

Title: Special geometries associated to quaternion-Kähler 8-manifolds

Date: May 08, 2009 01:00 PM

URL: <http://pirsa.org/09050030>

Abstract: In this talk we will discuss the (local) construction of a calibrated  $G_2$  structure on the 7-dimensional quotient of an 8-dimensional quaternion-Kähler (QK) manifold  $M$  under the action of a group  $S^1$  of isometries. The idea is to construct explicitly a 3-form of type  $G_2$ , using the data associated to the  $S^1$  action and to the QK structure on  $M$ . In the same spirit, we can consider the level sets of the QK moment-map square-norm function on  $M$ , and again take the  $S^1$  quotient: we will discuss in this case the construction of half-flat metrics in dimension 6, under suitable circumstances. This talk is based on a joint work with F. Longro, Y. Nagatomo and S. Salamon, still in progress.

# Special Geometries associated to 8-dimensional quaternion-Kähler manifolds

Andrea Gambioli

Connections in Geometry and Physics  
Perimeter Institute

5/9/2008

joint work with:

Lonegro, Y. Nagatomo, S. Salamon, still in progress.

# Quaternions

The Algebra of Quaternions  $\mathbb{H}$  is a 4-dimensional real vector space generated by the elements

$$1, \quad i, \quad j, \quad k$$

which satisfy the relations

$$i^2 = j^2 = k^2 = -1 \quad ij = k.$$

- It is *associative* but *not commutative*;
- we can define the quaternionic vector space  $\mathbb{H}^n$  with scalar multiplication on the *right*.
- We have an inclusion

$$Gl(n, \mathbb{H}) \mathbb{H}^* \subset Gl(4n, \mathbb{R})$$

of invertible matrices with quaternionic entries acting on the *left* commuting with  $\mathbb{H}^*$  acting on the *right*.

# Quaternions

The Algebra of Quaternions  $\mathbb{H}$  is a 4-dimensional real vector space generated by the elements

$$1, \quad i, \quad j, \quad k$$

which satisfy the relations

$$i^2 = j^2 = k^2 = -1 \quad ij = k.$$

- It is *associative* but **not commutative**;

- we can define the quaternionic vector space  $\mathbb{H}^n$  with scalar multiplication on the *right*.

- We have an inclusion

$$Gl(n, \mathbb{H}) \mathbb{H}^* \subset Gl(4n, \mathbb{R})$$

of invertible matrices with quaternionic entries acting on the *left* commuting with  $\mathbb{H}^*$  acting on the *right*.

# Quaternions

The Algebra of Quaternions  $\mathbb{H}$  is a 4-dimensional real vector space generated by the elements

$$1, \quad i, \quad j, \quad k$$

which satisfy the relations

$$i^2 = j^2 = k^2 = -1 \quad ij = k.$$

- It is *associative* but **not commutative**;
- we can define the quaternionic vector space  $\mathbb{H}^n$  with scalar multiplication on the *right*.
- We have an inclusion

$$Gl(n, \mathbb{H}) \mathbb{H}^* \subset Gl(4n, \mathbb{R})$$

of invertible matrices with quaternionic entries acting on the *left* commuting with  $\mathbb{H}^*$  acting on the *right*.

# Quaternions

The Algebra of Quaternions  $\mathbb{H}$  is a 4-dimensional real vector space generated by the elements

$$1, \quad i, \quad j, \quad k$$

which satisfy the relations

$$i^2 = j^2 = k^2 = -1 \quad ij = k.$$

- It is *associative* but **not commutative**;
- we can define the quaternionic vector space  $\mathbb{H}^n$  with scalar multiplication on the *right*.
- We have an inclusion

$$Gl(n, \mathbb{H}) \mathbb{H}^* \subset Gl(4n, \mathbb{R})$$

of invertible matrices with quaternionic entries acting on the *left* commuting with  $\mathbb{H}^*$  acting on the *right*.



# Quaternions

The Algebra of Quaternions  $\mathbb{H}$  is a 4-dimensional real vector space generated by the elements

$$1, \quad i, \quad j, \quad k$$

which satisfy the relations

$$i^2 = j^2 = k^2 = -1 \quad ij = k.$$

- It is *associative* but **not commutative**;
- we can define the quaternionic vector space  $\mathbb{H}^n$  with scalar multiplication on the *right*.
- We have an inclusion

$$Gl(n, \mathbb{H}) \mathbb{H}^* \subset Gl(4n, \mathbb{R})$$

of invertible matrices with quaternionic entries acting on the *left* commuting with  $\mathbb{H}^*$  acting on the *right*.



# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$I_1, I_2, I_3 \quad \text{satisfying} \quad I_i^2 = -1 \quad \text{and} \quad I_i I_j = I_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(I_i \cdot, I_i \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$ , satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad X \in TM$ ;
- if  $\omega_i = g(I_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s = 0$ .

# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \quad \text{satisfying} \quad l_i^2 = -1 \quad \text{and} \quad l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$  satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad \forall X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s \neq 0$ .

# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \quad \text{satisfying} \quad l_i^2 = -1 \quad \text{and} \quad l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$  satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s \neq 0$ .



# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \text{ satisfying } l_i^2 = -1 \text{ and } l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure compatible with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$  satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s = 0$ .

# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \text{ satisfying } l_i^2 = -1 \text{ and } l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure compatible with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \delta_{ij}$ ,  $i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$  satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G}$ ,  $X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_{i+1}$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s = 0$ .

# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \quad \text{satisfying} \quad l_i^2 = -1 \quad \text{and} \quad l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure compatible with the metric ( $g(l_i \cdot, l_i \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK if it satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$  satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant.  
We will deal with the case  $s \neq 0$ .



# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \quad \text{satisfying} \quad l_i^2 = -1 \quad \text{and} \quad l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$ , satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad \forall X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s = 0$ .

# K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \quad \text{satisfying} \quad l_i^2 = -1 \quad \text{and} \quad l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$ , satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad \forall X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant.  
We will deal with the case  $s = 0$ .

## K manifolds

We define a *quaternionic structure* over a manifold  $M$  a subbundle  $\mathcal{G} \subset \text{End}(TM)$  whose fiber  $\mathbb{R}^3$  is spanned locally by

$$l_1, l_2, l_3 \text{ satisfying } l_i^2 = -1 \text{ and } l_i l_j = l_k$$

A Riemannian manifold  $(M, g)$  endowed with a quaternionic structure *compatible* with the metric ( $g(l_i \cdot, l_j \cdot) = g(\cdot, \cdot) \quad i = 1, 2, 3$ ) is called QK. It satisfies one of the following (equivalent) conditions:

- the holonomy group is contained in  $Sp(n)Sp(1)$ ;
- the bundle  $\mathcal{G}$ , satisfies  $\nabla_X \mathcal{G} \subseteq \mathcal{G} \quad \forall X \in TM$ ;
- if  $\omega_i = g(l_i \cdot, \cdot)$  span  $\mathcal{G} \subset \wedge^2 TM$  then the 4-form  $\Omega = \sum_{i=1}^3 \omega_i \wedge \omega_i$  is parallel.

QK manifolds are Einstein  $\implies$  the scalar curvature  $s$  is constant. We will deal with the case  $s \neq 0$ .



# Examples

The projective plane  $\mathbb{H}\mathbb{P}^2$  parametrizes the quaternionic lines in  $\mathbb{H}^3$ . It is homogeneous w.r.t.  $Sp(3) = GL(3, \mathbb{H}) \cap SO(12)$ :

$$\mathbb{H}\mathbb{P}^2 \cong \frac{Sp(3)}{Sp(2)Sp(1)}$$

Therefore we have a 21-dimensional algebra of Killing vector fields. There are 2 QK manifolds of dimension 8 and  $s > 0$ :

$$\frac{G_2}{SO(4)} \quad \text{and} \quad Gr_2(\mathbb{C}^4) \cong \frac{SU(4)}{SU(2) \times SU(2)}$$

with isometry group of dimension respectively 14 and 15.

## Examples

The projective plane  $\mathbb{H}\mathbb{P}^2$  parametrizes the quaternionic lines in  $\mathbb{H}^3$ . It is homogeneous w.r.t.  $Sp(3) = GL(3, \mathbb{H}) \cap SO(12)$ :

$$\mathbb{H}\mathbb{P}^2 \cong \frac{Sp(3)}{Sp(2)Sp(1)}$$

Therefore we have a 21-dimensional algebra of Killing vector fields. There are 2 QK manifolds of dimension 8 and  $s > 0$ :

$$\frac{G_2}{SO(4)} \quad \text{and} \quad Gr_2(\mathbb{C}^4) \cong \frac{SU(4)}{SU(2) \times SU(2)}$$

with isometry group of dimension respectively 14 and 15.

## Examples

The projective plane  $\mathbb{H}\mathbb{P}^2$  parametrizes the quaternionic lines in  $\mathbb{H}^3$ . It is homogeneous w.r.t.  $Sp(3) = GL(3, \mathbb{H}) \cap SO(12)$ :

$$\mathbb{H}\mathbb{P}^2 \cong \frac{Sp(3)}{Sp(2)Sp(1)}$$

Therefore we have a 21-dimensional algebra of Killing vector fields. There are 2 QK manifolds of dimension 8 and  $s > 0$ :

$$\frac{G_2}{SO(4)} \quad \text{and} \quad Gr_2(\mathbb{C}^4) \cong \frac{SU(4)}{SU(2) \times SU(2)}$$

with isometry group of dimension respectively 14 and 15.



## 2 Geometry

The compact Lie group  $G_2$  can be defined as the subgroup of  $GL(7, \mathbb{R})$  preserving the 3-form

$$\phi = (e^{12} - e^{34})e^7 - (e^{13} - e^{42})e^6 - (e^{14} - e^{23})e^5 + e^{765} \quad (1)$$

Let  $N$  be a 7 dimensional Riemannian manifold admitting a section  $\phi \in \Gamma(\Lambda^3 M)$  which can be locally expressed as 1. Then

$$G \subset G_2 \subset SO(7)$$

where  $G$  is the structure group. If moreover

$$\nabla \phi = 0 \quad \Leftrightarrow \quad d\phi = 0 = d * \phi$$

then  $Hol_0(M, g) \subset G_2$ . (Fernandez-Gray). This is relevant in M-Theory.

# First Examples of Holonomy $G_2$ metrics

In the late '80 the first examples of complete metrics with  $G_2$  appear in

- R.L. Bryant, S. Salamon: "On the construction of some complete metrics with exceptional holonomy", Duke Math. J. (1989)

on the total spaces of vector bundles with fibre  $\mathbb{R}^3$

$$\begin{array}{ccc} \Lambda_+^2 & & \Lambda_+^2 \\ \downarrow & & \downarrow \\ S^4 & & \mathbb{C}P^2 \end{array}$$

These metrics are *invariant* w.r.t. the action of  $SO(5)$  and  $SU(3)$  respectively, acting with *cohomogeneity one*.

## 2 Geometry

The compact Lie group  $G_2$  can be defined as the subgroup of  $GL(7, \mathbb{R})$  preserving the 3-form

$$\phi = (e^{12} \wedge e^{34})e^7 - (e^{13} - e^{42})e^6 - (e^{14} - e^{23})e^5 + e^{765} \quad (1)$$

Let  $N$  be a 7 dimensional Riemannian manifold admitting a section  $\phi \in \Gamma(\Lambda^3 M)$  which can be locally expressed as 1. Then

$$G \subset G_2 \subset SO(7)$$

where  $G$  is the structure group. If moreover

$$\nabla \phi = 0 \quad \Leftrightarrow \quad d\phi = 0 = d * \phi$$

then  $Hol_0(M, g) \subset G_2$ . (Fernandez-Gray). This is relevant in M-Theory.



# First Examples of Holonomy $G_2$ metrics

In the late '80 the first examples of complete metrics with  $G_2$  appear in

- R.L. Bryant, S. Salamon: "On the construction of some complete metrics with exceptional holonomy", Duke Math. J. (1989)

on the total spaces of vector bundles with fibre  $\mathbb{R}^3$

$$\begin{array}{ccc} \Lambda_+^2 & & \Lambda_+^2 \\ \downarrow & & \downarrow \\ S^4 & & \mathbb{C}P^2 \end{array}$$

These metrics are *invariant* w.r.t. the action of  $SO(5)$  and  $SU(3)$  respectively, acting with *cohomogeneity one*.

## Other Examples

- D. D. Joyce: Compact Riemannian 7-manifolds with holonomy  $G_2$  I, II. J. Differential Geom. 43 (1996)
- A. Brandhuber, J. Gomis, S. S. Gubser, S. Gukov: Gauge theory at large  $N$  and new  $G_2$  holonomy metrics. Nuclear Phys. B 611 (2001)
- G.W. Gibbons, H. Lü, C.N. Pope, K. S. Stelle: Supersymmetric domain walls from metrics of special holonomy, Nuclear Phys. B 623 (2002)

## Question

Is it possible to construct  $G_2$ -holonomy metrics on quotients

$$X/S^1$$

where  $X$  is some special holonomy 8-dimensional manifold and  $S^1$  is a group of isometries ?

For instance:

- B. Acharya, E. Witten: "Chiral Fermions from Manifolds of  $G_2$  Holonomy" hep-th/0109152 (2001).

In the paper, the authors discuss the existence of  $G_2$  holonomy metrics on the quotients  $X/S^1$  of certain 8-dimensional *hyperKähler* (HK) manifolds  $X$

where HK iff  $Hol_0(X) \subset Sp(n)$ .



## Question

Is it possible to construct  $G_2$ -holonomy metrics on quotients

$$X/S^1$$

where  $X$  is some special holonomy 8-dimensional manifold and  $S^1$  is a group of isometries ?

For instance:

- B. Acharya, E. Witten: "Chiral Fermions from Manifolds of  $G_2$  Holonomy" hep-th/0109152 (2001).

In the paper, the authors discuss the existence of  $G_2$  holonomy metrics on the quotients  $X/S^1$  of certain 8-dimensional *hyperKähler* (HK) manifolds  $X$

where HK iff  $Hol_0(X) \subset Sp(n)$ .

## The QK case

Can we obtain something analogous with  $M$  an 8-dimensional QK manifold?

naïve guess

consider for instance  $\mathbb{H}\mathbb{P}^2$ .

$$K_w \text{ Killing v.f.} \longleftrightarrow S_w^1 \cong \mathbb{T}^3$$

with weight vector  $w = (q_0, q_1, q_2) \in \Sigma^3$ . On the subset  $U = \{K \neq 0\}$  we can consider the form

$$\gamma = K \lrcorner \Omega$$

which satisfies

$$\begin{cases} \mathcal{L}_K(K \lrcorner \Omega) = 0 \\ d(K \lrcorner \Omega) = 0 \end{cases}$$

which provides a closed 3-form  $\gamma$  on  $U/S^1$ .

## The QK case

Can we obtain something analogous with  $M$  an 8-dimensional QK manifold?

### naïve guess

Consider for instance  $\mathbb{H}\mathbb{P}^2$ .

$$K_{\mathbf{w}} \text{ Killing v.f.} \longleftrightarrow S_{\mathbf{w}}^1 \subset \mathbb{T}^3$$

With weight vector  $\mathbf{w} = (q_0, q_1, q_2) \in \mathbb{Z}^3$  On the subset  $U = \{K \neq 0\}$  we can consider the form

$$\gamma = K \lrcorner \Omega$$

which satisfies

$$\begin{cases} \mathcal{L}_K(K \lrcorner \Omega) = 0 \\ d(K \lrcorner \Omega) = 0 \end{cases}$$

which provides a closed 3-form  $\gamma$  on  $U/S^1$ .

## The QK case

Can we obtain something analogous with  $M$  an 8-dimensional QK manifold?

### naïve guess

Consider for instance  $\mathbb{H}\mathbb{P}^2$ .

$$K_{\mathbf{w}} \text{ Killing v.f.} \iff S_{\mathbf{w}}^1 \subset \mathbb{T}^3$$

with weight vector  $\mathbf{w} = (q_0, q_1, q_2) \in \mathbb{Z}^3$ . On the subset  $U = \{K \neq 0\}$  we can consider the form

$$\gamma = K \lrcorner \Omega$$

which satisfies

$$\begin{cases} \mathcal{L}_K(K \lrcorner \Omega) = 0 \\ d(K \lrcorner \Omega) = 0 \end{cases}$$

which provides a closed 3-form  $\gamma$  on  $U/S^1$ .



Unfortunately, this is **not** the correct answer: in fact, we can find an ON local coframe  $e^1, \dots, e^8$  on  $M^8$  with respect to which

$$\begin{cases} \omega_1 &= e^{12} - e^{34} + e^{56} - e^{78} \\ \omega_2 &= e^{13} - e^{42} + e^{57} - e^{86} \\ \omega_3 &= e^{14} - e^{23} + e^{58} - e^{67}. \end{cases} \quad (2)$$

here we can identify  $e^8 = \alpha_0 / |\alpha_0| = K^\# / |K|$ . In this case

$$\begin{aligned} \gamma &= K \lrcorner \Omega = (e^{12} - e^{34})e^7 - (e^{13} - e^{42})e^6 \\ &\quad - (e^{14} - e^{23})e^5 - 3e^{765}, \end{aligned}$$

which has  $G_2 \subset SO(3, 4)$  as a stabilizer.

In order to have the correct stabilizer we need to change the last command:

$$-3e^{765} \longrightarrow +\lambda e^{765}$$

Unfortunately, this is **not** the correct answer: in fact, we can find an ON orthonormal coframe  $e^1, \dots, e^8$  on  $M^8$  with respect to which

$$\begin{cases} \omega_1 &= e^{12} - e^{34} + e^{56} - e^{78} \\ \omega_2 &= e^{13} - e^{42} + e^{57} - e^{86} \\ \omega_3 &= e^{14} - e^{23} + e^{58} - e^{67}. \end{cases} \quad (2)$$

where we can identify  $e^8 = \alpha_0 / |\alpha_0| = K^\# / |K|$ . In this case

$$\begin{aligned} \gamma = K \lrcorner \Omega &= (e^{12} - e^{34})e^7 - (e^{13} - e^{42})e^6 \\ &\quad - (e^{14} - e^{23})e^5 - 3e^{765}, \end{aligned}$$

which has  $G_2^* \subset SO(3, 4)$  as a stabilizer.

In order to have the correct stabilizer we need to change the last command:

$$-3e^{765} \quad \longrightarrow \quad -e^{765}$$



Unfortunately, this is **not** the correct answer: in fact, we can find an ON local coframe  $e^1, \dots, e^8$  on  $M^8$  with respect to which

$$\begin{cases} \omega_1 &= e^{12} - e^{34} + e^{56} - e^{78} \\ \omega_2 &= e^{13} - e^{42} + e^{57} - e^{86} \\ \omega_3 &= e^{14} - e^{23} + e^{58} - e^{67}. \end{cases} \quad (2)$$

here we can identify  $e^8 = \alpha_0 / |\alpha_0| = K^\# / |K|$ . In this case

$$\begin{aligned} \gamma = K \lrcorner \Omega &= (e^{12} - e^{34})e^7 - (e^{13} - e^{42})e^6 \\ &\quad - (e^{14} - e^{23})e^5 - 3e^{765}, \end{aligned}$$

which has  $G_2^* \subset SO(3, 4)$  as a stabilizer.

In order to have the correct stabilizer we need to change the last command:

$$-3e^{765} \longrightarrow +\lambda e^{765}$$

$\lambda > 0$ .

## Objects associated to an action

The presence of an  $S^1$  action on a QK manifold provides the following related objects:

- a Killing vector field  $K$
- a moment map  $\mu \in \Gamma(\mathcal{G})$  defined by  $c(\nabla K)^\mathcal{G}$
- a reduction of the structure group of  $\mathcal{G}$  to  $S^1 \subset SO(3)$  on  $M = \mu^{-1}(0)$

In other words:

$$\mathcal{G} = \mu^{-1} N$$

where  $N$  is spanned locally by  $\omega_2, \omega_3$ .

## Objects associated to an action

The presence of an  $S^1$  action on a QK manifold provides the following related objects:

- a Killing vector field  $K$
- a moment map  $\mu \in \Gamma(\mathfrak{g})$  defined by  $\iota(\nabla K)^\flat$
- a reduction of the structure group of  $\mathfrak{g}$  to  $S^1 \cong SO(3)$  on  $M := \mu^{-1}(0)$

In other words:

$$\mathfrak{g} = \mu \oplus N$$

where  $N$  is spanned locally by  $\omega_2, \omega_3$ .

## Objects associated to an action

The presence of an  $S^1$  action on a QK manifold provides the following related objects:

- a Killing vector field  $K$
- a moment map  $\mu \in \Gamma(\mathcal{G})$  defined by  $c(\nabla K)^\mathcal{G}$
- a reduction of the structure group of  $\mathcal{G}$  to  $S^1 \simeq SO(3)$  on  $M = \mu^{-1}(0)$

In other words:

$$\mathcal{G} = \mu \oplus N$$

where  $N$  is spanned locally by  $\omega_2, \omega_3$ .



## Objects associated to an action

The presence of an  $S^1$  action on a QK manifold provides the following related objects:

- a Killing vector field  $K$
- a moment map  $\mu \in \Gamma(\mathcal{G})$  defined by  $c(\nabla K)^{\mathcal{G}}$
- a reduction of the structure group of  $\mathcal{G}$  to  $S^1 \subset SO(3)$  on  $M \setminus \mu^{-1}(0)$

other words:

$$\mathcal{G} = \mu \oplus N$$

where  $N$  is spanned locally by  $\omega_2, \omega_3$ .

## Structure equations for $\mathcal{G}$

$$\nabla\omega_1 = \alpha_2 \otimes \omega_2 + \alpha_3 \otimes \omega_3$$

$$\nabla\omega_2 = -\alpha_2 \otimes \omega_1 + \beta \otimes \omega_3$$

$$\nabla\omega_3 = -\beta \otimes \omega_2 + \alpha_3 \otimes \omega_1$$

with  $\beta, \alpha_2, \alpha_3$  local 1-forms.

## $I_1$ -invariant forms

- $d\beta$
- $\omega_1 = \frac{\mu}{|\mu|}$
- $d\omega_1 = \alpha_2 \wedge \omega_2 + \alpha_3 \wedge \omega_3$
- $I_1 d\omega_1 = \alpha_2 \wedge \omega_3 - \alpha_3 \wedge \omega_2$

are well defined on the open set  $M^8 \setminus \{\mu^{-1}(0)\}$ .

## Calibrated $G_2$ Structures

Let us set

$$M_0 = M^8 \setminus (\{\mu = 0\} \cup \{K = 0\}),$$

and let us define

$$\tau = I_1 \alpha_0 \wedge (d\beta + \omega_1)$$

### Theorem

Consider an  $S^1$  action on  $M^8$  as before. Let us consider

$$\phi = A\gamma + B\tau, \tag{3}$$

where  $A, B$  are certain functions of  $\|\mu\|$  and of a parameter  $t \in \mathbb{R}$ .  
Then the form  $\phi$  induces a 1-parameter family of calibrated  $G_2$  structures on the quotient  $M^7 = M_0/S^1$ .

## Example

Let us consider  $\mathbb{H}\mathbb{P}^2$  with  $S^1$  associated to  $\mathbf{w} = (1, 0, 0)$ . Then

$$\{K = 0\} \cong S^4 \cup [1, 0, 0] \quad \text{and} \quad \{\mu = 0\} \cong S^4$$

Moreover  $C(S^1_{\mathbf{w}}) = S^1 \times Sp(2)$ . So

$$\mathbb{H}\mathbb{P}^2 \setminus (S^4 \cup [1, 0, 0]) \longrightarrow \Lambda^2_+ S^4 \setminus S^4$$

surjectively and  $Sp(2)$ -equivariantly.

the Bryant-Salamon metric amongst the calibrated  $G_2$ -structures obtained in the theorem?



## Half-flat geometry

Let  $M^6$  be a 6-dimensional manifold with an  $SU(3)$ -structure characterized by

$$\omega \in \Lambda^{1,1} \quad \psi^+ + v\psi^- \in \Lambda^{3,0}.$$

Then we say that  $M^6$  is *half-flat* if the following equations are satisfied:

$$\begin{cases} d\omega \wedge \omega = 0 \\ d(\psi^+) = 0 \end{cases}$$

The *intrinsic torsion* of the  $SU(3)$  structure lies in a direct sum

$$W_1^\pm + W_2^\pm + W_3 + W_4 + W_5$$

The half-flat condition implies that the projections on  $W_{1,2}^-$  and  $W_{4,5}$  are zero.

## Example

Let us consider  $\mathbb{H}\mathbb{P}^2$  with  $S^1$  associated to  $\mathbf{w} = (1, 0, 0)$ . Then

$$\{K = 0\} \cong S^4 \cup [1, 0, 0] \quad \text{and} \quad \{\mu = 0\} \cong S^4$$

Moreover  $C(S^1_{\mathbf{w}}) = S^1 \times Sp(2)$ . So

$$\mathbb{H}\mathbb{P}^2 \setminus (S^4 \cup [1, 0, 0]) \longrightarrow \Lambda^2_+ S^4 \setminus S^4$$

surjectively and  $Sp(2)$ -equivariantly.

the Bryant-Salamon metric amongst the calibrated  $G_2$ -structures obtained in the theorem?

## Half-flat geometry

Let  $M^6$  be a 6-dimensional manifold with an  $SU(3)$ -structure characterized by

$$\omega \in \Lambda^{1,1} \quad \psi^+ + \nu\psi^- \in \Lambda^{3,0}.$$

Then we say that  $M^6$  is *half-flat* if the following equations are satisfied:

$$\begin{cases} d\omega \wedge \omega = 0 \\ d\psi^+ = 0 \end{cases}$$

The *intrinsic torsion* of the  $SU(3)$  structure lies in a direct sum

$$W_1^\pm + W_2^\pm + W_3 + W_4 + W_5$$

The half-flat condition implies that the projections on  $W_{1,2}^-$  and  $W_{4,5}$  are zero.

## Open Questions

- find an expression for  $*\phi$  in terms of the known forms, and see if in the manifold of calibrated  $G_2$  structure there are any which are *integrable*;
- the  $S^1$  quotients of the hypersurfaces  $\{\|\mu\| = c \neq 0\}$  admit a half flat structure: does the  $G_2$  cone over these coincide with some of the above metrics?
- study the relationships with the Bryant-Salamon examples for the weights  $(1, 1, 1)$  and  $(1, 0, 0)$  on  $\mathbb{H}\mathbb{P}^2$ ;