Title: Toy Models for Retrocausality

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Abstract:

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Huw Price

Centre for Time University of Sydney



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- 1 Taking the future seriously
- 2 The Helsinki model
- 3 Revealing the retrocausality
- 4 Where next?

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- 1 Taking the future seriously
  - 'Een vergeten genie'
  - 'More extensive renunciation'
  - Looking for holes in the future absorbers
  - Facing the future in QM
  - The Leipzig connection
  - Taking sides on retrocausality
- 2 The Helsinki model
- 3 Revealing the retrocausality
- 4 Where next?

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Taking the future seriously

- 'Een vergeten genie'

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# EEN VERGETEN GENIE

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- 'Een vergeten genie'



"The sun would not radiate if it were alone in space and no other bodies could absorb its radiation. . . . If e.g. I observed in my telescope yesterday evening that star which . . . is 100 light years away . . . the star or individual atoms of it knew already 100 years ago that I, who then did not even exist, would view it yesterday evening at such and such a time."

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- 'Een vergeten genie'



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— Hugo Martin Tetrode (1895–1931)

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- 'More extensive renunciation'

REVIEWS OF MODERN PHYSICS

VOLUME 17. NUMBERS 2 AND 3

APRIL-JULV, 1945

# Interaction with the Absorber as the Mechanism of Radiation†\*

JOHN ARCHIBALD WHEELER\*\* AND RICHARD PHILLIPS FEYNMAN\*\*\*
Palmer Physical Laboratory, Princeton University, Princeton, New Jersey

"We must, therefore, be prepared to find that further advance into this region will require a still more extensive renunciation of features which we are accustomed to demand of the space time mode of description."—Niels Bohr<sup>1</sup>

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- Taking the future seriously

- 'More extensive renunciation'

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- Neils Bohr (1934)

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-Taking the future seriously

-Looking for holes in the future absorbers

J. Phys. A: Math., Nucl. Gen., Vol. 7, No. 15, 1974. Printed in Great Britain. @ 1974.

### A proposed experiment on absorber theory

M L Heron and D T Pegg

Physics Department, James Cook University, Townsville, 4811, Australia

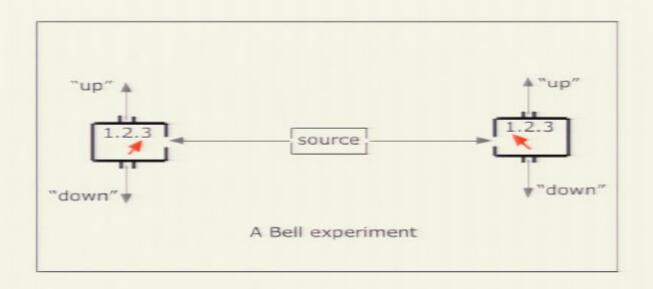
Received 1 October 1973, in final form 20 May 1974

Abstract. As distinct from conventional electrodynamics in which the advanced potential solution of Maxwell's equations is rejected on causal grounds, absorber theory allows the possibility of a mixture of advanced and retarded radiation, dependent on cosmological boundary conditions.

In a recent experiment Partridge attempted to detect advanced effects by introducing a local absorber, but it was maintained by Pegg that, because a static absorber was used, only a null result was possible. In this paper we give the theory and a brief outline of an experiment which uses a time-asymmetric chopper absorber to alter the boundary conditions and thus the ratio of the advanced to retarded components in the mixture, provided this is non-zero initially, leading to possibly detectable effects.

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Facing the future in QM

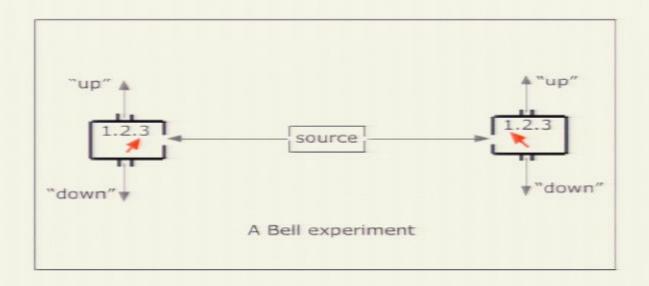


genetic hypothesis. For me, it is so reasonable to assume that the photons in those experiments carry with them programs—telling them how to behave. This is so rational that I think that when Einstein saw that, and the others refused to see it he was the rational man. The other people, although history has justified them were burying their heads in the sand. I feel that Einstein's intellectual superiority over Bohr in this instance, was enormous, a vast guit between the man who saw clearly what was needed, and the obscurantist. So for me, it is a pity that Einstein's lifea doesn't work.

— John Bell (1928-1990)

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Facing the future in QM



"[T]he observed perfect quantum correlations seem to demand something like the 'genetic' hypothesis. For me, it is so reasonable to assume that the photons in those experiments carry with them programs . . . telling them how to behave. This is so rational that I think that when Einstein saw that, and the others refused to see it, he was the rational man. The other people, although history has justified them, were burying their heads in the sand. I feel that Einstein's intellectual superiority over Bohr, in this instance, was enormous; a vast gulf between the man who saw clearly what was needed, and the obscurantist. So for me, it is a pity that Einstein's idea doesn't work. The reasonable thing just doesn't work."

— John Bell (1928-1990)

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Taking the future seriously

Facing the future in QM



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Facing the future in QM

"In 1947 I proposed an explanation that was not to the liking of [my thesis advisor,] Louis de Broglie. I said to him, it is well known that all phenomena of fundamental physics are symmetrical between past and future, at the elementary level: this is certainly a basic phenomenon.

And between two distant events [in an EPR experiment] there is no direct link, but there is a direct link with the past. Therefore, I am fully entitled to suggest that the influence . . . spreads via a zigzag first to the past and then into the future."



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Toy Models for Retrocausality

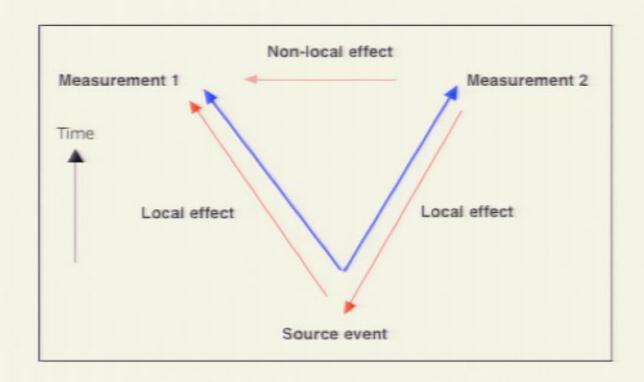
Taking the future seriously

Facing the future in QM

Costa de Beauregard's zig-zag 'retrocausality'.

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Facing the future in QM



Costa de Beauregard's zig-zag 'retrocausality'.

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Toy Models for Retrocausality

Taking the future seriously

The Leipzig connection

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The Leipzig connection



Grete Henry-Hermann

Philosopher, Physicist and Mathematician before her time?

The first retrocausalist?

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Taking the future seriously

The Leipzig connection



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The Leipzig connection

"The idea of using backward causation to explain the non-locality of the Einstein Podolsky Rosen paradox has been around since the year the EPR paper was published. The idea that future events have a causal effect on past events was introduced by Grete Hermann in 1935 and further explored by Costa de Beauregard in 1953 and later, but has been commonly ignored by almost everyone including books devoted to the EPR paradox."

— W. Wharton [quant-ph/9810060].



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Taking the future seriously

The Leipzig connection

>In those years (1933-36) in which Einstein,
>but also Popper, were thinking about
>measurements of correlated observables,
>and related uncertainties, and predictions and
>retrodictions, and 'non-separability' of quantum
>entangled systems, and Grete Hermann developed
>her "relative state" interpretation of QM (now
>known as MWI) and - it seems so, according to Max
>Jammer - also the first "retrocausation" solution
>of EPR effect (decades ahead of Huw Price, O. Costa
>de Beauregard, Pegg, Hoyle, etc.), W. Pauli
>and C.G. Jung were corresponding about telepathy,
>as well as 'psychic' entanglements, 'non-separability'
>of systems, and 'retrocausations'.



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Toy Models for Retrocausality

Taking the future seriously

Taking sides on retrocausality

# Taking sides on retrocausality

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Taking sides on retrocausality

# Taking sides on retrocausality

■ Yes: Hermann, Costa de Beauregard, Cramer, Sutherland, Pegg, Schulman, Price, Miller . . .

No/Don't know:

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Taking sides on retrocausality

# Taking sides on retrocausality

- Yes: Hermann, Costa de Beauregard, Cramer, Sutherland, Pegg, Schulman, Price, Miller . . .
- No/Don't know: Most people. A recent example:

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Taking sides on retrocausality

## Taking sides on retrocausality

- Yes: Hermann, Costa de Beauregard, Cramer, Sutherland, Pegg, Schulman, Price, Miller . . .
- No/Don't know: Most people. A recent example:

"To be scrupulous, there are perhaps four other ways [i.e., other than nonlocality] that the correlations in [an EPR-Bohm] experiment could be explained away.

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Taking sides on retrocausality

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Taking sides on retrocausality

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— Howard Wiseman (2005)

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- 1 Taking the future seriously
- 2 The Helsinki model
  - Motivation
  - The 'dynamics'
  - Adding 'preparation' and 'observation'
- 3 Revealing the retrocausality
- 4 Where next?

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The Helsinki model

- Motivation

# Why toy models?

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Motivation

# Why toy models?

■ Simple 'intuition pumps', for clarifying and motivating unfamiliar ideas

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- Motivation

# Why toy models?

Simple 'intuition pumps', for clarifying and motivating unfamiliar ideas – and for looking for latitude in "the core assumptions necessary to undertake scientific experiments".

A good way of asking the question. "What QM-like features might retrocausality explain?"

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- Motivation

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# Why toy models?

- Simple 'intuition pumps', for clarifying and motivating unfamiliar ideas and for looking for latitude in "the core assumptions necessary to undertake scientific experiments".
- A good way of asking the question, "What QM-like features might retrocausality explain?" - cf. Rob Spekkens' 'epistemic' toy models.

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Toy Models for Retrocausality

The Helsinki model

The 'dynamics'

## The Helsinki model

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#### Toy Models for Retrocausality

The Helsinki model

The 'dynamics'

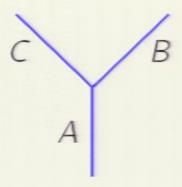
### The Helsinki model

1 Two kinds of primitive nodes ('interactions').

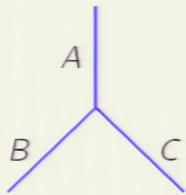
Pair production

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-The 'dynamics'



'Pair production'



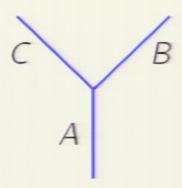
'Pair annihilation'

### The Helsinki model

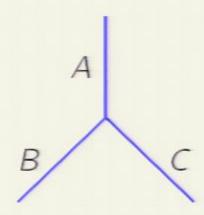
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The 'dynamics'



'Pair production'

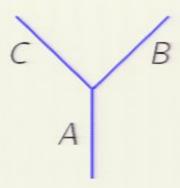


'Pair annihilation'

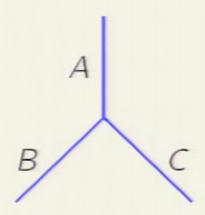
### The Helsinki model

- 1 Two kinds of primitive nodes ('interactions').
- 2 Three kinds of edges ('particles').
- El Each node must be strictly inhomogeneous (i.e., all edges different) or strictly homogeneous (all edges the same).

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'Pair production'

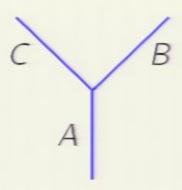


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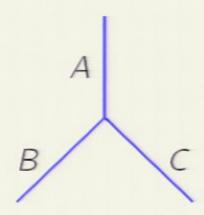
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- Pair production and pair annihilation must alternate

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#### The 'dynamics'



'Pair production'

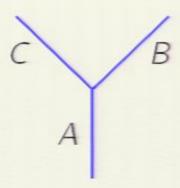


'Pair annihilation'

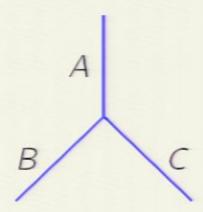
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- 3 Each node must be strictly inhomogeneous (i.e., all edges different) or strictly homogeneous (all edges the same).
- 4 Pair production and pair annihilation must alternate.
- Successive homogeneous nodes are prohibited.

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'Pair production'



'Pair annihilation'

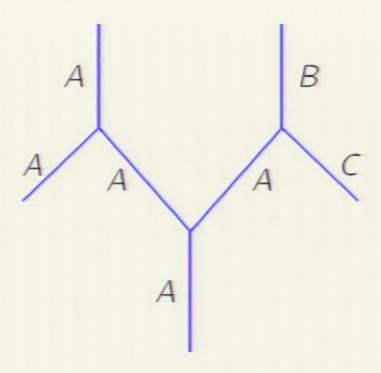
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Toy Models for Retrocausality

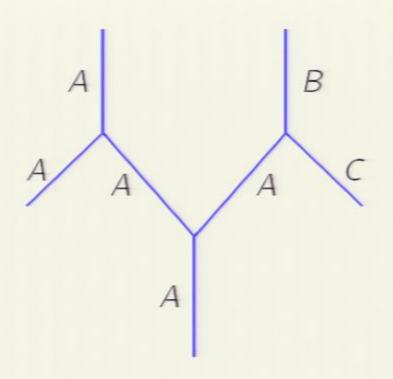
The Helsinki model

The 'dynamics'



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The 'dynamics'

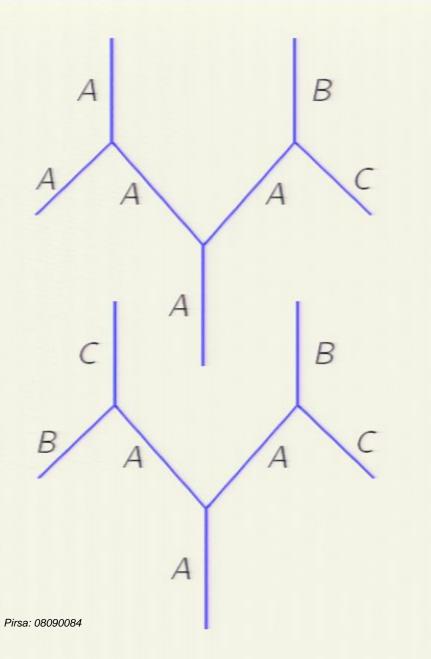


## Prohibited!

Repeated homogeneous nodes.

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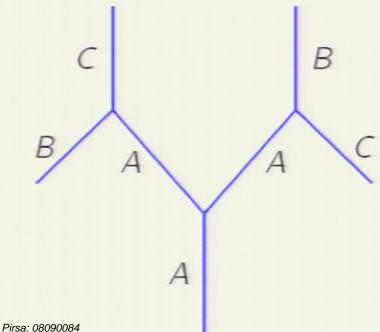
The 'dynamics'



### Toy Models for Retrocausality

The Helsinki model

The 'dynamics'



## Allowed

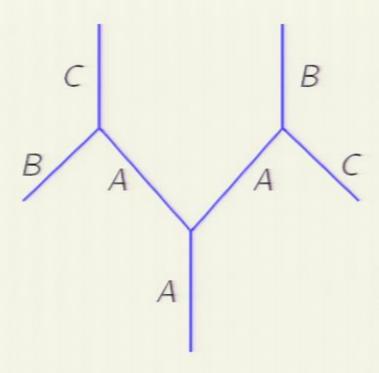
No repeated homogeneous nodes.

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#### Toy Models for Retrocausality

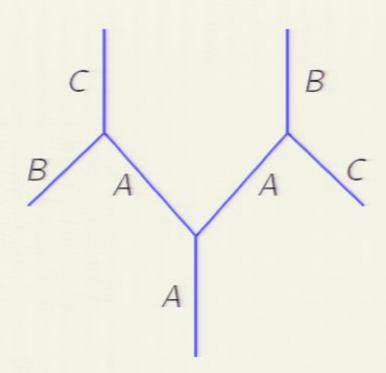
The Helsinki model

Adding 'preparation' and 'observation'



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-Adding 'preparation' and 'observation'

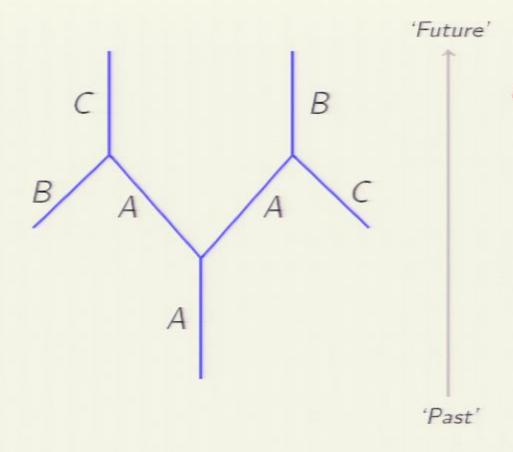


# 'Preparation' & 'measurement'

- The bare dynamics is 'up-down' symmetric . . .
- up-down as a temporal axis.

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-Adding 'preparation' and 'observation'

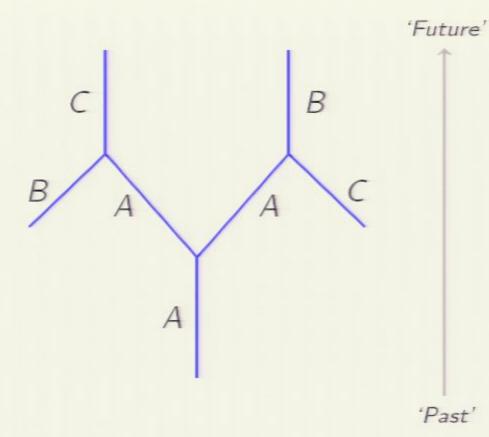


# 'Preparation' & 'measurement'

- The bare dynamics is 'up-down' symmetric . . .
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—Adding 'preparation' and 'observation'

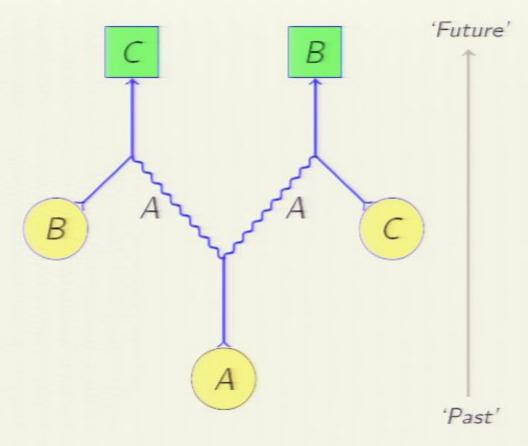


# 'Preparation' & 'measurement'

- The bare dynamics is 'up-down' symmetric . . .
- or time-symmetric if we treat up-down as a temporal axis.
- But now it is natural to imagine we can control the inputs and read off the outputs, like this . . .

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Adding 'preparation' and 'observation'



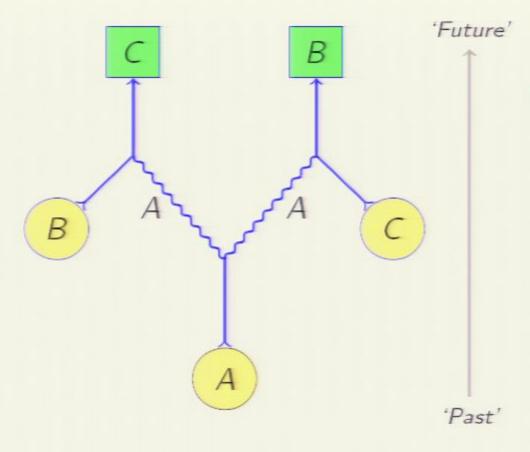
# 'Preparation' & 'measurement'

- The bare dynamics is 'up-down' symmetric . . .
- or time-symmetric if we treat up-down as a temporal axis.
- But now it is natural to imagine we can control the inputs and read off the outputs, like this . . .
- represent the hidden sectors.

  that we can't directly control or observe.

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Adding 'preparation' and 'observation'

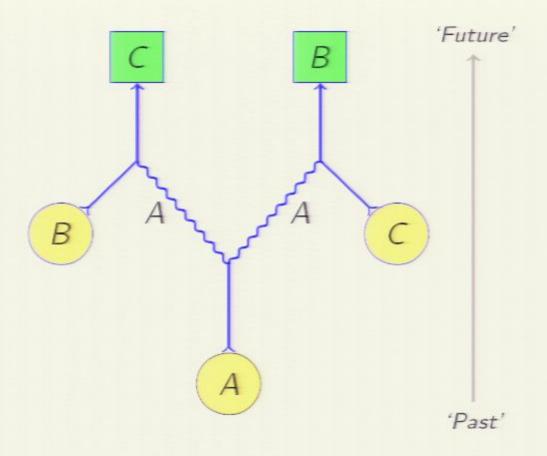


# 'Preparation' & 'measurement'

- The bare dynamics is 'up-down' symmetric . . .
- or time-symmetric if we treat up-down as a temporal axis.
- But now it is natural to imagine we can control the inputs and read off the outputs, like this . . .
- ... where the wavy lines now represent the 'hidden' sectors, that we can't directly control or observe.

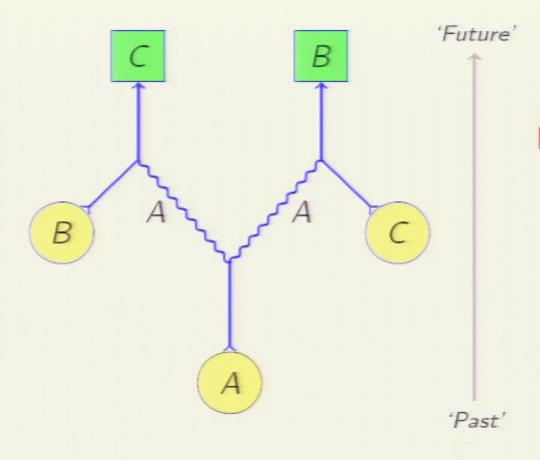
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Adding 'preparation' and 'observation'



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Adding 'preparation' and 'observation'

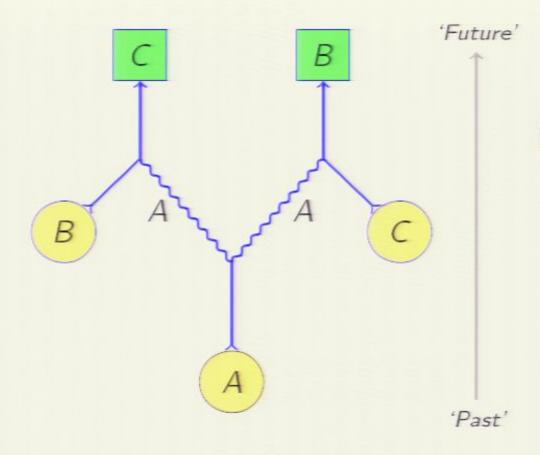


### Notes

- 1 The direction of causation is 'put in by hand', by our stipulation of what we can control.
  - The two pair annihilations provided imeasurements of the hidden sectors, in the sense that if we know one input and the output the dynamics uniquely determine the value of the other input

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Adding 'preparation' and 'observation'



#### Notes

- 1 The direction of causation is 'put in by hand', by our stipulation of what we can control.
- The two pair annihilations provide 'measurements' of the hidden sectors, in the sense that if we know one input and the output, the dynamics uniquely determine the value of the other input.

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Toy Models for Retrocausality

The Helsinki model

-Adding 'preparation' and 'observation'

### Next tasks

Explaining what retrocausality amounts to (when the direction of causation is only put in by hand)

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Adding 'preparation' and 'observation'

### Next tasks

Explaining what retrocausality amounts to (when the direction of causation is only put in by hand).

Showing that the Helsinki model requires retrocausality

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Adding 'preparation' and 'observation'

#### Next tasks

- Explaining what retrocausality amounts to (when the direction of causation is only put in by hand).
- 2 Showing that the Helsinki model requires retrocausality.

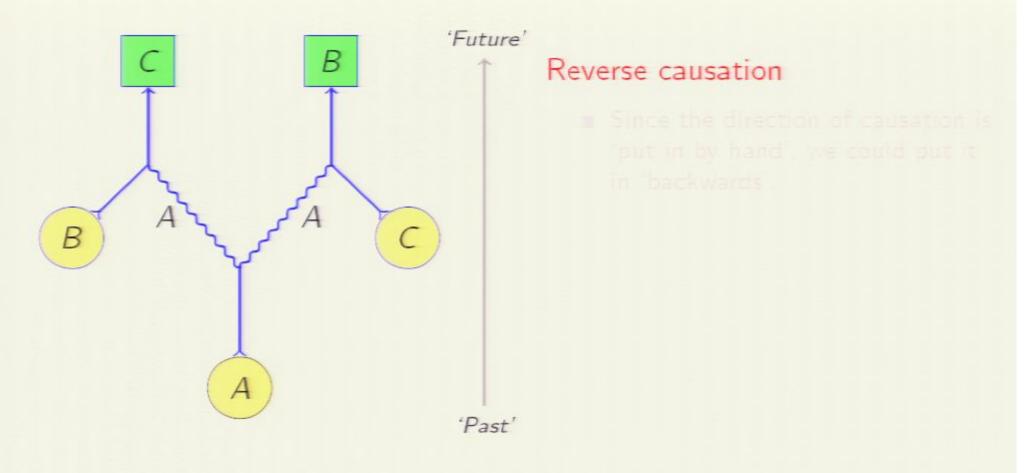
Pirsa: 08090084 Page 63/124

- 1 Taking the future seriously
- 2 The Helsinki model
- 3 Revealing the retrocausality
  - Reverse causation v. retrocausation
  - Admissible cases
  - The state table
  - Retrocausality revealed

4 Where next?

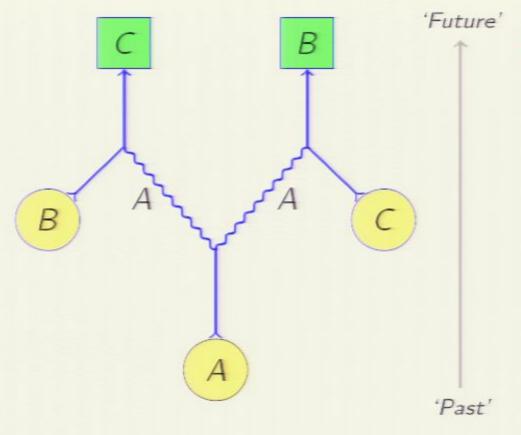
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Reverse causation v. retrocausation



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Reverse causation v. retrocausation

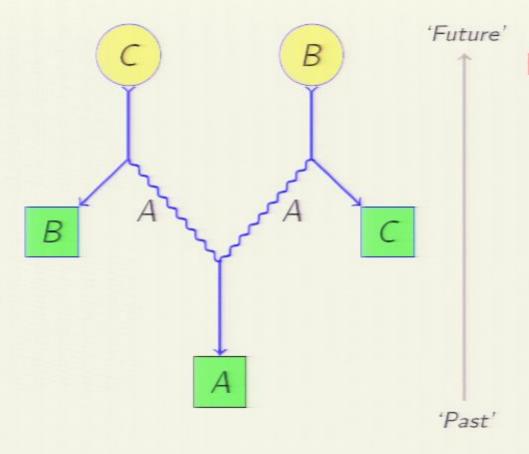


### Reverse causation

Since the direction of causation is 'put in by hand', we could put it in 'backwards'.

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Reverse causation v. retrocausation

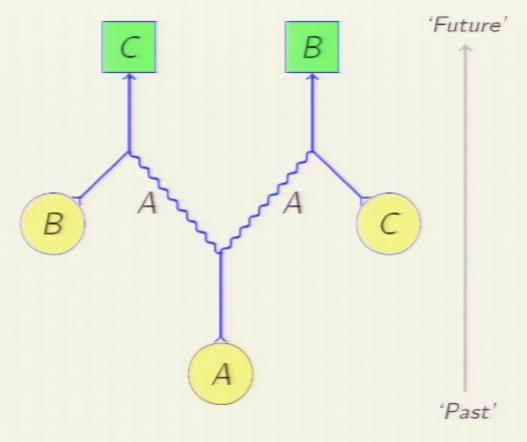


## Reverse causation

- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case

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Reverse causation v. retrocausation

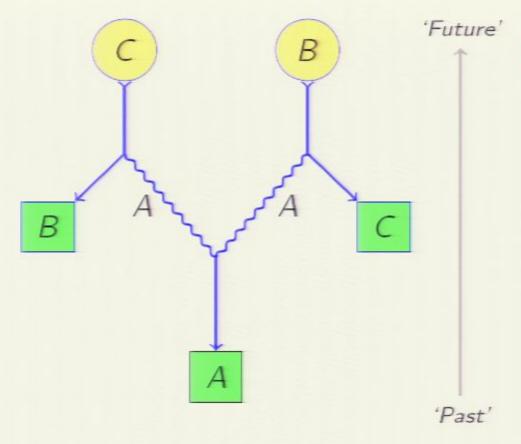


### Reverse causation

Since the direction of causation is 'put in by hand', we could put it in 'backwards'.

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-Reverse causation v. retrocausation



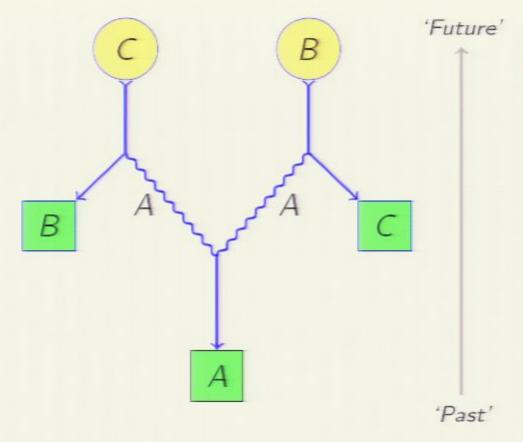
## Reverse causation

Since the direction of causation is 'put in by hand', we could put it in 'backwards'.

But this isn t the interesting case

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Reverse causation v. retrocausation

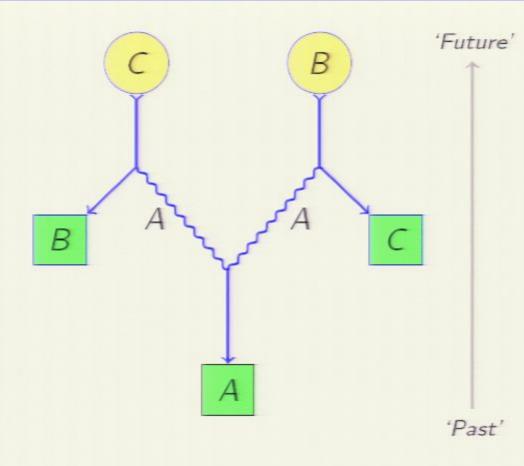


## Reverse causation

- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case

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Reverse causation v. retrocausation

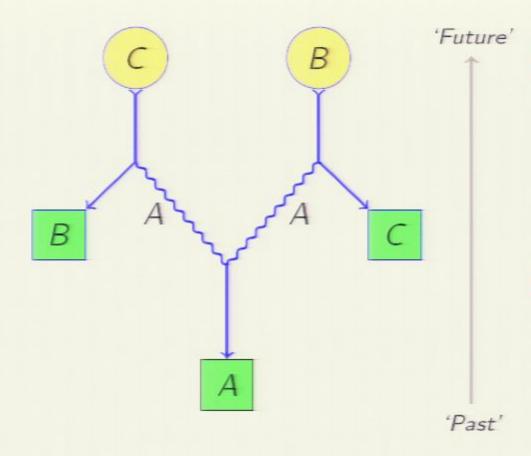


### Reverse causation

- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case.

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Reverse causation v. retrocausation



### Reverse causation

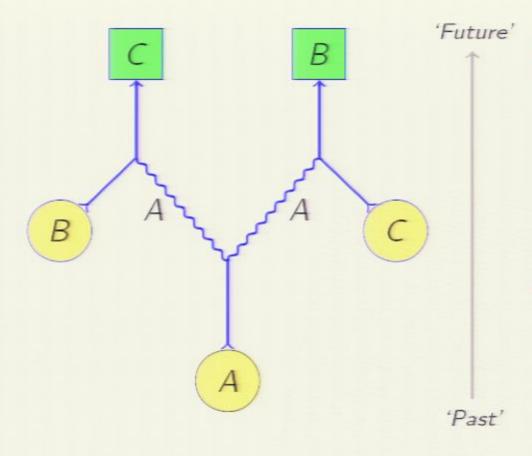
- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case.

### Retrocausation

 The interesting case is when ordinary interventions 'from the past'

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Reverse causation v. retrocausation



#### Reverse causation

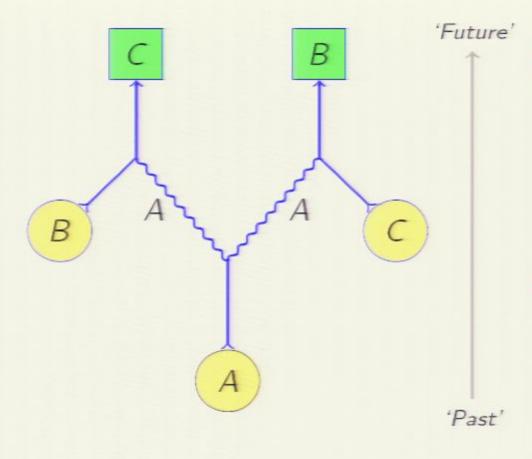
- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case.

#### Retrocausation

The interesting case is when ordinary interventions 'from the past' make a difference prior to

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- Reverse causation v. retrocausation



#### Reverse causation

- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case.

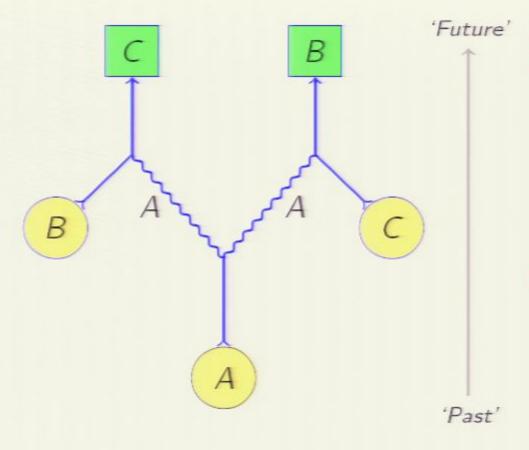
#### Retrocausation

- The interesting case is when ordinary interventions 'from the past' make a difference prior to the intervention ...
- measurement settings 8 and 0 affects the hidden state here.

  AA of the two particles.

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Reverse causation v. retrocausation



#### Reverse causation

- Since the direction of causation is 'put in by hand', we could put it in 'backwards'.
- But this isn't the interesting case.

#### Retrocausation

- The interesting case is when ordinary interventions 'from the past' make a difference prior to the intervention ...
- ... e.g., if the choice of the two 'measurement settings' B and C affects the 'hidden state' – here, \(\langle AA \rangle \) – of the two particles.

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Toy Models for Retrocausality

Revealing the retrocausality

-Reverse causation v. retrocausation

# Retrocausality in the Helsinki model

To find the retrocausality in the Helsinki model, let's first enumerate the admissible interactions

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- Reverse causation v. retrocausation

## Retrocausality in the Helsinki model

 To find the retrocausality in the Helsinki model, let's first enumerate the admissible interactions

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- Reverse causation v. retrocausation

## Retrocausality in the Helsinki model

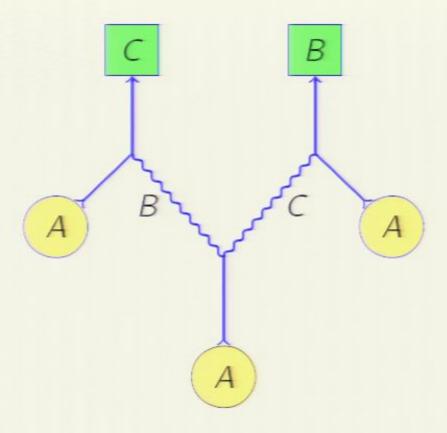
 To find the retrocausality in the Helsinki model, let's first enumerate the admissible interactions (ignoring some obvious symmetries).

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Toy Models for Retrocausality

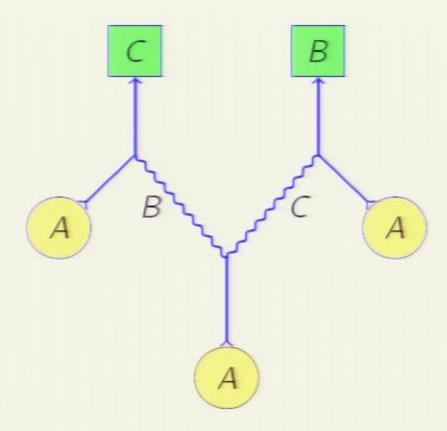
Revealing the retrocausality

—Admissible cases



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Admissible cases



Setting: AAA1

Hidden state:  $\langle BC \rangle$ 

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The state table

### Summary

- We have (up to symmetry) just four possible choices of measurement settings, and three possible hidden states.
- The admissible combinations are as follows:

|     | $\langle AA \rangle$ | $\langle BC \rangle$ | $\langle CB \rangle$ |
|-----|----------------------|----------------------|----------------------|
| AAA | X                    | 1                    | 1                    |
| AAB | X                    | 1                    | 1                    |
| BAB | 1                    | 1                    | 1                    |
| BAC | 1                    | 1                    | 1                    |

 $\blacksquare$  Thus the inputs AAA and AAB exclude the hidden state AA

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The state table

### Summary

- We have (up to symmetry) just four possible choices of measurement settings, and three possible hidden states.
- The admissible combinations are as follows:

|     | $\langle AA \rangle$ | $\langle BC \rangle$ | $\langle CB \rangle$ |
|-----|----------------------|----------------------|----------------------|
| AAA | X                    | 1                    | 1                    |
| AAB | X                    | 1                    | 1                    |
| BAB | 1                    | 1                    | 1                    |
| BAC | 1                    | 1                    | 1                    |

Thus the inputs AAA and AAB exclude the hidden state  $\langle AA \rangle$ .

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Toy Models for Retrocausality

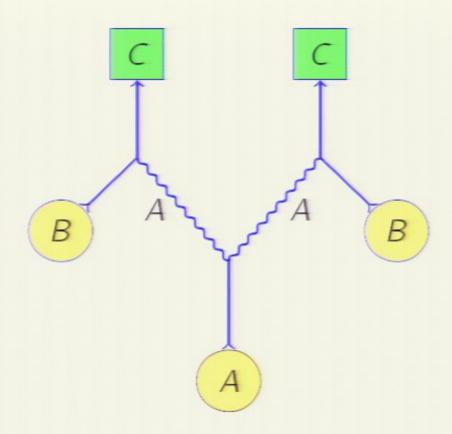
Revealing the retrocausality

Retrocausality revealed

Why this implies retrocausality

Pirsa: 08090084 Page 83/124

Retrocausality revealed



# Why this implies retrocausality

Consider this case.

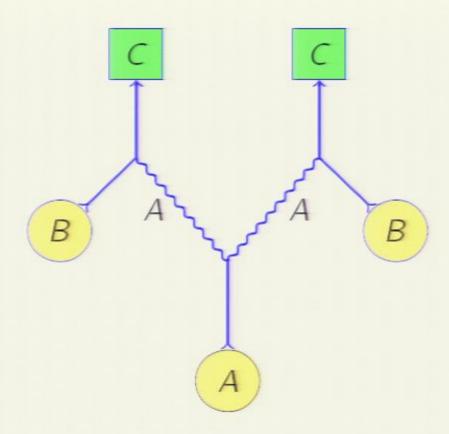
measurement settings were an A

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#### Toy Models for Retrocausality

-Revealing the retrocausality

Retrocausality revealed

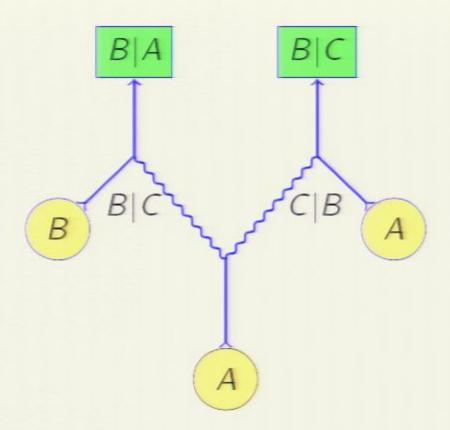


# Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

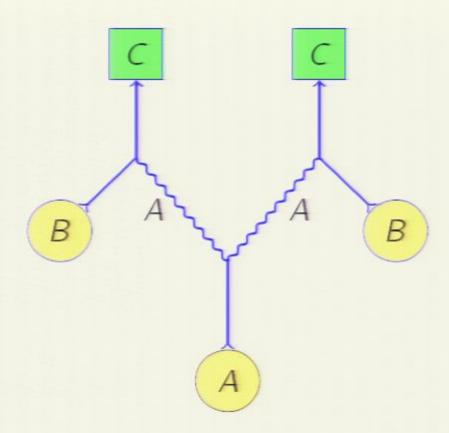


## Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

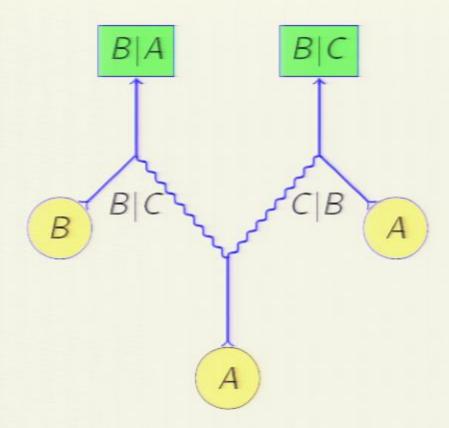


# Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

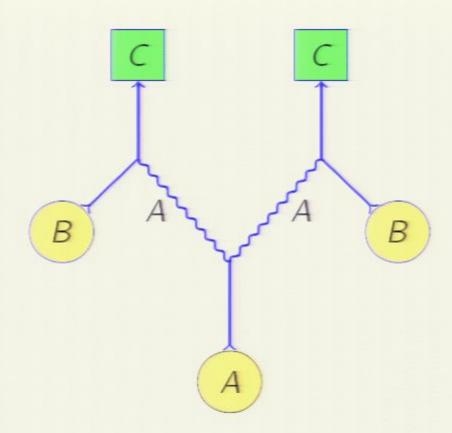


## Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

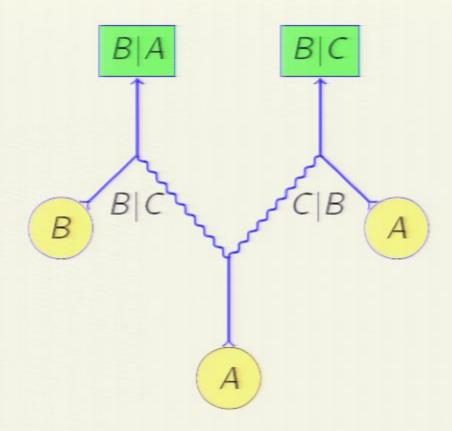


# Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

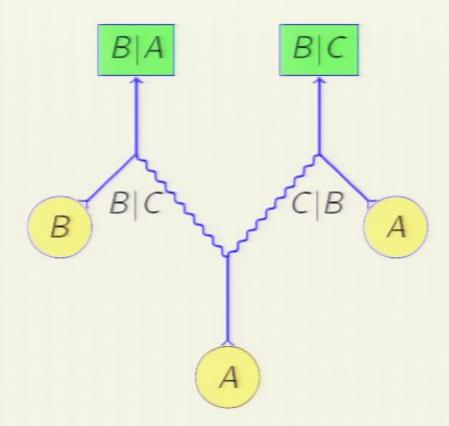


## Why this implies retrocausality

 Consider this case. If either of the measurement settings were an A, like this

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Retrocausality revealed

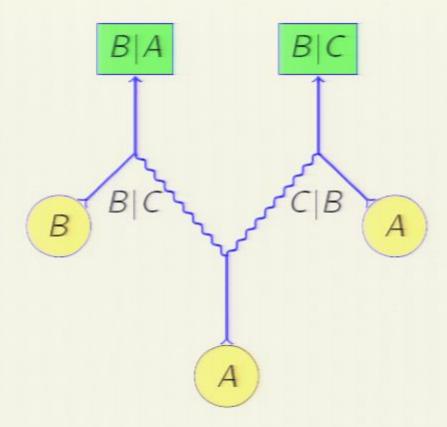


## Why this implies retrocausality

- Consider this case. If either of the measurement settings were an A, like this – the hidden state couldn't be \(\lambda A A \rangle).
- So the hidden state depends retrocausally on the fact that neither 'observer' chose A.
- Note that the output on the left also depends on the measurement setting on the right (and week versa) the left of the left

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Retrocausality revealed

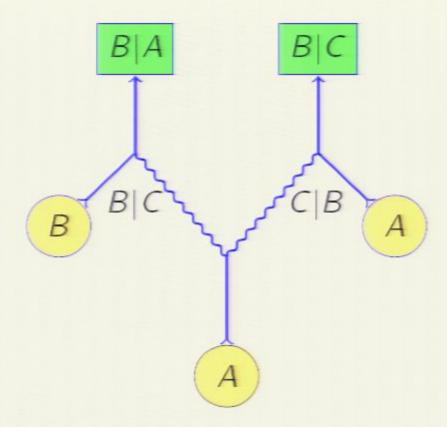


## Why this implies retrocausality

- Consider this case. If either of the measurement settings were an A, like this – the hidden state couldn't be \(\langle AA \rangle \).
- So the hidden state depends retrocausally on the fact that neither 'observer' chose A.
- Note that the output on the left also depends on the measurement setting on the right (and vice versa) –

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Retrocausality revealed



## Why this implies retrocausality

- Consider this case. If either of the measurement settings were an A, like this – the hidden state couldn't be \(\lambda AA \rangle\).
- So the hidden state depends retrocausally on the fact that neither 'observer' chose A
- Note that the output on the left also depends on the measurement setting on the right (and vice versa) – so we also have a kind of non-locality.

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- 1 Taking the future seriously
- 2 The Helsinki model
- 3 Revealing the retrocausality
- 4 Where next?
  - Consistency?
  - Causal loops?
  - Improving the model
  - The End

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Toy Models for Retrocausality

-Where next?

-Consistency?

#### Is the Helsinki model consistent?

Are there larger systems in which some choice of inputs allows no consistent assignment of outputs?

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-Consistency?

#### Is the Helsinki model consistent?

1 Are there larger systems in which some choice of inputs allows no consistent assignment of outputs?

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-Consistency?

#### Is the Helsinki model consistent?

- 1 Are there larger systems in which some choice of inputs allows no consistent assignment of outputs? (Answer: Probably not.)
- 2 Are there problems if we allow the output on one side to control the input on the other side

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-Consistency?

#### Is the Helsinki model consistent?

- 1 Are there larger systems in which some choice of inputs allows no consistent assignment of outputs? (Answer: Probably not.)
- 2 Are there problems if we allow the output on one side to control the input on the other side – as is possible in EPR/Bell experiments (and a recognised source of causal loops, in that case)?

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Toy Models for Retrocausality

-Where next?

-Causal loops?

# Causal loops

 Consider case in which output on the left controls input on the right.

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Toy Models for Retrocausality

-Where next?

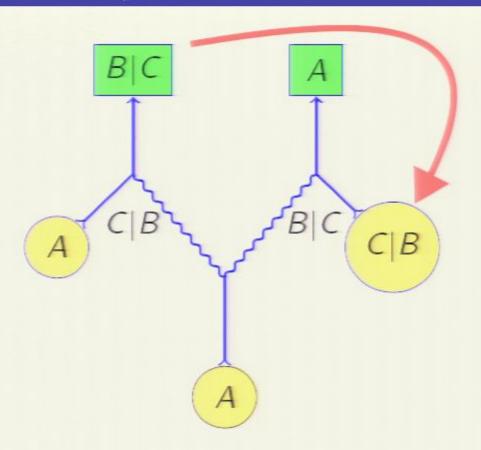
-Causal loops?

# Causal loops

Consider case in which output on the left controls input on the right.

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-Causal loops?

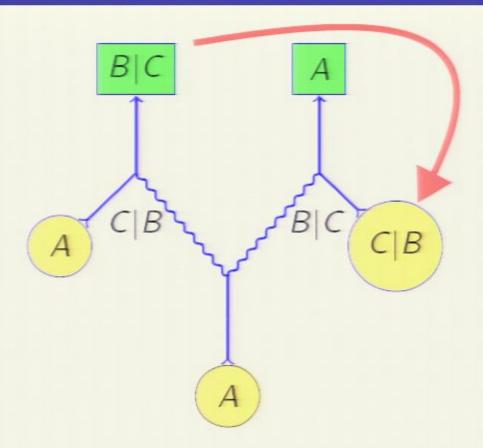


# Causal loops

- Consider case in which output on the left controls input on the right.
- No inconsistency in this case -

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-Causal loops?

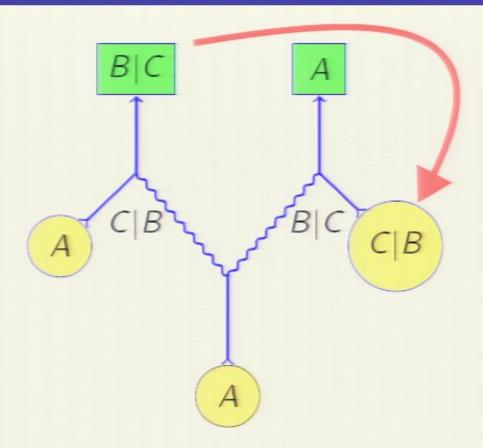


## Causal loops

- Consider case in which output on the left controls input on the right.
- No inconsistency in this case there are two self-consistent results –

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-Causal loops?

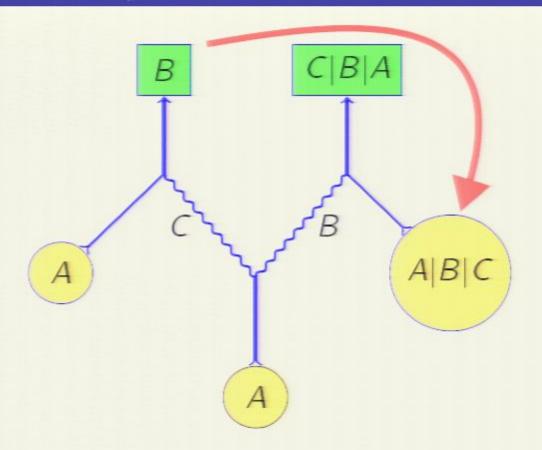


# Causal loops

- Consider case in which output on the left controls input on the right.
- No inconsistency in this case there are two self-consistent results – but perhaps in other cases of this kind?

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-Causal loops?

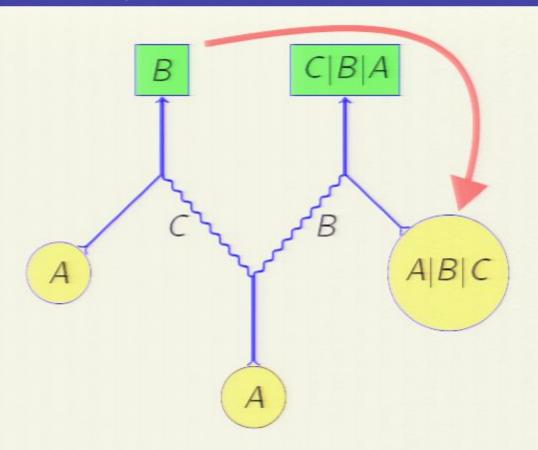


# Causal loops

Generalising the previous case consider the three possible ways in which a left output S can fix a right input.

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-Causal loops?

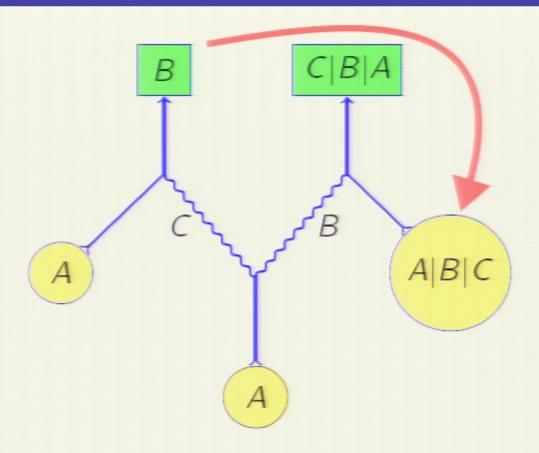


# Causal loops

- Generalising the previous case, consider the three possible ways in which a left output B can fix a right input.
- All three cases allow a consistent assignment of the

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-Causal loops?



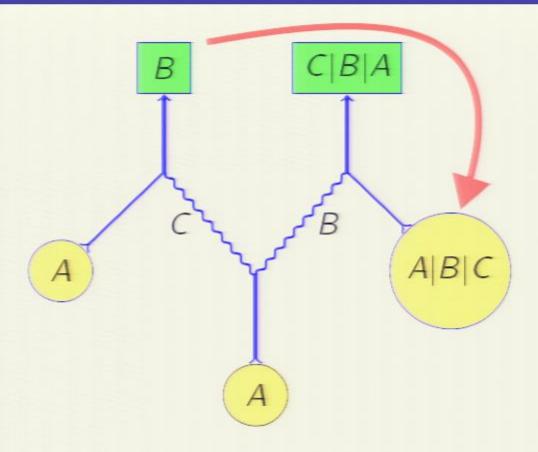
#### Causal loops

- Generalising the previous case, consider the three possible ways in which a left output B can fix a right input.
- All three cases allow a consistent assignment of the right output.

left inputs are the same. and set of left-output-to-right-input constraints allows at least one consistent assignment of hidden states and right output

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Causal loops?



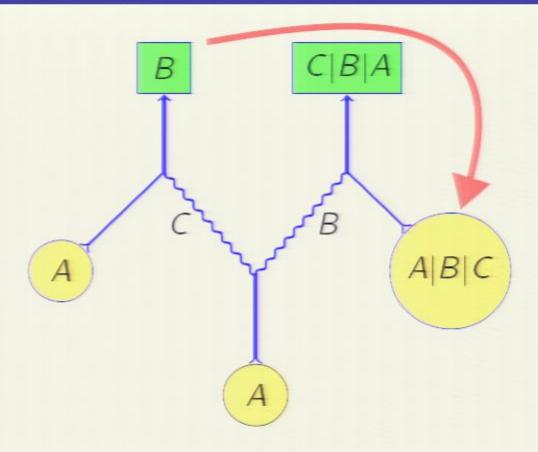
## Causal loops

- Generalising the previous case, consider the three possible ways in which a left output B can fix a right input.
- All three cases allow a consistent assignment of the right output.
- So when the initial input and left inputs are the same, any set of left-output-to-right-input constraints allows at least one consistent assignment of hidden states and right output

 i.e. no such constraint can shut the system down.

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-Causal loops?

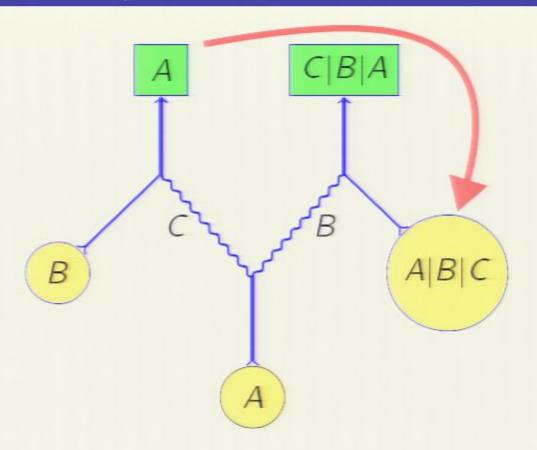


## Causal loops

- Generalising the previous case, consider the three possible ways in which a left output B can fix a right input.
- All three cases allow a consistent assignment of the right output.
- So when the initial input and left inputs are the same, any set of left-output-to-right-input constraints allows at least one consistent assignment of hidden states and right output i.e., no such constraint can shut the system down.

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-Causal loops?

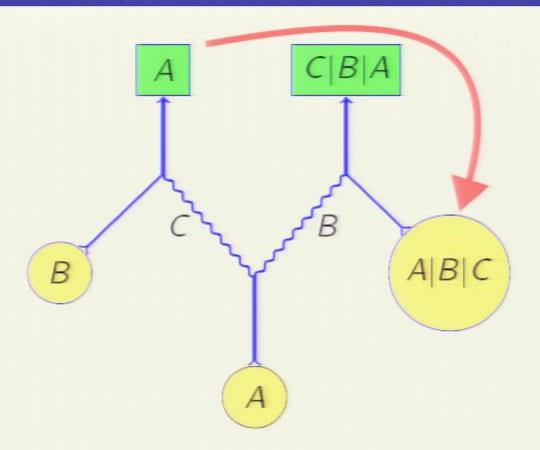


# Causal loops

This leaves the cases in which the initial and left inputs are

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-Causal loops?

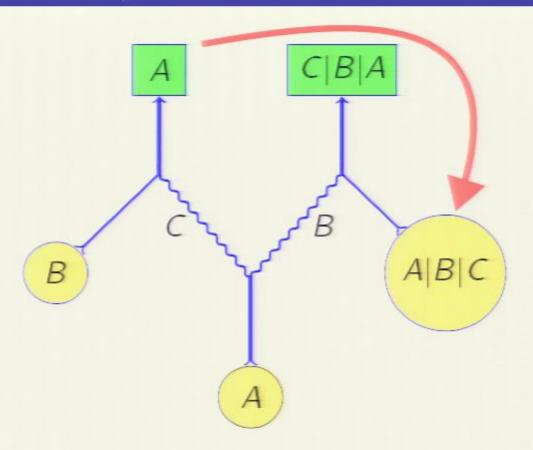


## Causal loops

- This leaves the cases in which the initial and left inputs are different.
- possible ways in which a left
  output A can fix a right input

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-Causal loops?



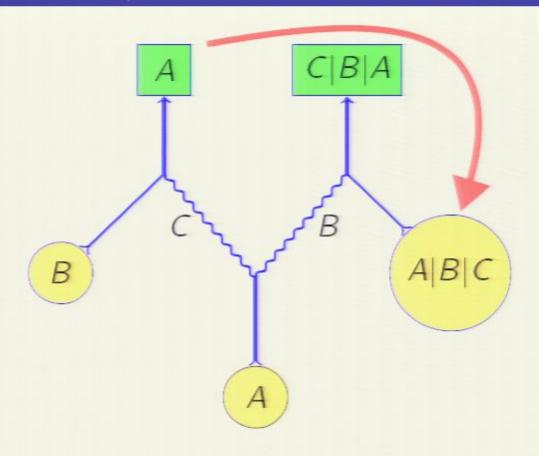
# Causal loops

- This leaves the cases in which the initial and left inputs are different.
- Here, consider (e.g.) the three possible ways in which a left output A can fix a right input.

Again all three allow a consistent right output.

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-Causal loops?



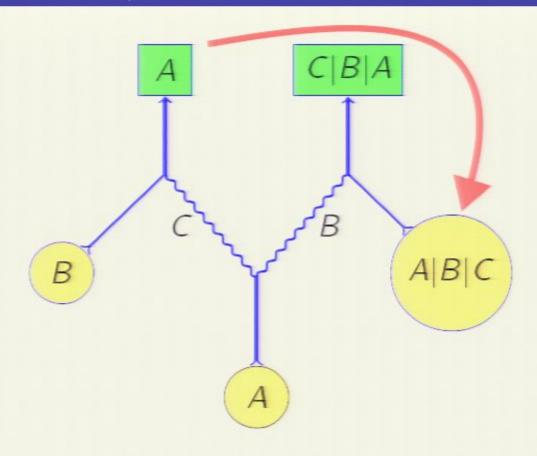
# Causal loops

- This leaves the cases in which the initial and left inputs are different.
- Here, consider (e.g.) the three possible ways in which a left output A can fix a right input.
- Again, all three allow a consistent right output.
- And again, any set of left-output-to-right-input constraints allows at least one consistent assignment of hidden states and right output

 again, no such constraint can shut the system down.

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-Causal loops?



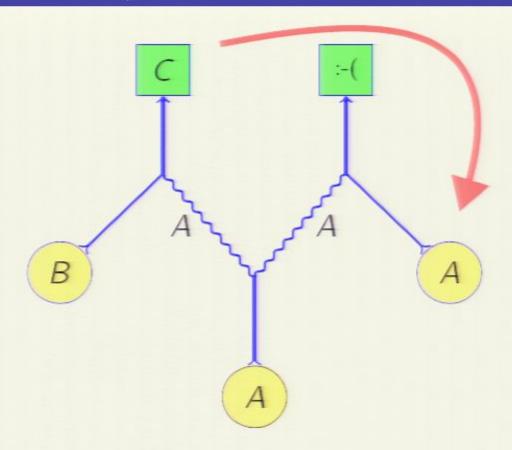
# Causal loops

- This leaves the cases in which the initial and left inputs are different.
- Here, consider (e.g.) the three possible ways in which a left output A can fix a right input.
- Again, all three allow a consistent right output.
- And again, any set of left-output-to-right-input constraints allows at least one consistent assignment of hidden states and right output

   again, no such constraint can shut the system down.

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-Causal loops?

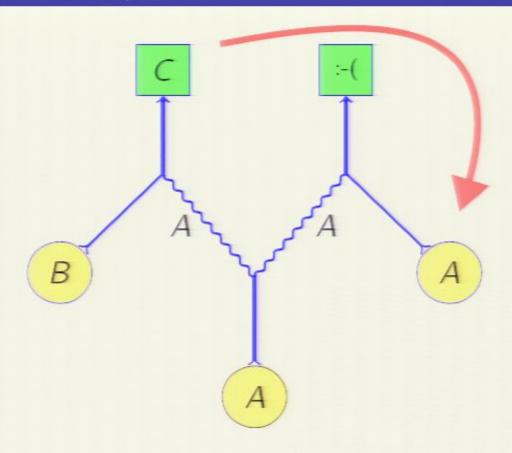


### But non-trivial!

of constraint does exclude a hidden state — AA — which would otherwise be permitted.

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-Causal loops?

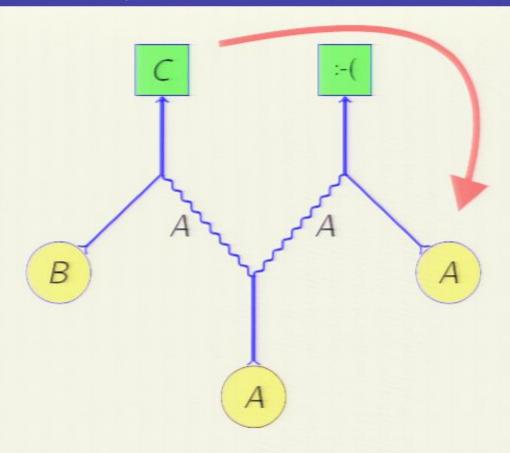


#### But non-trivial!

- Here's a case in which this kind of constraint does exclude a hidden state – (AA) – which would otherwise be permitted.
- enough to show how this kind of causal loop can impose new constraints, without leading to inconsistency.

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-Causal loops?



#### But non-trivial!

- Here's a case in which this kind of constraint does exclude a hidden state – (AA) – which would otherwise be permitted.
- So the Helsinki model is rich enough to show how this kind of causal loop can impose new constraints, without leading to inconsistency.

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Toy Models for Retrocausality

-Where next?

Improving the model

# Things it would be nice to do next

Add probabilities, and show that in virtue of the retrocausality they have some of the characteristics of QM amplitudes—

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-Improving the model

# Things it would be nice to do next

1 Add probabilities, and show that in virtue of the 'retrocausality', they have some of the characteristics of QM amplitudes –

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Improving the model

# Things it would be nice to do next

Add probabilities, and show that in virtue of the 'retrocausality', they have some of the characteristics of QM amplitudes — i.e., probabilities of results of measurements cannot generally be regarded as probabilities of pre-existing states, if those states have to be independent of the choice of future measurements.

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-Improving the model

# Things it would be nice to do next

- Add probabilities, and show that in virtue of the 'retrocausality', they have some of the characteristics of QM amplitudes – i.e., probabilities of results of measurements cannot generally be regarded as probabilities of pre-existing states, if those states have to be independent of the choice of future measurements.
- Hence develop the analogy between what we know in the Helsinki model if we don't know the measurement settings and the standard QM state function?

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-Improving the model

# Things it would be nice to do next

- Add probabilities, and show that in virtue of the 'retrocausality', they have some of the characteristics of QM amplitudes i.e., probabilities of results of measurements cannot generally be regarded as probabilities of pre-existing states, if those states have to be independent of the choice of future measurements.
- 2 Hence develop the analogy between what we know in the Helsinki model if we don't know the measurement settings and the standard QM state function?
- Hence connect the Helsinki model (or descendants) to Rob Spekkens epistemic toy models?

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-Improving the model

# Things it would be nice to do next

- Add probabilities, and show that in virtue of the 'retrocausality', they have some of the characteristics of QM amplitudes i.e., probabilities of results of measurements cannot generally be regarded as probabilities of pre-existing states, if those states have to be independent of the choice of future measurements.
- 2 Hence develop the analogy between what we know in the Helsinki model if we don't know the measurement settings and the standard QM state function?
- 3 Hence connect the Helsinki model (or descendants) to Rob Spekkens' 'epistemic' toy models?

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Toy Models for Retrocausality

-Where next?

The End

# The End

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