

Title: General Relativity for Cosmology - Lecture 1

Date: Sep 21, 2009 04:00 PM


URL: <http://pirsa.org/09090012>


Abstract:

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[www.math.uwaterloo.ca/~akempf/AMATH875-F09.shtml](http://www.math.uwaterloo.ca/~akempf/AMATH875-F09.shtml)

Out of the ordinary... out of this world.  hubblesite.org



The 'Tadpole' galaxy

≈ 420 M. light yrs away

billions of light yrs away!

Pirsa: 09090012

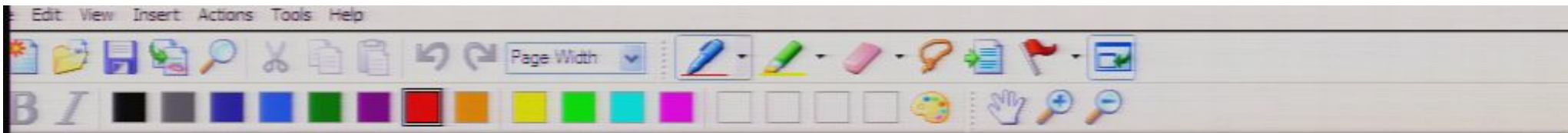
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1 / 14

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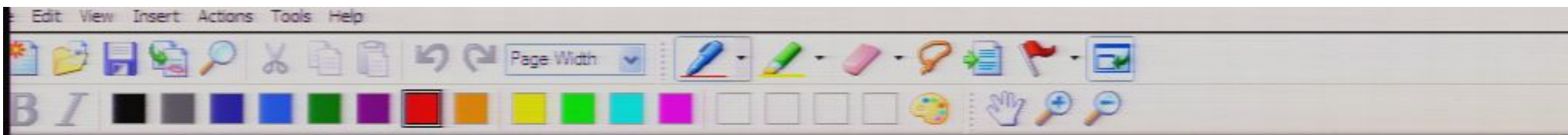


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Age of the universe?

$\approx 13.7$  billion yrs

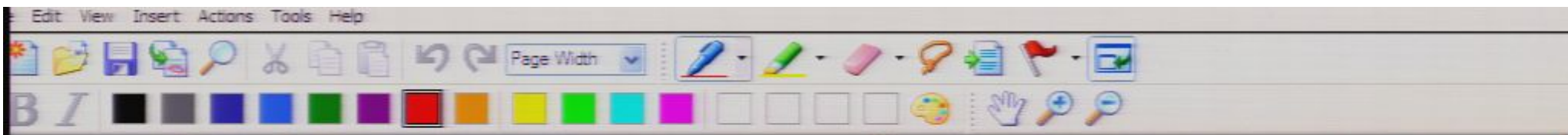


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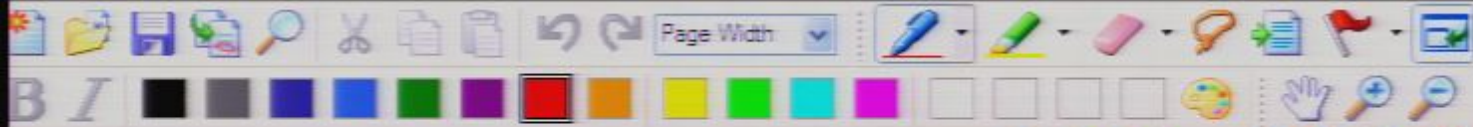


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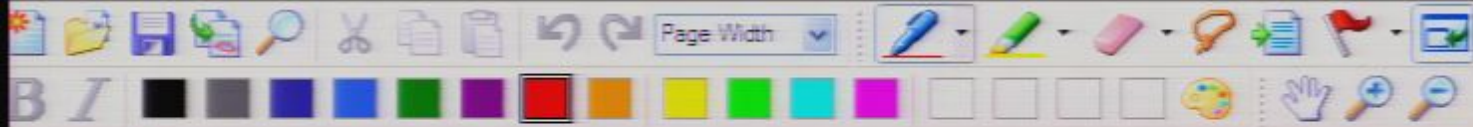


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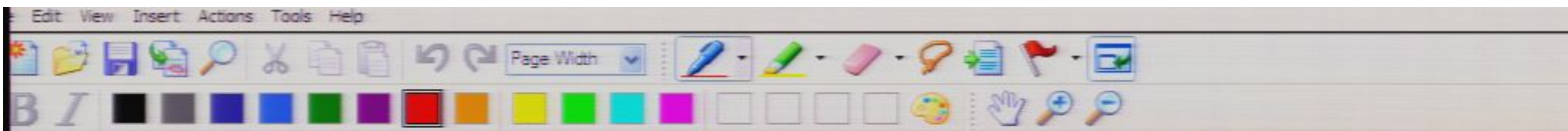
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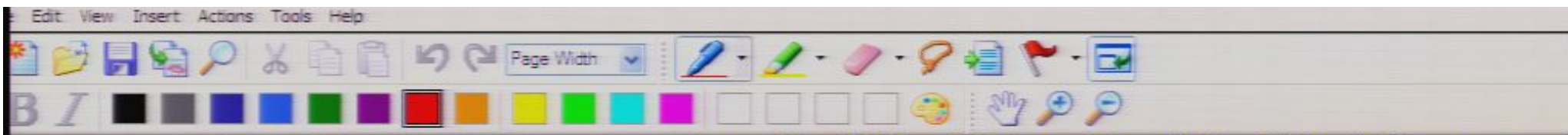


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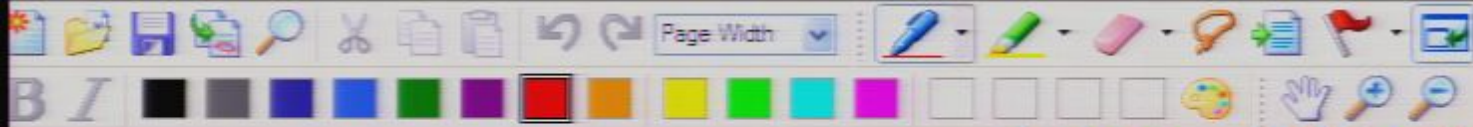


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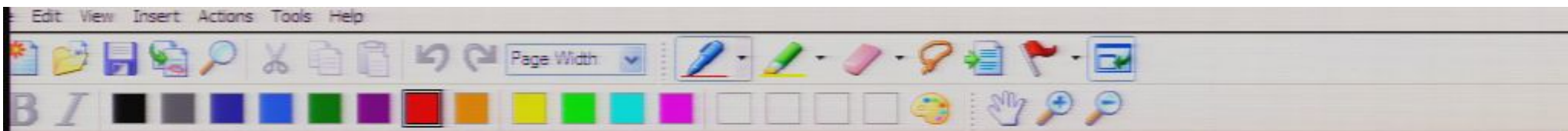
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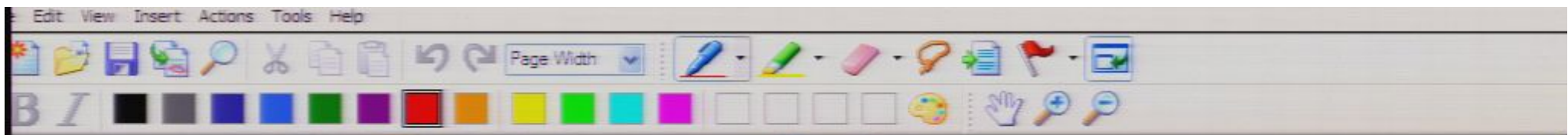


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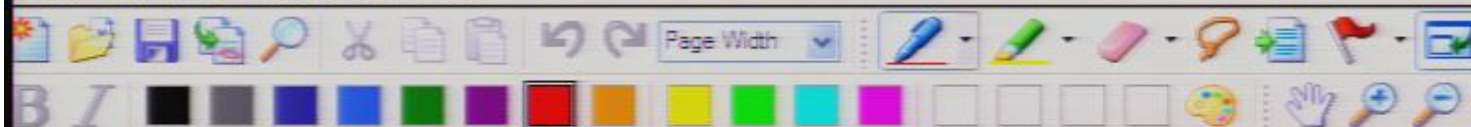


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## General Relativity for Cosmology

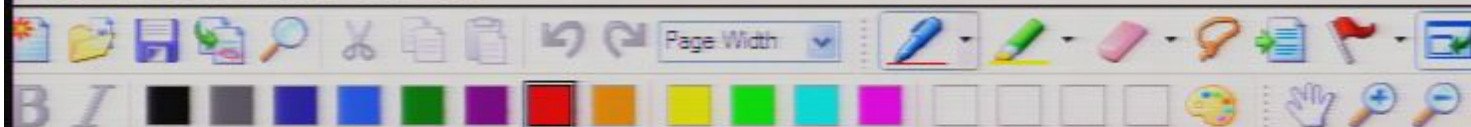
Fall 2009

AMATH 875 / PHYS 786

- Instructor:** [A. Kempf](#) (MC6071, ext. 5462)
- Prerequisite:** Introductory general relativity, e.g., AMATH 675.
- Time and venue:** Mon + Thu 4-5:20pm, Bob room at PI.  
**Video-linked to:**
- \* Univ. of Waterloo, Room MC6091
  - \* Univ. of Guelph, Room Rozanski106.
  - \* McMaster Univ., Room ABB131
- Office hours:** by arrangement
- Literature:** Detailed lecture notes will be freely available electronically. Also, see the texts listed below.

### Outline:

This course begins by introducing the differential geometry of Lorentzian manifolds from scratch and then builds up quickly to the advanced framework in terms of differential forms and the vielbein formalism. These methods are then used to define general relativity, also as a gauge theory. We then study some of general relativity's deeper properties, such as the formalism of spinors, and aspects of the causal structure and singularities. One key goal is to lay the foundations for students who wish to proceed to studies in quantum gravity. We then apply general relativity to cosmological models and to cosmological perturbation theory. Thereby, we are covering the theory of cosmic inflation which is very successful in predicting in



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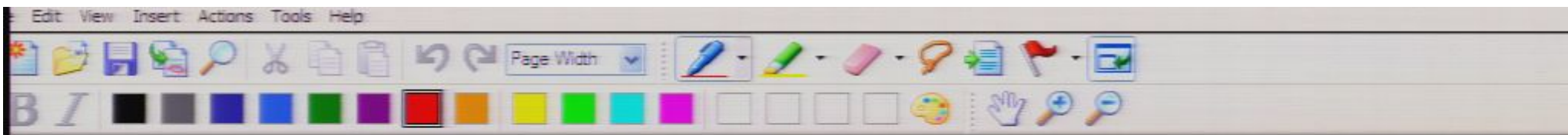
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### Lecture Notes:

To be posted here.

In the meanwhile, here are those of F07, in pdf format: [1](#), [2](#), [3](#), [4](#), [5](#), [6](#), [7](#), [8](#), [9](#), [10](#), [11](#), [12](#), [13](#), [14](#), [15](#), [16](#), [17](#), [18](#), [19](#), [20](#), [21](#), [22](#)

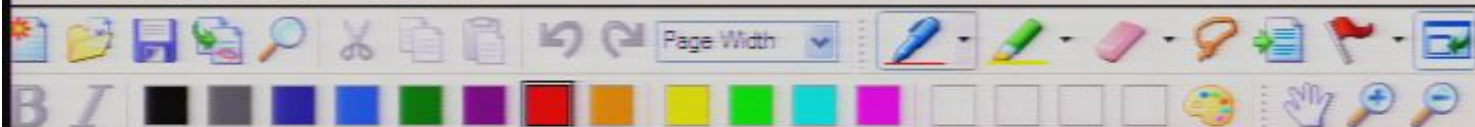
(You may also be interested in viewing the colloquium that I gave at Perimeter Institute on Sep. 16, 2009:

*"Spacetime can be simultaneously continuous and discrete, the same way that information can".*

For the recording, see [here](#).)

### Additional literature

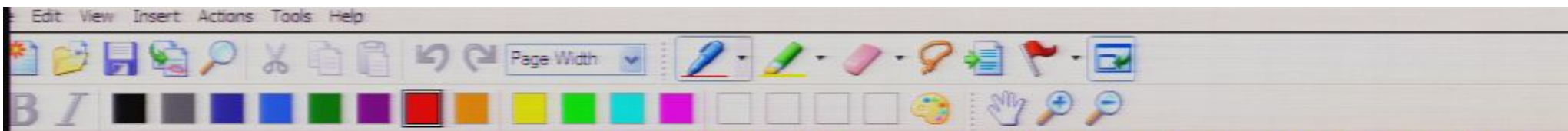
Our introduction to the differential geometry for General relativity uses material mainly from these three texts, while our notation conforms with that of the text by Straumann:



symmetric between A and B,  
as it must be by the principle  
of relativity.

The time ...

- B can use above calculation and concludes that A's wrist watch lags behind his coordinate system's clocks that it passes.



is accelerating, so that above calculation fails.

Note: It seemed a small problem

because can always choose to work in

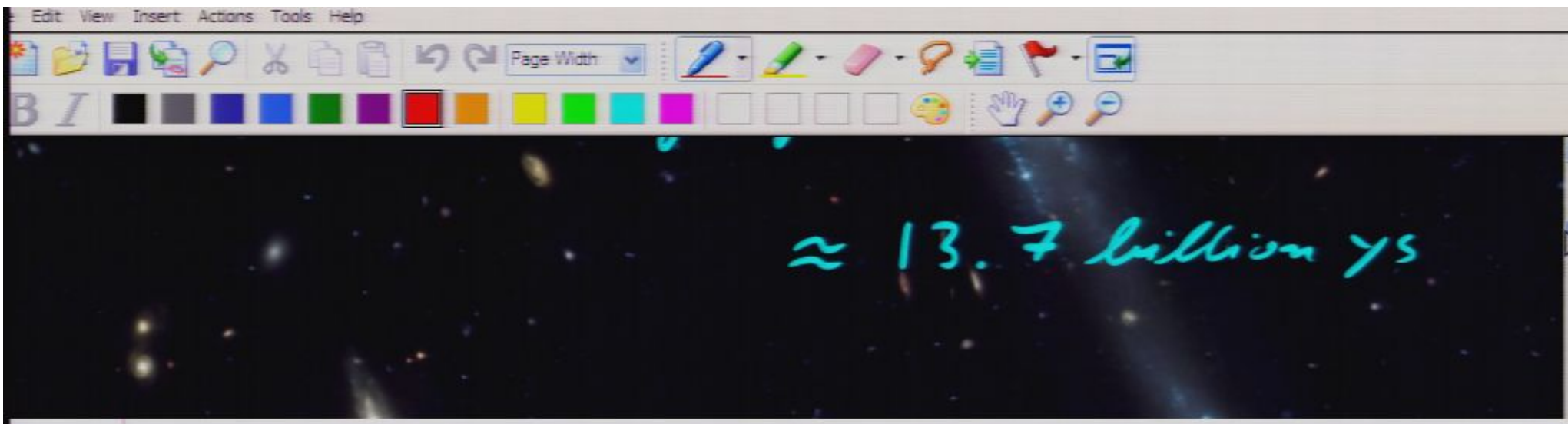
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because can always choose to work in

an inertial coordinate system - and in it

the laws of nature take the usual form.

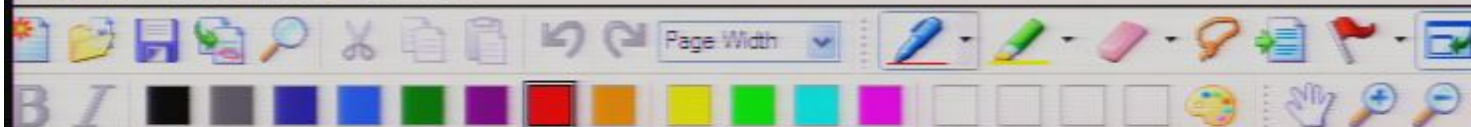


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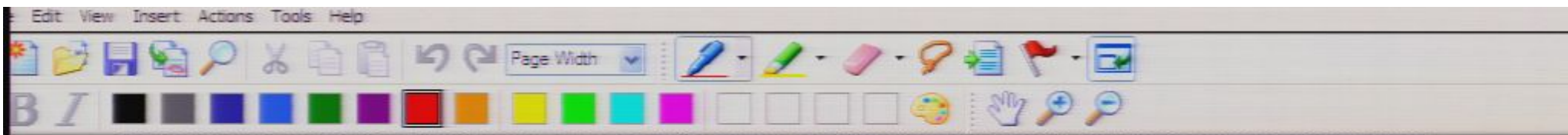
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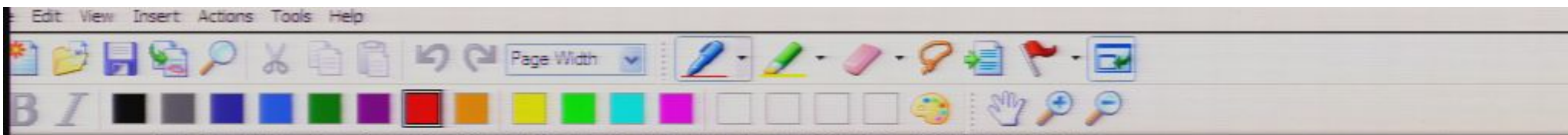
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3. S. Hawking, G.F.R. Ellis, *The Large Scale Structure of Space-Time*, Cambridge (1973)

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3. G.F.R. Ellis and J. Wainwright, *Dynamical Systems in Cosmology*, CUP (1997)
4. R. M. Wald, *General Relativity*, University of Chicago Press (1984)
5. H. Stephani, *General Relativity*, Cambridge University Press (CUP) (1982)





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We will cover Sakharov's "induced gravity" argument. Find the original (very short) paper here: [Sakharov](#), and this [review](#).

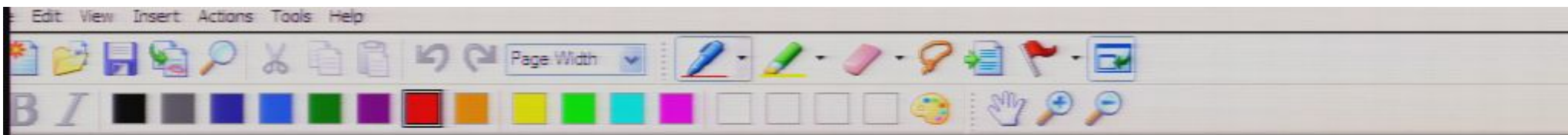
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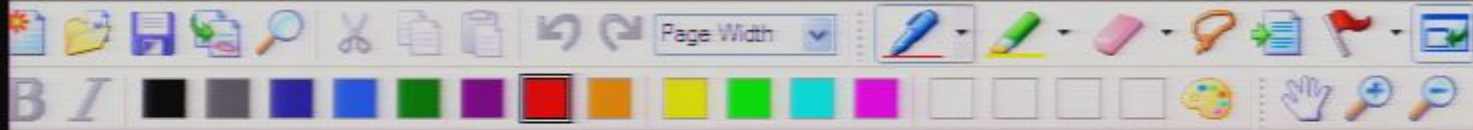
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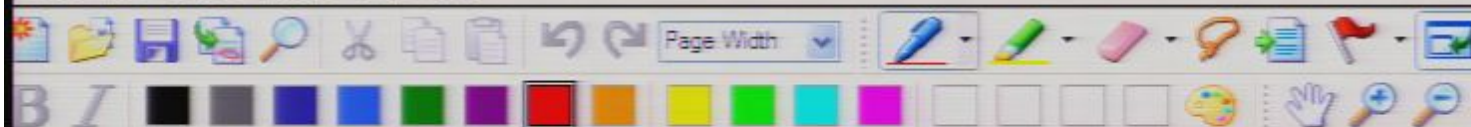
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- PHYS784/AMATH874, *Advanced Techniques in General Relativity and Applications to Black Holes (and gravitational waves)*, taught W08, W10, etc.
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These courses can be taken in arbitrary sequence and no course is a pre- or anti- requisite for another.



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Department of Applied Mathematics  
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Waterloo, Ontario  
Canada N2L 3G1  
Phone: (519) 888-4567 ext. 2700  
Fax: (519) 746-4319



## 2. [Straumann \(2005\)](#)

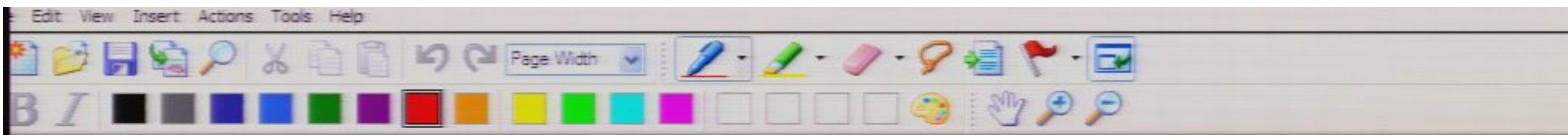
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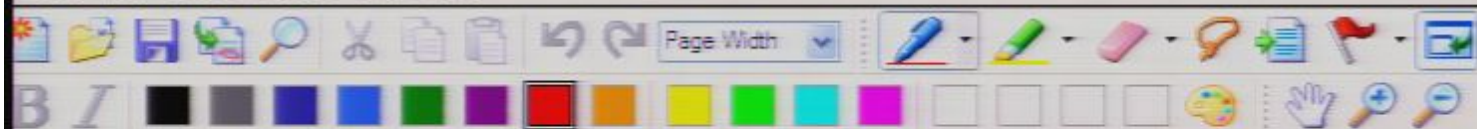
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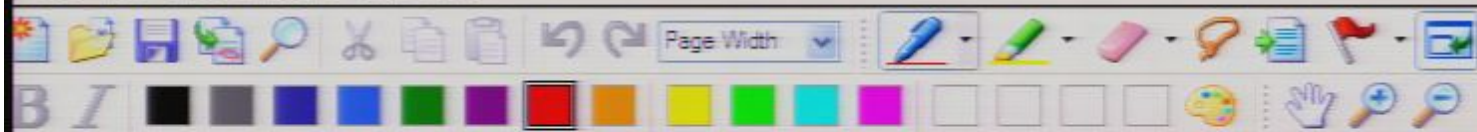
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- Review of aspects of Special Relativity and motivation for General Relativity

This is assigned reading!

Plan:

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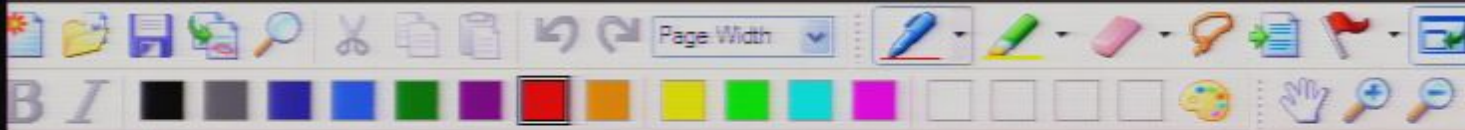
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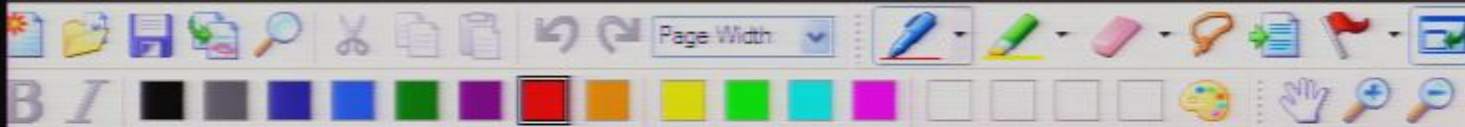


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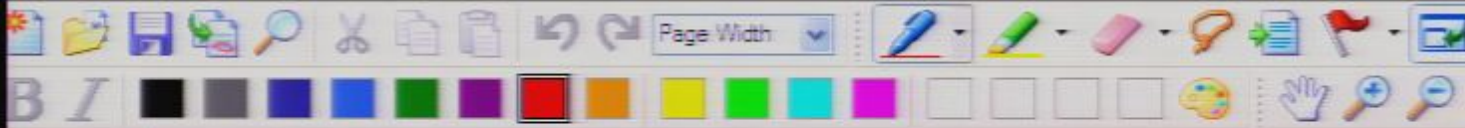
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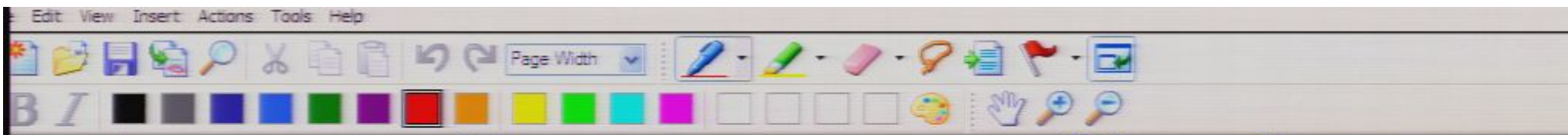
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Review: Special Relativity

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D: ... + D ... + ?

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A:

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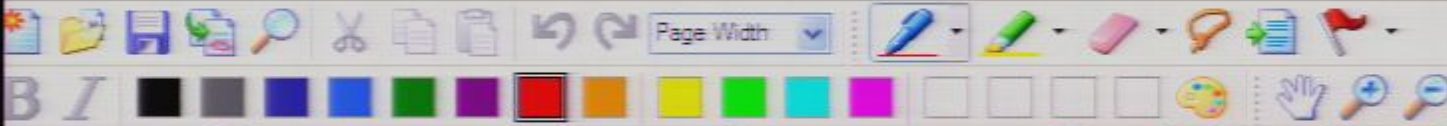
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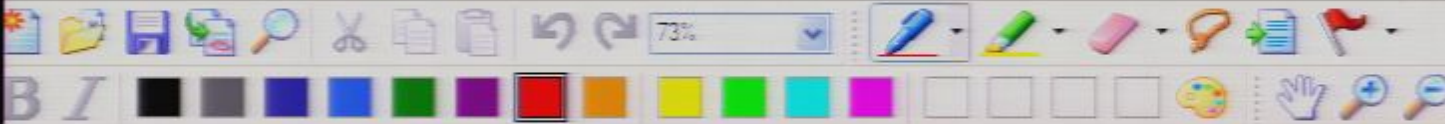
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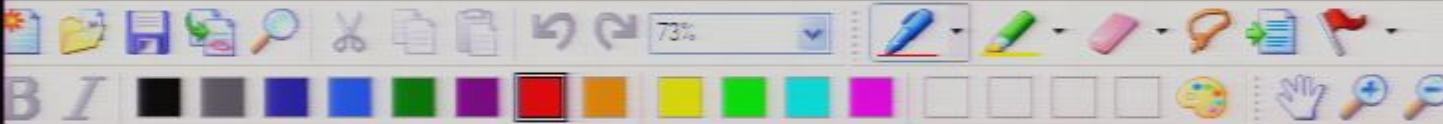
## GR for Cosmology, Fall 09, Achim Kempf, Lecture 2

Note Title

9/18/2005

What had Einstein achieved with special relativity?

- Laws of nature took the same form in all inertial, cartesian coordinate systems (i.e. in all coordinate systems that are a freely moving rectangular arrangement of equal length rods with synchronized clocks at the vertices).
- He could deduce the form of the laws of nature in an arbitrary coordinate system



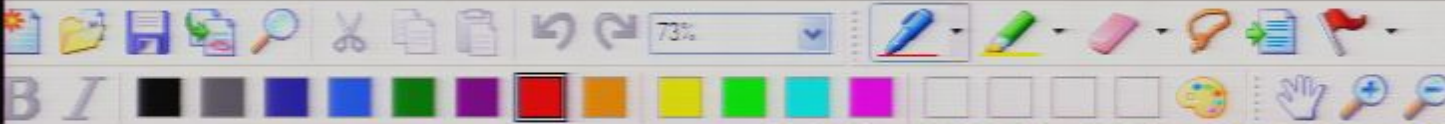
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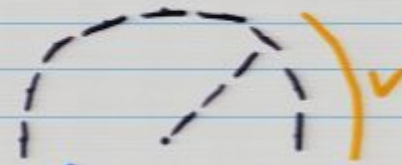
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rest may not be synchronized.

(Recall that as the travelling twin accelerates he cannot keep his cds's clocks synchronized)

**E.g.:** Consider, built from equally-made rods, in an inertial cartesian cds:

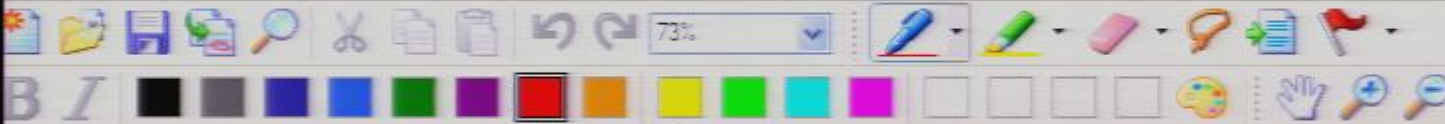


$$\frac{\text{Circumference}}{\text{Diameter}} = \pi$$

fit around.

→ The radial rods get thinner but stay the same length. Thus, as many as usual fit on the radius.

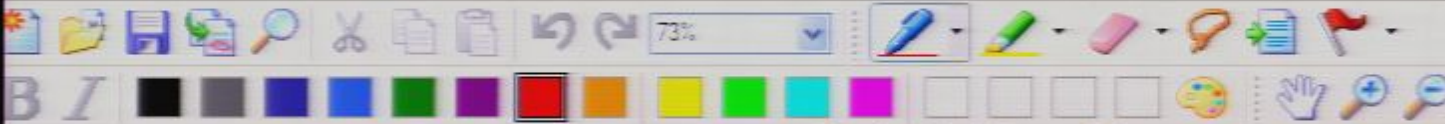
→ But now consider this in a rotating cds in which all rods are at rest.



o the direction.

2. Rather than seeing this as the complete downfall of special relativity, Einstein conjectured:  
Even in the presence of gravity, an inertial, cartesian coordinate system can be constructed around

every point (event), with arbitrary precision, at least in a suitably small neighborhood of that point. And, the laws of special relativity hold in that local coordinate system.

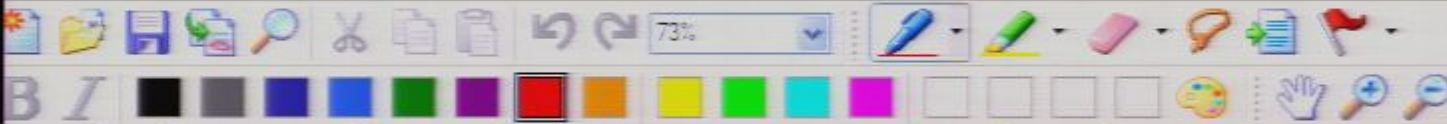


pulled differently.

3. Einstein remembered a similar problem earlier faced by Riemann:

- Euclidean geometry is nice and simple, but how to describe a smooth but curved manifold?
- Riemann solved the problem after observing that at each point such manifolds are flat to any arbitrary precision - within a sufficiently small neighborhood.

⇒ Einstein's strategy:



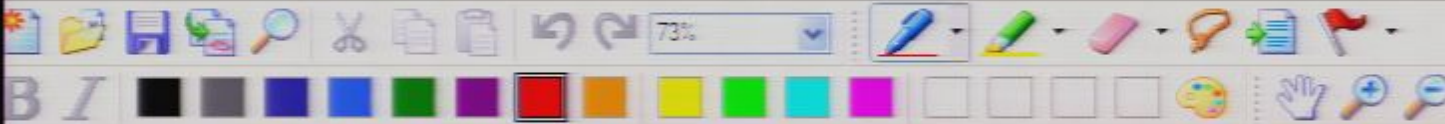
# Pseudo-Riemannian Differential Geometry

## A. Differentiable Manifolds

(Riemann  $\approx$  1850s, Poincaré  $\approx$  1890s, Whitney  $\approx$  1930s...)

Def: An  $n$ -dimensional topological manifold,  $M$ , is a Hausdorff space which is locally homeomorphic to  $\mathbb{R}^n$ .



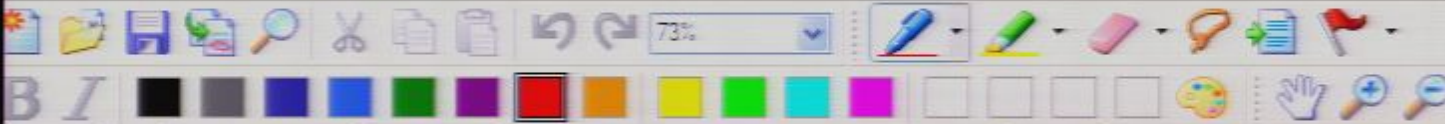


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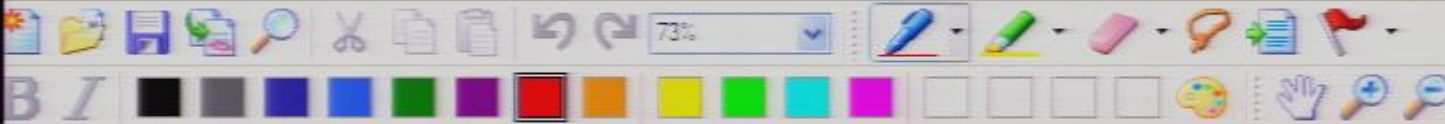


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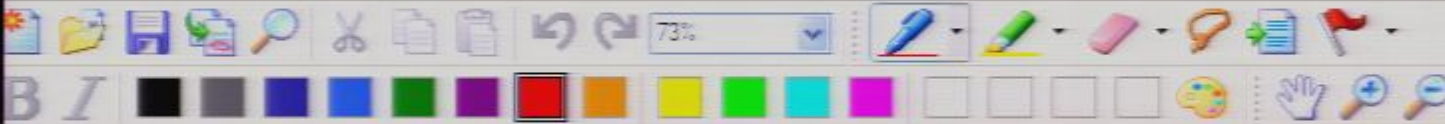


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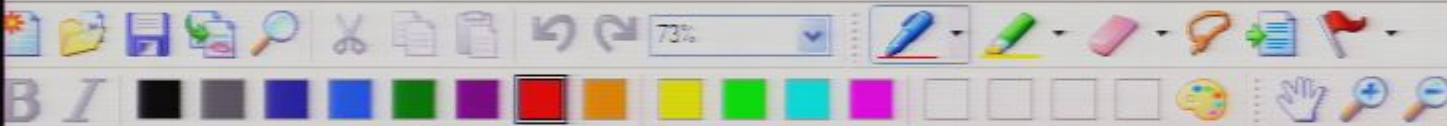
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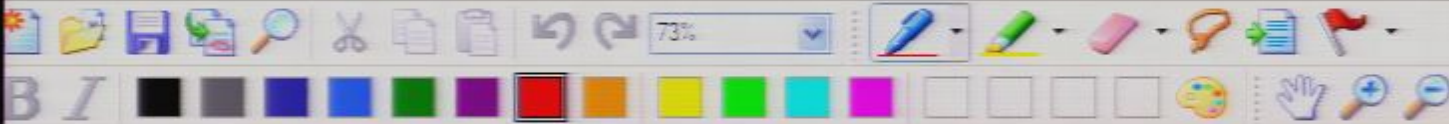
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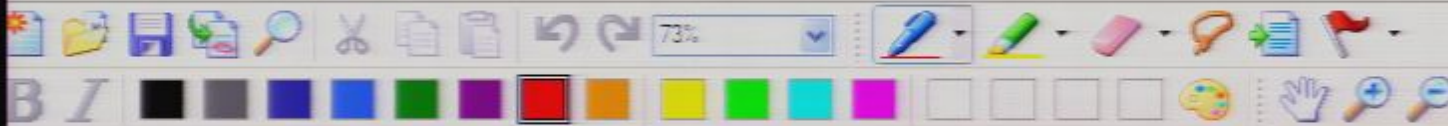
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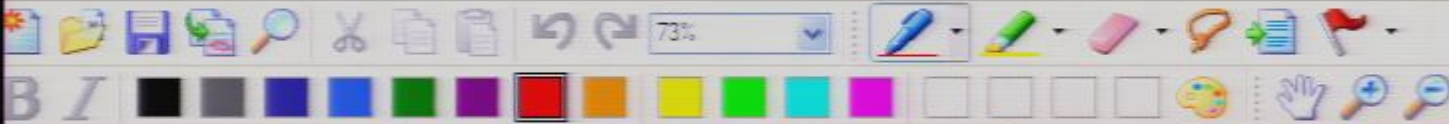


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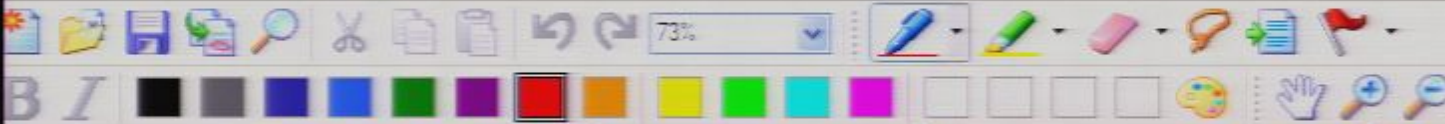
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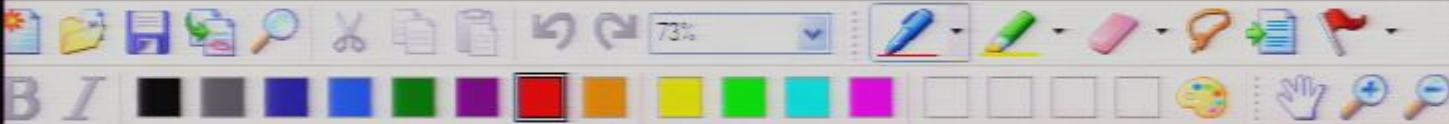


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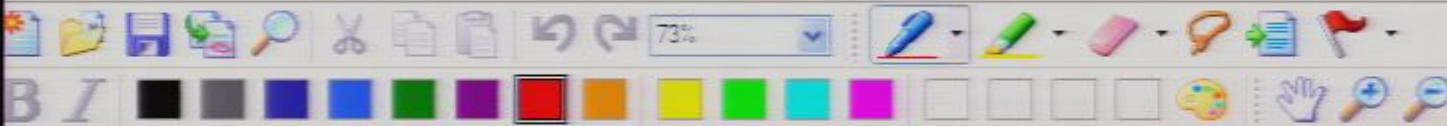


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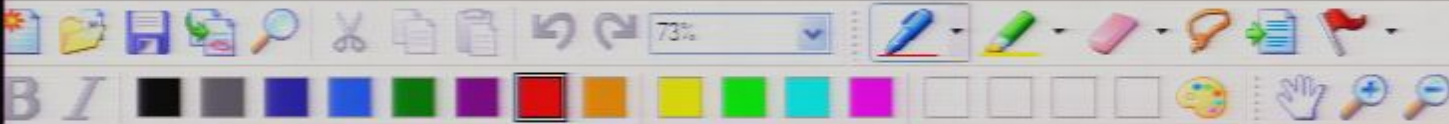
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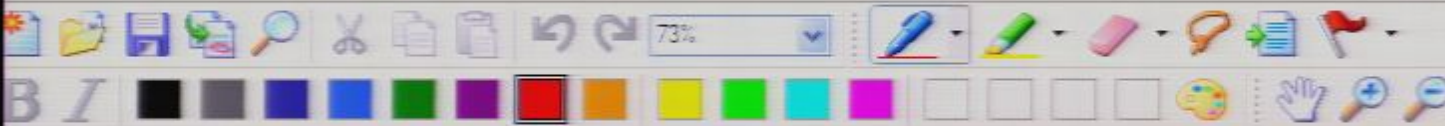
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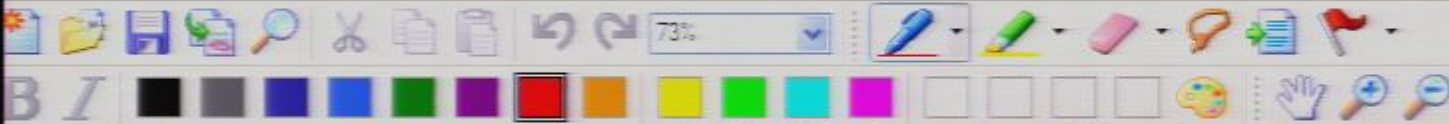
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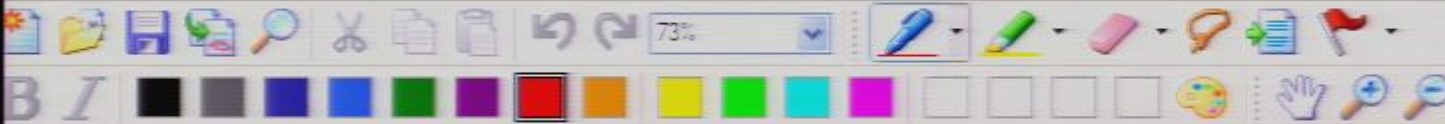
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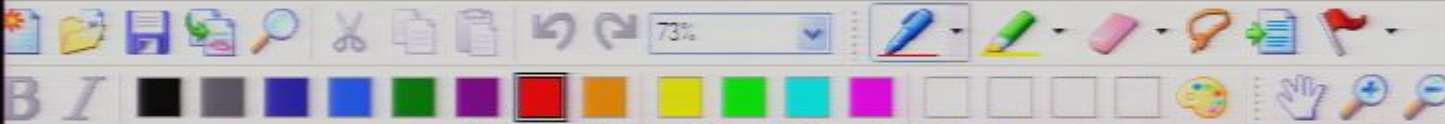


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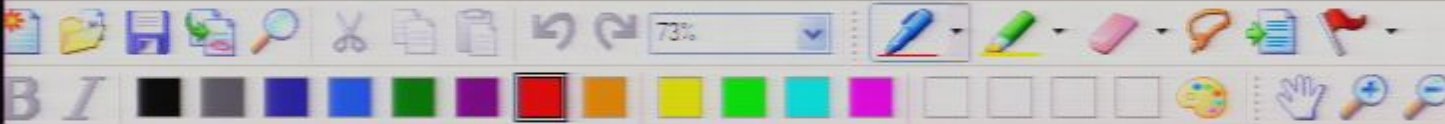
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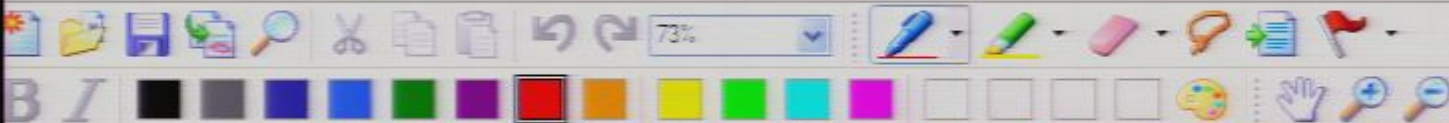


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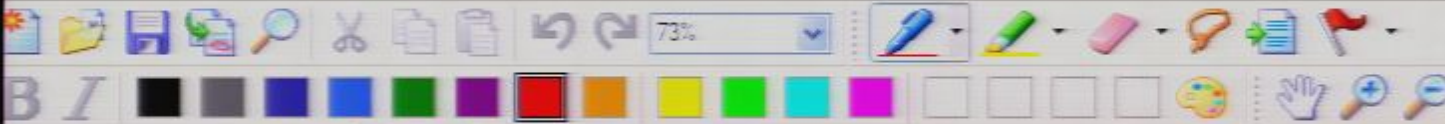
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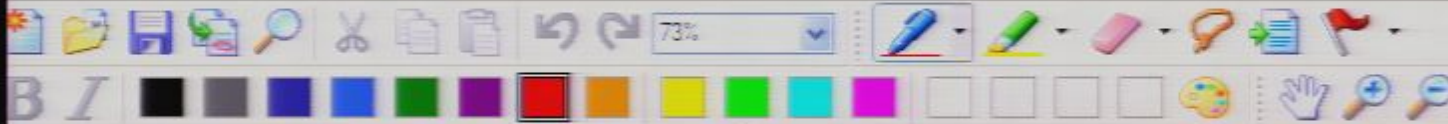
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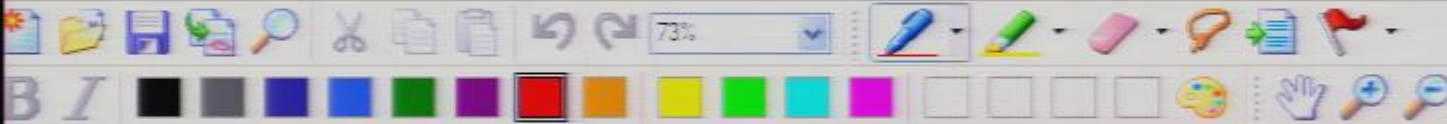
$$h: \mathcal{U} \rightarrow \mathbb{R}^n, \quad \mathcal{U} \subset M$$

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is called a chart of  $M$ .

For any point  $q \in \mathcal{U}$  its image

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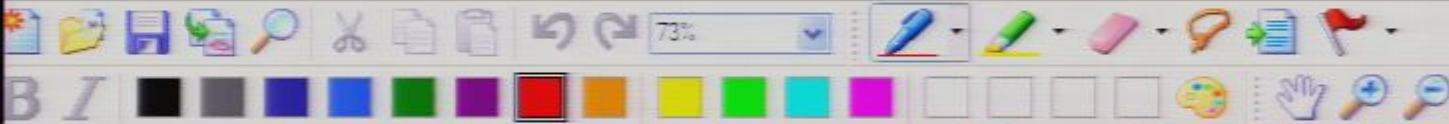
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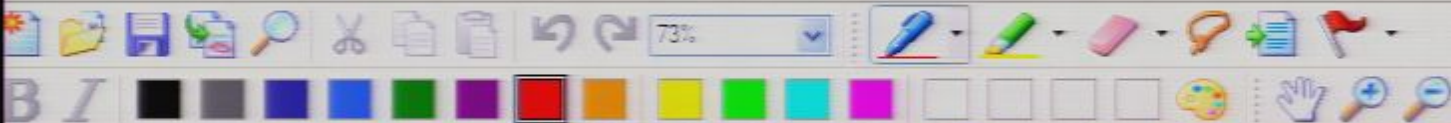
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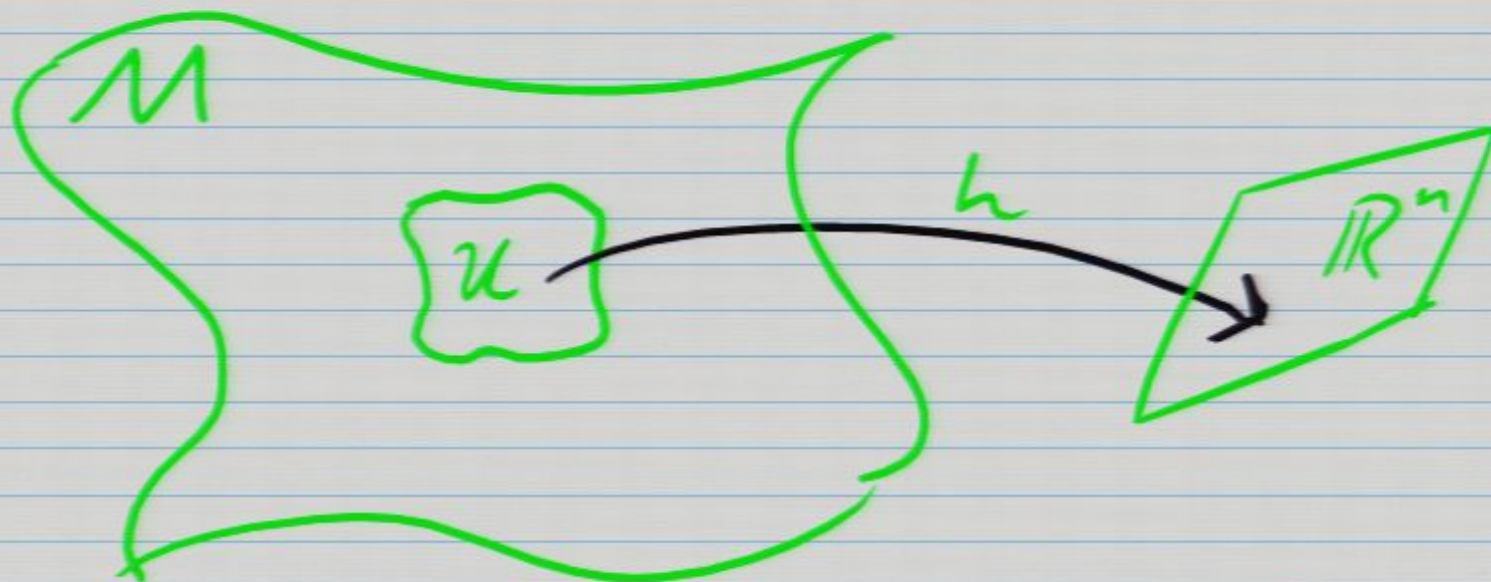
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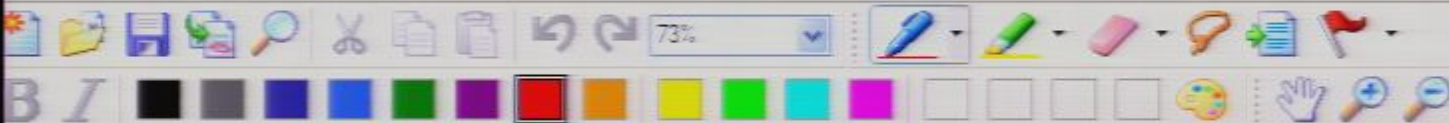


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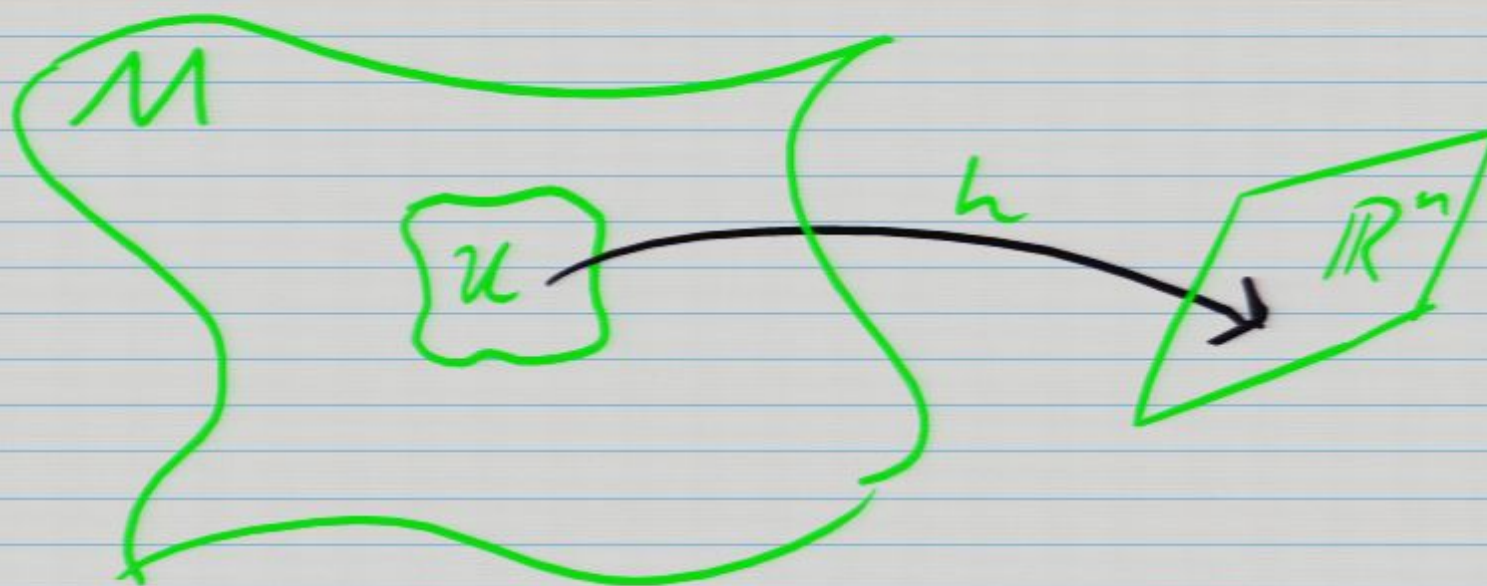
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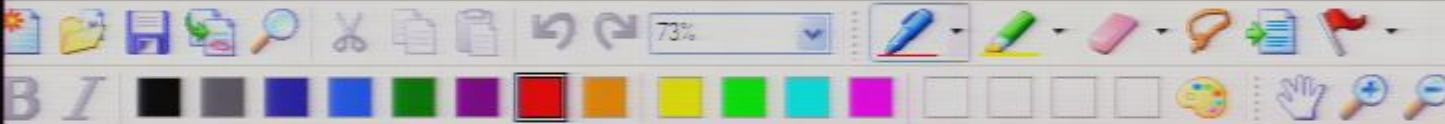


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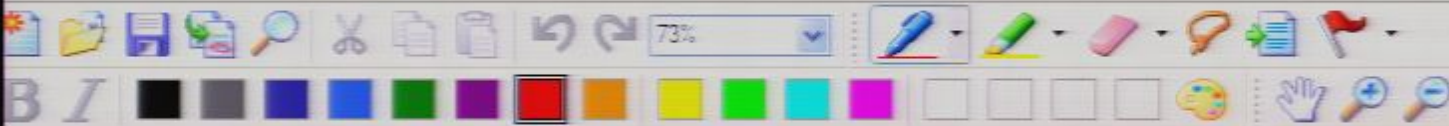
local coordinate system for  $U$ .



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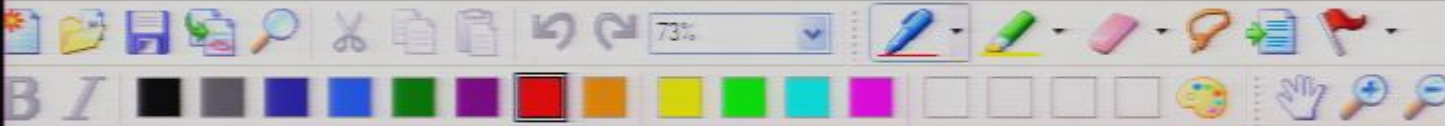
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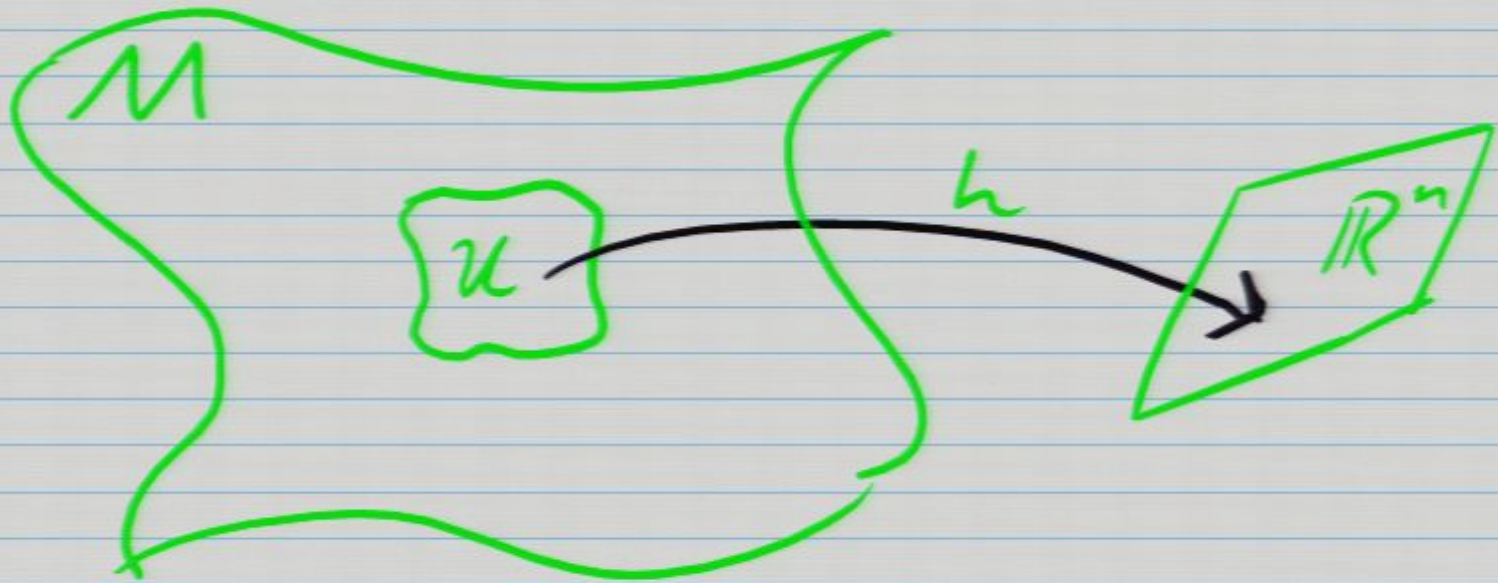


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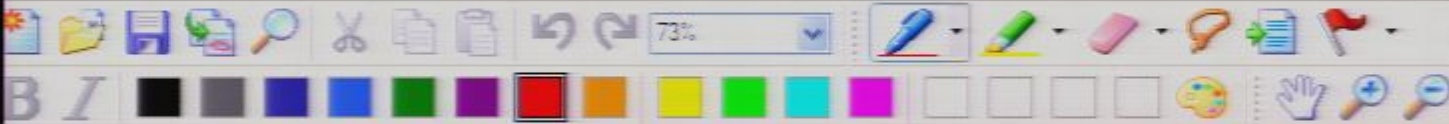


Def A chart,  $h$ , with domain  $U$ ,



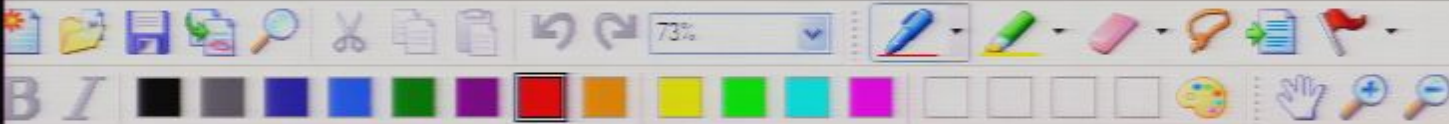
is also called a:

local coordinate system for  $U$ .



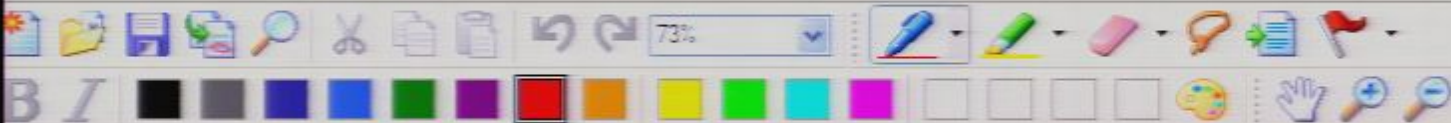
Def: A collection of charts  $h_\alpha$   
with domains  $U_\alpha$  is called an  
atlas if  $\bigcup_\alpha U_\alpha = M$ .

What, if we want to change coordinates,  
i.e. if we want to re-label the  
coordinates of (or a subset of) the manifold?



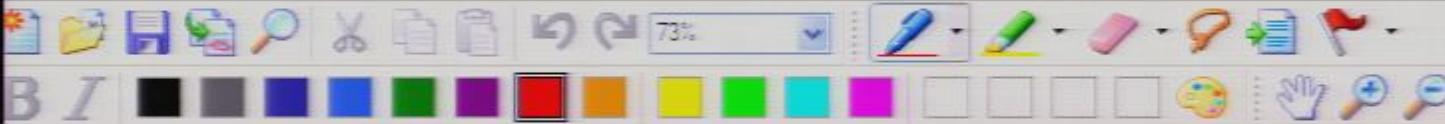
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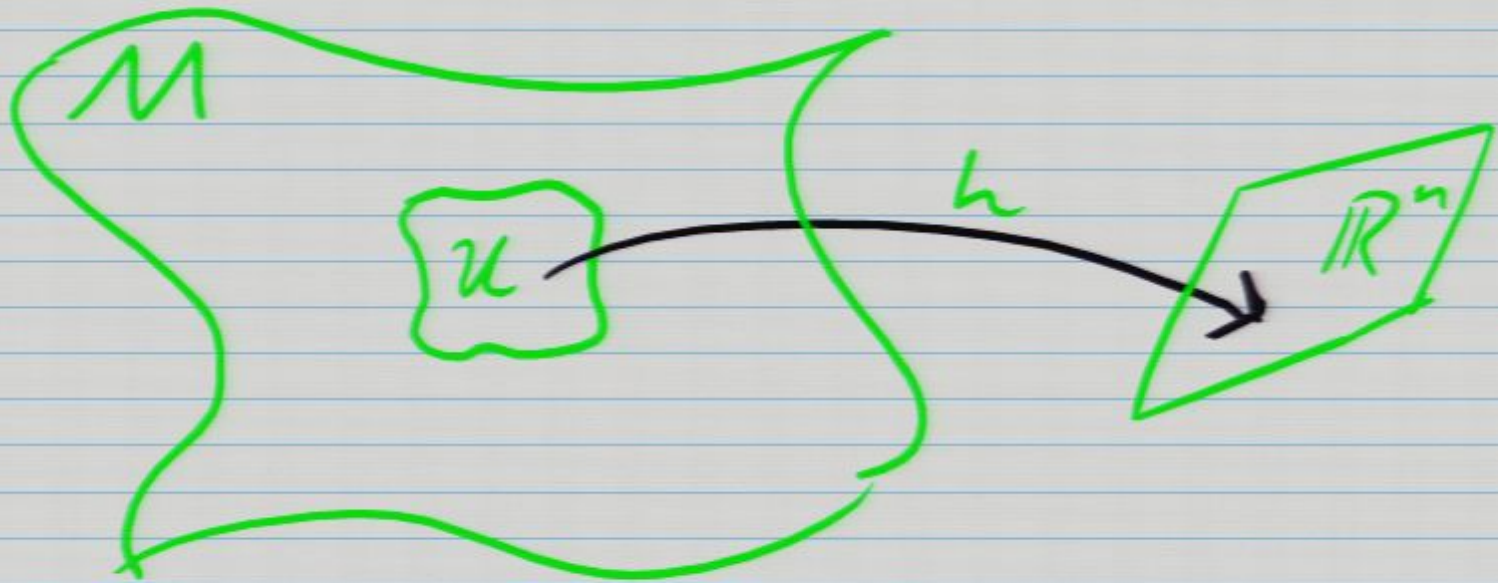


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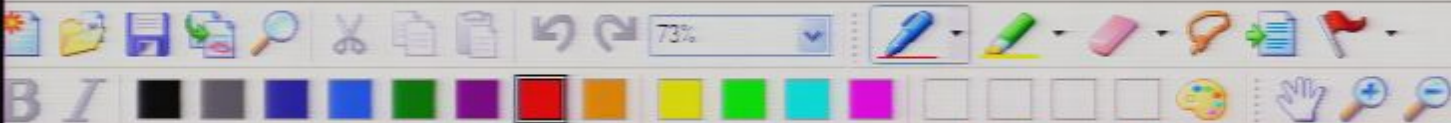
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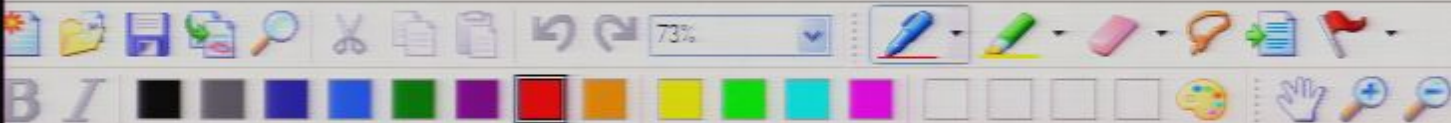
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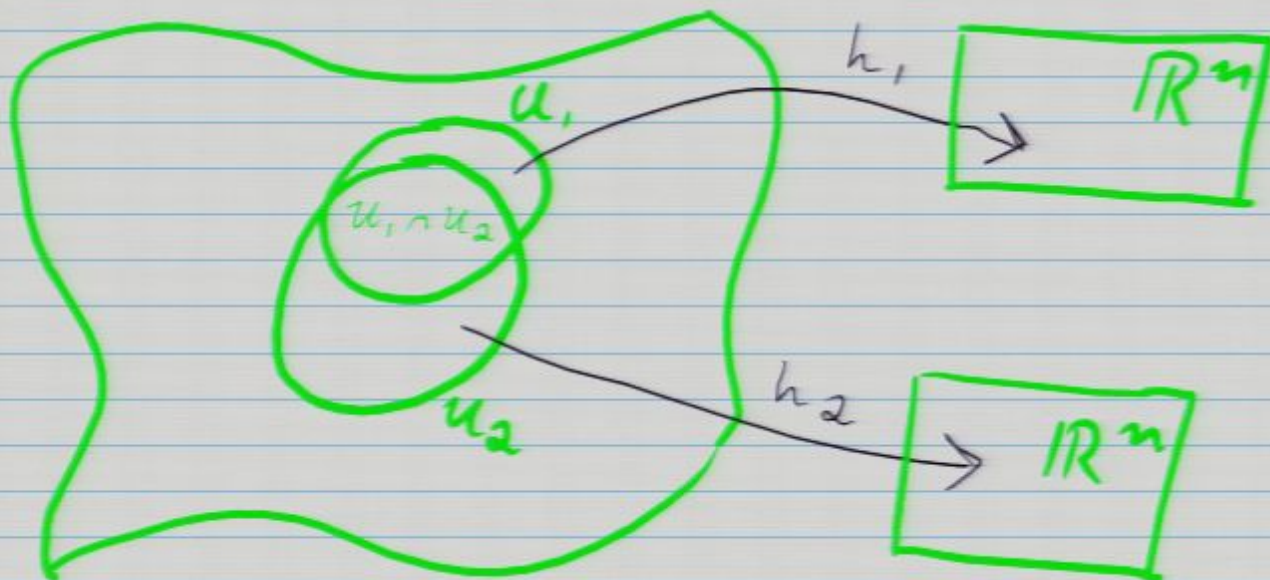


What, if we want to change coordinates,  
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Consider 2 charts  $h_1, h_2$  with  
intersecting domains  $U_1 \cap U_2 \neq \emptyset$ :

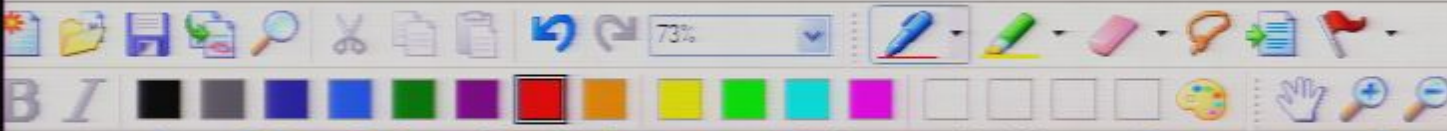


Consider 2 charts  $h_1, h_2$ , with intersecting domains  $U_1 \cap U_2 \neq \emptyset$ :



Then,  $h_{12} = h_2 \circ h_1^{-1}$  is a continuous

change of coordinates map  $h_{12} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ .

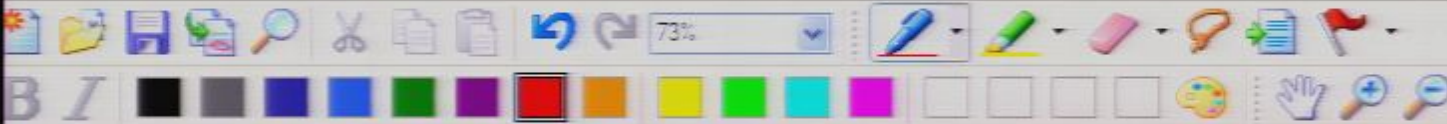


change of coordinates map  $h_{12}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ .

Crucial: For maps  $\mathbb{R}^n \rightarrow \mathbb{R}^n$  we know what differentiability means!



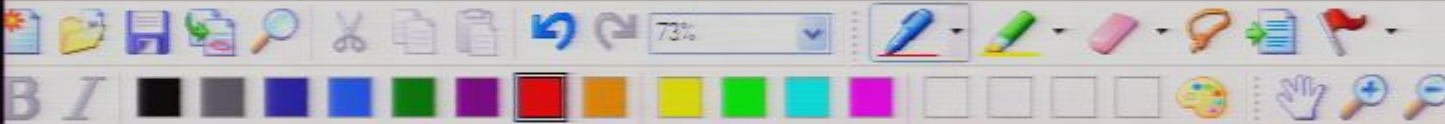
Def: An atlas is called  $C^r$  differentiable, if all its coordinate changes,  $h_{\alpha\beta}$ , are  $C^r$  diffeomorphisms, i.e.  $r$  times



Crucial: For maps  $\mathbb{R}^n \rightarrow \mathbb{R}^n$  we know what differentiability means!



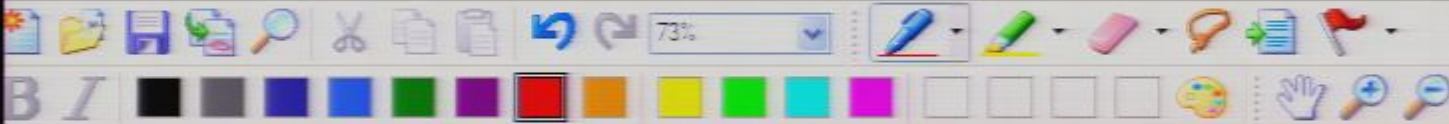
Def: An atlas is called  $C^r$  differentiable, if all its coordinate changes,  $h_{\alpha\beta}$ , are  $C^r$  diffeomorphisms, i.e.  $r$  times continuous differentiable



Def: A differentiable manifold of class  $C^r$  is a topol. manifold with an atlas of class  $C^r$ .

Def: A  $C^\infty$  manifold is also called a smooth manifold.

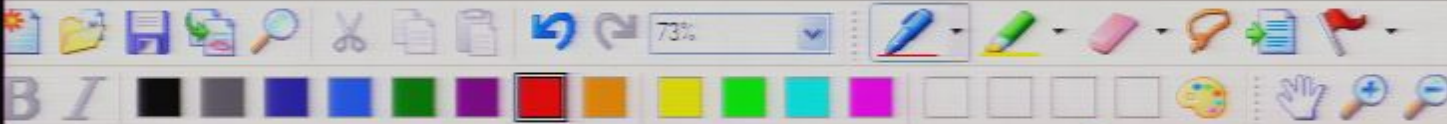
Note: For simplicity, we will henceforth let "differentiable" stand for  $C^\infty$ .



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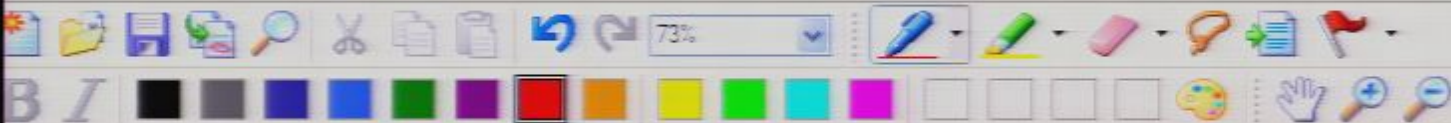
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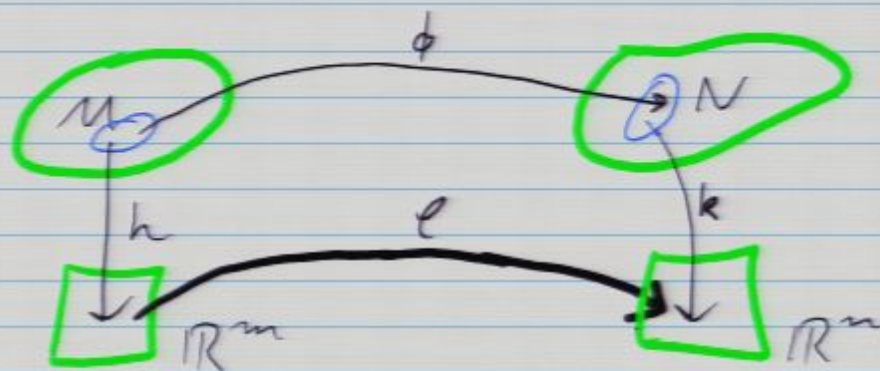


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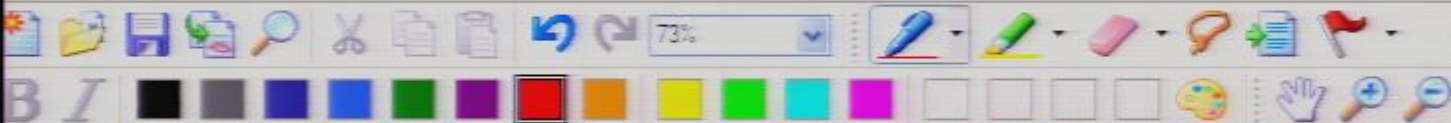
Def: A map  $\phi: M \rightarrow N$  between differentiable manifolds is called an *immersion* if there are charts  $h: M \rightarrow \mathbb{R}^m$ ,  $k: N \rightarrow \mathbb{R}^n$  so that  $\ell := k \circ \phi \circ h^{-1}$



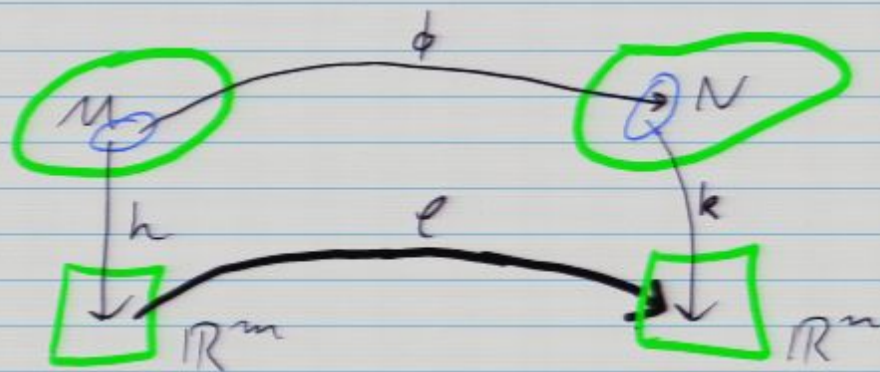
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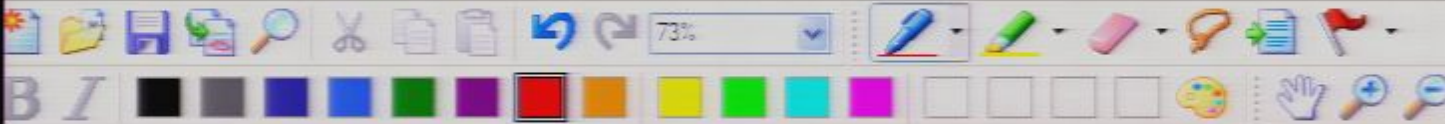


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is differentiable and reads  $(x^1, \dots, x^m) \rightarrow (x^1, \dots, x^n, 0, \dots)$



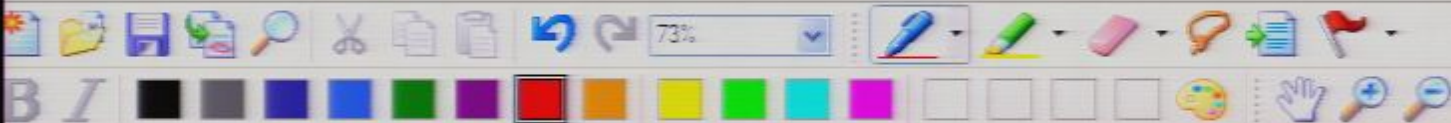


Def: If  $\phi$  is invertible, it is called an **embedding**.

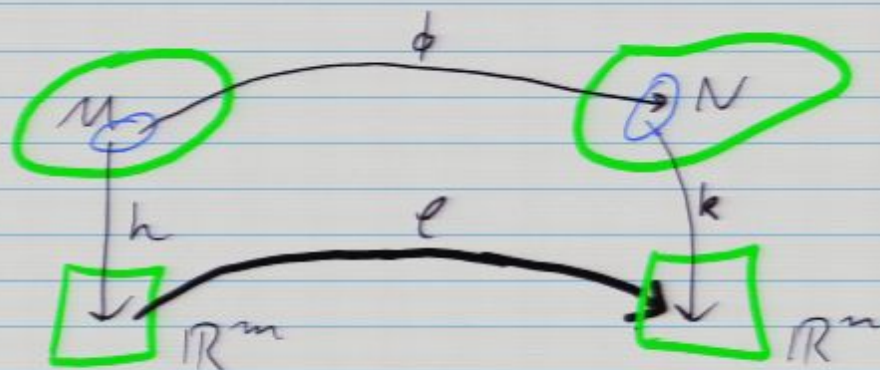
Def: If  $M \subset N$  are <sup>short for differentiable</sup> diffeable manifolds and the inclusion  $\phi: M \rightarrow N$  is an embedding, then  $M$  is called a **submanifold** of  $N$ .

Note: there are slightly varying definitions in the literature

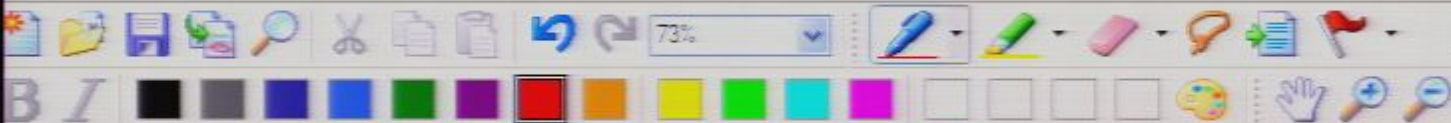
(Remark: every smooth manifold can be given a 'metric' structure and can, therefore, by Nash's theorem, be embedded in some euclidean  $\mathbb{R}^n$ .)



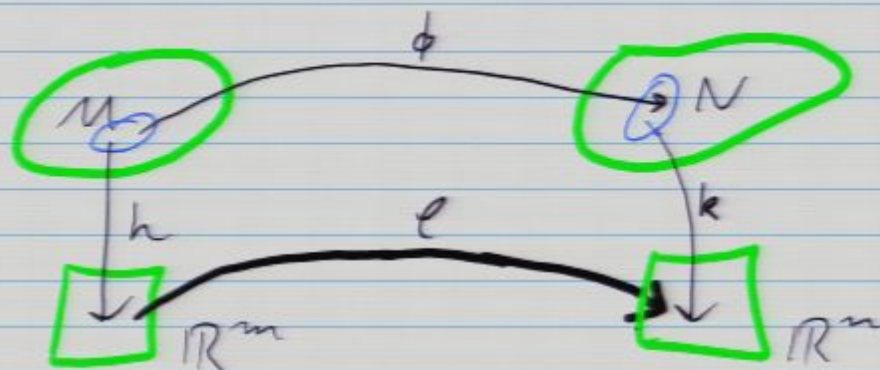
called an immersion if there are charts  $h: M \rightarrow \mathbb{R}^m$ ,  $k: N \rightarrow \mathbb{R}^n$  so that  $e := k \circ \phi \circ h^{-1}$



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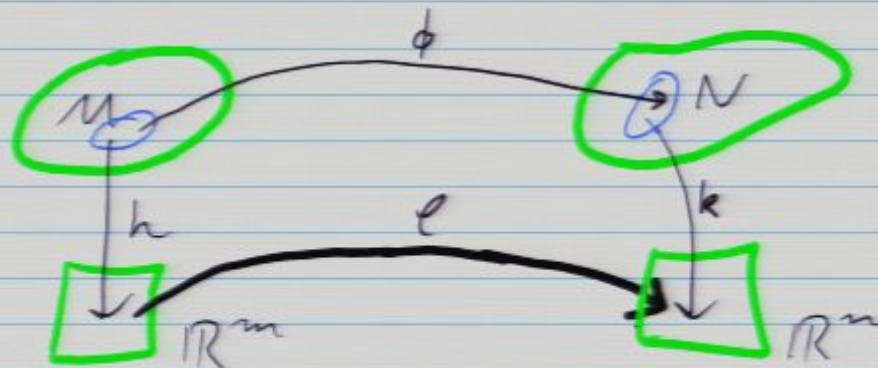
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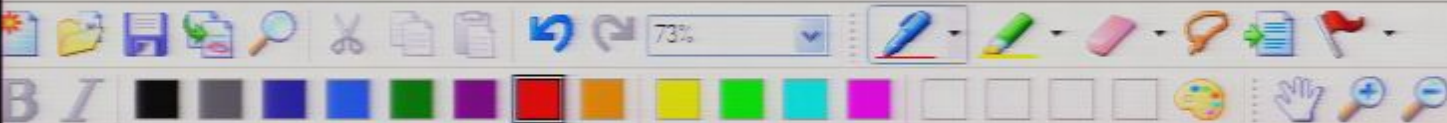
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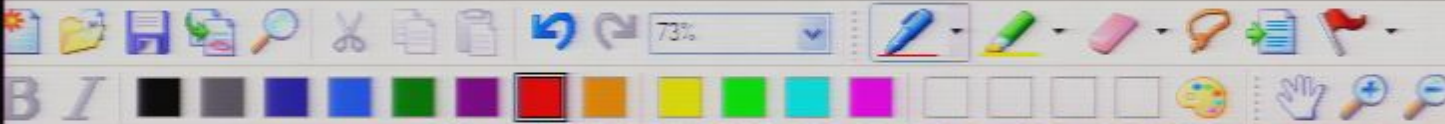


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↙ short for differentiable



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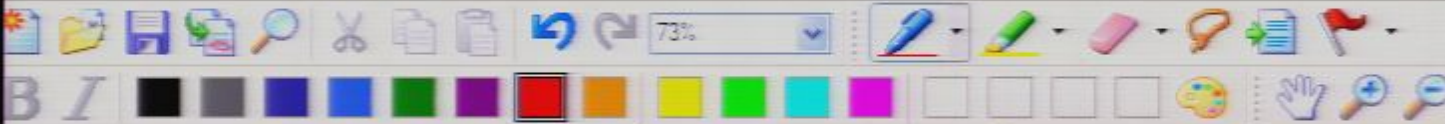
Def: If  $M \subset N$  are diffable manifolds and the inclusion  $\phi: M \rightarrow N$  is an embedding, then  $M$  is called a submanifold of  $N$ .

*short for differentiable*

Note: there are slightly varying definitions in the literature

(Remark: even smooth manifold can be given)



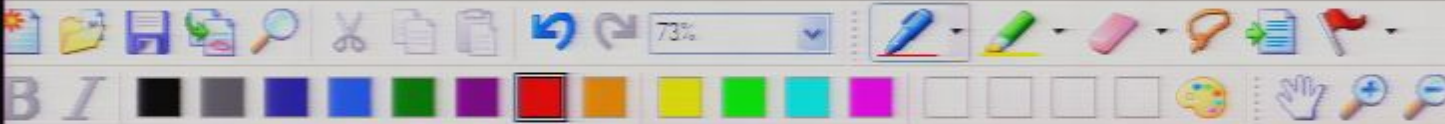


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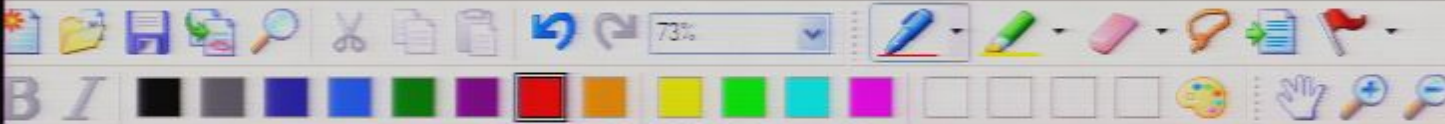


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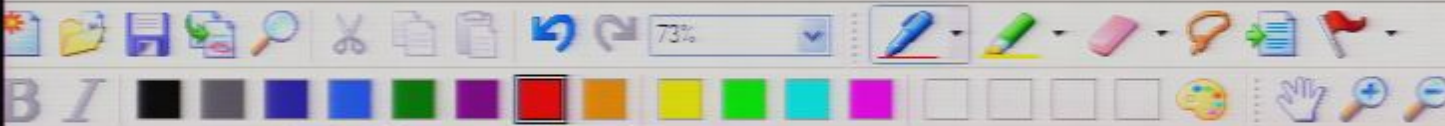
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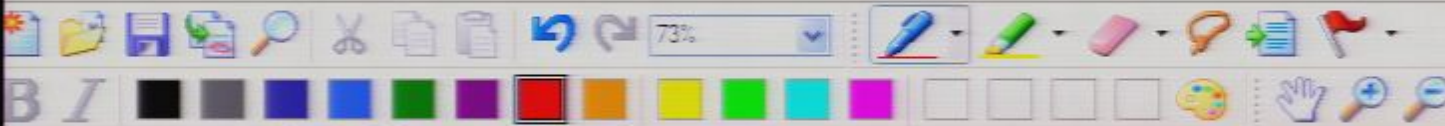


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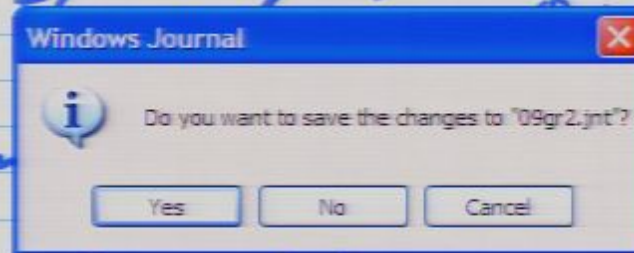
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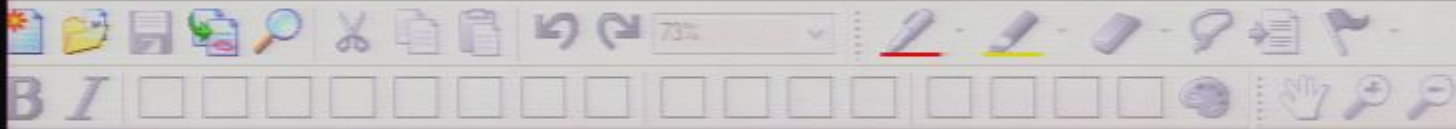
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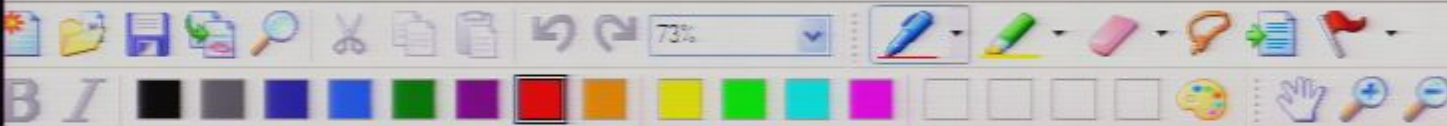
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□ e.g.  $\eta = \frac{\partial}{\partial x^i} \Big|_{x=p}$  is the image

of some abstract  $\xi \in T_p(M)$ , for fixed  $p$ .

Notation:  $\xi = \frac{\partial}{\partial x^i} \Big|_{x=p}$

↑ symbolic notation

Question:

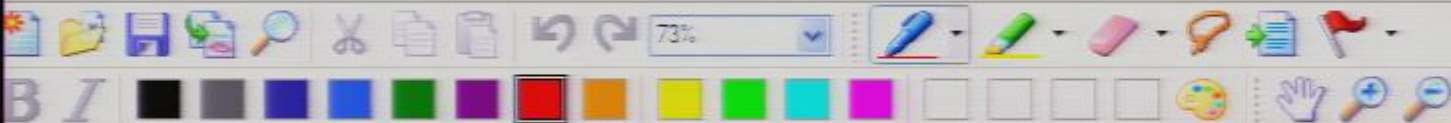
If we hold  $p$  and  $\xi \in T(p)$  fixed,

how do the numbers  $(x^1, \dots, x^n)$

and  $(\eta^1, \dots, \eta^n)$  change when we

change the chart?

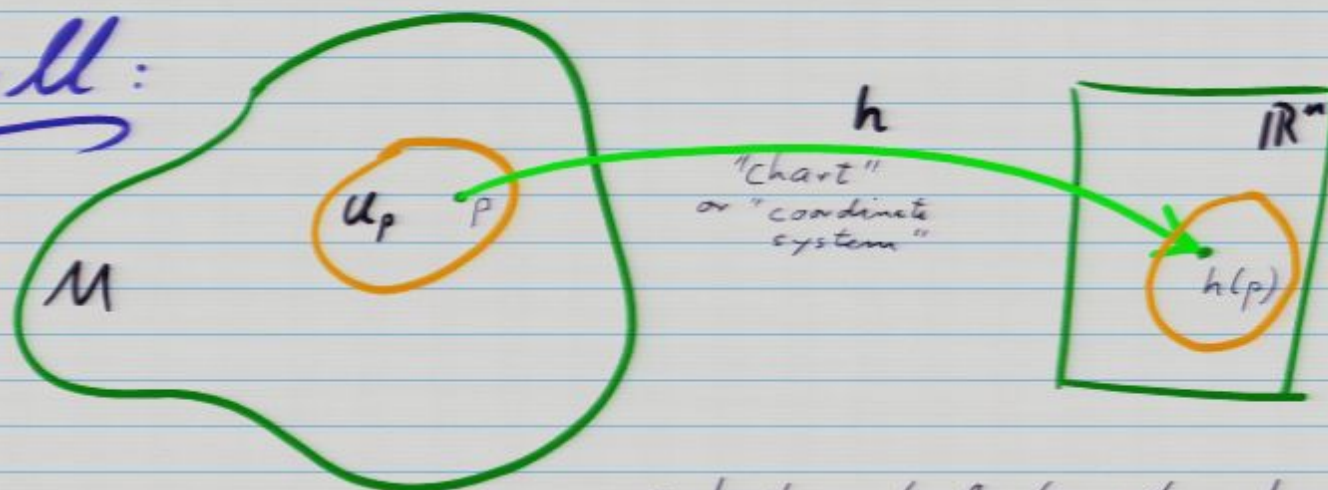




# GR for Cosmology, Fall 09, Achim Kempf, Lecture 3

9/18/2005

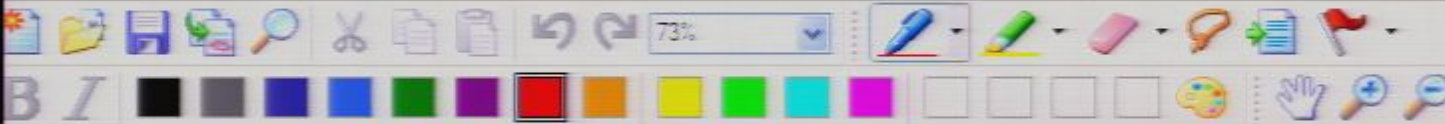
Recall:



→ charts are tools to get a handle at the otherwise nameless abstract points of the manifold.

Problem:

How to define the abstract  
"Tangent space,  $T_p(M)$ ,"

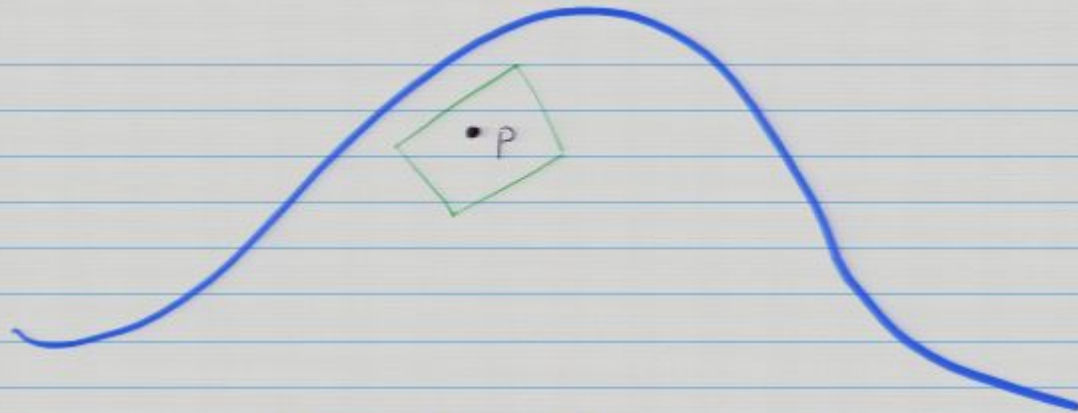


abstract points of the manifold.

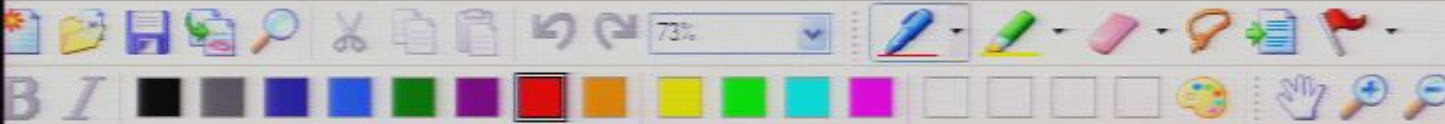
Problem:

How to define the abstract  
"Tangent space,  $T_p(M)$ ,"  
of a differentiable manifold at a point  $p$ ?

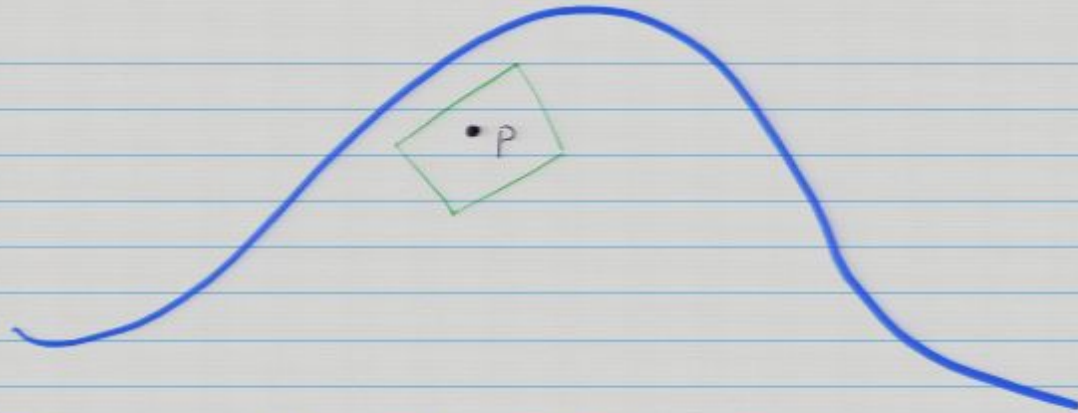
Intuition:



E.g. 2 dim manifold has 2 dim vector space of  
tangent vectors.



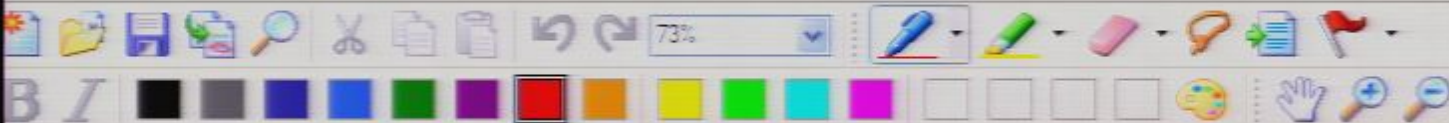
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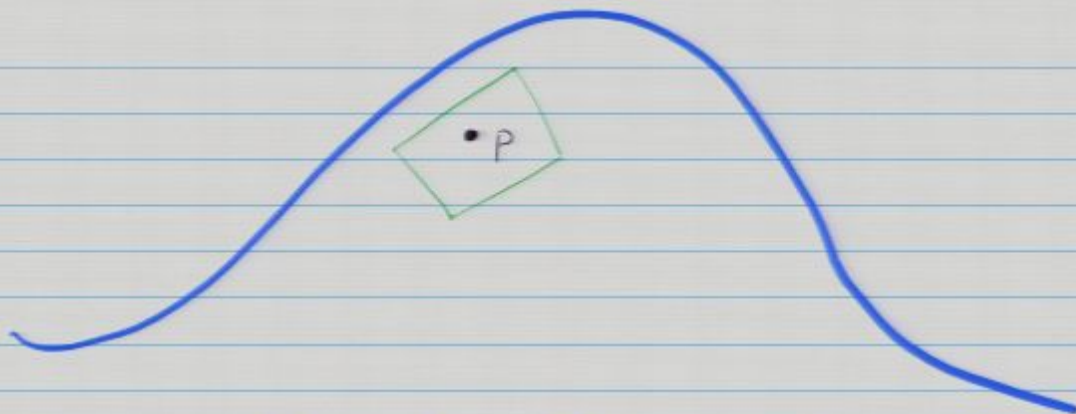
E.g. 2 dim manifold has 2 dim vector space of tangent vectors.

→ Proper definition should imply:

An  $n$ -dim mfld possesses for every point  $p$  an  $n$ -dim vector space of tangent vectors.



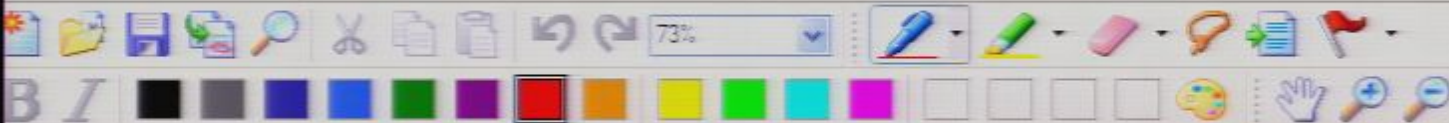
Intuition:



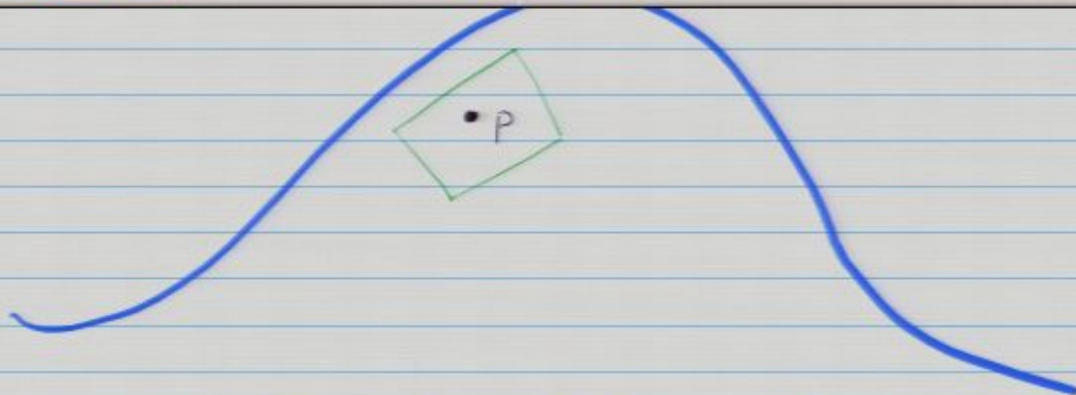
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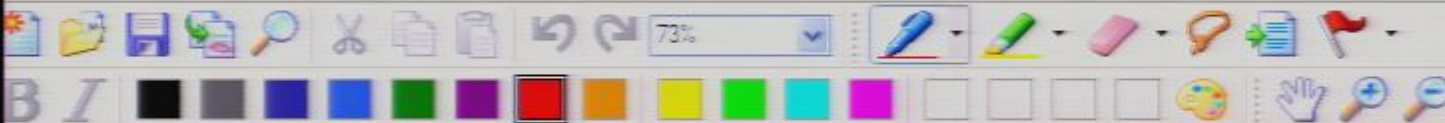
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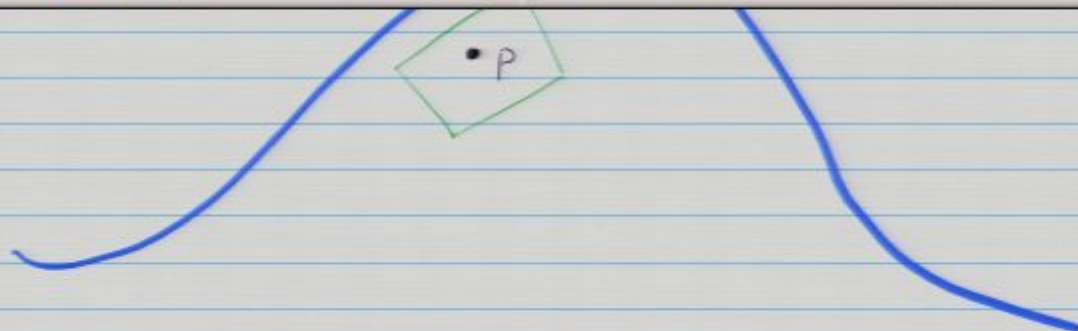
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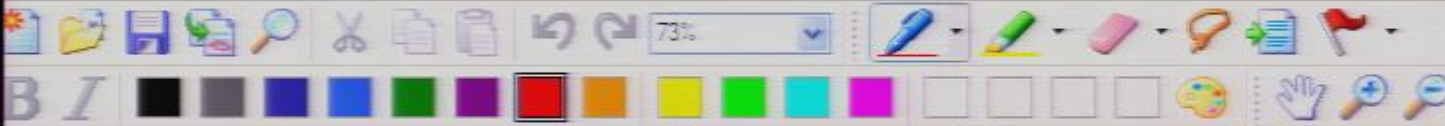
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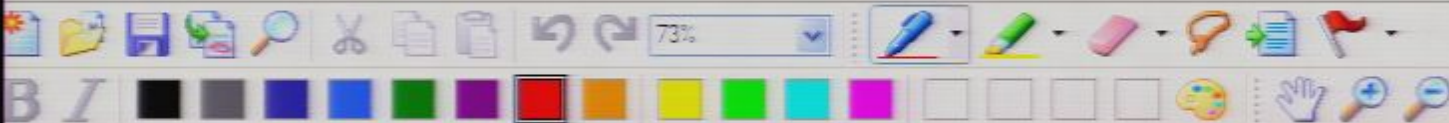
### 3 equivalent definitions of $T_p(M)$ :

#### 1. "Algebraic" definition of $T_p(M)$

lengthy and abstract  
but modern and powerful!

Idea: A tangent vector can denote a directional derivative  $\Rightarrow$  recognizable by Leibniz rule of derivatives:  
$$(fg)' = f'g + fg'$$

2 "PI" limit +  $T(M)$



## 3 equivalent definitions of $T_p(M)$ :

### 1. "Algebraic" definition of $T_p(M)$

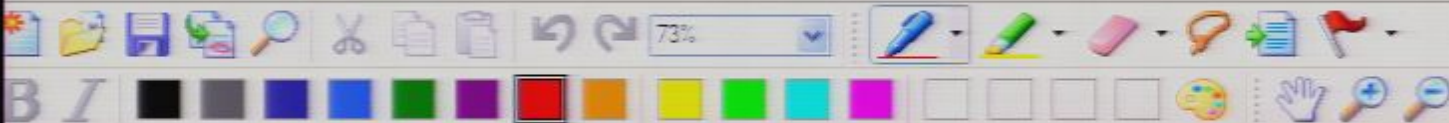
lengthy and abstract  
but modern and powerful!

Idea: A tangent vector can denote a directional derivative  $\Rightarrow$  recognizable  
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$$\nabla(g) = \nabla g + \nabla g$$

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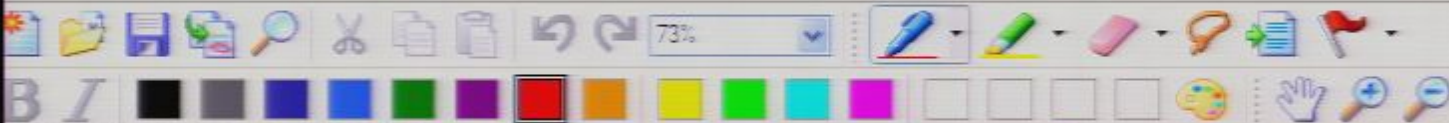
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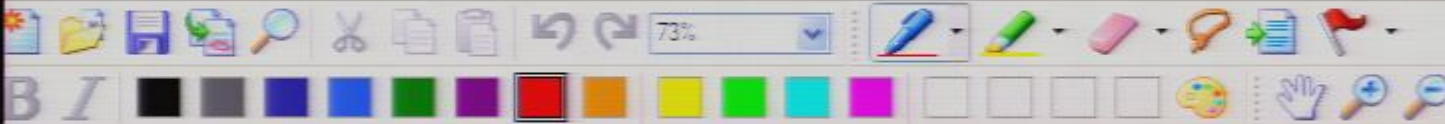
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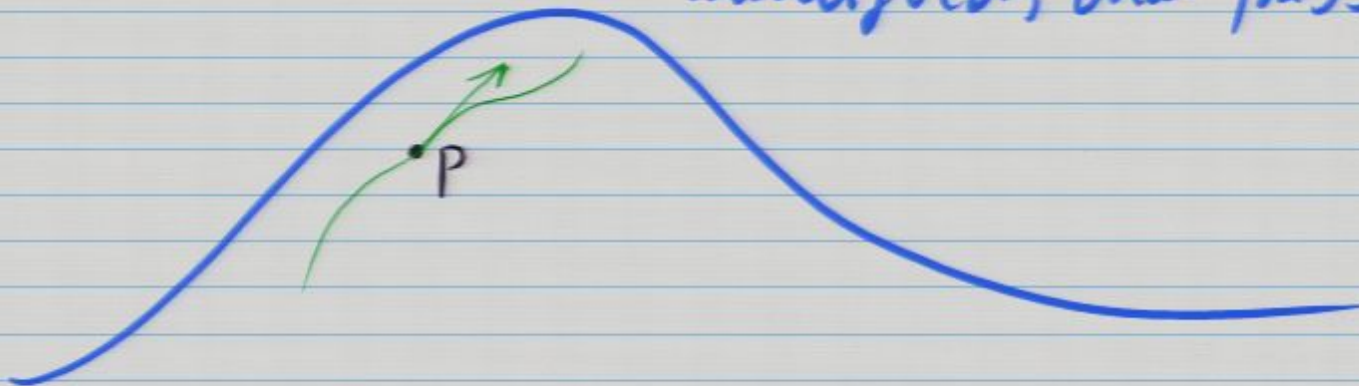
## 3. "Geometric definition of $T_p(M)$ "

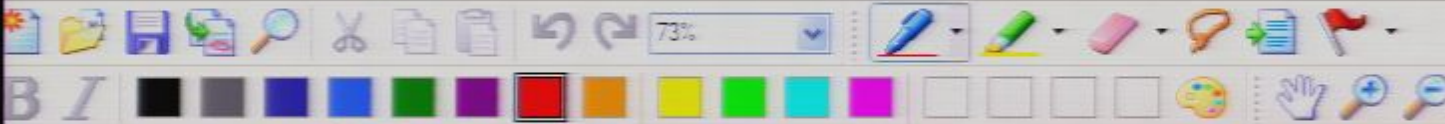
$T_p(M) = T_p(M) + T_p(M)$



### 3. "Geometric definition of $T_p(M)$ "

Idea: The elements of  $T_p(M)$  are to be actual tangent vectors of one-dim paths in the manifold, that pass through  $p$ .





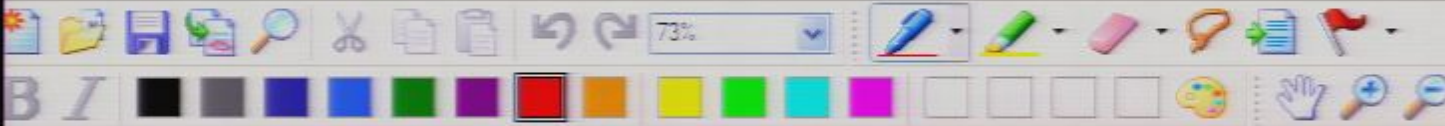
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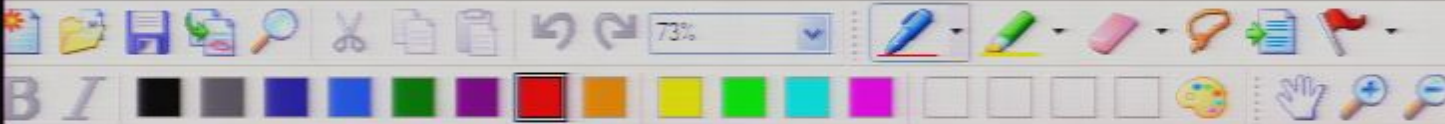
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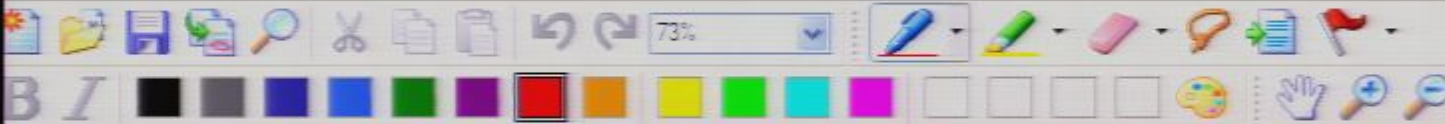
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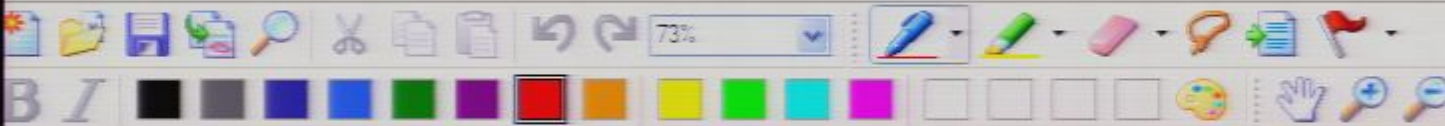
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Namely: In the case of  $M = \mathbb{R}^n$ , any tangent vector  $\xi$  at a point  $p$  can be viewed as a directional 1st derivative:

$$\xi = \sum_{i=1}^n \xi_i \frac{\partial}{\partial x^i} \Big|_{x=p}$$



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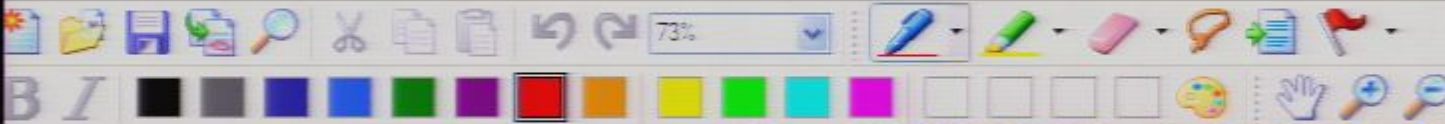
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Thus:

Each tangent vector maps functions into numbers:

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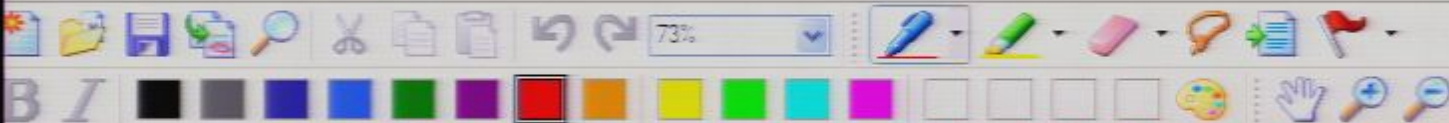
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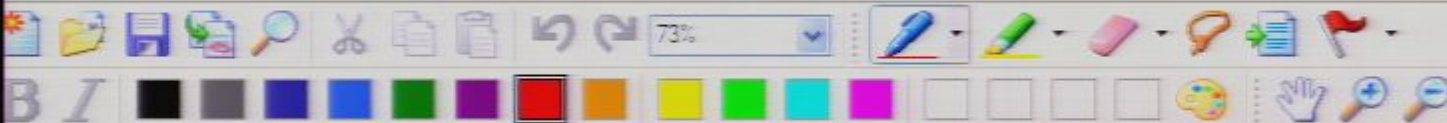
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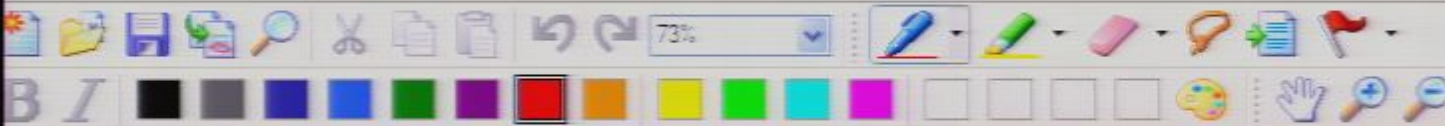
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Def: □ Assume  $M, N$  are diffable mflds.

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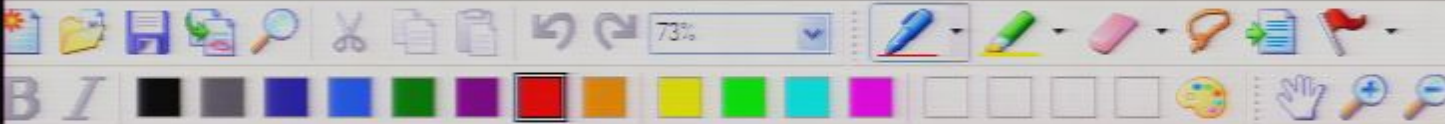
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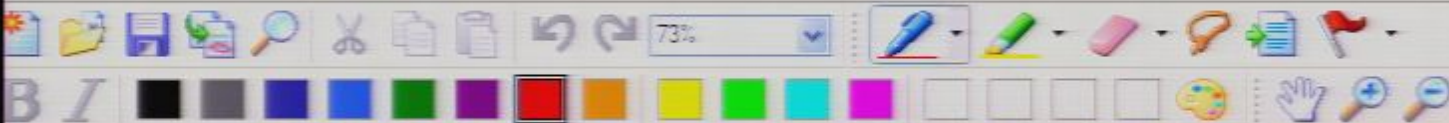
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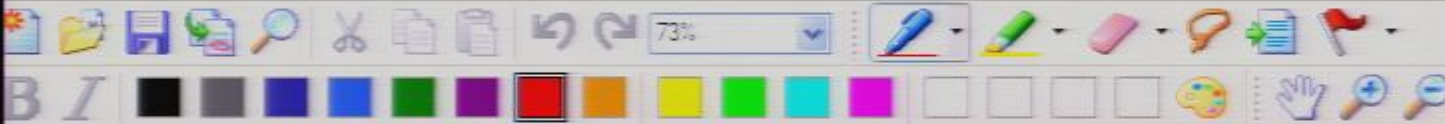
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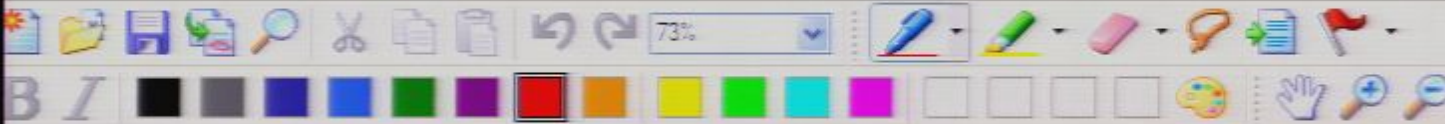
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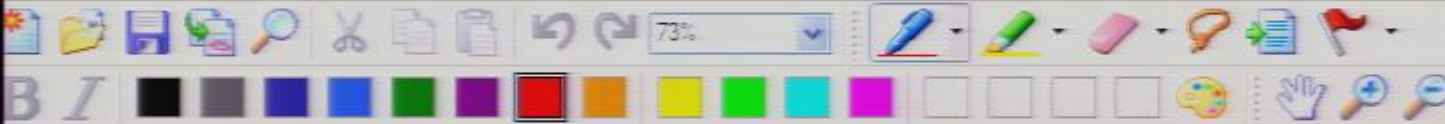
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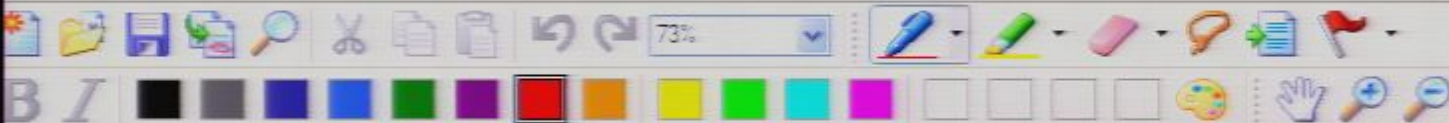
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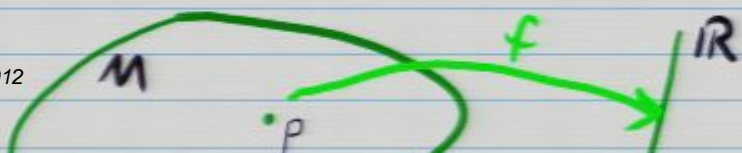
Intuition:

The elements of  $\overline{\phi}_p$  ought to be all those functions  $\psi: M \rightarrow N$  which possess the same 1st derivatives at  $p$ .

Note that the definition does not even assume existence of derivatives, but the intuition holds for differentiable functions.

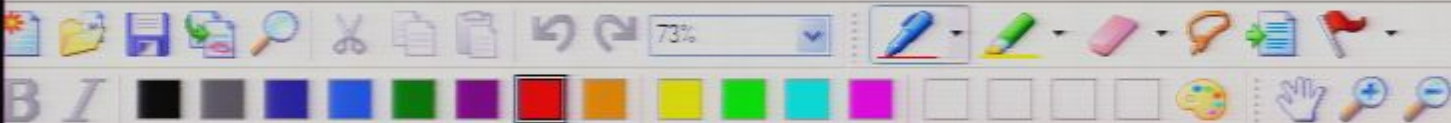
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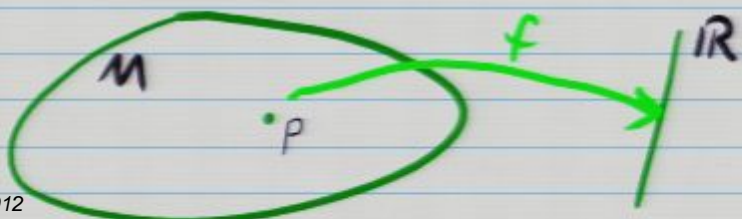


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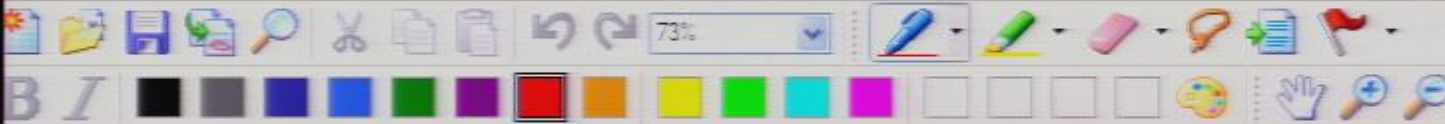
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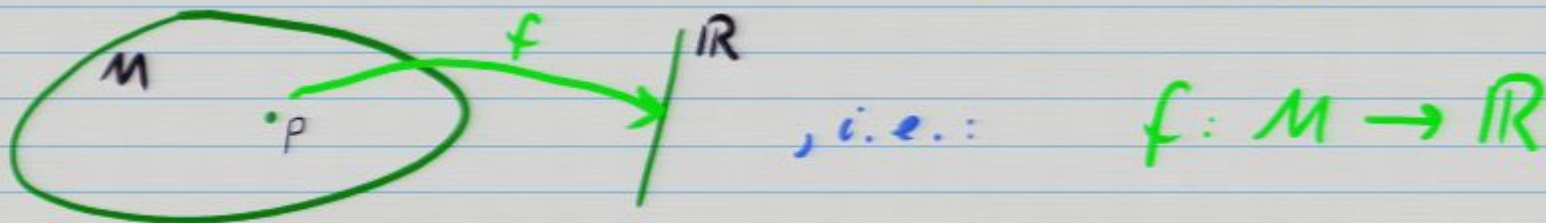
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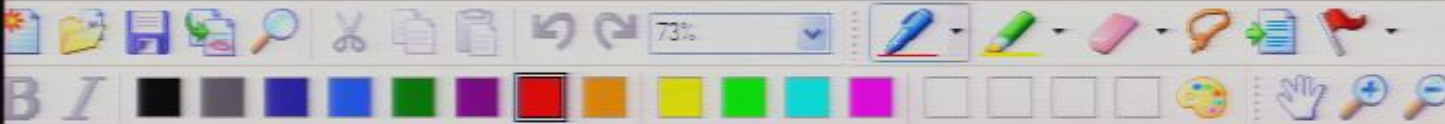
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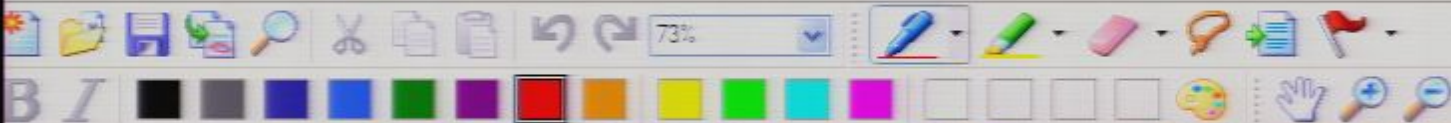
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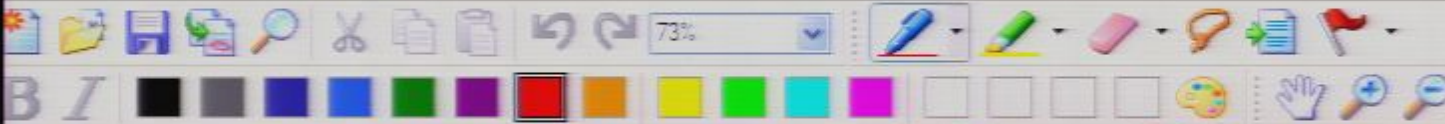
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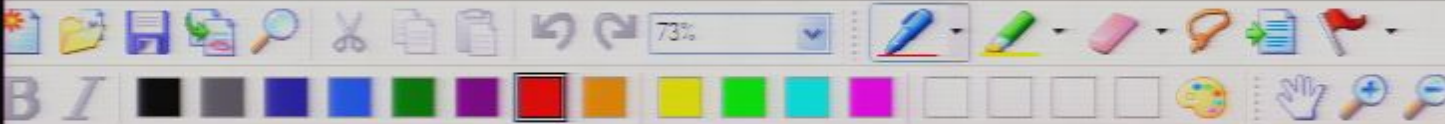
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Recall idea: The elements of  $T(p)$  are to be 1st derivatives  $\Rightarrow$  recognizable by Leibniz rule.

Definition: The tangent space  $T_p(M)$  is the set of "derivations" of  $\mathcal{F}(p)$ , i.e. the set of linear maps  $\mathcal{L}: \mathcal{F}(p) \rightarrow \mathbb{R}$  which



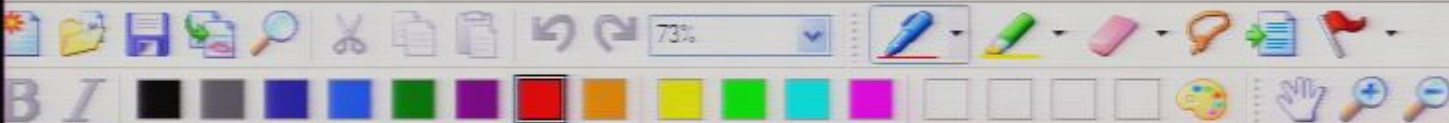


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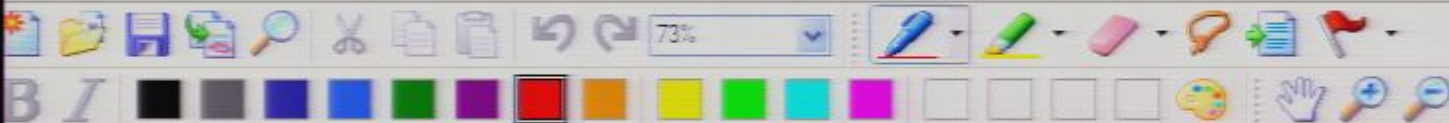
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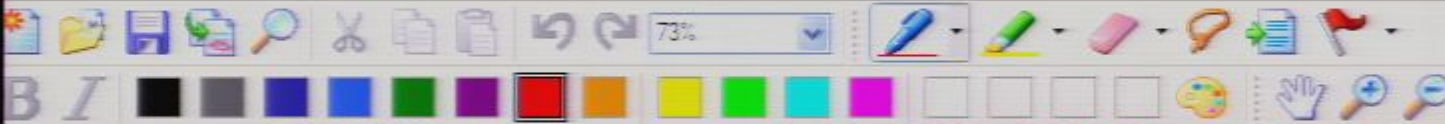
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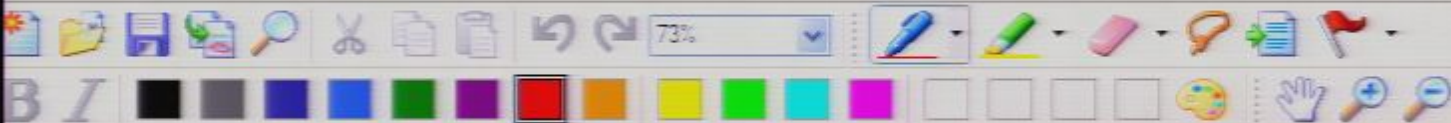
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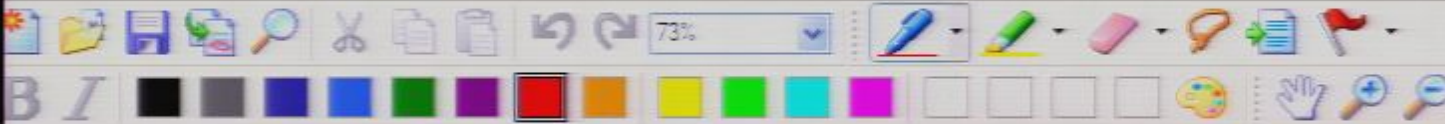
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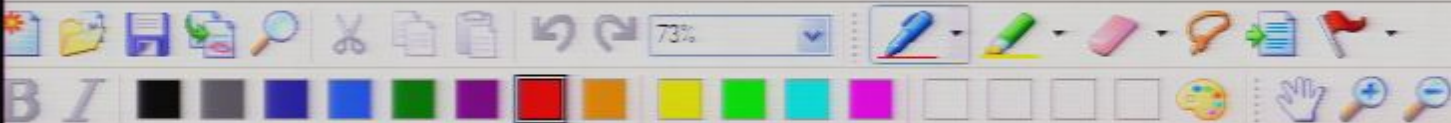
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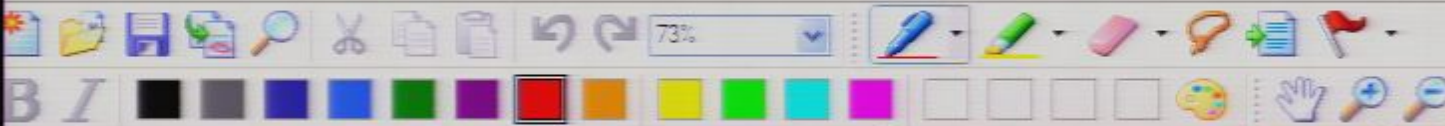
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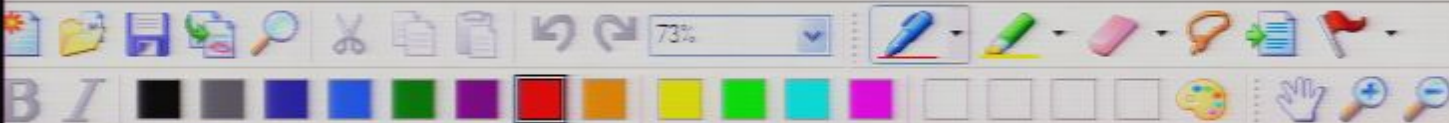
$$\xi(\bar{f}_p \bar{g}_p) = \xi(\bar{f}_p) \cdot \bar{g}_p(p) + \bar{f}_p(p) \xi(\bar{g}_p)$$

$\parallel_{g(p)}$ 
 $\parallel_{f(p)}$

Remark:

▢ this definition is abstract enough  
not only for arbitrary differentiable manifolds!

▢ this definition (as derivations of  
the algebra of functions) is also suitable



Recall idea: The elements of  $T(p)$  are to be 1st derivatives  $\Rightarrow$  recognizable by Leibniz rule.

Definition: The tangent space  $T_p(M)$  is the set of "derivations" of  $\mathcal{F}(p)$ , i.e. the set of linear maps  $\xi: \mathcal{F}(p) \rightarrow \mathbb{R}$  which obey: (Leibniz rule for differentiable functions  $g, f$ )

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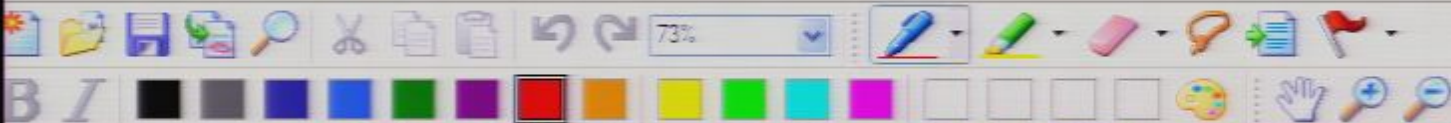
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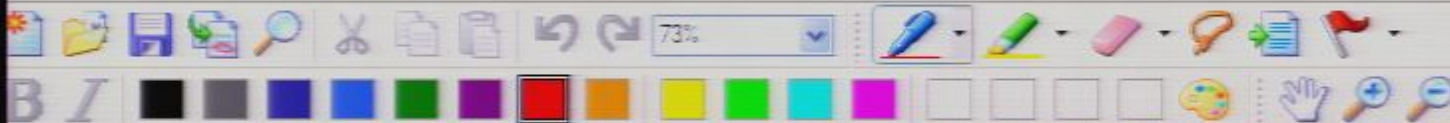
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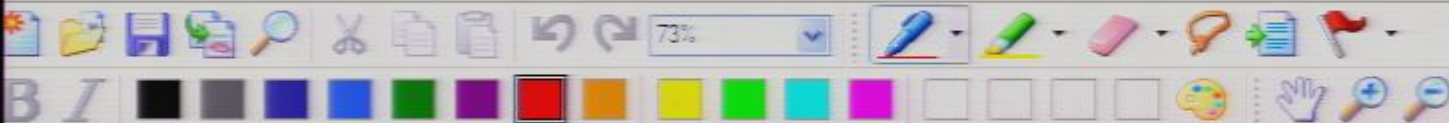
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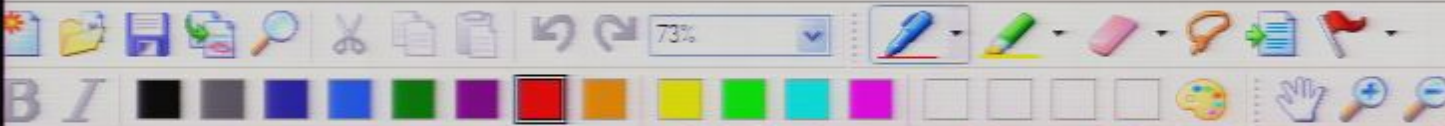


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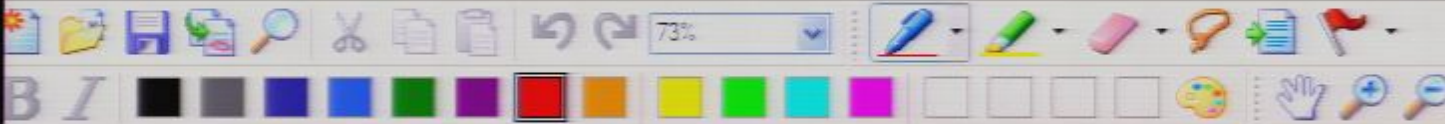
$\parallel_{g(p)}$                        $\parallel_{f(p)}$



$$\zeta(t_p g_p) = \underbrace{\zeta(t_p)}_{\text{"}g(p)\text{"}} \cdot \underbrace{g_p(p)}_{\text{"}f(p)\text{"}} + t_p(p) \zeta(g_p)$$

Remark:

- this definition is abstract enough  
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- this definition (as derivations of the algebra of functions) is also suitable for "Noncommutative Geometry":  
There, (Quantum Gravity,) the algebra of functions  $F(p)$  is noncommutative.

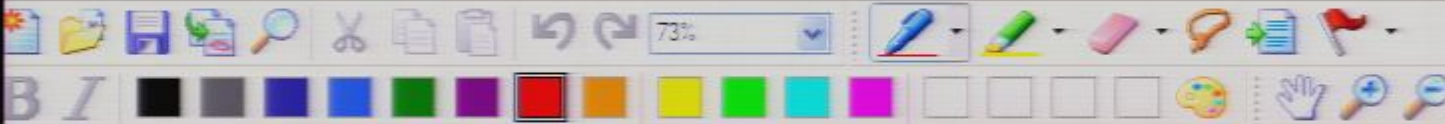


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- ▣ Note: Can't do Newton's derivatives then but algebraic def'n of derivation still works.

Properties of  $T_p(M)$ :

Simple example: a constant function  $c$ :





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