

Title: General Relativity for Cosmology - Lecture 14A

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Abstract:



GR for Cosmology, Achim Kempf, Fall 09, **Lecture 15**

11/6/2009

# The tetrad formulation of GR

## Why?

1. Need a formalism that is suited for study of local versus global entities:

E.g. a binary star system, or a galaxy, far from other matter  
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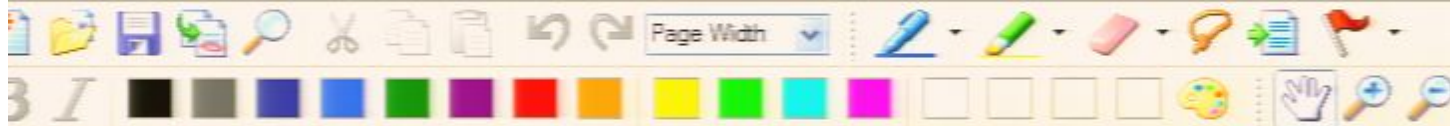
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2. Need a formalism that is suited for the study of fermions:

E.g.: In special relativity, the Dirac equation (for electrons and quarks etc) has the form:

$$\left( i\gamma^\mu \frac{\partial}{\partial x^\mu} - m\mathbf{1} \right) \Psi = 0 \quad \text{with } \Psi = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$$

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$$\gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu = 2 g^{\mu\nu} = 2 \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

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Strategy: At each  $p \in M$  choose an orthonormal basis  $\{\theta^i\}$  of  $T_p(M)$ , and dual basis  $\{e_i\}$  so that  $g_{\mu\nu} = g(e_\mu, e_\nu) = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$ .



### 3. Important benefit:

General relativity takes the form of a so-called "gauge theory", which is analogous to the gauge theories of electromagnetism, the weak and the strong force.  $\rightarrow$  Useful for Quantum Gravity?

### Recall the math:

#### □ Frames $\{\theta^\mu\}, \{e_\mu\}$ :

Often, one uses as the bases of  $T_p(M)$ , and  $T_p(M)^*$  the canonical bases  $\{dx^\mu\}$  and  $\{\frac{\partial}{\partial x^\mu}\}$  respectively, which suggest themselves when one chooses coordinates, say  $(x^0, \dots, x^3)$ .



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**Important:** The only reason why the components of a tensor can <sup>but don't have to</sup> change when we change coordinates is that we can <sup>and often do</sup> change basis in the (co-) tangent spaces, namely



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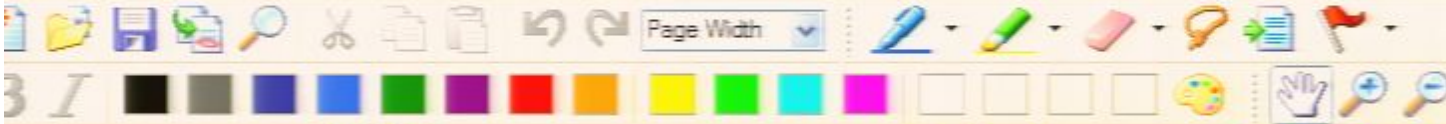
**Important:** The only reason why the components of a tensor can change when we change coordinates is that we can change basis in the (co-) tangent spaces, namely from one canonical basis to another canonical basis, when we change coord. system.

*Hand icon*  
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Recall:  
 Pirs: 09110007  $\psi$  has different coefficients in different bases:

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Recall:

(a fixed vector has different coefficients in different bases:)

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**We notice:** If we choose a fixed basis, say  $\{\theta^\mu\}, \{e_\mu\}$  then the coefficients of tensors no longer depend on the choice of coordinates, i.e. they are scalars! E.g.:

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scalar functions.

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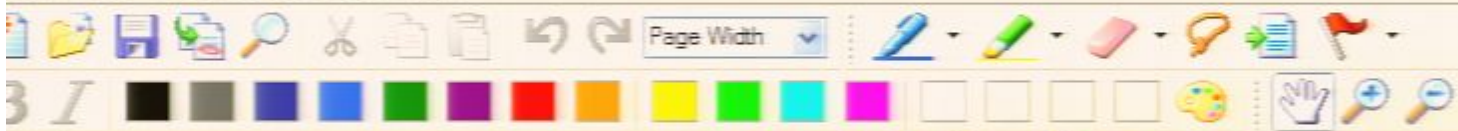
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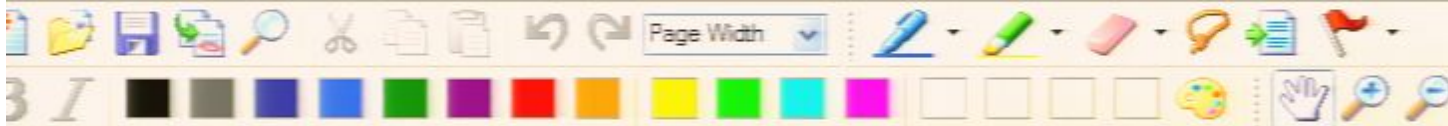
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Examples:

□ The curvature form:  $\Omega'^\mu_\nu = A^\mu_\alpha (A^{-1})^\beta_\nu \Omega^a_b$





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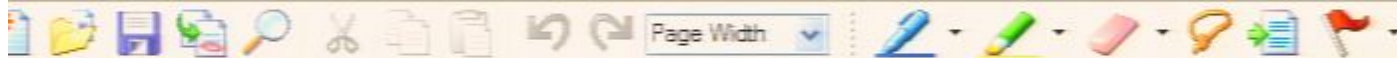
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(Matrix notation:  $\omega' = A \omega A^{-1} - (dA) A^{-1}$ )

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J.e.:  $\xi'^{\nu} = A^{\nu}_{\mu} \xi^{\mu}$

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## How to specify frames?

In an arbitrary coordinate system, we may specify the bases in terms of the canonical bases:

$$\Theta^i(x) = \lambda^i_j(x) dx^j$$

(Another possibility? Take  $n$  scalar functions  $f^1, \dots, f^n$  and define  $\Theta^i := df^i$ . For generic functions these  $\{\Theta^i\}$  will be linearly independent almost everywhere.)



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## Our choice now: orthonormal frames, i.e. "Tetrads":

□ We say that a frame  $\{\theta^r\}, \{e_\mu\}$  is orthonormal if in this frame, for all  $p \in M$ :

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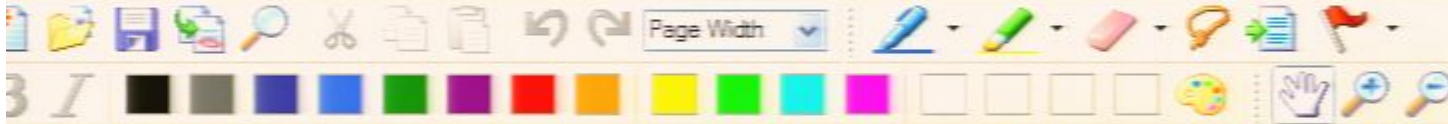
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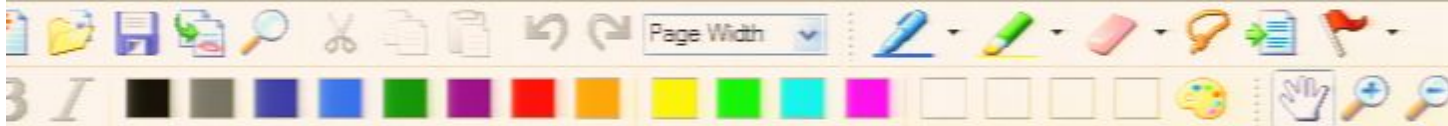
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i.e.  $\gamma$ :  $\Lambda^a \Lambda^b \gamma_{ab} = \gamma_{ab}$  (\*)

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Can now answer an old question:

**Q:** The connection 1-forms  $\omega^r_v$  are not, we know, tensor-valued 1-forms. Wherin do they take their values?

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The connection yields the change under infinitesimal parallel transport - and parallel transport preserves the metric, i.e. it preserves the lengths of vectors, i.e. the change can only be an infinitesimal "rotation", i.e. an infinitesimal Lorentz transformation.



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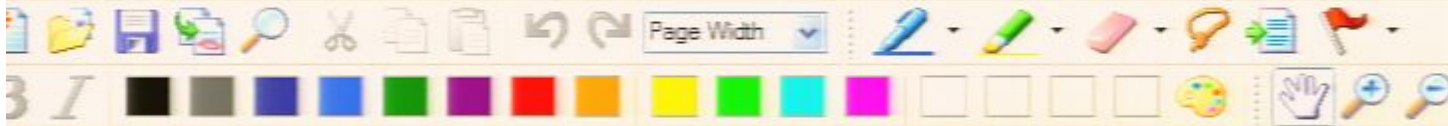
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Infinitesimal Lorentz transformations are of this form:

$$A^{\mu}_{\alpha} = \delta^{\mu}_{\alpha} + \epsilon^{\mu}_{\alpha}$$

$\epsilon^2 = 0$  assumed

(technically, we are going from the Lorentz group to the Lorentz Lie algebra)

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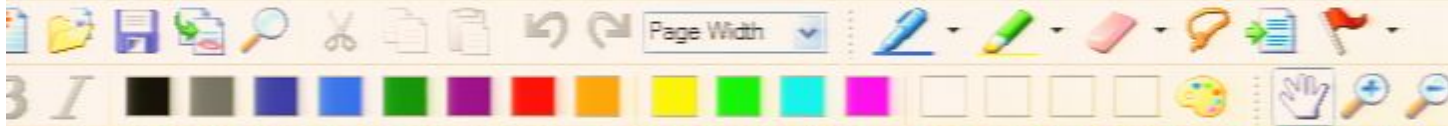
$$(\delta^{\mu}_{\alpha} + \epsilon^{\mu}_{\alpha})(\delta^{\nu}_{\beta} + \epsilon^{\nu}_{\beta}) \eta_{\mu\nu} = \eta_{\alpha\beta}$$

i.e. 
$$\epsilon^{\mu}_{\alpha} \eta_{\mu\beta} + \epsilon^{\nu}_{\beta} \eta_{\alpha\nu} = 0$$

$\Rightarrow$  Infinitesimal Lorentz transformations are given by all  $A^{\mu}_{\alpha} = \delta^{\mu}_{\alpha} + \epsilon^{\mu}_{\alpha}$

which obey:

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Proposition:

In orthonormal frames, the 1-form  $\omega_{\mu\nu}$  obeys

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i.e. it takes values that are infinitesimal Lorentz transformations.

Proof:

□ Recall: Absolute exterior derivative: (an anti-derivative)

$$Dt^{a...b}_{c...d} = dt^{a...b}_{c...d} + \omega^a{}_i \wedge t^{i...b}_{c...d} + \dots - \omega^i{}_c \wedge t^{a...b}_{i...d} - \dots$$

↑ any tensor-valued differential form.

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Thus:

$$0 = \nabla g_{\mu\nu} = Dg_{\mu\nu} = dg_{\mu\nu} - \omega^i{}_{\mu} \wedge g_{i\nu} - \omega^i{}_{\nu} \wedge g_{\mu i}$$

(0,2) tensor-valued 0-form

= 0 because  $g_{\mu\nu} = \eta_{\mu\nu} = \text{const}$

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Recall that by using a tetrad, we achieved that  $g_{\mu\nu} = (\delta^i{}_{\mu} \delta^j{}_{\nu}) = \eta_{\mu\nu}$  everywhere!

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Then: (0,2) tensor-valued 1-form = 0 because  $g_{\mu\nu} = \eta_{\mu\nu} = \text{const}$



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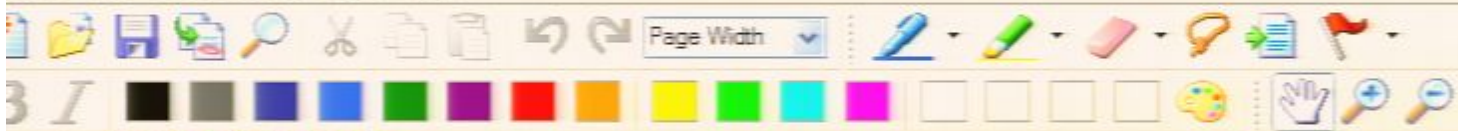
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Recall that by using a tetrad, we achieved that  $g_{\mu\nu} = \begin{pmatrix} -1 & & \\ & 1 & \\ & & \ddots \end{pmatrix} = \eta_{\mu\nu}$  everywhere!





Propose above.

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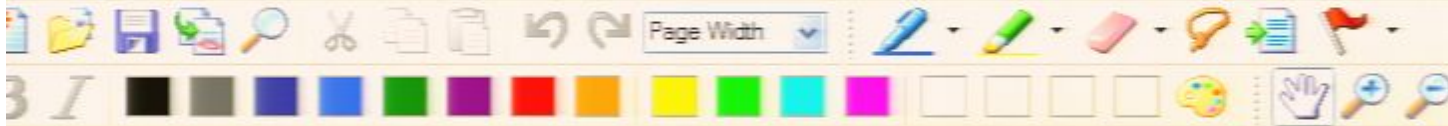
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## Tetrad formulation of GR:

□ Redefine the degrees of freedom:

- We used to specify space-times



## Tetrad formulation of GR:

### □ Redefine the degrees of freedom:

- We used to specify space-times through these data:  $(M, g)$
- Now, let us specify space-times, equivalently, through data  $(M, \{\theta^{\mu}\})$ :

Namely:

Assume the  $\{\theta^{\mu}\}$  are given w. resp. to a basis  $\{dx^{\nu}\}$ .

through functions  $A^{\mu}_{\nu}$  so that:

$$\theta^{\mu}(x) = A^{\mu}_{\nu}(x) dx^{\nu}$$

Then,  $g_{\mu\nu} = \begin{pmatrix} 0 & \\ & 0 \end{pmatrix} = \eta_{\mu\nu}$  in the basis  $\{\theta^{\mu}\}$ .

But: knowing the  $A^{\mu}_{\nu}(x)$ , can reconstruct  $g_{\mu\nu}(x)$  in basis  $\{dx^{\nu}\}$ :



through these data:  $(M, g)$

- o Now, let us specify space-times, equivalently, through data  $(M, \{\theta^i\})$ :

**Namely:**

Assume the  $\{\theta^i\}$  are given w. resp. to a basis  $\{dx^r\}$ .

through functions  $A^{\mu}_{\nu}$  so that:

$$\theta^{\mu}(x) = A^{\mu}_{\nu}(x) dx^{\nu}$$

Then,  $g_{\mu\nu} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \eta_{\mu\nu}$  in the basis  $\{\theta^i\}$ .

**But:** knowing the  $A^{\mu}_{\nu}(x)$ , can reconstruct  $g_{\mu\nu}(x)$  in basis  $\{dx^r\}$ :

Recall:

The abstract  $g$  is always the same, no matter which basis we express it in.  $\Rightarrow$

$$g = \underbrace{\eta_{\mu\nu}}_{\text{because it's fixed}} \theta^{\mu} \otimes \theta^{\nu} = \eta_{\mu\nu} \overbrace{A^{\mu}_{\alpha} A^{\nu}_{\beta}} = g_{\alpha\beta}(x) dx^{\alpha} \otimes dx^{\beta}$$



equivalently, through data  $(M, \{\theta^i\})$ :

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$\Rightarrow \{\theta^i(x)\}$  indeed determines  $g_{\mu\nu}(x)$ :



- o We used to specify space-times through these data:  $(M, g)$
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Then,  $g_{\mu\nu} = (\delta^i_j, 0) = \eta_{\mu\nu}$  in the basis  $\{\theta^i\}$ .

**But:** knowing the  $A^{\mu}_{\nu}(x)$ , can reconstruct  $g_{\mu\nu}(x)$  in basis  $\{dx^r\}$ :

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The abstract  $g$  is always the same, no matter which

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$$= g_{ab}(x)$$



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Recall:

The abstract  $g$  is always the same, no matter which basis we express it in.  $\Rightarrow$

$$g = \underbrace{\eta_{ij} \theta^i \otimes \theta^j}_{\text{because it's abstract}} = \eta_{ij} \underbrace{A^{\mu}_a A^{\nu}_b}_{= g_{ab}(x)} dx^a \otimes dx^b = g_{\mu\nu}(x) dx^{\mu} \otimes dx^{\nu}$$

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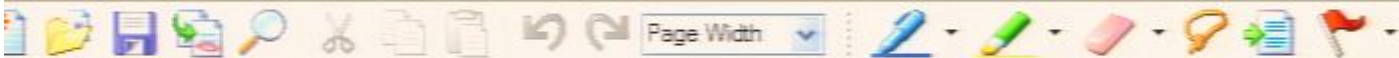
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- It should be possible to formulate the action principle with variations with respect to  $\{\theta^{\mu}\}$ .

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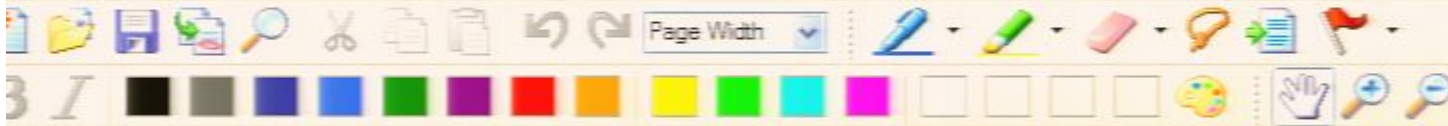
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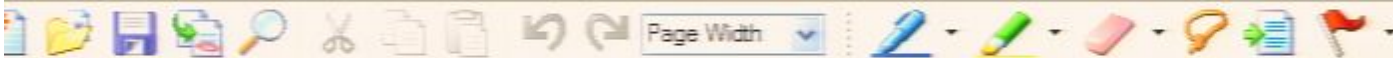
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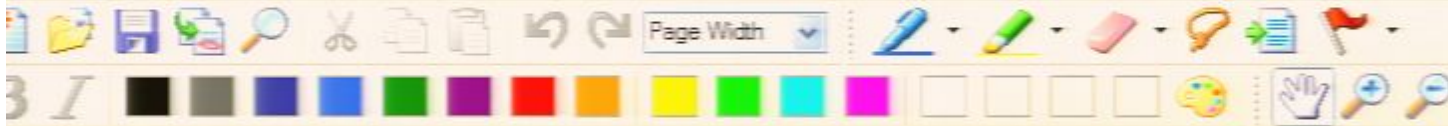
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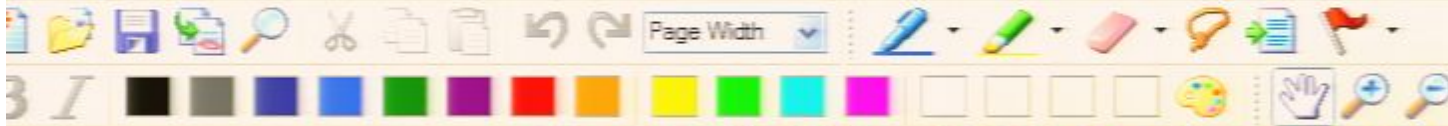
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"Gauge principle of GR":

- $\rightsquigarrow$  GR can be viewed as generalizing SR by allowing local, not just global, Lorentz transformations at the 'cost' of introducing curvature  $\Omega^\mu{}_\nu$ .



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"Gauge principle of GR":

- o  $\rightarrow$  GR can be viewed as generalizing SR by allowing local, not just global, Lorentz transformations at the 'cost' of introducing curvature  $\Omega^\mu_\nu$ .

### Remark:

The Schrödinger and Dirac equations allow

$$\psi(x) \rightarrow e^{i\alpha} \psi(x) \quad \text{"global" phase transformation}$$

trivially. Indeed, also local transformations

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## □ Remark:

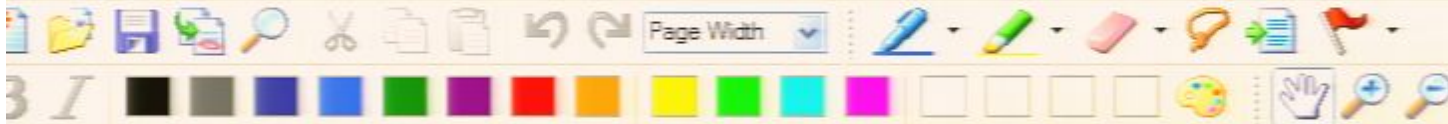
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trivially. Indeed, also local transformations

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work: At the cost of introducing a field  $F_{\mu\nu}(x)$ . Thus, the electromagnetic field is derivable this way. Similar for weak and strong force. Main difference to gravity: Connection yes, but no



to gravity: Connection yes, but no metric.

□ The action principle: (in terms of  $\{\theta^i\}$  and  $\Omega^i$ ;

Consider the action, for now, without cosmological constant and without matter:

$$S_{\text{grav}} = \frac{1}{16\pi G} \int_B R \sqrt{g} d^4x$$

← 0-form

Recall Hodge \*:  $\int \nu = \frac{1}{p!} \nu_{i_1 \dots i_p} \theta^{i_1} \wedge \dots \wedge \theta^{i_p}$

then  $*\nu = \frac{1}{p!} \sqrt{g} \epsilon_{i_1 \dots i_{n-p}} \nu^{i_1 \dots i_p} \theta^{i_{p+1}} \wedge \dots \wedge \theta^{i_n}$

= ±1, totally anti-symmetric

i.e.  $*: \Lambda^p \rightarrow \Lambda^{n-p}$



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Thus:

$$S_{\text{grav}} = \frac{1}{16\pi G} \int_B \underbrace{*R}_{\text{3-form}}$$



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Thus:

$$S'_{\text{grav}} = \frac{1}{16\pi G} \int_B \underbrace{*R}_{4\text{-form}}$$

Aim now: Re-express  $S'$  in terms of  $\{\theta^{\mu\nu}\}$  and  $\Omega^{\mu\nu}$



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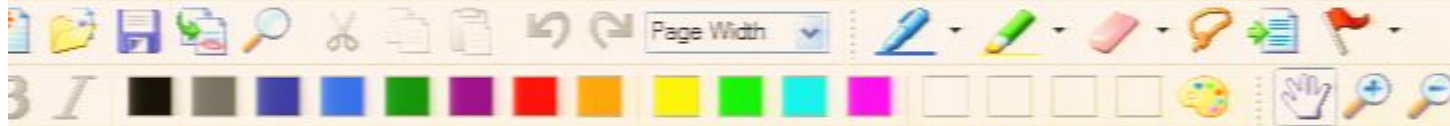
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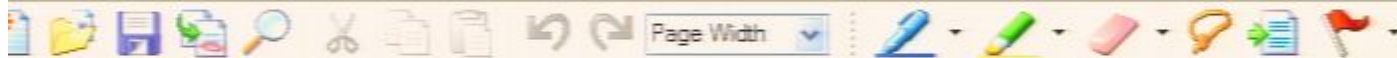
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Aim now: Re-express  $S'_{grav}$  in terms of  $\{\theta^M\}$  and  $\Omega^M \nu$ .

□ Define: "capital  $\eta$ " is a  $(0, 2)$  tensor-valued 2-form



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□ Define:

"capital  $\eta$ " is a  $(0,2)$  tensor-valued 2-form

$$H := *(\theta^A \wedge \theta^B) = \frac{1}{2} \sqrt{g} \epsilon_{ABCD} \theta^C \wedge \theta^D$$



Aim now: Re-express  $S'_{\mu\nu}$  in terms of  $\{\theta^\mu\}$  and  $\Omega^{\mu\nu}$ .

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$$H_{\mu\beta} := *(\theta^\mu \wedge \theta^\beta) = \frac{1}{2} \sqrt{|g|} \epsilon_{\mu\beta\gamma\delta} \theta^\gamma \wedge \theta^\delta$$

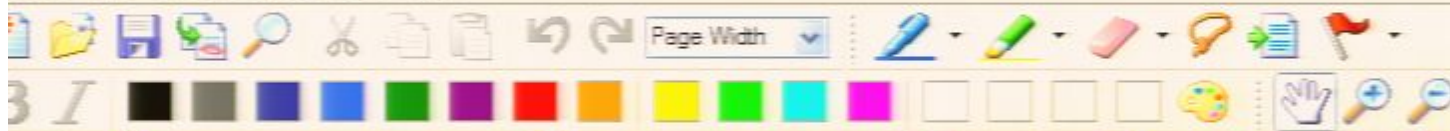
$$H_{\mu\beta\gamma} := *(\theta^\mu \wedge \theta^\beta \wedge \theta^\gamma) = \frac{1}{2} \sqrt{|g|} \epsilon_{\mu\beta\gamma\delta} \theta^\delta$$

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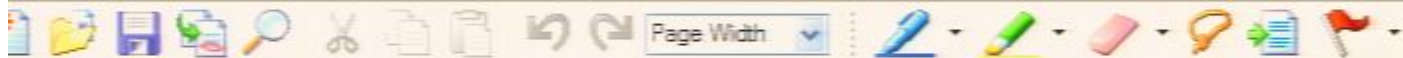
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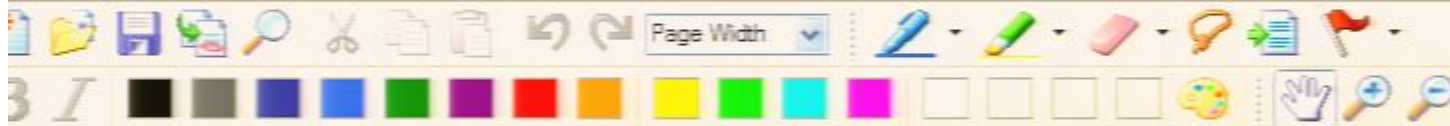
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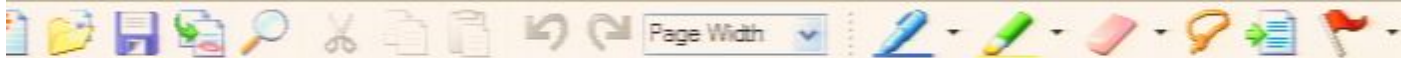
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□ Proof:

$$\text{Use } \Omega^{\mu\nu} = \frac{1}{2} R^{\mu\nu\kappa\lambda} \theta^\kappa \wedge \theta^\lambda \Rightarrow$$



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$\uparrow$  a (0,3) tensor-valued 1-form.

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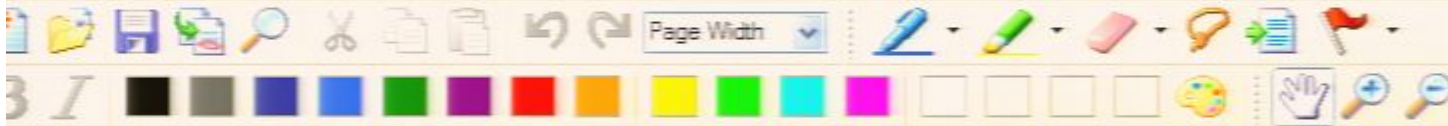
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(need later for derivation of the Einstein equation)



Proposition:  $DH_{\mu\nu} = 0$

constant because DV basis

Recall the "first structure equation":  $D\theta^a = 0$

$$\text{Proof: } DH_{\mu\nu} = D\left(\frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^\sigma \wedge \theta^\tau\right) = \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} (D\theta^\sigma \wedge \theta^\tau + \theta^\sigma \wedge D\theta^\tau)$$



Proof:

$$\text{Use } \Omega^\mu{}_\nu = \frac{1}{2} R^\mu{}_{\nu\kappa\lambda} \theta^\kappa \wedge \theta^\lambda \Rightarrow$$

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{1}{2 \cdot 2} \sqrt{g} \epsilon_{\mu\nu\gamma\delta} R^{\mu\nu}{}_{\kappa\lambda} \underbrace{\theta^\kappa \wedge \theta^\lambda \wedge \theta^\mu \wedge \theta^\nu}_{\epsilon^{\gamma\delta\kappa\lambda} \theta^\gamma \otimes \theta^\delta \otimes \theta^\kappa \otimes \theta^\lambda}$$

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$$*R = H_{\mu\nu} \wedge \Omega^{\mu\nu}$$

(it is a (0,2) tensor-valued 4-form)

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$$\text{Use also: } \epsilon_{\gamma\delta\kappa\lambda} \epsilon_{\mu\nu\gamma\delta} = 2(\delta_{\nu\mu} \delta_{\lambda\kappa} - \delta_{\nu\kappa} \delta_{\lambda\mu}) \Rightarrow$$



□ Define: "capital  $\gamma$ " is a  $(0, 2)$  tensor-valued 2-form

$$H_{\mu\nu} := *(\theta^\mu \wedge \theta^\nu) = \frac{1}{2} \sqrt{|g|} \epsilon_{\mu\nu\gamma\delta} \theta^\gamma \wedge \theta^\delta$$

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$$*R = H_{\mu\nu} \wedge \Omega^{\mu\nu}$$

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Proof:

$$\text{Use } \Omega^{\mu\nu} = \frac{1}{2} R^{\mu\nu\kappa\lambda} \theta^{\kappa} \wedge \theta^{\lambda} \Rightarrow$$

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(need later for derivation of the Einstein equation)

Proposition:  $DH_{\mu\nu} = 0$

Recall the "first structure equation":  $D\theta^a = 0$

constant because ON basis

Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$



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Use  $\Omega^{\mu\nu} = \frac{1}{2} R^{\mu\nu\kappa\lambda} \theta^{\kappa} \wedge \theta^{\lambda} \Rightarrow$

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Proof:

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Proposition:  $DH_{\mu\nu} = 0$

constant because ON basis

Recall the "first structure equation":  $D\theta^i = 0$



Proof:

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constant because ON basis

Recall the "first structure equation":  $D\theta^a = 0$

Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^\sigma \wedge \theta^\tau\right) = \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} (D\theta^\sigma \wedge \theta^\tau + \theta^\sigma \wedge D\theta^\tau)$



2

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{1}{2 \cdot 2} \sqrt{g} \epsilon_{\mu\nu\gamma\delta} R^{\mu\nu}{}_{\kappa\lambda} \underbrace{\theta^{\gamma} \wedge \theta^{\delta} \wedge \theta^{\kappa} \wedge \theta^{\lambda}}_{\epsilon_{\gamma\delta\kappa\lambda} \theta^{\gamma} \otimes \theta^{\delta} \otimes \theta^{\kappa} \otimes \theta^{\lambda}}$$

Use also:  $\epsilon_{\gamma\delta\kappa\lambda} \epsilon_{\mu\nu\gamma\delta} = 2(\delta_{\nu\mu} \delta_{\lambda\kappa} - \delta_{\nu\kappa} \delta_{\lambda\mu}) \Rightarrow$

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{4}{4} R^{\mu\nu}{}_{\mu\nu} \sqrt{g} \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 = *R \checkmark$$

(need later for derivation of the Einstein equation)

□ Proposition:  $DH_{\mu\nu} = 0$

constant because DV basis

Recall the "first structure equation":  $D\theta^a = 0$

△ Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$



$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{1}{2 \cdot 2} \sqrt{g} \epsilon_{\mu\nu\gamma\delta} R^{\mu\nu}{}_{\kappa\lambda} \underbrace{\theta^{\gamma} \wedge \theta^{\delta} \wedge \theta^{\kappa} \wedge \theta^{\lambda}}_{\epsilon_{\gamma\delta\kappa\lambda} \theta^{\gamma} \otimes \theta^{\delta} \otimes \theta^{\kappa} \otimes \theta^{\lambda}}$$

Use also:  $\epsilon_{\gamma\delta\kappa\lambda} \epsilon_{\mu\nu\gamma\delta} = 2(\delta_{\nu\mu} \delta_{\lambda\kappa} - \delta_{\nu\kappa} \delta_{\lambda\mu}) \Rightarrow$

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{4}{4} R^{\mu\nu}{}_{\mu\nu} \sqrt{g} \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 = *R \checkmark$$

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□ Proposition:  $DH_{\mu\nu} = 0$

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Recall the "first structure equation":  $D\theta^a = 0$

△ Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$

Recall important identities: (torsionless case)

$\epsilon_{\mu\nu\kappa\lambda} \epsilon^{\mu\nu\sigma\rho} = 2(\delta_{\nu\rho}\delta_{\lambda\sigma} - \delta_{\nu\sigma}\delta_{\lambda\rho}) \Rightarrow$

Use also:  $\epsilon_{\mu\nu\kappa\lambda} \epsilon^{\mu\nu\sigma\rho} = 2(\delta_{\nu\rho}\delta_{\lambda\sigma} - \delta_{\nu\sigma}\delta_{\lambda\rho}) \Rightarrow$

$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{4}{4} R^{\mu\nu}{}_{\mu\nu} \nabla_{\sigma} \theta^1 \wedge \theta^2 \wedge \theta^3 \wedge \theta^4 = *R \checkmark$

(need later for derivation of the Einstein equation)

□ Proposition:  $DH_{\mu\nu} = 0$

constant because ON basis

Recall the "first structure equation":  $D\theta^a = 0$

□ Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \nabla_{\sigma} \epsilon_{\mu\nu\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \nabla_{\sigma} \epsilon_{\mu\nu\sigma\tau} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$

Recall important identities: (torsionless case)

□ Structure eqn. I:

used it just now



$$\epsilon_{\mu\delta\kappa\lambda} \theta^{\mu} \otimes \theta^{\delta} \otimes \theta^{\kappa} \otimes \theta^{\lambda}$$

Use also:  $\epsilon_{\mu\delta\kappa\lambda} \epsilon_{\mu\nu\gamma\delta} = 2(\delta_{\nu\gamma} \delta_{\lambda\mu} - \delta_{\nu\mu} \delta_{\lambda\gamma}) \Rightarrow$

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{4}{4} R^{\mu\nu}{}_{\mu\nu} \nabla_{\mu} \theta^{\lambda} \wedge \theta^{\sigma} \wedge \theta^{\tau} \wedge \theta^{\rho} = *R \checkmark$$

(need later for derivation of the Einstein equation)



□ Proposition:  $DH_{\mu\nu} = 0$

constant because ON basis

Recall the "first structure equation":  $D\theta^{\alpha} = 0$

△ Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \nabla_{\mu} \epsilon_{\nu\sigma\tau\alpha} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \nabla_{\mu} \epsilon_{\nu\sigma\tau\alpha} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$

Recall important identities: (torsionless case)

□ Structure eqn. I:

used it just now

$$D\theta^i = d\theta^i + \omega^i{}_j \wedge \theta^j = 0$$

(need later for derivation of the Einstein equation)

$$H_{\mu\nu} \wedge \Omega^{\mu\nu} = \frac{1}{4} R^{\mu\nu}{}_{\rho\sigma} \nabla_j \theta^{\rho} \wedge \theta^{\sigma} \wedge \theta^{\mu} \wedge \theta^{\nu} = *R \quad \checkmark$$

□ Proposition:  $DH_{\mu\nu} = 0$

constant because ON basis

Recall the "first structure equation":  $D\theta^a = 0$

△ Proof:  $DH_{\mu\nu} = D\left(\frac{1}{2} \nabla_j \epsilon_{\mu\nu\sigma\tau} \theta^{\sigma} \wedge \theta^{\tau}\right) = \frac{1}{2} \nabla_j \epsilon_{\mu\nu\sigma\tau} (D\theta^{\sigma} \wedge \theta^{\tau} + \theta^{\sigma} \wedge D\theta^{\tau})$

Recall important identities: (torsionless case)

□ Structure eqn. I:

used it just now

$$D\theta^i = d\theta^i + \omega^i{}_j \wedge \theta^j = 0$$

□ Structure eqn II:

$$\Omega^i{}_j = d\omega^i{}_j + \omega^i{}_k \wedge \omega^k{}_j$$

← (Recall:  $R^i{}_{jkl} = \Gamma^i{}_{[k} \Gamma^j{}_{l]} + \Gamma^i{}_{[k} \Gamma^j{}_{l]} + \Gamma^i{}_{[k} \Gamma^j{}_{l]} + \Gamma^i{}_{[k} \Gamma^j{}_{l]}$ )



↳  $\square$  Proposition:  $DH_{\mu\nu} = 0$

constant because ON basis

Recall the "first structure equation":  $D\theta^a = 0$

$$\triangle \text{ Proof: } DH_{\mu\nu} = D\left(\frac{1}{2}V_j^i \epsilon_{\mu\nu\sigma} \theta^{\sigma} \wedge \theta^{\sigma}\right) = \frac{1}{2}V_j^i \epsilon_{\mu\nu\sigma} (D\theta^{\sigma} \wedge \theta^{\sigma} + \theta^{\sigma} \wedge D\theta^{\sigma})$$

Recall important identities: (torsionless case)

$\square$  Structure eqn. I:



used it just now

$$D\theta^i = d\theta^i + \omega^i{}_j \wedge \theta^j = 0$$

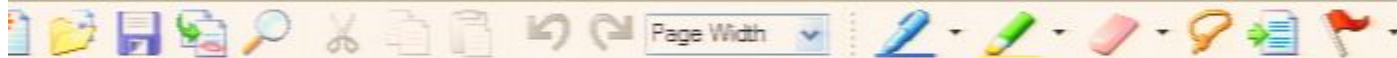
$\square$  Structure eqn II:

$$\Omega^i{}_j = d\omega^i{}_j + \omega^i{}_k \wedge \omega^k{}_j$$

$\square$  Bianchi identity I:

$$\Omega^i{}_j \wedge \theta^j = 0$$

← (Recall:  $R^{\dots} = \Gamma^{\dots} + \Gamma^{\dots} + \Gamma^{\dots} + \Gamma^{\dots}$ )



constant because ON basis

recall = the first structure equation:  $D\theta^i = 0$

$$\Delta \text{ Proof: } DH_{\mu\nu} = D\left(\frac{1}{2}V_j^i \epsilon_{\mu\nu c} \theta^c \wedge \theta^c\right) = \frac{1}{2}V_j^i \epsilon_{\mu\nu c} (D\theta^c \wedge \theta^c + \theta^c \wedge D\theta^c)$$

Recall important identities: (torsionless case)

□ Structure eqn. I: used it just now

$$D\theta^i = d\theta^i + \omega^i_j \wedge \theta^j = 0$$

□ Structure eqn II:

$$\Omega^i_j = d\omega^i_j + \omega^i_k \wedge \omega^k_j$$

□ Bianchi identity I:

$$\Omega^i_j \wedge \theta^j = 0$$

← (Recall:  $R^i_{jkl} = \Gamma^i_{[k,l]j} + \Gamma^i_{[l,j]k} + \Gamma^i_{[j,l]k}$ )

□ Bianchi identity II:



## Recall important identities: (torsionless case)

□ Structure eqn. I:

$$D\theta^i = d\theta^i + \omega^i{}_j \wedge \theta^j = 0$$

used it just now



□ Structure eqn II:

$$\Omega^i{}_j = d\omega^i{}_j + \omega^i{}_k \wedge \omega^k{}_j$$

← (Recall:  $R^i{}_{jkl} = \Gamma^i{}_{[k,l]} + \Gamma^i{}_{[l,k]} + \Gamma^i{}_{[m,l]} \Gamma^m{}_{[k]} + \Gamma^i{}_{[m,k]} \Gamma^m{}_{[l]}$ )

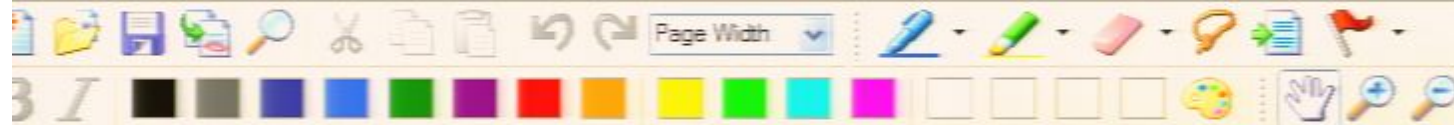
- R.  $\Omega^i{}_j \wedge \theta^j = 0$

□ Bianchi identity II:

$$D\Omega^i{}_j = 0$$

And, in the case of ON frames:

$$\omega_{\mu\nu} + \omega_{\nu\mu} = 0$$



## Recall important identities: (torsionless case)

□ Structure eqn. I:

$$D\theta^i = d\theta^i + \omega^i_{j1} \theta^j = 0$$

used it just now

□ Structure eqn II:

$$\Omega^i_j = d\omega^i_j + \omega^i_k \wedge \omega^k_j$$

← (Recall:  $R^i_{jkl} = \Gamma^i_{j,lk} - \Gamma^i_{j,kl} + \Gamma^m_{j,l}\Gamma^i_{m,k} - \Gamma^m_{j,k}\Gamma^i_{m,l}$ )

□ Bianchi identity I:

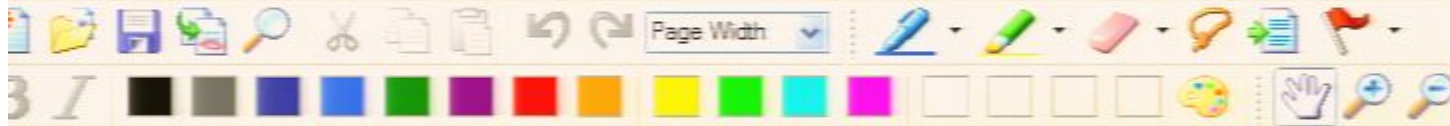
$$\Omega^i_j \wedge \theta^j = 0$$

□ Bianchi identity II:

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And, in the case of ON frames:

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□ Structure eqn. I:

$$D\theta^i = d\theta^i + \omega^i{}_j \wedge \theta^j = 0$$

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□ Structure eqn II:

$$\Omega^i{}_j = d\omega^i{}_j + \omega^i{}_k \wedge \omega^k{}_j$$

← (Recall:  $R^i{}_{jkl} = \Gamma^i{}_{[k,l]} + \Gamma^i{}_{[l,k]} + \Gamma^i{}_{[m,l]} \Gamma^m{}_{[k]} + \Gamma^i{}_{[m,k]} \Gamma^m{}_{[l]}$ )

□ Bianchi identity I:

$$\Omega^i{}_j \wedge \theta^j = 0$$

□ Bianchi identity II:

$$D\Omega^i{}_j = 0$$

And, in the case of ON frames:

$$\omega_{\mu\nu} + \omega_{\nu\mu} = 0$$



$$\omega_{\mu\nu} + \omega_{\nu\mu} = 0$$

The main proposition:

variation, not co-derivative

Variation of the action with respect to  $\delta\theta^\mu$  yields:

$$\delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

It implies:

$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^\mu \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

Stokes:

$$\int_B df = \int_{\partial B} f$$

← require variation to vanish at boundary  $\partial B$ ,  
so: = 0

Definition: The "energy-momentum 1-form"  $T_\nu$  is defined as the solution to:



$$\Omega^i_j \wedge \theta^j = 0$$

□ Bianchi identity II:

$$D\Omega^i_j = 0$$

And, in the case of ON frames:

$$\omega_{\mu\nu} + \omega_{\nu\mu} = 0$$

The main proposition:

variation, not co-derivative



Variation of the action with respect to  $\delta\theta^{\mu}$  yields:

$$\delta(*R) = (\delta\theta^{\mu}) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

Stokes:  
 $\int_B df = \int_{\partial B} f$

It implies:

$$16\pi G \delta S = (\delta\theta^{\mu} \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something}))$$



The main proposition:

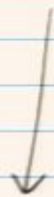
variation, not co-derivative



Variation of the action with respect to  $\delta\theta^\mu$  yields:

$$\delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

Stokes:  
 $\int_B df = \int_{\partial B} f$



It implies:

$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^\mu \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

← require variation to vanish at boundary  $\partial B$ , so: = 0

Definition: The "energy-momentum 1-form"  $T_\mu$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_{\mathcal{D}} \delta\theta^\mu \wedge (*T_\mu)$$





The main proposition:

variation, not co-derivative  
↓

Variation of the action with respect to  $\delta\theta^r$  yields:

$$\delta(*R) = (\delta\theta^r) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

Stokes:  
 $\int_B df = \int_{\partial B} f$

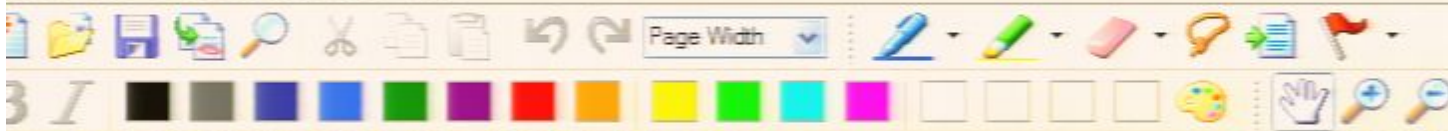
It implies:

$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^r \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

← require variation to vanish at boundary  $\partial B$ , so: = 0

Definition: The "energy-momentum 1-form"  $T_r$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_B \delta\theta^r \wedge (*T_r)$$



The main proposition.

Variation, not co-derivative

Variation of the action with respect to  $\delta\theta^\mu$  yields:

$$\delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

It implies:

$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^\mu \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

Stokes:  
 $\int_B df = \int_{\partial B} f$

← require variation to vanish at boundary  $\partial B$ , so: = 0

Definition: The "energy-momentum 1-form"  $T_\mu$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_B \delta\theta^\mu \wedge (*T_\mu)$$



Variation of the action with respect to  $\delta\theta^\mu$  yields:

$$\delta(*R) = (\delta\theta^\mu) \lrcorner H_{\mu\nu\sigma} \lrcorner \Omega^{\nu\sigma} + d(\text{something})$$

It implies:

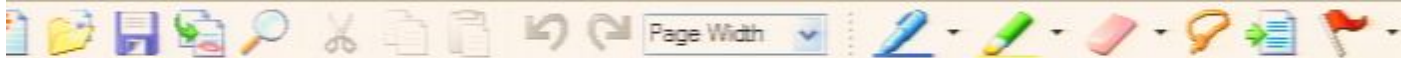
$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^\mu \lrcorner H_{\mu\nu\sigma} \lrcorner \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

Stokes:  
 $\int_B df = \int_{\partial B} f$

← require variation to vanish at boundary  $\partial B$ , so: = 0

Definition: The "energy-momentum 1-form"  $T_\mu$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_B \delta\theta^\mu \lrcorner (*T_\mu)$$



Variation of the action with respect to  $\delta\theta^r$  yields:

$$\delta(*R) = (\delta\theta^r) \lrcorner H_{\mu\nu} \lrcorner \Omega^{\nu\sigma} + d(\text{something})$$

It implies:

$$16\pi G \delta S'_{\text{grav}} = \int_B \delta\theta^r \lrcorner H_{\mu\nu} \lrcorner \Omega^{\nu\sigma} + \int_{\partial B} (\text{something})$$

Stokes:

$$\int_B df = \int_{\partial B} f$$



← require variation to vanish at boundary  $\partial B$ ,  
so: = 0

Definition: The "energy-momentum 1-form"  $T_\mu$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_B \delta\theta^r \lrcorner (*T_\mu)$$

⇒ The equation of motion, i.e., the **Einstein equation**



B

 $\partial B$ 

← require variation to vanish at boundary  $\partial B$ ,  
so:  $= 0$

Definition: The "energy-momentum 1-form"  $T_\mu$  is defined as the solution to:

$$\delta S_{\text{matter}} =: \int_B \delta \theta^\mu \wedge (*T_\mu)$$



⇒ The equation of motion, i.e., the Einstein equation,

$$\frac{\delta(S_{\text{grav}} + S_{\text{matter}})}{\delta \theta^\mu} = 0$$

becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_\mu$$



Definition: The "energy-momentum 1-form"  $T_\nu$  is defined as the solution to:

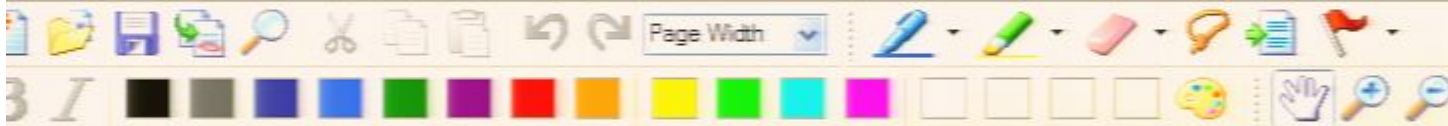
$$\delta S_{\text{matter}} =: \int_B \delta \theta^\nu \wedge (*T_\nu)$$

$\Rightarrow$  The equation of motion, i.e., the Einstein equation,

$$\frac{\delta(S_{\text{grav}} + S_{\text{matter}})}{\delta \theta^\nu} = 0$$

becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_\mu$$



$$\delta S_{\text{matter}} =: \int_B \delta \theta^{\rho} \wedge (*T_{\rho})$$

⇒ The equation of motion, i.e., the Einstein equation,

$$\frac{\delta(S_{\text{grav}} + S_{\text{matter}})}{\delta \theta^{\rho}} = 0$$

becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.



⇒ The equation of motion, i.e., the Einstein equation,

$$\frac{\delta(S_{\text{grav}} + S_{\text{matter}})}{\delta\theta^r} = 0$$

becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.

Remark: The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys  $*G_{\mu} = -\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma}$  (it is a (0,1) tensor-valued 1-form)

$$G = 8\pi G T$$





The divergence of matter is 0  
 $\delta \theta^{\mu}$

becomes:

$$-\frac{1}{2} H_{\mu\nu\rho} \wedge \Omega^{\nu\rho} = 8\pi G * T_{\mu}$$

Exercise: add the cosmological constant.

Remark:

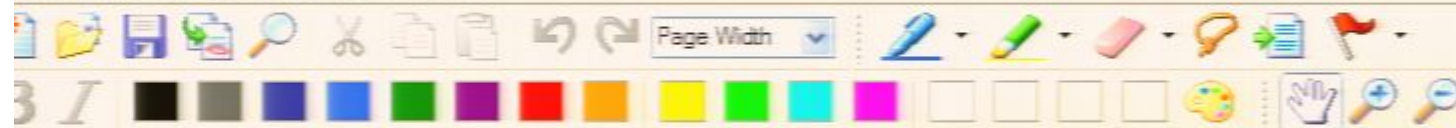
The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys

$$*G_{\mu} = -\frac{1}{2} H_{\mu\nu\rho} \wedge \Omega^{\nu\rho}$$

$\Rightarrow$

$$G_{\mu} = 8\pi G T_{\mu}$$

Proof of the main proposition:



becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.

Remark: The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys

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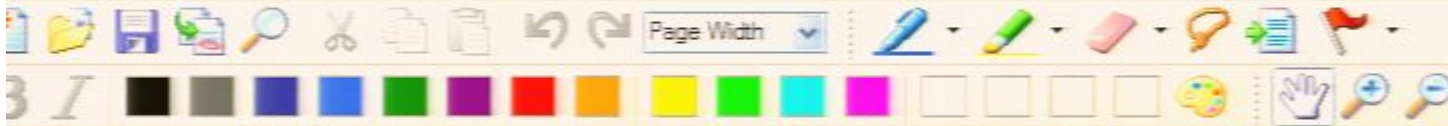
$\Rightarrow$

$$G_{\mu} = 8\pi G T_{\mu}$$

(it is a  $(0,1)$  tensor-valued 1-form)

Proof of the main proposition:

$$\delta(*R) = (\delta\theta^{\mu}) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$



becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.

Remark: The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys  
 $*G_{\mu} = -\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma}$

(it is a (1,1) tensor-valued 1-form)

$\Rightarrow$

$$G_{\mu} = 8\pi G T_{\mu}$$

Proof of the main proposition:

$$S(*R) = (S\theta^{\mu}) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

$$\frac{\delta(S_{\text{grav}} + S_{\text{matter}})}{\delta\theta^r} = 0$$

becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.

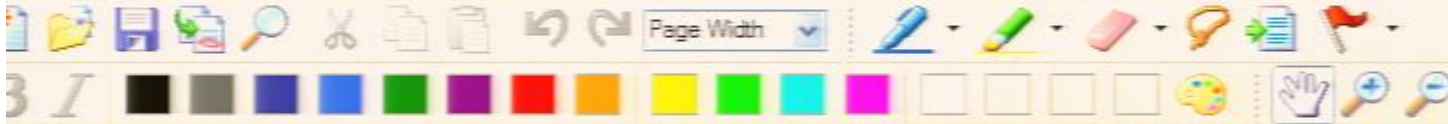
Remark: The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys

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Proof of the main proposition:



$$\frac{\delta \theta^\mu}{\delta \theta^\nu} = 0$$

becomes:

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Exercise: add the cosmological constant.

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The Einstein form  $G_\mu := G_{\mu\nu} \theta^\nu$  obeys

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$\Rightarrow$

$$G_\mu = 8\pi G T_\mu$$

(it is a (0,1) tensor-valued 1-form)

Proof of the main proposition:



Exercise: add the cosmological constant.

Remark: The Einstein form  $G_\mu := G_{\mu\nu} \theta^\nu$  obeys  
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Proof of the main proposition:

$$S(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

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$$G_{\mu} = 8\pi G T_{\mu}$$

Proof of the main proposition:

$$\delta(*R) = (\delta\theta^{\mu}) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$





becomes:

$$-\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} = 8\pi G *T_{\mu}$$

Exercise: add the cosmological constant.

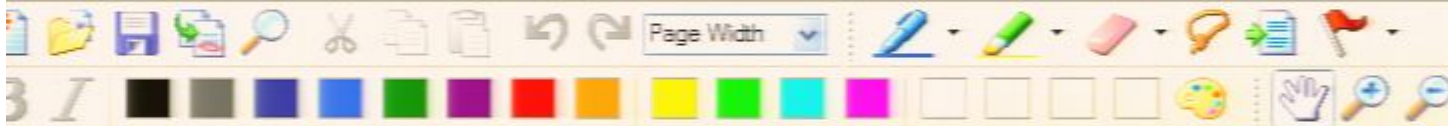
Remark: The Einstein form  $G_{\mu} := G_{\mu\nu} \theta^{\nu}$  obeys  $*G_{\mu} = -\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma}$  (it is a (0,1) tensor-valued 1-form)

$\Rightarrow$

$$G_{\mu} = 8\pi G T_{\mu}$$

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$$*G_\mu = -\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma}$$

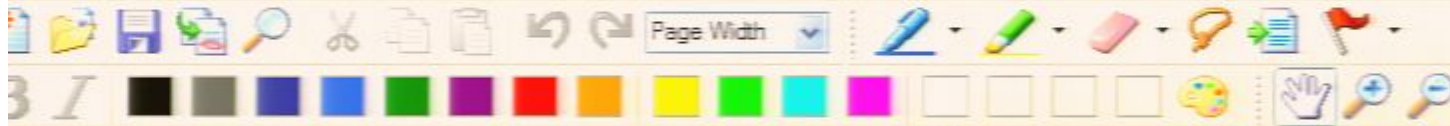
$\Rightarrow$   $G_\mu = 8\pi G T_\mu$

Proof of the main proposition:

$$\delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + d(\text{something})$$

Indeed:

$$\delta(*R) = (\delta H_{\mu\nu}) \wedge \Omega^{\mu\nu} + H_{\mu\nu} \wedge \delta\Omega^{\mu\nu}$$



$$*G_\mu = -\frac{1}{2} H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma}$$

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Consider the first term: 

$$\delta H_{\mu\nu} = \delta \overbrace{\frac{1}{2} \sqrt{g}}^{\text{const.}} \epsilon_{\mu\nu\sigma\alpha} \theta^\sigma \wedge \theta^\alpha$$



$\Rightarrow$

$$G_{\mu} = 8\pi G T_{\mu}$$

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$$= (\delta\theta^{\mu}) \wedge H_{\mu\nu\sigma}$$

by definition of  $H_{\mu\nu\sigma}$  above:

$$H_{\mu\nu\sigma} := \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\delta} \theta^{\delta}$$



## Proof of the main proposition:

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⇒



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$$\begin{aligned} \delta H_{\mu\nu} &= \delta \overset{\text{const.}}{\frac{1}{2} \sqrt{|g|}} \epsilon_{\mu\nu\sigma\delta} \theta^\sigma \wedge \theta^\delta \\ &= (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \end{aligned}$$

by definition of  $H_{\mu\nu\sigma}$  above:  
 $H_{\mu\nu\sigma} := \frac{1}{2} \sqrt{|g|} \epsilon_{\mu\nu\sigma\delta} \theta^\delta$

$$\Rightarrow \delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \underbrace{H_{\mu\nu} \wedge \delta\Omega^{\mu\nu}}_{\text{examine this term}}$$



Consider the first term:

$$\delta H_{\mu\nu} = \delta \overset{\text{const.}}{\frac{1}{2} \sqrt{g}} \epsilon_{\mu\nu\sigma\tau} \theta^\sigma \wedge \theta^\tau$$

$$= (\delta \theta^\mu) \wedge H_{\mu\nu\sigma}$$

by definition of  $H_{\mu\nu\sigma}$  above:

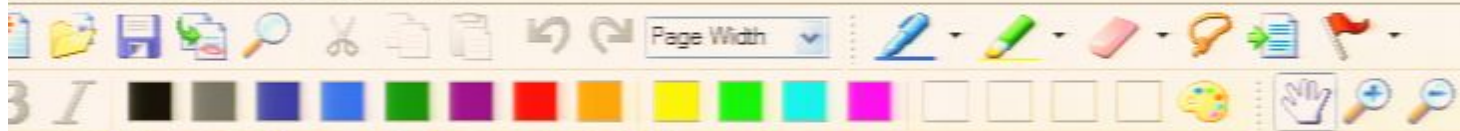
$$H_{\mu\nu\sigma} := \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^\tau$$

$$\Rightarrow \delta(*R) = (\delta \theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \underbrace{H_{\mu\nu} \wedge \delta \Omega^{\mu\nu}}_{\text{examine this term:}}$$

$$\delta \Omega^{\mu\nu} \overset{\text{2nd structure equation}}{=} \delta (d\omega^{\mu\nu} + \omega^\mu{}_\sigma \wedge \omega^{\sigma\nu})$$

$$= d\delta\omega^{\mu\nu} + \delta\omega^\mu{}_\sigma \wedge \omega^{\sigma\nu} + \omega^\mu{}_\sigma \wedge \delta\omega^{\sigma\nu}$$

$$\Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} = d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu}$$



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$$\delta H_{\mu\nu} = \delta \overset{\text{const.}}{\frac{1}{2} \sqrt{g}} \epsilon_{\mu\nu\sigma\tau} \theta^\sigma \wedge \theta^\tau$$

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$$H_{\mu\nu\sigma} := \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\tau} \theta^\tau$$

⇒

$$\delta(*R) = (\delta \theta^\mu) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\nu\sigma} + \underbrace{H_{\mu\nu\sigma} \wedge \delta \Omega^{\mu\nu}}_{\text{examine this term:}}$$

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$$\Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} = d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu}$$





2nd structure equation

$$\delta \Omega^{\mu\nu} = \delta (d\omega^{\mu\nu} + \omega^{\mu}_{\rho} \wedge \omega^{\rho\nu})$$

$$= d\delta\omega^{\mu\nu} + \delta\omega^{\mu}_{\rho} \wedge \omega^{\rho\nu} + \omega^{\mu}_{\rho} \wedge \delta\omega^{\rho\nu}$$

$$\begin{aligned} \Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} &= d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu} \\ &\quad + H_{\mu\nu} \wedge \delta \omega^{\mu}_{\rho} \wedge \omega^{\rho\nu} + H_{\mu\nu} \wedge \omega^{\mu}_{\rho} \wedge \delta \omega^{\rho\nu} \\ &\stackrel{\text{by Def. of } D}{=} (\delta \omega^{\mu\nu}) \wedge D H_{\mu\nu} + d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) \end{aligned}$$

recall:  $= 0$   
by Prop. above.

$\Rightarrow$  Indeed:

$$\delta(*R) = (\delta\theta^{\mu}) \wedge H_{\mu\nu\rho} \wedge \Omega^{\nu\rho} + d(H_{\mu\nu} \wedge \delta\omega^{\mu\nu}) \quad \checkmark$$

$\Rightarrow$  The Einstein eqn. indeed follows from local Lorentz invariance



$$\delta H_{\mu\nu} = \delta \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\delta} \Theta^{\sigma} \wedge \Theta^{\delta}$$

$$= (\delta \Theta^{\sigma}) \wedge H_{\mu\nu\sigma}$$

by definition of  $H_{\mu\nu\sigma}$  above:

$$H_{\mu\nu\sigma} := \frac{1}{2} \sqrt{g} \epsilon_{\mu\nu\sigma\delta} \Theta^{\delta}$$

$$\Rightarrow \delta(*R) = (\delta \Theta^{\sigma}) \wedge H_{\mu\nu\sigma} \wedge \Omega^{\mu\nu} + H_{\mu\nu} \wedge \delta \Omega^{\mu\nu}$$

examine this term:

$$\delta \Omega^{\mu\nu} = \delta(d\omega^{\mu\nu} + \omega^{\mu}_{\rho} \wedge \omega^{\rho\nu})$$

$$= d\delta\omega^{\mu\nu} + \delta\omega^{\mu}_{\rho} \wedge \omega^{\rho\nu} + \omega^{\mu}_{\rho} \wedge \delta\omega^{\rho\nu}$$

$$\Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} = d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu} + H_{\mu\nu} \wedge \delta \omega^{\mu}_{\rho} \wedge \omega^{\rho\nu} + H_{\mu\nu} \wedge \omega^{\mu}_{\rho} \wedge \delta \omega^{\rho\nu}$$

$$= (\delta \omega^{\mu\nu}) \wedge D H_{\mu\nu} + d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu})$$



2nd structure equation

$$\delta \Omega^{\mu\nu} = \delta (d\omega^{\mu\nu} + \omega^{\mu\rho} \wedge \omega^{\rho\nu})$$

$$= d\delta\omega^{\mu\nu} + \delta\omega^{\mu\rho} \wedge \omega^{\rho\nu} + \omega^{\mu\rho} \wedge \delta\omega^{\rho\nu}$$

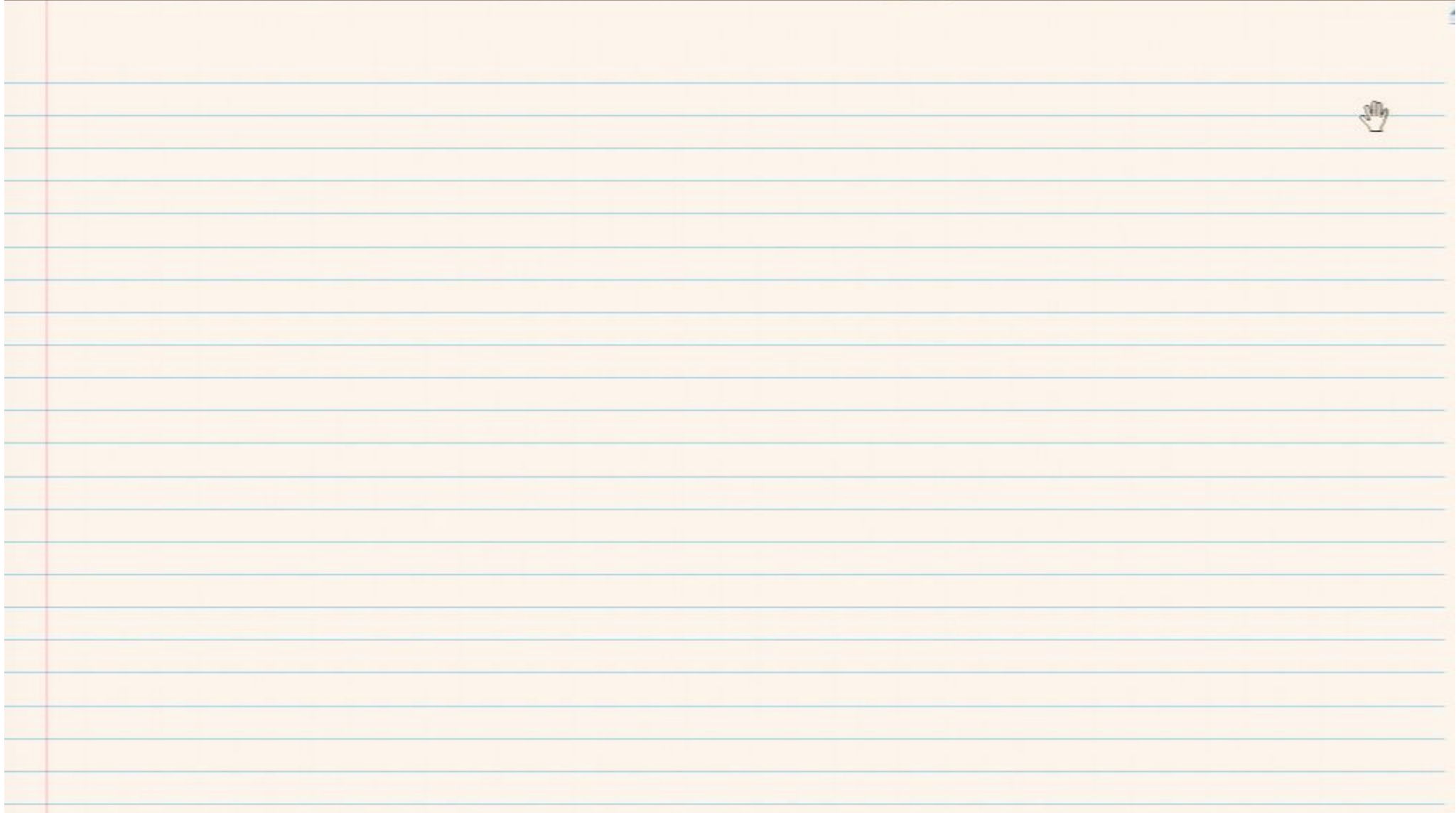
$$\Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} = d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu} + H_{\mu\nu} \wedge \delta \omega^{\mu\rho} \wedge \omega^{\rho\nu} + H_{\mu\nu} \wedge \omega^{\mu\rho} \wedge \delta \omega^{\rho\nu}$$

by Def. of D:

$$= (\delta \omega^{\mu\nu}) \wedge \underbrace{DH_{\mu\nu}}_{\substack{\text{recall: } = 0 \\ \text{by Prop. above.}}} + d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu})$$

⇒ Indeed:

$$\delta(*R) = (\delta\theta^\mu) \wedge H_{\mu\nu\rho} \wedge \Omega^{\nu\rho} + d(H_{\mu\nu} \wedge \delta\omega^{\mu\nu}) \quad \checkmark$$



$$\delta \Omega = \delta (d\omega' + \omega' \wedge \omega')$$

$$= d\delta\omega^{\mu\nu} + \delta\omega^\mu \wedge \omega^{\nu\sigma} + \omega^\mu \wedge \delta\omega^{\sigma\nu}$$

$$\Rightarrow H_{\mu\nu} \wedge \delta\Omega^{\mu\nu} = d(H_{\mu\nu} \wedge \delta\omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta\omega^{\mu\nu} \\ + H_{\mu\nu} \wedge \delta\omega^\mu \wedge \omega^{\nu\sigma} + H_{\mu\nu} \wedge \omega^\mu \wedge \delta\omega^{\sigma\nu} \\ \stackrel{\text{by Def. of } D}{=} (\delta\omega^{\mu\nu}) \wedge \underbrace{DH_{\mu\nu}}_{\text{recall: } = 0 \text{ by Prop. above.}} + d(H_{\mu\nu} \wedge \delta\omega^{\mu\nu})$$

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$$\begin{aligned} \Rightarrow H_{\mu\nu} \wedge \delta \Omega^{\mu\nu} &= d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) - (dH_{\mu\nu}) \wedge \delta \omega^{\mu\nu} \\ &\quad + H_{\mu\nu} \wedge \delta \omega^{\rho\sigma} \wedge \omega^{\mu\nu} + H_{\mu\nu} \wedge \omega^{\rho\sigma} \wedge \delta \omega^{\mu\nu} \\ &\stackrel{\text{by Def. of } D}{=} (\delta \omega^{\mu\nu}) \wedge \underbrace{D H_{\mu\nu}}_{\text{recall: } = 0 \text{ by Prop. above.}} + d(H_{\mu\nu} \wedge \delta \omega^{\mu\nu}) \end{aligned}$$

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