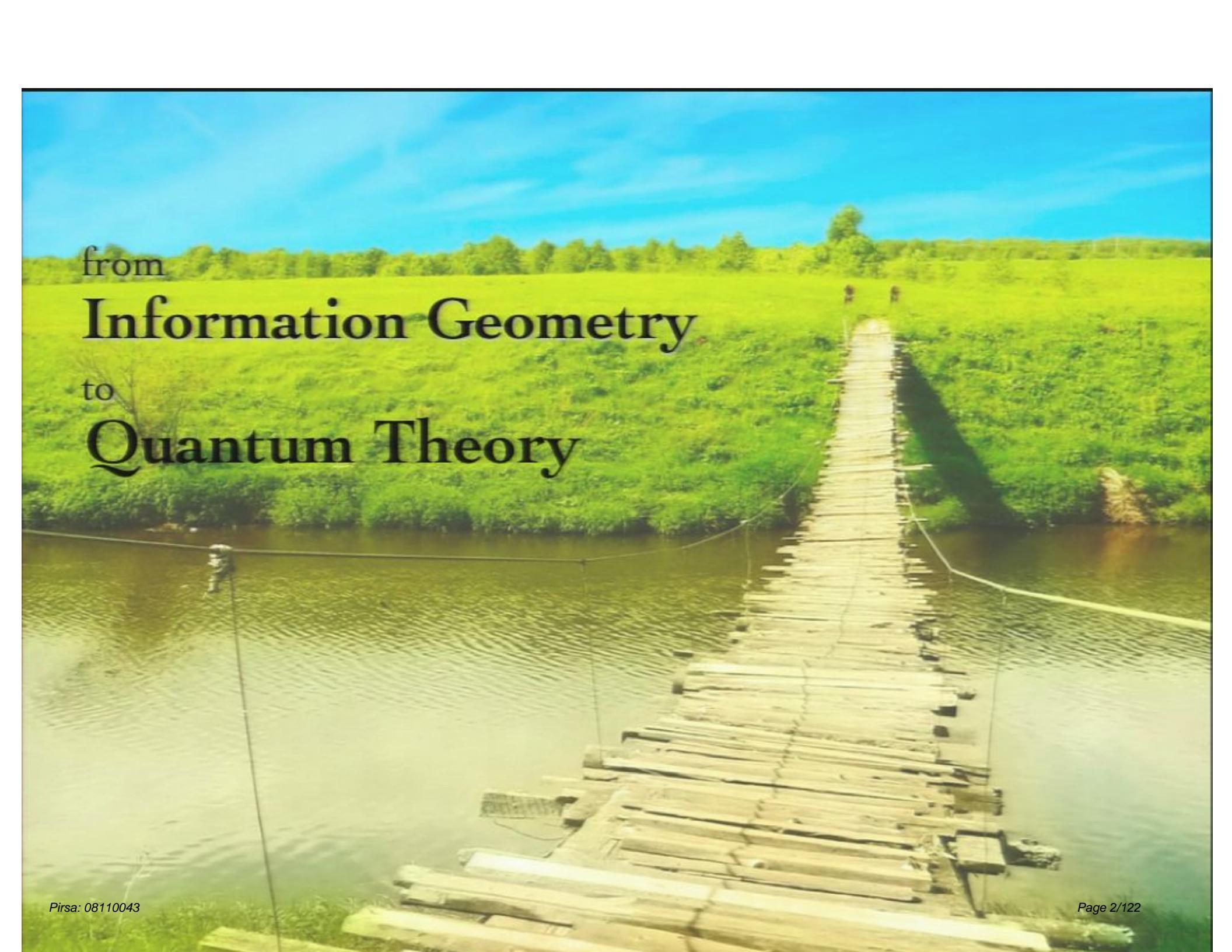


Title: From Information Geometry to Quantum Theory

Date: Nov 04, 2008 04:00 PM

URL: <http://pirsa.org/08110043>

Abstract: The unparalleled empirical success of quantum theory strongly suggests that it accurately captures fundamental aspects of the workings of the physical world. The clear articulation of these aspects is of inestimable value --- not only for the deeper understanding of quantum theory in itself, but for its further development, particularly for the development of a theory of quantum gravity. Recently, there has been growing interest in elucidating these aspects by expressing, in a less abstract mathematical language, what we think quantum theory might be telling us about how nature works, and trying to derive, or reconstruct, quantum theory from these postulates. In this talk, I describe a simple reconstruction of the finite-dimensional quantum formalism. The derivation takes place with a classical probabilistic framework equipped with the information (or Fisher-Rao) metric, and rests upon a small number of elementary ideas (such as complementarity and global gauge invariance). The complex structure of quantum formalism arises very naturally. The derivation provides a number of non-trivial insights into the quantum formalism, such as the extensive nature of the role of information geometry in determining the quantum formalism, the importance of global gauge invariance, and the importance (or lack thereof) of assumptions concerning separated systems.

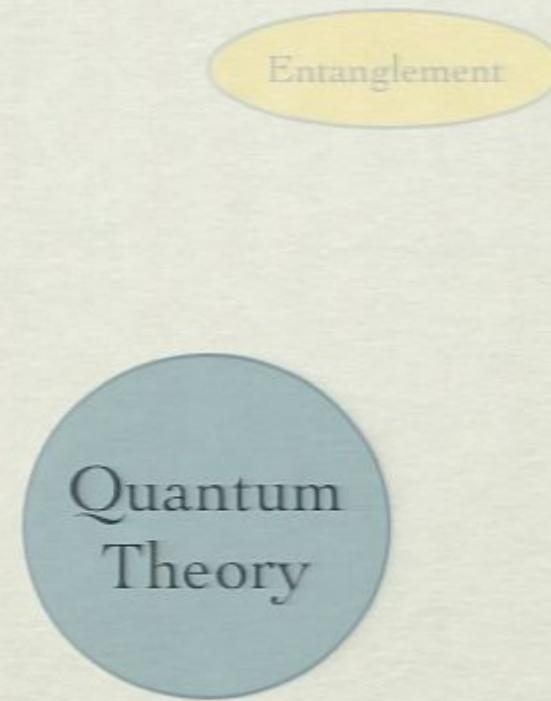
A photograph of a wooden boardwalk or bridge made of planks, extending from the bottom left towards the center of the frame. It crosses a body of water with some ripples. On either side of the water, there are lush green fields. In the far distance, a line of trees is visible under a clear blue sky.

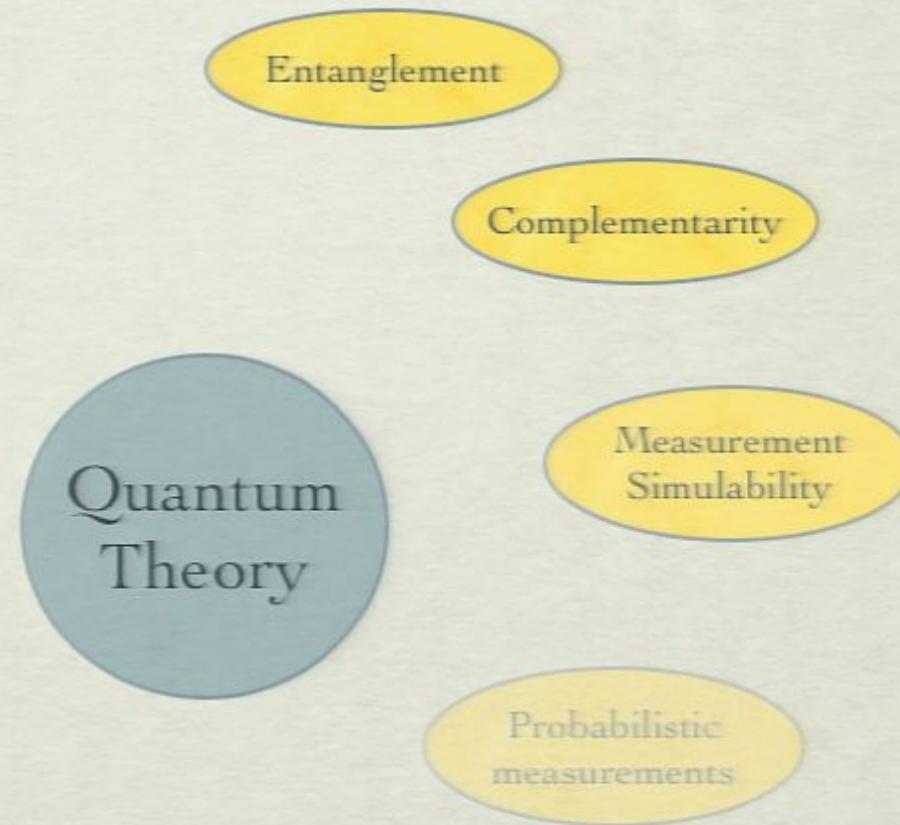
from

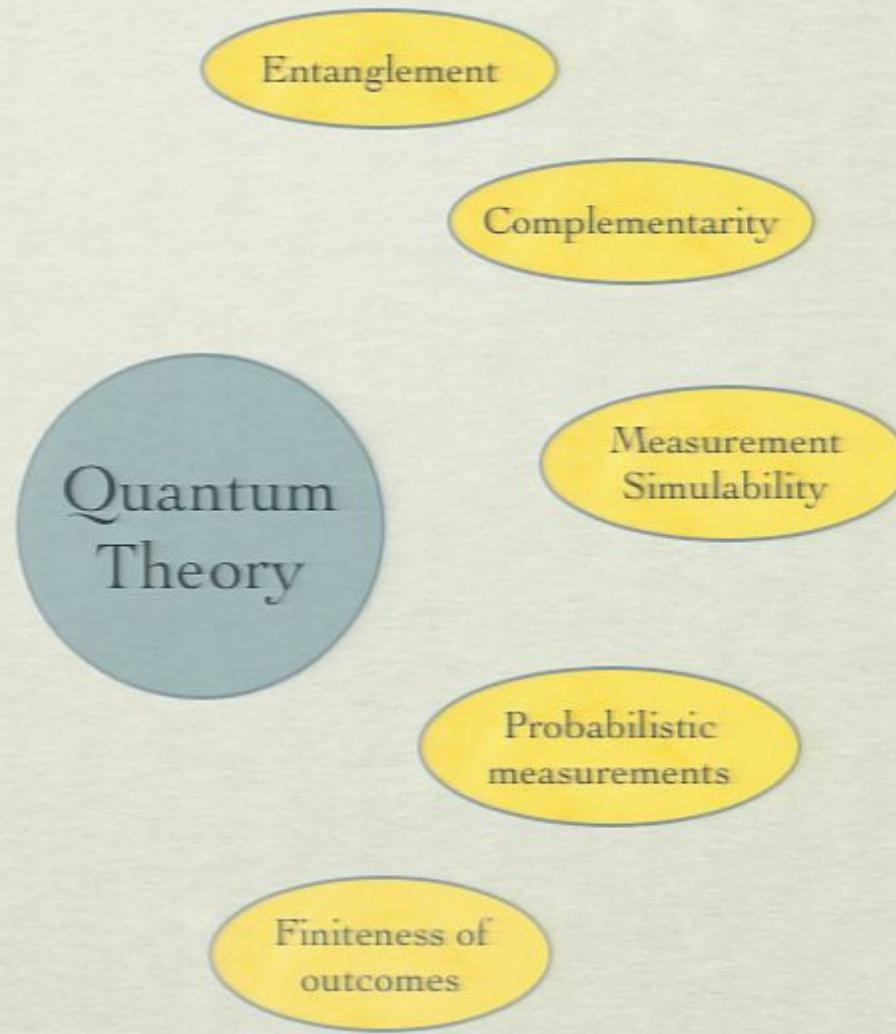
Information Geometry

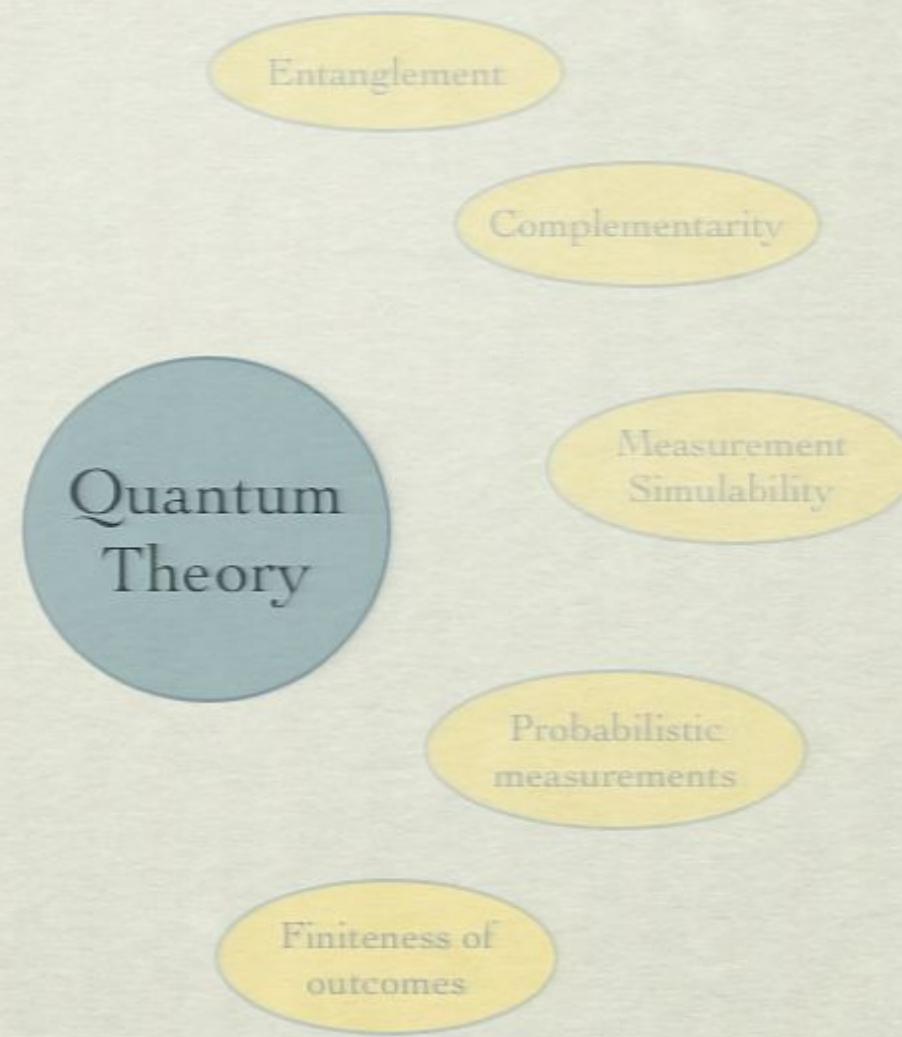
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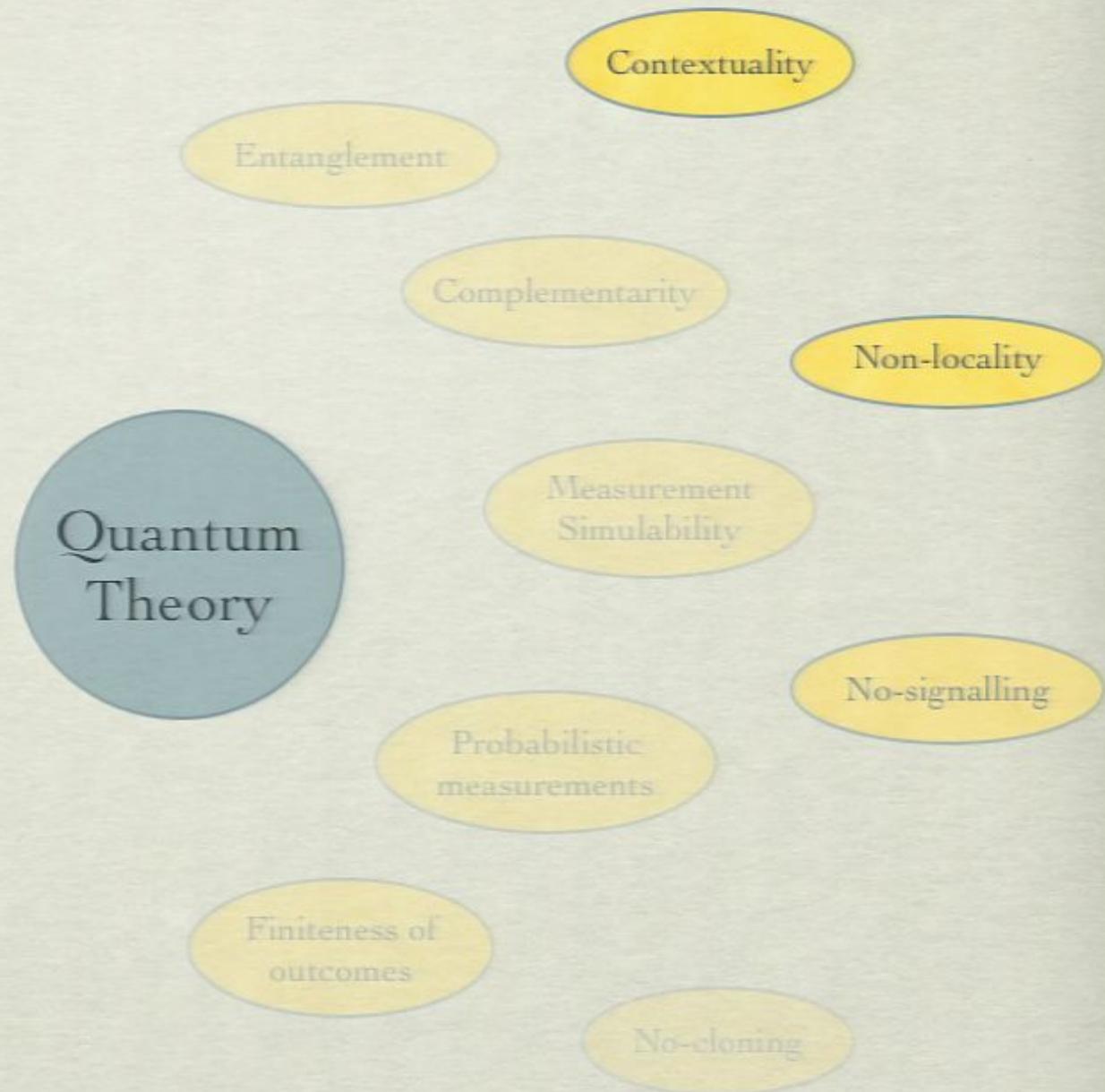
Quantum Theory

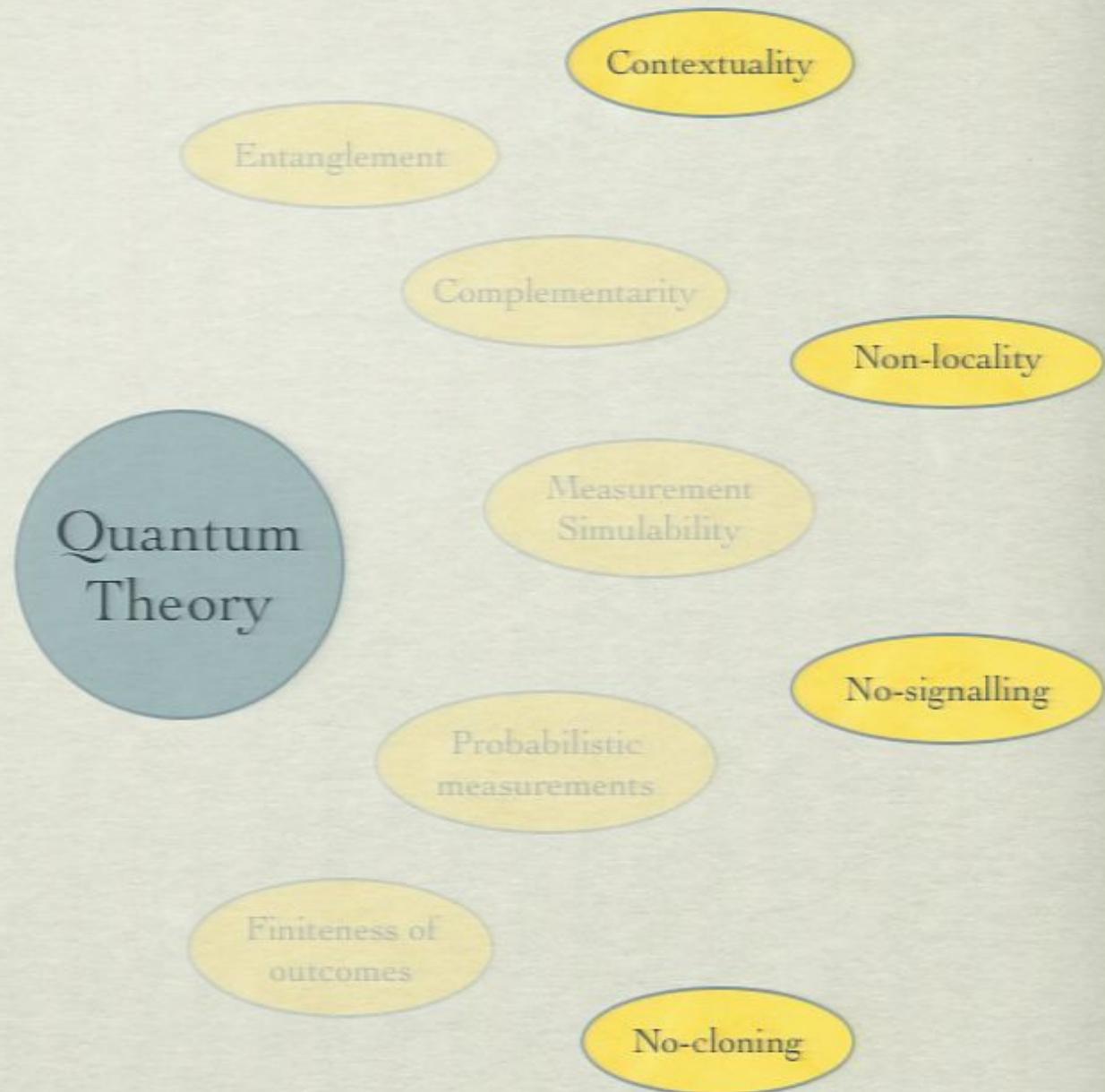




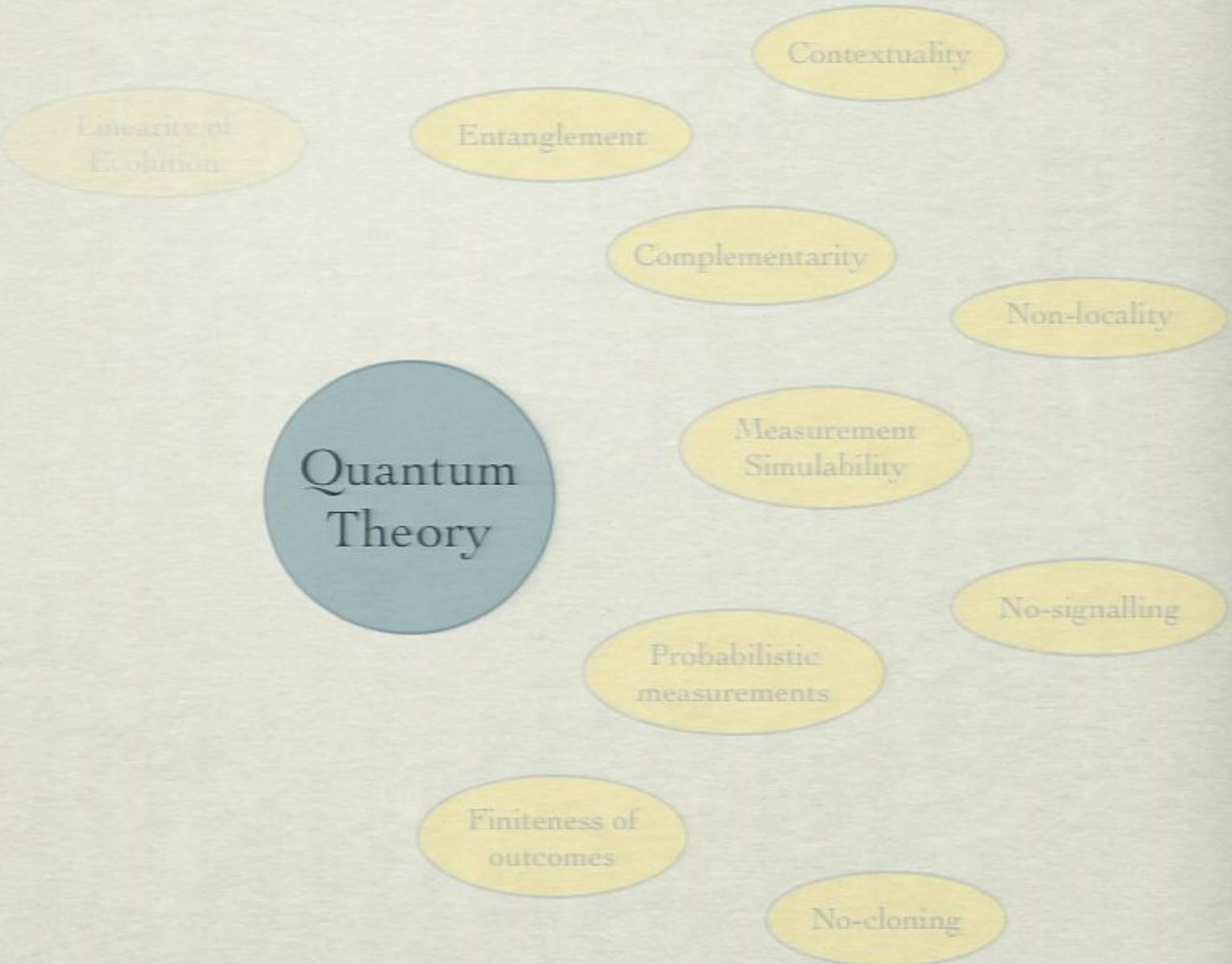


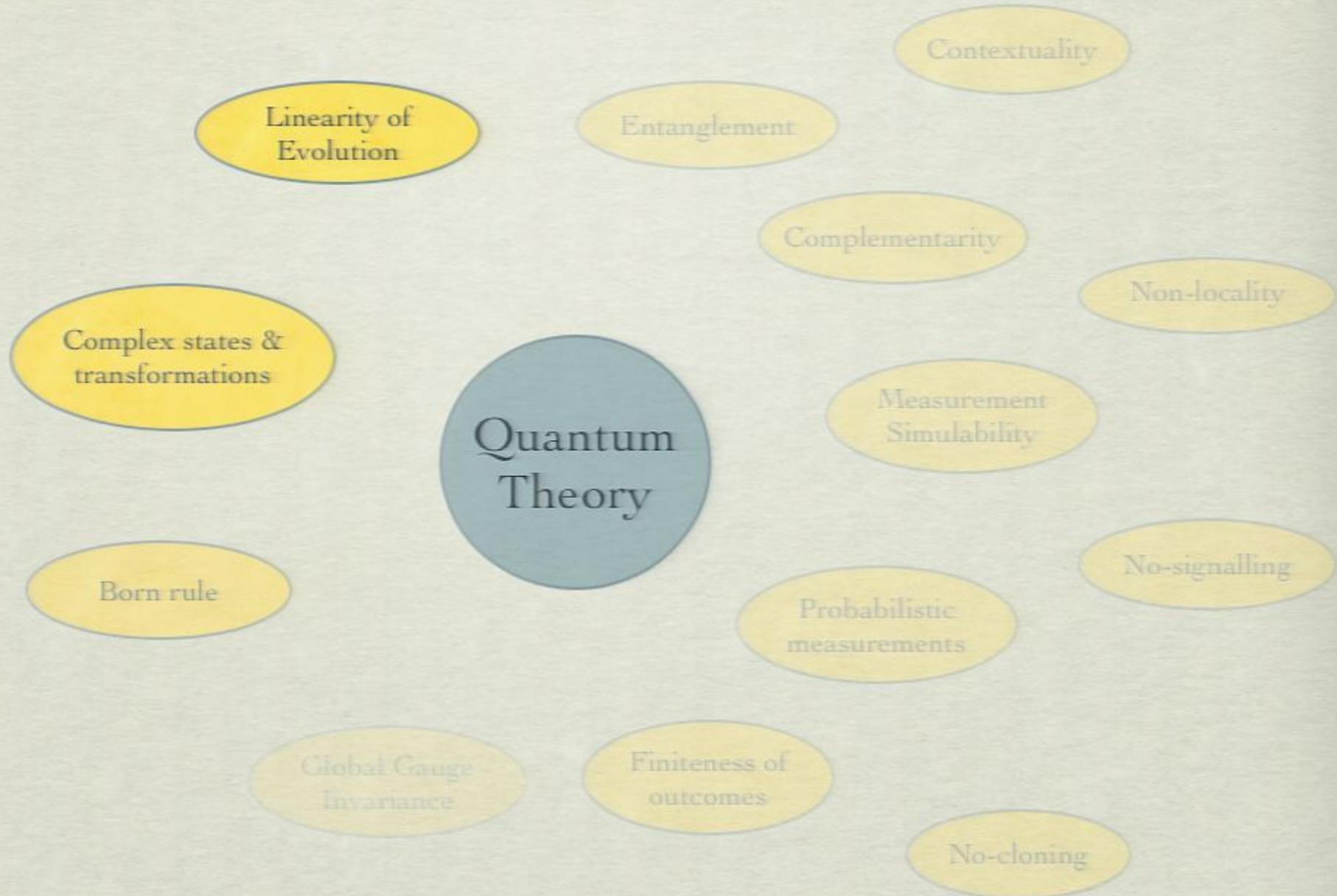


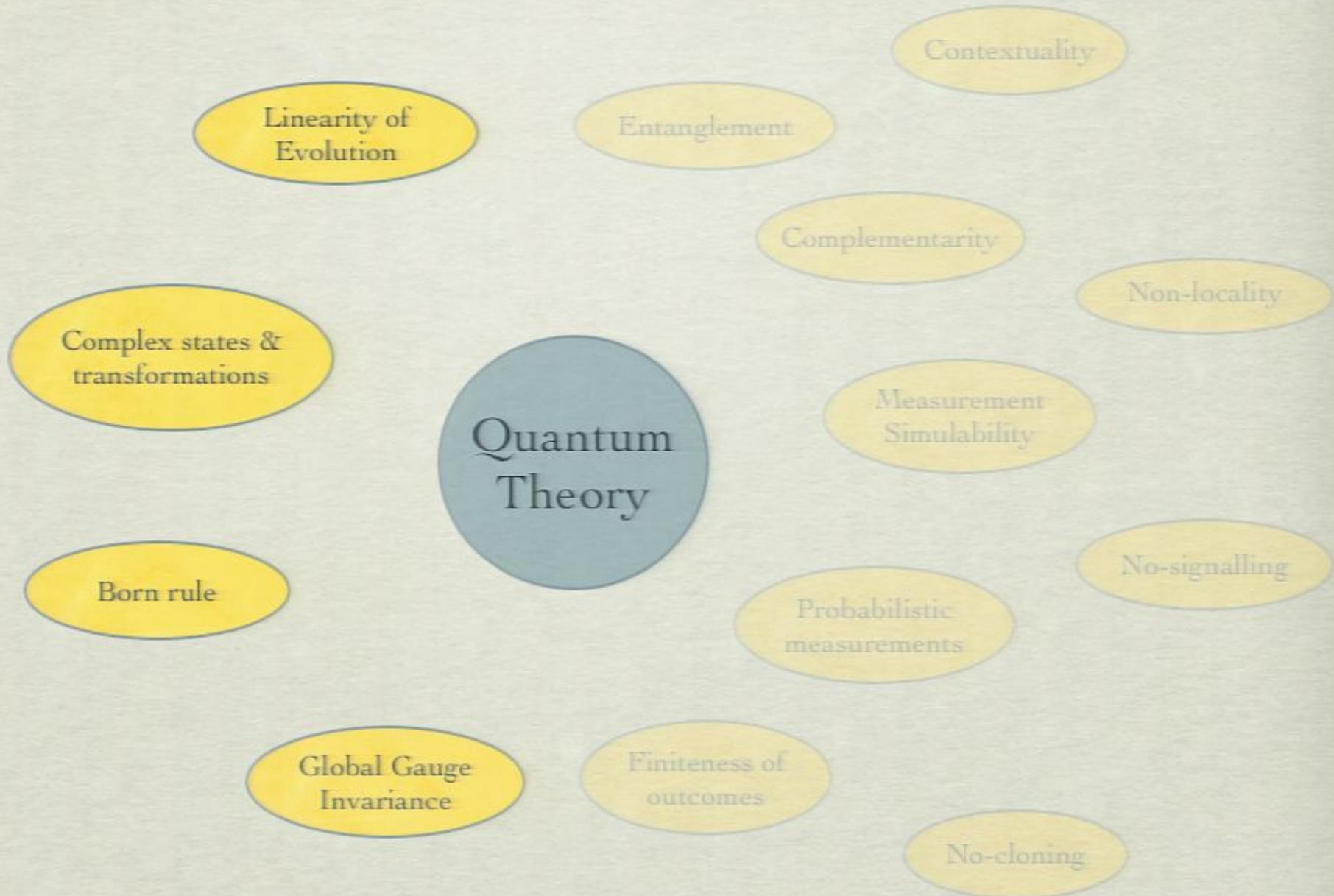




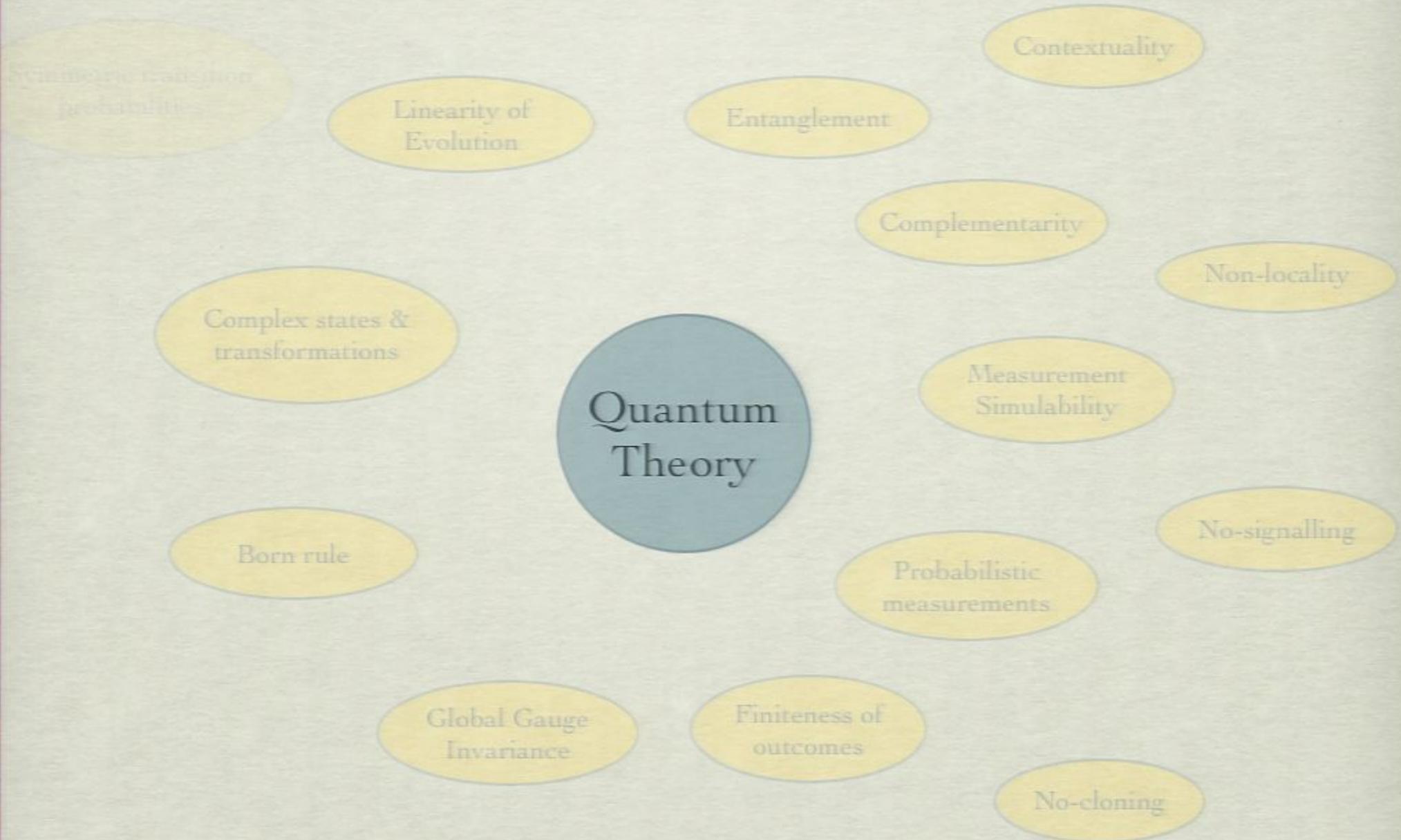
Quantum Theory







Quantum Theory



Quantum Theory

Symmetric transition probabilities

Linearity of Evolution

Entanglement

Contextuality

Complex states & transformations

Complementarity

Non-locality

Born rule

Measurement Simulability

No-signalling

Continuous transformations between states

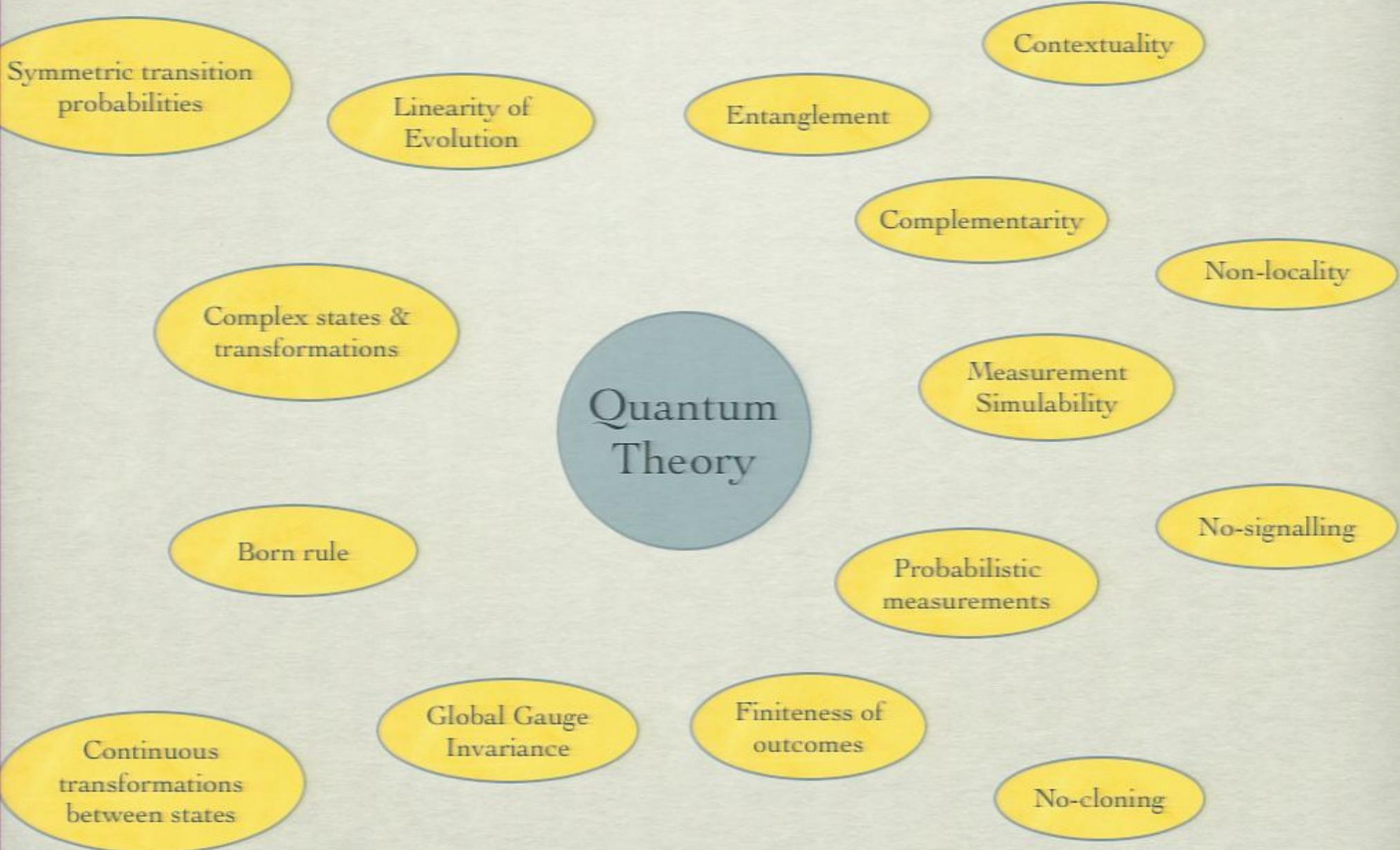
Probabilistic measurements

Global Gauge Invariance

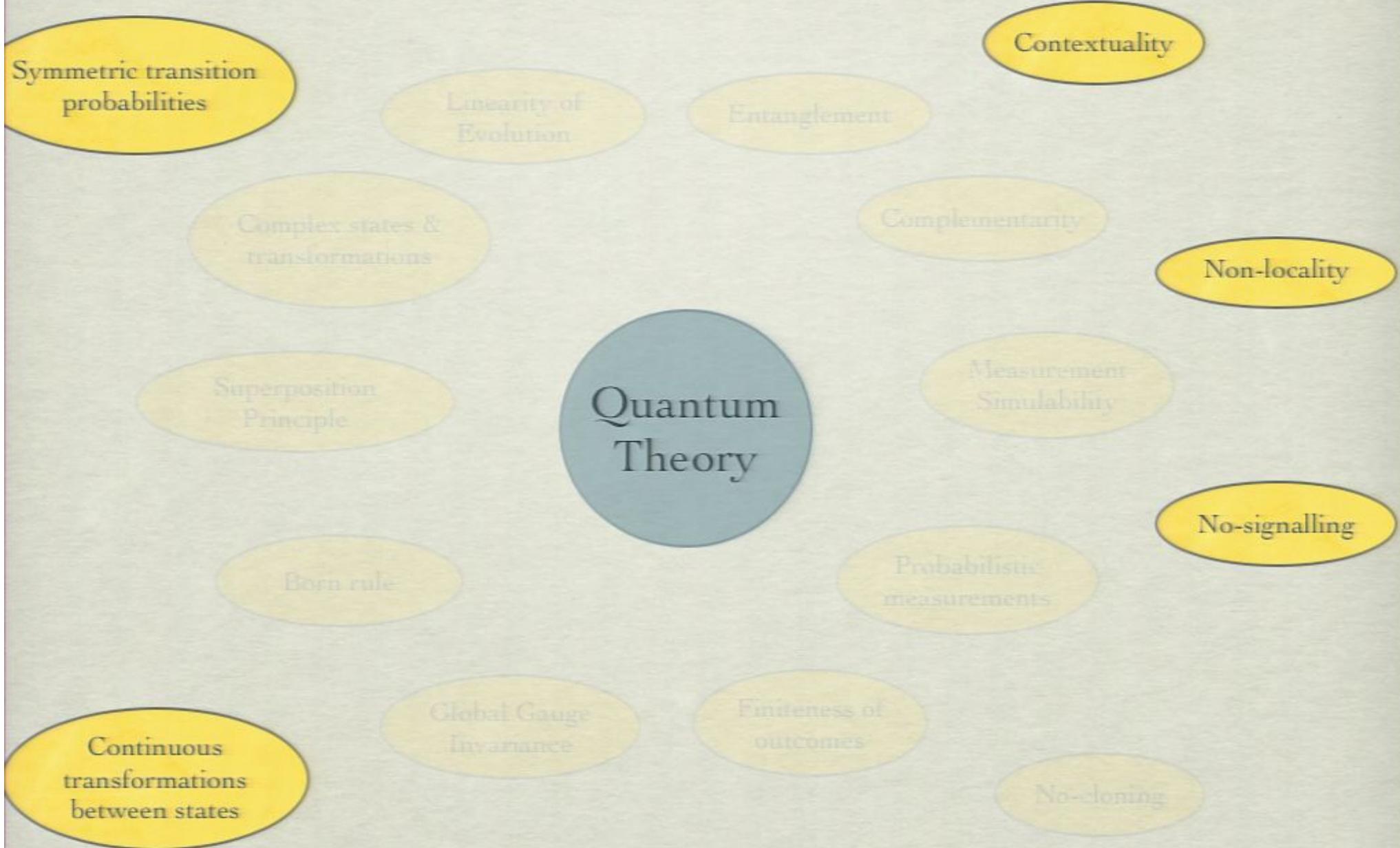
Finiteness of outcomes

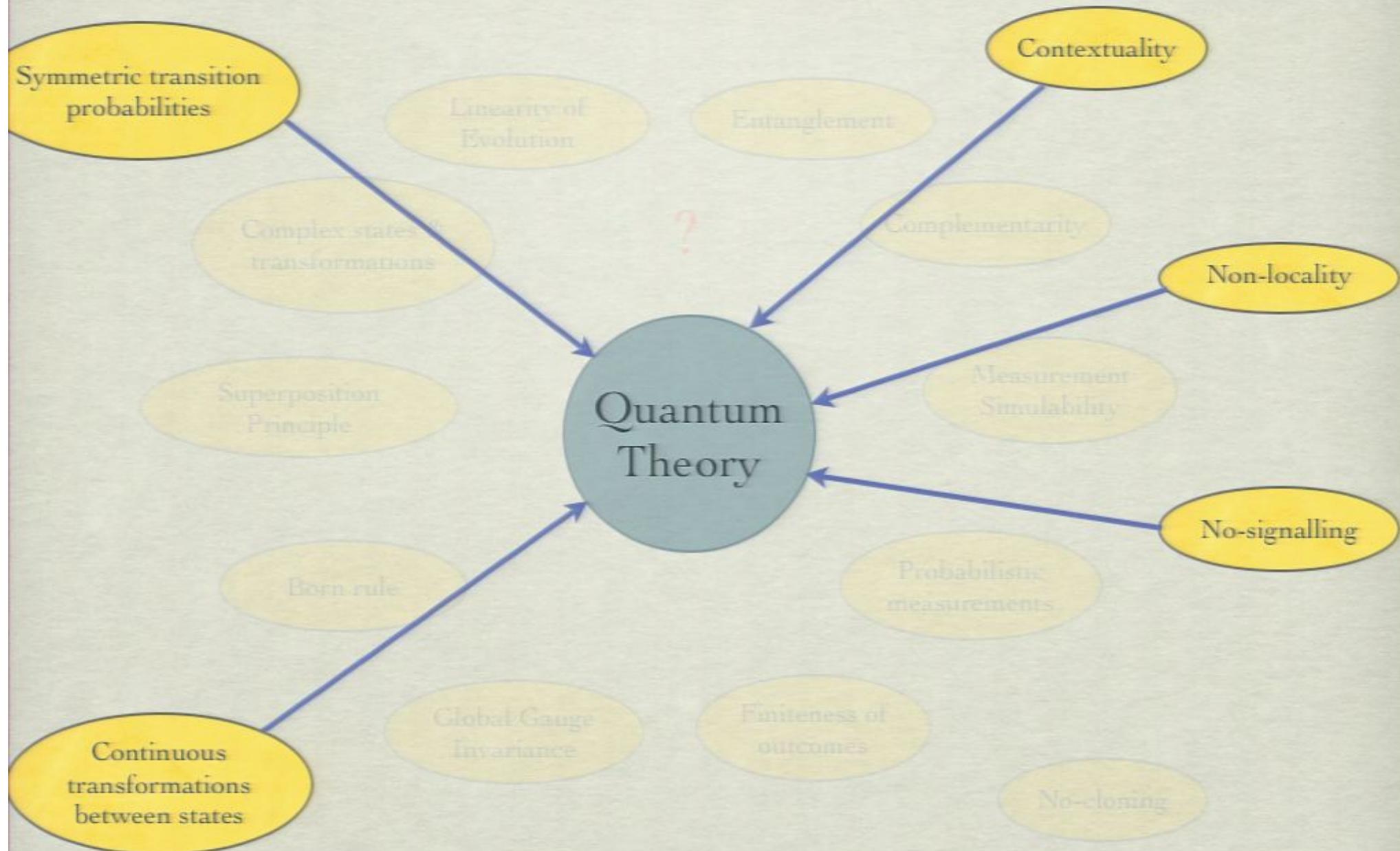
No-cloning

Quantum Theory

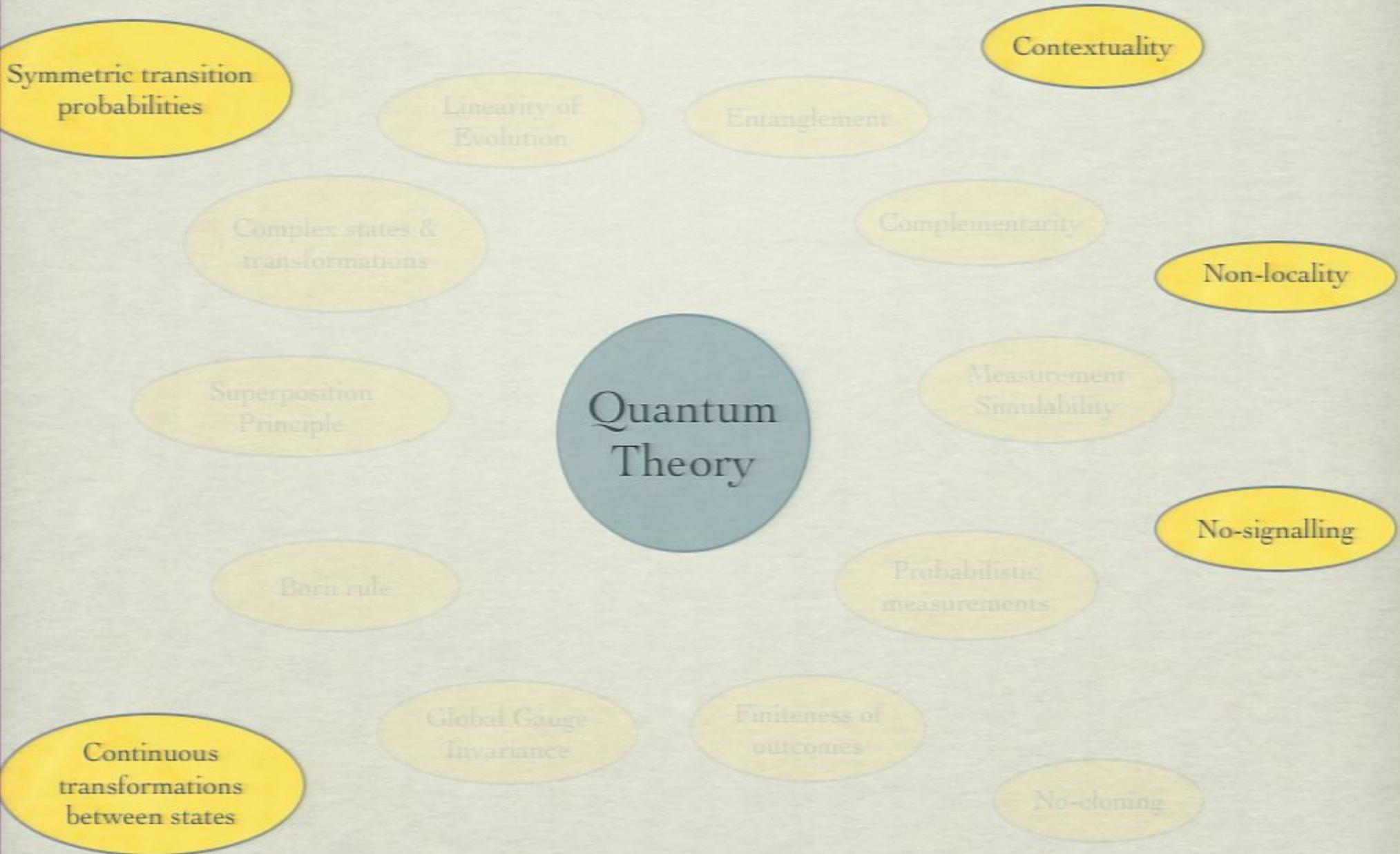


Quantum Theory

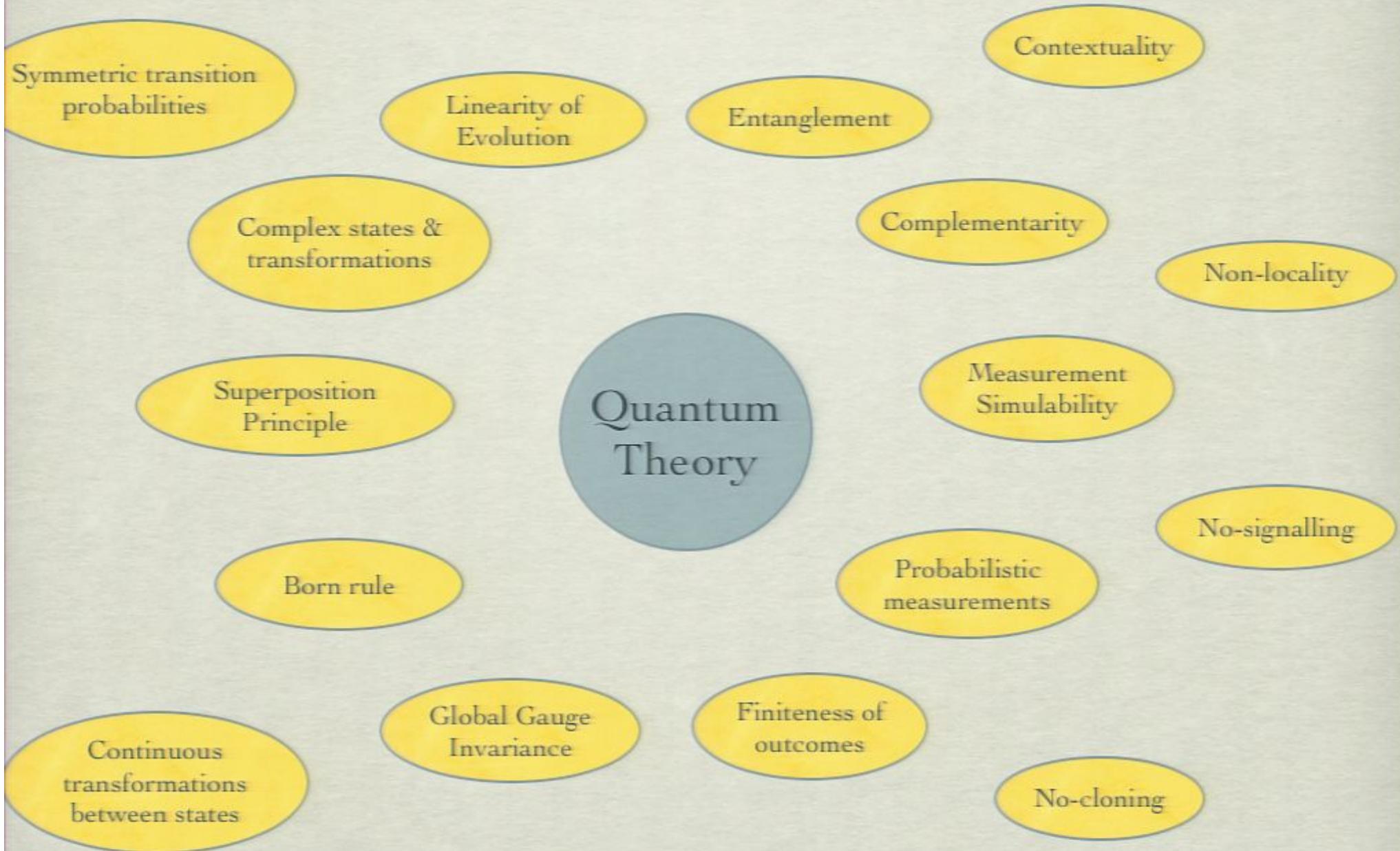


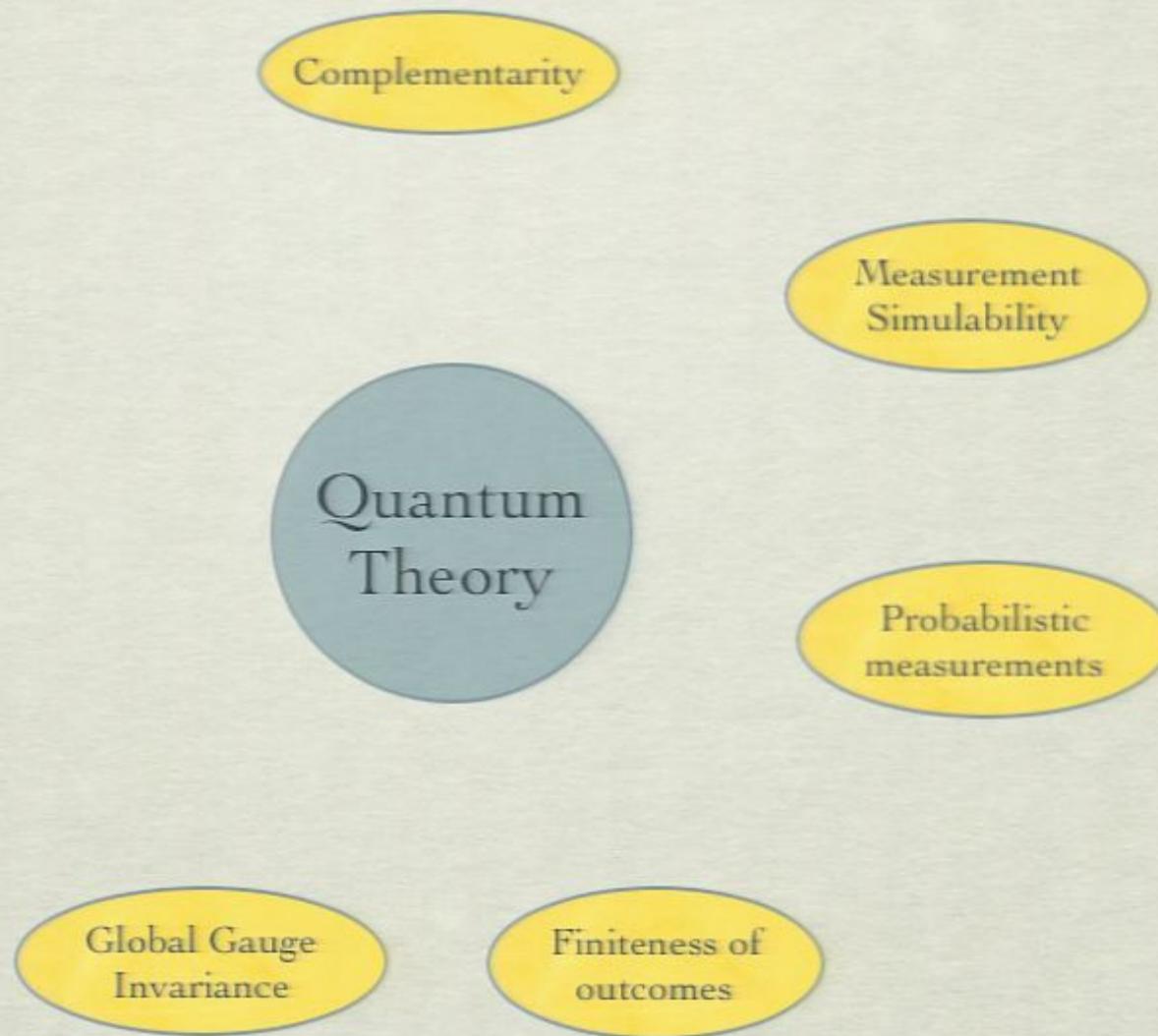


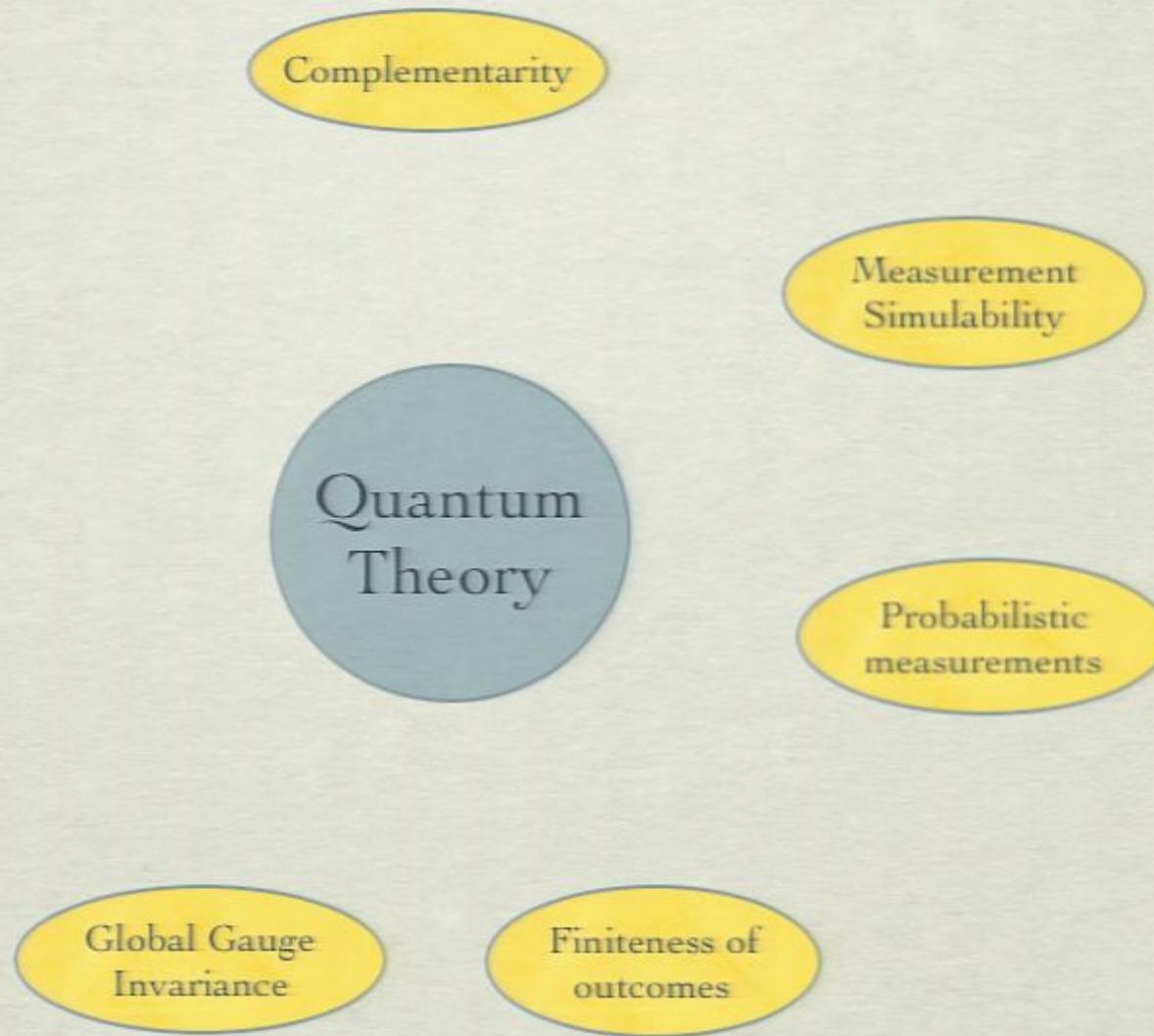
Quantum Theory

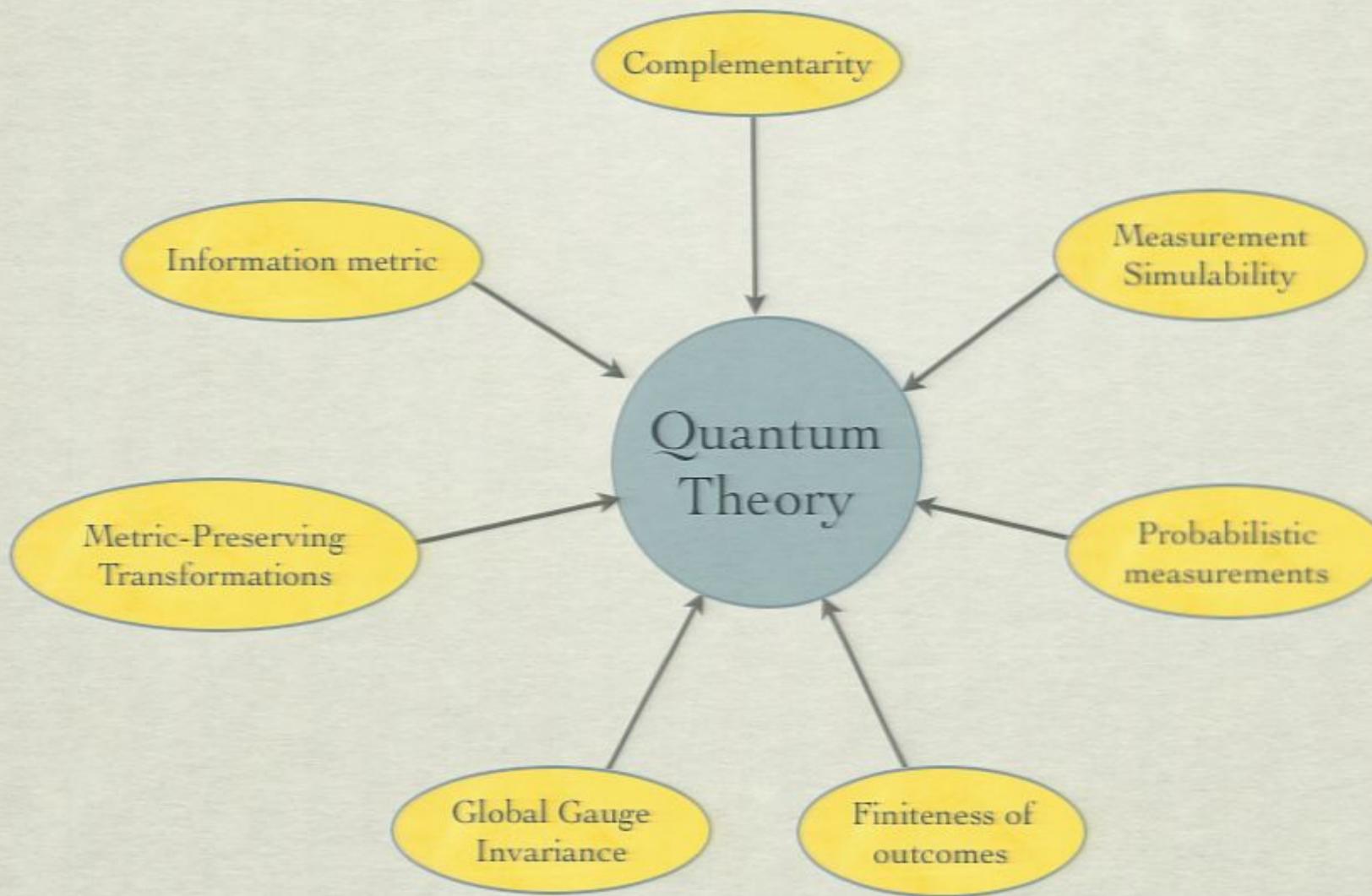


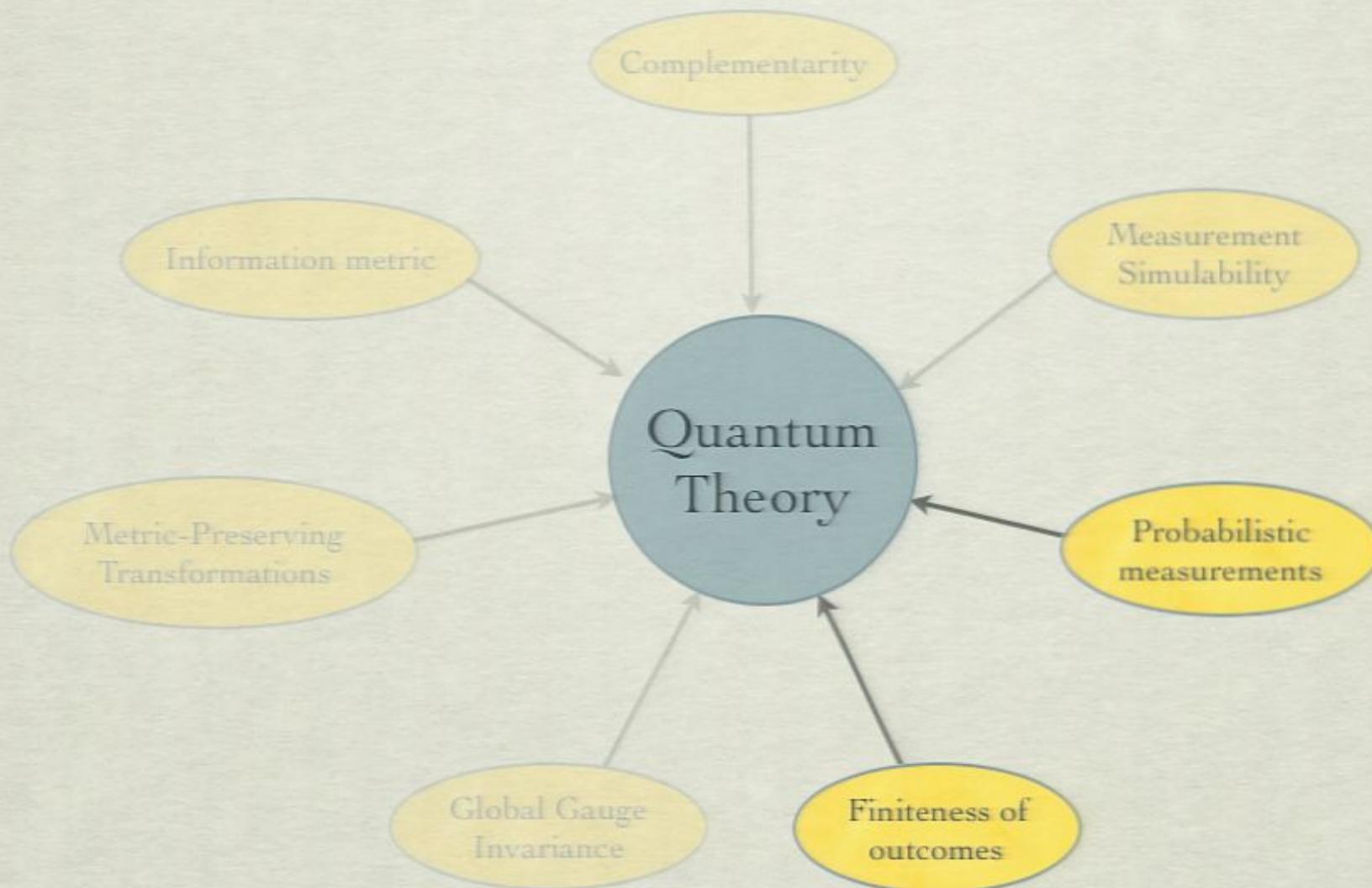
Quantum Theory











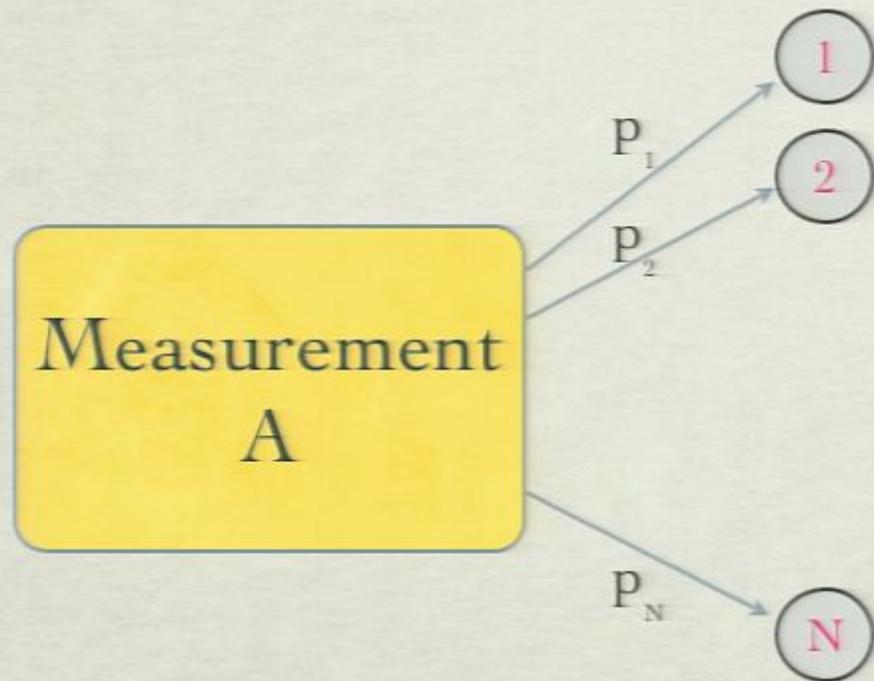
System

System

Measurement
A

1

System

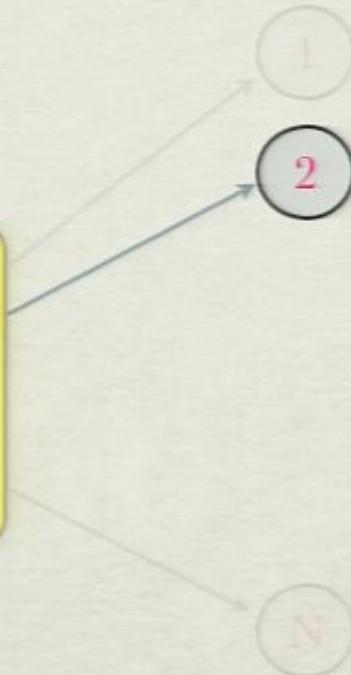


System



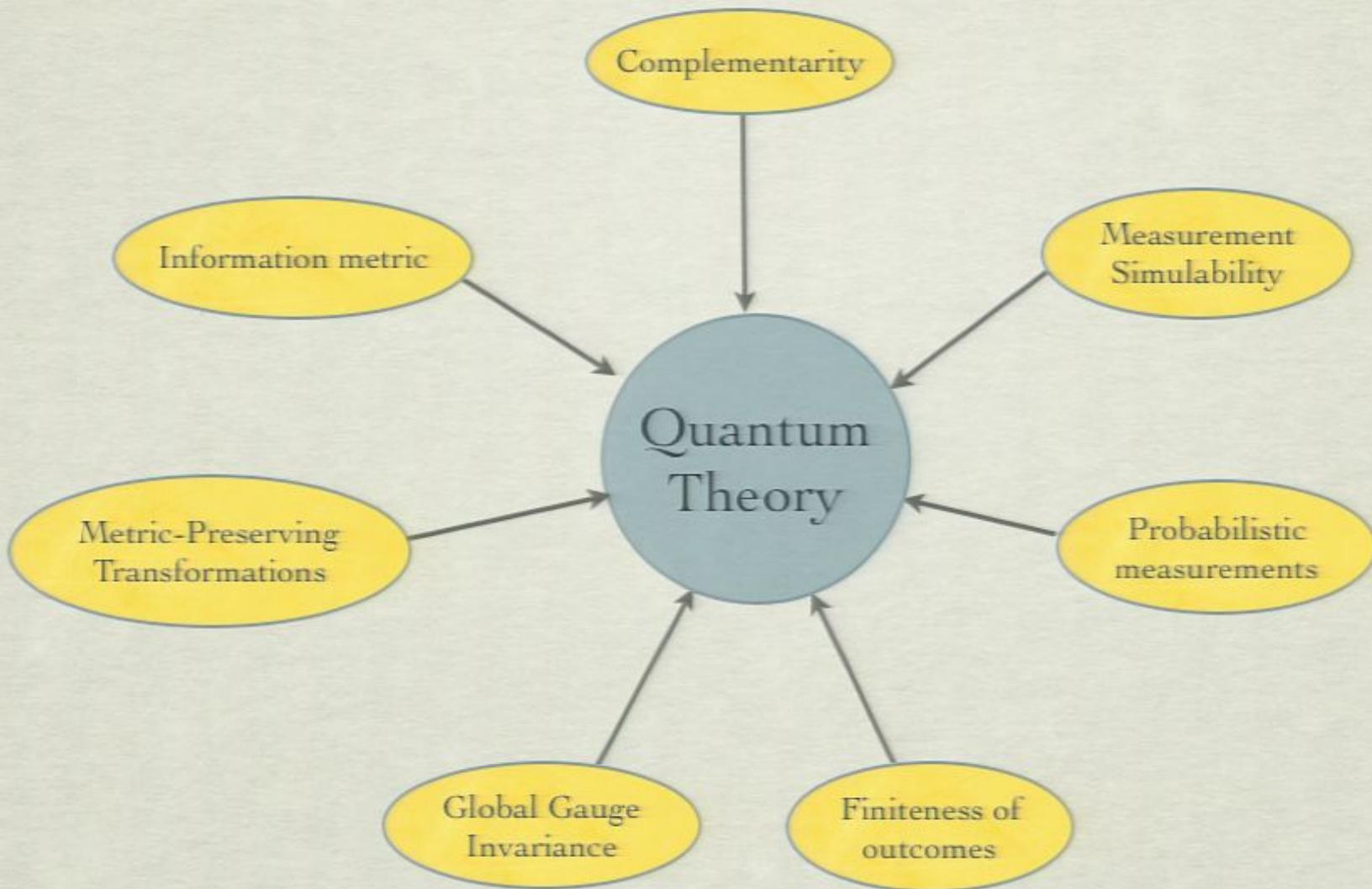
System

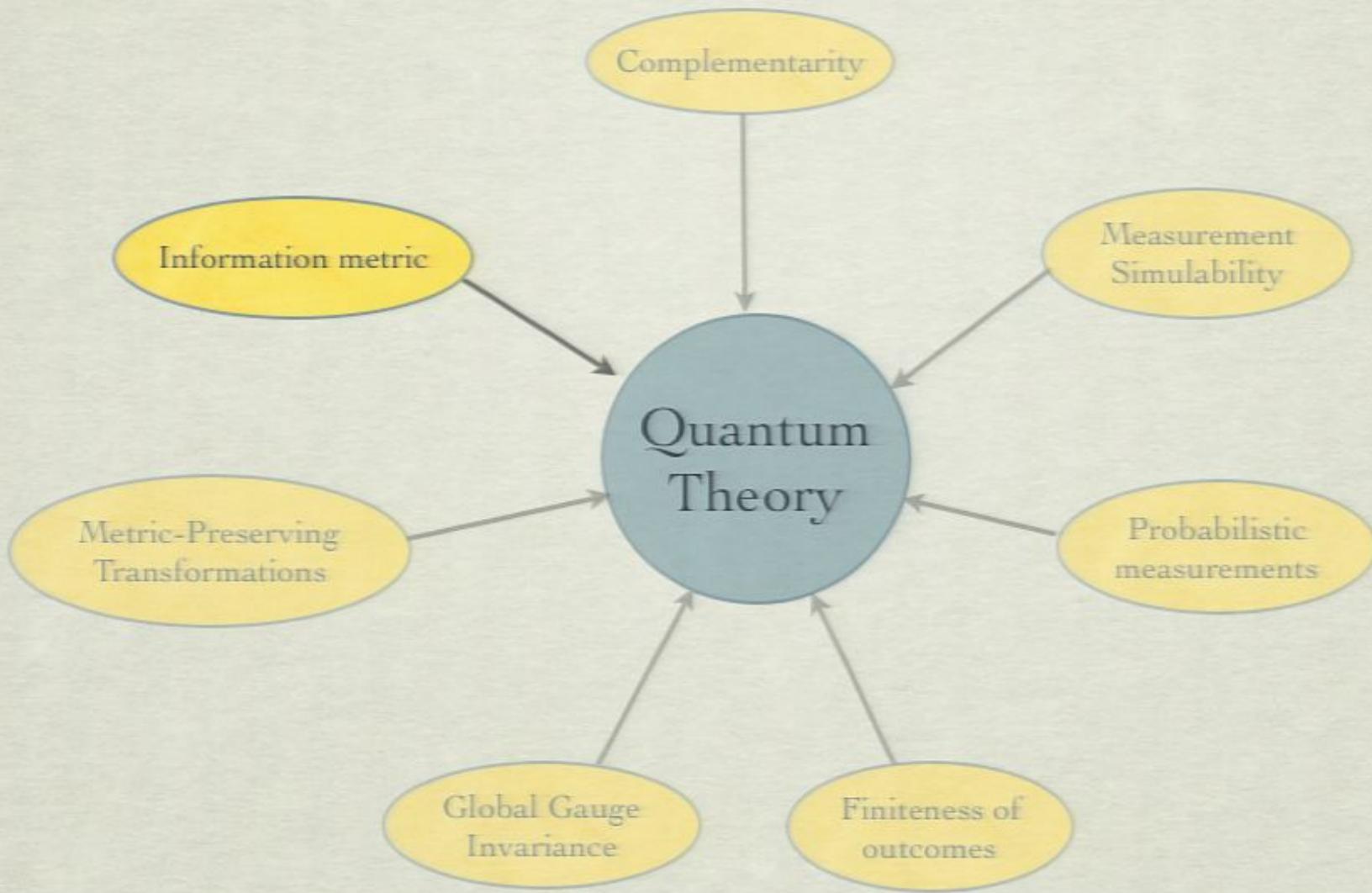
Measurement
A

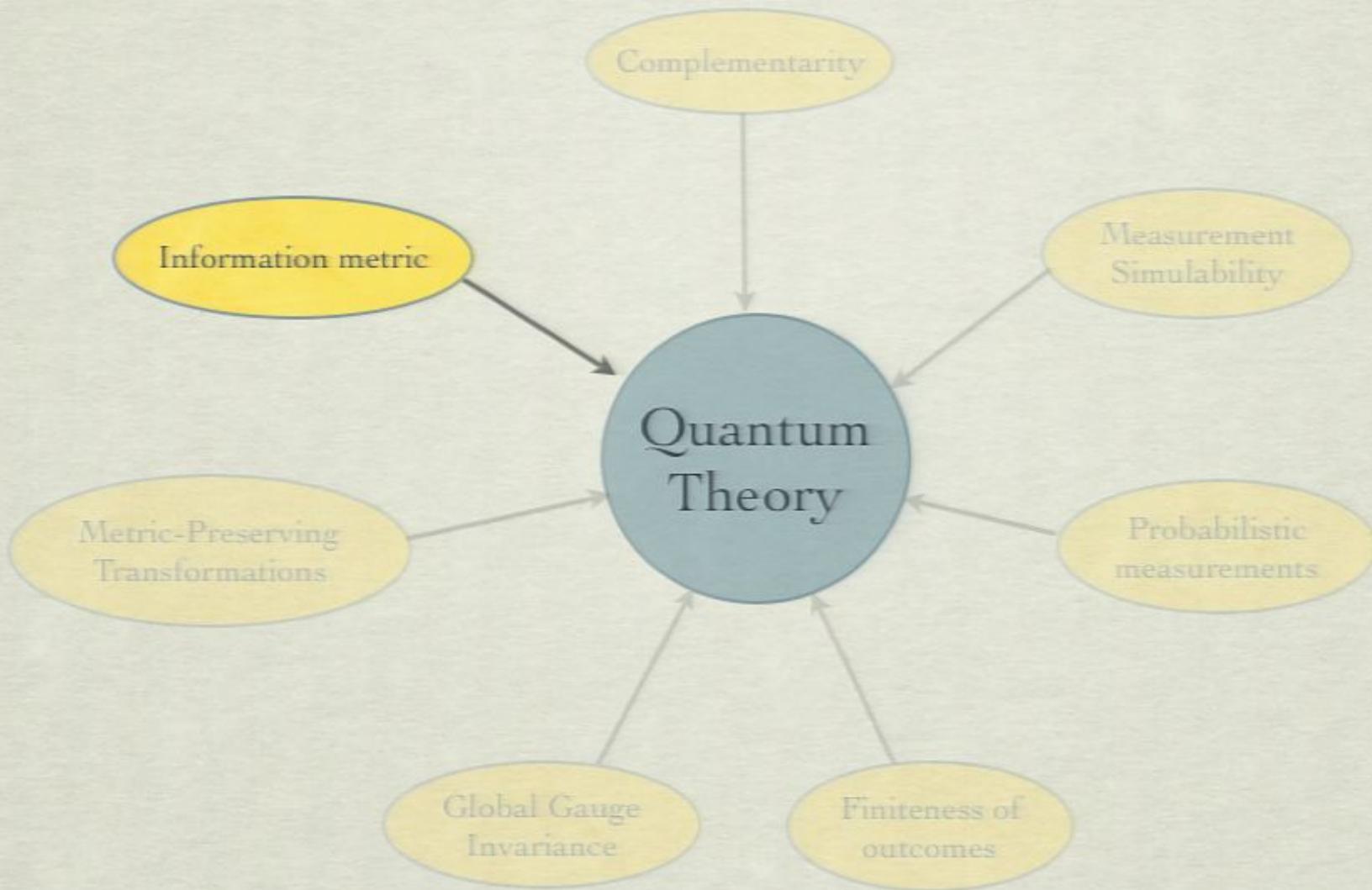


Measurement
A









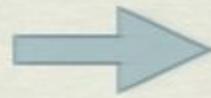
Coin A: $\mathbf{p} = (p_1, p_2)$

Coin B: $\mathbf{p}' = (p'_1, p'_2)$

Coin A: $\mathbf{p} = (p_1, p_2)$

Coin B: $\mathbf{p}' = (p'_1, p'_2)$

n tosses



"HTHT.....T"

Coin A: $\mathbf{p} = (p_1, p_2)$

Coin B: $\mathbf{p}' = (p'_1, p'_2)$

n tosses



“HTHT.....T”

Coin A: $\mathbf{p} = (p_1, p_2)$

Coin B: $\mathbf{p}' = (p'_1, p'_2)$

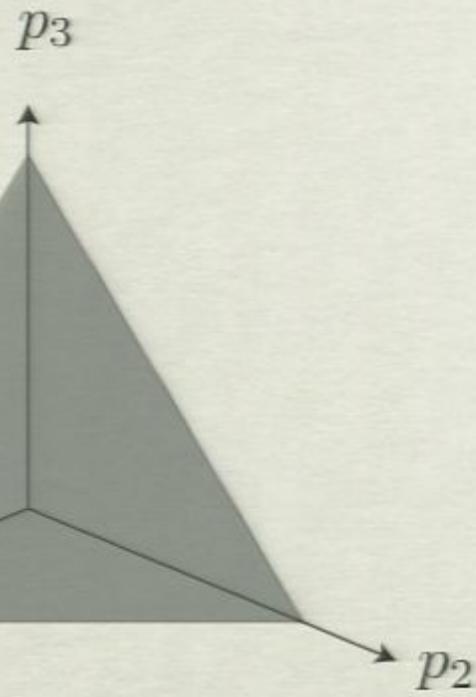
n tosses



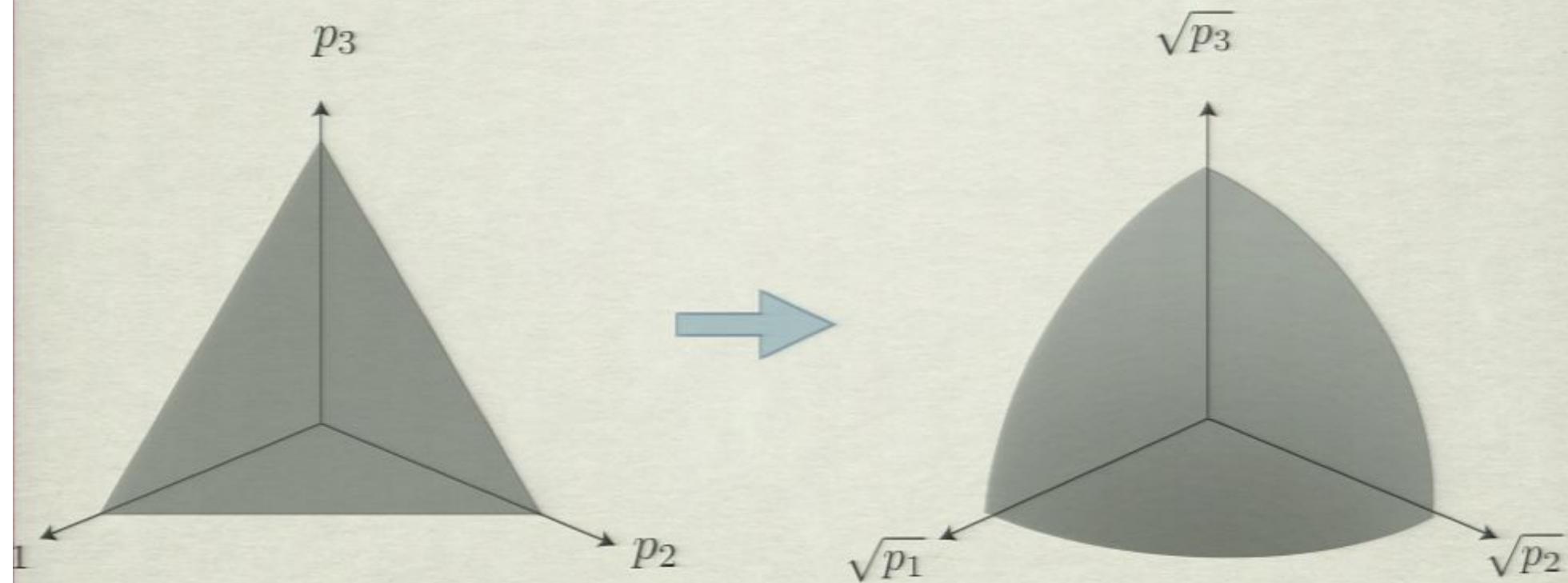
“HTHT.....T”

Information gained = $f(n ds^2)$, when $\mathbf{p}' = \mathbf{p} + d\mathbf{p}$

$$\text{where } ds^2 = \frac{1}{4} \sum_{i=1}^2 \frac{dp_i^2}{p_i}$$



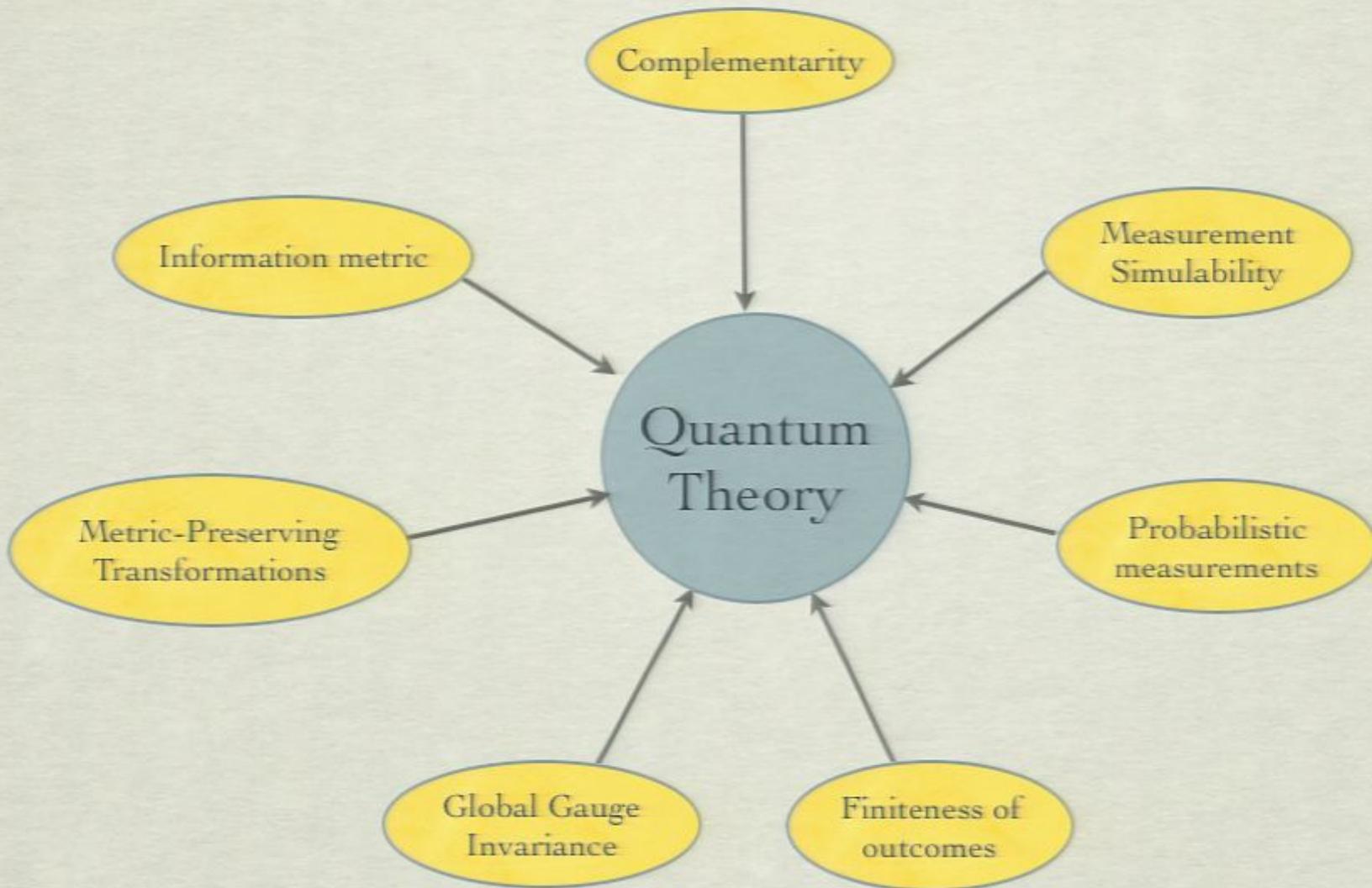
$$ds^2 = \frac{1}{4} \sum_i \frac{dp_i^2}{p_i}$$

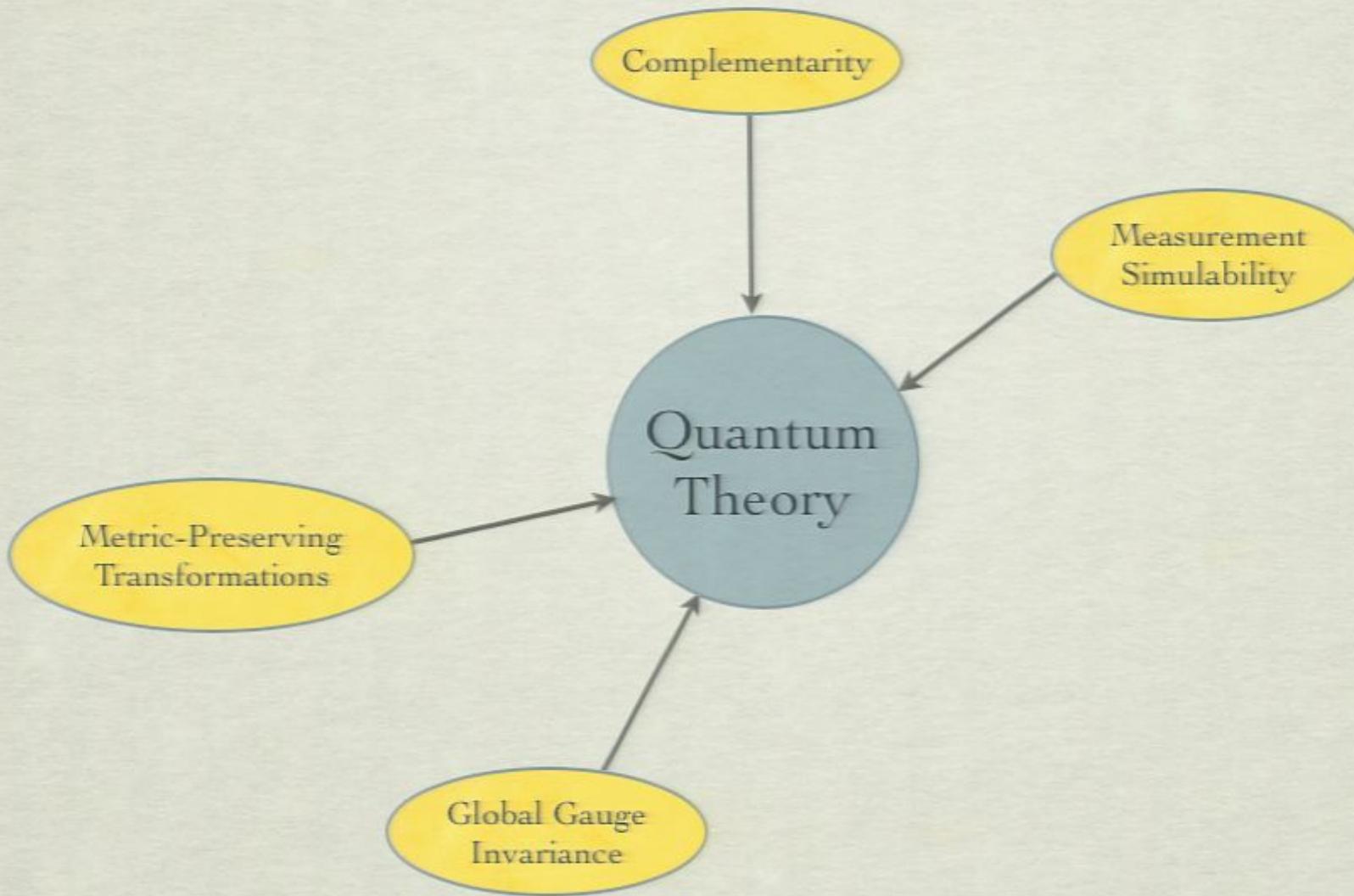


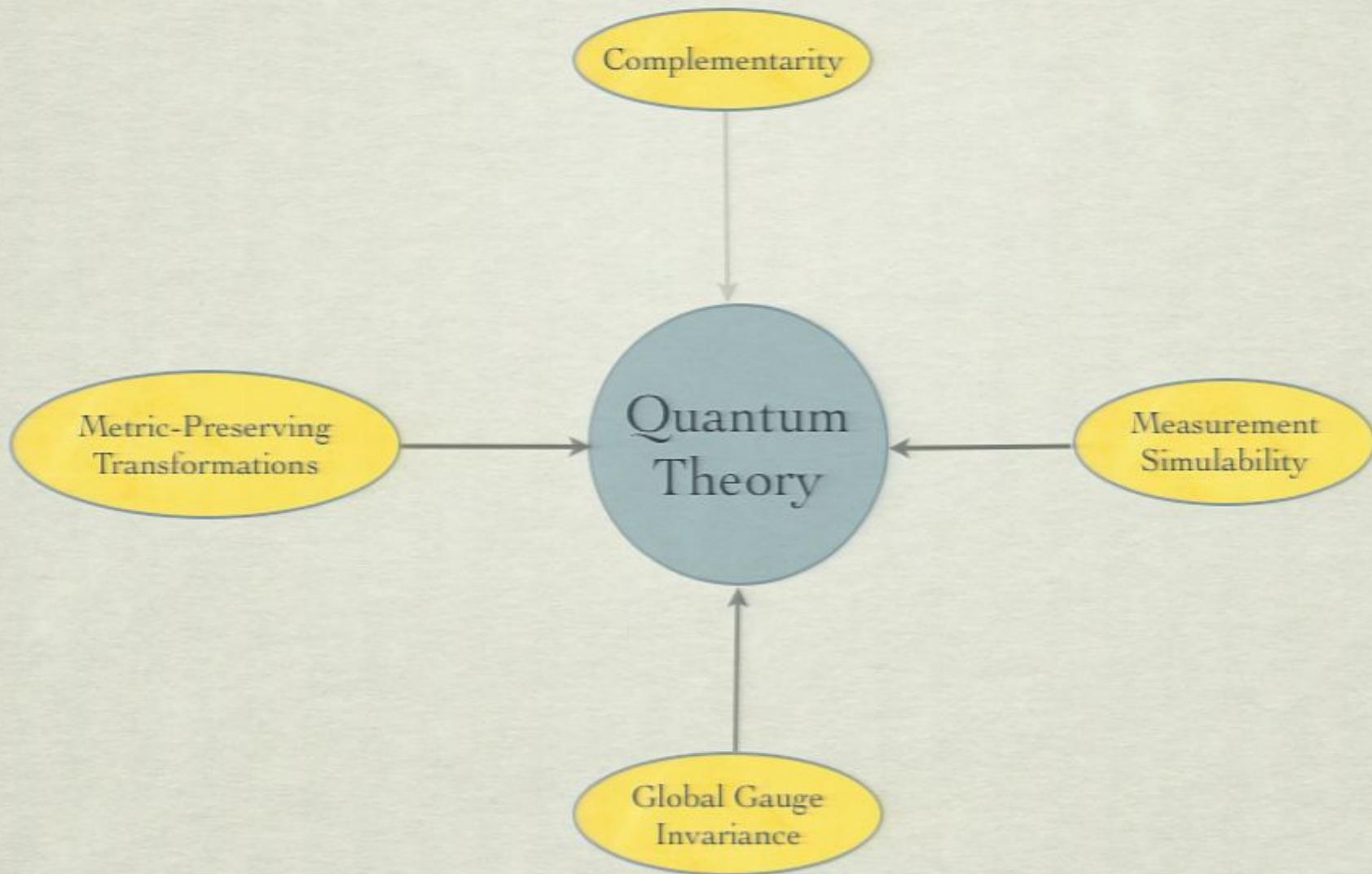
$$ds^2 = \frac{1}{4} \sum_i \frac{dp_i^2}{p_i}$$

$$ds^2 = \sum_i dq_i^2$$

where $q_i = \sqrt{p_i}$



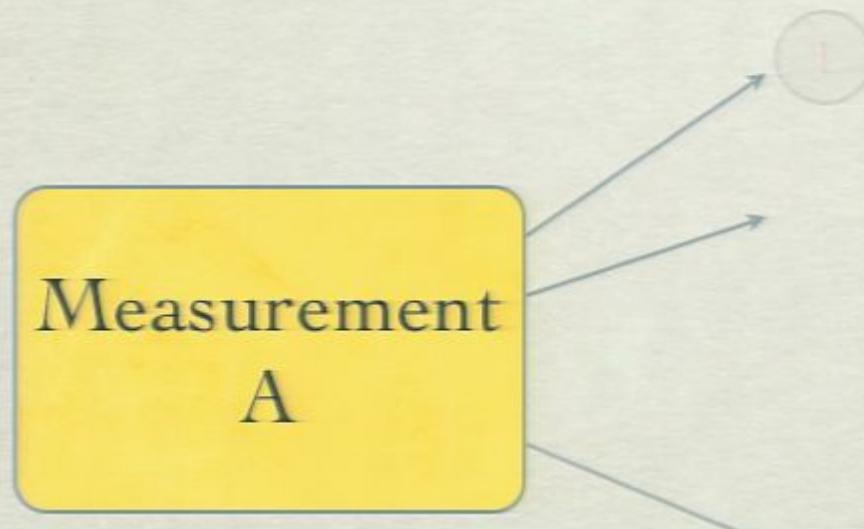




Complementarity

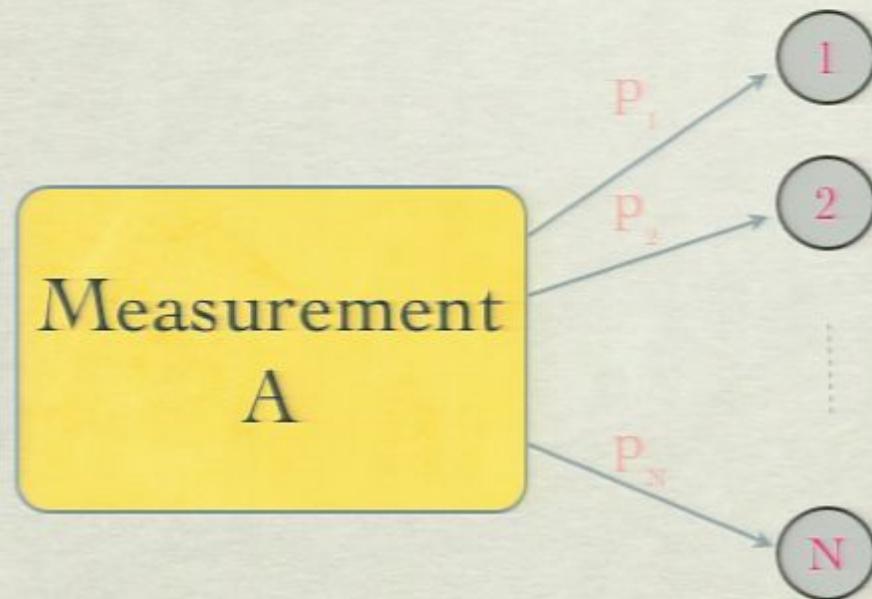
Complementarity

System



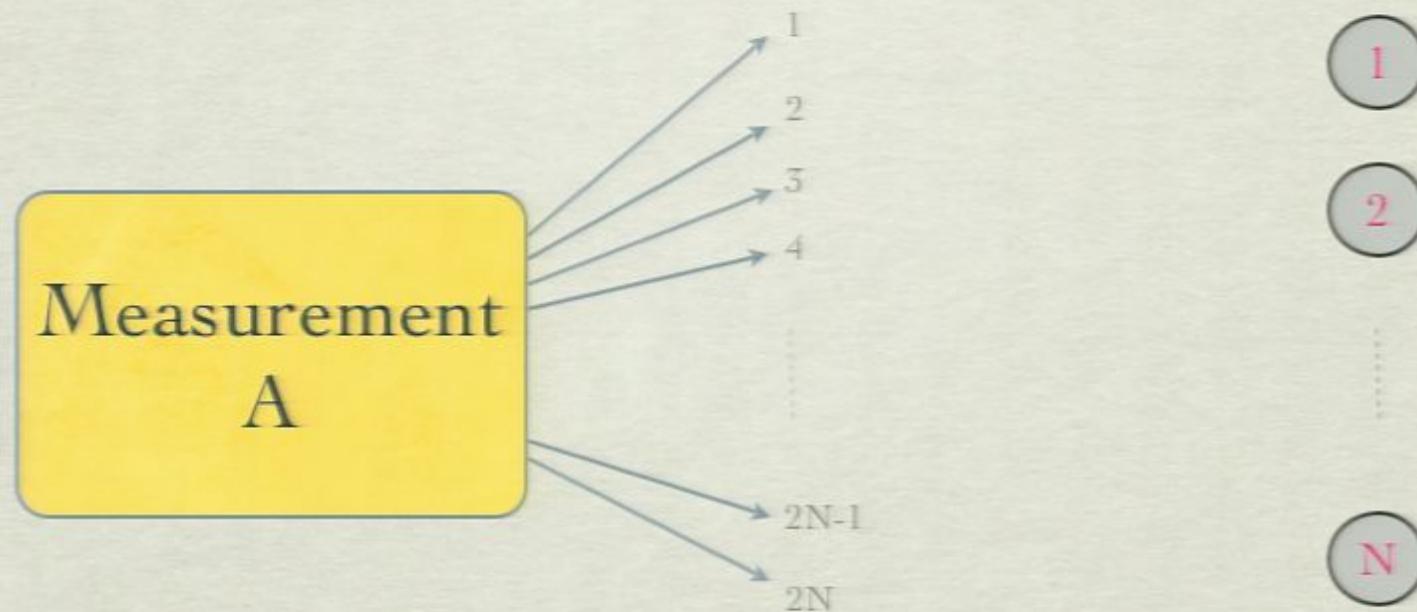
Complementarity

System



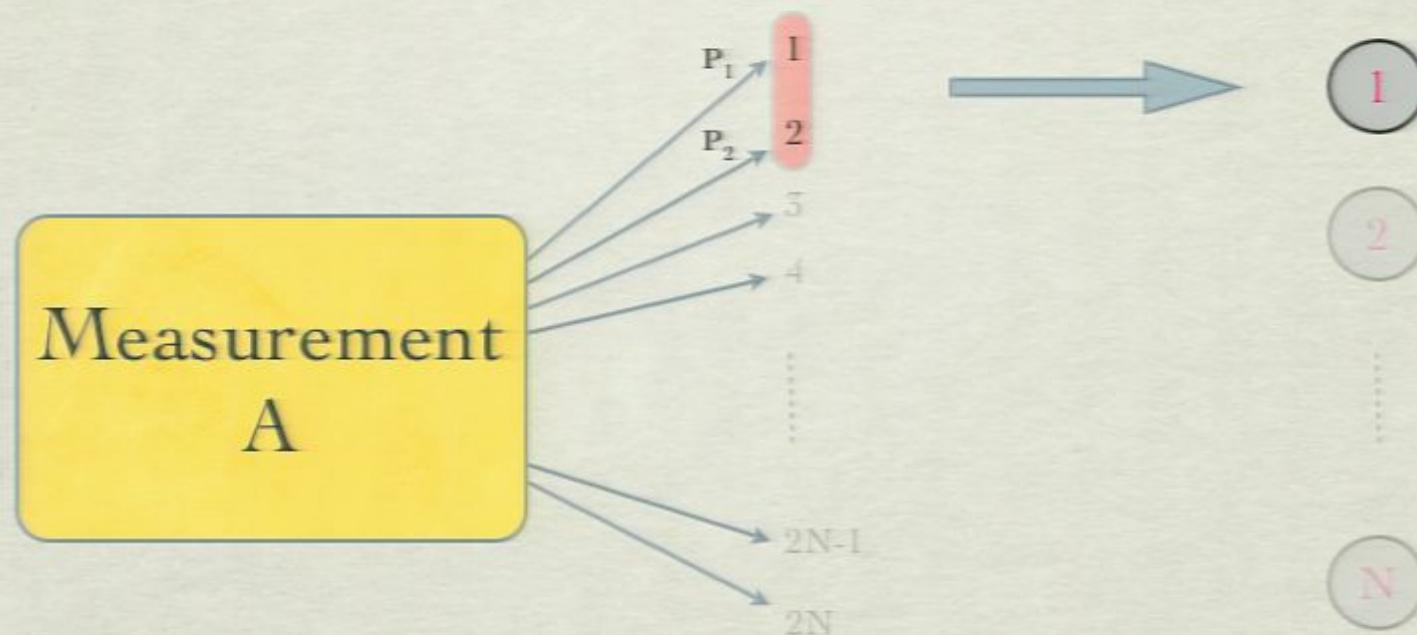
Complementarity

System



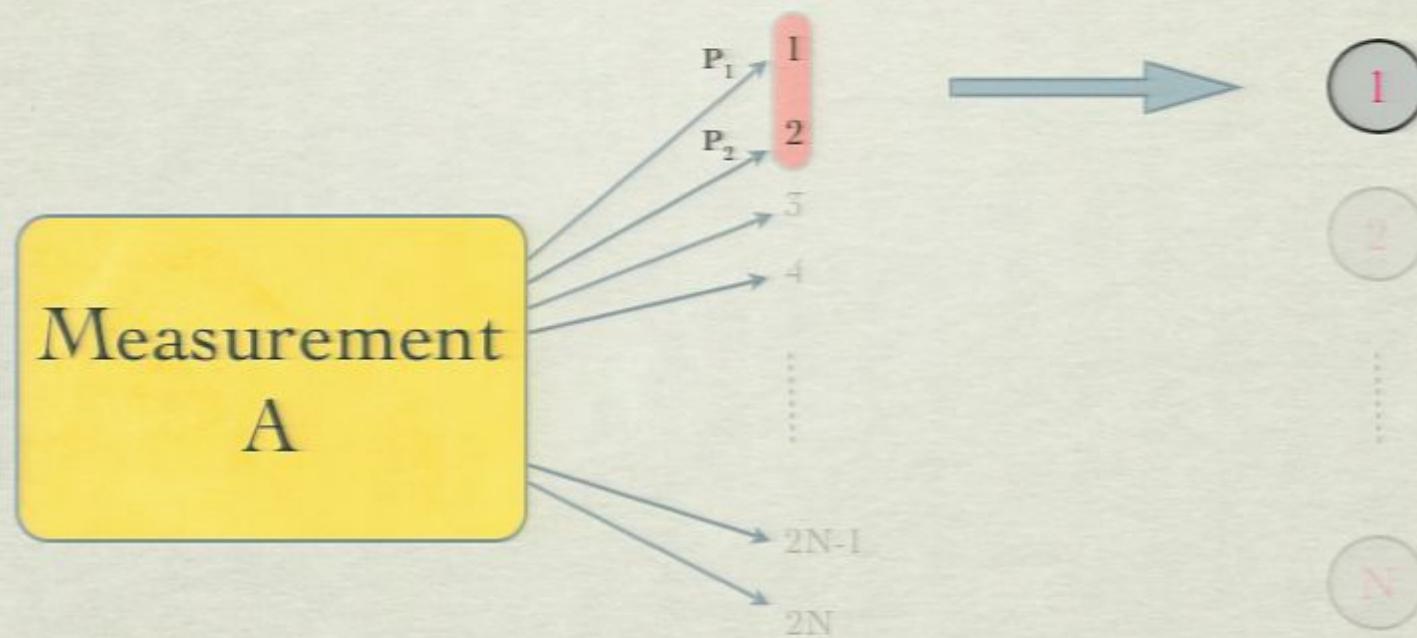
Complementarity

System



Complementarity

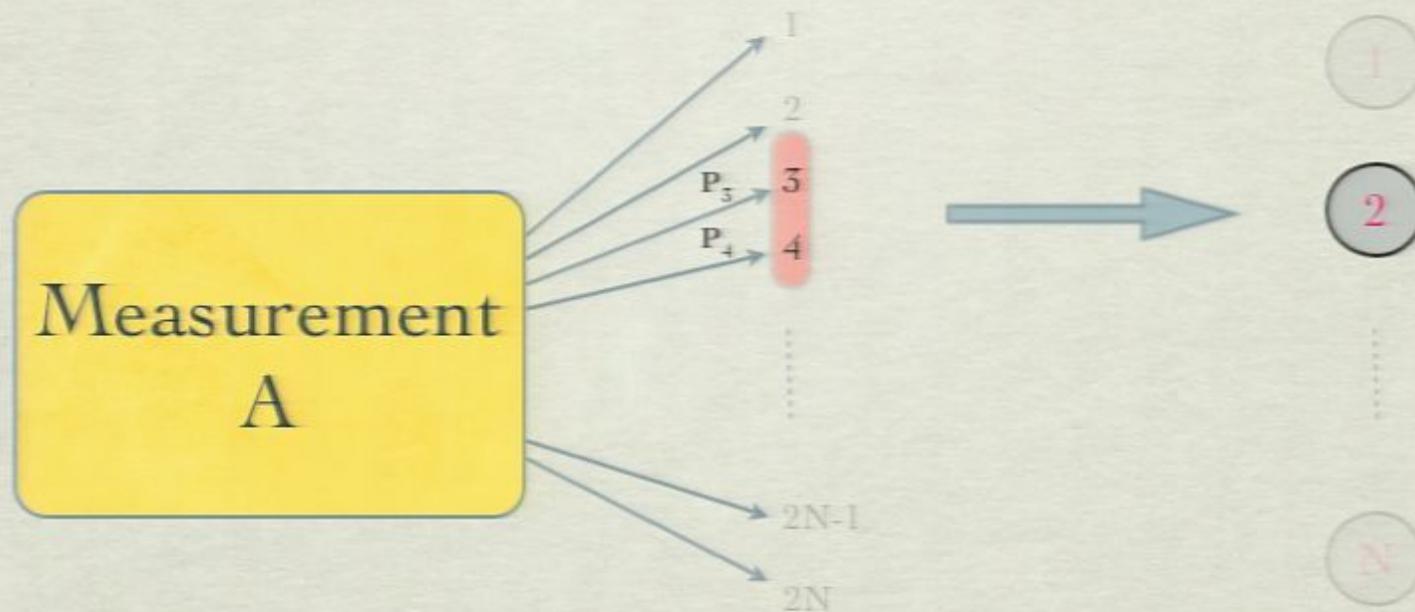
System



$$P_1 = P_1 + P_2$$

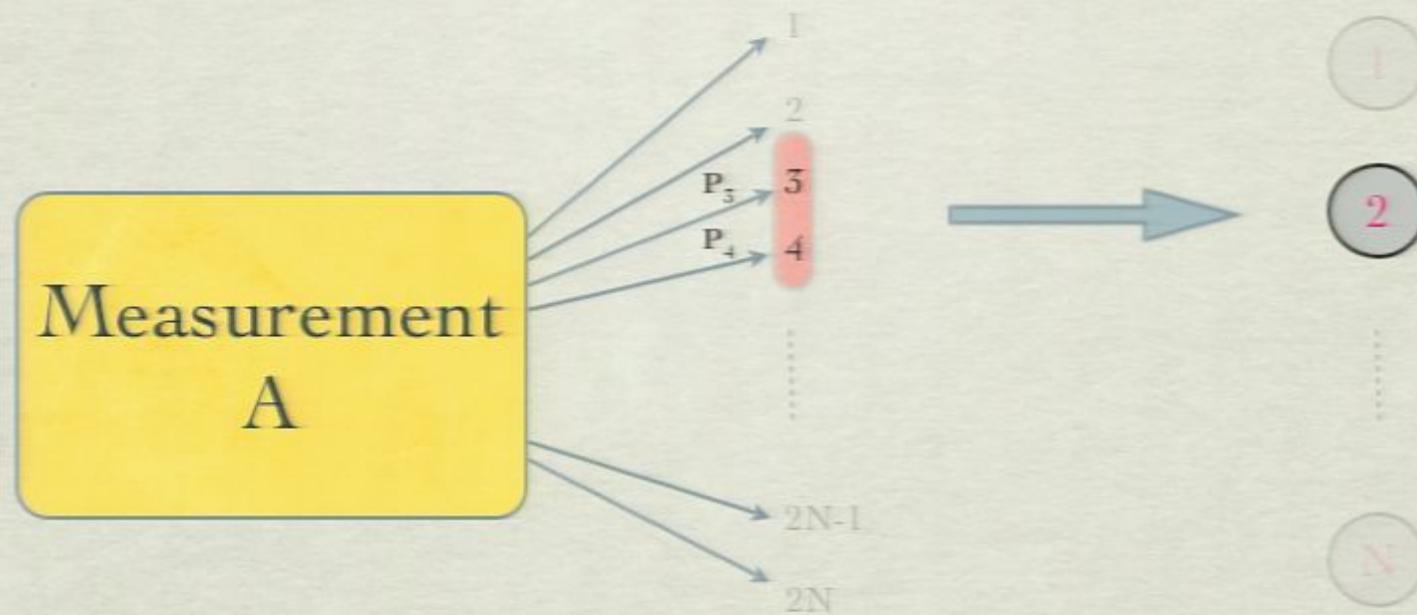
Complementarity

System



Complementarity

System



$$P_2 = P_3 + P_4$$

$$\mathbf{P} = \begin{pmatrix} P_1 \\ P_2 \\ \vdots \\ P_{2N-1} \\ P_{2N} \end{pmatrix}$$

$$\mathbf{P} = \begin{pmatrix} P_1 \\ P_2 \\ \vdots \\ P_{2N-1} \\ P_{2N} \end{pmatrix}$$



$$\mathbf{Q} = \begin{pmatrix} \sqrt{P_1} \\ \sqrt{P_2} \\ \vdots \\ \sqrt{P_{2N-1}} \\ \sqrt{P_{2N}} \end{pmatrix}$$

$$\mathbf{P} = \begin{pmatrix} P_1 \\ P_2 \\ \vdots \\ P_{2N-1} \\ P_{2N} \end{pmatrix}$$



$$\mathbf{Q} = \begin{pmatrix} \sqrt{P_1} \\ \sqrt{P_2} \\ \vdots \\ \sqrt{P_{2N-1}} \\ \sqrt{P_{2N}} \end{pmatrix}$$

$$p_1 = P_1 + P_2$$

⋮

$$p_N = P_{2N-1} + P_{2N}$$



$$p_1 = Q_1^2 + Q_2^2$$

⋮

$$p_N = Q_{2N-1}^2 + Q_{2N}^2$$

$$\mathbf{P} = \begin{pmatrix} P_1 \\ P_2 \\ \vdots \\ P_{2N-1} \\ P_{2N} \end{pmatrix}$$



$$\mathbf{Q} = \begin{pmatrix} \sqrt{P_1} \\ \sqrt{P_2} \\ \vdots \\ \sqrt{P_{2N-1}} \\ \sqrt{P_{2N}} \end{pmatrix}$$

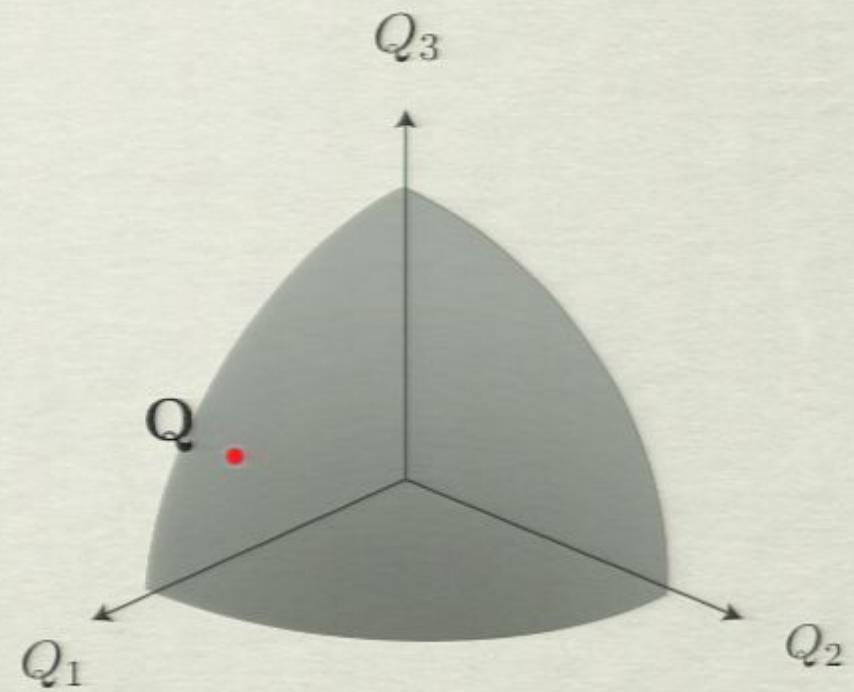
$$ds^2 = \frac{1}{4} \sum_{q=1}^{2N} \frac{dP_q^2}{P_q}$$



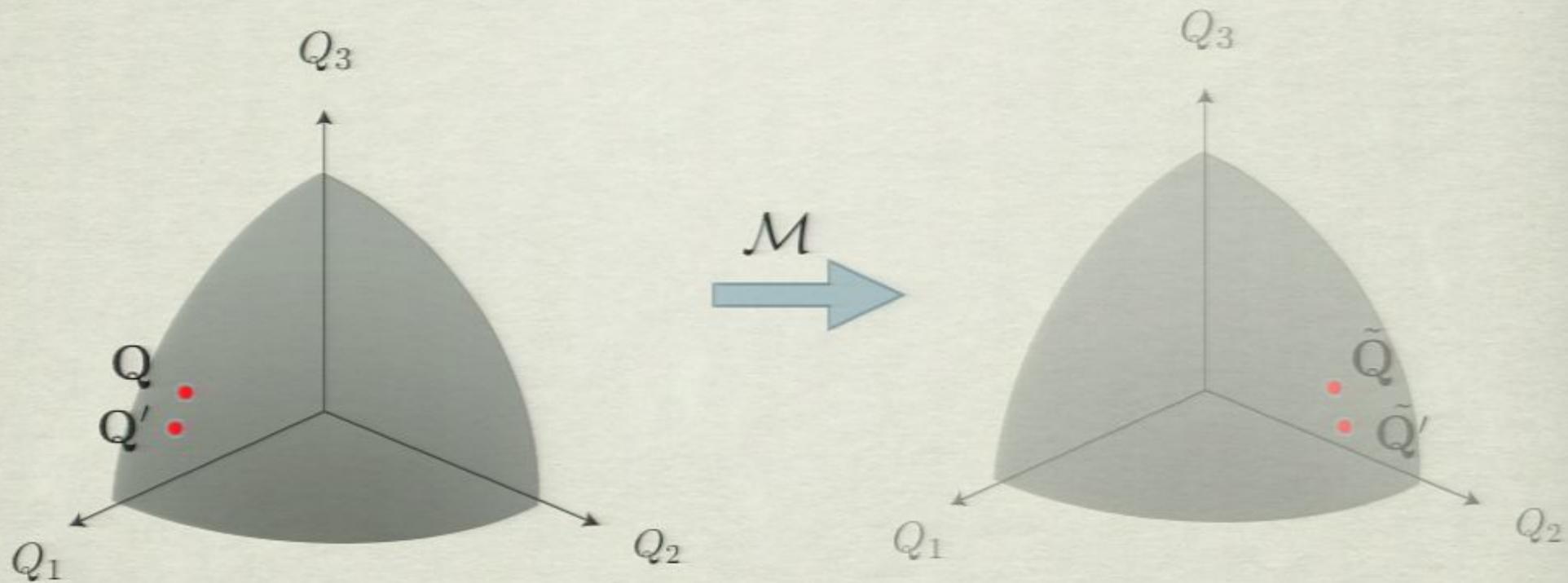
$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

$$\mathbf{Q} = \begin{pmatrix} \sqrt{P_1} \\ \sqrt{P_2} \\ \vdots \\ \sqrt{P_{2N-1}} \\ \sqrt{P_{2N}} \end{pmatrix}$$

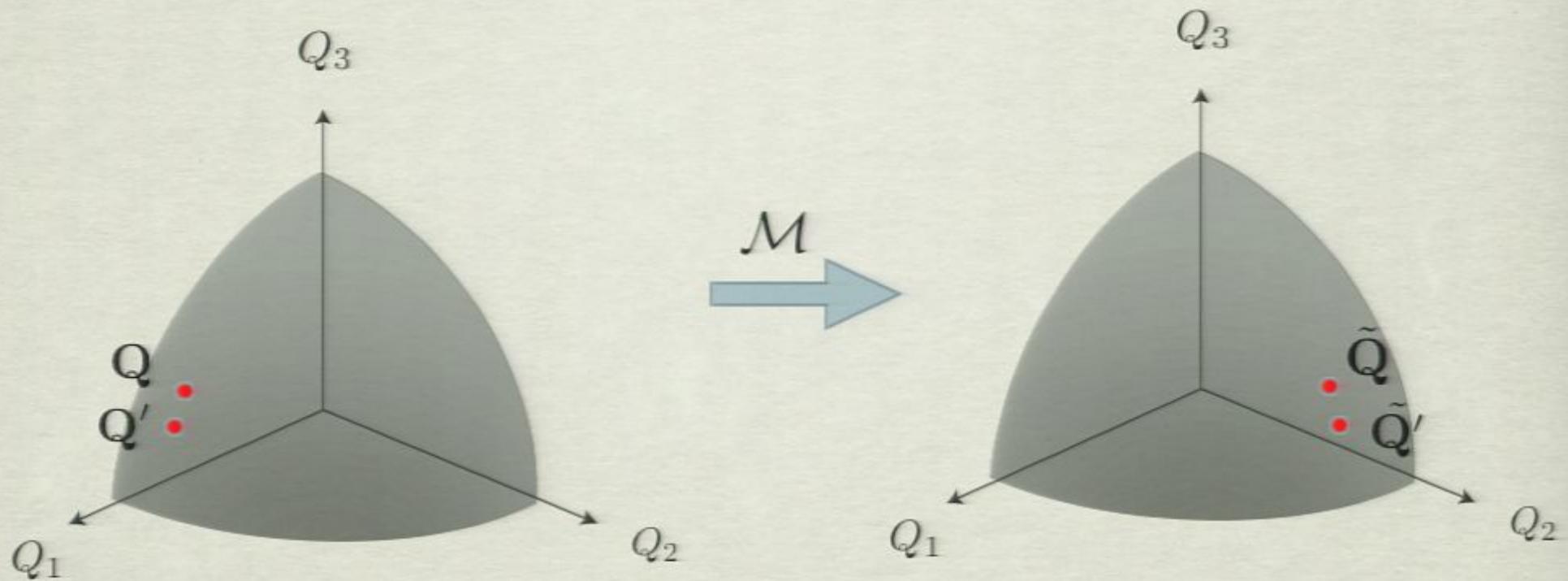
$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$



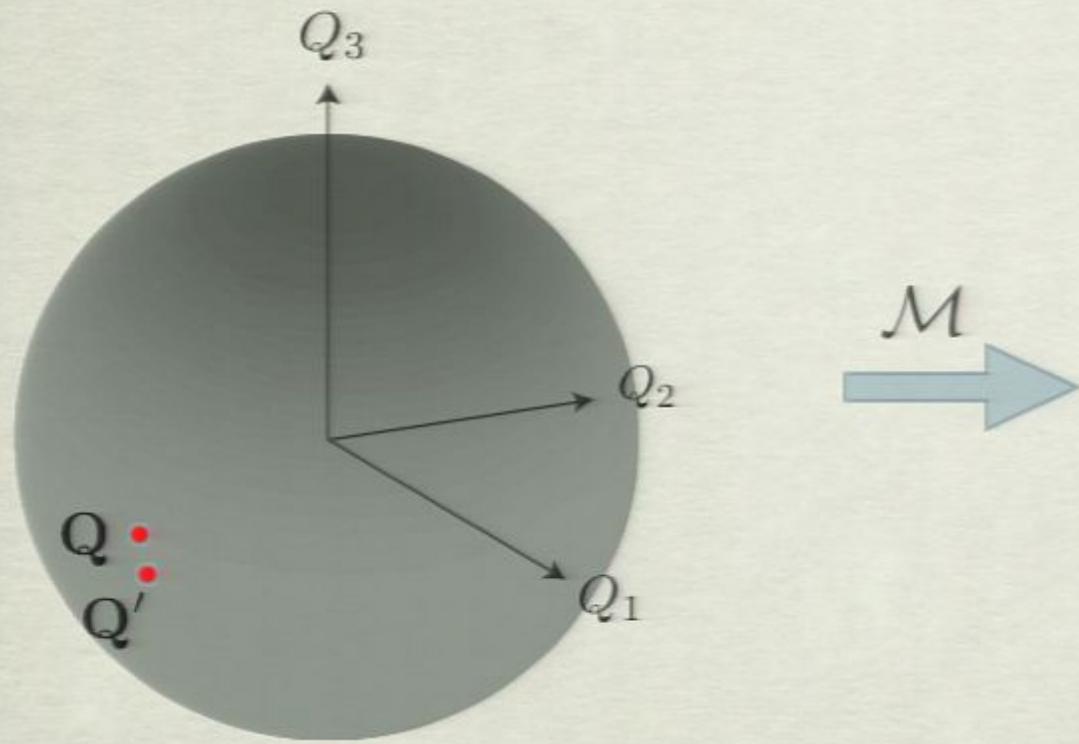
Metric-Preserving Transformations

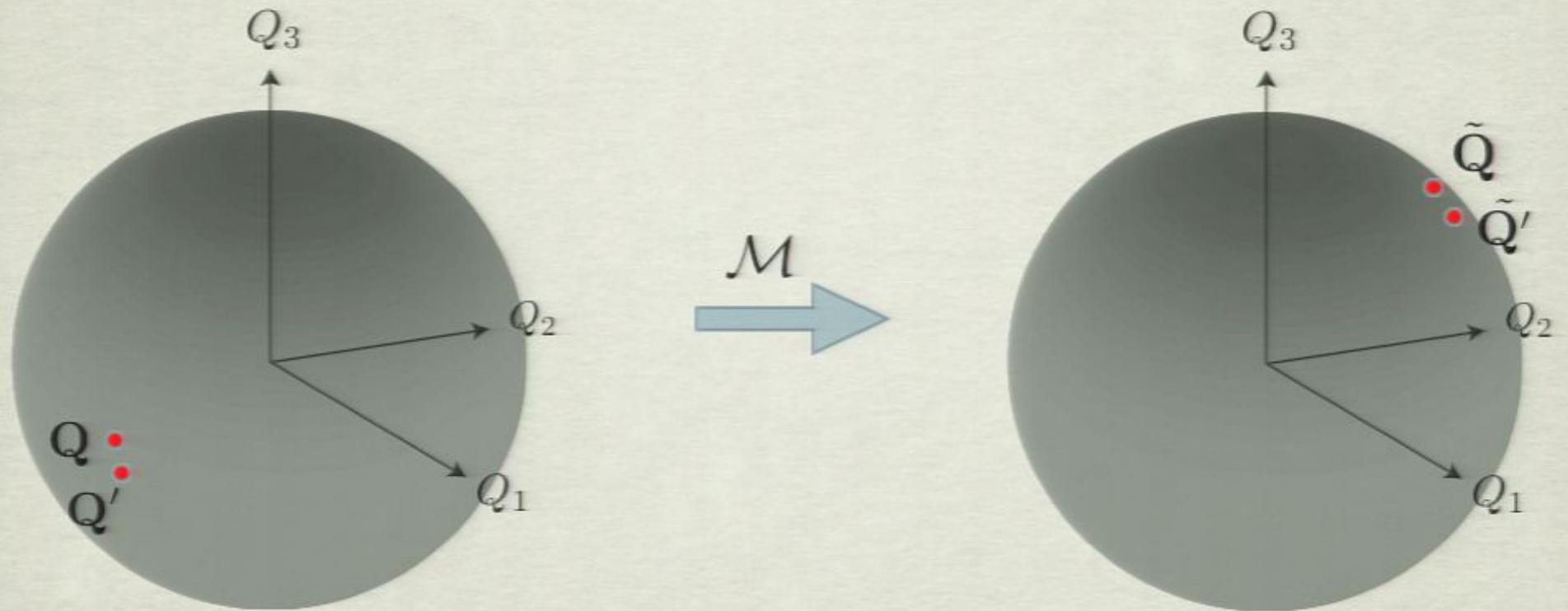


Metric-Preserving Transformations



$$d(\mathbf{Q}, \mathbf{Q}') = d(\mathcal{M}\mathbf{Q}, \mathcal{M}\mathbf{Q}')$$





$$d(\mathbf{Q}, \mathbf{Q}') = d(\mathcal{M}\mathbf{Q}, \mathcal{M}\mathbf{Q}')$$



\mathcal{M} is orthogonal

Global Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix}$$

$$p_1 = Q_1^2 + Q_2^2$$



$$p_N = Q_{2N-1}^2 + Q_{2N}^2$$

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta_1 \\ \sqrt{p_1} \sin \theta_1 \\ \vdots \\ \sqrt{p_N} \cos \theta_N \\ \sqrt{p_N} \sin \theta_N \end{pmatrix}$$

Global Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta_1 \\ \sqrt{p_1} \sin \theta_1 \\ \vdots \\ \sqrt{p_N} \cos \theta_N \\ \sqrt{p_N} \sin \theta_N \end{pmatrix}$$

Let $\theta_i = \theta(\chi_i)$



Global Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta_1 \\ \sqrt{p_1} \sin \theta_1 \\ \vdots \\ \sqrt{p_N} \cos \theta_N \\ \sqrt{p_N} \sin \theta_N \end{pmatrix}$$

Let $\theta_i = \theta(\chi_i)$



$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta(\chi_1) \\ \sqrt{p_1} \sin \theta(\chi_1) \\ \vdots \\ \sqrt{p_N} \cos \theta(\chi_N) \\ \sqrt{p_N} \sin \theta(\chi_N) \end{pmatrix}$$

Global Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta_1 \\ \sqrt{p_1} \sin \theta_1 \\ \vdots \\ \sqrt{p_N} \cos \theta_N \\ \sqrt{p_N} \sin \theta_N \end{pmatrix}$$

Let $\theta_i = \theta(\chi_i)$



$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta(\chi_1) \\ \sqrt{p_1} \sin \theta(\chi_1) \\ \vdots \\ \sqrt{p_N} \cos \theta(\chi_N) \\ \sqrt{p_N} \sin \theta(\chi_N) \end{pmatrix}$$

Assume $\chi_i \rightarrow \chi_i + \chi_0$ is a global gauge transformation

Measure Invariance

Measure Invariance

$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

Measure Invariance

$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

$$\begin{aligned} Q_1 &= \sqrt{p_1} \cos \theta(\chi_1) \\ Q_2 &= \sqrt{p_1} \sin \theta(\chi_1) \end{aligned}$$

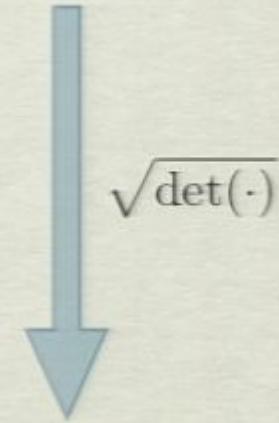
$$ds^2 = \frac{1}{4} \sum_{i=1}^N \frac{dp_i^2}{p_i} + \sum_{i=1}^N \theta'^2(\chi_i) d\chi_i^2$$

Measure Invariance

$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

$$\begin{aligned} Q_1 &= \sqrt{p_1} \cos \theta(\chi_1) \\ Q_2 &= \sqrt{p_1} \sin \theta(\chi_1) \end{aligned}$$

$$ds^2 = \frac{1}{4} \sum_{i=1}^N \frac{dp_i^2}{p_i} + \sum_{i=1}^N \theta'^2(\chi_i) d\chi_i^2$$



$$\mu(p_1, \dots, p_N; \chi_1, \dots, \chi_N) \propto |\theta'(\chi_1) \dots \theta'(\chi_N)|$$

$$\mu(p_i; \chi_1, \dots, \chi_N) = \mu(p_i; \chi_1 + \chi_0, \dots, \chi_N + \chi_0)$$

$$\mu(p_i; \chi_1, \dots, \chi_N) = \mu(p_i; \chi_1 + \chi_0, \dots, \chi_N + \chi_0)$$



$$\theta(\chi) = a\chi + b$$

$$\mu(p_i; \chi_1, \dots, \chi_N) = \mu(p_i; \chi_1 + \chi_0, \dots, \chi_N + \chi_0)$$



$$\theta(\chi) = a\chi + b$$

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \theta(\chi_1) \\ \sqrt{p_1} \sin \theta(\chi_1) \\ \vdots \\ \sqrt{p_N} \cos \theta(\chi_N) \\ \sqrt{p_N} \sin \theta(\chi_N) \end{pmatrix}$$

$$\phi_i = a\chi_i + b$$

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \phi_1 \\ \sqrt{p_1} \sin \phi_1 \\ \vdots \\ \sqrt{p_N} \cos \phi_N \\ \sqrt{p_N} \sin \phi_N \end{pmatrix}$$

Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \phi_1 \\ \sqrt{p_1} \sin \phi_1 \\ \vdots \\ \sqrt{p_N} \cos \phi_N \\ \sqrt{p_N} \sin \phi_N \end{pmatrix} \xrightarrow{M} \mathbf{Q}' = \begin{pmatrix} \sqrt{p'_1} \cos \phi'_1 \\ \sqrt{p'_1} \sin \phi'_1 \\ \vdots \\ \sqrt{p'_N} \cos \phi'_N \\ \sqrt{p'_N} \sin \phi'_N \end{pmatrix}$$

Gauge Invariance

$$\mathbf{Q} = \begin{pmatrix} \sqrt{p_1} \cos \phi_1 \\ \sqrt{p_1} \sin \phi_1 \\ \vdots \\ \sqrt{p_N} \cos \phi_N \\ \sqrt{p_N} \sin \phi_N \end{pmatrix}$$

$$M \longrightarrow$$

$$\mathbf{Q}' = \begin{pmatrix} \sqrt{p'_1} \cos \phi'_1 \\ \sqrt{p'_1} \sin \phi'_1 \\ \vdots \\ \sqrt{p'_N} \cos \phi'_N \\ \sqrt{p'_N} \sin \phi'_N \end{pmatrix}$$

$$\longrightarrow$$

$$p'_1, \dots, p'_N$$

$\phi_i \rightarrow \phi_i + \phi_0$ leaves the p'_i invariant

Orthogonal Transformations

$$\begin{array}{c|c} \left(\begin{array}{cc} \cos \varphi_{11} & -\sin \varphi_{11} \\ \sin \varphi_{11} & \cos \varphi_{11} \end{array} \right) & \left(\begin{array}{cc} \cos \varphi_{12} & -\sin \varphi_{12} \\ \sin \varphi_{12} & \cos \varphi_{12} \end{array} \right) \\ \hline \left(\begin{array}{cc} \cos \varphi_{21} & -\sin \varphi_{21} \\ \sin \varphi_{21} & \cos \varphi_{21} \end{array} \right) & \left(\begin{array}{cc} \cos \varphi_{22} & -\sin \varphi_{22} \\ \sin \varphi_{22} & \cos \varphi_{22} \end{array} \right) \end{array}$$

type 1

Orthogonal Transformations

$$\begin{array}{c|c} \left(\begin{array}{cc} \alpha_{11} \begin{pmatrix} \cos \varphi_{11} & -\sin \varphi_{11} \\ \sin \varphi_{11} & \cos \varphi_{11} \end{pmatrix} & \alpha_{12} \begin{pmatrix} \cos \varphi_{12} & -\sin \varphi_{12} \\ \sin \varphi_{12} & \cos \varphi_{12} \end{pmatrix} \\ \hline \alpha_{21} \begin{pmatrix} \cos \varphi_{21} & -\sin \varphi_{21} \\ \sin \varphi_{21} & \cos \varphi_{21} \end{pmatrix} & \alpha_{22} \begin{pmatrix} \cos \varphi_{22} & -\sin \varphi_{22} \\ \sin \varphi_{22} & \cos \varphi_{22} \end{pmatrix} \end{array} \right) & \text{type 1} \end{array}$$

$$\begin{array}{c|c} \left(\begin{array}{cc} \alpha_{11} \begin{pmatrix} \cos \varphi_{11} & -\sin \varphi_{11} \\ \sin \varphi_{11} & \cos \varphi_{11} \end{pmatrix} F & \alpha_{12} \begin{pmatrix} \cos \varphi_{12} & -\sin \varphi_{12} \\ \sin \varphi_{12} & \cos \varphi_{12} \end{pmatrix} F \\ \hline \alpha_{21} \begin{pmatrix} \cos \varphi_{21} & -\sin \varphi_{21} \\ \sin \varphi_{21} & \cos \varphi_{21} \end{pmatrix} F & \alpha_{22} \begin{pmatrix} \cos \varphi_{22} & -\sin \varphi_{22} \\ \sin \varphi_{22} & \cos \varphi_{22} \end{pmatrix} F \end{array} \right) & \text{type 2} \end{array}$$

where $F = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix}$$

orthogonals {
type 1
type 2

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix} \quad \longleftrightarrow \quad \mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

orthogonals {
 type 1
 type 2

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix} \quad \longleftrightarrow \quad \mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

orthogonals { type 1
type 2

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix} \quad \longleftrightarrow \quad \mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

orthogonals { type 1  unitary
 type 2 antiunitary

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix} \quad \longleftrightarrow \quad \mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

$$\text{orthogonals} \left\{ \begin{array}{l} \text{type 1} \\ \text{type 2} \end{array} \right. \quad \longleftrightarrow \quad \begin{array}{l} \text{unitary} \\ \text{antiunitary} \end{array}$$

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$$\mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

orthogonals {
type 1
type 2}



unitary
antiunitary

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix}$$



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orthogonals {
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orthogonals {
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type 2



unitary
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$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix}$$



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$$p_i = Q_{2i-1}^2 + Q_{2i}^2$$

$$\mathbf{Q} = \begin{pmatrix} Q_1 \\ Q_2 \\ \vdots \\ Q_{2N-1} \\ Q_{2N} \end{pmatrix}$$



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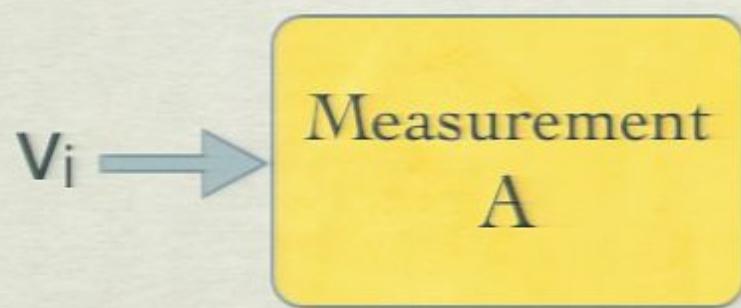
$$\mathbf{v} = \begin{pmatrix} Q_1 + iQ_2 \\ \vdots \\ Q_{2N-1} + iQ_{2N} \end{pmatrix}$$

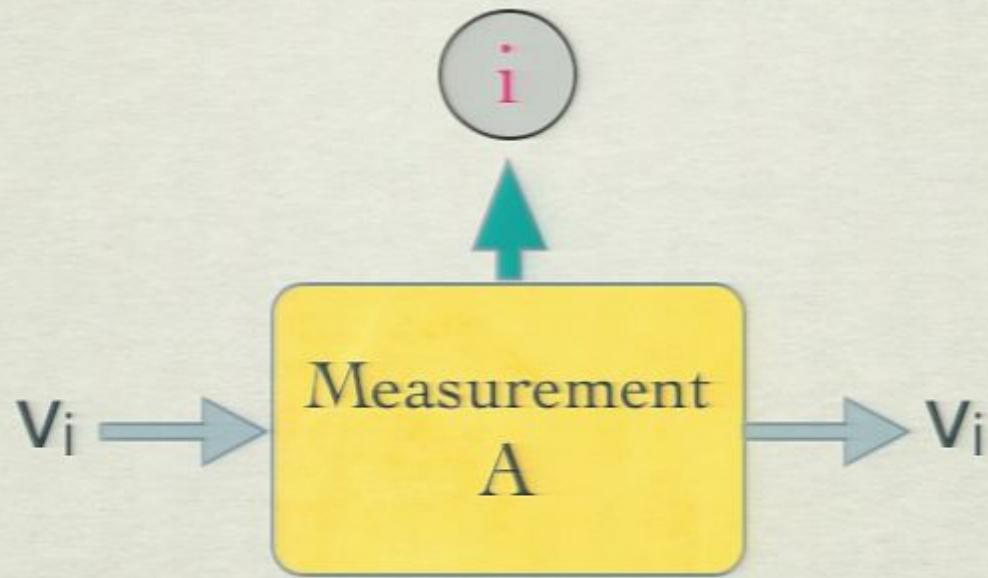
$$p_i = Q_{2i-1}^2 + Q_{2i}^2$$

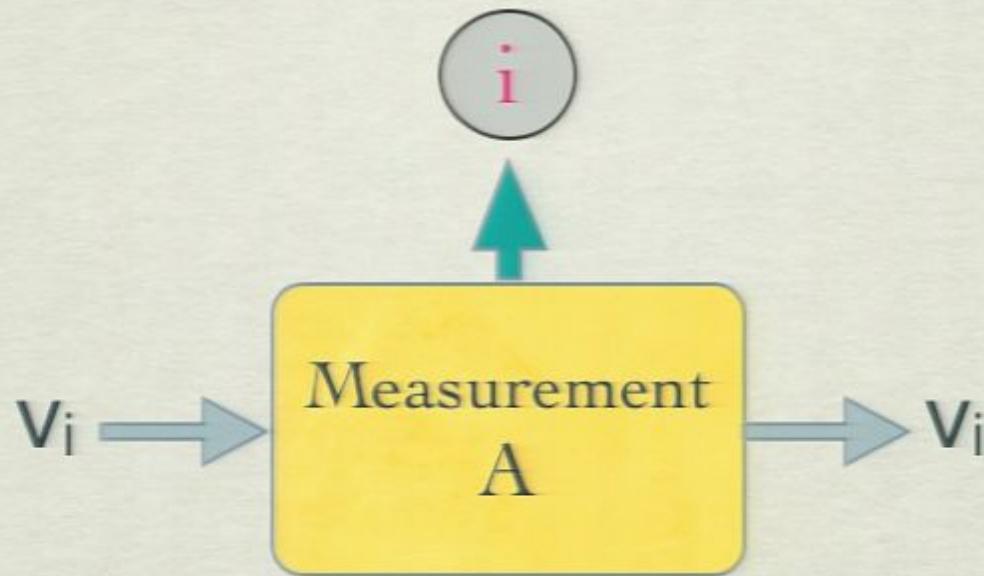


$$p_i = |v_i|^2$$

Measurement A

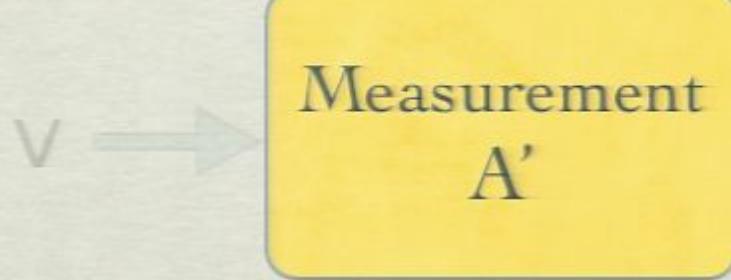




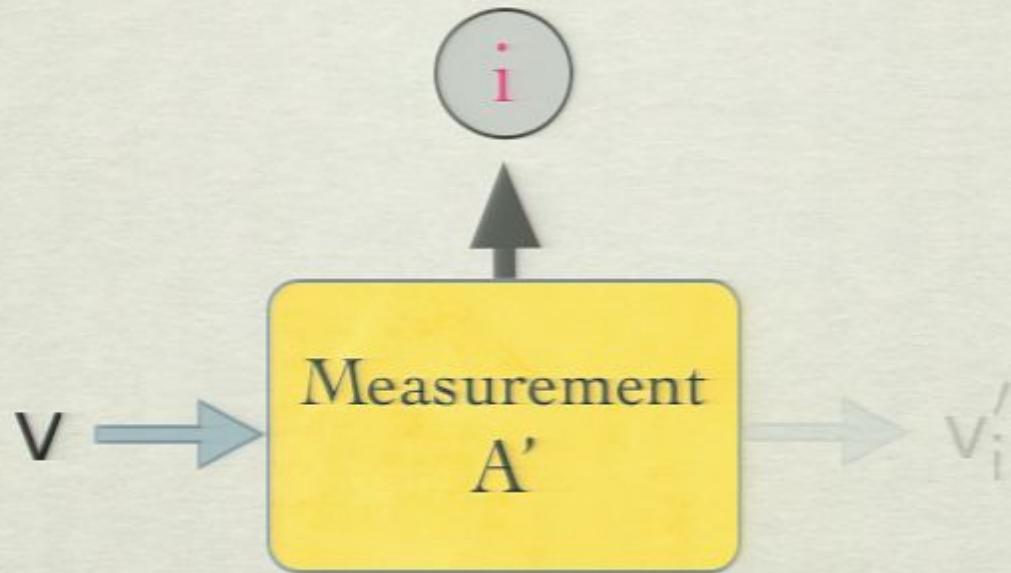


States $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \dots, \mathbf{v}_N = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ N \end{pmatrix}$ yield outcomes 1,..,N with certainty

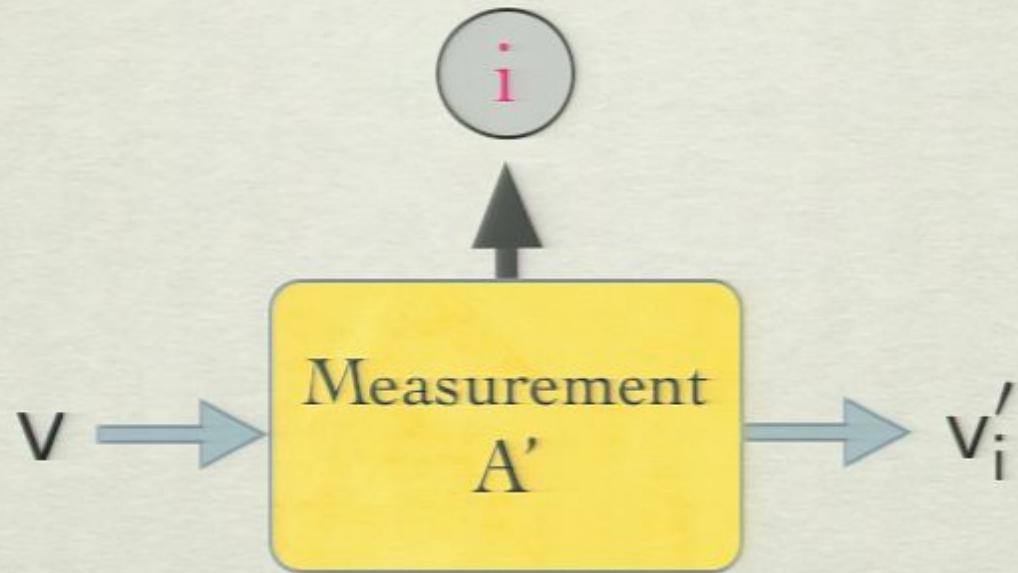
Measurement Simulability



Measurement Simulability



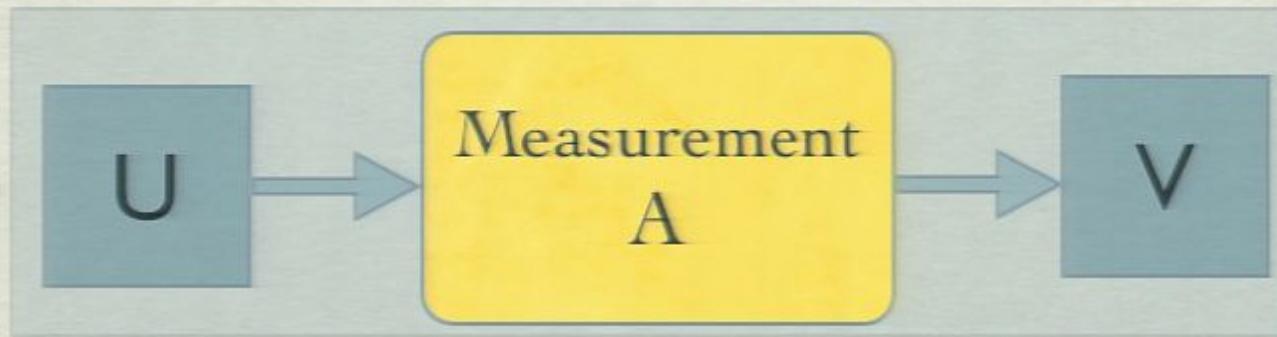
Measurement Simulability



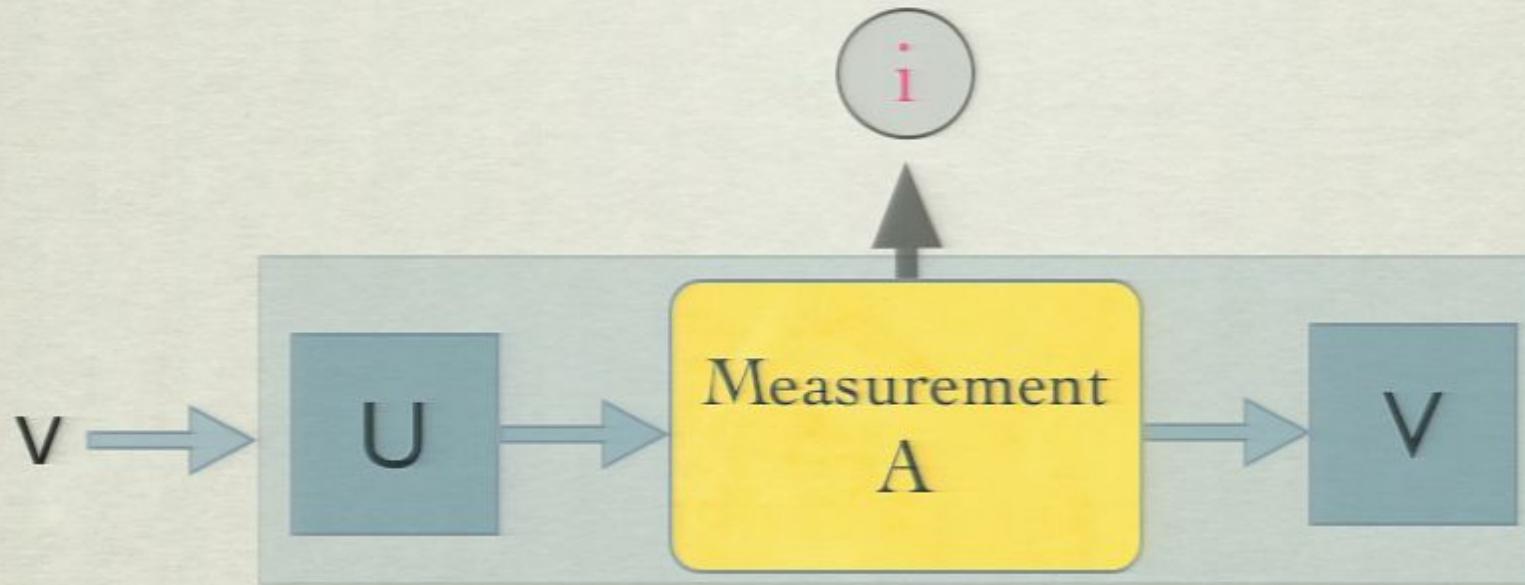
Measurement Simulability

Measurement
A

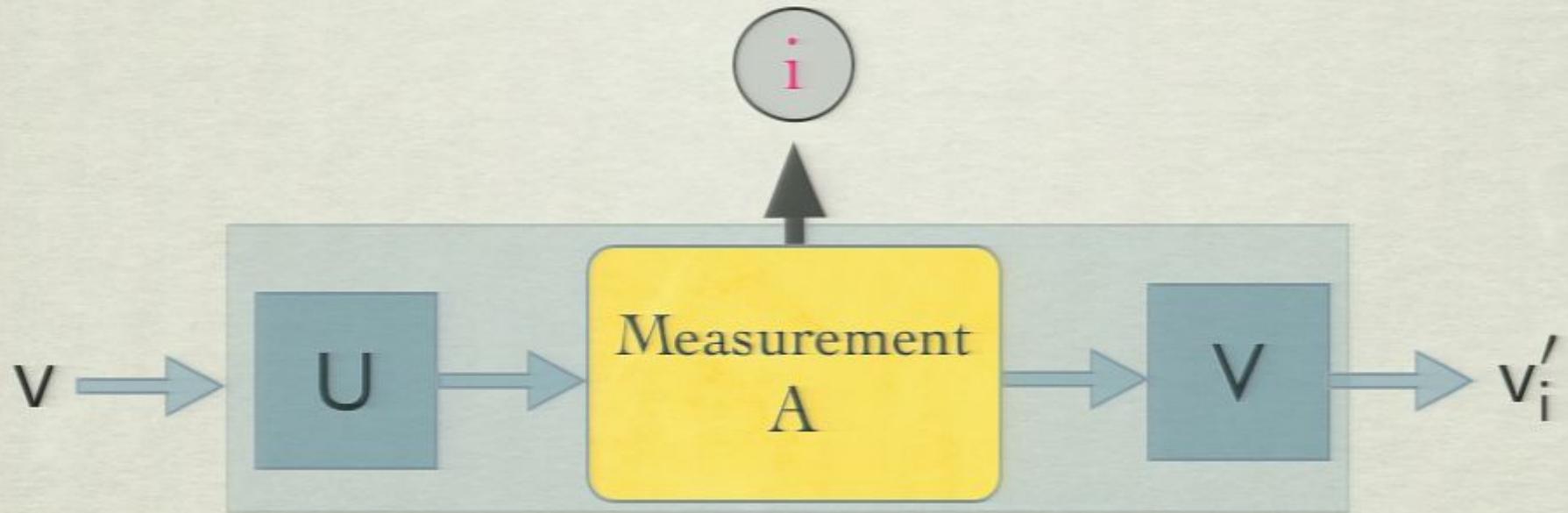
Measurement Simulability



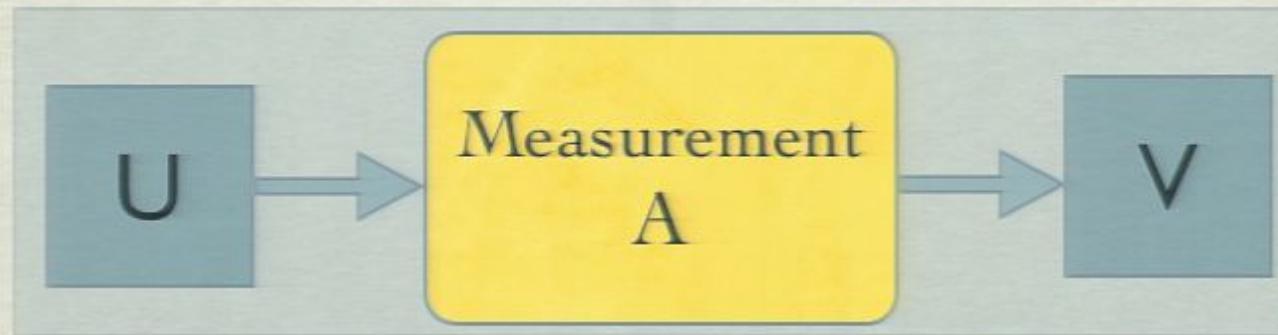
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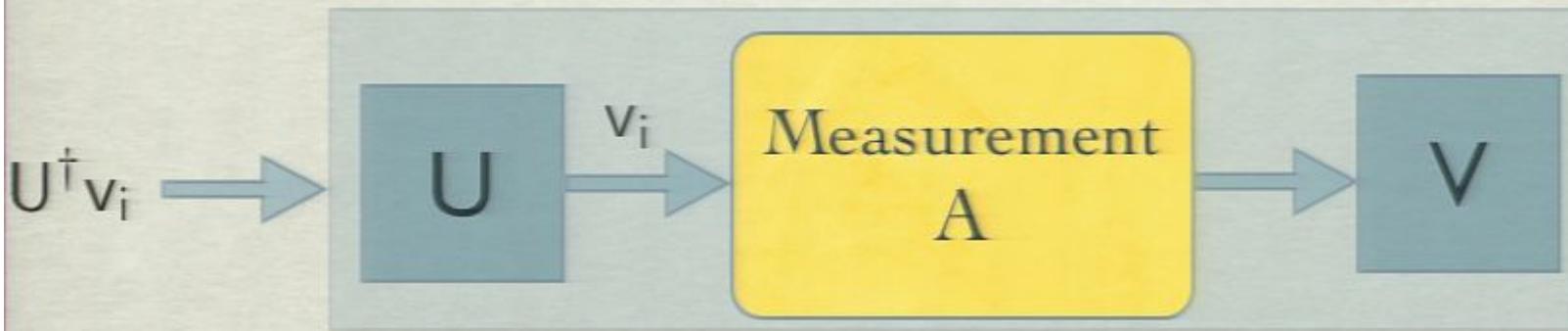
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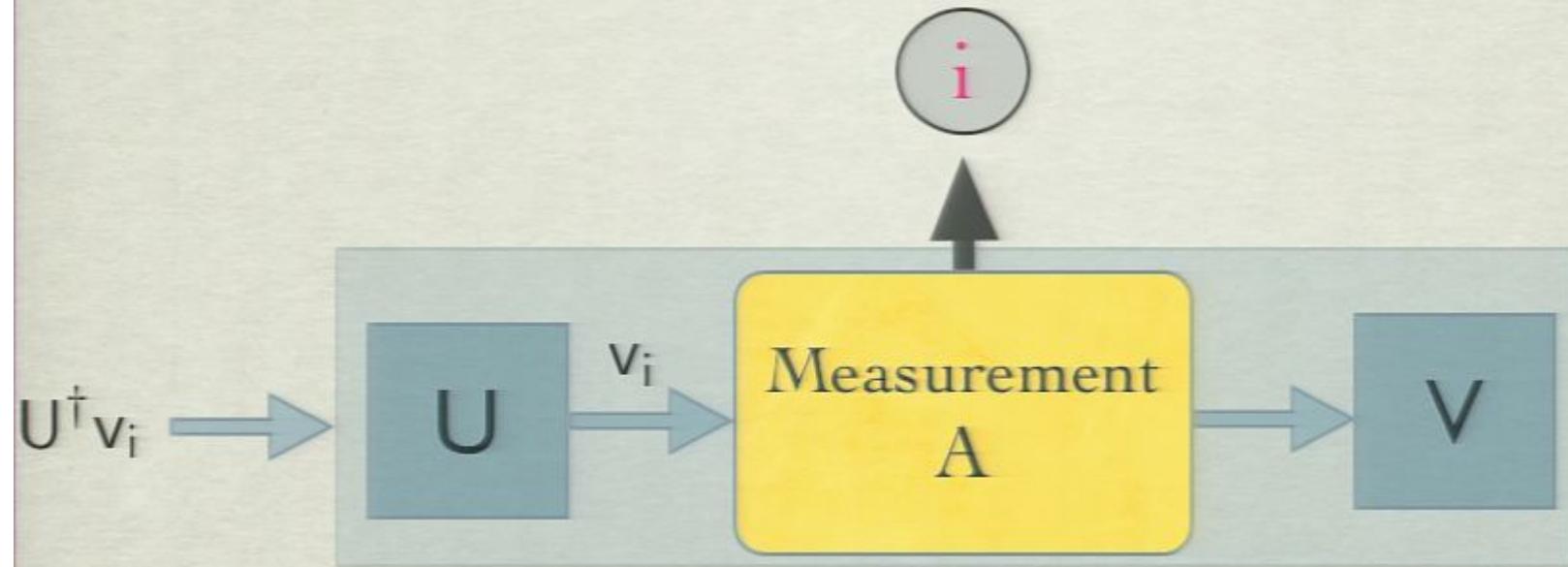
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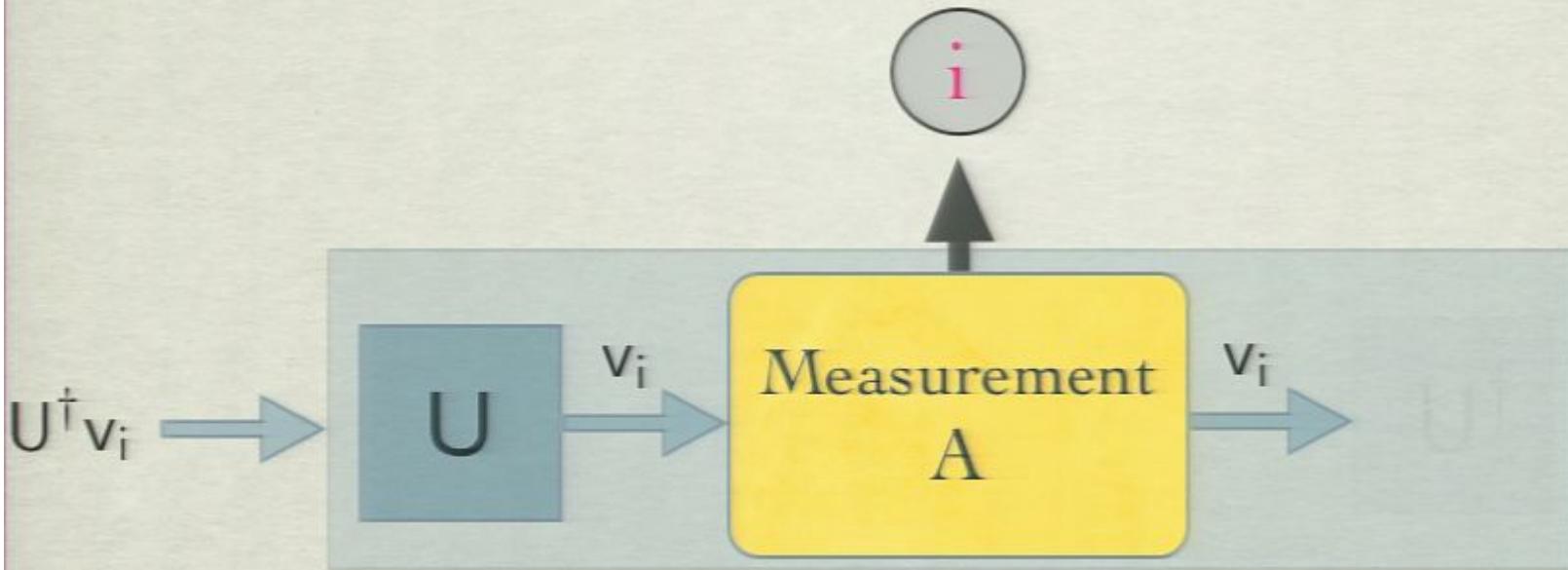
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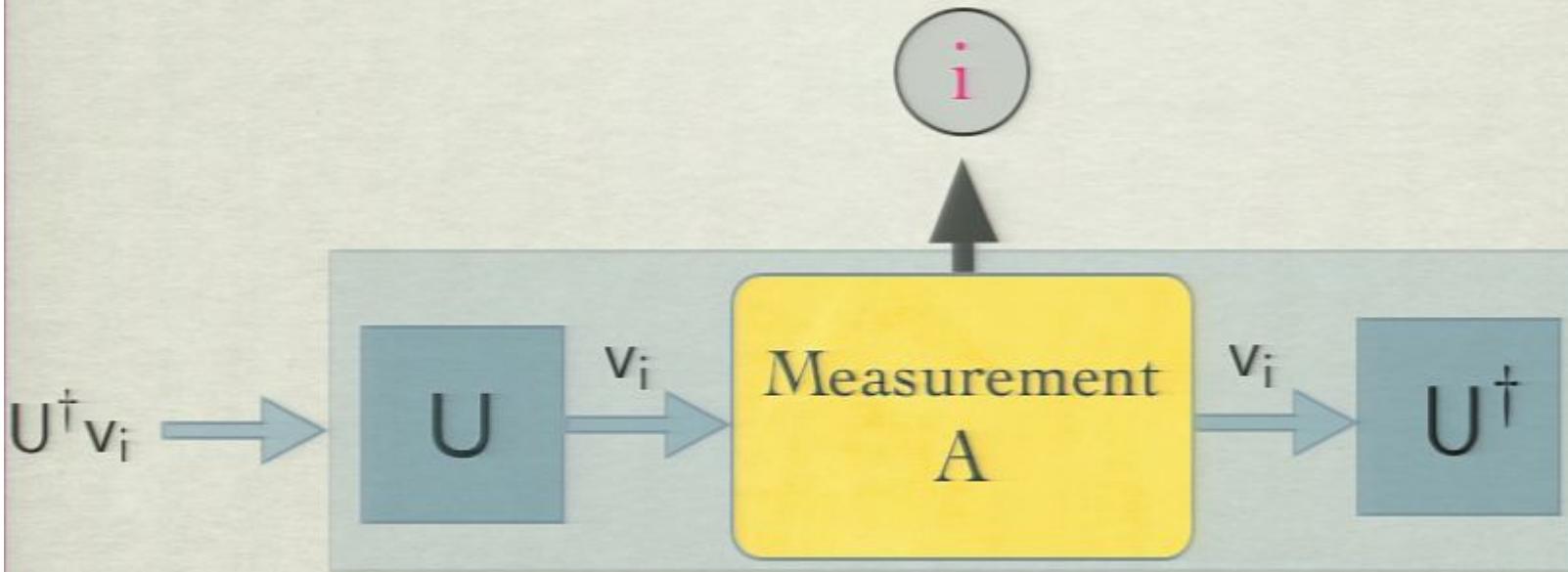
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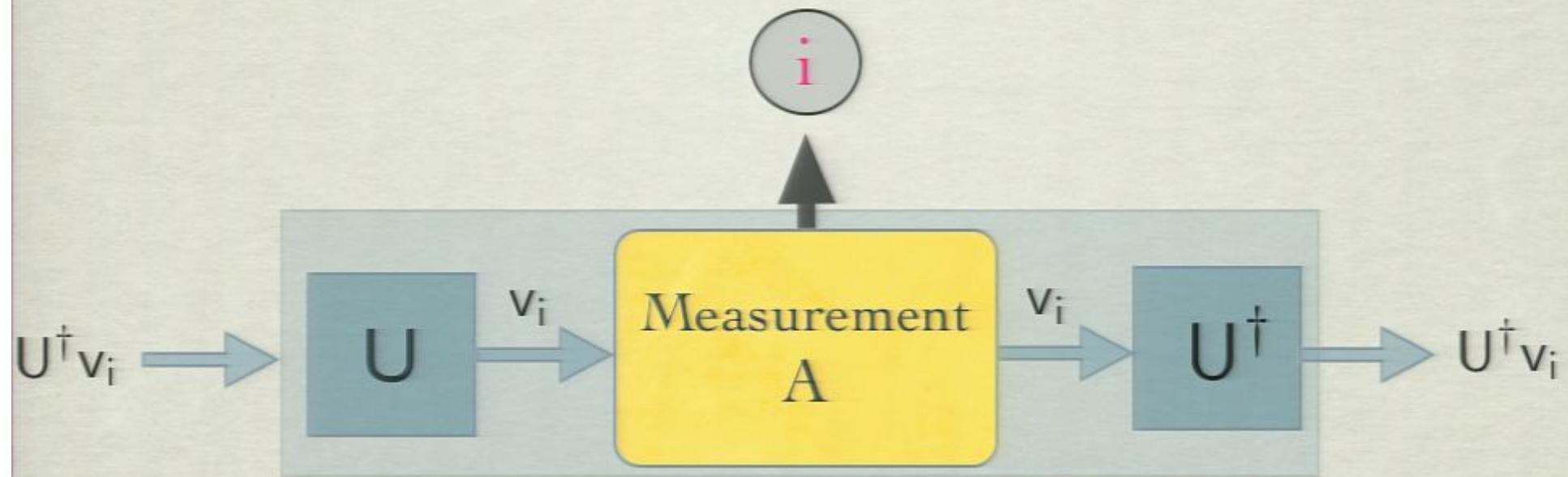
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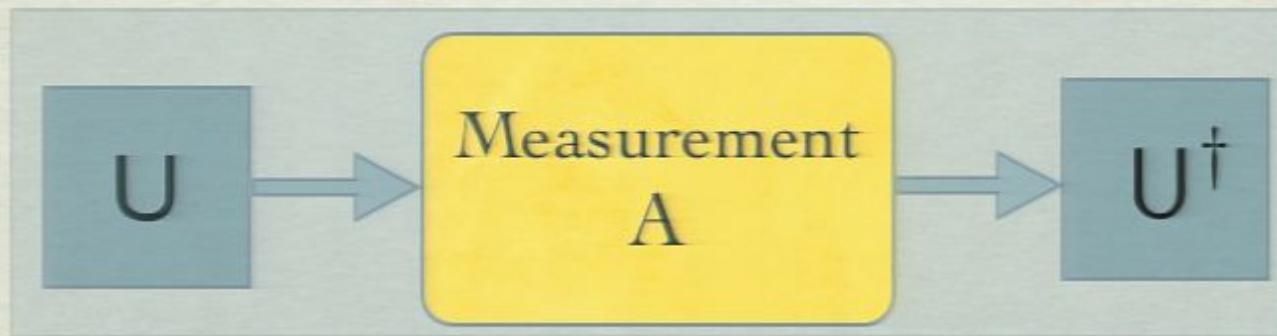
Measurement Simulability



Measurement Simulability

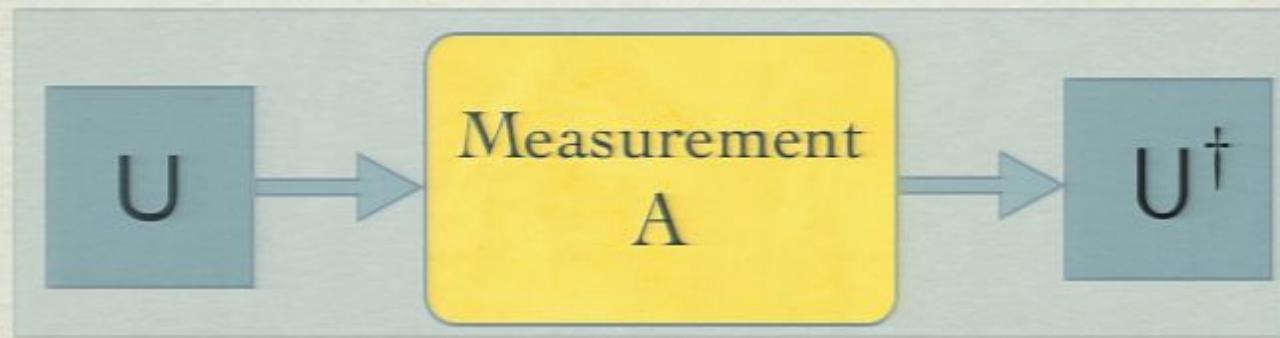


Measurement Simulability



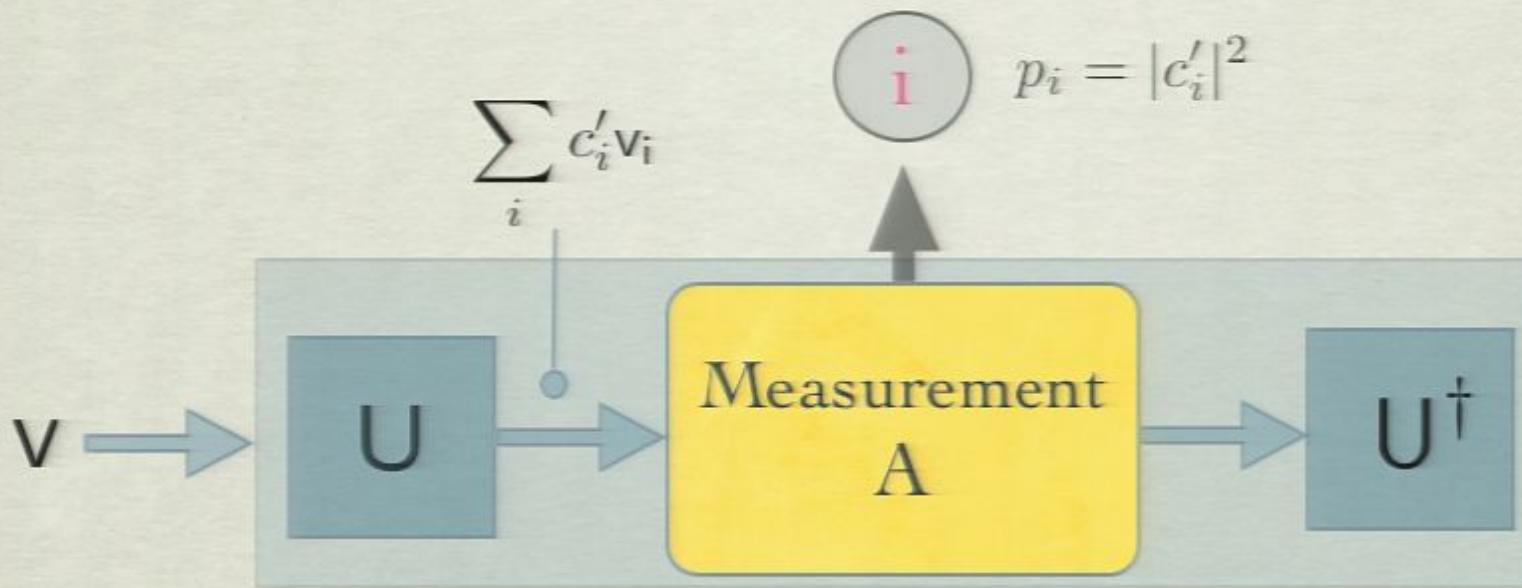
Let $\begin{cases} v'_i = U^\dagger v_i \\ v = \sum_i c'_i v'_i \end{cases}$

Measurement Simulability



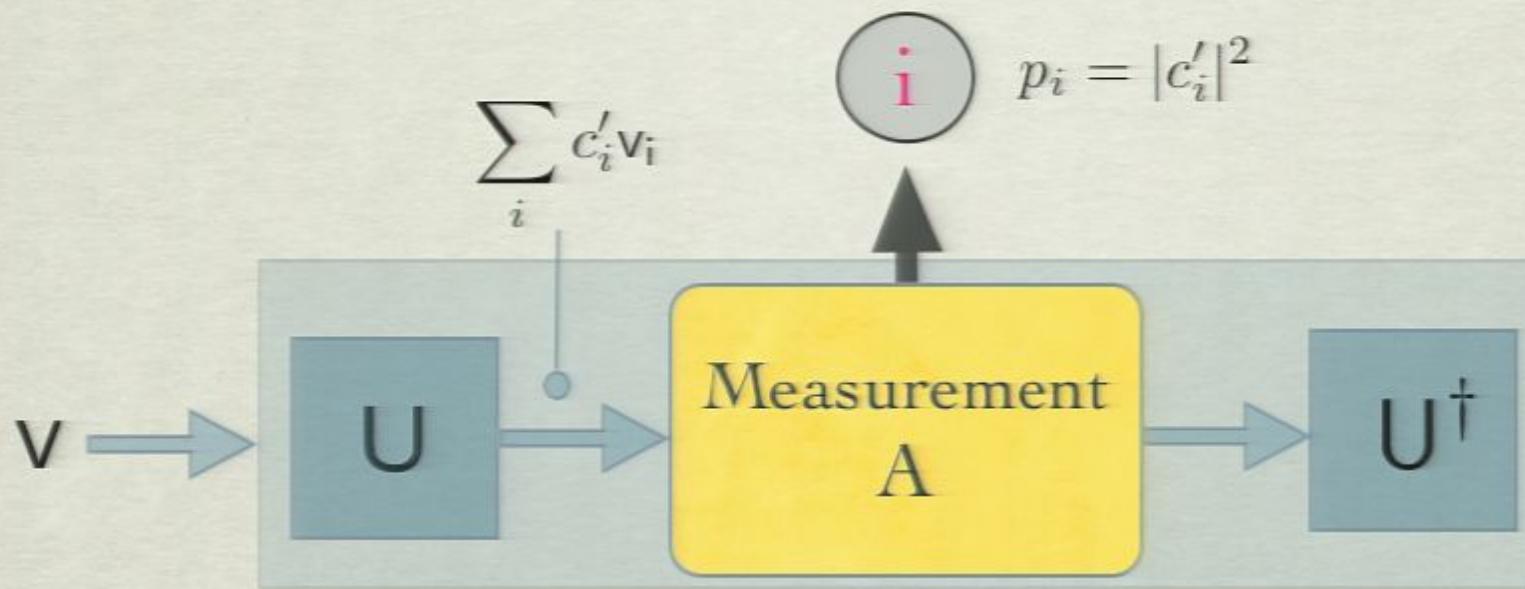
Let $\begin{cases} v'_i = U^\dagger v_i \\ v = \sum_i c'_i v'_i \end{cases}$

Measurement Simulability



Let $\begin{cases} v'_i = U^\dagger v_i \\ v = \sum_i c'_i v'_i \end{cases}$

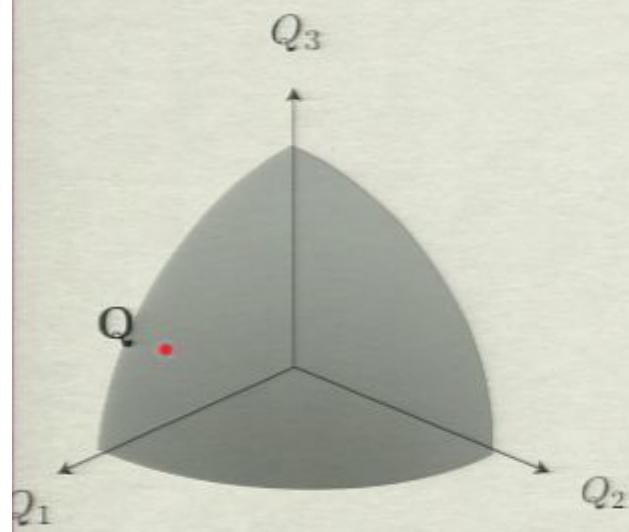
Measurement Simulability



$$\text{Let } \begin{cases} v'_i = U^\dagger v_i \\ v = \sum_i c'_i v'_i \end{cases}$$

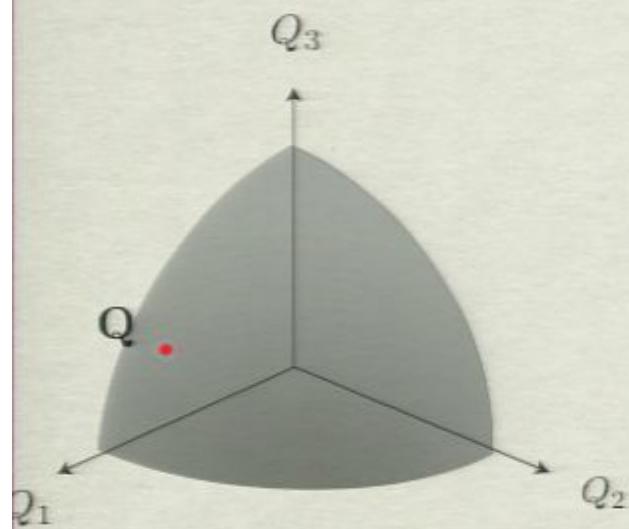
Complementarity

Complementarity



$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

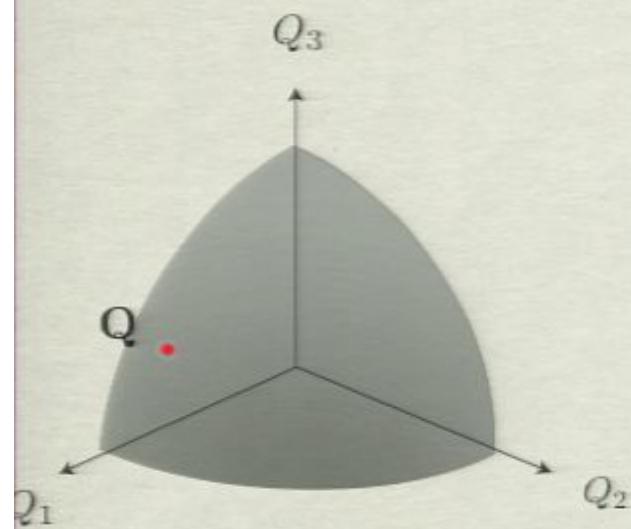
Complementarity



$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

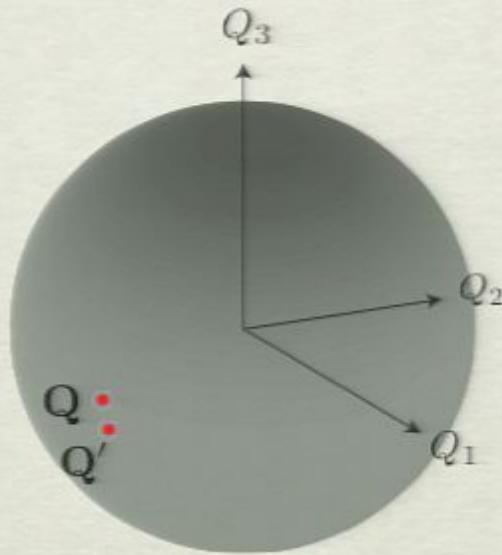
Metric-Preservation

Complementarity



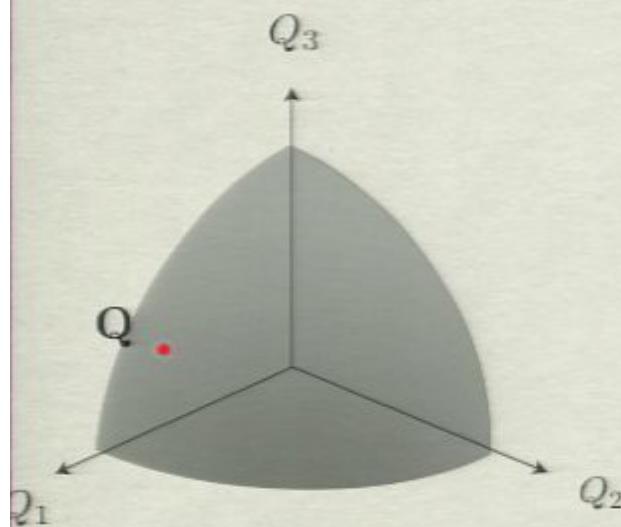
$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

Metric-Preservation



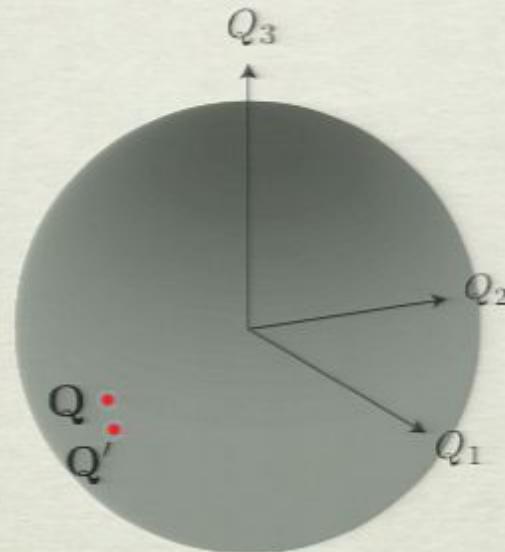
Transformations are
orthogonal

Complementarity



$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

Metric-Preservation

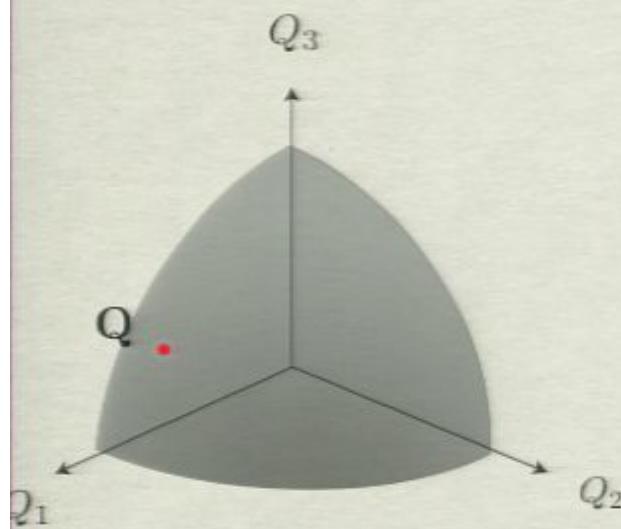


Transformations are
orthogonal

Global Gauge Invariance

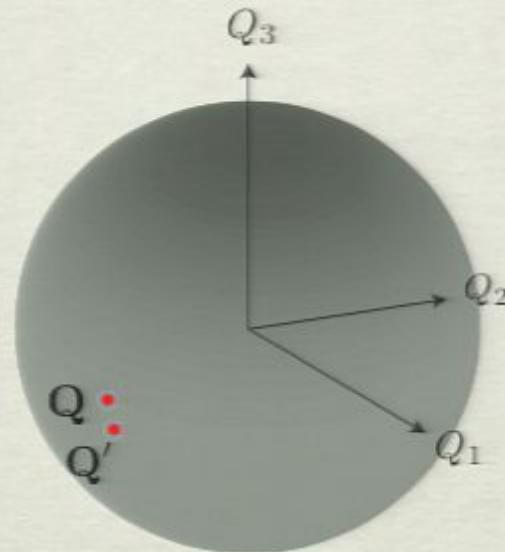
Transformations are
orthogonal of *type 1*
or type 2

Complementarity



$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

Metric-Preservation



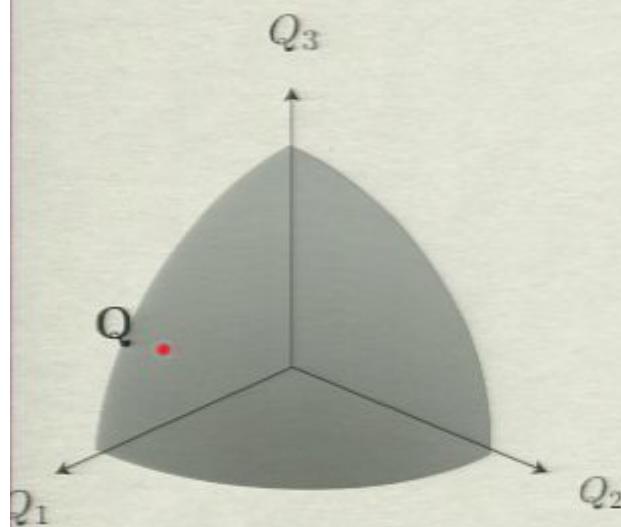
Transformations are
orthogonal

Global Gauge Invariance

Transformations are
orthogonal of *type 1*
or *type 2*

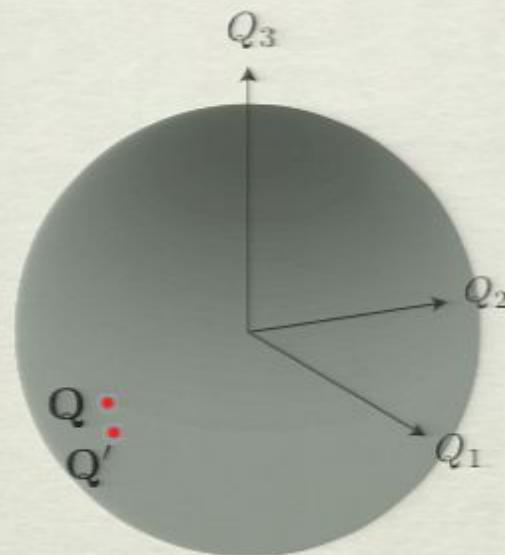


Complementarity



$$ds^2 = \sum_{q=1}^{2N} dQ_q^2$$

Metric-Preservation



Transformations are orthogonal

Global Gauge Invariance

Transformations are orthogonal of *type 1* or *type 2*

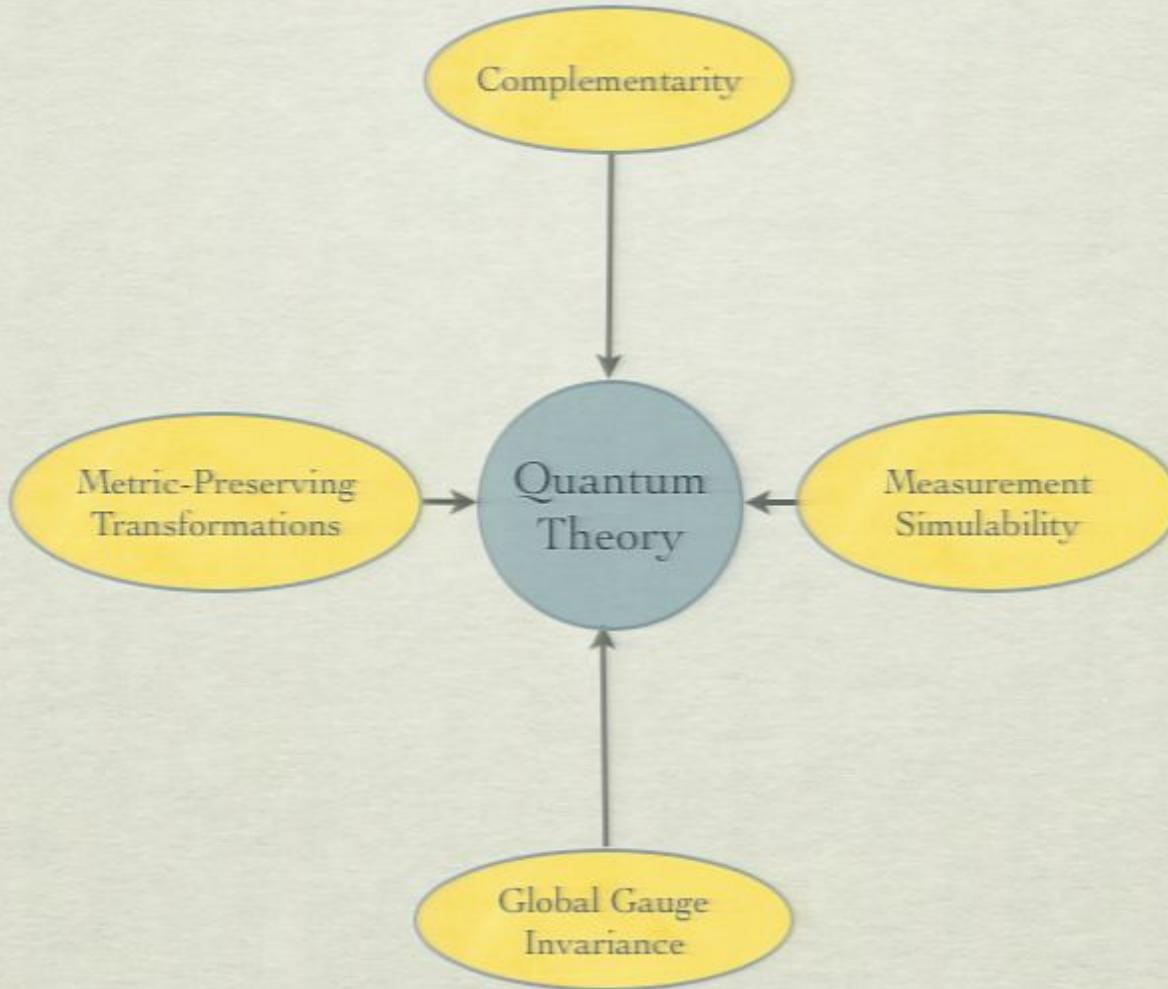


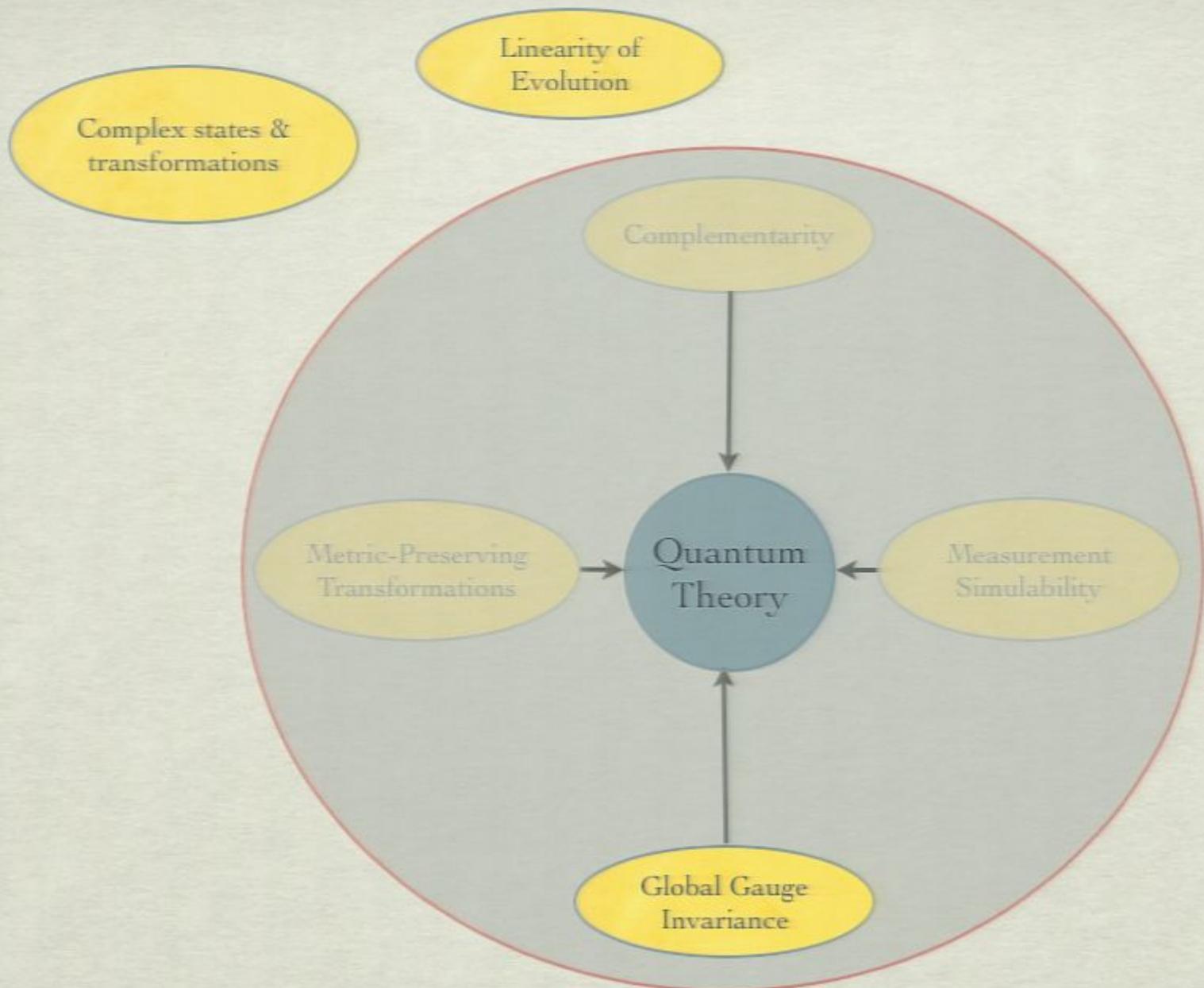
States are complex vectors

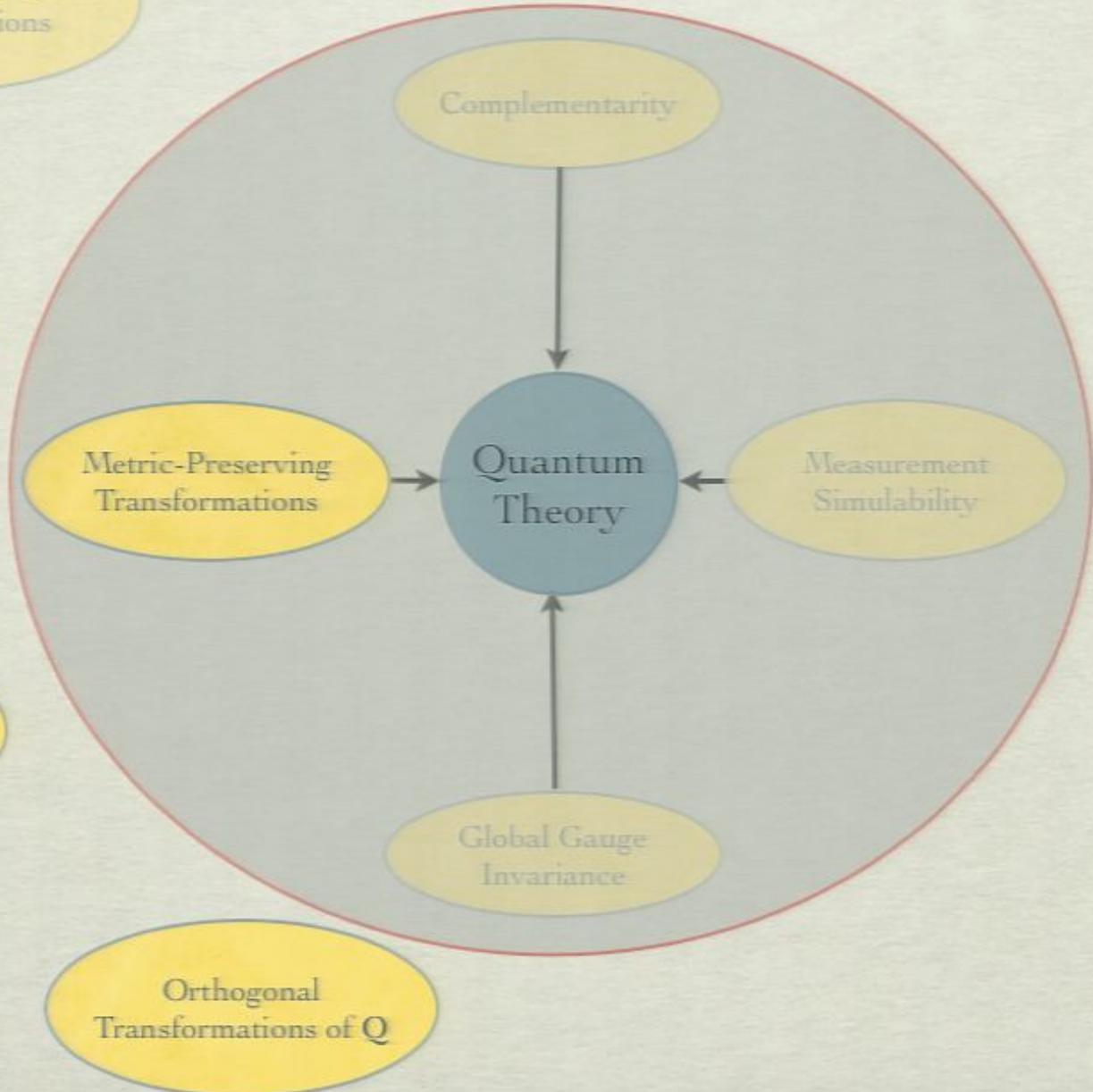
Transformations are unitary or antiunitary

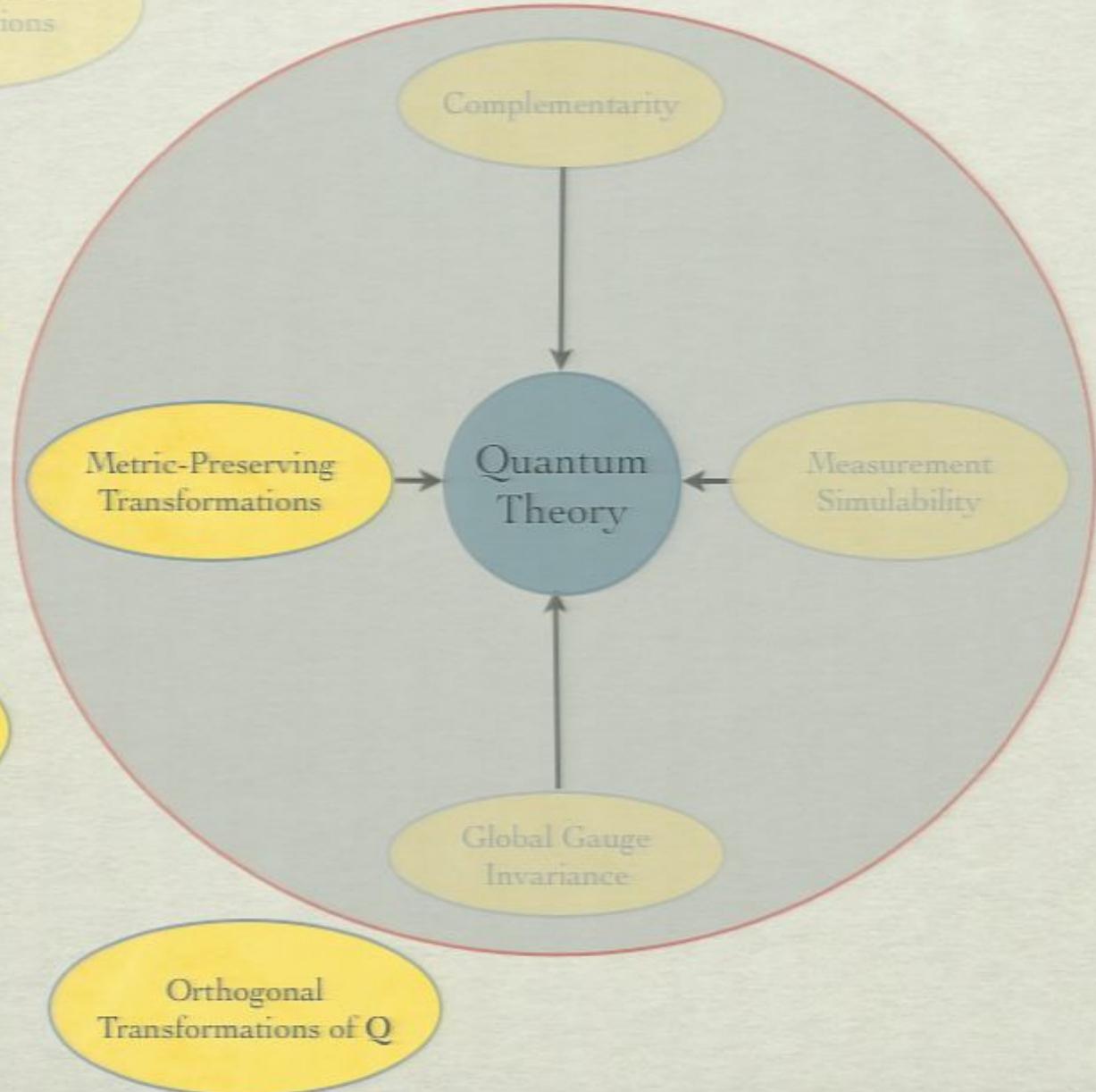
Further Steps

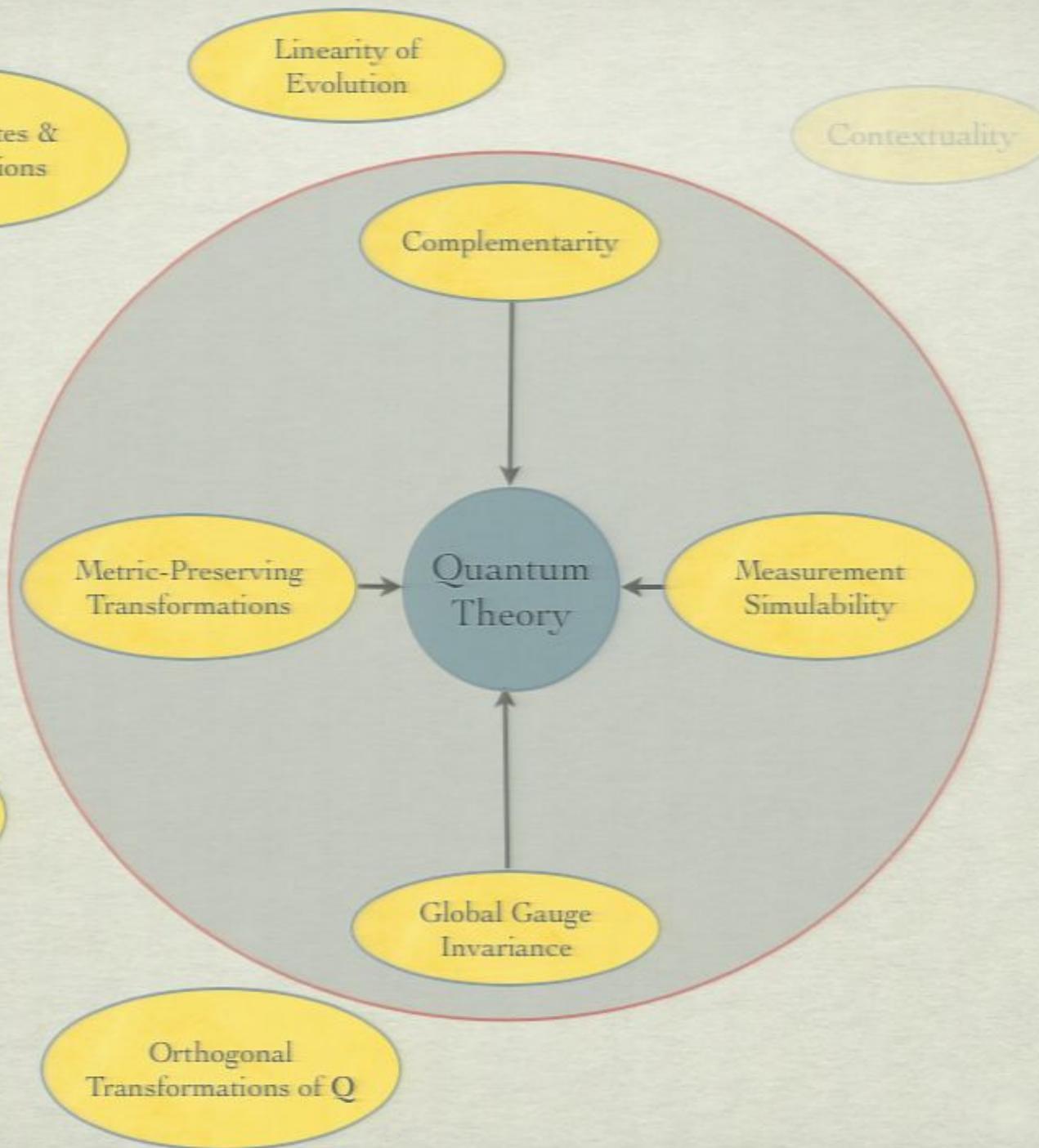
- **Tensor Product Rule**
 $v = v^{(1)} \otimes v^{(2)}$
- **Temporal Evolution Operator**
 $U_t(dt) = \exp(i\mathcal{H} dt/\hbar)$
- **Correspondence Rules**
 $[\mathcal{L}_x, \mathcal{L}_y] = i\hbar\mathcal{L}_z$, etc.

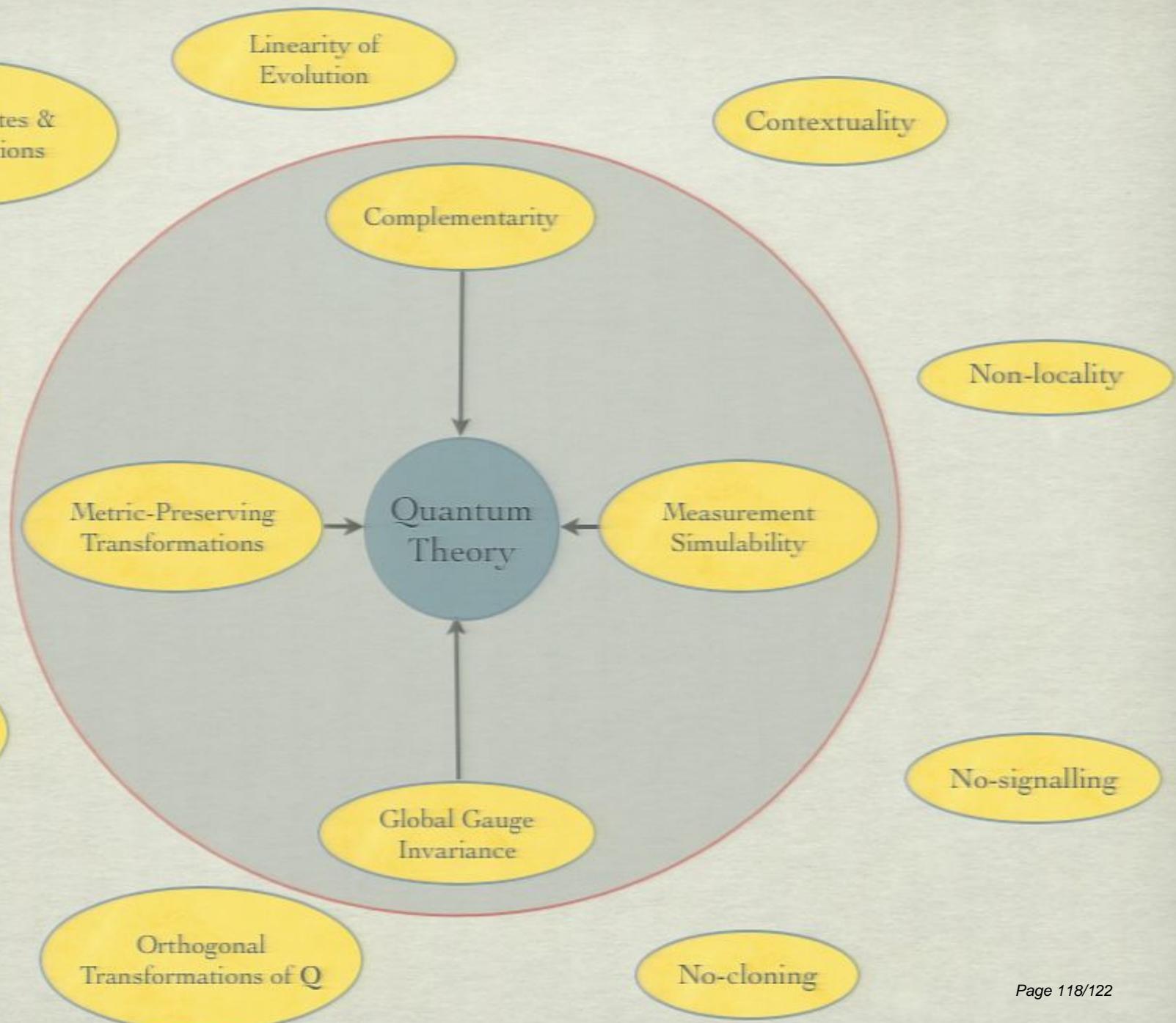




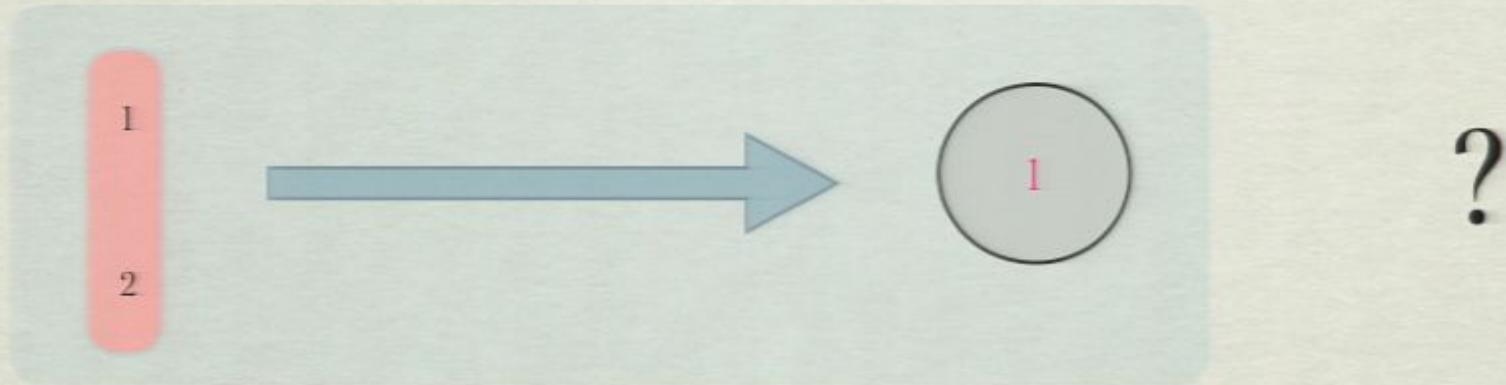




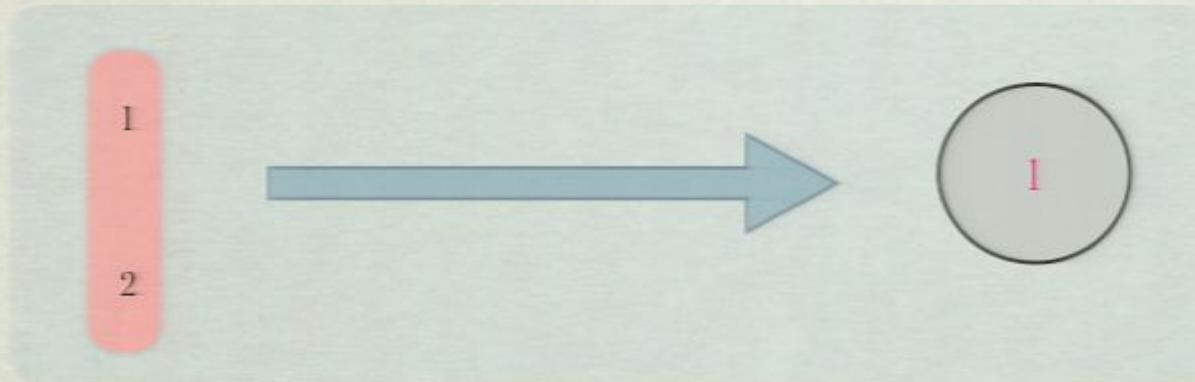




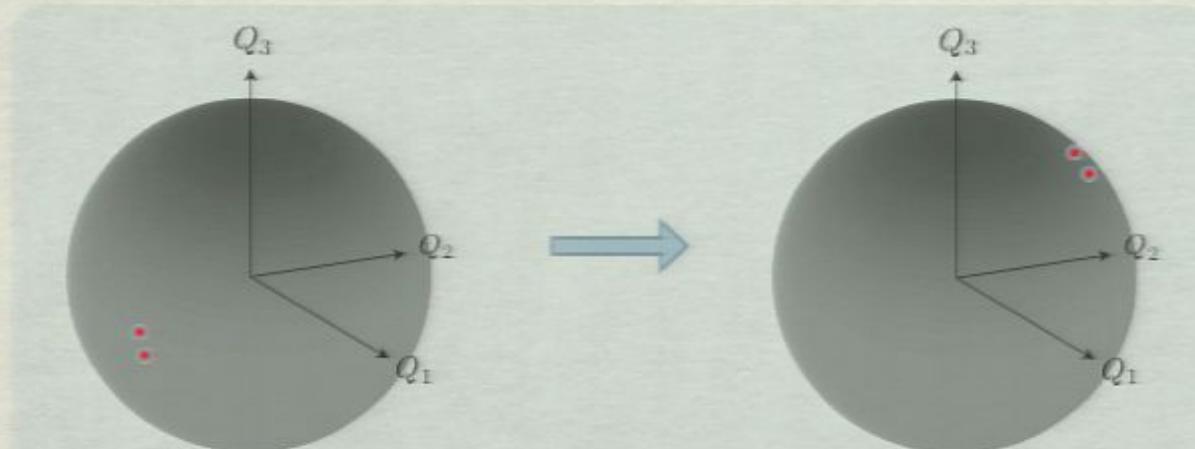
Questions



Questions



?



?

Questions

$\chi_i \rightarrow \chi_i + \chi_0$?

