Title: Observational tests of eternal inflation

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URL: http://pirsa.org/11010114

Abstract: In the picture of eternal inflation, our observable universe resides inside a single bubble nucleated from an inflating false vacuum. Some of the theories giving rise to eternal inflation predict that we have causal access to collisions with other bubble universes, providing an opportunity to confront these theories with observation. In this talk, I will outline progress on the theoretical description of eternal inflation and bubble collisions, and present results from the first search for the effects of bubble collisions in the WMAP 7-year data.

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Observational tests of eternal inflation

Matthew C. Johnson Perimeter Institute

In collaboration with: Stephen Feeney Daniel Mortlock Hiranya Peiris

arXiv:1012.1995

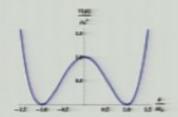
arXiv:1012.3667

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Theories of particle physics with a unique vacuum are hard to come by.

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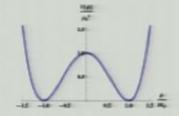
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- Spontaneous symmetry breaking gives rise to multiple vacua:



Happens in the standard model, Grand Unified Theories, Supersymmetry....

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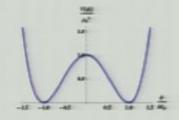
A more extreme example arises in string theory:



The extra dimensions can assume different sizes, topologies, shapes = many 4D vacua!

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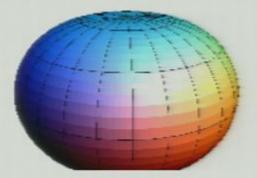
• How did we evolve into this vacuum? Are there cosmological signatures?

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One proposal: all vacua are realized somewhere.



Tunneling = Bubble nucleation.

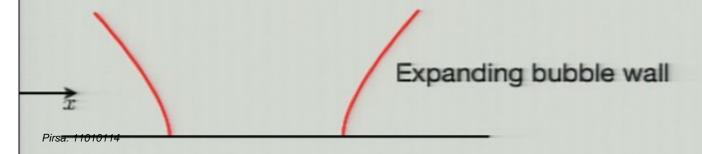


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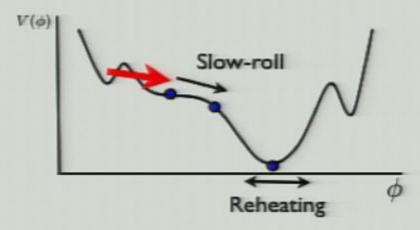
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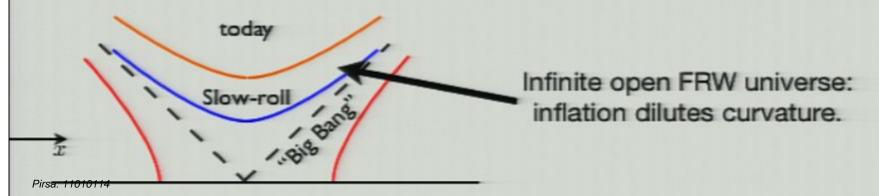
Our cosmology can be embedded inside the bubble:



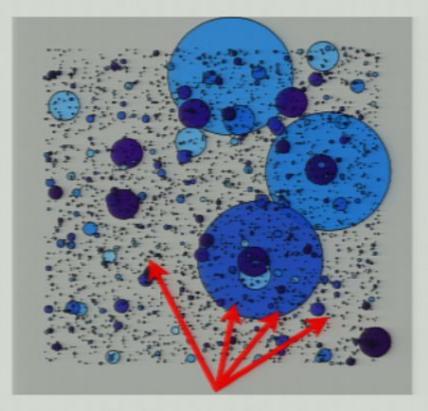
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Our cosmology can be embedded inside the bubble:



With positive vacuum energy, bubbles form, but space expands between them: inflation can become eternal.



Many cosmologies evolving to many vacua.

We are somewhere in here.

Science or science fiction?

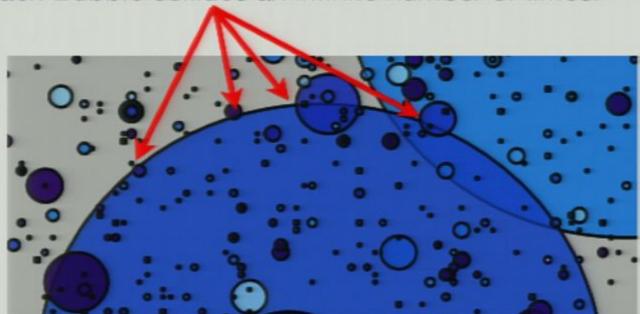
- This picture seems to be a generic consequence of extra dimensions and multiple positive energy vacua.
- Strong theoretical motivation, but is it experimentally verifiable?

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Each Bubble collides an infinite number of times!



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• Who gets to observe these collisions and what would they see?

Bubble collisions

- Two necessary conditions to see a collision:
 - 1) Observers must exist to the future of a collision to see it.

2) Such observers should not be rare.

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Detectable: lead to small perturbations on our observed cosmology.

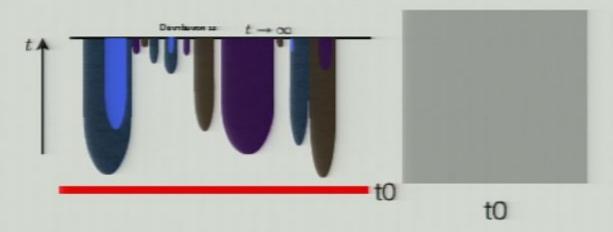
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Bubble collisions

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 - 2) Such observers should not be rare.
- Further, we are most interested in collisions that are
 Detectable: lead to small perturbations on our observed cosmology.
- To determine the observability of bubble collisions we need to assess:
 - 1) How lucky do we need to be?
 - 2) What is the spacetime structure in the aftermath of a collision?
 - 3) What could the observational effects of a collision be?

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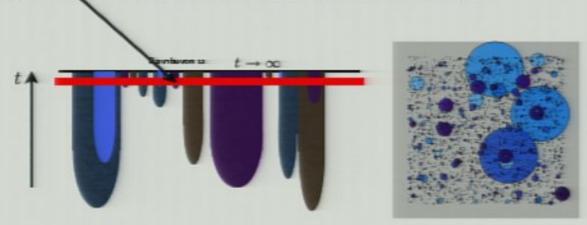
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- At some initial time, the universe was in the false vacuum:
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- Collisions do not perturb the bubble interior, and the original open FRW foliation is still sensible:

$$ds^{2} = -d\tau^{2} + a^{2}(\tau) \left[d\xi^{2} + \sinh^{2} \xi \ d\Omega_{2}^{2} \right]$$

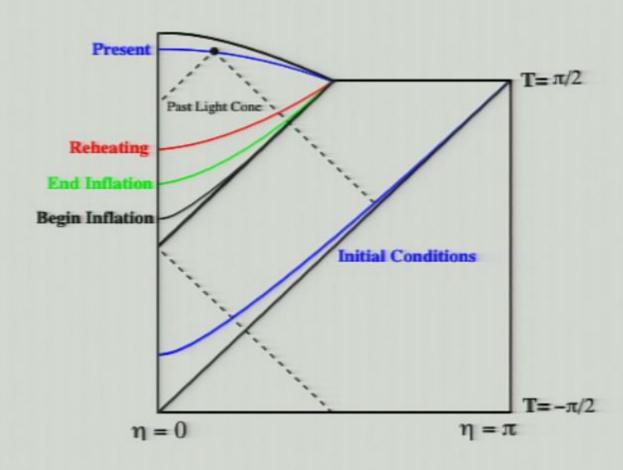
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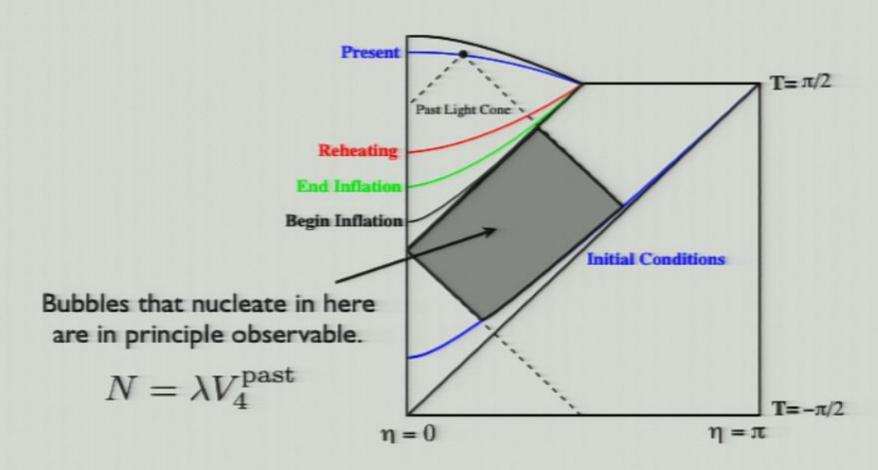
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Bubbles are approximated as light cones.





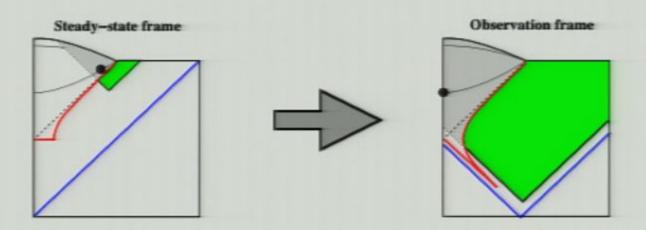
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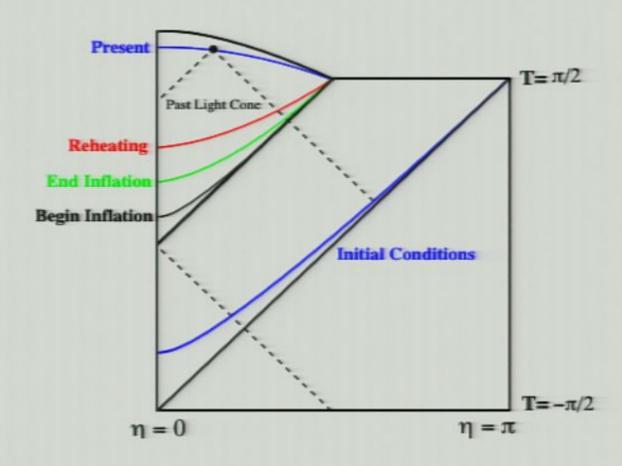
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nitial value surface

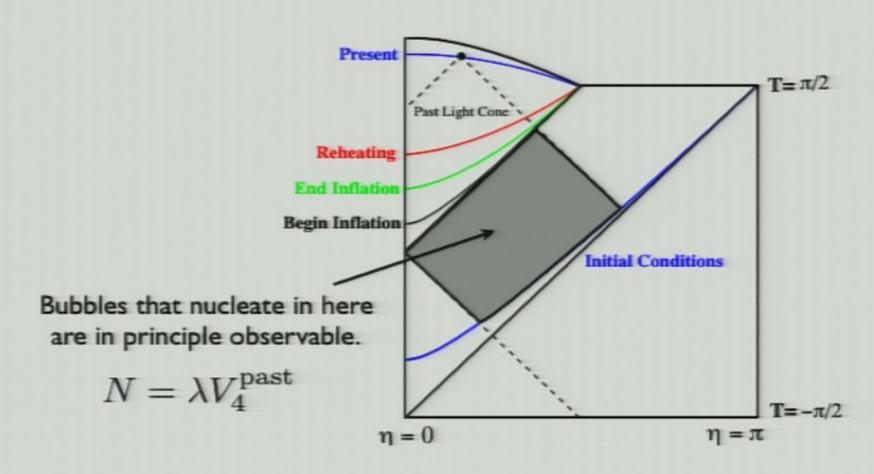
The initial value surface breaks the original SO(3,1) symmetry of the bubble: we can be boosted with respect to the initial value surface.



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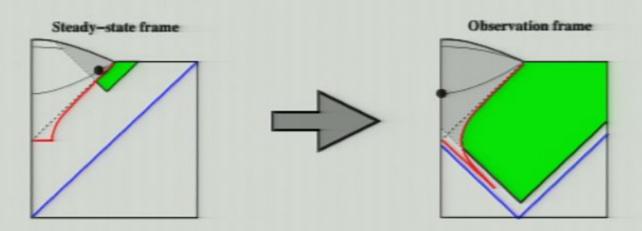
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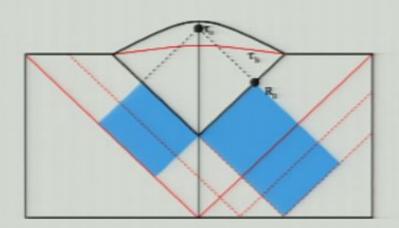
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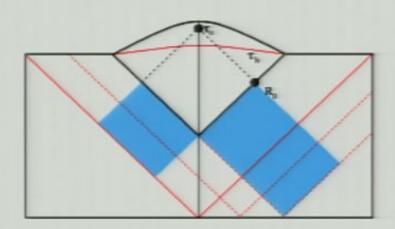
 If we are not at rest with respect to the initial value surface, the direction of arrival for collisions is anisotropic.
 Garriga, Guth, and Vilenkin



$$N \simeq \frac{4\pi\lambda}{3H_F^4} \left(\frac{H_F^2}{H_I^2}\right) \xi_o$$

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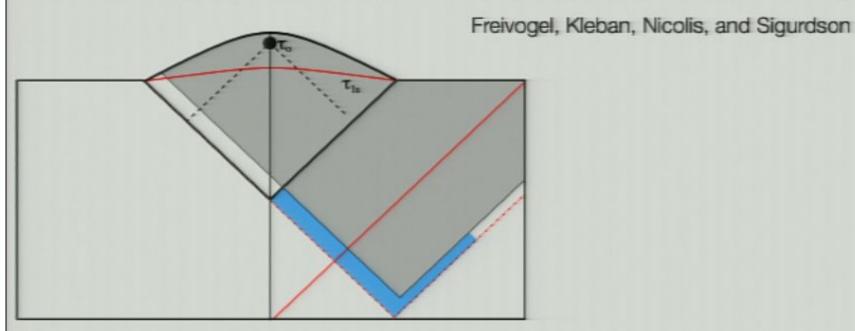
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• All of the volume is at large ξ_o , so if we are at a randomly chosen position, we should have many collisions in our past.

Aguirre, Johnson, and Shomer

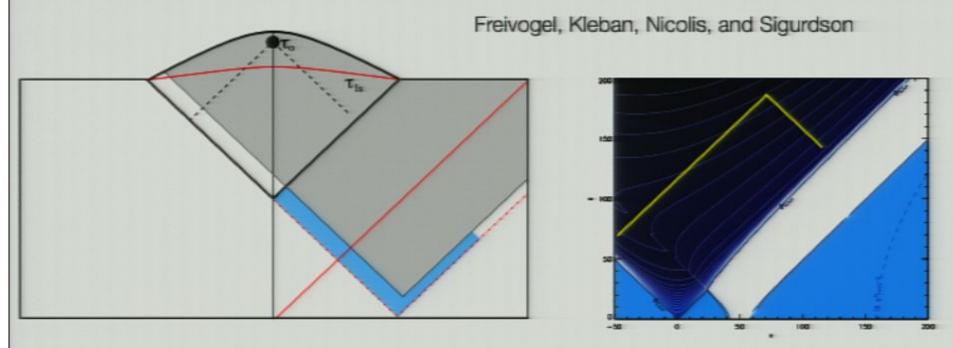
But.....

Most such collisions are larger than the observable portion of the SLS.



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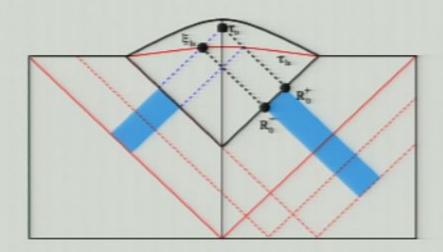
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 This means that the only conceivable signatures are at large wavelengths: hard to see....

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 Counting only collisions which intersect the observable part of the surface of last scattering:

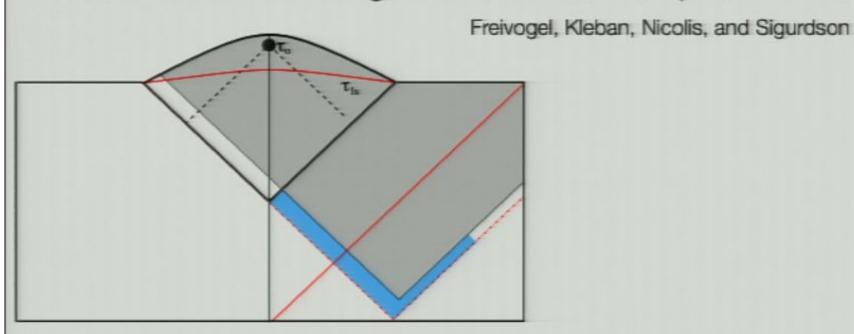


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Freivogel, Kleban, Nicolis, and Sigurdson

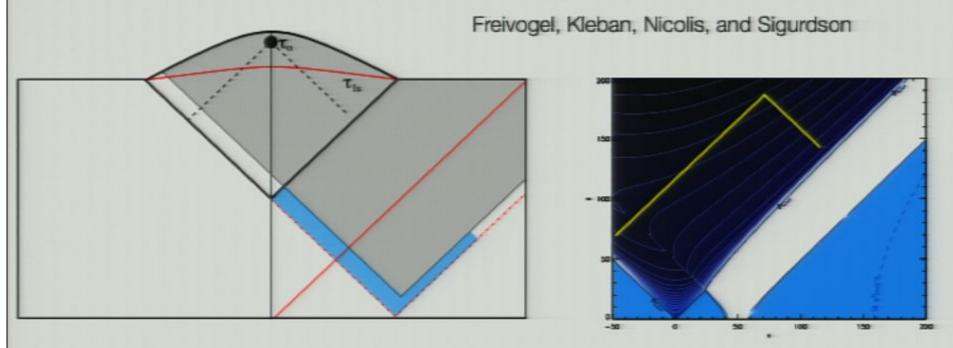
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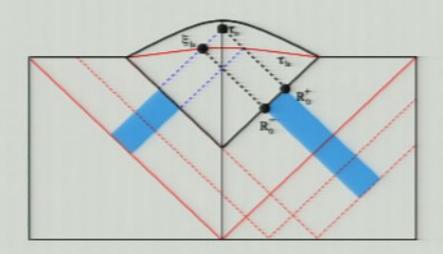
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Bottom line

- If collisions are survivable, we almost certainly have one in our past.
- But, to expect more than 1 visible collision to our past,
- at least one type of transition from the false vacuum must satisfy:

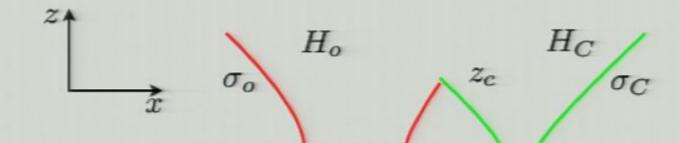
$$\lambda H_F^{-4} > \left(\frac{H_I}{H_F}\right)^2$$

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Bubble collision spacetime

- The collision spacetime has SO(2,1) symmetry.
- Hyperbolic Birkhoff's theorem: no gravitational wave solutions, just as for a spherical source!
- Thin wall matching:

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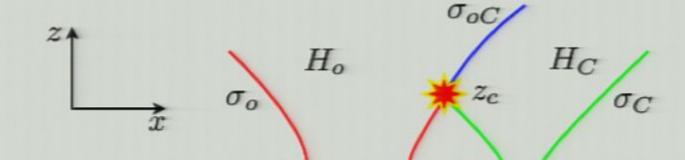


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- Accelerates to the right if $H_C^2 H_o^2 + 16\pi^2\sigma_{oC}^2 > 0$ (roughly $H_C > H_o$)

 Aguirre and Johnson also Kleban, Chang, and Levi

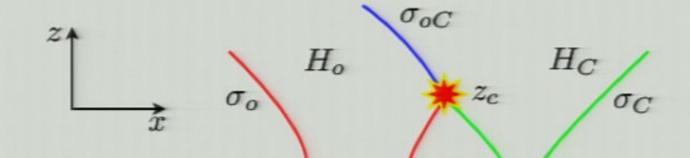


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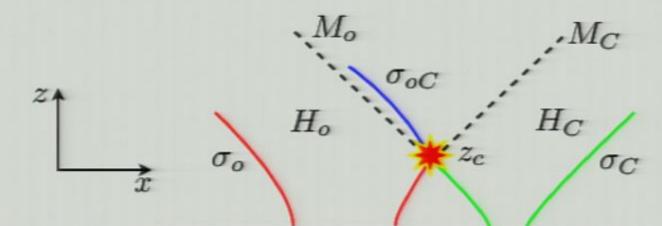


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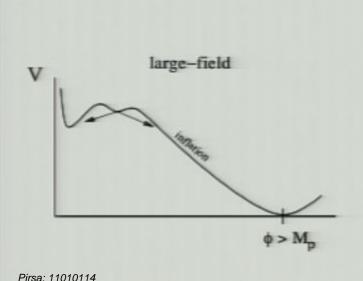
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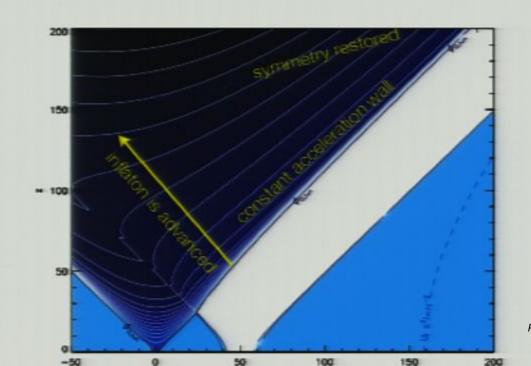
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- Energy conservation indicates there are extra debris shells: M_o, M_C



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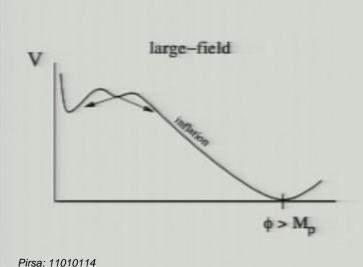
- Performing numerical simulations, there are examples where inflation can survive a collision.
- The original FRW symmetry is approximately restored to the future of the collision.

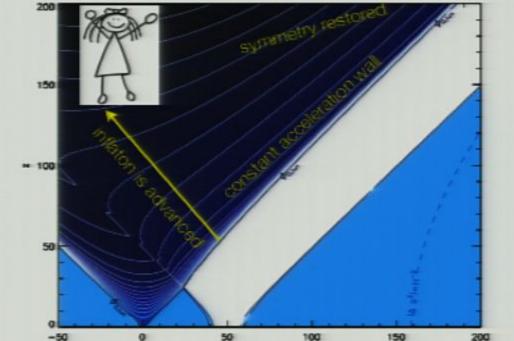




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Theory

Assessing the details of this story has been the topic of many papers:

Aguirre, Chang, Czech, Dahlen, Easther, Garriga, Giblin, Guth, Hui, Kleban, Larjo, Levi, Lim, Nicolis, Sigurdson, Shomer, Tysanner, Vilenkin.....

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- Much more work to be done on:
 - Possible outcomes of collisions.
 - Model building to see in what cases we get observable collisions.
 - Simulations of bubble collisions.
 - The exact imprint left in the CMB.

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Theory

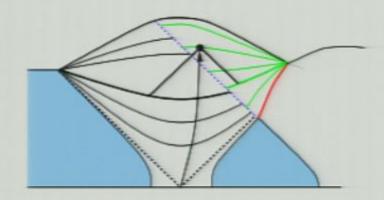
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- Much more work to be done on:
 - Possible outcomes of collisions.
 - Model building to see in what cases we get observable collisions.
 - Simulations of bubble collisions.
 - The exact imprint left in the CMB.
- For this talk: What is a good guess for the signature? How might we look for signatures of this type?

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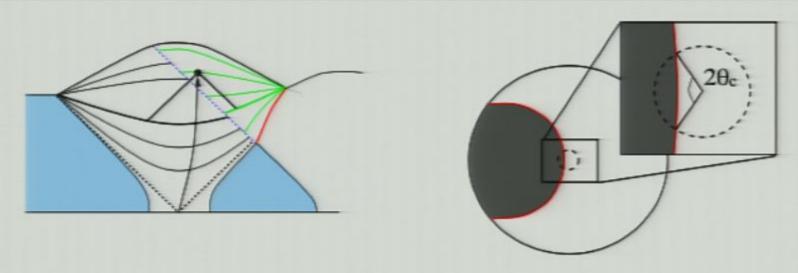
Observational effects



At last scattering, there will be a causal boundary for the collision.

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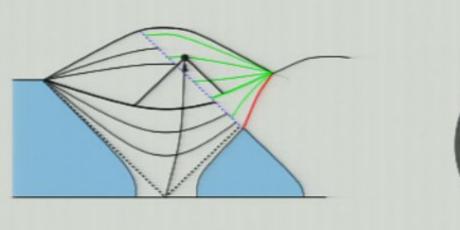
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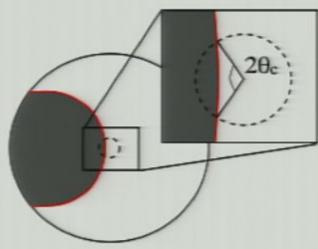


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Observational effects





- At last scattering, there will be a causal boundary for the collision.
- A collision has approximate planar symmetry in vicinity of our PLC.
- A collision will have azimuthal symmetry on the CMB sky.



Observability

Assume that the inflationary fluctuations are modulated by the collision:

$$\frac{\delta T(\hat{\mathbf{n}})}{T_0} = (1 + f(\hat{\mathbf{n}}))(1 + \delta(\hat{\mathbf{n}})) - 1,$$

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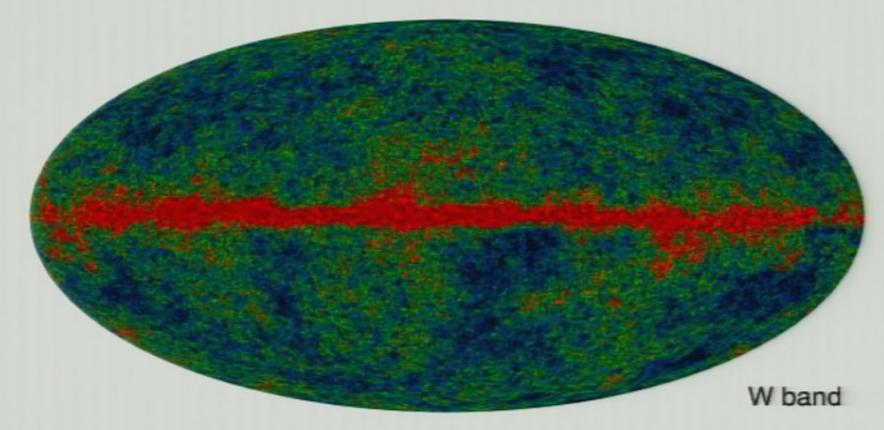
 Since the collision is a pre-inflationary relic, it is stretched. We can Taylorexpand and keep the lowest order terms:

$$f_{\mathbf{z}_0} = \begin{bmatrix} \frac{\theta_{\text{crit}}}{1 - \cos \theta_{\text{crit}}} + \frac{z_0 - z_{\text{crit}}}{1 - \cos \theta_{\text{crit}}} \cos \theta \end{bmatrix} \Theta(\theta_{\text{crit}} - \theta)$$

Confirmed by simulations, and can be realized in toy models.

Data analysis

• How do we find evidence for a bubble collision from a full-sky map?



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- The optimal way to test the hypothesis that there might be bubble collisions on the CMB sky: Bayesian model selection.
- How much better does one model describe the data than another?

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- M_0 $_{\Lambda {
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- $M_{\rm b}$ $\Lambda {\rm CDM}$ cosmology & parameters in the power spectrum + N bubble collisions described by $f_i(\hat{n}_i), \ (i=1\dots N)$

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$$\frac{P(M_{\rm b}|\mathbf{d})}{P(M_{\rm 0}|\mathbf{d})} = \frac{P(M_{\rm b})}{P(M_{\rm 0})} \frac{P(\mathbf{d}|M_{\rm b})}{P(\mathbf{d}|M_{\rm 0})} \qquad \qquad \rho \equiv \frac{P(\mathbf{d}|M_{\rm b})}{P(\mathbf{d}|M_{\rm 0})}$$

model evidence

evidence ratio

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How do we calculate the evidence ratio?

$$P(\mathbf{d}|M) = \int P(\mathbf{\Theta}, M) P(\mathbf{d}|\mathbf{\Theta}, M) \, \mathrm{d}^n \mathbf{\Theta}$$
 prior likelihood model parameters

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 data model covariance

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 At full resolution, there are ~ 3 million data points! No way to invert the covariance matrix, let alone scan a many-dimensional parameter space!

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 data model covariance

- At full resolution, there are ~ 3 million data points! No way to invert the covariance matrix, let alone scan a many-dimensional parameter space!
- Full resolution is needed to explore the range of possible collision templates.
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- What about isolating the most promising candidate signatures?
- Important to do a blind analysis to avoid a posteriori choices!

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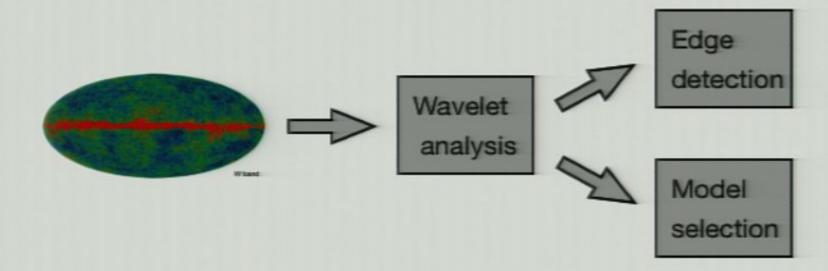
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- Our targets:
 - Azimuthal symmetry
 - Causal boundary
 - long-wavelength modulation inside a disc

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- What about isolating the most promising candidate signatures?
- Important to do a blind analysis to avoid a posteriori choices!
- Our targets:
 - Azimuthal symmetry
 - Causal boundary
 - long-wavelength modulation inside a disc
 - We use the following tools:
 - Wavelet analysis good for picking out localized features.
 - Edge detection sensitive to the causal boundary.
 - Model selection sensitive to the postulated form of the modulation.

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- What about isolating the most promising candidate signatures?
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- Our pipeline is fully automated.
- We calibrate it with simulations and freeze all free parameters before looking at real data.

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Now to describe the steps......

Vavelet analysis

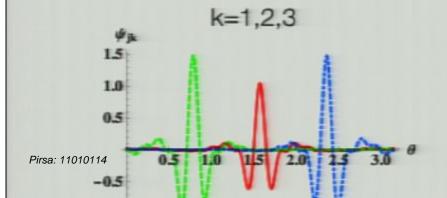
- Wavelets: a way to pick out localized features of varying angular scale.
- Real data is given on a pixelated sphere:
- We use the "spherical needlet transform"

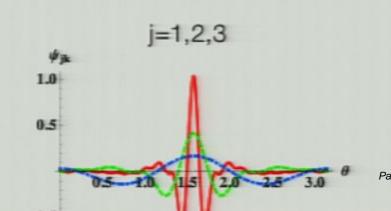


pixels labeled by integer k

$$T(\hat{\gamma}) = \sum_{j,k} \beta_{jk} \psi_{jk}(\hat{\gamma}) \qquad \beta_{jk} = \int T(\hat{\gamma}) \psi_{jk}(\hat{\gamma}) d\Omega.$$

• The needlet functions are labeled by their pixel center k and "frequency" j:





Assess the significance

For a gaussian CMB on a full sky without noise we expect:

$$\langle \beta_{jk} \rangle = 0$$
 $\langle \beta_{jk}^2 \rangle = \sum_{l} f(l,j)C_l$

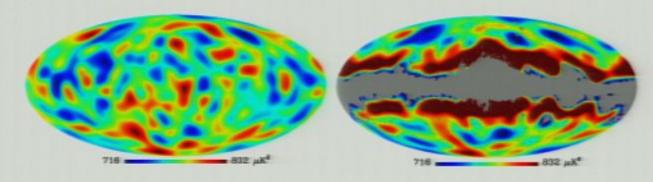
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Assess the significance

For a gaussian CMB on a full sky without noise we expect:

$$\langle \beta_{jk} \rangle = 0$$
 $\langle \beta_{jk}^2 \rangle = \sum_{l} f(l,j)C_l$

On a cut sky with noise, there is a mildly biased variance and mean:



(variance from 1000 gaussian realizations)

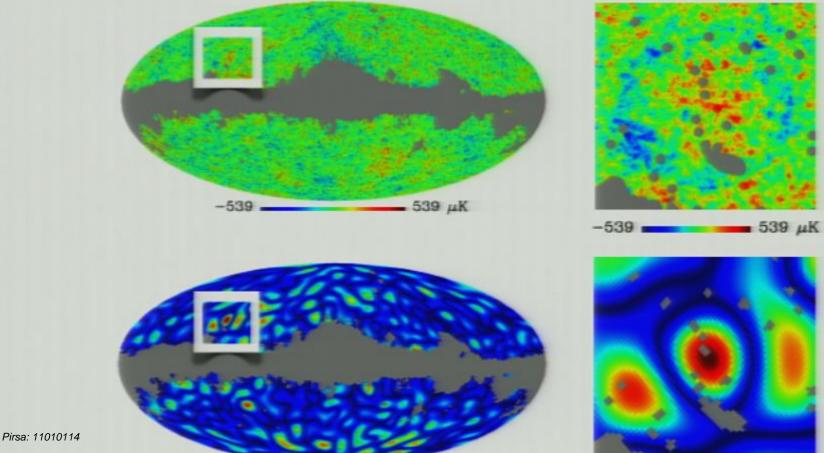
So, define an unbiased statistic....

$$S_{jk} = \frac{|\beta_{jk} - \langle \beta_{jk} \rangle_{\text{gauss,cut}}}{\sqrt{\langle \beta_{jk}^2 \rangle_{\text{gauss,cut}}}} \qquad \text{Calculated}$$
from sims

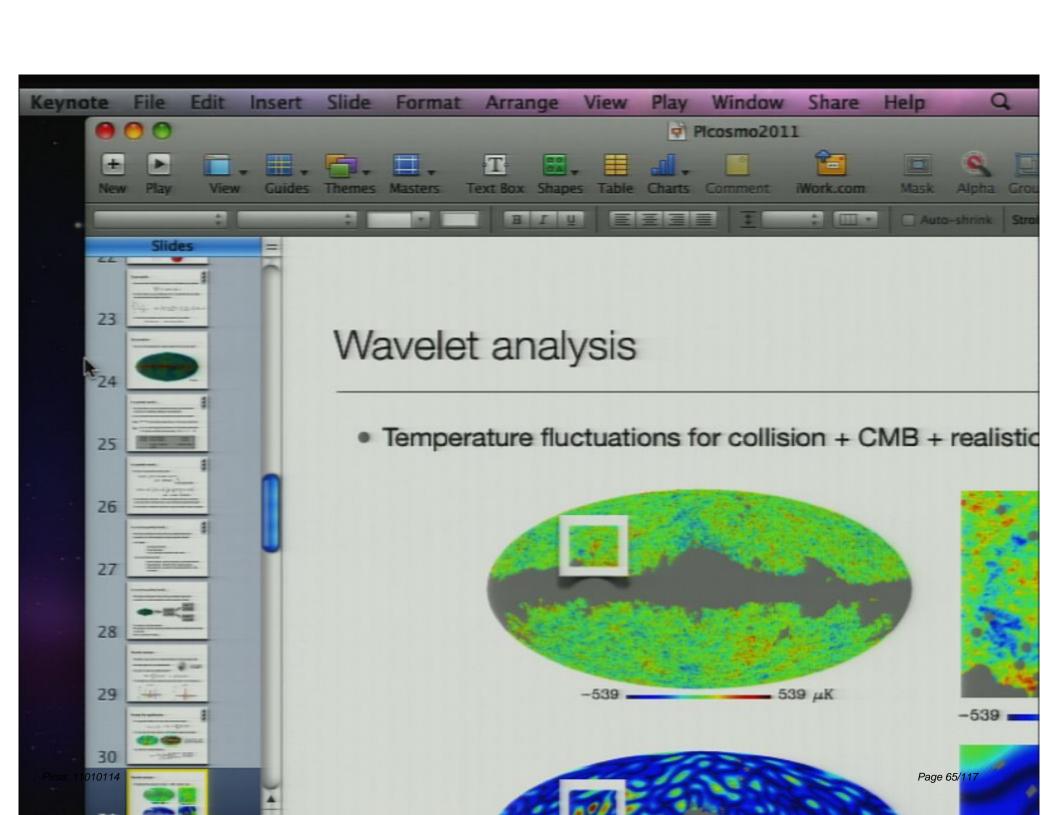
Pirsa: 11010114

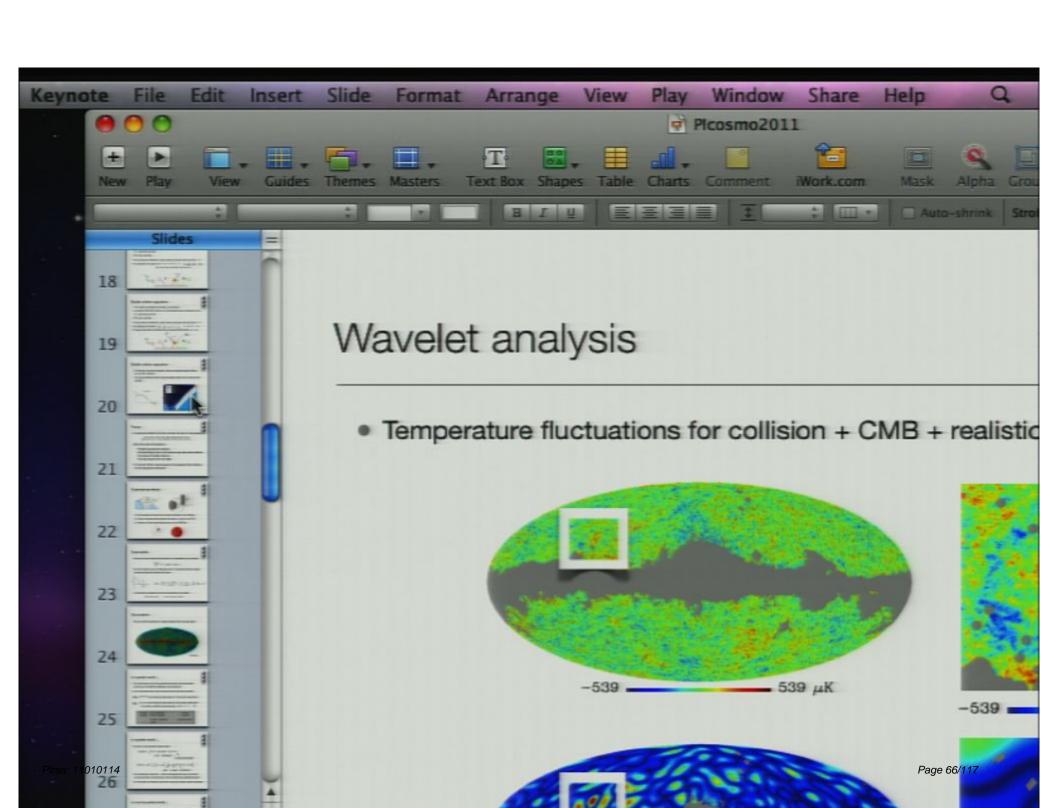
Vavelet analysis

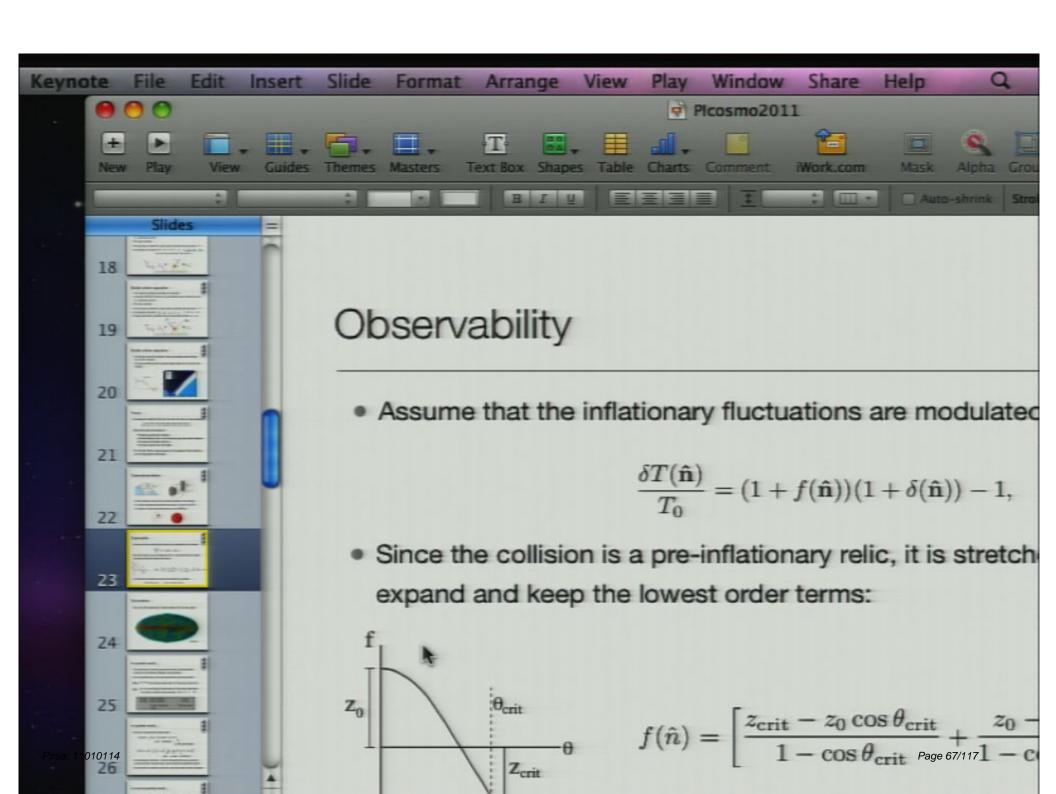
Temperature fluctuations for collision + CMB + realistic noise:



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Observability

Assume that the inflationary fluctuations are modulated by the collision:

$$\frac{\delta T(\hat{\mathbf{n}})}{T_0} = (1 + f(\hat{\mathbf{n}}))(1 + \delta(\hat{\mathbf{n}})) - 1,$$

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Observability

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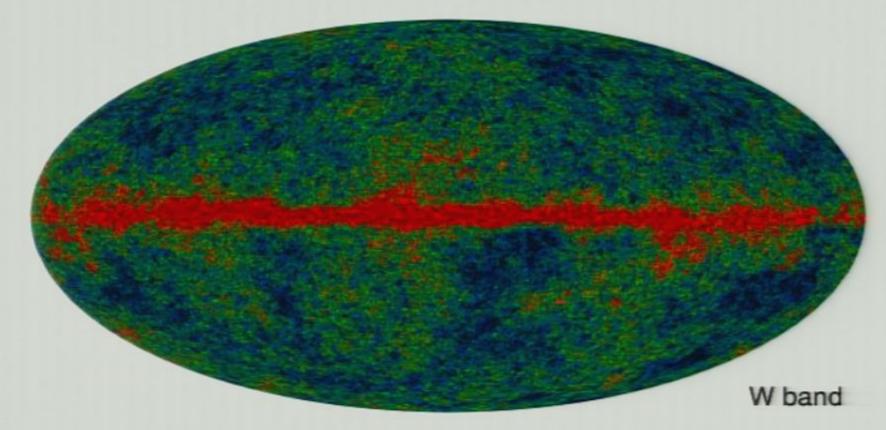
 Since the collision is a pre-inflationary relic, it is stretched. We can Taylorexpand and keep the lowest order terms:

$$f_{\mathbf{z}_0} = \begin{bmatrix} \frac{\theta_{\text{crit}}}{1 - \cos \theta_{\text{crit}}} + \frac{z_0 - z_{\text{crit}}}{1 - \cos \theta_{\text{crit}}} \cos \theta \end{bmatrix} \Theta(\theta_{\text{crit}} - \theta)$$

· Confirmed by simulations, and can be realized in toy models.

Data analysis

• How do we find evidence for a bubble collision from a full-sky map?



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How do we calculate the evidence ratio?

$$P(\mathbf{d}|M) = \int P(\mathbf{\Theta}, M) P(\mathbf{d}|\mathbf{\Theta}, M) \, \mathrm{d}^n \mathbf{\Theta}$$
 prior likelihood model parameters

$$P(\mathbf{d}|\mathbf{\Theta}) \propto \exp\left(-\frac{1}{2}\chi^2\right) = \exp\left\{-\frac{1}{2}[\mathbf{d} - \mathbf{t}(\mathbf{\Theta})]^{\mathrm{T}}\mathbf{C}^{-1}[\mathbf{d} - \mathbf{t}(\mathbf{\Theta})]\right\}$$
 data model covariance

- At full resolution, there are ~ 3 million data points! No way to invert the covariance matrix, let alone scan a many-dimensional parameter space!
- Full resolution is needed to explore the range of possible collision templates.
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Vavelet analysis

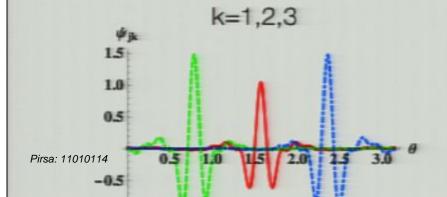
- Wavelets: a way to pick out localized features of varying angular scale.
- Real data is given on a pixelated sphere:
- We use the "spherical needlet transform"

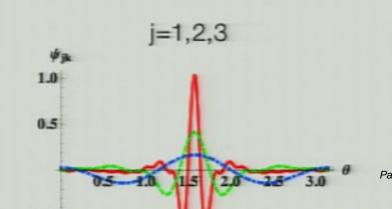


pixels labeled by integer k

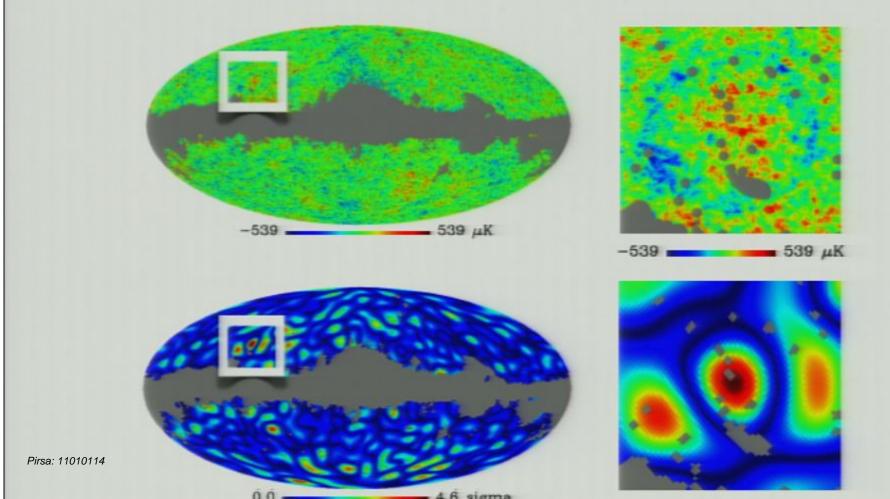
$$T(\hat{\gamma}) = \sum_{j,k} \beta_{jk} \psi_{jk}(\hat{\gamma}) \qquad \beta_{jk} = \int T(\hat{\gamma}) \psi_{jk}(\hat{\gamma}) d\Omega.$$

The needlet functions are labeled by their pixel center k and "frequency" j:



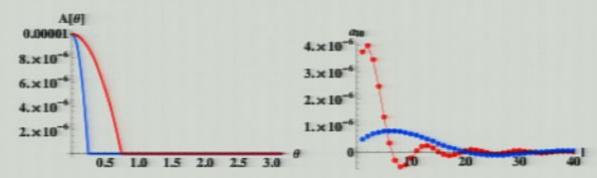


Temperature fluctuations for collision + CMB + realistic noise:

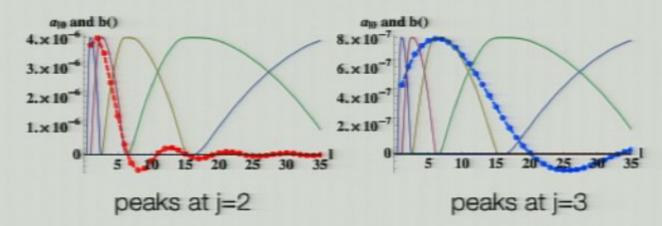


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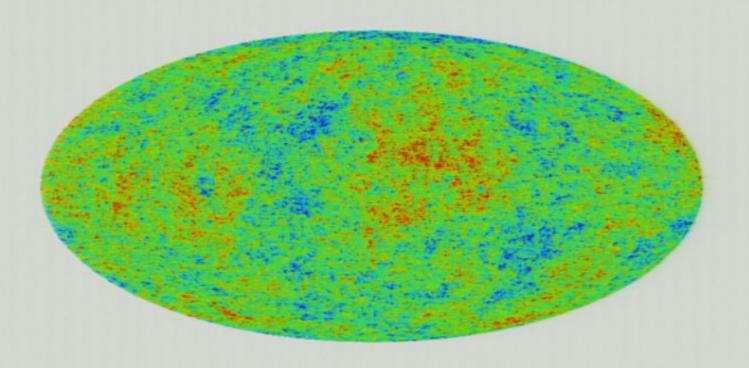
For our collision templates:



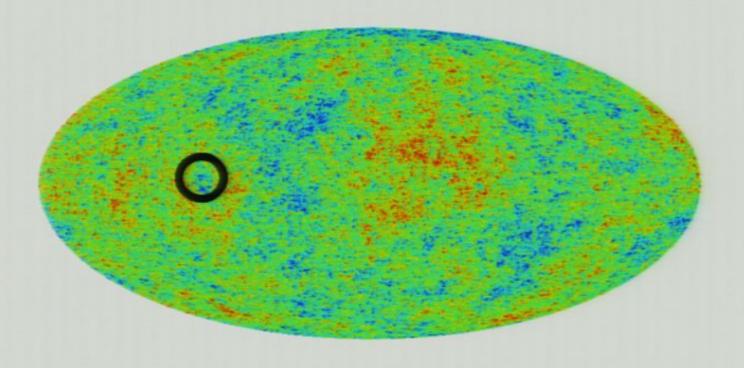
The needlets are most sensitive to a collision of a given angular scale at some j.



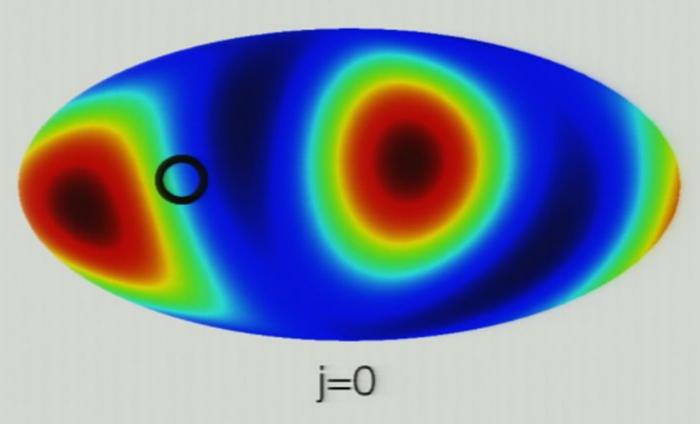
Pirs@ 2011 Hearn about size of candidate feature from value of j at which you find and signal.



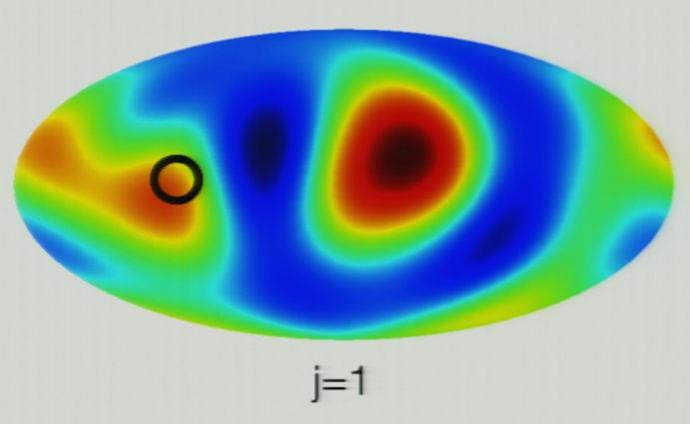
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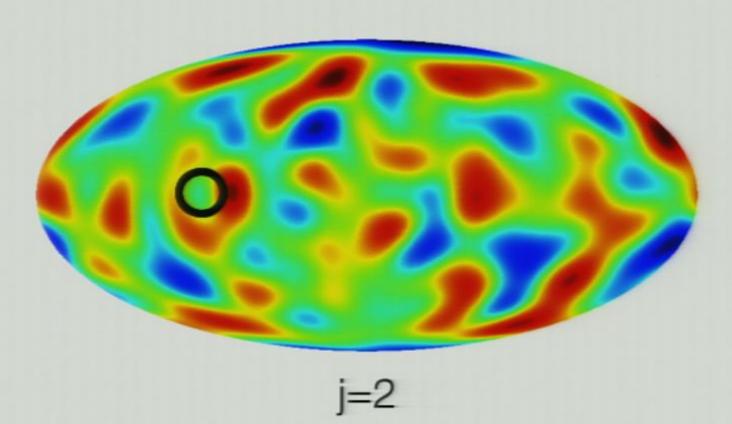
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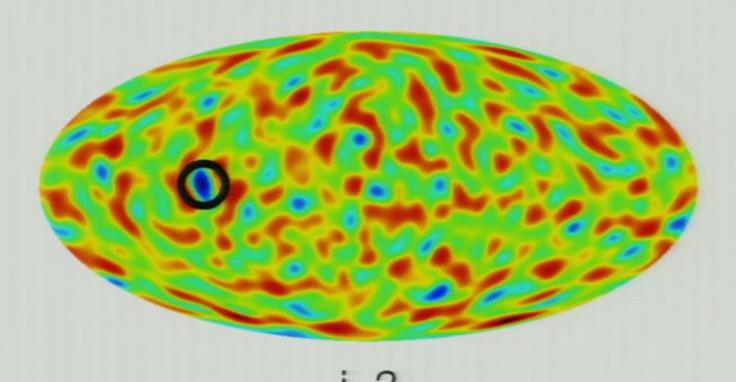
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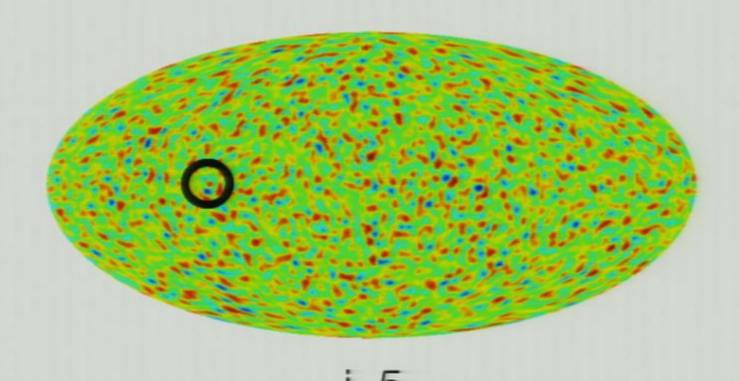
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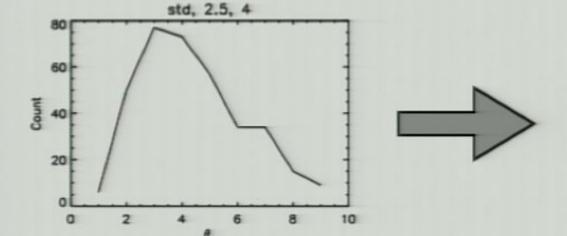


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Sampling many templates, we define a range in possible disc sizes for each needlet frequency.

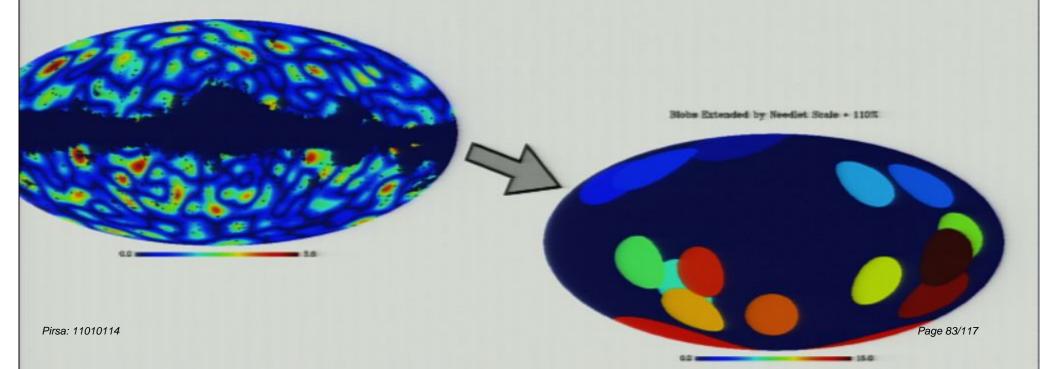


j	$\theta_{ m crit,min}$	$\theta_{ m crit,max}$	
0	60°	90°	
1	33°	71°	
2	12°	32°	
3	5°	14°	
4	2°	5°	
5	1°	2°	

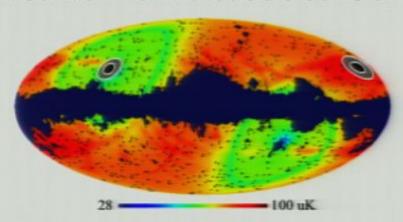
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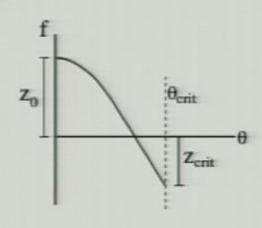
Blobs

- Define a significance threshold from a bubble-free end-to-end simulation of the experiment - controls for systematics and quantifies expected signals.
- Use needlet information to segment the CMB sky into "Blobs."
- Repeat for a variety of needlet shapes.



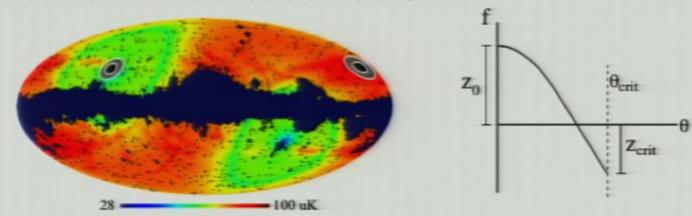
Does this method work to find bubble collisions?

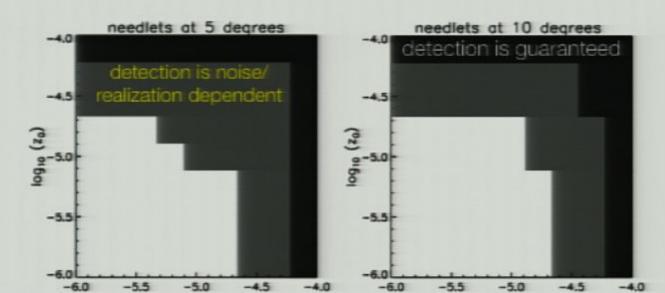




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Does this method work to find bubble collisions?

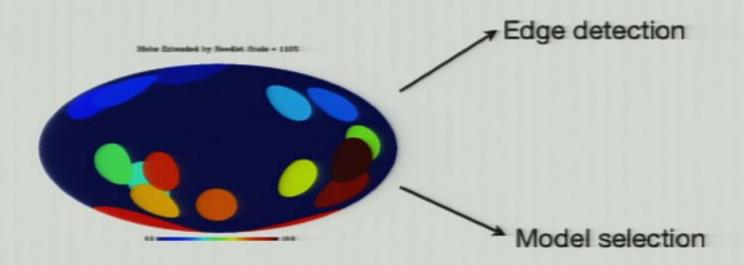




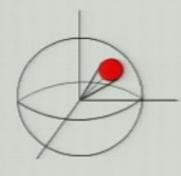
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Vext steps....

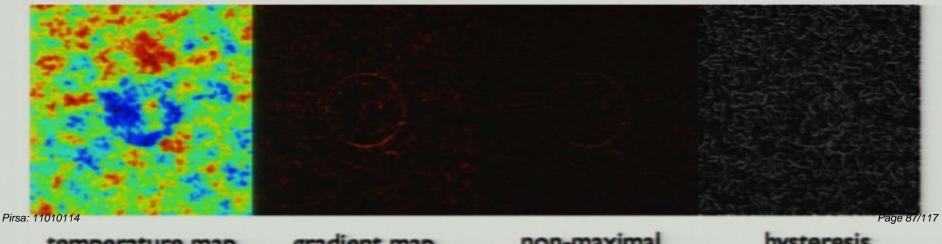


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- The causal boundary can form a detectable edge in the temperature field and its derivatives.
- Detection schemes similar to those used in searches for cosmic strings.
- The Canny algorithm:

Amsel, Berger, Brandenburger, Danos



temperature map

gradient map

non-maximal

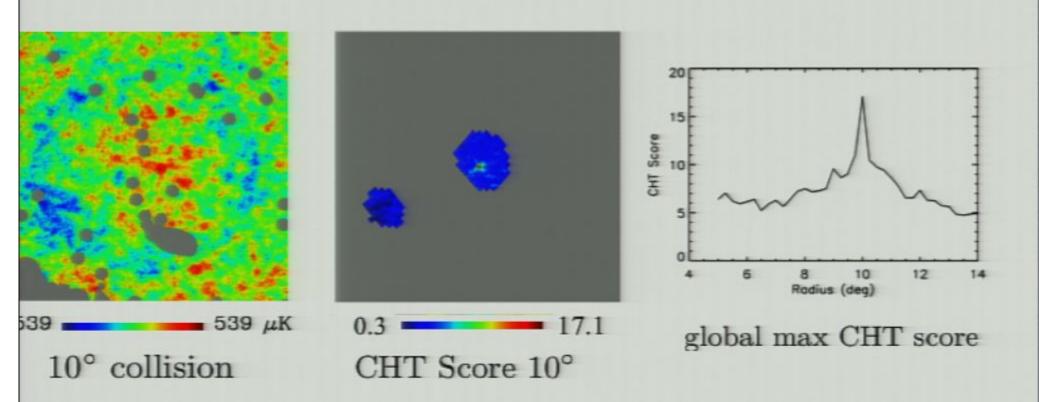
hysteresis

To find circular edges, we apply the Circular Hough Transform (CHT):



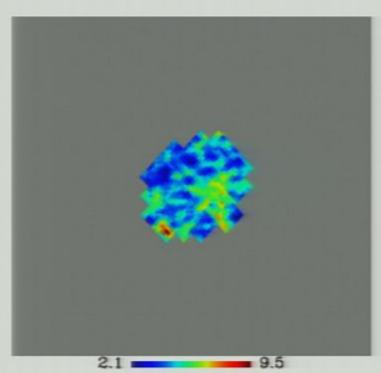
CHT Score =
$$\frac{N_{\text{hits}}}{\theta_{\text{circ}}}$$

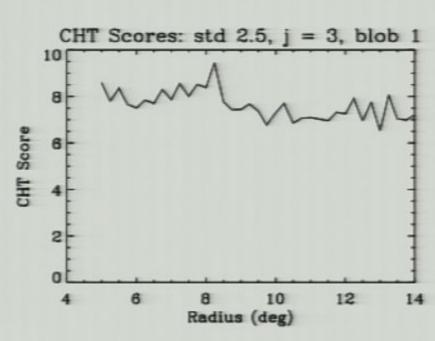
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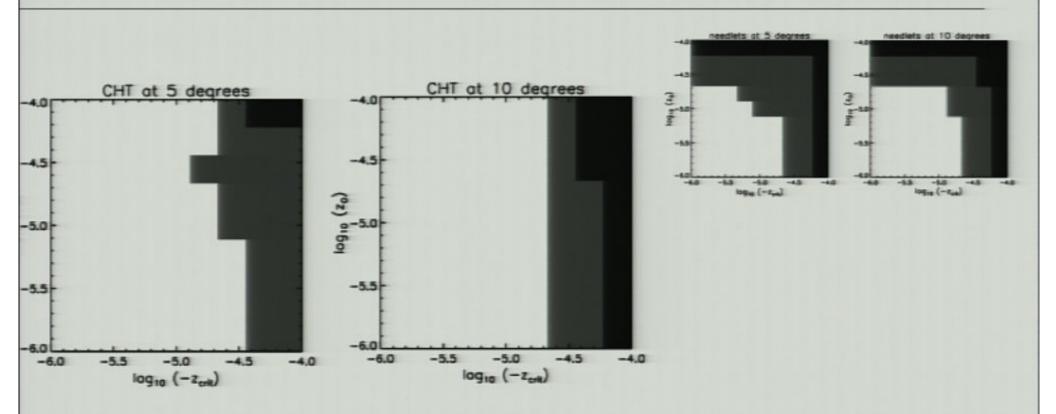
"peakiest" example from the end-to-end sim:





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Sims



For small collisions, the ~1 degree blobs in the CMB affect performance.

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• For each blob, compute the evidence ratio: $\rho \equiv \frac{P(\mathbf{d}|M_{\mathrm{b}})}{P(\mathbf{d}|M_{0})}$

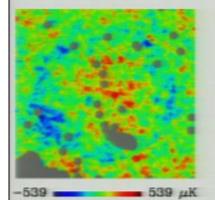
$$\begin{split} P(\mathbf{d}|M) &= \int P(\mathbf{\Theta}, M) P(\mathbf{d}|\mathbf{\Theta}, M) \, \mathrm{d}^n \mathbf{\Theta} \\ \\ P(\mathbf{d}|\mathbf{\Theta}) \propto \exp\left(-\frac{1}{2}\chi^2\right) &= \exp\left\{-\frac{1}{2}[\mathbf{d} - \mathbf{t}(\mathbf{\Theta})]^\mathrm{T} \mathbf{C}^{-1}[\mathbf{d} - \mathbf{t}(\mathbf{\Theta})]\right\} \\ \\ \mathbf{\Theta} &= \left\{\theta_0, \phi_0, z_{\mathrm{crit}}, z_0, \theta_{\mathrm{crit}}\right\} \quad \text{noise and cosmic variance} \end{split}$$

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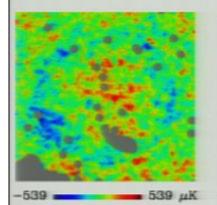
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- ullet Computationally limited to use data from regions of diameter $\leq 22^\circ$
- We use flat priors for all parameters.
- Priors on $\{\theta_0, \phi_0, \theta_{crit}\}$ are set by the needlet step.
- Priors on $\{z_0, z_{\rm crit}\}$ are set by the amplitude of fluctuations in the CMB.



$z_0 \times 10^5$	$z_{ m crit} imes 10^5$	$ heta_{ m crit}$	θ_0	ϕ_0
5.0	-5.0	10.0	57.7	99.2
$5.2^{+1.0}_{-1.0}$	$-5.0^{+0.3}_{-0.3}$	$10.0^{+.002}_{002}$	$57.7^{+0.00}_{-0.00}$	$99.2^{+0.00}_{-0.00}$

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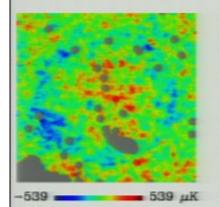


$z_0 \times 10^5$	$z_{\rm crit} \times 10^5$	$ heta_{ m crit}$	θ_0	ϕ_0
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$$\ln \rho = 127.9 \pm 0.3$$

• This is an overwhelmingly strong detection!

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$$\ln \rho = 127.9 \pm 0.3$$

- This is an overwhelmingly strong detection!
- Running the whole pipeline on simulated bubble collisions:

The presence of an edge really helps!

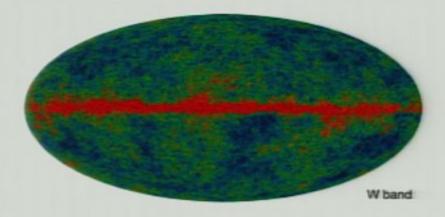
$$\ln \rho \simeq 130 \longrightarrow \ln \rho \simeq 30$$

Running the whole pipeline on the end-to-end sim:

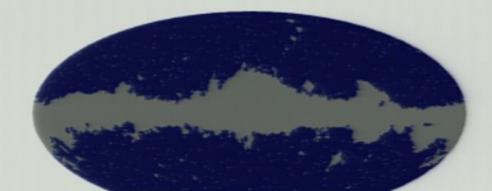
feature	blob	$\theta_{ m crit}$ prior	$\log \rho$
1	1	5 - 14	1.5 ± 0.1
1	2	6 - 12	-0.02 ± 0.1
2	1	10 - 21	-0.04 ± 0.1
3	1	6 - 12	-0.8 ± 0.1
4	1	6 - 12	0.5 ± 0.1
4	2	4 - 8	2.6 ± 0.1
5	1	3 - 7	0.6 ± 0.1
9	1	3 - 6	1.8 ± 0.1

 For features on a scale larger than a few degrees, we shouldn't expect foregrounds or systematics to mimic a bubble collision.

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- We primarily use the W band (94 GHz), which has the highest resolution.
- Foregrounds are removed using the KQ75 mask (cuts ~30% of the sky).



 15 features pass the needlet significance threshold, 4 of which are discarded as they are likely to be responses to the mask.

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 for $\theta_{\rm crit} > 5 - 10^{\circ}$

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 Of the 11 remaining features, 4 have evidence ratios larger than expected from systematics based on the end-to-end simulation of the experiment. (Yes, one of these features is the famous Cold Spot)

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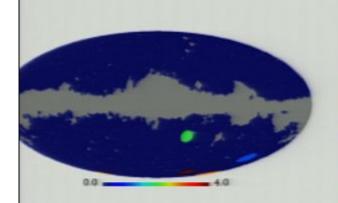
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Four candidates consistent with bubble collisions

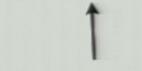


$$\log \rho = 4.8 \pm .2$$

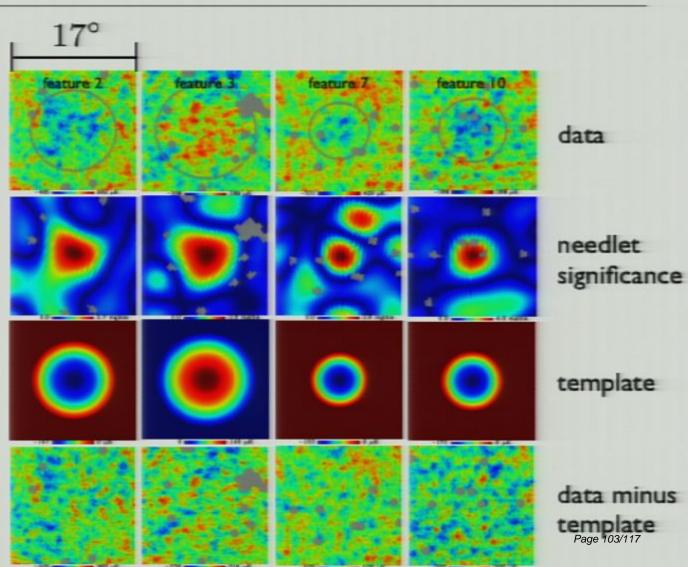
$$\log \rho = 4.3 \pm .1$$

$$\log \rho = 4.0 \pm .1$$

$$\log \rho = 7.0 \pm .2$$



values consistent
Pirsa: 11010114
Ollision sims



Future work and Planck

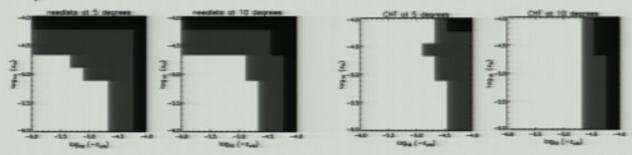
- How well can we distinguish hypotheses in feature finding?
 ie bubbles vs textures.
- With more simulations of bubble collisions, we can update our template.
- Planck temperature data: 3 x better resolution, 10 x lower noise. This
 data will improve every step in the pipeline.
- Planck polarization data: provides a complementary signature of bubble collisions (Czech, Kleban, Larjo, Levi, Sigurdson).
- Cross correlation with large-scale structure (Larjo and Levi)?

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We have developed an automated feature-finding algorithm.

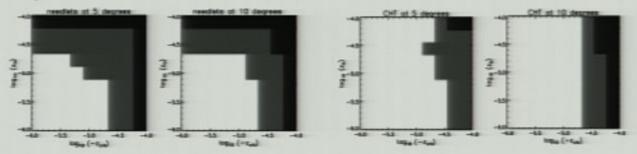
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- We have developed an automated feature-finding algorithm.
- Using simulations, we are able to define exclusion regions in parameter space:



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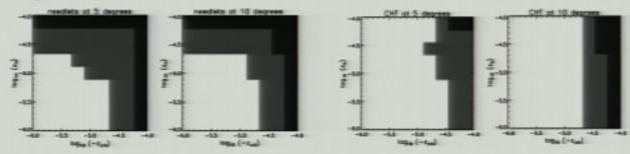
- We have developed an automated feature-finding algorithm.
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 Looking at the WMAP 7 year data, we find 4 features that merit further analysis.

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- We have developed an automated feature-finding algorithm.
- Using simulations, we are able to define exclusion regions in parameter space:



 Looking at the WMAP 7 year data, we find 4 features that merit further analysis.

Planck will go a long way towards determining if these are in fact signatures

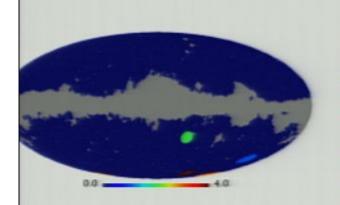
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- Of the 11 remaining features, 4 have evidence ratios larger than expected from systematics based on the end-to-end simulation of the experiment. (Yes, one of these features is the famous Cold Spot)
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Four candidates consistent with bubble collisions

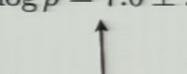


$$\log \rho = 4.8 \pm .2$$

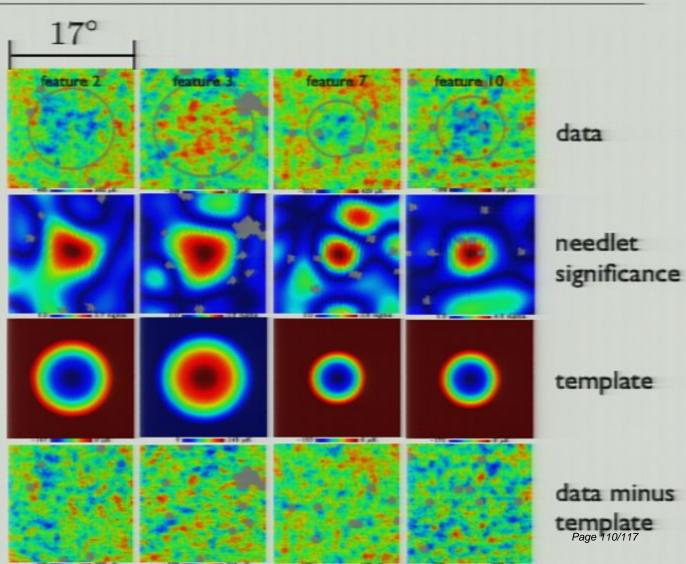
$$\log \rho = 4.3 \pm .1$$

$$\log \rho = 4.0 \pm .1$$

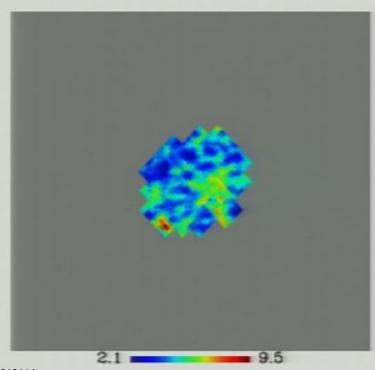
$$\log \rho = 7.0 \pm .2$$

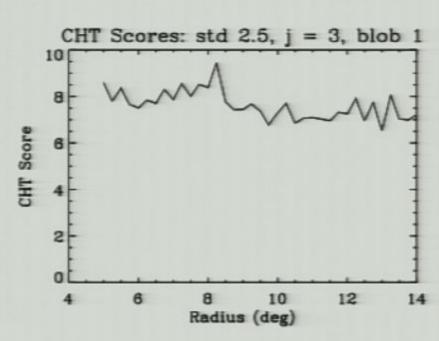


values consistent
Pirsa: 11010114
Ollision sims

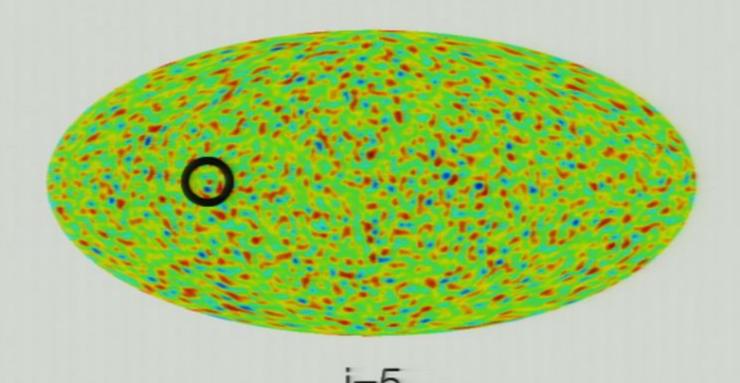


"peakiest" example from the end-to-end sim:



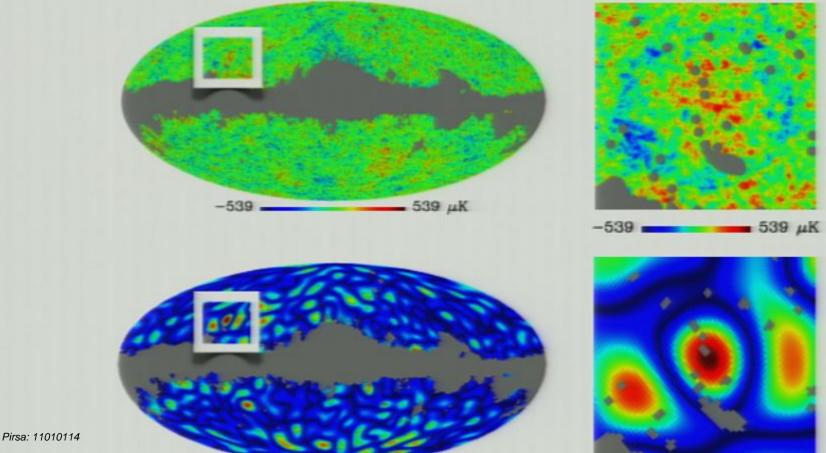


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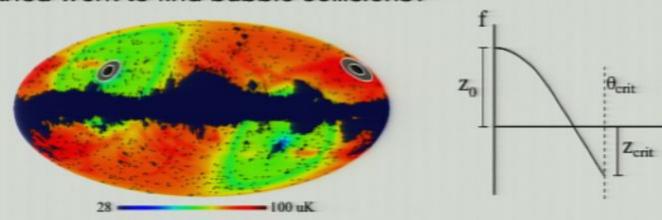
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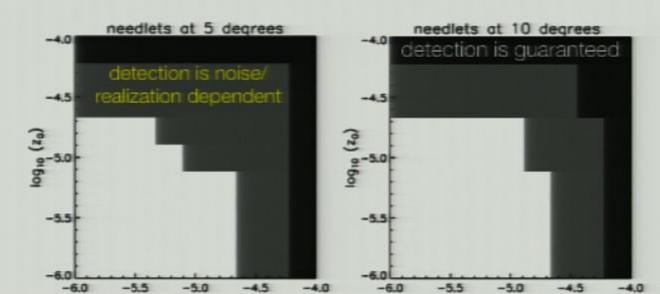
Temperature fluctuations for collision + CMB + realistic noise:



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Does this method work to find bubble collisions?

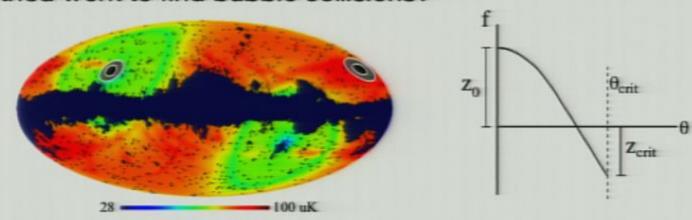


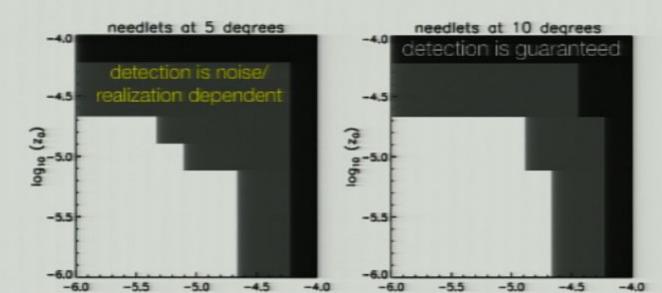


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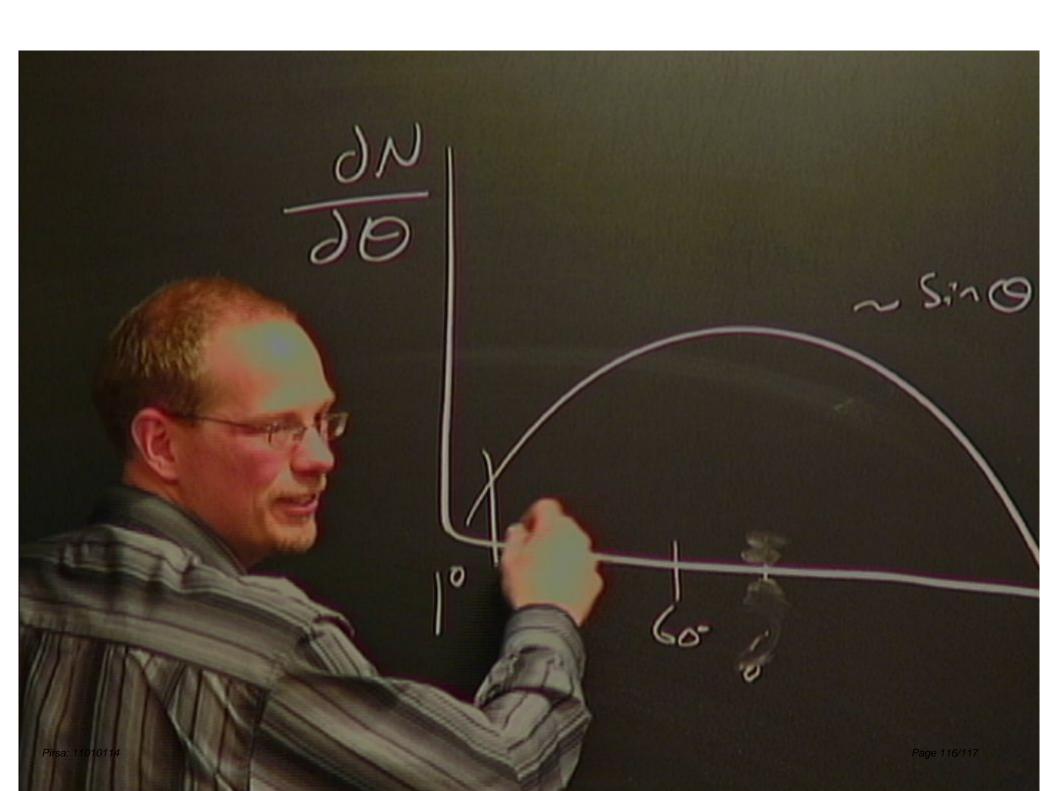
Does this method work to find bubble collisions?



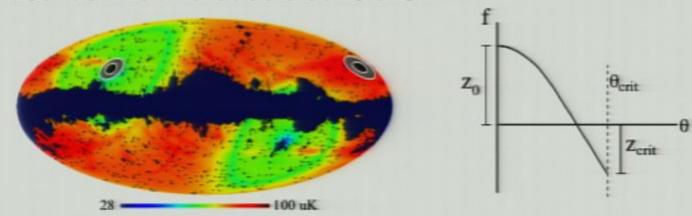


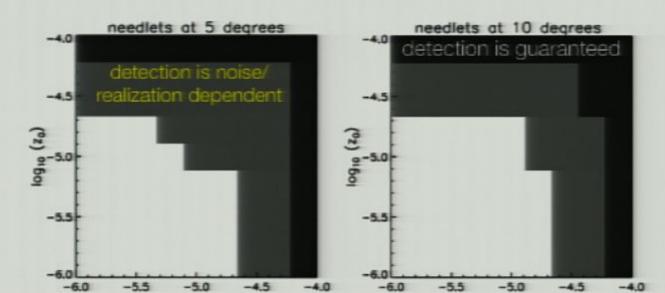
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Does this method work to find bubble collisions?





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