

Title: Explorations in Particle Theory - Lecture 5

Date: Apr 08, 2011 10:15 AM

URL: <http://pirsa.org/11040025>

Abstract:

Barger & Phillips, Collider Physics

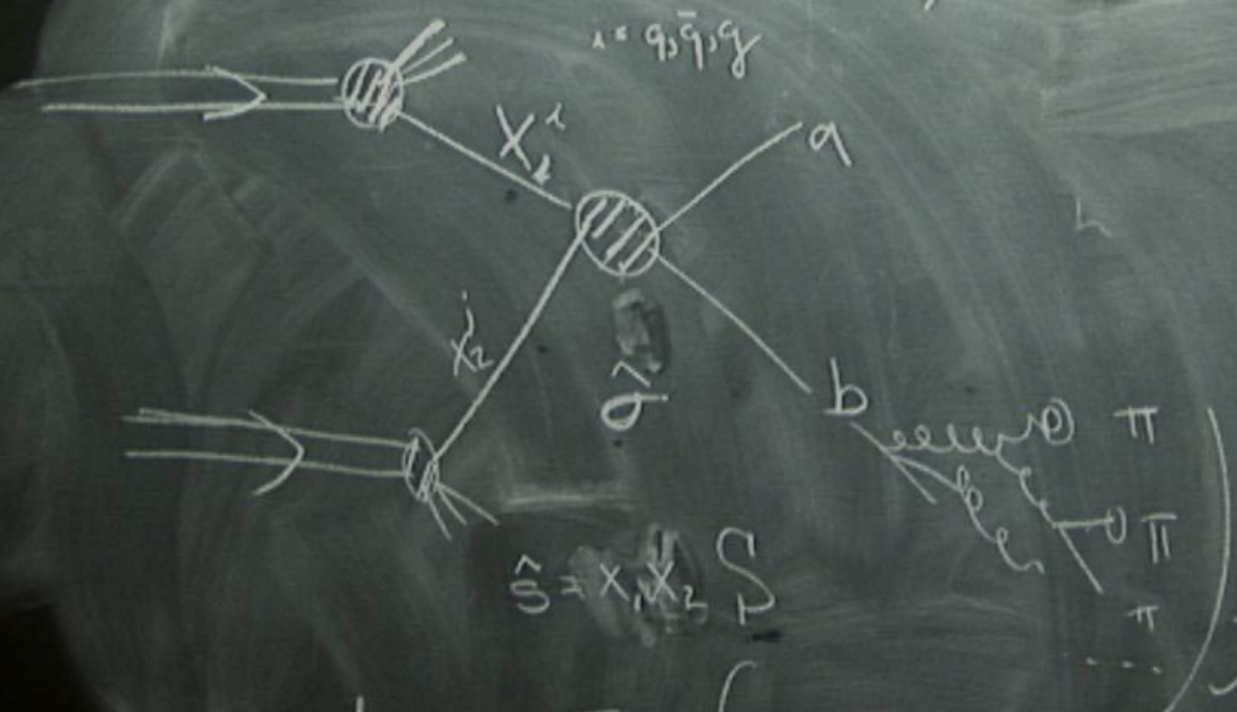
Ellis, Stirling, Webber QCD & Collider Physics

Green, High p_T Physics at Colliders

Campbell, Hirston, Stirling "Hard Interactions of Quarks & Gluons"
(Outline)







$$\frac{d\sigma}{dX} = \sum_{ijr} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j)$$

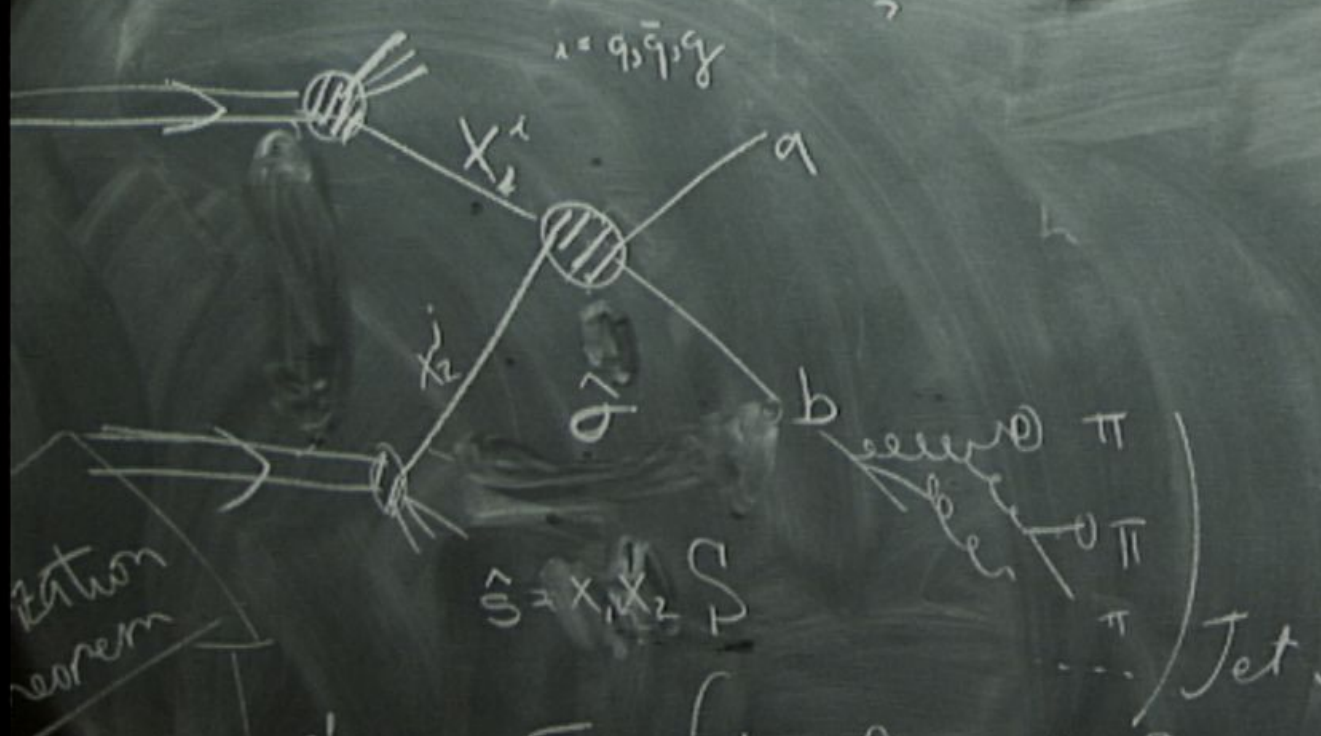
↑ inclusive
kinematic
variables

$= 9,9,9$



$$\int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_i) \cdot \frac{d\hat{\sigma}}{d\hat{X}} \times F(\hat{X} \rightarrow X)$$

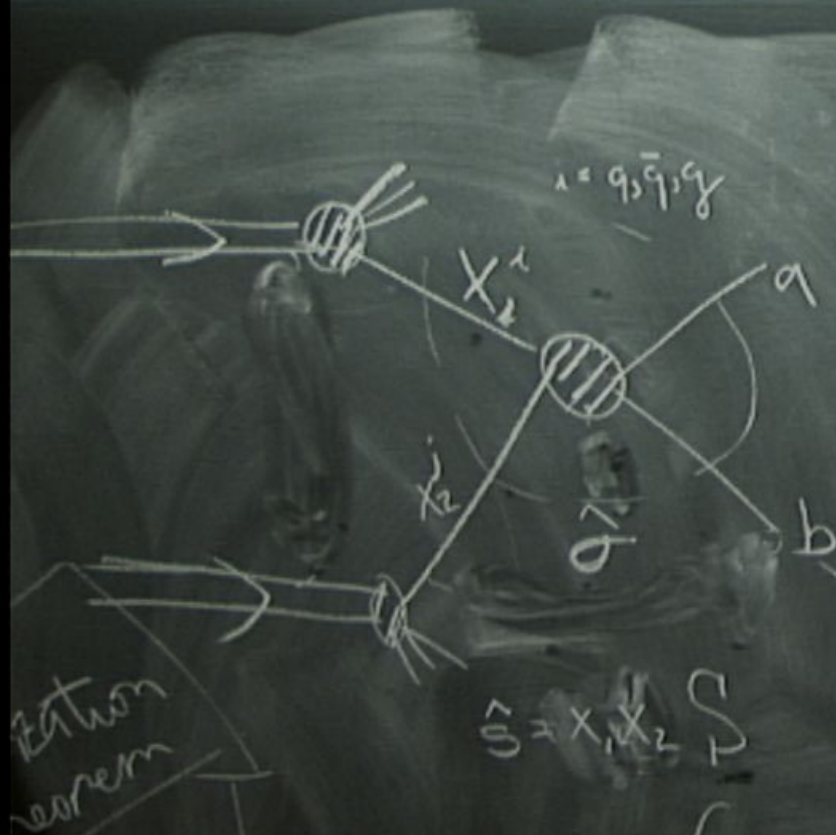
just like incl. scattering



$$\frac{d\sigma}{dX} = \sum_{ijr} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j) \cdot \frac{d\hat{\sigma}}{d\hat{X}}$$

exclusive
 kinematic
 variables

just like incl. scattering



Eaton
reparam

$$a = g, \bar{g}, g$$

$$\hat{S} = x_1, x_2, S$$

$$\hat{\sigma}_0 + \hat{\sigma}_1 + \dots$$

Jet
 π
 π
 π

$$\frac{d\sigma}{dX} = \sum_{ijr} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j) \cdot \frac{d\hat{\sigma}}{d\hat{X}} \times F(\hat{X})$$

exclusive
kinematic
variables

just like incl. scattering

Evolution
of PDFs

Per t
of h

Λ_{QCD}

Q_F

Evolution
of PDFs

per t. thg
of hard parts (ren at
scale Q_r)



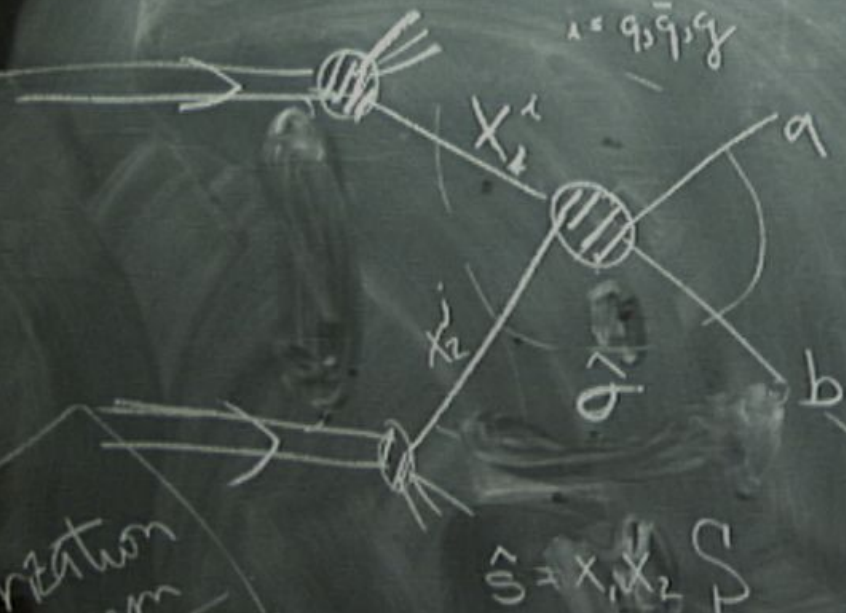
$$\sigma_0 + \sigma_1 + \dots$$

π
 π
 π
 Jet.

$$(x_1, Q_i) \int dx_2 f(x_2, Q) \cdot \frac{d\hat{\sigma}}{d\hat{X}} \times F(\hat{X} \rightarrow X)$$

like incl. scattering

Factorization theorem



$$\lambda = g_1 \bar{g}_1 g_2$$

$$d\sigma_0 + d\sigma_1 + \dots$$



$$\hat{S} = X_1 X_2 S$$

π
 π
 π
 Jet

$$\frac{d\sigma}{dX} = \sum_{ijr} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j)$$

inclusive kinematic variables

just like incl. scattering

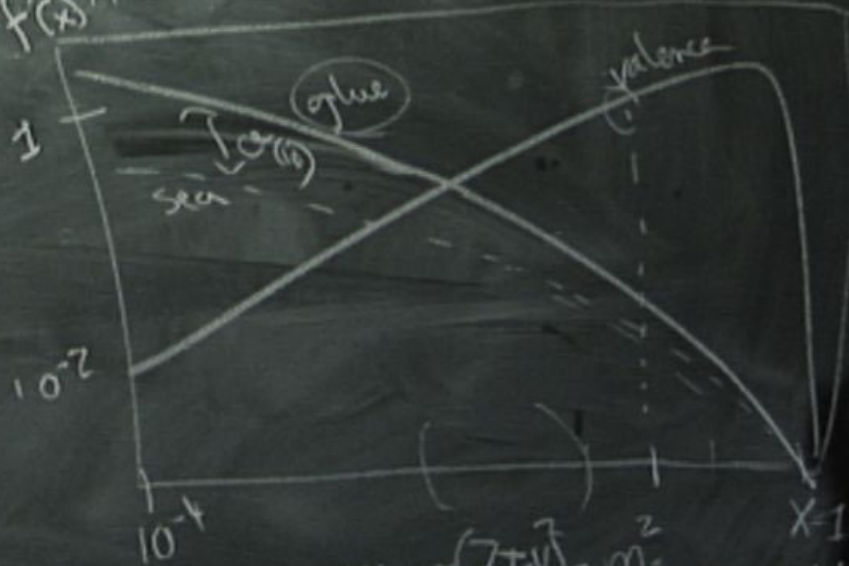
Evolution of PDFs

Per t. thing of hard part (ren at scale Q_r)

Q_F

Q_S

$F(x) \times x, Q \sim \text{TeV}$



$$x_1 \times x_2 \times (7 \text{TeV})^2 = m_z^2$$

$$x_3 \sim \frac{m_z}{7 \text{TeV}} \sim 1\%$$

$$\frac{1}{20}$$

$$\frac{d\hat{\sigma}}{dx} \times F(\hat{x} \rightarrow X)$$

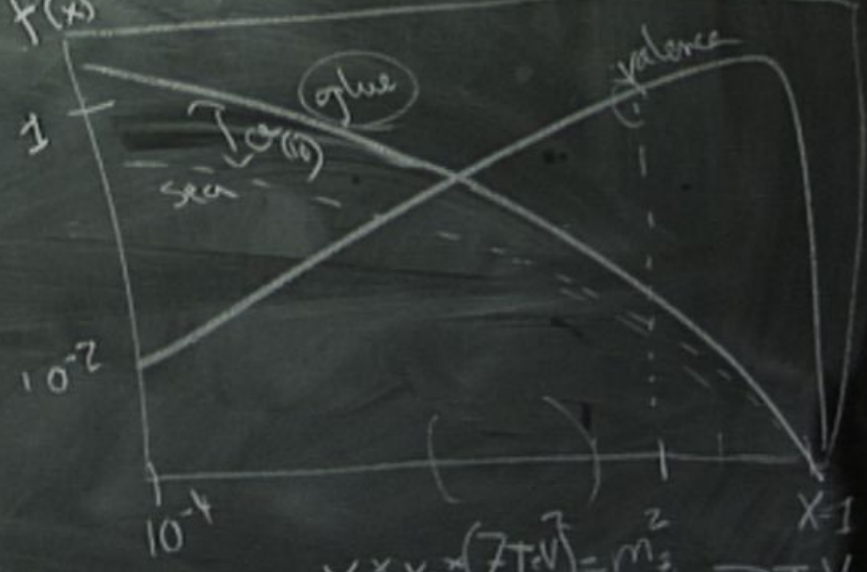
evolution of PDFs

Per t. thiy of hard proct (ren at scale Q_r)

Q_F

Q_r

$P(x) \times x, Q \sim TeV$



$$x_1 \times x_2 \times (7TeV)^2 = m_z^2$$

$$x_2 \sim \frac{m_z^2}{7TeV} \sim \frac{1}{20}$$

$$\frac{d\hat{\sigma}}{dx} \times F(\hat{x} \rightarrow X)$$

$$\frac{d\sigma}{dX} = \sum_{ij} \int dx_1 f(x_2, Q) \cdot \frac{d\hat{\sigma}}{d\hat{X}}$$

↑
inclusive
kinematic
variables

$$T = \sum_i \sum_j T_{ij} = x_1 x_2$$

$$x_1 =$$

$$\frac{d\sigma}{dX} = \sum_{ij} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j) \cdot \frac{d\hat{\sigma}}{d\hat{X}}$$

inclusive kinematic variables

$$T = \frac{\sum_i \vec{p}_i}{\sum_i E_i} = \frac{x_1}{x_2}$$

$$x_1 = \sqrt{t} e^y, \quad x_2 = \sqrt{t} e^{-y}$$

$y = \text{rapidity of the CM frame}$
 $\cosh y = \gamma$

$$dx_1, dx_2, \dots$$

$$\frac{d\sigma}{dx}$$

$$f(x_1, Q_i) \int dx_2 f(x_2, Q_i) = \frac{d\hat{\sigma}}{dx}$$

$$T = \sqrt{\frac{E}{\mu}} = x_1 x_2$$

$$x_1 = \sqrt{T} e^y, \quad x_2 = \sqrt{T} e^{-y}$$

$y =$ rapidity of the CM frame
 $\cosh y = \gamma$

$$dx_1 dx_2 = dT dy$$

$$d\sigma = \sum_{ij} \int d\vec{r} dy f(\dots)$$

$$\frac{d\sigma}{dX} = \sum_{ij} \int dx_1 f(x_1, Q_i) \int dx_2 f(x_2, Q_j) \cdot \frac{d\hat{\sigma}}{d\hat{X}}$$

inclusive kinematic variables

$\sqrt{\pi} e^{-y}$
CM frame

$$d\sigma = \sum_{ij} \int d\vec{\tau} dy f_i(\sqrt{\tau} e^y) f_j(\sqrt{\tau} e^{-y})$$

dy

$$x_1 f(x_1, Q_i) \int dx_2 f(x_2, Q) \sim \frac{d\hat{\sigma}}{d\hat{x}}$$

$$x_1 = \sqrt{\tau} e^y, \quad x_2 = \sqrt{\tau} e^{-y}$$

y = rapidity of the CM frame

$$\cosh y = \gamma$$

$$dx_1 dx_2 = d\tau dy$$

$$d\sigma = \sum_{ij} \int d\tau \int dy f_i(\sqrt{\tau} e^y) f_j(\sqrt{\tau} e^{-y})$$

$$\sum_{ij} \int_{\frac{3}{5}}^{\frac{1}{2}} dx_1 f_i(x_1, Q_i) \int_{\frac{1}{2}}^{\frac{1}{3}} dx_2 f_j(x_2, Q_j) \cdot \frac{d\hat{\sigma}}{d\hat{x}}$$

$$X_1 = \sqrt{\tau} e^y, \quad X_2 = \sqrt{\tau} e^{-y}$$

, $y =$ rapidity of the CM frame
 $\cosh y = \gamma$

$$dX_1 dX_2 = d\tau dy$$

$$d\sigma = \sum_{ij} \int_{\frac{3}{5}}^1 d\tau$$

$$f_1(\sqrt{\tau} e^y) f_2(\sqrt{\tau} e^{-y})$$

$$\frac{d\sigma}{dX} = \sum_{ij} \int_{\frac{3}{5}}^1 dx_1 f_1(x_1, Q_i) \int_{\frac{3}{5}}^1 dx_2 f_2(x_2, Q_j) \cdot \frac{d\sigma}{dX}$$

exclusive kinematic variables

$$y_{\max} \sqrt{s} < 1$$

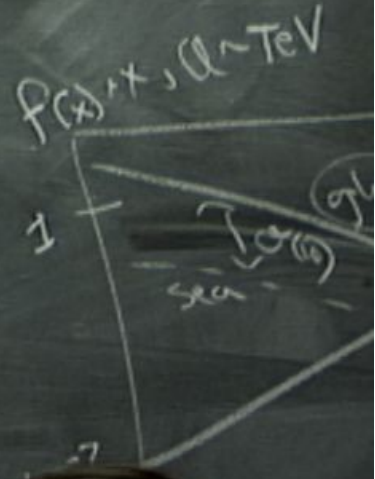
$$y_{\max} = \frac{1}{2} \log \frac{s}{M^2}$$

\Rightarrow $\sqrt{s} \approx 4.3$ LHC

$y_{\max, \text{abs}} \approx 8.9$ LHC

$$d\sigma = \sum_{ij} \int_{s_{\min}/s}^1 dt' \int_{-y_{\max}}^{y_{\max}} dy f_i(\sqrt{t'} e^y) f_j(\sqrt{t'} e^{-y})$$

$$\int_{s_{\min}/s}^1 dx_2 f(x_2, Q) = \frac{d\hat{\sigma}}{dx}$$



$$y_{\max} \sqrt{s} e^{y_{\max}} < 1$$

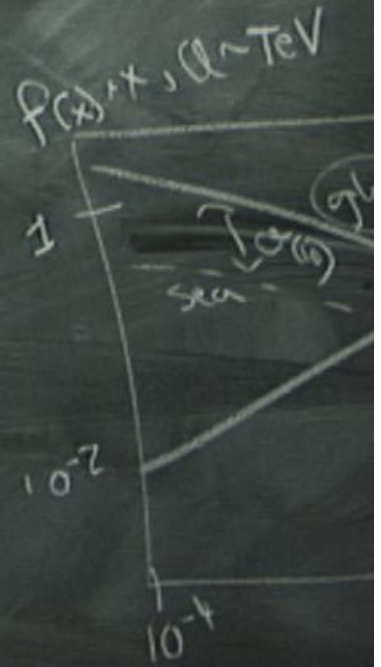
$$y_{\max} = \frac{1}{2} \log \frac{\sqrt{s}}{m}$$

$\approx \ln m @ \text{LHC} \approx 4.3$

$y_{\max, \text{abs}} \approx 8.9 \text{ LHC}$

$$d\sigma = \sum_{ij} \int_{s_{\min}/s}^1 d\tau \int_{-y_{\max}}^{y_{\max}} dy f_i(\sqrt{\tau} e^y) f_j(\sqrt{\tau} e^{-y})$$

$$\int_{s_{\min}/s}^1 dx_2 f(x_2, Q) = \frac{d\hat{\sigma}}{dx}$$



$$y_{max} \rightarrow e^{y_{max}} < 1$$

$$y_{max} = \frac{1}{2} \log \frac{\sqrt{s}}{m}$$

\rightarrow brem @ LHC ~ 4.3

$y_{max, abs} \approx 8.9$ LHC

$$d\sigma = \sum_{ij} \int \frac{d\tau}{\tau} \int_{-y_{max}(\tau)}^{y_{max}(\tau)} dy f_i(\sqrt{\tau} e^y) f_j(\sqrt{\tau} e^{-y}) \hat{\tau}$$

$\frac{3 \text{ min}}{S}$

$$\frac{1}{S} F(\tau, S)$$

parton luminosity

$$f(x_2, Q) = \frac{d\hat{\sigma}}{dx}$$

$f(x), x, Q \sim \text{TeV}$



$$y_{max} \sqrt{\tau} e^{y_{max}} < 1$$

$$y_{max} = \frac{1}{2} \log \frac{1}{\tau}$$

$\sqrt{s} \approx 13.6$ LHC ≈ 4.3

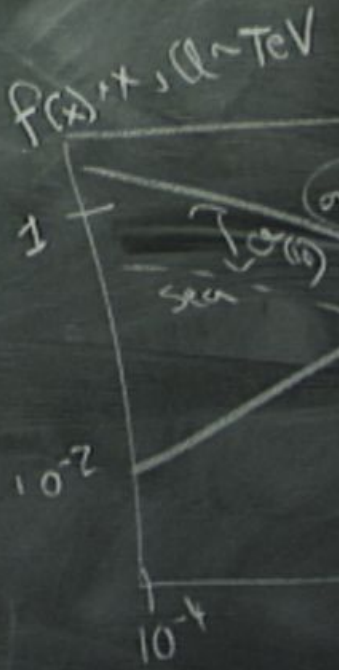
$y_{max, abs} \approx 8.9$ LHC

$$d\sigma = \sum_{ij} \int \frac{d\tau}{\tau} \int_{-y_{max}(\tau)}^{y_{max}(\tau)} dy f_i(\sqrt{\tau} e^y) f_j(\sqrt{\tau} e^{-y}) \tau$$

$3 \text{ min} / \text{s}$

$$\frac{1}{S} F(\tau, S)$$

parton luminosity



$$\int_{\frac{\sqrt{s}}{2}}^1 dx_2 f(x_2, Q) = \frac{d\hat{\sigma}}{dx}$$

$$\hat{\sigma}_{q\bar{q} \rightarrow W} = \frac{\pi R^2}{3} G_F^2 m_W^2 \delta(\hat{s} - m_W^2)$$

$$\hat{\sigma}_{pp \rightarrow W} = \sum_q \int \frac{d\tau}{\tau}$$

$$d\sigma = \sum_{ij} \int \frac{d\tau}{\tau} \left(\frac{1}{s_{min}/s} \right)$$

$$= \sum_{ij} \int_{\frac{3}{5}s}^{\frac{1}{5}s} dx_1 f_i(x_1, Q_i) \int_{\frac{3}{5}s}^{\frac{1}{5}s} dx_2 f_j(x_2, Q_j)$$

$$\hat{\sigma}_{q\bar{q} \rightarrow W} = \frac{\pi R^2}{3} G_F m_W^2 \times \delta(\hat{s} - m_W^2)$$

$$\hat{\sigma}_{pp \rightarrow W} = \sum_{q_i} \int \frac{d\hat{s}}{\hat{s}} \times F_{q_i q_i}(\tau, \hat{s}) \times \hat{\sigma}_{q\bar{q} \rightarrow W}$$

$$\frac{d\sigma}{dX} = \sum_{ij} \int_{\frac{\hat{s}}{S}}^1 dx_1 f_i(x_1, Q_i) \int_{\frac{\hat{s}}{S}}^1 dx_2 f_j(x_2, Q_j)$$

inclusive
kinematic
variables

$$\hat{\sigma}_{q\bar{q} \rightarrow W} = \frac{\pi R^2}{3} G_F m_W^2 \times \delta(\hat{s} - m_W^2)$$

$$\hat{\sigma}_{pp \rightarrow W} = \sum_{q_i \bar{q}_i} \int \frac{d\hat{s}}{\hat{s}} \times F_{q_i \bar{q}_i}(\tau, \hat{s}) \times \hat{\sigma}_{q\bar{q} \rightarrow W}$$

$$= \sum_{q_i \bar{q}_i} \underbrace{F_{q_i \bar{q}_i} \left(\frac{m_W^2}{\hat{s}}, \hat{s} \right)}_{N \left(\frac{m_W}{\hat{s}} \right)^{-q}} \times \left(\alpha_1 \alpha_2 \times \frac{m_W^2}{M_W^2} \right)$$

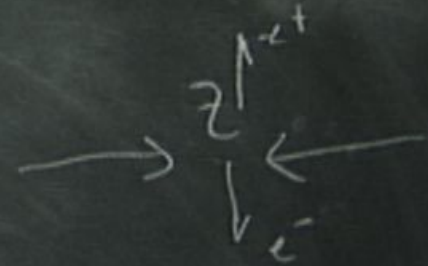
$$\hat{\sigma}_{q\bar{q} \rightarrow W} = \frac{\pi R^2}{3} G_F m_W^2 \delta(\hat{s} - m_W^2)$$

$$\hat{\sigma}_{pp \rightarrow W} = \sum_{q_i} \int \frac{d\hat{s}}{\hat{s}} \times F_{q_i \bar{q}_i}(\tau, \hat{s}) \times \hat{\sigma}_{q\bar{q} \rightarrow W}$$

$$= \sum_{q_i} \frac{1}{m_W^2} F_{q_i \bar{q}_i} \left(\frac{m_W^2}{\hat{s}}, \hat{s} \right) \times \left(\alpha_1 \alpha_2 \times \frac{m_W^2}{M_W^2} \right)$$

$$\sigma = \frac{\alpha_2}{m_W^2} \times N \left(\frac{m_W}{\hat{s}} \right)^{-q}$$

$$\sigma \propto \sum \frac{1}{m_W^{2+q}} \text{ grows with } \hat{s}$$



Use z -boost-invariant variables!

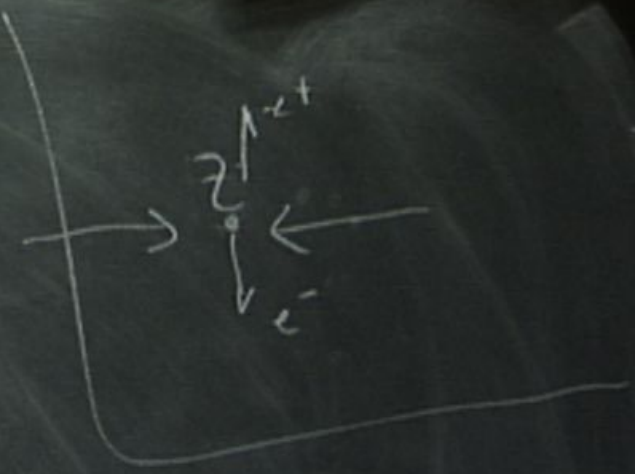
$$(E, p_x, p_y, p_z) \longrightarrow (E', p_x, p_y, z')$$

$$m, (p_x, p_y, p_z)$$

Use z -boost-invariant variables!

$$(E, \underbrace{p_x, p_y, p_z}) \longrightarrow (E', \underbrace{p_x, p_y, z'})$$

$$m, (p_x, p_y) \longrightarrow p_T, \phi$$



Use z -boost-invariant variables!

$$(E, \underbrace{p_x, p_y, p_z}_{\vec{p}}) \longrightarrow (E', \underbrace{p_x, p_y, z}_{\vec{p}'})$$

$$m, (p_x, p_y) \longrightarrow p_T = \sqrt{p_x^2 + p_y^2}, \quad \phi = \arctan\left(\frac{y}{x}\right)$$

$$E_T = \sqrt{m^2 + p_T^2} \leq \frac{y}{x}$$

Use z -boost-invariant variables!

$$(E, p_x, p_y, p_z) \rightarrow (E', p_x, p_y, p_z')$$

$$m (p_x, p_y) \rightarrow p_T = \sqrt{p_x^2 + p_y^2}, \quad \phi = \arctan\left(\frac{y}{x}\right)$$

$$E_T = \sqrt{m^2 + p_T^2} \leq \frac{E}{\gamma}$$

$$\begin{pmatrix} E \\ p_z \end{pmatrix} = \begin{pmatrix} \cosh \zeta & \sinh \zeta \\ \sinh \zeta & \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ p_z \end{pmatrix}$$

\downarrow \downarrow
 γ_p γ_p

Use z -boost-invariant variables!

$$(E, p_x, p_y, p_z) \longrightarrow (E', p_x, p_y, p_z')$$

$$m, (p_x, p_y) \longrightarrow p_T = \sqrt{p_x^2 + p_y^2}, \quad \phi = \arctan\left(\frac{y}{x}\right)$$

$$\begin{aligned} \cosh \zeta &= \gamma \\ \sinh^2 \zeta &= \cosh^2 \zeta - 1 \\ &= (\gamma^2 - 1) \end{aligned}$$

$$E_T = \sqrt{m^2 + \frac{p_T^2}{c^2}} \leq \frac{E}{c}$$

$$\begin{pmatrix} E \\ p_z \end{pmatrix} = \begin{pmatrix} \cosh \zeta & \sinh \zeta \\ \sinh \zeta & \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ p_z \end{pmatrix}$$

\downarrow γ_β \downarrow γ_β
 β β

st-invariant variables!

$$(p_y, p_z) \rightarrow (E', p_x, p_y, p_z')$$

$$p_T = \sqrt{p_x^2 + p_y^2}, \quad \phi = \arctan\left(\frac{y}{x}\right)$$

$$E_T = \sqrt{m^2 + p_T^2} < \frac{E}{\gamma}$$

$$\begin{pmatrix} E \\ p_z \end{pmatrix} = \begin{pmatrix} \cosh \zeta & \sinh \zeta \\ \sinh \zeta & \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ p_z \end{pmatrix}$$

$\left(\begin{matrix} \gamma_\beta \\ \gamma_\beta \end{matrix} \right)$

$$E = A \cosh y$$

$$p_z = A \sinh y$$

$$\cosh y \rightarrow \cosh(y + \zeta)$$

$$E^2 - p_z^2 = A^2$$

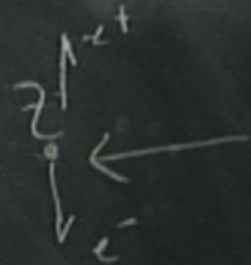
$$E_T^2 = A^2$$

$$\frac{E}{E_T}$$

$$E^2 - P_z^2 = A^2$$

$$E_T^2 = A^2$$

$$\frac{E}{E_T} = \cosh y, \quad \frac{P_z}{E_T} = \sinh y$$



Massless

$$\frac{P_z}{P_T} = \cosh y = \frac{1}{\cos \theta}, \quad \frac{P_z}{P_T} = \sinh y = \frac{1}{\tan \theta}$$

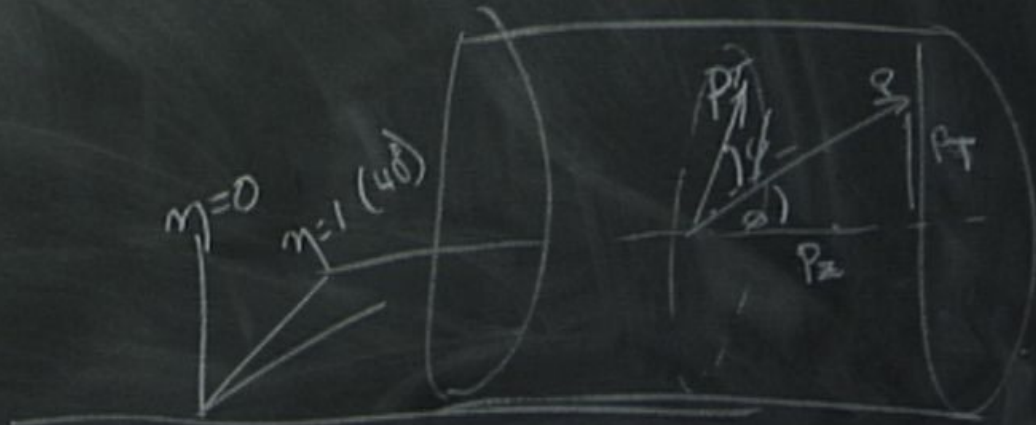
$$y = -\ln \tan \frac{\theta}{2}$$

$$\eta = -\ln \tan \frac{\theta}{2}$$

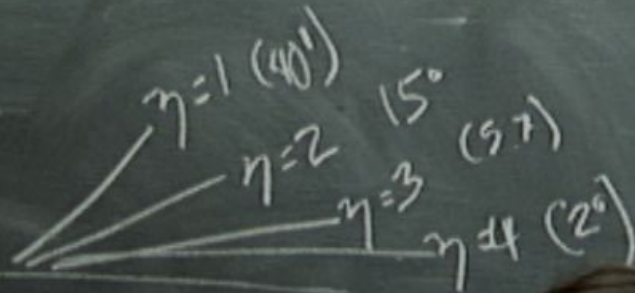
$\cosh y$

$A \sinh y$

$\cosh y \rightarrow \cosh(y+\xi)$



Use z -boost-invariant variables!



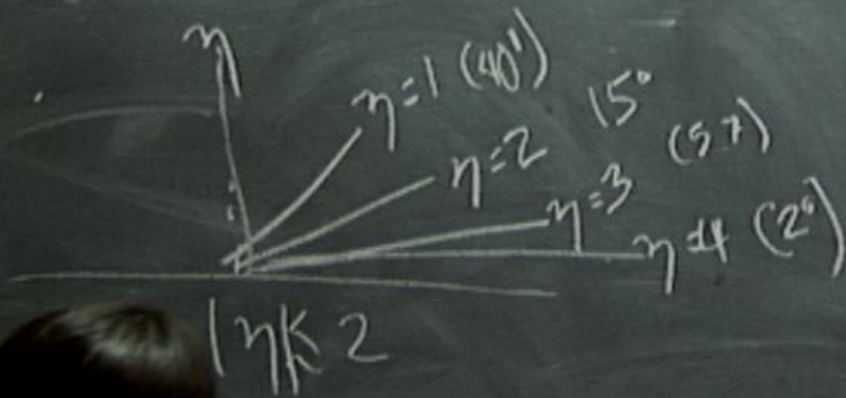
$$\begin{pmatrix} E \\ p_z \end{pmatrix}$$

$$\begin{pmatrix} \sinh \zeta \\ \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ p_z \end{pmatrix}$$

$$E = \dots$$

$$p_z = \dots$$

Use z -boost-invariant variables!



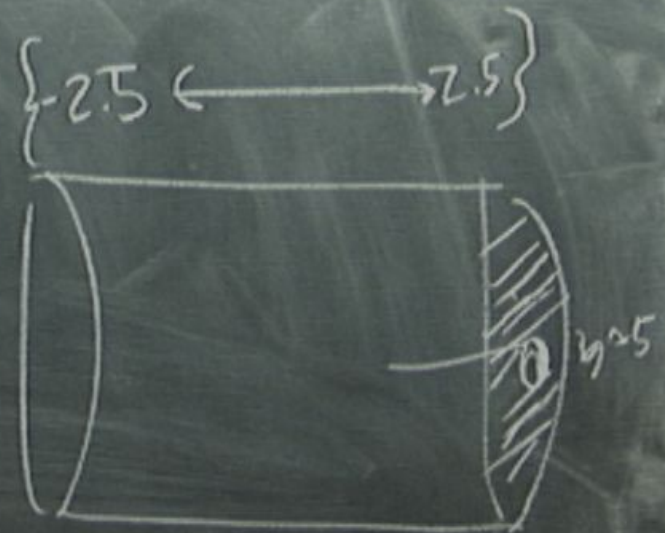
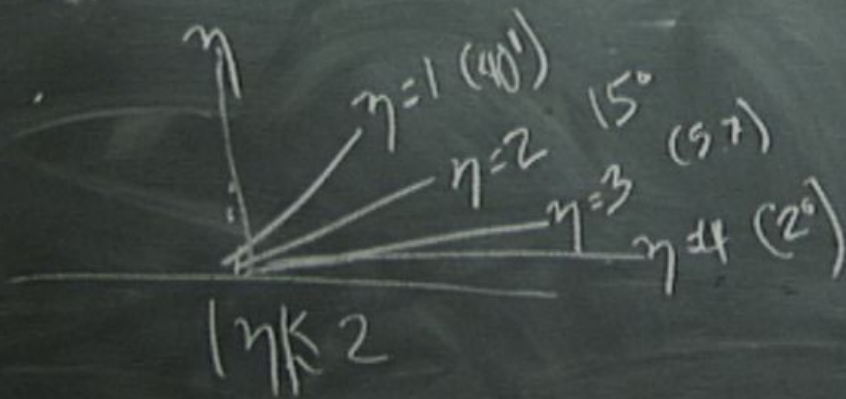
$$\begin{pmatrix} E \\ P_z \end{pmatrix} = \begin{pmatrix} \cosh \zeta & \sinh \zeta \\ \sinh \zeta & \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ P_z \end{pmatrix}$$

$\left(\begin{matrix} \downarrow & \downarrow \\ x_\beta & x_\alpha \end{matrix} \right)$

$E = \dots$

$P_z = \dots$

Use z -boost-invariant variables!



$$\begin{pmatrix} E \\ p_z \end{pmatrix} = \begin{pmatrix} \cosh \zeta & \sinh \zeta \\ \sinh \zeta & \cosh \zeta \end{pmatrix} \begin{pmatrix} E \\ p_z \end{pmatrix}$$

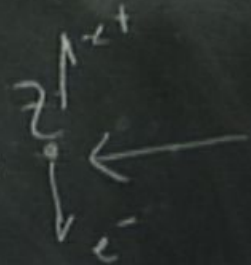
\downarrow \downarrow \downarrow \downarrow
 x_β x_α y_β y_α

$E = \dots$
 $p_z = \dots$

$$E^2 - P_z^2 = A^2$$

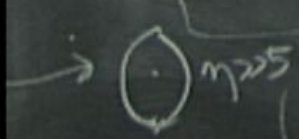
$$E_T^2 = A^2$$

$$\frac{E}{E_T} = \cosh y, \quad \frac{P_z}{E_T} = \sinh y$$



Masalah

$$\frac{P}{P_T} = \cosh y = \frac{1}{\cos \theta}, \quad \frac{P_z}{P_T} = \sinh y = \frac{1}{\tan \theta}$$



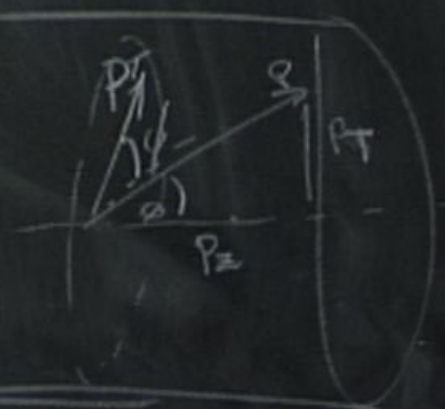
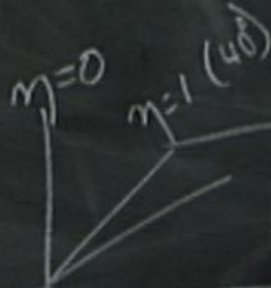
$$y = -\ln \tan \frac{\theta}{2}$$

$$\eta = -\ln \tan \frac{\theta}{2}$$

$\cosh y$

$A \sinh y$

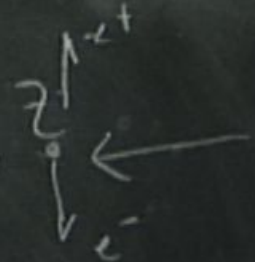
$\cosh y \rightarrow \cosh(y + \zeta)$



$$E^2 - P_z^2 = A^2$$

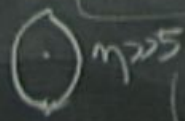
$$E_T^2 = A^2$$

$$\frac{E}{E_T} = \cosh y, \quad \frac{P_z}{E_T} = \sinh y$$



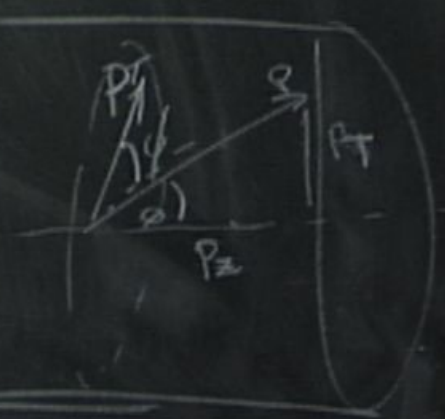
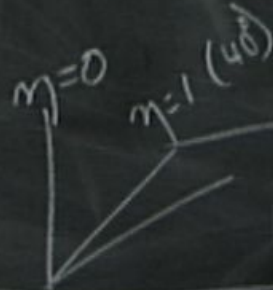
Masalah

$$\frac{P_z}{P_T} \rightarrow \cosh y \leftarrow \frac{1}{\cos \theta}, \quad \frac{P_z}{P_T} \rightarrow \sinh y \leftarrow \frac{1}{\tan \theta}$$



$$y \Rightarrow -\ln \tan \frac{\theta}{2}$$

$$\eta = -\ln \tan \frac{\theta}{2}$$



$\cosh y$

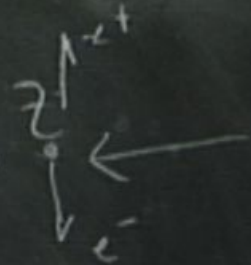
$A \sinh y$

$$\cosh y \rightarrow \cosh(y + \xi)$$

$$E^2 - P_z^2 = A^2$$

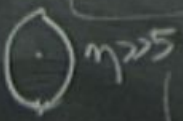
$$E_T^2 = A^2$$

$$\frac{E}{E_T} = \cosh y, \quad \frac{P_z}{E_T} = \sinh y$$



Masalah

$$\frac{P_z}{P_T} \rightarrow \cosh y \leftarrow \frac{1}{\cos \theta}, \quad \frac{P_z}{P_T} \rightarrow \sinh y \leftarrow \frac{1}{\tan \theta}$$



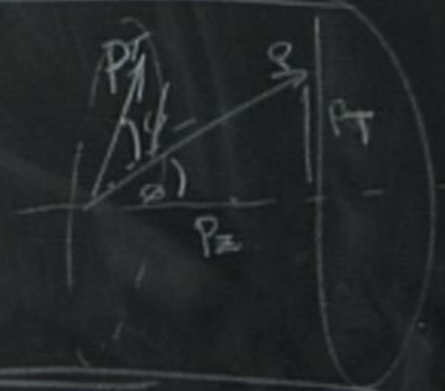
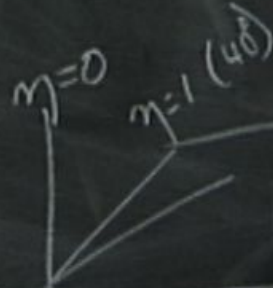
$$y \Rightarrow -\ln \tan \frac{\theta}{2}$$

$$\eta = -\ln \tan \frac{\theta}{2}$$

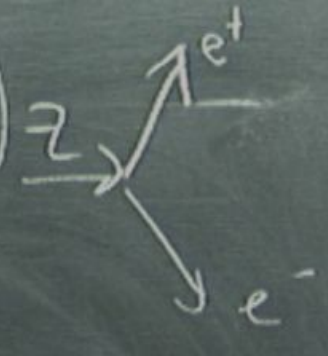
$\cosh y$

$A \sinh y$

$$\cosh y \rightarrow \cosh(y + \xi)$$



Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = z(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-)$$


=

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = z(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

$$= z \vec{p}_T^+ \vec{p}_T^- \left(\cosh \eta_+ \cosh \eta_- - \frac{p_z^+ + p_z^-}{p_T^+ p_T^-} \right) z$$

$p_T^+ \cosh \eta, p_z^+ = p_T^+ \sinh \eta,$
 $E = \sqrt{m^2 + |\vec{p}|^2}$

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = 2(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

$\nearrow e^+$
 $\searrow e^-$

$$= 2\vec{p}_T^+ \vec{p}_T^- \left(\underbrace{\cosh \eta_+ \cosh \eta_-}_{\substack{p_z^+ + p_z^+ p_z^- \\ p_z^+ + p_z^-}} - \sinh \eta_+ \sinh \eta_- \right) - \cos \Delta\phi$$

$$M_z^2 = 2\vec{p}_T^+ \vec{p}_T^- (\cosh(\Delta\eta) - \cos \Delta\phi)$$

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = 2(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

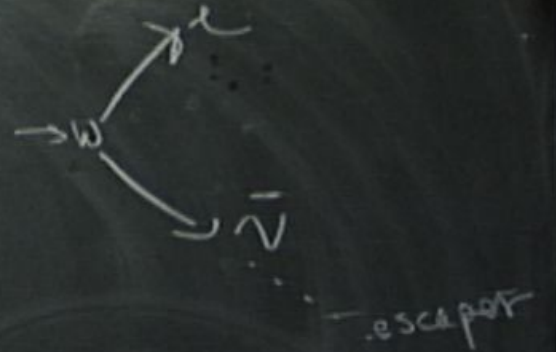
$p_z^+ + p_z^- + p_T^+ p_T^-$

$$= 2 p_T^+ p_T^- \left(\cosh \eta_+ \cosh \eta_- - \sinh \eta_+ \sinh \eta_- - \cos \Delta\phi \right)$$

e^+
 e^-

$$M_z^2 = 2 p_T^+ p_T^- (\cosh(\Delta\eta) - \cos \Delta\phi)$$

L n



A diagram showing a vector \vec{v} on the left. Two arrows branch out from \vec{v} : one pointing up and to the right towards a vector \vec{c} , and another pointing down and to the right towards a vector \vec{v} . Below the vector \vec{v} , the text "unknown" is written.

$$\vec{v} = -\vec{v}$$

unknown

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = 2(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

$\nearrow e^+$
 $\searrow e^-$

$$= 2 \cancel{p_T^+} \cancel{p_T^-} \left(\underbrace{\cosh \eta_+ \cosh \eta_-}_{\cosh(\eta_+ - \eta_-)} - \underbrace{\sinh \eta_+ \sinh \eta_-}_{-\cos \Delta\phi} \right)$$

$$= 2 p_T^+ p_T^- (\cosh(\Delta\eta) - \cos \Delta\phi)$$

$$M_w^2 = 2 p_T^c E_T (\cosh \Delta\eta - \cos \Delta\phi)$$

$$\approx 2 p_T^c E_T (1 - \cos \Delta\phi) = M_{+}^2$$

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = 2(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

$$= 2\bar{p}_T^+ \bar{p}_T^- \left(\cosh \eta_+ \cosh \eta_- - \sinh \eta_+ \sinh \eta_- - \cos \Delta\phi \right)$$

e^+
 e^-

$$M_z^2 = 2\bar{p}_T^+ \bar{p}_T^- (\cosh(\Delta\eta) - \cos \Delta\phi)$$

$$M_w^2 = 2\bar{p}_T^+ \bar{E}_T^- (\cosh \Delta\eta - \cos \Delta\phi)$$

$$\geq 2\bar{p}_T^+ \bar{E}_T^- (1 - \cos \Delta\phi) = M_+^2$$

Use z -boost-invariant variables!

$$M_z^2 = (p^+ + p^-)^2 = 2(E^+ E^- - \vec{p}^+ \cdot \vec{p}^-) z$$

$\underbrace{\quad}_{p_z^+ + p_z^-}$

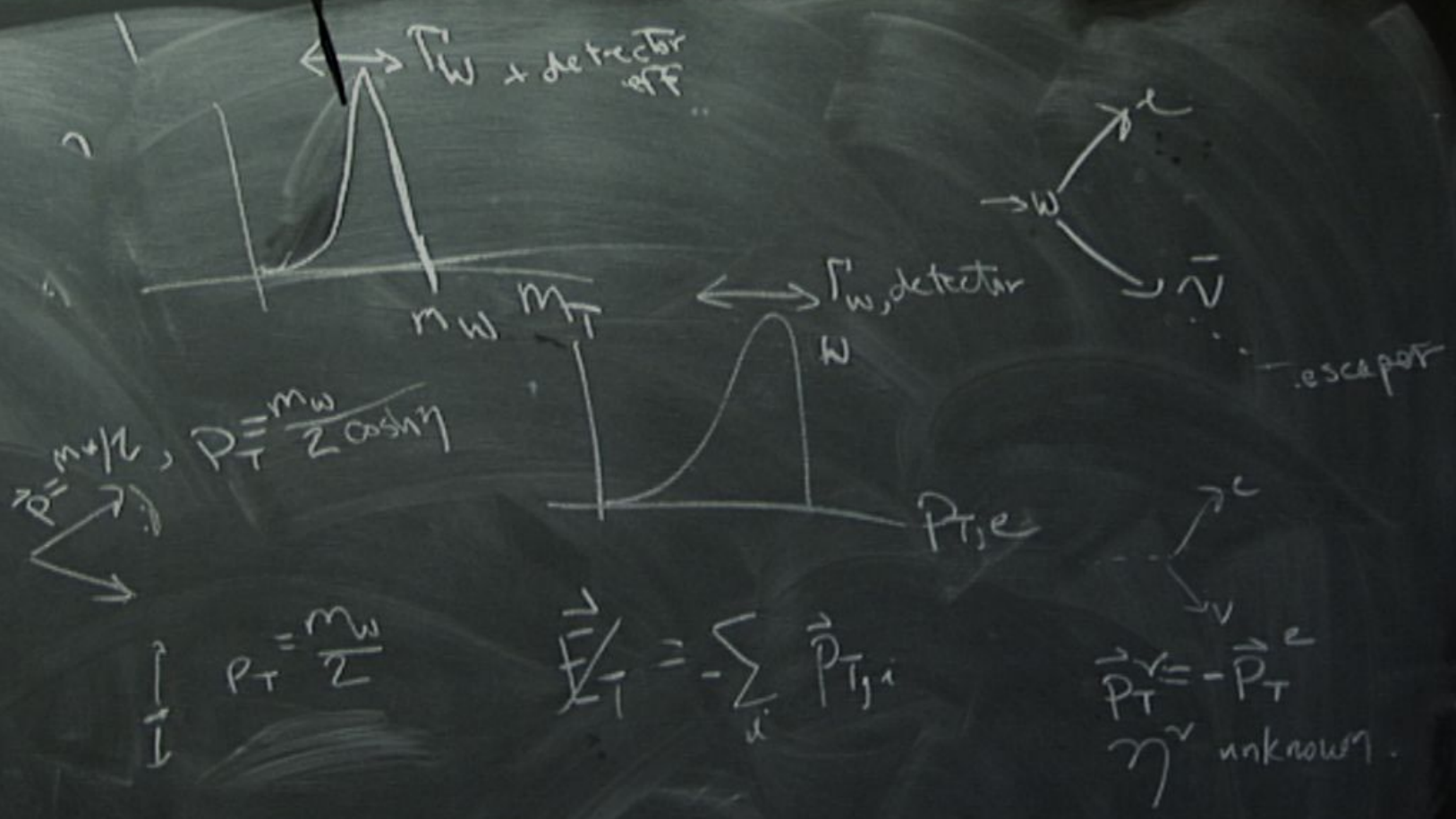
$$= 2 p_T^+ p_T^- \left(\cosh \eta_+ \cosh \eta_- - \sinh \eta_+ \sinh \eta_- - \cos \Delta\phi \right)$$

$\cosh(\eta_+ - \eta_-)$

$$M_z^2 = 2 p_T^+ p_T^- (\cosh(\Delta\eta) - \cos \Delta\phi)$$

$$M_w^2 = 2 p_T^+ E_T^- (\cosh \Delta\eta - \cos \Delta\phi)$$

$$\geq 2 p_T^+ E_T^- (1 - \cos \Delta\phi) = M_+^2$$



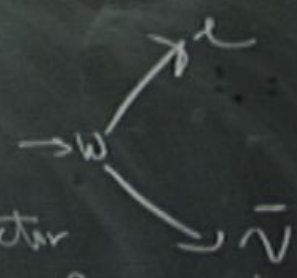
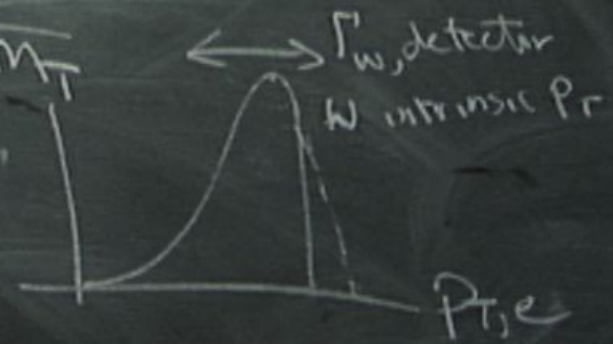
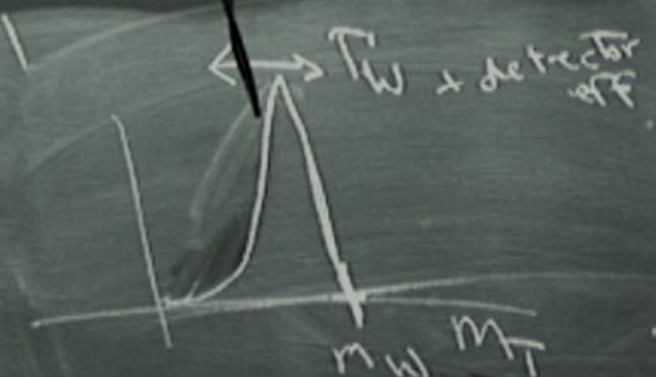


$\vec{p} = m\vec{w}/\hbar$, $P_T = \frac{m\omega}{2 \cos \eta}$

$P_T = \frac{m\omega}{2}$

$\vec{P}_T = -\sum_i \vec{P}_{T,i}$

$\vec{P}_T = -\vec{P}_T^e$
 η^v unknown



escape