

Title: Space-Time, Quantum Mechanics and Scattering Amplitudes

Date: Jan 26, 2011 02:00 PM

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Abstract: Scattering amplitudes in gauge theories and gravity have extraordinary properties that are completely invisible in the textbook formulation of quantum field theory using Feynman diagrams. In the standard approach--going back to the birth of quantum field theory--space-time locality and quantum-mechanical unitarity are made manifest at the cost of introducing huge gauge redundancies in our description of physics. As a consequence, apart from the very simplest processes, Feynman diagram calculations are enormously complicated, while the final results turn out to be amazingly simple, exhibiting hidden infinite-dimensional symmetries. This strongly suggests the existence of a new formulation of quantum field theory where locality and unitarity are derived concepts, while other physical principles are made more manifest. Rapid advances have been made towards uncovering this new picture, especially for the maximally supersymmetric gauge theory in four dimensions. These developments have interwoven and exposed connections between a remarkable collection of ideas from string theory, twistor theory and integrable systems, as well as a number of new mathematical structures in algebraic geometry. In this talk I will review the current state of this subject and describe a number of ongoing directions of research.

Space-Time, Quantum Mechanics

+

Scattering Amplitudes

with

F. Cachazo
C. Cheng
J. Kaplan
J. Bourjaily
J. Trnka
S. Caron-Huot

also

E. Witten
L. Dolan
P. Goddard
M. Spradlin
A. Volovich
S. Gaiotto

J. Maldacena
F. Alday
D. Gaiotto
P. Vieira
A. Sever
N. Beisert
M. Staudacher

Z. Bern
L. Dixon
D. Kosower
G. Korchemsky
E. Sokatchev
J. Henn
J. Drummond

R. Penrose
A. Hodges
L. Mason
D. Skinner
M. Bullimore

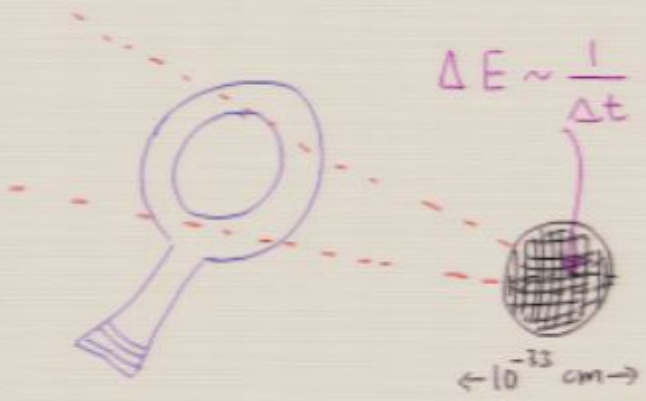
Motivations



Gravity + QM



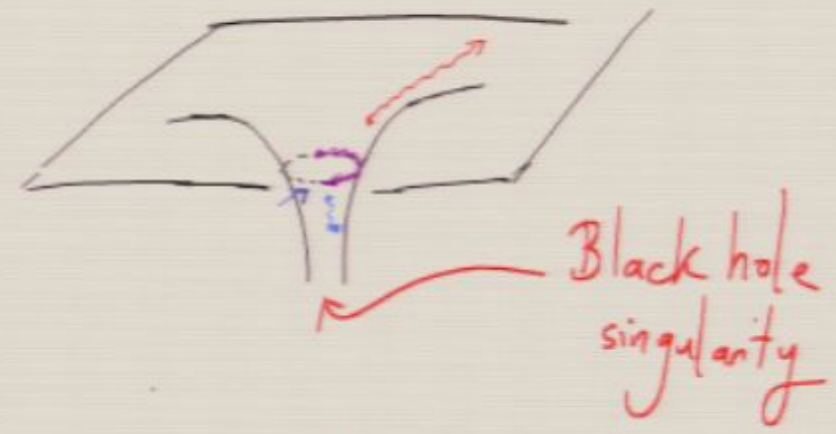
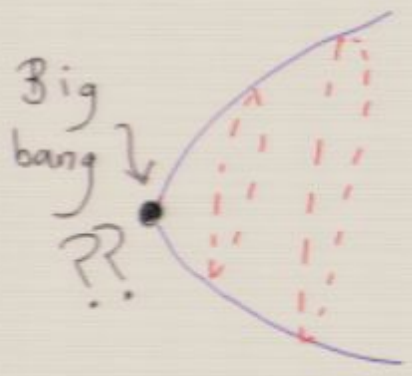
"Space-time is Doomed"



$\Delta E \sim \frac{1}{\Delta t} \rightarrow$ eventually make Black Hole!

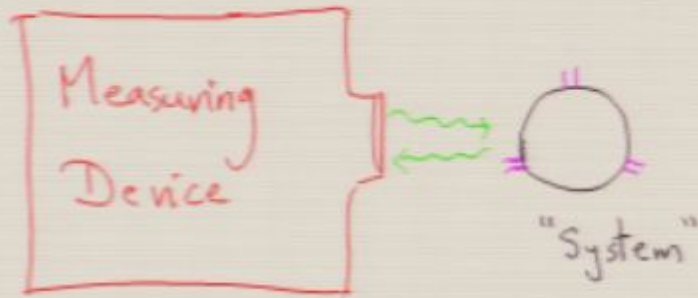
No Operational meaning to distance $< 10^{-33}$ cm, times $< 10^{-43}$ s,

End of Space-Time



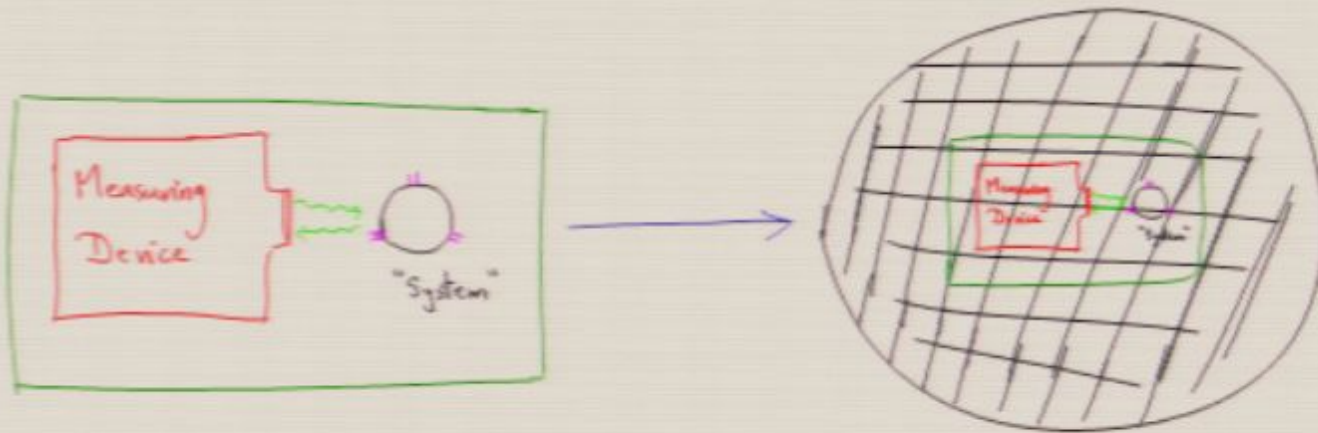
Our theories just break down when gravity is strong and quantum gravity effects are dominant.

Exact Quantum Predictions

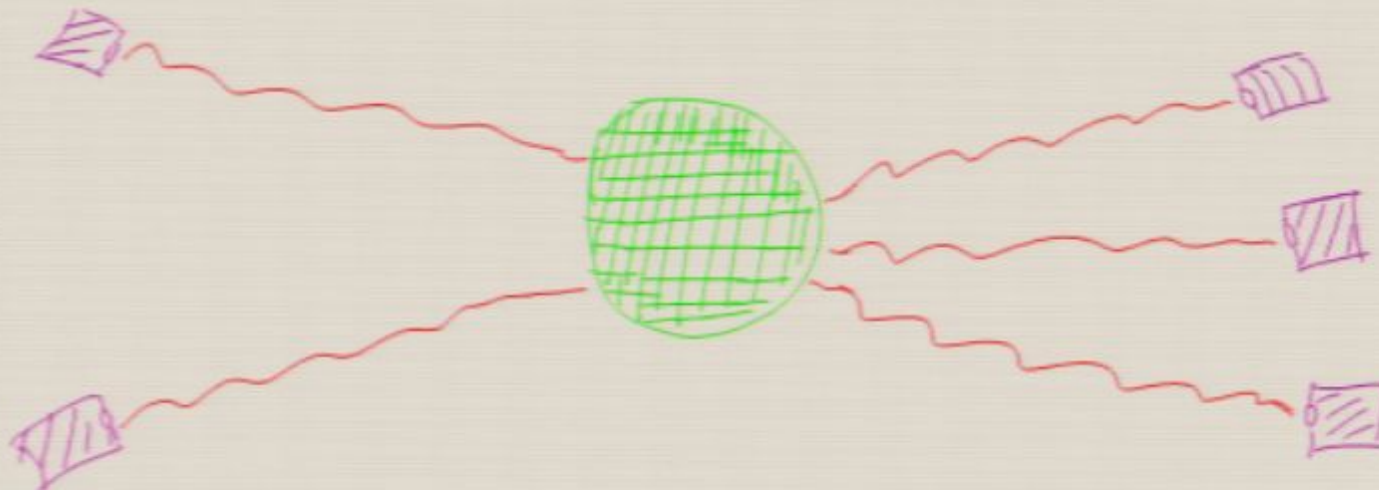


Infinitely many measurements with an Infinitely large measuring apparatus!

No Local Observables!



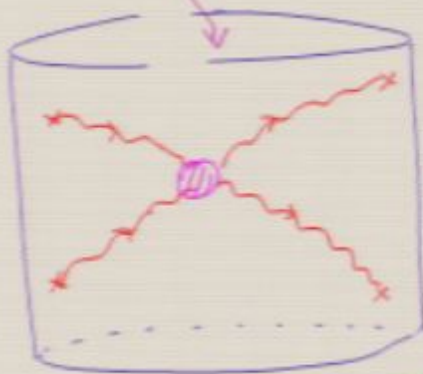
Observables on "Boundary at Infinity"



$$(Quantum\ Gravity)_{D+1} = (Quantum\ Field\ Theory)_D (!)$$

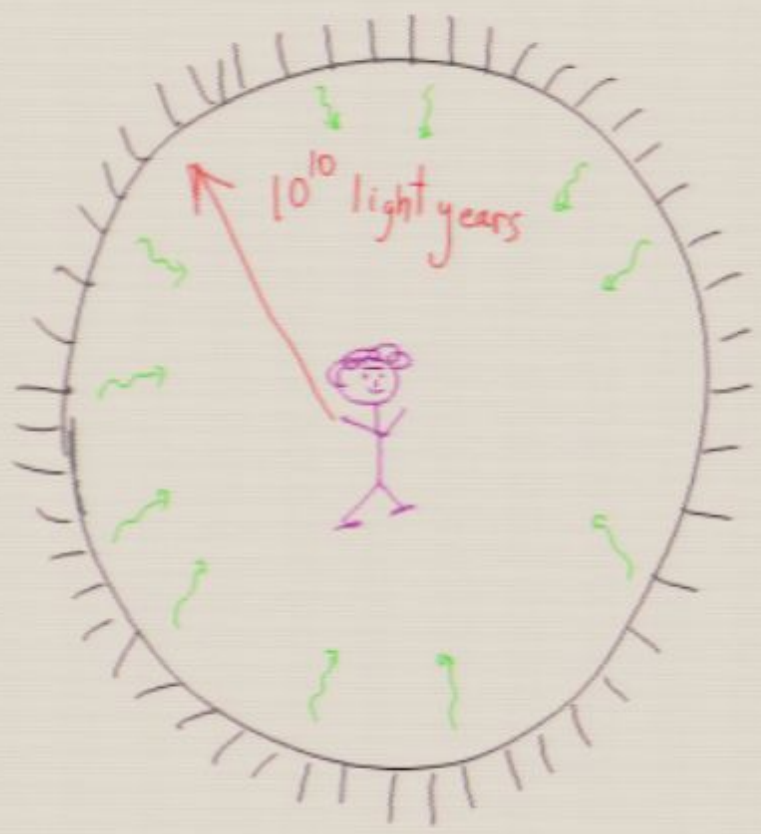
Emergent
Space, Gravity,
Strings ...

↑
time



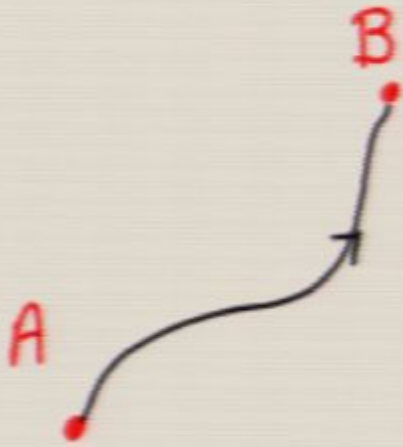
"Anti-de Sitter
Space"

String Theory = Particle Physics
[Weakly interacting] [strongly interacting]



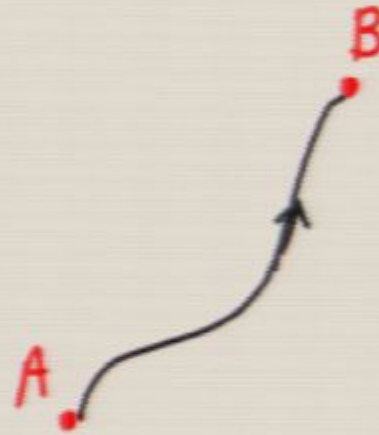
What are
the correct
observables??

Emergent Space-time?



$$m\ddot{x} = -\frac{\partial V}{\partial x}$$

Manifestly Deterministic

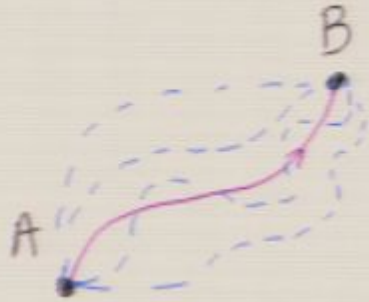


$x(t)$ minimizes action

$$S = \int dt \left[\frac{1}{2} m \dot{x}^2 - V(x) \right]$$

Not manifestly deterministic

Quantum Mechanics

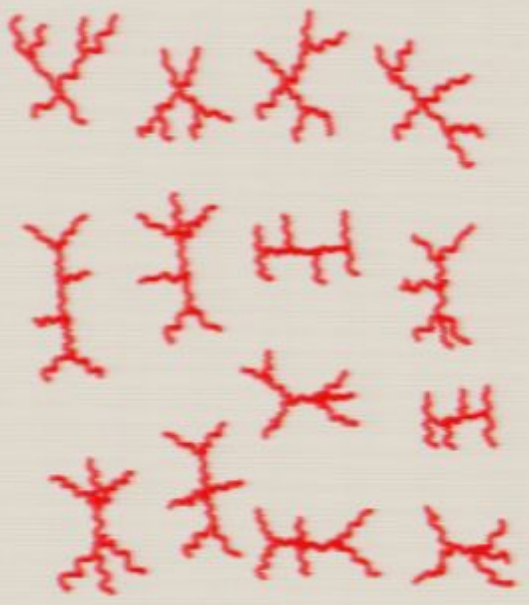


All paths are taken.

$$Amp = \sum_{\text{paths}} e^{i S/\hbar}$$

$\hbar \rightarrow 0$ limit of QM = Least action principle,
not $F = ma!$

Feynman Follies



+ ...

220 Diagrams
10's of thousands
of terms ...

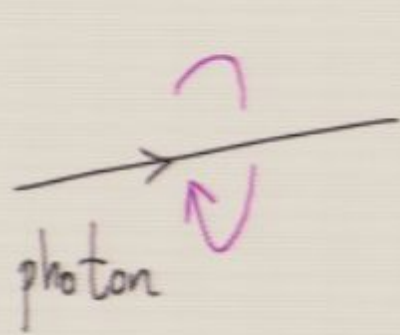
$$\text{Amp}(1^+ 2^- 3^+ 4^- 5^+ 6^+) = \frac{\langle 24 \rangle^4}{\langle 12 \rangle \langle 23 \rangle \langle 34 \rangle \langle 45 \rangle \langle 56 \rangle} !$$

"MHV Amplitudes": i, j bars, rest plus

$$\frac{\langle ij \rangle^4}{\langle 12 \rangle \langle 23 \rangle \dots \langle n1 \rangle}$$

Q. What makes Feynman
Diagrams so complicated, obscuring
simplicity of answer?

A. Insistence on Manifest
Locality + Unitarity!



2 helicities ± 1 .

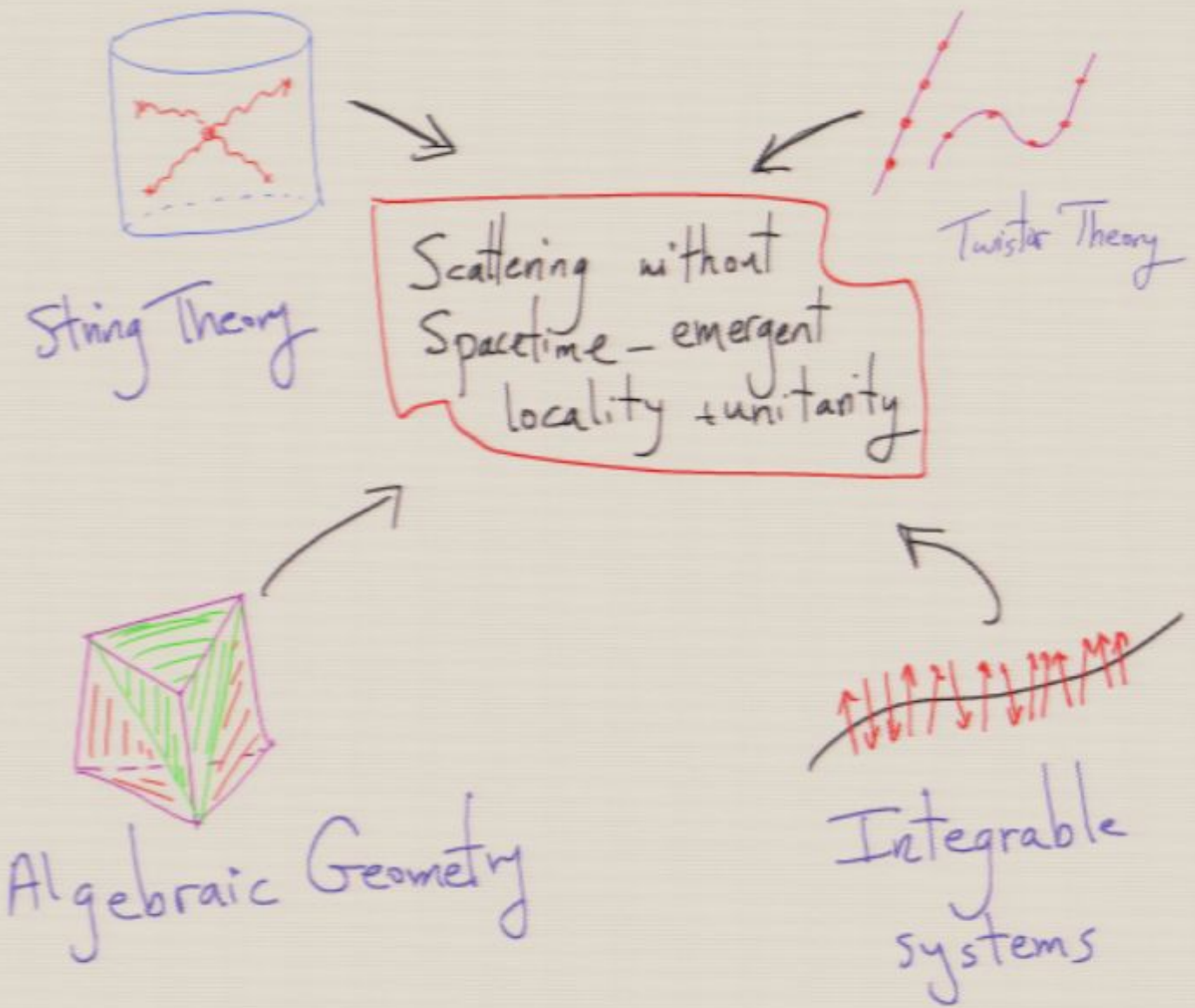
Locality \Rightarrow Field $A_\mu(x) = \epsilon_\mu e^{ipx}$
4 components!

$$\epsilon \cdot p = 0, \quad \epsilon_\mu \sim \epsilon_\mu + \alpha p_\mu$$


$$A_\mu \sim A_\mu + \partial_\mu \Delta$$

Gauge ~~Redundancy~~ \rightarrow All the trouble!

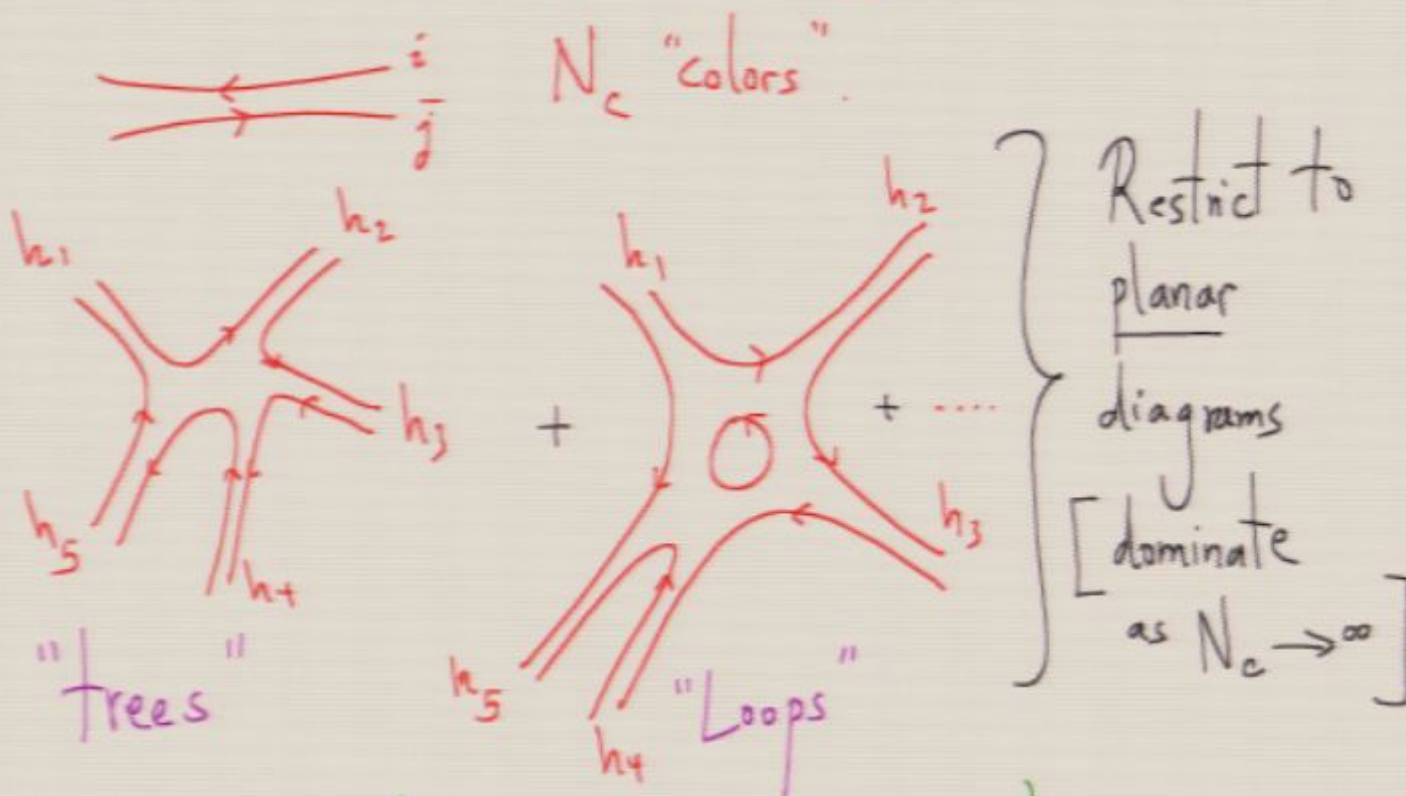
Sitting Under our Noses for 60 yrs



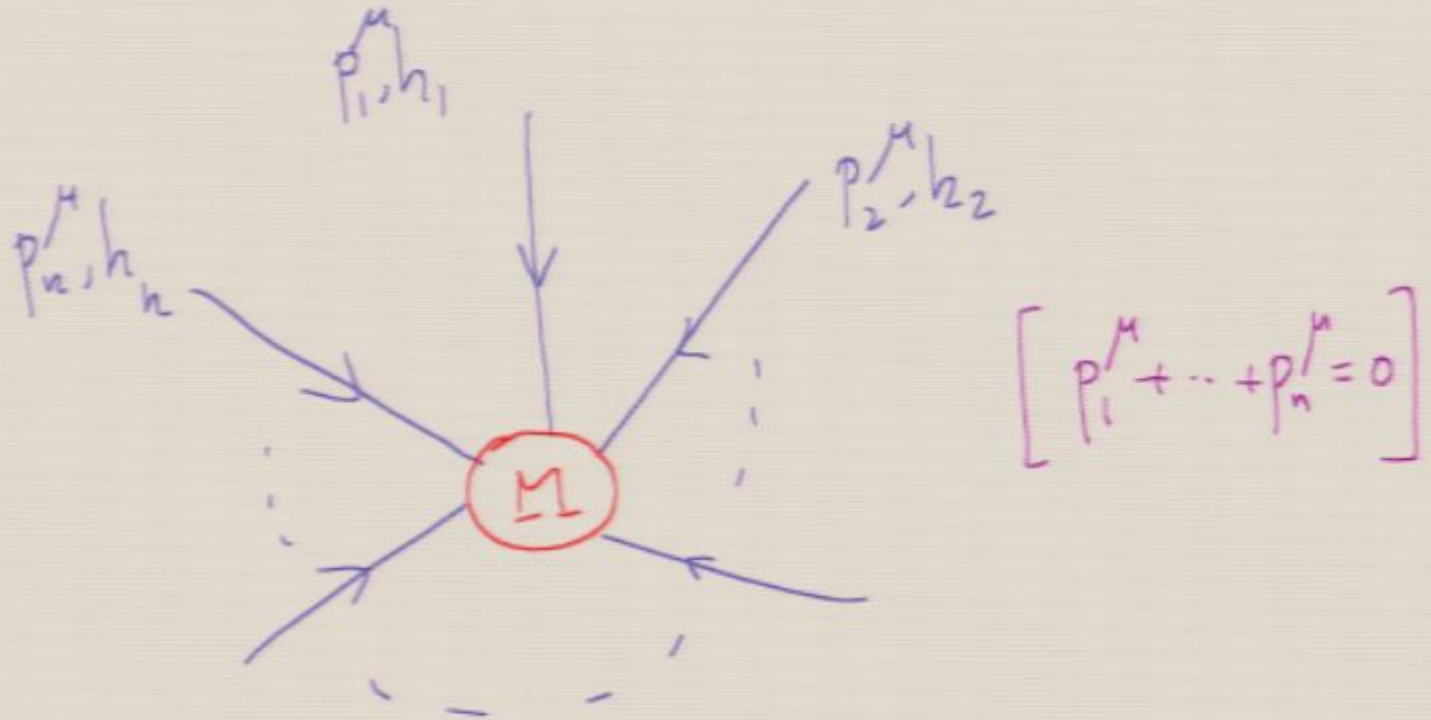
Cast of Characters



Gluon Scattering Amplitudes



Important: Planar Loop
Integrand is well-defined



$$M_n [p_a, h_a, j, l_i] \quad l_i : \text{loop momenta}$$

More Kinematics

$$p^M = (p^0, \vec{p}) \leftrightarrow p_{AA} = \begin{pmatrix} p^0 + p^3 & p^1 + ip^2 \\ p^1 - ip^2 & p^0 - p^3 \end{pmatrix}$$

$$\det p = p^2 = 0$$

$$\Rightarrow p_{AA} = \lambda_A \tilde{\lambda}_{\dot{A}} \cdot \text{Lorentz: } SL(2) \times SL(2)$$

$$\begin{aligned} \text{Invariants } \langle \lambda_1, \lambda_2 \rangle &= \epsilon^{AB} \lambda_{1A} \lambda_{2B} \\ [\tilde{\lambda}_1, \tilde{\lambda}_2] &= \epsilon^{\dot{A}\dot{B}} \tilde{\lambda}_{1\dot{A}} \tilde{\lambda}_{2\dot{B}} \end{aligned}$$

Manifest Little Group Transf.

$$M_n(\lambda_a, \tilde{\lambda}_a, h_a) = M_n(t_a \lambda_a, t_a^{-1} \tilde{\lambda}_a, h_a) \\ = t_a^{-2h_a} M_n(\lambda_a, \tilde{\lambda}_a, h_a)$$

e.g.

$$M_6(1^+ 2^- 3^+ 4^- 5^+ 6^+) = \frac{\langle 24 \rangle^4}{\langle 12 \rangle \langle 23 \rangle \langle 34 \rangle \langle 45 \rangle \langle 56 \rangle}$$

$$M_6(t_2 \lambda_2) = t_2^2 M_6(\lambda_2) \Leftrightarrow \text{helicity of 2 is } -1.$$

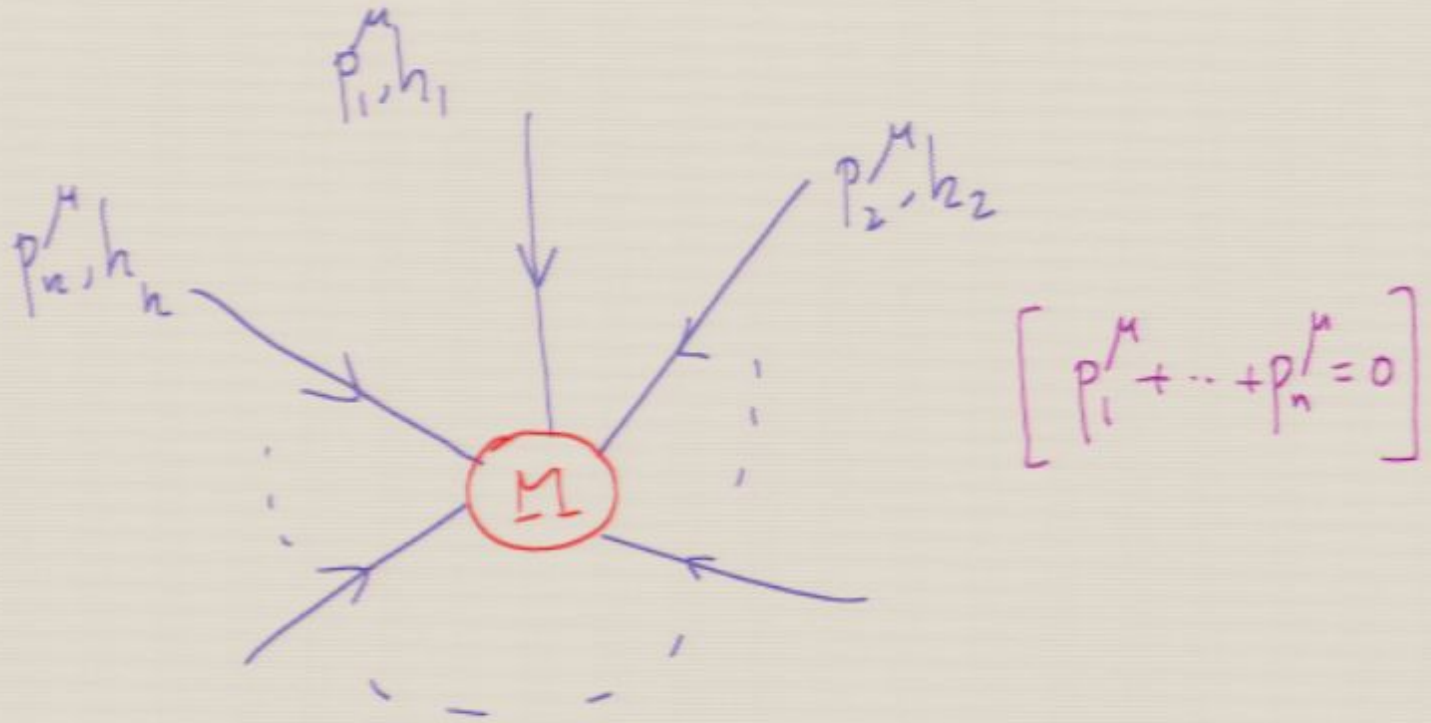
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$$M [p_a, h_a; j; l_i] \quad l_i : \text{loop momenta}$$

More Kinematics

$$p^M = (p^0, \vec{p}) \iff p_{AA} = \begin{pmatrix} p^0 + p^3 & p^1 + ip^2 \\ p^1 - ip^2 & p^0 - p^3 \end{pmatrix}$$

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e.g.

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Finally - simplest gauge theory of all
 is "maximally supersymmetric, $\mathcal{N}=4$ Super Yang Mills":
 "Harmonic Oscillator of the 21st Century"

Unifies heliotes.

$Q_{1,2,3,4}$	$+1$	} "Supermultiplet"	$ \tilde{\eta}\rangle = e^{Q\tilde{\eta}} +1 \rangle$
\downarrow	$+\frac{1}{2}$		
$\tilde{\eta} \uparrow$	0		
$Q_{1,2,3,4}$	$-\frac{1}{2}$		
	-1		$= +1 \rangle + \eta +\frac{1}{2} \rangle + \dots + \eta^4 - \rangle$

$$M_n(\lambda_a, \tilde{\lambda}_a, \eta_a) = \sum_{k=0}^n M_{n,k}(\lambda_a, \tilde{\lambda}_a, \eta_a)$$

Turns out $M_{n,0} = M_{n,1} = 0$

$M_{n,2}$ = "MHV" amplitude

$M_{n,3}$ = "NMHV" amplitude

⋮

↑
contains amps with
 k - helicity
gluons.

Summary: We are after a theory for

$$M_{n,k}[\lambda_a, \tilde{\lambda}_a, \tilde{\eta}_{a_i} b_i]$$

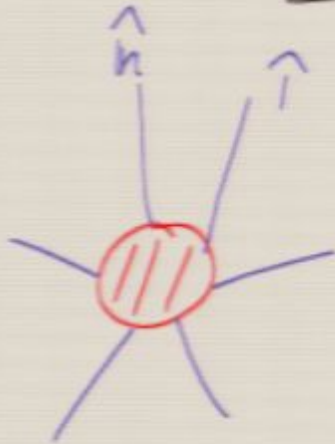
Without Unitary evolution through Spacetime

{ Emergent Space-time, Emergent QM }

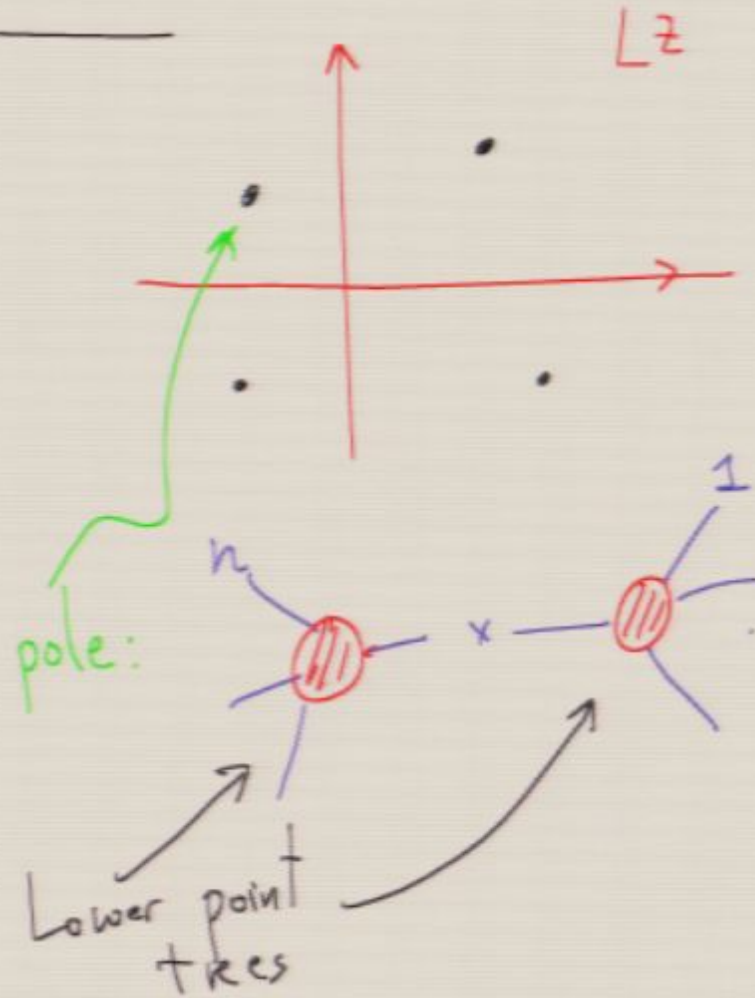
Tree Amplitudes :

Gathering "Data"

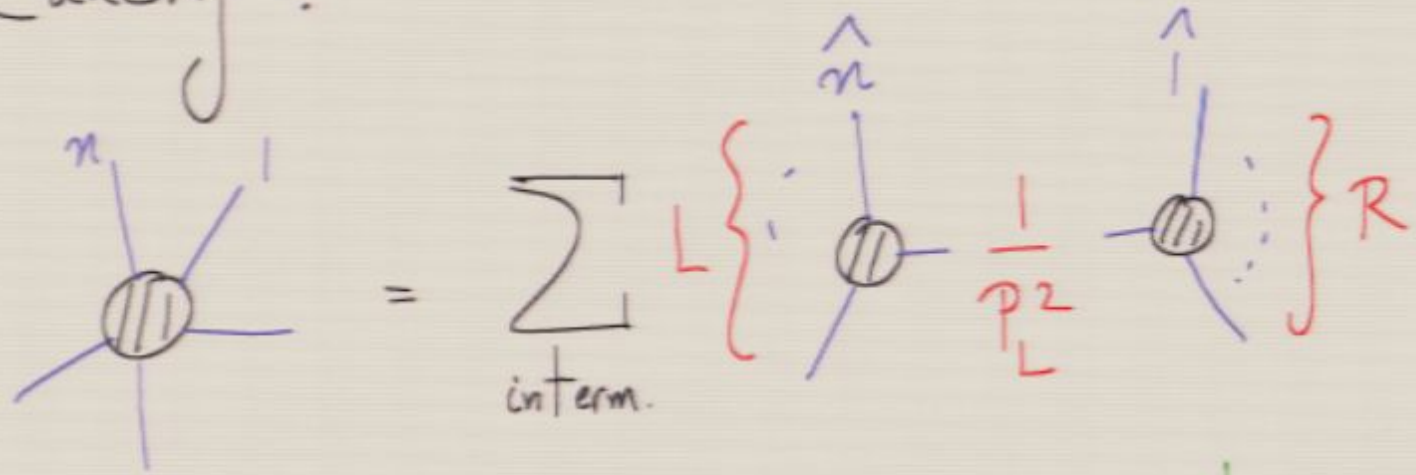
"BCFW Recursion"



Deform $\lambda_n \rightarrow \lambda_n + z\lambda_1$
 $\tilde{\lambda}_1 \rightarrow \tilde{\lambda}_1 - z\lambda_n$

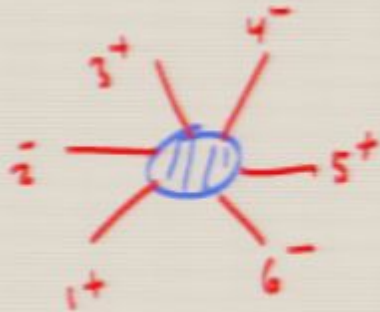


Cauchy :



Q_n - Shell recursion relation!

BCFW 6pt



$$= \frac{\langle 46 \rangle^4 [13]^4}{[12][23] \langle 45 \rangle \langle 56 \rangle} \frac{1}{(p_1 + p_2 + p_3)^2}$$

$$\times \frac{1}{\langle 6 | 5 + 4 | 3 \rangle} \frac{1}{\langle 4 | 5 + 6 | 1 \rangle}$$

“Spurious”
Poles:
Don't occur
in local
theories!

$$+ \{i \rightarrow i+2\} + \{i \rightarrow i+4\}$$

Remarkable 6-term Id

$$\frac{\langle 46 \rangle^4 [13]^4}{[12][23] \langle 45 \rangle \langle 54 \rangle} \frac{1}{(p_1 + p_2 + p_3)^2}$$

$$\times \frac{1}{\langle 615+43 \rangle} \frac{1}{\langle +15+612 \rangle} = \frac{\langle 31(2+4)16 \rangle^4}{[22][34] \langle 56 \rangle \langle 61 \rangle} \frac{1}{(p_5 + p_6 + p_7)^2}$$

$$\times \frac{1}{\langle 116+514 \rangle} \frac{1}{\langle 516+112 \rangle}$$

+ {i → i+2} + {i → i+4}

Guarantees { Parity
Cyclicity
No Spurious Poles

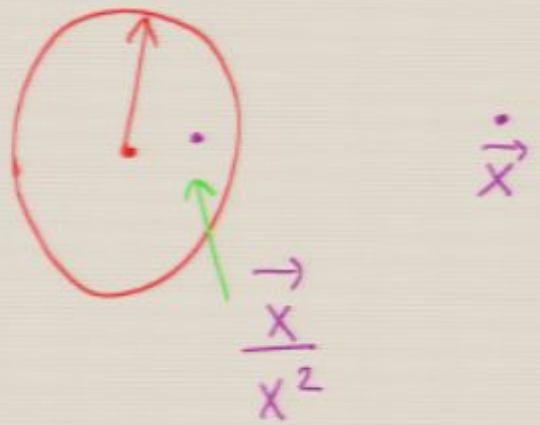
7-pt 12 terms
8-pt 20 terms
40 terms
⋮

SOME POWERFUL
MATHEMATICAL
STRUCTURE
IS AT WORK!

Infinitely Many Hidden Symmetries

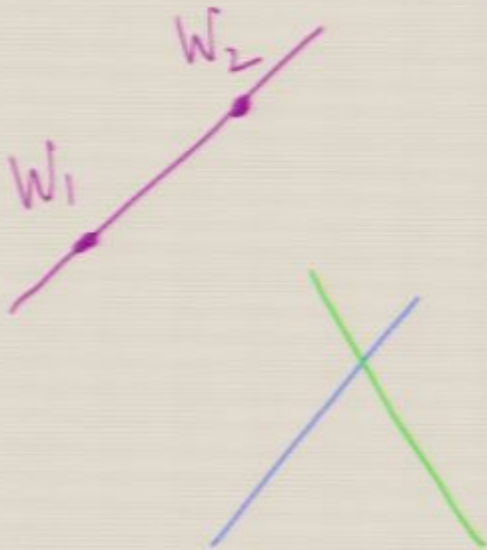
Theories of massless particles
enjoy **conformal invariance** —
the remarkable symmetry under **inversions**

$$x^\mu \rightarrow \frac{x^\mu}{x^2}$$



Twistor Space

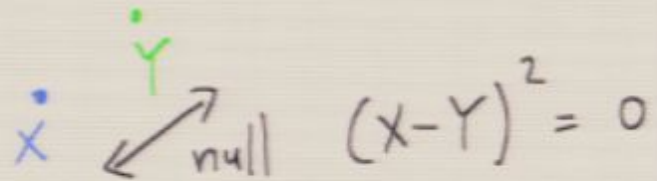
• $W = \begin{pmatrix} \tilde{\lambda}^A \\ \tilde{\lambda}^A \end{pmatrix}_i$ $W \rightarrow LW$
 $\det L = 1$
 are conf. transf.



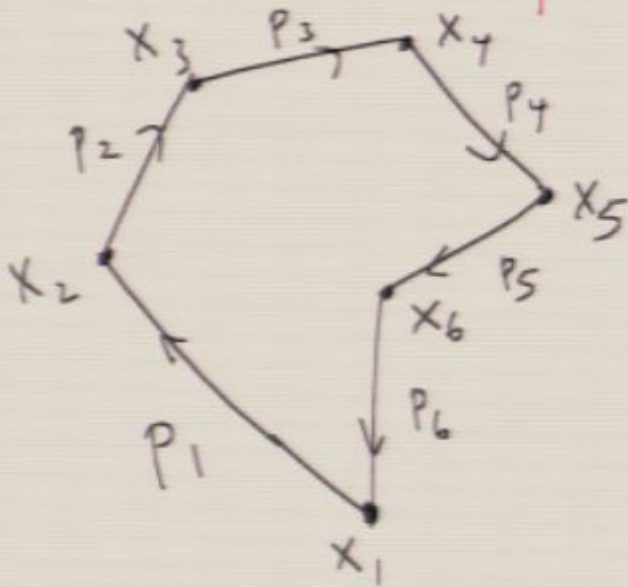
Spacetime

$\tilde{\mu}_A = X_{AA} \tilde{\lambda}^A$
 null ray

• $X = \frac{\mu_1 \lambda_2 - \mu_2 \lambda_1}{\langle 12 \rangle}$



Dual (Super) Conformal Symmetry

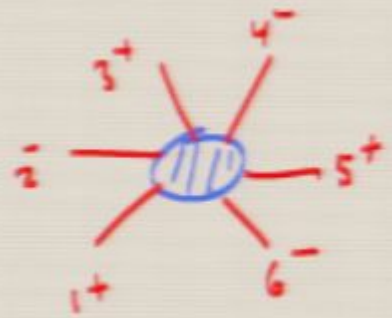


$$P_a = X_{a+1} - X_a$$

"Experimental" observation
 - amplitudes invariant under

Conf. transf. on
this X space!

[Term by term for BCFW form of trees]



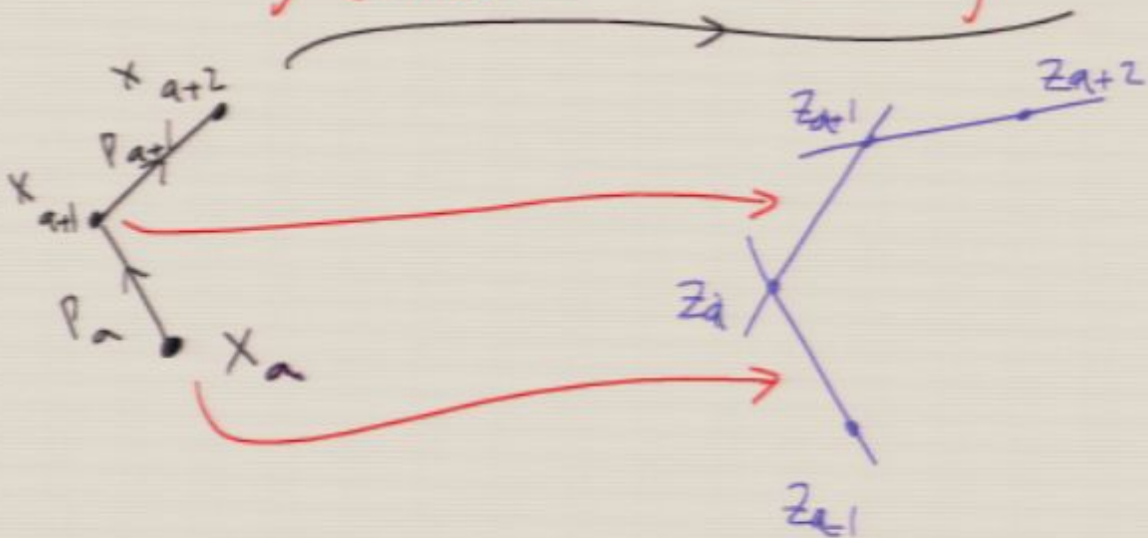
$$= \frac{\langle 46 \rangle^4 [13]^4}{[12][23] \langle 45 \rangle \langle 56 \rangle} \frac{1}{(p_1 + p_2 + p_3)^2}$$

$$\times \frac{1}{\langle 615 + 413 \rangle} \frac{1}{\langle 415 + 613 \rangle}$$

“Spurious Poles”

Are there because these BCFW terms know about both spacetimes!

"Momentum" Twistor Space



$$Z_a = \begin{pmatrix} \mu_a \\ \lambda_a \\ -\lambda_a \\ \eta_a \end{pmatrix}, \quad \tilde{\lambda}_a = \frac{\langle a-1 \ a \rangle \mu_{a+1} + \text{cyclic}}{\langle a-1 \ a \rangle \langle a \ a+1 \rangle}$$

$$\tilde{\eta}_a = \frac{\langle a-1 \ a \rangle \eta_{a+1} + \text{cyclic}}{\langle a-1 \ a \rangle \langle a \ a+1 \rangle}$$

[Invariants $\langle z_1 z_2 z_3 z_4 \rangle$, Schouten-Skinner
 identity $\underbrace{\langle a b c d \rangle}_{\text{cyclic}} \langle e 1 2 3 \rangle = 0$]

(Super) Conformal + Dual (Super) Conformal

↓ generate

“ Yangian Algebra ”

Infinite Dimensional Symmetry

Completely Invisible In \mathcal{L}

Very striking connection with
integrability



$$H = \sum_i S_i \cdot S_{i+1}$$

$$Q = \sum_{i < j} [S_i, S_j]$$

⋮

+ AdS/CFT, spectrum of anom.
 dimensions in $\mathcal{N}=4$ SYM, + amplitudes!

[In particular major breakthroughs
in last ~ 5 yrs have solved

the problem of determining anom.
dimensions in $\mathcal{N}=4$ SYM —

again no Feynman diagrams! —

extension to amplitudes more physical
+ expect richer structure ...]

(Super) Conformal + Dual (Super) Conformal

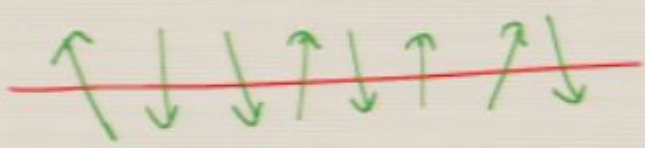
↓ generate

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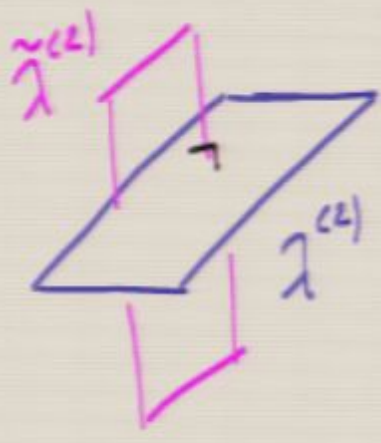
A New Formulation



Start by thinking about momentum conservation afresh!

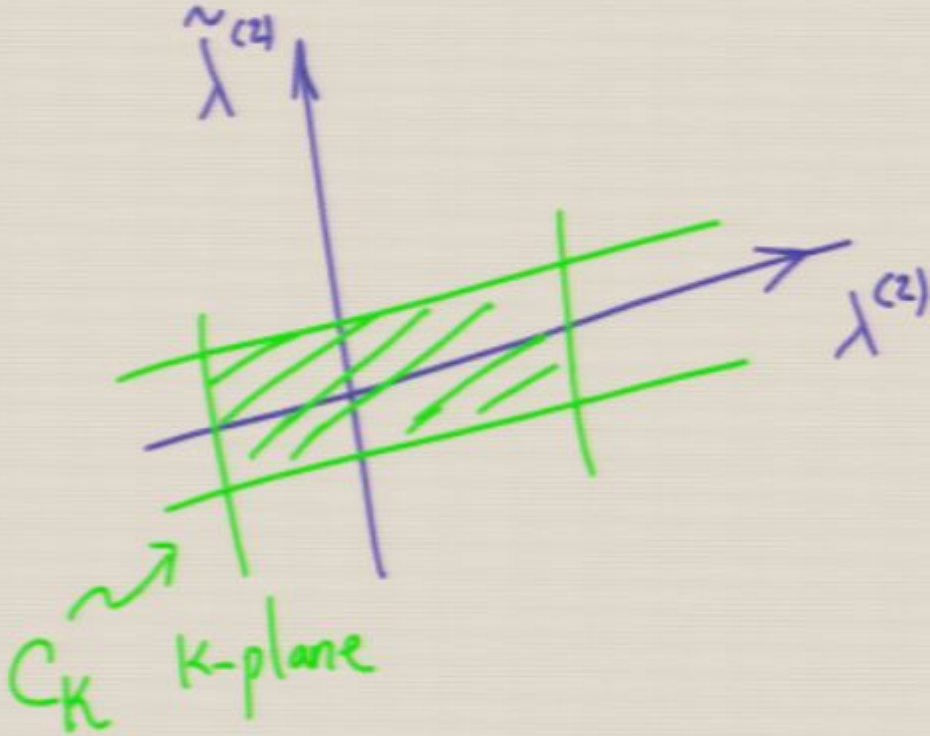
$$\lambda_A^a, \tilde{\lambda}_A^a$$

L_n



mom. conservation:

$$\lambda \cdot \tilde{\lambda} = 0.$$



Note: parity
invariant since
 $\lambda \leftrightarrow \tilde{\lambda}$

k plane $\leftrightarrow n-k$ plane

Note: impossible
for $k = 0, 1, n-1, n$.
Good!

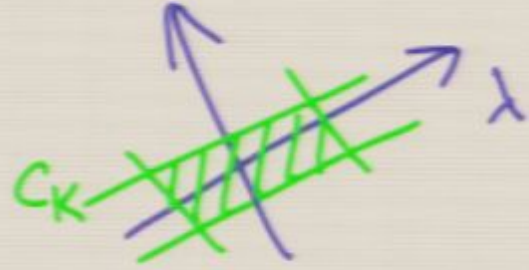
Egns:

$$C = \begin{bmatrix} n_1 \\ \vdots \\ n_k \end{bmatrix} = C_{\alpha a}$$

Invariance under $GL(k)$ $C_{\alpha a} \rightarrow L_a^{\beta} C_{\beta a}$.

Space of k -planes in n -dim: **Grassmannian** $G(k, n)$

$$\dim G(k, n) = kn - k^2 = k(n-k)$$



$$\int d^k \rho_\alpha \underbrace{\delta^2 [C_{\alpha a} p_a - \tilde{\lambda}_a]}_{C \text{ contains } \lambda} \underbrace{\delta^2 [C_{\alpha a} \tilde{\lambda}_a]}_{C \text{ orthogonal to } \tilde{\lambda}} \underbrace{\delta^4 [C_{\alpha a} \tilde{\eta}_a]}_{\text{SUSY partner}}$$

Motivation: preserve $GL(k)$

This object is very simple
in Twistor Space :

$$\prod_{\alpha=1}^k \mathcal{S}^{4/4} [C_{\alpha a} W_a]$$

Manifests (Super) conformal symmetry

$k=0, 1, n-1, n$: no possible planes.

$k=2$ unique: $C = \lambda$ plane.

General k : integrate over all k -planes!

$$\int \frac{d^{k \times n} C \propto a.}{C(1 \dots k)(2 \dots k+1) \dots (n-1 \dots k-1)}$$

simplest + most
natural GL(k)
invariant measure!

$(m_1 \dots m_k)$: $k \times k$ minor of C made of columns m_1, \dots, m_k .

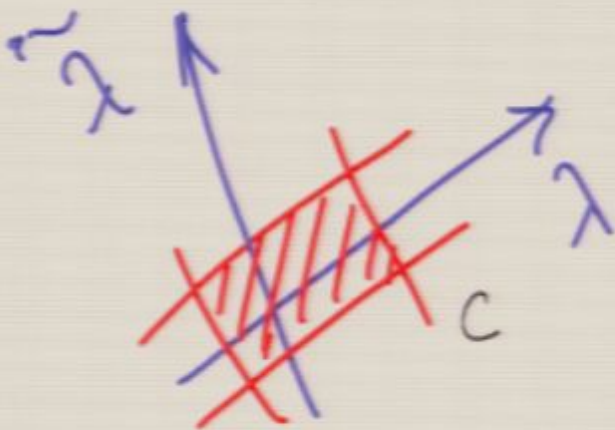
$$\mathcal{L}_{n,k} = \int \frac{d^{k(n-k)} C_{\alpha a}}{(1 \dots k) \dots (n-1 \dots k-1)} \times \prod_{\alpha} \mathcal{S}^{4/4} [C_{\alpha a} W_a]$$

simplest measure
simplest dependence on kinematics



All-Loop Scattering in $\mathcal{N}=4$ SYM!

Manifest Dual Superconformal Invariance



C contains λ plane:
so really an integral over
 $(k-2)$ planes in n dimensions!

Natural linear transformation mapping $k \times k$ minors to $(k-2) \times (k-2)$
minors ...

$$\mathcal{L}_{n,k} \rightarrow \int \frac{d^{p \times (n-p)} D_{\alpha a}}{(1 \dots p) \dots (n! \dots (p-1)!) } \times \prod_{\alpha=1}^p \delta^{4|4} [D_{\alpha a} Z_a]$$

↑
momentum
- twistor
variables

Identical Structure!

Dual superconformal symmetry manifest

The Grassmannian Formulation

makes no mention of locality

or Unitarity - but makes all

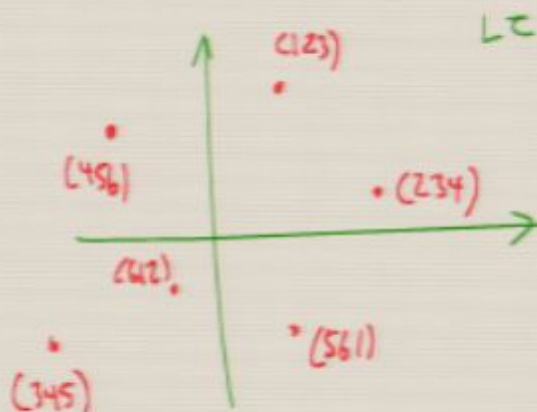
symmetries - The Yangian - manifest.

Quick Example

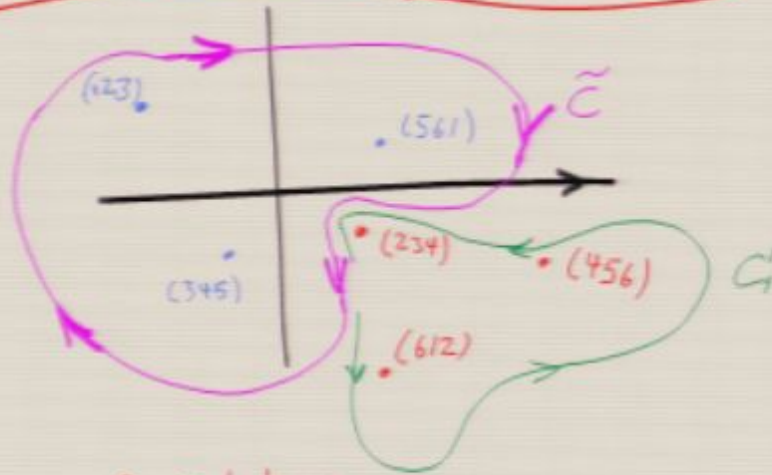
First non-trivial $k=3, n=6$, NMHV, $(k-2)(n-k-2) = 1$ variable!

$$\mathcal{Z}_{6,3} = \int \frac{d\tau}{(123)(45) - (612)(\tau)}$$

each minor linear
in τ



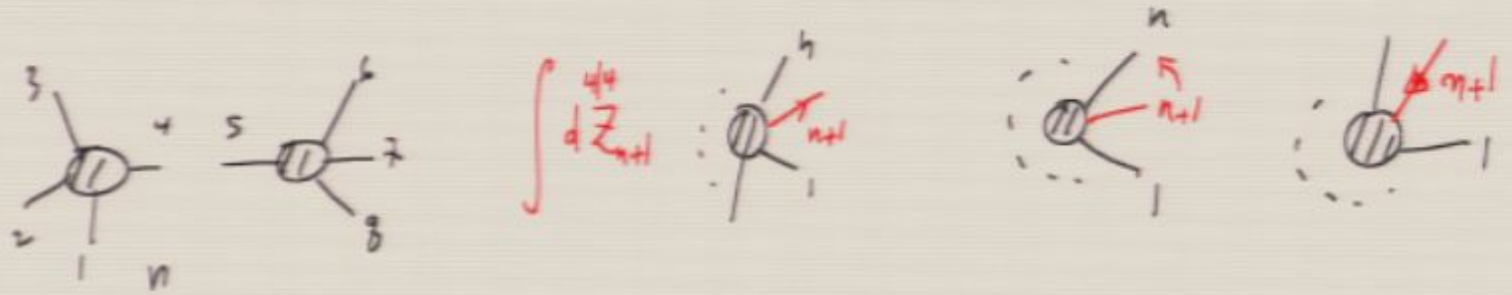
Tree Amplitude



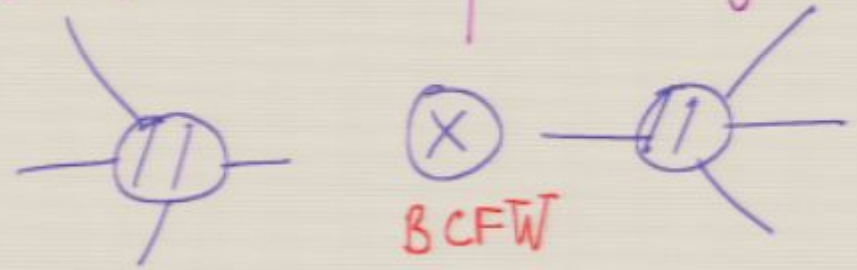
[Unique choices
respecting
cyclic symmetry]

- residues : BCFW terms
- residues : P[BCFW] terms
- Cauchy : $BCFW = P[BCFW] = \text{Remarkable 6-term identity!}$

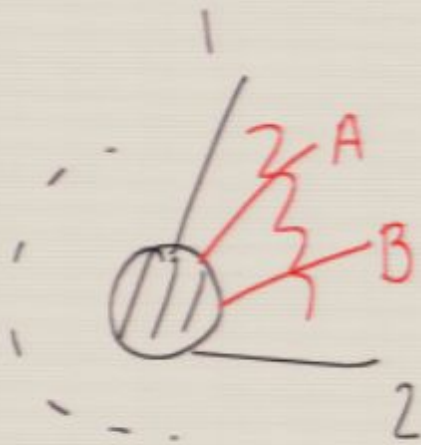
Basic Operations on Yangian Invariants



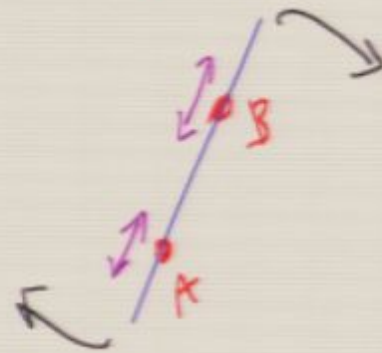
BCFW terms composed from these



Origin of Loops



$$\int d^{4|4} z_A d^{4|4} z_B$$



"Entangled"
removal
of a pair
of particles

Quantum
Loop Corrections

All-Loop Recursion

$$\begin{array}{c} n \\ \curvearrowright \\ n-1 \\ \vdots \\ \textcircled{n \ k} \\ \vdots \\ \ell \end{array} \begin{array}{c} 1 \\ \vdots \\ 2 \\ \vdots \end{array} = \sum_{n_L, k_L, \ell_L, j} \begin{array}{c} n \\ \vdots \\ n-1 \\ \vdots \\ \textcircled{n_L \ k_L} \\ \vdots \\ \ell_L \\ j+1 \end{array} \otimes_{\text{BCFW}} \begin{array}{c} 1 \\ \vdots \\ 2 \\ \vdots \\ \textcircled{n_R \ k_R} \\ \vdots \\ \ell_R \\ j \end{array} + \begin{array}{c} n \\ \vdots \\ 1 \\ \vdots \\ \textcircled{n+1 \ k+1} \\ \vdots \\ \ell-1 \\ 2 \end{array} \begin{array}{c} 1 \\ \vdots \\ A_\ell \\ B_\ell \\ \vdots \\ 1 \\ 2 \end{array}$$

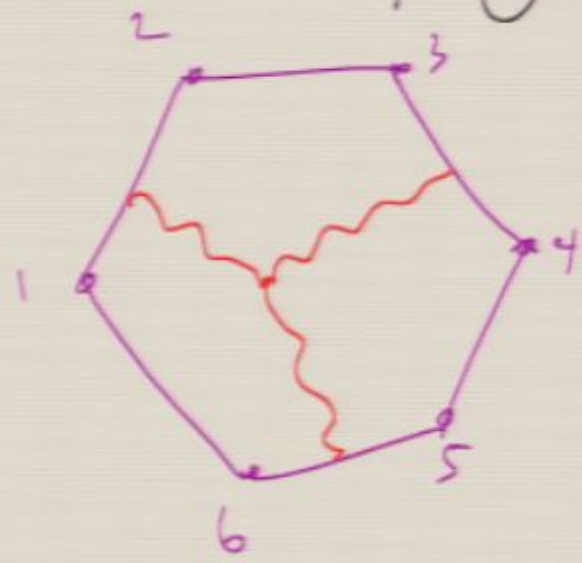
"Classical"

"Quantum"

Complete definition of theory,
Yangian symmetry manifest.

The words "spacetime", "Lagrangian",
"Path Integral", "Gauge Symmetry" ...
make no appearance.

In the dual space-time, this object is interpreted as a certain supersymmetric Wilson loop:



Perfect symmetry has been established between both descriptions.



$$-\frac{1}{4} \begin{bmatrix} a & a+1 & b-1 \\ b+1 & c-1 & c \end{bmatrix} \quad (53)$$

B. Kissing double-box topologies

$$-\begin{array}{c} | \quad b \quad | \\ \hline | \quad a \quad | \\ \hline \end{array} - \quad -\frac{1}{4} \begin{bmatrix} a & a+1 & b-1 & b \\ b & b+1 & a-1 & a \end{bmatrix} + \frac{1}{4} \begin{bmatrix} a & a+1 \\ b-1 & b \end{bmatrix} \begin{bmatrix} b & b+1 \\ a-1 & a \end{bmatrix} =$$

$$\frac{1}{4} \left(x_{a-1,b+1}^2 x_{a+1,b-1}^2 (x_{ab}^2)^2 - x_{a-1,b-1}^2 x_{a+1,b+1}^2 (x_{ab}^2)^2 + \right.$$

$$+ x_{a-1,a+1}^2 x_{b-1,b+1}^2 (x_{ab}^2)^2 - x_{a-1,b}^2 x_{a,b+1}^2 x_{a+1,b-1}^2 x_{ab}^2 -$$

$$- x_{a-1,b+1}^2 x_{a,b-1}^2 x_{a+1,b}^2 x_{ab}^2 + x_{a-1,b-1}^2 x_{a,b+1}^2 x_{a+1,b}^2 x_{ab}^2 +$$

$$\left. + x_{a-1,b}^2 x_{a,b-1}^2 x_{a+1,b+1}^2 x_{ab}^2 \right) \quad (54)$$

$$-\begin{array}{c} | \quad b \quad | \\ \hline | \quad a \quad | \\ \hline \end{array} - \quad -\frac{1}{4} \begin{bmatrix} a+1 & a+2 & b-1 & b \\ b & b+1 & a-1 & a \end{bmatrix} + \frac{1}{4} \begin{bmatrix} a-1 & a \\ b & b+1 \end{bmatrix} \begin{bmatrix} a+1 & a+2 \\ b-1 & b \end{bmatrix} \quad (55)$$

$$-\begin{array}{c} | \quad b \quad | \\ \hline | \quad a \quad | \\ \hline \end{array} - \quad -\frac{1}{4} \begin{bmatrix} a+1 & a+2 & b-1 & b \\ b+1 & b+2 & a-1 & a \end{bmatrix} + \frac{1}{4} \begin{bmatrix} a+1 & a+2 \\ b-1 & b \end{bmatrix} \begin{bmatrix} b+1 & b+2 \\ a-1 & a \end{bmatrix} \quad (56)$$

$$-\begin{array}{c} | \quad b \quad | \\ \hline | \quad a \quad | \quad c \quad | \\ \hline \end{array} - \quad -\frac{1}{4} \begin{bmatrix} a & a+1 & b-1 & b \\ b & b+1 & c-1 & c \end{bmatrix} + \frac{1}{4} \begin{bmatrix} a & a+1 \\ b-1 & b \end{bmatrix} \begin{bmatrix} b & b+1 \\ c-1 & c \end{bmatrix} \quad (57)$$

$$-\begin{array}{c} | \quad b \quad | \\ \hline | \quad a \quad | \quad c \quad | \\ \hline \end{array} - \quad -\frac{1}{4} \begin{bmatrix} a & a+1 & b-1 & b \\ b+1 & b+2 & c-1 & c \end{bmatrix} + \frac{1}{4} \begin{bmatrix} a & a+1 \\ b-1 & b \end{bmatrix} \begin{bmatrix} b+1 & b+2 \\ c-1 & c \end{bmatrix} \quad (58)$$

$$A_{\text{MHV}}^{2\text{-loop}} = \frac{1}{2} \sum_{i < j < k < l < i} \text{Diagram}$$

$$A_{\text{NMHV}}^{2\text{-loop}} = \sum_{\substack{i < j < l < m < k < i \\ i < j < k < l < m < i \\ i < l < m < j < k < i}} \text{Diagram} + \frac{1}{2} \sum_{i < j < k < l < i} \text{Diagram}$$

$\times [i, j, j+1, k, k+1]$

$\times \left\{ \begin{aligned} &A_{\text{NMHV}}^{\text{tree}}(j, \dots, k; l, \dots, i) \\ &+ A_{\text{NMHV}}^{\text{tree}}(i, \dots, j) \\ &+ A_{\text{NMHV}}^{\text{tree}}(k, \dots, l) \end{aligned} \right\}$

$$A_{\text{MHV}}^{3\text{-loop}} = \frac{1}{3} \sum_{\substack{i_1 \leq i_2 < j_1 \leq \\ \leq j_2 < k_1 \leq k_2 < i_1}} \text{Diagram} + \frac{1}{2} \sum_{\substack{i_1 \leq j_1 < k_1 < \\ < k_2 \leq j_2 < i_2 < i_1}} \text{Diagram}$$

$$\begin{aligned}
 & \frac{1}{2} \mathcal{G} \left(\frac{1}{1-u_3}, v_{321}, \frac{1}{1-u_3}, 1; 1 \right) + \frac{1}{4} \mathcal{G} \left(\frac{1}{1-u_3}, v_{321}, \frac{1}{1-u_3}, \frac{1}{1-u_3}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{123}, 0, 1, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 0, \frac{1}{1-u_1}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 1, 0, \frac{1}{1-u_1}; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{123}, 1, 1, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 0, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, \frac{1}{1-u_1}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{132}, \frac{1}{1-u_1}, \frac{1}{1-u_1}, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{132}, 1, 1, \frac{1}{1-u_1}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{132}, 1, \frac{1}{1-u_1}, 1; 1 \right) - \\
 & \frac{1}{4} \mathcal{G} \left(v_{132}, \frac{1}{1-u_1}, 1, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{213}, 1, 1, \frac{1}{1-u_2}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{213}, 1, \frac{1}{1-u_2}, 1; 1 \right) - \\
 & \frac{1}{4} \mathcal{G} \left(v_{213}, \frac{1}{1-u_2}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, 0, 1, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, 0, \frac{1}{1-u_2}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{211}, 1, 0, \frac{1}{1-u_2}; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{211}, 1, 1, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, 1, \frac{1}{1-u_2}, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{211}, 1, \frac{1}{1-u_2}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, 1, \frac{1}{1-u_2}, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, \frac{1}{1-u_2}, 0, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{211}, \frac{1}{1-u_2}, 1, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{211}, \frac{1}{1-u_2}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{211}, \frac{1}{1-u_2}, 1, \frac{1}{1-u_2}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{211}, \frac{1}{1-u_2}, \frac{1}{1-u_2}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 0, 1, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 0, \frac{1}{1-u_3}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, 1, 0, \frac{1}{1-u_3}; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{312}, 1, 1, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 0, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, \frac{1}{1-u_3}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, \frac{1}{1-u_3}, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{321}, 1, 1, \frac{1}{1-u_3}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{321}, 1, \frac{1}{1-u_3}, 1; 1 \right) - \\
 & \frac{1}{4} \mathcal{G} \left(v_{321}, \frac{1}{1-u_3}, 1, 1; 1 \right) - \frac{3}{4} \mathcal{G} \left(0, \frac{1}{u_1}, \frac{1}{u_1+u_2}, 1 \right) H(0; u_1) -
 \end{aligned}$$

$$\begin{aligned}
 & \frac{1}{2}G\left(\frac{1}{1-u_1}, \frac{1}{1-u_1}, 1; 1\right) - \frac{1}{4}G\left(\frac{1}{1-u_1}, 1, 1; 1\right) - \frac{1}{4}G\left(\frac{1}{1-u_1}, 1, 1; 1\right) - \\
 & \frac{1}{4}G\left(\frac{1}{1-u_1}, 1, 1; 1\right) - \frac{1}{4}G\left(\frac{1}{1-u_2}, 1, 1; 1\right) - \frac{1}{4}G\left(\frac{1}{1-u_2}, 1, 1; 1\right) - \\
 & \frac{1}{4}G\left(\frac{1}{1-u_2}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, 0, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, 0, 1; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_2}, 1, 0; 1\right) - \frac{5}{4}G\left(\frac{1}{1-u_2}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, 1, 0; 1\right) - \\
 & \frac{5}{4}G\left(\frac{1}{1-u_2}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, 0; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, 1, 0; 1\right) - \frac{5}{4}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, 1, \frac{1}{1-u_2}; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_2}, \frac{1}{1-u_2}, \frac{1}{1-u_2}, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, 0, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, 0, \frac{1}{1-u_3}; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_3}, 1, 0; 1\right) - \frac{5}{4}G\left(\frac{1}{1-u_3}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, 1, 0; 1\right) - \\
 & \frac{5}{4}G\left(\frac{1}{1-u_3}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, 0; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, 1, 0; 1\right) - \frac{5}{4}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, 1, 1; 1\right) + \frac{1}{2}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, 1, \frac{1}{1-u_3}; 1\right) + \\
 & \frac{1}{2}G\left(\frac{1}{1-u_3}, \frac{1}{1-u_3}, \frac{1}{1-u_3}, 1; 1\right) - \frac{1}{4}G\left(\frac{1}{u_1}, \frac{1}{u_1}, \frac{1}{1-u_3}; 1\right) - \frac{1}{4}G\left(\frac{1}{u_1}, \frac{1}{u_1}, \frac{1}{1-u_3}; 1\right) - \\
 & \frac{1}{4}G\left(\frac{1}{u_1}, \frac{1}{u_1}, 1, 1; 1\right) - \frac{3}{4}G\left(0, \frac{1}{u_1}, \frac{1}{u_1+u_2}; 1\right) H(0; u_1) - \\
 & \frac{3}{4}G\left(0, \frac{1}{u_1}, \frac{1}{u_1+u_3}; 1\right) H(0; u_1) - \frac{1}{4}G\left(0, \frac{1}{u_2}, \frac{1}{u_1+u_2}; 1\right) H(0; u_1) - \\
 & \frac{1}{4}G\left(0, \frac{1}{u_2}, \frac{1}{u_1+u_3}; 1\right) H(0; u_1) - \frac{1}{4}G\left(0, \frac{u_1-1}{u_1+u_3-1}, \frac{1}{1-u_3}; 1\right) H(0; u_1) + \\
 & \frac{1}{4}G\left(0, \frac{u_3-1}{u_2+u_3-1}, \frac{1}{1-u_2}; 1\right) H(0; u_1) - \frac{3}{4}G\left(\frac{1}{u_1}, 0, \frac{1}{u_1+u_2}; 1\right) H(0; u_1) - \\
 & \frac{3}{4}G\left(\frac{1}{u_1}, 0, \frac{1}{u_1+u_3}; 1\right) H(0; u_1) + \frac{1}{2}G\left(\frac{1}{u_1}, \frac{1}{u_1}, \frac{1}{u_1+u_2}; 1\right) H(0; u_1) + \\
 & \frac{1}{2}G\left(\frac{1}{u_1}, \frac{1}{u_1}, \frac{1}{u_1+u_3}; 1\right) H(0; u_1) + \frac{1}{4}G\left(\frac{1}{u_1}, \frac{1}{u_2}, \frac{1}{u_1+u_2}; 1\right) H(0; u_1) + \\
 & \frac{1}{4}G\left(\frac{1}{u_1}, \frac{1}{u_3}, \frac{1}{u_1+u_3}; 1\right) H(0; u_1) - \frac{1}{4}G\left(\frac{1}{1-u_2}, 1, \frac{1}{u_1}; 1\right) H(0; u_1) +
 \end{aligned}$$

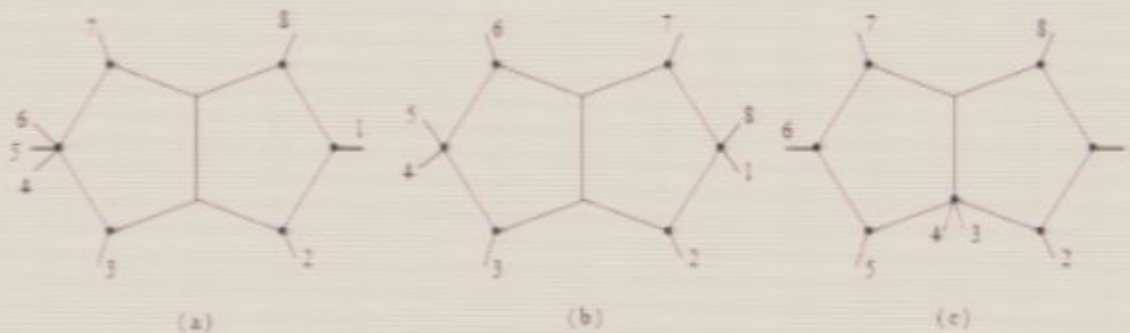
$$\begin{aligned}
 & \frac{1}{2} \mathcal{G} \left(\frac{1}{1-u_3}, v_{321}, \frac{1}{1-u_3}, 1; 1 \right) + \frac{1}{4} \mathcal{G} \left(\frac{1}{1-u_3}, v_{321}, \frac{1}{1-u_3}, \frac{1}{1-u_3}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{123}, 0, 1, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 0, \frac{1}{1-u_1}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 1, 0, \frac{1}{1-u_1}; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{123}, 1, 1, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{123}, 1, \frac{1}{1-u_1}, \frac{1}{1-u_1}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 0, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{123}, \frac{1}{1-u_1}, 1, \frac{1}{1-u_1}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{132}, \frac{1}{1-u_1}, \frac{1}{1-u_1}, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{132}, 1, 1, \frac{1}{1-u_1}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{132}, 1, \frac{1}{1-u_1}, 1; 1 \right) - \\
 & \frac{1}{4} \mathcal{G} \left(v_{132}, \frac{1}{1-u_1}, 1, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{213}, 1, 1, \frac{1}{1-u_2}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{213}, 1, \frac{1}{1-u_2}, 1; 1 \right) - \\
 & \frac{1}{4} \mathcal{G} \left(v_{213}, \frac{1}{1-u_2}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, 0, 1, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, 0, \frac{1}{1-u_2}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{231}, 1, 0, \frac{1}{1-u_2}; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{231}, 1, 1, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, 1, \frac{1}{1-u_2}, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{231}, 1, \frac{1}{1-u_2}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, 1, \frac{1}{1-u_2}, \frac{1}{1-u_2}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, \frac{1}{1-u_2}, 0, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{231}, \frac{1}{1-u_2}, 1, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{231}, \frac{1}{1-u_2}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{231}, \frac{1}{1-u_2}, 1, \frac{1}{1-u_2}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{231}, \frac{1}{1-u_2}, \frac{1}{1-u_2}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 0, 1, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 0, \frac{1}{1-u_3}, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, 1, 0, \frac{1}{1-u_3}; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{312}, 1, 1, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, 0; 1 \right) - \\
 & \frac{5}{4} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, 1, \frac{1}{1-u_3}, \frac{1}{1-u_3}; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 0, 1; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, 0; 1 \right) - \frac{5}{4} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, 1; 1 \right) + \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, 1, \frac{1}{1-u_3}; 1 \right) + \\
 & \frac{1}{2} \mathcal{G} \left(v_{312}, \frac{1}{1-u_3}, \frac{1}{1-u_3}, 1; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{321}, 1, 1, \frac{1}{1-u_3}; 1 \right) - \frac{1}{4} \mathcal{G} \left(v_{321}, 1, \frac{1}{1-u_3}, 1; 1 \right) -
 \end{aligned}$$

Stunning Simplification

$$R_6^{(2)}(u_1, u_2, u_3) = \sum_{i=1}^3 \left(L_4(x_i^+, x_i^-) - \frac{1}{2} \text{Li}_4(1 - 1/u_i) \right) - \frac{1}{8} \left(\sum_{i=1}^3 \text{Li}_2(1 - 1/u_i) \right)^2 + \frac{1}{24} J^4 + \frac{\pi^2}{12} J^2 + \frac{\pi^4}{72}. \quad (3)$$

[Makes use of "theory of motives"]

New Integrals are Simple!



$$\partial_{\chi^+} \partial_{\chi^-} I^{\text{total}} = \tag{16}$$

$$\frac{1}{\chi^+ \chi^-} \log \chi^+ \log \chi^- + \frac{2(\chi^+ - 1)}{\chi^+ \chi^- (1 + \chi^+)} \log \chi^- \log(1 + \chi^-) + \frac{2(\chi^- - 1)}{\chi^+ \chi^- (1 + \chi^-)} \log \chi^+ \log(1 + \chi^+) +$$

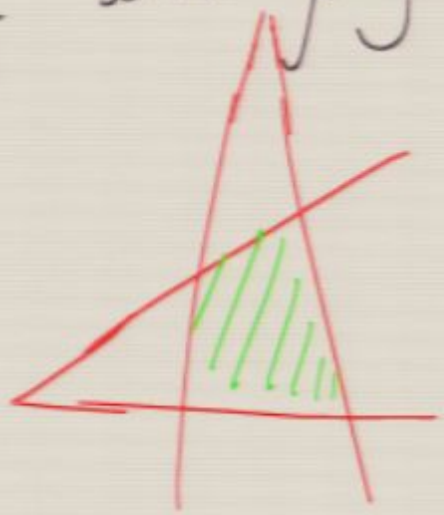
$$+ \frac{4(\chi^+ - 1)}{\chi^+ \chi^- (1 + \chi^+)} \text{Li}_2(-\chi^-) + \frac{4(\chi^- - 1)}{\chi^+ \chi^- (1 + \chi^-)} \text{Li}_2(-\chi^+)$$

This Picture

$$A_{\text{MHV}}^{2\text{-loop}} = \frac{1}{2} \sum_{i < j < k < l < i} \text{Diagram}$$

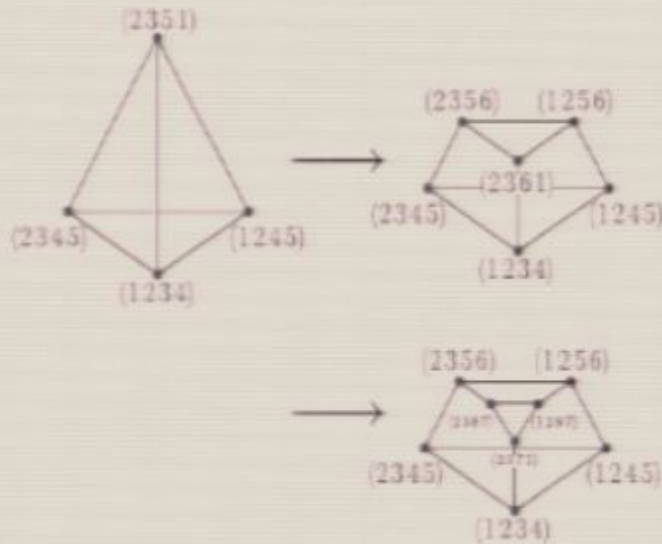
is telling a geometric story —
 once we understand it we'll just
 write down the answer...

• In a specific sense, amplitudes are to be thought of as "the volume" of some polytope:



Different "triangulations" make different properties (Yangian, locality, Unitarity...) manifest.

Our solution should be thought of
as providing one class of triangulations
— but we need to more deeply
understanding what the object is that
is being triangulated!



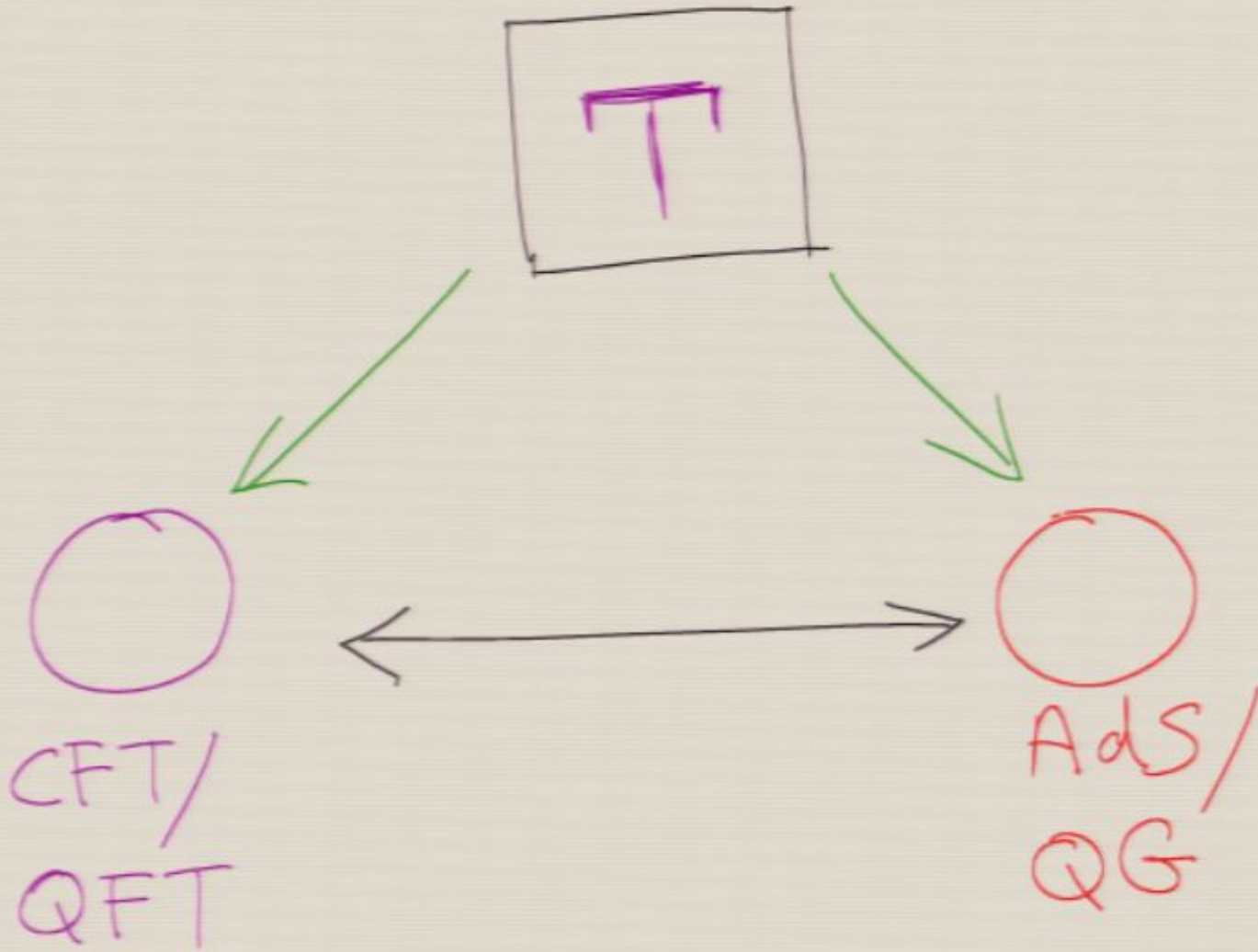
Understood
in Simple
Cases
⋮

$$F_{j,n} = \sum_i \left(\begin{array}{c} (j+1, i-1) \quad (j-1, i-1) \\ \diagdown \quad \diagup \\ (j-1, i+1) \\ \diagup \quad \diagdown \\ (j-1, j+1, j+2) \end{array} + \begin{array}{c} (j-1, i-1) \\ \diagdown \quad \diagup \\ (j+1, i+1) \quad (j-1, i+1) \\ \diagup \quad \diagdown \\ (j-1, j+1, j+2) \end{array} \right) = \sum_{i, s = \pm 1} \begin{array}{c} (j+1, i+1) \quad (j-1, i-1) \\ \diagdown \quad \diagup \\ (j+1, i-s) \\ \diagup \quad \diagdown \\ (j-1, j+1, j+2) \end{array}$$

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$$M_n^{\text{NMHV}} = \sum_{i, j, s = \pm 1} \frac{\langle \eta_j, \{j-1, j, j+1, j+2, i\}, \{j-1, j, j+1, i-s, i\}, \{j, j+1, i, i+1\} \rangle}{\langle j-1, j, j+1, j+2 \rangle \langle j-1, j, i-1, i \rangle \langle j, j+1, i, i+1 \rangle \langle j, j+1, i, i-s \rangle}$$

NEW LOCAL FORM!





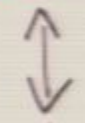
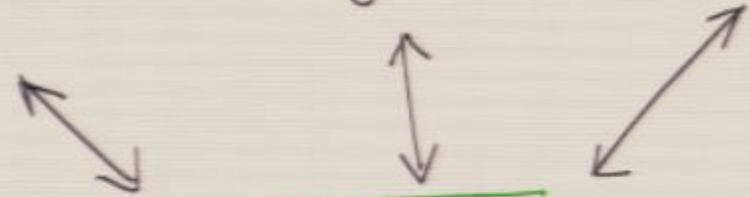
String Theory



Integrability



Twistor theory




Amazing new mathematical structures:
(Grassmannians, Polylogs, "Motivic Galois Theory",)

Still an enormous amount left
to understand: what is the
one-sentence "physical picture"
behind all of this magic?
What moral lesson should we
extract from $N=4$ example?

But there is strong encouragement
to try + fully eviscerate
Locality + Unitarity from
our language for describing
all of standard physics.

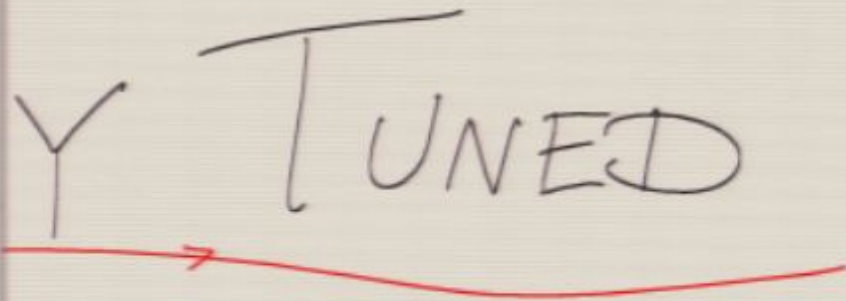
STAY TUNED



File Edit View Insert Actions Tools Help

- New Note Ctrl+N
- New Note from Template...
- Open... Ctrl+O
- Import...
- Search...
- Save Ctrl+S
- Save As...
- Export As...
- Move to Folder... Ctrl+Shift+V
- Delete Note
- Page Setup...
- Print... Ctrl+P
- Send to Mail Recipient...
- Recently Used Notes ▶
- Exit Alt+F4

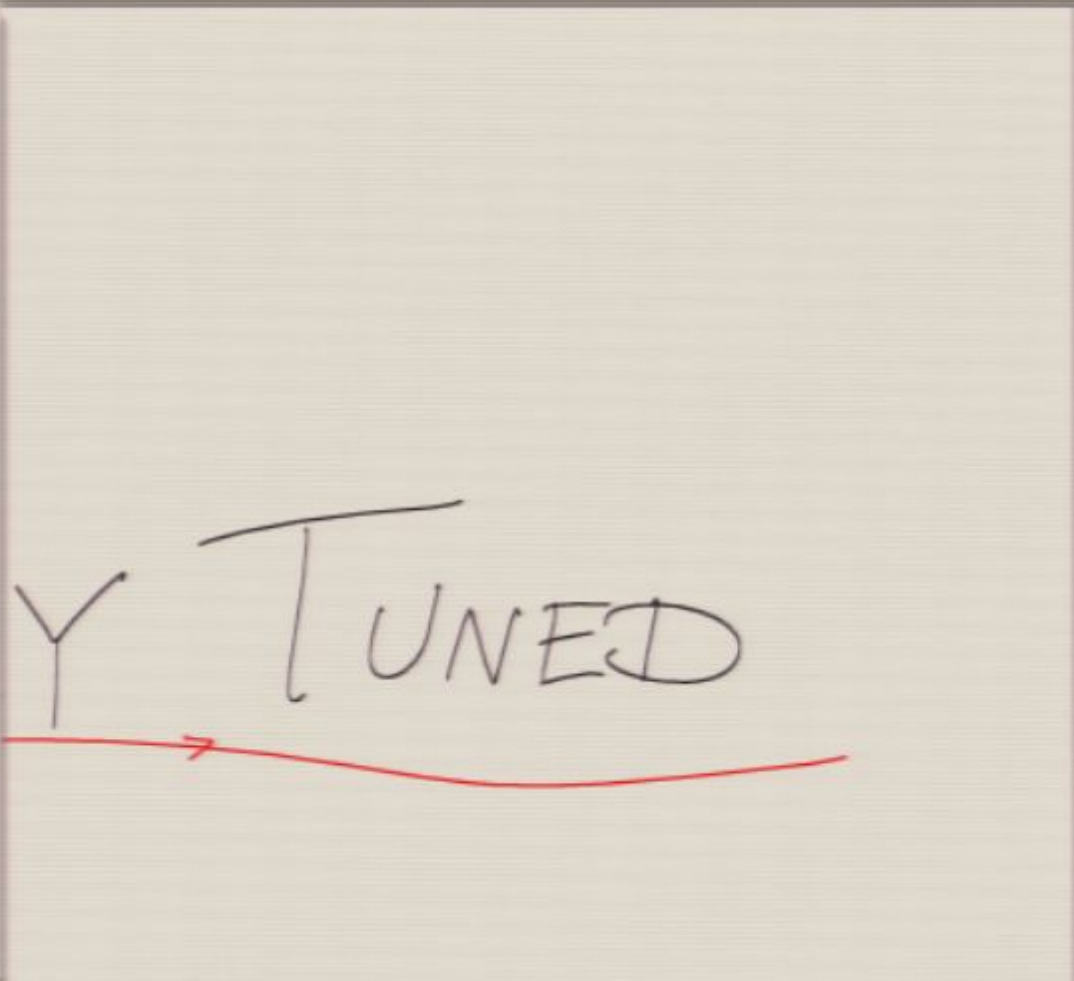
Y TUNED

The image shows the handwritten text "Y TUNED" in a simple, sketchy font. A red horizontal line is drawn underneath the text, starting from the left side of the 'Y' and extending to the right. A small red arrowhead is positioned at the end of this line, pointing towards the right.

File Edit View Insert Actions Tools Help

- New Note Ctrl+N
- New Note from Template...
- Open... Ctrl+O
- Import...
- Search...
- Save Ctrl+S
- Save As...
- Export As...
- Move to Folder... Ctrl+Shift+V
- Delete Note
- Page Setup...
- Print... Ctrl+P
- Send to Mail Recipient...
- Recently Used Notes ▶
- Exit Alt+F4

Y TUNED

The image shows a digital note-taking application interface. On the left, a vertical sidebar contains a yellow notepad icon with a blue pen. The main area is a light-colored canvas. The text 'Y TUNED' is written in a simple, hand-drawn black font. A red horizontal line with an arrowhead pointing to the right is drawn underneath the text, starting from the 'Y' and extending past the 'D'. The 'File' menu is open, showing various options and their keyboard shortcuts.