

Title: Relativity - Core (PHYS 604) - Lecture 7

Date: Sep 11, 2009 09:00 AM

URL: <http://pirsa.org/09090062>

Abstract:

Why tensors?

$$\begin{array}{l} \text{x coords} \rightarrow \begin{array}{l} V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta \\ S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta \end{array} \\ \text{y coords} \end{array}$$

- geometry/physics indep of coords



Why tensors?

x coord's \rightarrow

$$V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta$$
$$S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta$$

\rightarrow

- geometry/physics indep of coord

\rightarrow coords important to calcula

Why tensors?

x coords $\left\{ \begin{array}{l} V^\alpha \\ S_\alpha \end{array} \right.$

$$V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta$$
$$S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta$$

- geometry/physics indep of coord

→ coords important to calculate

Eg given a worldline - $x^\alpha(\tau)$ →
might also calculate $\frac{d^2 x^\alpha}{d\tau^2}$

$v^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} v^\beta$
 $s_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} s_\beta$

x coords $\swarrow \searrow$
 v^α
 s_α

v^β
 s_β
 y coords



physics indep of coords

important to calculate

a worldline - $x^\alpha(\tau) \rightarrow u^\alpha = \frac{dx^\alpha}{d\tau}$

might also calculate $\frac{d^2 x^\alpha}{d\tau^2} =$

$v^{\alpha} = \frac{dx^{\alpha}}{d\tau}$

$v^{\hat{\beta}} = \frac{dy^{\hat{\beta}}}{d\tau}$

$s_{\alpha} = \frac{\partial y^{\hat{\beta}}}{\partial x^{\alpha}}$

x coords \rightarrow v^{α} \leftarrow s_{α}

\hat{y} coords \rightarrow $v^{\hat{\beta}}$ \leftarrow $s_{\hat{\beta}}$



physics indep of coords

important to calculate

world line - $x^{\alpha}(\tau) \rightarrow u^{\alpha} = \frac{dx^{\alpha}}{d\tau}$

also calculate $\frac{d^2 x^{\alpha}}{d\tau^2} = \Gamma^{\alpha}_{\beta\gamma} u^{\beta} u^{\gamma}$

v^{α} ?
 x coords \rightarrow $v^{\alpha} = \frac{\partial x^{\alpha}}{\partial y^{\beta}}$ v^{β} (*)
 s_{α} \leftarrow $s_{\hat{\alpha}} = \frac{\partial y^{\beta}}{\partial x^{\alpha}}$ y coords



physics indep of coords
 important to calculate

world line - $x^{\alpha}(\tau) \rightarrow u^{\alpha} = \frac{dx^{\alpha}}{d\tau}$

what also calculate $\frac{d^2 x^{\alpha}}{d\tau^2} = v^{\alpha} \leftarrow$ this v^{α} doesn't satisfy (*)

tensors?

$$\begin{array}{l} \text{x coords} \swarrow \searrow \\ V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta \quad \text{y coords} \\ S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta \end{array}$$

geometry / physics indep of coords

coords important to calculate

given a worldline - $x^\alpha(\tau) \rightarrow u^\alpha = \frac{dx^\alpha}{d\tau}$

might also calculate

$$\frac{d^2 x^\alpha}{d\tau^2} = V^\alpha \leftarrow \text{this satisfies}$$

calculate $\underline{u} \cdot \underline{v}$

tensors?

$$V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta$$

$$S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta$$

x coords \rightarrow V^α \leftarrow y coords

S_α \leftarrow S_β

V^β \leftarrow S_β (*)

geometry / physics indep of coords

coords important to calculate

given a worldline - $x^\alpha(\tau) \rightarrow u^\alpha = \frac{dx^\alpha}{d\tau}$

might also calculate

$$\frac{d^2 x^\alpha}{d\tau^2} = V^\alpha \leftarrow \text{this is sat}$$

calculate $\underline{u} \cdot \underline{V}$

tensors?

$$V^\alpha = \frac{\partial x^\alpha}{\partial y^\beta} V^\beta \quad (*)$$

$$S_\alpha = \frac{\partial y^\beta}{\partial x^\alpha} S_\beta$$

x coords \swarrow \searrow y coords

geometry / physics indep of coords

coords important to calculate

given a worldline - $x^\alpha(\tau) \rightarrow u^\alpha = \frac{dx^\alpha}{d\tau}$

might also calculate $\frac{d^2 x^\alpha}{d\tau^2} = a^\alpha \leftarrow$ this is sat

calculate $\underline{u}' \cdot \underline{v} = f(\tau) \leftarrow$ x coords

$\underline{u}' \cdot \underline{v} = g(\tau) \leftarrow$ y coords

$f(\tau) \neq g(\tau)$



metric

$$g_{\alpha\beta} = \begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} t \\ r \\ \theta \\ \phi \end{matrix} & \begin{matrix} -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & 0 & 0 & 0 \\ 0 & \frac{1}{1 - \frac{2GM}{c^2 r}} & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ 0 & 0 & 0 & r^2 \sin^2 \theta \end{matrix} \end{matrix}$$

Hence V^α is not useful in characterizing worldline

metric

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Hence V^α is not useful in characterizing worldline

$$U^\alpha = \frac{dx^\alpha}{d\tau} + \Gamma^\alpha_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \leftarrow \text{this is a 4 vector}$$

$$\underline{U} \cdot \underline{U} = 0$$

metric

$$g_{\alpha\beta} = \begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} t \\ r \\ \theta \\ \phi \end{matrix} & \begin{matrix} -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & 0 & 0 & 0 \\ 0 & \frac{1}{1 - \frac{2GM}{c^2 r}} & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ 0 & 0 & 0 & r^2 \sin^2 \theta \end{matrix} \end{matrix}$$

Hence V^α is not useful in characterizing worldline

$$a^\alpha = \frac{dV^\alpha}{d\tau} + \Gamma^\alpha_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \leftarrow \text{this is a 4 vector}$$

so everyone agrees $\underline{u} \cdot \underline{a} = 0$

Schwarzschild Geometry

$$ds^2 = - \left(1 - 2 \frac{GM}{c^2 r} \right) (cdt)^2 + \frac{dr^2}{1 - \frac{2GM}{c^2 r}} + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

simplicity of invariant/scalar objects
makes transformations easy

$$\text{eg } s_{\alpha} dx^{\alpha}$$

Schwarzschild Geometry

$$ds^2 = - \left(1 - 2 \frac{GM}{c^2 r} \right) (cdt)^2 + \frac{dr^2}{1 - \frac{2GM}{c^2 r}} + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

simplicity of invariant/scalar objects
makes transformations easy

eg $\sum dx^\mu dx^\mu$ rather than $\circledast\ast$

Schwarzschild Geometry

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- solution of "Einstein's eq's"
describing geometry outside of a
spherical star

metric

$$g_{\alpha\beta} = \begin{matrix} & + & r & \theta & \phi \\ + & -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & & & \\ r & & 1 & & \\ \theta & & & r^2 & \\ \phi & & & & r^2 \sin^2 \theta \end{matrix}$$

metric

$$g_{\alpha\beta} = \begin{matrix} & + & r & \theta & \phi \\ + & -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & & & \\ r & & \frac{1}{1 - \frac{2GM}{c^2 r}} & & \\ \theta & & & r^2 & \\ \phi & & & & r^2 \sin^2 \theta \end{matrix}$$

Comments

①

metric

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Comments

① metric is static - independent of t

metric

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Comments

① metric is static - independent of t

Killing vector $\xi^\alpha = \xi^\alpha_{,t}$, or $\xi = (1, 0, 0, 0)$

Schwarzschild Geometry

$$\rightarrow \sum_{\mu} \dot{x}^{\mu} = \text{const for geodesics}$$

(2)

Schwarzschild Geometry

→ $\sum_{\mu} \dot{x}^{\mu} = \text{const}$ for geodesics

② metric independent of ϕ

→ $\eta_{\alpha\beta} = (0, 0, 0, 1)$ or $\eta^{\alpha\beta} = \delta^{\alpha}_{\beta}$

Schwarzschild Geometry

→ $\sum_{\tilde{\mu}} \tilde{u}^{\tilde{\mu}} = \text{const}$ for geodesics

② metric independent of ϕ

→ $\tilde{\eta} = (0, 0, 0, 1)$ or $\tilde{\eta}^{\tilde{\mu}} = \delta_{\tilde{\mu}}^4$

for fixed (t, r) , geometry of surfaces
described by
 $d\sigma^2$

Schwarzschild Geometry

→ $\sum_{\tilde{\alpha}} \cdot \tilde{u} = \text{const}$ for geodesics

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for fixed (t, r) , geometry of surfaces described by

$$d\sigma^2 = r^2 (d\theta^2 + \sin^2\theta d\phi^2)$$

→ same as spherical "polar coord's"

→ geometry is spherically symmetric

→ so actually would have symmetries under
basis of three independent Killing vectors
(η is one of these)

Schwarzschild Geometry

③ at $r \rightarrow \infty$

$$ds^2 \sim -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

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$$ds^2 \sim -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

→ Minkowski space (which is flat)

→ asymptotically flat

④

Schwarzschild Geometry

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$$ds^2 \sim -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

→ Minkowski space (which is flat)

→ a symmetrically flat

expanding in $1/c^2$ for large c (NR limit)

④

$$ds^2 \approx -\left(c^2 + 2\left(-\frac{GM}{r}\right)\right) dt^2 +$$

Schwarzschild Geometry

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$$ds^2 \approx -\left(c^2 + 2\left(\frac{-GM}{r}\right)\right) dt^2 + \underbrace{dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)}_{(dx^i)^2}$$

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$$ds^2 \approx -\left(c^2 + 2 \left(\frac{-GM}{r} \right) \right) dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2) + (dx^i)^2$$

→ recover the N.R geometry that we discussed earlier for $\frac{\Phi}{c^2} \ll 1$ and $\frac{v^2}{c^2} \ll 1$

Schwarzschild Geometry

③ at $r \rightarrow \infty$

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$$ds^2 \approx -\left(c^2 + 2\left(\frac{-GM}{r}\right)\right) dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

Φ

$(dx^i)^2$

→ recover the N.R geometry that we discussed earlier for $\Phi/c^2 \ll 1$ and $v^2/c^2 \ll 1$ for a spherical mass $M \leftarrow M$ really is mass

metric

$$g_{\alpha\beta} = \begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} t \\ r \\ \theta \\ \phi \end{matrix} & \begin{matrix} -c^2 \left(1 - \frac{2GM}{c^2 r}\right) \\ 0 \\ 0 \\ 0 \end{matrix} & \begin{matrix} 0 \\ \frac{1}{1 - \frac{2GM}{c^2 r}} \\ 0 \\ 0 \end{matrix} & \begin{matrix} 0 \\ 0 \\ r^2 \\ r^2 \sin^2 \theta \end{matrix} & \begin{matrix} 0 \\ 0 \\ 0 \\ 0 \end{matrix} \end{matrix}$$

④ something interesting happens at $r = r_s$

metric

$$g_{\alpha\beta} = \begin{pmatrix} -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & 0 & 0 & 0 \\ 0 & r^2 & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ 0 & 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

④

Something interesting happens at $r=0$ and $r = 2GM/c^2$

metric

$$g_{\alpha\beta} = \begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} t \\ r \\ \theta \\ \phi \end{matrix} & -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & & & \\ & & \frac{1}{1 - \frac{2GM}{c^2 r}} & & \\ & & & r^2 & \\ & & & & r^2 \sin^2 \theta \end{matrix}$$

(4)

Something interesting happens at $r=0$,
 and $r = 2GM/c^2 \leftarrow$ return to this later

$$ds^2 \approx -c^2 dt^2 + dr^2$$

→ Minkowski space

→ asymptotically expanding in $1/c^2$ for large

$$ds^2 \approx -\left(c^2 + 2\left(\frac{-GM}{r}\right)\right) dt^2$$

$\stackrel{\text{}}{=} \Phi$

(4)

$$\frac{GM}{c^2 r}$$

→ recover the N.R. discussed earlier for a spherical mass

at $r \rightarrow \infty$

$$ds^2 \sim -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

→ Minkowski space (which is flat)

→ a symmetrically flat

expanding in $1/c^2$ for large c (NR limit)

$$ds^2 \approx - \left(c^2 + 2 \left(\frac{-GM}{r} \right) \right) dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2) \quad (4)$$

$$\approx dt^2 \left(- \left(c^2 + 2\Phi \right) + \frac{dr^2}{dt^2} + r^2 \left(\frac{d\theta^2}{dt^2} + \sin^2 \theta \frac{d\phi^2}{dt^2} \right) \right)$$

③ at $r \rightarrow \infty$

$$ds^2 \sim -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

→ Minkowski space (which is flat)

→ a symmetrically flat expanding in $1/c^2$ for large c (NR limit)

$$ds^2 \approx -\left(c^2 + 2\left(\frac{GM}{r}\right)\right) dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

Φ/c^2

$$\approx c^2 dt^2 \left(-\left(\frac{\Phi}{c^2} + 2\frac{\Phi}{c^2}\right) + \frac{1}{c^2} \frac{dr^2}{dt^2} + \frac{1}{c^2} r^2 \left(\frac{d\theta^2}{dt^2} + \sin^2 \theta \frac{d\phi^2}{dt^2}\right) \right)$$

③ at $r \rightarrow \infty$

$$ds^2 \approx -c^2 dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

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→ a Symptotically flat

expanding in $1/c^2$ for large c (NR limit)

$$ds^2 \approx - \left(c^2 + 2 \left(\frac{-GM}{r} \right) \right) dt^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

$\frac{\Phi}{c^2} \ll 1$
 $\sqrt{1 - \frac{2\Phi}{c^2}}$

$$\approx c^2 dt^2 \left(- \left(\frac{2\Phi}{c^2} + 2 \frac{\Phi}{c^2} \right) + \frac{1}{c^2} \left(\frac{dr}{dt} \right)^2 + r^2 \left(\frac{d\theta}{dt} \right)^2 + 2 \frac{1}{c^2} \frac{dr}{dt} \frac{d\theta}{dt} \right)$$

metric

$$g_{\alpha\beta} = \begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} t \\ r \\ \theta \\ \phi \end{matrix} & \begin{bmatrix} -c^2 \left(1 - \frac{2GM}{c^2 r}\right) & 0 & 0 & 0 \\ 0 & \frac{1}{1 - \frac{2GM}{c^2 r}} & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ 0 & 0 & 0 & r^2 \sin^2 \theta \end{bmatrix} & & & \end{matrix}$$

$g_{\alpha\beta} =$
Schwarzschild
coord's

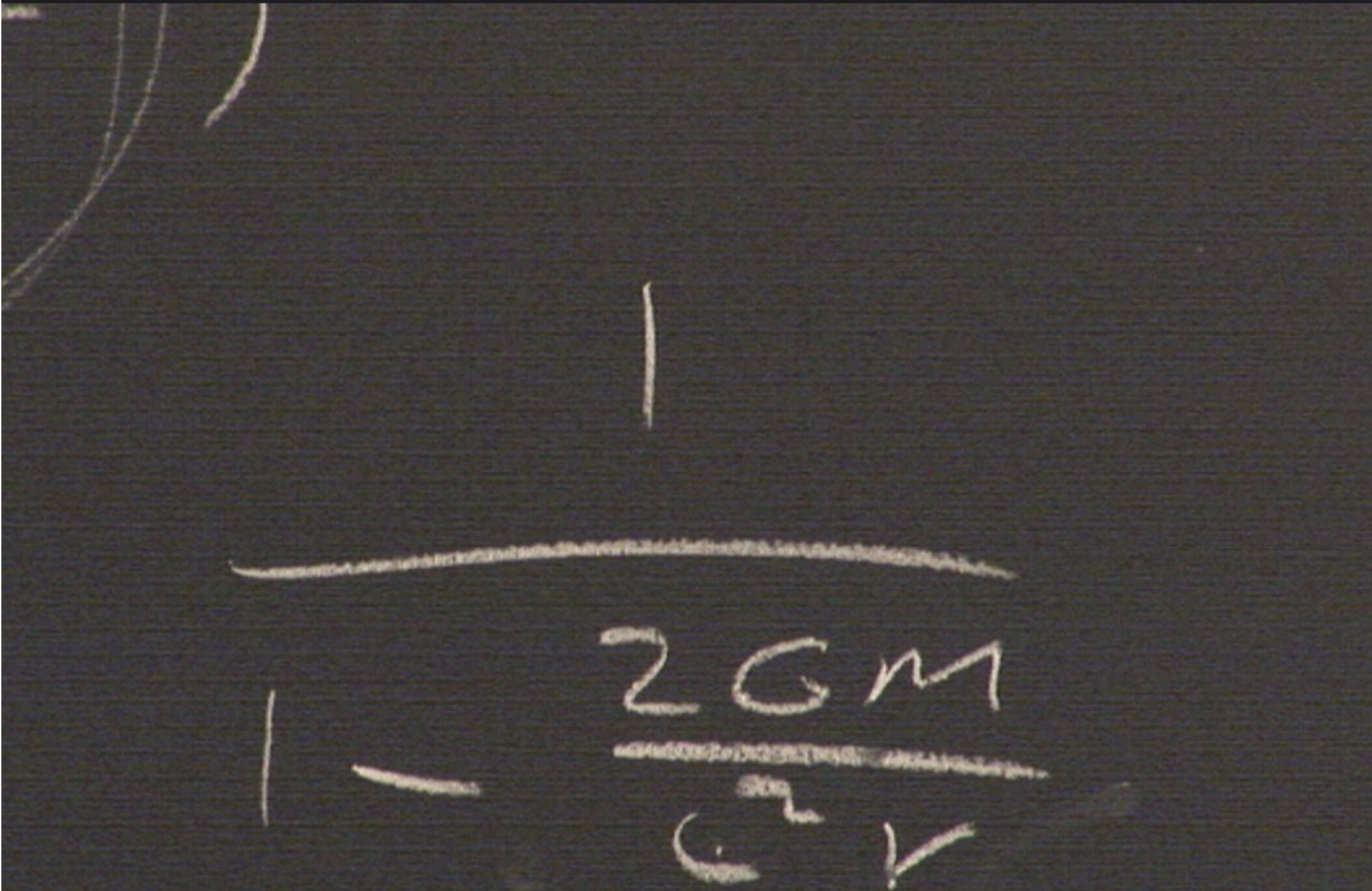
④ something interesting happens at $r=0$
and $r = 2GM/c^2$ ← return to this later

Geometrized Units

- recall in SR, c

Geometrized Units

- recall in SR, c was a conversion constant between standard time and length units
- measure time in length units → $c=1$



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→ measure time in length units → $c=1$

→ similarly in GR find M

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G/c^2 → conversion constant to change mass units (kg)
to length units (metres)

Geometrized Units

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→ if mass measured in length units

Geometrized Units

- recall in SR, c was a conversion constant
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→ measure time in length units → $c=1$

→ similarly in GR find M accompanied by

G/c^2 → conversion constant to change mass units (kg)
to length units (metres)

→ if mass measured in length units → $G/c^2=1$

Schwarzschild Geometry

$$\Rightarrow G = 1, \quad c = 1$$

"geometrized" units

→ a symmetrically flat
expanding in $1/c^2$ for large c (NR limit)

④

$$ds^2 \approx - \left(c^2 + 2 \left(\frac{-GM}{r} \right) \right) dt^2 + \underbrace{dr^2 + r^2 (d\theta^2 + \sin^2\theta d\phi^2)}_{(dx^i)^2}$$

$$\approx c^2 dt^2 \left(- \left(1 + 2 \frac{\Phi}{c^2} \right) + \frac{1}{c^2} \left(\frac{dr}{dt} \right)^2 + \frac{1}{c^2} r^2 \left(\left(\frac{d\theta}{dt} \right)^2 + \dots \right) + 2 \frac{1}{c^2} \frac{dr}{dt} \frac{d\theta}{dt} \right)$$

$\frac{\Phi}{c^2}$
 $\sqrt{1 + \frac{2\Phi}{c^2}}$

metric

$$\begin{array}{c}
 \theta \\
 + \\
 r \\
 \phi
 \end{array}
 \left[
 \begin{array}{cccc}
 & + & r & \theta & \phi \\
 + & - \left(1 - \frac{2GM}{r}\right) & & & \\
 r & & \frac{1}{1 - \frac{2GM}{r}} & & \\
 \theta & & & r^2 & \\
 \phi & & & & r^2 \sin^2 \theta
 \end{array}
 \right]$$

$g_{\alpha\beta}$
 - schwarzschild
 coord's

(4) something interesting happens at $r=0$
 and $r = 2GM/c^2 \leftarrow$ return to this later

metric

$$\begin{matrix} & t & r & \theta & \phi \\ \begin{matrix} + \\ + \\ r \\ \theta \\ \phi \end{matrix} & - \left(1 - \frac{2GM}{r}\right) & & & \\ & & \frac{1}{1 - \frac{2GM}{r}} & & \\ & & & r^2 & \\ & & & & r^2 \sin^2 \theta \end{matrix}$$

$g_{\alpha\beta} =$
Schwarzschild
coords
→ in geom.
units

④ Something interesting happens at $r=0$,
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Schwarzschild Geometry

$$\Rightarrow G = 1, \quad c = 1$$

"geometrized" units



Schwarzschild Geometry

$$\Rightarrow G = 1, \quad c = 1$$

"geometrized" units

particle motion

$$I = m \int d\lambda \underbrace{g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}}_{\text{L}}$$

hwarz schild Geometry

$$\Rightarrow G = 1, \quad c = 1$$

"geometrized" units

particle motion

$$L = m \int dx \quad \underbrace{g_{\alpha\beta} \frac{dx^\alpha}{dx} \frac{dx^\beta}{dx}}_{\text{K.P.}}$$

$$\tilde{L} = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{d\tau}\right)^2 + \frac{\left(\frac{dr}{d\tau}\right)^2}{1 - \frac{2m}{r}} + r^2 \left(\frac{d\theta}{d\tau}\right)^2 + \sin^2\theta \left(\frac{d\phi}{d\tau}\right)^2$$

Schwarzschild Geometry

$$\Rightarrow G = 1, \quad c = 1$$

"geometrized" units

particle motion

$$L = m \int d\lambda \underbrace{g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}}_{\tilde{L}}$$

$$\tilde{L} = -\left(1 - \frac{2m}{r}\right) \left(\frac{dt}{d\lambda}\right)^2 + \frac{(dr/d\lambda)^2}{1 - \frac{2m}{r}} + r^2 \left(\left(\frac{d\theta}{d\lambda}\right)^2 + \sin^2\theta \left(\frac{d\phi}{d\lambda}\right)^2 \right)$$

→ first look for conserved quantities

Σ Killing vectors:

$$\sum_{\alpha}^{\leftarrow} = \sum_{+}^{\leftarrow} \longrightarrow \sum_{\sim} \cdot \omega_{\sim} = \text{const}$$

→ first look for conserved quantities

2 Killing vectors:

$$\underline{\underline{\Sigma}}^\alpha = \underline{\underline{S}}_+$$



$$\underline{\underline{\Sigma}} \cdot \underline{\underline{U}} = \text{const}$$

$$g_{\mu\nu} \frac{dx^\mu}{d\lambda} = \text{const}$$

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{\mu}^{\alpha} = \delta_{+}^{\alpha} \longrightarrow \sum_{\mu} \cdot \underline{u} = \text{const}$$

$$g_{\mu\nu} \frac{dx^{\mu}}{d\lambda} = \text{const}$$

as a constraint, impose

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{-}^{\alpha} = \sum_{+}^{\alpha} \longrightarrow \sum_{-} \cdot \underline{u} = \text{const}$$

$$g_{++} \frac{dt}{d\lambda} = \text{const}$$

as a constraint, impose

$$g_{\alpha\beta} \frac{dx^{\alpha}}{d\lambda} \frac{dx^{\beta}}{d\lambda} = -1$$

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{\mu} \dot{x}^{\mu} = \dot{s}^{\mu} \longrightarrow \sum_{\mu} \dot{x}^{\mu} \cdot \eta_{\mu} = \text{const}$$

$$g_{\mu\nu} \frac{dx^{\mu}}{d\lambda} = \text{const}$$

as a constraint, impose

$$\Rightarrow \lambda = \tau$$

$$g_{\alpha\beta} \frac{dx^{\alpha}}{d\lambda} \frac{dx^{\beta}}{d\lambda} = -1$$

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{\mu} \dot{x}^{\mu} = \dot{S}_+^{\mu} \longrightarrow \sum_{\mu} \dot{x}^{\mu} \cdot \underline{u}_{\mu} = \text{const}$$

$$g_{tt} \frac{dt}{d\tau} = \text{const}$$

$$-\left(1 - \frac{2M}{r}\right) \frac{dt}{d\tau} =$$

as a constraint, impose

$$\Rightarrow \lambda = \tau$$

$$g_{\alpha\beta} \frac{dx^{\alpha}}{d\lambda} \frac{dx^{\beta}}{d\lambda} = -1$$

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{\mu} \dot{x}^{\mu} = \dot{x}^{\mu} \rightarrow \sum_{\mu} \dot{x}^{\mu} \cdot \eta_{\mu} = \text{const}$$

$$g_{tt} \frac{dt}{d\tau} = \text{const}$$

$$-\left(1 - \frac{2m}{r}\right) \frac{dt}{d\tau} = -e$$

as a constraint, impose

$$\Rightarrow \lambda = \tau$$

$$g_{\alpha\beta} \frac{dx^{\alpha}}{d\lambda} \frac{dx^{\beta}}{d\lambda} = -1$$

$$\frac{dt}{dr} = \frac{r}{1 - \frac{2m}{r}}$$

particle motion

$$L = m \int dr \left(g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda} \right)$$

$$\tilde{L} = - \left(1 - \frac{2m}{r} \right) \left(\frac{dt}{d\lambda} \right)^2 + \frac{(dr/d\lambda)^2}{1 - \frac{2m}{r}} + r^2 \left(\left(\frac{d\theta}{d\lambda} \right)^2 + \dots \right)$$

$$\frac{dt}{d\tau} = \frac{e}{1 - \frac{2m}{r}} \quad r \rightarrow \infty \quad e = \text{energy/mass}$$

particle motion

$$I = m \int d\lambda \left(g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda} \right)$$

$$\tilde{L} = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{d\lambda}\right)^2 + \frac{(dr/d\lambda)^2}{1 - \frac{2m}{r}} + r^2 \left(\left(\frac{d\theta}{d\lambda}\right)^2 + \sin^2\theta \right)$$

$$\frac{dt}{dr} = \frac{1}{1 - \frac{2M}{r}}$$

$r \rightarrow \infty$

$e = \frac{\text{relativistic energy}}{\text{mass}}$

$$z^x = s^x$$

$$\rightarrow \tilde{u} \cdot \tilde{k} = \text{const}$$

$$g_{tt} \frac{dt}{d\tau} = \text{const}$$

$$r^2 \sin^2 \theta \frac{d\phi}{d\tau} = \text{const}$$

$$\frac{dt}{dr} = \frac{e}{1 - \frac{2M}{r}}$$

$r \rightarrow \infty$

$e = \frac{\text{relativistic energy}}{\text{mass}}$

$$\vec{h} = \vec{S} \times \vec{L}$$

$$\vec{h} \cdot \vec{L} = \text{const}$$

$$g_{\phi\phi} \frac{d\phi}{dr} = \text{const}$$

$$r^2 \sin^2 \theta \frac{d\phi}{dr} = l$$

$$\frac{d\phi}{dr} = \frac{l}{r^2 \sin^2 \theta}$$

$\leftarrow \frac{\text{angular momentum}}{\text{mass}}$

→ first look for conserved quantities

2 Killing vectors:

$$\sum_{\mu} \dot{x}^{\mu} \rightarrow \sum_{\mu} \dot{x}^{\mu} \eta_{\mu} = \text{const}$$

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$$\frac{dt}{d\tau} = \frac{e}{1 - \frac{2M}{r}} \quad \xrightarrow{r \rightarrow \infty} \quad e = \frac{\text{relativistic energy}}{\text{mass}}$$

$$\dot{\phi} = \dot{\phi} \quad \rightarrow \quad \dot{\phi} \cdot r = \text{const}$$

$$g_{\phi\phi} \frac{d\phi}{d\tau} = \text{const}$$

$$r^2 \sin^2 \theta \frac{d\phi}{d\tau} = l$$

$$\frac{d\phi}{d\tau} = \frac{l}{r^2 \sin^2 \theta}$$

← angular momentum / mass

- need one more eq; look at geodesic eq for \ominus

$$\vec{S}_0 \rightarrow \frac{d \vec{S}}{dt} = \frac{\vec{S}}{S_0}$$

$$\delta \theta \rightarrow \frac{d \tilde{L}}{d \dot{\theta}} = \frac{\tilde{L}}{\dot{\theta}}$$

$$\frac{d}{dt}(2r^2 \dot{\theta}) = 2 \sin \theta \cos \theta \dot{\phi}^2$$

$$\delta \theta \rightarrow \frac{d \tilde{S}_L}{d \tilde{\theta}} = \frac{\tilde{S}_L}{\delta \theta}$$

$$\frac{d}{dt}(2r^2 \dot{\theta}) = 2r^2 \sin \theta \cos \theta \dot{\phi}^2$$

$$\delta \Theta \rightarrow \frac{d}{dr} \frac{\delta L}{\delta \dot{\Theta}} = \frac{\delta L}{\delta \Theta}$$

$$\frac{d}{dr}(2r^2 \dot{\Theta}) = 2r^2 \sin \Theta \cos \Theta \dot{\Theta}^2$$

a consistent solution is $\Theta = \pi/2$

$$\delta \Theta \rightarrow \frac{d}{dt} \frac{\delta \tilde{L}}{\delta \dot{\Theta}} = \frac{\delta \tilde{L}}{\delta \Theta}$$

$$\frac{d}{dt}(2r^2 \dot{\Theta}) = 2r^2 \sin \Theta \cos \Theta \dot{\phi}^2$$

a consistent solution is $\Theta = \pi/2$

$$\delta \Theta \rightarrow \frac{d}{dr} \frac{\delta L}{\delta \dot{\Theta}} = \frac{\delta L}{\delta \Theta}$$

$$\frac{d}{dr}(2r^2 \dot{\Theta}) = 2r^2 \sin \Theta \cos \Theta \dot{\phi}^2$$

a consistent solution is $\Theta = \pi/2$

→ but using spherical symmetry to orient coord's can always set any orbit to be in plane $\Theta = \pi/2$
 (orbits were planar)

$$\frac{dr}{dz}$$

eq

from

$$\underline{u} \cdot \tilde{\underline{u}} = -1$$

$\frac{dr}{d\tau}$ eq from $u_{\tilde{t}} \cdot \tilde{u} = -1$

$$-1 = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{d\tau}\right)^2 + \frac{\dot{r}^2}{1 - \frac{2m}{r}} + r^2 \dot{\phi}^2$$

$\frac{dr}{dt}$ eq from $u_{\tilde{t}} \cdot u_{\tilde{t}} = -1$

$$-1 = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{dt}\right)^2 + \frac{\dot{r}^2}{1 - \frac{2m}{r}} + r^2 \dot{\phi}^2$$

$$= - \frac{e^2}{1 - \frac{2m}{r}} + \frac{r^2}{1 - \frac{2m}{r}} + \frac{l^2}{r^2}$$

$\frac{dr}{dz}$ eq from $\underline{u} \cdot \underline{\dot{u}} = -1$

$$-1 = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{dz}\right)^2 + \frac{\dot{r}^2}{1 - \frac{2m}{r}} + r^2 \dot{\phi}^2$$
$$= - \frac{e^2}{1 - \frac{2m}{r}} + \frac{r^2}{1 - \frac{2m}{r}} + \frac{e^2}{r^2}$$

with some algebra,

$$\frac{e^2 - 1}{2}$$

$\frac{dr}{dz}$ eq from $\underline{u} \cdot \underline{\dot{u}} = -1$

$$\begin{aligned} -1 &= - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{dz}\right)^2 + \frac{\dot{r}^2}{1 - \frac{2m}{r}} + r^2 \dot{\phi}^2 \\ &= - \frac{e^2}{1 - \frac{2m}{r}} + \frac{r^2}{1 - \frac{2m}{r}} + \frac{e^2}{r^2} \end{aligned}$$

with some algebra,

$$\frac{e^2 - 1}{2} = \frac{1}{2} \dot{r}^2 + \frac{1}{2} \left[\left(1 - \frac{2m}{r}\right) \left(1 + \frac{e^2}{r^2}\right) - 1 \right]$$

$\frac{dr}{dt}$ eq from $\underline{u} \cdot \underline{\dot{u}} = -1$

$$-1 = - \left(1 - \frac{2m}{r}\right) \left(\frac{dt}{dt}\right)^2 + \frac{\dot{r}^2}{1 - \frac{2m}{r}} + r^2 \dot{\phi}^2$$

$$= - \frac{e^2}{1 - \frac{2m}{r}} + \frac{r^2}{1 - \frac{2m}{r}} + \frac{e^2}{r^2}$$

with some algebra,

$$\frac{e^2 - 1}{2} = \frac{1}{2} \dot{r}^2 + \frac{1}{2} \left[\left(1 - \frac{2m}{r}\right) \left(1 + \frac{e^2}{r^2}\right) - 1 \right]$$

looks like 1-dim classical motion in potential

$$\Sigma = \frac{1}{2} \dot{r}^2 + V(r)$$

effective energy

$$\Sigma = \frac{e^2 - 1}{2}$$

effective potential

$$V(r) =$$

$$\Sigma = \frac{1}{2} \dot{r}^2 + V(r)$$

effective energy

$$\Sigma = \frac{e^2 - 1}{2}$$

effective potential
in Newtonian grav

effective potential

$$V(r) = -\frac{M}{r} + \frac{l^2}{2r^2}$$

$$-\frac{M l^2}{r^3}$$

GR correction

$$\Sigma = \frac{1}{2} \dot{r}^2 + V(r)$$

effective energy

$$\Sigma = \frac{e^2 - 1}{2}$$

effective potential
in Newtonian grav

effective potential

$$V(r) = -\frac{M}{r} + \frac{l^2}{2r^2}$$

$$-\frac{M l^2}{r^3}$$

GR correction

$$\Sigma = \frac{1}{2} \dot{r}^2 + V(r)$$

effective energy

$$\Sigma = \frac{e^2 - 1}{2} \text{ effective pot. in Newtonian gravity}$$

effective potential

$$V(r) = -\frac{M}{r} + \frac{l^2}{2r^2}$$

$$-\frac{Ml^2}{r^3}$$

GR correction

Pract 7-7

show: $\left(\frac{d\phi}{dt}\right)^2 R^3 = \text{const}$ for

same set
of orbit

$$\left(\frac{d\phi}{dt}\right)^2 R^3 = \mathcal{M}(M, r, e, l)$$

Pract 7-7

show: $\left(\frac{d\phi}{dt}\right)^2 R^3 = \text{const}$ for

same set
of orbits

$$\left(\frac{d\phi}{dt}\right)^2 R^3 = \mathcal{M}(M, R, e, l)$$
$$= \mathcal{M}(M)$$

Prob 7-7

show $\left(\frac{d\phi}{dt}\right)^2 R^3 = \text{const}$ for

some set
of or

$$\left(\frac{d\phi}{dt}\right)^2 R^3 = \mathcal{M}(M, R, e, l)$$

$$= \mathcal{M}(M)$$

physics

algebra