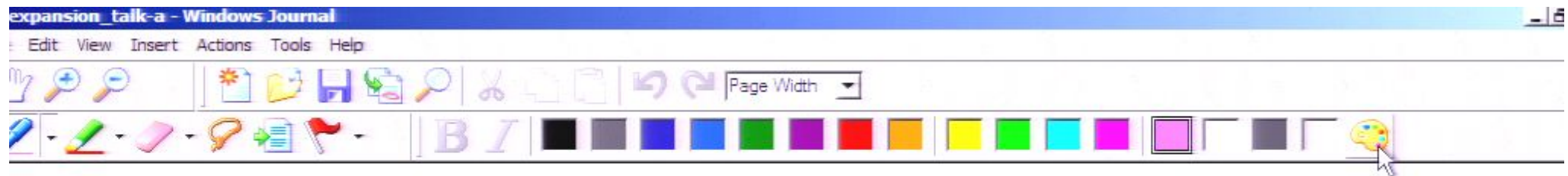


Title: Graph expansions and simulating one-way quantum computation

Date: Apr 30, 2008 02:50 PM

URL: <http://pirsa.org/08040052>

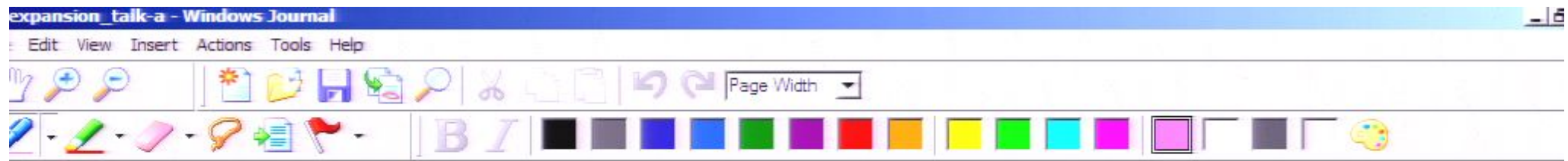
Abstract: It is well-known that if a graph  $G_1$  can be obtained from another graph  $G_2$  by removing a degree-2 vertex and combing its two neighbors, the graph state  $|G_1\rangle$  can be obtained from  $|G_2\rangle$  through LOCC. In this talk, I will describe how to construct a graph  $G'$  from a given graph  $G$  so that (a) The maximum degree of  $G'$ ,  $\Delta(G')$ , is no more than 3. (b)  $G$  can be obtained from  $G'$  by a sequence of contraction operations described above. (c) The treewidth of  $G'$ ,  $\text{tw}(G')$ , is no more than  $\text{tw}(G)+1$ . (d) The construction takes  $\exp(O(\text{tw}(G)))$  time. Those properties imply that a one-way quantum computation on the graph state  $|G\rangle$  can be simulated by a randomized algorithm in time  $\exp(O(\text{tw}(G)))$ . Previously, it was known that such a computation can be simulated in time  $\exp(O(\text{tw}(G) \Delta(G)))$  [Markov and Shi, to appear in SICOMP], which is substantially more expensive than our bound when  $\Delta(G)$  is large. Joint work with Igor Markov, based on arXiv:0707.3622.



# Graph expansions and simulating one-way quantum computation

Yaoyun Shi  
University of Michigan

Joint work with Igor Markov  
based on arXiv:0707.3622



## Motivation

---

Is quantum computation indeed much more powerful than classical computation?

An incrementalist's program: identify largest sets of efficiently simulatable quantum computation.

- If the answer is “No”, we are on the right track;
- Otherwise, we know better any non-simulatable quantum computation must be like.

Simulatable classes of quantum computation

- Quantum circuits using a restricted gate set [Gottesman and Knill '98;...]
- Reduction to the Fisher-Kasteleyn-Temperley algorithm [Valiant '02, Terhal and DiVincenzo '02;



computation.

- If the answer is “No”, we are on the right track;
- Otherwise, we know better any non-simulatable quantum computation must be like.

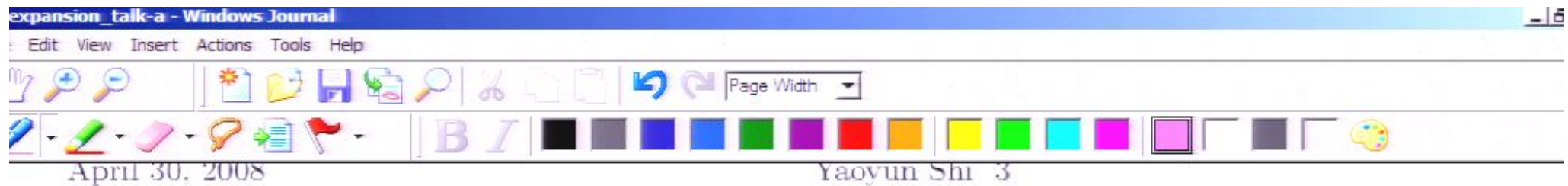
Simulatable classes of quantum computation

- Quantum circuits using a restricted gate set [Gottesman and Knill '98;...]
- Reduction to the Fisher-Kasteleyn-Temperley algorithm [Valiant '02, Terhal and DiVincenzo '02; Bravyi and Raussendorf '06;...]

---

April 30, 2008

Yaoyun Shi 2



## Quantum circuit

---

A quantum circuit describes a quantum algorithm

- Start with a fixed initial state in the computational basis.
- Sequentially apply quantum gates, some on multiple qubits.
- Measure on the computational basis.



## Quantum circuit

---

A quantum circuit describes a quantum algorithm

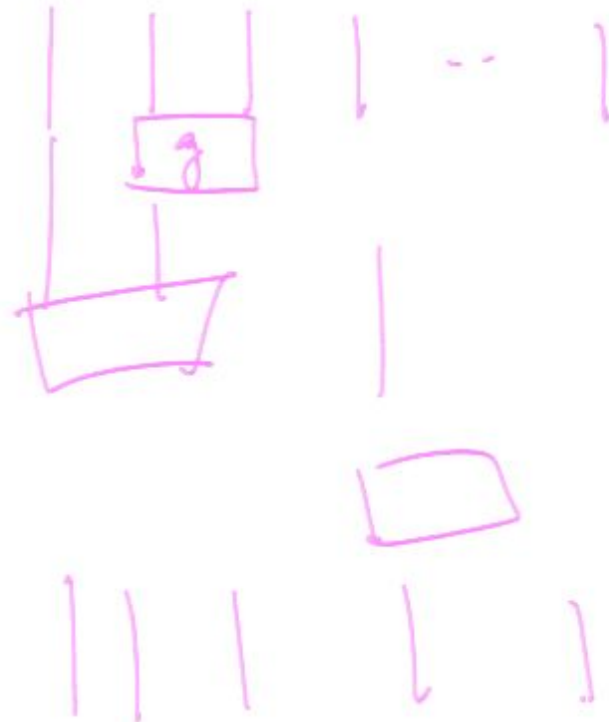
- Start with a fixed initial state in the computational basis.
- Sequentially apply quantum gates, some on multiple qubits.
- Measure on the computational basis.



## Quantum circuit

A quantum circuit describes a quantum algorithm

- Start with a fixed initial state in the computational basis.
- Sequentially apply quantum gates, some on multiple qubits.
- Measure on the computational basis.





April 30, 2008

Yaoyun Shi 4

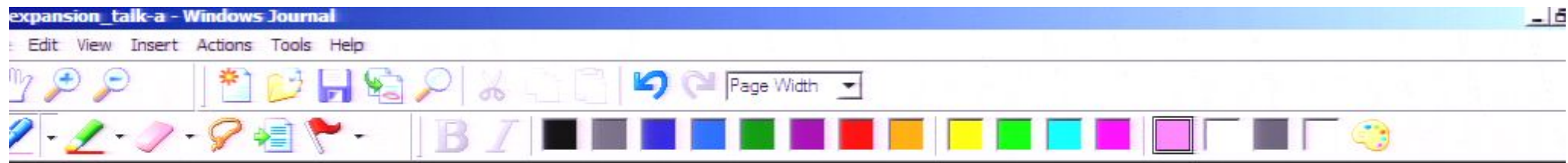
## One-way quantum computation [Raussendorf and Briegel '01]

One-way quantum computation

1. Start with a fixed state  $|S\rangle$ .
2. Adaptively apply *single* qubit measurements.





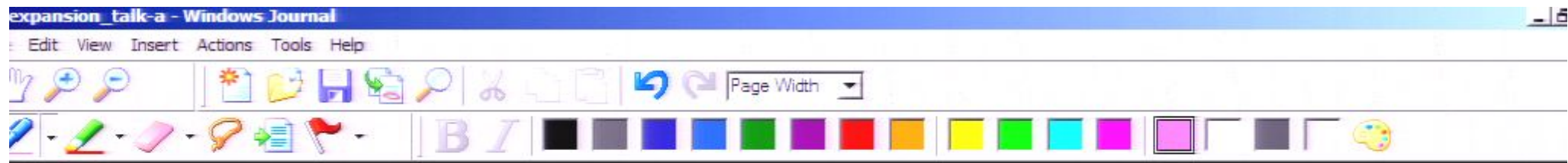


## One-way quantum computation [Raussendorf and Briegel '01]

One-way quantum computation

1. Start with a fixed state  $|S\rangle$ .
2. Adaptively apply *single* qubit measurements.





## One-way quantum computation [Raussendorf and Briegel '01]

One-way quantum computation

1. Start with a fixed state  $|S\rangle$ .
2. Adaptively apply *single* qubit measurements.





April 30, 2008

Yaoyun Shi 5

## Graph states [Briegel and Raussendorf '01]

---

Given an undirected simple graph  $G = \langle V, E \rangle$ ,  
the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices  
in  $V'$ .



## Graph states [Briegel and Raussendorf '01]

---

Given an undirected simple graph  $G = \langle V, E \rangle$ ,  
the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices  
in  $V'$ .

Theorem [Raussendorf and Briegel '01] For any  
quantum circuit, there exists a one-way  
quantum computation on the grid state of

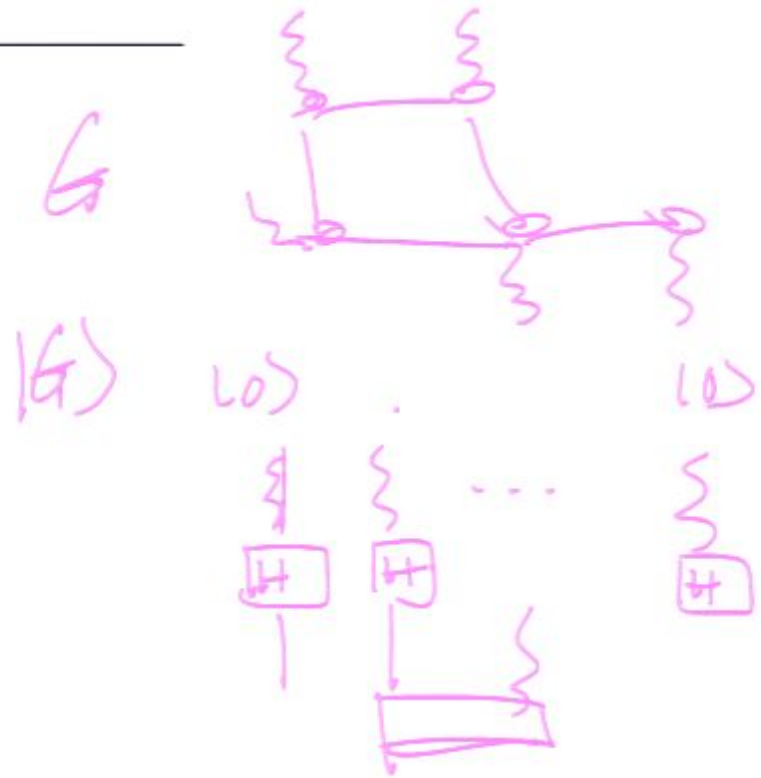


Graph states [Briegel and Raussendorf '01]

Given an undirected simple graph  $G = \langle V, E \rangle$ , the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices in  $V'$ .



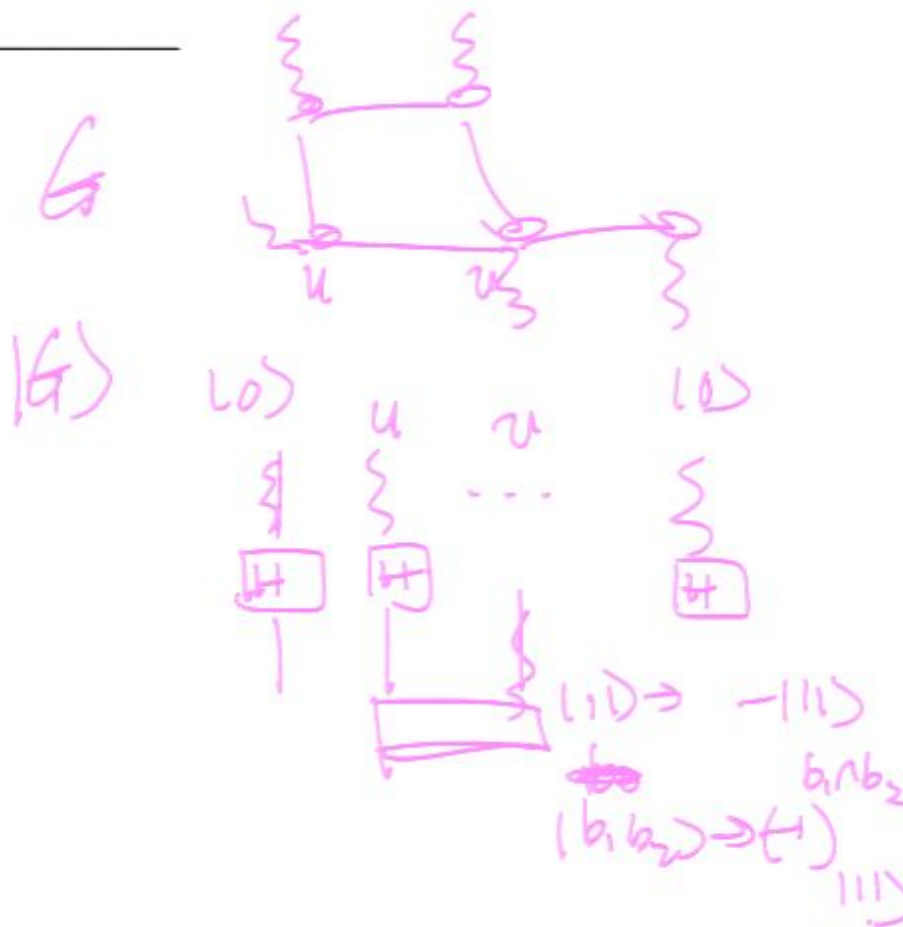
Theorem [Raussendorf and Briegel '01] For any quantum circuit, there exists a one-way quantum computation on the grid state of about the same size that outputs the same final

Graph states [Briegel and Raussendorf '01]

Given an undirected simple graph  $G = \langle V, E \rangle$ , the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices in  $V'$ .



Theorem [Raussendorf and Briegel '01] For any quantum circuit, there exists a one-way quantum computation on the grid state of about the same size that outputs the same final

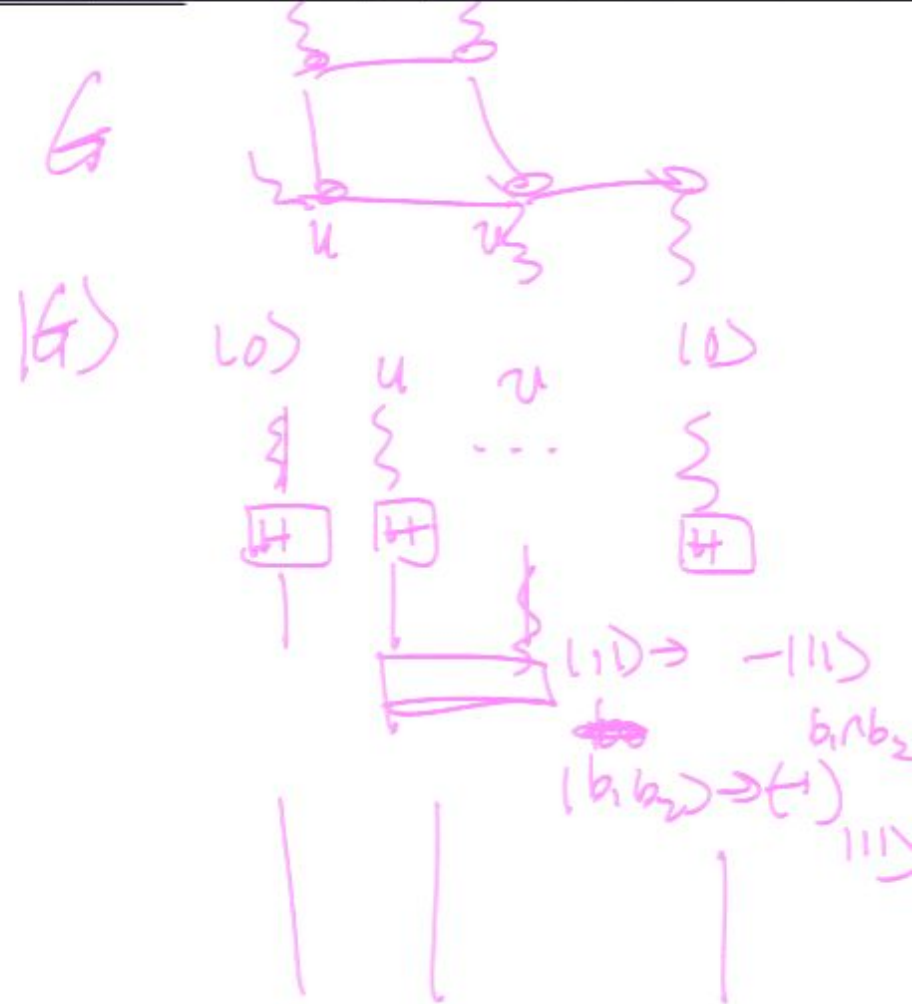


Given an undirected simple graph  $G = \langle V, E \rangle$ , the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices in  $V'$ .

Theorem [Raussendorf and Briegel '01] For any quantum circuit, there exists a one-way quantum computation on the grid state of about the same size that outputs the same final state.



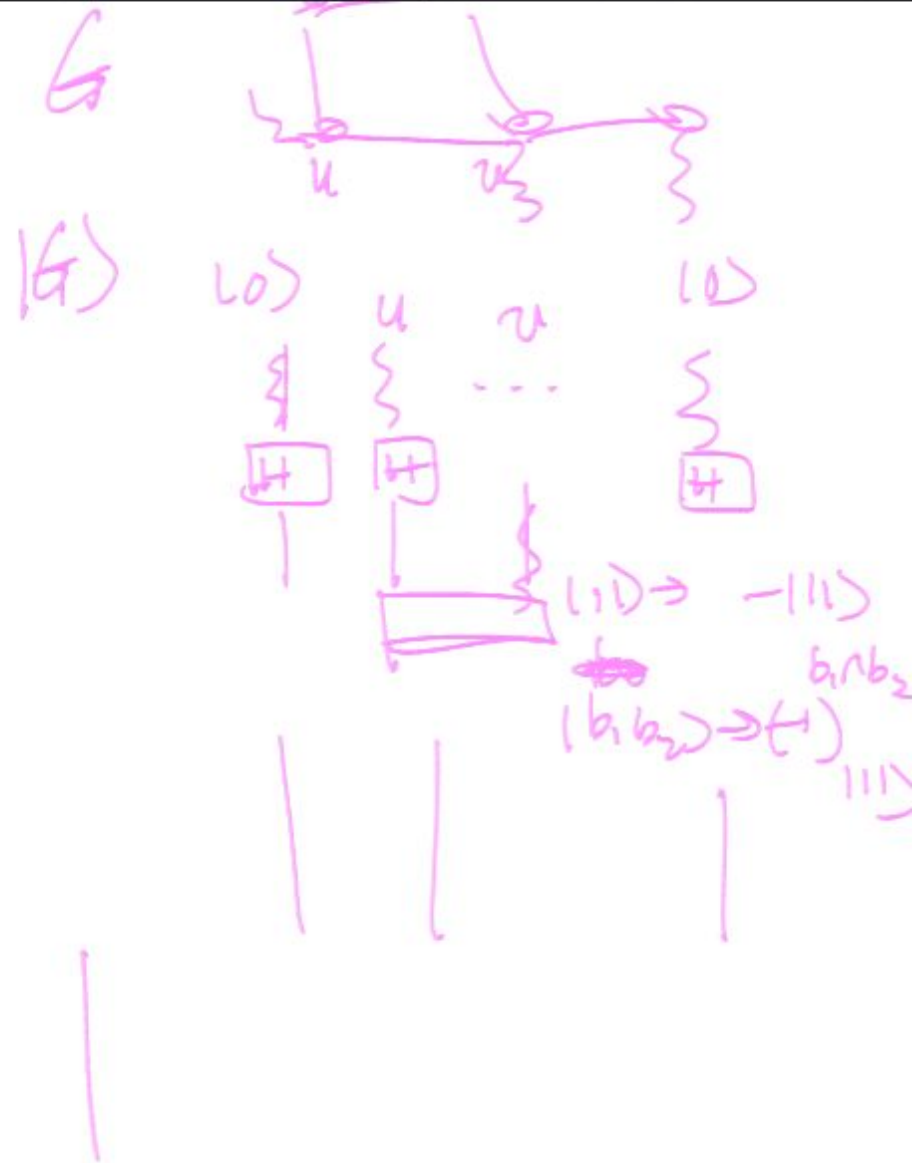


Given an undirected simple graph  $G = \langle V, E \rangle$ ,  
 the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices  
 in  $V'$ .

Theorem [Raussendorf and Briegel '01] For any  
 quantum circuit, there exists a one-way  
 quantum computation on the grid state of  
 about the same size that outputs the same final  
 state.





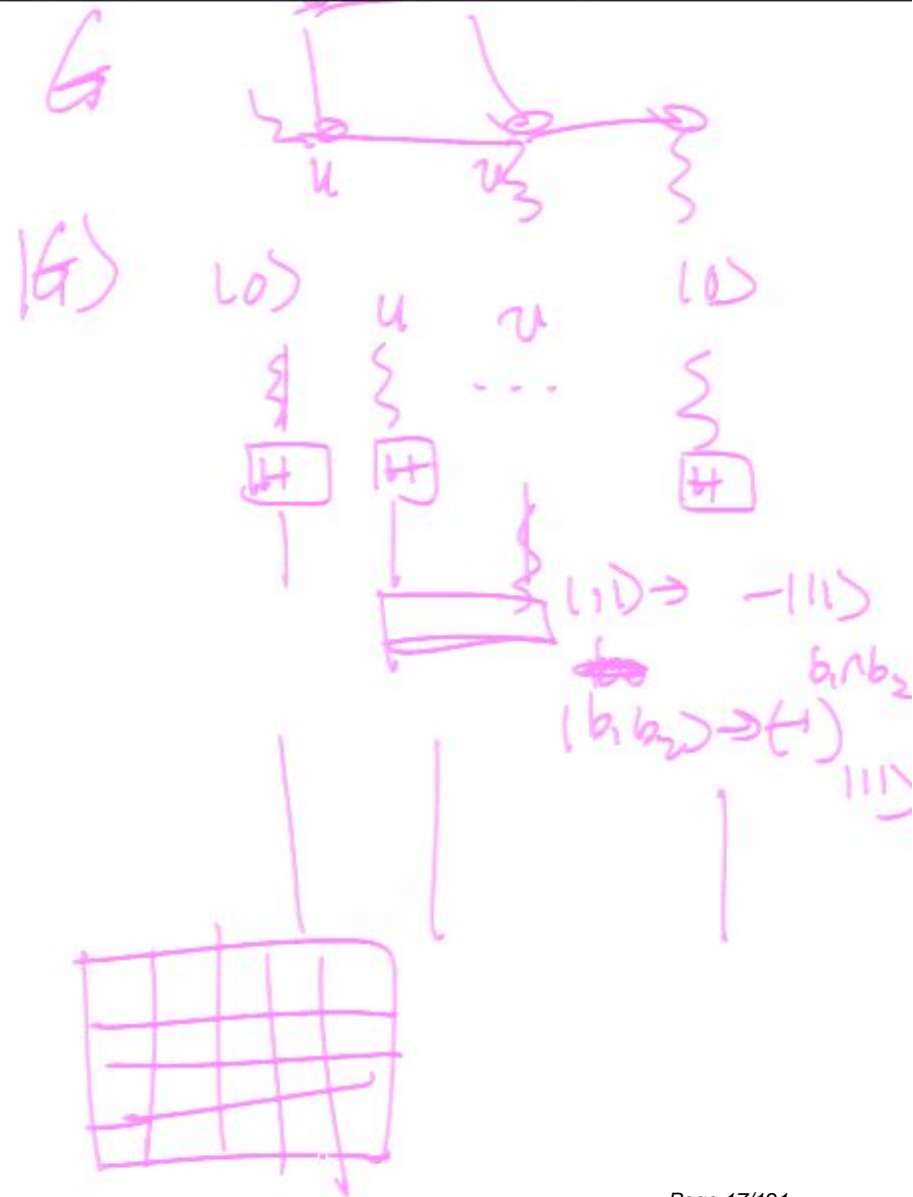


Given an undirected simple graph  $G = \langle V, E \rangle$ , the graph state  $|G\rangle$  is

$$|G\rangle := \frac{1}{2^{|V|/2}} \sum_{V' \subseteq V} (-1)^{|E(V')|} |V'\rangle,$$

where  $E(V') \subseteq E$  are edges connecting vertices in  $V'$ .

Theorem [Raussendorf and Briegel '01] For any quantum circuit, there exists a one-way quantum computation on the grid state of about the same size that outputs the same final state.



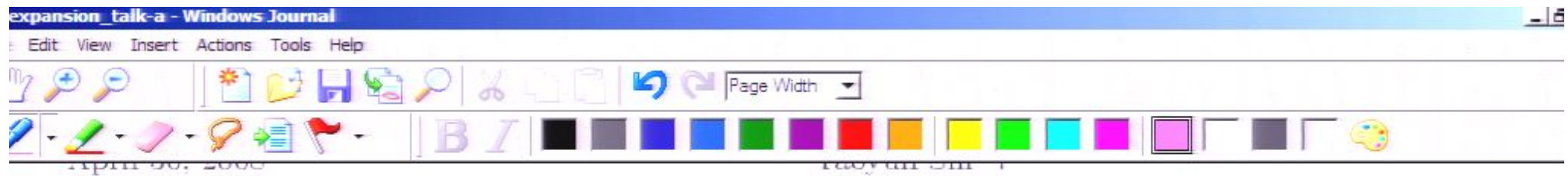


## Which states are universal?

---

Definition. Let  $|S_n\rangle$ ,  $n = 0, 1, \dots$ , be a (family of)  $n$ -qubit quantum state. We say that  $|S_n\rangle$  is *simulatable* if if for any one-way quantum computation on  $|S_n\rangle$ , there exists a  $poly(n)$  time randomized algorithm that outputs an identical distribution of the measurement outcomes.

Main Theorem (Informally): If a graph  $G$  is close to a tree then  $|G\rangle$  is simulatable.



## Tensor and tensor network

---

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

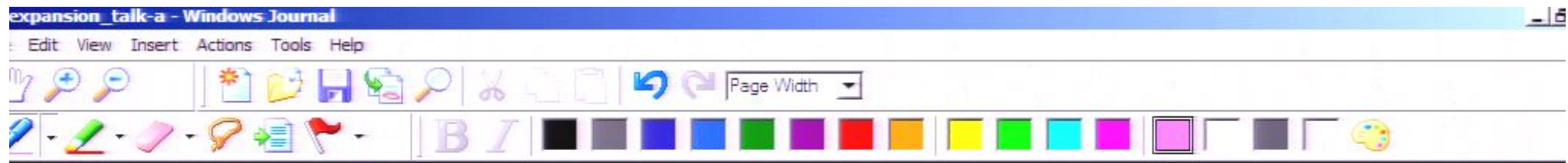
is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and  $h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor  $f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$



## Tensor and tensor network

---

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

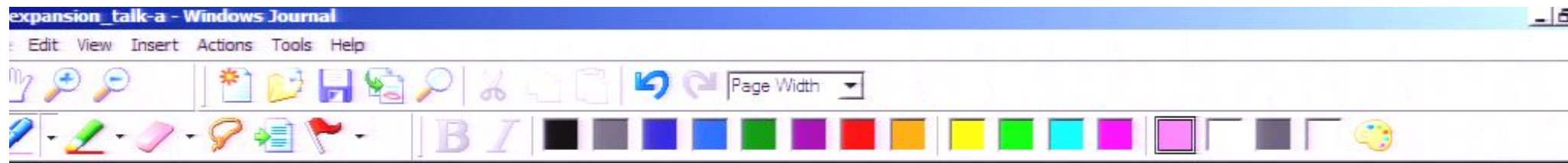
is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and  $h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor  $f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$



## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.



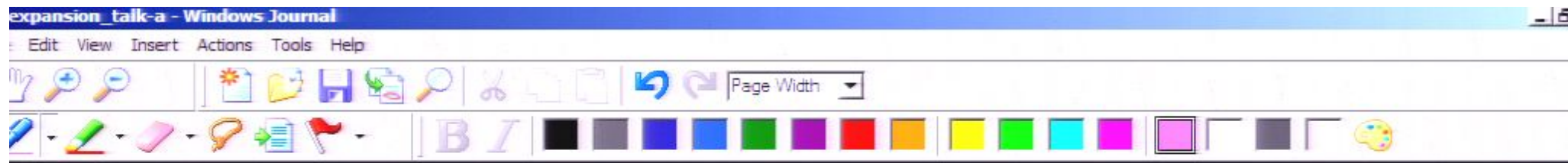
Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and

$h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor

$f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$



## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and  $h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor  $f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$



## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

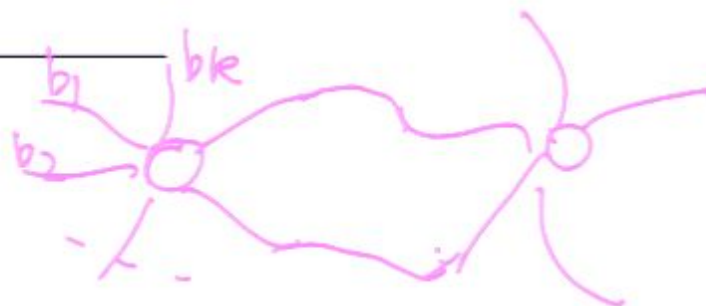
Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and

$h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor

$f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$





## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

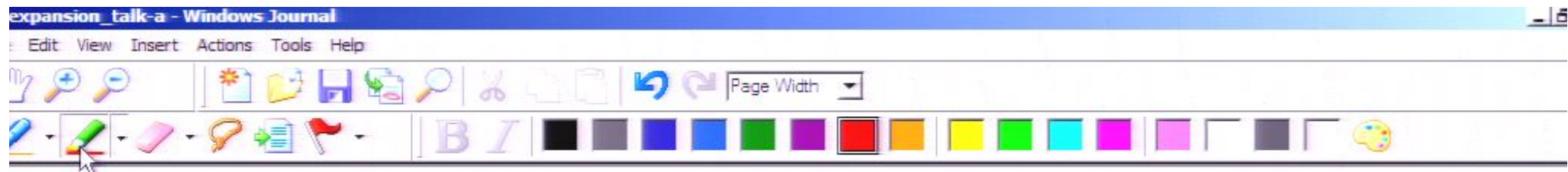
Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and  $h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor  $f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$







## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

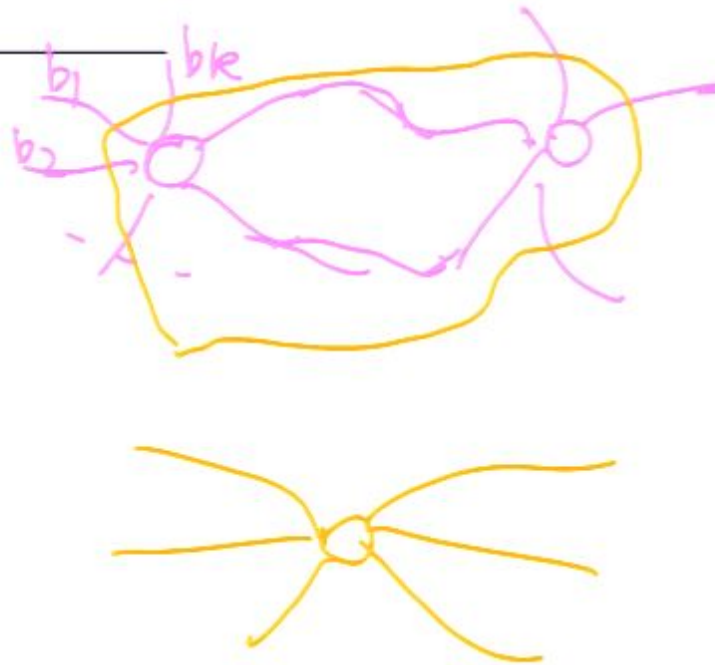
is a  $m^k$ -dimensional array of complex numbers.

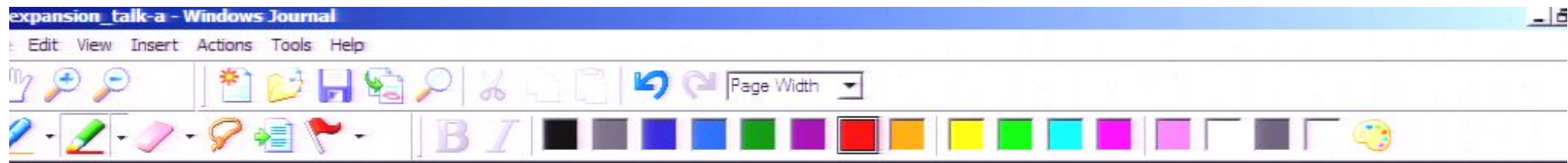
Variants include *Matrix Product States* and *Projected Entangled Paired States*.

Tensor contraction: generalizes matrix multiplication.

Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and  $h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor  $f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$





## Tensor and tensor network

A rank- $k$  tensor in an  $m$ -dimension space

$$g = [g_{i_1, \dots, i_k}]_{1 \leq i_1, \dots, i_k \leq m}$$

is a  $m^k$ -dimensional array of complex numbers.

Variants include *Matrix Product States* and *Projected Entangled Paired States*.

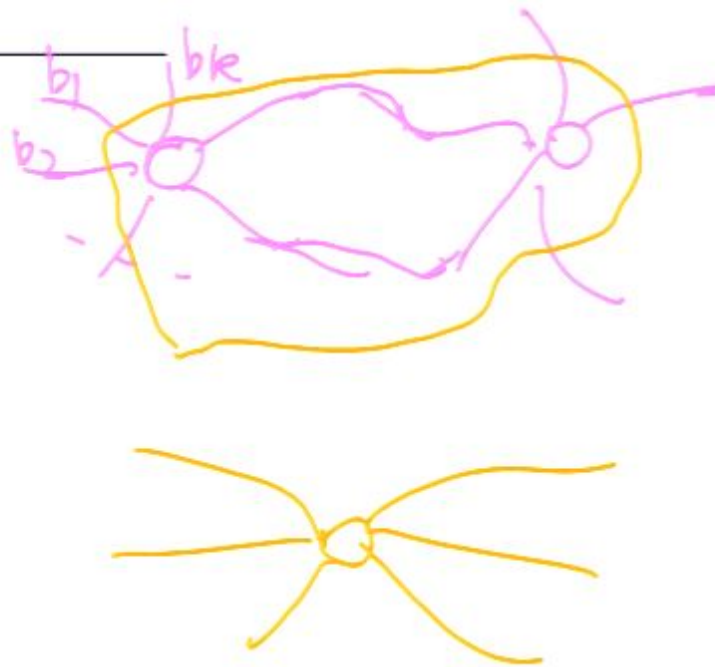
Tensor contraction: generalizes matrix multiplication.

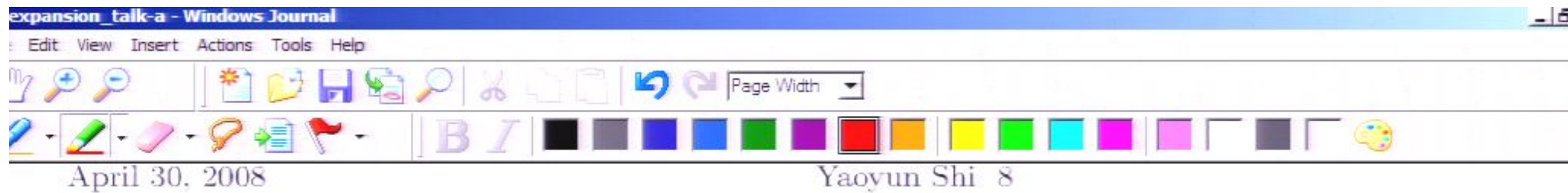
Contracting  $g = [g_{i_1, \dots, i_s, u_1, \dots, u_k}]$  and

$h = [h_{i_1, \dots, i_s, v_1, \dots, v_\ell}]$  gives a rank- $k - \ell$  tensor

$f = [f_{u_1, \dots, u_k, v_1, \dots, v_\ell}]$ , where

$$f_{u_1, \dots, u_k, v_1, \dots, v_\ell} = \sum_{i_1, \dots, i_s} g_{i_1, \dots, i_s, u_1, \dots, u_k} \cdot h_{i_1, \dots, i_s, v_1, \dots, v_\ell}$$



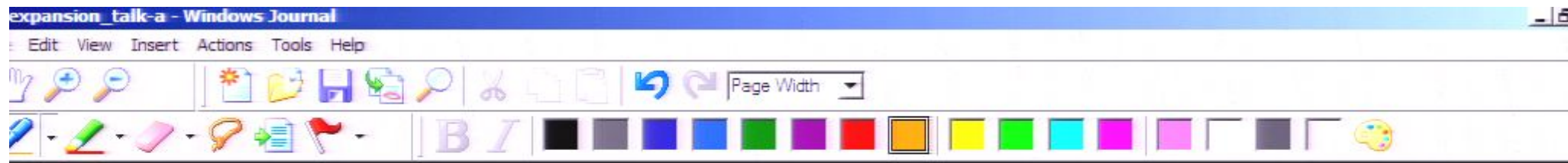


## Simulation through tensor contraction [Vidal '03; Verstraete et al. '04, Markov and Shi '05]

---

Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  
 $T \exp(O(\Delta(\pi)))$ , where



## Simulation through tensor contraction [Vidal '03; Verstraete et al. '04, Markov and Shi '05]

---

Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  
 $T \exp(O(\Delta(\pi)))$ , where  
 $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .





## Simulation through tensor contraction [Vidal '03; Verstraete et al. '04, Markov and Shi '05]

Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  
 $T \exp(O(\Delta(\pi)))$ , where  
 $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .





## Simulation through tensor contraction [Vidal '03; Verstraete et al. '04, Markov and Shi '05]

Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .

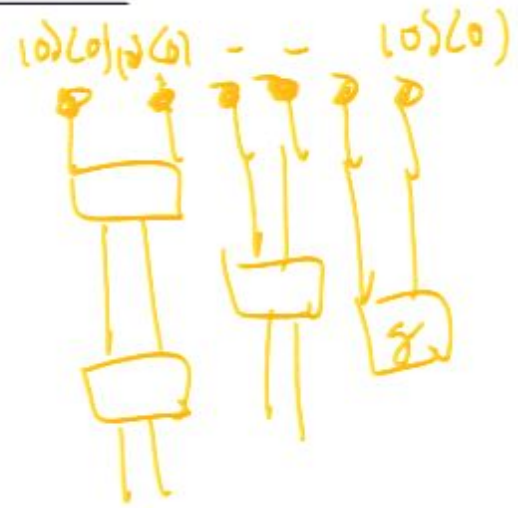




## Simulation through tensor contraction [Vidal '03; Verstraete et al. '04, Markov and Shi '05]

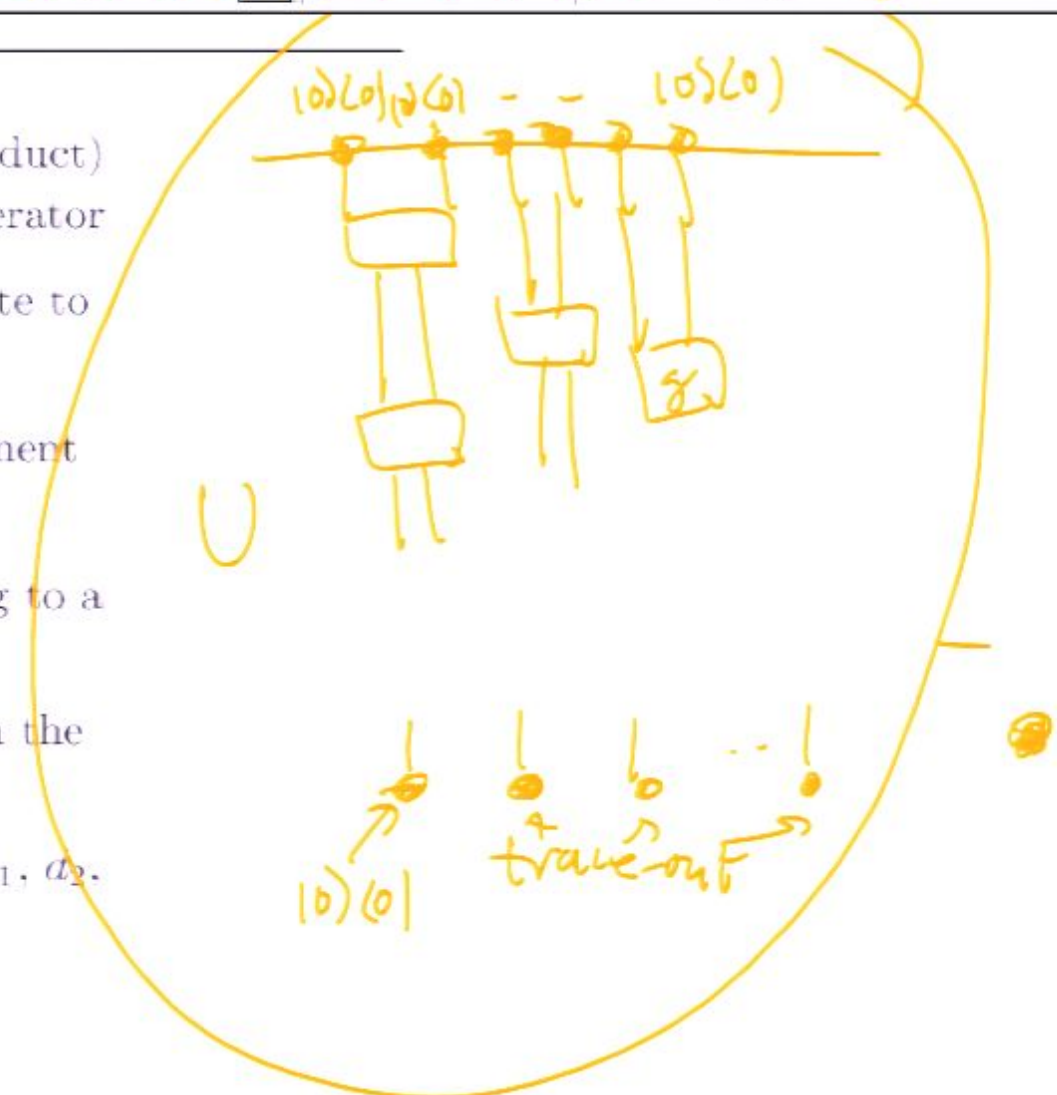
Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .



Given a quantum circuit, an initial (product) state, and a (product) measurement operator

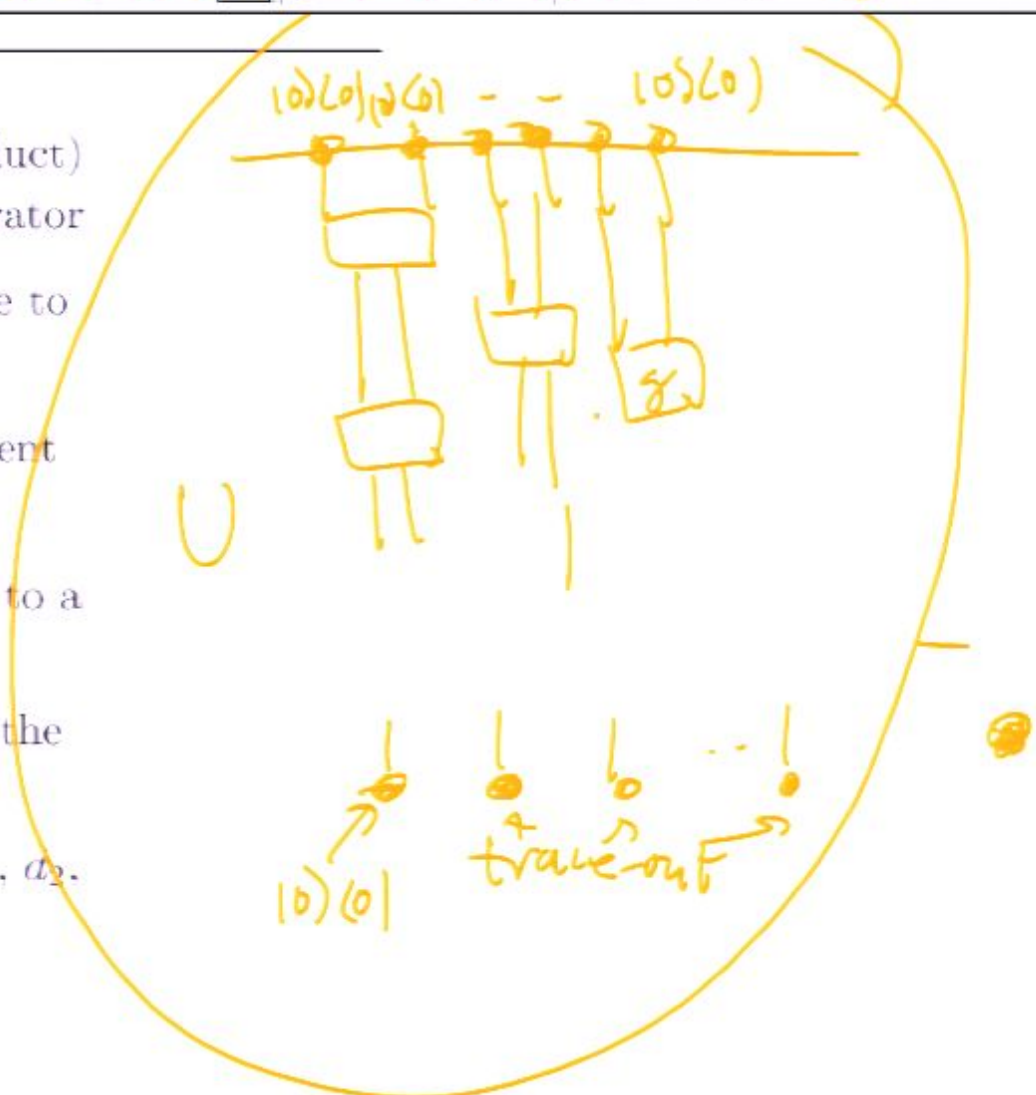
- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .





Given a quantum circuit, an initial (product) state, and a (product) measurement operator

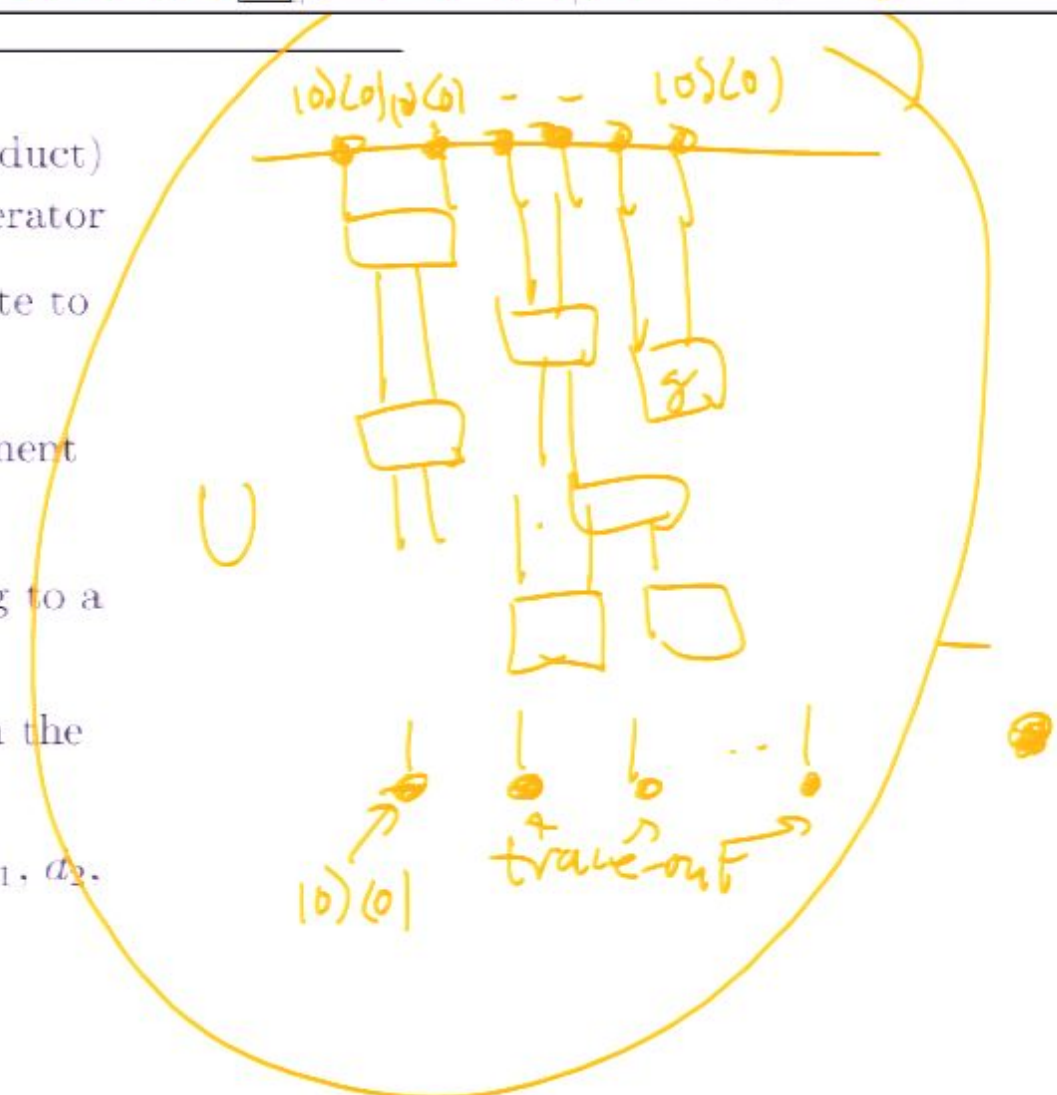
- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .





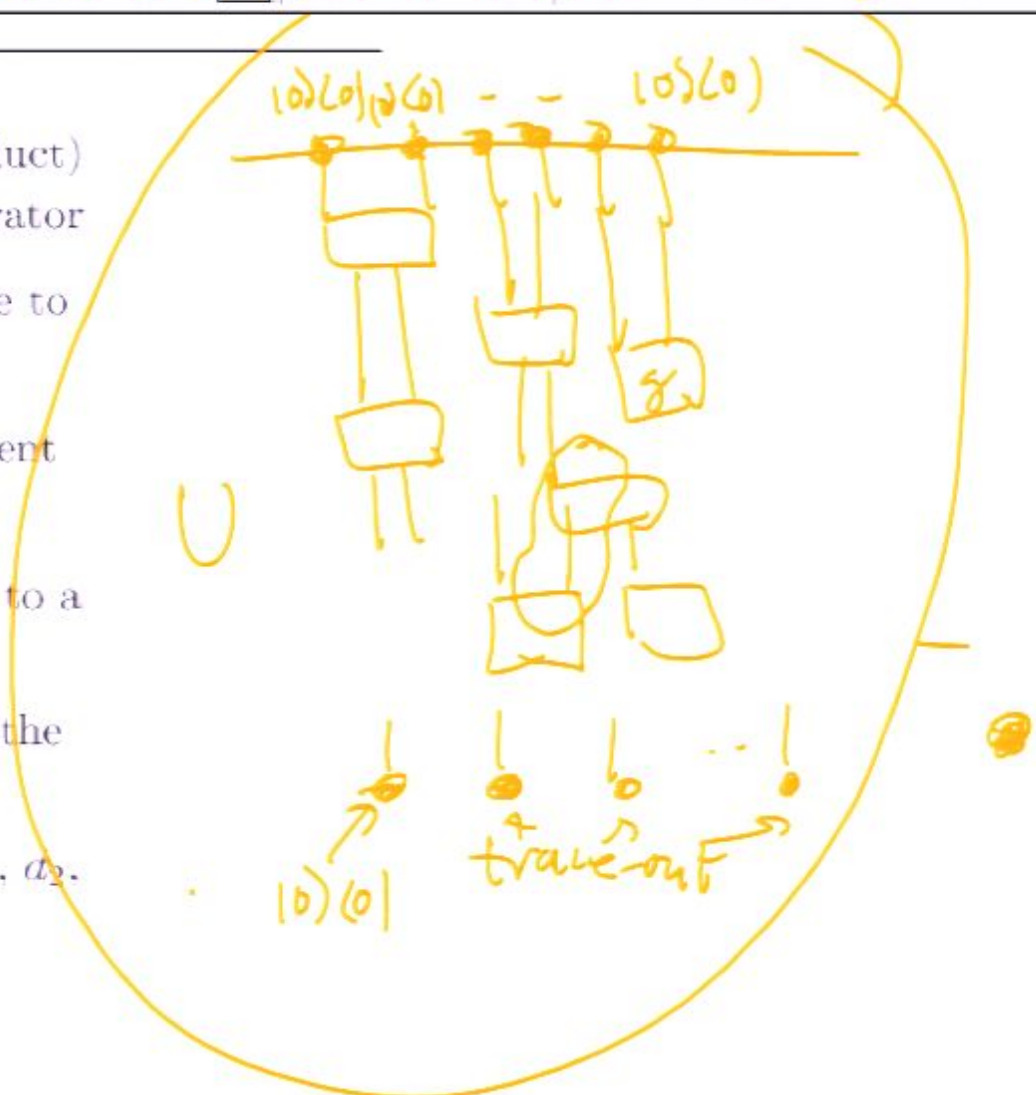
Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .



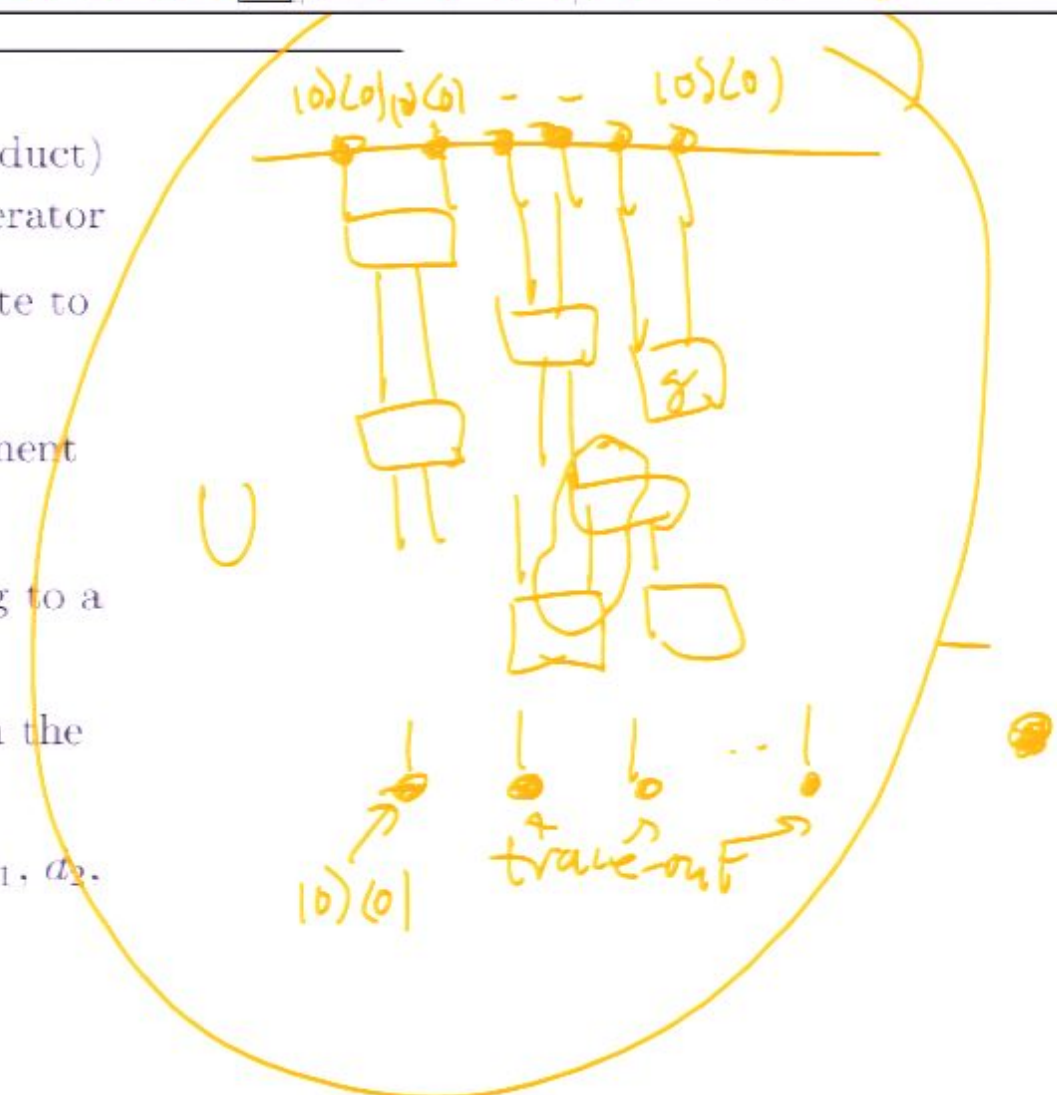
Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .



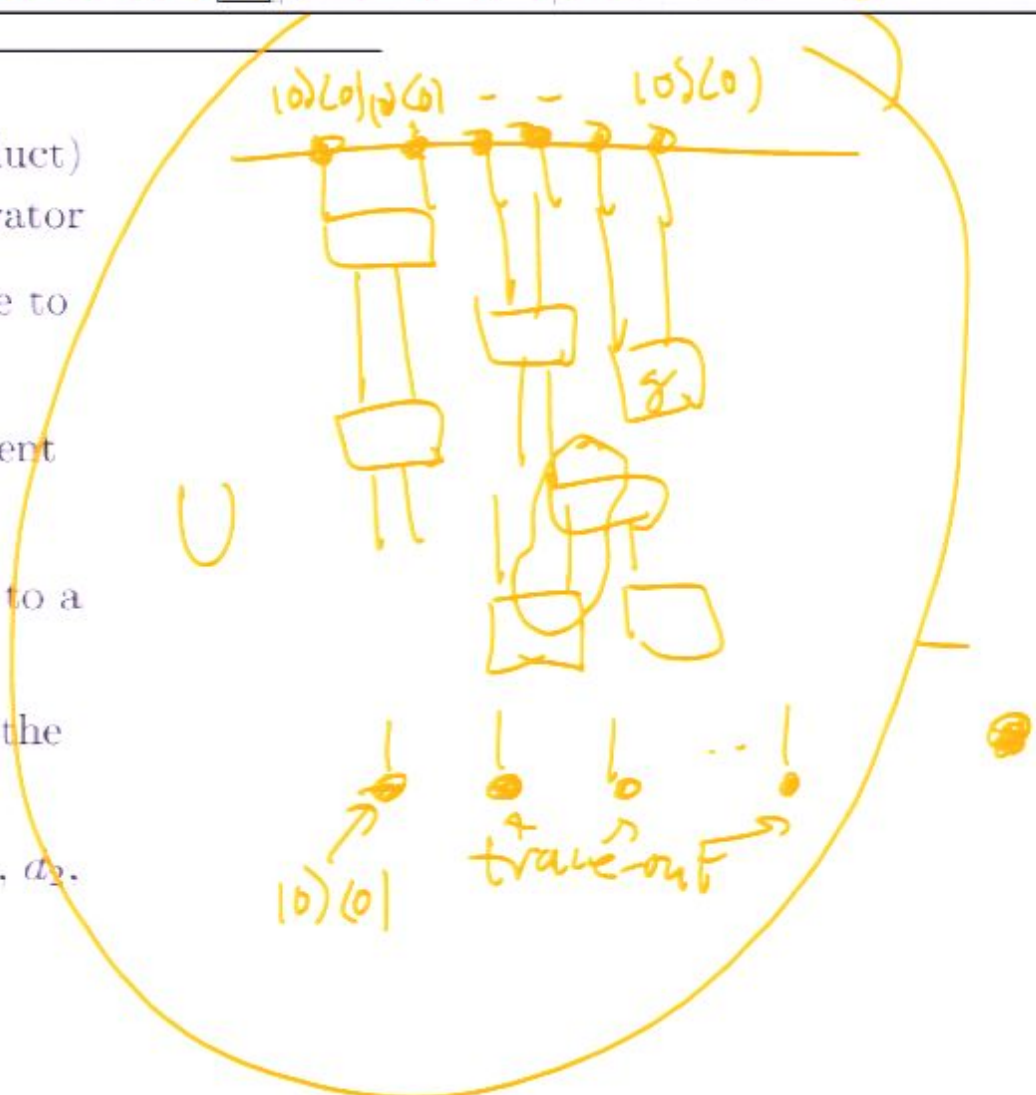
Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .



Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .

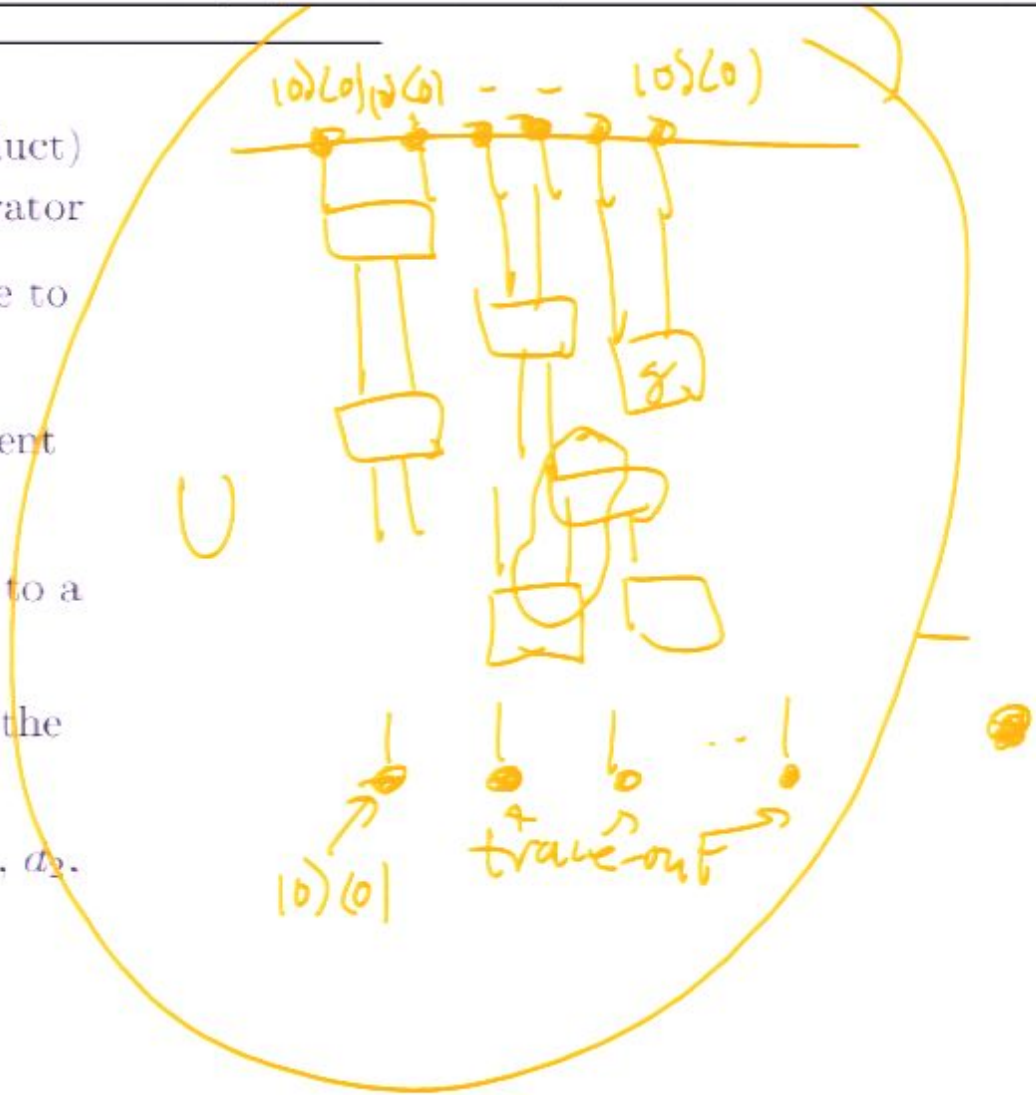




et al. 04, Markov and Shi 05]

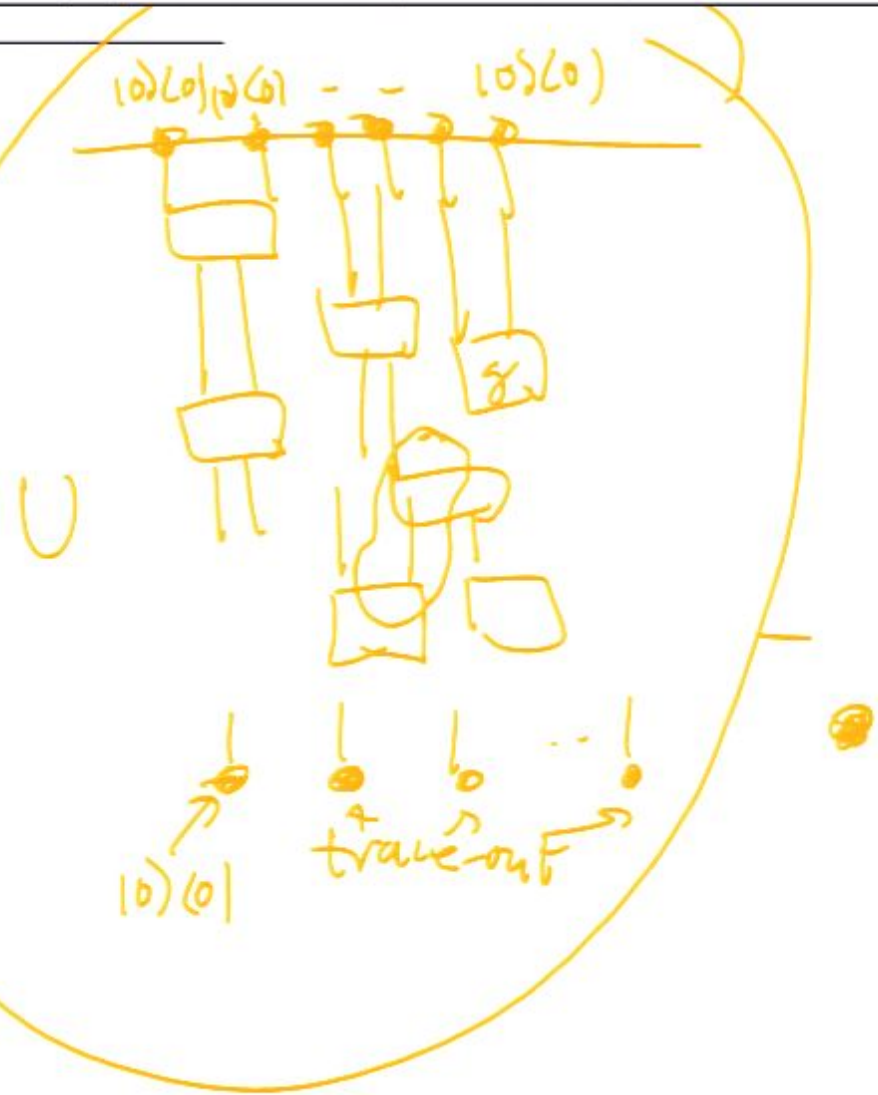
Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .



Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .

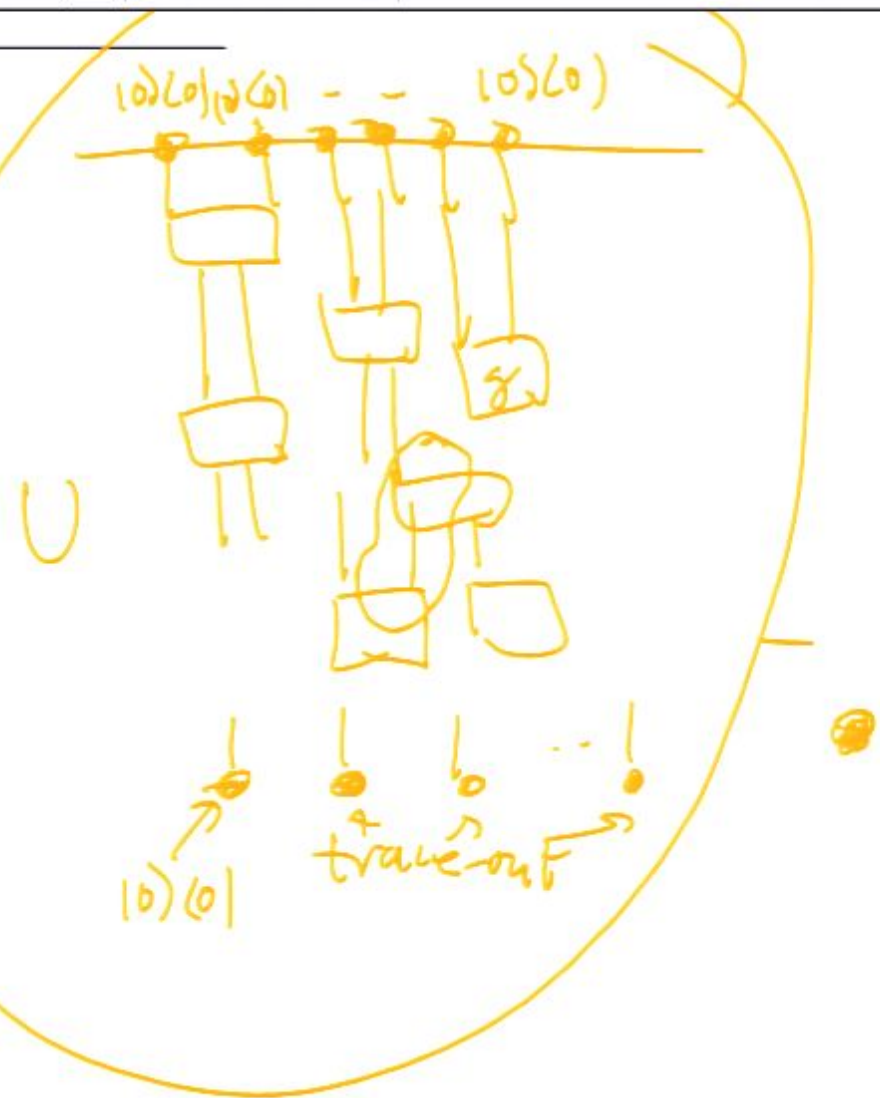




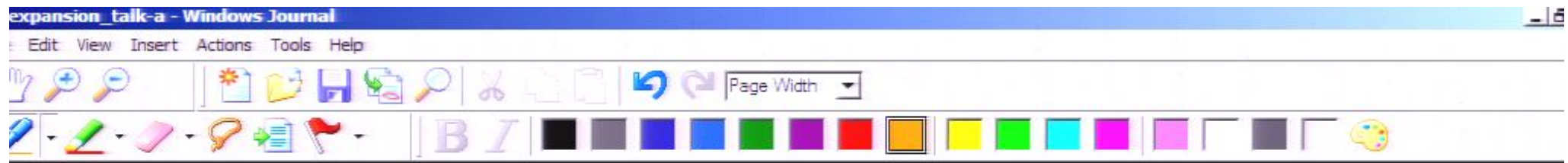
et al. 04, Markov and Shi 05]

Given a quantum circuit, an initial (product) state, and a (product) measurement operator

- Attach the tensors for the input state to the input wires.
- Attach the tensors for the measurement operator to the output wires.
- Contract the whole tensor according to a sequence of wires  $\pi : e_1, e_2, \dots, e_T$ .
  - For each contraction, write down the entries of the new tensor.
  - Resulting in a degree sequence  $d_1, d_2, \dots, d_T = 0$ .
  - Time (and space used):  $T \exp(O(\Delta(\pi)))$ , where  $\Delta(\pi) = \max \{d_i : i = 1 \dots T\}$ .







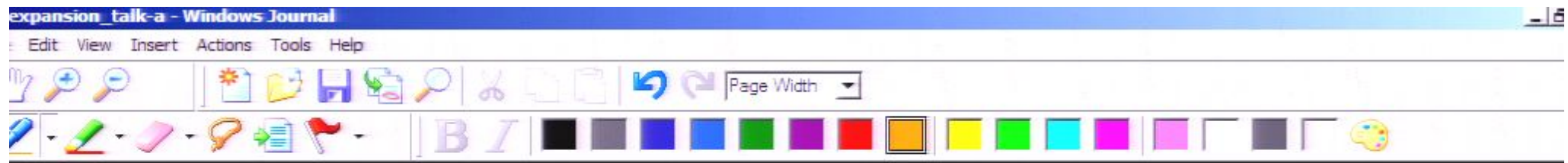
## Contraction complexity and treewidth

---

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$CC(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .



## Contraction complexity and treewidth

---

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .



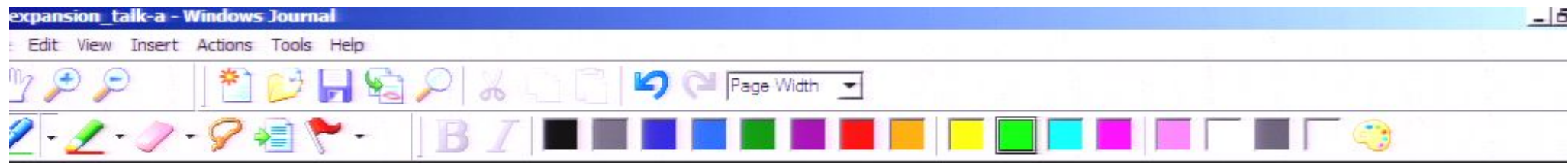
## Contraction complexity and treewidth

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .





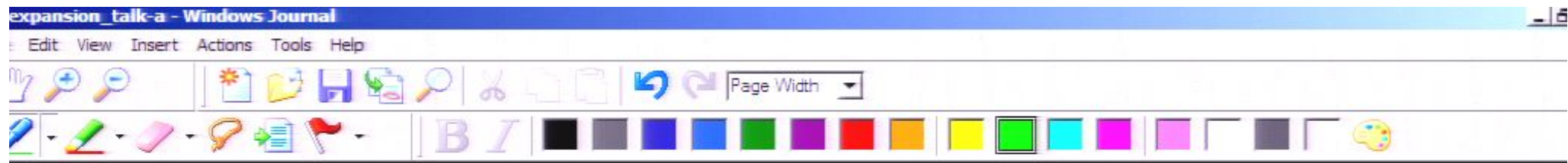
## Contraction complexity and treewidth

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .





## Contraction complexity and treewidth

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .





## Contraction complexity and treewidth

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .





## Contraction complexity and treewidth

Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .





Definition [Markov and Shi '05]. The *contraction complexity* of a graph  $G$  is

$$\text{CC}(G) := \min_{\pi} \Delta(\pi).$$

Definition. The line graph of  $G = \langle V, E \rangle$  is the graph  $G^*$  whose vertex set is  $E$  and  $e_1 e_2$  is an edge if they are incident to a common vertex in  $G$ .



Proposition [Markov and Shi '05]. The contraction complexity of  $G$  is identical to the *treewidth* of  $G^*$ .





## Treewidth

---

The treewidth of a graph  $G$ ,  $\text{tw}(G)$ , describes how close  $G$  is to a tree.

- If  $G$  is a (nonempty) tree,  $\text{tw}(G) = 1$ .
- If  $G$  is a series parallel graph,  $\text{tw}(G) \leq 2$ .
- If  $G$  is fully connected,  $\text{tw}(G) = |V(G)| - 1$ .
- If  $G'$  is a *minor* of  $G$ , i.e.,  $G'$  can be obtained from a subgraph of  $G$  through edge contractions, then  $\text{tw}(G') \leq \text{tw}(G)$ .



## Treewidth

---

The treewidth of a graph  $G$ ,  $\text{tw}(G)$ , describes how close  $G$  is to a tree.

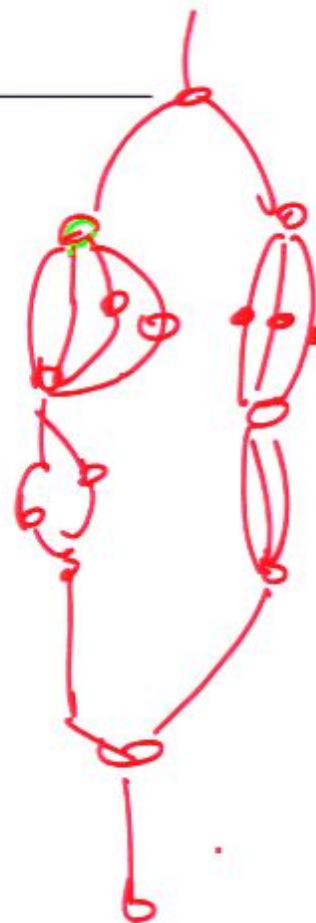
- If  $G$  is a (nonempty) tree,  $\text{tw}(G) = 1$ .
- If  $G$  is a series parallel graph,  $\text{tw}(G) \leq 2$ .
- If  $G$  is fully connected,  $\text{tw}(G) = |V(G)| - 1$ .
- If  $G'$  is a *minor* of  $G$ , i.e.,  $G'$  can be obtained from a subgraph of  $G$  through edge contractions, then  $\text{tw}(G') \leq \text{tw}(G)$ .



## Treewidth

The treewidth of a graph  $G$ ,  $\text{tw}(G)$ , describes how close  $G$  is to a tree.

- If  $G$  is a (nonempty) tree,  $\text{tw}(G) = 1$ .
- If  $G$  is a series parallel graph,  $\text{tw}(G) \leq 2$ .
- If  $G$  is fully connected,  $\text{tw}(G) = |V(G)| - 1$ .
- If  $G'$  is a *minor* of  $G$ , i.e.,  $G'$  can be obtained from a subgraph of  $G$  through edge contractions, then  $\text{tw}(G') \leq \text{tw}(G)$ .

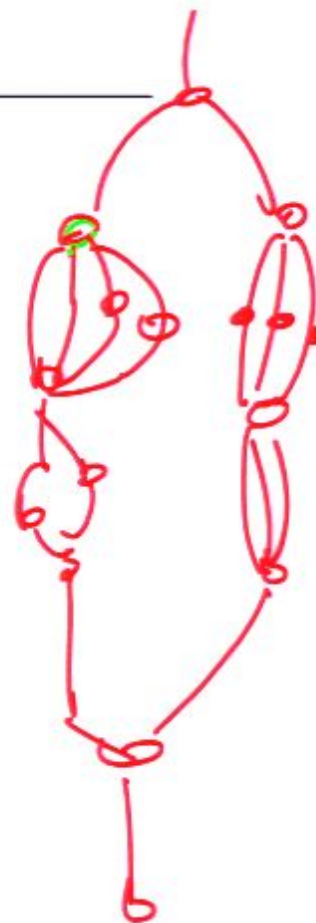




## Treewidth

The treewidth of a graph  $G$ ,  $\text{tw}(G)$ , describes how close  $G$  is to a tree.

- If  $G$  is a (nonempty) tree,  $\text{tw}(G) = 1$ .
- If  $G$  is a series parallel graph,  $\text{tw}(G) \leq 2$ .
- If  $G$  is fully connected,  $\text{tw}(G) = |V(G)| - 1$ .
- If  $G'$  is a *minor* of  $G$ , i.e.,  $G'$  can be obtained from a subgraph of  $G$  through edge contractions, then  $\text{tw}(G') \leq \text{tw}(G)$ .





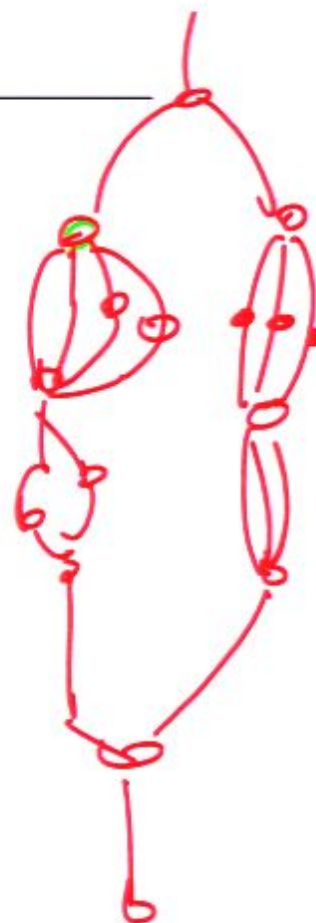
April 30, 2008

Yaoyun Shi 10

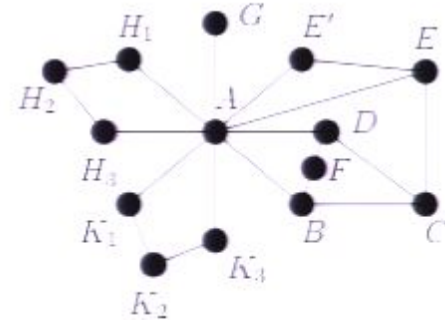
## Treewidth

The treewidth of a graph  $G$ ,  $\text{tw}(G)$ , describes how close  $G$  is to a tree.

- If  $G$  is a (nonempty) tree,  $\text{tw}(G) = 1$ .
- If  $G$  is a series parallel graph,  $\text{tw}(G) \leq 2$ .
- If  $G$  is fully connected,  $\text{tw}(G) = |V(G)| - 1$ .
- If  $G'$  is a *minor* of  $G$ , i.e.,  $G'$  can be obtained from a subgraph of  $G$  through edge contractions, then  $\text{tw}(G') \leq \text{tw}(G)$ .

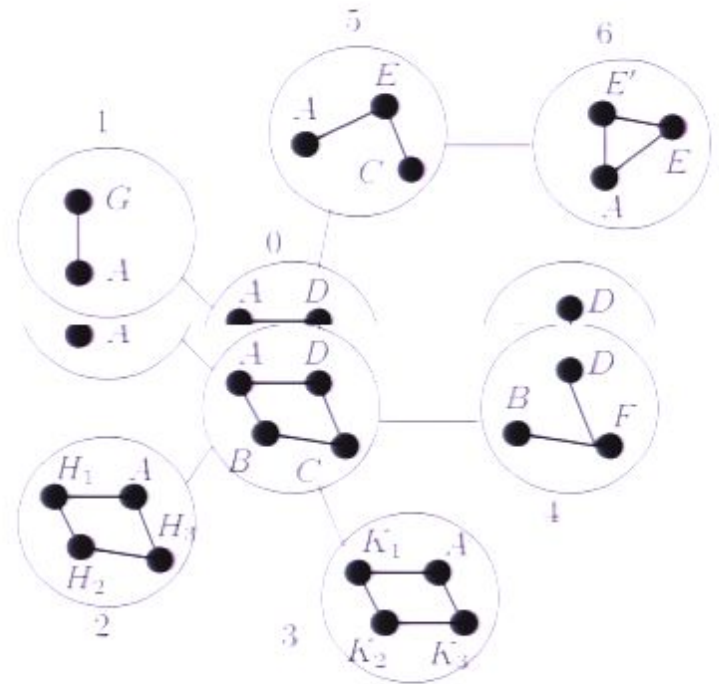


Definition [Robertson and Seymour '84]. A *tree decomposition* of  $G$  is a tree  $\mathcal{T}$ , together with a function that maps each vertex  $w \in V(\mathcal{T})$  to a subset  $B_w \subseteq V(G)$ , called *bags*. In addition, the following conditions must hold.



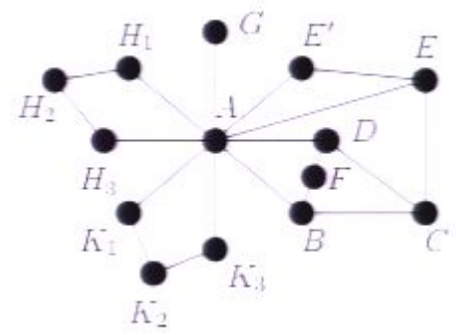
- (T1)  $\bigcup_{v \in V(\mathcal{T})} B_v = V(G)$ , i.e., each vertex must appear in at least one bag.
- (T2)  $\forall \{u, v\} \in E(G), \exists w \in V(\mathcal{T}), \{u, v\} \subseteq B_w$ , i.e., for each edge, at least one bag must contain both of its end vertices.
- (T3)  $\forall u \in V(G)$ , the set of vertices  $w \in V(\mathcal{T})$  with  $u \in B_w$  form a connected subtree, i.e., all bags containing a given vertex must be connected in  $\mathcal{T}$ .

The *width* of a tree decomposition is  $\max_{w \in V(\mathcal{T})} |B_w| - 1$ . The *treewidth* of  $G$  is the minimum width over its tree decompositions.

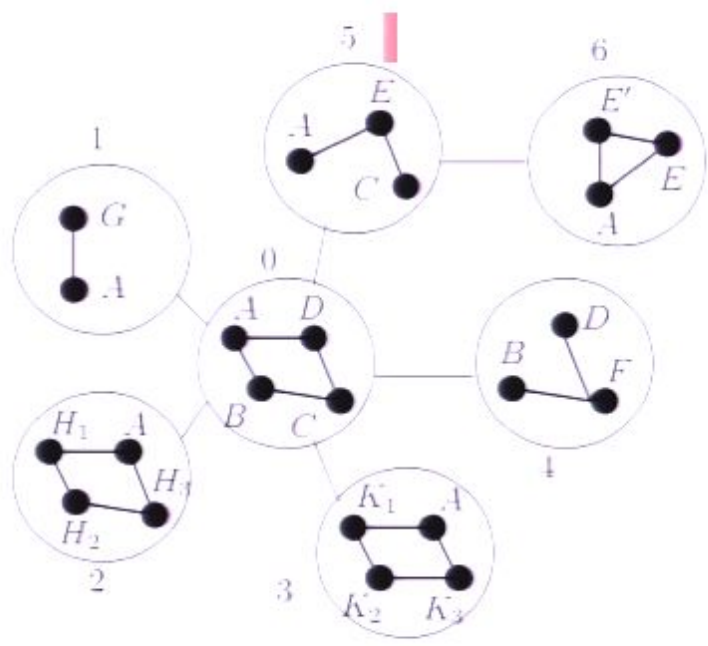




Definition [Robertson and Seymour '84]. A **tree decomposition** of  $G$  is a tree  $\mathcal{T}$ , together with a function that maps each vertex  $w \in V(\mathcal{T})$  to a subset  $B_w \subseteq V(G)$ , called *bags*. In addition, the following conditions must hold.



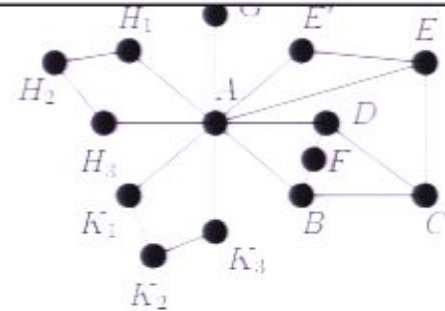
- (T1)  $\bigcup_{v \in V(\mathcal{T})} B_v = V(G)$ , i.e., each vertex must appear in at least one bag.
- (T2)  $\forall \{u, v\} \in E(G), \exists w \in V(\mathcal{T}), \{u, v\} \subseteq B_w$ , i.e., for each edge, at least one bag must contain both of its end vertices.
- (T3)  $\forall u \in V(G)$ , the set of vertices  $w \in V(\mathcal{T})$  with  $u \in B_w$  form a connected subtree, i.e., all bags containing a given vertex must be connected in  $\mathcal{T}$ .



The *width* of a tree decomposition is  $\max_{w \in V(\mathcal{T})} |B_w| - 1$ . The *treewidth* of  $G$  is the minimum width over its tree decompositions.

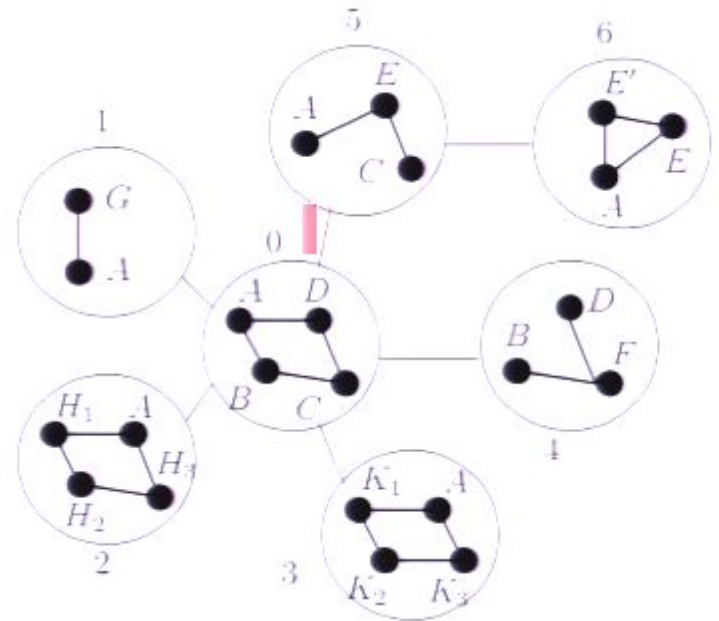


**decomposition** of  $G$  is a tree  $\mathcal{T}$ , together with a function that maps each vertex  $w \in V(\mathcal{T})$  to a subset  $B_w \subseteq V(G)$ , called *bags*. In addition, the following conditions must hold.



- (T1)  $\bigcup_{v \in V(\mathcal{T})} B_v = V(G)$ , i.e., each vertex must appear in at least one bag.
- (T2)  $\forall \{u, v\} \in E(G), \exists w \in V(\mathcal{T}), \{u, v\} \subseteq B_w$ , i.e., for each edge, at least one bag must contain both of its end vertices.
- (T3)  $\forall u \in V(G)$ , the set of vertices  $w \in V(\mathcal{T})$  with  $u \in B_w$  form a connected subtree, i.e., all bags containing a given vertex must be connected in  $\mathcal{T}$ .

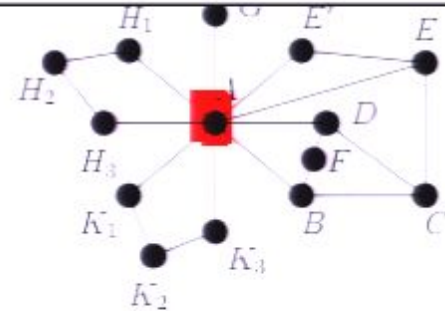
The *width* of a tree decomposition is  $\max_{w \in V(\mathcal{T})} |B_w| - 1$ . The *treewidth* of  $G$  is the minimum width over its tree decompositions.



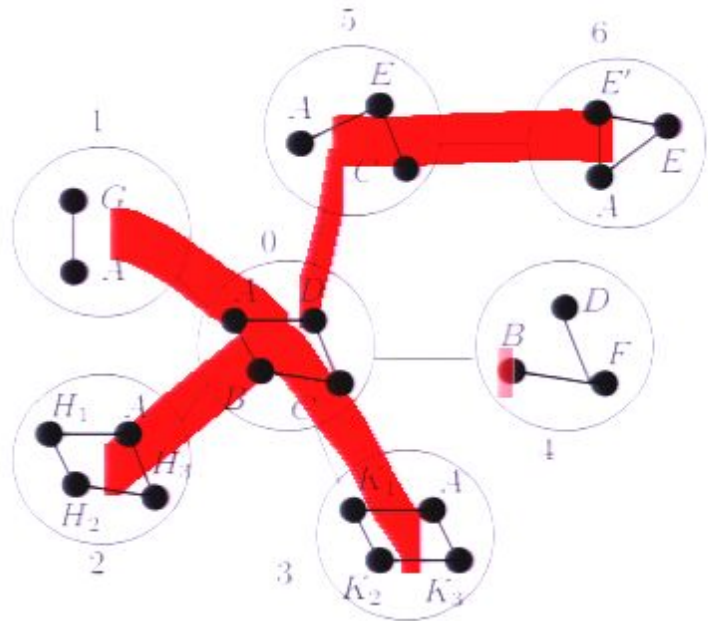




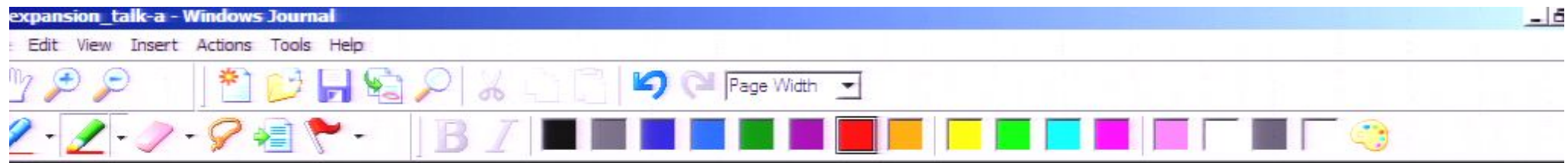
**decomposition** of  $G$  is a tree  $\mathcal{T}$ , together with a function that maps each vertex  $w \in V(\mathcal{T})$  to a subset  $B_w \subseteq V(G)$ , called *bags*. In addition, the following conditions must hold.



- (T1)  $\bigcup_{v \in V(\mathcal{T})} B_v = V(G)$ , i.e., each vertex must appear in at least one bag.
- (T2)  $\forall \{u, v\} \in E(G), \exists w \in V(\mathcal{T}), \{u, v\} \subseteq B_w$ , i.e., for each edge, at least one bag must contain both of its end vertices.
- (T3)  $\forall u \in V(G)$ , the set of vertices  $w \in V(\mathcal{T})$  with  $u \in B_w$  form a connected subtree, i.e., all bags containing a given vertex must be connected in  $\mathcal{T}$ .



The *width* of a tree decomposition is  $\max_{w \in V(\mathcal{T})} |B_w| - 1$ . The *treewidth* of  $G$  is the minimum width over its tree decompositions.



Denote the maximum degree of  $G$  by  $\Delta(G)$ .

Proposition.

$$(\text{tw}(G) - 1)^2 \leq \text{tw}(G^*) \leq \Delta(G)(\text{tw}(G) + 1) - 1.$$



## The treewidths of the graph and its line graph

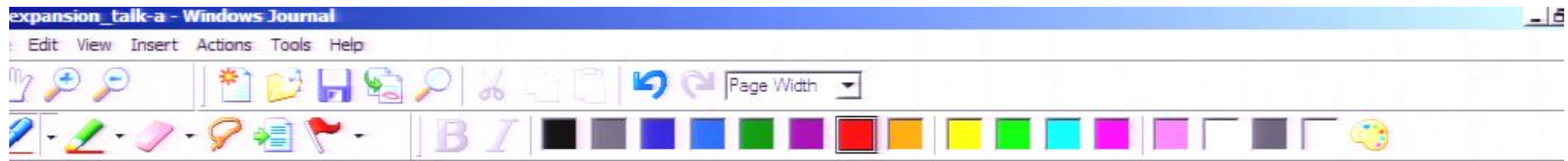
---

Denote the maximum degree of  $G$  by  $\Delta(G)$ .

Proposition.

$$(\text{tw}(G) - 1)^2 \leq \text{tw}(G^*) \leq \Delta(G) (\text{tw}(G) + 1) - 1.$$





## The treewidths of the graph and its line graph

---

Denote the maximum degree of  $G$  by  $\Delta(G)$ .

Proposition.

$$(\text{tw}(G) - 1)^2 \leq \text{tw}(G^*) \leq \Delta(G) \text{tw}(G) + 1 - 1).$$



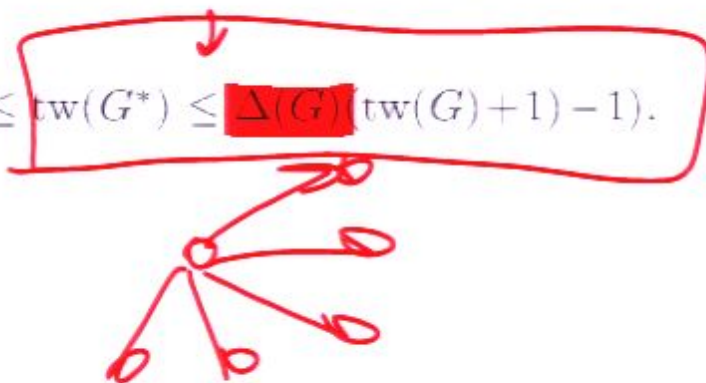


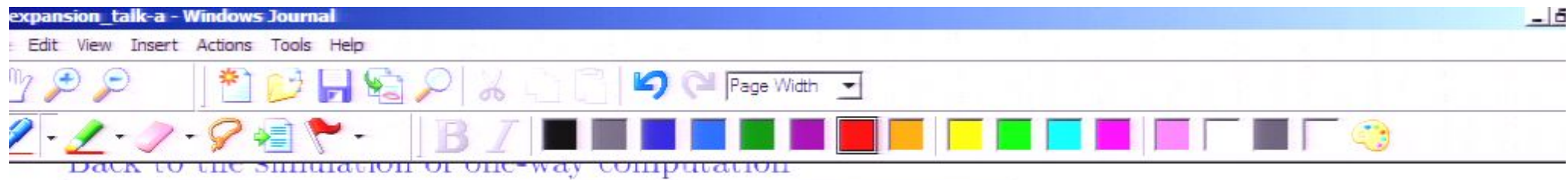
## The treewidths of the graph and its line graph

Denote the maximum degree of  $G$  by  $\Delta(G)$ .

Proposition.

$$(\text{tw}(G) - 1)^2 \leq \text{tw}(G^*) \leq \Delta(G) (\text{tw}(G) + 1) - 1.$$





Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.
  - The  $t$ 'th contraction computes the probability of outputting  $b_1 b_2 \cdots b_{t-1} 0$ .
  - Should remember the prob. of

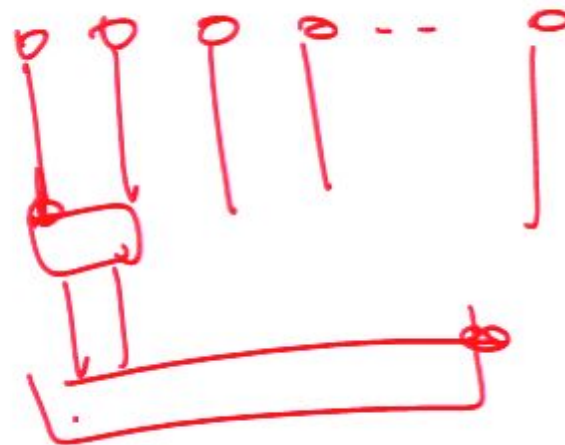


$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



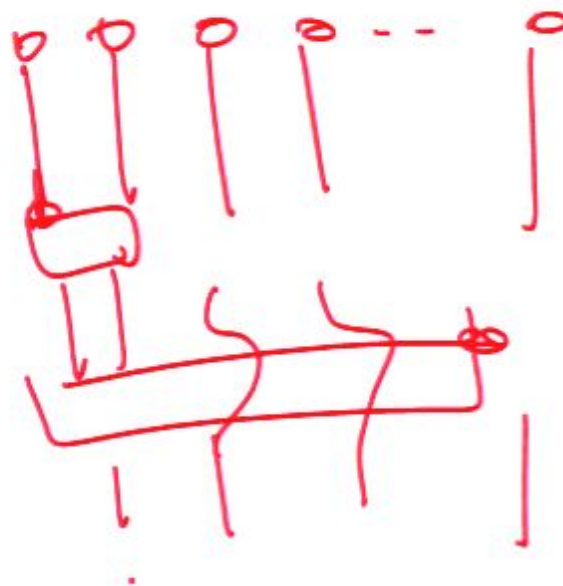


$G$

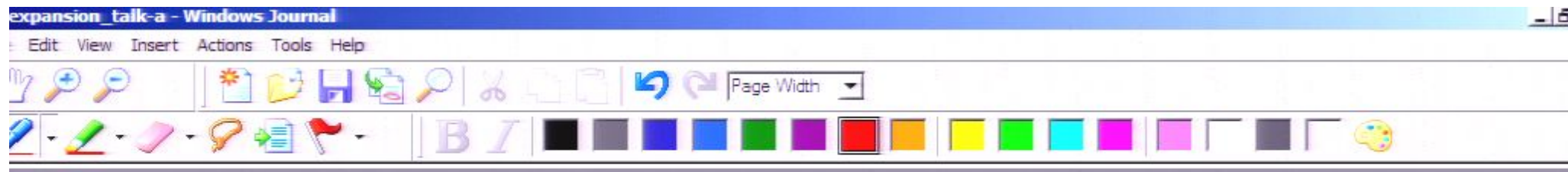
## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.





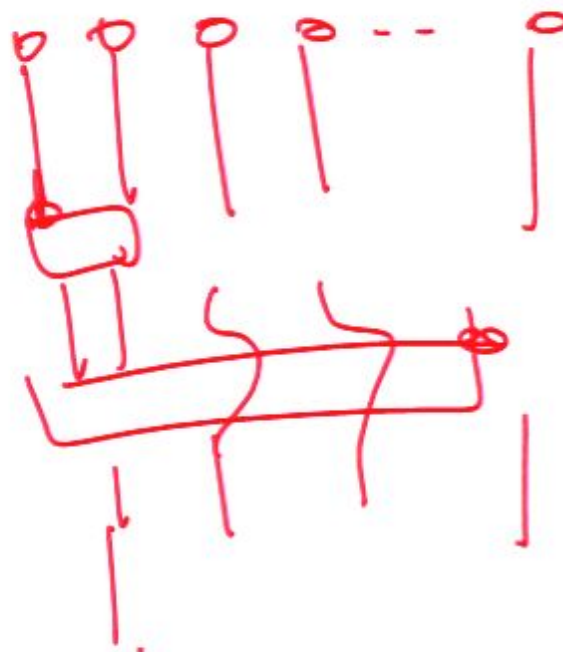


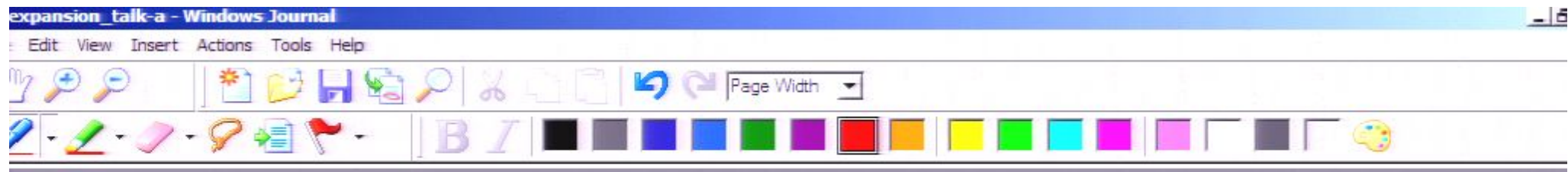
$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



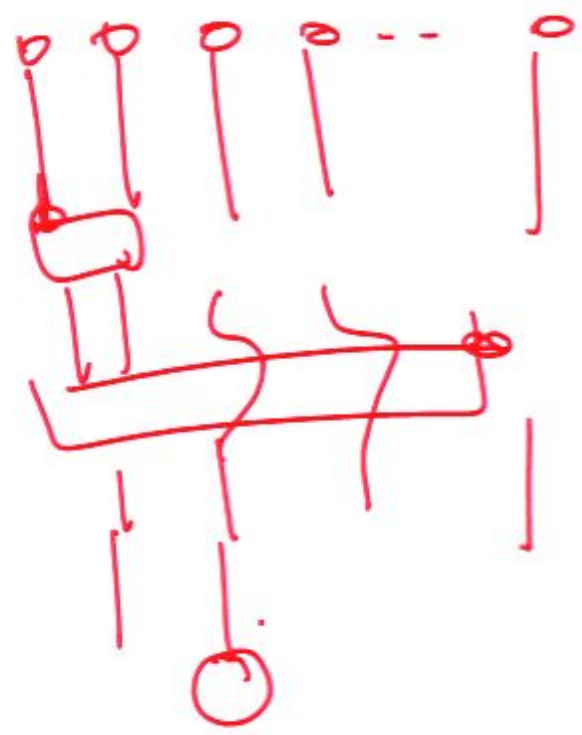


$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



– The  $t$ 'th contraction computes the

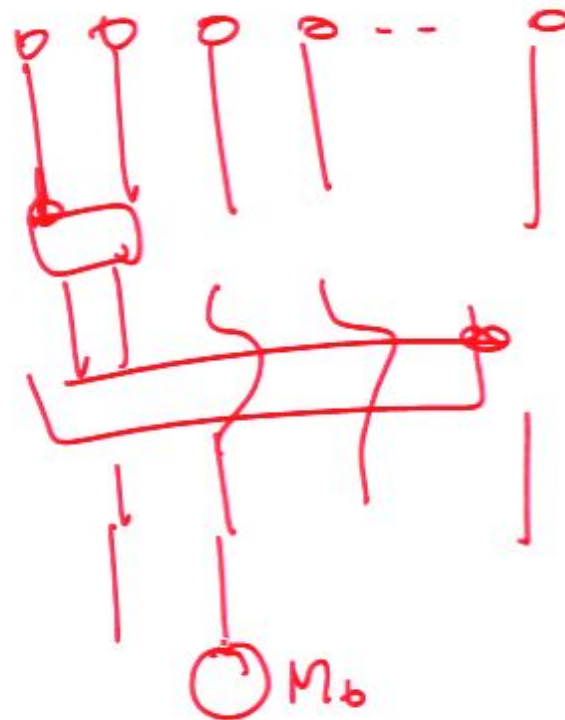


$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



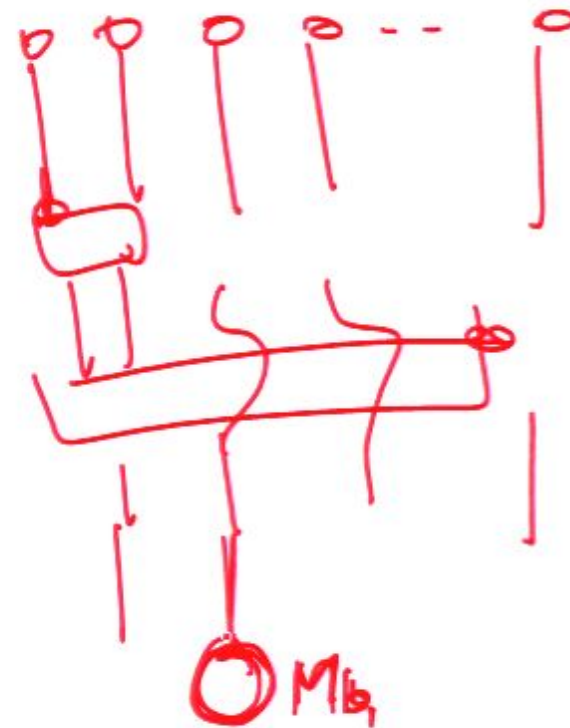


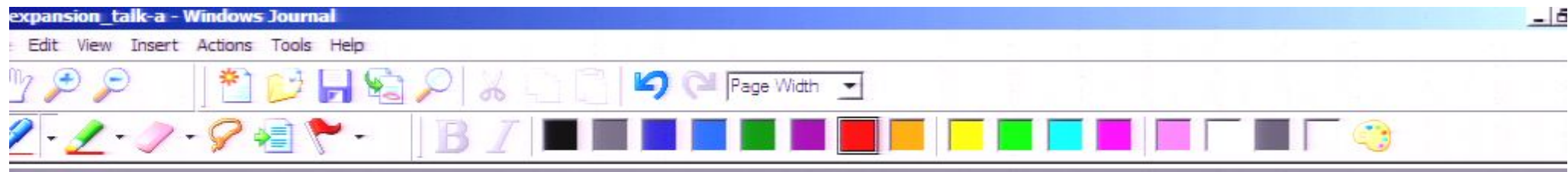
$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



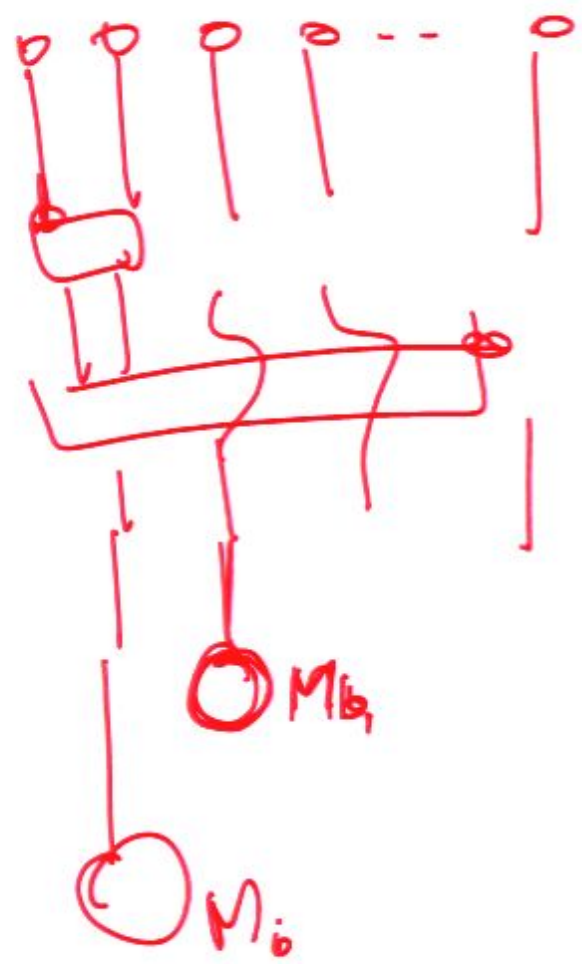


G

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



- The  $t$ 'th contraction computes the

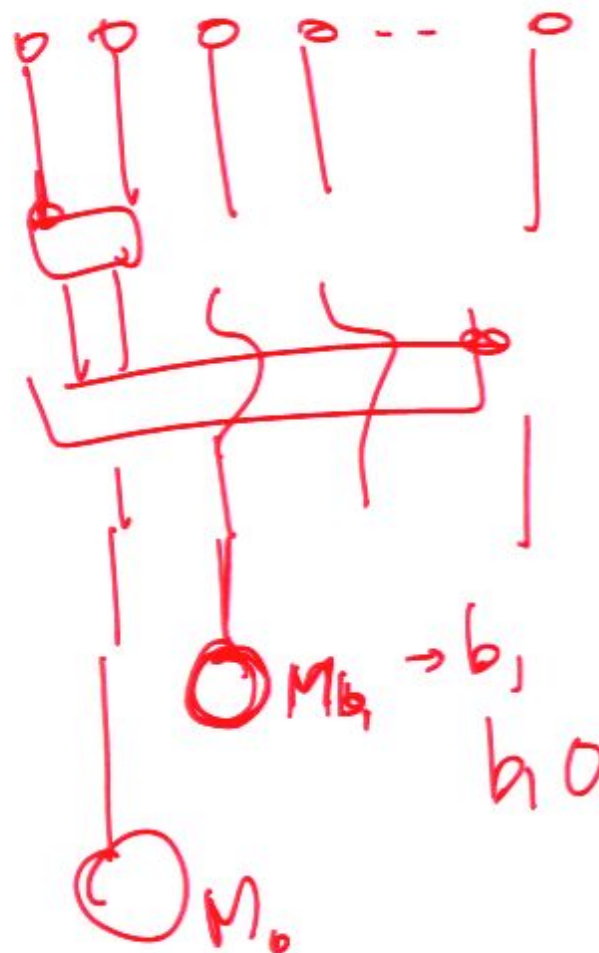


G

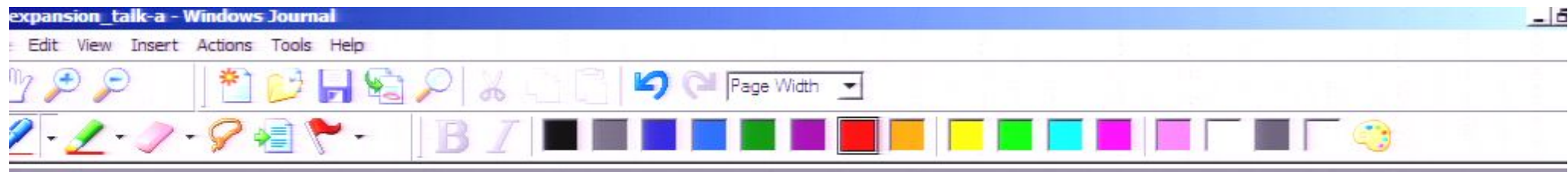
Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.



- The  $t$ 'th contraction computes the

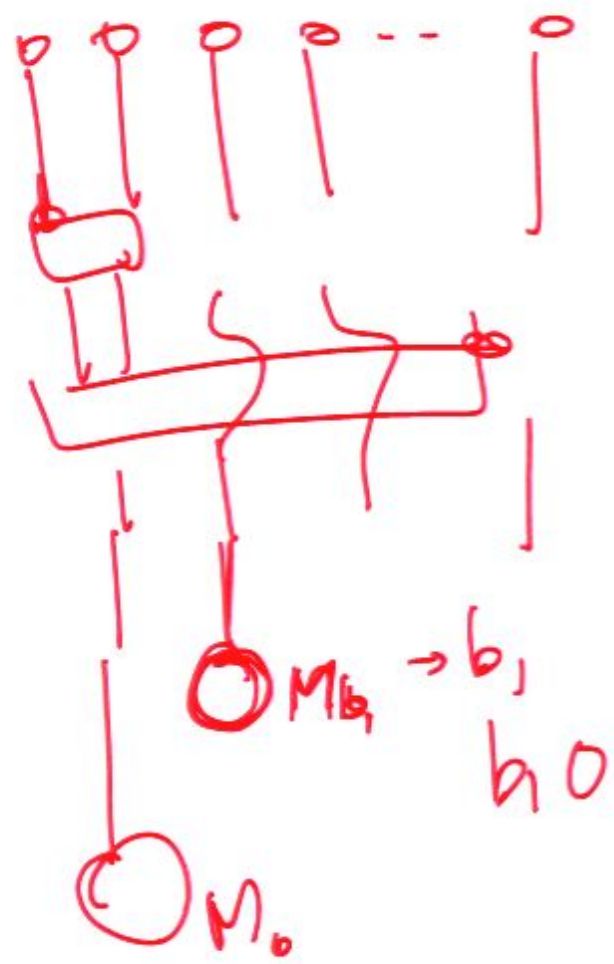


$G$

## Back to the simulation of one-way computation

Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.

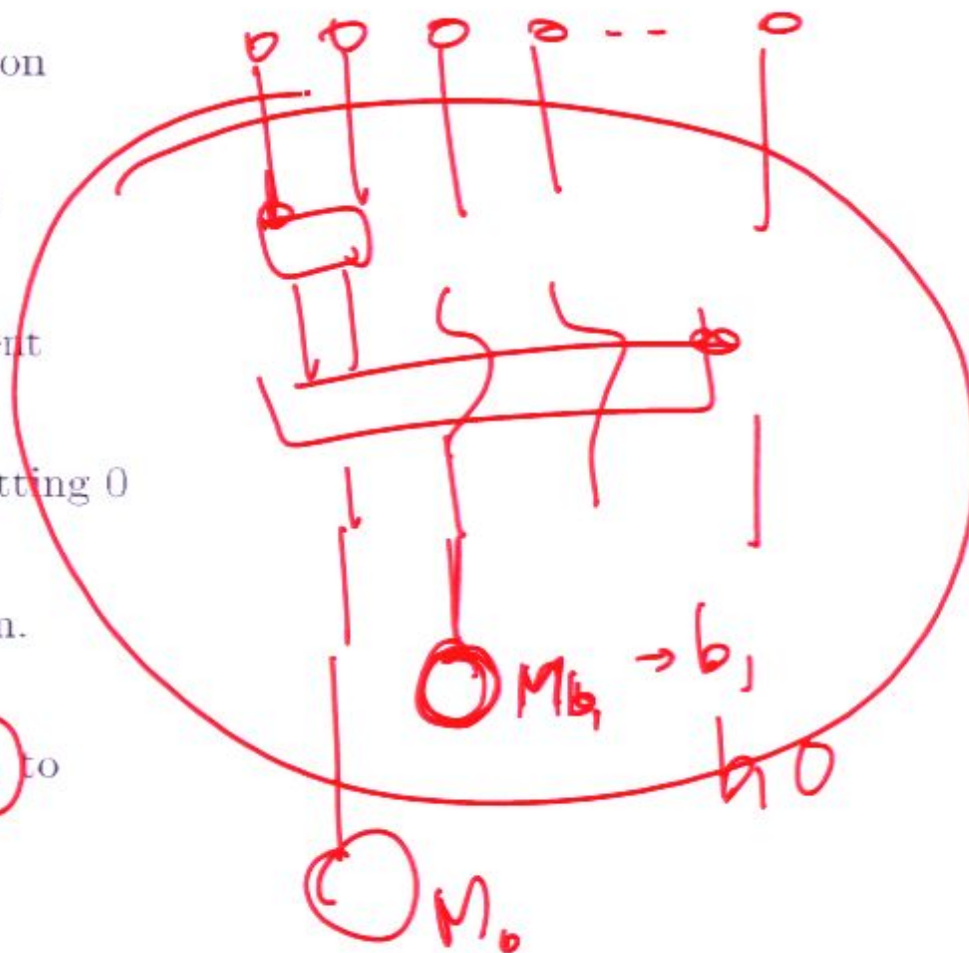


– The  $t$ 'th contraction computes the



Fix a circuit  $C_G$  creating  $|G\rangle$ . A simulation algorithm:

- Select the next qubit to be measured according to the one-way algorithm.
- Attach the corresponding measurement element to the circuit.
- Compute the probability  $p_0$  of outputting 0 through tensor contraction.
- Toss a coin with identical distribution.
- Attach the measurement element corresponding to the coin outcome  $b_1$  to the circuit.
- Repeat till the end of the one-way algorithm.
  - The  $t$ 'th contraction computes the probability of outputting  $b_1 b_2 \dots b_{t-1} 0$ .
  - Should remember the prob. of







## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(CC(C_G))$ .

But  $CC(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star



## Back to the simulation of one-way computation

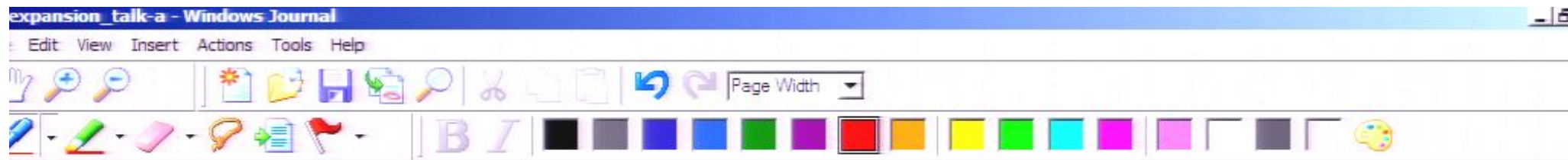
outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement. •

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star



## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\underline{CC(C_G)})$ .

But  $CC(C_G) = \underline{O(\Delta(G) \text{tw}(G))}$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\cdot \exp(\Delta(G) \cdot t_u)$$

$$\text{tw}(h^*) \leq \Delta(G) \cdot \text{tw}(G)$$



## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\underline{CC(C_G)})$ .

But  $CC(C_G) = \underline{O(\Delta(G) \text{tw}(G))}$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\cdot \exp(\Delta(G) \cdot \text{tw}(G))$$

$$\text{tw}(G^*) \leq \Delta(G) \cdot \text{tw}(G)$$



## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\underline{CC(C_G)})$ .

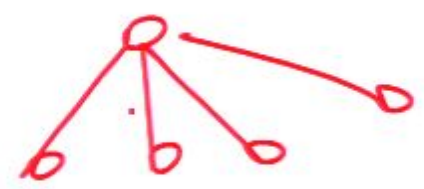
But  $CC(C_G) = \underline{O(\Delta(G) \text{tw}(G))}$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$

$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$





## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\underline{CC(C_G)})$ .

But  $CC(C_G) = \underline{O(\Delta(G) \text{tw}(G))}$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\cdot \exp(\Delta(G) \cdot \text{tw}(G))$$





Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\underline{CC(C_G)})$ .

But  $CC(C_G) = \underline{O(\Delta(G) \text{tw}(G))}$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$



$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$





## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

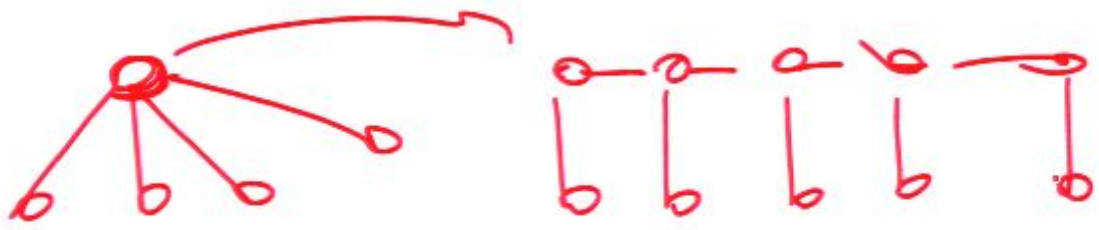
But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(G^*) \leq \Delta(G) \cdot \text{tw}(G)$$

$$\cdot \exp(\Delta(G) \cdot \text{tw}(G))$$







## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

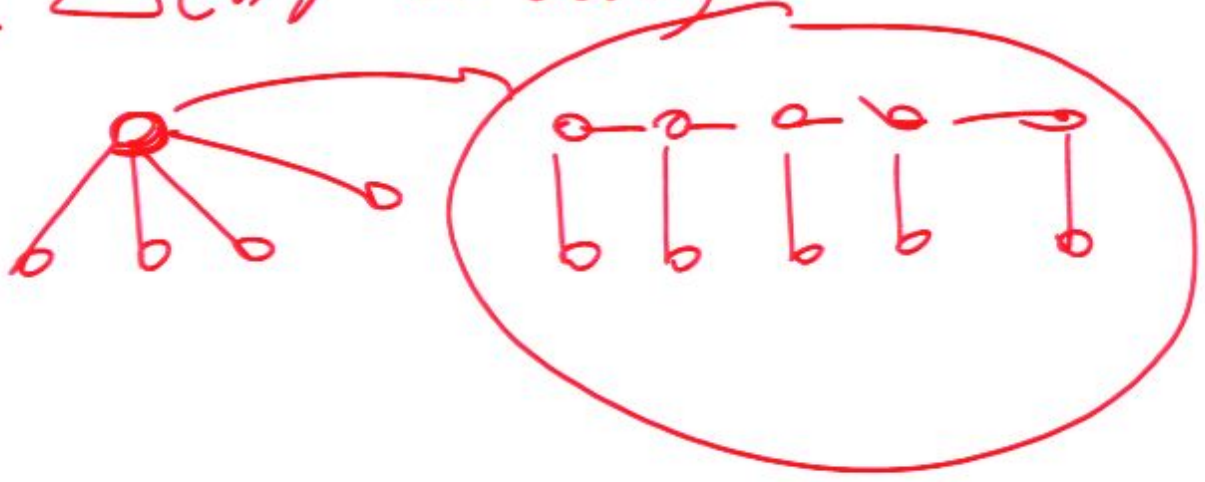
But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$

$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$





## Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

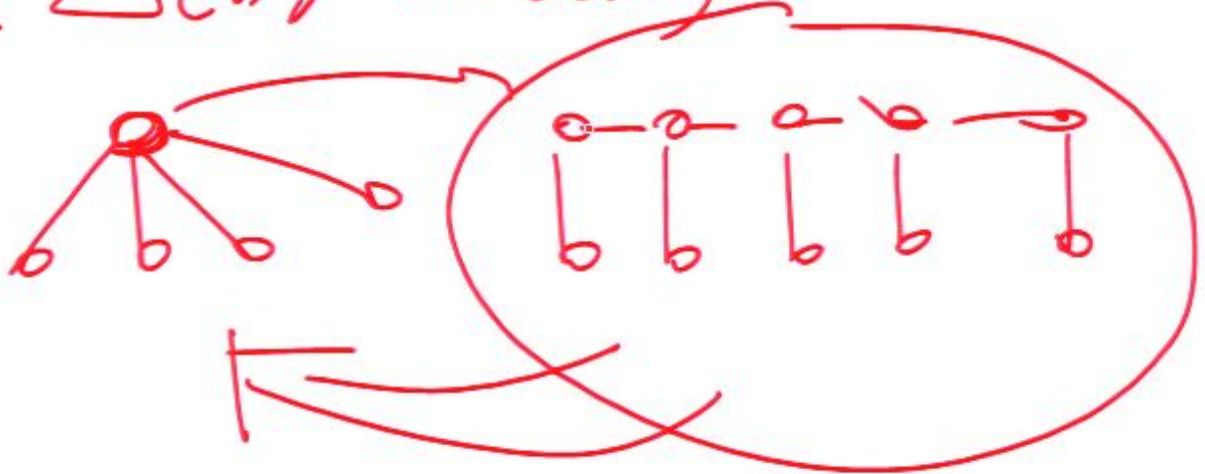
But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$

$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$





Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

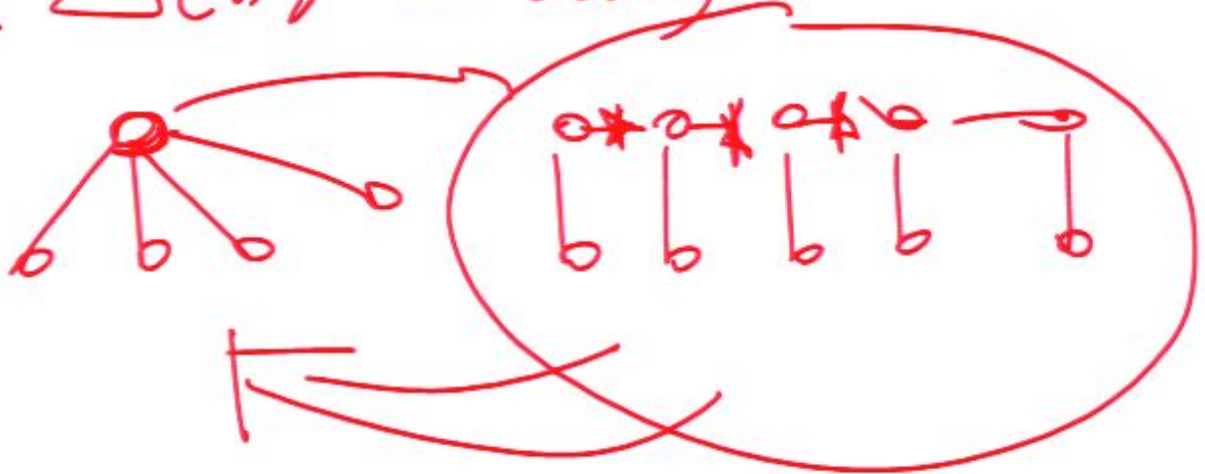
But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$

$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$





### Back to the simulation of one-way computation

outputting  $b_1 b_2 \dots b_{t-1}$  to compute the conditional probability of outputting 0 for the current measurement.

Complexity:  $O(T) \exp(\text{CC}(C_G))$ .

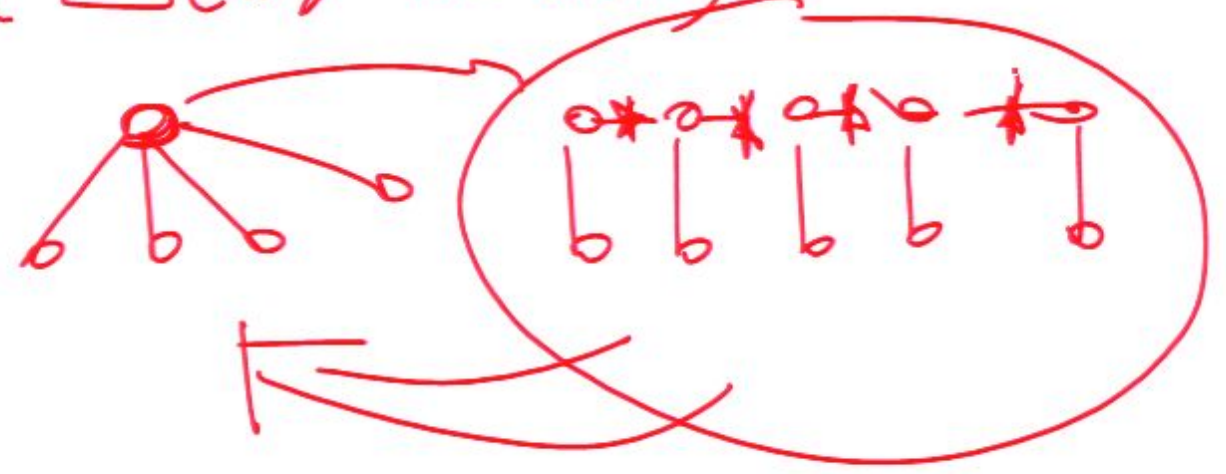
But  $\text{CC}(C_G) = O(\Delta(G) \text{tw}(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star

$$\text{tw}(h^*) \leq \Delta(h) \cdot \text{tw}(h)$$

$$\cdot \exp(\Delta(h) \cdot \text{tw}(h))$$

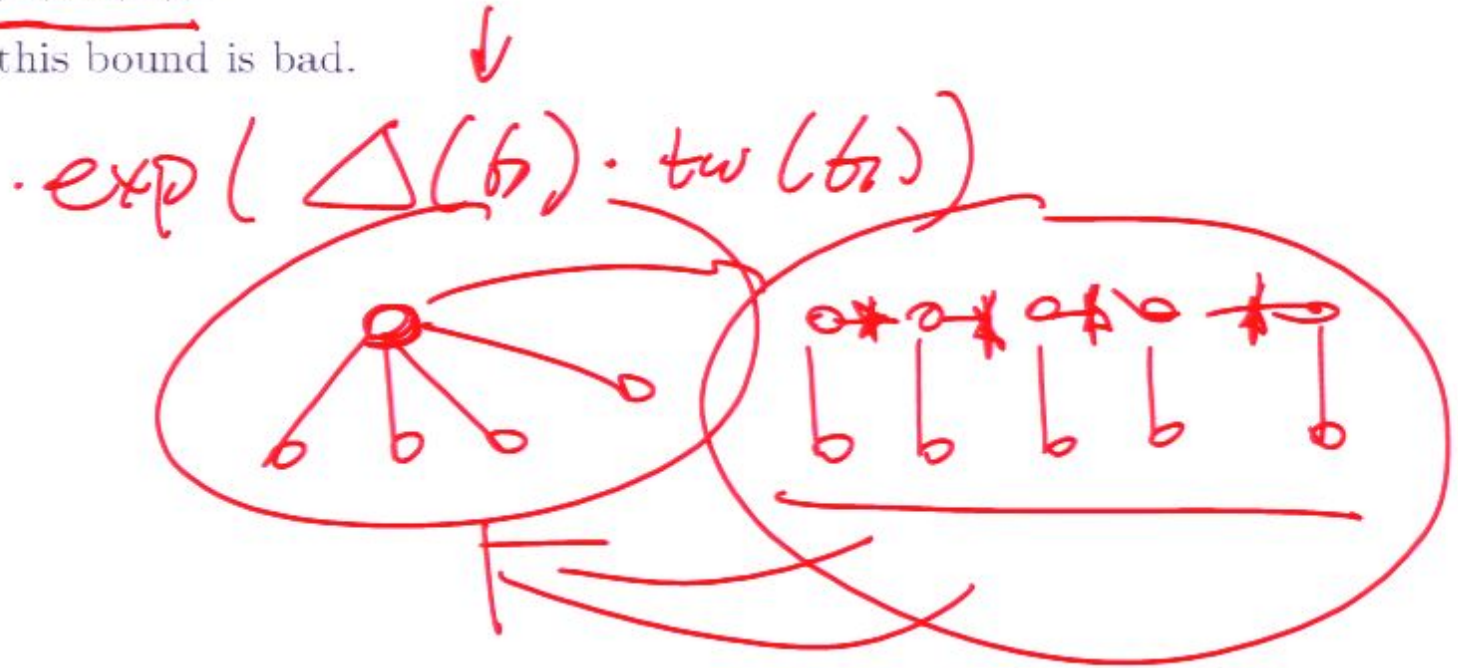


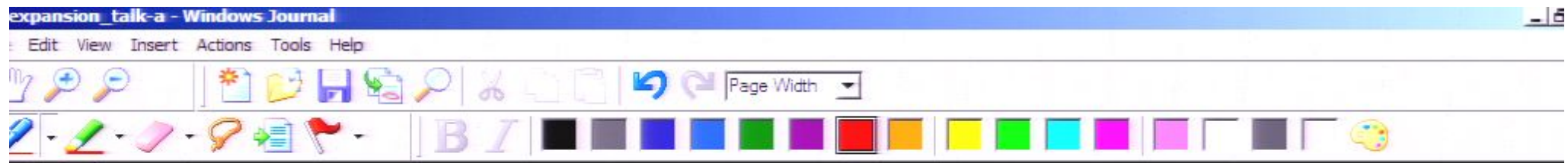


But  $CC(C_G) = O(\Delta(G)tw(G))$ .

When  $\Delta(G)$  is large this bound is bad.

Example: a star





## Graph expansion

---

Splitting a vertex  $v$  of a graph  $G = \langle V, E \rangle$ :

- Replace  $v$  by two new vertices  $v_1$  and  $v_2$ ;
- Connect  $v_1 v_2$ ;
- Connect each neighbor of  $v$  to either  $v_1$  or  $v_2$ .

Definition. An *expansion* of  $G$  is a graph obtained from  $G$  through a sequence of vertex splitting.

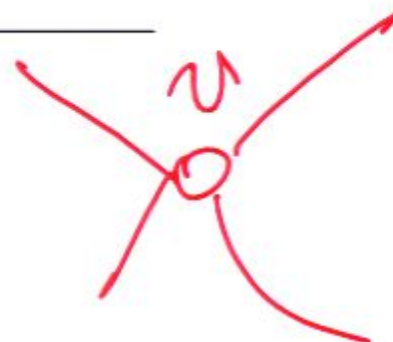


## Graph expansion

Splitting a vertex  $v$  of a graph  $G = \langle V, E \rangle$ :

- Replace  $v$  by two new vertices  $v_1$  and  $v_2$ ;
- Connect  $v_1 v_2$ ;
- Connect each neighbor of  $v$  to either  $v_1$  or  $v_2$ .

Definition. An *expansion* of  $G$  is a graph obtained from  $G$  through a sequence of vertex splitting.



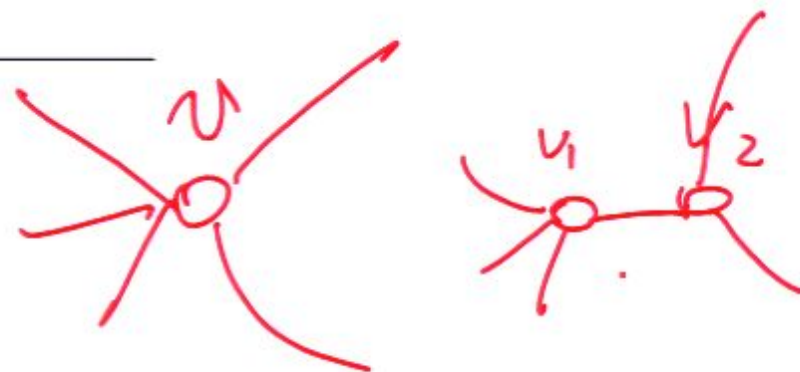


## Graph expansion

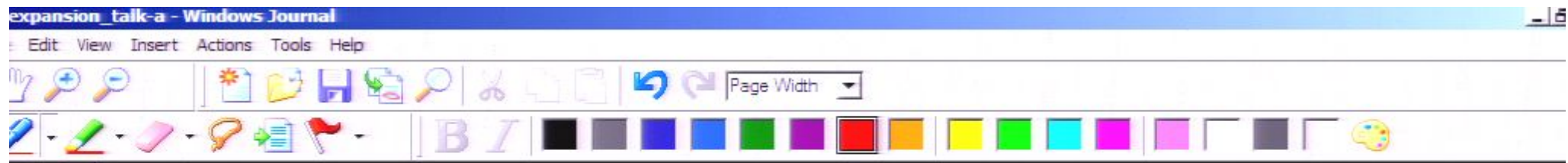
Splitting a vertex  $v$  of a graph  $G = \langle V, E \rangle$ :

- Replace  $v$  by two new vertices  $v_1$  and  $v_2$ ;
- Connect  $v_1 v_2$ ;
- Connect each neighbor of  $v$  to either  $v_1$  or  $v_2$ .

Definition. An *expansion* of  $G$  is a graph obtained from  $G$  through a sequence of vertex splitting.





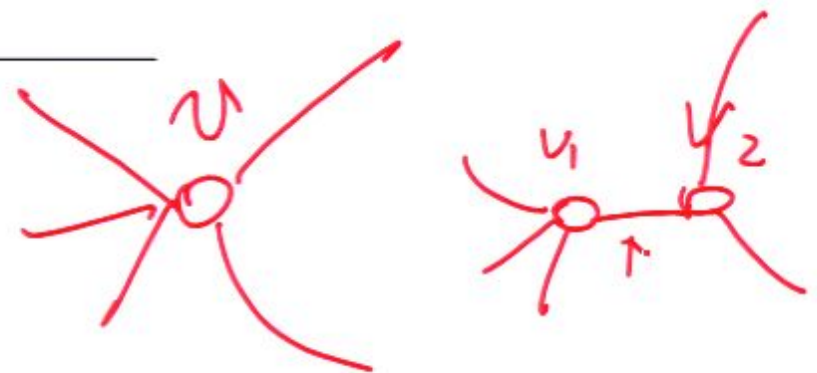


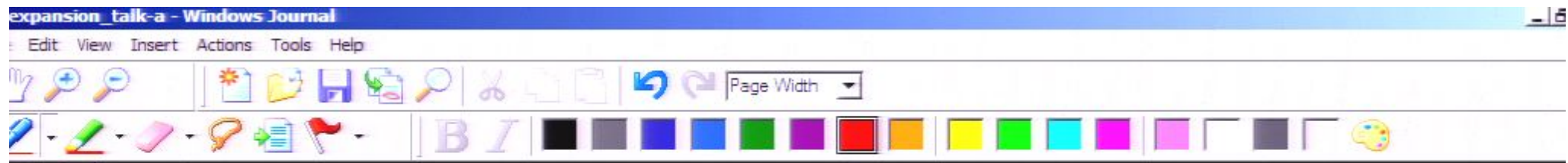
## Graph expansion

Splitting a vertex  $v$  of a graph  $G = \langle V, E \rangle$ :

- Replace  $v$  by two new vertices  $v_1$  and  $v_2$ ;
- Connect  $v_1 v_2$ ;
- Connect each neighbor of  $v$  to either  $v_1$  or  $v_2$ .

Definition. An *expansion* of  $G$  is a graph obtained from  $G$  through a sequence of vertex splitting.



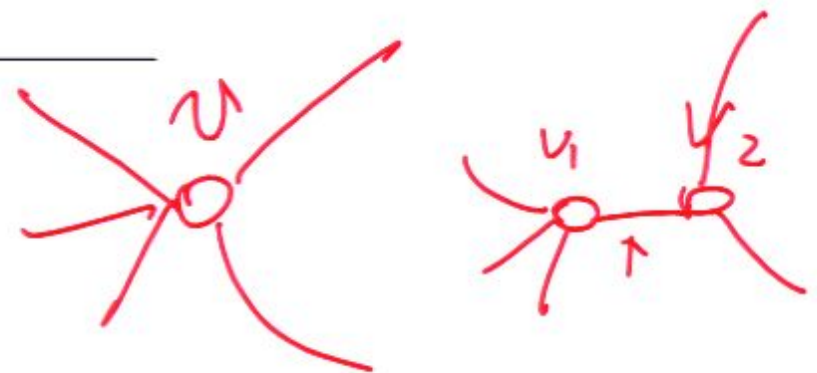


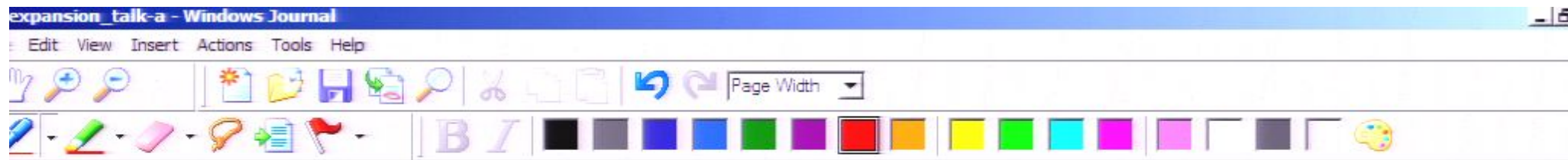
## Graph expansion

Splitting a vertex  $v$  of a graph  $G = \langle V, E \rangle$ :

- Replace  $v$  by two new vertices  $v_1$  and  $v_2$ ;
- Connect  $v_1 v_2$ ;
- Connect each neighbor of  $v$  to either  $v_1$  or  $v_2$ .

Definition. An expansion of  $G$  is a graph obtained from  $G$  through a sequence of vertex splitting.





---

April 30, 2008

Yaoyun Shi 16

---

### Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $|G''\rangle$  that produces  $|G\rangle$ .

Thus a  $T$ -step one-way computation on  $|G\rangle$  can be simulated in time (and space)  
 $O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?



April 30, 2008

Yaoyun Shi 16

## Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $|G''\rangle$  that produces  $|G\rangle$ .



Thus a  $T$ -step one-way computation on  $|G\rangle$  can be simulated in time (and space)  $O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?



April 30, 2008

Yaoyun Shi 16

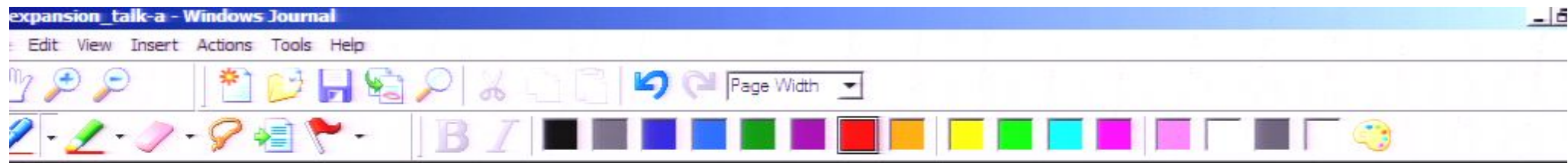
## Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $\underline{G''}$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $\underline{G''}$  that produces  $\underline{G}$ .



Thus a  $T$ -step one-way computation on  $\underline{G''}$  can be simulated in time (and space)  
 $O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?



April 30, 2008

Yaoyun Shi 16

### Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $G''$  that produces  $G$ .

Thus a  $T$ -step one-way computation on  $G$  can be simulated in time (and space)  $O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?





April 30, 2008

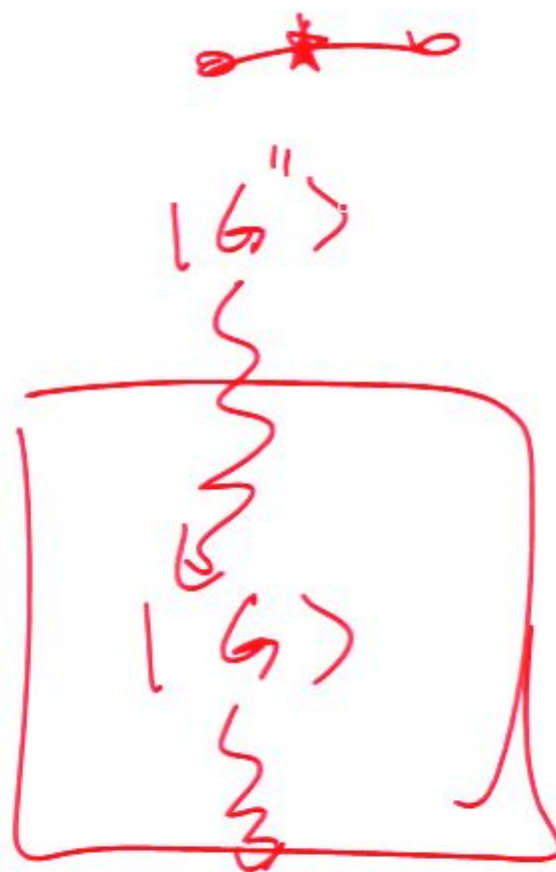
Yaoyun Shi 16

## Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $G''$  that produces  $G$ .

Thus a  $T$ -step one-way computation on  $G$  can be simulated in time (and space)  $O((T + |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?





April 30, 2008

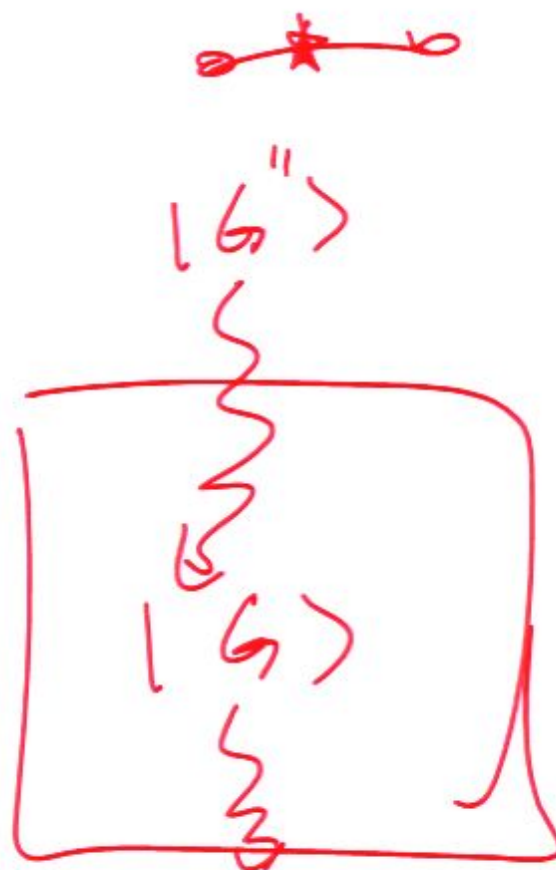
Yaoyun Shi 16

Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $G''$  that produces  $G$ .

Thus a  $T$ -step one-way computation on  $G$  can be simulated in time (and space)  $O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?







April 30, 2008

Yaoyun Shi 16

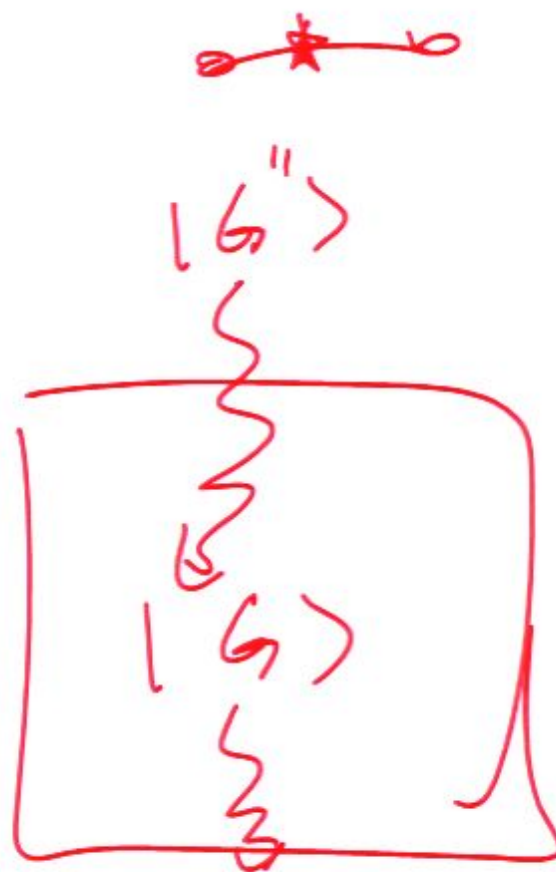
## Use a graph expansion for one-way computation

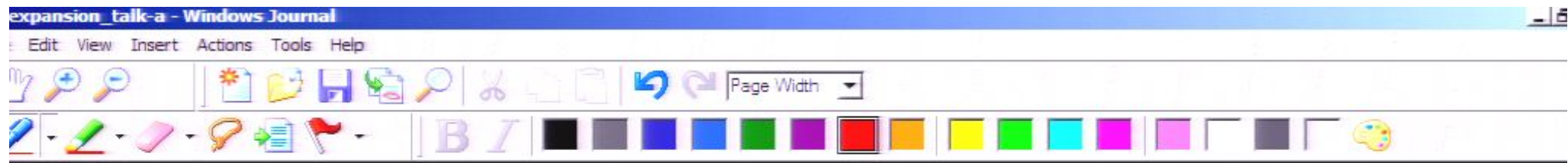
Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $\underline{G''}$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $\underline{G''}$  that produces  $\underline{G}$ .

Thus a  $T$ -step one-way computation on  $\underline{G}$  can be simulated in time (and space)

$$O((T - |V(G'')|) \exp(\Delta(G'') \text{tw}(G''))).$$

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?





April 30, 2008

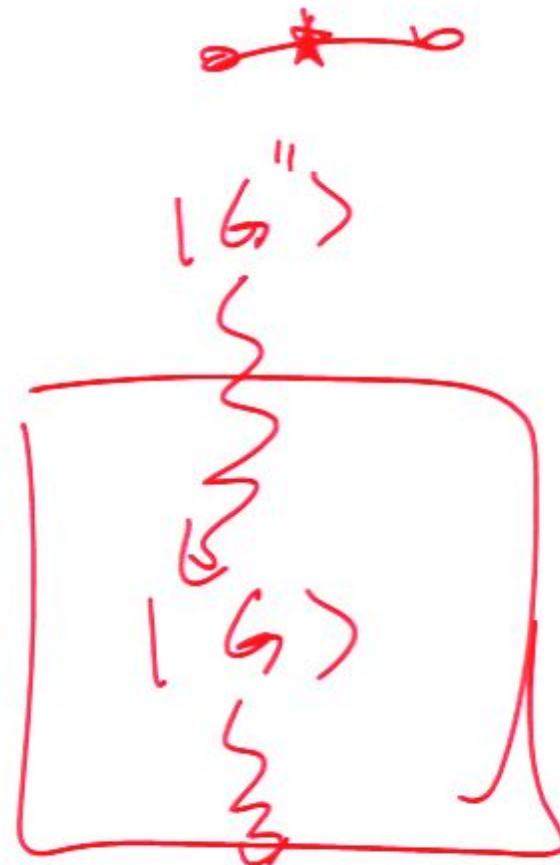
Yaoyun Shi 16

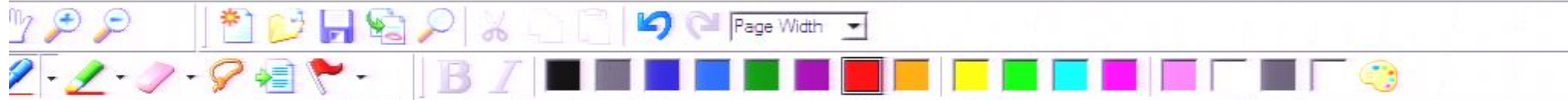
### Use a graph expansion for one-way computation

Fact [RB'01]. Suppose that  $G'$  is an expansion of  $G$ , and  $G''$  is obtained from  $G'$  by inserting a new vertex on each edge. Then there exists a one-way computation on  $G''$  that produces  $G$ .

Thus a  $T$ -step one-way computation on  $G$  can be simulated in time (and space)  $O((T + |V(G'')|) \exp(\Delta(G'') \text{tw}(G'')))$ .

Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $\text{tw}(G'') \approx \text{tw}(G)$ ?





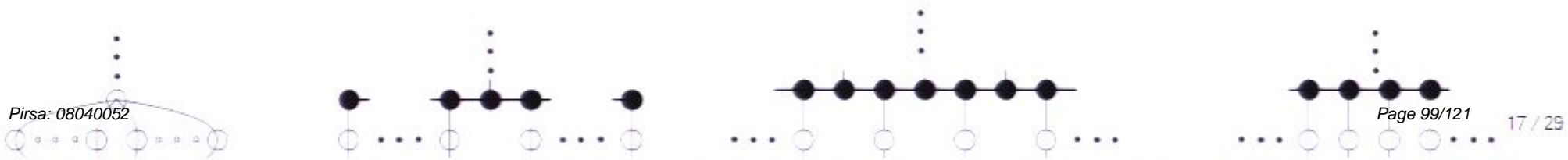
Question: How to expand  $G$  so that  $\Delta(G'') \leq 3$  and  $tw(G'') \approx tw(G)$ ?

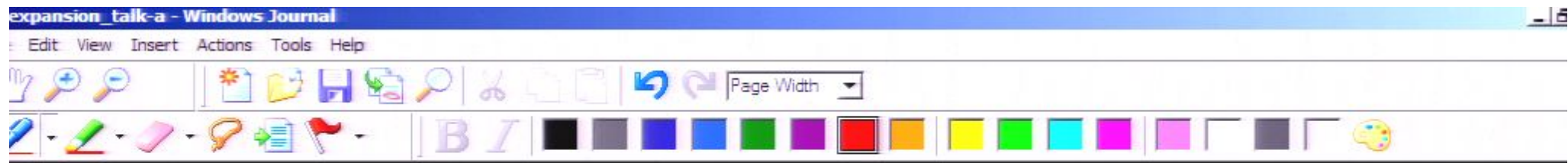


April 30, 2008

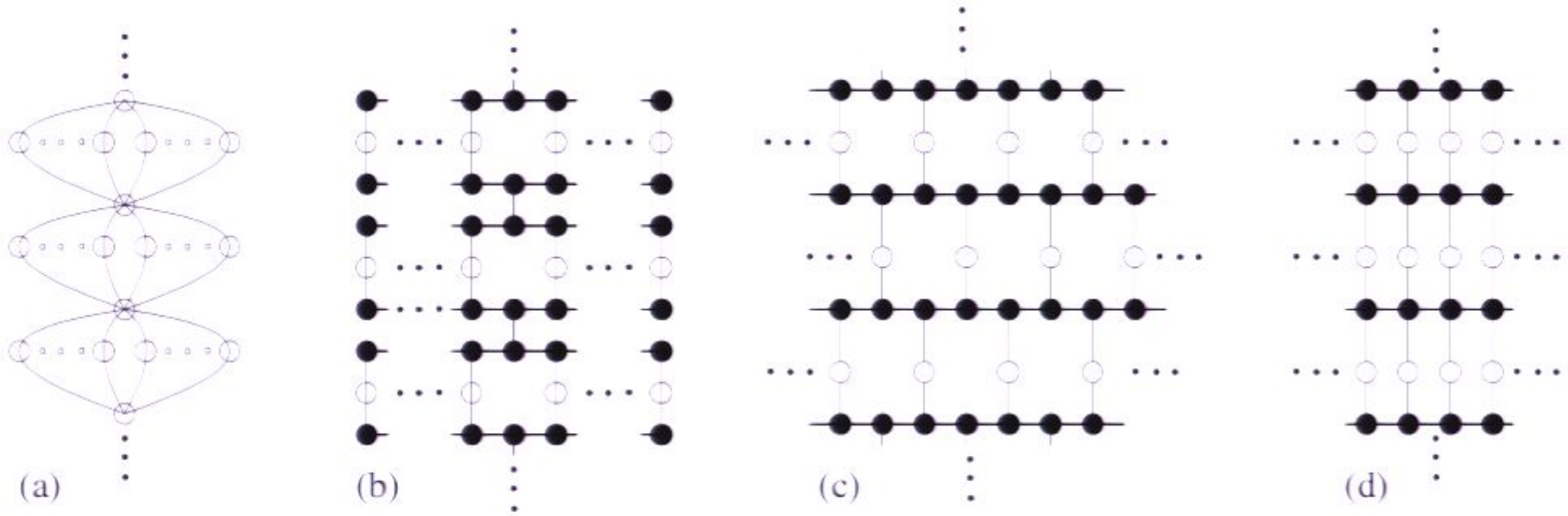
Yaoyun Shi 17

### An example for careless expansion



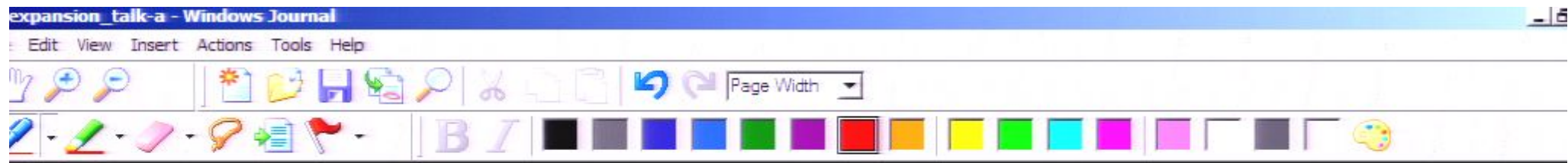


## An example for careless expansion

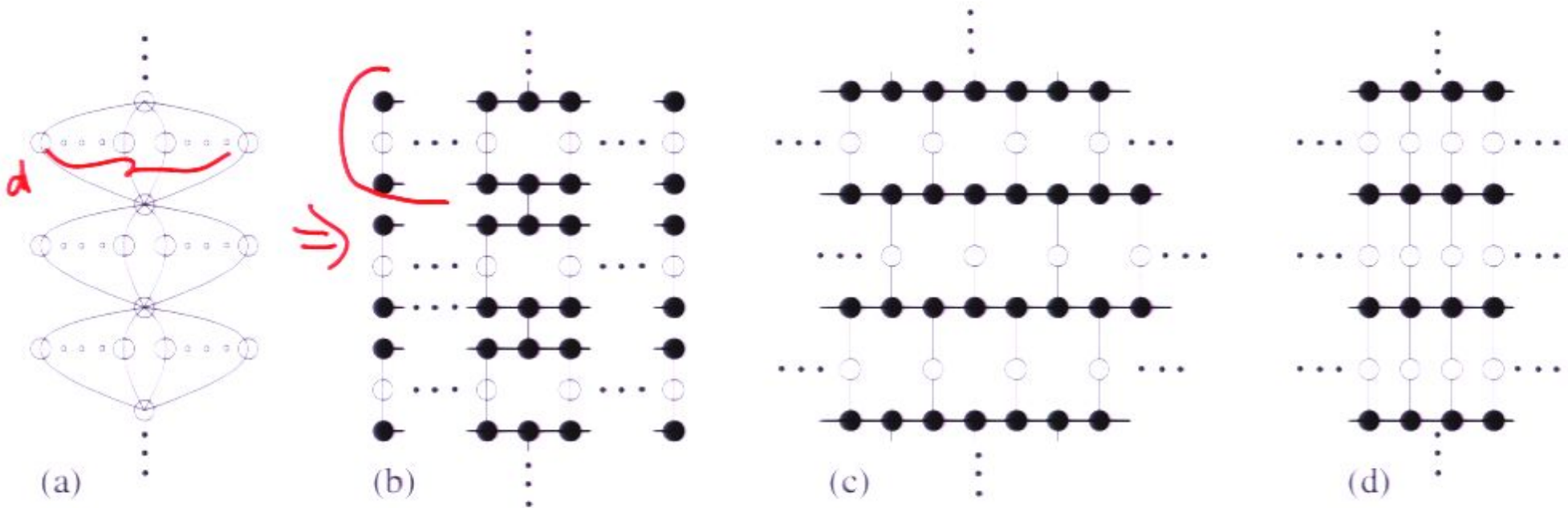


- The graph in (a) has treewidth 2, and
- has a ternary expansion (b) of the same treewidth.

• Another expansion (c) contains a grid

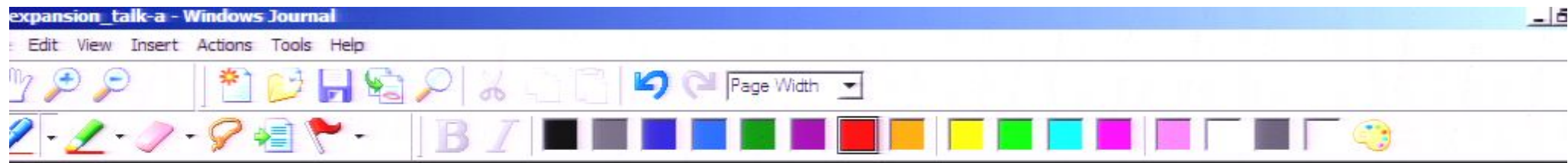


## An example for careless expansion

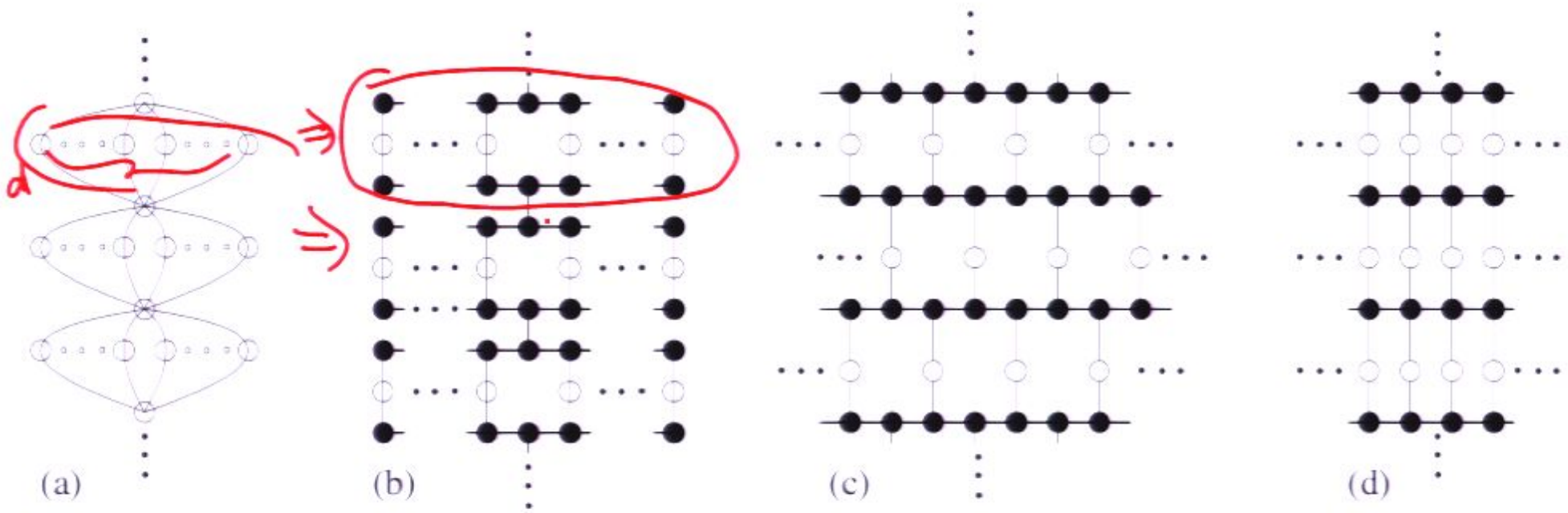


- The graph in (a) has treewidth 2, and
- has a ternary expansion (b) of the same treewidth.

- Another expansion (c) contains a grid



## An example for careless expansion



- The graph in (a) has treewidth 2, and
- has a ternary expansion (b) of the same treewidth.

- Another expansion (c) contains a grid



April 30, 2008

Yaoyun Shi 18

## Main Result

---

- For any graph  $G$  there exists an expansion  $G'$  such that  $\Delta(G') \leq 3$  and  $\text{tw}(G') \leq \text{tw}(G) + 1$ . Such an expansion can be computed efficiently from an optimal tree decomposition of  $G$ .
- There exists a family of graphs so that the increase in treewidth is necessary for any ternary expansions.

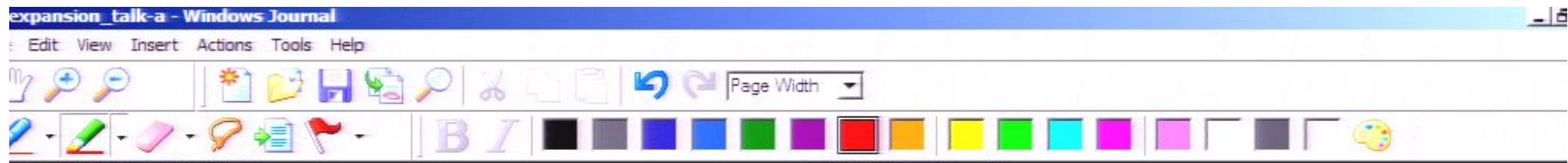


## Main Result

---

- For any graph  $G$  there exists an expansion  $G'$  such that  $\Delta(G') \leq 3$  and  $\text{tw}(G') \leq \text{tw}(G) + 1$ . Such an expansion can be computed efficiently from an optimal tree decomposition of  $G$ .
- There exists a family of graphs so that the increase in treewidth is necessary for any ternary expansions.





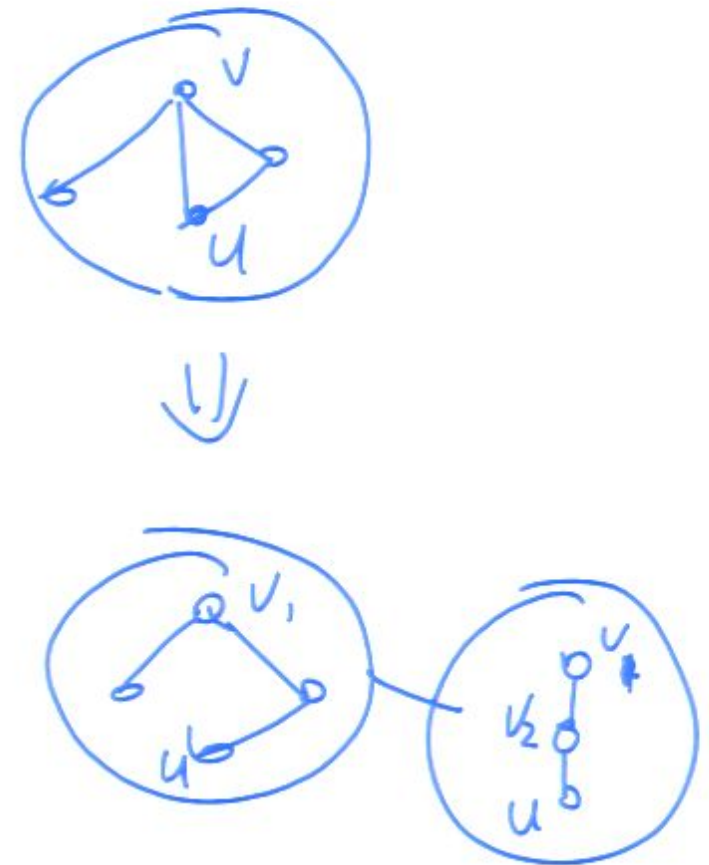
## Reducing in-bag max degree

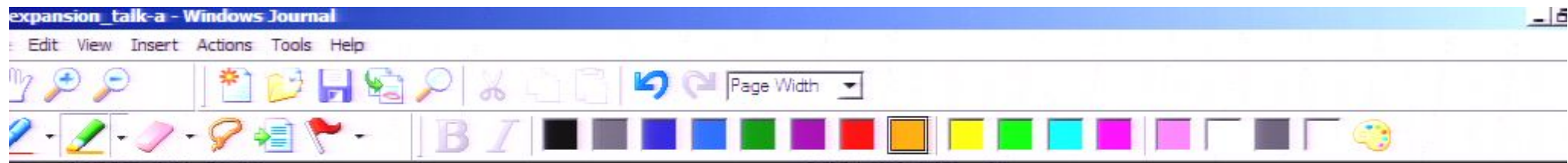
Fix a tree decomposition  $\mathcal{T}$  of  $G$ .

For each bag  $B$  and each  $v \in B$ , if  $v$  has  $\geq 3$  neighbors in  $B$ ,

- Split  $v \rightarrow v_1 v_2$ .
- Attach a neighbor  $u \in B$  to  $v_2$ , and all other neighbors to  $v_1$ .
- Create a new bag  $\{v_2, v_1, u\}$  and attach it to  $B$ .

We can now assume that each vertex has  $\leq 2$  neighbors in each bag.





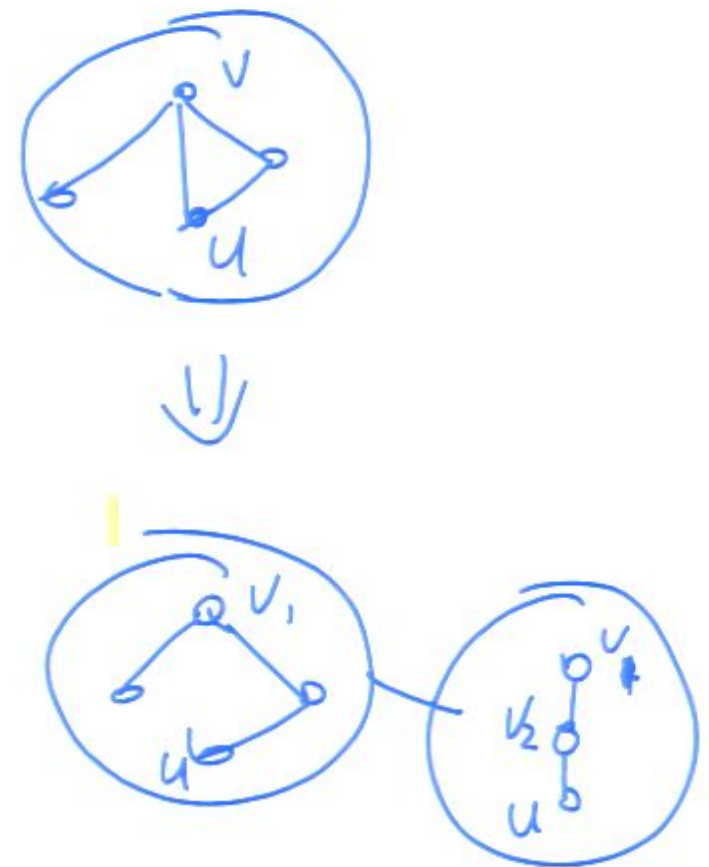
## Reducing in-bag max degree

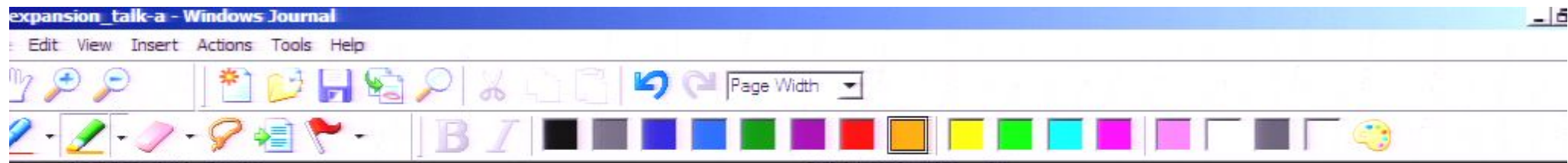
Fix a tree decomposition  $\mathcal{T}$  of  $G$

For each bag  $B$  and each  $v \in B$ , if  $v$  has  $\geq 3$  neighbors in  $B$ ,

- Split  $v \rightarrow v_1 v_2$ .
- Attach a neighbor  $u \in B$  to  $v_2$ , and all other neighbors to  $v_1$ .
- Create a new bag  $\{v_2, v_1, u\}$  and attach it to  $B$ .

We can now assume that each vertex has  $\leq 2$  neighbors in each bag.





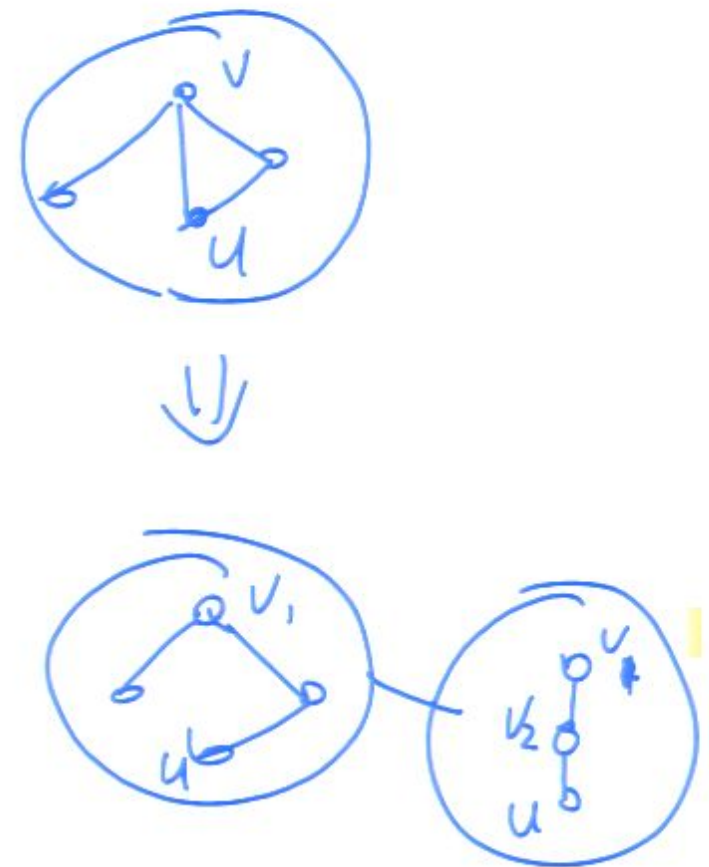
## Reducing in-bag max degree

Fix a tree decomposition  $\mathcal{T}$  of  $G$

For each bag  $B$  and each  $v \in B$ , if  $v$  has  $\geq 3$  neighbors in  $B$ ,

- Split  $v \rightarrow v_1 v_2$ .
- Attach a neighbor  $u \in B$  to  $v_2$ , and all other neighbors to  $v_1$ .
- Create a new bag  $\{v_2, v_1, u\}$  and attach it to  $B$ .

We can now assume that each vertex has  $\leq 2$  neighbors in each bag.





## Constructing the expansion

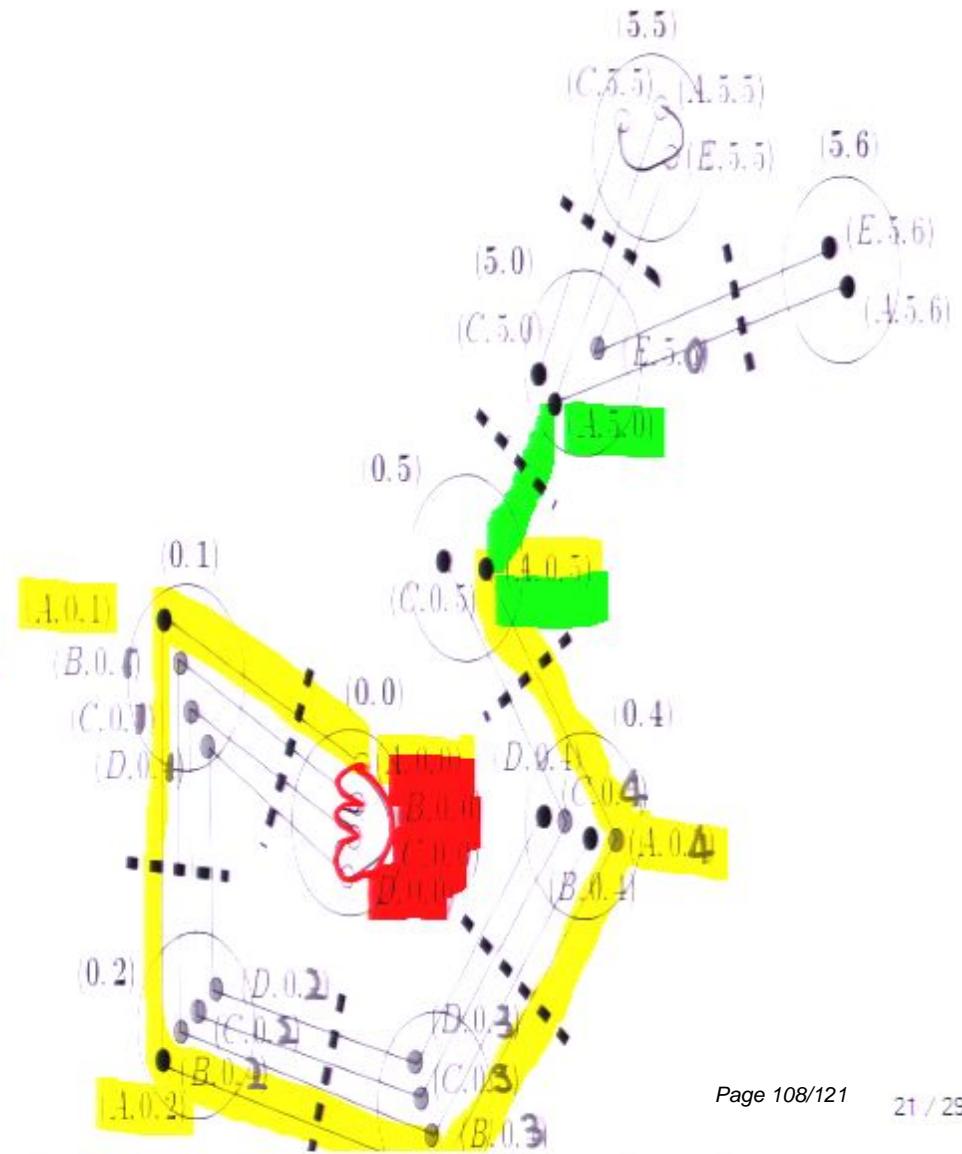
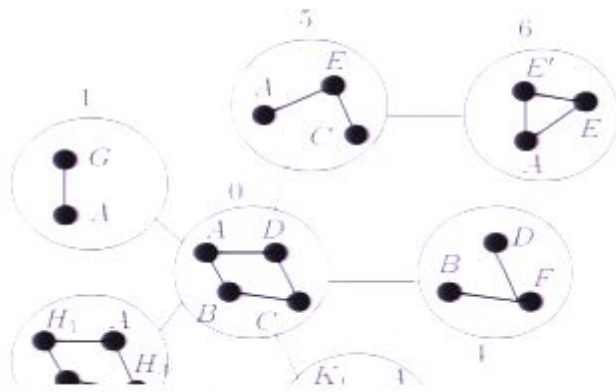
For each bag  $B_0$  with adjacent bags  $B_1, B_2, \dots, B_t$ , and each  $v \in B_0$ , create a path graph

$$(v, B_0, B_0) - (v, B_0, B_1) - \dots - (v, B_0, B_t).$$

Add the following edges

- If  $v \in B \cap B'$ , connect  $(v, B, B') - (v, B', B)$ .
- For each edge  $uv \in E(G)$ , fix a bag  $B_0$  with  $u, v \in B_0$ , connect  $(u, B_0, B_0) - (v, B_0, B_0)$ .

Call the resulting graph  $G'$ .





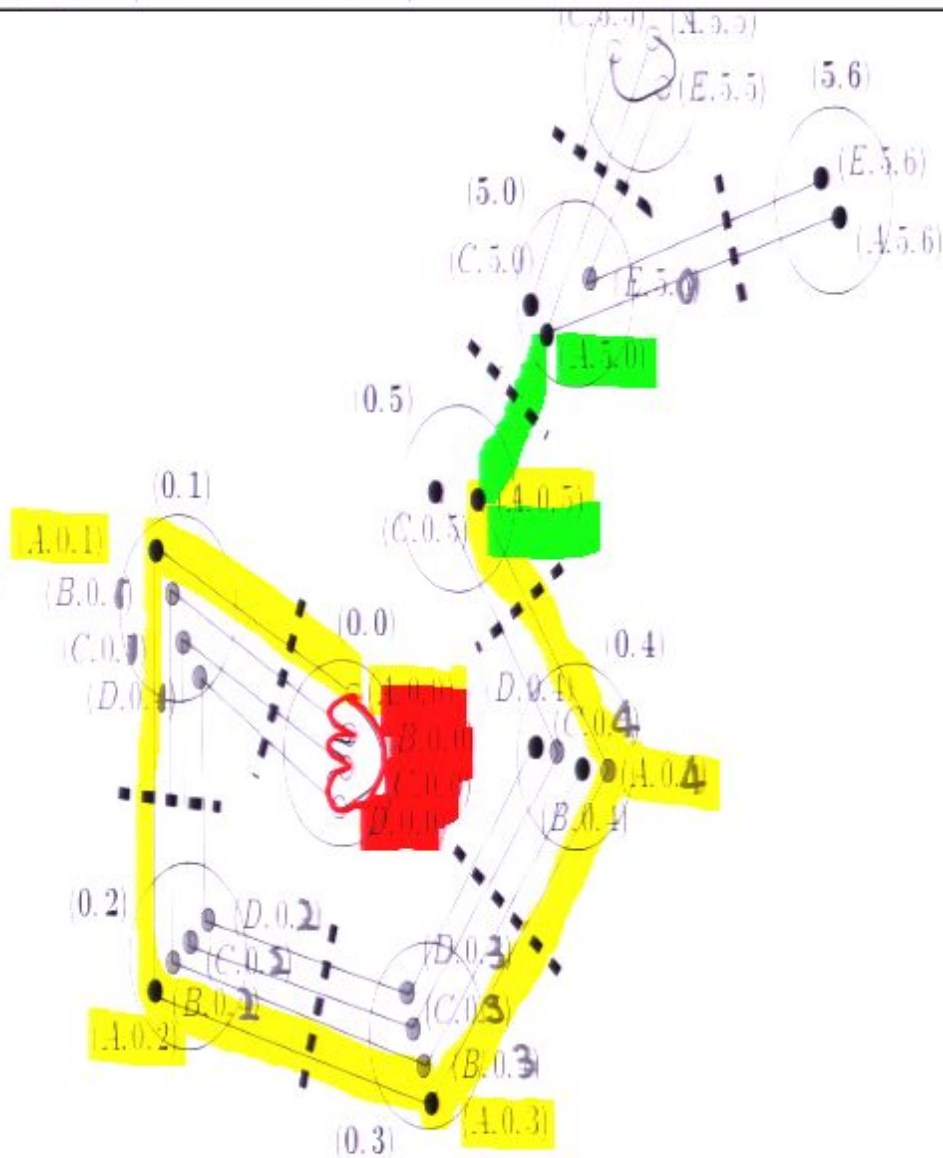
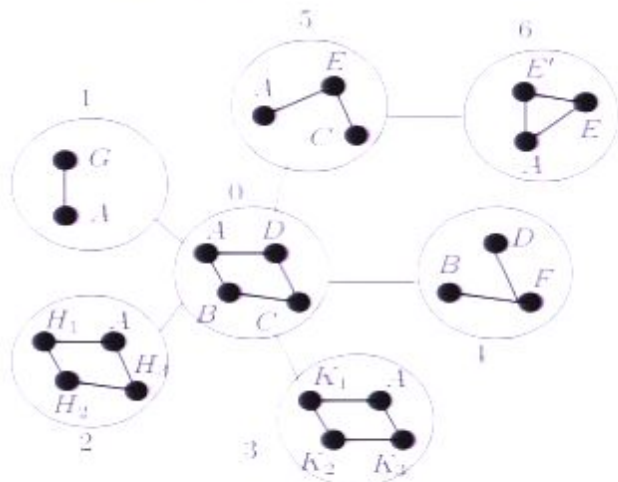
$B_t$ , and each  $v \in B_0$ , create a path graph

$$(v, B_0, B_0) - (v, B_0, B_1) - \dots - (v, B_0, B_t).$$

Add the following edges

- If  $v \in B \cap B'$ , connect  $(v, B, B') - (v, B', B)$ .
- For each edge  $uv \in E(G)$ , fix a bag  $B_0$  with  $u, v \in B_0$ , connect  $(u, B_0, B_0) - (v, B_0, B_0)$ .

Call the resulting graph  $G'$ .





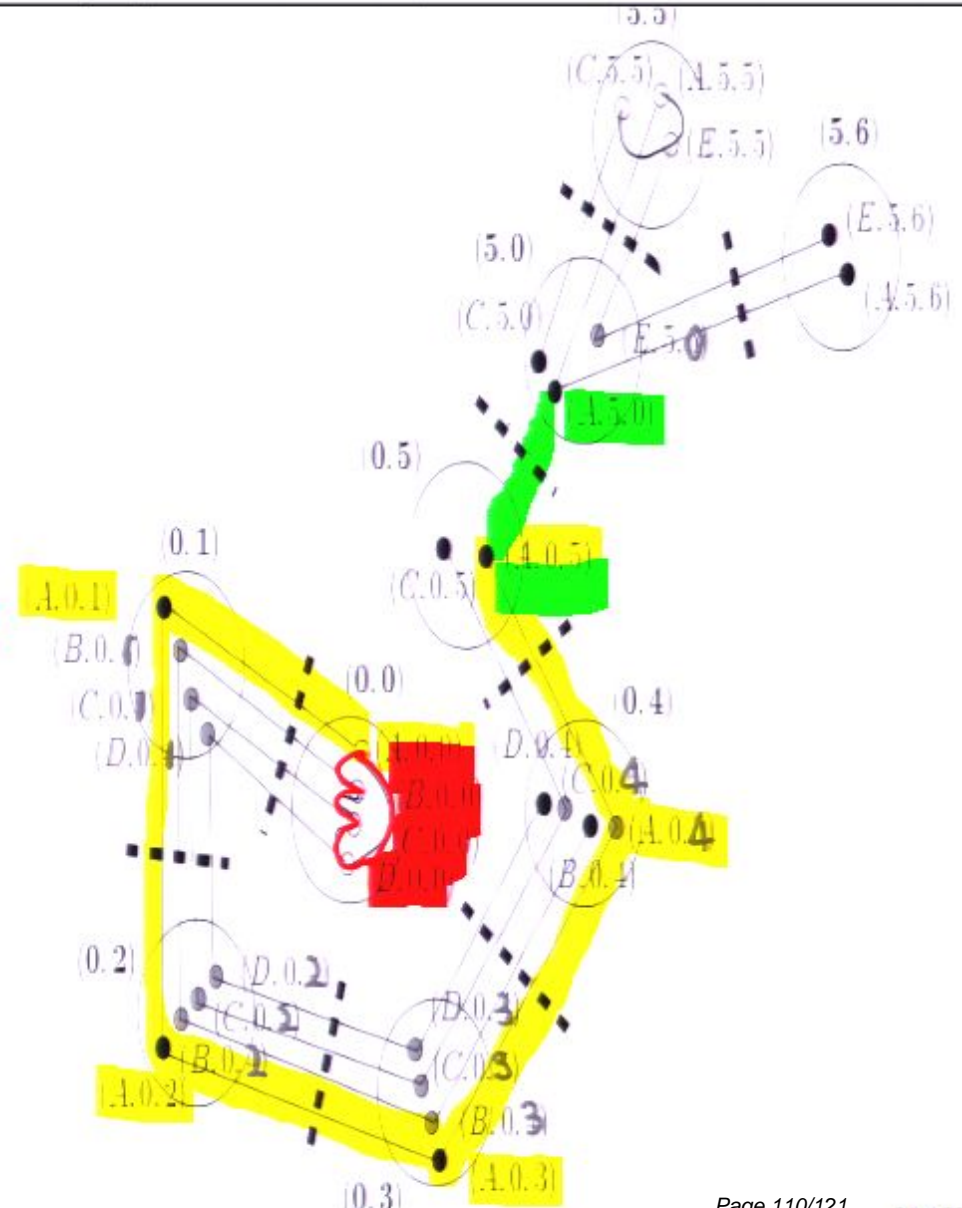
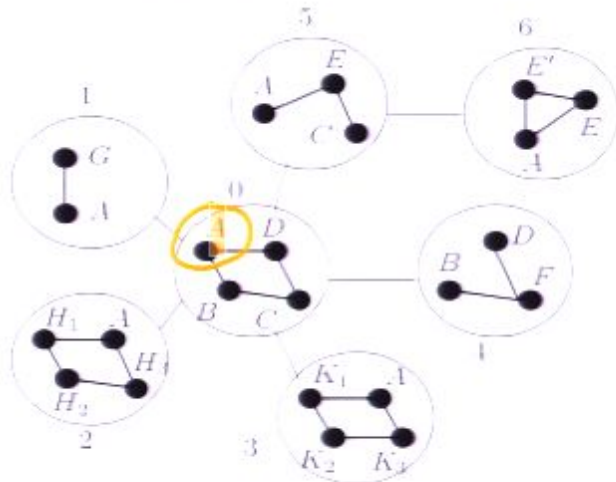
For each bag  $B_0$  with adjacent bags  $B_1, B_2, \dots, B_t$ , and each  $v \in B_0$ , create a path graph

$$(v, B_0, B_0) - (v, B_0, B_1) - \dots - (v, B_0, B_t).$$

Add the following edges

- If  $v \in B \cap B'$ , connect  $(v, B, B') - (v, B', B)$ .
- For each edge  $uv \in E(G)$ , fix a bag  $B_0$  with  $u, v \in B_0$ , connect  $(u, B_0, B_0) - (v, B_0, B_0)$ .

Call the resulting graph  $G'$ .





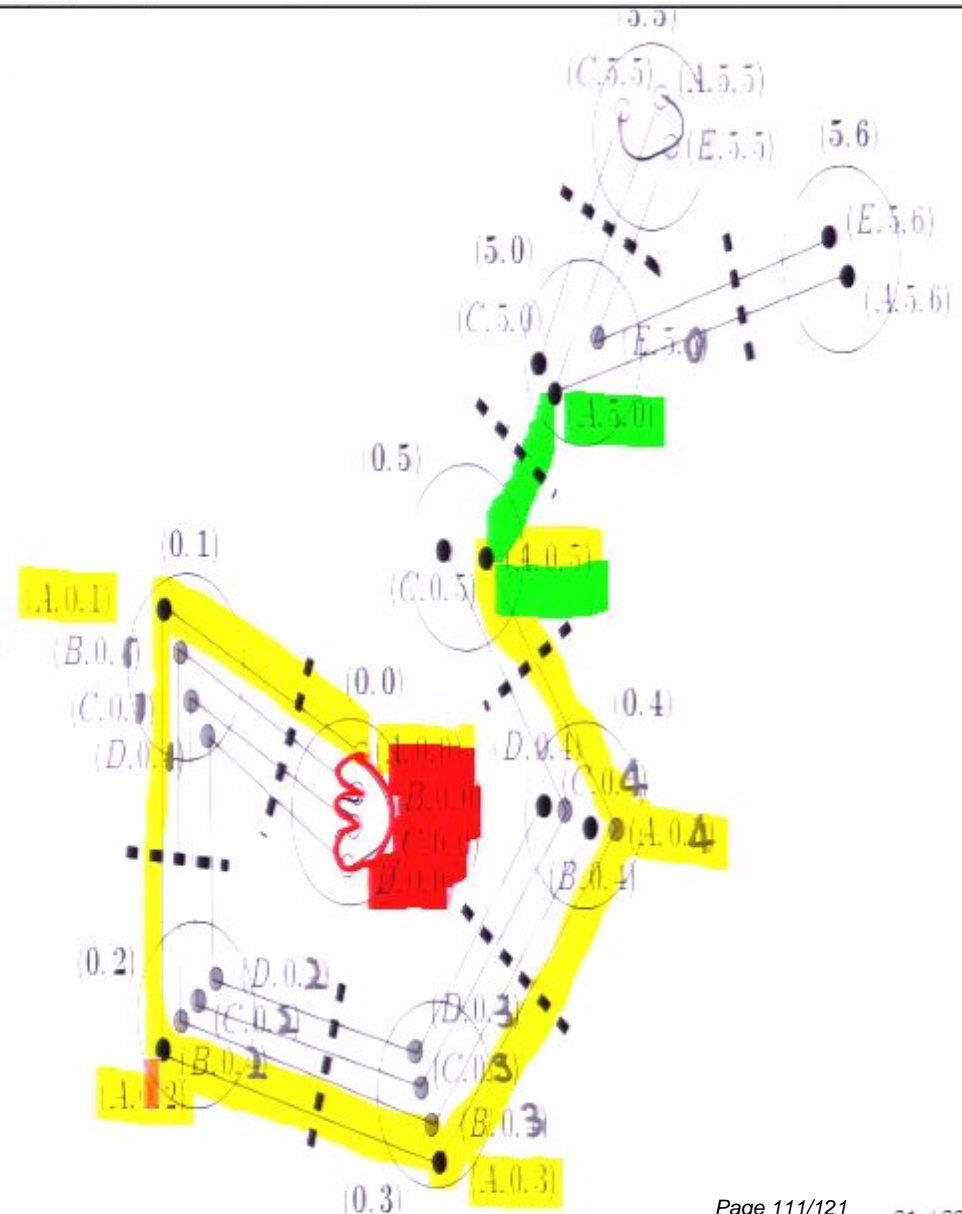
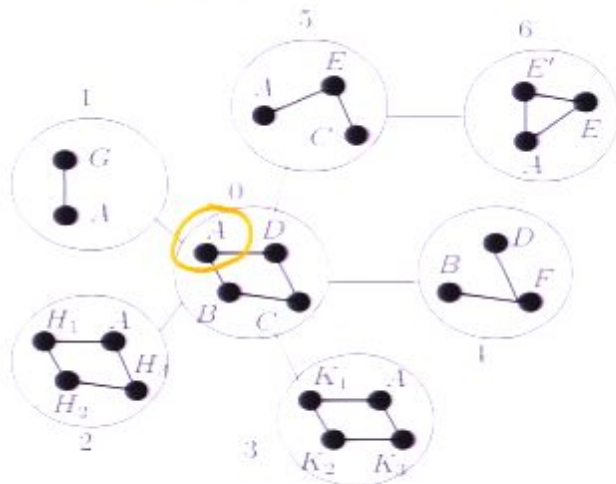
For each bag  $B_0$  with adjacent bags  $B_1, B_2, \dots, B_t$ , and each  $v \in B_0$ , create a path graph

$$(v, B_0, B_0) - (v, B_0, B_1) - \dots - (v, B_0, B_t).$$

Add the following edges

- If  $v \in B \cap B'$ , connect  $(v, B, B') - (v, B', B)$ .
- For each edge  $uv \in E(G)$ , fix a bag  $B_0$  with  $u, v \in B_0$ , connect  $(u, B_0, B_0) - (v, B_0, B_0)$ .

Call the resulting graph  $G'$ .





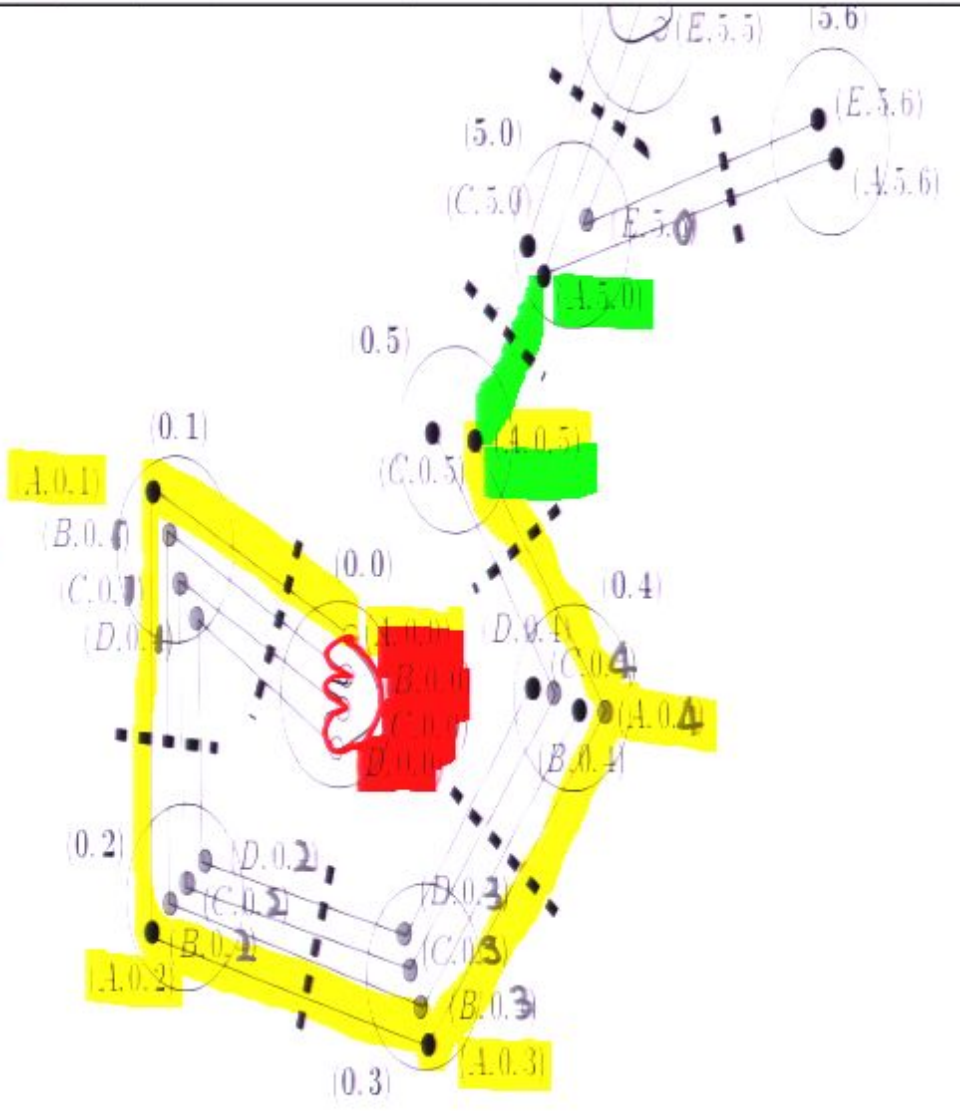
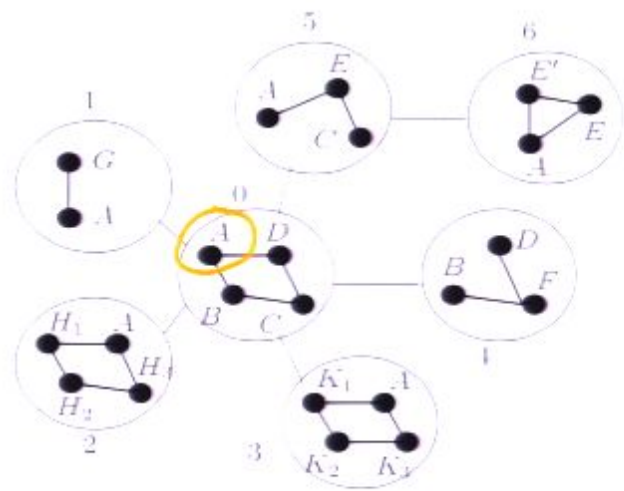
$B_t$ , and each  $v \in B_0$ , create a path graph

$$(v, B_0, B_0) - (v, B_0, B_1) - \dots - (v, B_0, B_t).$$

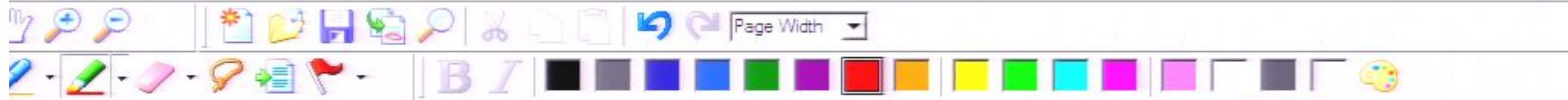
Add the following edges

- If  $v \in B \cap B'$ , connect  $(v, B, B') - (v, B', B)$ .
- For each edge  $uv \in E(G)$ , fix a bag  $B_0$  with  $u, v \in B_0$ , connect  $(u, B_0, B_0) - (v, B_0, B_0)$ .

Call the resulting graph  $G'$ .







Three types of bags:

- For each bag  $B$  of  $\mathcal{T}$ , create a bag

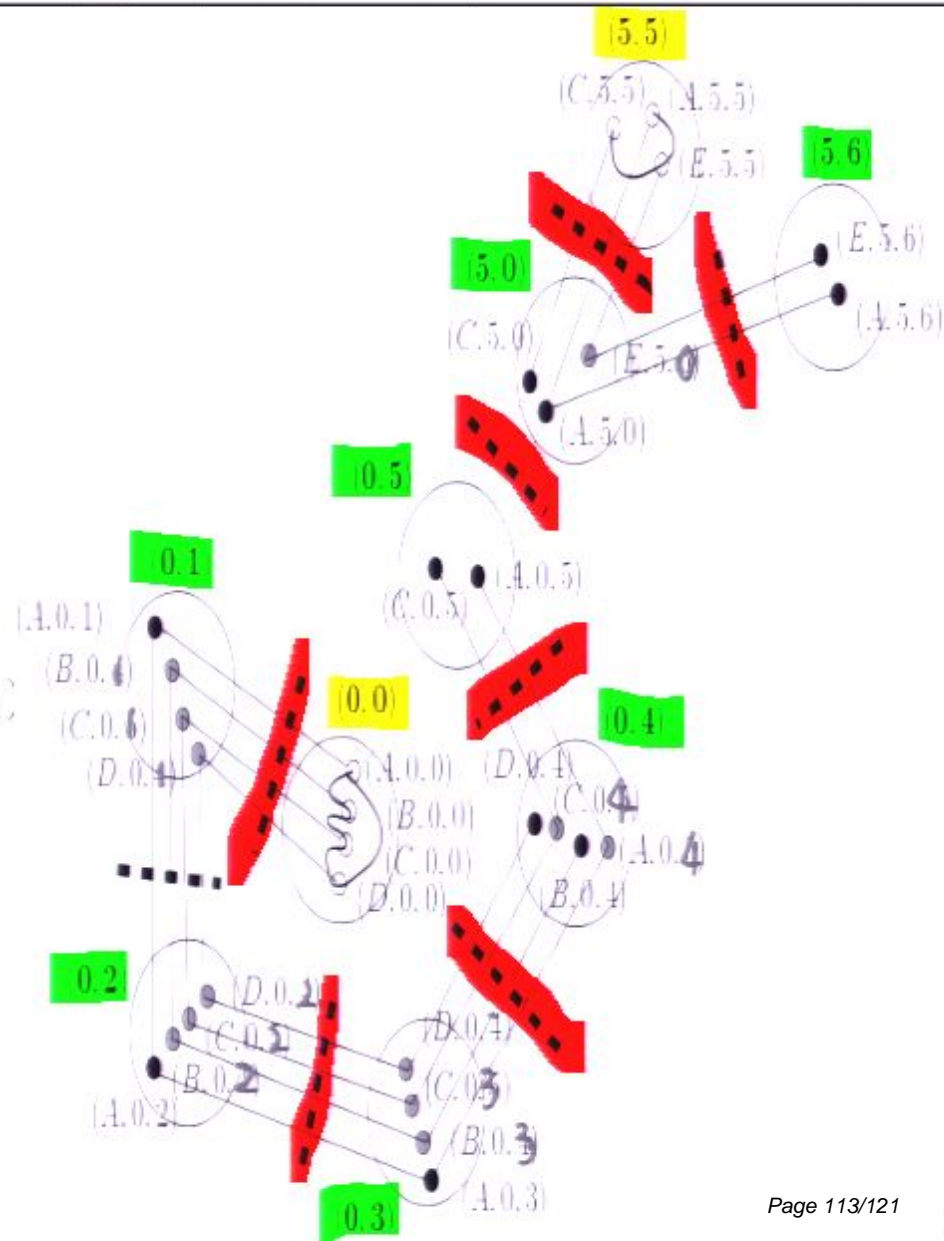
$$(B, B) = \{(v, B, B) : v \in B\}.$$

This bag covers all edges between vertex trees.

- For adjacent bags  $B_0 B_i$  in  $\mathcal{T}$ , create

$$(B_0, B_i) = \{(v, B_0, B_i) : v \in B\}.$$

- “Bridge” the bags  $(B_0, B_i)$  and  $(B_0, B_{i-1})$  and the bags  $(B, B')$  and  $(B', B)$  by a chain of bags.





- $A \cap B = \{u_1, \dots, u_s\}$ , and
- $E_{AB} \stackrel{\text{def}}{=} \{v_i v'_i : 1 \leq i \leq t\}$ , are edges in  $G'$ .

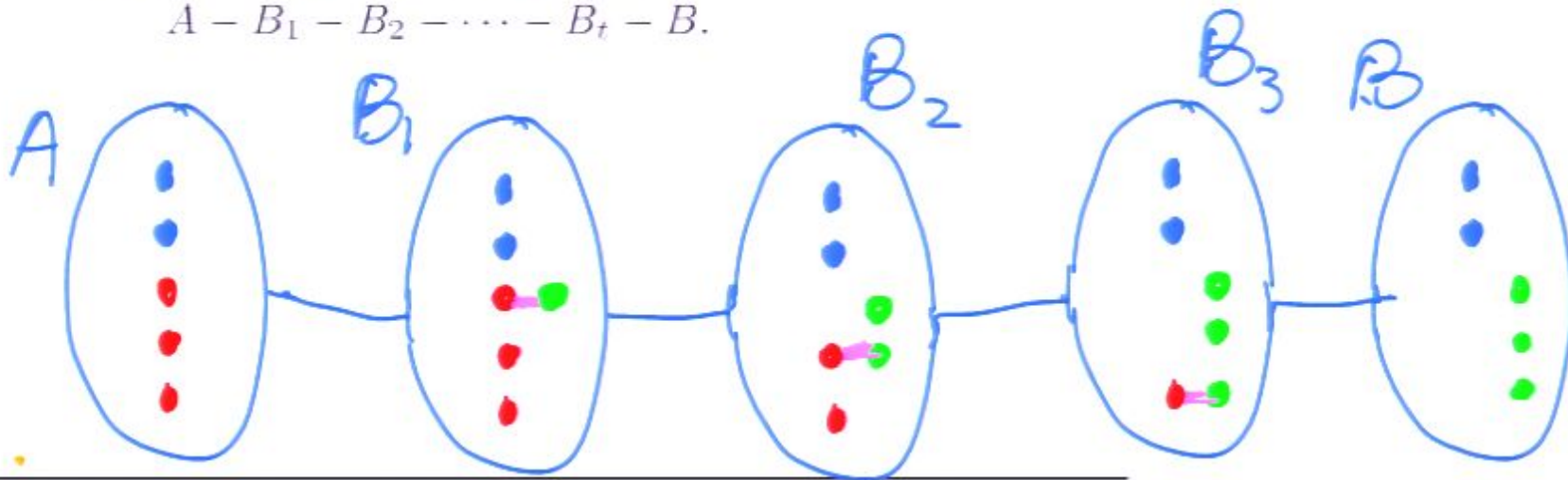
*Bridging* the two bags to cover  $E_{AB}$ :

(Step 1) Create bags  $B_1, B_2, \dots, B_t$ , where

$$B_i = (A \cap B) \cup \{v'_1, v'_2, \dots, v'_{i-1}, v'_i, v_i, v_{i+1}, \dots, v_t\}.$$

(Step 2) Form a path graph of bags

$$A - B_1 - B_2 - \dots - B_t - B.$$





- $A \cap B = \{u_1, \dots, u_s\}$ , and
- $E_{AB} \stackrel{\text{def}}{=} \{v_i v'_i : 1 \leq i \leq t\}$ , are edges in  $G'$ .

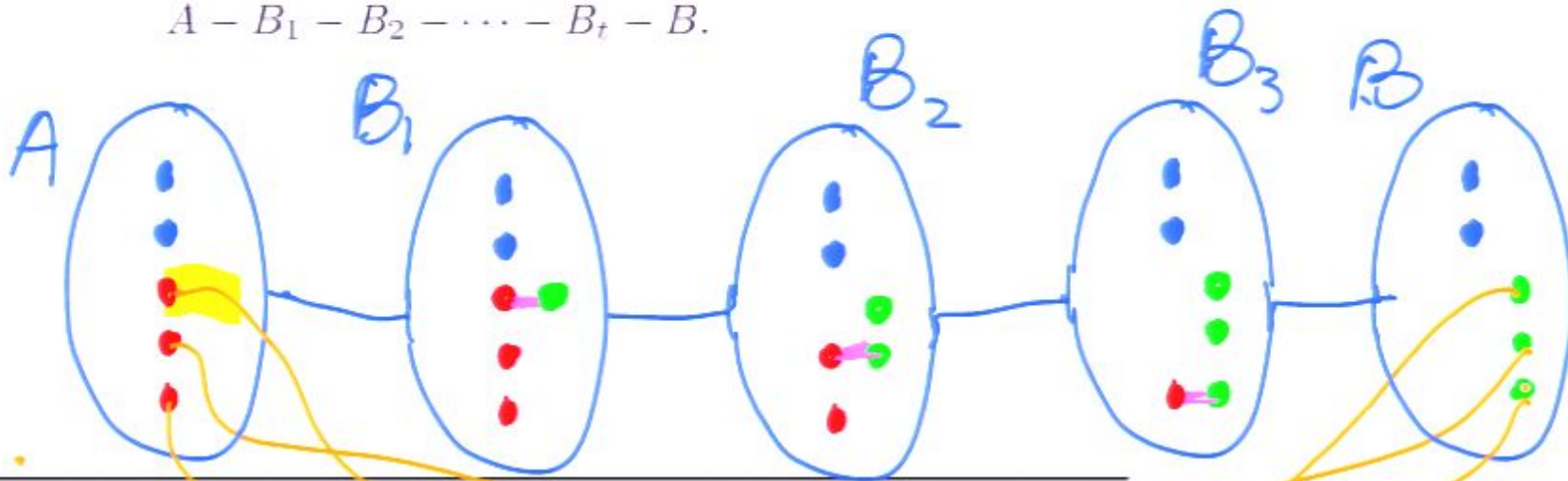
*Bridging* the two bags to cover  $E_{AB}$ :

(Step 1) Create bags  $B_1, B_2, \dots, B_t$ , where

$$B_i = (A \cap B) \cup \{v'_1, v'_2, \dots, v'_{i-1}, v'_i, v_i, v_{i+1}, \dots, v_t\}.$$

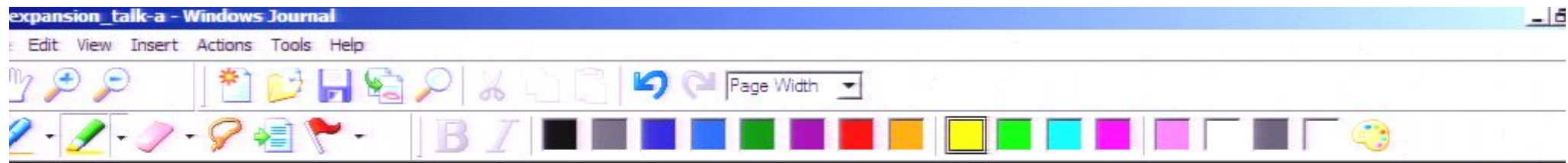
(Step 2) Form a path graph of bags

$$A - B_1 - B_2 - \dots - B_t - B.$$



April 30, 2008

Yaoyun Shi 24



## Open problems

---

- Which states are universal for measurement-based computation?
  - A universal state does not need to be a graph state [Gross and Eisert '06...]
  - A definition of universality.  
A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = \text{poly}(m)$ , that creates the same state as the final state of the circuit.
- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).

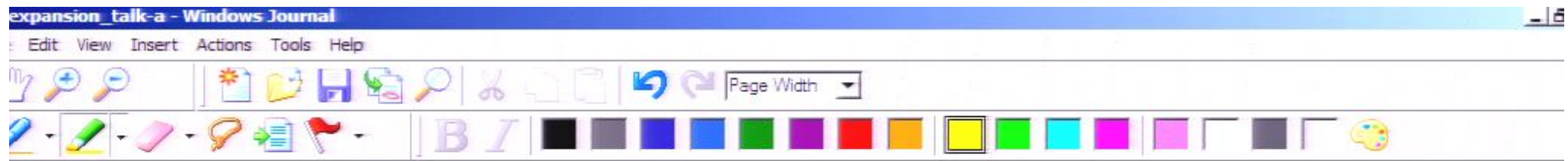


measurement-based computation?

- A universal state does not need to be a graph state [Gross and Eisert '06...]
- A definition of universality.

A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = poly(m)$ , that creates the same state as the final state of the circuit.

- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).
  - A reduction from a BQP problem to  $\exists\forall\cdots SAT$ , for a constant number of alternations of the quantifiers?

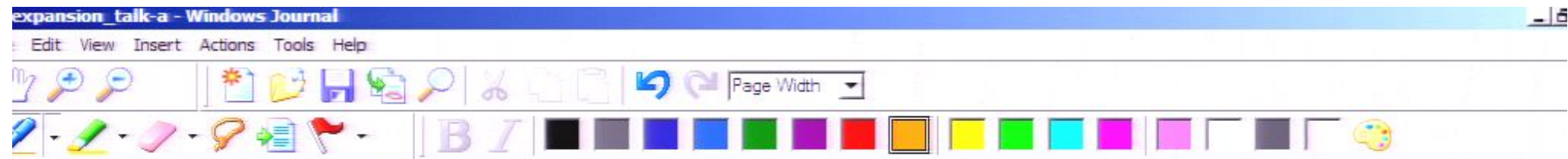


measurement-based computation?

- A universal state does not need to be a graph state [Gross and Eisert '06...]
- A definition of universality.

A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = poly(m)$ , that creates the same state as the final state of the circuit.

- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).
  - A reduction from a BQP problem to  $\exists\forall\cdots SAT$ , for a constant number of alternations of the quantifiers?



measurement-based computation?

- A universal state does not need to be a graph state [Gross and Eisert '06...]
- A definition of universality.

A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = poly(m)$ , that creates the same state as the final state of the circuit.

$$\exists x_1, x_2, \dots, x_n \rightarrow \forall y_1, y_2, \dots, y_n \rightarrow \exists z_1, z_2, \dots, z_n \rightarrow \phi(x_1, \dots, x_n)$$

- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).
  - A reduction from a BQP problem to  $\exists \forall \dots SAT$ , for a constant number of alternations of the quantifiers?



measurement-based computation?

- A universal state does not need to be a graph state [Gross and Eisert '06...]
- A definition of universality.

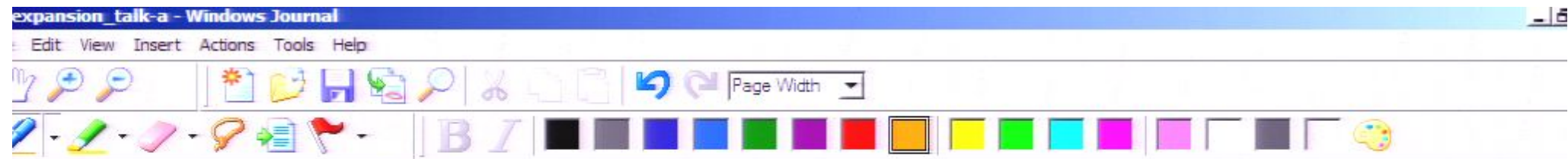
A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = poly(m)$ , that creates the same state as the final state of the circuit.

$$\exists x_1, x_2, \dots, x_n \rightarrow \forall y_1, y_2, \dots, y_n \rightarrow \exists z_1, z_2, \dots, z_n \rightarrow \phi(x_1, \dots, x_n)$$

constant

- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).
  - A reduction from a BQP problem to  $\exists \forall \dots SAT$ , for a constant number of alternations of the quantifiers?





measurement-based computation?

- A universal state does not need to be a graph state [Gross and Eisert '06...]
- A definition of universality.

A family of states  $|S_n\rangle$  on  $n$  qubits is universal if for any quantum circuit of size  $m$ , there exists a measurement-based quantum computation on  $|S_n\rangle$ , for some  $n = poly(m)$ , that creates the same state as the final state of the circuit.

$\exists$

$\exists x_1, x_2, \dots, x_n \rightarrow \forall y_1, y_2, \dots, y_n \rightarrow \exists z_1, z_2, \dots, z_n \rightarrow \phi(x_1, \dots, x_n)$   
constant

- Sharpen the classical upper bound of BQP (the class of functions computable by a polynomial time quantum algorithm).
  - A reduction from a BQP problem to  $\exists \forall \dots SAT$ , for a constant number of alternations of the quantifiers?