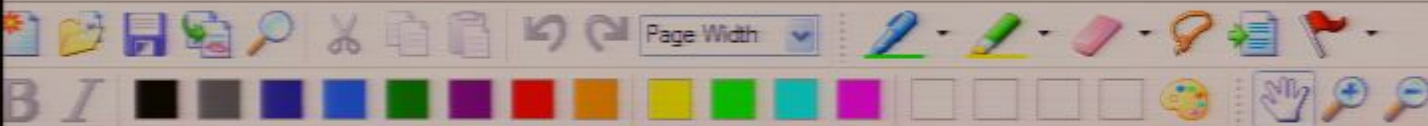


Title: General Relativity for Cosmology - Lecture 3

Date: Sep 28, 2009 04:00 PM

URL: <http://pirsa.org/09090013>

Abstract:



We notice:

For every (germ of a) function at p ,

$$f \in \mathcal{F}(p)$$

one naturally obtains an element

$$"df \in T_p(M)^*"$$

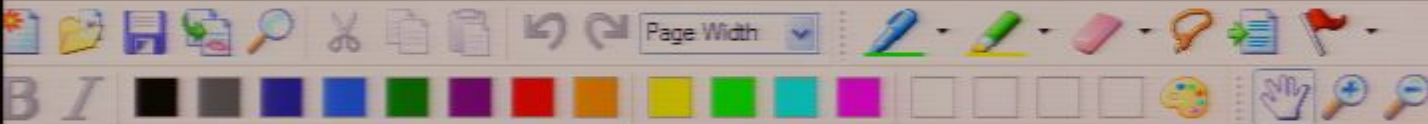
called the "differential of f ."

Namely:

$df : T_p(M) \rightarrow \mathbb{R}$ is the linear map:

$$df : \xi \rightarrow \xi(f)$$

(Note: thus, we can view "d" as a map: $d : \mathcal{F}_p(M) \rightarrow T_p(M)^*$. See later...)



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Concretely, in a cds., i.e. in a chart, $\xi \in T_p(M)$

and $f \in F(p)$ correspond to some

$\eta \in T_q(\mathbb{R}^n)$ and $g \in F(q)$. Then:

$$dg: T_q(\mathbb{R}^n) \rightarrow \mathbb{R}$$

$$dg: \eta \rightarrow \eta(g) = \sum_{i=1}^n \eta^i \frac{\partial}{\partial x^i} \Big|_{x=q} g(x^1, \dots, x^n)$$

Recall: Since all $\eta \in T_q(\mathbb{R}^n)$ take the form $\eta = \sum_{i=1}^n \eta^i \frac{\partial}{\partial x^i} \Big|_{x=q}$

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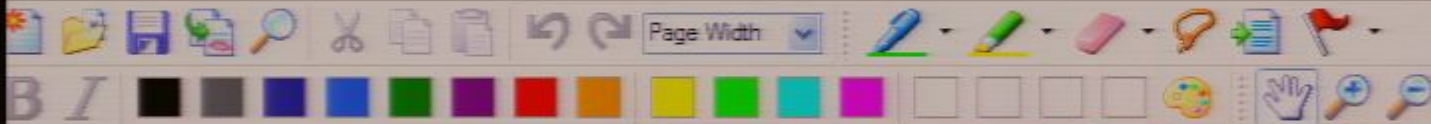
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Recall: Since all $\eta \in T_q(\mathbb{R}^n)$ take the form $\eta = \sum_{i=1}^n \eta^i \frac{\partial}{\partial x^i} \Big|_{x=q}$

a basis of $T_q(\mathbb{R}^n)$ is $\left\{ \frac{\partial}{\partial x^i} \Big|_{x=q} \right\}_{i=1}^n$



a basis of $T_q(\mathbb{R}^n)$ is $\{\partial x^i|_{x=q}\}_{i=1}^n$

Question: What is the dual basis in $T_q(\mathbb{R}^n)^*$?

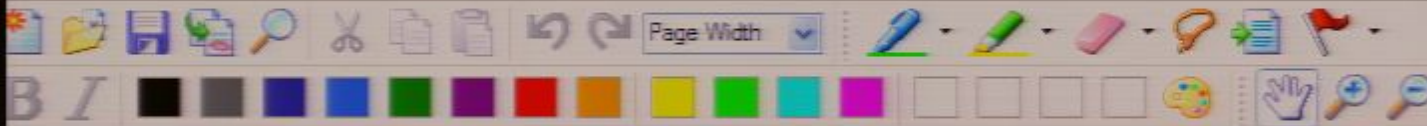
□ Consider the coordinate functions' $x^k: \mathbb{R}^n \rightarrow \mathbb{R}$.

□ Their differentials $dx^k \in T_q(\mathbb{R}^n)^*$ obey:

$$dx^k: T_q(\mathbb{R}^n) \rightarrow \mathbb{R}$$

$$dx^k: \left. \frac{\partial}{\partial x^i} \right|_{x=q} \rightarrow \left. \frac{\partial}{\partial x^i} x^k \right|_{x=q} = \delta_i^k$$

□ \Rightarrow The dual basis in $T_q(\mathbb{R}^n)^*$ is given by



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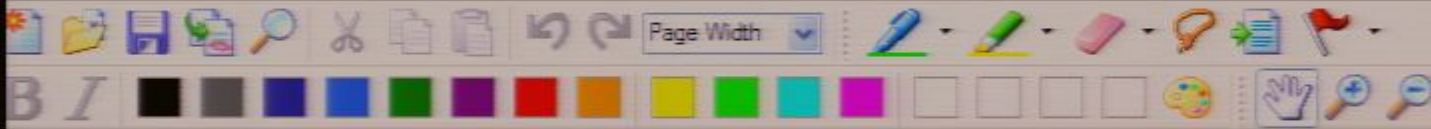
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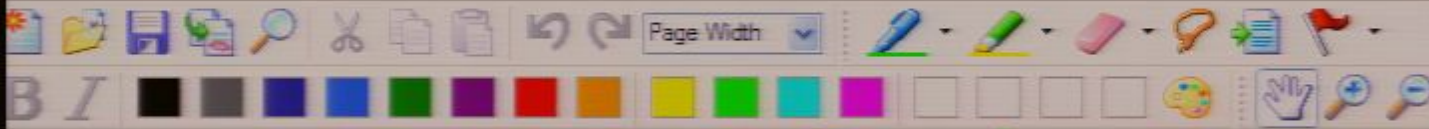
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$\left. \begin{array}{l} \text{ } \\ \text{ } \end{array} \right\} k=1$

Thus:

Every element $\omega \in T_q(\mathbb{R}^n)^*$ takes the form:

$$\omega = \sum_{i=1}^n \omega_i dx^i$$

$\uparrow \in \mathbb{R}$

and its action is:

$$\omega: T_q(\mathbb{R}^n) \rightarrow \mathbb{R}$$

$$\begin{aligned} \omega: \sum_{j=1}^n \eta^j \frac{\partial}{\partial x^j} &\rightarrow \sum_{i=1}^n \omega_i dx^i \left(\sum_{j=1}^n \eta^j \frac{\partial}{\partial x^j} \right) \\ &= \sum_{i=1}^n \omega_i \sum_{j=1}^n \eta^j \frac{\partial}{\partial x^j} x^i \end{aligned}$$

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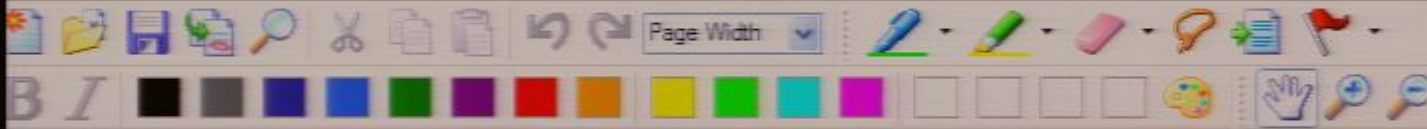
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$$\Rightarrow \omega \left(\sum_{j=1}^n \eta^j \frac{\partial}{\partial x^j} \right) = \sum_{i=1}^n \omega_i \eta^i \quad (\text{I})$$



In particular: For arbitrary $g \in \mathcal{F}(q)$, its

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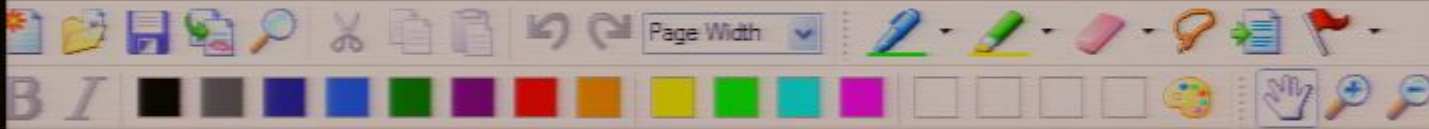
↑ How to calculate them?

We know:

$$dg(\gamma) = \gamma'(g) = \sum_{i=1}^n \gamma^i \underbrace{\frac{\partial}{\partial x^i} g(x)}_{\omega_i} \Big|_{x=q} \quad (\text{II})$$

Compare I, II $\Rightarrow \omega_i = \frac{\partial}{\partial x^i} g(x) \Big|_{x=q}$

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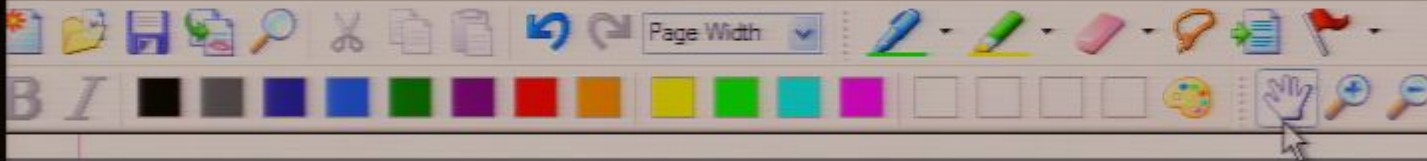
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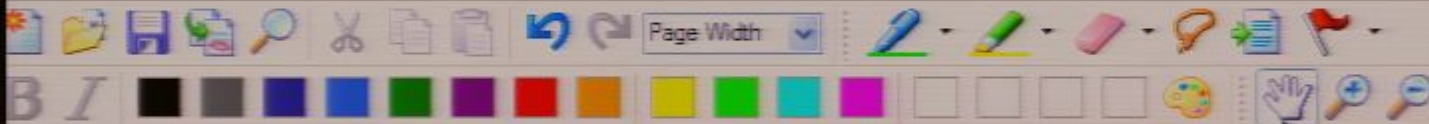
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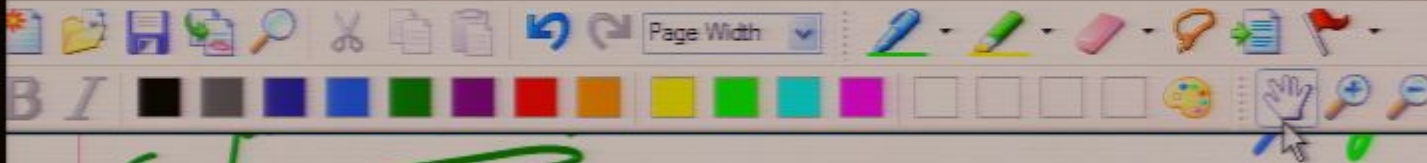
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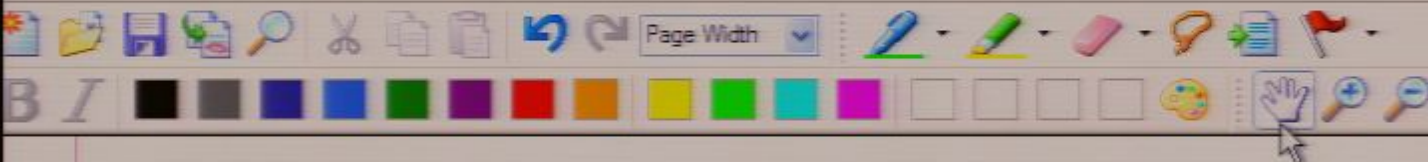
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Exercise: (the "pull back" map)

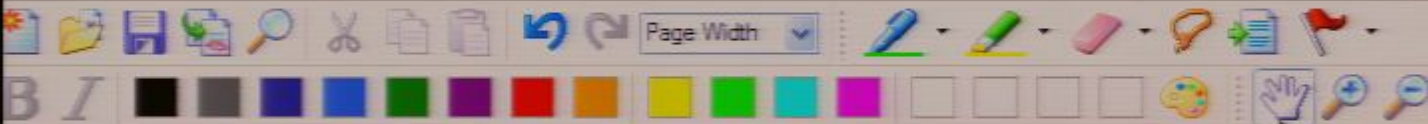
Assume that $\varrho \in T_p(M)^*$, under two charts α, β , as above, corresponds to $\omega \in T_q(\mathbb{R}^m)^*$ and $\mu \in T_s(\mathbb{R}^m)^*$ with:

$$\omega = \sum_{i=1}^m \omega_i dx^i \quad \text{and} \quad \mu = \sum_{i=1}^m \mu_i d\tilde{x}^i$$

Show that $\mu_i = \sum_{j=1}^m \frac{\partial x^j}{\partial \tilde{x}^i} \Big|_{\tilde{x}=s} \omega_j$

Notice that this is the inverse of the Jacobian matrix of $\beta \circ \alpha^{-1}$ at q

Remark: The physicist's definition of $T_p(M)^*$ uses this



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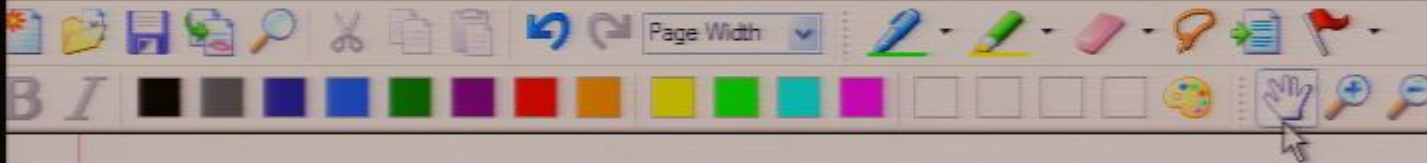
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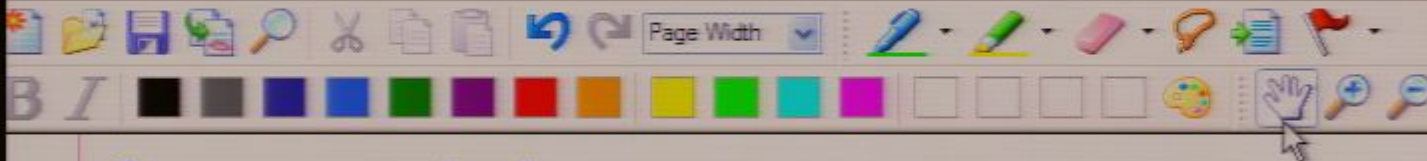


Some notation and terminology:

- Elements of $T_p(M)$ are called *contravariant vectors*
- Elements of $T_p(M)^*$ are called *covariant vectors*
- One often writes symbolically

$$\xi = \sum_{i=1}^n \xi^i \frac{\partial}{\partial x^i} \Big|_p \quad \text{for } \xi \in T_p(M)$$

$$\omega = \sum_{i=1}^n \omega_i dx^i \quad \text{for } \omega \in T_p(M)^*$$



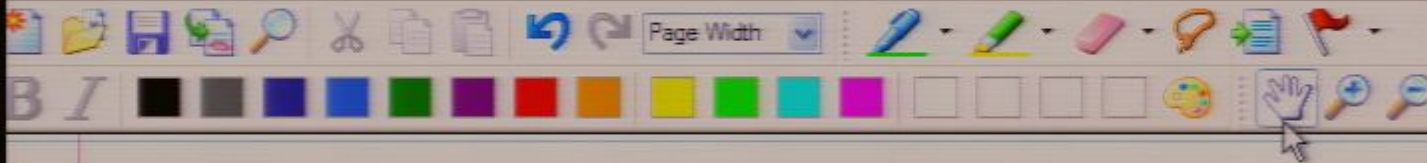
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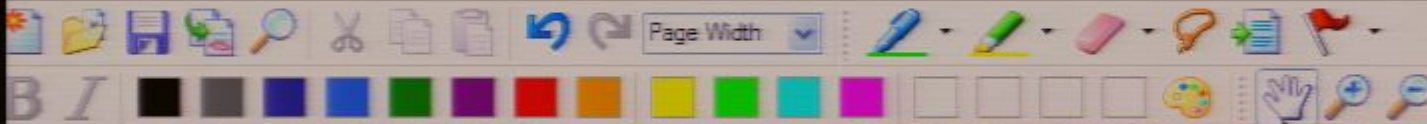


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Tensors:



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Def: A tensor, t , of rank (r, s) is an element of

$\underbrace{\hspace{10em}}_{r \text{ factors}} \quad \underbrace{\hspace{10em}}_{s \text{ factors}}$

$$T_p(\mathcal{M})_s^r := T_p(\mathcal{M}) \otimes \dots \otimes T_p(\mathcal{M}) \otimes T_p(\mathcal{M})^* \otimes \dots \otimes T_p(\mathcal{M})^*$$

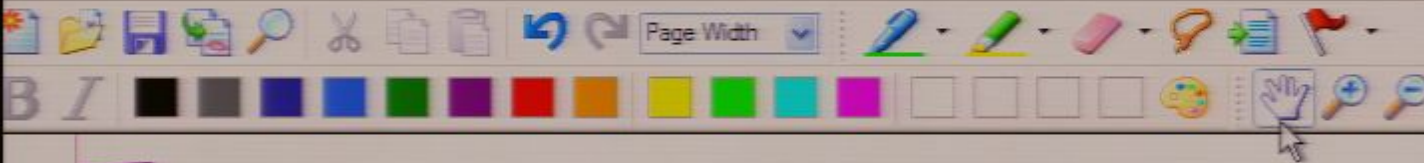
In a chart:

$$t = \sum_{\substack{i_1, \dots, i_r \\ j_1, \dots, j_s}} t_{j_1, \dots, j_s}^{i_1, \dots, i_r} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_r}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_s}$$

$\underbrace{\hspace{10em}}_{\mathbb{R}}$

Under chart change: (physicists, incl. Einstein, defined tensors this way)

$$\bar{t}_{j_1, \dots, j_s}^{i_1, \dots, i_r} = \sum_{k_1, \dots, k_r} \frac{\partial \bar{x}^{i_1}}{\partial x^{k_1}} \dots \frac{\partial \bar{x}^{i_r}}{\partial x^{k_r}} \frac{\partial x^{l_1}}{\partial \bar{x}^{j_1}} \dots \frac{\partial x^{l_s}}{\partial \bar{x}^{j_s}} t_{l_1, \dots, l_s}^{k_1, \dots, k_r}$$



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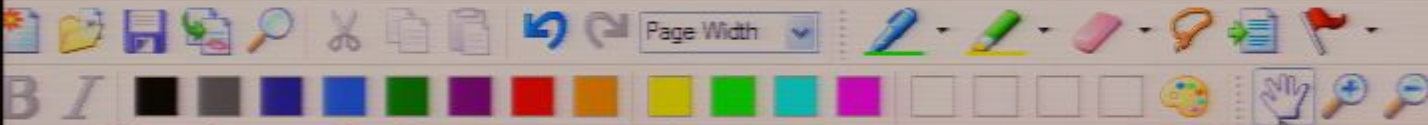
$$T_p(M)_s^r := \overbrace{T_p(M) \otimes \dots \otimes T_p(M)}^{r \text{ factors}} \otimes \overbrace{T_p(M)^* \otimes \dots \otimes T_p(M)^*}^{s \text{ factors}}$$

In a chart:

$$t = \sum_{\substack{i_1, \dots, i_r \\ j_1, \dots, j_s}} t_{j_1, \dots, j_s}^{i_1, \dots, i_r} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_r}} \otimes dx^{j_1} \otimes \dots \otimes dx^{j_s}$$

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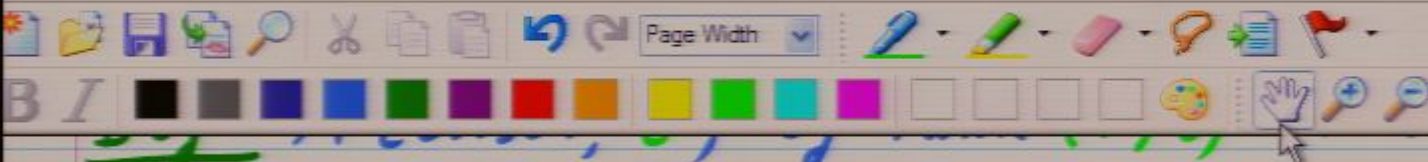
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Thus: $T_p(M) = T_p(M)'$ and $T_p(M)^* = T_p(M)$, i.e.



$$T_p(M)_s^r := \overbrace{T_p(M) \otimes \dots \otimes T_p(M)}^{r \text{ factors}} \otimes \overbrace{T_p(M)^* \otimes \dots \otimes T_p(M)^*}^{s \text{ factors}}$$

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\uparrow
 \mathbb{R}

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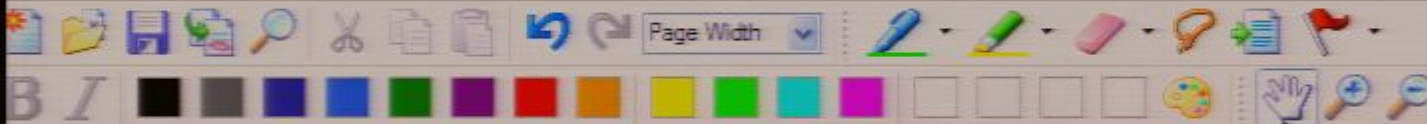
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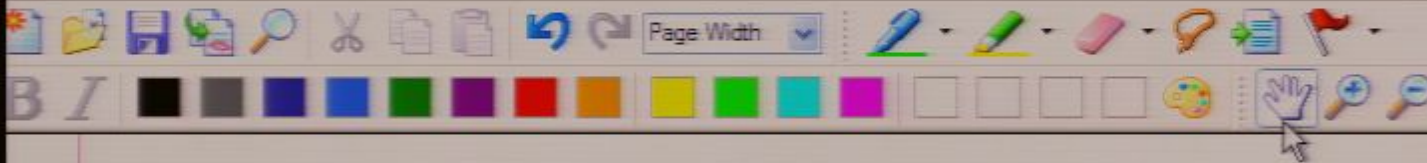
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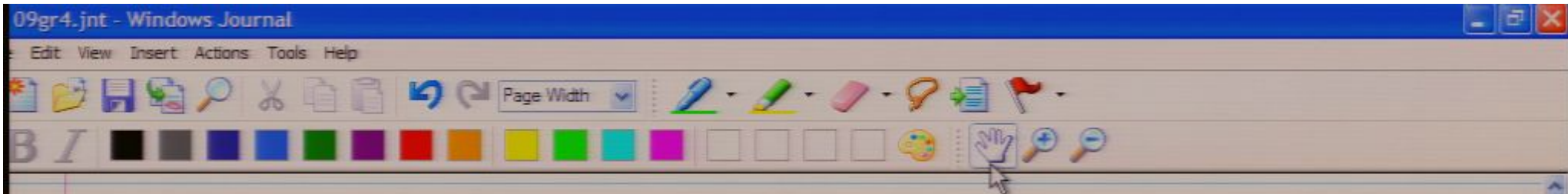
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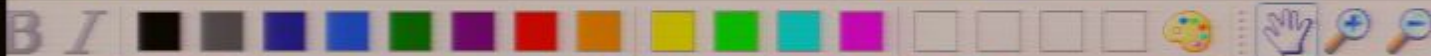
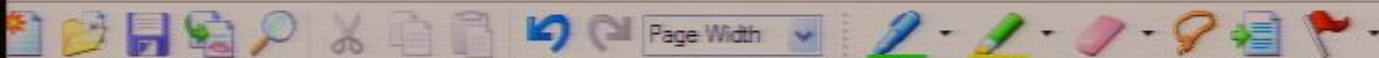
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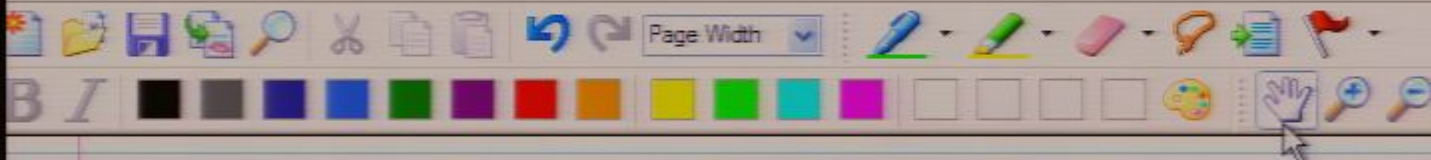
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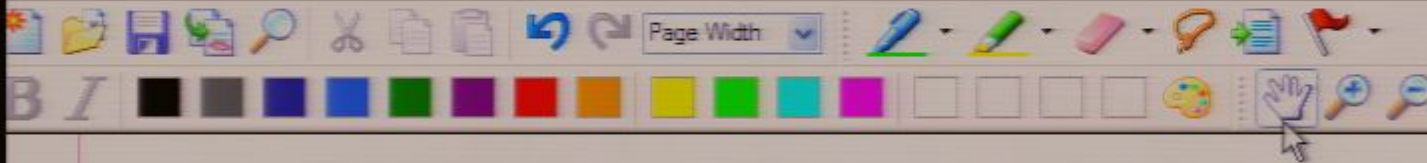
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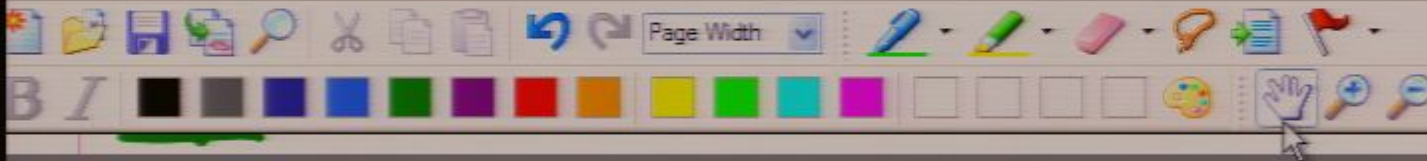
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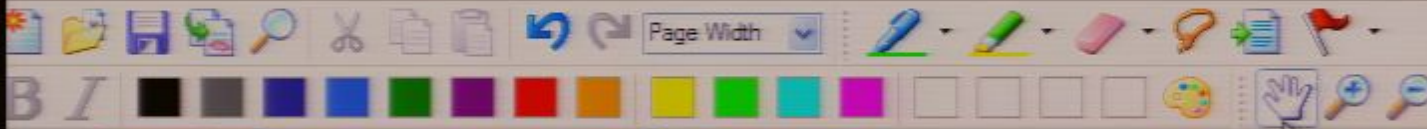
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Remark: One obtains other Fibre bundles



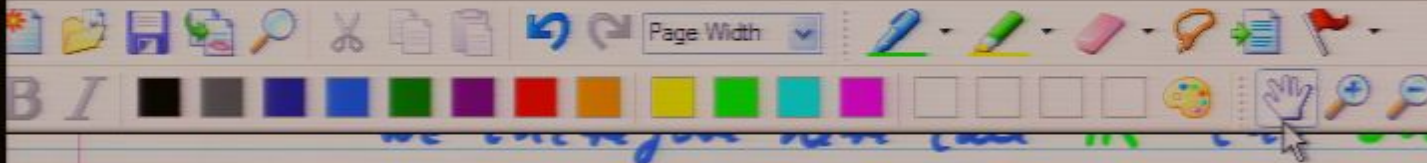
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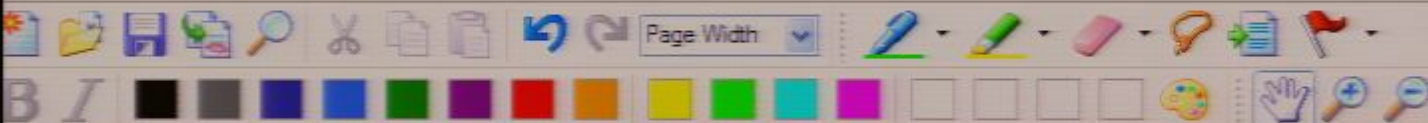
Note: \square Fibre bundles are required to be locally trivial:

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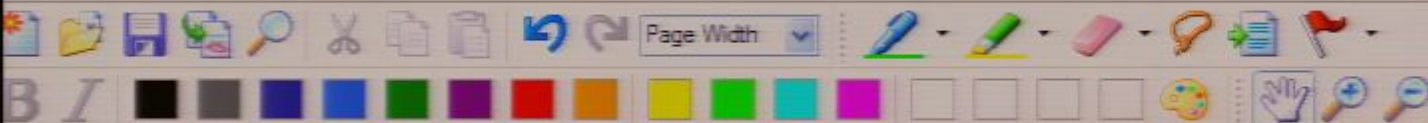
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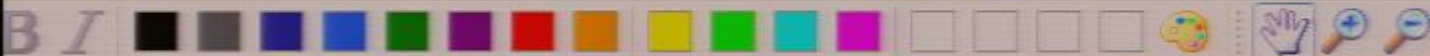
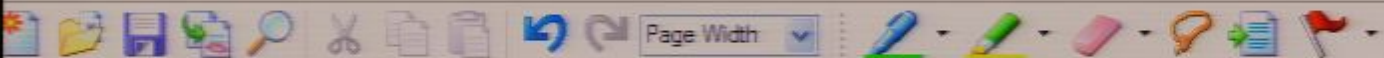


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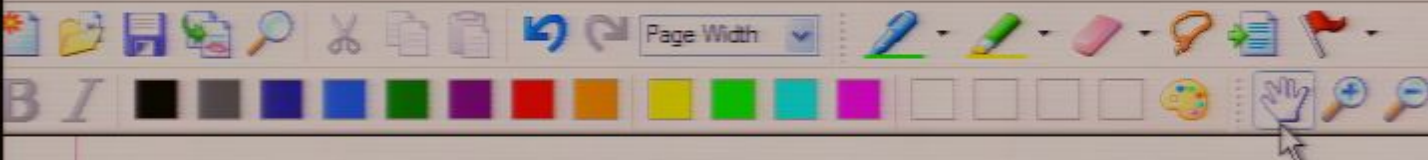
(The isomorphisms may differ by elements of $GL_m(\mathbb{R})$, the "structure group" here)

Def: \square A tangent vector field:

is a map $\xi: M \rightarrow T_p(M)$

In a chart: $\xi = \sum_{i=1}^m \xi^i(x) \frac{\partial}{\partial x^i}$

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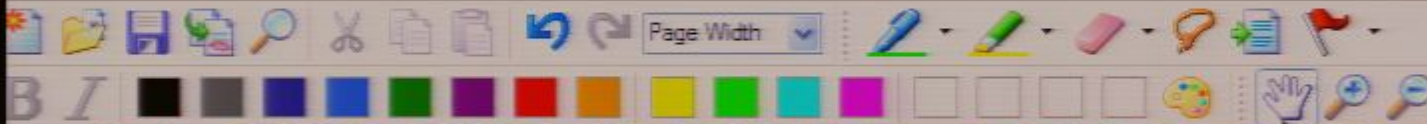
\square A cotangent vector field:

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In a chart: $\omega = \sum_{i=1}^n \omega_i(x) dx^i$

\square Similarly, tensor fields:

$t: \underset{\downarrow}{M} \rightarrow \underset{\downarrow}{T_p(M)^{\otimes r}}$, $t = \sum t_{i_1, \dots, i_r}^{j_1, \dots, j_r}(x) \frac{\partial}{\partial x^{j_1}} \dots \frac{\partial}{\partial x^{j_r}} dx^{i_1} \dots dx^{i_r}$



Def. Each point is called a section of the manifold.

Definition: For the algebra of (C^∞) functions $M \rightarrow \mathbb{R}$
we write $\mathcal{F}(M)$.

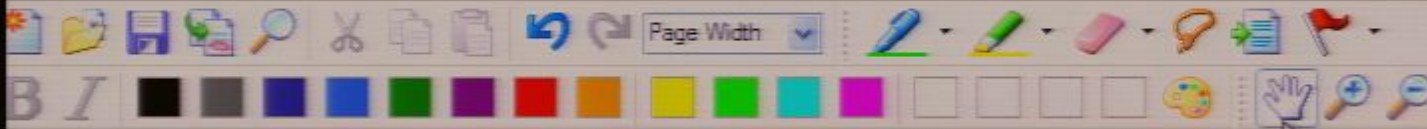
Note: One can show that vector fields
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If ξ is a contravariant vector field, then

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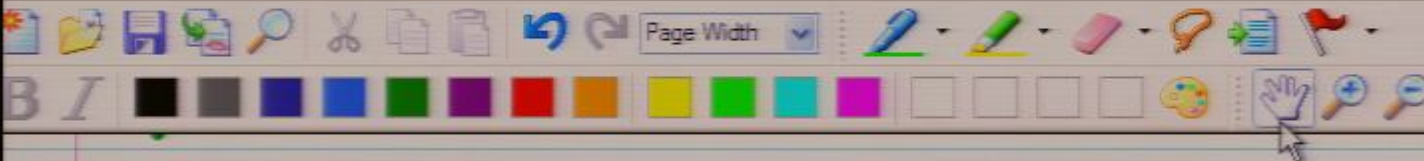
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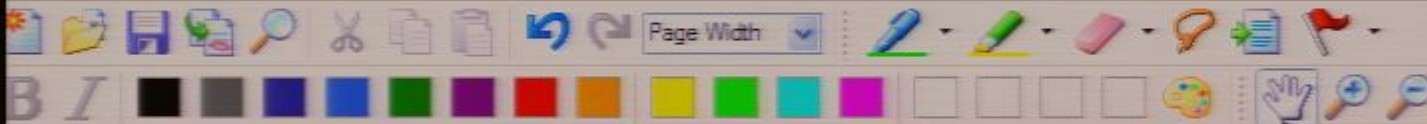
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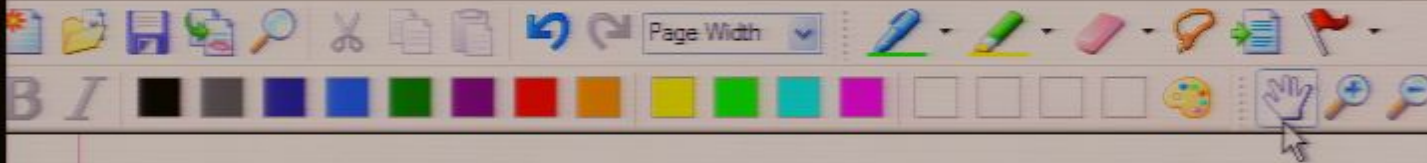
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Differential forms:

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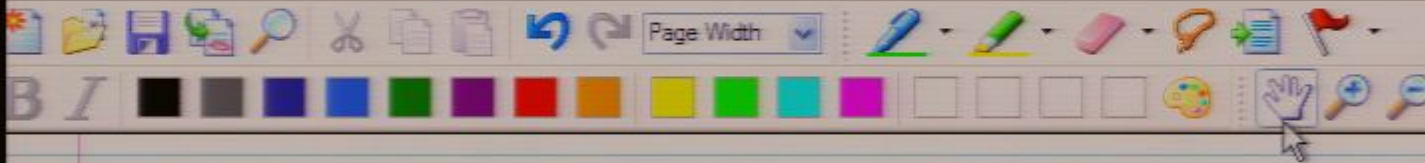
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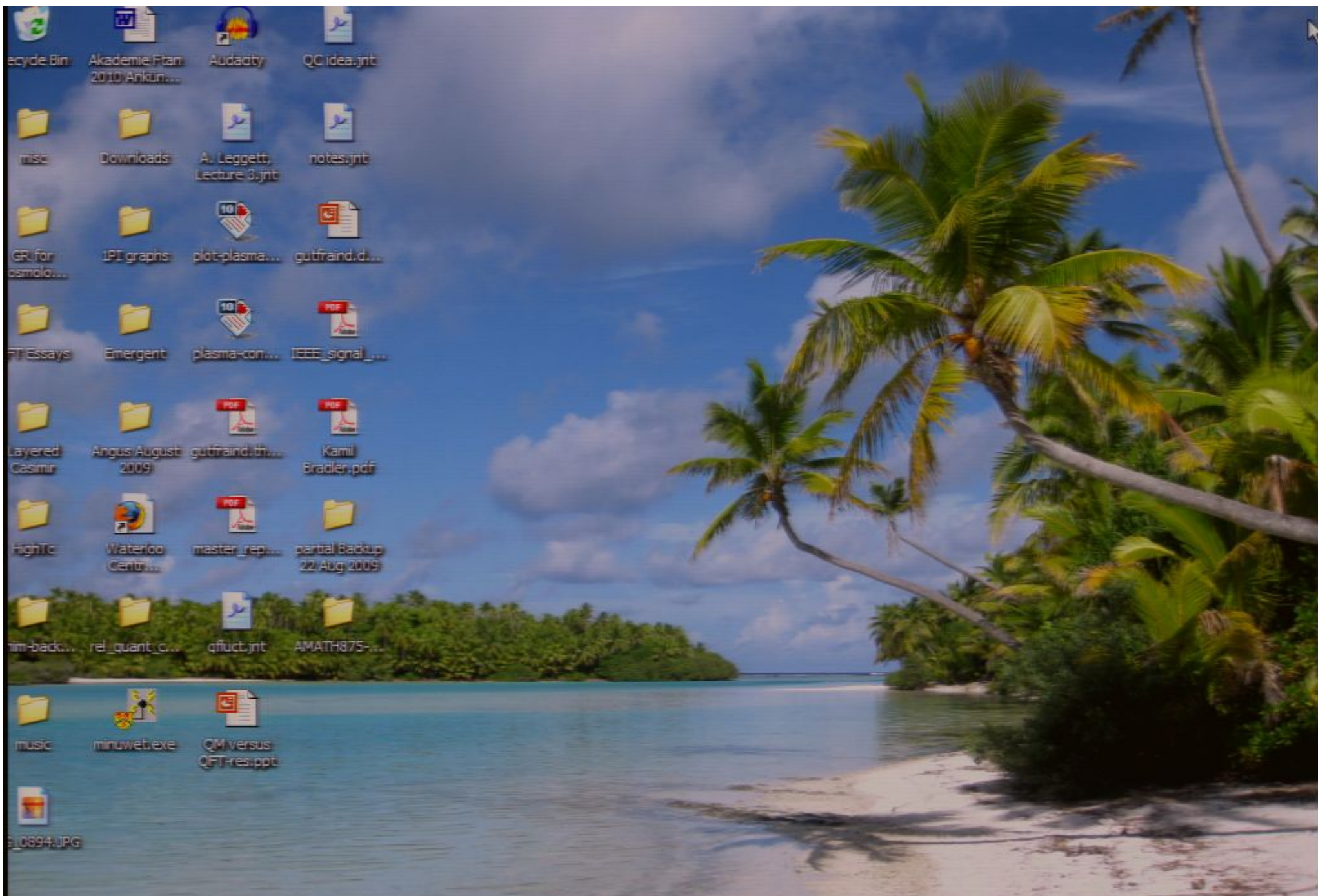
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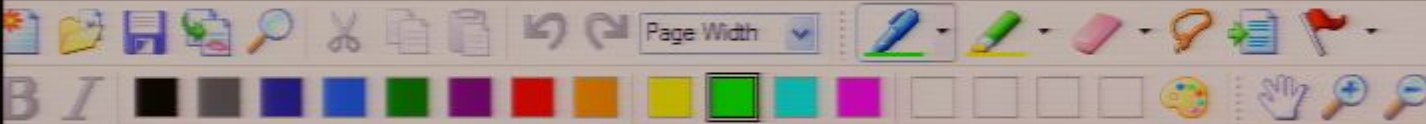
Differential forms:

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- The set of covariant vector fields is denoted Λ_1 , and called the set of 1-forms.



□ For $r = 2, 3, \dots$ the set, Λ_r , of r -forms is defined to be the set of totally anti-symmetric tensor fields of rank $(0, r)$.





Definition: If $r > 1$ and $v \in T_p(M)_r$, then we define the "anti-symmetric part of v " as the image $\tilde{v} = A(v)$ of the linear antisymmetrization map A :

$$\tilde{v}(\xi_1, \dots, \xi_r) = A(v)(\xi_1, \dots, \xi_r)$$

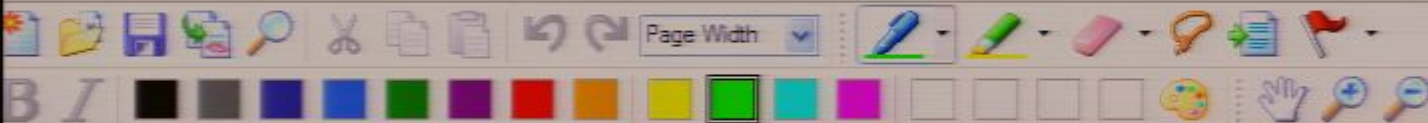
$$:= \frac{1}{r!} \sum_{\sigma \in S_r} \text{sgn}(\sigma) v(\xi_{\sigma(1)}, \dots, \xi_{\sigma(r)})$$

the sign (± 1) of the permutation σ

Why consider these?

They will be key for integration! Only antisym. cov. tensors transform under chart change so as to match the Jacobian determinant arising in integrals when changing charts.

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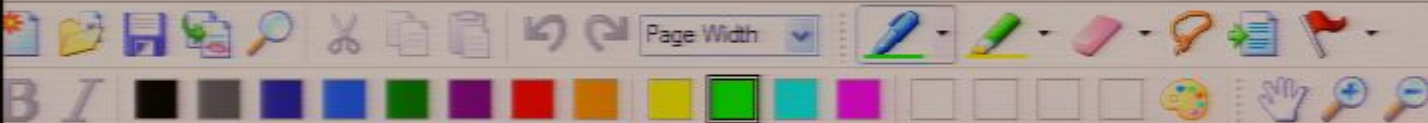
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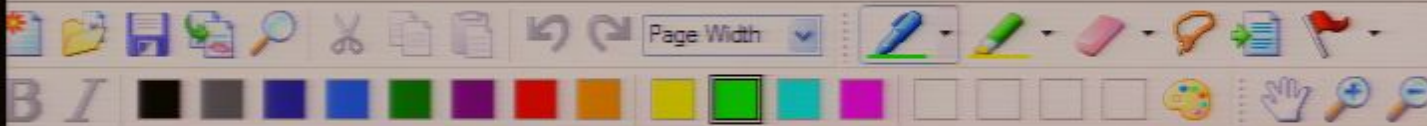
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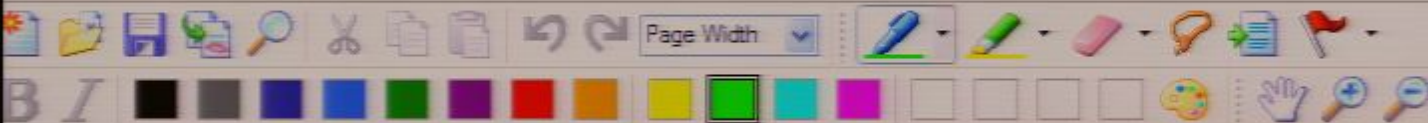
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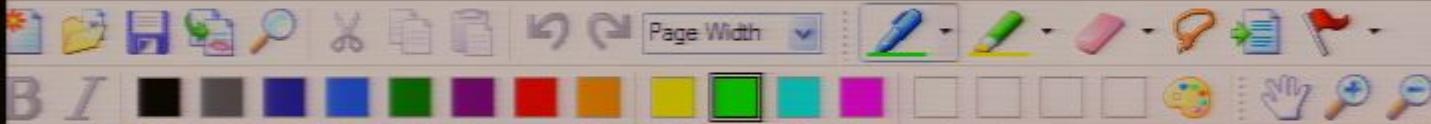
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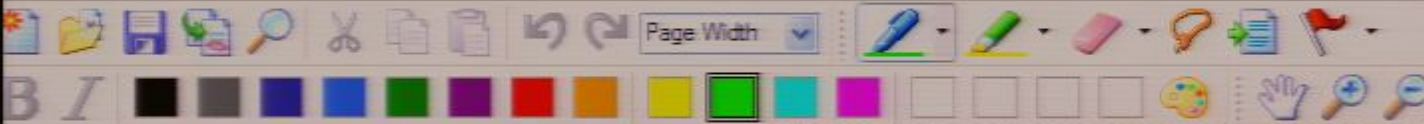
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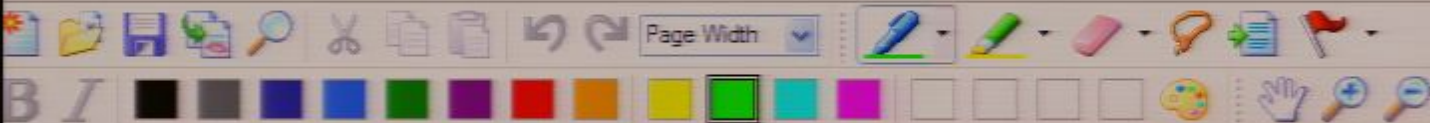


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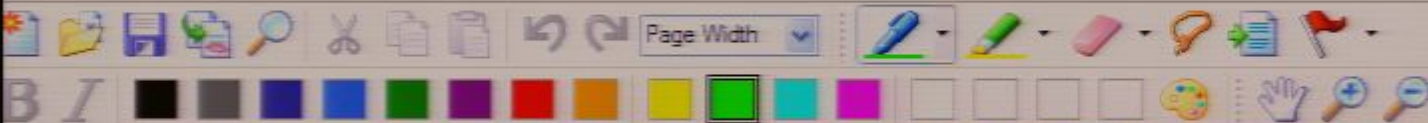
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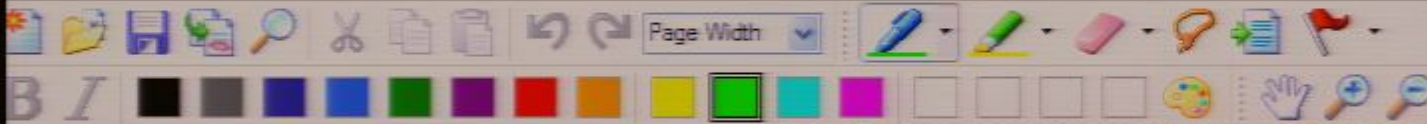
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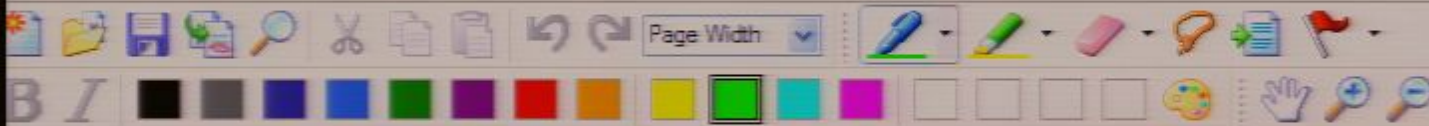
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$$A(df \otimes dg) = \frac{1}{2} (df \otimes dg - dg \otimes df)$$



□ Consider $v := df \otimes dg$, for $f, g \in \mathcal{F}_p(M)$

□ Then $v(\xi_1, \xi_2) = df(\xi_1) dg(\xi_2)$ (which is $\xi_1(f) \xi_2(g)$)

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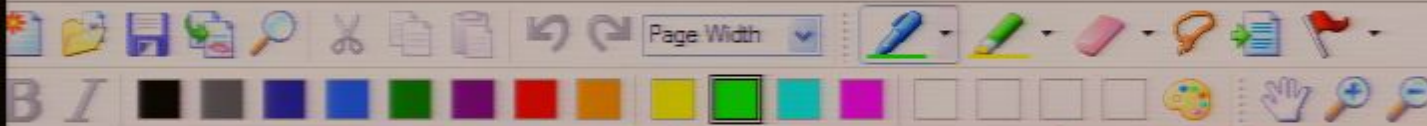
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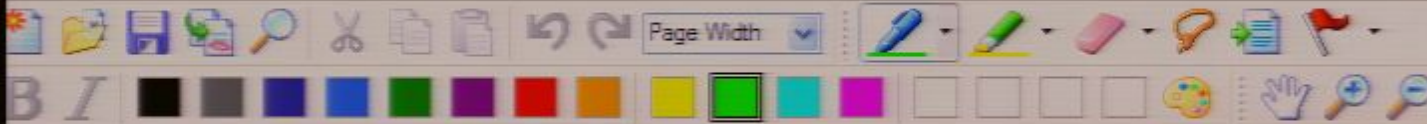
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Check in above example:

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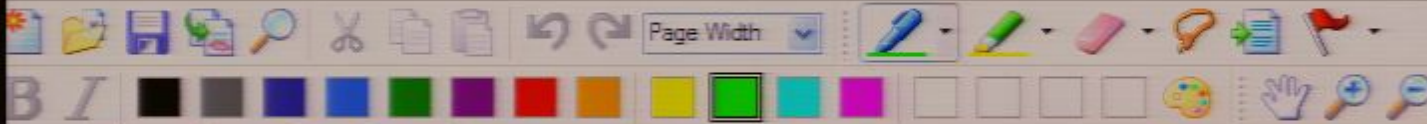
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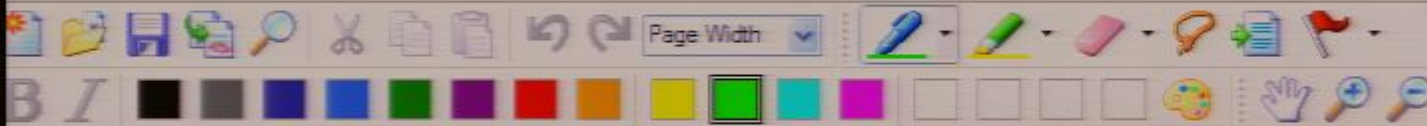
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For $r > 1$ we define the space of differential r -forms (or 'exterior' r -forms) $\Lambda_r(p)$ at $p \in M$ as the subspace of totally anti-symmetric tensors

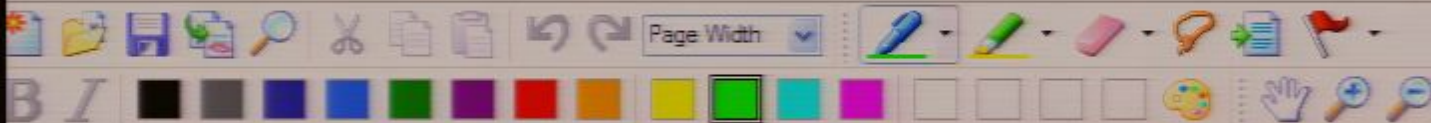
of rank $(0, r)$:

$$\Lambda_r(p) := A T_p(M)_r$$

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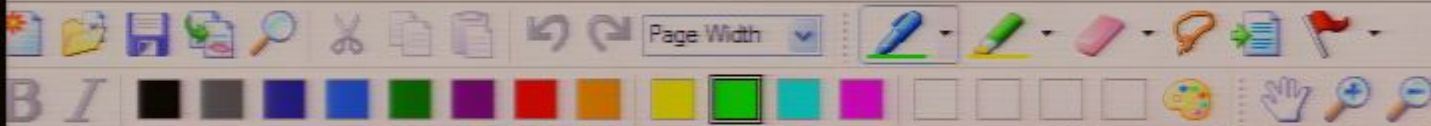
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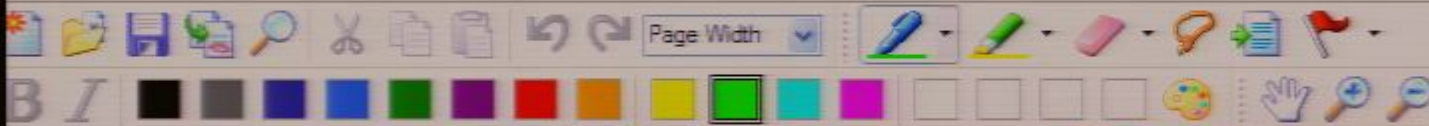
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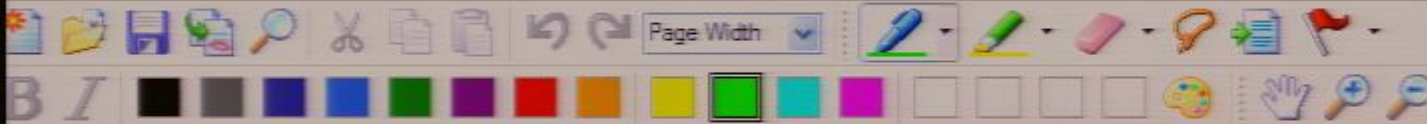
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Properties of \wedge :

□ bi-linear:

$$(\omega + \nu) \wedge \eta = \omega \wedge \eta + \nu \wedge \eta$$

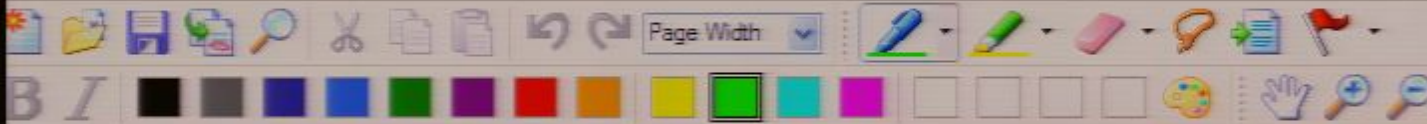
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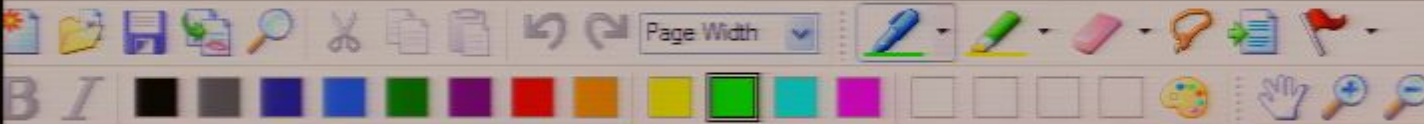
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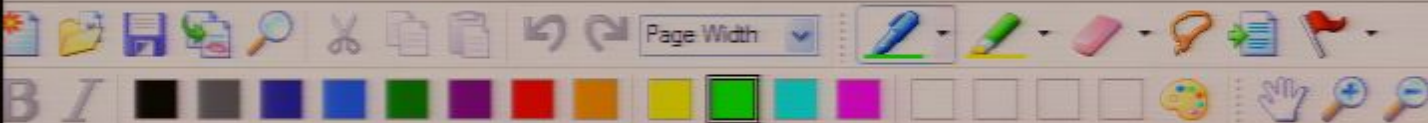
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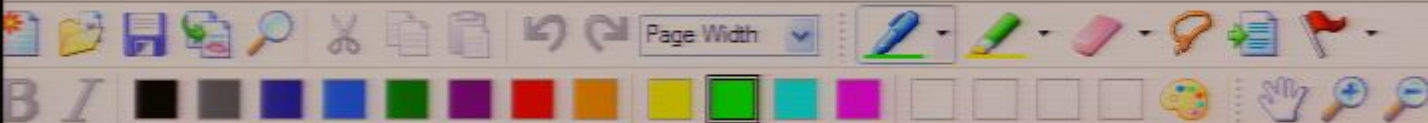
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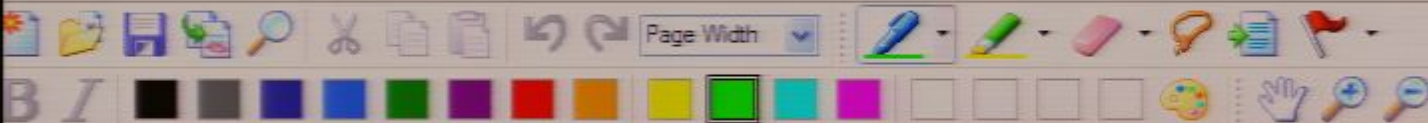
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□ We can use \wedge to build bases of $\Lambda_r(p)$:

Assume: $\{\theta^i\}_{i=1}^m$ is a basis of $\Lambda_1 = T_p(M)^*$.

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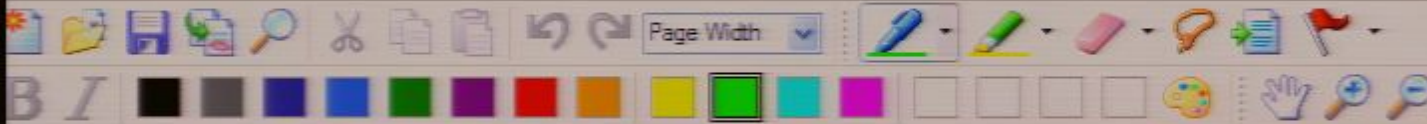
Then: $\{\theta^{i_1} \wedge \theta^{i_2} \wedge \dots \wedge \theta^{i_r}\}_{1 \leq i_1 < i_2 < \dots < i_r \leq m}$
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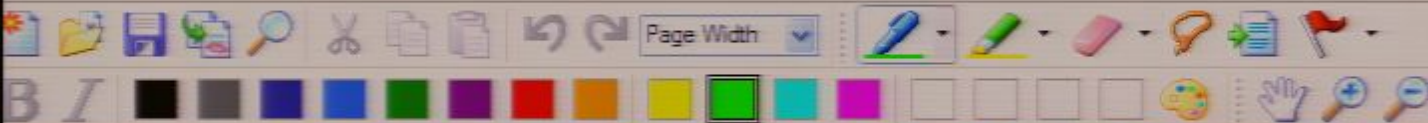
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$(\dim(\Lambda) = 2^n)$ $\Lambda(p) := \bigoplus_{i=0}^n \Lambda_i(p)$ equipped with the multiplication \wedge , is an associative algebra, called the exterior algebra or the Grassmann algebra over $T_p(M)$.

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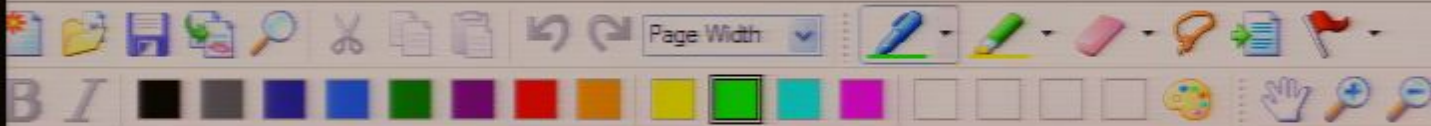
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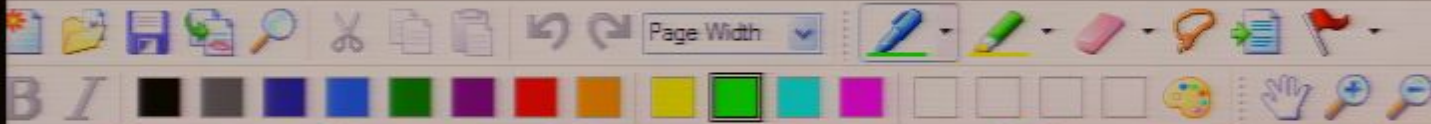
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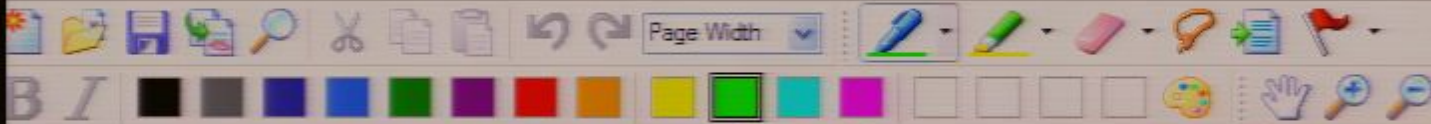
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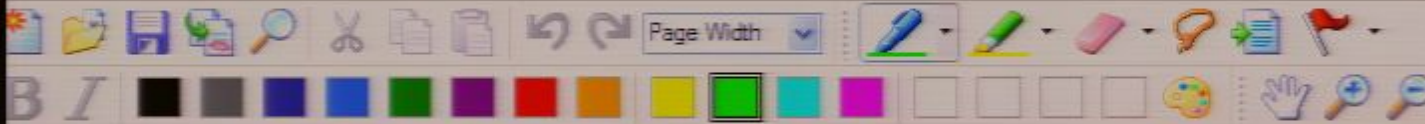
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Generalization to fields:

□ A differential form field is a mapping that associates to each $p \in M$ an element:

$$\omega(p) \in \Lambda(p)$$



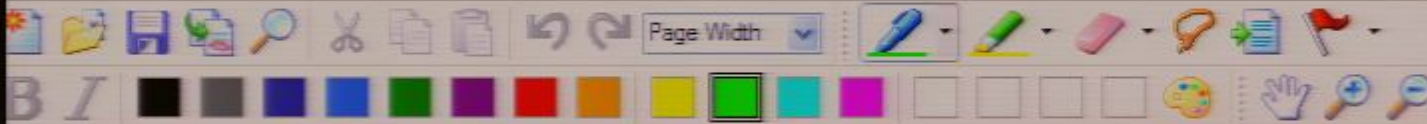
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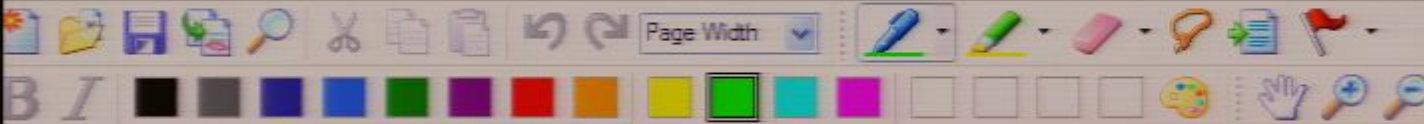
- ▢ They form the Grassmann algebra of differential forms, $\Lambda(M)$.



Recall:

Given an algebra, it is often useful to consider derivations of the algebra, i.e. to consider maps that obey the Leibniz rule. (we defined tangent vectors as derivations of $F_r(M)$)

Here: For the algebra $\Lambda(M)$, let us consider the exterior and the inner derivations:



Definition:

A linear map $\Phi: \Lambda(M) \rightarrow \Lambda(M)$ is called a derivation of degree k , if:

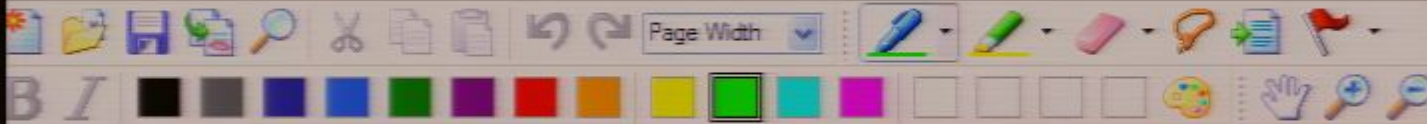
$$\Phi: \Lambda_s(M) \rightarrow \Lambda_{s+k}(M) \quad \text{for all } s$$

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Leibniz rule \nearrow

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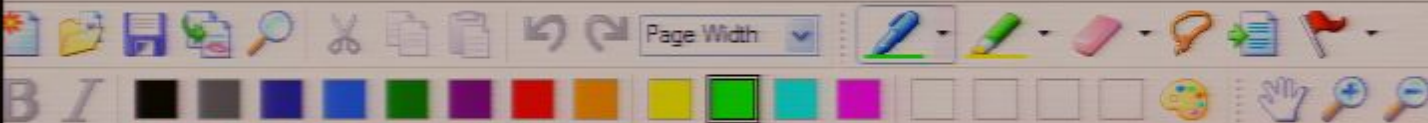
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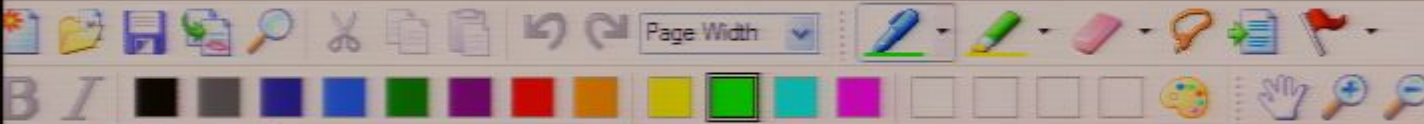
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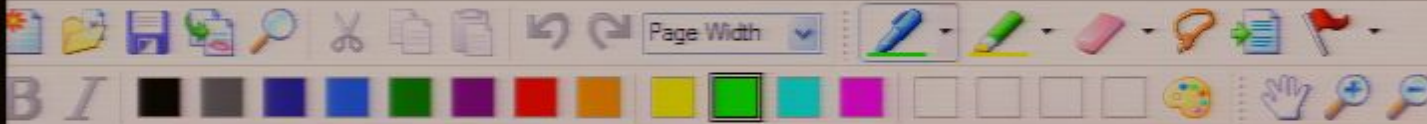
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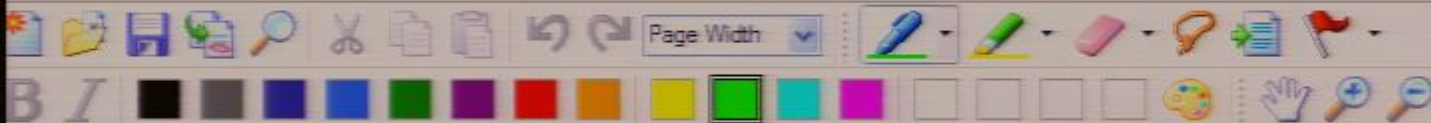


Proposition:

(Because of the Leibniz rule and linearity) any (anti-)derivation

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is already fully determined by its action only on $\Lambda_0(M)$ and on a basis of $\Lambda_1(M)$.

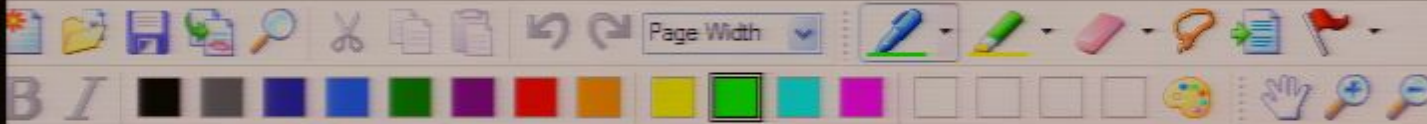


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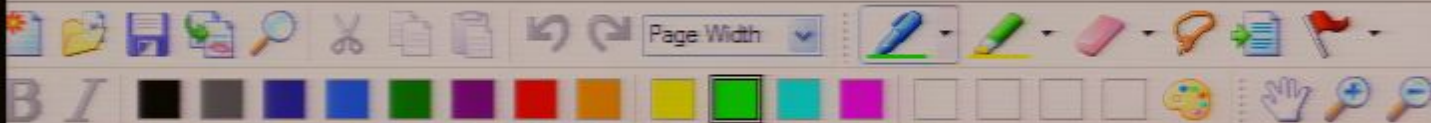
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THE EXTERIOR DERIVATIVE

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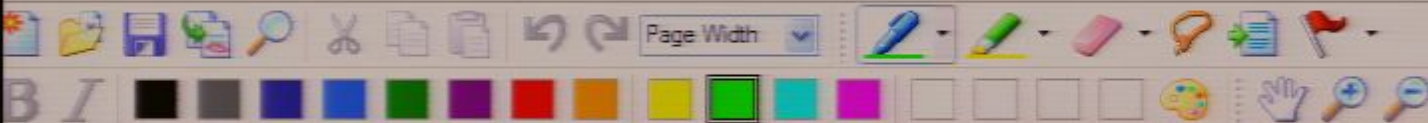
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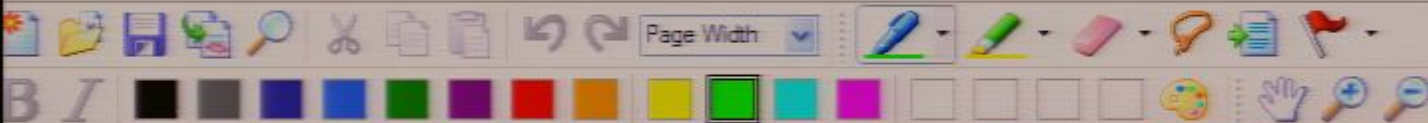
Now we have more generally, e.g. for

$$\beta = \sum_{i_1, \dots, i_s} \beta_{i_1, \dots, i_s}(x) \wedge dx^{i_1} \wedge \dots \wedge dx^{i_s} \in \Lambda_s(M)$$

\Rightarrow like $f(x)$ above

$$d: \beta \rightarrow d\beta$$

namely, by applying the anti-Leibniz rule:



□ $d: dx^i \rightarrow 0$ for all i . } action of d on a basis of $\Lambda_1(M)$

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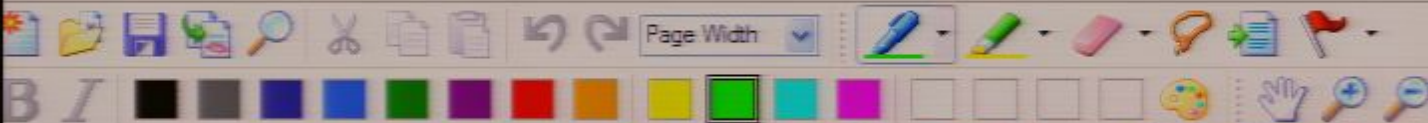
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$\alpha, dx \rightarrow \dots$ for $\alpha \in \dots$ basis of $\Lambda_1(M)$

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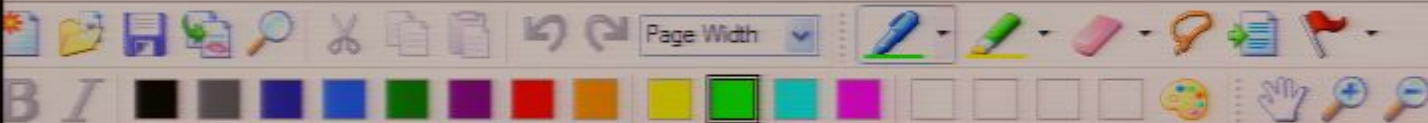
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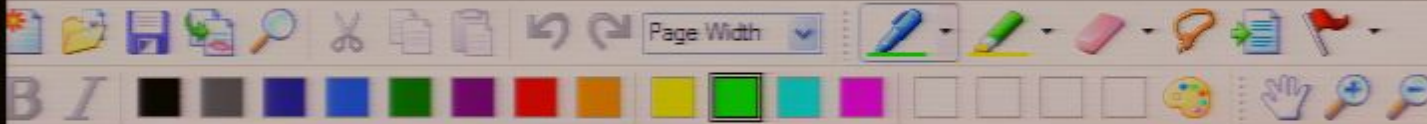
$\Lambda_0(M)$ above $\beta_{i_1, \dots, i_s}(x)$ and $\in \Lambda_s(M)$ above $\wedge dx^{i_1} \wedge \dots \wedge dx^{i_s}$

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The exterior derivative

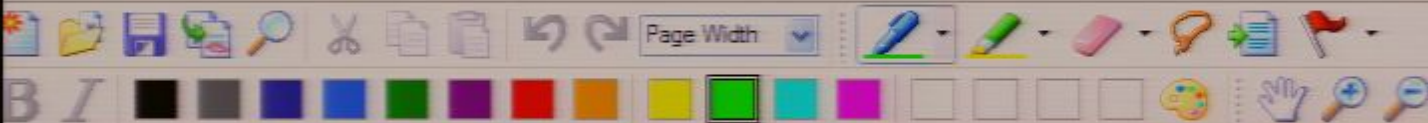
The exterior derivative,

$$d: \Lambda(M) \rightarrow \Lambda(M)$$

is the anti-derivation of degree $K=1$
defined through:

$$\left. \begin{array}{l} \square \quad d: \Lambda_0(M) \rightarrow \Lambda_1(M) \\ \quad \quad d: \quad \quad f \rightarrow df \end{array} \right\} \text{action of } d \text{ on } \Lambda_0(M)$$

$$\square \quad d: dx^i \rightarrow 0 \text{ for all } i. \left. \right\} \text{action of } d \text{ on a basis of } \Lambda_1(M)$$



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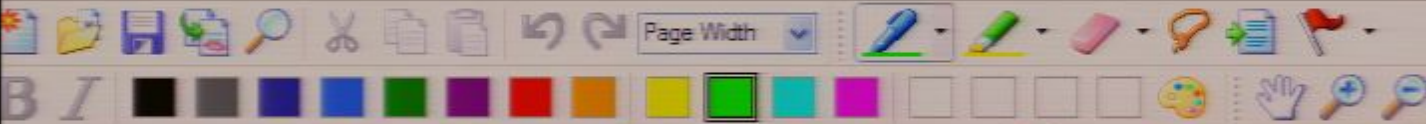
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+ terms of the form $d(dx^{i_1} \wedge \dots \wedge dx^{i_s})$



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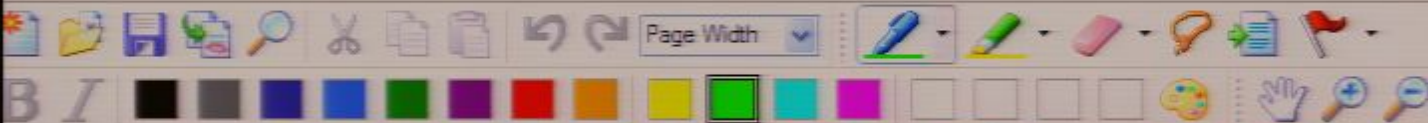
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+ terms of the form $d(dx^{i_1} \wedge \dots \wedge dx^{i_s})$

= 0 because when applying Leibniz rule to $d(dx^{i_1} \wedge \dots \wedge dx^{i_s})$ we eventually



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Proposition:

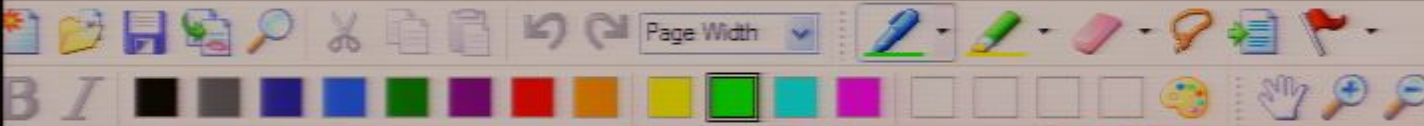
$d: \Lambda(M) \rightarrow \Lambda(M)$ obeys:

$$d \circ d = 0$$

Proof:

$$d \circ d(\beta) = \sum_{\substack{i_1 < \dots < i_p \\ j, k}} \frac{\partial^2 \beta_{i_1, \dots, i_p}(x)}{\partial x^j \partial x^k} \underbrace{dx^k \wedge dx^j \wedge dx^{i_1} \wedge \dots \wedge dx^{i_p}}_{\substack{\text{Sym. in } j, k \\ \text{i.e. antisym. in } j, k}}$$

$$= 0$$



$\underbrace{c_1 \dots c_n}_{i_1, \dots, i_n} dx^{i_1} \wedge \dots \wedge dx^{i_n}$

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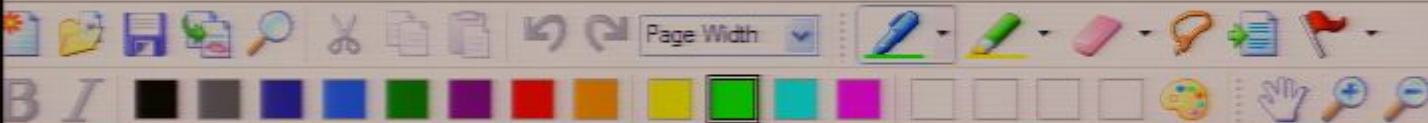
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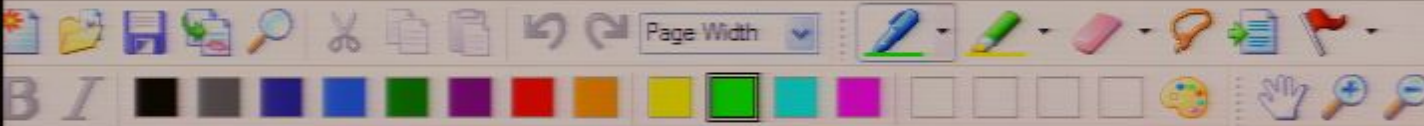
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Example:

□ For $M = \mathbb{R}^3$ and $f \in \mathcal{F}(M)$ we have:

e.g.: electric potential

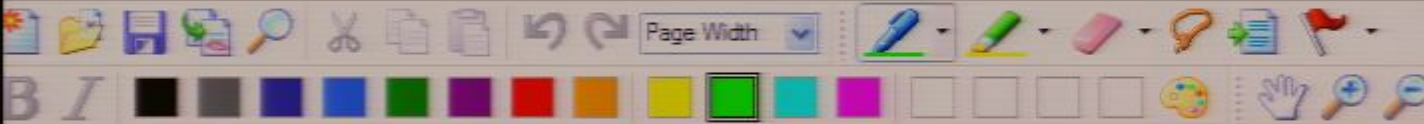
$$df = \sum_{i=1}^3 \frac{\partial f}{\partial x^i} dx^i$$

□ Notice:

$\left(\frac{\partial f}{\partial x^1}, \frac{\partial f}{\partial x^2}, \frac{\partial f}{\partial x^3} \right)$ is the

"Gradient field ∇f of f "

e.g. electric force on a test charge



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□ Now assume $\mu \in \Lambda_1(M)$ is an