

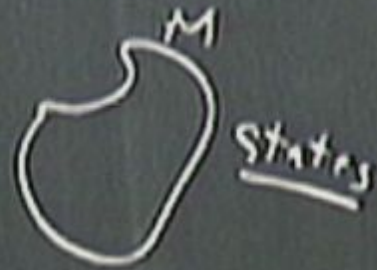
Title: Combining An Infinite Number of Quantum Systems

Date: Mar 13, 2008 11:00 AM

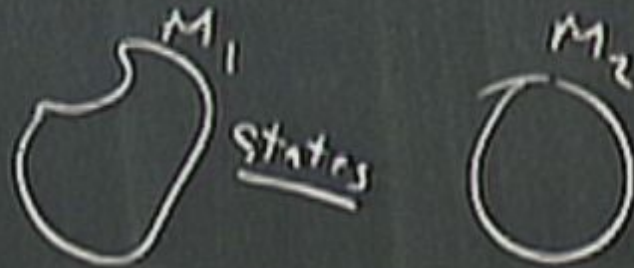
URL: <http://pirsa.org/08030029>

Abstract: A single classical system is characterized by its manifold of states; and to combine several systems, we take the product of manifolds. A single quantum system is characterized by its Hilbert space of states; and to combine several systems, we take the tensor product of Hilbert spaces. But what if we choose to combine an infinite number of systems? A naive attempt to describe such combinations fails, for there is apparently no natural notion of an infinite product of manifolds; nor of an infinite tensor product of Hilbert spaces. But, at least in the quantum case, the situation is not as hopeless as it might appear. We argue that there does indeed exist a natural mathematical framework for combinations of infinite numbers of quantum systems.

Class mock

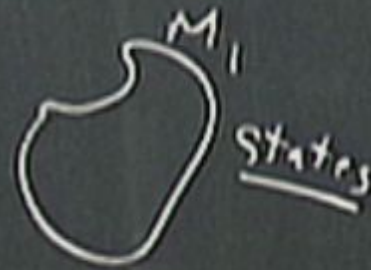


Class mech



$M_1 \times M_2$

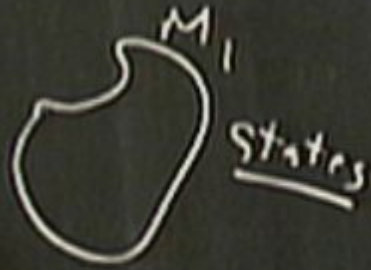
Class mock



$$M_1 \times M_2$$

(States)

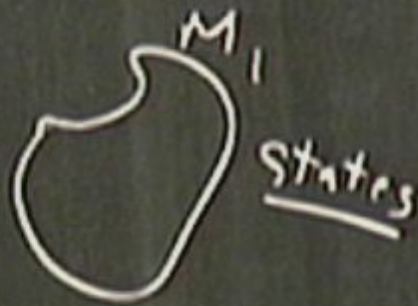
Class mock



$M_1 \times M_2$
(x, y)



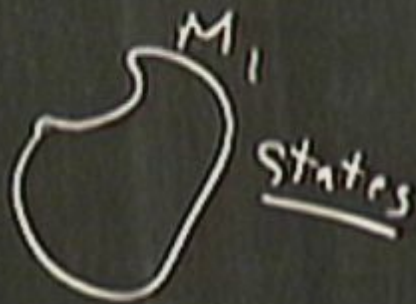
Class mech



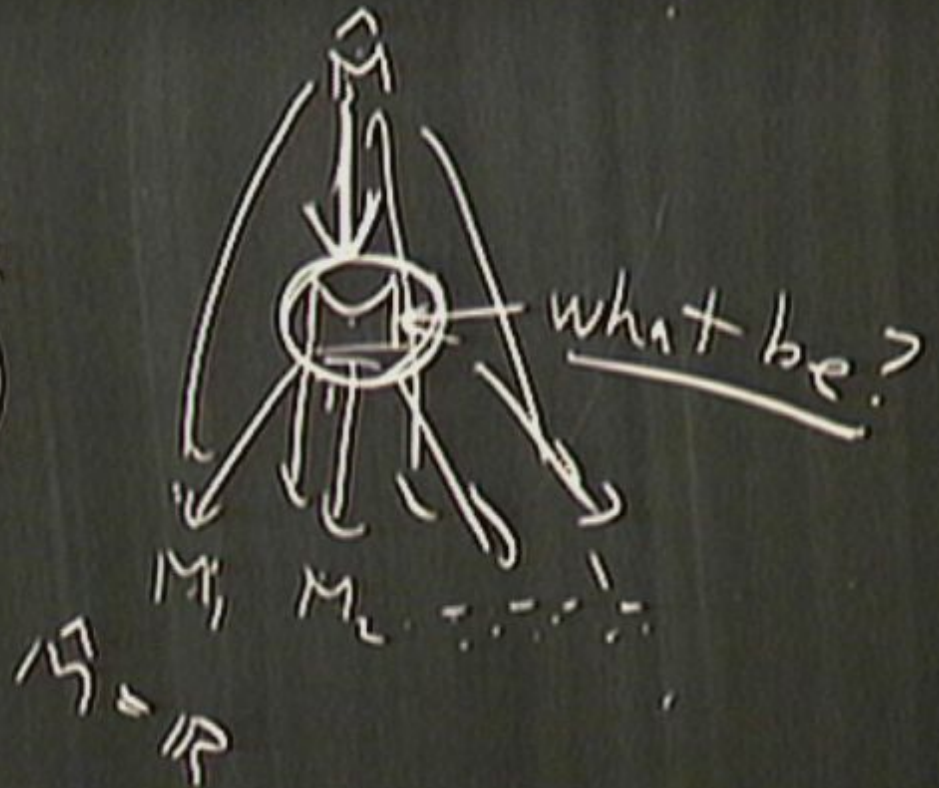
$$\frac{M_1 \times M_2}{(x, x)}$$



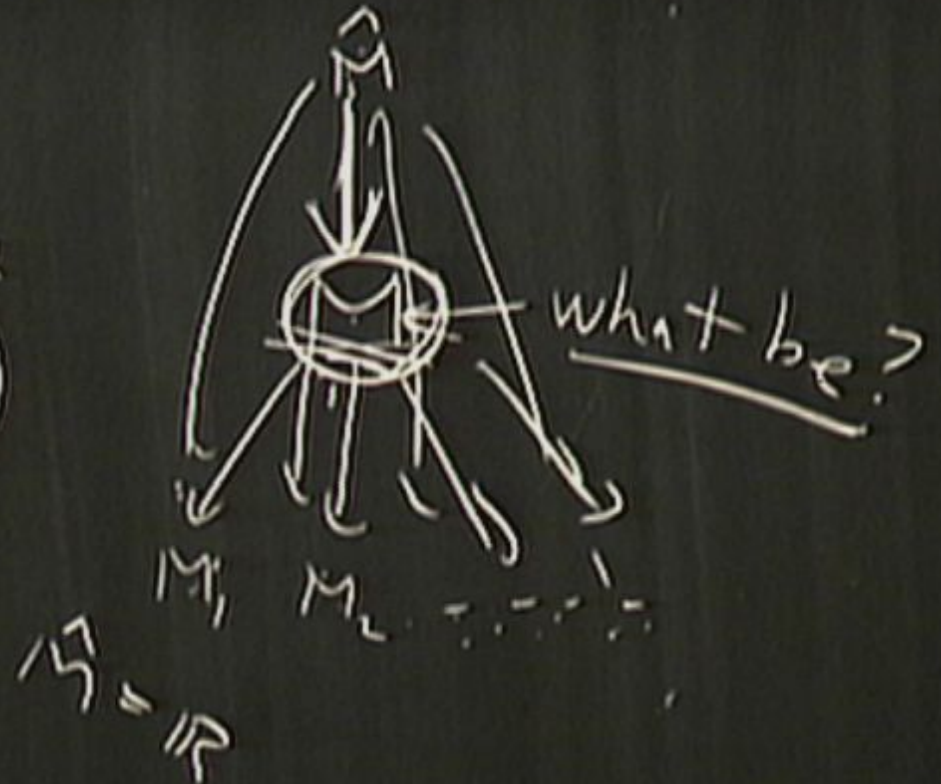
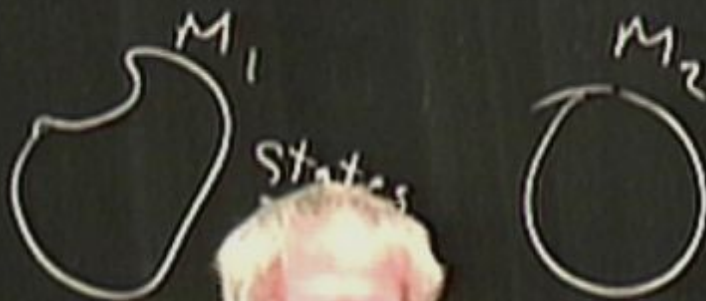
Class mech



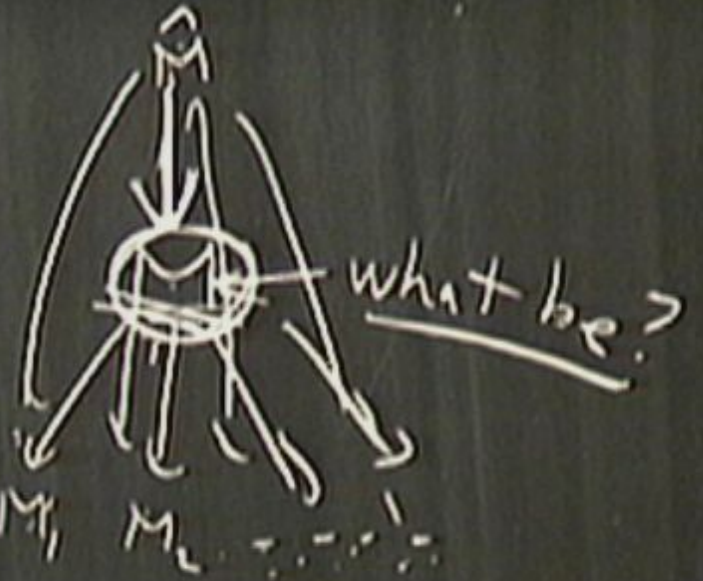
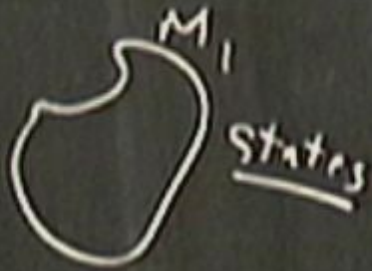
$$\frac{M_1 \times M_2}{(x, x)}$$



Class mock



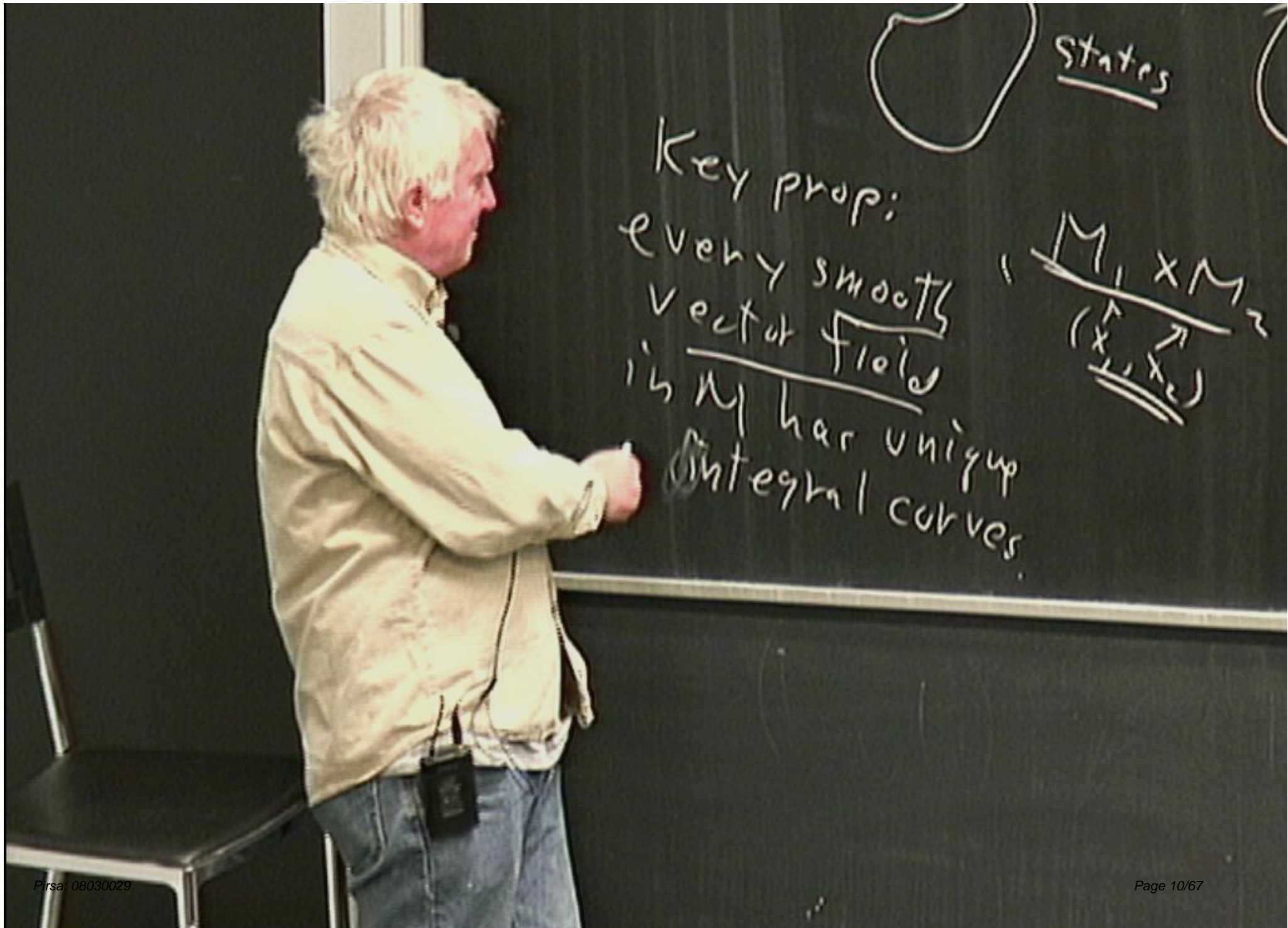
Class mock



Key prop:
every smooth
vector field
in M has unique
integral curves

$$\frac{M_1 \times M_2}{(x, y)}$$

$$\mathbb{R} = \mathbb{R}$$

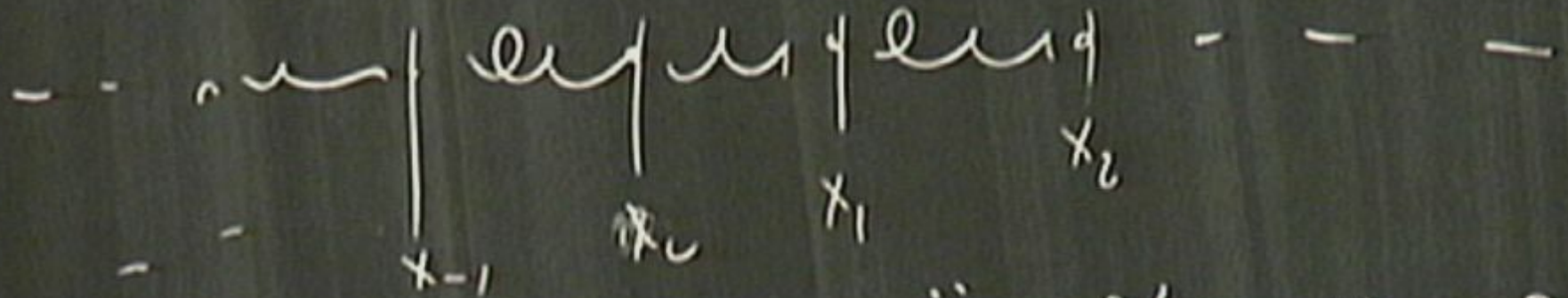


Key prop:
every smooth
vector field
is M has unique
integral curves.

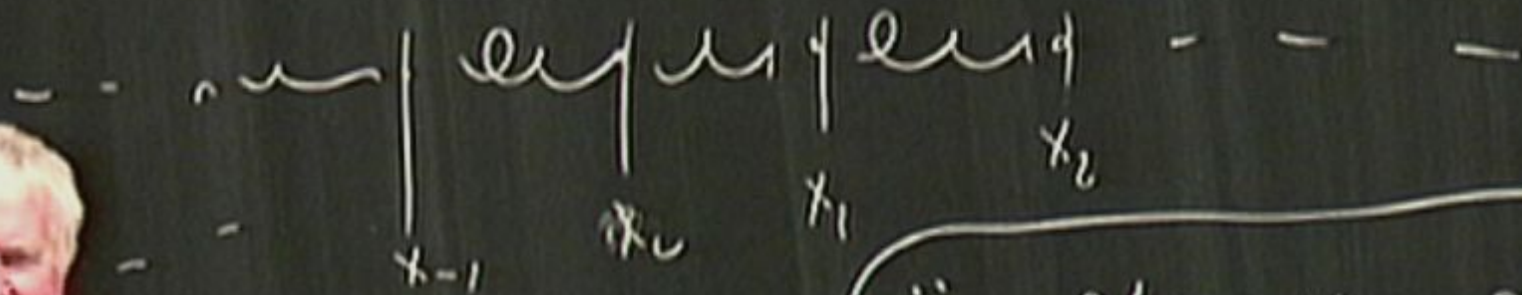


States





$$\ddot{x}_n = \mathcal{L}(x_{n+1} + x_{n-1} - 2x_n)$$

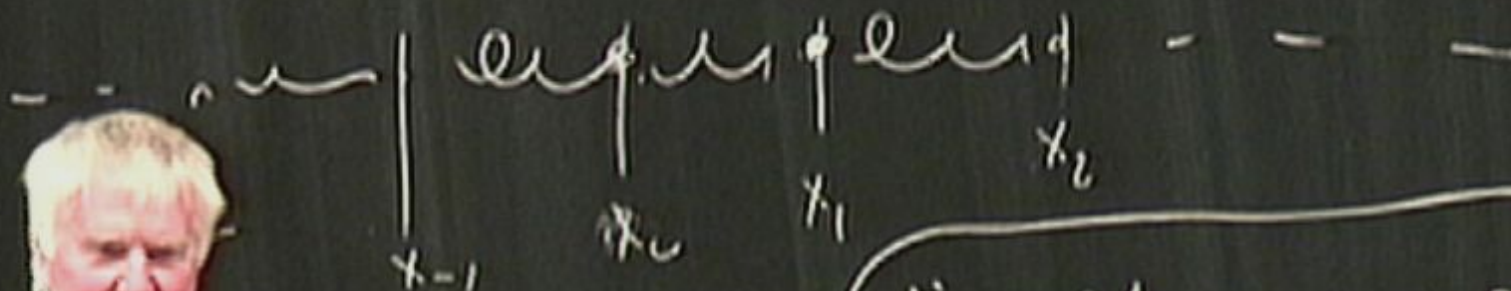


$$\ddot{x}_n = \lambda(x_{n+1} + x_{n-1} - 2x_n)$$

Claim: given $x_0(t)$, $x_1(k)$: exists soln of
that system.

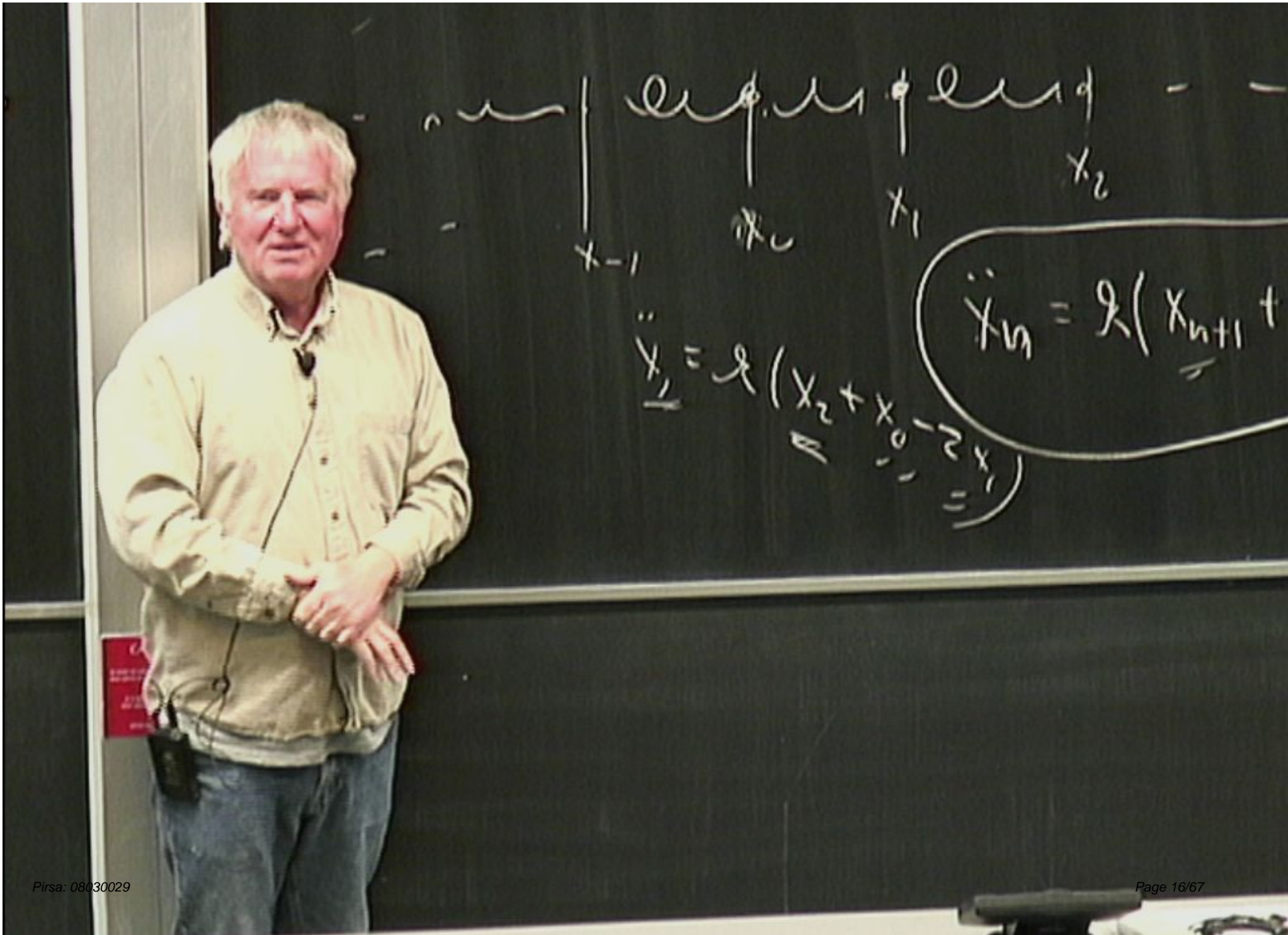
... $\frac{1}{2} \frac{d^2 x}{dt^2} + \dots$

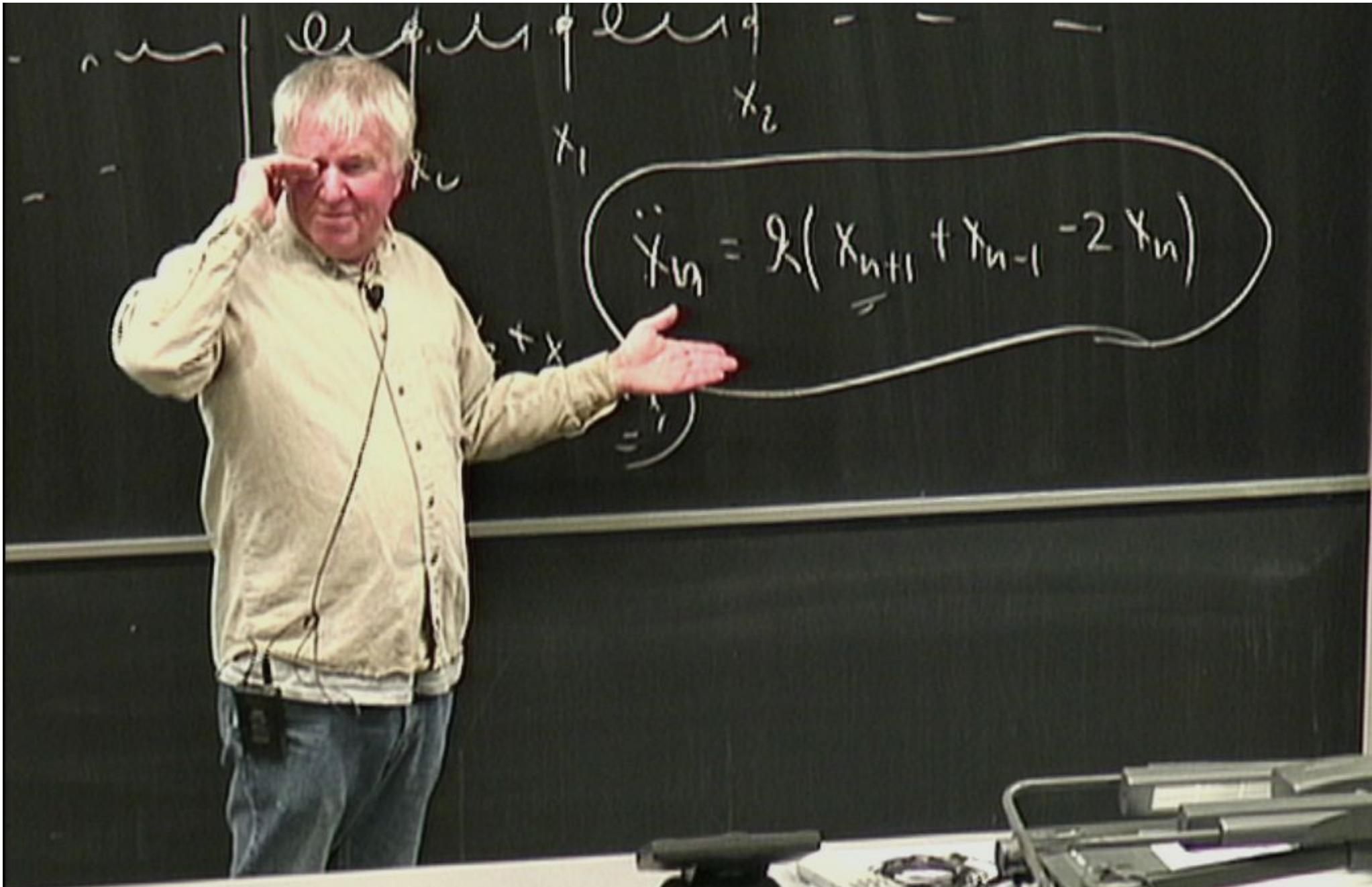
$$\ddot{x}_n = \lambda (x_{n+1} + x_{n-1} - 2x_n)$$



$$\ddot{x}_2 = \mathcal{L}(x_2 + x_0 - 2x_1)$$

$$\ddot{x}_n = \mathcal{L}(x_{n+1} + x_{n-1} - 2x_n)$$





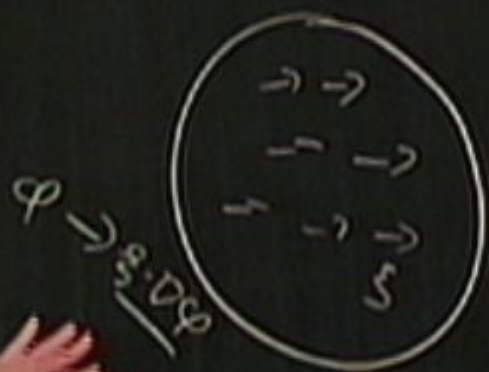
Claim: given $x_0(t)$, $x_1(k)$: exists soln of that system.



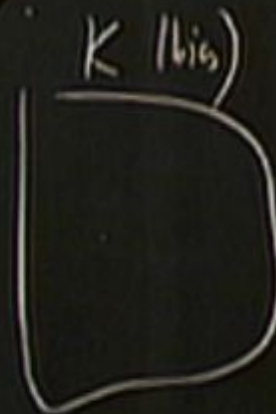
$K = \text{smooth fns } \varphi.$



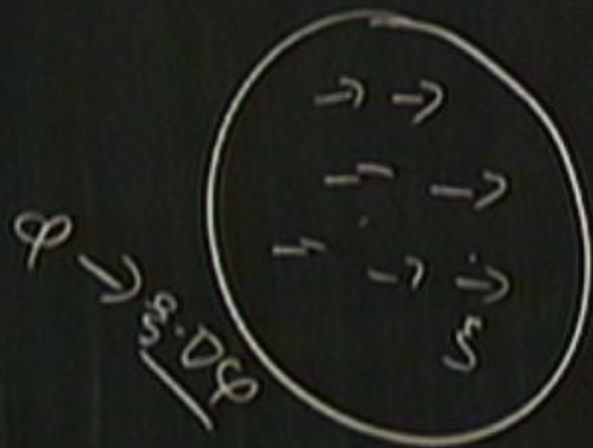
claim: given $x_0(t), x_1(k)$: exists soln of that system.



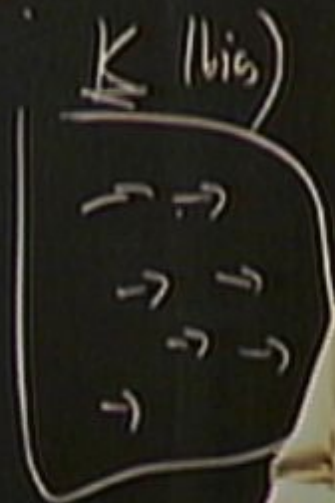
$K = \text{small, fns } \phi.$



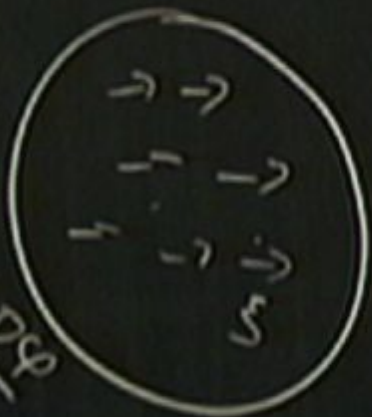
Claim: given $x_0(t), x_1(k)$: exists soln of that system.



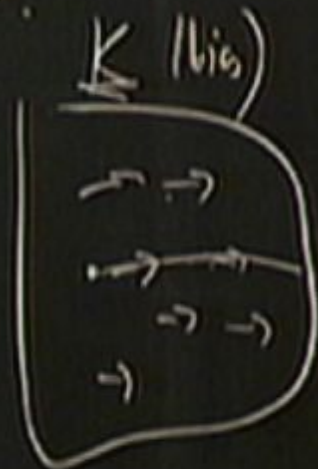
$K = \text{smooth, fns } \phi.$



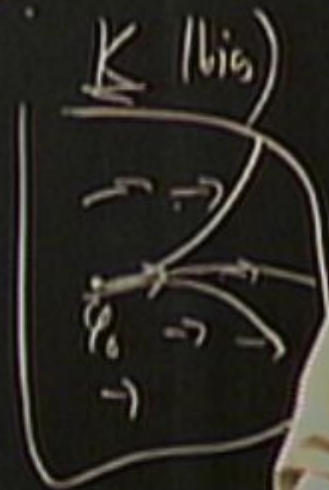
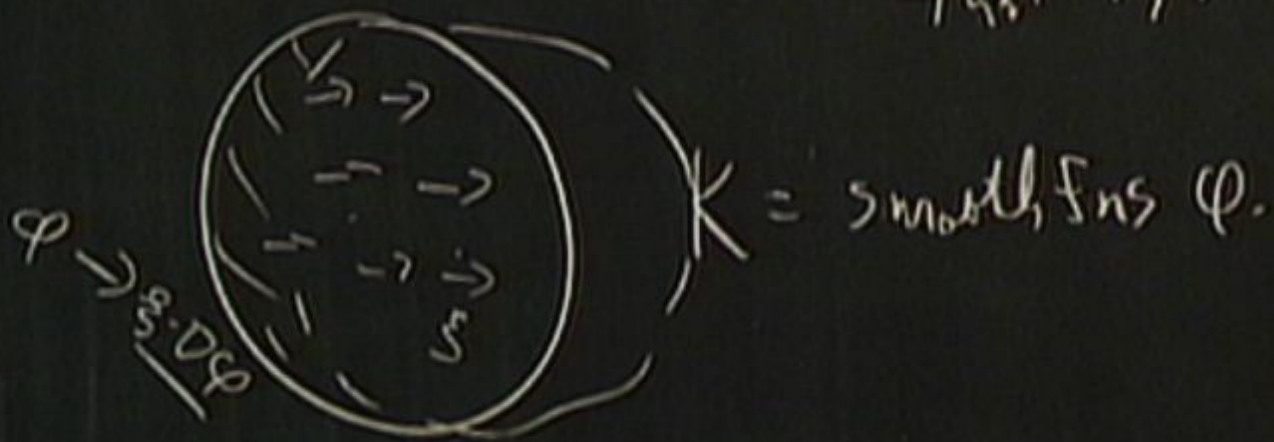
Claim: given $x_0(t)$, $x_1(k)$: exists soln of that system.



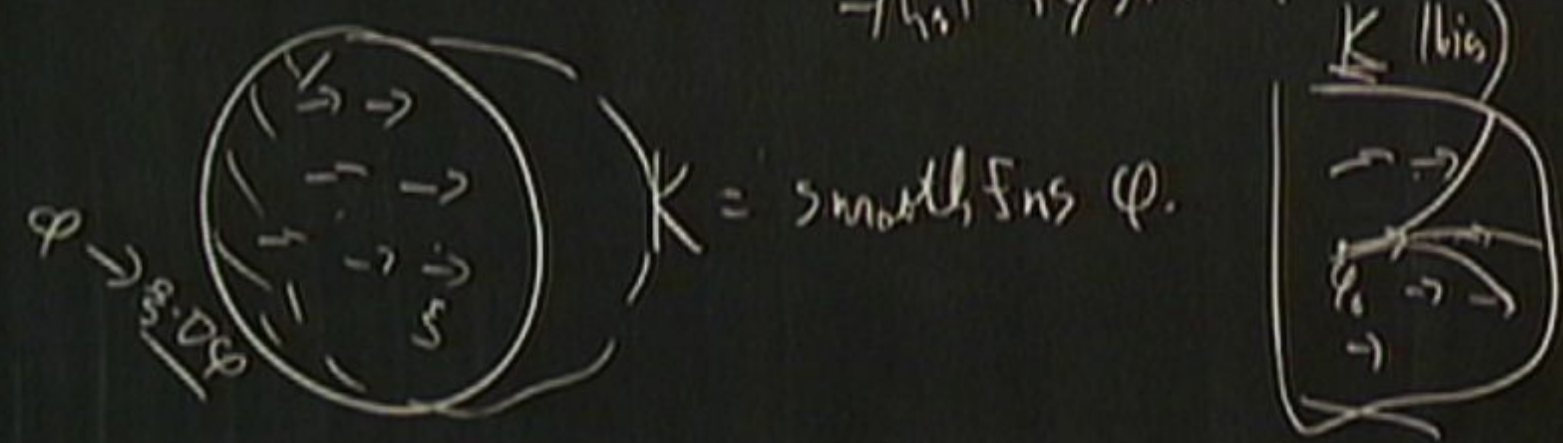
$K = \text{smooth, fns } \varphi.$



claim: given $x_0(t), x_1(t)$: exists soln of that system.



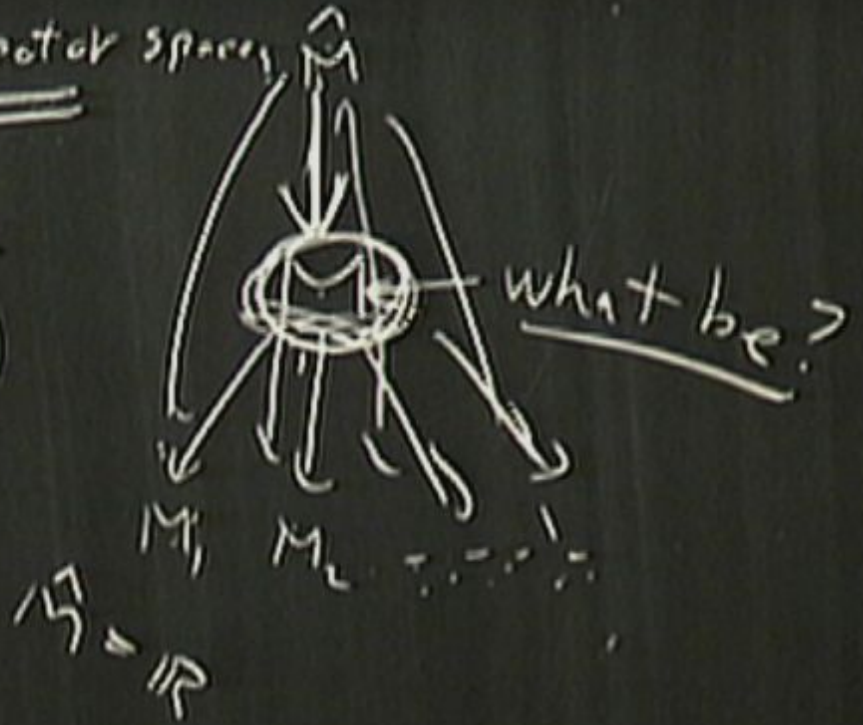
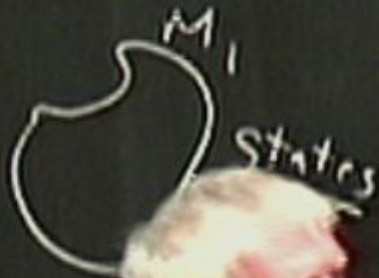
Claim: given $x_0(t), x_1(k)$: exists soln of that system.



Big manifolds

Class mech

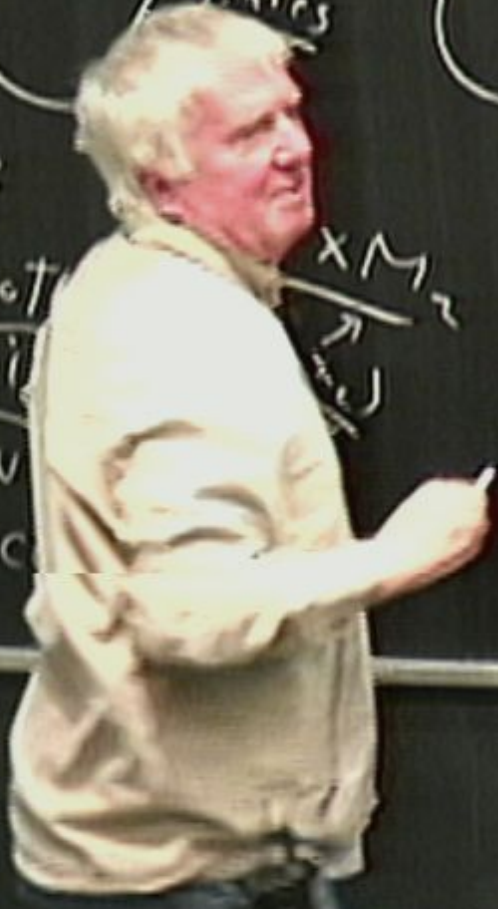
big top vector spaces



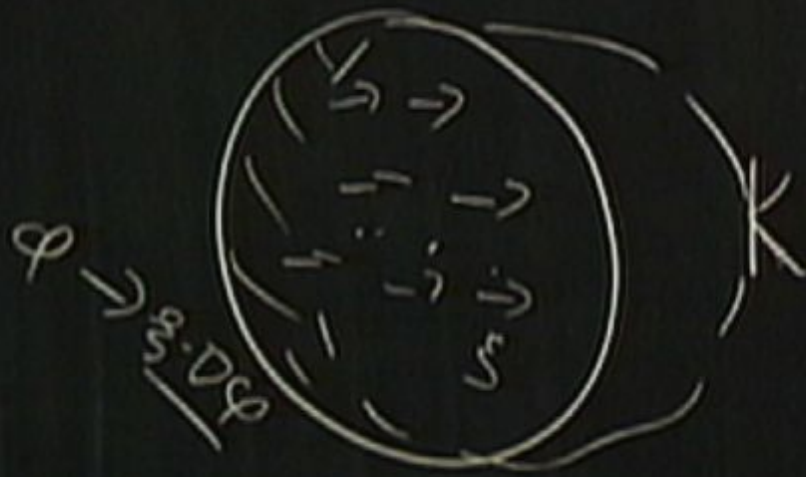
Key prop:

every smooth
vector field

is M has a
integral curve



Claim: given $x_0(t), x_1(k)$: exists soln of that system.



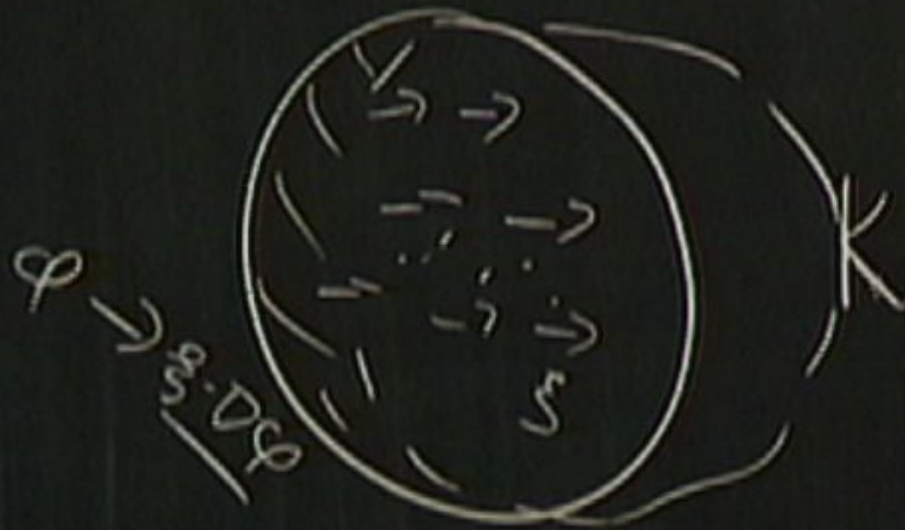
$K = \text{smooth fns } \phi$

C^n fns
 $\phi_1 \dots \phi_m$

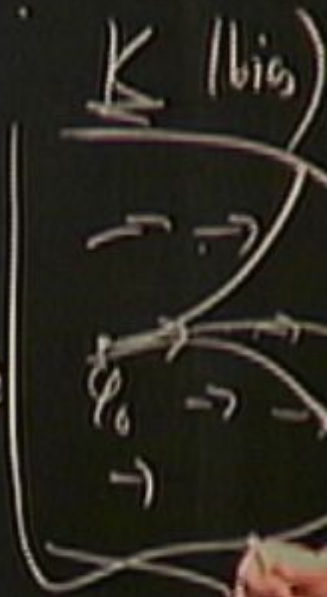
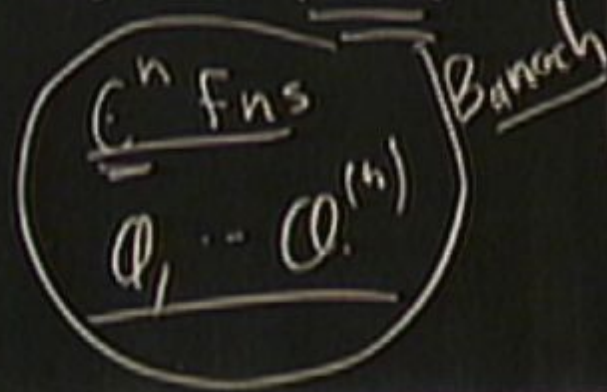


Claim: given $f_0(x), \dots, f_n(x)$

that system.



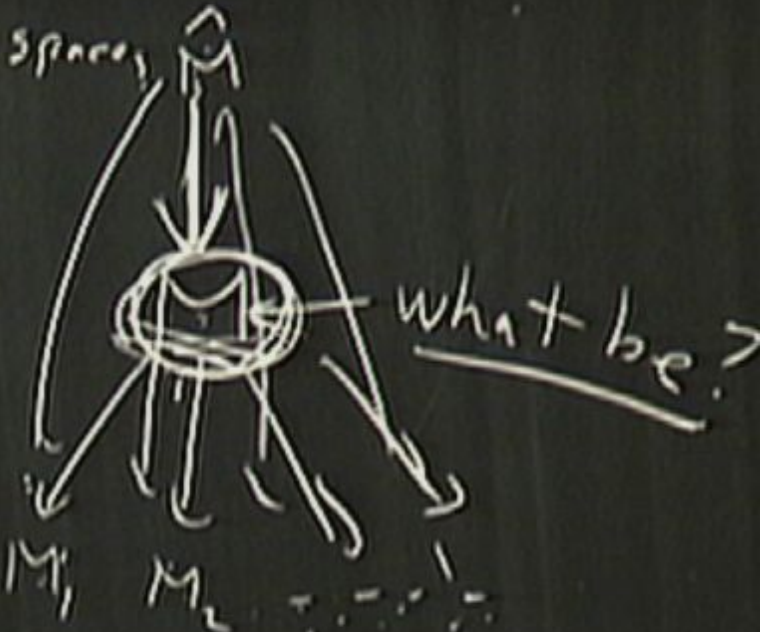
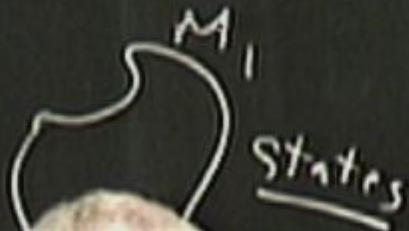
$K = \text{smooth fns } \varphi.$



Big manifolds

Class mech

big top vector spaces



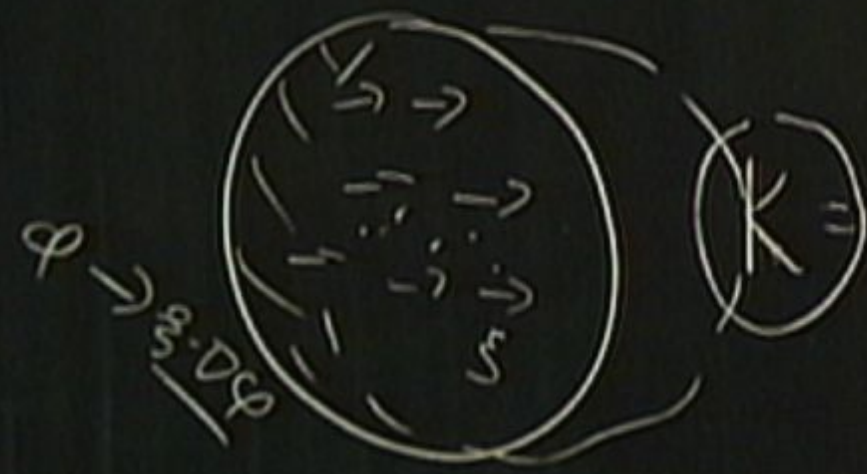
Key prop
every s
vect
is n
int

$M_1 \times M_2$
 \rightarrow
 \mathbb{R}^n

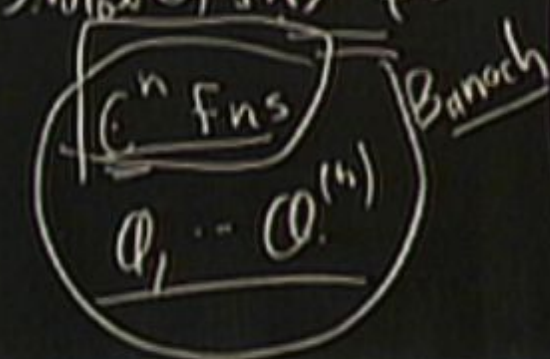
$\mathbb{R}^n = \mathbb{R}$

FALSE

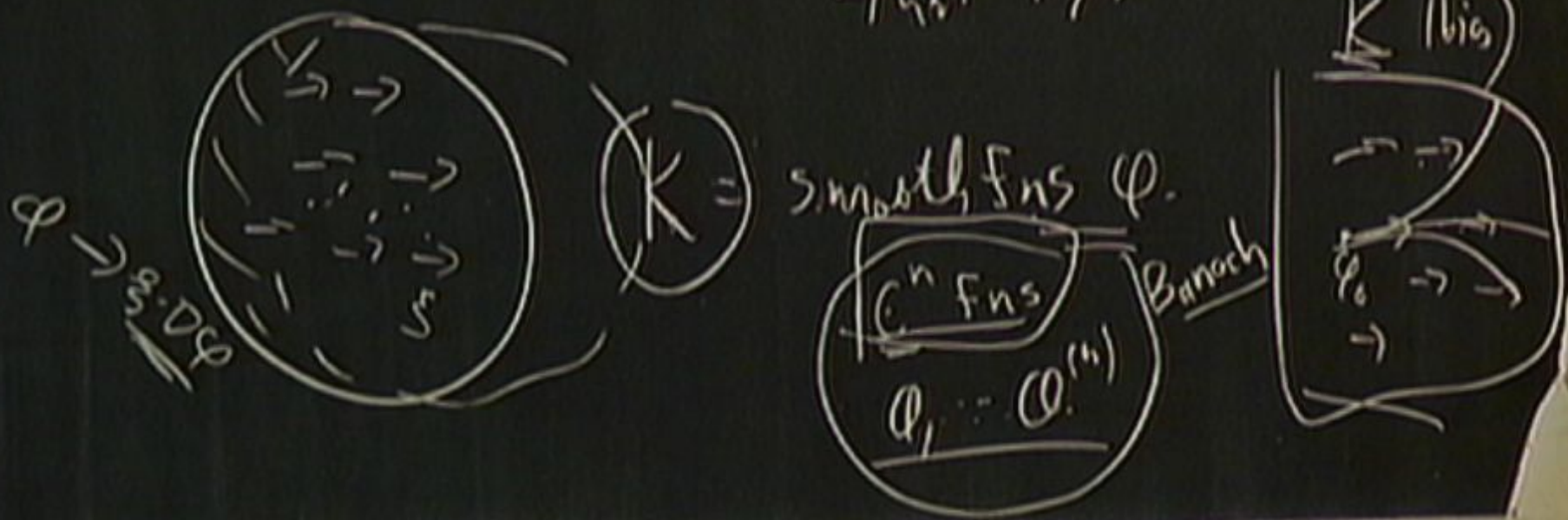
claim: given $x_0(t), x_1(k)$: exists soln of that system.



smooth fns φ .



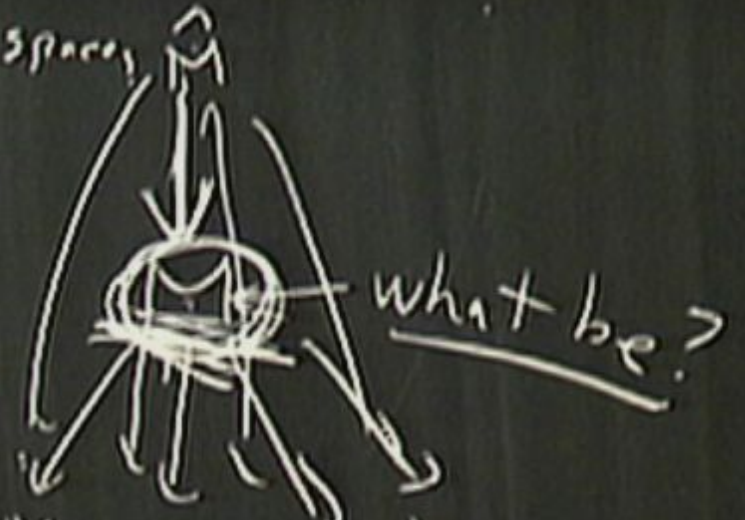
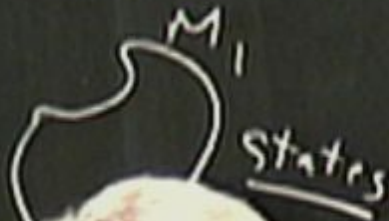
claim: given $x_0(t), x_1(k)$: exists soln of that system.



Big manifolds

Class mech

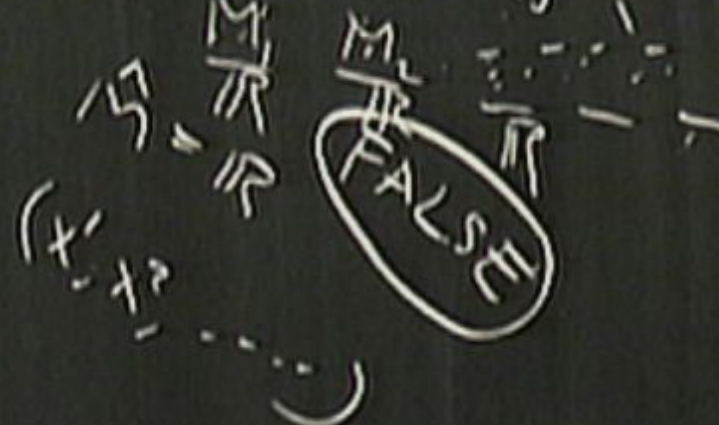
big top vector spaces



Key prop
every state
vector
is in M_1
inter

$$M_1 \times M_2$$

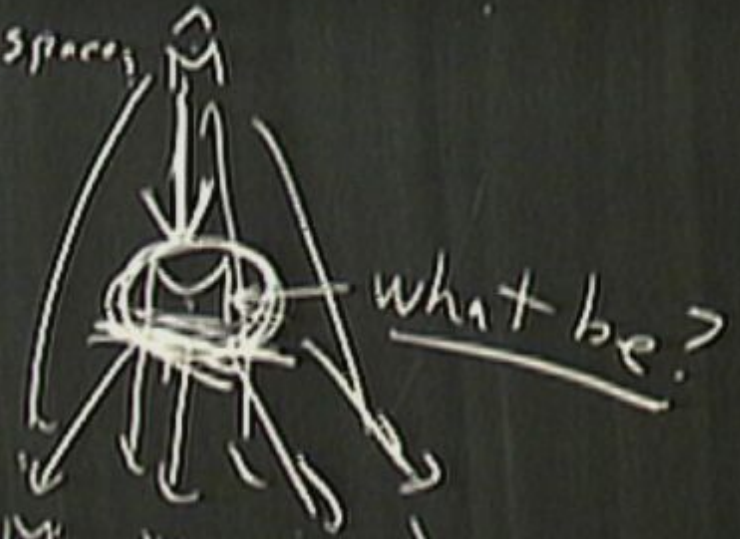
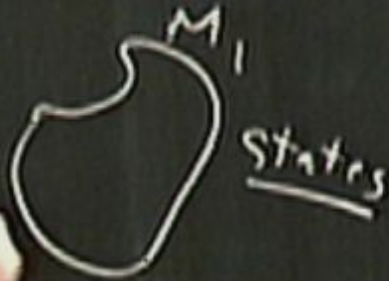
(x_1, x_2)



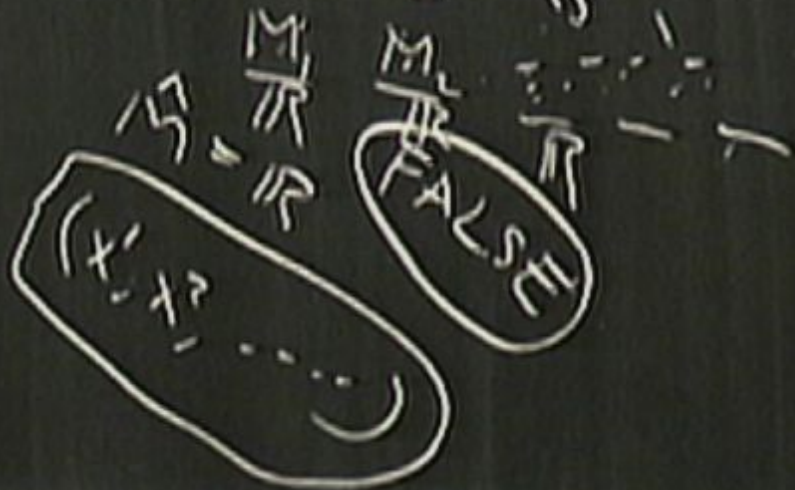
Big manifolds

Class mech

big top vector spaces



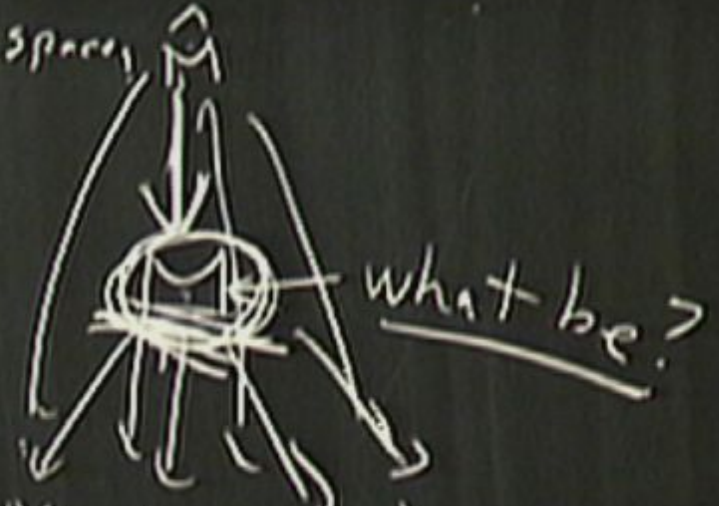
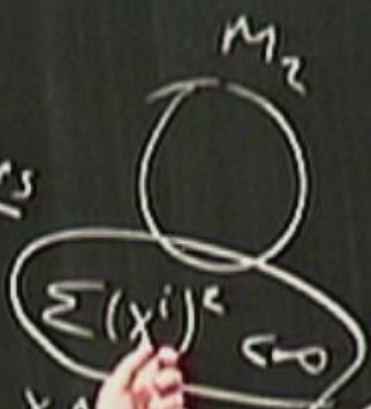
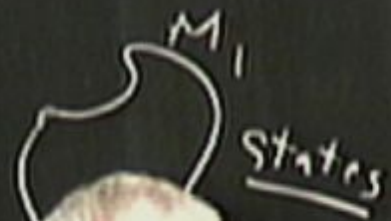
$$\frac{M_1 \times M_2}{(x_1, x_2)}$$



Class mock

Big manifolds

big top vector spaces

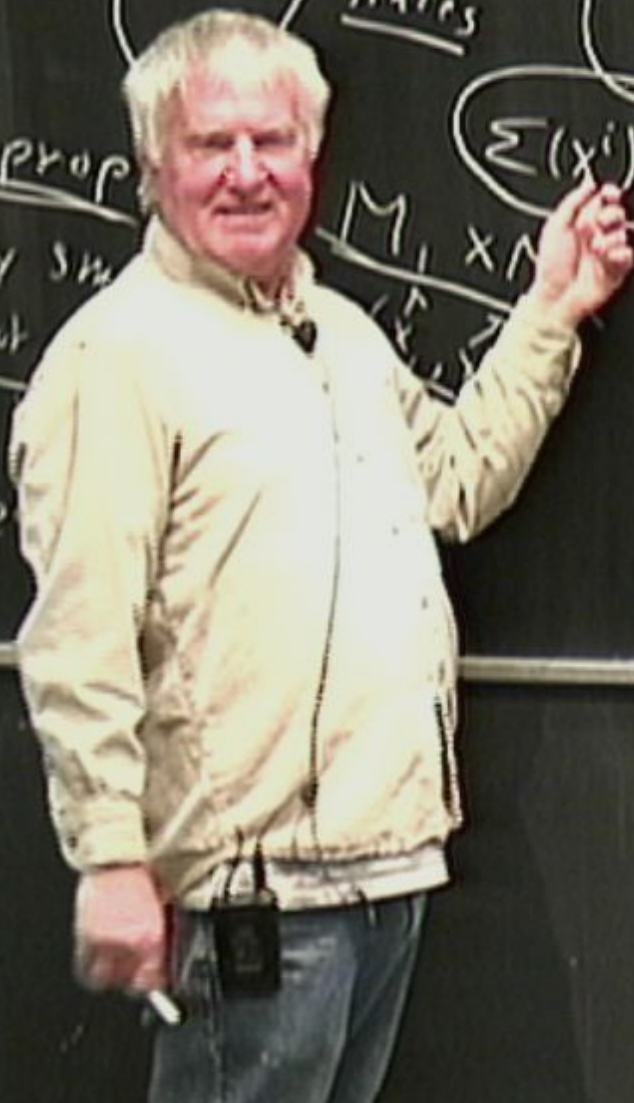


Key prop
every sm
vector
is M_1
inter

$M_1 \times M_2$

(x_1, x_2, \dots)

$M_1 \times \mathbb{R}$
 $M_2 \times \mathbb{R}$
FALSE



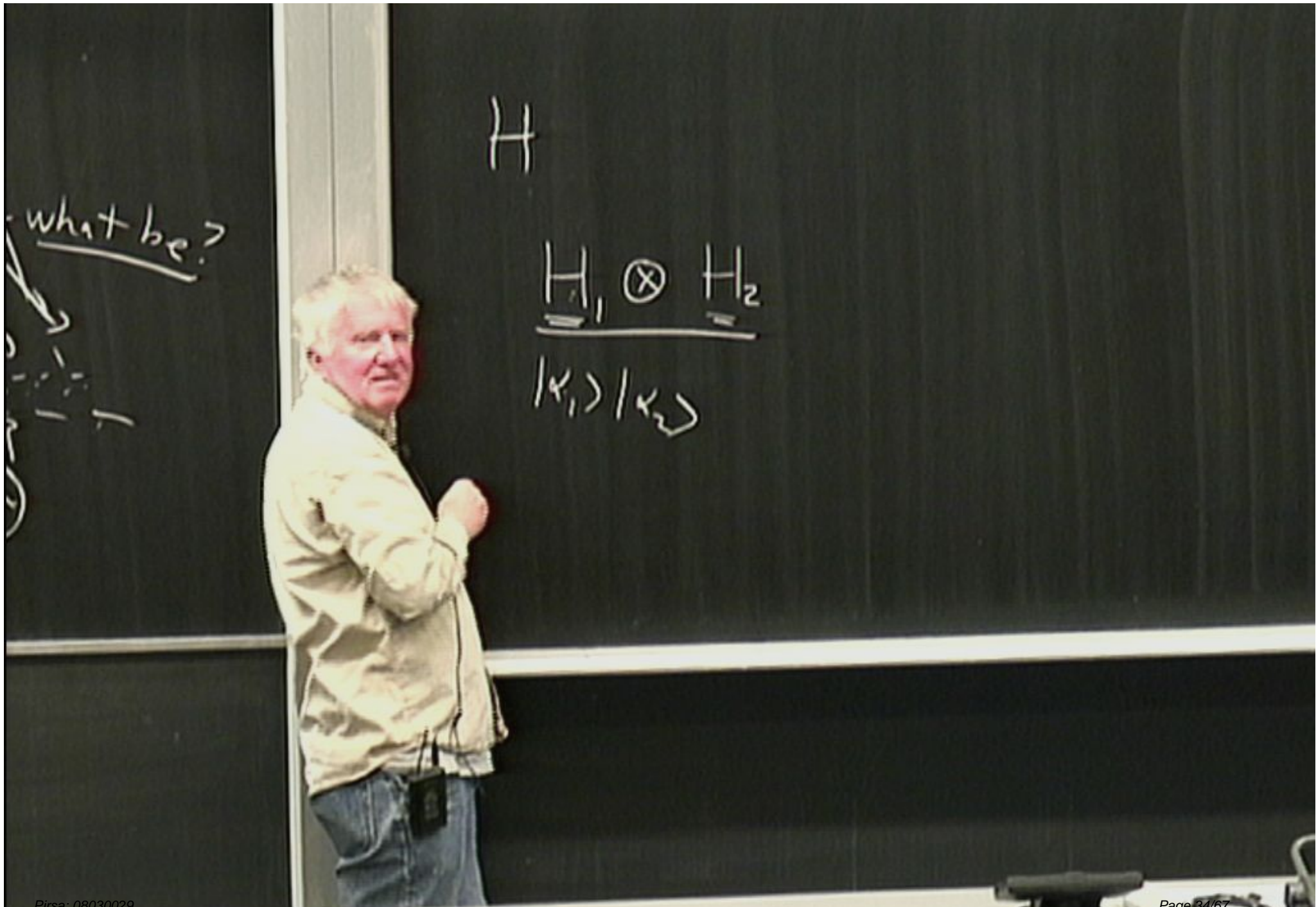
what be?

$$\mathbb{H}$$

$$\underline{H_1 \otimes H_2}$$

$$|k_1\rangle |k_2\rangle$$



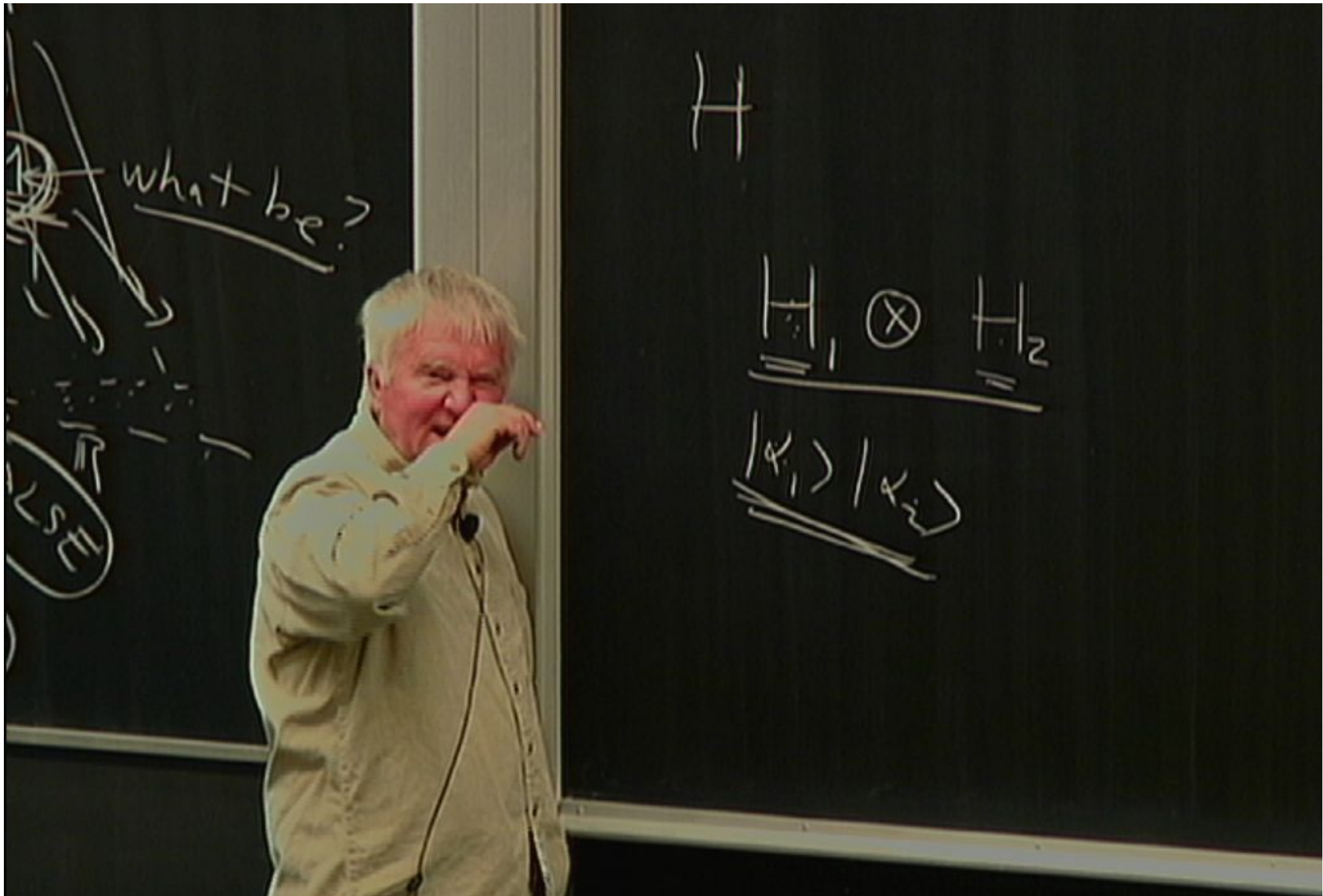


H

$$\underline{H_1} \otimes \underline{H_2}$$

$$|k_1\rangle |k_2\rangle$$

what be?



H

$H_1 \otimes H_2$

$|k_1\rangle |k_2\rangle$

$|p_1\rangle |p_2\rangle$

$|l_1\rangle |l_2\rangle$

H_1, H_2, \dots

$H_1 \otimes H_2 \otimes \dots$

H

$$\underline{H_1} \otimes \underline{H_2}$$

$$\underline{|k_1\rangle |k_2\rangle}$$

$$\begin{aligned} & |p_1\rangle |p_2\rangle \\ & |q_1\rangle |q_2\rangle \end{aligned}$$

$$\begin{aligned} & H_1, H_2, \dots \\ & U_1, U_2 \quad (H_1 \otimes H_2 \otimes \dots) \end{aligned}$$

H

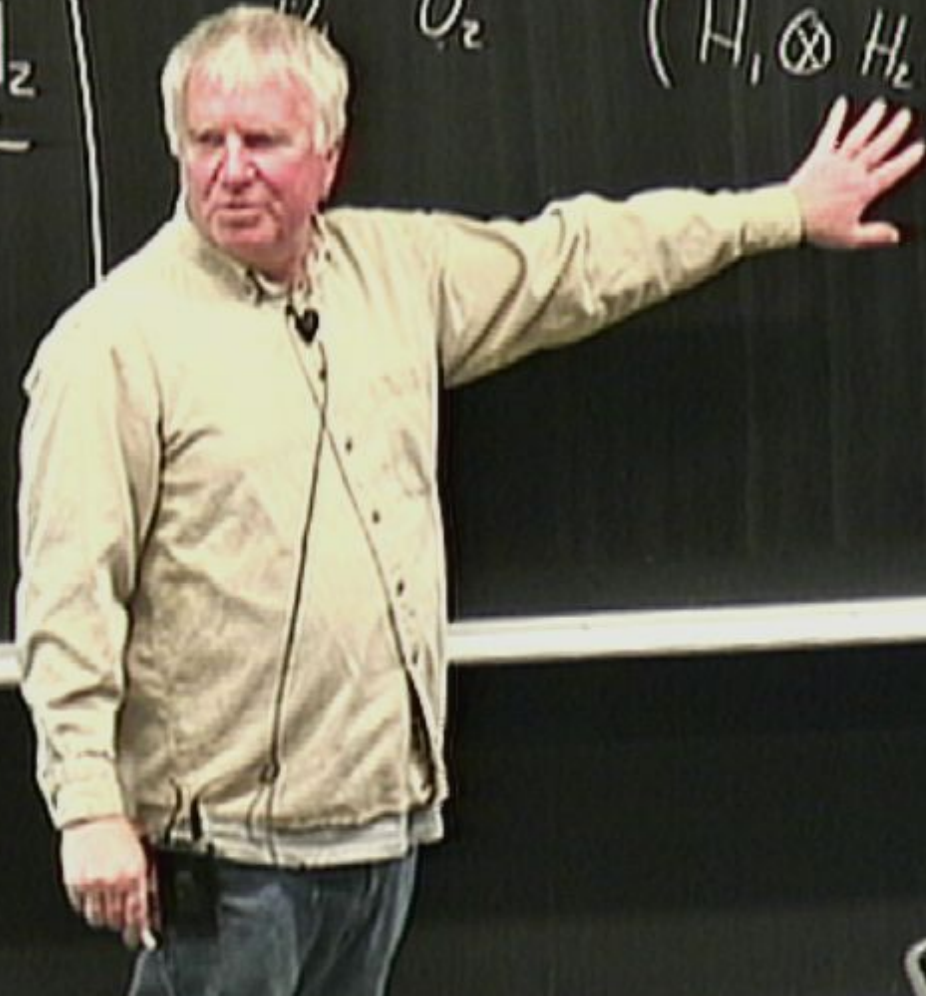
$H_1 \otimes H_2$

$|k_1\rangle |k_2\rangle$

$|p_1\rangle |p_2\rangle$
 $(|k_1 p_1\rangle |k_2 p_2\rangle)$

A_2
 \downarrow
 H_1, H_2, \dots
 U_2

$(H_1 \otimes H_2 \otimes \dots)$



H

$$\underline{H_1} \otimes \underline{H_2}$$

$$\underline{|k_1\rangle |k_2\rangle}$$

$$\begin{aligned} & |p_1\rangle |p_2\rangle \\ & \leftarrow |k_1\rangle |k_2\rangle \end{aligned}$$

$$\begin{array}{c} A_2 \\ \downarrow \\ H_1, H_2, \dots \\ U_1, U_2 \end{array} \quad \mathcal{H} = \left(\underline{H_1} \otimes \underline{H_2} \otimes \dots \right)$$

$|\alpha_1\rangle |\alpha_2\rangle |\alpha_3\rangle \dots \in \mathcal{H}$

$\uparrow \quad \uparrow$
 $\mathcal{H}_1 \quad \mathcal{H}_2$

$K = (\alpha_1, \alpha_2, \dots) \in \mathcal{H}_2 \quad \sum (1 - \|\alpha_i\|) \text{ Converge}$

$$|\alpha_1\rangle \quad |\alpha_2\rangle \quad |\alpha_3\rangle \quad \dots \quad \in \mathbb{R}^6$$

$$\begin{array}{cccc} \uparrow & \uparrow & & \\ H_1 & H_2 & & \end{array}$$

"Converse"
(ind. ep of order)

$$\underline{K} = (\alpha_1, \alpha_2, \dots) \in H_2 \quad \sum (1 - \|\alpha_i\|) \text{ converges.}$$

$$\Downarrow$$

$$\prod \|\alpha_i\| \text{ converges}$$

$$(\alpha_1, \alpha_2, \dots) \sim (\alpha'_1, \alpha'_2, \dots)$$

$$\mathcal{H} \sum (1 - \langle \alpha_i | \alpha'_i \rangle) \text{ converges.}$$

$$(\alpha_1, \alpha_2, \dots) \underset{=}{\sim} (\alpha'_1, \alpha'_2, \dots)$$

$$\mathcal{H} \underset{=}{\sim} \sum (1 - \langle \alpha_i | \alpha'_i \rangle) \text{ converges.}$$

$$(\alpha_1, \alpha_2, \dots) \underset{=}{\sim} (\alpha'_1, \alpha'_2, \dots)$$

$$\mathbb{H} \frac{\sum (1 - \langle \alpha_i | \alpha'_i \rangle) \text{ emerges}}{\quad}$$

$$\Downarrow \mathbb{H} \langle \alpha_i | \alpha'_i \rangle \text{ emerges}$$

$$(\alpha_1, \alpha_2, \dots) \stackrel{!}{\sim} (\alpha'_1, \alpha'_2, \dots)$$

$$\Downarrow \frac{\sum (1 - \langle \alpha_i | \alpha'_i \rangle) \text{ emerges}}{\Downarrow \prod \langle \alpha_i | \alpha'_i \rangle \text{ emerges}}$$

$$\Downarrow \prod \langle \alpha_i | \alpha'_i \rangle \text{ emerges}$$

~~...~~ $(\alpha_1, \alpha_2, \dots)$ \swarrow unix

$$(\alpha_1, -\alpha_2, \alpha_3, -\alpha_4, \dots)$$

$$(\alpha_1, \alpha_2, \dots) \underset{=}{\sim} (\alpha'_1, \alpha'_2, \dots)$$

$$\mathbb{H} \frac{\sum (1 - \langle \alpha_i | \alpha'_i \rangle)}{\text{unit}} \text{ emerges}$$

$$\Downarrow \underline{\underline{\prod \langle \alpha_i | \alpha'_i \rangle \text{ emerges}}}}$$

~~$\mathbb{H} | (\alpha_1, \alpha_2, \dots)$~~

$(\alpha_1, -\alpha_2, \alpha_3, -\alpha_4, \dots)$

Fix equivalence class K .

H_K

cov

Fix equivalence class K .

$$H_K$$

$$\sum$$

$$H_K$$

$$= \mathcal{H}$$

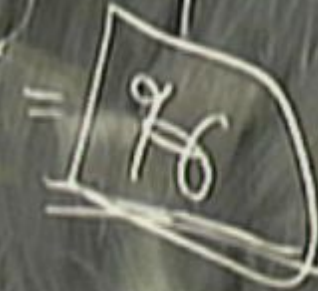
all in
class K

be?

Fix equivalence class K .



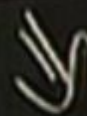
H_{1K}



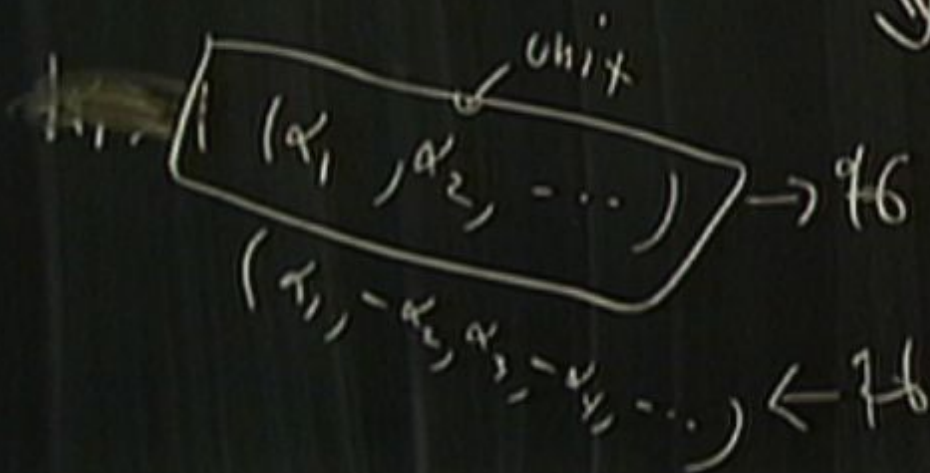
all your classes

$$(\alpha_1, \alpha_2, \dots) \approx (\alpha'_1, \alpha'_2, \dots)$$

$$\mathbb{H} \sum (1 - \langle \alpha_i | \alpha'_i \rangle) \text{ converges}$$



$$(\alpha'_i) \text{ converges}$$



H $\underline{H_1} \otimes \underline{H_2}$ $\underline{|\alpha_1\rangle} \underline{|\alpha_2\rangle}$ $\begin{matrix} |\beta_1\rangle |\beta_2\rangle \\ \leftarrow |\alpha_1\rangle |\alpha_2\rangle \end{matrix}$ $H_1, \overset{A_2}{\downarrow} H_2, \dots$ $U_1, U_2 \mathcal{H} = (\underline{H_1 \otimes H_2 \otimes \dots})$ $|\alpha_1\rangle, |\alpha_2\rangle, \dots$

Fix equivalence class K .

$$\Sigma$$

all in class K

$$H_{1K}$$

$$= \mathbb{H}$$

be?

H

$H_1 \otimes H_2$

$| \alpha_1 \rangle | \alpha_2 \rangle$

$| \beta_1 \rangle | \beta_2 \rangle$
 $| \gamma_1 \rangle | \gamma_2 \rangle$

H_1, H_2, \dots

$U_1, U_2 \mathcal{H} = (H_1 \otimes H_2 \otimes \dots)$

unit

$| \alpha_1 \rangle, | \alpha_2 \rangle, \dots$

H $H_1 \otimes H_2$ $|x_1\rangle, |x_2\rangle$ A_2
 \downarrow
 H_1, H_2, \dots $U_1, U_2 \mathcal{H} = (H_1 \otimes H_2 \otimes \dots)$ unit $|x_1\rangle, |x_2\rangle, \dots$

H $H_1 \otimes H_2$ $|k_1\rangle |k_2\rangle$ $|p_1\rangle |p_2\rangle$
 $|q_1\rangle |q_2\rangle$ H_1, H_2, \dots A_2 U_1 U_2 $\mathcal{H} = (H_1 \otimes H_2 \otimes \dots)$ unit $|k_1\rangle, |k_2\rangle, \dots$

H

$H_1 \otimes H_2$

$|k_1\rangle |k_2\rangle$

$|p_1\rangle |p_2\rangle$
 $(|k_1\rangle |p_1\rangle) (|k_2\rangle |p_2\rangle)$

H_1, H_2, \dots

$U_1, U_2 \mathcal{H} = (H_1 \otimes H_2 \otimes \dots)$

unit

$|k_1\rangle, |k_2\rangle, \dots$

Actual system

Fix equivalence class K .

$$\boxed{H_K}$$

$$\bigcup$$

$$H_K$$

$$= \boxed{H_K}$$

all equiv
classes

Fix equivalence class K .



H_K

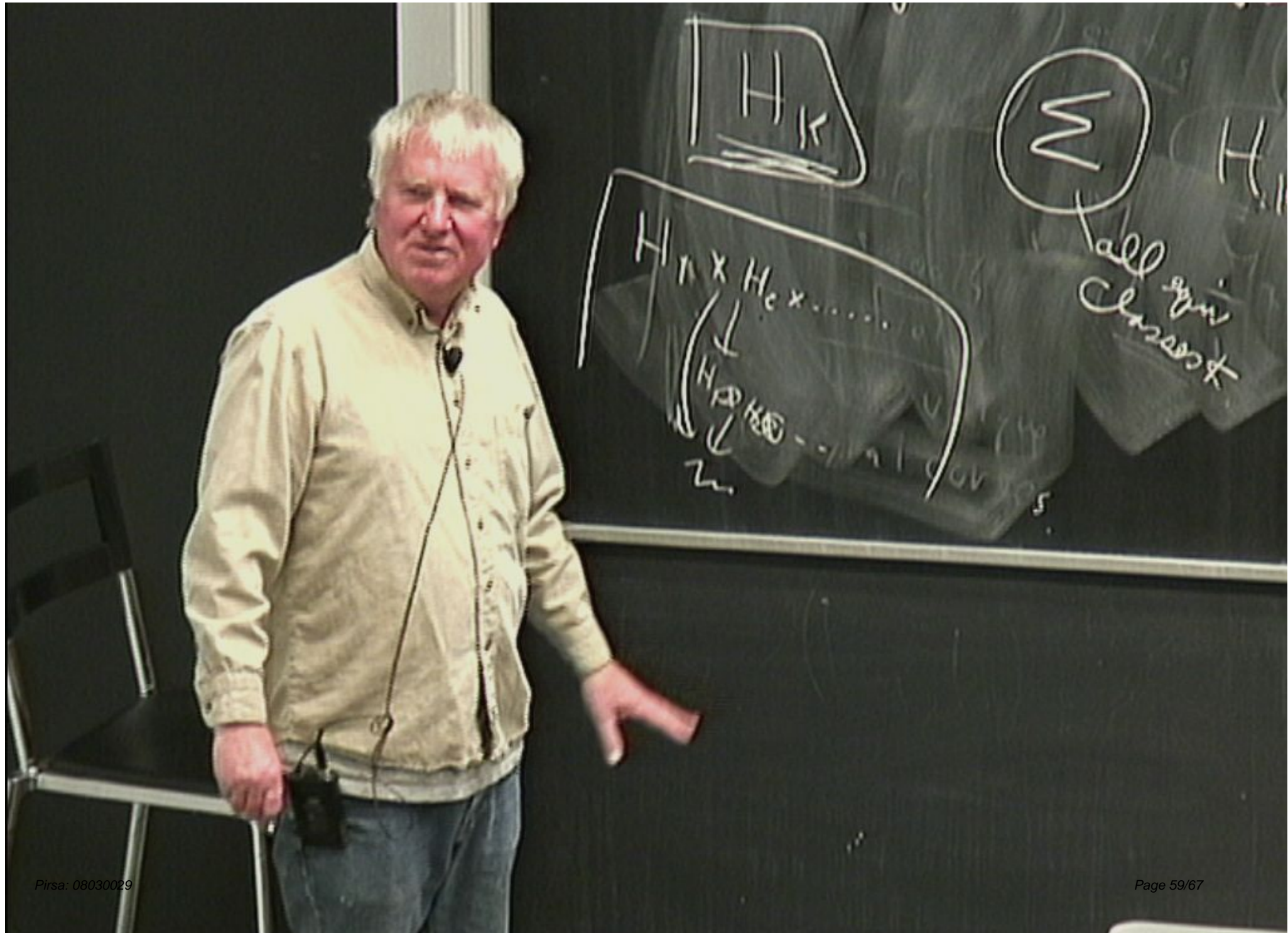


all equiv
classes

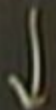
$H_{K_1} \times H_{K_2} \times \dots$

$H_{K_1} \times H_{K_2} \times \dots$





$$K \sim K'$$



$$|K_1\rangle |K_2\rangle \dots$$

$$|K'_1\rangle |K'_2\rangle \dots$$

system

ns φ .

ns

$\varphi^{(n)}$

Bar

Fix equivalence class K .

$$\boxed{H_{iK}}$$

$$\sum$$

$$H_{iK}$$

$$= \boxed{\cancel{H}}$$

be?

$$\begin{array}{c} H_{i_1} \times H_{i_2} \times \dots \\ \downarrow \\ H_{i_1 i_2} \dots \end{array}$$

all in class K

Fix equivalence class K .

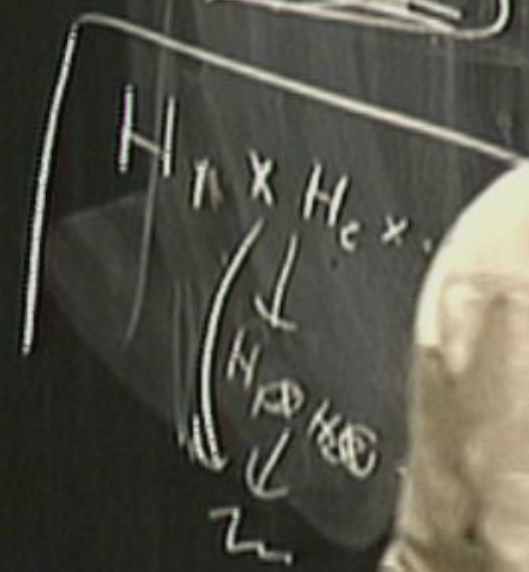


$H \cdot K$

=



all
se gr



Fix equivalence class K .



H_K



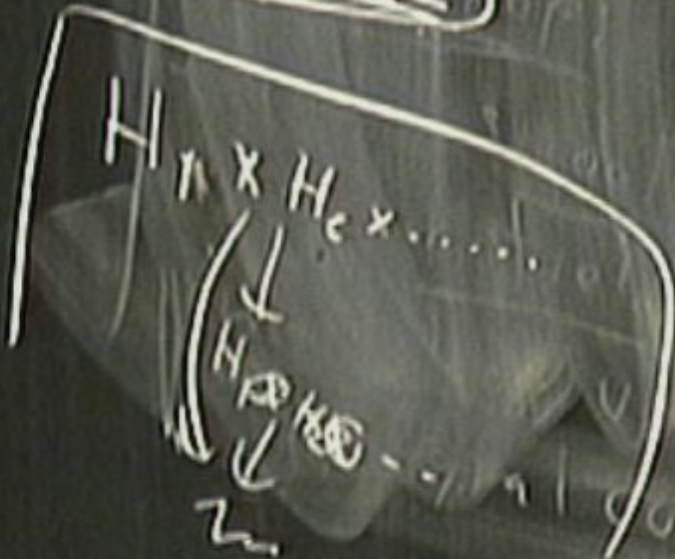
all equiv
classes
one of each
equiv class.

$1 \times H_c \times \dots$

Fix equivalence class K .



$H:K$



all eqi
class
x
rep of eqi
class.

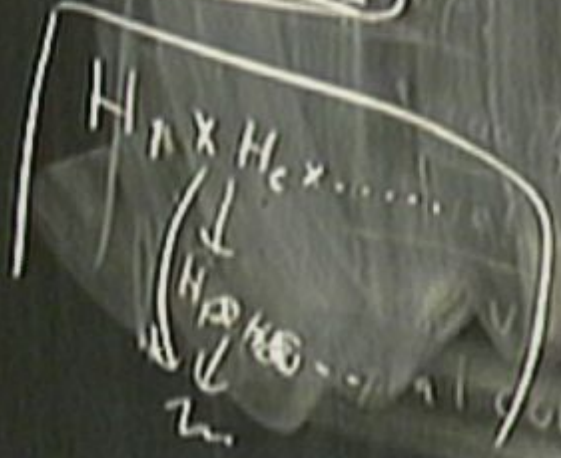
Fix equivalence class K .



H_K



not unique



all the classes
are rep of only
one equiv class.

H

$H_1 \otimes H_2$

$|k_1\rangle |k_2\rangle$

$|p_1\rangle |p_2\rangle$
 $(|k_1, p_1\rangle) (|k_2, p_2\rangle)$

H_1, H_2, \dots

$U_1, U_2 \mathcal{H} = (H_1 \otimes H_2 \otimes \dots)$

unit

$|k_1\rangle, |k_2\rangle, \dots$

Actual system

Fix equivalence class K .



H_1/K



be?

not unique

all the classes
a rep of each
of equiv class.

