

Title: PSI - Relativity (PHYS 604) - 4

Date: Sep 08, 2009 10:30 AM

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Abstract:

$m_G/m_I = 1 \rightarrow$  Equivalence Principle

$\rightarrow$  clocks run at different rates depending on position in grav. field

$\rightarrow$  grav. potential part of geometry

$$ds^2 \approx - (c^2 + 2\Phi(\vec{x})) dt^2 + dx^2 + dy^2 + dz^2$$

considering physical problems where

$$\Phi/c^2 \ll 1 \quad \text{and} \quad v^2/c^2 \ll 1$$

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- we can test this conclusion with exp.  
"gravitational redshift"

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if we think of measuring the frequency  
of an electromagnetic wave:  $\omega$



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if we think of measuring the frequency  
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if we think of measuring the frequency of an electromagnetic wave:  $\omega \propto 1/\Delta\tau$

$$d\tau = \left(1 + \frac{\Phi(r)}{c^2}\right) dt$$

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$$\frac{\omega_2}{\omega_1}$$

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$$\frac{\Delta\omega}{\omega_1} = \frac{\omega_2 - \omega_1}{\omega_1} = \frac{\Phi(x_1) - \Phi(x_2)}{c^2}$$



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$$\frac{\Delta\omega}{\omega_1} = \frac{\omega_2 - \omega_1}{\omega_1} = \frac{\Phi(x_1) - \Phi(x_2)}{c^2} = -gh/c^2$$



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$$d\tau = (1 + \Phi(\vec{x})/c^2) dt$$

$$\frac{d\tau_1}{dt} = (1 + \Phi(\vec{x}_1)/c^2)$$

proper time  
 @  $|\vec{x}| \rightarrow \vec{x}$

$$\frac{(1 + \Phi(\vec{x}_1)/c^2)}{(1 + \Phi(\vec{x}_2)/c^2)} = 1 + \frac{\Phi(\vec{x}_1) - \Phi(\vec{x}_2)}{c^2}$$

$$= \Phi(\vec{x}_1) - \Phi(\vec{x}_2)/c^2 = -gh/c^2$$



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→ best experiments agree to about .02

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$\omega$  decreases  
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 $\Phi(x) \rightarrow x$

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consider particle motion in spacetime geometry.

$$I = \int c$$

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$$I = \int dx$$

consider particle motion in spacetime geometry.

$$I = \int d\lambda \quad m g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}$$

consider particle motion in spacetime geometry

$$I = \int d\lambda \quad m \underset{\uparrow}{g_{\alpha\beta}} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}$$

replace  $g_{\alpha\beta}$  by new "metric"

consider particle motion in spacetime geometry.

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$$= \int d\lambda \quad m \left[ - (c^2 + 2\Phi(\vec{x})) \left( \frac{dt}{d\lambda} \right)^2 + \left( \frac{dx^i}{d\lambda} \right)^2 \right]$$



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eom.  $\frac{d}{d\lambda} \left( \frac{\delta L}{\delta \dot{x}^\alpha} \right) = \frac{\delta L}{\delta x^\alpha}$

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com.  $\frac{d}{d\lambda} \frac{\delta L}{\delta \dot{x}^i} = \frac{\delta L}{\delta x^i}$

given  $\frac{\delta L}{\delta t} = 0 \Rightarrow \frac{d}{d\lambda} \left( c^2 + \Phi(\vec{x}) \frac{dt}{d\lambda} \right) = 0$

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fix. integration const with physical picture  
in mind

- if we think  $|\vec{x}| \rightarrow \infty$ ,  $\vec{\Phi}(\vec{x}) \rightarrow 0$   
we are doing S.R., so clever choice  
is

$$\text{const} = \frac{\vec{E}}{m}$$



fix. integration const with physical picture  
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- if we think  $|\vec{x}| \rightarrow \lambda$ ,  $\Phi(x) \rightarrow 0$   
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const =  $\frac{E}{m}$  ← with this choice  
 $\tau = \lambda$

$$(c^2 + 2\Phi(x)) \frac{dt}{d\lambda} = \frac{E}{m}$$

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$$(c^2 + 2\Phi(x)) \frac{dt}{d\tau} = \frac{E}{m}$$

$$\Rightarrow \frac{dt}{d\tau} = \frac{E}{mc^2} \left(1 - \frac{2\Phi}{c^2}\right)$$

fix. integration const with physical picture  
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SR

$$\frac{dt}{d\tau} = \frac{E}{mc^2} \leftarrow \text{const} = \frac{E}{m} \leftarrow \text{with this choice } \tau = \lambda$$

$$(c^2 + 2\Phi(x)) \frac{dt}{d\tau} = \frac{E}{m}$$

$$\Rightarrow \frac{dt}{d\tau} = \frac{E}{mc^2} \left(1 - 2\Phi/c^2\right)$$

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SR  
 $\frac{dt}{d\tau} = \frac{E}{mc^2}$

$m \frac{cdt}{d\tau} = \frac{E}{c}$

const =  $\frac{E}{m}$  ← with this choice  
 $\tau = \lambda$

$(c^2 + 2\Phi(x)) \frac{dt}{d\tau} = \frac{E}{m}$

$\Rightarrow \frac{dt}{d\tau} \approx \frac{E}{mc^2} (1 - 2\Phi/c^2) \approx 1 + 0()$

fix. integration const with physical picture  
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- if we think  $|\vec{x}| \rightarrow \Delta$ ,  $\vec{\Phi}(x) \rightarrow 0$   
we are doing S.R. , so choice

SR

$$\frac{dt}{dz} = \frac{E}{mc^2}$$

$$m \frac{cdt}{d\tau} = \frac{E}{c}$$

const =  $\frac{E}{m}$

$$(c^2 + 2\vec{\Phi}(x)) \frac{dt}{d\tau} = E$$

$$\Rightarrow \frac{dt}{d\tau} \approx \frac{E}{mc^2}$$

$$1 + O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

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$$\Rightarrow \frac{dt}{d\tau} = \frac{E}{mc^2} (1 - 2\Phi/c^2) \approx 1 + O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

$Sx'$

$I =$

cor

given



$$\delta x' \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) =$$

$$I = \int d\lambda m \left[ - (c^2 + 2\Phi(\vec{x})) \left( \frac{dt}{d\lambda} \right)^2 + \left( \frac{dx^i}{d\lambda} \right)^2 \right]$$

com.  $\frac{d}{d\lambda} \frac{\delta L}{\delta \dot{x}^i} = \frac{\delta L}{\delta x^i}$

given  $\frac{\delta L}{\delta t} = 0 \Rightarrow$

$$\left( c^2 + 2\Phi(\vec{x}) \right) \frac{dt}{d\lambda} = \text{const}$$

$$0 \left( \frac{v^2}{c^2}, \frac{\Phi}{c^2} \right)$$

$$\delta x' \frac{d}{dt} \left( 2m \frac{dx'}{dt} \right) =$$

$$I = \int d\lambda m \left[ - (c^2 + 2\Phi(\vec{x})) \left( \frac{d\lambda}{d\lambda} \right)^2 + \left( \frac{dx^i}{d\lambda} \right)^2 \right]$$

com.  $\frac{d}{d\lambda} \frac{\delta L}{\delta \dot{x}^i} = \frac{\delta L}{\delta x^i}$

given  $\frac{\delta L}{\delta \lambda} = 0 \Rightarrow \left( c^2 + 2\Phi(\vec{x}) \right) \frac{d\lambda}{d\lambda} = \text{const}$

$$+ O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

$$S_{x^i} \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) = m(-) \approx \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{d\tau} \right)^2$$

$$I = \int d\lambda m \left[ - (c^2 + 2\Phi(\vec{x})) \left( \frac{dt}{d\lambda} \right)^2 + \left( \frac{dx^i}{d\lambda} \right)^2 \right]$$

com.  $\frac{d}{d\lambda} \frac{\delta L}{\delta \dot{x}^i} = \frac{\delta L}{\delta x^i}$

given  $\frac{\delta L}{\delta t} = 0 \Rightarrow \left( c^2 + 2\Phi(\vec{x}) \right) \frac{dt}{d\lambda} = \text{const}$

+ O( $\frac{v^2}{c^2}, \frac{\Phi}{c^2}$ )

$$\delta x^i \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) = m(-) \approx \frac{\partial \mathcal{L}}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$I = \int d\lambda \, m \left[ - (c^2 + 2\Phi(\vec{x})) \left( \frac{dt}{d\lambda} \right)^2 + \left( \frac{dx^i}{d\lambda} \right)^2 \right]$$

com.  $\frac{d}{d\lambda} \frac{\delta L}{\delta \dot{x}^a} = \frac{\delta L}{\delta x^a}$

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$$+ O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

$$S_{x^i} \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) = m(-) \neq \frac{\partial \hat{\Phi}}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \hat{\Phi}}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$+ O\left(\frac{v^2}{c^2}, \frac{\phi}{c^2}\right)$$

$$S_{x^i} \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) = m(-) \times \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \Phi}{\partial x^i}$$

$$+ O\left(\frac{v^2}{c^2}, \frac{\phi}{c^2}\right)$$

$$S_{x^i} \frac{d}{dt} \left( m \frac{dx^i}{dt} \right) = m(-) \neq \frac{\partial \bar{\Phi}}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \bar{\Phi}}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \bar{\Phi}}{\partial x^i} \quad \text{using } \frac{dt}{dt} = 1$$

$$+ O\left(\frac{v^2}{c^2} \frac{\Phi}{c^2}\right)$$

$$S_{x^i} \frac{d}{d\tau} \left( 2m \frac{dx^i}{d\tau} \right) = m(-) \approx \frac{\partial \Phi}{\partial x^i} \left( \frac{d\tau}{dt} \right)^2$$

$$\frac{d^2 x^i}{d\tau^2} = - \frac{\partial \Phi}{\partial x^i} \left( \frac{d\tau}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \Phi}{\partial x^i} \quad \text{using } \frac{d\tau}{dt} \approx 1$$

$$\bar{L} = \int dx^m g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}$$

$$+ O\left(\frac{v^2}{c^2}, \frac{\phi}{c^2}\right)$$



$$S_{x^i} \frac{d}{dt} \left( 2m \frac{dx^i}{dt} \right) = m(-) \approx \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

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$$+ O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

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$$\bar{L} = \int d\lambda m g_{\alpha\beta} \frac{dx^\alpha}{d\lambda} \frac{dx^\beta}{d\lambda}$$

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$$S_x' \frac{d}{d\tau} \left( 2m \frac{dx^i}{d\tau} \right) = m(-) \approx \frac{\partial \Phi}{\partial x^i} \left( \frac{d\tau}{dt} \right)^2$$

$$\frac{d^2 x^i}{d\tau^2} = - \frac{\partial \Phi}{\partial x^i} \left( \frac{d\tau}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \Phi}{\partial x^i} \quad \text{using } \frac{d\tau}{dt} \approx 1$$

→ our metric and the free particle action yield the physics of Newtonian gravity

$$+ O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

$$S_x = \int dt \left( m \frac{dx^i}{dt} \right) = m(-) \approx \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

$$\frac{d^2 x^i}{dt^2} = - \frac{\partial \Phi}{\partial x^i} \left( \frac{dt}{dt} \right)^2$$

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→ our metric and the free particle action yield the physics of Newtonian gravity

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$$+ O\left(\frac{v^2}{c^2}, \frac{\Phi}{c^2}\right)$$

- not yet resolving inconsistencies between Newtonian gravity & SR, but on our way
- new physical picture.



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Newton

① mass.

- not yet resolving inconsistencies between  
Newtonian gravity & S.R., but on  
our way  
- new physics picture.

Newton

① mass · product  
field  $\Phi$   
a for

- not yet resolving inconsistencies between Newtonian gravity & SR, but on our way
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Newton

① mass produces a field  $\Phi$  which exerts a force

Einstein

① mass:

- not yet resolving inconsistencies between Newtonian gravity & SR, but on our way
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### Newton

- ① mass produces a field  $\Phi$  which exerts a force

### Einstein

- ① mass: spacetime around mass is curved

- not yet resolving inconsistencies between Newtonian gravity & SR, but on our way
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### Newton

- ① mass produces a field  $\Phi$  which exerts a force

### Einstein

- ① mass: spacetime around mass is curved

particle moves according

$\vec{a}$

- not yet resolving inconsistencies between Newtonian gravity & S.R., but on our way
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### Newton

- ① mass produces a field  $\vec{\Phi}$  which exerts a force
- ② particle moves! according to  $\vec{F} = m\vec{a}$

### Einstein

- ① mass: spacetime around mass is curved
- ② m

- not yet resolving inconsistencies between Newtonian gravity & SR, but on our way
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### Newton

- ① mass produces a field  $\vec{\Phi}$  which exerts a force
- ② particle moves according to  $\vec{F} = m\vec{a}$

### Einstein

- ① mass: spacetime around mass is curved
- ② particles follow free particle trajectories in curved space

③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(\underline{x})$$

→ our metric and the free particle action  
yield the physics of Newtonian gravity



③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(\underline{x})$$

③

"Einstein's equations"

→ our metric and the free particle action yield the physics of Newtonian gravity

③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(\vec{x})$$

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"Einstein's  
equations"  
missing ingredient

→ our metric and the free particle action  
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$$\nabla^2 \underline{\Phi} = 4\pi G \rho(\vec{x})$$

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"Einstein's equations"  
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---

"Curved Spacetime"

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(x)$$

③

"Einstein's equations"  
missing ingredient

---

"Curved Spacetime"

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

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$$\nabla^2 \underline{\Phi} = 4\pi G \rho(x)$$

③

"Einstein's  
equations"  
missing ingredient

"Curved Spacetime"

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

Symmetric matrix with  
coefficients depending on position  $(ct, x^i)$

③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(x)$$

③

"Einstein's  
equations"  
missing "ingredient"

---

"Curved Spacetime"

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

Symmetric matrix with  
coefficients depending on position  $(t, x^i)$

$$\textcircled{3} \quad \nabla^2 \underline{\Phi} = 4\pi G \rho(x)$$

$\textcircled{3}$  "Einstein's equations"  
missing ingredient

"Curved Spacetime"

$$ds^2 = \underbrace{g_{\alpha\beta}(x)} dx^\alpha dx^\beta$$

Symmetric matrix with  
coefficients depending on position  $(ct, x^i)$

→ already saw  $g_{\mu\nu}(x^a)$  in flat space  
with interesting coordinates (eg polar coords)



③

$$\nabla^2 \underline{\Phi} = 4\pi G \rho(x)$$

③

"Einstein's  
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"Curved Spacetime"

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Symmetric matrix with  
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- already saw  $g_{\mu\nu}(x)$  in flat space  
with interesting coordinates (eg polar coords)
- how is flat Minkowski space distinguished from

curved spacetime

→ flat spacetime means there is a coordinate transformation which makes the metric take the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$

force

② particle moves according to  $\vec{F} = m\vec{a}$

② particles follow free particle trajectories in curved space

curved spacetime

→ flat spacetime means there is a coordinate transformation which makes the metric take the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$  everywhere

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

=

←  $y^m = y^m(x)$

curved spacetime

→ flat spacetime means there is a coordinate transformation

which makes the metric take the form

$$g_{\alpha\beta} = \eta_{\alpha\beta} \text{ everywhere}$$

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

$$g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

$$\leftarrow x^\mu = x^\mu(y^\nu)$$

curved spacetime

→ flat spacetime means there  
is a coordinate transformation  
which makes the metric take  
the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$  everywhere

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

$$= g_{\alpha\beta}(x) d$$

←  $x^\mu = x^\mu(y)$

curved spacetime

→ flat spacetime means there is a coordinate transformation which makes the metric take the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$  everywhere

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

$$= \underbrace{g_{\alpha\beta}(x)}_{\eta_{\alpha\beta}} \frac{dx^\alpha}{dy^\mu} \frac{dx^\beta}{dy^\nu} dy^\mu dy^\nu \leftarrow x^\mu = x^\mu(y^\nu)$$

curved spacetime

→ flat spacetime means there is a coordinate transformation which makes the metric take the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$  everywhere

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta$$

$$= \underbrace{g_{\alpha\beta}(x)}_{\eta_{\alpha\beta}} \frac{dx^\alpha}{dy^\sigma} \frac{dx^\beta}{dy^\delta} dy^\sigma dy^\delta \leftarrow x^\mu = x^\mu(y^\nu)$$

(1) if we can't do such a transformation

→ curved spacetime

"Curved Spacetime"

$$ds^2 = g_{\alpha\beta}(x^\mu) dx^\alpha dx^\beta$$

Symmetric matrix with  
coefficients depending on position  $(ct, x^i)$

→ already saw  $g_{\mu\nu}(x^\mu)$  in flat space

with interesting coordinates (eg polar coords)

→ how is flat Minkowski space distinguished from



(1) if we can't do such a transformation  
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//  
in general for 4 spacetime dimensions

(1) if we can't do such a transformation  
→ curved spacetime

//  
In general for 4 spacetime dimensions  
 $g_{\mu\nu}(x)$  contains 10 independent functions

curved spacetime

→ flat spacetime means there is a coordinate transformation

which the metric take

the form  $g_{\alpha\beta} = \eta_{\alpha\beta}$  everywhere

$$ds^2 = \frac{1}{2}(g_{\alpha\beta} + g_{\beta\alpha}) dx^\alpha dx^\beta$$
$$\frac{dx^\alpha}{dy^\mu} \frac{dx^\beta}{dy^\nu} dy^\mu dy^\nu \leftarrow x^\mu = x^\mu(y^\nu)$$

curved spacetime

→ flat spacetime means there is a coordinate transformation

which makes the metric take the form

$$g_{\alpha\beta} = \eta_{\alpha\beta} \text{ everywhere}$$

$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta = \frac{1}{2} (g_{\alpha\beta} + g_{\beta\alpha}) dx^\alpha dx^\beta$$

$$= \underbrace{g_{\alpha\beta}(x) \frac{dx^\alpha}{dy^\mu} \frac{dx^\beta}{dy^\nu}}_{\eta_{\mu\nu}} dy^\mu dy^\nu \leftarrow x^\mu = x^\mu(y^\nu)$$

(1) if we can't do such a transformation  
→ curved spacetime

in general for 4 spacetime dimensions  
 $g_{\alpha\beta}(x)$  contains 10 independent functions  
since symmetric matrix

60

$dx^\beta$

y)

(1) If we can't do such a transformation  
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in general for 4 spacetime dimensions

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$$ds^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta = \frac{1}{2} (g_{\alpha\beta} + g_{\beta\alpha}) dx^\alpha dx^\beta$$

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ed spacetime

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which makes the metric take

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$$s^2 = g_{\alpha\beta}(x) dx^\alpha dx^\beta = \frac{1}{2} (g_{\alpha\beta} + g_{\beta\alpha}) dx^\alpha dx^\beta$$

$$= \underbrace{g_{\alpha\beta}(x) \frac{\partial x^\alpha}{\partial y^\gamma} \frac{\partial x^\beta}{\partial y^\delta}}_{\eta_{\gamma\delta}} dy^\gamma dy^\delta \leftarrow x^\mu = x^\mu(y^\nu)$$

$\eta_{\gamma\delta}$

if we

in gen

$g_{\alpha\beta}$

coordina



(1) if we can't do such a transformation

→ curved spacetime

in general for 4 spacetime dimensions

$g_{\alpha\beta}(x)$  contains 10 independent functions

since symmetric matrix

coordinate transformation

$$\hat{g}_{\alpha\beta}(y) = \frac{\partial x^\alpha}{\partial y^\delta} \frac{\partial x^\beta}{\partial y^\gamma} g_{\alpha\beta}(x)$$

$dx^\beta$

$y^\gamma$

(1) if we can't do such a transformation

→ curved spacetime

in general for 4 spacetime dimensions

$g_{\alpha\beta}(x)$  contains 10 independent functions  
since symmetric matrix  
coordinate transformation

$$\hat{g}_{\alpha\gamma}(y) = \frac{\partial x^\alpha}{\partial y^\delta} \frac{\partial x^\beta}{\partial y^\gamma} g_{\alpha\beta}(x)$$

→ describes the same geometry  
with "new labels"

inverse metric:  $g^{\alpha\beta}(x)$

$$g^{\alpha\beta}(x) g_{\beta\gamma}(x) = \delta^{\alpha}_{\gamma}$$

Inverse metric:  $g^{\alpha\beta}(x)$

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$$\hat{g}_{\alpha\beta}(y) = \frac{\partial x^\alpha}{\partial y^\mu} \frac{\partial x^\beta}{\partial y^\nu} g_{\alpha\beta}(x)$$

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Inverse metric:  $g^{\alpha\beta}(x)$

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---

gain more insight:

Inverse metric:  $g^{\alpha\beta}(x)$

$$g^{\alpha\beta}(x) g_{\beta\gamma}(x) = \delta^{\alpha}_{\gamma}$$

---

gain more insight: equivalence principle



Inverse metric:  $g^{\alpha\beta}(x)$

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---

gain more insight: equivalence principle  
→ locally curved spacetime should

Inverse metric:  $g^{\alpha\beta}(x)$

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gain more insight: equivalence principle

→ locally curved spacetime should  
be same as flat spacetime

Inverse metric:  $g^{\alpha\beta}(x)$

$$g^{\alpha\beta}(x) g_{\beta\gamma}(x) = \delta^{\alpha}_{\gamma}$$

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in more insight: equivalence principle

locally curved spacetime should  
be same as flat spacetime

→ Mathematically means that at any  
p

Inverse metric:  $g^{\alpha\beta}(x)$

$$g^{\alpha\beta}(x) g_{\beta\gamma}(x) = \delta^{\alpha}_{\gamma}$$

---

gain more insight: equivalence principle

→ locally curved spacetime should be same as flat spacetime

→ Mathematically means that at any point, we can find a coord trans

such that

$$g_{\alpha\beta}(x^{\mu} = x^{\mu}_0) = \eta_{\alpha\beta}$$

inverse metric:  $g^{\alpha\beta}(x)$

$$g^{\alpha\beta}(x) g_{\beta\gamma}(x) = \delta^{\alpha}_{\gamma}$$

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gain more insight: equivalence principle

→ locally curved spacetime should be same as flat spacetime

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gain more insight: equivalence principle

→ locally curved spacetime should be same as flat spacetime

→ Mathematically means that at any point, we can find a coord trans. such that

$$g_{\alpha\beta}(x^{\mu} = x^{\mu}_0) = \eta_{\alpha\beta}$$

→ doesn't hold away from  $x^\mu = x_0^\mu$

$g_{\alpha\beta}(x)$  contains 10 independent functions  
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Coordinate transformation

$$\hat{g}_{\alpha\beta}(y) = \frac{\partial x^\alpha}{\partial y^\delta} \frac{\partial x^\beta}{\partial y^\gamma} g_{\alpha\beta}(x)$$

→ describes the same geometry  
with "new labels"

→ doesn't hold away from  $x^\mu = x_0^\mu$

had  $\hat{g}_{\alpha\beta}(y) = \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$



→ doesn't hold away from  $x^h = x_0^h$

had  $\hat{g}_{\alpha\beta}(y) = \frac{\partial x^h}{\partial y} \frac{\partial x}{\partial y} g_{\mu\nu}(x)$

at  $x^h = x_0^h$ ,  $g_{\mu\nu}(x_0^h)$  is a metric  
with

→ doesn't hold away from  $x^\mu = x_0^\mu$

had 
$$\hat{g}_{\alpha\beta}(y) = \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix  
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at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix  
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similarly  $\left. \frac{\partial x^\mu}{\partial y^\alpha} \right|_{x=x_0}$  is a matrix with  
16 numbers

→ doesn't hold away from  $x^\mu = x_0^\mu$

$$\text{had } \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

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16 numbers

$$\left. \hat{g}_{\alpha\beta} \right|_{x=x_0} = \eta_{\alpha\beta} \leftarrow 10 \text{ eq's}$$

→ doesn't hold away from  $x^\mu = x_0^\mu$

$$\text{had } \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix with 10 numbers

similarly  $\left. \frac{\partial x^\mu}{\partial y^\alpha} \right|_{x=x_0}$  is a matrix with 16 numbers

$$\left. \hat{g}_{\alpha\beta} \right|_{x=x_0} = \eta_{\alpha\beta} \leftarrow 10 \text{ eq's in } 16 \text{ unknowns}$$

→ should be solutions with in fact  
6 extra d.o.f.



→ should be solutions with in fact  
6 extra d.o.f.

→ 3 boosts and 3 rotations  
which are symmetries of  
Minkowski space ( $\eta_{\alpha\beta}$ )

→ doesn't hold away from  $x^\mu = x_0^\mu$

$$\text{had } \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix

$(g^{\alpha\beta} \quad g_{\mu\nu} = \delta_{\mu\nu}^{\alpha\beta})$  with 10 numbers  
similarly  $\left. \frac{\partial x^\mu}{\partial y^\alpha} \right|_{x=x_0}$  is a matrix with

16 numbers  
 $\left. g_{\alpha\beta} \right|_{x=x_0} = \eta_{\alpha\beta} \leftarrow 10 \text{ eq's in 16 unknowns}$

→ should be solutions with in fact  
6 extra d.o.f.

→ 3 boosts and 3 rotations  
which are symmetries of  
Minkowski space ( $\eta_{\alpha\beta}$ )

Can we do better?

Can we set  $\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\mu} \Big|_{x=x_0} = 0$ ?

→ should be solutions with in fact  
6 extra d.o.f.

→ 3 boosts and 3 rotations  
which are symmetries of  
Minkowski space ( $\eta_{\alpha\beta}$ )

Can we do better?

Can we set  $\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\mu} \Big|_{x=x^0} = 0$ ?

YES!

→ should be solutions with in fact  
6 extra d.o.f.

→ 3 boosts and 3 rotations  
which are symmetries of  
Minkowski space ( $\eta_{ab}$ )

Can we do better?

Can we set  $\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\mu} \Big|_{x=x_0} = 0$ ?

YES!

$$\frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left[ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right]$$

at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix  
with 10 numbers

Similarly  $\left. \frac{\partial x^\mu}{\partial y^\alpha} \right|_{x=x_0}$  is a matrix with  
16 numbers

$\left. g_{\alpha\beta} \right|_{x=x_0} = \eta_{\alpha\beta} \leftarrow 10 \text{ eq's in } 16 \text{ unknowns}$

$$\frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left[ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right]$$

at  $x^\mu = x_0^\mu$ ,  $g_{\mu\nu}(x_0^\mu)$  is a matrix  
with 10 numbers

similarly  $\left. \frac{\partial x^\mu}{\partial y^\alpha} \right|_{x=x_0}$  is a matrix with  
16 numbers

$\left. \hat{g}_{\alpha\beta} \right|_{x=x_0} = \eta_{\alpha\beta} \leftarrow 10 \text{ eq's in } 16 \text{ unknowns}$

$$\frac{\partial}{\partial y^\alpha} g_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left\{ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right\}$$

$$= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{\mu\nu}(x) \right]$$



$$\begin{aligned}
 \frac{\partial}{\partial y^\alpha} \tilde{g}_{\alpha\beta}(y) &= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left[ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right] \\
 &= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{\mu\nu}(x) \right]
 \end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta}(y) &= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left\{ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right\} \\
&= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{\mu\nu}(x) \right] \\
&\quad + \frac{\partial^2 x^\mu}{\partial y^\alpha \partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \\
&\quad + \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial^2 x^\nu}{\partial y^\alpha \partial y^\beta} g_{\mu\nu}(x)
\end{aligned}$$

$$\frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left\{ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right\}$$

$$= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{\mu\nu}(x) \right]$$

NOT tensor  
transformation  
rule

$$+ \frac{\partial^2 x^\mu}{\partial y^\alpha \partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

$$+ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial^2 x^\nu}{\partial y^\alpha \partial y^\beta} g_{\mu\nu}(x)$$

$$\frac{\partial}{\partial y^\alpha} \tilde{g}_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left\{ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x) \right\}$$

$$= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^\mu}{\partial y^\lambda} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{\mu\nu}(x) \right]$$

NOT tensor  
transformation  
rule

$$+ \frac{\partial^2 x^\mu}{\partial y^\alpha \partial y^\lambda} \frac{\partial x^\nu}{\partial y^\beta} g_{\mu\nu}(x)$$

$$+ \frac{\partial x^\mu}{\partial y^\alpha} \frac{\partial^2 x^\nu}{\partial y^\lambda \partial y^\beta} g_{\mu\nu}(x)$$

of  $x^m = x_0^m$ ; in fixing  $\hat{g}_{\alpha\beta} = \eta_{\alpha\beta}$

wh

at  $x^n = x_0^n$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta 0}$

we already fixed  $\left. \frac{\partial x^n}{\partial y^\alpha} \right|_{x=x_0}$

what's new is:

at  $x^m = x_0^m$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta}(x_0)$

we already fixed  $\left. \frac{\partial x^m}{\partial y^\alpha} \right|_{x=x_0}$

what's new is:  $\left. \frac{\partial g_{\alpha\beta}}{\partial x^\lambda} \right|_{x=x_0}$  ←

at  $x^n = x_0^n$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta 0}$

we already fixed  $\left. \frac{\partial x^n}{\partial y^\alpha} \right|_{x=x_0}$

what's new is:  $\left. \frac{\partial g_{\alpha\beta}}{\partial x^\lambda} \right|_{x=x_0} \leftarrow 40 \text{ numbers}$



at  $x^n = x_0^n$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta}$

we already fixed  $\left. \frac{\partial x^n}{\partial y^\alpha} \right|_{x=x_0}$

new is:  $\left. \frac{\partial g_{\alpha\beta}}{\partial x^\lambda} \right|_{x=x_0} \leftarrow 40 \text{ numbers}$

$\left. \frac{\partial^2 x^\lambda}{\partial x^\alpha \partial x^\beta} \right|_{x=x_0} \leftarrow$

at  $x^a = x_0^a$ ; in fixing  $\hat{g}_{\alpha\beta} = \hat{g}_{\alpha\beta}$

we already fixed  $\left. \frac{\partial x^a}{\partial y^\alpha} \right|_{x=x_0}$

what's new is:  $\left. \frac{\partial g_{\alpha\beta}}{\partial x^a} \right|_{x=x_0} \leftarrow \underline{40}$  numbers

precisely right  $\left. \frac{\partial^2 x^a}{\partial y^\alpha \partial y^\beta} \right|_{x=x_0} \leftarrow \underline{40}$  numbers

counting to satisfy  $\left. \frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta} \right|_{x=x_0} = 0$

at  $x^a = x_0^a$ ; in fixing  $\overset{\wedge}{g}_{\alpha\beta} = g_{\alpha\beta}$

we already fixed  $\left. \frac{\partial x^a}{\partial y^\alpha} \right|_{x=x_0}$

what's new is:  $\left. \frac{\partial g_{\alpha\beta}}{\partial x^a} \right|_{x=x_0} \leftarrow \underline{40}$  numbers

precisely right  $\left. \frac{\partial^2 x^a}{\partial y^\alpha \partial y^\beta} \right|_{x=x_0} \leftarrow \underline{40}$  numbers

counting to satisfy

$$\left. \frac{\partial}{\partial y^\alpha} \overset{\wedge}{g}_{\alpha\beta} \right|_{x=x_0} = 0$$

$$\frac{\partial}{\partial y^\alpha} \hat{g}_{\alpha\beta}(y) = \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial}{\partial x^\lambda} \left\{ \frac{\partial x^m}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{m\nu}(x) \right\}$$

$$= \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial x^m}{\partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} \left[ \frac{\partial}{\partial x^\lambda} g_{m\nu}(x) \right]$$

$$+ \frac{\partial^2 x^m}{\partial y^\alpha \partial y^\alpha} \frac{\partial x^\nu}{\partial y^\beta} g_{m\nu}(x)$$

$$+ \frac{\partial x^\lambda}{\partial y^\alpha} \frac{\partial^2 x^\nu}{\partial y^\alpha \partial y^\beta} g_{m\nu}(x)$$

NOT tensor  
transformation  
rule

at  $x^a = x_0^a$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta 0}$

we already fixed  $\frac{\partial x^a}{\partial y^\alpha} \Big|_{x=x_0}$

what's new is:  $\frac{\partial g_{\alpha\beta}}{\partial x^\lambda} \Big|_{x=x_0} \leftarrow \underline{40}$  numbers

$\frac{\partial^2 x^a}{\partial x^\lambda \partial x^\mu} \Big|_{x=x_0} \leftarrow \underline{40}$  numbers

precisely right

counting to satisfy

$$\frac{\partial}{\partial y^\alpha} g_{\alpha\beta} \Big|_{x=x_0} = 0$$

$\leftarrow$  can also eliminate

at  $x^m = x_0^m$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta}|_{x=x_0}$

we already fixed  $\frac{\partial x^m}{\partial y^\alpha} \Big|_{x=x_0}$

what's new is:  $\frac{\partial^2 g_{\alpha\beta}}{\partial x^\gamma \partial x^\delta} \Big|_{x=x_0} \leftarrow \underline{40}$  numbers

$\frac{\partial^2 x^m}{\partial x^\gamma \partial x^\delta} \Big|_{x=x_0} \leftarrow \underline{40}$  numbers

precisely right

counting to satisfy

$$\frac{\partial}{\partial y^\alpha} g_{\alpha\beta} \Big|_{x=x_0} = 0$$

$\leftarrow$  can also eliminate first derivatives

at  $x^m = x_0^m$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta}|_{x_0}$

we already fixed  $\frac{\partial x^m}{\partial y^\alpha} \Big|_{x=x_0}$

what's new is:  $\frac{\partial^2 g_{\alpha\beta}}{\partial x^m \partial x^n} \Big|_{x=x_0} \leftarrow 40 \text{ numbers}$

$\frac{\partial^2 x^m}{\partial y^\alpha \partial y^\beta} \Big|_{x=x_0} \leftarrow 40 \text{ numbers}$

ely right

counting to satisfy

$$\frac{\partial}{\partial y^\alpha} g_{\alpha\beta} \Big|_{x=x_0} = 0$$

can also eliminate first derivatives at a point

NOT +  
transf  
r 41

at  $x^a = x_0^a$ ; in fixing  $g_{\alpha\beta} = g_{\alpha\beta}$

we already fixed  $\frac{\partial x^a}{\partial y^\alpha} \Big|_{x=x_0}$

what's new is:  $\frac{\partial g_{\alpha\beta}}{\partial x^a} \Big|_{x=x_0}$  ← 40 numbers

$\frac{\partial^2 x^a}{\partial x^b \partial y^\alpha} \Big|_{x=x_0}$  ← 40 numbers

precisely right

counting to satisfy

$$\frac{\partial}{\partial y^\alpha} g_{\alpha\beta} \Big|_{x=x_0} = 0$$

← can also eliminate first derivatives at a point

NOT tensor transformation rule



- can we go further?

say setting

$$\frac{\partial \hat{g}_{\alpha\beta}}{\partial x^\alpha \partial x^\beta} = 0?$$

No

find

$$\frac{\partial g_{\mu\nu}}{\partial x^\alpha \partial x^\beta}$$

- can we go further?

say setting  $\frac{\partial \hat{g}_{AB}}{\partial x^\alpha \partial x^\beta} = 0$ ?

NO

find  $\frac{\partial g_{\mu\nu}}{\partial x^\alpha \partial x^\beta}$  ← 100 new numbers

- can we go further?

say setting  $\frac{\partial \hat{g}_{AB}}{\partial y^\alpha \partial y^\beta} = 0$ ?

NO

find  $\frac{\partial g_{\mu\nu}}{\partial x^\alpha \partial x^\beta} \leftarrow 100$  new numbers

$\frac{\partial^3 x^\gamma}{\partial y^\alpha \partial y^\beta \partial y^\mu} \leftarrow 80$

- can we go further?

say setting  $\frac{\partial \hat{g}_{\alpha\beta}}{\partial y^\alpha \partial y^\beta} = 0$ ?

NO

find  $\frac{\partial g_{\mu\nu}}{\partial x^\alpha \partial x^\beta} \leftarrow 100$  new numbers

$\frac{\partial^3 x^\alpha}{\partial y^\alpha \partial y^\beta \partial y^\gamma} \leftarrow 80$  new coefficients

$\Rightarrow 20$  components of the second derivatives

- can we go further?

say setting  $\frac{\partial \hat{g}_{\alpha\beta}}{\partial y^\alpha \partial y^\beta} = 0$ ?

NO

find  $\frac{\partial g_{\mu\nu}}{\partial x^\alpha \partial x^\beta} \leftarrow 100$  new numbers

$\frac{\partial^3 x^\alpha}{\partial y^\alpha \partial y^\beta \partial y^\gamma} \leftarrow 80$  new coefficients

$\Rightarrow$  20 components of the second derivatives  
can NOT be set to zero in general

→ reflects the fact that in general  
we are working with curved spacetime

- reflects the fact that in general we are working with curved space-time
- develop further technology to deal with this more systematically