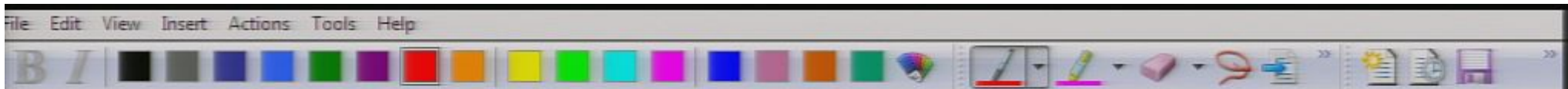


Title: Vectors and affine forms, straight and twisted

Date: May 24, 2011 04:00 PM

URL: <http://pirsa.org/11050024>

Abstract: This is a geometric tutorial about straight and twisted vectors and forms (ie, de Rham currents) leading to some wild thoughts about the EM field as a *thing*, ie with properties similar to a piece of matter; and to some even wilder thoughts about a metric-free GR.



Vectors and affine forms, straight and twisted

with examples of their physically intuitive meaning

P.G.L. Porta Mana

PI

24 May 2011



Vectors and affine forms, straight and twisted

with examples of their physically intuitive meaning



P.G.L. Porta Mana

PI

24 May 2011



Affine spaces

- Parallelism
- No absolute length
- No angles
- Relative length, but only along the same direction



same shape
in affine space





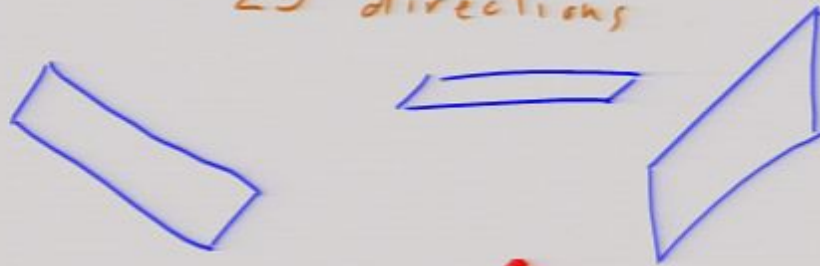
Directions and complement spaces

mD direction = mD subspace (without a definite position)

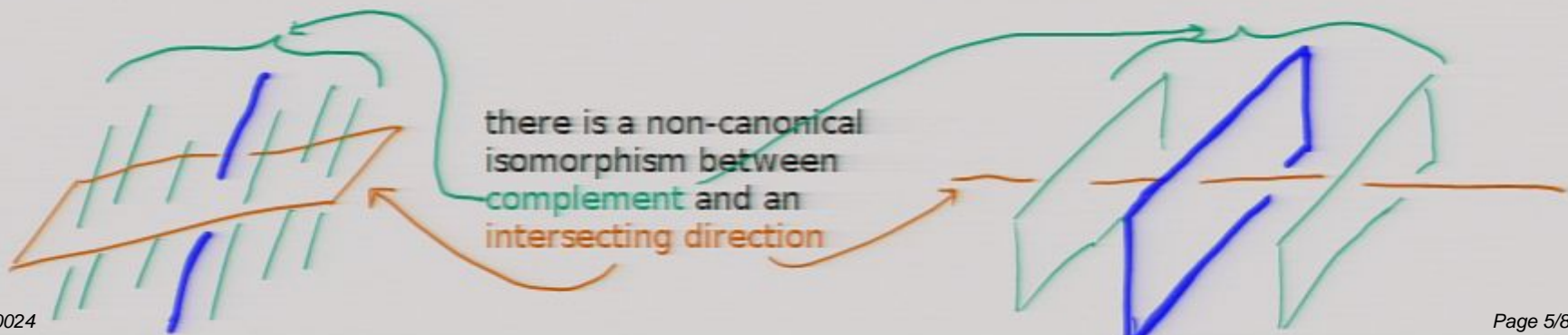
1D directions



2D directions



$(n-m)D$ complement space = space of parallel mD directions





Ordinary vectors

1D direction



magnitude



orientation



Generalize:

n D direction

magnitude:

- on direction
- or on complement

orientation:

- on direction
- or on complement



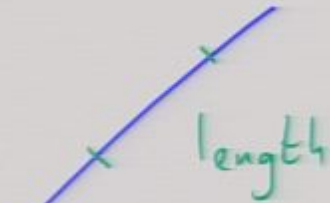


1D

direction



magnitude



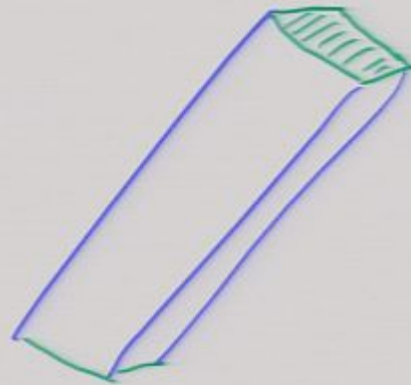
orientation



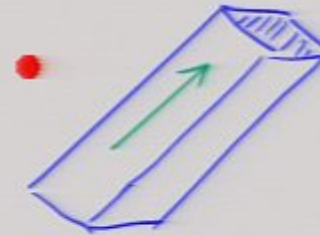
'forces'
(Maxwell, 1873)



area



'fluxes'
(Maxwell, 1873)



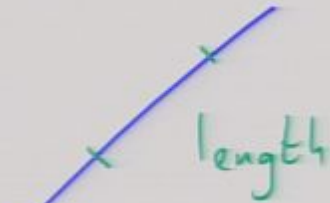


1D

direction



magnitude



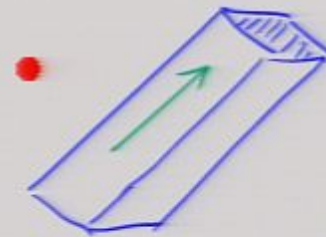
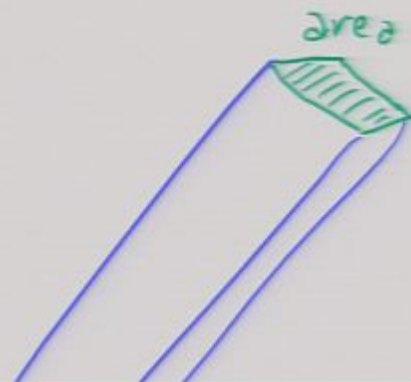
orientation



'forces'
(Maxwell, 1873)



area



'fluxes'
(Maxwell, 1873)



4

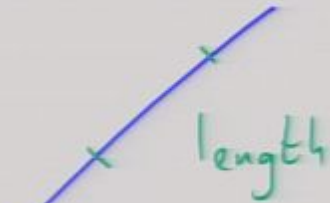


1D

direction



magnitude



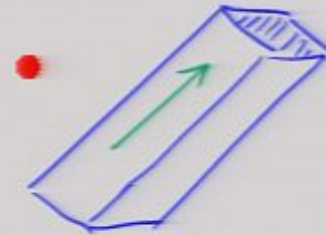
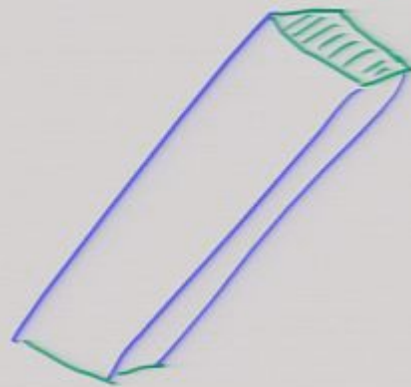
orientation



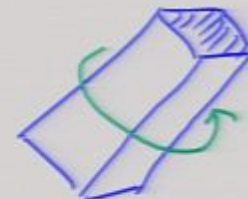
'forces'
(Maxwell, 1873)



area



'fluxes'
(Maxwell, 1873)





2D

direction



magnitude



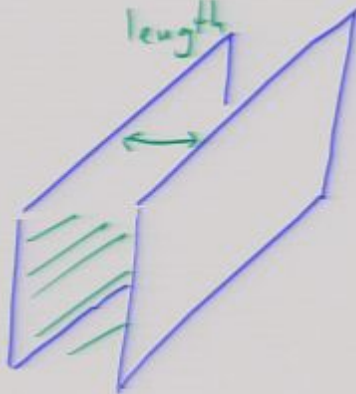
orientation



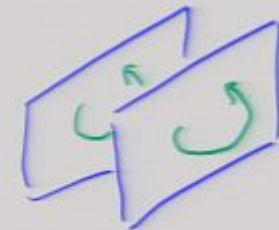
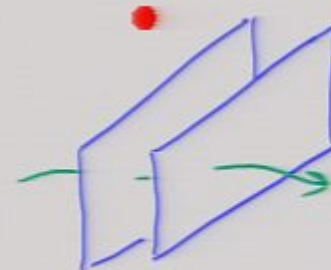
'fluxes'



length



'forces'





OD

direction



magnitude

$|a|$
number



volume

orientation

$-|a|$

$\partial |a|$

oriented
scalar

$\left. \begin{matrix} 2 \\ 1 \\ 6 \end{matrix} \right\}$ screw
senses



density





OD

direction



magnitude

$|a|$
number



volume

orientation

$-|a|$

oriented
scalar

$\partial |a|$

$\left. \begin{matrix} \partial \\ 1 \\ 6 \end{matrix} \right\}$ screw
sense



density



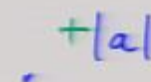
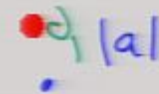
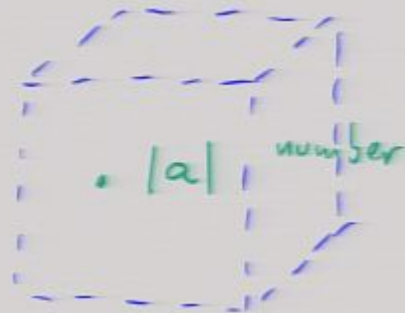
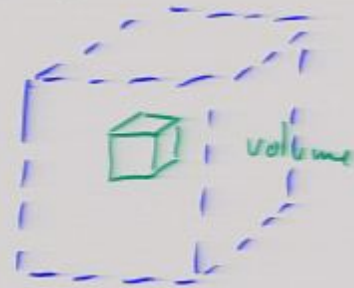
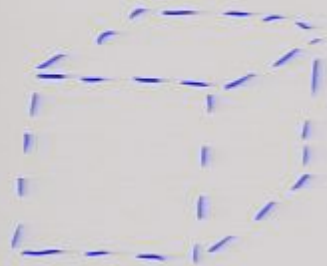


3D

direction

magnitude

orientation



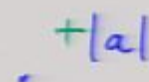
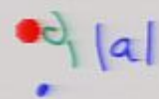
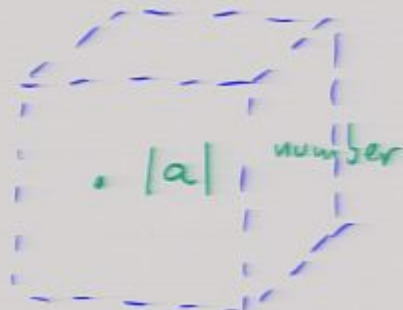
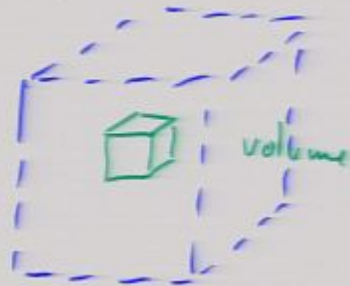
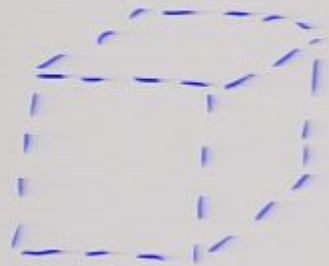


3D

direction

magnitude

orientation





if magnitude is on:

- direction = *vector*
- complement = *form (covector)*

dimension of magnitude:

1-vector, *2*-vector (bivector), etc.

1-form, *2*-form, etc.

if orientation is on:

- direction = *straight (even)*
- complement = *twisted (odd)*



2D

direction



magnitude



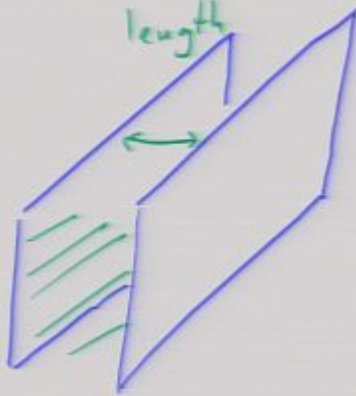
orientation



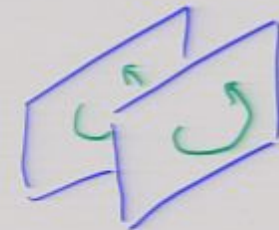
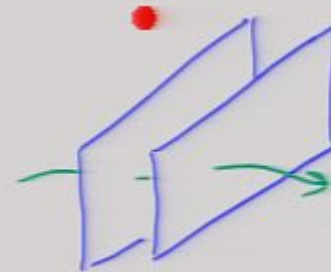
'fluxes'



length



'forces'





OD

direction



magnitude

 $|a|$
number


volume

orientation

 $-|a|$
 $\partial |a|$
oriented
scalar
 $\left. \begin{matrix} \partial \\ 1 \\ 6 \end{matrix} \right\}$ screw
sense


density





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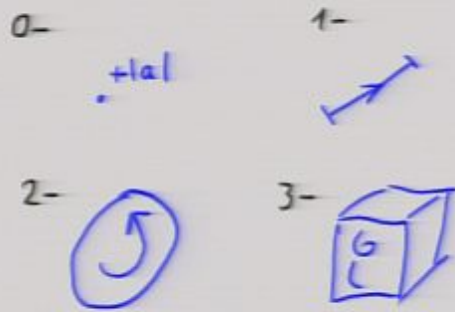
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- complement = *twisted (odd)*



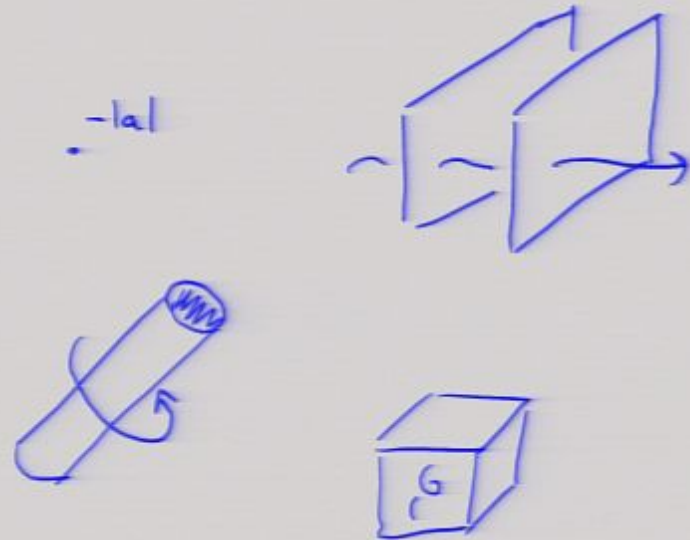
VECTORS

straight



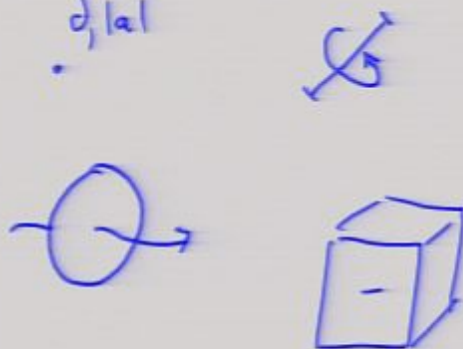
FORMS

-|a|

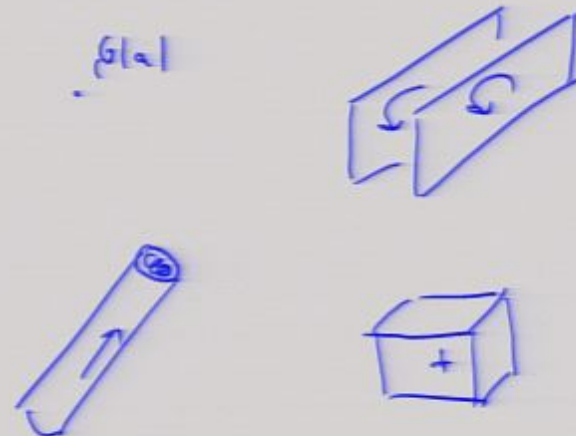


twisted

$\partial|a|$



$\partial|a|$







forms and vectors of same dimension and orientation
act on each other to give scalars

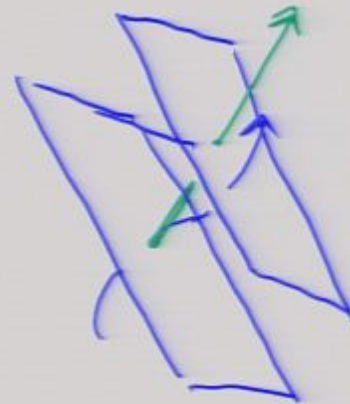
1-form



1-vector

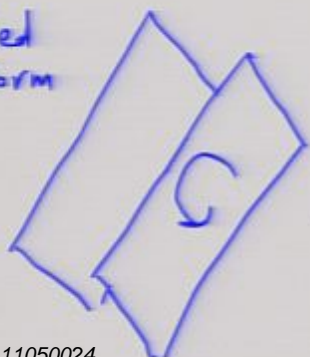


=

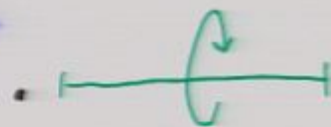


= +2 (eg, work)

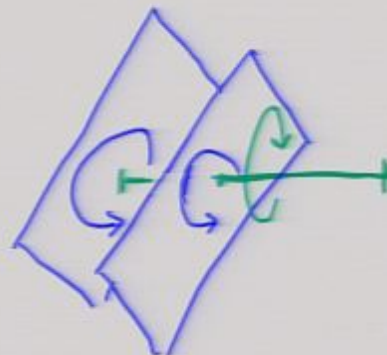
twisted
1-form



twisted
1-vector



=



= -2.5



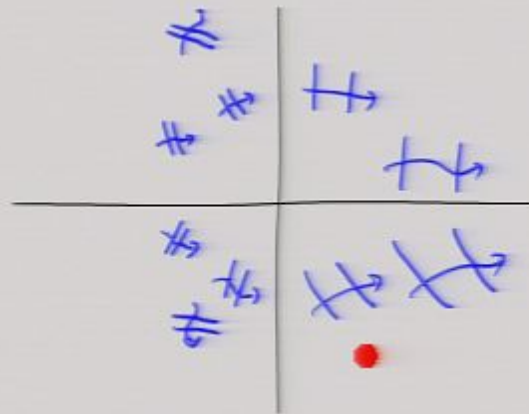
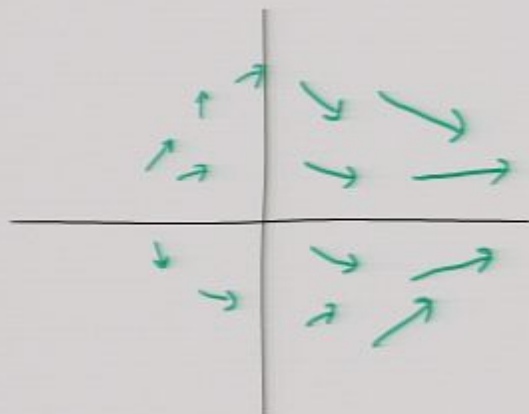
z-form \cdot z-vector = -4 (eg, magnetic flux)

twisted z-form \cdot twisted z-vector = $+1$

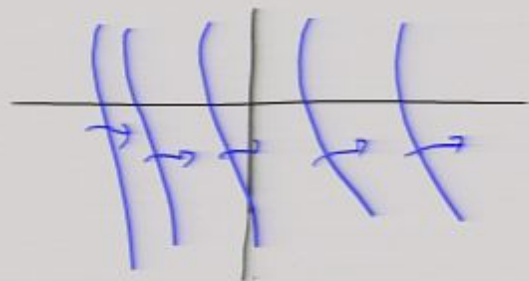
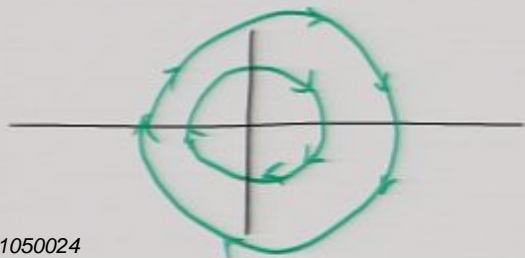


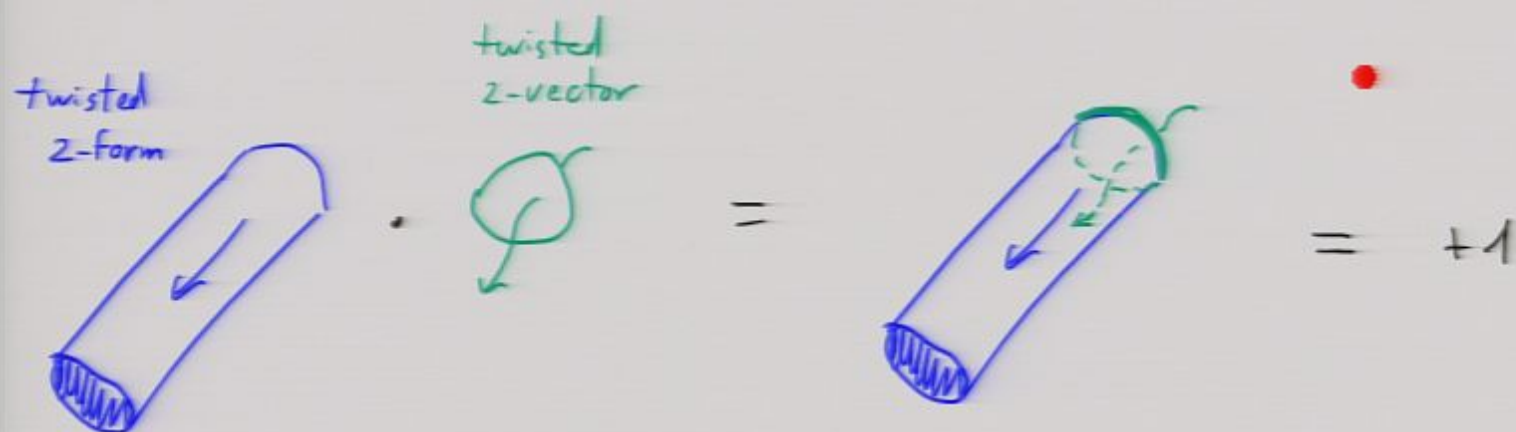
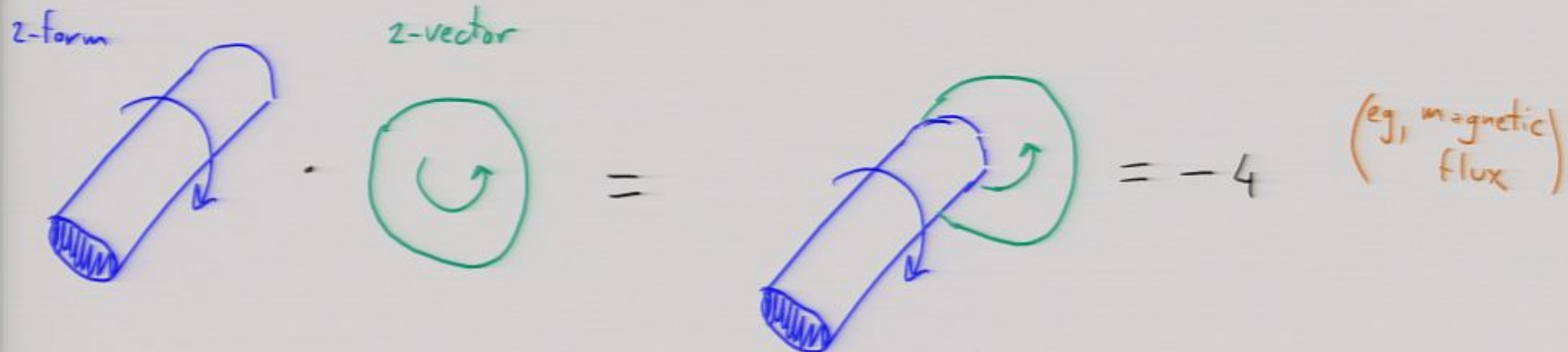
Vector fields and differential forms

On a differential manifold we can associate a vector or form to each tangent space: **vector field** or **differential-form field**



these fields may be tangent to a submanifold (integral manifold)

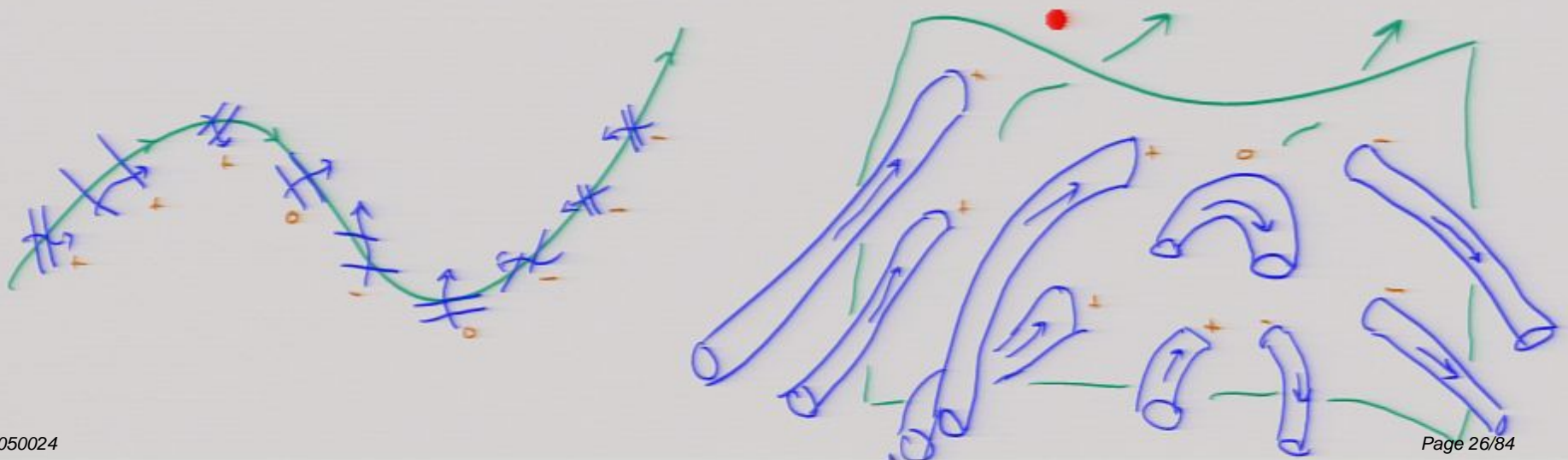






Integration

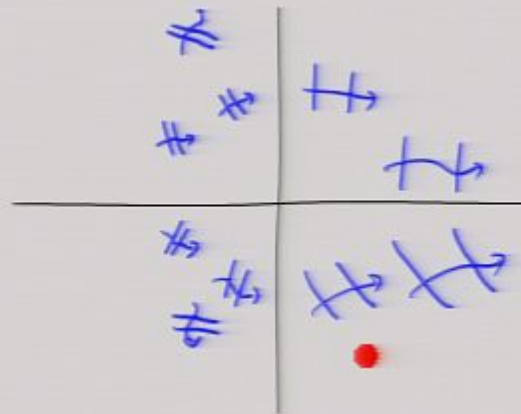
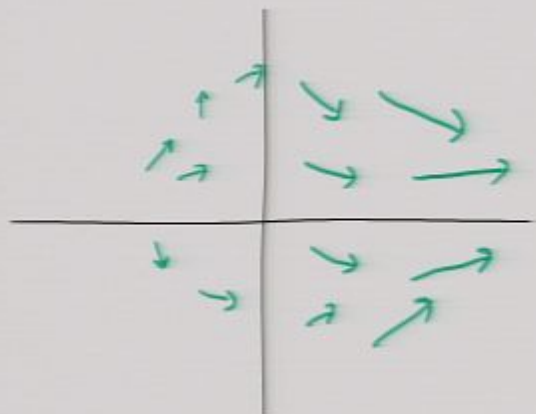
- Choose an m -form field, choose an m -submanifold
- at each point, apply the m -form to the tangent m -vector
- sum up the scalars
- that's the **integral** of the **form** on the **submanifold**



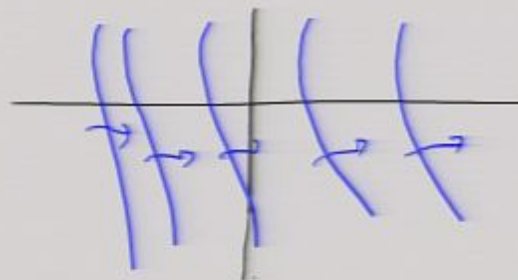
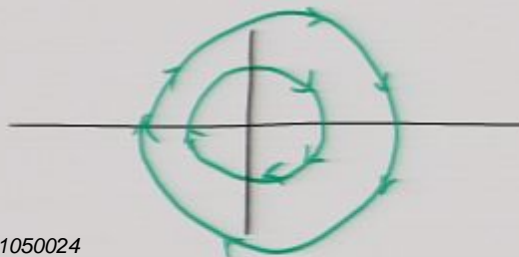


Vector fields and differential forms

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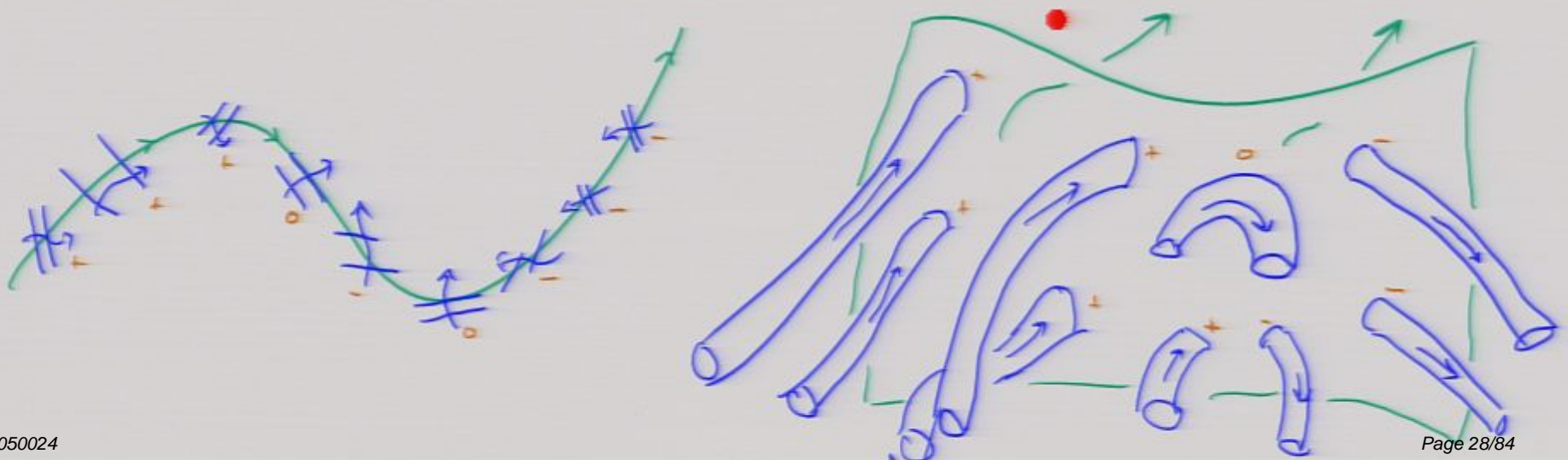
these fields may be tangent to a submanifold (integral manifold)





Integration

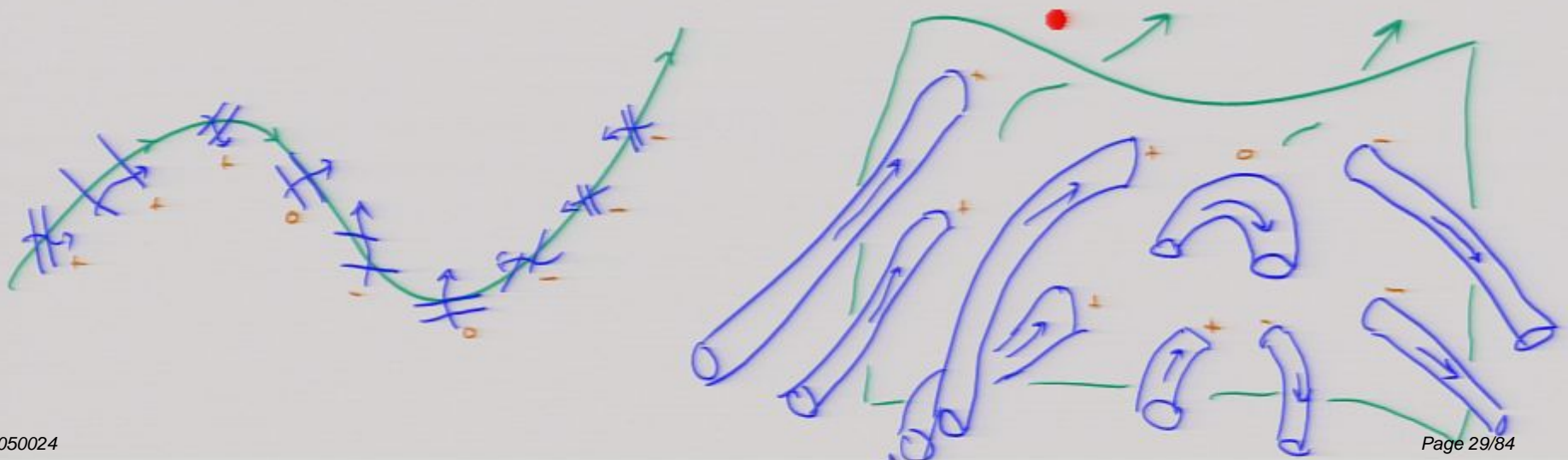
- Choose an m -form field, choose an m -submanifold
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Integration

- Choose an m -form field, choose an m -submanifold
- at each point, apply the m -form to the tangent m -vector
- sum up the scalars
- that's the **integral** of the **form** on the **submanifold**





Note: none of these concepts and operations
involves a **metric!**

Only topology



Algebraically:

vectors: $\sum a^i \partial_{x^i}$, $\sum a^{ij} \partial_{x^i} \wedge \partial_{x^j}$, ...

forms: $\sum b_i dx^i$, $\sum b_{ij} dx^i \wedge dx^j$, ...

twisted forms: $\sum c_i d\tilde{x}^i$

\sim = 'twisting operator' introduced by Burke (J. Math. Phys., 1983)



Differential forms and physical intuition

Our representation of matter: something that

- is associated to a (small) bounded 3D region of space, eg a ball
- can be marked and followed around
- doesn't disappear
- We can count how many 'balls' are there inside a 3D region
- we can count how many 'balls' cross some 2D surface (in a given time)

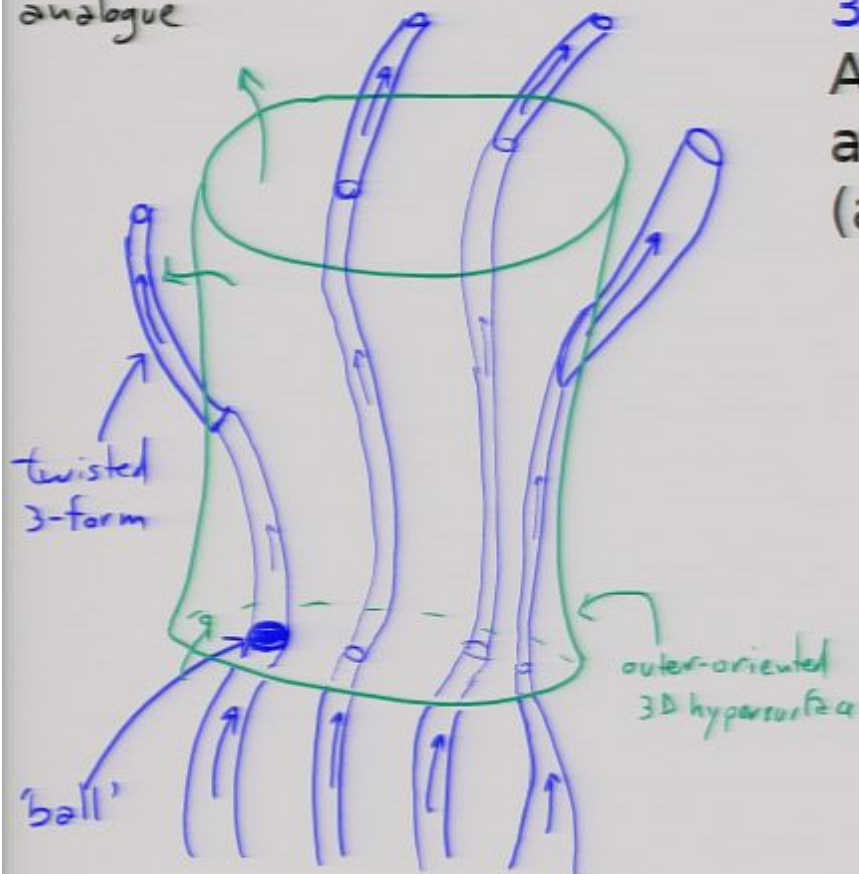


'The ball that was then here, is now there...'



Matter/mass (and charge) is a twisted 3-form in spacetime

3D spacetime
analogue



3-form in **spacetime** = 'hypertubes'

A 3D observer sees them
as 'balls' moving around in 3D space
(and changing shape)

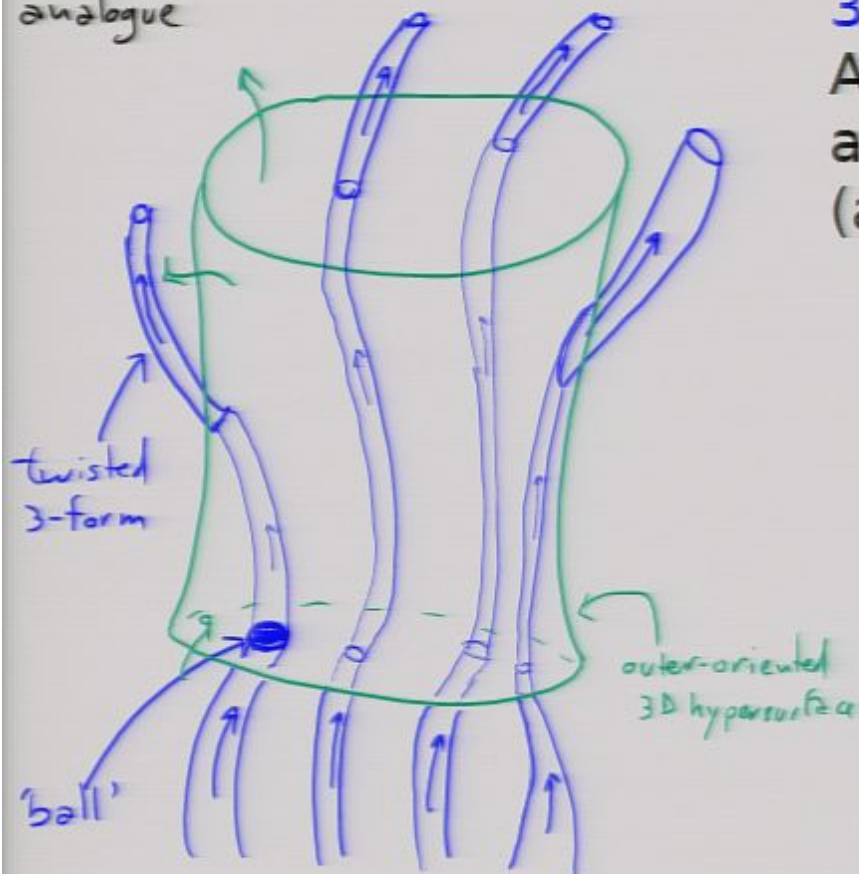
balls initially in 3D region
+ balls entering 2D surface
- balls exiting 2D surface
- balls finally in 3D region
= 0

This property =
the twisted 3-form is **closed**
(its tubes never end)



Matter/mass (and charge) is a twisted 3-form in spacetime

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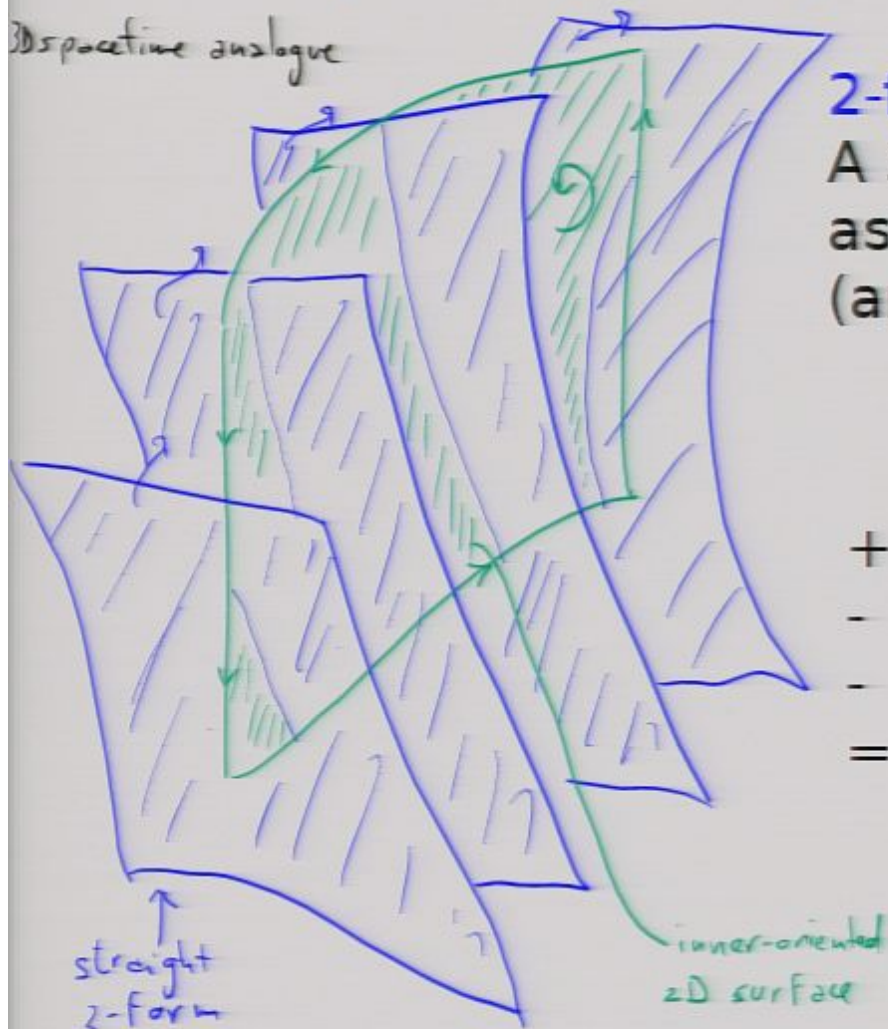
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EM-field (Faraday tensor) is a straight 2-form in spacetime

3D spacetime analogue



2-form in spacetime = 'hypersurfaces'

A 3D observer sees them
as 'tubes' moving around in 3D space
(and changing shape)

tubes initially intersect 2D surface

+ tubes crossing into 1D edge

- tubes crossing out of 1D edge

- tubes finally intersect 3D surface

= 0

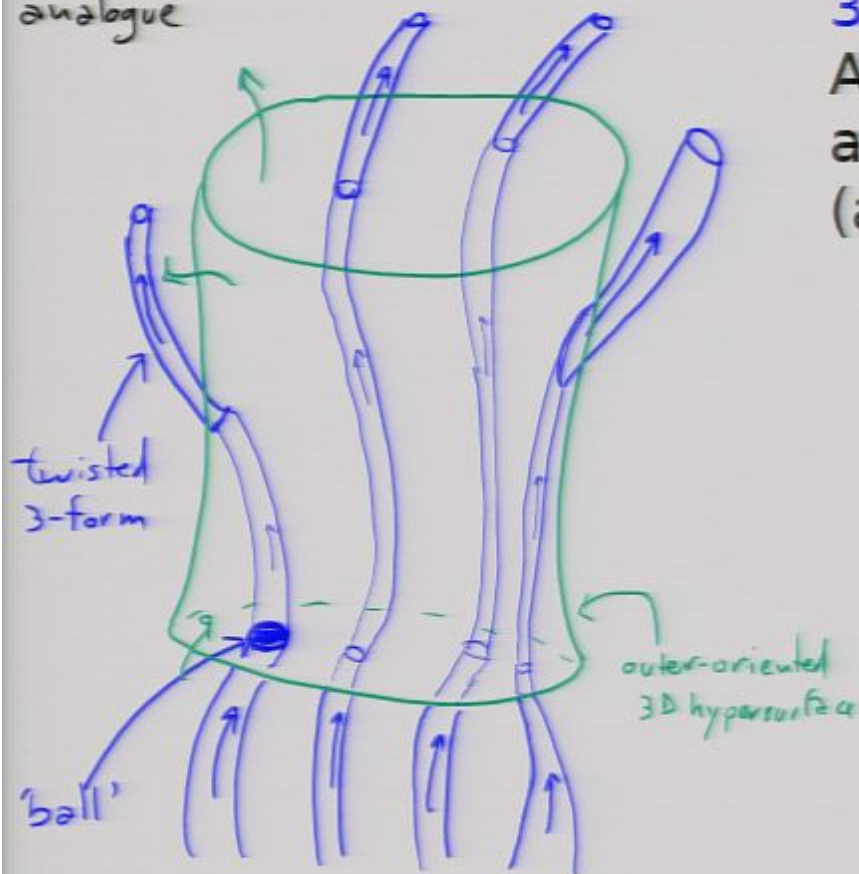
This property =

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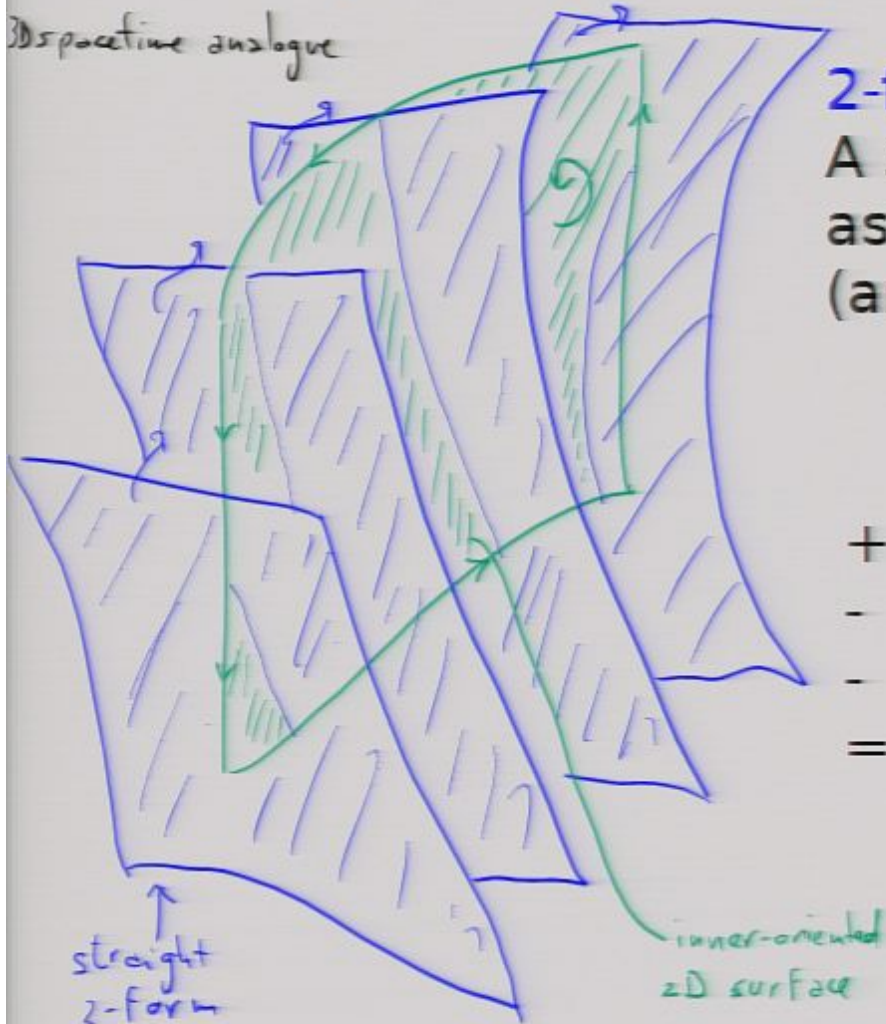
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$$d\omega = 0$$



EM-field (Faraday tensor) is a straight 2-form in spacetime

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New Page

Insert/Remove Space

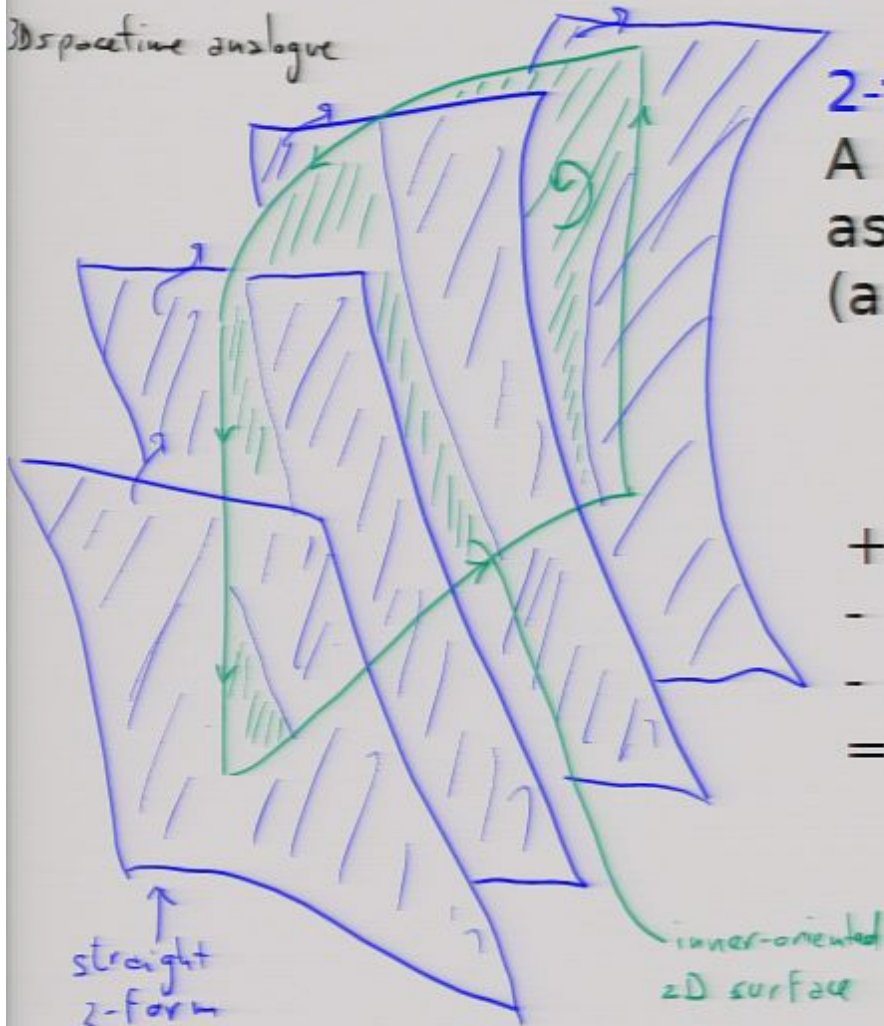
Text Box

Picture...

Flag

(Faraday tensor) is a straight 2-form in spacetime

3D spacetime analogue

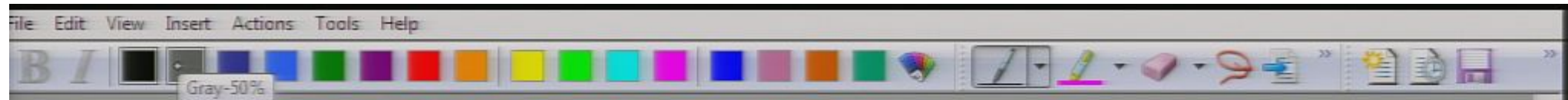


2-form in spacetime = 'hypersurfaces'

A 3D observer sees them
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(and changing shape)

- + tubes initially intersect 2D surface
- + tubes crossing into 1D edge
- tubes crossing out of 1D edge
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- = 0

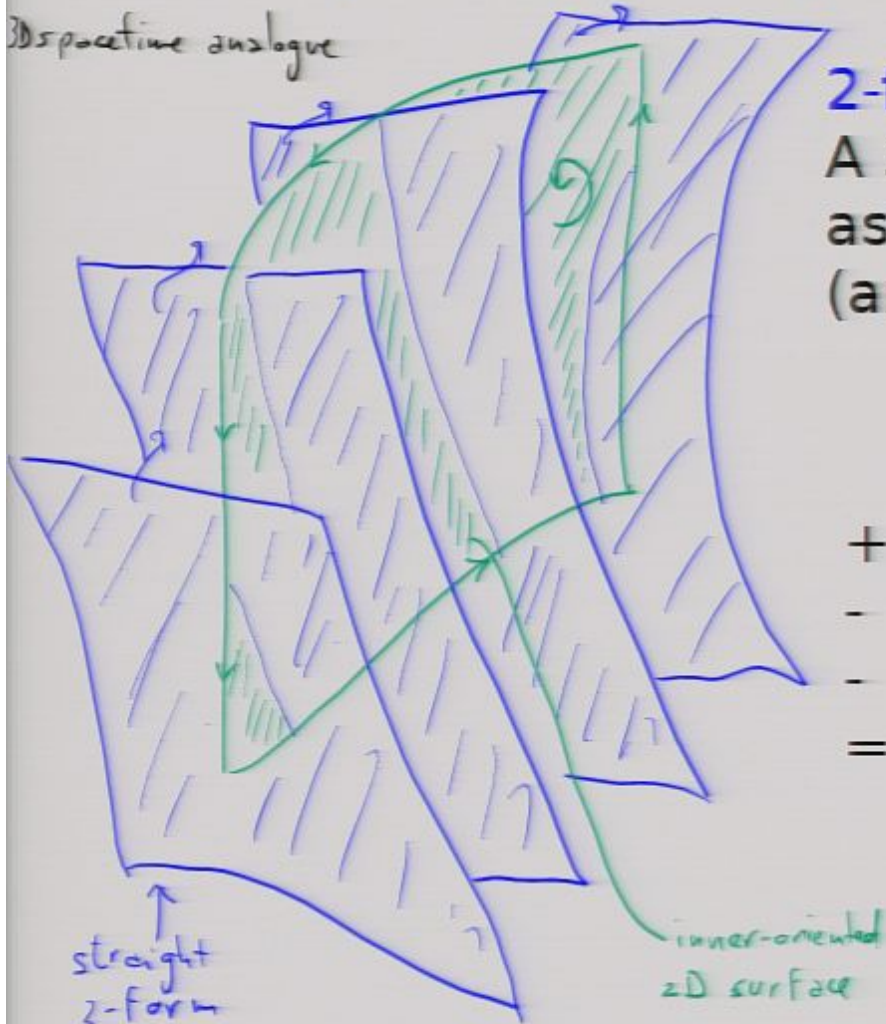
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EM-field (Faraday tensor) is a straight 2-form in spacetime

3D spacetime analogue



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- doesn't disappear
- We can count how many 'balls' are there inside a 3D region
- we can count how many 'balls' cross some 2D surface (in a given time)

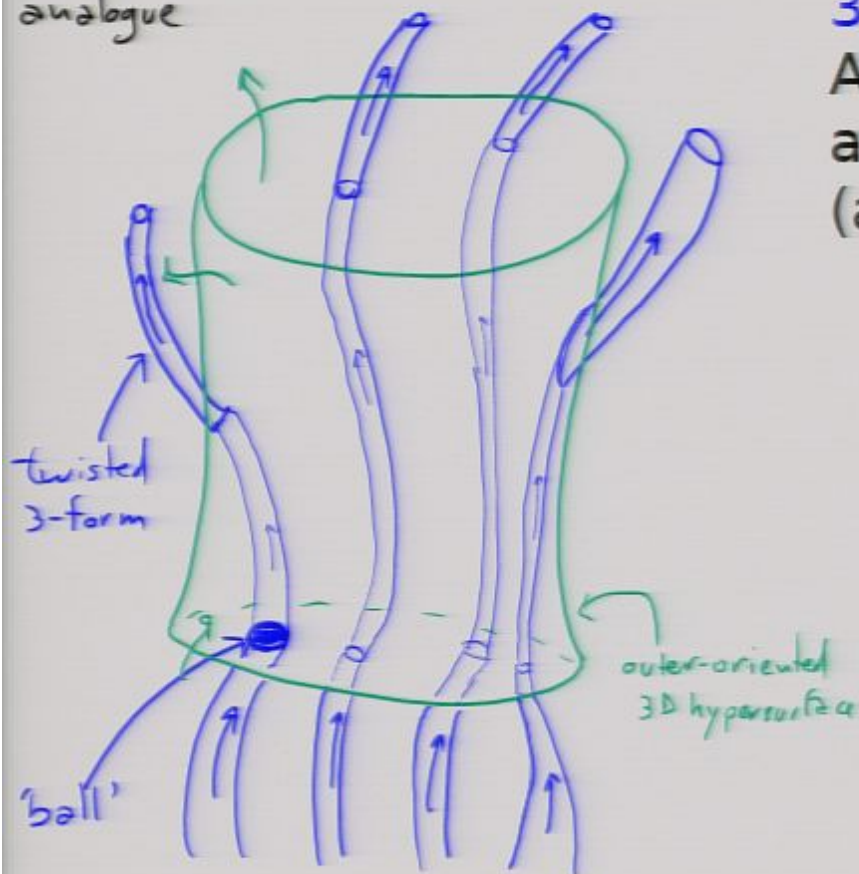


'The ball that was then here, is now there...'



Matter/mass (and charge) is a twisted 3-form in spacetime

3D spacetime
analogue



3-form in **spacetime** = 'hypertubes'

A 3D observer sees them
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(and changing shape)

- + balls initially in 3D region
- + balls entering 2D surface
- balls exiting 2D surface
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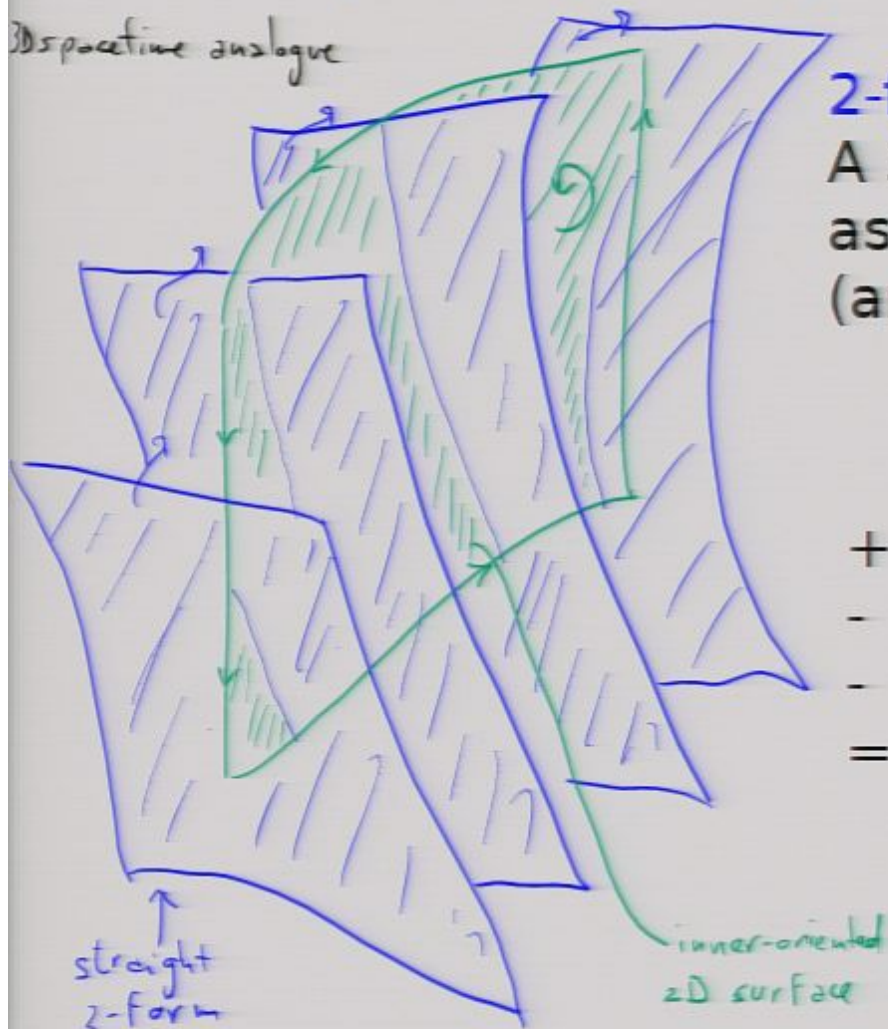
This property =
the twisted 3-form is **closed**
(its tubes never end)

$$d\omega = 0$$



EM-field (Faraday tensor) is a straight 2-form in spacetime

3D spacetime analogue



2-form in spacetime = 'hypersurfaces'

A 3D observer sees them
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tubes initially intersect 2D surface

+ tubes crossing into 1D edge

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= 0

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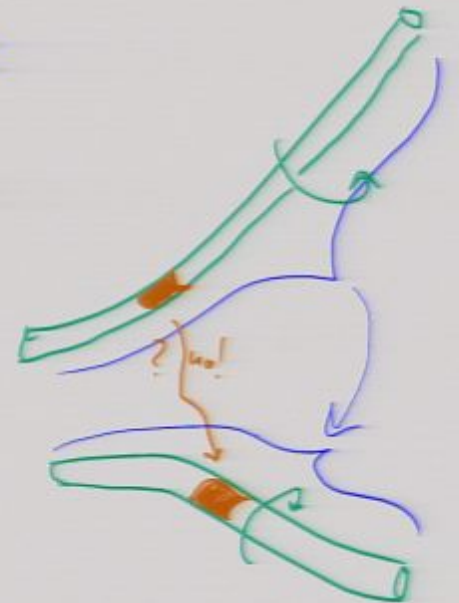
- We can count how many 'tubes' intersect a 2D surface
- we can count how many 'tubes' cross a 1D edge

The EM field can be thought of as something that

- is associated to a (thin) tubular region of space
- can be marked and followed around
- doesn't disappear

'The tube that was then here, is now there...'

- The whole tube can be identified, but not parts of it!





*OK, fine, this may have some pedagogical use
and may help visualization...*

...but then?



- Can we generalize the concept of force, from something applied to points to something applied to lines?

This idea is not so absurd:

- Ericksen (*J. Elasticity*, 2007):
'...the idea that electromagnetic fields can sustain forces'.
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Force not as a form-valued 2-form,
but as a form-valued 3-form...



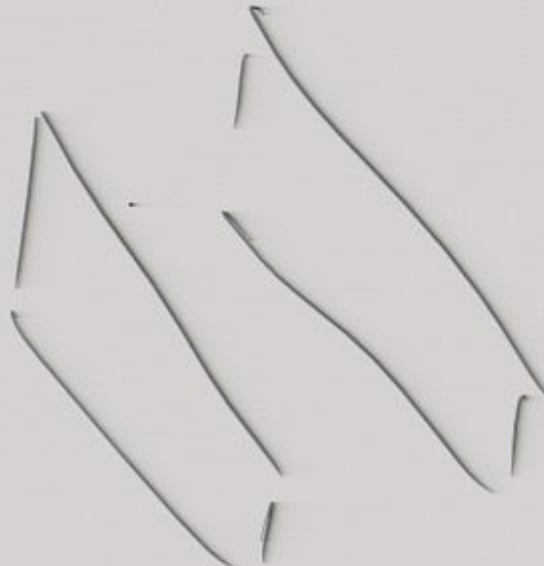
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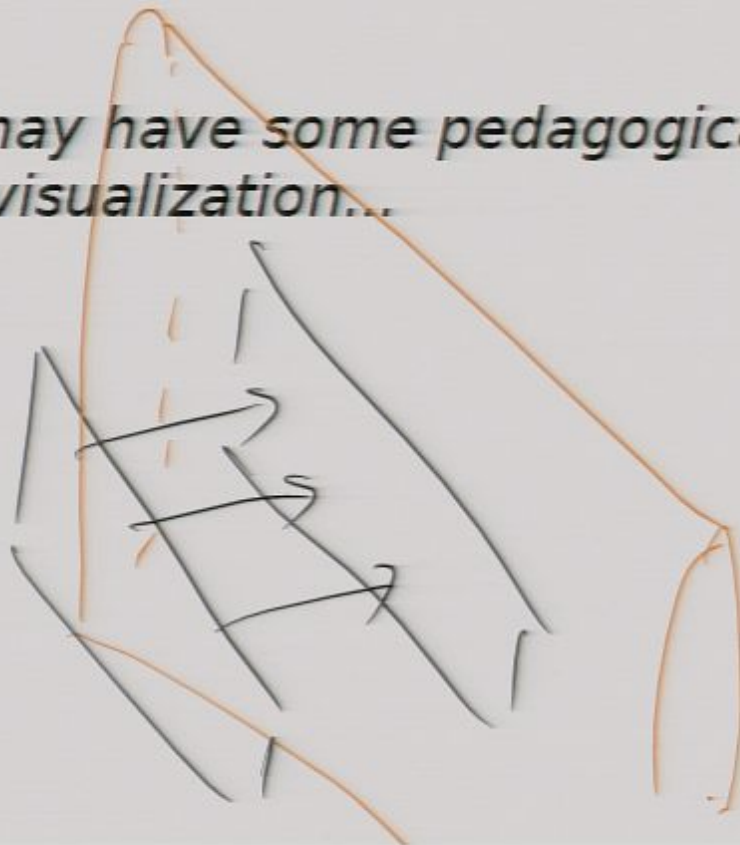
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Kotler 1820

v2



Kotler 1820
van Dantzig
Truesdell



Kotler 1820
van Dantzig
Truesdell & Toupin
Hehl
/



Kotler 1820
van Dantzig
Truesdell & Toupin

Hehl
Bateman

Q



Kotler 1820
van Dantzig
Truesdell & Toupin
Hehl
Bateman

do

Q tw. 3-form
charge-current



Kotler 1920
van Dantzig
Truesdell & Toupin
Hehl
Bateman

$dQ=0 \leftarrow$ cons. of charge
 Q tw. 3-form
charge-current

$$dQ=0$$



Kotler 1920
 van Dantzig
 Truesdell & Toupin
 Hehl
 Bateman

$dQ=0 \leftarrow$ cons. of charge

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 charge-current

$dQ=0 \Rightarrow \exists M$ 2-form

$$Q = dM$$

(g, \cdot)



Kotler 1920
 van Dantzig
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F \nwarrow z-form
 \swarrow

$dQ=0 \leftarrow$ cons. of charge

Q tw. 3-form
 charge-current

$dQ=0 \Rightarrow \exists M$ z-form

$$\begin{array}{ccc}
 & Q = dM & \\
 \nearrow & & \nwarrow \\
 (P, J) & & (D, A)
 \end{array}$$



Kotler 1920
van Dantzig
Truesdell & Toupin
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$$dF=0$$

F 2-form
 (E, B)



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$$dQ=0 \Rightarrow \exists M \quad \text{2-form}$$

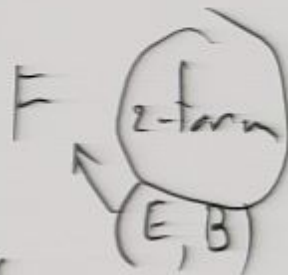
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$$F = dA$$

↑
vector
potential

$$Q = dM$$

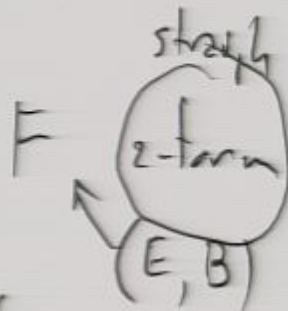
↑ ↑
(ρ, J) (D, A)



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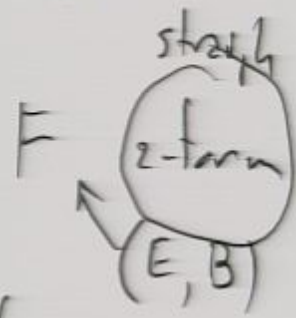
↑
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$$\lambda(F) -$$



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$$\lambda(F) = M \rightarrow * \rightarrow \text{conformal structure}$$



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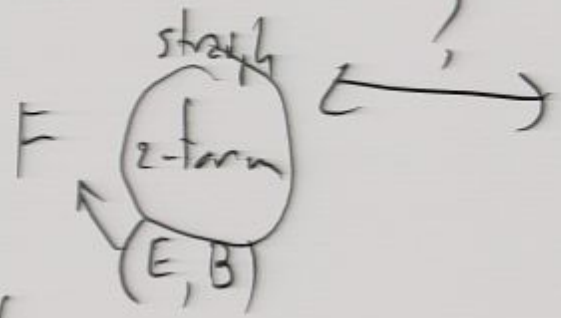
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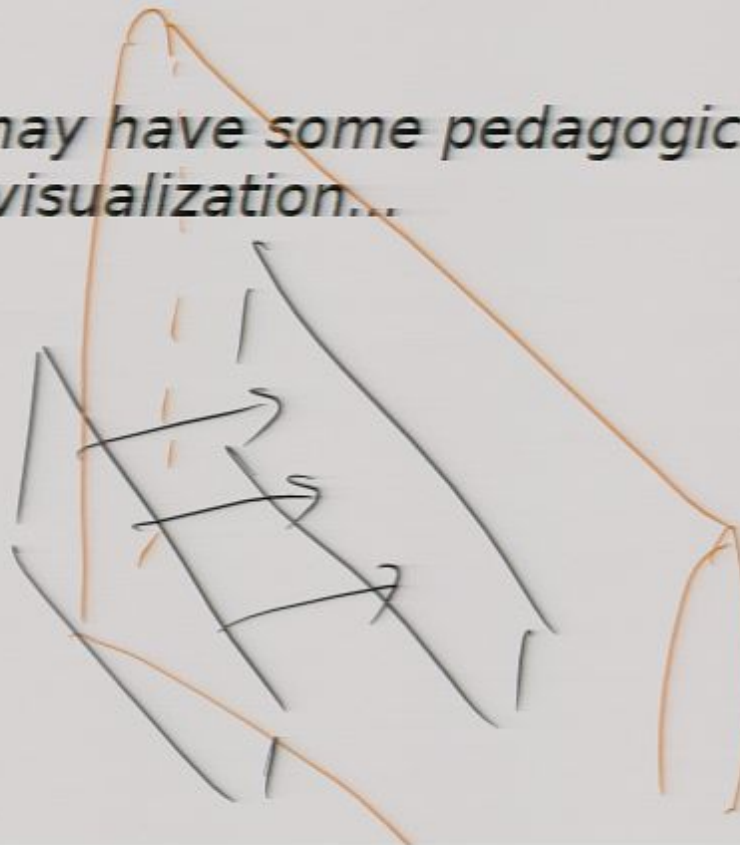
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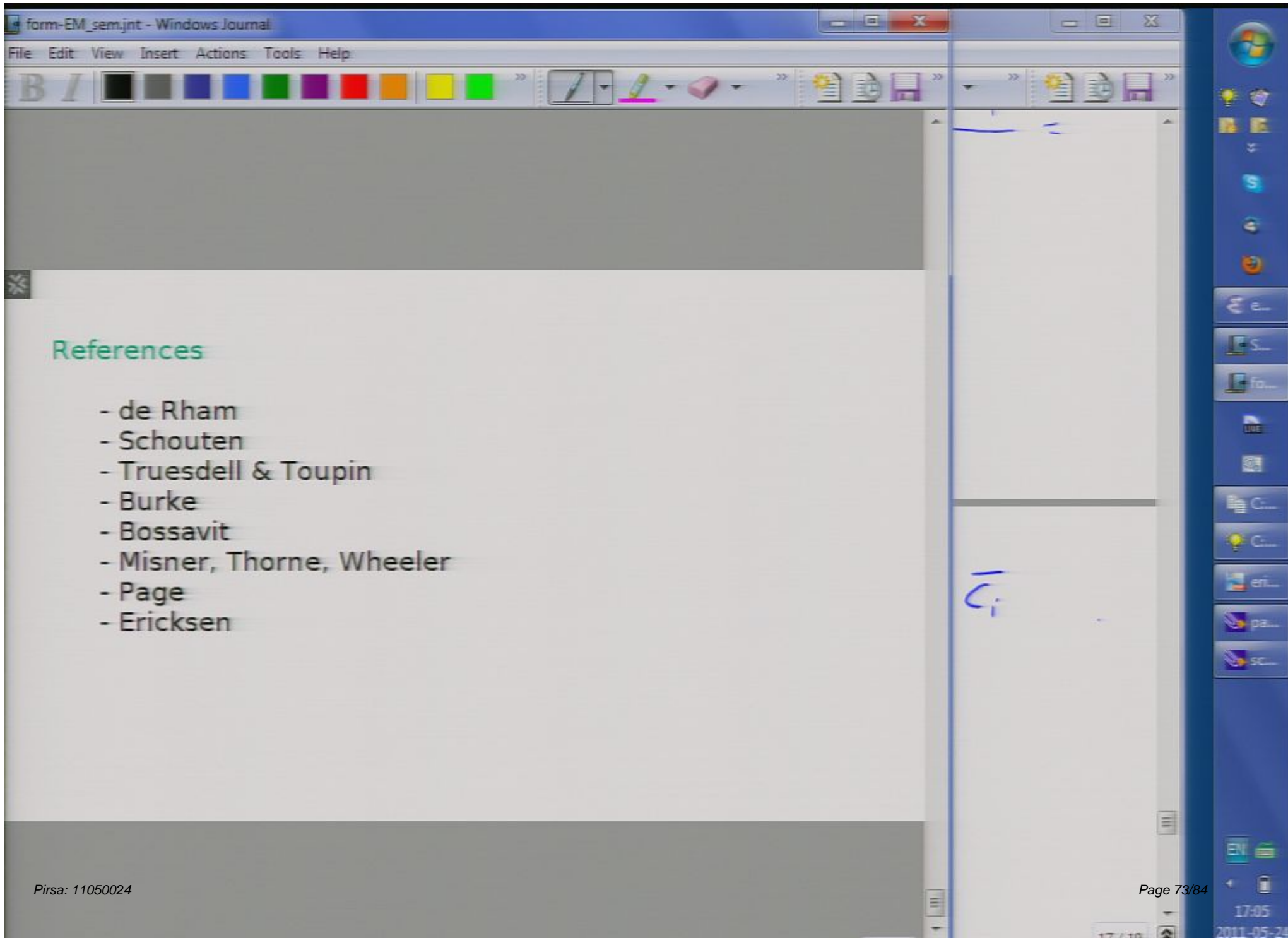
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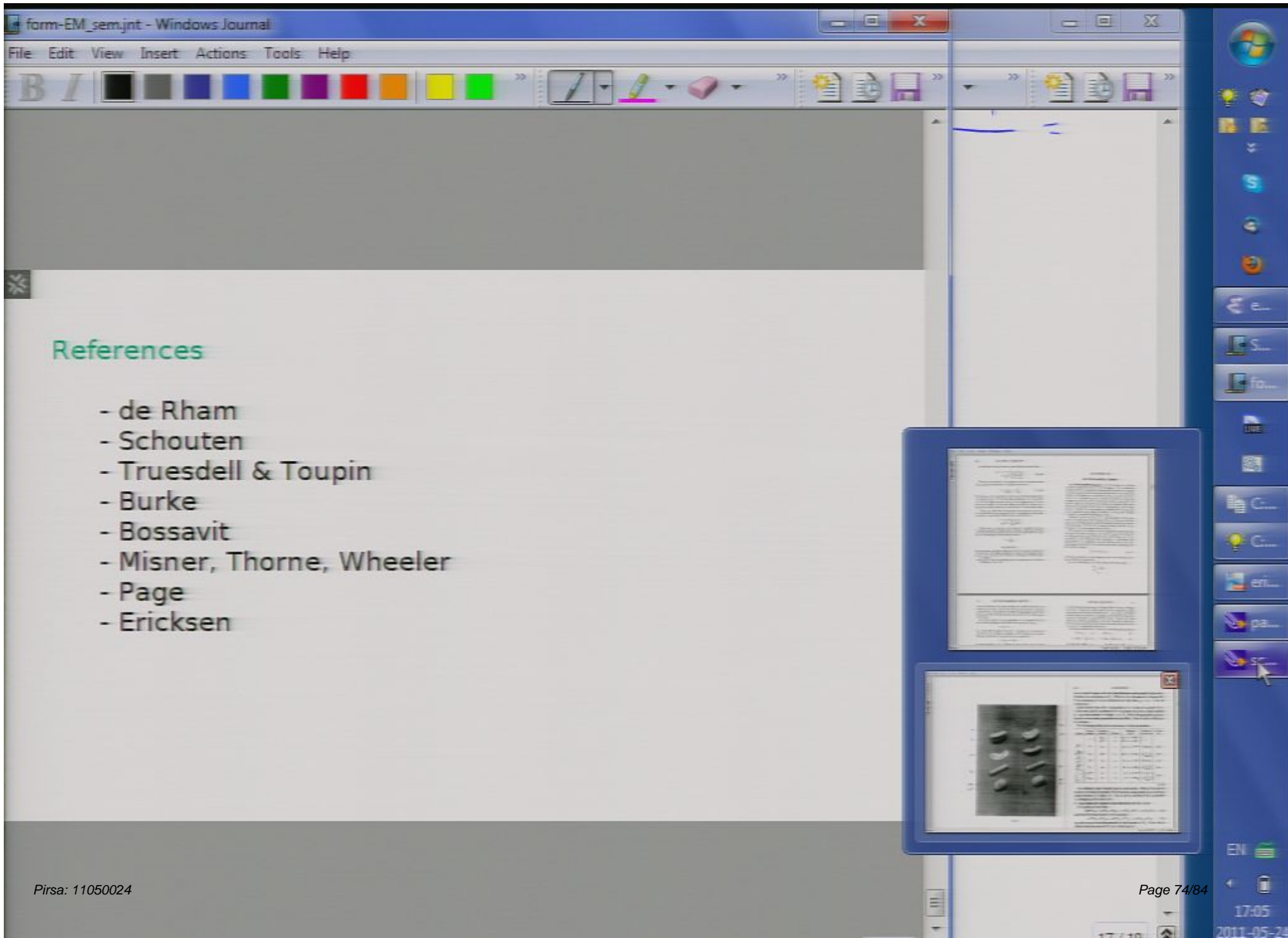
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C_i



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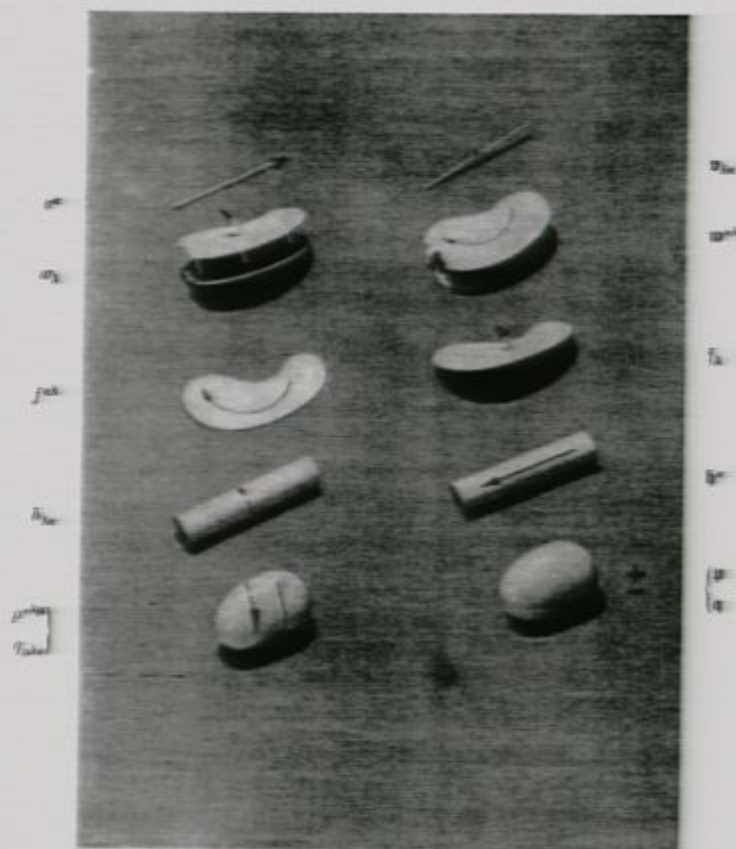


FIG. 6

[4]

DENSITIES

13

can be made to agree with the identifications made possible after introduction of a sub-group of G_x . This is to be discussed in Chapter III. If no sub-group of G_x is introduced we may take $\gamma_p = \delta_p = \theta$ for all values of p .

(8.14) shows that the components of a contra-(co)-variant W - p -vector may also be considered as components of a co-(contra)-variant $(n-p)$ -vector density of weight $-I(+I)$. Hence the geometrical meanings of corresponding quantities do not differ. There is only a difference in notation.

The following table gives a summary of these quantities:

Figure	Second notation	Ordinary notation	Weight	Relations (cyclic)	Number of components	Orientation
	ρ	ρ_{ab}	$-I$	$\rho_{123} = (-1)^{p+q} \rho$	I	
		ρ^{ab}	$+I$	$\rho^{123} = (-1)^{p+q} \rho$		
	ρ^a	ρ_a	$-I$	$\rho_{12} = (-1)^{p+q} \rho^1$	$I(\text{prop.})$	outer
	ρ_k	ρ^k	$+I$	$\rho^{12} = (-1)^{p+q} \rho_k$	$I\left(\frac{I}{\text{area}}\right)$	inner
	f^{ab}	f_k	$-I$	$f_{12} = (-1)^{p+q} f^1$	$I(\text{prop.})$	outer
	h_{ab}	h^a	$+I$	$h^1 = (-1)^{p+q} h_{12}$	$I\left(\frac{I}{\text{area}}\right)$	inner
	ρ^{ab}	ρ	$-I$	$\rho = (-1)^{p+q} \rho^{12}$	$I(\text{vol.})$	
	ρ_{ab}	q	$+I$	$q = (-1)^{p+q} \rho_{12}$	$I\left(\frac{I}{\text{vol.}}\right)$	outer

(8.15)

An ordinary scalar density has no screw-sense. This is the kind of density occurring in physics. For instance a mass density is an ordinary scalar density of weight $+I$. Fig. 6 shows models of the quantities occurring in (8.10) and (8.15).

9. Quantities of valence 2 and matrices (cf. B.C. I § 8)

It is easily proved that

$$\text{Det}(P^a_{b}) = n! P^a_{1} \dots P^a_{n} = n! P^1_{a} \dots P^n_{a} = n! P^1_{1} \dots P^n_{n} \quad (9.1)$$

and that the components of the quantity

$$s! P^{a_1 \dots a_s}_{b_1 \dots b_s} = s! P^{a_1 \dots a_s}_{1 \dots 1} = s! P^{a_1 \dots a_s}_{1 \dots 1} \quad (9.2)$$

are the s -rowed sub-determinants in the matrix of P^a_{b}. From this it follows that the rank of P^a_{b} is r if and only if

$$P^{a_1 \dots a_s}_{b_1 \dots b_s} \begin{cases} \neq 0 & \text{for } s \leq r, \\ = 0 & \text{for } s > r. \end{cases} \quad (9.3)$$

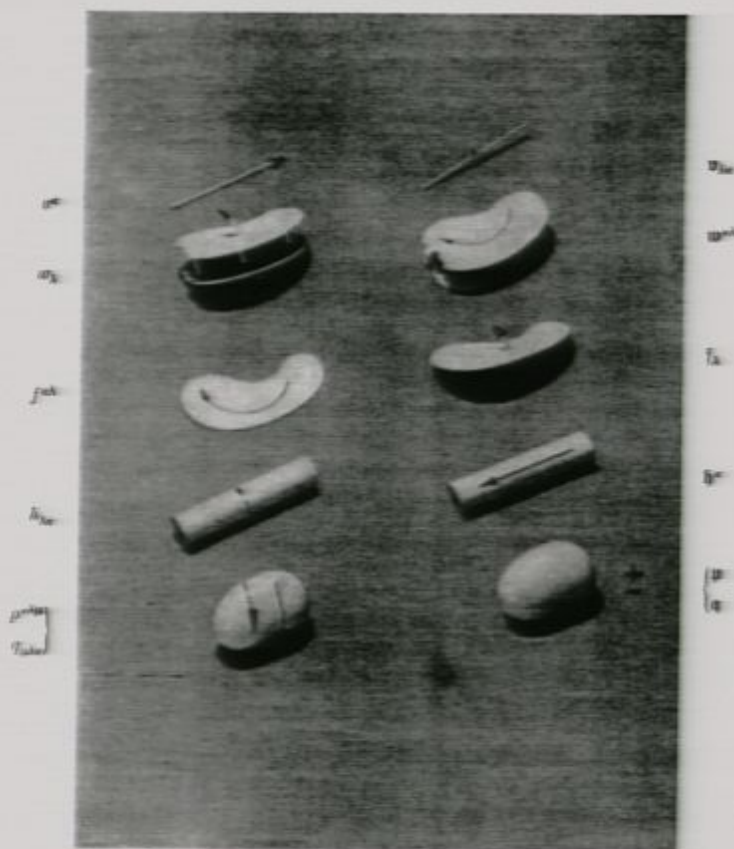


FIG. 6

[8]

DENSITIES

13

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	β	β_{abc}	$-I$	$\beta_{123} = (-1)^p \beta$	I	
		β^{abc}	$+I$	$\beta^{123} = (-1)^q \beta$		
	α^a	α_a	$-I$	$\alpha_{12} = (-1)^p \alpha^1$	$I(\text{prop.})$	outer
	α_a	α^a	$+I$	$\alpha^{12} = (-1)^q \alpha_1$	$I \left(\frac{I}{\text{sect.}} \right)$	inner
	f^{ab}	f_{ab}	$-I$	$f_{12} = (-1)^p f^{12}$	$I(\text{prop.})$	outer
	f_{ab}	f^{ab}	$+I$	$f^{12} = (-1)^q f_{12}$	$I \left(\frac{I}{\text{sect.}} \right)$	inner
	β^{abc}	β	$-I$	$\beta = (-1)^p \beta^{123}$	$I(\text{vol.})$	outer
	β_{abc}	β	$+I$	$\beta = (-1)^q \beta_{123}$	$I \left(\frac{I}{\text{vol.}} \right)$	

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It is easily proved that

$$\text{Det}(P^a_{b}) = n! P^1_{1} P^2_{2} \dots P^n_{n} = n! P^1_{1} P^2_{2} \dots P^n_{n} = n! P^1_{1} P^2_{2} \dots P^n_{n} \quad (9.1)$$

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FIG. 6

[8]

DENSITIES

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can be made to agree with the introduction of a sub-group of G_n . If no sub-group of G_n is introduced, values of p .

(8.14) shows that the component vector may also be considered as an $(n-p)$ -vector density of weight p . The corresponding quantities are denoted in notation.

The following table gives a summary

Figure	Second notation	Ordinary notation	Weight
	ρ	ρ_{ab}	0
	ρ^a	ρ^a_{bc}	1
	ρ^a_b	ρ^a_{bcd}	2
	ρ^{ab}	ρ^{ab}_{cde}	3
	ρ^{abc}	ρ^{abc}_{def}	4
	ρ^{abcd}	ρ^{abcd}_{efgh}	5
	ρ^{abcde}	ρ^{abcde}_{fghij}	6

An ordinary scalar density has no screw-sense. This is the kind of density occurring in physics. For instance a mass density is an ordinary scalar density of weight $+1$. Fig. 6 shows models of the quantities occurring in (8.10) and (8.15).

9. Quantities of valence 2 and matrices (cf. R.C. I § 8)

It is easily proved that

$$\text{Det}(P^a_{b}) = n! P^a_{1} P^a_{2} \dots P^a_{n} = n! P^1_{a} P^2_{a} \dots P^n_{a} = n! P^a_{1} P^a_{2} \dots P^a_{n} \quad (9.1)$$

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nents of a co-(contra-)variant
Hence the geometrical mean-
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of these quantities:

Relations (cyclic)	Number of components	Orienta- tion
$\rightarrow (-1)^{p+q} \delta$ $\rightarrow (-1)^{p+q} \delta$	I	
$\rightarrow (-1)^{p+q} \delta$	$I(\text{proj.})$	outer
$\rightarrow (-1)^{p+q} \delta$	$I\left(\frac{I}{\text{area}}\right)$	inner
$\rightarrow (-1)^{p+q} \delta$	$I(\text{proj.})$	outer
$\rightarrow (-1)^{p+q} \delta$	$I\left(\frac{I}{\text{area}}\right)$	inner
$\rightarrow (-1)^{p+q} \delta$	$I(\text{vol.})$	
$\rightarrow (-1)^{p+q} \delta$	$I\left(\frac{I}{\text{vol.}}\right)$	outer

(8.15)

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ce a mass density is an ordinary
hows models of the quantities

ices (cf. B.C. I § 8)

$$\partial_{\alpha} P^{\alpha}_{\beta} = \partial_{\beta} P^{\alpha}_{\alpha} - \partial_{\alpha} P^{\alpha}_{\beta} \quad (9.1)$$

$$\partial_{\alpha} P^{\alpha}_{\beta} = \partial_{\beta} P^{\alpha}_{\alpha} - \partial_{\alpha} P^{\alpha}_{\beta} \quad (9.2)$$

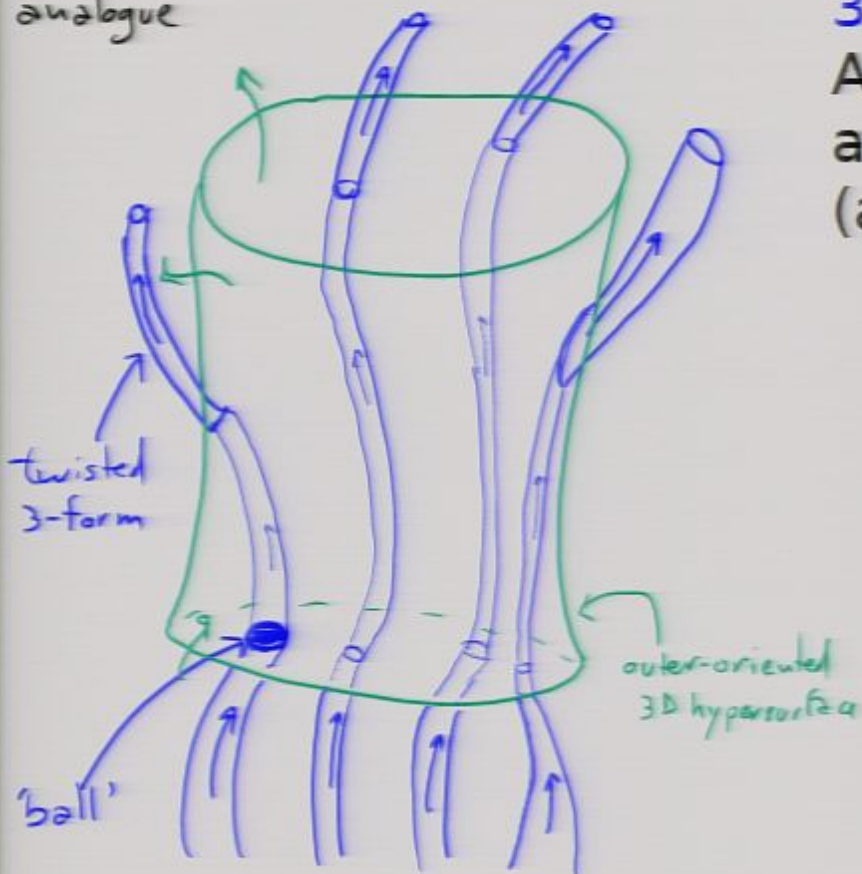
e matrix of P^{α}_{β} . From this it
only if

$$\begin{aligned} &\text{for } s \leq r, \\ &\text{for } s > r. \end{aligned} \quad (9.3)$$



Matter/mass (and charge) is a twisted 3-form in spacetime

3D spacetime
analogue



3-form in spacetime = 'hypertubes'

A 3D observer sees them
as 'balls' moving around in 3D space
(and changing shape)

balls initially in 3D region
+ balls entering 2D surface
- balls exiting 2D surface
- balls finally in 3D region
= 0

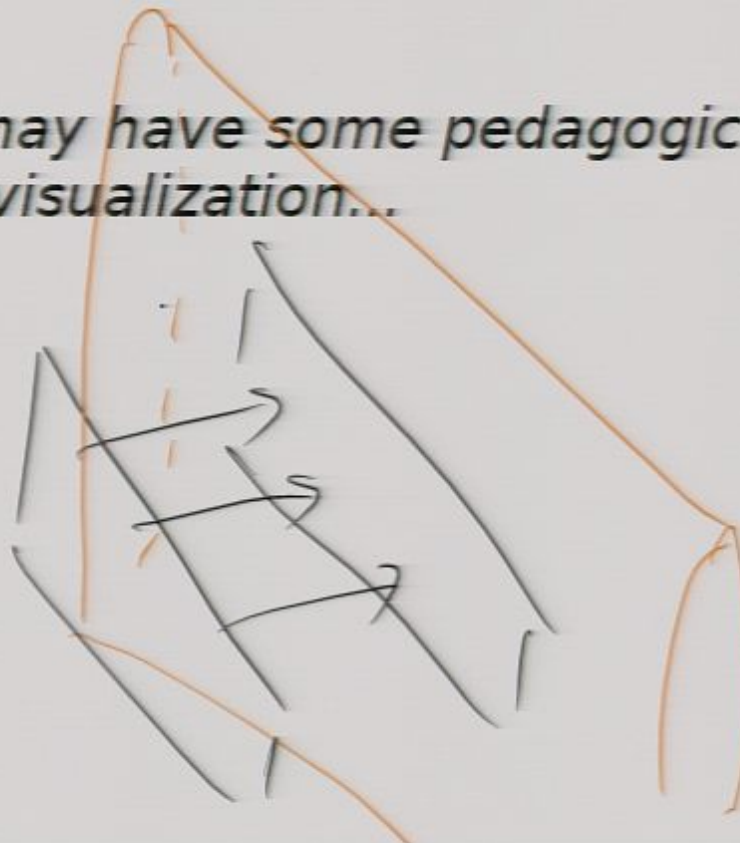
This property =
the twisted 3-form is **closed**
(its tubes never end)

$$d\omega = 0$$



*OK, fine, this may have some pedagogical use
and may help visualization...*

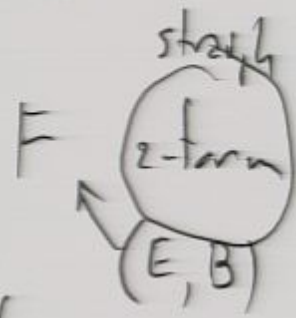
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Hehl
Bateman



$dQ=0 \Rightarrow \exists M$ twisted 2-form

$$F = dA$$

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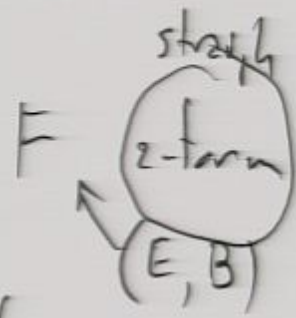
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