

Title: Torsion as a Probe in Condensed Matter Systems

Date: Nov 12, 2010 11:00 AM

URL: <http://pirsa.org/10110065>

Abstract: : In this talk I will review the common appearance of torsion in solids as well as some new developments.

Torsion typically appears in condensed matter physics associated to topological defects known as dislocations. Now we are beginning to uncover new aspects of the coupling of torsion to materials. Recently, a dissipationless viscosity has been studied in the quantum Hall effect. I will connect this viscosity to a 2+1-d torsion Chern-Simons term and discuss possible thought experiments in which this could be measured. Additionally I will discuss a new topological defect in 3+1-d, the torsional monopole, which does not require a lattice deformation to exist. If present, torsional monopoles are likely to impact the behavior of materials with strong spin-orbit coupling such as topological insulators.

# **Applications of Torsion in Condensed Matter Physics**

**Taylor L. Hughes**  
**UIUC**

**Perimeter Institute**  
**November 12, 2010**

In collaboration with Rob Leigh and Eduardo Fradkin, and Andy Randono

Hughes, Leigh, Fradkin (in preparation)

Randono, Hughes arxiv: 1010.1031

# Overview

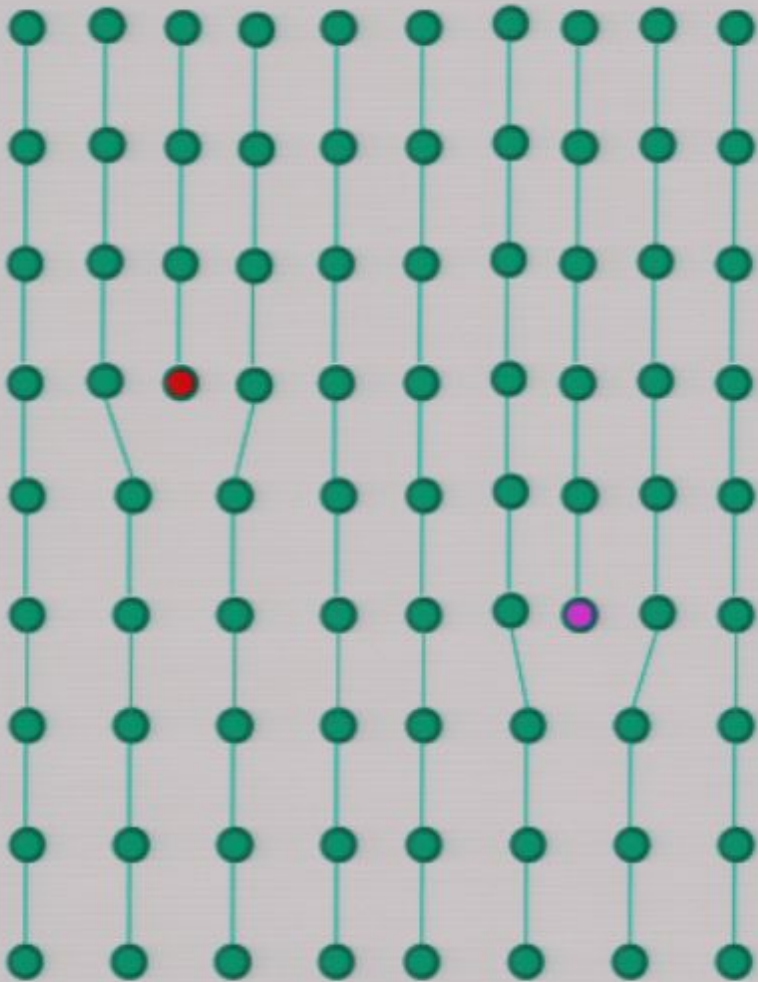
Part 1: Dislocations as sources of torsion

Part 2: Torsional Response of Topological Insulators

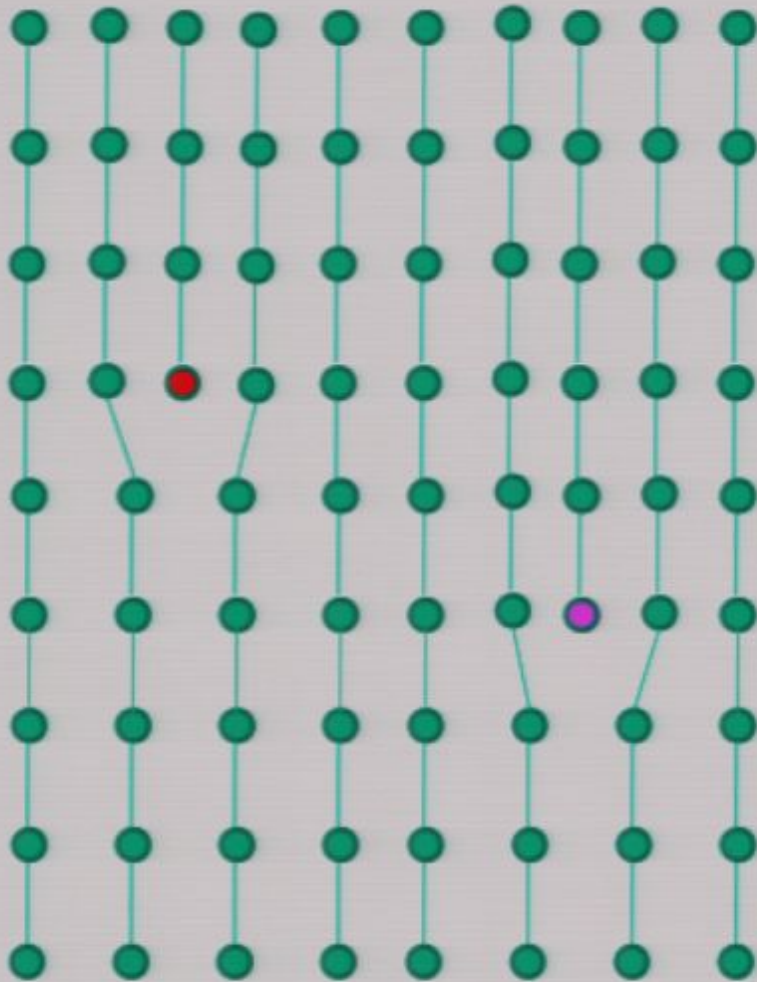
Part 3: Torsional Monopoles in 3+1-d

# **Part 1: Dislocations**

# Crystal Dislocations



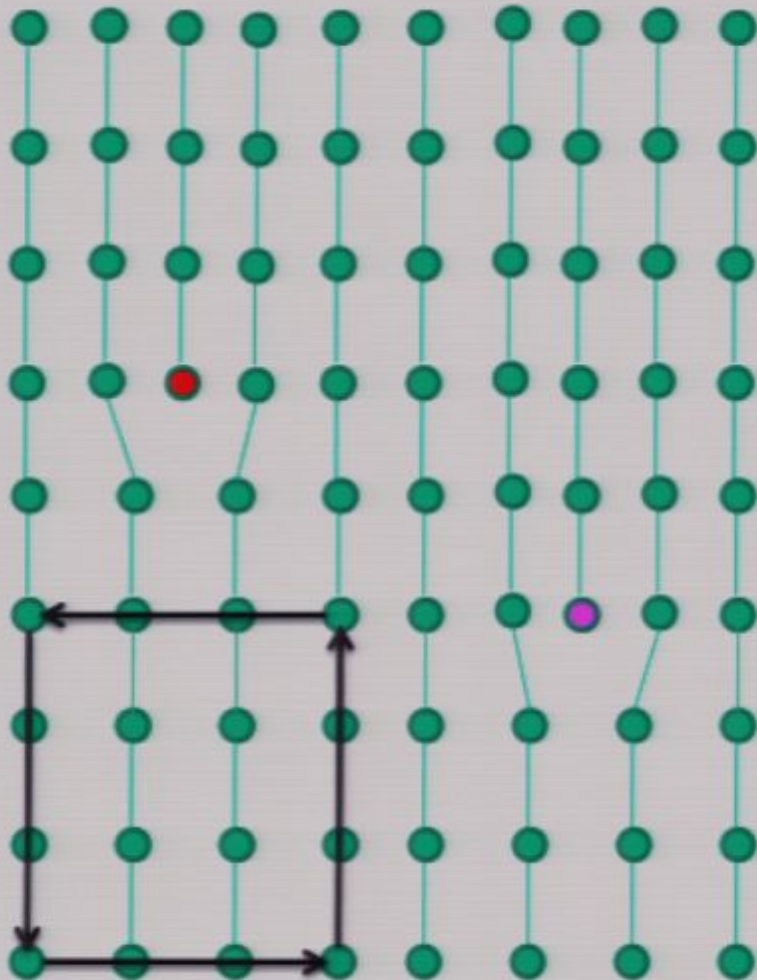
# Crystal Dislocations



Let's take a path in the lattice  
3 steps right  
3 steps up  
3 steps left  
3 steps down  
This path is closed in the  
reference state.

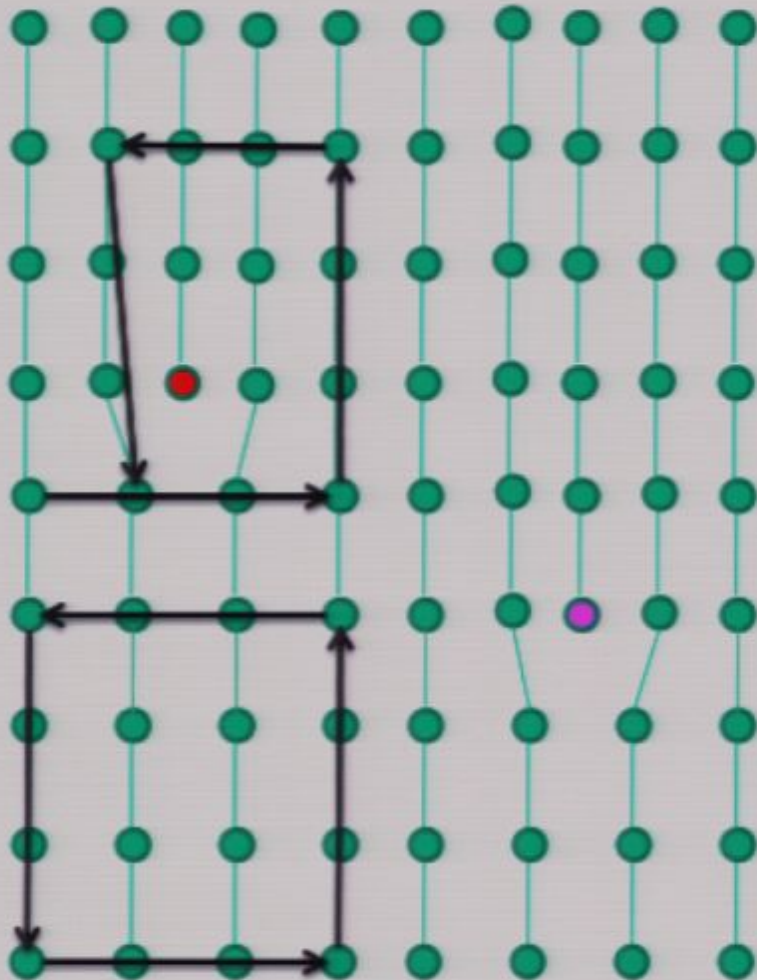


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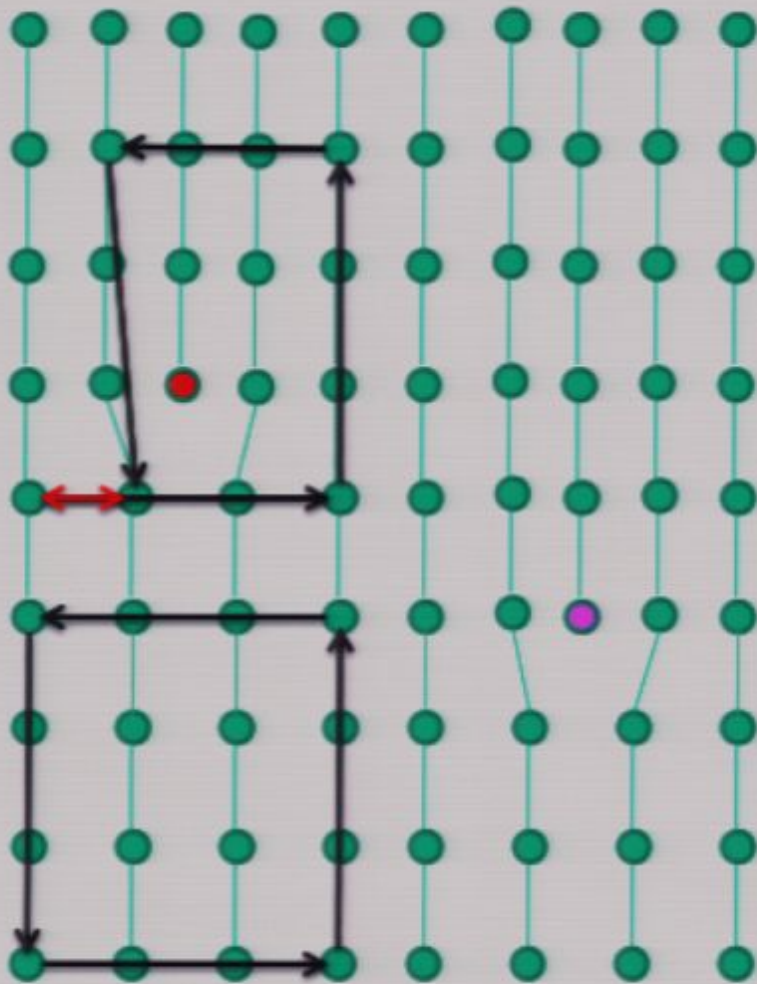
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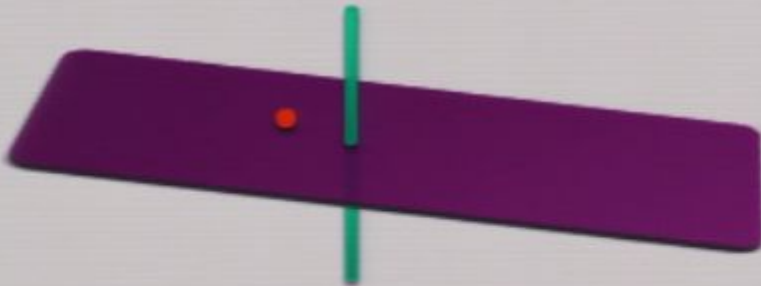
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The amount of translation is the  
Burgers vector and it is a vector of  
topological charges. It doesn't change  
if you continuously deform the  
dislocation.

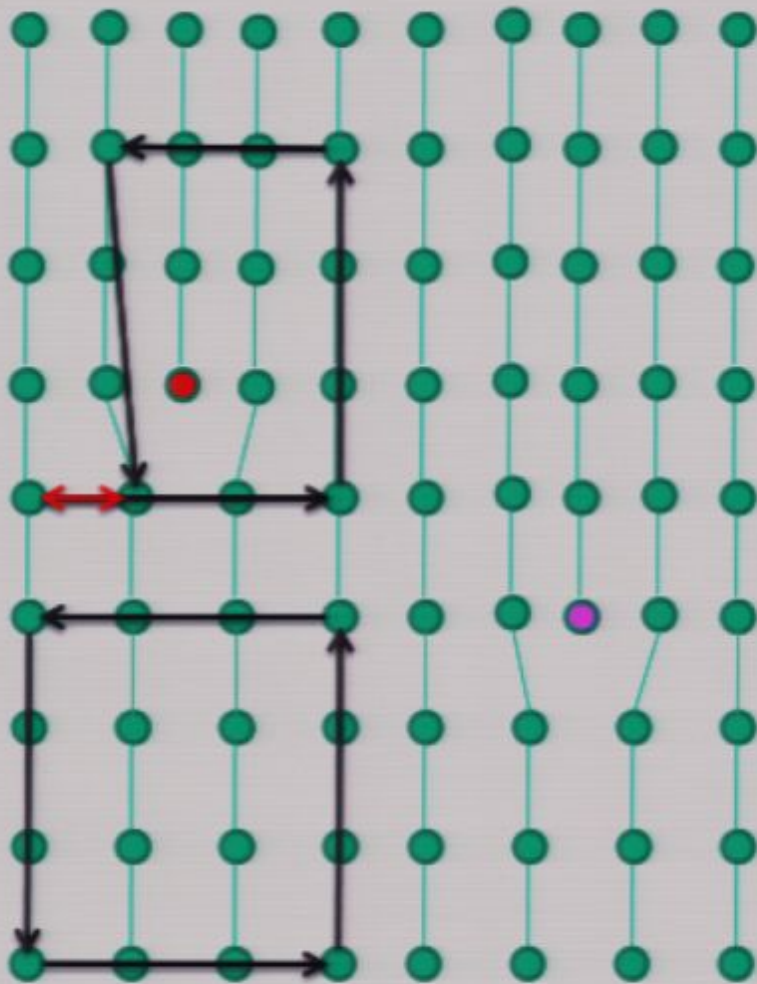
# Crystal Dislocations and Aharonov-Bohm Phases

Magnetic flux gives a U(1) phase

$$U = \exp[i\phi]$$



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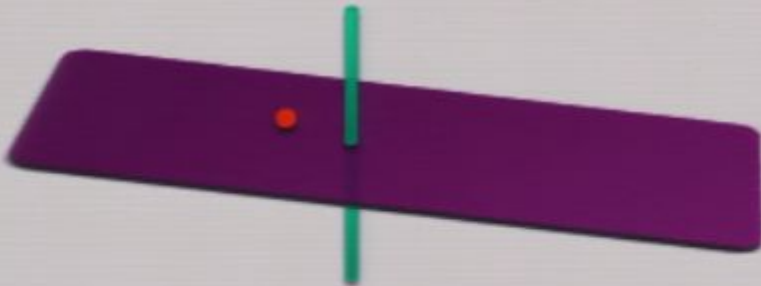
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The amount of translation is the Burgers vector and it is a vector of topological charges. It doesn't change if you continuously deform the dislocation.

# Crystal Dislocations and Aharonov-Bohm Phases

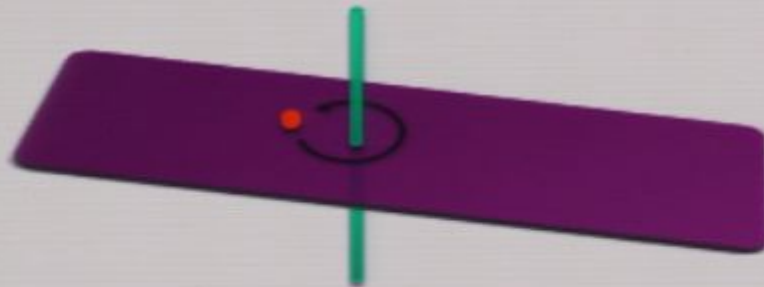
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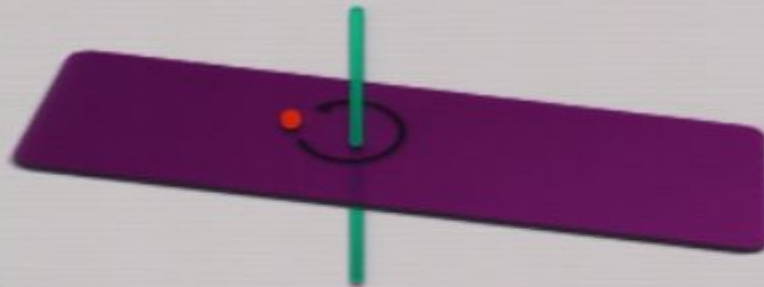
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Dislocation gives a translation operator. Only equivalent to a phase if the state is a momentum eigenstate.

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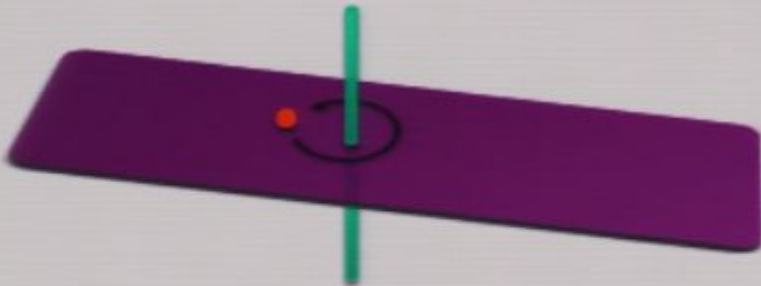
$$U = \exp \left[ \frac{i}{\hbar} p_a b^a \right]$$

$$\exp \left[ \frac{i}{\hbar} p_a b^a \right] \psi(x^a) = \sum_p \phi(p) \exp \left[ \frac{i}{\hbar} p_a (x^a + b^a) \right]$$

# Crystal Dislocations and Aharonov-Bohm Phases

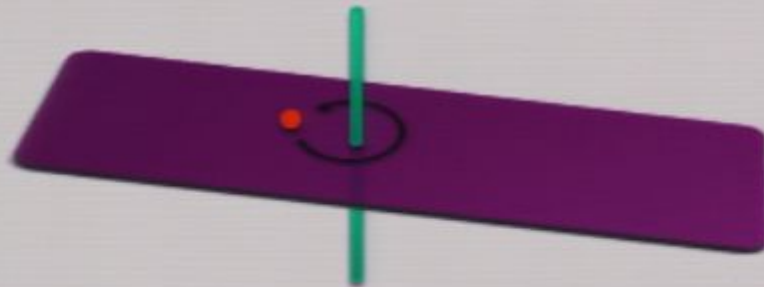
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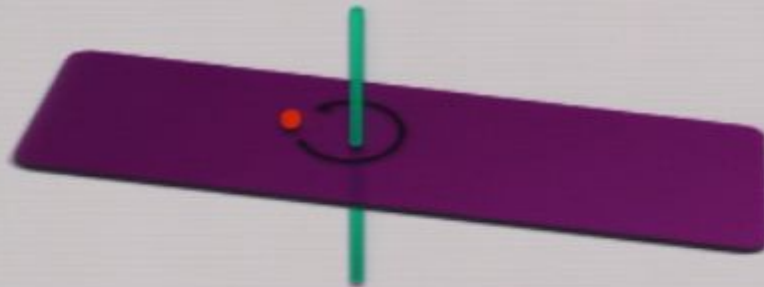
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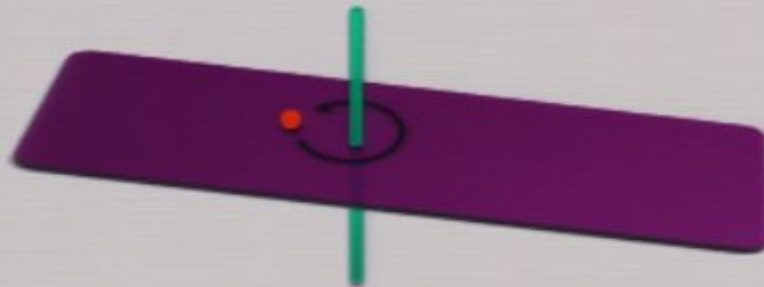
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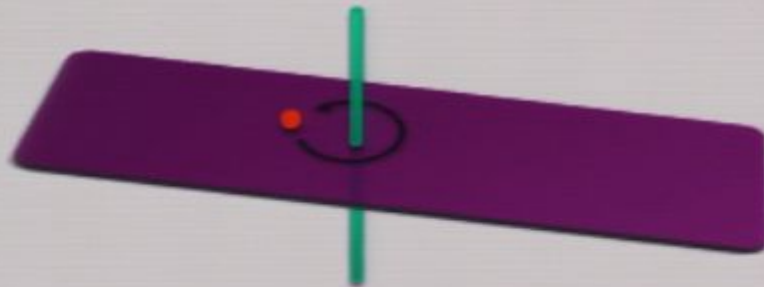
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Gauge potential and Wilson loop for dislocations:

$$[A_\mu] = \frac{1}{\text{Length}}$$

$$[e_\mu^a] = 1$$

$$\mathcal{B}^a = \nabla \times \mathbf{e}^a$$

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## Example: 2+1-d Topological Insulator (QHE)

Take Dirac Hamiltonian in 2+1-d

$$H_{2d} = \sum_k c_k^\dagger (k_x \sigma^x + k_y \sigma^y + m \sigma^z) c_k = \sum_k c_k^\dagger \begin{pmatrix} m & k_x - ik_y \\ k_x + ik_y & -m \end{pmatrix} c_k$$

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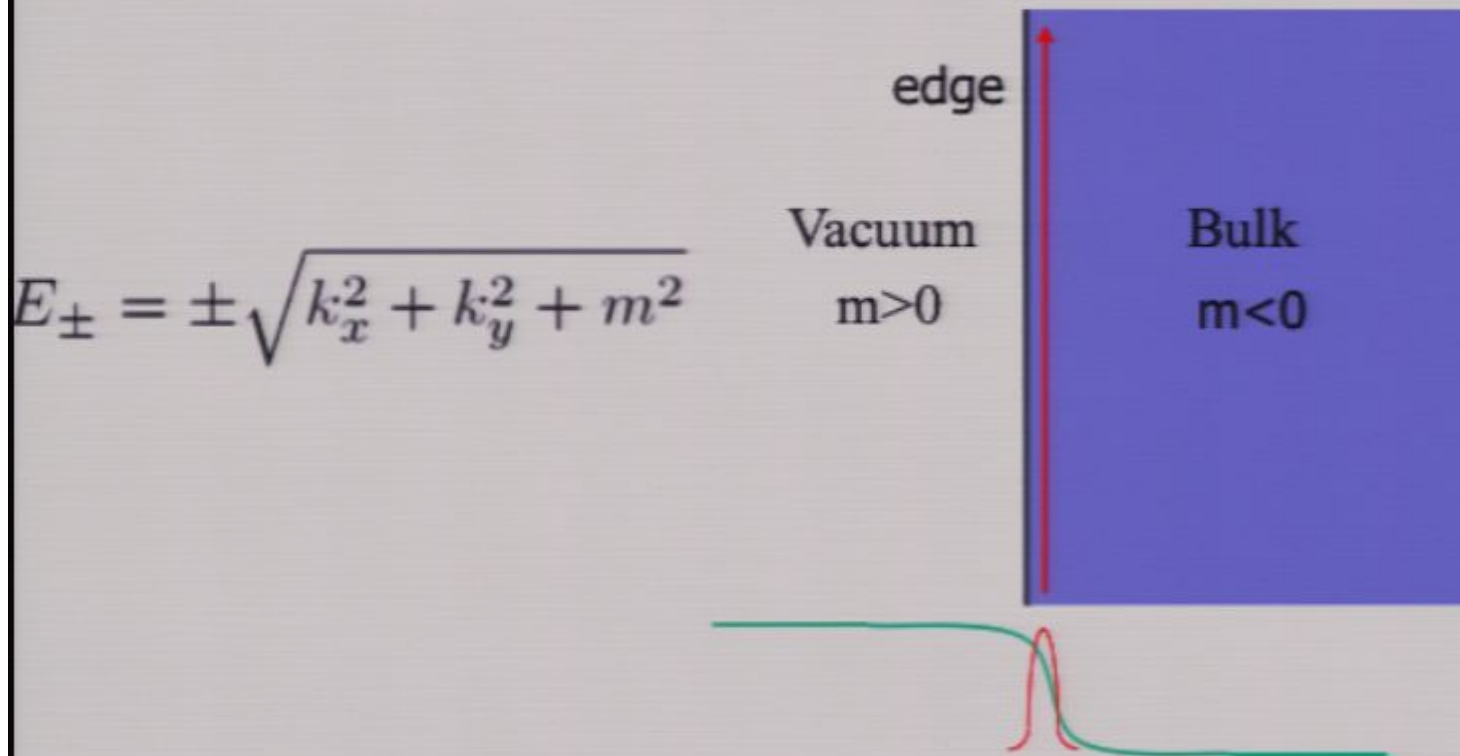
$m > 0$

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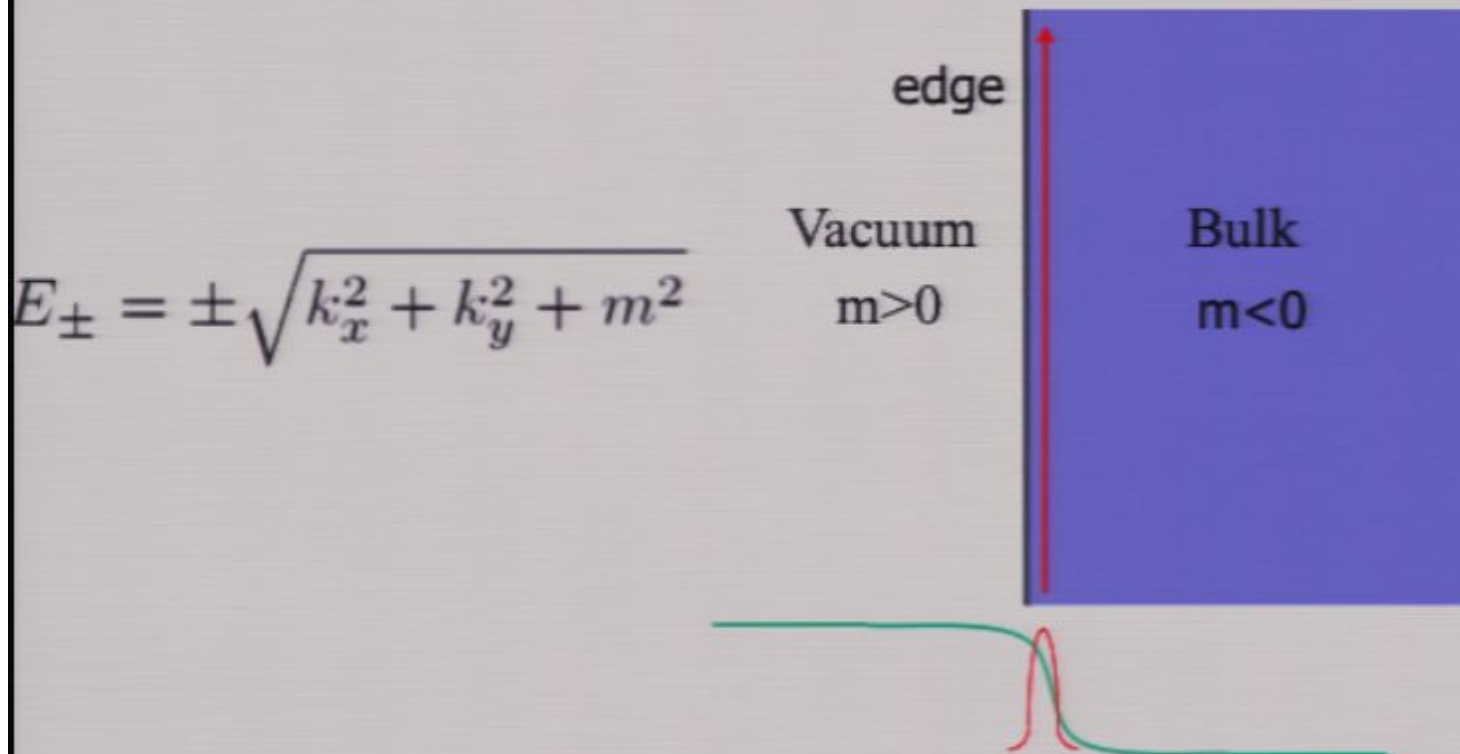
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Bulk described by massive Dirac fermions, boundary described by massless chiral fermions in one lower dimension, Clifford algebra dimension cut in half

# Electro-magnetic Response

Electromagnetic linear response:



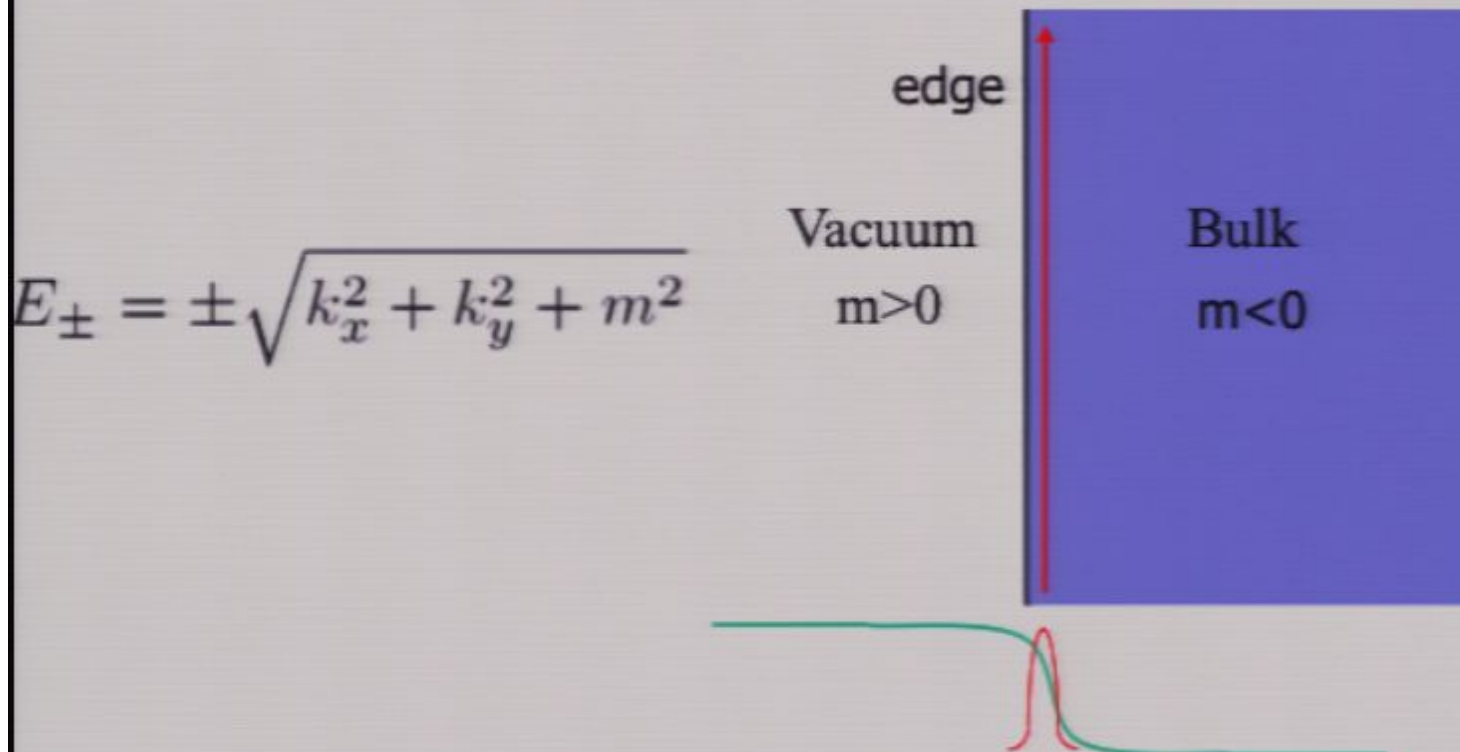
$$S_{eff}[A_\mu] = \frac{n}{4\pi} \int d^3x \epsilon^{\mu\nu\rho} A_\mu \partial_\nu A_\rho$$

$$j^i = \frac{ne^2}{h} \epsilon^{ij} E_j$$

$$j^0 = \frac{ne^2}{h} B$$

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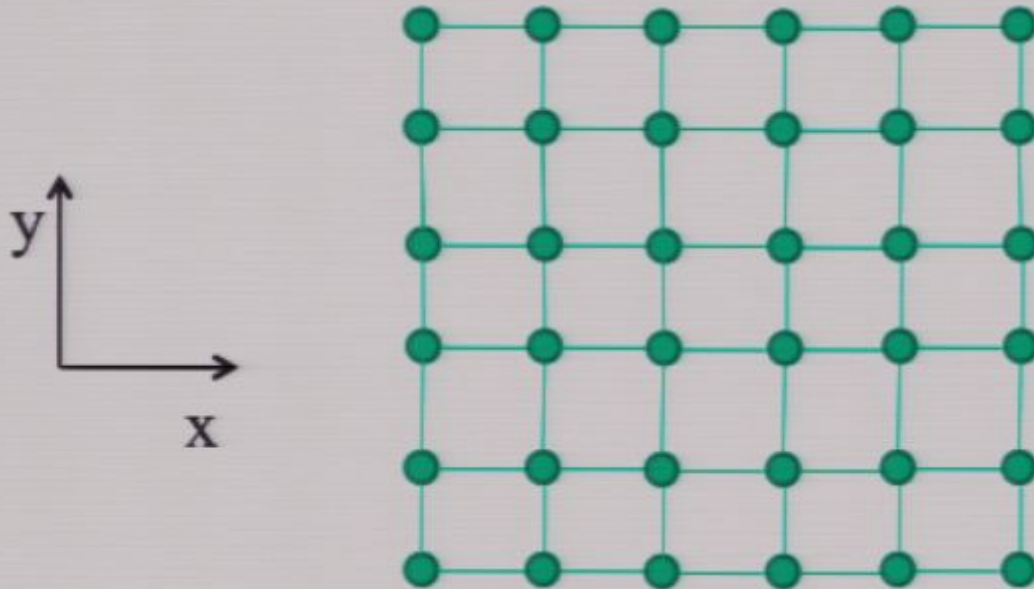


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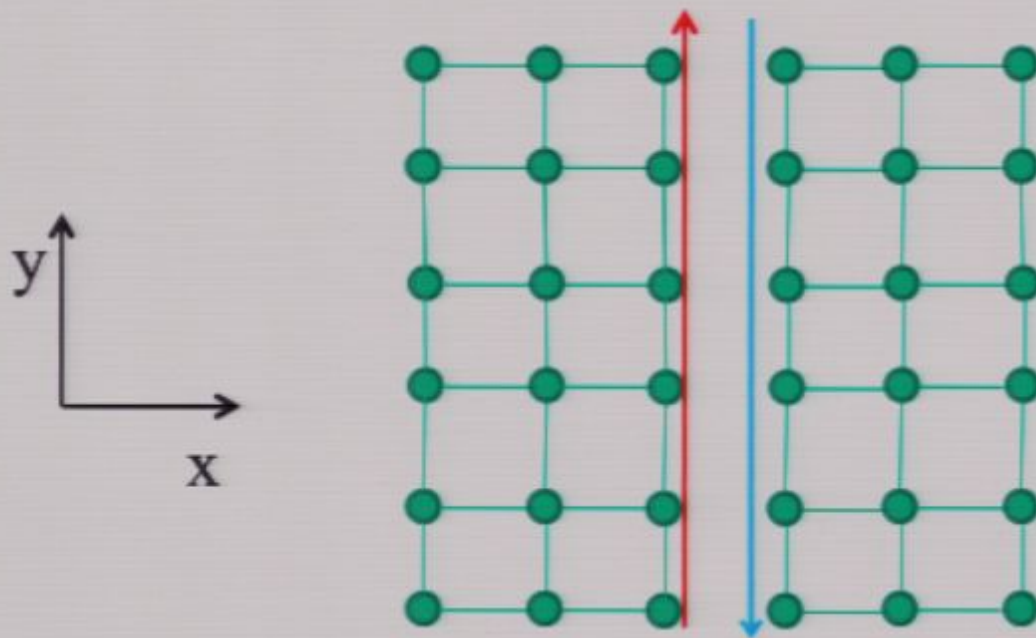
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# Bound States on a flux in the QHE

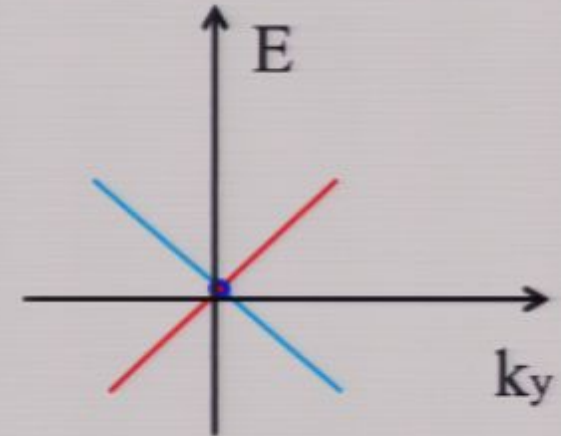




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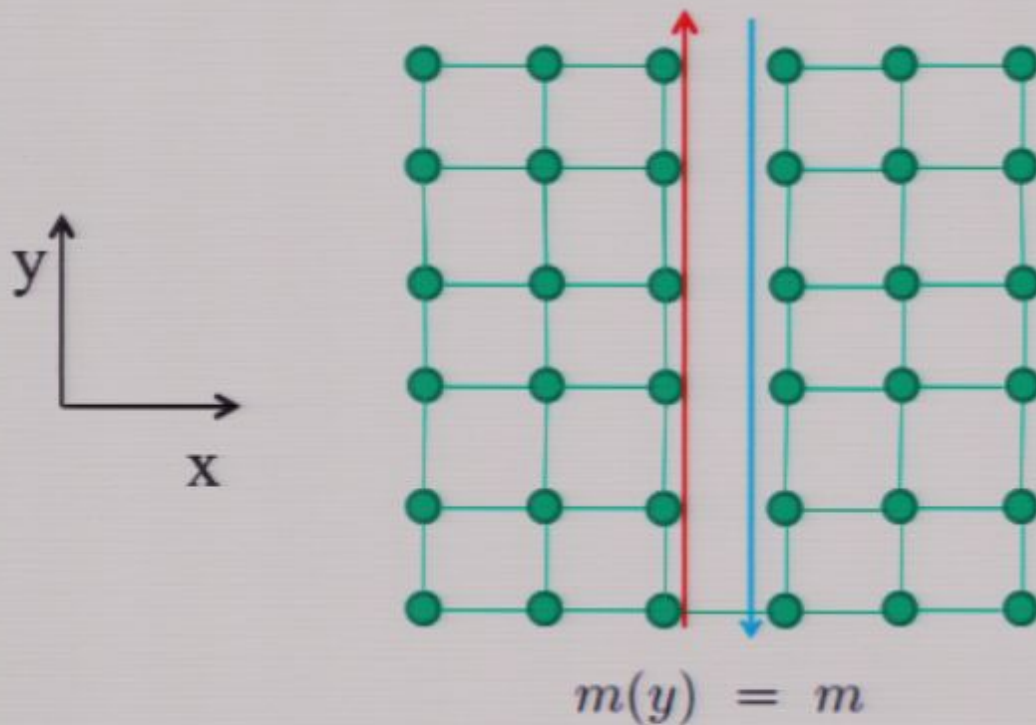


Gapless fermion spectrum on cut

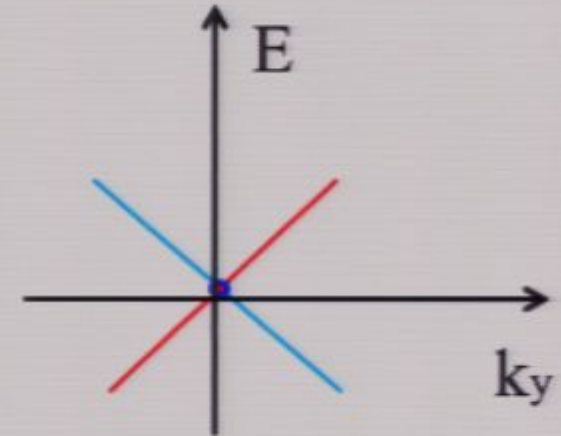


$$H = \begin{pmatrix} p_y & 0 \\ 0 & -p_y \end{pmatrix}$$

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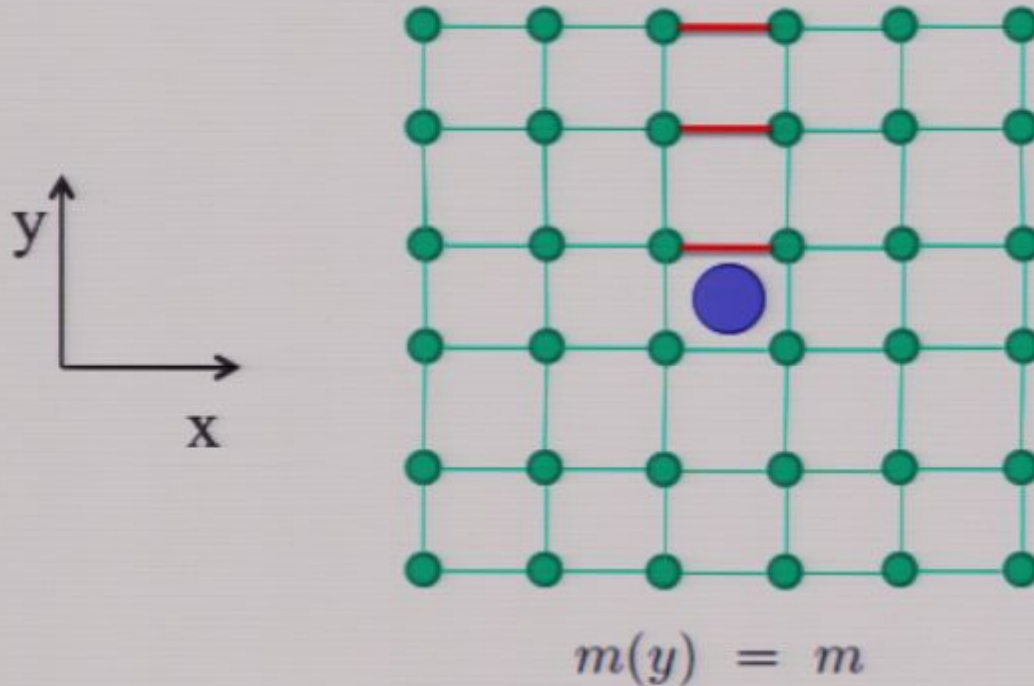


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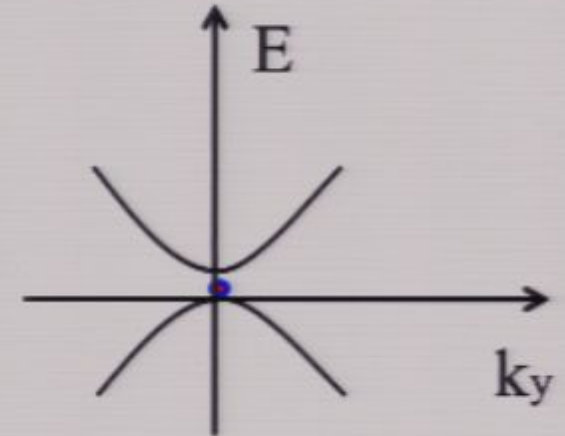


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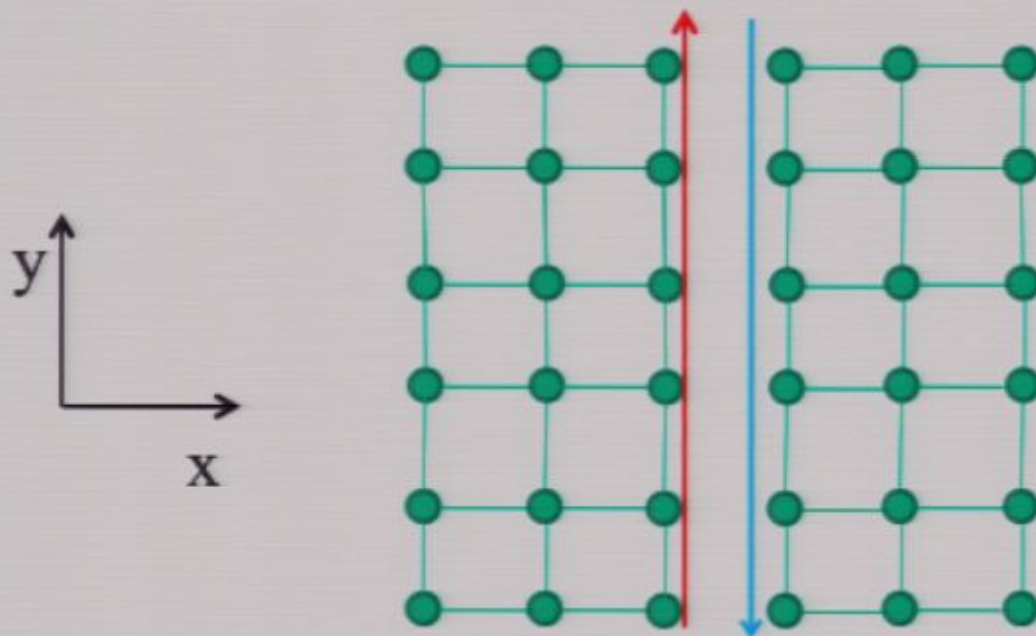


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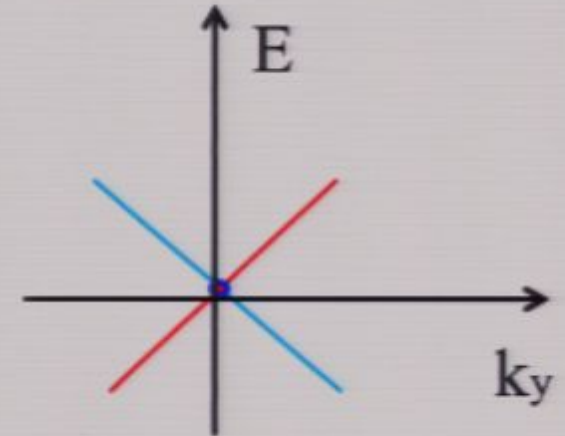


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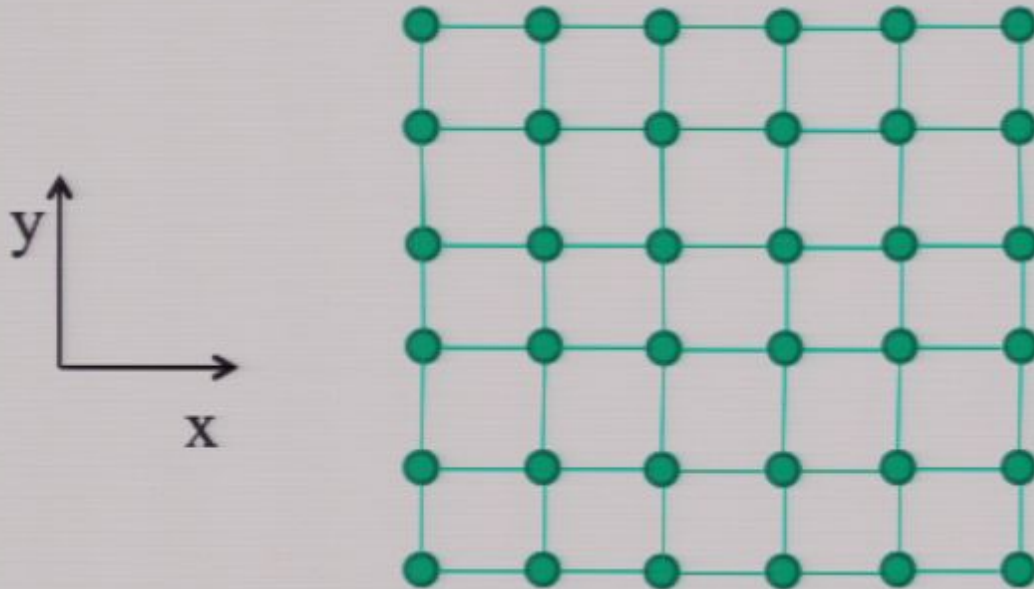


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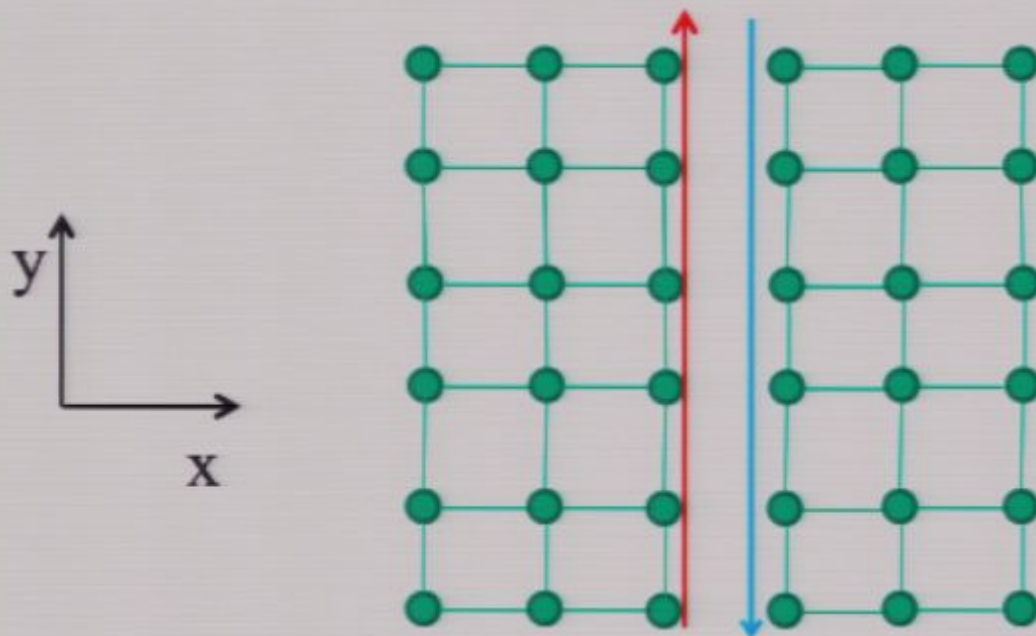
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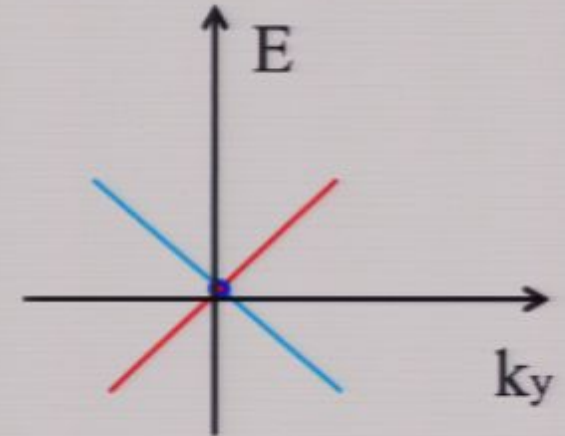




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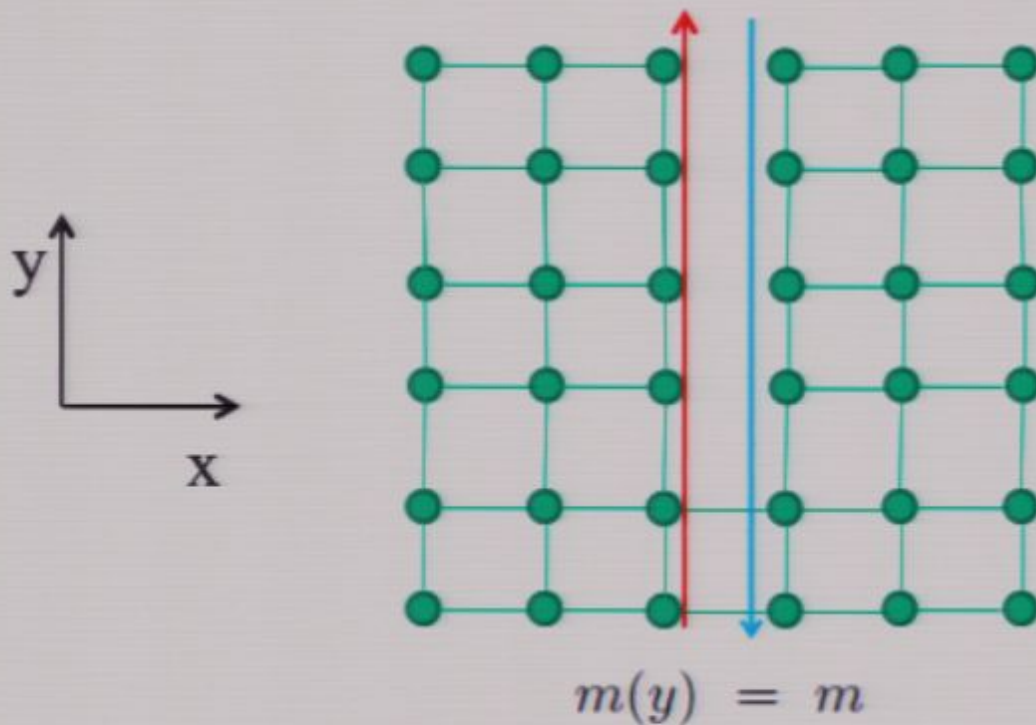


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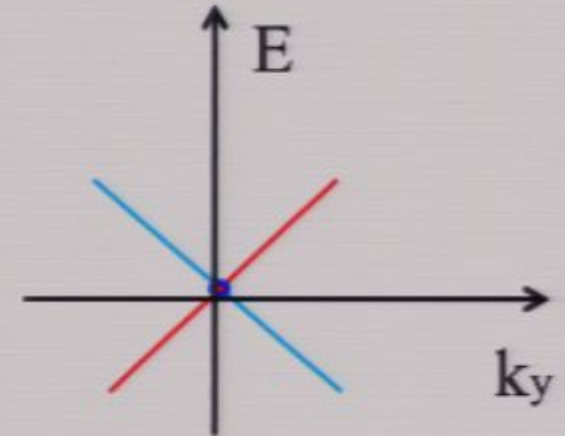


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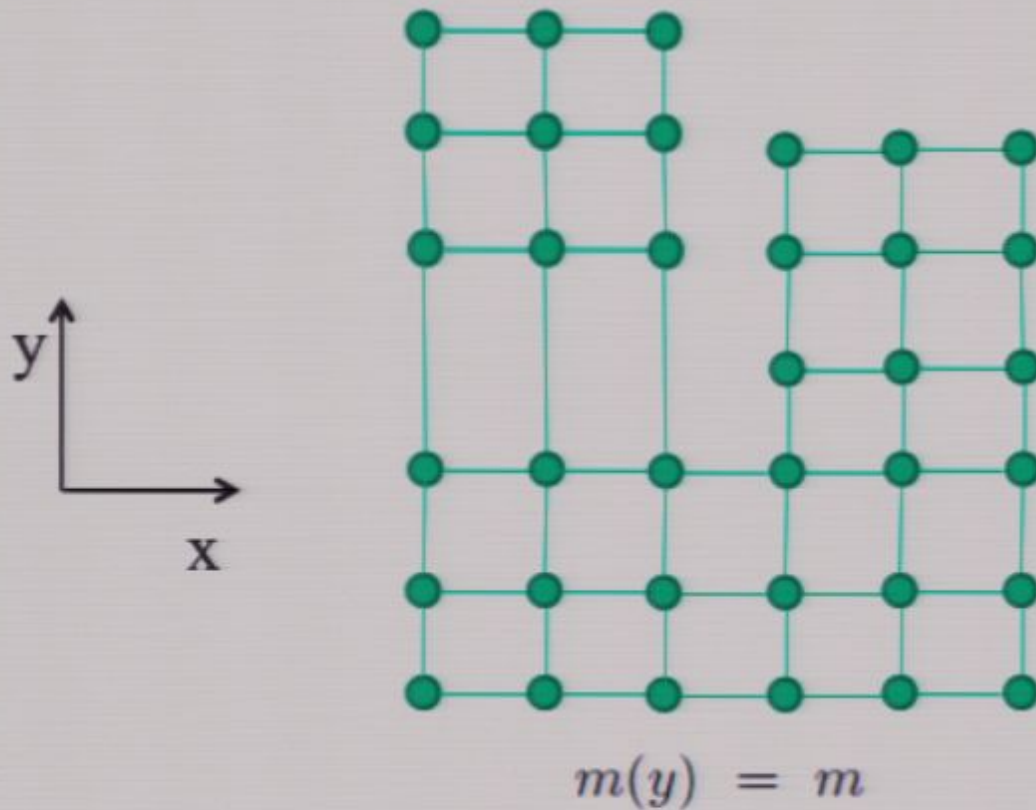


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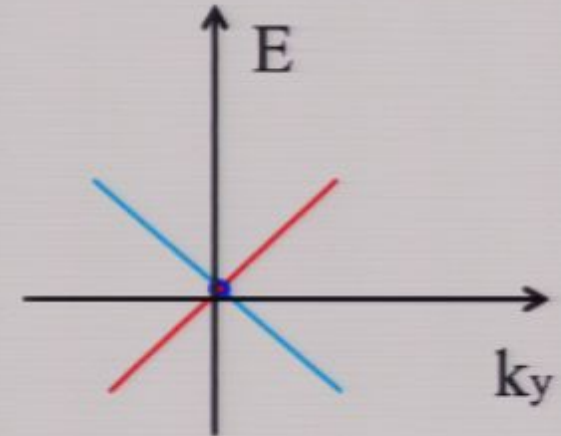


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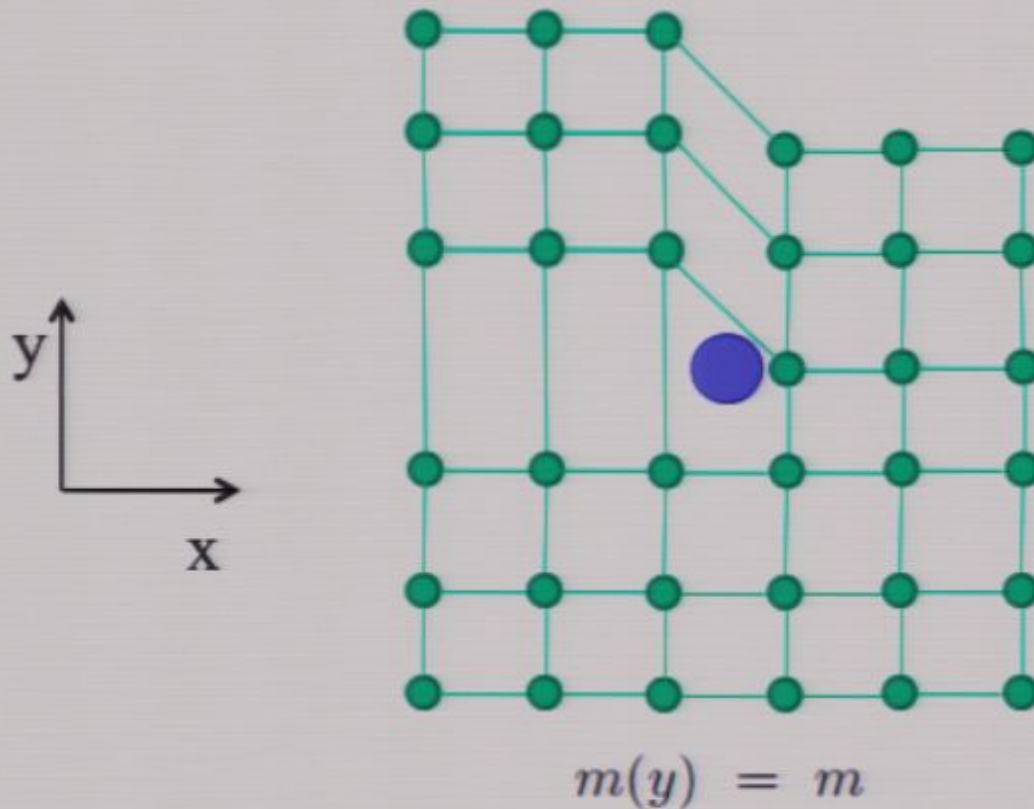
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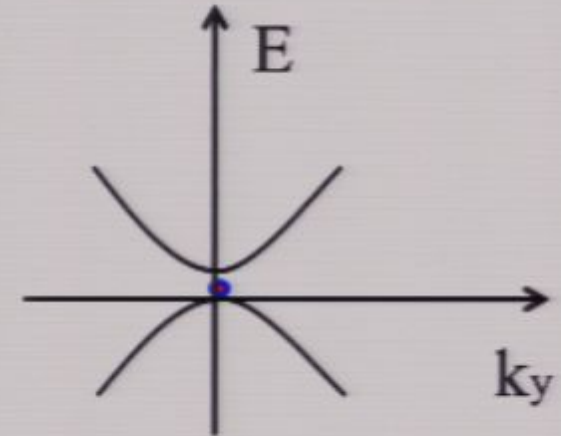
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# Bound States on Dislocations

$$m(y) = me^{ib \cdot K}$$



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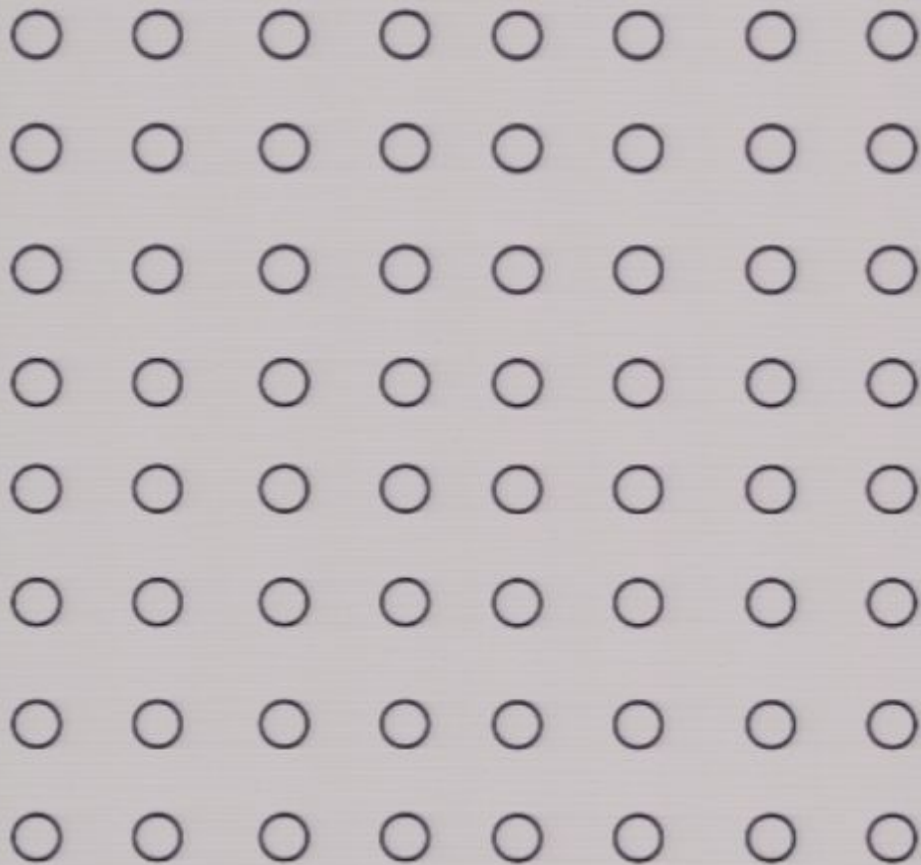


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# **Part 2: Topological Viscosity**



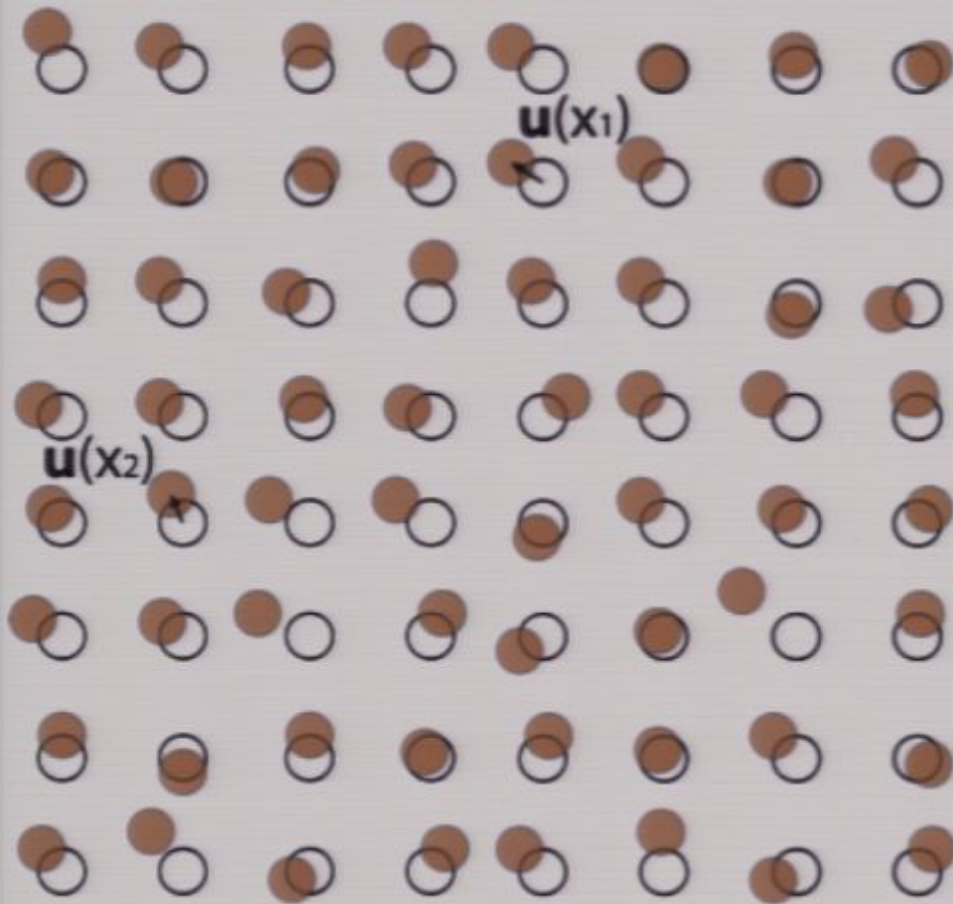
# Elasticity and Viscosity



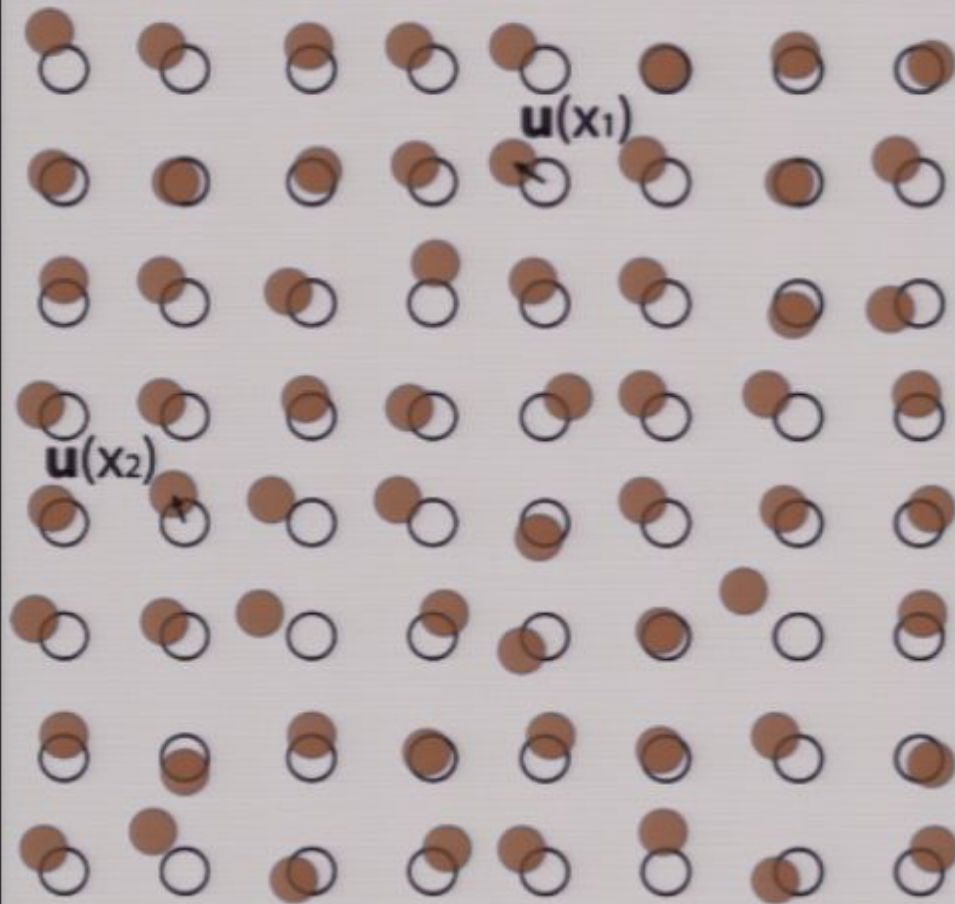
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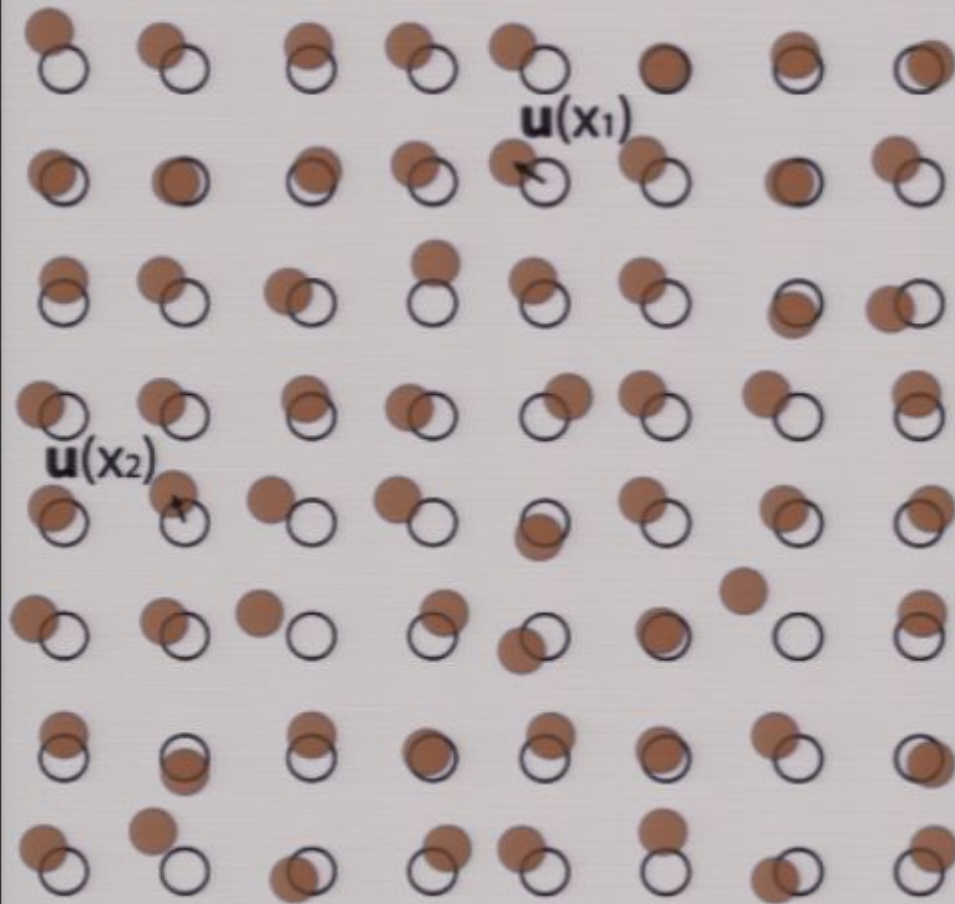
We begin with an elastic medium in a reference state, and look at perturbations around the reference state.

$$T^{ij} = \Lambda^{ijk\ell} u_{k\ell} + \eta^{ijk\ell} \dot{u}_{k\ell}$$

$$u_{k\ell} = \frac{1}{2} \left( \frac{\partial u^k}{\partial x^\ell} + \frac{\partial u^\ell}{\partial x^k} \right)$$



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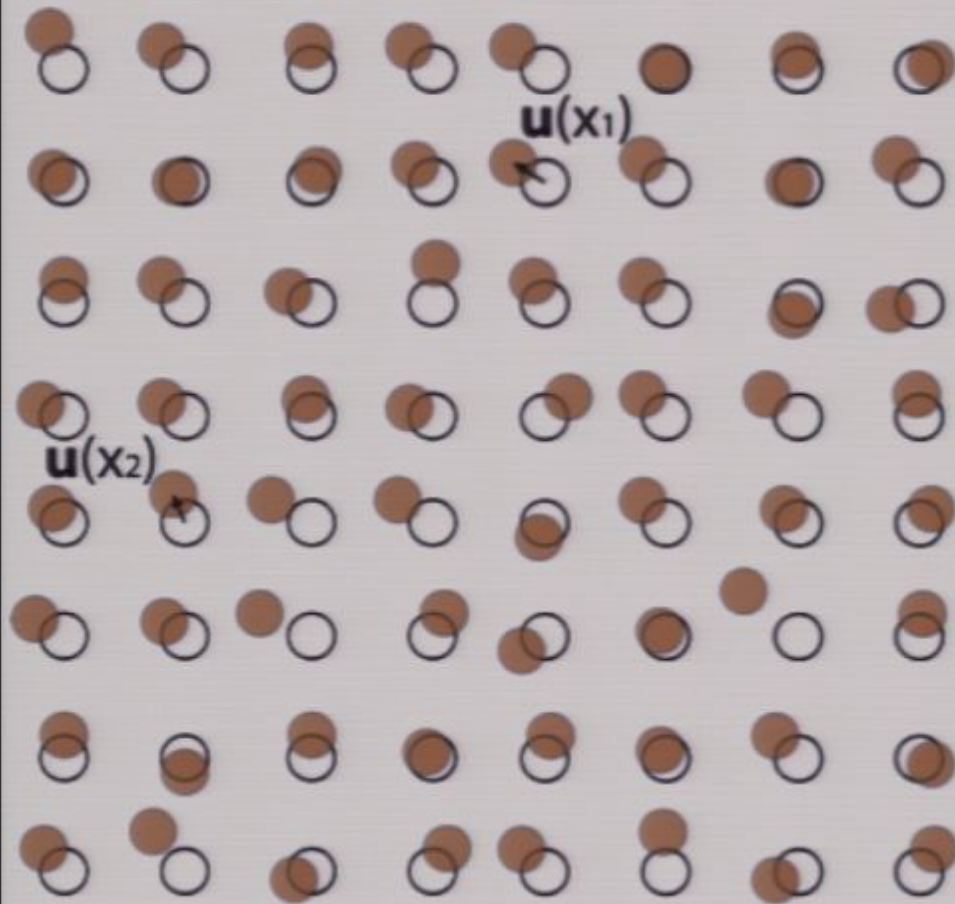
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Viscosity

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$$e_{\mu}^a = \delta_{\mu}^a + w_{\mu}^a$$

$$w_{\mu}^a = \frac{\partial u^a}{\partial x^{\mu}}$$



# Elasticity and Viscosity

Formulate in terms of an effective action:

$$S_{eff}[u_{ij}] = \frac{1}{2} \int d^3x (u_{ij} \Lambda^{ijkl} u_{kl} + u_{ij} \eta^{ijkl} \dot{u}_{kl})$$

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Isotropic Viscosities:

Shear:  $\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}$

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This symmetry implies that the viscosity term cannot be derived  
From an action (*i.e.* the term vanishes identically)

This makes sense since the viscosity is dissipative.

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In 2d there is one more isotropic term we can write:

$$\eta^{ijkl} = \eta_3 (\epsilon^{ik} \delta^{jl} + \epsilon^{il} \delta^{jk} + \epsilon^{jk} \delta^{il} + \epsilon^{jl} \delta^{ik})$$

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This is anti-symmetric under  
(ij)  $\rightarrow$  (kl)

This is a non-dissipative viscosity called the QH viscosity or odd viscosity.  
To be non-zero, time-reversal symmetry must be broken.



# Topological Viscosity

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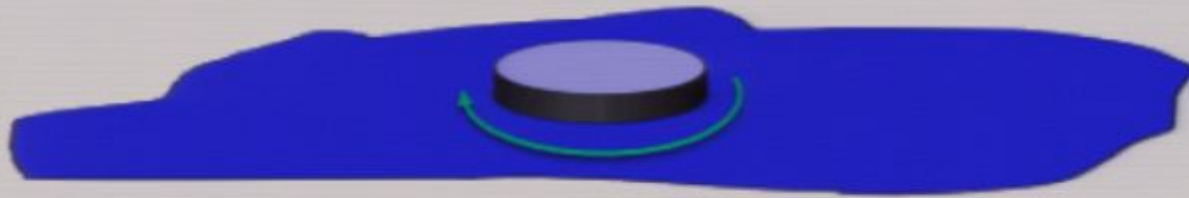
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The viscosity is known to be non-zero in quantum Hall fluids. We want to also consider massive Dirac fermions in 2+1-d which exhibit a QHE.

# Non-Dissipative Viscosity

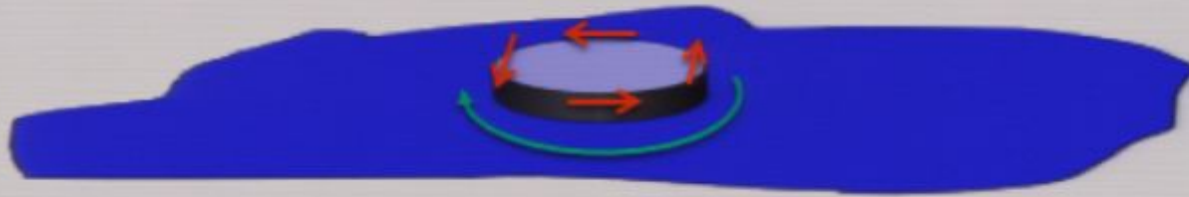


# Non-Dissipative Viscosity



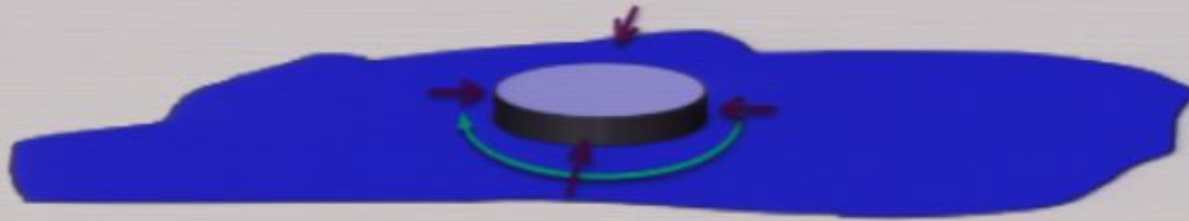


# Non-Dissipative Viscosity



**Shear viscosity:** Force tangent to motion

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**Non-dissipative viscosity:** Force perpendicular to motion

## Calculating Viscosity

We will be considering massive fermions coupled to external gravitational fields so we can just integrate out the fermions:

$$S = \int d^3x \det(e) \bar{\psi} (iD_\mu e^\mu_a \gamma^a - m) \psi$$

$$D_\mu = \partial_\mu - i\omega_{\mu ab} \Sigma^{ab}$$

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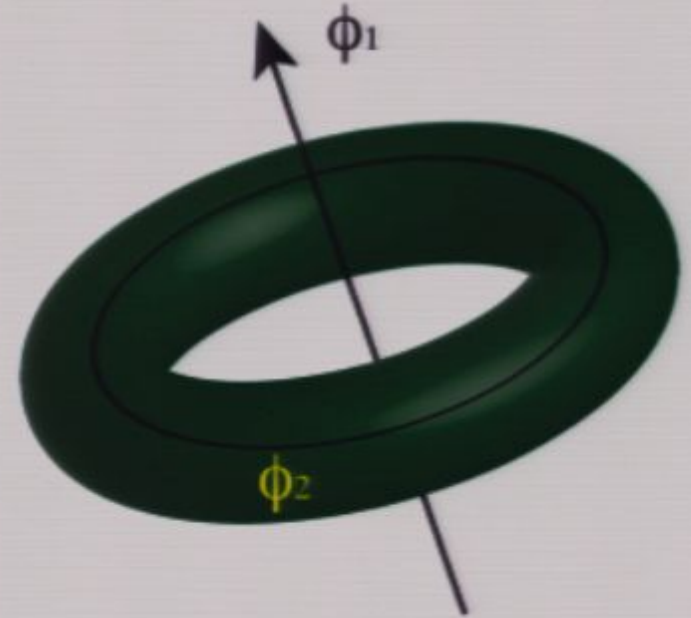
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$$T^a = de^a + \omega_b^a \wedge e^b$$

# Calculating Viscosity via Adiabatic Transport

For gapped systems you can calculate conductivities and other transport coefficients by looking at the behavior of the ground state under adiabatic deformations.

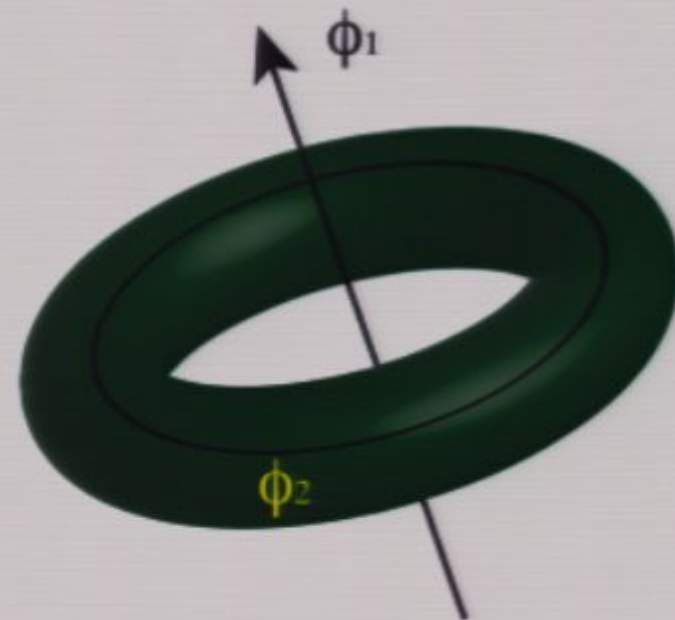
(Hall) Conductivity is the response to E-M flux insertion  
Or twisting of boundary conditions (due to Faraday effect)



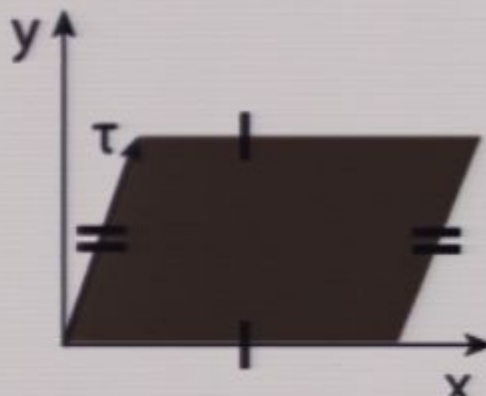
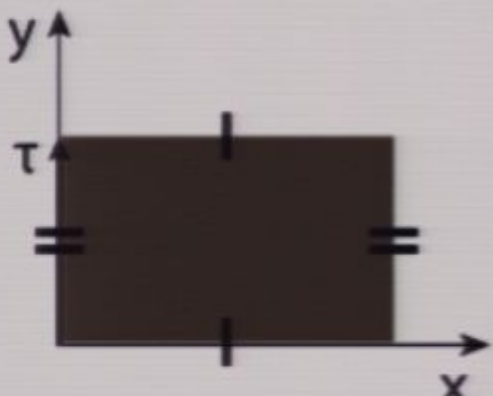
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For the viscosity we calculate the response to deformations of the modular parameter of the torus



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- We will only look at the torsion term and to simplify the description we focus on a flat background where we pick a gauge where the spin-connection vanishes:

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$$\eta_3 = \frac{\hbar}{4\pi} \left( \frac{|m|c}{\hbar} \right)^2 \text{sgn}(m) \equiv \frac{\hbar}{4\pi\ell^2}$$

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We can calculate the stress-energy tensor and find:

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The torsion magnetic field is simply tied to the dislocation density

## Magnetic Torsion Response

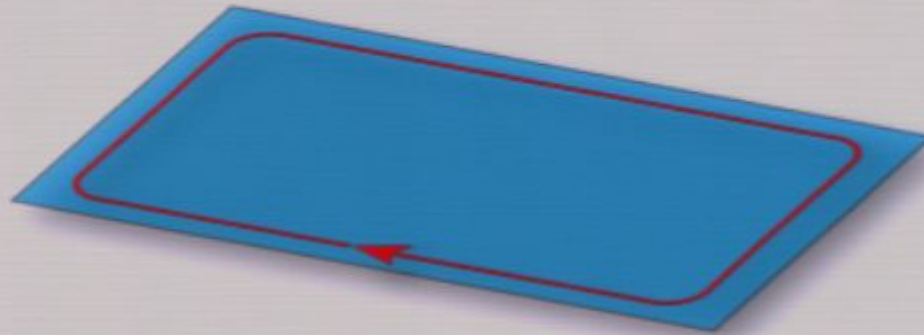
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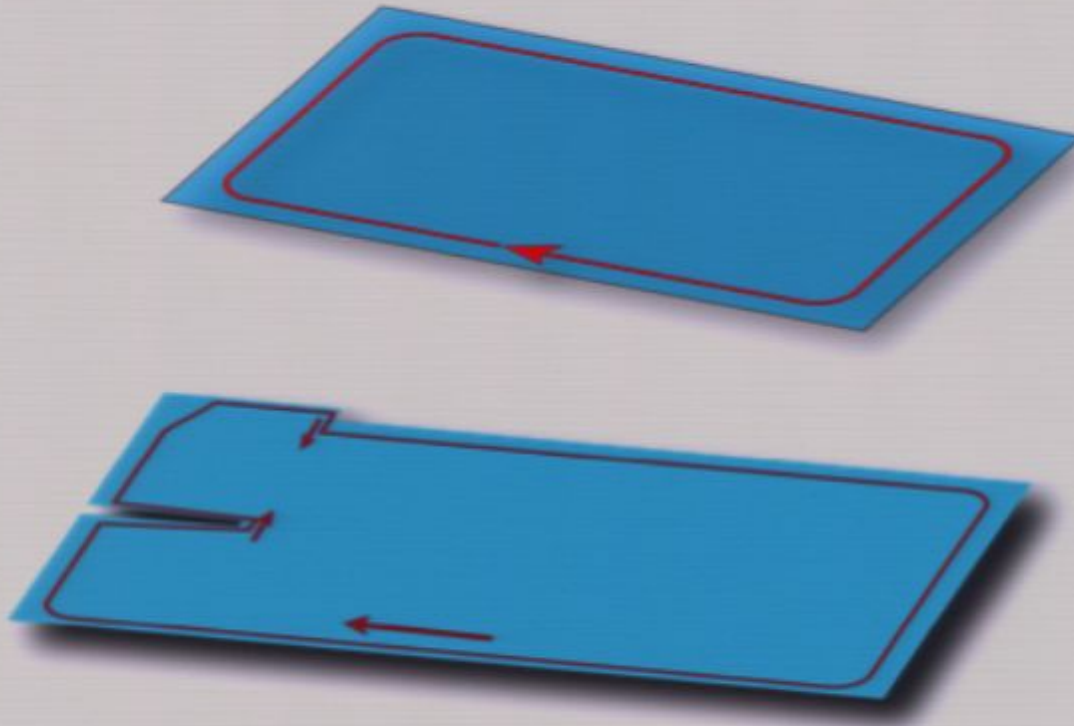




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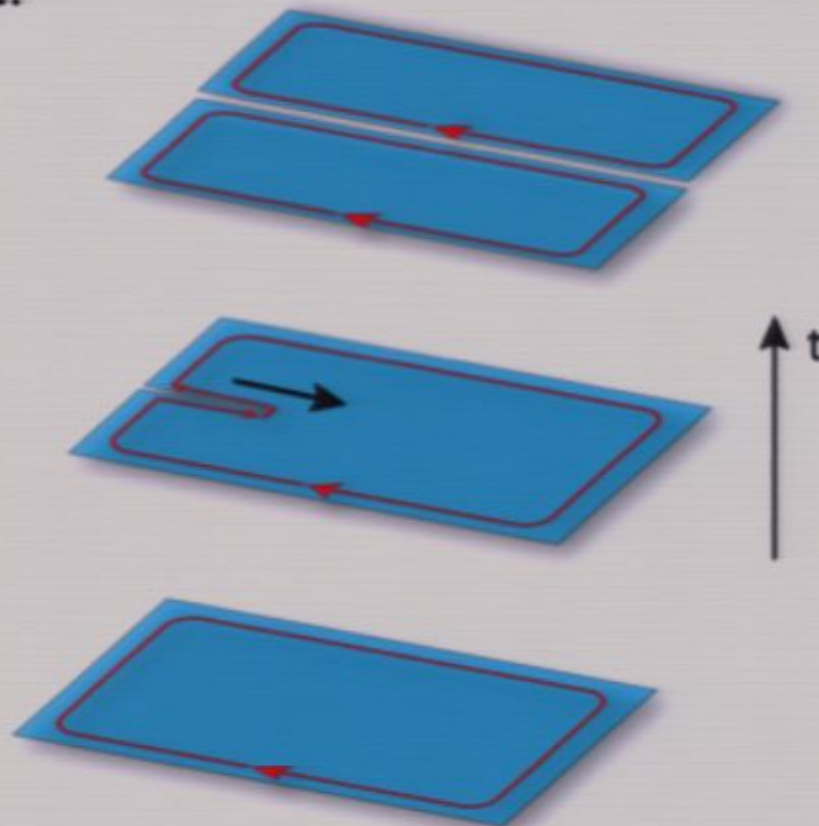
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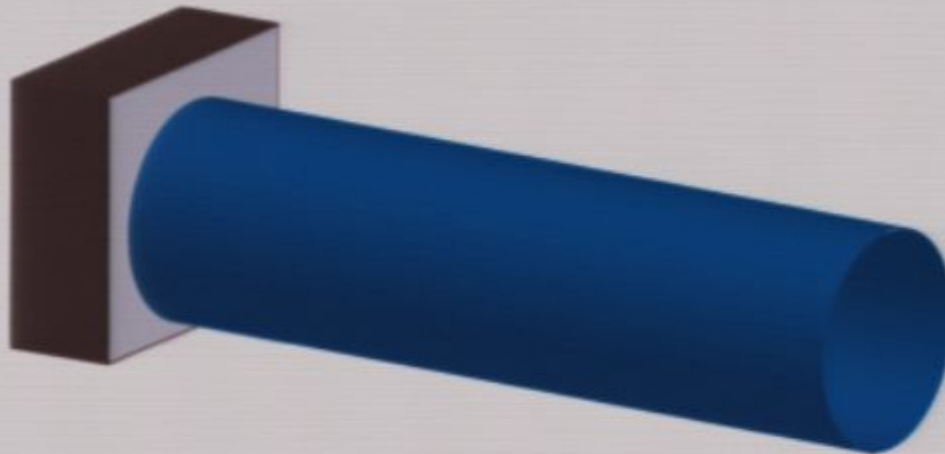
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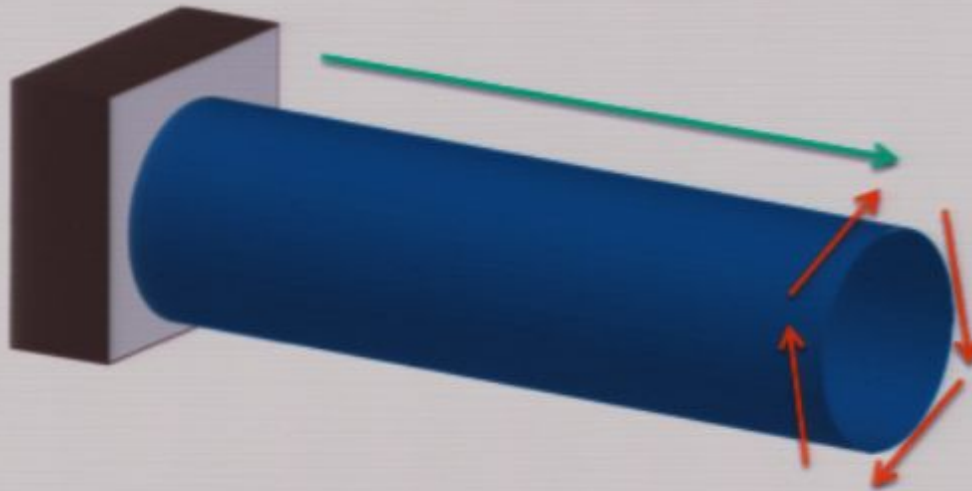
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- In 3+1-d we have the Nieh-Yan term which simply implies there is a quantum Hall viscosity on an axion domain wall.

$$S_{eff}^{(4d)}[e^a, \omega_b^a] = \sigma_4 \int R^{ab} \wedge R_{ab} + \eta_4 \int \theta [T^a \wedge T_a - R_{ab} \wedge e^a \wedge e^b]$$

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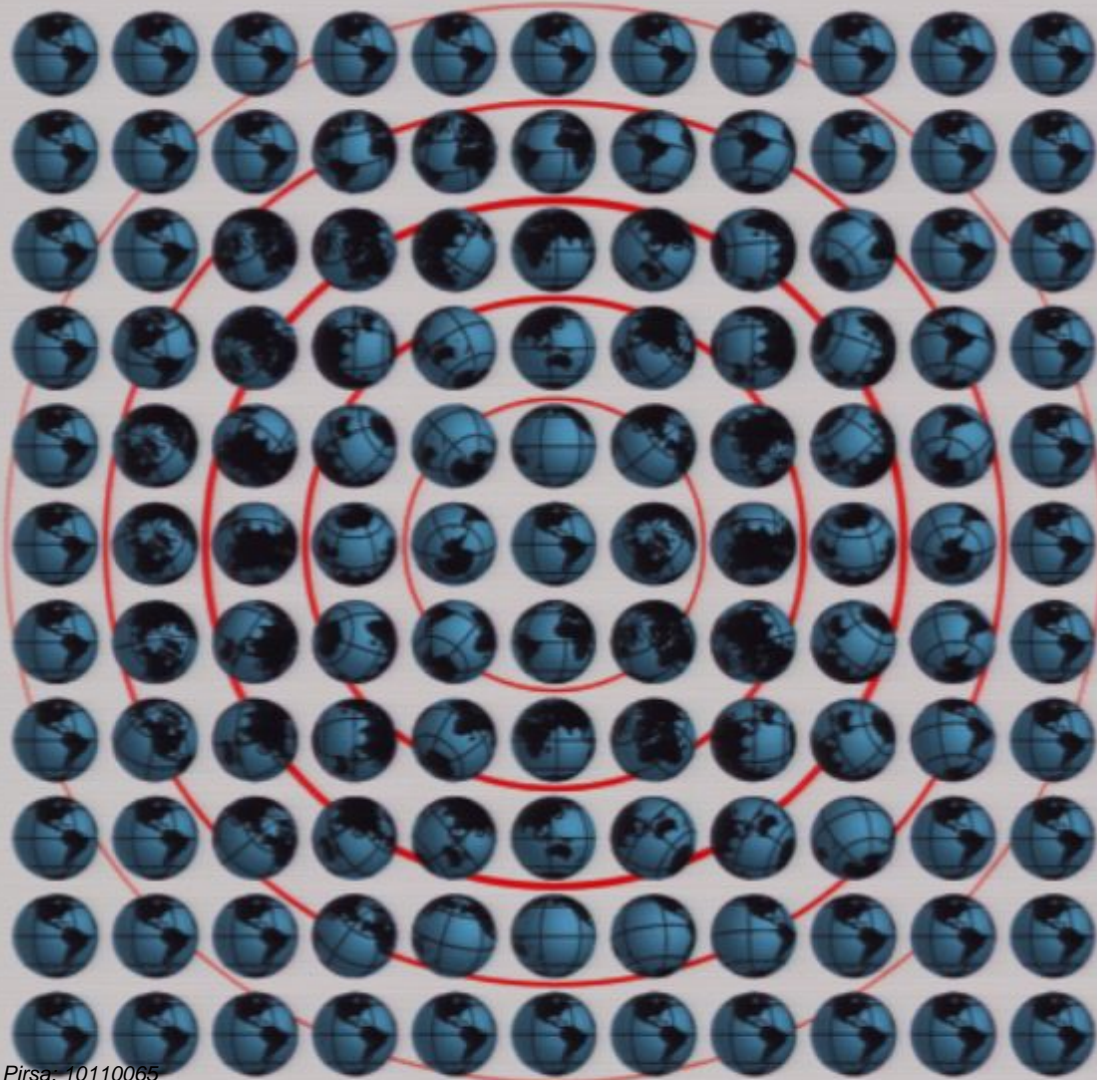
Again the coefficient of the torsion piece has units of  $1/[\text{Length}]^2$ .

So topological insulators in 3+1-d should exhibit a quantum Hall viscosity on the surface. It goes hand in hand with the QHE on the surface. 'Axion visco-elasticity.'

# **Part 3: Torsional Monopole**



# Heuristic Picture



We begin in 3+1-d flat space in the first order formalism:

$$e^a, \omega_b^a$$

To simplify the description we pick a gauge where

$$\omega_b^a \equiv 0$$



## Mathematical Description

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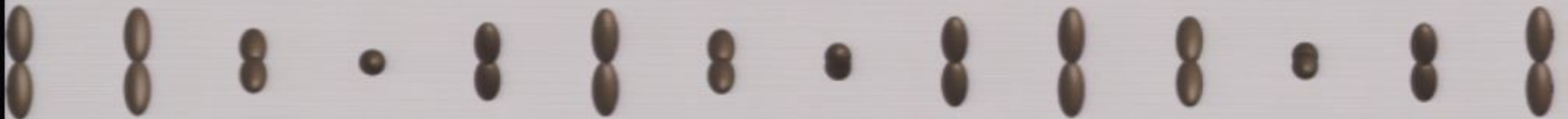
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## Torsion Monopoles in Solids

We can gauge transform our monopole solution so that the spin connection becomes the Levi-Civita connection and all of the torsion is contained in the tetrad. When this is done we do not have to deform the underlying lattice:



However, simple Schrodinger electrons won't even feel the defect:

$$H = \frac{e_a^i e_a^j p_i p_j}{2m} = \frac{g^{ij} p_i p_j}{2m}$$

## Torsion Monopoles in Solids

The place to look for the effects of such defects is in materials which have strong spin-orbit coupling. This means that you want the motion/momentum coupled to spin degrees of freedom:

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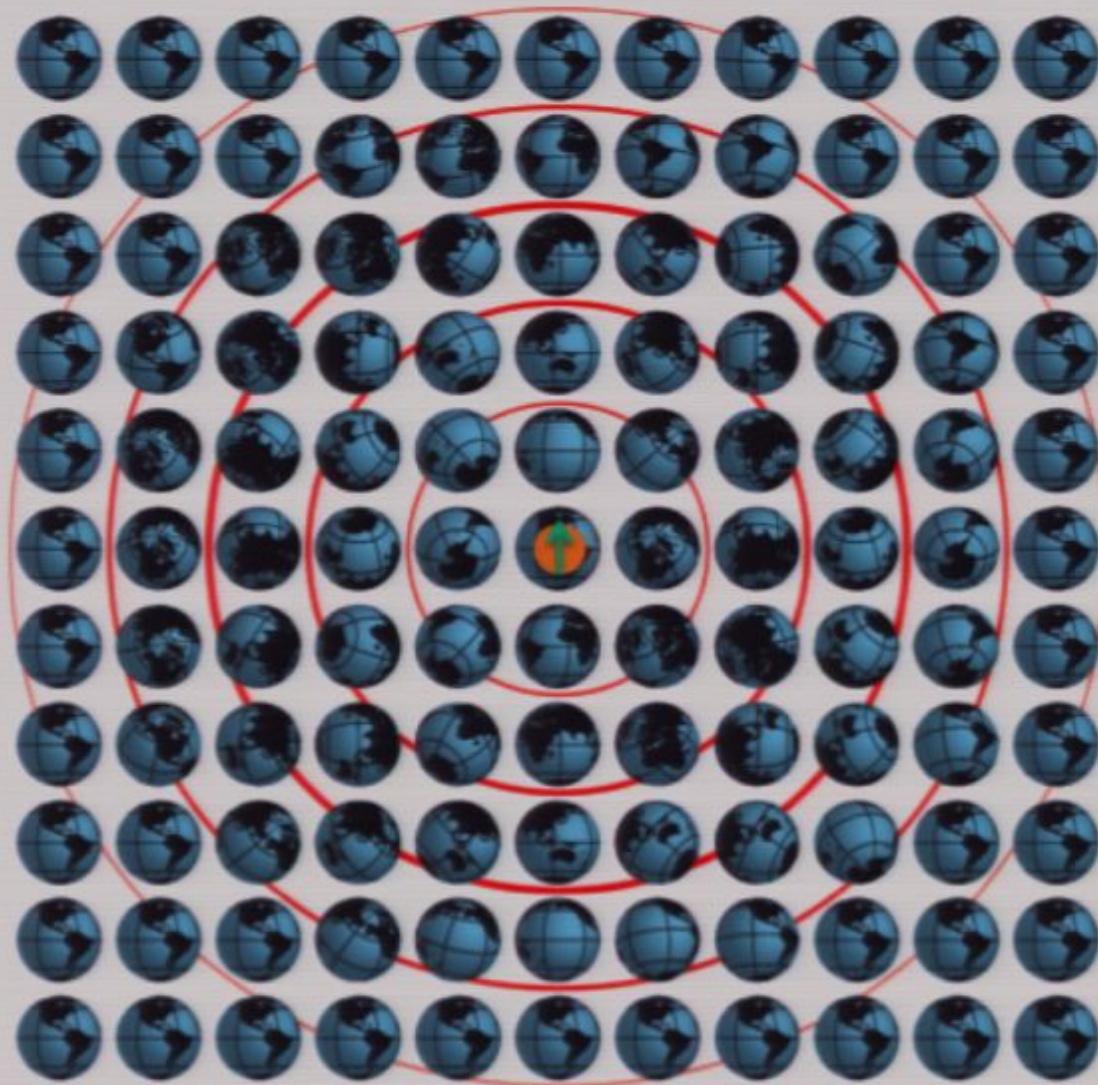
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Luttinger model for common semi-conductors (spin 3/2)



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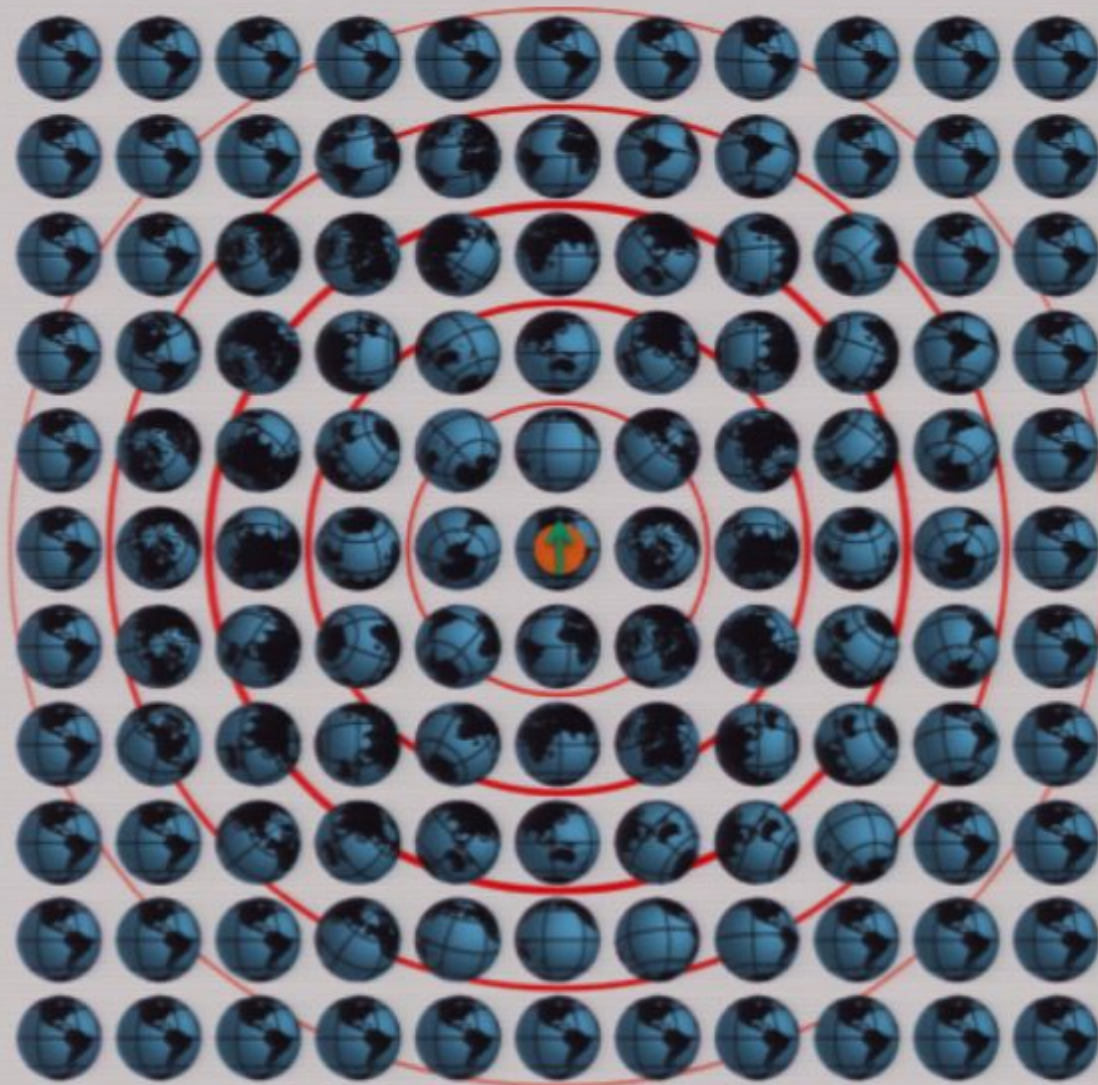
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