

Title: Explorations in Condensed Matter - Lecture 6

Date: Mar 21, 2011 10:15 AM

URL: <http://pirsa.org/11030039>

Abstract:



perimeter scholars
INTERNATIONAL

$$m \frac{dV}{dt} = -eE + f_0$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$\chi(t) = \ell_B$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$m \frac{d\vec{V}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{V} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

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$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$\boxed{l_B = v_0 \cdot \frac{1}{\omega_c}}$$

$$\omega_c = \frac{eB}{m}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$\dot{\vec{p}} = -e\vec{E} - q\vec{A}$$



$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{r}$$

$$\delta =$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\delta = \frac{\hbar e^2 \tau}{m}$$

$P(t)$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\delta = \frac{ne^2 \tau}{m}$$

$$P(t) = P_0 e^{-t/\tau} + eE$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\sigma = \frac{ne^2\tau}{m}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\delta = \frac{ne^2\tau}{m}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\sigma = \frac{ne^2\tau}{m}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - e \frac{\vec{p}}{m} \times \vec{B} - \frac{\vec{p}}{\tau}$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\delta = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - \frac{eB\vec{p}}{m} \times \hat{z} - \frac{\vec{p}}{\tau} = -eE - \omega_c \vec{p} \times \hat{z} - \frac{\vec{p}}{\tau}$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\sigma = \frac{ne^2\tau}{m}$$

$$p(t) = p_0 e^{-t/\tau} + eE\tau$$

$$\vec{p} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle p \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p}}{m} \times \hat{z} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$\dot{p}_x =$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\delta = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p}}{m} \times \hat{z} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$\dot{p}_x = -eE - \omega_c p_y - \frac{1}{\tau} p_x$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\sigma = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\dot{\vec{p}} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p} \times \hat{z}}{m} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$\dot{p}_x = -eE - \omega_c p_y - \frac{1}{\tau} p_x$$

$$\dot{p}_y = \omega_c p_x$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\sigma = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\vec{D} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p} \times \hat{z}}{m} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$\dot{p}_x = -eE - \omega_c p_y - \frac{1}{\tau} p_x$$

$$\dot{p}_y = \omega_c p_x - \frac{1}{\tau} p_y \rightarrow p_x = \frac{1}{\omega_c} \left(\dot{p}_y + \frac{1}{\tau} p_y \right)$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\sigma = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\vec{p} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p} \times \hat{z}}{m} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$1) \dot{p}_x = -eE - \omega_c p_y - \frac{1}{\tau} p_x$$

$$2) \ddot{p}_y = \omega_c p_x - \frac{1}{\tau} \dot{p}_y \rightarrow p_x = \frac{1}{\omega_c} (\dot{p}_y + \frac{1}{\tau} p_y)$$

$$2 \rightarrow 1) \frac{1}{\omega_c} (\ddot{p}_y + \frac{1}{\tau} \dot{p}_y) = -eE - \omega_c p_y - \frac{1}{\tau} \omega_c (\dot{p}_y + \frac{1}{\tau} p_y)$$

$$\dot{\vec{p}} = -eE - \frac{\vec{p}}{\tau}$$

$$\boxed{\sigma = \frac{ne^2\tau}{m}}$$

$$P(t) = P_0 e^{-t/\tau} + eE\tau$$

$$\vec{p} = -\frac{\vec{p}}{\tau}$$

$$J = \frac{e}{m} \langle P \rangle n$$

$$\dot{\vec{p}} = -eE - eB \frac{\vec{p} \times \hat{z}}{m} - \frac{\vec{p}}{\tau} = -eE_x - \omega_c \vec{p} \times \hat{z} - \frac{1}{\tau} \vec{p}$$

$$1) \dot{p}_x = -eE - \omega_c p_y - \frac{1}{\tau} p_x$$

$$2) \dot{p}_y = \omega_c p_x - \frac{1}{\tau} p_y \rightarrow p_x = \frac{1}{\omega_c} \left(\dot{p}_y + \frac{1}{\tau} p_y \right)$$

$$2 \rightarrow 1) \frac{1}{\omega_c} \left(\ddot{p}_y + \frac{1}{\tau} \dot{p}_y \right) = -eE - \omega_c p_y - \frac{1}{\tau} \omega_c \left(\dot{p}_y + \frac{1}{\tau} p_y \right)$$

$$\vec{p} \times \hat{z} = \frac{1}{c} \vec{p}$$

$$0 = -eE - \omega_c p_y$$

$$-\frac{1}{c^2} \omega_c$$

$$+ \frac{1}{c} p_y)$$

$$p_y + \frac{1}{c} p_y)$$

$$\vec{p} \times \hat{z} - \frac{1}{z} \vec{p}$$

$$0 = -eE - \omega_c p_y$$

$$-\frac{1}{z^2} \omega_c p_y$$

$$\langle p_y \rangle = eE$$

$$+ \frac{1}{z} p_y)$$

$$p_y + \frac{1}{z} p_y)$$

$$\vec{p} \times \hat{z} = \frac{1}{c} \vec{p}$$

$$0 = -eE - \omega_c p_y$$

$$-\frac{1}{c^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{c^2} \omega_c \right)^{-1}$$

$$+ \frac{1}{c^2} p_y)$$

$$p_y + \frac{1}{c^2} p_y)$$

$$\vec{p} \times \hat{z} = \frac{1}{\tau} \vec{p}$$

$$0 = -eE - \omega_c p_y$$

$$-\frac{1}{\tau^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$

$$\vec{p} \times \hat{z} = \frac{1}{\tau} \vec{p}$$

$$0 = -eE - \omega_c p_y$$

$$-\frac{1}{\tau^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$\begin{bmatrix} 0 & 1/\omega_c \\ -1/\omega_c & 0 \end{bmatrix}$$

$$\omega_c = \frac{eB}{m}$$

$\hat{\delta}$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = v_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$\hat{O} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\dot{p} = -$$

$$l \delta =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = v_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$\hat{O} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\dot{p} = -$$

$$|\delta =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$

$$\hat{\delta} = \frac{ne^2\tau}{m} \frac{1}{1 + \omega_c^2\tau^2} \begin{pmatrix} 1 & \omega_c\tau \\ -\omega_c\tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\delta_{xy} = \frac{ne^2\tau}{m} \frac{1}{\omega_c\tau}$$

$$\dot{p} = -$$

$$\delta =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = v_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$\hat{\sigma} = \frac{ne^2\tau}{m} \cdot \frac{1}{1 + \omega_c^2\tau^2} \begin{pmatrix} 1 & \omega_c\tau \\ -\omega_c\tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\tau \omega_c \gg 1$$

$$\sigma_{xy} = \frac{ne^2\tau}{m} \frac{1}{\omega_c\tau} = \frac{ne\tau}{m} \frac{m}{eB} = \frac{ne}{B}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{B}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - \underbrace{e\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$

$$l_B = v_0 \cdot \frac{1}{\omega_c}$$

$$\omega_c = \frac{eB}{m}$$



$$\hat{\sigma} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\omega_c \tau \gg 1$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau^2}{m} \frac{\omega_c}{\tau} = \frac{ne^2 \tau^2}{m} \frac{eB}{m} = \frac{ne^2}{B}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

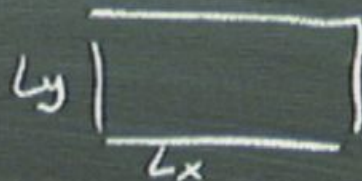
$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne^2}{B}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - e \underbrace{\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l \left[\frac{1}{\omega_c} \right]$$

$$I_y = G V_x$$

$$\hat{\delta} = \frac{ne^2 \tau}{m} \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$\tau \gg \omega_c^{-1}$
 $\omega_c \tau \gg 1$

$$\delta_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau^2}{m} \omega_c = \frac{ne}{B}$$

$$\dot{p} = -$$

$$\delta =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

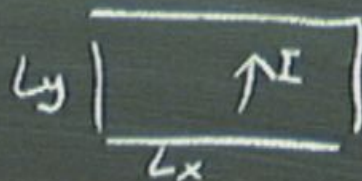
$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{B}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - e \underbrace{\vec{v} \times \vec{B}}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l_B = \frac{v}{\omega_c}$$

$$I_y = G V$$

$$L_x J_y = G$$

$$\hat{\chi} = \frac{ne^2 \tau}{m} \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau}{m \omega_c} = \frac{ne}{B} = \frac{ne}{\hbar} \frac{\hbar}{eB}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

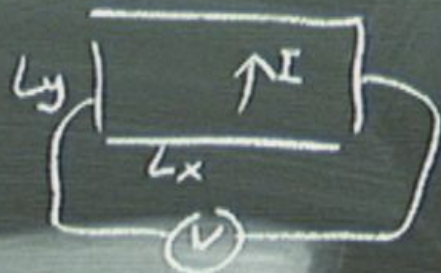
$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{B}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - e\vec{v} \times \vec{B}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$I_y = G V_x$$

$$L_x J_y = G E \cdot L_x$$



$$\hat{\sigma} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\omega_c \tau \gg 1$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau^2}{m} \omega_c = \frac{ne}{B}$$

$$\dot{p} = \dots$$

$$\sigma = \dots$$

$$\dot{p} = \dots$$

$$1) \dot{p}_x = \dots$$

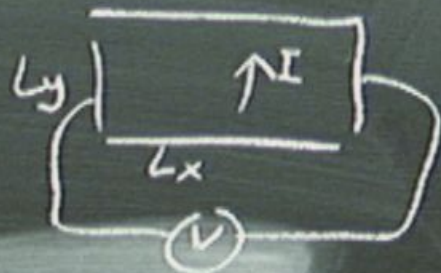
$$2) \dot{p}_y = \dots$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - e\vec{v} \times \vec{B}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$I_y = G V_x$$

$$L_x J_y = G E \cdot L_x$$

$$J_y = (G E_x) \rightarrow \sigma_{xy}$$



$$\hat{\sigma} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\tau \omega_c \gg 1$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne \hbar}{4\pi} \frac{\omega}{\omega_c} = \frac{ne}{4\pi} \frac{\omega}{\omega_c}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

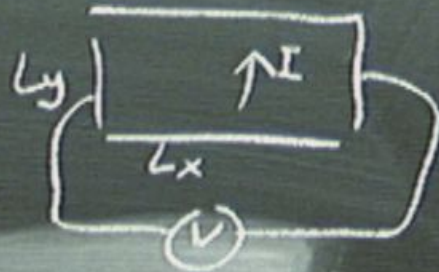
$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{4\pi}$$

$$m \frac{dV}{dt} = -eE + f_0 - e \vec{V} \times \vec{B}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$I_y = G V_x$$

$$L_x J_y = G E \cdot L_x$$

$$J_y = G E_x \rightarrow \sigma_{xy}$$



$$\hat{\sigma} = \frac{ne^2 \tau}{m} \cdot \frac{1}{1 + \omega_c^2 \tau^2} \begin{pmatrix} 1 & \omega_c \tau \\ -\omega_c \tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\tau \omega_c \gg 1$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau^2}{m} \omega_c = \frac{ne}{B}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

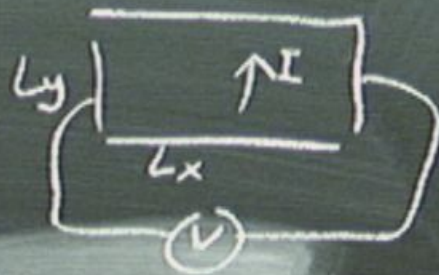
$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{B}$$

$$m \frac{d\vec{v}}{dt} = -e\vec{E} + f_0 - e\vec{v} \times \vec{B}$$

$$x(t) = l_B \cos(\omega_c t)$$

$$y(t) = l_B \sin(\omega_c t)$$



$$l_B = V_0 \cdot \frac{1}{\omega_c}$$

$$I_y = G V_x$$

$$L_x J_y = G E \cdot L_x$$

$$J_y = G E_x \rightarrow \sigma_{xy}$$



$$\hat{\sigma} = \frac{ne^2\tau}{m} \frac{1}{1+\omega_c^2\tau^2} \begin{pmatrix} 1 & \omega_c\tau \\ -\omega_c\tau & 1 \end{pmatrix}$$

$$\tau \gg \omega_c^{-1}$$

$$\omega_c \tau \gg 1$$

$$\sigma_{xy} = \frac{ne^2\tau}{m} \frac{1}{\omega_c\tau} = \frac{ne\tau}{m} \frac{\omega_c}{\omega_c\tau} = \frac{ne}{B}$$

$$\dot{p} = -$$

$$\sigma =$$

$$\dot{p} = -$$

$$1) \dot{p}_x =$$

$$2) \dot{p}_y =$$

$$2 \rightarrow 1) \frac{1}{\omega_c}$$

$$= \frac{ne}{B}$$

$$eE_x - \omega_c \dots$$

$$0 = -eE - \omega_c P_y$$

$$-\frac{1}{\tau}$$

$$\frac{1}{\omega_c} \left(\dot{P}_y + \frac{1}{\tau} P_y \right)$$

$$\langle P_y \rangle =$$

$$P_y - \frac{1}{\tau} \omega_c \left(\dot{P}_y + \frac{1}{\tau} P_y \right)$$

$$\sigma_{xy} = \frac{\hbar}{4m\omega_c}$$

$\vec{p} = \hbar \vec{k}$

$E = \hbar \omega$

$$\vec{v}_{gr} \times \vec{B}$$

$$\downarrow$$

$$\frac{2E}{2k}$$

$$0 = -eE - \frac{1}{2} \hbar \omega_c$$

$$\langle p_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

$$\frac{1}{\hbar \omega_c} (\ddot{p}_y + \frac{1}{2} \dot{p}_y) = -eE - \hbar \omega_c p_y - \frac{1}{2} \hbar \omega_c (\dot{p}_y + \frac{1}{2} p_y)$$

$$\begin{aligned} & \nabla_{gr} \times B \\ & \downarrow \\ & \frac{1}{\hbar} \frac{2E}{2\kappa} \times \hat{z} \end{aligned}$$

$$0 = -eE - \frac{1}{2} \omega_c \dot{p}_y$$

$$\langle p_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

$$\frac{1}{\omega_c} (\ddot{p}_y + \frac{1}{2} \dot{p}_y) = -eE - \omega_c p_y - \frac{1}{2} \omega_c (\dot{p}_y + \frac{1}{2} p_y)$$

$$\mathbf{V}_{gr} \times \mathbf{B}$$

$$\downarrow$$

$$\frac{1}{\hbar} \frac{2E}{2K} \times \hat{z}$$



\mathbf{B} ↑

$$0 = -eE - \frac{1}{2} \omega_c \hbar$$

$$\langle P_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

$$E - \omega_c P_y - \frac{1}{2} \omega_c \hbar \left(\dot{P}_y + \frac{1}{\hbar} P_y \right)$$

$$\dot{\vec{p}} = \frac{eB\vec{p} \times \hat{z}}{m}$$

$$\vec{v}_{gr} \times \vec{B}$$

$$\downarrow$$

$$\frac{1}{\hbar} \frac{2E}{2k} \times \hat{z}$$

\vec{B}



$$0 = -eE - \frac{1}{2} \omega_c v$$

$$\langle p_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

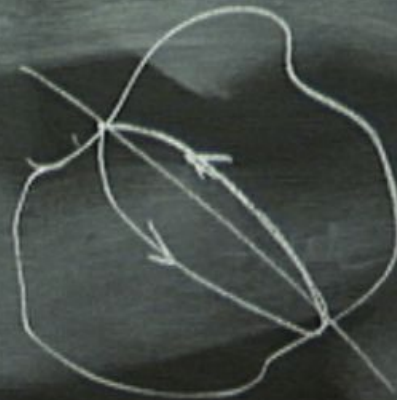
$$\frac{1}{\omega_c} (\ddot{p}_y + \frac{1}{2} \dot{p}_y) = -eE - \omega_c p_y - \frac{1}{2} \omega_c (\dot{p}_y + \frac{1}{2} p_y)$$

$$\dot{\vec{p}} = \frac{eB\vec{p} \times \hat{z}}{m}$$

$$\sqrt{g} \times \vec{B}$$

$$\downarrow$$

$$\frac{1}{\hbar} \frac{2E}{2K} \times \hat{z}$$



\vec{B}

$$0 = -eE - \frac{1}{2} \omega_c$$

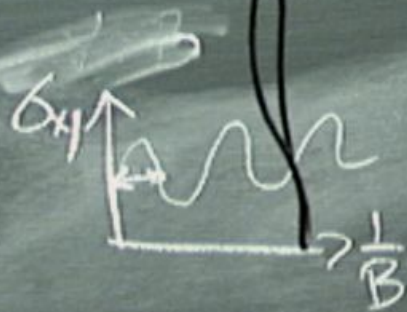
$$\langle p_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

$$\frac{1}{\omega_c} (\ddot{p}_y)$$

$$\langle p_y \rangle = \frac{1}{2} \omega_c (\dot{p}_y + \frac{1}{\hbar} p_y)$$

$$\dot{p} = \frac{eBp \times z}{m}$$



$$\begin{aligned} & \nabla_{gr} \times B \\ & \downarrow \\ & \frac{2E}{2k} \times \hat{z} \end{aligned}$$



$$0 = -eE - \frac{1}{2} \dot{z} v$$

$$\langle P_y \rangle =$$

$$\sigma_{xy} = \frac{n}{v}$$

$$+ \frac{1}{2} \dot{P}_y) = -eE - \omega_c P_y - \frac{1}{2} \omega_c (\dot{P}_y + \frac{1}{2} P_y)$$

$$1) \mathbf{B} \cdot \hat{\mathbf{z}} \rightarrow \vec{\mathbf{A}} = (0, -x) \mathbf{B} \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

=

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c} \quad \text{net } v$$

$$1) \vec{B} \cdot \hat{z} \rightarrow \vec{A} = (0, -x) \vec{B} \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$\boxed{H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2}$$

$$K = \frac{(eB)^2}{m}$$

x

p

$$1) \quad \vec{B} \cdot \hat{z} \rightarrow \vec{A} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2$$

$$p_y = \hbar k_y$$

$$K = \frac{(eB)^2}{m}$$

$$= k_y l_B^2$$

$$l_B^2 = \frac{\hbar}{eB}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c}$$

$$1) \quad \mathbf{B} \cdot \hat{\mathbf{z}} \rightarrow \vec{\mathbf{A}} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2$$

$$p_y = \hbar k_y$$

$$K = \frac{(eB)^2}{m}$$

$$x_0 = k_y l_B^2$$

$$l_B^2 = \frac{\hbar}{eB}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c} = \frac{ne^2 \tau}{m} \frac{1}{\frac{eB}{\hbar}}$$

$$1) \quad \mathbf{B} \cdot \hat{\mathbf{z}} \rightarrow \vec{\mathbf{A}} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$\boxed{H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2}$$

$$p_y = \hbar k_y$$

$$\boxed{K = \frac{(eB)^2}{m}}$$

$$\boxed{x_0 = k_y l_B^2}$$

$$\boxed{l_B^2 = \frac{\hbar}{eB}}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c \tau} = \frac{ne^2 \tau^2}{m} \frac{1}{2\tau} = \frac{ne^2 \tau}{2m}$$

$$1) \quad \vec{B} \cdot \hat{z} \rightarrow \vec{A} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2$$

$$p_y = \hbar k_y$$

$$x_0 = k_y l_B^2$$

$$l_B^2 = \frac{\hbar}{eB}$$

$$= H_n(x + x_0) \cdot e^{-\frac{(x+x_0)^2}{2l_B^2}}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\omega_c}$$

$$1) \mathbf{B} \cdot \hat{z} \rightarrow \vec{A} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$\boxed{H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2}$$

$$p_y = \hbar k_y$$

$$\boxed{K = \frac{(eB)^2}{m}}$$

$$\boxed{x_0 = k_y l_B^2}$$

$$\boxed{l_B^2 = \frac{\hbar}{eB}}$$

$$\psi_n(x, k_y) = H_n(x + x_0) \cdot e^{-\frac{(x+x_0)^2}{2l_B^2}}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{1}{\dots}$$

$$1) \vec{B} \cdot \hat{z} \rightarrow \vec{A} = (0, -x) B \rightarrow$$

$$H = \frac{\vec{p}^2}{2m} \rightarrow \frac{p_x^2}{2m} + \frac{(p_y + eBx)^2}{2m} =$$

$$\boxed{H = \frac{p_x^2}{2m} + \frac{1}{2} K (x + x_0)^2}$$

$$p_y = \hbar k_y$$

$$\boxed{K = \frac{(eB)^2}{m}}$$

$$\boxed{x_0 = k_y l_B^2}$$

$$\boxed{l_B^2 = \frac{\hbar}{eB}}$$

$$\psi_n(x, k_y) = H_n(x + x_0) \cdot e^{-\frac{(x+x_0)^2}{2l_B^2}}$$

$$E_n = \hbar \omega_c \left(n + \frac{1}{2}\right)$$

$\gamma \lambda_B$

$\lambda_B - e_B$

$$o) - e - \frac{(x + x_0)^2}{2\lambda_B^2}$$

$$\omega_c = \sqrt{\frac{k}{m}}$$

$$x_B - e_B$$

$$\frac{(x+x_0)^2}{2x_B^2}$$

$$\omega_c = \sqrt{\frac{k}{m}}$$

$$= \sqrt{\frac{(e_B)^2}{m^2}} = \frac{e_B}{m}$$



$$-eE$$

$$\frac{\partial p}{\partial z} = \frac{eB}{m}$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE (\omega_c)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \dots}$$



$$0 = -eE - \omega_c P_y - \frac{1}{\tau} \omega_c P_y$$

$$\langle P_y \rangle = eE \left(\omega_c \tau \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$

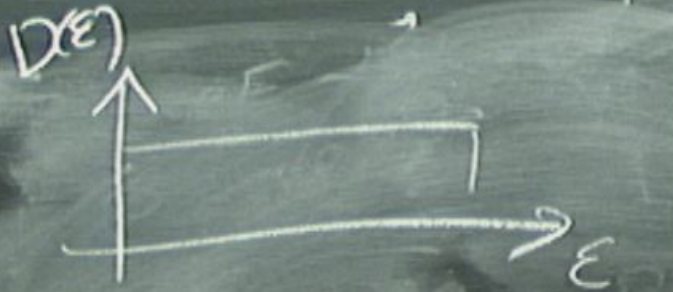


$$\sqrt{\frac{eB\hbar}{m^2}} = \frac{eB}{m}$$

$$0 = -eE - \omega_c P_y - \frac{1}{2} \omega_c P_y$$

$$\langle P_y \rangle = eE (\omega_c)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$

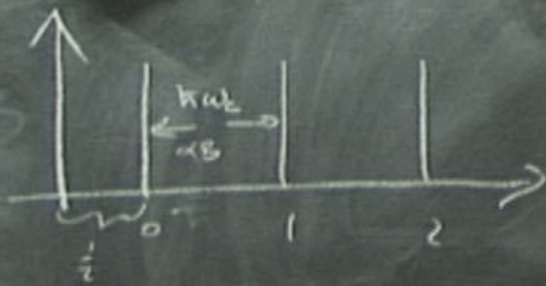
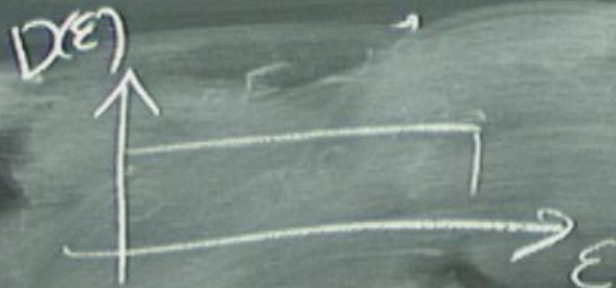


$$0 = -eE - \hbar k_z P_y$$

$$- \frac{1}{\tau} \hbar k_z P_y$$

$$\langle P_y \rangle = eE \left(\frac{\hbar k_z}{m} \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\hbar k_z}{1 + \dots}$$



$$\sqrt{\frac{eB\hbar}{m^2}} = \frac{eB}{m}$$

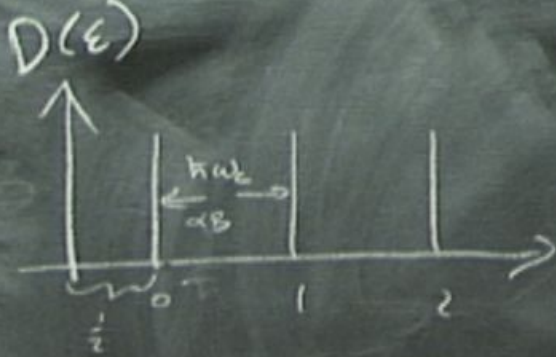
$$0 = -eE - \hbar\omega_c P_y - \frac{1}{2}\hbar\omega_c P_y$$

$$\langle P_y \rangle = eE (\omega_c)$$

$$\sigma_{xy} = \frac{ne^2\hbar}{m} \frac{\omega_c}{1 + \omega_c^2}$$



$$D(E) = \sum_k \delta(E - E_k)$$



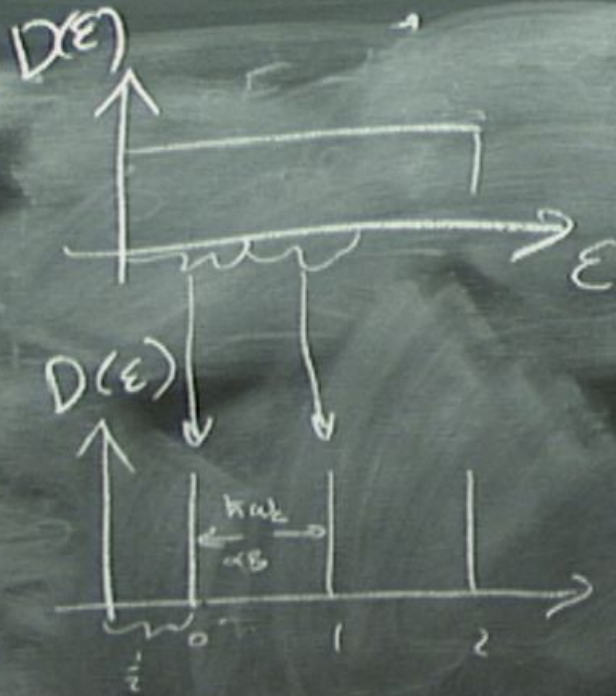
$$\sqrt{\frac{eB\hbar}{m^2}} = \frac{eB}{m}$$

$$0 = -eE - \hbar \omega_c P_y$$

$$- \frac{1}{2} \hbar \omega_c P_y$$

$$\langle P_y \rangle = eE \left(\frac{\hbar}{2m\omega_c} \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\hbar \omega_c}{1 + \omega_c^2 \tau^2}$$



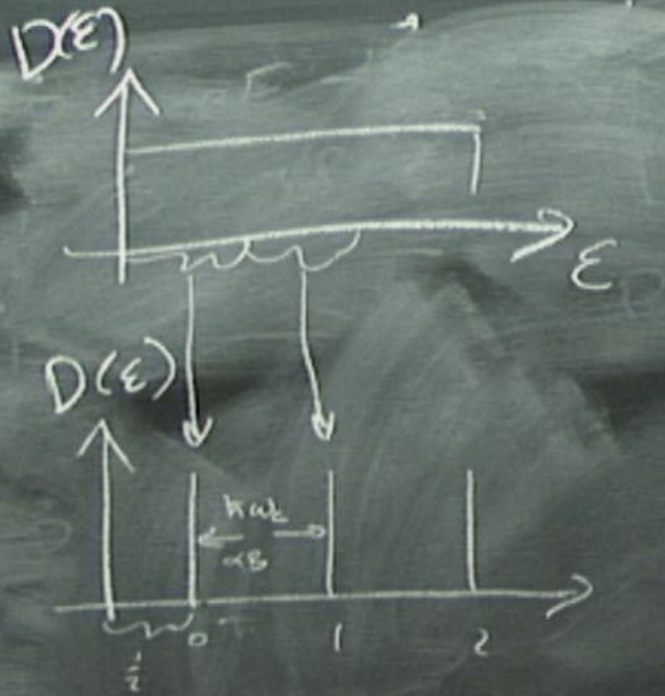
$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$

$$\sqrt{\frac{eB}{m^2}} = \frac{eB}{m}$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE (\omega_c)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$\sqrt{\frac{eB\hbar}{m^2}} = \frac{eB}{m}$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega_c \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$





$$D(E) = \sum_k \delta(E - E_k)$$

D

$$\frac{L_x}{\Delta X}$$

$$0 = -eE - \omega_c p_y$$

$$- \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\frac{\omega_c}{\omega} \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$



$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X}$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega}{1 + \omega^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

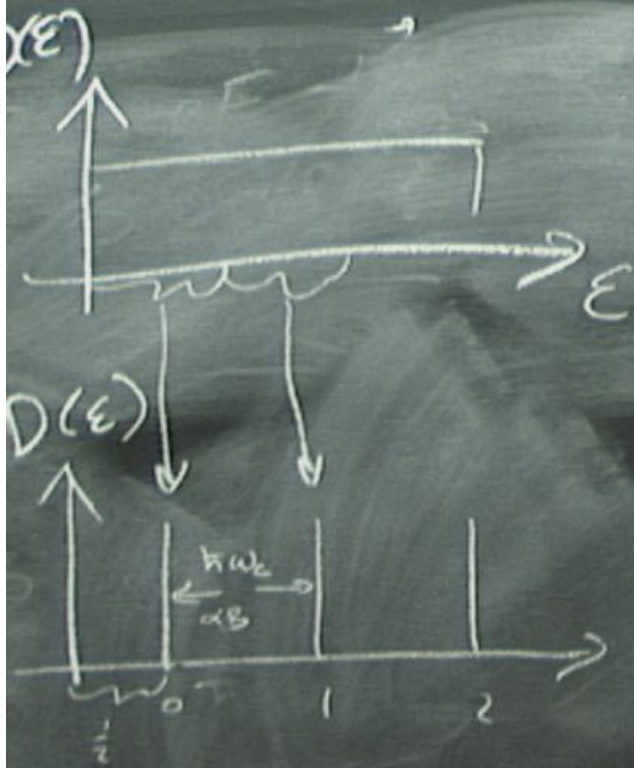
$$D_E = \frac{L_x}{\Delta X}$$

$$\Delta k = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega}{1 + \omega^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X}$$

$$\Delta X = l_B^2 \Delta k = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega}{1 + \omega^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

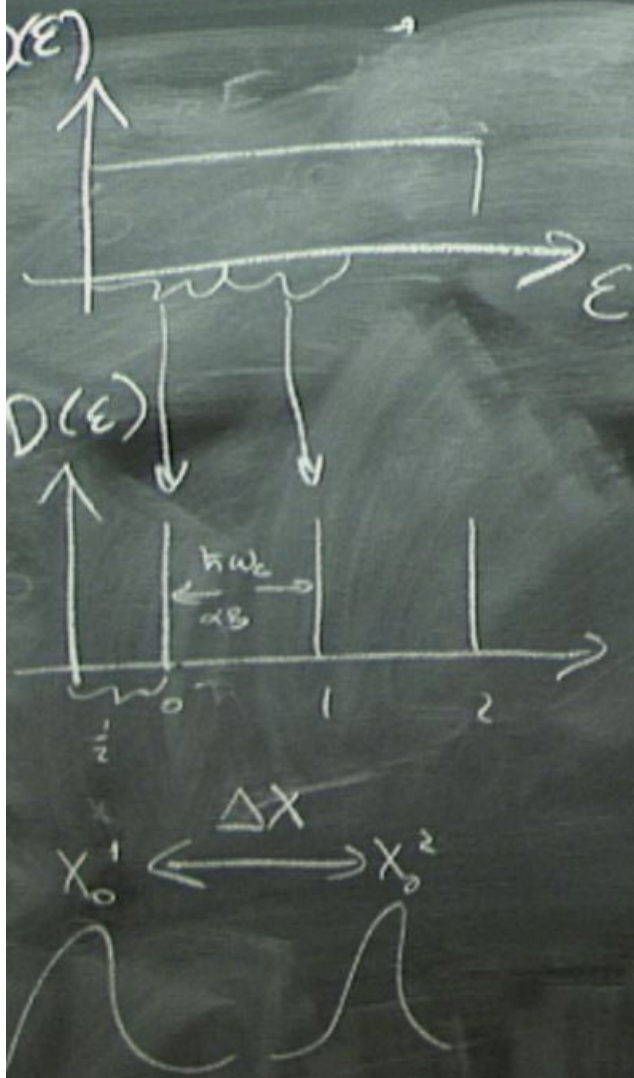
$$D_E = \frac{L_x}{\Delta X}$$

$$\Delta X = l_B^2 \Delta k = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega \right)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega}{1 + \omega^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X} = \frac{L_x}{2\pi l}$$

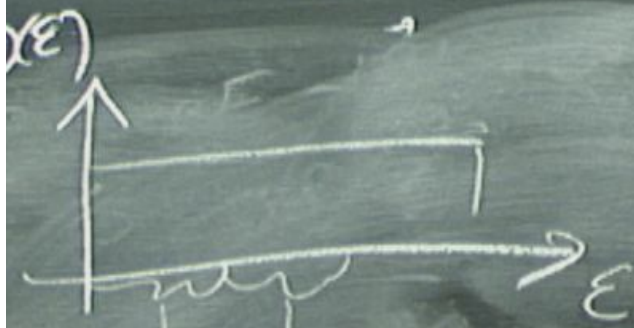
$$\Delta \epsilon = \frac{2\pi \hbar^2}{L_x^2} \left(\frac{2\pi}{L_x} \right)$$

$$0 = -eE - \hbar \omega_c p_y$$

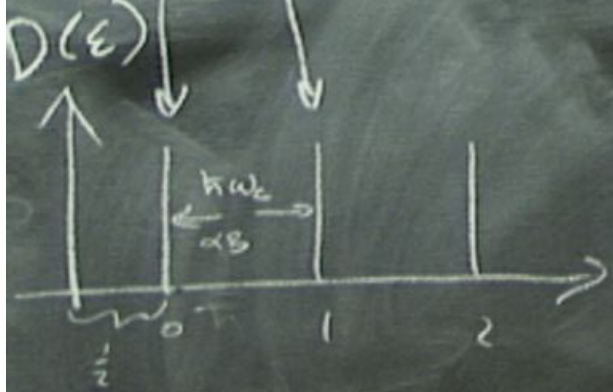
$$-\frac{1}{2} \hbar \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\frac{\hbar}{2m\omega_c} \right)$$

$$\sigma_{xy} = \frac{ne^2 \hbar}{m} \frac{\omega_c}{1 + \omega_c^2}$$



$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$



$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area } e}{2\pi \hbar}$$

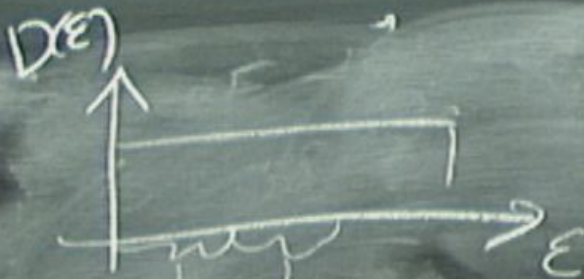
$$\Delta X = l_B^2 \Delta k_y$$



$$0 = -eE \omega_c p_y$$

$$= eE \omega_c p_y$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c}{1 + \omega_c^2 \tau^2}$$

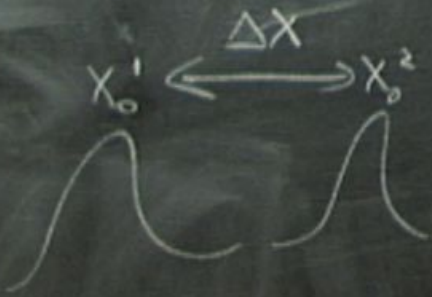


$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$



$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area } eB}{2\pi \hbar h}$$

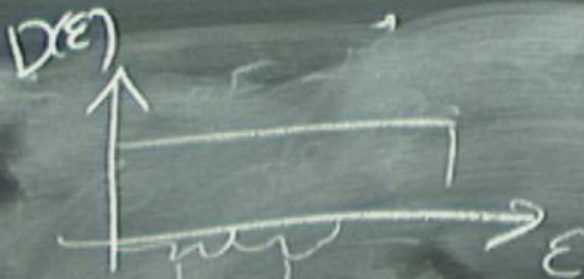
$$\Delta X = l_B^2 \Delta k_y = l^2$$



$$0 = -eE - \omega_c p_y - \frac{1}{\tau^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2} \omega \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area } (l_B)}{2\pi \hbar} \hbar$$

$$= \frac{\Phi}{\Phi_0}$$

$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$0 = -eE - \hbar\omega_c p_y - \frac{1}{\tau^2 \omega_c} p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2 \omega} \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$

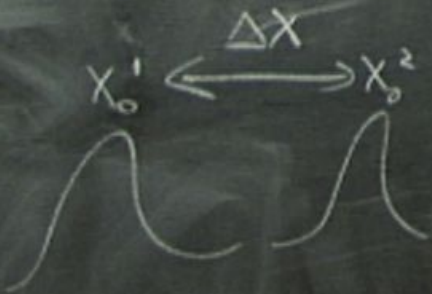


$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$



$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area } eB}{2\pi \hbar h} = \frac{\Phi}{\Phi_0}$$

$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$



$$0 = -eE - \hbar\omega_c p_y - \frac{1}{2} \hbar\omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$D(E) = \sum_{\mathbf{k}} \delta(E - E_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area } l_B}{2\pi \hbar} = \frac{\Phi}{\Phi_0}$$

$$\Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$\nabla \cdot D_{LL}$

$$0 = -eE - \omega_c p_y - \frac{1}{\tau^2 \omega_c} p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2 \omega_c} \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$D(\epsilon) = \sum_k \delta(\epsilon - \epsilon_k)$$

$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area} \cdot \frac{eB}{h}}{2\pi \hbar h} = \frac{\Phi}{\Phi_0}$$

$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$0 = -eE - \omega_c p_y - \frac{1}{\tau^2} \omega_c p_y$$

$$eE \left(\omega + \frac{1}{\tau^2} \omega_c \right)$$

$$\frac{\omega_c \tau}{\omega_c^2 \tau^2}$$

classical

$$\sigma_{xy} = \frac{ne}{B} = v \cdot D_{LL} \cdot \frac{e}{B} = v \cdot \frac{1}{2\pi l_B^2} \cdot \frac{e}{B} =$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$D_{\epsilon} = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area} \ell_B}{2\pi \hbar} = \frac{\Phi}{\Phi_0}$$

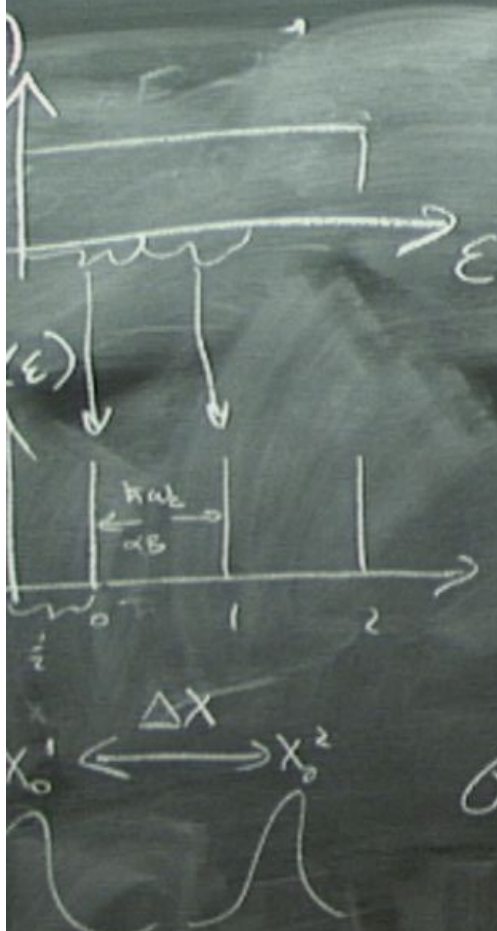
$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$\begin{aligned} \sigma_{xy}^{\text{classical}} &= \frac{ne}{B} = v \cdot D_{LL} \cdot \frac{e}{B} = \\ &= v \cdot \frac{1}{2\pi l_B^2} \cdot \frac{e}{B} = v \frac{eB}{h} \cdot \frac{e}{B} \\ &= v \frac{e^2}{h} \end{aligned}$$

$$0 = -eE - \omega_c p_y - \frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE (\omega_c + \frac{1}{2} \omega_c)$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$D_{\epsilon} = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area} \cdot l_B}{2\pi \hbar} = \frac{\Phi}{\Phi_0}$$

$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

classical

$$\sigma_{xy} = \frac{ne}{B} = v \cdot D_{LL} \cdot \frac{e}{B} = v \cdot \frac{1}{2\pi l_B^2} \cdot \frac{e}{B} = v \frac{eB}{h} \cdot \frac{e}{B}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$

$$0 = -eE - \omega_c p_y - \frac{1}{\tau^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{\tau^2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$D(\epsilon) = \sum_k \delta(\epsilon - \epsilon_k)$$

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$$l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

$$\frac{e}{B} = v \cdot D_{LL} \cdot \frac{e}{B} =$$

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$$\sigma_{xy} = v \frac{e^2}{\hbar}$$

$$0 = -eE - \omega_c p_y - \frac{1}{c^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{c^2 \omega} \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$\frac{L_x}{\Delta x} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{(\text{Area}) eB}{2\pi \hbar} = \frac{\Phi}{\Phi_0}$$

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$$\frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{(\text{Area}) e B}{2\pi \hbar h} = \frac{\Phi}{\Phi_0}$$

$$\Delta k_y = l_B^{-2} \left(\frac{2\pi}{L_y} \right)$$

$$\frac{e}{B} = v \cdot D_{LL} \cdot \frac{e}{B} =$$

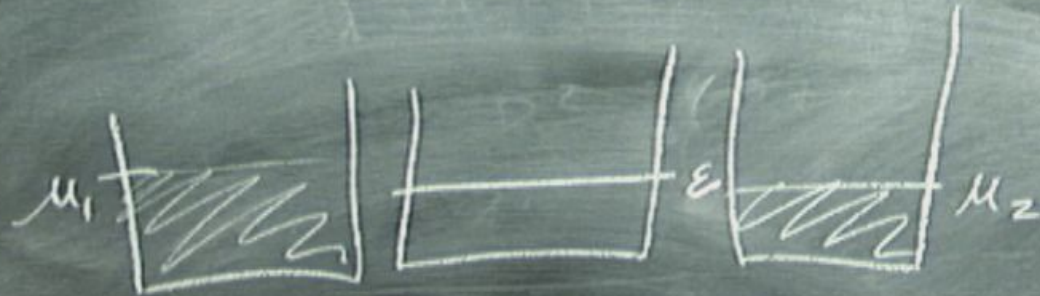
$$= v \cdot \frac{1}{2\pi l_B^2} \cdot \frac{e}{B} = v \frac{e B}{h} \cdot \frac{e}{B}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$

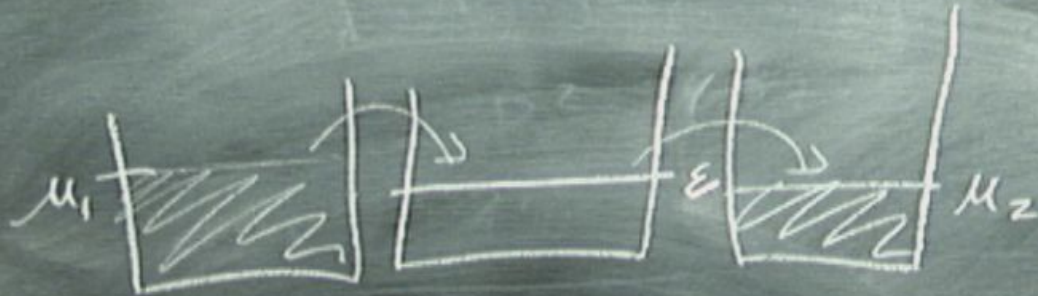
$$0 = -eE - \omega_c p_y - \frac{1}{c^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{c^2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$



$$\mu_1 - \mu_2 = eV$$



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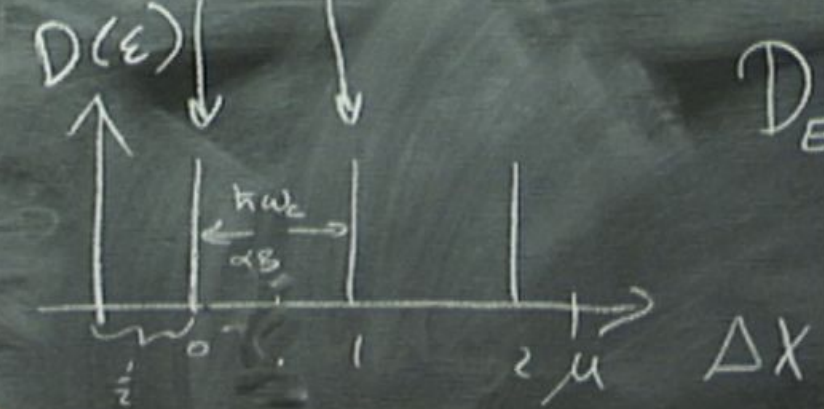
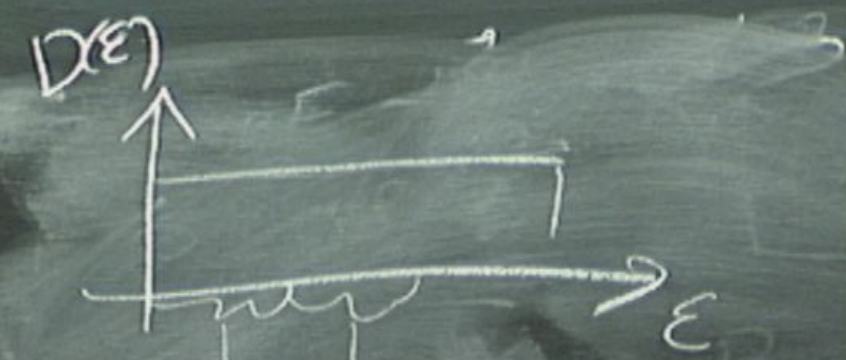
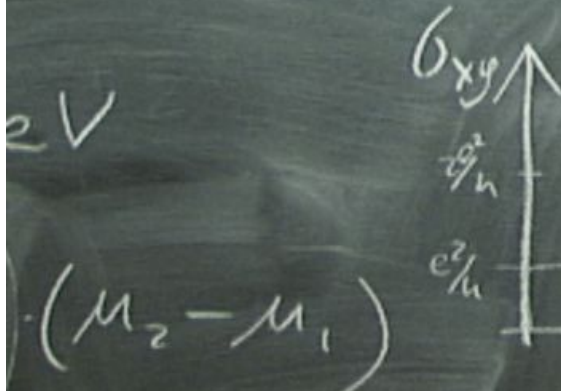
$$I = \frac{e^2}{h} (\mu_2 - \mu_1)$$

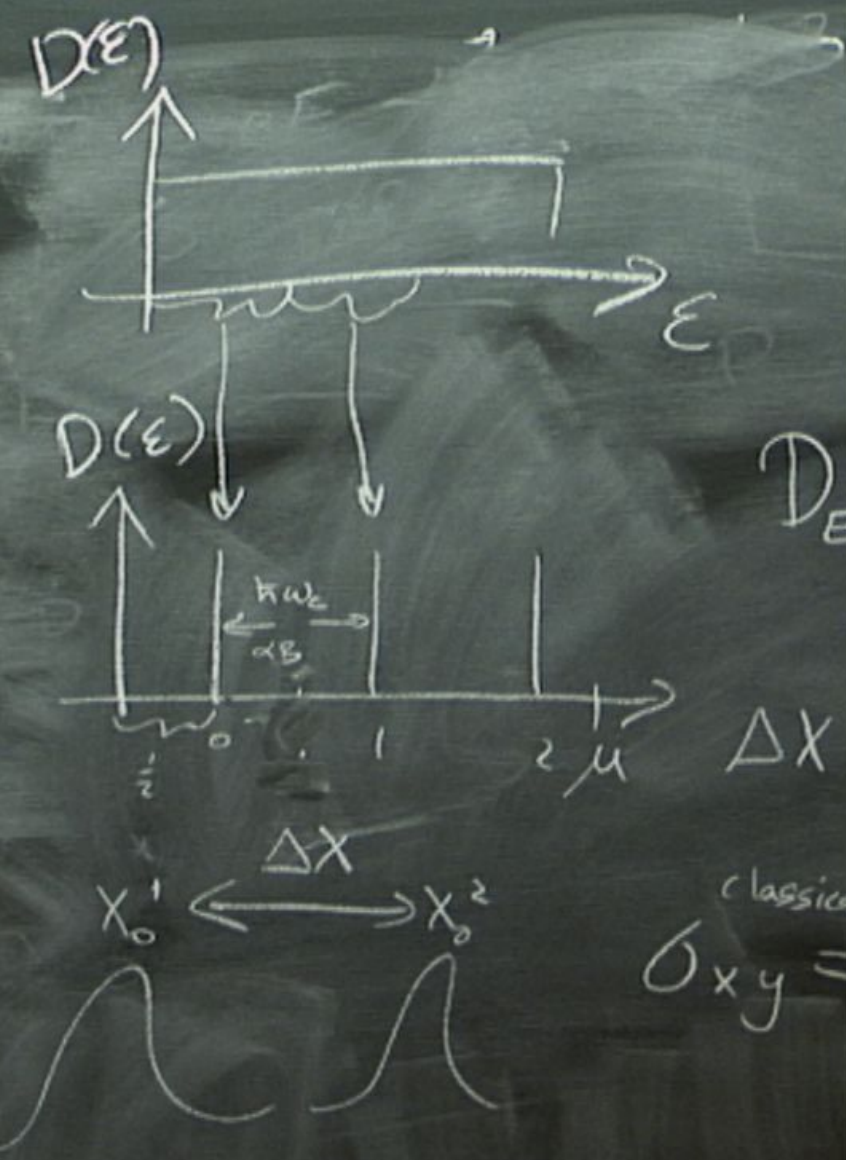
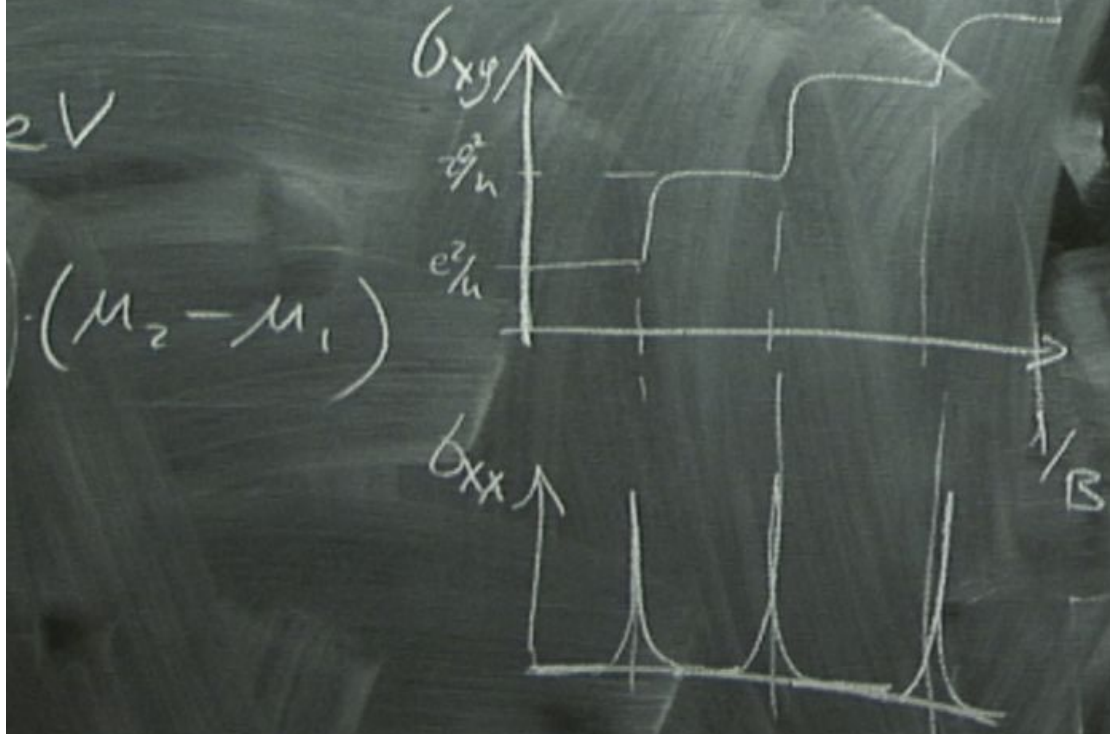


$$\mu_1 - \mu_2 = eV$$

$$I = \frac{e^2}{h} \mu_1$$







$$D(\epsilon) = \sum_{\mathbf{k}} \delta(\epsilon - \epsilon_{\mathbf{k}})$$

$$D_E = \frac{L_x}{\Delta X} = \frac{L_x L_y}{2\pi l_B^2} = \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area} \cdot \frac{1}{l_B}}{2\pi \hbar} = \frac{\Phi}{\Phi_0}$$

$$\Delta X = l_B^2 \Delta k_y = l_B^2 \left(\frac{2\pi}{L_y} \right)$$

classical

$$\sigma_{xy} = \frac{ne}{B} = V \cdot D_{LL} \cdot \frac{e}{B} = V \cdot \frac{1}{2\pi l_B^2} \cdot \frac{e}{B} = V \frac{e}{h} \frac{eB}{B}$$

$$\sigma_{xy} = V \frac{e^2}{h}$$

$$0 = -eE - \omega_c p_y - \frac{1}{c^2} \omega_c p_y$$

$$\langle p_y \rangle = eE \left(\omega + \frac{1}{c^2} \omega_c \right)^{-1}$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m} \frac{\omega_c \tau}{1 + \omega_c^2 \tau^2}$$

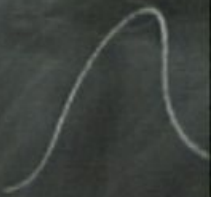
$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} (eBx + p_y + \alpha E)^2 - A$$

$$2 \cdot \alpha E \cdot eBx$$



x_0

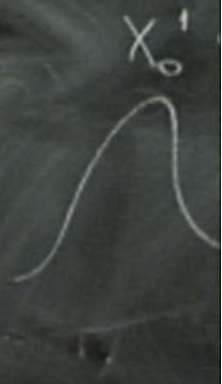
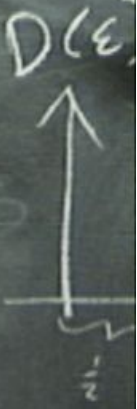


$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \underbrace{\alpha E}_{\frac{mE}{m}} \right)^2 - A$$

$$\cancel{2} \cdot \frac{\cancel{2} E \cdot \cancel{2} B x}{\cancel{2} m} = \cancel{2} E x$$

$$\alpha = \frac{m}{B}$$

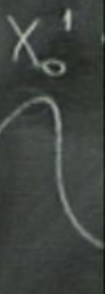


$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \frac{mE}{m} \right)^2 - \frac{A}{m}$$

$$\cancel{\frac{2 \cdot 2E \cdot 2Bx}{2m}} = \cancel{2Ex}$$

$$\alpha = \frac{m}{B}$$



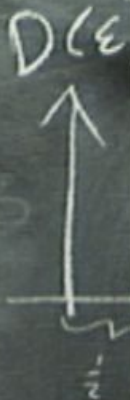
$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \frac{mE}{m} \right)^2 - \frac{A}{m}$$

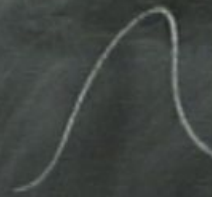
$$\cancel{2} \cdot \frac{\cancel{2} E \cdot \cancel{2} B x}{\cancel{2} m} = \cancel{2} E x$$

$$\alpha = \frac{m}{B}$$

J



x_0



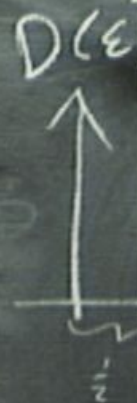
$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \frac{\alpha E}{m} \right)^2 - \frac{A}{m}$$

$$\cancel{\frac{2 \cdot \alpha E \cdot eBx}{2m}} = \cancel{eE}x$$

$$\alpha = \frac{m}{B}$$

$$\langle p_y \rangle = \langle \psi_p | \hat{p}_y | \psi_p \rangle$$



x_0



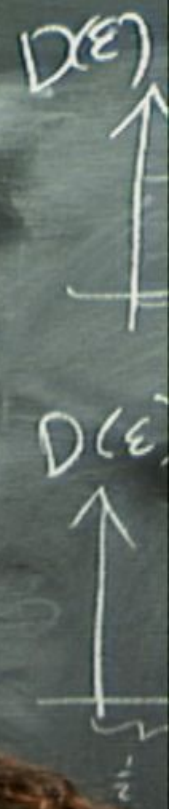
$$H = \frac{p_x^2}{2m} + \frac{1}{2} \kappa (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \frac{\alpha E}{\hbar \kappa} \right)^2 - \frac{A}{m}$$

$$\cancel{\frac{2 \cdot \alpha E \cdot eBx}{2m}} = \cancel{eEx}$$

$$\alpha = \frac{\hbar}{B}$$

$$\langle p_y \rangle = \langle \psi_p | \hat{p}_y | \psi_p \rangle = \langle \psi_p | (p_y - eAx) | \psi_p \rangle$$



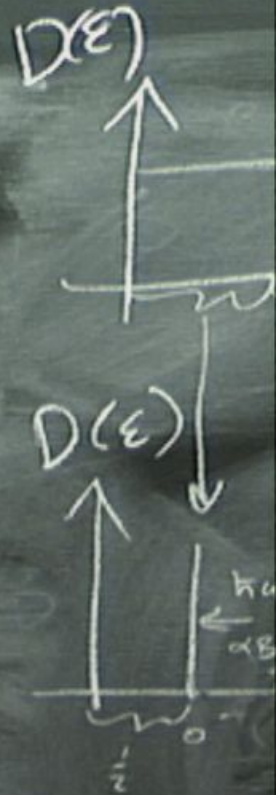
$$H = \frac{p_x^2}{2m} + \frac{1}{2} k (x + p_y)^2 + eEx$$

$$= \frac{p_x^2}{2m} + \frac{1}{2m} \left(eBx + p_y + \underbrace{\alpha E}_{\frac{mE}{m}} \right)^2 - \frac{A}{m}$$

$$\cancel{2} \cdot \frac{\cancel{2} E \cdot \cancel{e} B x}{\cancel{2} m} = \cancel{e} E x$$

$$\alpha = \frac{m}{B}$$

$$\langle p_y \rangle = \langle \psi_p | \hat{p}_y | \psi_p \rangle = \langle \psi_k | (p_y - eAy) | \psi_k \rangle$$



$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_D^2}}$$

$\frac{k l_D^2}{2}$ $\frac{k l_D^2}{2}$ $\frac{k l_D^2}{2}$

$$x e^{-ax^2} dx = 0$$

$$= \frac{\text{Area}}{2\pi l_D^2} = \frac{\text{Area}}{2\pi l_D^2}$$

$$= \frac{\Phi}{\Phi_0}$$

$$0 = -eE - \omega_c$$

$$-\frac{1}{2} \omega_c p_y$$

$$\langle p_y \rangle = eE$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m}$$

$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_B^2}}$$

$\frac{1}{2} \left(\frac{2mE}{\hbar^2} \right)^{-1/2}$
 $\frac{1}{2} \left(\frac{2mE}{\hbar^2} \right)^{-1/2}$

$$x e^{-ax^2} dx = 0$$

$$= \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area}}{2\pi \hbar^2}$$

$$= \frac{\Phi}{\Phi_0}$$

$$0 = -\rho \vec{E} - \omega_c$$

$$\langle P_y \rangle$$

$$\sigma_{xy} =$$

$$\langle \psi_k | P_y - eA + \frac{mE}{\hbar^2} eB | \psi_k \rangle = m e E$$

$$\psi_k = e^{-\frac{(x-x_0+x_1)^2}{2l_0^2}}$$

$\frac{1}{2} \left(\frac{1}{l_0^2} \right)$ $\frac{1}{2} \left(\frac{1}{l_0^2} \right)$

$$x e^{-ax^2} dx = 0$$

$$\langle P_y \rangle = m e E \langle \psi_k | \psi_k \rangle$$

$$\langle \psi_k | P_y - eA + \frac{mE}{eB} eB | \psi_k \rangle = \langle m e E \rangle$$

$$= \frac{\text{Area}}{2\pi l_0^2} = \frac{\text{Area}}{2\pi \hbar^2}$$

$$= \frac{\Phi}{\Phi_0}$$

$$0 = -eE - \omega_c$$

$$-\frac{1}{2} \omega_c P_y$$

$$\langle P_y \rangle = eE$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m}$$

$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_0^2}}$$

$\frac{1}{2} \frac{mE}{\hbar^2}$
 $\frac{1}{2} \frac{mE}{\hbar^2}$

$$x e^{-ax^2} dx = 0$$

$$J_y = \frac{m e E}{B} \cdot V$$

$$\langle P_y \rangle = \frac{m e E}{B} \langle \psi_k | \psi_k \rangle$$

$$\langle \dots \rangle = \langle \psi_k | P_y - eA + \frac{mE}{B} e | \psi_k \rangle = \langle m e E \rangle$$

$$= \frac{\text{Area}}{2\pi l_0^2} = \frac{\text{Area}}{2\pi \hbar^2}$$

$$= \frac{\Phi}{\Phi_0}$$

$$0 = -eE - \omega_c$$

$$-\frac{1}{2} \omega_c P_y$$

$$\langle P_y \rangle = eE$$

$$\sigma_{xy} = \frac{ne^2 \tau}{m}$$

$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_B^2}}$$

$\frac{1}{2} \left(\frac{2}{k l_B^2} \right) \left(\frac{1}{2} \frac{2}{k l_B^2} \right)$

$$x e^{-ax^2} dx = 0$$

$$J_y = \frac{m e E}{B} \cdot v \frac{e}{m}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$

$$\langle P_y \rangle = \frac{m e E}{B} \langle \psi_k | \psi_k \rangle$$

$$\langle \psi_k | P_y - eA + \frac{m E}{B} e | \psi_k \rangle = \langle m e E \rangle$$

$$= \frac{\text{Area}}{2\pi l_B^2} = \frac{\text{Area}}{2\pi \hbar^2} = \frac{\Phi}{\Phi_0}$$

$$0 = -eE - \omega_c P_y - \frac{1}{2} \omega_c P_y$$

$$\langle P_y \rangle = eE$$

$$\sigma_{xy} = \frac{n e^2 v}{m}$$

$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_0^2}} e^{ikx}$$

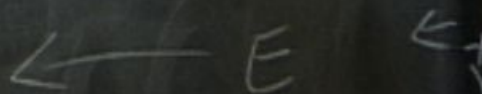
$$\int x e^{-ax^2} dx = 0$$

$$J_y = \frac{m e E}{B} \cdot v \frac{e}{m}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$

$$\langle P_y \rangle = \frac{m e E}{B} \langle \psi_k | \psi_k \rangle$$

$$\langle \psi_k | \psi_k \rangle = \langle \psi_k | P_y - eA + \frac{mE}{B} e | \psi_k \rangle = \langle m e E \rangle$$



$$\psi_k = e^{-\frac{(x+x_0 + x_1)^2}{2l_0^2}}$$

$\frac{k l_0^2}{2} \rightarrow \frac{m E}{B}$



$$\int x e^{-ax^2} dx = 0$$

$$J_y = \frac{m E}{B} \cdot v \frac{e}{m}$$

$$\delta_{xy} =$$

$$\langle P_y \rangle = \frac{m E}{B} \langle \psi_0 | \psi_k \rangle$$

$$\langle \psi_k | = \langle \psi_0 | P_y - e A + \frac{m E}{B} e$$

$$\psi_k = e^{-\frac{(x+x_0+x_1)^2}{2l_0^2}}$$

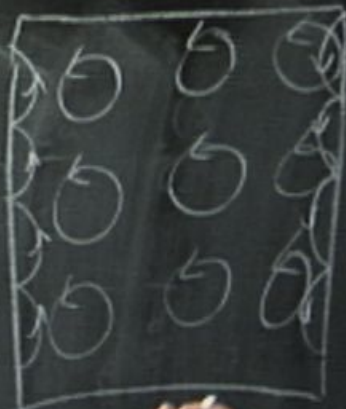
$\frac{k l_0^2}{2} \rightarrow \frac{m E}{B}$
 \downarrow
 $\frac{m E}{B}$



$$\int x e^{-ax^2} dx = 0$$

$$J_y = \frac{m E}{B} \cdot v \frac{e}{m}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$



$$\langle P_y \rangle = \frac{m E}{B} \langle \psi_0 | \psi_k \rangle \left(P_{xy} = \frac{h}{e^2} = 13 k \Omega \right)$$

$$\langle \psi_k | \psi_k \rangle = \langle \psi_k | P_y - e A + \frac{m E}{B} e | \psi_k \rangle = \langle m E \rangle$$

$$\psi_k = e^{-\frac{(x-x_0 + x_1)^2}{2l_0^2}} e^{ikx}$$



$$\int x e^{-ax^2} dx = 0$$

$$J_y = \frac{m e E}{B} \cdot v \frac{e}{m}$$

$$\sigma_{xy} = v \frac{e^2}{h}$$

$$\langle P_y \rangle = \frac{m e E}{B} \langle \psi_0 | \psi_k \rangle \left(P_{xy} = \frac{h}{e^2} = 13 \text{ k}\Omega \right)$$

$$\langle \psi_k | \psi_k \rangle = \langle \psi_k | P_y - eA + \frac{mE}{B} e | \psi_k \rangle = \langle m e E \rangle$$