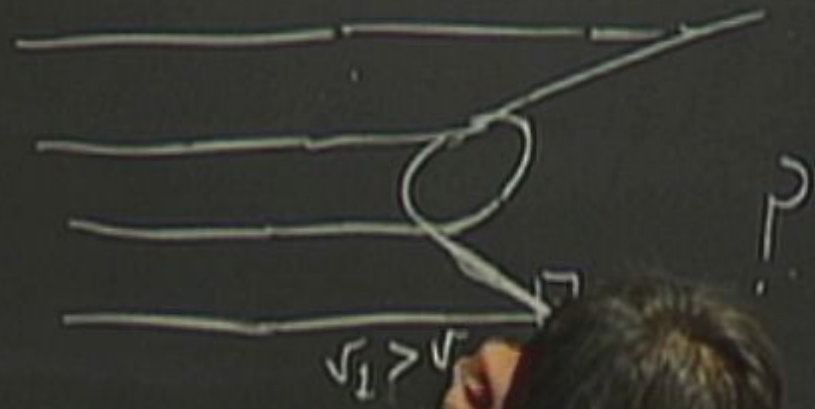
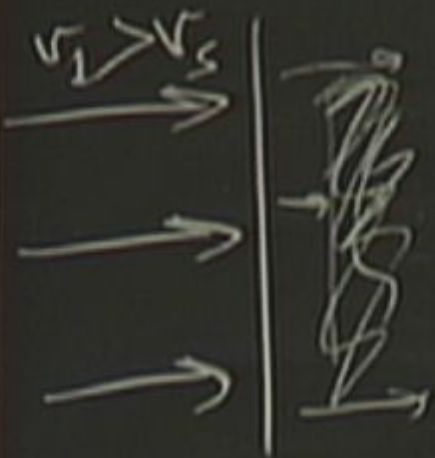


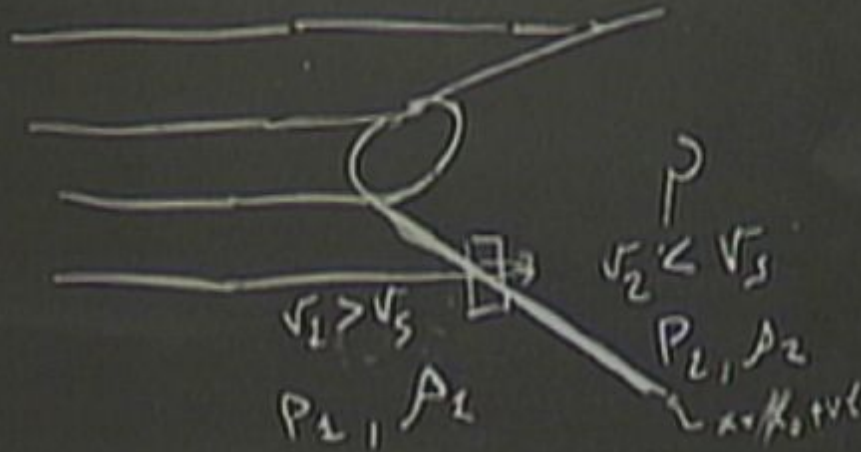
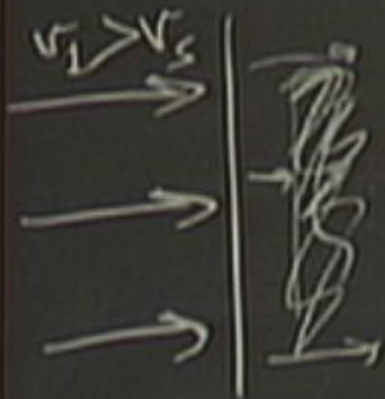
Title: Astrophysics and Cosmology through Problems - 7A

Date: Oct 16, 2008 10:00 AM

URL: <http://pirsa.org/08100003>

Abstract: This course is aimed at advanced undergraduate and beginning graduate students, and is inspired by a book by the same title, written by Padmanabhan. Each session consists of solving one or two pre-determined problems, which is done by a randomly picked student. While the problems introduce various subjects in Astrophysics and Cosmology, they do not serve as replacement for standard courses in these subjects, and are rather aimed at educating students with hands-on analytic/numerical skills to attack new problems.





$$dM_1 = dM_2$$

$$\rho_1 v_1 A_1 = \rho_2 v_2 A_2$$

$$\rho_1 v_1 = \rho_2 v_2$$

$$PV = k_B T$$

$$P = \rho R T, \quad R = \frac{k_B}{m}$$

$$w = \cancel{e} + \frac{P}{\rho}$$

$$= e + RT$$

$$= C_V T + RT$$

$$= \frac{R}{\gamma - 1} T + RT$$

$$PV = k_B T$$

$$P = \rho R T, \quad R = \frac{k_B}{m}$$

$$w = \cancel{e} + \frac{P}{\rho}$$

$$\cancel{P} = \rho^\gamma$$

$$= e + RT$$

$$= C_V T + RT$$

$$= \frac{R}{\gamma-1} T + RT$$

$$= \left(\frac{1}{\gamma-1} + 1 \right) RT$$

$$= \frac{\gamma}{\gamma-1} \frac{P}{\rho}$$

$$PV = k_B T$$

$$P = \rho R T$$

$$R = \frac{k_B}{m}$$

$$w = e + \frac{P}{\rho}$$

$$= e + RT$$

$$= C_v T + RT$$

$$= \frac{R}{\gamma - 1} T + RT$$

$$= \left(\frac{\gamma}{\gamma - 1} + 1 \right) RT$$

$$= \frac{\gamma}{\gamma - 1} \frac{P}{\rho}$$

$$P = \rho^\gamma$$

$$w = \int \frac{dP}{\rho}$$

$$dw = T ds + \frac{dP}{\rho}$$

$$\frac{1}{2} v^2 + \int \frac{dP}{\rho} + \Phi = C$$

$$PV = k_B T$$

$$P = \rho R T, \quad R = \frac{k_B}{m}$$

$$w = e + \frac{P}{\rho}$$

$$= e + RT$$

$$= C_V T + RT$$

$$= \frac{R}{\gamma - 1} T + RT$$

$$= \left(\frac{\gamma}{\gamma - 1} + 1 \right) RT$$

$$= \frac{\gamma}{\gamma - 1} \frac{P}{\rho}$$

$$P = \rho^\gamma$$

$$w = \int \frac{dP}{\rho}$$

$$dw = T ds + \frac{dP}{\rho}$$

$$\frac{1}{2} v^2 + \int \frac{dP}{\rho} + \Phi = \text{const.}$$

$$PV = k_B T$$

$$P = \rho R T$$

$$R = \frac{k_B}{m}$$

$$w = \epsilon + \frac{P}{\rho}$$

$$= \epsilon + RT$$

$$= C_V T + RT$$

$$= \frac{R}{\gamma - 1} T + RT$$

$$= \left(\frac{\gamma}{\gamma - 1} + 1 \right) RT$$

$$= \frac{\gamma}{\gamma - 1} \frac{P}{\rho}$$

$$P = \rho^\gamma$$

$$w = \int \frac{dP}{\rho}$$

$$dw = T ds + \frac{dP}{\rho}$$

$$\frac{1}{2} v^2 + \int \frac{dP}{\rho} + \Phi = \text{const.}$$

$$\frac{1}{2} v_1^2 + \frac{\gamma}{\gamma - 1} \frac{P_1}{\rho_1} = \frac{1}{2} v_2^2 + \frac{\gamma}{\gamma - 1} \frac{P_2}{\rho_2}$$

$$PV = k_B T$$

$$P = \rho R T, \quad R = \frac{k_B}{m}$$

$$w = \epsilon + \frac{P}{\rho} \quad P = \rho^\gamma$$

$$= \epsilon + R T$$

$$= C_V T + R T$$

$$= \frac{R}{\gamma-1} T + R T$$

$$= \left(\frac{\gamma}{\gamma-1} + 1 \right) R T$$
$$= \frac{\gamma}{\gamma-1} \frac{P}{\rho}$$

$$w = \int \frac{dP}{\rho}$$

$$dw = T ds + \frac{dP}{\rho}$$

$$\frac{1}{2} v^2 + \int \frac{dP}{\rho} + \Phi = \text{const.}$$

$$\frac{1}{2} v_2^2 + \frac{\gamma}{\gamma-1} \frac{P_2}{\rho_2} = \frac{1}{2} v_1^2 + \frac{\gamma}{\gamma-1} \frac{P_1}{\rho_1}$$

$$\frac{d}{dt}(\text{density}) + \partial_i(\text{flux}) = 0$$

$$\frac{d}{dt} \rho + \partial_i(\rho v^i) = 0$$

$$\frac{d}{dt}(\text{density}) + \partial_i(\text{flux}) = 0$$

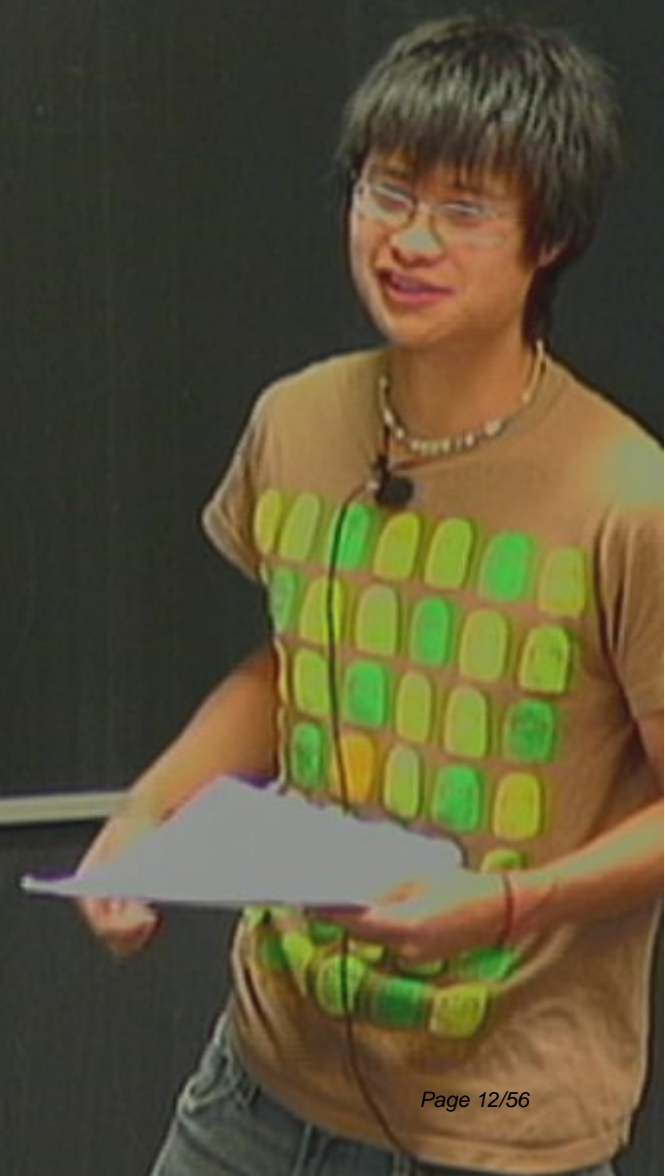
$$\frac{d}{dt} \rho + \partial_i(\rho v^i) = 0$$

$$v_j \frac{d}{dt} \rho + v_j \partial_i(\rho v^i) = 0$$

$$v_j \frac{d}{dt} \rho + v_j v^i \partial_i \rho + \rho v_j \partial_i v^i = 0$$

$$\frac{d}{dt} v_j + (v^i \partial_i) v_j = \frac{-\partial_i P}{\rho} + F_j, \quad F_j = 0$$

$$\rho \frac{d}{dt} v_j + \rho v^i \partial_i v_j = -\partial_i P$$



$$\frac{d}{dt} v_j + (v^i \partial_i) v_j = \frac{-\partial_i P}{\rho} + F_j, \quad F_j = 0$$

$$\rho \frac{d}{dt} v_j + \rho v^i \partial_i v_j = -\partial_i P$$

$$v_j \frac{d}{dt} \rho + \rho \frac{d}{dt} v_j + \rho v^i \partial_i v_j + \rho v_j \partial_i v^i + v_j v^i \partial_i P = -\partial_i P$$

$$\frac{d}{dt} (\rho v_j) + \partial_i (\rho v^i v_j) + \partial_i P = 0$$

$$T'_{ij} = P \delta_{ij} + \rho v^i v_j$$

$$v_1 > v_2$$

$$P_1, A_1$$

$$v_2 < v_1$$

$$P_2, A_2$$

$$x = x_0 + vt$$

$$P_1 v_1 = P_2 v_2$$

$$P_1 + \rho_1 v_1^2 = P_2 + \rho_2 v_2^2$$

P_1, A_1

$x = x_0 + vt$

$$P_1 + \rho_1 v_1^2 = P_2 + \rho_2 v_2^2$$

$$M_1 = \frac{v_1}{c_s}$$

c

$v_j \partial_i v_j - \partial_i P$

$$v_j + \rho v^i \partial_i v_j + \rho v_j \partial_i v^i + v_j v^i \partial_i P = -\partial_i P$$

$$+ \partial_j (v^i v_j) + \partial_j P = 0$$

$$P_1 + \rho_1 v_1^2 = P_2 + \rho_2 v_2^2$$

$$M_1 = \frac{v_1}{c_s} \quad M_2 = v_2 \frac{\rho_1}{\gamma P_1} \quad c_s = \sqrt{\frac{\gamma P_1}{\rho_1}}$$

$$\rho v^i \partial_i v_j + \rho v_j \partial_i v^i + v_j v^i \partial_i P = -$$

$$(\rho v^i v_j) + \partial_j P = 0$$

$$P_1 + \rho_1 v_1^2 = P_2 + \rho_2 v_2^2$$

$$M_1 = \frac{v_1}{c_{s1}}$$

$$M_1^2 = v_1^2 \frac{\rho_1}{\gamma P_1}$$

$$c_s = \sqrt{\frac{\gamma P_1}{\rho_1}}$$

$$f_j = -\partial_j P$$

$$\rho v^i \partial_i v_j + \rho v_j \partial_i v^i + v_j v^i \partial_i P = -\partial_j P$$

$$(\rho v^i v_j) + \partial_j P = 0$$

$$P_1 + \rho_1 v_1^2 = P_2 + \rho_2 v_2^2$$

$$M_1 = \frac{v_1}{c_s}$$

$$M_2 = v_2 \frac{\rho_1}{\gamma P_1}$$

$$c_s = \sqrt{\frac{\gamma P_1}{\rho_1}}$$

$$\frac{\partial}{\partial t} = -\partial_i P$$

$$\rho v^i \partial_i v_j + \rho v_j \partial_i v^i + v_j v^i \partial_i P = -\partial_i P$$

$$(\rho v^i v_j) + \partial_j P = 0$$

$$\begin{aligned} P_2 &= \frac{\gamma-1}{2\gamma} \rho_2 v_1^2 + \frac{P_1}{\rho_1} \rho_2 - \frac{\gamma-1}{2\gamma} \rho_2 v_2^2 \\ &= \rho_1 \frac{\rho_2}{\rho_1} + \frac{\gamma-1}{2\gamma} \rho_2 (v_1^2 - v_2^2) \end{aligned}$$

$$P_2 = \frac{\gamma-1}{2\gamma} \rho_2 v_1^2 + \frac{P_1}{\rho_1} \rho_2 - \frac{\gamma-1}{2\gamma} \rho_2 v_2^2$$
$$= \rho_1 \frac{\rho_2}{\rho_1} + \frac{\gamma-1}{2\gamma} \rho_2 (v_1^2 - v_2^2)$$

$$P_1 + \rho_1 v_1^2 - \rho_2 v_2^2 = \rho_1 \frac{\rho_2}{\rho_1} + \frac{\gamma-1}{2\gamma} \rho_2 (v_1^2 - v_2^2)$$

$$v_2^2 = \frac{\rho_1^2 v_1^2}{\rho_2^2}$$

$$P_1 + P_1 v_1^2 \left(1 - \frac{P_1}{P_2}\right) = P_1 \frac{P_2}{P_1} + \frac{\gamma-1}{2\gamma} + \frac{\gamma-1}{2\gamma} P_2 v_1^2 \left(1 - \frac{P_1}{P_2}\right)$$

$\rho_1^2 v_1^2$

$$\frac{\rho_2}{\rho_1} \left(\frac{\rho_1}{\rho_1 v_1^2} \right) \left(1 - \frac{\rho_1}{\rho_2} \right) + \frac{\rho_2}{\rho_1} \left(1 - \frac{\rho_1}{\rho_2} \right) + \frac{1-\gamma}{\gamma} \frac{\rho_2^2}{\rho_1^2} \left(1 - \frac{\rho_1}{\rho_2^2} \right) = 0$$

$\frac{\partial \rho_1}{\partial \rho_2}$ $\frac{\partial \rho_2}{\partial \rho_1}$

$$\rho_1^2 v_1^2$$

$$\frac{\rho_2}{\rho_1} \left(\frac{\rho_1}{\rho_1 v_1^2} \right) \left(1 - \frac{\rho_1}{\rho_2} \right)$$

$$+ \left(\frac{\rho_2}{\rho_1} \right) \left(1 - \frac{\rho_1}{\rho_2} \right) + \frac{1-\gamma}{2\gamma} \frac{\rho_2^2}{\rho_1^2} \left(1 - \frac{\rho_1}{\rho_2} \right) = 0$$

$$\frac{\rho_2^2}{\rho_1^2} \left(\frac{1-\gamma}{2\gamma} - \frac{1}{\gamma M_1^2} \right) +$$

$\rho_1 v_1$

$$\frac{\rho_2}{\rho_1} \left(\frac{\rho_1}{\rho_1 v_1^2} \right) \left(1 - \frac{\rho_1}{\rho_2} \right) + \frac{\rho_2}{\rho_1} \left(1 - \frac{\rho_1}{\rho_2} \right) + \frac{1-\gamma}{2\gamma} \frac{\rho_2^2}{\rho_1^2} \left(1 - \frac{\rho_1^2}{\rho_2^2} \right) = 0$$

$$\frac{\rho_2^2}{\rho_1^2} \left(\frac{1-\gamma}{2\gamma} - \frac{1}{\gamma M_1^2} \right) + \frac{\rho_2}{\rho_1} \left(\frac{1}{\gamma M_1^2} + 1 \right) - 1 - \frac{1-\gamma}{2\gamma} = 0$$

$$T_j = P \delta_j + P^0 \delta_j$$

$$\frac{P_2^2}{P_1^2} (M_1^2 - \delta M_1^2 - 2) + \frac{P_2}{P_1} (2 + 2\delta M_1^2) - 2$$

$-\frac{P_2}{P_1}$

$$\frac{P_2}{P_1} (M_1^2 - 2M_1^2 - 2) + \frac{P_2}{P_1} (2 + 2\gamma M_1^2) - 2\gamma M_1^2 - M_1^2 + \gamma M_1^2 = 0$$

$$\frac{P_2}{P_1}$$

$= \frac{1}{\gamma-1} \gamma$

$$\frac{P_2}{P_1} (M_1^2 - \gamma M_1^2 - 2) + \frac{P_2}{P_1} (2 + 2\gamma M_1^2) - 2\gamma M_1^2 - M_1^2 + \gamma M_1^2 = 0$$

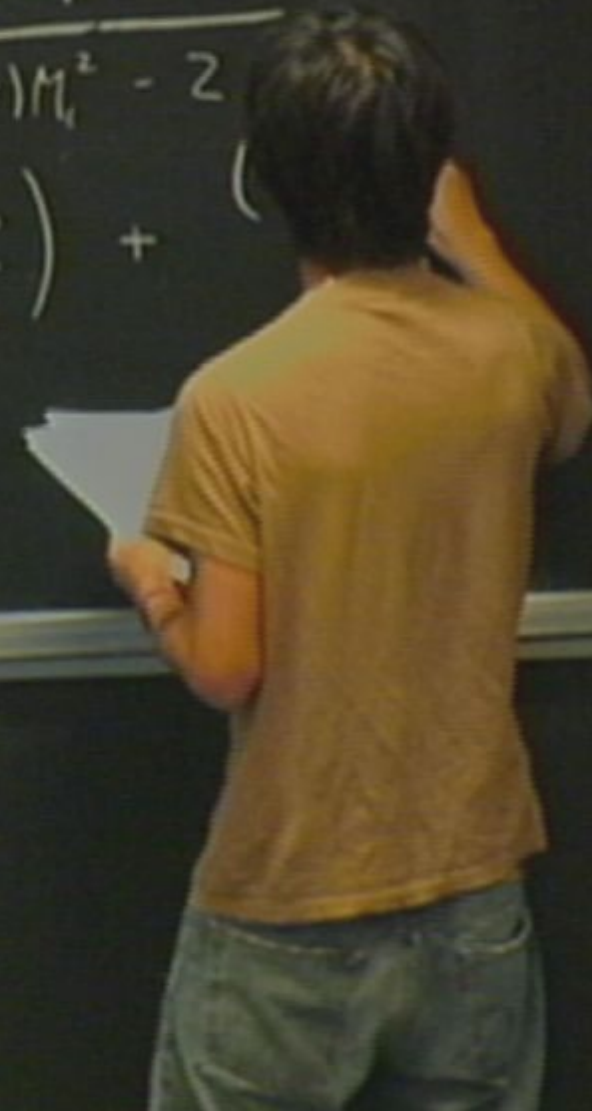
$$\frac{P_2}{P_1} + \frac{P_1}{P_1} \left[\frac{2 + 2\gamma M_1^2}{(1-\gamma)M_1^2 - 2} \right] = \frac{-(\gamma M_1^2 + M_1^2)}{(1-\gamma)M_1^2}$$

$-\gamma + 1$

$$\frac{P_2}{P_1} (M_1^2 - \gamma M_1 - 2) + \frac{P_2}{P_1} (2 + 2\gamma M_1^2) - 2\gamma M_1^2 - M_1^2 + \gamma M_1^2 = 0$$

$$\frac{P_2}{P_1} + \frac{P_2}{P_1} \left[\frac{2 + 2\gamma M_1^2}{(1-\gamma)M_1^2 - 2} \right] - \frac{(\gamma M_1^2 + M_1^2)}{(1-\gamma)M_1^2 - 2}$$

$$\frac{P_2}{P_1} = \frac{(\gamma-1)M_1^2 + 2 + (\gamma+1)M_1^2}{(\gamma-1)M_1^2 + 2} \left(\frac{P_2}{P_1} \right) +$$



$$\frac{P_2}{P_1^2} (M_1^2 - \gamma M_1 - 2) + \frac{1}{P_1} (2 + 2\gamma M_1^2) - 2\gamma M_1^2 - M_1^2 + \gamma M_1^2 = 0$$

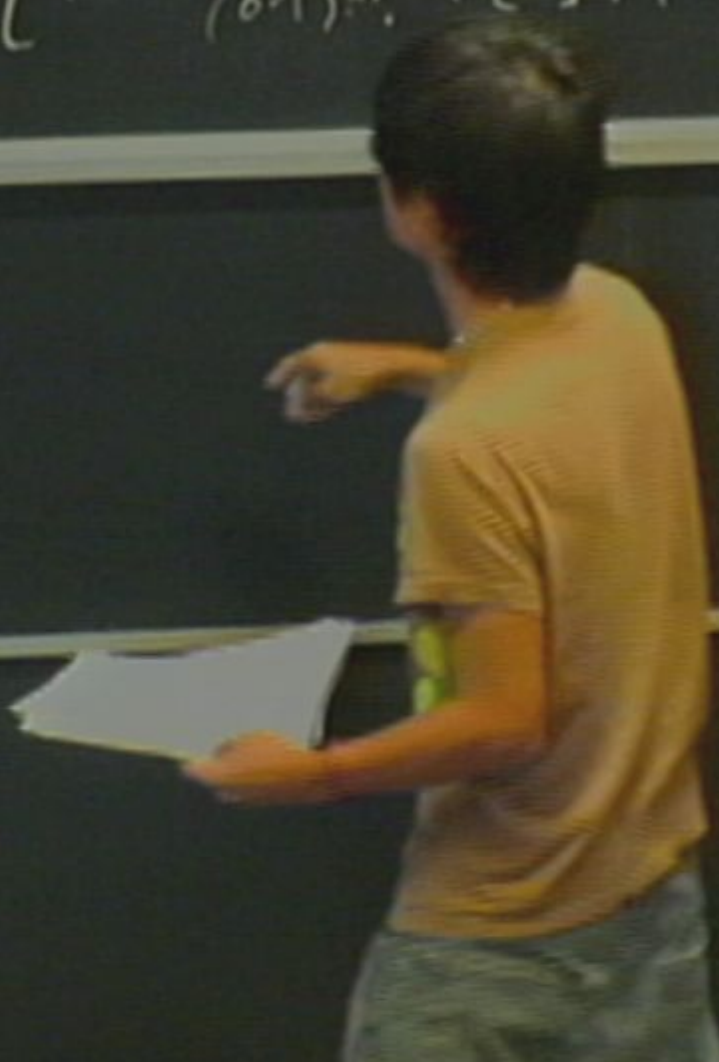
$$\frac{P_2}{P_1^2} + \frac{P_1}{P_1} \left[\frac{2 + 2\gamma M_1^2}{(1-\gamma)M_1^2 - 2} \right] - \frac{(\gamma M_1^2 + M_1^2)}{(1-\gamma)M_1^2 - 2} = 0$$

$$\frac{P_2}{P_1^2} = \frac{(\gamma-1)M_1^2 + 2 + (\gamma+1)M_1^2}{(\gamma-1)M_1^2 + 2} \left(\frac{P_2}{P_1} \right) + \frac{(\gamma+1)M_1^2}{(\gamma-1)M_1^2 + 2} = 0$$

P_1

$$= \gamma - 1 + \dots$$

$$\frac{P_2}{P_1} - \left[1 + \frac{(\gamma - 1)M_1^2 + 2}{(\gamma + 1)M_1^2} \right] \frac{P_2}{P_1} + \frac{(\gamma - 1)M_1^2 + 2}{(\gamma - 1)M_1^2 + 2} = 0$$



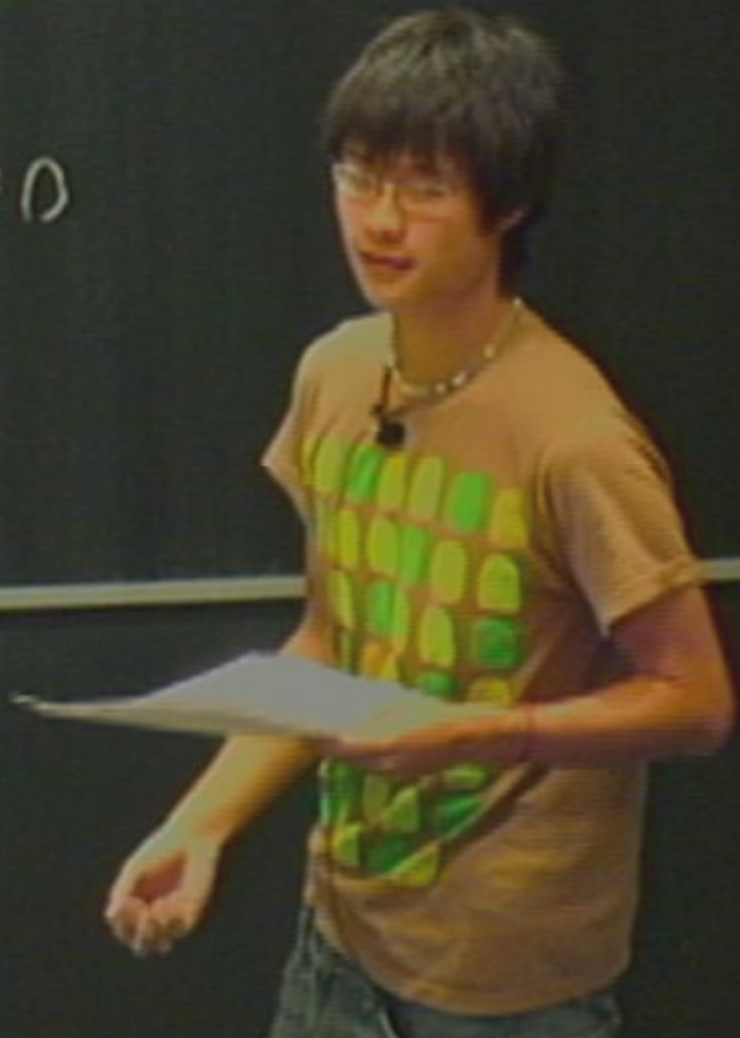
$\gamma - 1$

$$\frac{P_2}{P_1} - \left[1 + \frac{(\gamma - 1)M_1^2}{(\gamma - 1)M_1^2 + 2} \right] \frac{P_2}{P_1} + \frac{(\gamma - 1)M_1^2}{(\gamma - 1)M_1^2 + 2} = 0$$

$$x^2 - (1 + \lambda)x + \lambda = 0$$
$$x = 1, x = \lambda$$

$$\frac{P_2}{P_1} = \frac{(\gamma+1)M_1^2}{(\gamma-1)M_1^2 + 2}$$

$$x^2 - (1+\lambda)x + \lambda = 0$$
$$x=1, x=\lambda$$



$$\frac{P_2}{P_1} = \frac{(\gamma + 1)M_1^2}{(\gamma - 1)M_1^2 + 2}$$

$$\frac{v_2}{v_1} = \frac{P_1}{P_2}$$

$$x^2 - (1 + \lambda)x + \lambda = 0$$

$$x = 1, x = \lambda$$

$$\frac{P_2}{P_1} = \frac{(\gamma + 1) M_1^2}{(\gamma - 1) M_1^2 + 2}$$

$$\frac{v_2}{v_1} = \frac{P_1}{P_2}$$

$$x^2 - (1 + \lambda)x + \lambda = 0$$

$$x = 1, x = \lambda$$

$$\frac{RT_2}{RT_1} = \frac{P_2}{P_1} \left(\frac{P_1}{P_2} \right)$$

$$\frac{P_2}{P_1} = \frac{2\gamma M_1^2 - \gamma + 1}{\gamma + 1}$$

$$\frac{T_2}{T_1} = \frac{[2\gamma M_1^2 - (\gamma - 1)][(\gamma - 1)M_1^2 + 2]}{(\gamma + 1)^2}$$

$$= \frac{(\gamma + 1)M_1^2 + (\gamma - 1)(M_1^2 - 1)(\gamma M_1 + 1)}{(\gamma + 1)^2}$$

$$\frac{P_2}{P_1} = \frac{2\gamma M_1^2 - \gamma + 1}{\gamma + 1}$$

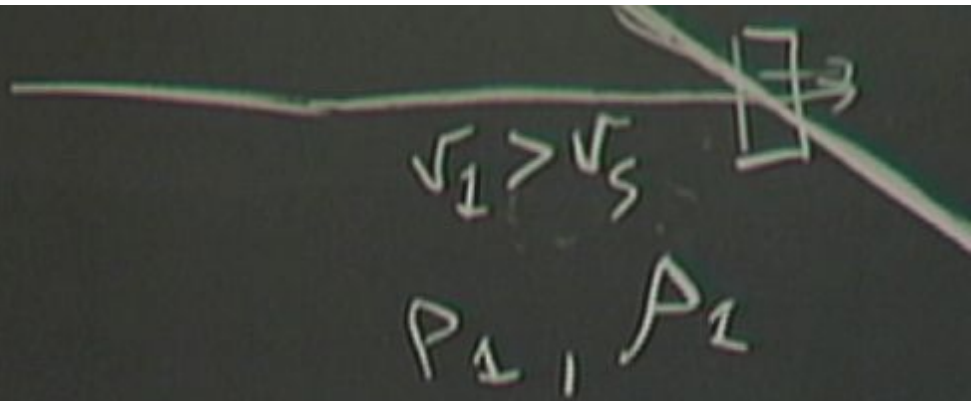
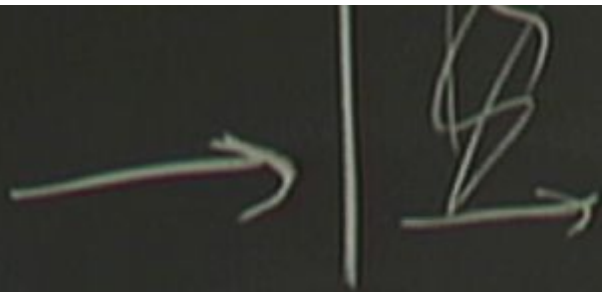
$$\frac{T_2}{T_1} = \frac{[2\gamma M_1^2 - (\gamma - 1)][(\gamma - 1)M_1^2 + 2]}{(\gamma + 1)^2 M_1^2}$$

$$= \frac{(\gamma + 1)M_1^2 + 2(\gamma - 1)(M_1^2 - 1)(\gamma M_1 + 1)}{(\gamma + 1)M_1^2}$$

$$\frac{P_2}{P_1} = \frac{2\gamma M_1^2 - \gamma + 1}{\gamma + 1}$$

$$\frac{T_2}{T_1} = \frac{[2\gamma M_1^2 - (\gamma - 1)][(\gamma - 1)M_1^2 + 2]}{(\gamma + 1)^2 M_1^2}$$

$$= \frac{(\gamma + 1)M_1^2 + 2(\gamma - 1)(M_1^2 - 1)(\gamma M_1 + 1)}{(\gamma + 1)M_1^2}$$



P_1, A_1

$$\gamma = \frac{C_p}{C_v}$$

$P_1 + P_1$

M_1

$$\frac{P_2}{P_1} = \frac{(\gamma + 1) M_1^2}{(\gamma - 1) M_1^2 + 2}$$

$$\frac{v_2}{v_1} =$$

$$\lambda = \frac{\gamma + 1}{(\gamma - 1) + \frac{2}{M_1^2}}$$

$$\frac{P_2}{P_1} = \frac{(\gamma + 1) M_1^2}{(\gamma - 1) M_1^2 + 2}$$

$$\frac{v_2}{v_1} =$$

$$\lambda = \frac{\gamma + 1}{(\gamma - 1) + \frac{2}{M_1^2}}$$

$$\frac{P_2}{P_1} = \frac{(\gamma + 1) M_1^2}{(\gamma - 1) M_1^2 + 2}$$

$$\frac{v_2}{v_1} =$$

$$\lambda = \frac{\gamma + 1}{(\gamma - 1) + \frac{2}{M_1^2}} \approx \frac{\gamma + 1}{\gamma - 1}$$

$$\begin{aligned}
 & (\gamma - 1) M_1^2 + \dots \\
 & = \frac{\gamma + 1}{(\gamma - 1) + \frac{2}{M_1^2}} \approx \frac{\gamma + 1}{\gamma - 1} \quad \frac{R T}{R T} \\
 & \frac{7}{3} = 7
 \end{aligned}$$

$$\rho v^2 + p - \Pi P = \text{const.}$$

$$\Pi P = \begin{pmatrix} \sigma_{xx} & - & - \\ \tau_{yx} & \sigma_{yy} & - \\ \tau_{zx} & - & \sigma_{zz} \end{pmatrix}$$

$$\rho v^2 + p - \sigma_{xx} = \text{const.}$$

$$\sigma_{xx} \frac{\partial v^2}{\partial x} = \frac{1}{2} \eta \left(2V_{2x} - \frac{2}{3} \frac{\partial v}{\partial x} \right)^2 + \sum \left(\frac{\partial v}{\partial x} \right)^2$$

$$\rho v^2 + P - \Pi P = \text{const.}$$

$$\Pi P = \begin{pmatrix} \sigma_{xx} & - & \\ \tau_{yx} & \sigma_{yy} & \\ \tau_{zx} & - & \sigma_{zz} \end{pmatrix}$$

$$\rho v^2 + P - \sigma_{xx} = \text{const.}$$

$$\sigma_{xx} \frac{\partial \vec{v}}{\partial x} = \frac{1}{2} \eta \left(2V_{yx} - \frac{2}{3} \frac{\partial v}{\partial x} \right)^2 + \sum \left(\frac{\partial v}{\partial x} \right)^2, \quad V_{yx} \approx \frac{\partial v}{\partial x}$$

$$= \frac{1}{2} \eta \left(\frac{4}{3} \right)^2 \frac{\partial v}{\partial x} + \sum \frac{\partial v}{\partial x}$$

$$\frac{1}{2} \left(\frac{4}{3} + \sum \right) \frac{\partial v}{\partial x}$$

$$\rho v^2 + p - \Pi P = \text{const.}$$

$$\Pi P = \begin{pmatrix} \sigma_{xx} & - & - \\ \tau_{yx} & \sigma_{yy} & - \\ \tau_{zx} & - & \sigma_{zz} \end{pmatrix}$$

$$\rho v^2 + p - \sigma_{xx} = \text{const.}$$

$$\sigma_{xx} \frac{\partial v}{\partial x} = \frac{1}{2} \eta \left(2V_{,xx} - \frac{2}{3} \frac{\partial v}{\partial x} \right)^2 + \sum \left(\frac{\partial v}{\partial x} \right)^2, \quad V_{,xy} \approx \frac{\partial v}{\partial x}$$

$$\sigma_{xx} = \frac{1}{2} \eta \left(\frac{4}{3} \right)^2 \frac{\partial v}{\partial x} + \sum \frac{\partial v}{\partial x}$$

$$\frac{1}{2} \left(\frac{4}{3} + \sum \right) \frac{\partial v}{\partial x}$$

$$\rho v^2 + P - \Pi P = \text{const.} \Rightarrow \rho v^2 + P - \eta \frac{\partial v}{\partial z} \sim \text{const.}$$

$$\Pi P = \begin{pmatrix} \sigma_{xx} & & & \\ \tau_{yx} & \sigma_{yy} & & \\ \tau_{zx} & & \sigma_{zz} & \\ & & & \end{pmatrix}$$

$$\rho v^2 + P - \sigma_{xx} = \text{const.}$$

$$\sigma_{xx} \frac{\partial v}{\partial x} = \frac{1}{2} \eta \left(2V_{yx} - \frac{2}{3} \frac{\partial v}{\partial x} \right)^2 + \sum \left(\frac{\partial v}{\partial x} \right)^2, \quad V_{yx} \approx \frac{\partial v}{\partial x}$$

$$\sigma_{xx} = \frac{1}{2} \eta \left(\frac{4}{3} \right)^2 \frac{\partial v}{\partial x} + \sum \frac{\partial v}{\partial x}$$

$$\frac{1}{2} (\eta + \sum) \frac{\partial v}{\partial x}$$

$$\sum = \eta \quad \text{or} \quad \sum < \eta$$

$$\rho v^2 + P - \Pi P \approx \text{const.} \Rightarrow \rho v^2 + P - \eta \frac{\partial v}{\partial z} \sim \text{const.}$$

$$\Pi P = \begin{pmatrix} \sigma_{xx} & & & \\ \tau_{yx} & \sigma_{yy} & & \\ \tau_{zx} & & \sigma_{zz} & \\ & & & \end{pmatrix}$$

$$\rho v^2 + P - \sigma_{xx} = \text{const.}$$

$$\sigma_{xx} \frac{\partial v}{\partial x} = \frac{1}{2} \eta \left(2V_{,xx} - \frac{2}{3} \frac{\partial v}{\partial x} \right)^2 + \sum \left(\frac{\partial v}{\partial x} \right)^2, \quad V_{,xx} \approx \frac{\partial v}{\partial x}$$

$$\sigma_{xx} = \frac{1}{2} \eta \left(\frac{4}{3} \right)^2 \frac{\partial v}{\partial x} + \sum \frac{\partial v}{\partial x}$$

$$\frac{1}{2} \left(\frac{4}{3} + \sum \right) \frac{\partial v}{\partial x}$$

$$\sum = \eta \quad \text{or} \quad \sum < \eta$$

$$\eta \frac{\partial v}{\partial x} = \rho v^2 \quad , \quad \frac{\Delta v}{\Delta x} \quad \phi = \frac{\eta}{\rho}$$

$$\Delta x \approx \phi \frac{\Delta v}{v} \quad \phi \approx l v$$

$$\Delta x \approx l$$

$$\frac{M^2}{5}$$



E, P

$$[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

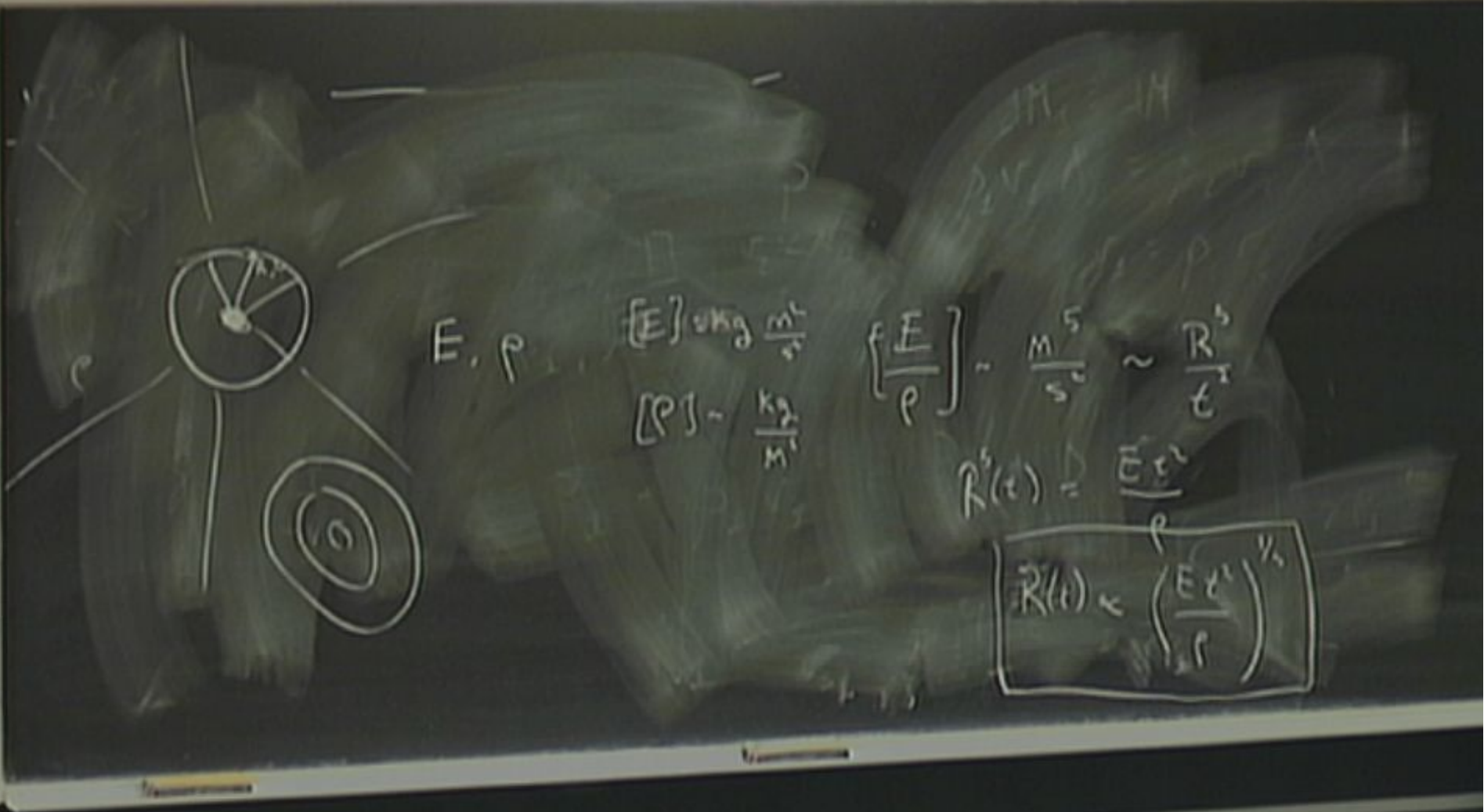
$$[P] = \frac{\text{kg}}{\text{s}}$$

$$\left[\frac{E}{P} \right] = \frac{\text{m}^2}{\text{s}} \sim \frac{R^2}{t}$$

$$R^2(t) \sim \frac{E t^2}{P}$$

$$R(t) \sim \left(\frac{E t^2}{P} \right)^{1/2}$$

CAUTION
 Do not touch the
 surface of the
 mirror as it
 may be damaged
 and the
 mirror will
 be ruined.

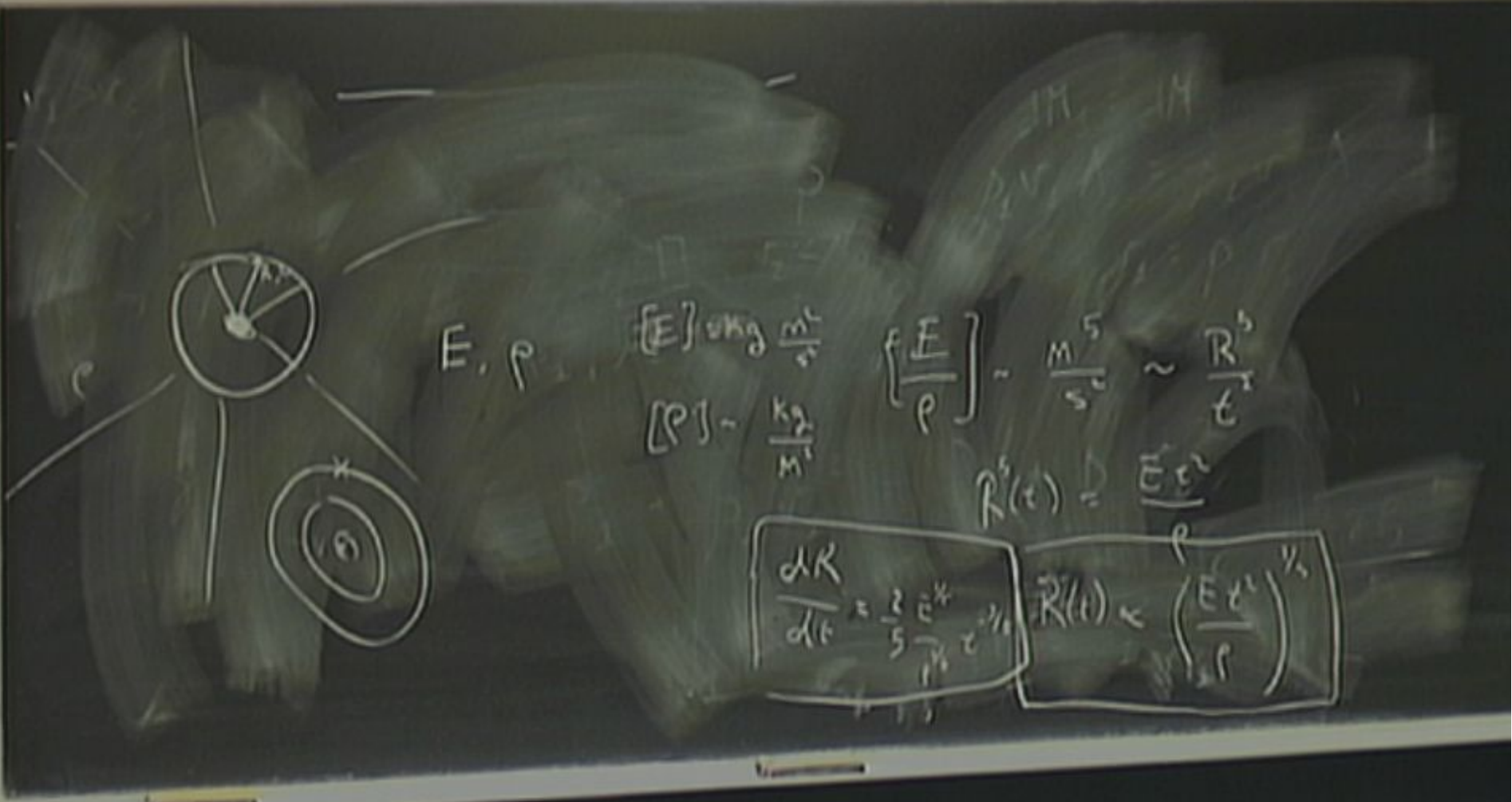


E, P
 $[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$
 $[P] = \frac{\text{kg}}{\text{s}}$

$\left[\frac{E}{P} \right] = \frac{\text{m}^2}{\text{s}} \sim \frac{R^2}{t}$

$R(t) = \sqrt{\frac{E t^2}{P}}$

$R(t) \propto \left(\frac{E t^2}{P} \right)^{1/2}$



E, P

$$[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

$$[P] = \frac{\text{kg} \text{m}^2}{\text{s}}$$

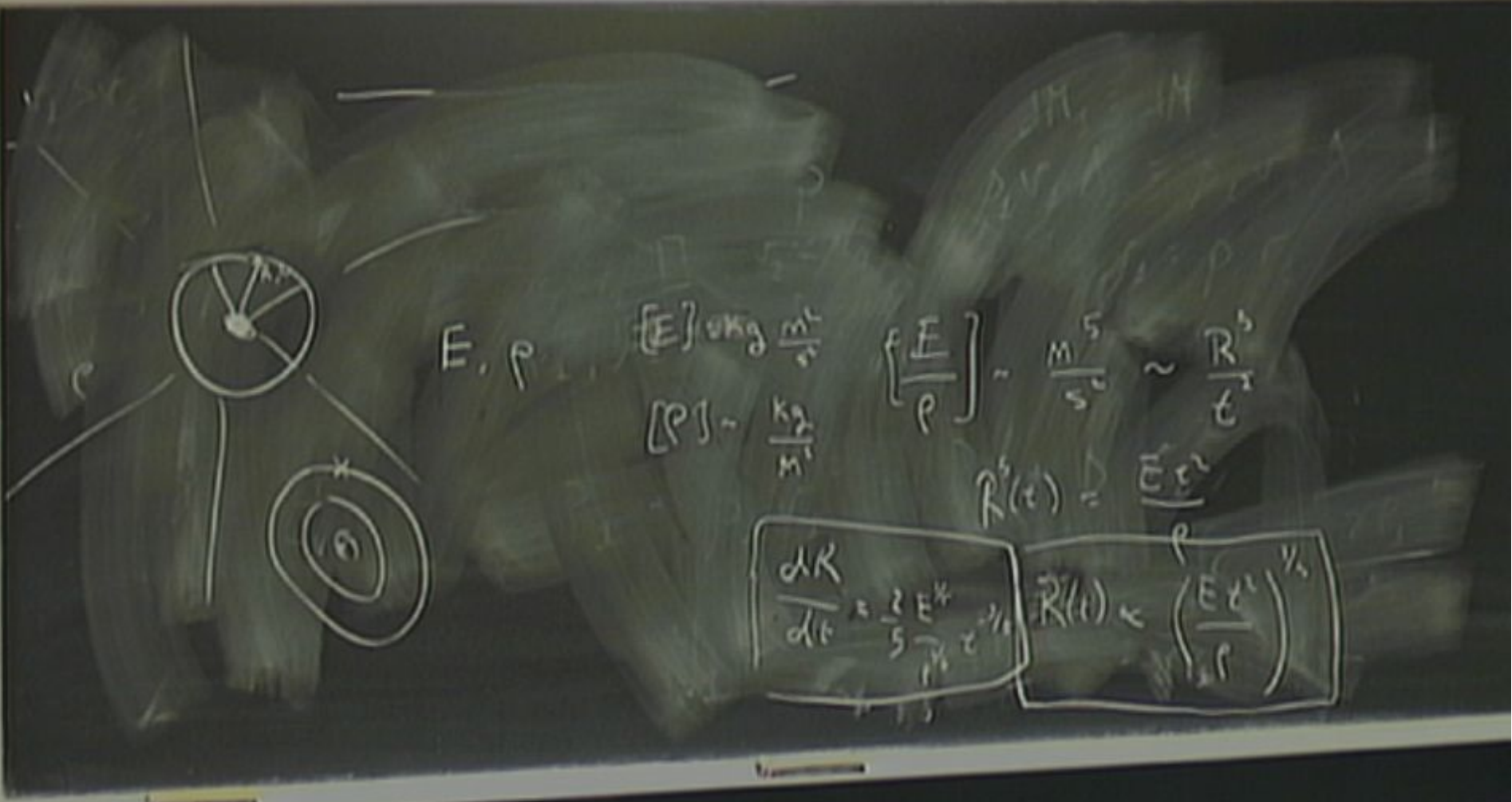
$$\left[\frac{E}{P} \right] = \frac{\text{m}^5}{\text{s}^2} \sim \frac{R^5}{t^2}$$

$$R(t) = \left(\frac{E t^2}{P} \right)^{1/5}$$

$$\frac{dR}{dt} = \frac{2}{5} \frac{E}{P} t^{-3/5}$$

$$R(t) \sim \left(\frac{E t^2}{P} \right)^{1/5}$$

CAUTION



E, P

$$[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

$$[P] = \frac{\text{kg}}{\text{m}^2} \frac{\text{m}^2}{\text{s}}$$

$$\left[\frac{E}{P} \right] = \frac{\text{m}^5}{\text{s}^3} \sim \frac{R^5}{t^3}$$

$$R(t) = \frac{E t^2}{P}$$

$$\frac{dR}{dt} = \frac{2 E t}{P}$$

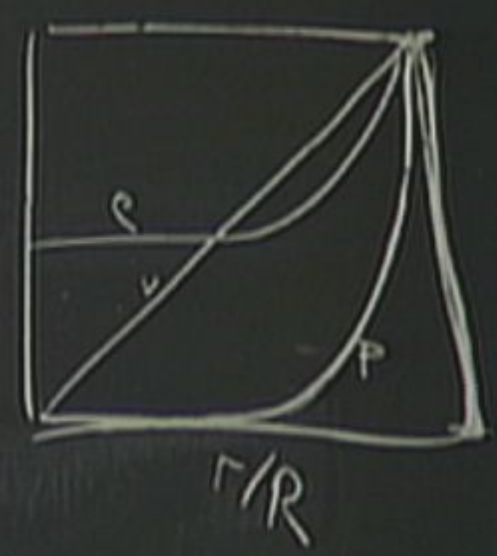
$$R(t) \sim \left(\frac{E t^2}{P} \right)^{1/2}$$

CAUTION

$$\frac{1}{\gamma} \rho_2 (v_1^2 - v_2^2)$$

$$= \rho_1 \frac{\rho_2}{\rho_1} + \frac{\gamma - 1}{2\gamma} \rho_2 (v_1^2 - v_2^2)$$

$$\frac{\rho_1^2 v_1^2}{\rho_2^2}$$



$$h\omega \ll \frac{p_0}{c} \sim m_e v_e c$$

E, p

$$[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

$$[p] = \frac{\text{kg} \cdot \text{m}}{\text{s}}$$

$$\left[\frac{E}{p} \right] \sim \frac{\text{m}^5}{\text{s}^2} \sim \frac{R^5}{t^2}$$

$$R^5(t) = \frac{E t^2}{p}$$

$$\frac{dR}{dt} = \frac{2 E^{1/5}}{5 p^{1/5}} t^{-3/5} \quad R(t) \sim \left(\frac{E t^2}{p} \right)^{1/5}$$



$$h \omega \ll \frac{p_0}{c} \sim m_e v_e c$$

E, p

$$[E] = \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

$$[p] = \frac{\text{kg} \cdot \text{m}}{\text{s}}$$

$$\left[\frac{E}{p} \right] \sim \frac{\text{m}^5}{\text{s}^2} \sim \frac{R^5}{t^2}$$

$$R^5(t) = \frac{E t^2}{p}$$

$$\frac{dR}{dt} = \frac{2 E^{1/5}}{5 t^{1/5}} \quad R(t) \propto \left(\frac{E t^2}{p} \right)^{1/5}$$

