

Title: Dynamical Systems - Review (PHYS 607) - Lecture 7

Date: Jan 12, 2010 09:00 AM

URL: <http://pirsa.org/10010019>

Abstract:

RG transformation

$$[Tf](x) = -af\left(f\left(-x/a\right)\right)$$

RG transformation

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fixed pt fn g satisfies

$$Tg = g$$

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RG transformation

$$[Tf](x) = -a f(-x/a)$$

fixed pt fn g satisfies

$$Tg = g$$

α fixed in this solution

to get δ

$$\text{write } h(x) = g(x) + \epsilon \eta(x)$$

$$[Th](x) \approx$$

RG transformation

$$[Tf](x) = -\alpha f(g(-x/\alpha))$$

fixed pt fn g satisfies

$$Tg = g$$

α fixed in this solution

To get δ

write $h(x) = g(x) + \epsilon \eta(x)$

$$[Th](x) \approx g(x) - \alpha \epsilon \eta(g(-x/\alpha)) - \alpha \epsilon \frac{dg}{dx}$$

tion

$$g(g(-z/\alpha))$$

g satisfies

g

ϵ in this solution

$$x) = g(x) + \epsilon \eta(x)$$

$$x) \approx g(z) - \alpha \epsilon \eta(g(-z/\alpha)) - \alpha \epsilon \frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha)$$

RG transformation

$$[Tf](x) = -\alpha f\left(g\left(-\frac{x}{\alpha}\right)\right)$$

fixed pt fn g satisfies

$$Tg = g$$

α fixed in this solution

To get δ

$$\text{write } h(z) = g(z) + \epsilon \eta(z)$$

$$[Th](z) \approx g(z) - \alpha \epsilon \eta\left(g\left(-\frac{z}{\alpha}\right)\right)$$

$$T: \eta \rightarrow \eta' \quad T(g + \epsilon \eta) \approx g + \epsilon \mathcal{L}(\eta)$$

RG transformation

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$$\text{write } h(z) = g(z) + \epsilon \eta(z)$$

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$$T: \eta \rightarrow \eta' \quad T(g + \epsilon \eta) \approx g + \epsilon \mathcal{L}(\eta)$$

$$(g(-z/\alpha))$$

satisfies

in this solution

$$= g(z) + \epsilon \eta(z)$$

$$\approx g(z) - \alpha \epsilon \eta(g(-z/\alpha))$$

$$T(g + \epsilon \eta) \approx g + \epsilon \mathcal{L}(\eta)$$

$$\mathcal{L}(\eta) = -\alpha \left[\eta \right]$$

$$-\alpha \epsilon \frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha)$$

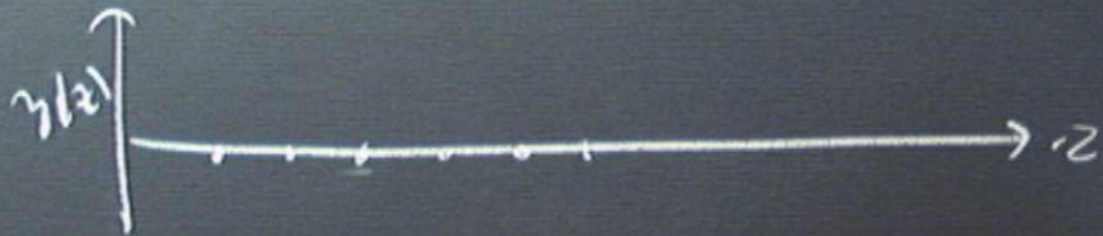
$$f(\eta) = -\alpha \left[\eta(g(-z/\alpha)) + \frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha) \right]$$

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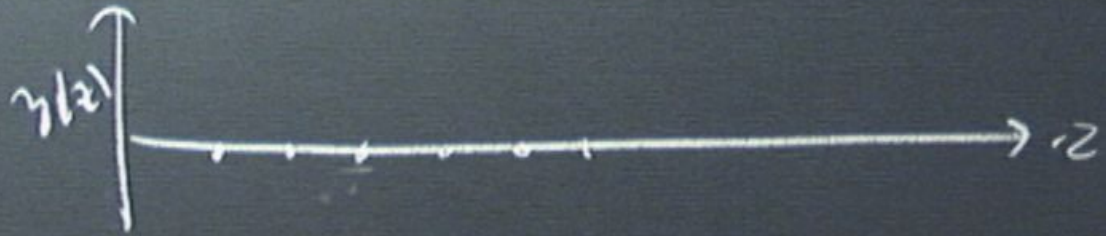
$$= \frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha)$$

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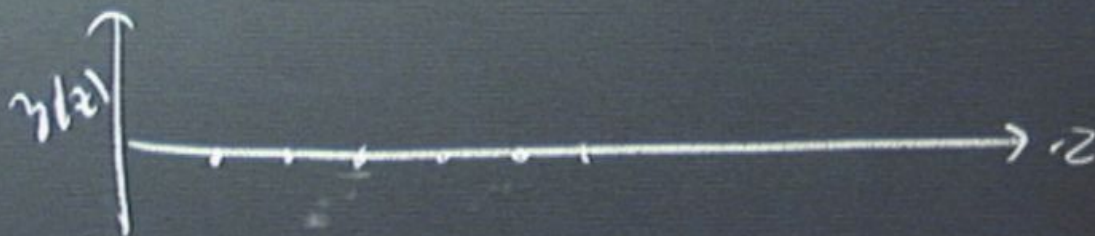
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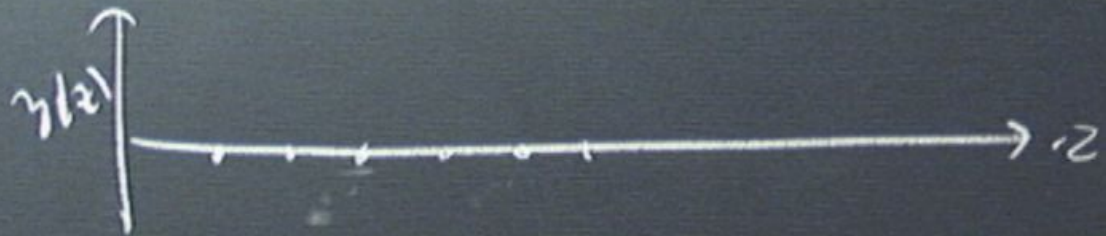


δ is the ^{only} eigenvalue

$$\mathcal{L}\eta_i = \lambda \eta_i$$

$$\in \frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha)$$

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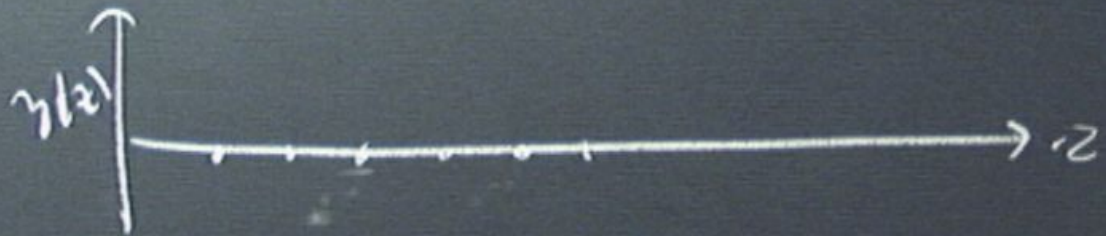


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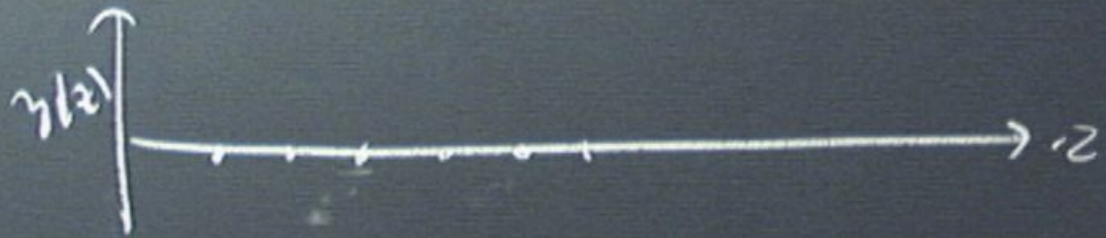


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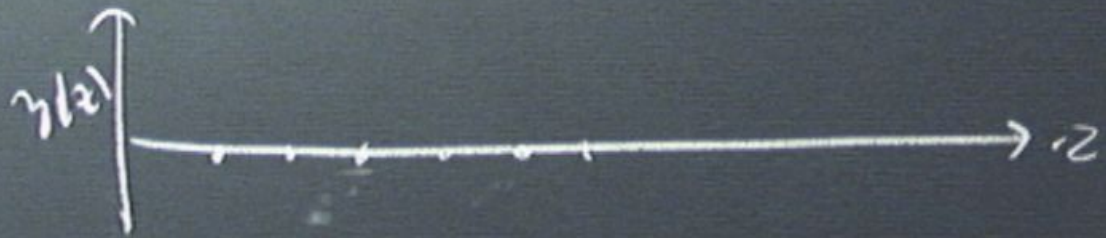


δ is the ^{only} eigenvalue > 1

$$\mathcal{L} \eta_i = \lambda \eta_i$$

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δ is the ^{only} eigenvalue > 1

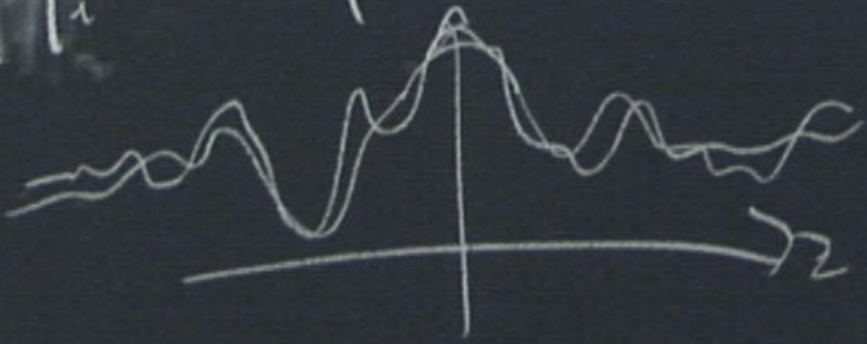
$$\mathcal{L}\eta_i = \lambda_i \eta_i$$

$$\frac{dg}{dx} \Big|_{g(-z/\alpha)} \eta(-z/\alpha)$$



only
is the eigenvalue > 1

$$L \eta_i = \lambda \eta_i$$



$$d/dx (g(-z))'$$

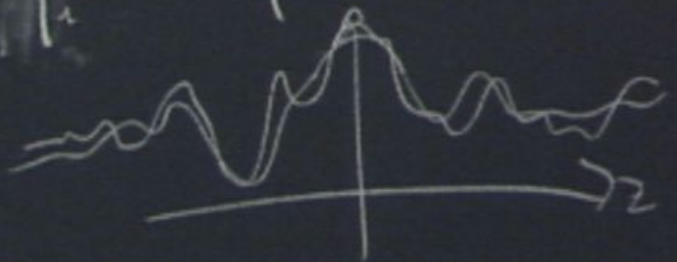
$$e^{\lambda}$$

$$\lambda$$

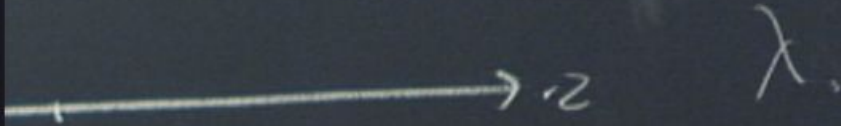
→ z

only
the eigenvalue > 1

$$L \eta_i = \lambda \eta_i$$

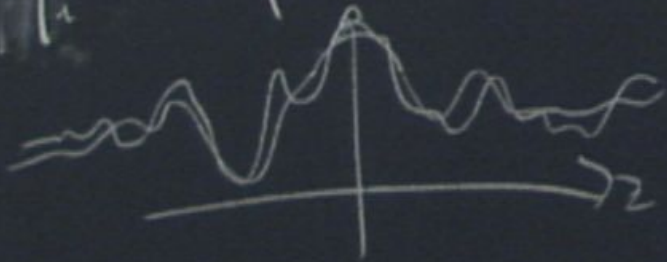


$$dX/g(-z)$$



only
the eigenvalue > 1

$$L\eta_i = \lambda_i \eta_i$$



Entropy

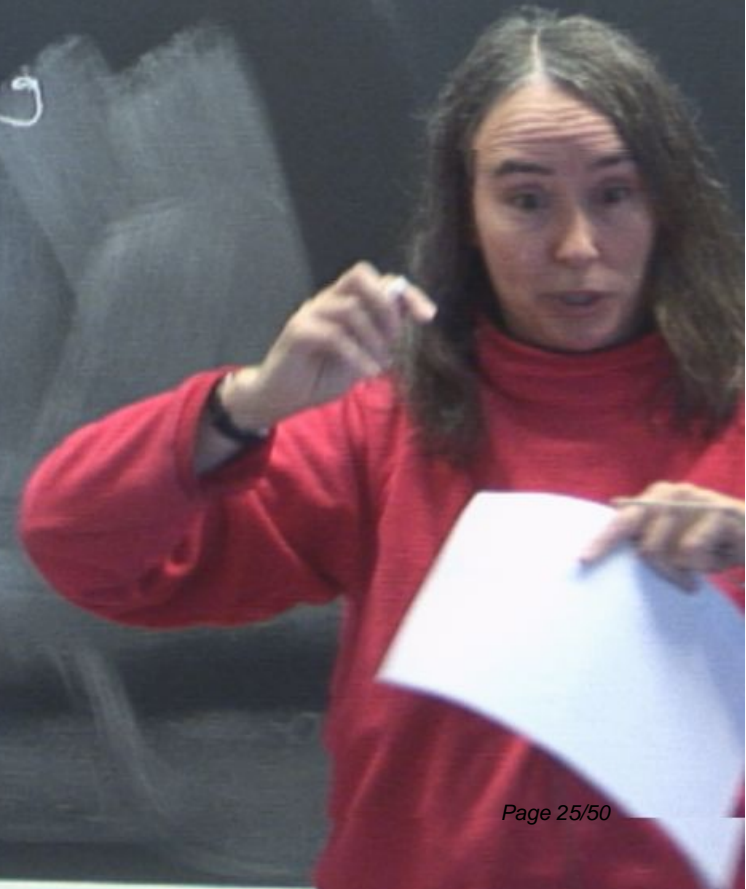
$$S = -k_B \sum_{\text{states } i} p_i \ln p_i$$

p_i = prob of being
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Shannon Entropy

How to quantify information?

n possible events with
probabilities p_1, \dots, p_n
[p_i known]



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probabilities p_1, \dots, p_n

[p_i known]

How much do we learn when
one event is chosen?

want to define a measure
 $S(p_1, \dots, p_n)$ of how much
choice is involved

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ii) S is continuous

events with

P_1, \dots, P_n

P_i known

do we learn when
it is chosen?

define a measure

(P_1, \dots, P_n) of how much
involved

ii) S is continuous in the P_i

events with
 $\{S, P_1, \dots, P_n\}$
 P_i known

do we learn when
it is chosen?

define a measure
 (P_1, \dots, P_n) of how much
is involved

1) S is continuous in the P_i

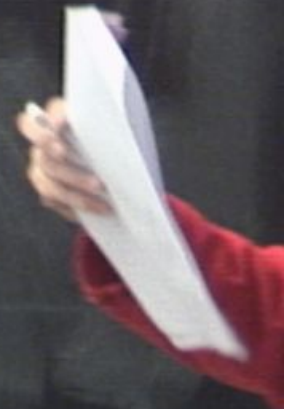
2) If the $P_i = 1/n$
then S is monotonically
increasing with n

events with \cup
 $S = \{A_1, \dots, A_n\}$
 p_i known

do we learn when
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define a measure
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- 1) S is continuous in the p_i
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- 3)



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- 1) S is continuous in the p_i
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- 3) If you break down a
choice into two steps,
you learn the same amount
as when you choose in
1 step

events with
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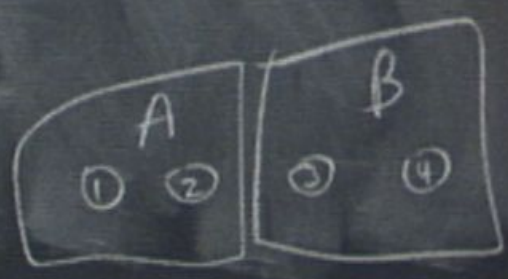
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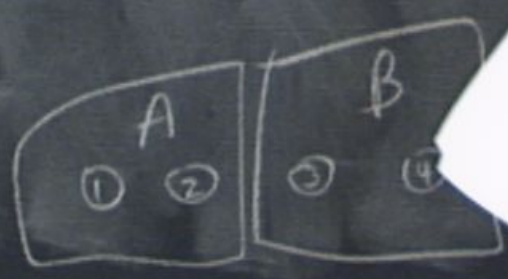


events with
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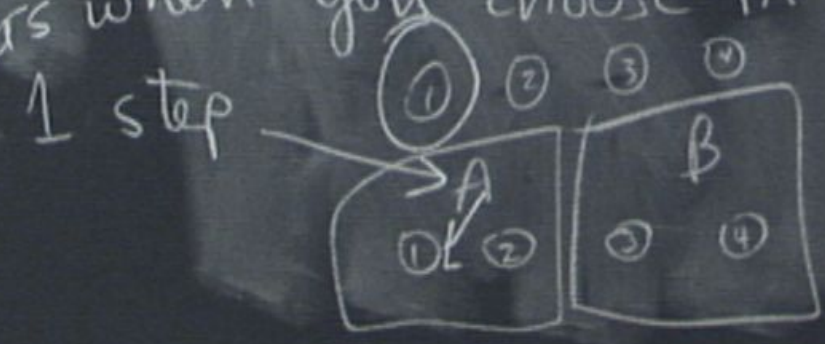


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Theorem:

The only S that satisfies (1), (2), (3)

is

$$S = -k_B \sum_{\text{States } i} p_i \ln p_i$$

n p
prob

How
one

Wa
S
ch

Theorem:

The only S that satisfies (1), (2), (3)

is

$$S = k \sum_{\text{states } i} g_i \ln g_i$$

with $k > 0$

n p
prob

How
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Theorem:

The only S that satisfies ①, ②, ③

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Theorem:

The only S that satisfies (1), (2), (3)

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$$S = k \sum_{\text{States } i} p_i \ln p_i$$

with $k > 0$

First consider the case
when the choices are all
equally likely [n choices]

$$S(1/n, 1/n, \dots, 1/n) = A(n)$$

will show

$$A(n) = K \ln n$$

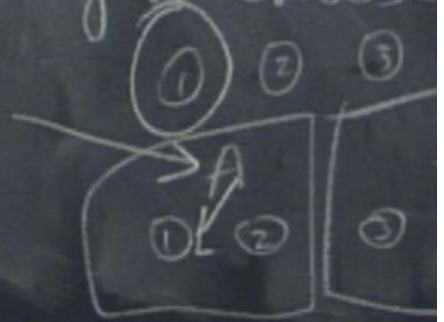
with $K > 0$

0 0 0 0

1) S is continuous in the

2) If the $p_i = 1/n$ then S is monotone increasing with

3) If you break down choice into two S you learn the same as when you choose 1 step



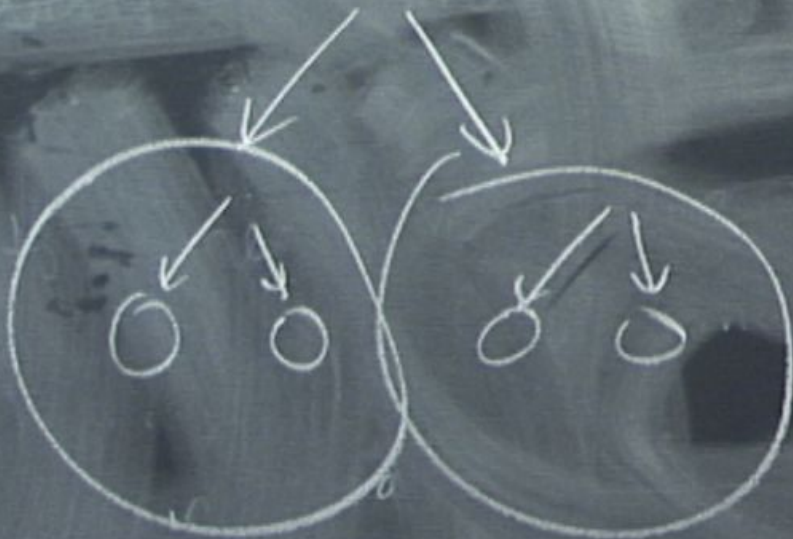
will show

$$A(n) = K \ln n$$

with $K > 0$

LP

0 0 0 0



1) S is continuous in the

2) If the $p_i = 1/n$ then S is monotone increasing with

3) If you have some choice in S you learn as when $\uparrow S$

will show

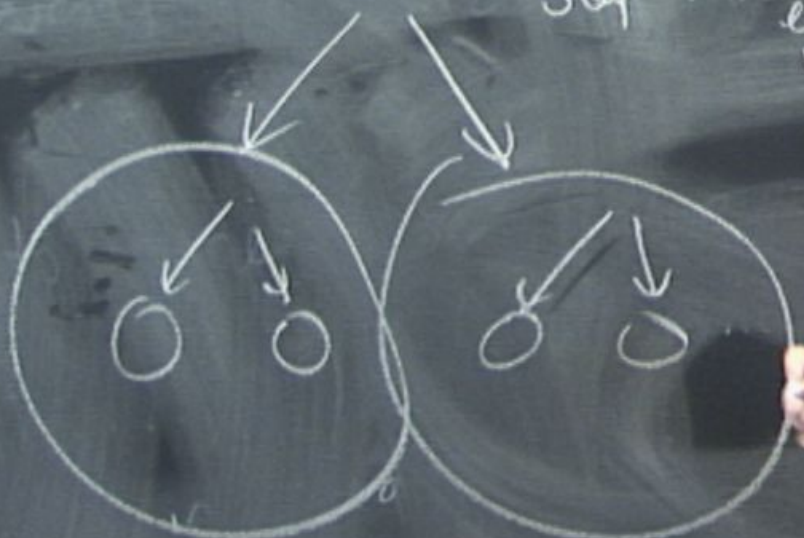
$$A(n) = K \ln n$$

with $K > 0$

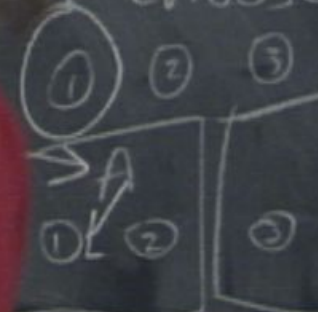
- 1) S is continuous in the
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Step 1: 1 of 2 equally likely choices



- 3) I break down to two S the same choose



will show

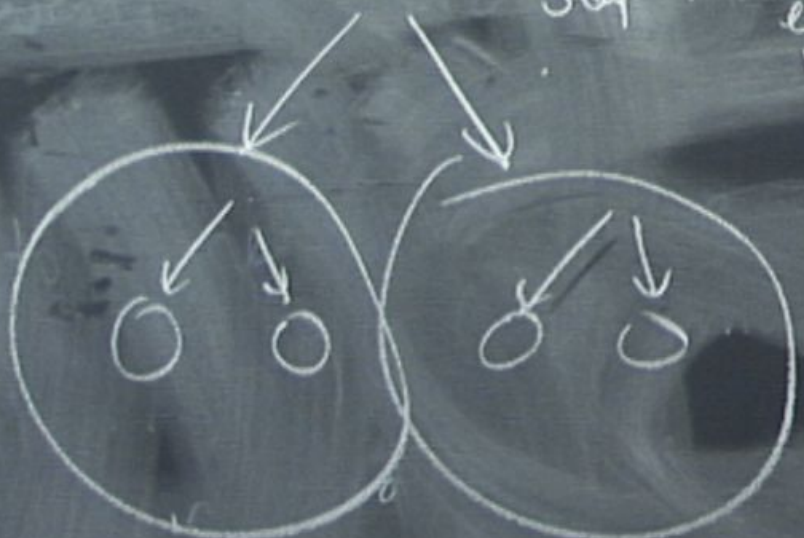
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with $K > 0$

- 1) S is continuous in the
- 2) If the $p_i = 1/n$ then S is monotone increasing with



step 1: 1 of 2 equally likely choices



$$2A(2)$$

$$A(4) = 2A(2)$$

- 3) If you break choice into - you learn the