

Title: Quantum Gravity - Review (PHYS 638) - Lecture 8

Date: Feb 03, 2010 10:00 AM

URL: <http://pirsa.org/10020062>

Abstract:

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$$\{f, g\} = \omega(X_f, X_g) = X_f(g)$$

Hamiltonian VFs

$N = p \cdot q \Rightarrow$

Pick  $p, q$  to be relatively

Euclid's algorithm

$$\{f, g\} = \omega(X_f, X_g) = X_f(g) = -X_g(f)$$

↑ ↑  
Hamiltonian VFs



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ex.  $X_{q_i} = \frac{\partial}{\partial p_i}$ ,  $X_{p_i} = -\frac{\partial}{\partial q_i}$

$$\{f, g\} = \omega(X_f, X_g) = X_f(g) = -X_g(f)$$

↑ ↑  
Hamiltonian VFs

$N = 2n \Rightarrow$

$$\left[ \text{ex. } X_{q_i} = \frac{\partial}{\partial p_i}, \quad X_{p_i} = -\frac{\partial}{\partial q_i} \right]$$

Constrained Hamiltonian systems

A  $n$ -dim. Lagrangian system is called singular if  $\det W_{ij} = 0$

$$W_{ij} = \frac{\partial^2 L}{\partial \dot{q}_i \partial \dot{q}_j}$$



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$$y_{(a)}^i W_{ij} = 0 \quad i, a = 1, \dots, m \Rightarrow \text{Legendre transform } (q_i, \dot{q}_i) \mapsto (q_i, p_i)$$

is singular since  $|W_{ij}| = \left| \frac{\partial^2 L}{\partial \dot{q}_i \partial \dot{q}_j} \right| = \left| \frac{\partial p_i}{\partial \dot{q}_i} \right|$

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⇒ can't solve  $\forall \dot{q}_i = \dot{q}_i(q, p)$

⇒ not all momenta are independent, but we have  
m relations  $\phi_\alpha(q, p) = 0$ ,  $\alpha = 1, \dots, m$ ,

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m relations  $\phi_\alpha(q, p) = 0$ ,  $\alpha = 1, \dots, m$ ,  
so-called "constraints"

ex.  $L = \frac{1}{2} \dot{q}_1^2 + c \dot{q}_2 q_1 - \frac{m}{2} (q_1^2 + q_2^2 + q_3^2)$  ( $n=3$ )

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$p_1 = \frac{\partial L}{\partial \dot{q}_1} = \dot{q}_1$ ,  $p_2 = \frac{\partial L}{\partial \dot{q}_2} = c q_1$ ,  $p_3 = 0$ ,  $w_{ij}$

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$$\phi_1(q, p) = p_2 - c q_1 = 0, \quad \phi_2(q, p) = p_3 = 0$$

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$$\phi_1(q, p) = \boxed{p_2 - c q_1 = 0}, \quad \phi_2(q, p) = \boxed{p_3 = 0}$$

$\Rightarrow \mathcal{F}_c$  is 4-dimensional.



A Hamiltonian system with  $m$  constraints  $\phi_a(q,p) = 0$  is called

"first class" if  $(*) \quad \{\phi_a, \phi_b\} = f_{ab}^c \phi_c$

$(**) \quad \{\phi_a, H\} = d_a^b \phi_b$

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[notation " $\approx$ " means "equality on  $\mathcal{P}_c$ "]

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$$(*) \quad \{\phi_a, \phi_b\} = f_{ab}^c \phi_c \quad \Leftrightarrow \quad \{\phi_a, \phi_b\} \approx 0$$

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(dim 2)

$\rho$



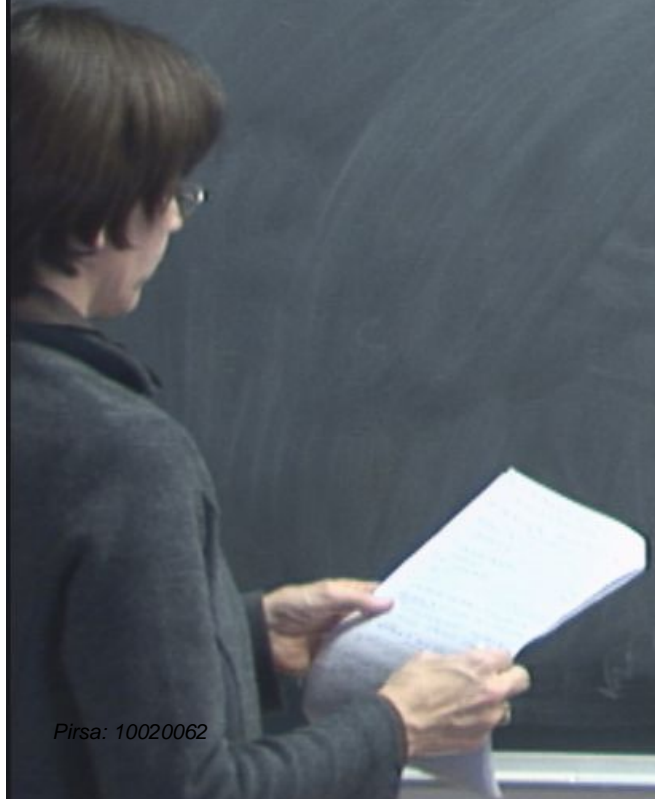
(dim  $2n$ )

$f$

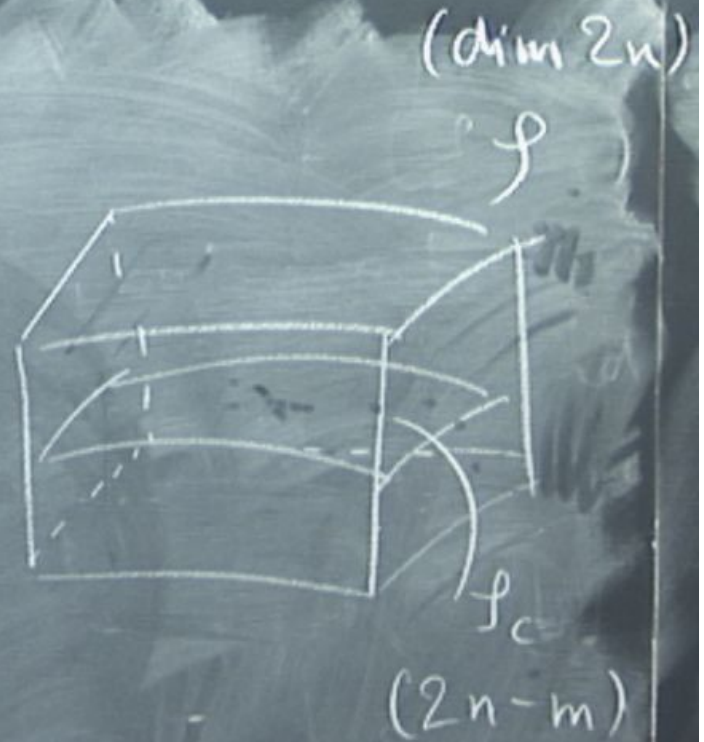


$f_c$

( $2n - m$ )



Hamiltonian is not unique



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$$H^* = H + c_m(q,p) \Phi_m(q,p)$$



(dim  $2n$ )

$\mathcal{P}$

$\mathcal{P}_c$

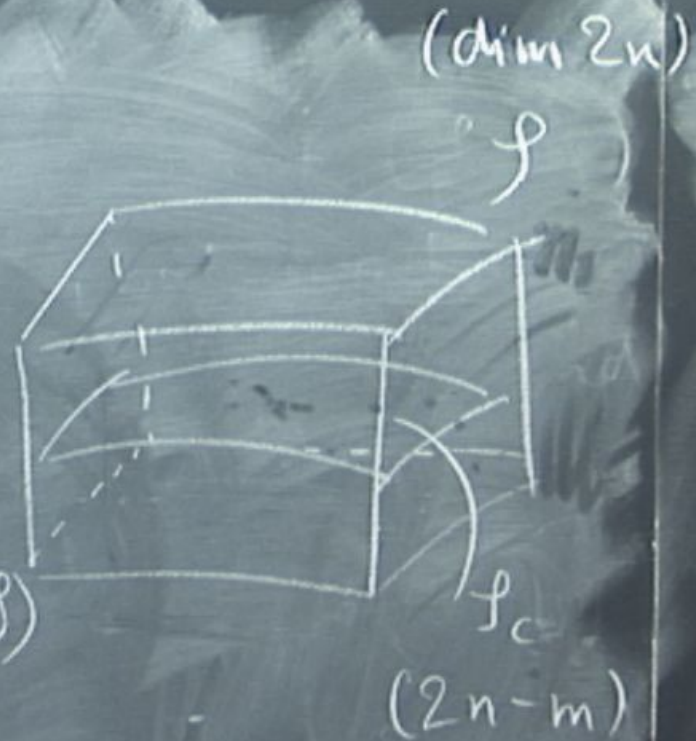
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the evolution of some  $g(q,p) \in C^\infty(\mathcal{Y})$

$$\{g, H^*\}$$



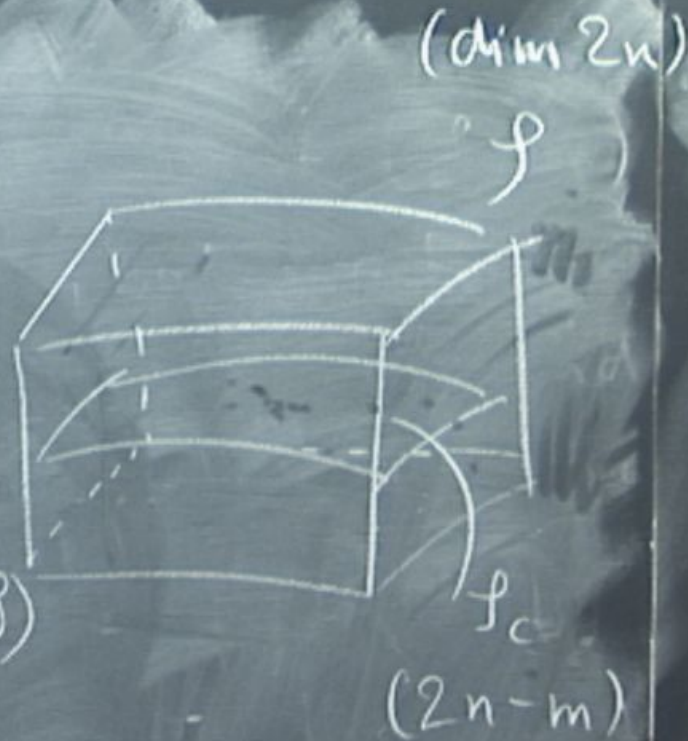


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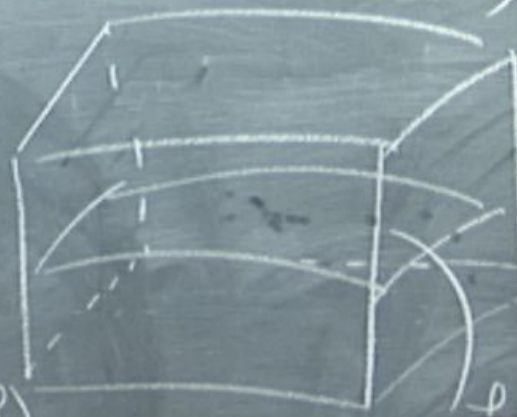


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(dim  $2n$ )

$\mathcal{Y}$

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$$\dot{g} = \{g, H^*\} = \{g, H\} + c_m \{g, \Phi_m\} + \Phi_m \{g, c_m\}$$

in particular

$$\dot{q}_i \approx \frac{\partial H}{\partial p_i} + c_m \frac{\partial \Phi_m}{\partial p_i} \approx 0$$

$$\dot{p}_i \approx -\frac{\partial H}{\partial q_i} - c_m \frac{\partial \Phi_m}{\partial q_i}$$

(dim  $2n$ )



( $2n - m$ )

e.l.o.m. contain in arbitrary phase space fns

consistency : constraint

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consistency: constraints are preserved under time evolution

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(i)  $X_H \phi_m \approx 0$  (flow of Hamiltonian stays on  $\mathcal{S}_c$ )

(ii)  $H$  is unchanged when moving in the direction of the  $X_{\phi}$

$X_\phi$ : ~ "gauge directions" ~~trajectories~~

ex  $\phi = p_3$

$X_\phi$ : ~ "gauge directions"  $\mathcal{P}$ , dim

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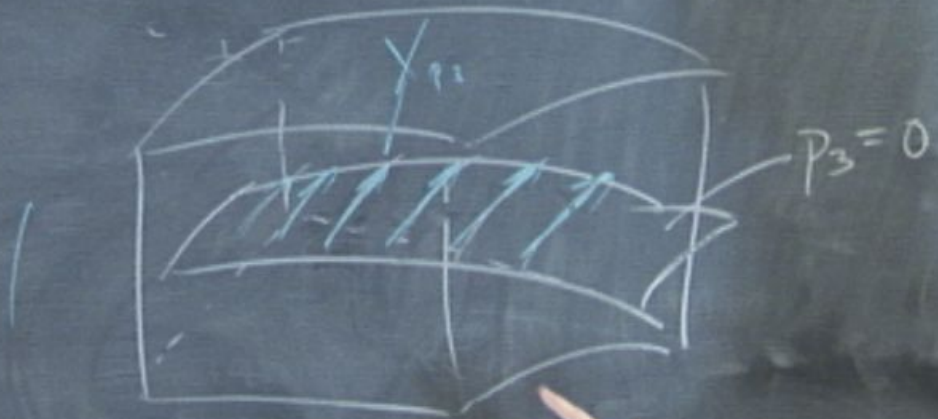


$X_\phi$ : ~ "gauge directions"

$\mathcal{F}$ ,  $\dim = 6$

ex  $\phi = p_3$

$$X_{p_3} = -\frac{2}{2q_3}$$



$X_\phi$ : ~ "gauge directions" / constraints

$\mathcal{F}$ , dim = 6

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$\mathbb{R}^4$