

Chosen by Alice

$$\langle z_{\pm} | \sigma_z | z_{\pm} \rangle = \pm 1$$

Not seen by Bob



# A causally non-separable example

Repreparation      Measurement

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2} \quad x, a = \pm 1$

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} [W^{A_1 A_2 B_1 B_2} (|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2})]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_x^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$$\langle z_a | \sigma_z | z_a \rangle = a$$

Chosen by Alice

$$\langle z_{\pm} | \sigma_z | z_{\pm} \rangle = \pm 1$$

Not seen by Bob



# A causally non-separable example

Repreparation      Measurement

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2} \quad x, a = \pm 1$

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} [W^{A_1 A_2 B_1 B_2} (|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2})]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_x^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$$\langle z_a | \sigma_z | z_a \rangle = a$$

Chosen by Alice

$$\langle z_{\pm} | \sigma_z | z_{\pm} \rangle = \pm 1$$

Not seen by Bob



➔ Bob receives the state:  $\widetilde{W}^{B_1 B_2} = \frac{1}{2} \left( \mathbb{1} + a \frac{1}{\sqrt{2}} \sigma_z^{B_2} \right)$

# A causally non-separable example

Repreparation      Measurement

Alice's CP map:  $|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2}$        $x, a = \pm 1$

Bob effectively „sees“:

$$\widetilde{W}^{B_1 B_2} = \sum_x \text{Tr}_{A_1 A_2} [W^{A_1 A_2 B_1 B_2} (|z_a\rangle\langle z_a|^{A_1} \otimes |z_x\rangle\langle z_x|^{A_2})]$$



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_x^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$$\langle z_a | \sigma_z | z_a \rangle = a$$

Chosen by Alice

$$\langle z_{\pm} | \sigma_z | z_{\pm} \rangle = \pm 1$$

Not seen by Bob



➡ Bob receives the state:  $\widetilde{W}^{B_1 B_2} = \frac{1}{2} (\mathbb{1} + a \frac{1}{\sqrt{2}} \sigma_z^{B_2})$

If Bob wants to read ( $b' = 1$ ), he measures in the z basis and achieves

$$P(y = a | b' = 1) = \frac{2 + \sqrt{2}}{4}$$

# A causally non-separable example



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



# A causally non-separable example

If Bob wants to send ( $b^c = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

← Repreparation
← Measurement



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$





# A causally non-separable example

If Bob wants to send ( $b^c = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

← Repreparation
← Measurement



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \otimes \sigma_z^{B_2} + \sigma_z^{A_2} \otimes \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$$\langle x_{\pm} | \sigma_z | x_{\pm} \rangle = 0$$

Not seen by Alice



# A causally non-separable example

If Bob wants to send ( $b^c = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

← Repreparation
← Measurement



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



$\langle x_{\pm} | \sigma_z | x_{\pm} \rangle = 0$   
 Not seen by Alice

The encoding correlated with the detection result



Alice receives the state  $\widetilde{W}^{A_1 A_2} = \frac{1}{2} \left( \mathbb{1} + b \frac{1}{\sqrt{2}} \sigma_z^{A_2} \right)$

# A causally non-separable example

If Bob wants to send ( $b' = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

Repreparation
Measurement

$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_1} \sigma_x^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

$\langle x_{\pm} | \sigma_z | x_{\pm} \rangle = 0$   
 Not seen by Alice

The encoding correlated with the detection result

➔ Alice receives the state  $\widetilde{W}^{A_1 A_2} = \frac{1}{2} \left( \mathbb{1} + b \frac{1}{\sqrt{2}} \sigma_z^{A_2} \right)$

She can read Bob's sent bit with probability

$$P(x = b | b' = 0) = \frac{2 + \sqrt{2}}{4}$$

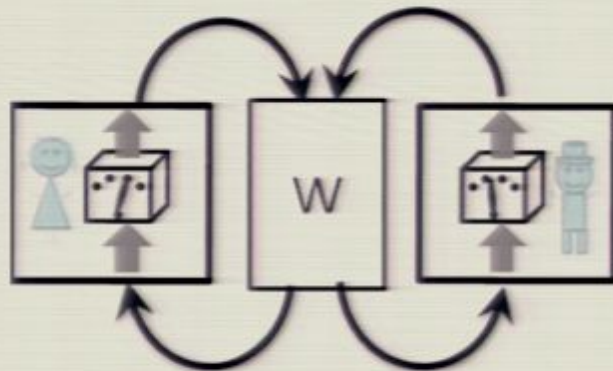
# Where to look for non-causal processes?

# Where to look for non-causal processes?

1. **Closed time-like curves?**: The entire process  $W$  is such that the information is sent back in time through a noisy channel.

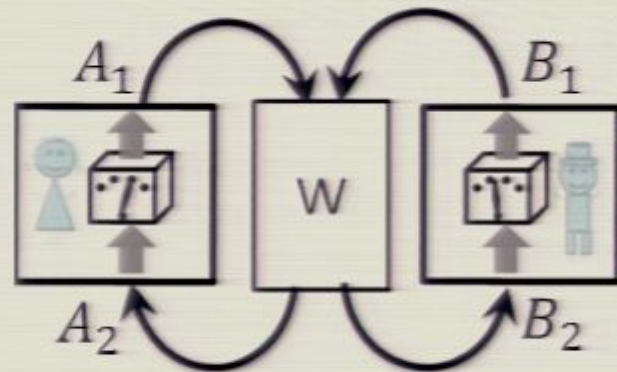
# Where to look for non-causal processes?

1. **Closed time-like curves?**: The entire process  $W$  is such that the information is sent back in time through a noisy channel.



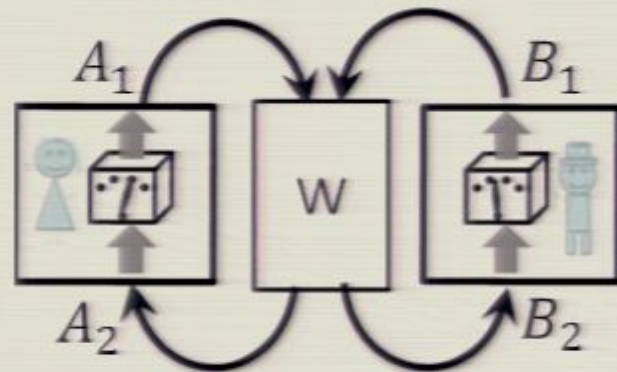
# Where to look for non-causal processes?

1. **Closed time-like curves?**: The entire process  $W$  is such that the information is sent back in time through a noisy channel.



# Where to look for non-causal processes?

1. **Closed time-like curves?**: The entire process  $W$  is such that the information is sent back in time through a noisy channel.



1. **“Superpositions of space-time”?**



# Conclusions

- [Not shown]: In the classical limit all correlations are causally ordered
- Unified framework for both signalling (“time-like”) and non-signalling (“space-like”) quantum correlations
- Situations where a causal ordering between laboratory operations is not definite → Suggests that causal ordering might not be a necessary element of quantum theory
- What one needs to do in the lab to realize the “processes”?  
New resource for quantum information processing?

Borivoje Dakic



Fabio Costa



Igor Pikovski



Magdalena Zych



Ognyan Oreshkov  
(U. Brüssels)



C.B.

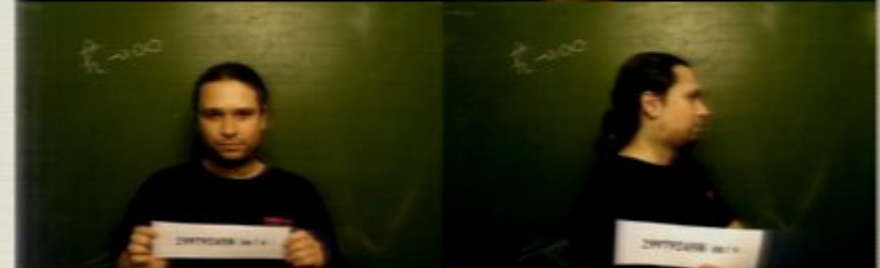


Borivoje Dakic



Poster! →

Fabio Costa



Igor Pikovski



Magdalena Zych



Ognyan Oreshkov  
(U. Brüssels)



C.B.



Thank you for  
your attention

Borivoje  
Dakic



Poster! →

Fabio  
Costa



Igor  
Pikovski



Magdalena  
Zych



Ognyan  
Oreshkov  
(U. Brüssels)



C.B.



# A causally non-separable example

If Bob wants to send ( $b^c = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

← Repreparation
← Measurement



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \otimes \sigma_z^{B_2} + \sigma_z^{A_2} \otimes \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$



$\langle x_{\pm} | \sigma_z | x_{\pm} \rangle = 0$   
 Not seen by Alice

The encoding correlated with the detection result

# A causally non-separable example

If Bob wants to send ( $b^c = 0$ )

Bob's CP map:  $|z_{by}\rangle\langle z_{by}|^{B_1} \otimes |x_y\rangle\langle x_y|^{B_2}$   $y, b = \pm 1$

Repreparation
Measurement



$$W^{A_1 A_2 B_1 B_2} = \frac{1}{4} \left[ \mathbb{1} + \frac{1}{\sqrt{2}} \left( \sigma_z^{A_1} \sigma_z^{B_2} + \sigma_z^{A_2} \sigma_z^{B_1} \sigma_x^{B_2} \right) \right]$$

