

Title: Quantum Information Theory #4

Date: Mar 20, 2008 06:30 PM

URL: <http://pirsa.org/08030009>

Abstract: Teleportation, quantum key distribution, and quantum algorithms.



**Swipe your finger slower**



The image was not accepted. Place the same finger on the fingerprint sensor again.

# Quantum Information

## Lecture 4: Quantum Computing

Sarah Croke

Perimeter Institute (Office: 252)

[scroke@perimeterinstitute.ca](mailto:scroke@perimeterinstitute.ca)

# Quantum Information

## Lecture 4: Quantum Computing

Sarah Croke

Perimeter Institute (Office: 252)

[scroke@perimeterinstitute.ca](mailto:scroke@perimeterinstitute.ca)

# Grover's Algorithm

- Search algorithm;
  - Problem is to search for one marked item in an unstructured database of  $N$  items.
  - Assume it is easy to recognize the solution, but difficult to find it.
- Classically, need  $O(N)$  queries to find item with probability  $p$ .
- Same problem solved by a quantum computer in  $O(\sqrt{N})$  queries.
- Algorithm is probabilistic.



# Quantum Information

## Lecture 4: Quantum Computing

Sarah Croke

Perimeter Institute (Office: 252)

[scroke@perimeterinstitute.ca](mailto:scroke@perimeterinstitute.ca)

# Grover's Algorithm

- Search algorithm;
  - Problem is to search for one marked item in an unstructured database of  $N$  items.
  - Assume it is easy to recognize the solution, but difficult to find it.
- Classically, need  $O(N)$  queries to find item with probability  $p$ .
- Same problem solved by a quantum computer in  $O(\sqrt{N})$  queries.
- Algorithm is probabilistic.

$$f(x) = 1, \quad x = x_0$$



$$\left( \begin{array}{l} f(x) = 1 \\ 0 \end{array} \right), x = x_0$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle \langle 0|$$

$$\bigcup_b |x\rangle$$

$$\left( \begin{array}{c} f(x) = 1 \\ 0 \end{array} \right), x = x_0$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle |0\rangle$$

$$U_f |x\rangle |0\rangle = |x\rangle |f(x)\rangle$$



$$\frac{1}{2} \sum_{x=0}^3 |x\rangle |0\rangle$$

$$U_f |x\rangle |0\rangle = |x\rangle |f(x)\rangle$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$



$$f(x) = \begin{matrix} 1 \\ 0 \end{matrix}, \quad x = x_0$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle |0\rangle$$

$$U_f |x\rangle |0\rangle = |x\rangle |f(x)\rangle$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$f(x) = \begin{matrix} 1 \\ 0 \end{matrix}, \quad x = x_0$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle |0\rangle$$

$$U_f |x\rangle |0\rangle = |x\rangle |f(x)\rangle$$

$$\frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$U_f \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$



$$U_b \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$

$$= \frac{1}{2} \sum_{x=0}^3 (-1)^{b(x)} |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$



$$U_6 \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$

$$= \frac{1}{2} \sum_{x=0}^3 \underbrace{(-1)^{f(x)} |x\rangle}_{\text{phase factor}} \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$



$$U_b \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$

$$= \underbrace{\frac{1}{2} \sum_{x=0}^3 (-1)^{b(x)} |x\rangle}_{\text{}} \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$U_b \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$

$$= \underbrace{\frac{1}{2} \sum_{x=0}^3 (-1)^{b(x)} |x\rangle}_{\text{}} \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$



$$\frac{1}{\sqrt{6}} \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right) \right)$$

$$= \frac{1}{2} \sum_{x=0}^3 (-1)^{f(x)} |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$\hat{D} = 2|\psi_{x\psi}\rangle - \mathbb{I}$$



$$U_6 \left( \frac{1}{2} \sum_{x=0}^3 |x\rangle \left( \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle) \right) \right)$$

$$= \frac{1}{2} \sum_{x=0}^3 (-1)^{f(x)} |x\rangle \left( \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle) \right)$$

$$\hat{D} = 2 |\psi\rangle\langle\psi| - \mathbb{I}$$

$$|\psi\rangle = \frac{1}{2} \sum_{x=0}^3 |x\rangle$$

$$0 = 2147941 - \underline{1}$$



$$0 = 2i\psi\chi\psi - 1$$

$$\begin{aligned} 0^\dagger 0 &= (2i\psi\chi\psi - 1)\chi\psi \\ &= 4i\psi\chi\psi - 2i\psi\chi\psi \\ &= 1 \end{aligned}$$



$$\begin{aligned}
 D^+ D &= (2i\pi x_4 - 1) \\
 &= 4i\pi x_4 - 1 \\
 &= 1
 \end{aligned}$$



$$\begin{aligned}
 D^\dagger D &= (2|1\rangle\langle 1| - \mathbb{1}) \\
 &= 4|1\rangle\langle 1| - 2|1\rangle\langle 1| - 2|1\rangle\langle 1| + \mathbb{1} \\
 &= 1
 \end{aligned}$$

$$\frac{1}{2}(|00\rangle + |01\rangle - |10\rangle + |11\rangle)$$



$$D = 2|x \times x| - \mathbb{I}$$

$$|x\rangle = \frac{1}{2} \sum_{n=0}^3 |x_n\rangle$$



$$D = 2|xx\rangle - \mathbb{I}$$

$$|x\rangle = \frac{1}{2} \sum_{y=0}^3 |xy\rangle$$

$$|xx\rangle = \frac{1}{4} \sum_{x=0}^3 \sum_{y=0}^3 |xy\rangle$$



$$D = 2|xx\rangle - \mathbb{I}$$

$$D = \sum_{x,y} |xx\rangle \langle yy|$$

$$|x\rangle = \frac{1}{2} \sum_{x=0}^3 |xx\rangle$$

$$|xx\rangle = \frac{1}{4} \sum_{x=0}^3 \sum_{y=0}^3 |xx\rangle$$



$$D = 2|x x| - \mathbb{I}$$

$$|x\rangle = \frac{1}{2} \sum_{x=0}^3 |x\rangle$$

$$|x x\rangle = \frac{1}{4} \sum_{x=0}^3 \sum_{y=0}^3 |x y\rangle$$

$$\begin{aligned} D &= \sum_{x,y} |x x\rangle \langle y x y| \\ &= \sum_{x,y} \frac{1}{2} |x x y\rangle \\ &\quad - \mathbb{I} \end{aligned}$$

$$Q = \begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix} \quad x = x_0$$



$$Q = \begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix} \quad x = x_0$$

$$12 =$$



$$D = \begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix}$$

$$x = x_0$$

$$|\alpha\rangle = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow D|\alpha\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$



$$D = \frac{1}{2} \begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix}, \quad x = x_0$$

$$|\alpha\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow D|\alpha\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$



$$D = \frac{1}{2} \begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{pmatrix} \quad x = x_0$$

$$|\alpha\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow D|\alpha\rangle = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = |10\rangle$$

$$\frac{1}{\sqrt{2}} \sum |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$



$$\frac{1}{\sqrt{N}} \sum |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$\rightarrow U_f \frac{1}{\sqrt{N}} \sum (-1)^{f(x)} |x\rangle$$

$$\frac{1}{\sqrt{N}} \sum |x\rangle \left( \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right)$$

$$\rightarrow U_6 \frac{1}{\sqrt{N}} \sum (-1)^{f(x)} |x\rangle$$

$$D = 2|4 \times 4| - \pi$$



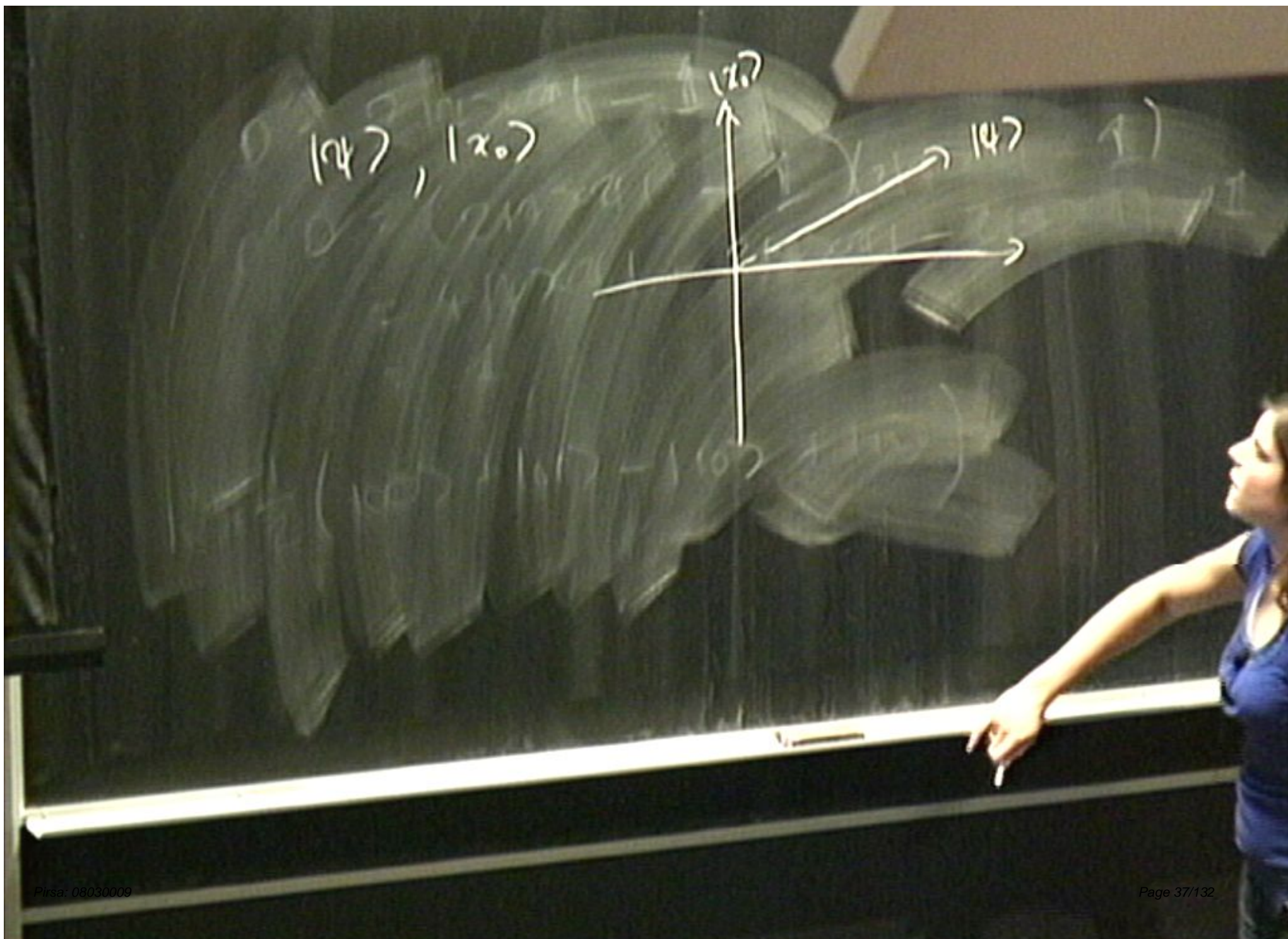


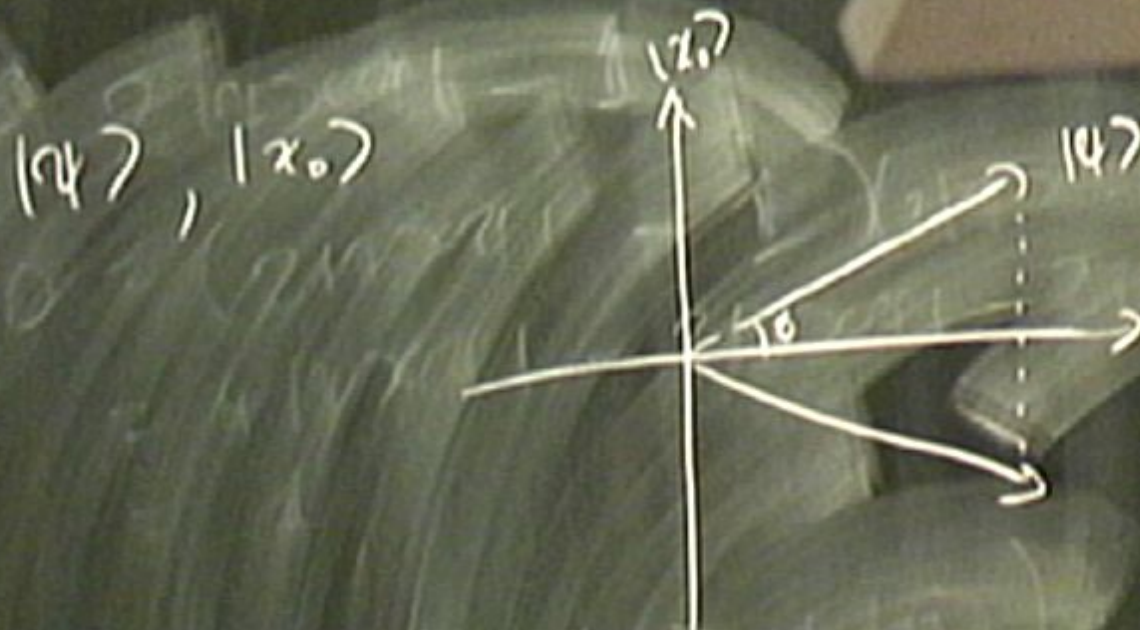
$|14\rangle, |x_0\rangle$

$|x_0\rangle$



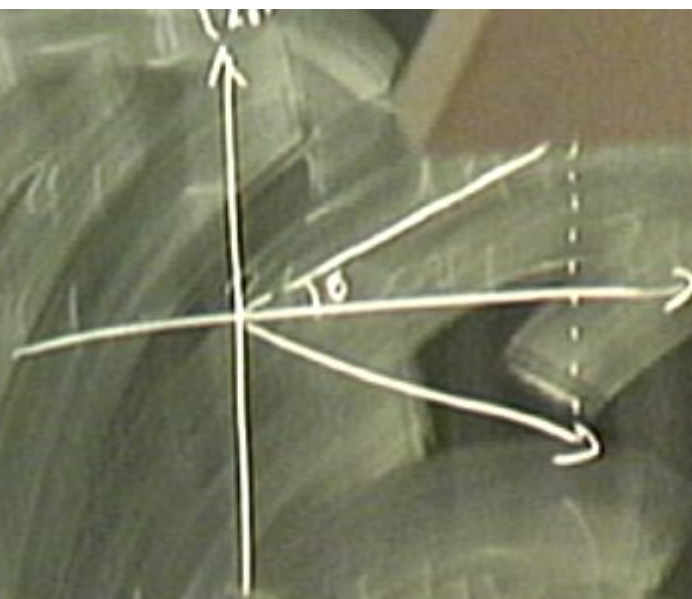


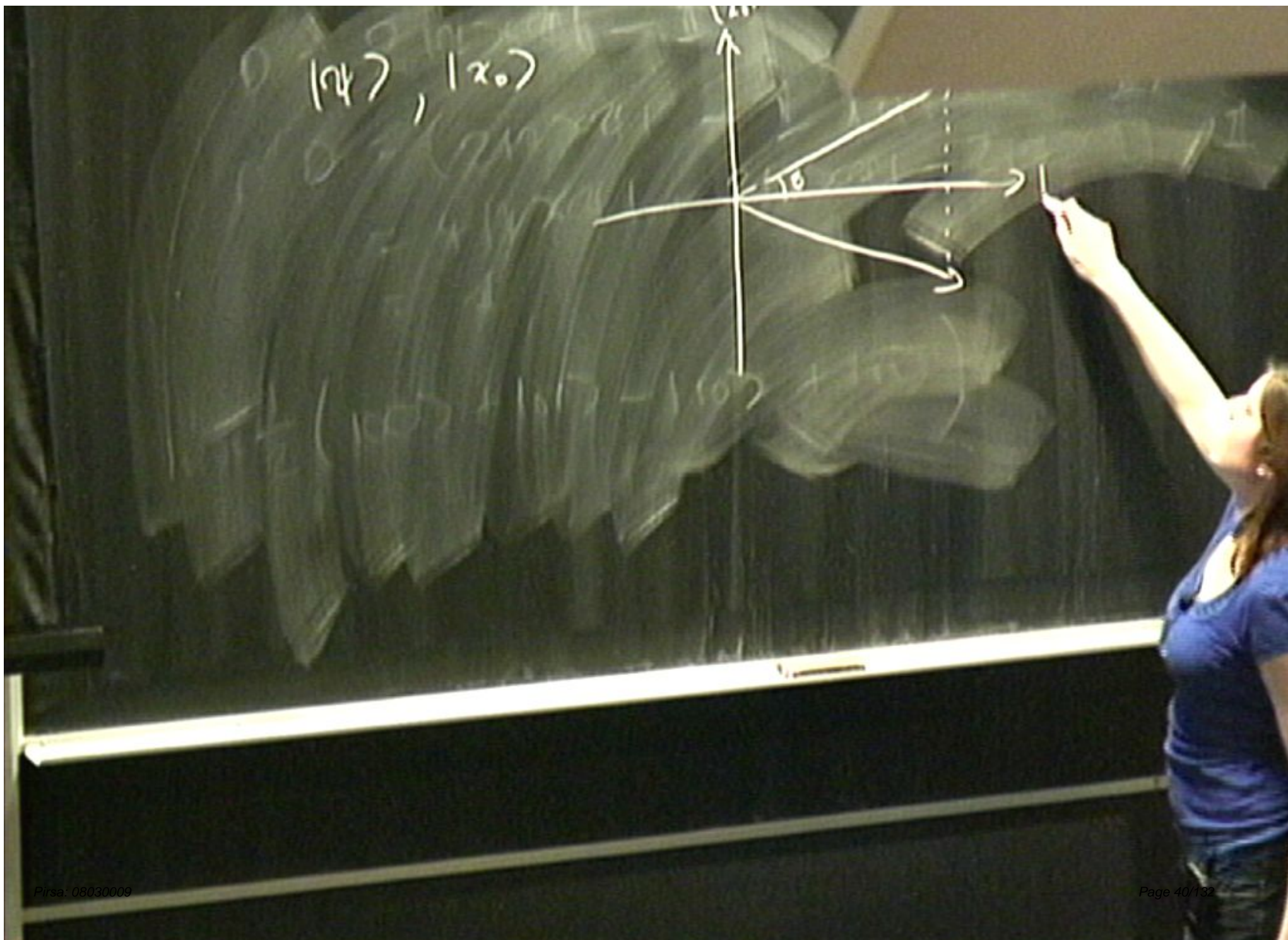




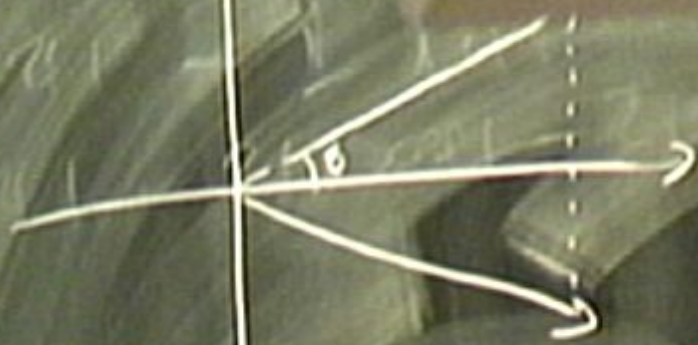


$|111\rangle, |1\bar{1}\bar{1}\rangle$



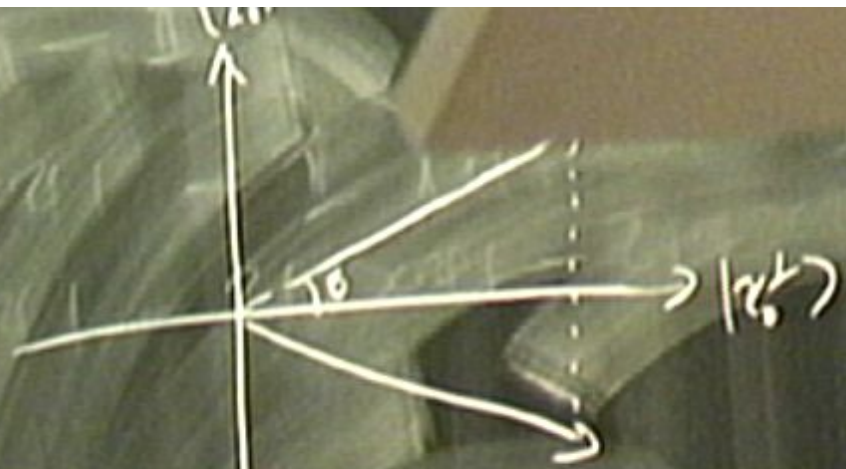


$|n_4\rangle, |x_0\rangle$

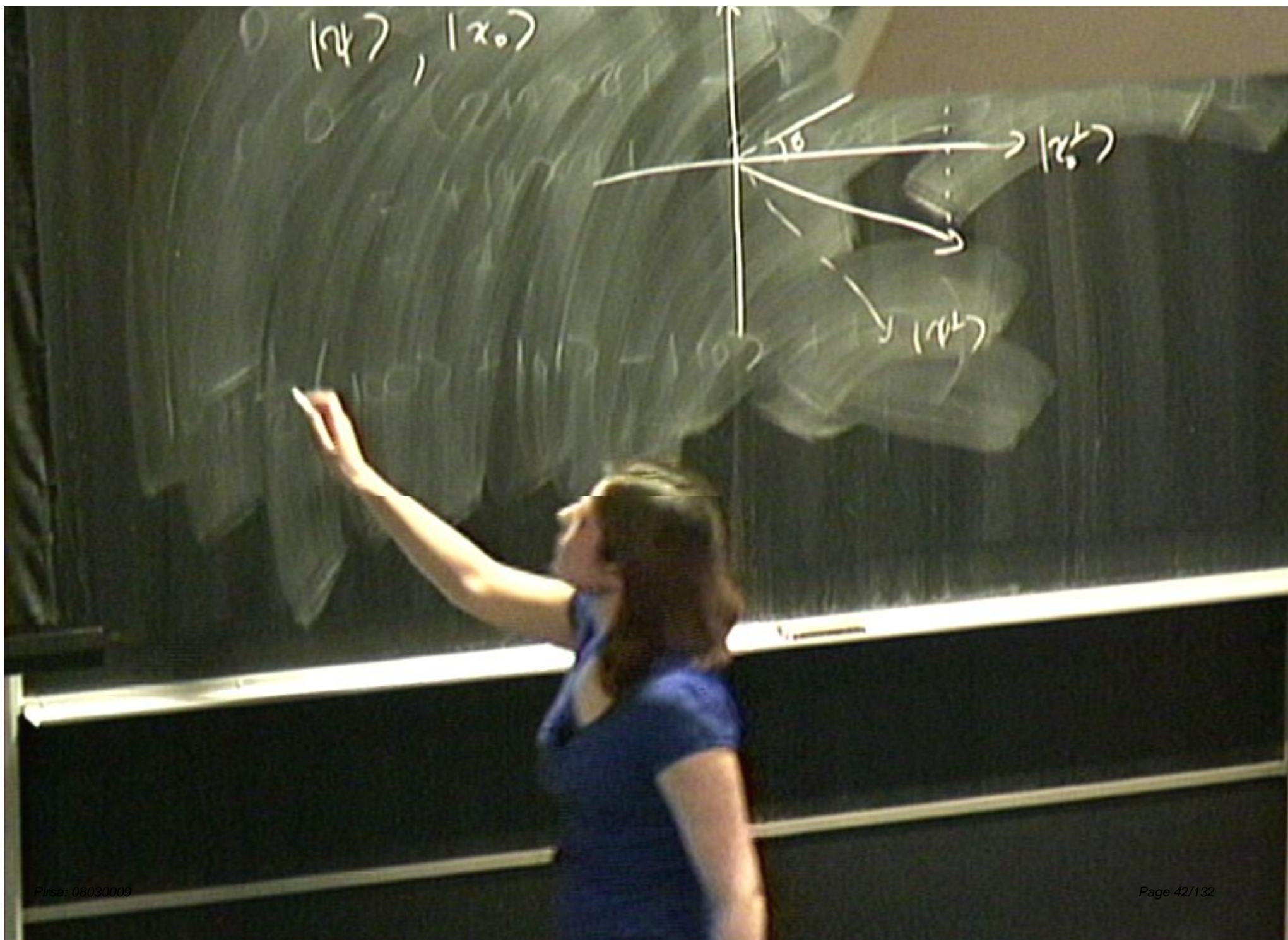




$|n_4\rangle, |x_0\rangle$









$$D = 2|u\rangle\langle u| - \mathbb{I}$$

$$D|\alpha\rangle = 2|u\rangle\langle u|\alpha\rangle - |\alpha\rangle$$

$$= (1002 + 1102 - 1002)$$





$$D = 2|\psi\rangle\langle\psi| - \mathbb{I}$$

$$\begin{aligned} D|\alpha\rangle &= 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\ &= 2(|\alpha\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \end{aligned}$$

$\rightarrow |\alpha\rangle$

$\rightarrow |\psi\rangle$

$$|\psi\rangle\langle\psi| = \frac{1}{4} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

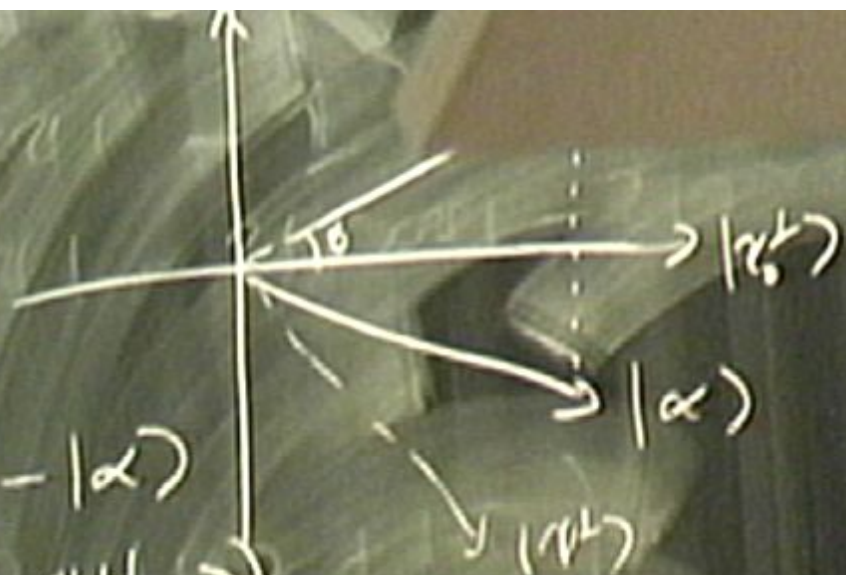


$|\psi\rangle, |\alpha\rangle$

$$D = 2|\psi\rangle\langle\psi| - \mathbb{I}$$

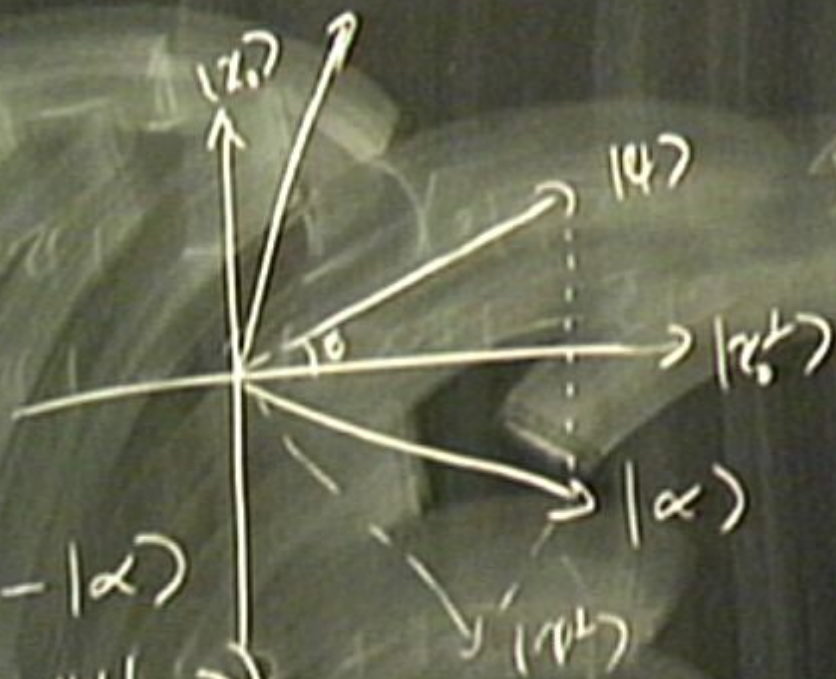
$$\begin{aligned} D|\alpha\rangle &= 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\ &= 2(|\psi\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \end{aligned}$$

$$= |\alpha\rangle - 2|\psi\rangle\langle\psi|\alpha\rangle$$





$|\psi\rangle, |\alpha\rangle$



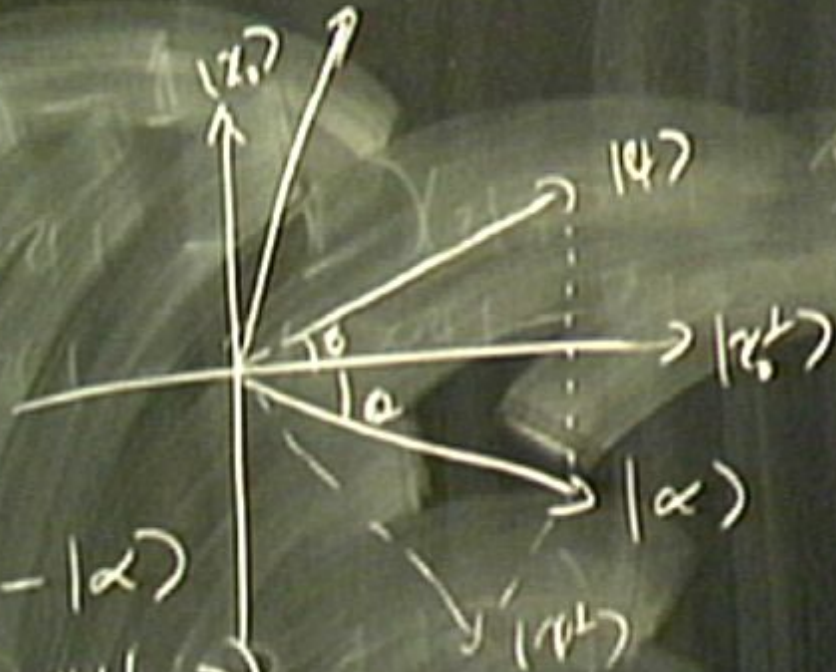
$$D = 2|\psi\rangle\langle\psi| - \mathbb{I}$$

$$\begin{aligned} D|\alpha\rangle &= 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\ &= 2(|\psi\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \end{aligned}$$

$$= |\psi\rangle - 2|\psi^\perp\rangle\langle\psi^\perp|\alpha\rangle$$



$|\psi\rangle, |\alpha\rangle$



$$0 = 2|\psi\rangle\langle\psi| - \mathbb{I}$$

$$\begin{aligned} 0|\alpha\rangle &= 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\ &= 2(|\alpha\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \end{aligned}$$

$$= |\alpha\rangle - 2|\psi\rangle\langle\psi|\alpha\rangle$$



$$= |\alpha\rangle - 2|\psi\rangle + |\alpha\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum |\alpha\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum |\alpha\rangle$$



$$= |\alpha\rangle - 2|\psi\rangle + |\alpha\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum |\alpha\rangle$$

$$= \frac{1}{\sqrt{N}} |\alpha_0\rangle$$



$$= |\alpha\rangle - 2|\psi^\perp\rangle + |\alpha\rangle$$

$$\begin{aligned}
 |\psi\rangle &= \frac{1}{\sqrt{N}} \sum |\alpha\rangle \\
 &= \frac{1}{\sqrt{N}} |\alpha_0\rangle + \sqrt{\frac{N-1}{N}} |\alpha_0^\perp\rangle
 \end{aligned}$$

$$|\alpha\rangle = \frac{1}{\sqrt{N}} \sum |\alpha\rangle$$



$$= |\alpha\rangle - \frac{2}{\sqrt{N}} |\alpha\rangle$$

$$|4\rangle = \frac{1}{\sqrt{N}} \sum |x\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$= |x\rangle - \frac{1}{N} \sum_{j=1}^N |x_j\rangle$$

$$|x\rangle = \frac{1}{\sqrt{N}} \sum_{j=1}^N |x_j\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$= \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$|x_0^\perp\rangle = \frac{1}{\sqrt{N-1}} \sum_{j=1}^N |x_j\rangle$$



$$= |x\rangle - \frac{1}{N} \sum_{j=1}^N |x_j\rangle$$

$$|x\rangle = \frac{1}{\sqrt{N}} \sum_{j=1}^N |x_j\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$= \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^b |x\rangle = \cos\theta |x_0\rangle + \sin\theta |x_0^\perp\rangle$$

$$= |x\rangle - \frac{1}{N} \sum_{y \neq x} |y\rangle$$

$$|x\rangle = \frac{1}{\sqrt{N}} \sum |y\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$|x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^t |x\rangle = -\sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$DU^t |x\rangle =$$



$$= |x\rangle - \frac{1}{\sqrt{N}} \sum_{y \neq x} |y\rangle$$

$$|x\rangle = \frac{1}{\sqrt{N}} \sum_y |y\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

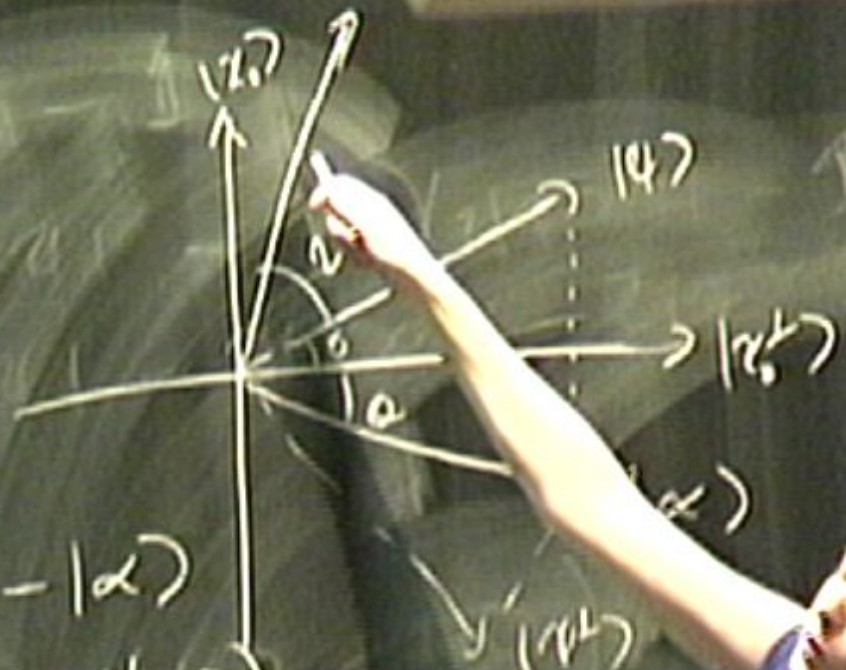
$$|x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^t |x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^{3t} |x\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^\perp\rangle$$

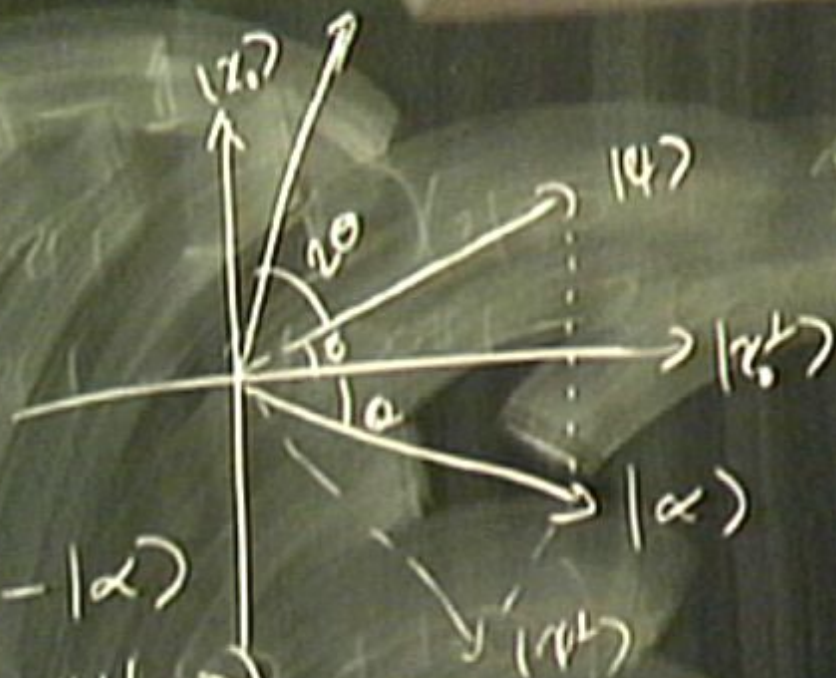


$$\begin{aligned}
 &|\psi\rangle, |\alpha\rangle \\
 &0 = 2|\psi\rangle\langle\psi| - \mathbb{I} \\
 &0|\alpha\rangle = 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\
 &= 2(|\alpha\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \\
 &= |\alpha\rangle - 2|\psi\rangle\langle\psi|\alpha\rangle
 \end{aligned}$$





$|\psi\rangle, |\chi\rangle$



$$0 = 2|\psi\rangle\langle\psi| - \mathbb{I}$$

$$\begin{aligned} 0|\alpha\rangle &= 2|\psi\rangle\langle\psi|\alpha\rangle - |\alpha\rangle \\ &= 2(|\alpha\rangle - |\psi\rangle\langle\psi|\alpha\rangle) - |\alpha\rangle \end{aligned}$$

$$= |\alpha\rangle - 2|\psi\rangle\langle\psi|\alpha\rangle$$



$$|4\rangle = \frac{1}{\sqrt{N}} \sum |x\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$|x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^t |x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^{3t} |x\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^\perp\rangle$$



$$|4\rangle = \frac{1}{\sqrt{N}} \sum |x\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$|x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^t |x\rangle = -\sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$DU^t |x\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^\perp\rangle$$

$$DU_f | \psi \rangle = \sin 3\theta | x_0 \rangle + \cos 3\theta | x_0^\perp \rangle$$

$$U_f DU_f | \psi \rangle$$



$$DU_f | \psi \rangle = \sin 3\theta | \chi_0 \rangle + \cos 3\theta | \chi_0^\perp \rangle$$

$$U_f DU_f | \psi \rangle = -\sin 3\theta | \chi_0 \rangle + \cos 3\theta | \chi_0^\perp \rangle$$

$$DU_f DU_f | \psi \rangle = \sin 5\theta | \chi_0 \rangle + \cos 5\theta | \chi_0^\perp \rangle$$



$$(DU_f | \psi) = \sin 30 | x_0 \rangle + \cos 30 | x_0^\perp \rangle$$

$$U_f DU_f | \psi \rangle = -\sin 30 | x_0 \rangle + \cos 30 | x_0^\perp \rangle$$

$$DU_f DU_f | \psi \rangle = \sin 50 | x_0 \rangle + \cos 50 | x_0^\perp \rangle$$

$\underbrace{\quad}_{\psi}$



$$\underbrace{DU_f DU_f}_{G^2} | \psi \rangle = \sin(5\theta) | x_0 \rangle + \cos(5\theta) | x_0^\perp \rangle$$

$$G^k | \psi \rangle = \sin((2k+1)\theta) | x_0 \rangle + \cos((2k+1)\theta) | x_0^\perp \rangle$$



$$DU_f DU_f |\chi\rangle = \sin 5\theta |\chi_0\rangle + \cos 5\theta |\chi_0^\perp\rangle$$

$G^2$

$$G^k |\chi\rangle = \sin((2k+1)\theta) |\chi_0\rangle + \cos((2k+1)\theta) |\chi_0^\perp\rangle$$



$$G^k |\psi\rangle = \sin((2k+1)\theta) |x_0\rangle + \cos((2k+1)\theta) |x_0^\perp\rangle$$

$$P(x_0) = \langle x_0 | G^k |\psi\rangle|^2 = \sin^2((2k+1)\theta)$$

$$D = 2|\psi\rangle\langle\psi| - \mathbb{I}$$



$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum |x\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^\perp\rangle$$

$$|x\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$U^b |\psi\rangle = -\sin\theta |x_0\rangle + \cos\theta |x_0^\perp\rangle$$

$$DU^b |\psi\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^\perp\rangle$$



$$|\alpha\rangle = U^{\dagger} |\alpha\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{N}} \sum |x\rangle$$

$$= \frac{1}{\sqrt{N}} |x_0\rangle + \sqrt{\frac{N-1}{N}} |x_0^{\perp}\rangle$$

$$|\psi\rangle = \sin\theta |x_0\rangle + \cos\theta |x_0^{\perp}\rangle$$

$$U^{\dagger} |\psi\rangle = -\sin\theta |x_0\rangle + \cos\theta |x_0^{\perp}\rangle$$

$$DU^{\dagger} |\psi\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^{\perp}\rangle$$

$$\sin^2((2k+1)\theta) \approx 1$$

$$\Rightarrow (2k+1)\theta \approx \frac{\pi}{2}$$



$$\sin^2((2k+1)\theta) \approx 1$$

$$\Rightarrow (2k+1)\theta \approx \frac{\pi}{2}$$

$$k = \frac{\frac{\pi}{2}}{\theta} - \frac{1}{2}$$

$$\sin^2((2k+1)\theta) \approx 1$$

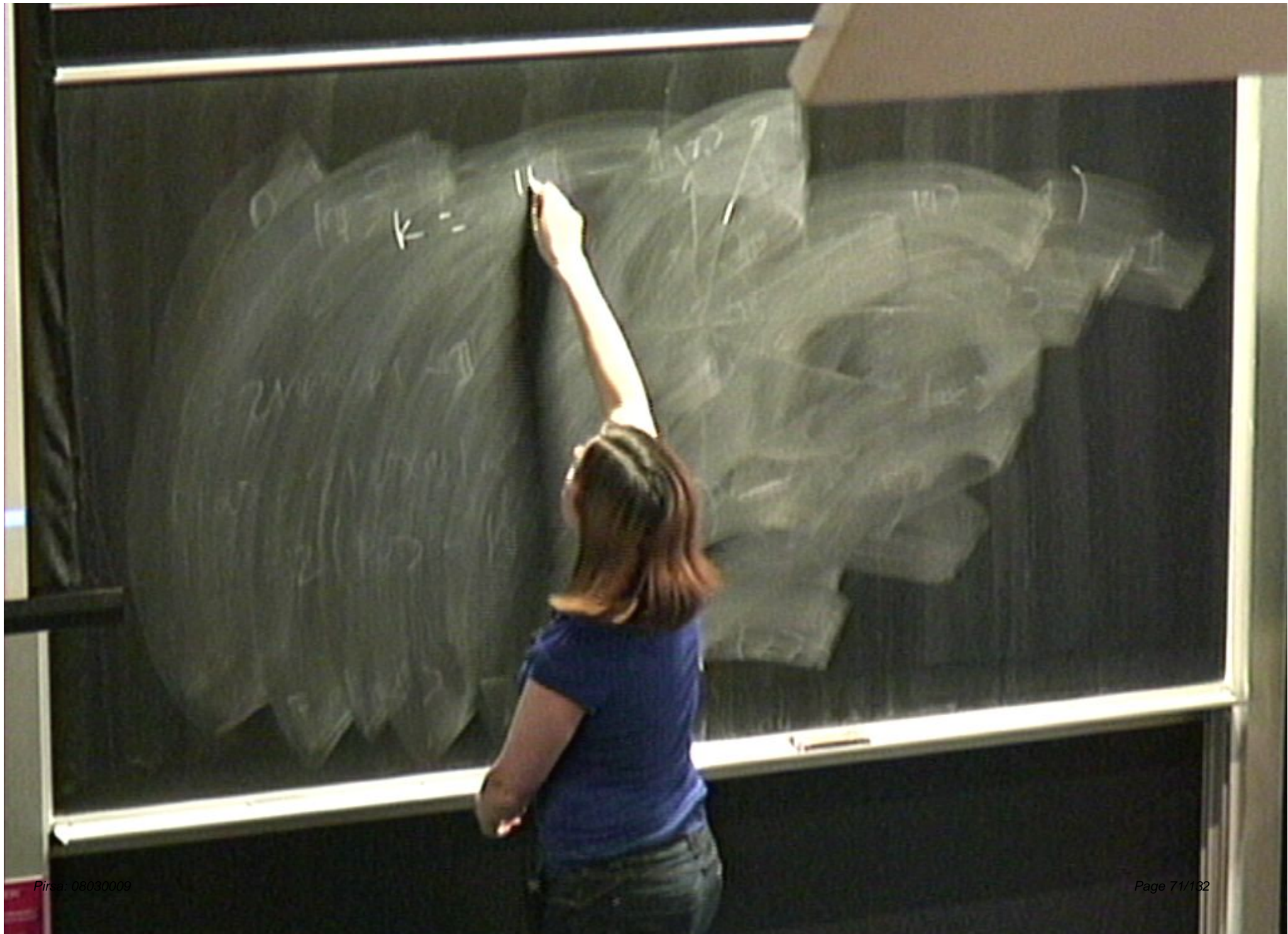
$$\Rightarrow (2k+1)\theta \approx \frac{\pi}{2}$$

$$k = \frac{\pi}{4\theta} - \frac{1}{2}$$

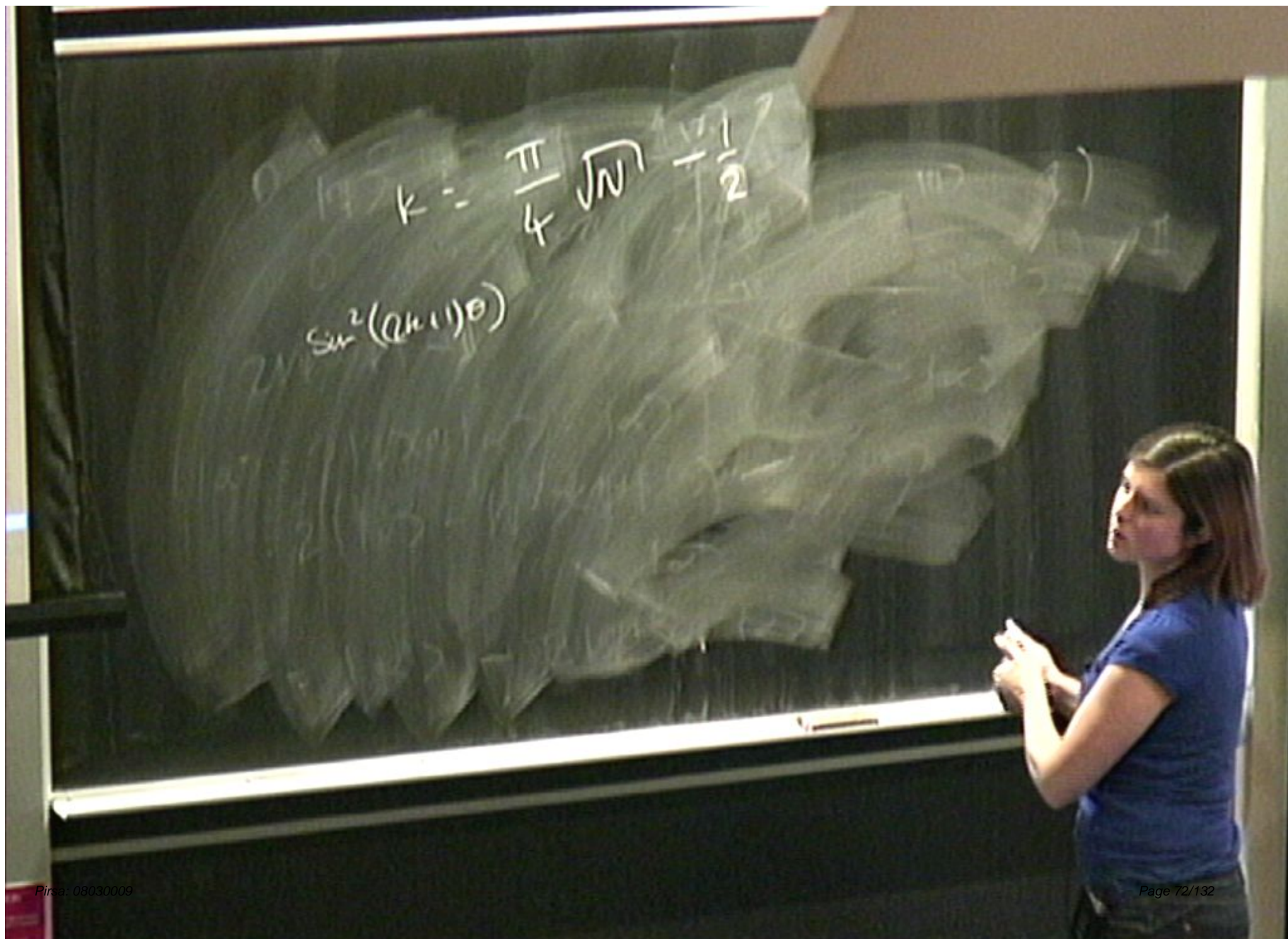
$$\sin\theta = \frac{1}{\sqrt{N}}, \quad \theta \approx \frac{1}{\sqrt{N}}$$

$$\Rightarrow k = \frac{\pi}{4\sqrt{N}} - \frac{1}{2} = O(\sqrt{N})$$

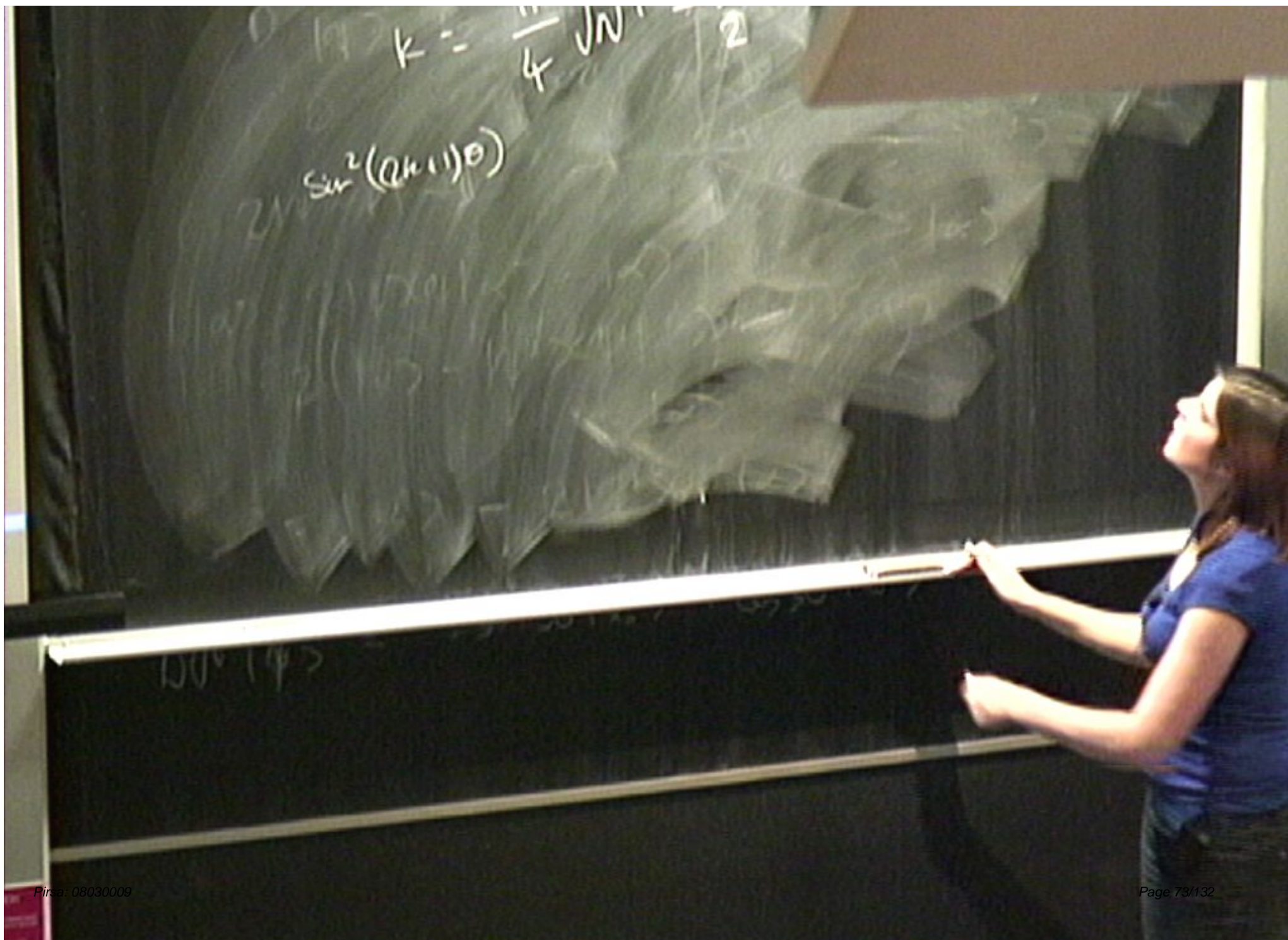














$$k = \frac{\pi}{4} \sqrt{N} - \frac{1}{2}$$

$$\frac{L+1}{\sqrt{N}} \approx \frac{1}{2}$$

$$\sin^2(qk(1)0)$$



$$\sin^2((2k+1)\theta)$$

$$p(\tau) = \cos^2((2k+1)\theta) \\ = \sin^2(\pi/2 - (2k+1)\theta)$$

$$\text{DUB} |\psi\rangle = \sin 3\theta \cos 3\theta |\psi_0^+\rangle$$



$$\sin^2((2k+1)\theta)$$

$$\begin{aligned} p(\epsilon) &= \cos^2((2k+1)\theta) \\ &= \sin^2\left(\frac{\pi}{2} - (2k+1)\theta\right) \\ &\sim O\left(\frac{\pi}{2} - (2k+1)\theta\right) \sim O\left(\frac{1}{N}\right) \end{aligned}$$

$$DUB|\psi\rangle = \sin 3\theta |x_0\rangle + \cos 3\theta |x_0^\perp\rangle$$



$$U|x\rangle|0\rangle \rightarrow |x\rangle|f(x)\rangle$$

$$D = 2|x\rangle\langle x| - I$$

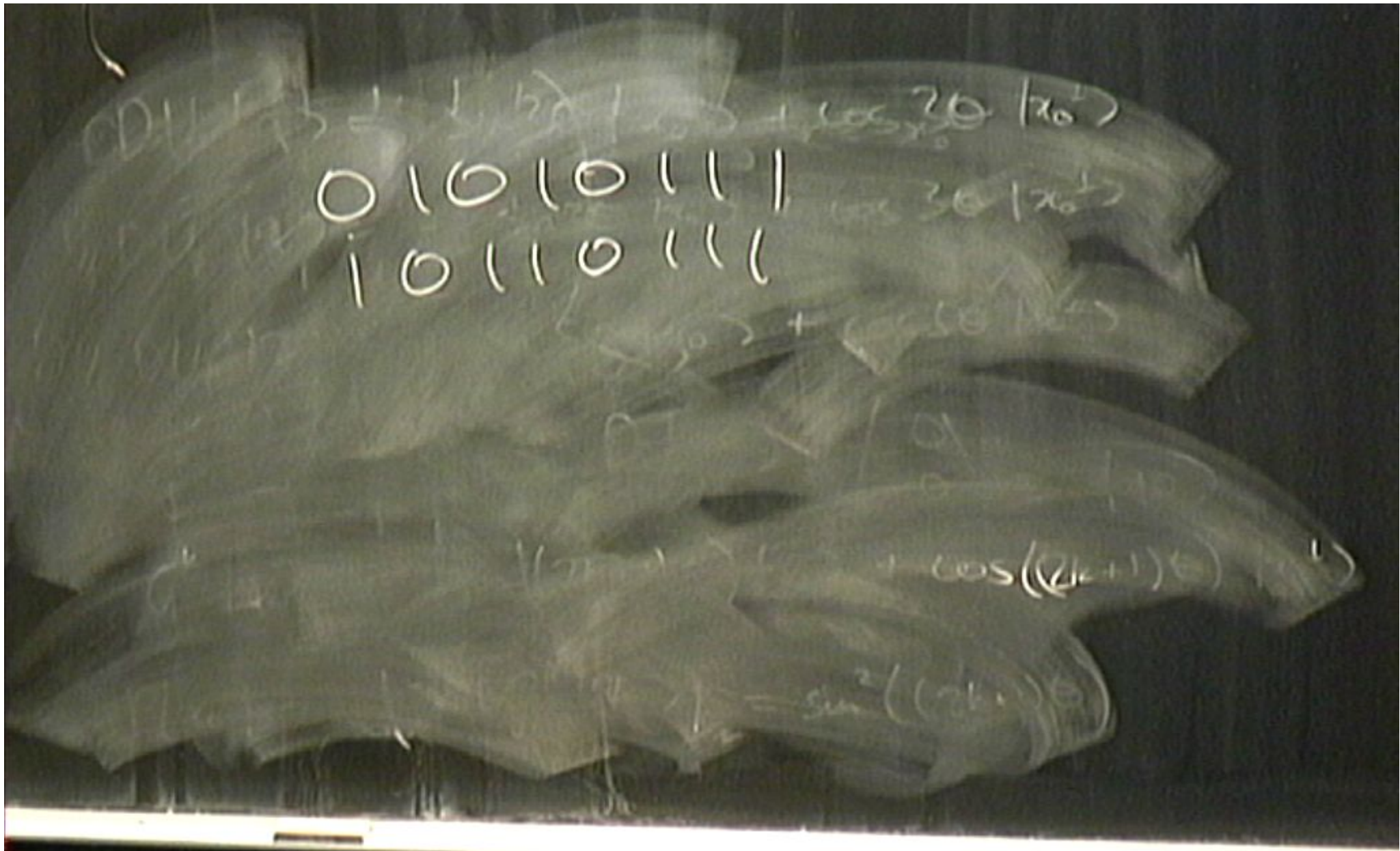
# Computational Complexity

- Problems which can be solved in a time polynomial in the size of the input (i.e. the number of bits needed to store the input) are in the complexity class P, e.g. multiplication.
- (Classical) Strong Church-Turing thesis: A probabilistic Turing machine can efficiently simulate any realistic model of computation.
- Problems whose solution can be verified in polynomial time are in the complexity class NP e.g. factorisation.
- Not known if  $P=NP$ . (It is conjectured, but not proven, that this is not the case).
- NP-complete problems, e.g. travelling salesman.



# Computational Complexity

- Problems which can be solved in a time polynomial in the size of the input (i.e. the number of bits needed to store the input) are in the complexity class P, e.g. multiplication.
- (Classical) Strong Church-Turing thesis: A probabilistic Turing machine can efficiently simulate any realistic model of computation.
- Problems whose solution can be verified in polynomial time are in the complexity class NP e.g. factorisation.
- Not known if  $P=NP$ . (It is conjectured, but not proven, that this is not the case).
- NP-complete problems, e.g. travelling salesman.





# Computational Complexity

- Problems which can be solved in a time polynomial in the size of the input (i.e. the number of bits needed to store the input) are in the complexity class P, e.g. multiplication.
- (Classical) Strong Church-Turing thesis: A probabilistic Turing machine can efficiently simulate any realistic model of computation.
- Problems whose solution can be verified in polynomial time are in the complexity class NP e.g. factorisation.
- Not known if  $P=NP$ . (It is conjectured, but not proven, that this is not the case).
- NP-complete problems, e.g. travelling salesman.

# Shor's Algorithm

- Integer factorization algorithm. Believed to be computationally hard classically, which is important for security of RSA public key cryptography.
- Best known classical algorithm requires  $\exp(O((\log N)^{1/3}(\log \log N)^{2/3}))$  gates.
- Shor's algorithm requires a number of gates which is polynomial in input size (polynomial in  $\log N$ ).
- Shor's algorithm is probabilistic.



# Decoherence and Scalability

- Have assumed unitary transformations, in the presence of an environment this is not the case.
- Interactions with an environment partially corrupt the information encoded in quantum states.
- Fault-tolerant quantum computation possible if probability of single gate error is below a certain threshold level.
- Is there a scale at which the world stops behaving quantum mechanically?

# Shor's Algorithm

- Integer factorization algorithm. Believed to be computationally hard classically, which is important for security of RSA public key cryptography.
- Best known classical algorithm requires  $\exp(O((\log N)^{1/3}(\log \log N)^{2/3}))$  gates.
- Shor's algorithm requires a number of gates which is polynomial in input size (polynomial in  $\log N$ ).
- Shor's algorithm is probabilistic.



find  $r$  such that  
 $a^r = a \pmod N$

$$\Rightarrow k = \frac{\pi}{4} \sqrt{N} - \frac{1}{2} = O(\sqrt{N})$$



(Classical)  $N$

find  $r$  such that  
 $a^r = a \pmod N$



$$f(x) = \sin^2(x)$$

$$f(x+r) = f(x)$$

$$f(x+r) = f(x)$$

$$\frac{1}{\sqrt{N}} \sum |x\rangle |0\rangle$$



$$f(x+r) = f(x)$$

$$\left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle$$

$$U^\dagger \left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle \rightarrow \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle$$



$$f(x+r) = f(x)$$

$$\left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle$$

$$U^\dagger \left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle \rightarrow \frac{1}{\sqrt{Q}} \sum_{x=10}^{Q-1} |x\rangle |f(x)\rangle$$



$$f(x+r) = f(x)$$

$$\left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle$$

$$U^{\dagger} \left( \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle \right) |0\rangle \rightarrow \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle |f(x)\rangle$$



$$\left( \frac{1}{\sqrt{Q}} \sum |x\rangle \right) |0\rangle$$

$$U^{\dagger} \left( \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle \right) |0\rangle \rightarrow \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle |f(x)\rangle$$

$$f(x_0) \rightarrow \frac{1}{\sqrt{Q}} \sum_{x: f(x)=f(x_0)} |x\rangle$$



$$-\left(\frac{1}{\sqrt{Q}} \sum |x\rangle\right) |0\rangle$$

$$U^\dagger \left( \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle \right) |0\rangle \rightarrow \frac{1}{\sqrt{Q}} \sum_{x=0}^{Q-1} |x\rangle |f(x)\rangle$$

$$f(x_0) \rightarrow \frac{1}{\sqrt{Q}} \frac{1}{\sqrt{Q}} \sum_{x: f(x)=f(x_0)} |x\rangle$$

$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$



$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$1 - \frac{x}{r} = M$$

$$\sum_{j=0}^{M-1} |x_0 + jr|$$

$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr|$$



$$\Rightarrow x = x_0 + jr, \quad j \text{ integer} \quad , \quad \frac{Q}{r} = m$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$U_{QR} |x\rangle =$$

$$\Rightarrow x = x_0 + jr, \quad j \text{ integer} \quad , \quad \frac{Q}{r} = m$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$U_{QFT} |x\rangle = \sum$$



$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$U_{QFT} |x\rangle = \sum_{y=0}^{m-1} e^{2\pi i xy/m} |y\rangle$$

$$\rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$U_{QR} |x\rangle = \sum_{y=0}^{Q-1} \left(e^{i\frac{2\pi}{Q}}\right)^{xy} |y\rangle$$



$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$\hookrightarrow \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}}$$

$$U_{QR} |x\rangle \approx \frac{1}{\sqrt{Q}} \sum_{y=0}^{Q-1} (e^{i\phi})^y |y\rangle$$



$$\Rightarrow x = x_0 + jr, \quad j \text{ integer}$$

$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$\hookrightarrow \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{m-1} \sum_{y=0}^{Q-1}$$

$$U_{QR} |x\rangle = \frac{1}{\sqrt{Q}} \sum_{y=0}^{Q-1} (e^{i\frac{2\pi}{Q}})^{xy} |y\rangle$$



$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

Unitary  $|x\rangle$

$$\hookrightarrow \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{m-1} \sum_{y=0}^{Q-1} (e^{2\pi i / Q})^{(x_0 + jr)y} |y\rangle$$



$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

Unitary  $U_{\text{QFT}}$

$$\left( \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{m-1} \sum_{y=0}^{Q-1} (e^{2\pi i y r / Q})^{x_0 + jr} \right) |y\rangle$$

$$= \frac{1}{\sqrt{mQ}} \sum_{y=0}^{Q-1} (e^{2\pi i y r / Q})^{x_0}$$



$$\rightarrow \frac{1}{\sqrt{N}} \sum_{j=0}^{N-1} (e^{i\pi j/a})^{*y} \left( \sum_{j=0}^{N-1} (e^{i\pi j/a})^j \right) |y\rangle$$

$$U_b |x\rangle |0\rangle \rightarrow |x\rangle |b(x)\rangle$$

$$D = 2|x\rangle\langle x| - I$$



$$= \frac{1}{\sqrt{N_0}} \sum_{j=0}^{N_0-1} (e^{j\pi/N_0})^{*y} \left( \sum_{j=0}^{N_0-1} (e^{j\pi/N_0})^j \right) |y\rangle$$

$\frac{N_0}{2}$  integer  $\Rightarrow \sum_{j=0}^{N_0-1} (e^{j\pi/N_0})^y$



$$= \frac{1}{\sqrt{a}} \sum_{j=0}^{a-1} (e^{\pi i/a})^{xy} \left( \sum_{j=0}^{a-1} (e^{\pi i/a})^j \right) |y\rangle$$

$\frac{xy}{a}$  integer

$$\Rightarrow \sum_{j=0}^{a-1} (e^{\pi i/a})^j = \sum_{j=0}^{a-1} (1)^j$$

$$= \frac{1}{\sqrt{4\pi\sigma^2}} \sum_{j=0}^{\infty} (e^{\frac{\pi^2 j^2}{\sigma^2}})^{-1} \left( \sum_{j=0}^{\infty} (e^{\frac{\pi^2 j^2}{\sigma^2}})^{-1} \right)^{-1}$$

$\frac{r_4}{\sigma}$  integer

$$\Rightarrow \sum_{j=0}^{n-1} (e^{\frac{\pi^2 j^2}{\sigma^2}})^{-1} = \sum_{j=0}^{n-1} (1)^j = n$$



$$\sqrt{n} \cdot 0 \leq \sum_{j=0}^{\infty} \dots$$

$$\frac{ry}{Q} \text{ integer}$$

$$\frac{2\pi r}{Q}$$

$$\Rightarrow \sum_{j=0}^{n-1} (e^{\frac{2\pi i r j}{Q}})^y = \sum_{j=0}^{n-1} (1)^j = n$$

$\frac{ry}{Q}$  integer

$$\Rightarrow \sum_{j=0}^{n-1} (e^{\frac{2\pi i ry}{Q}})^j = \sum_{j=0}^{n-1} (1)^j = n$$

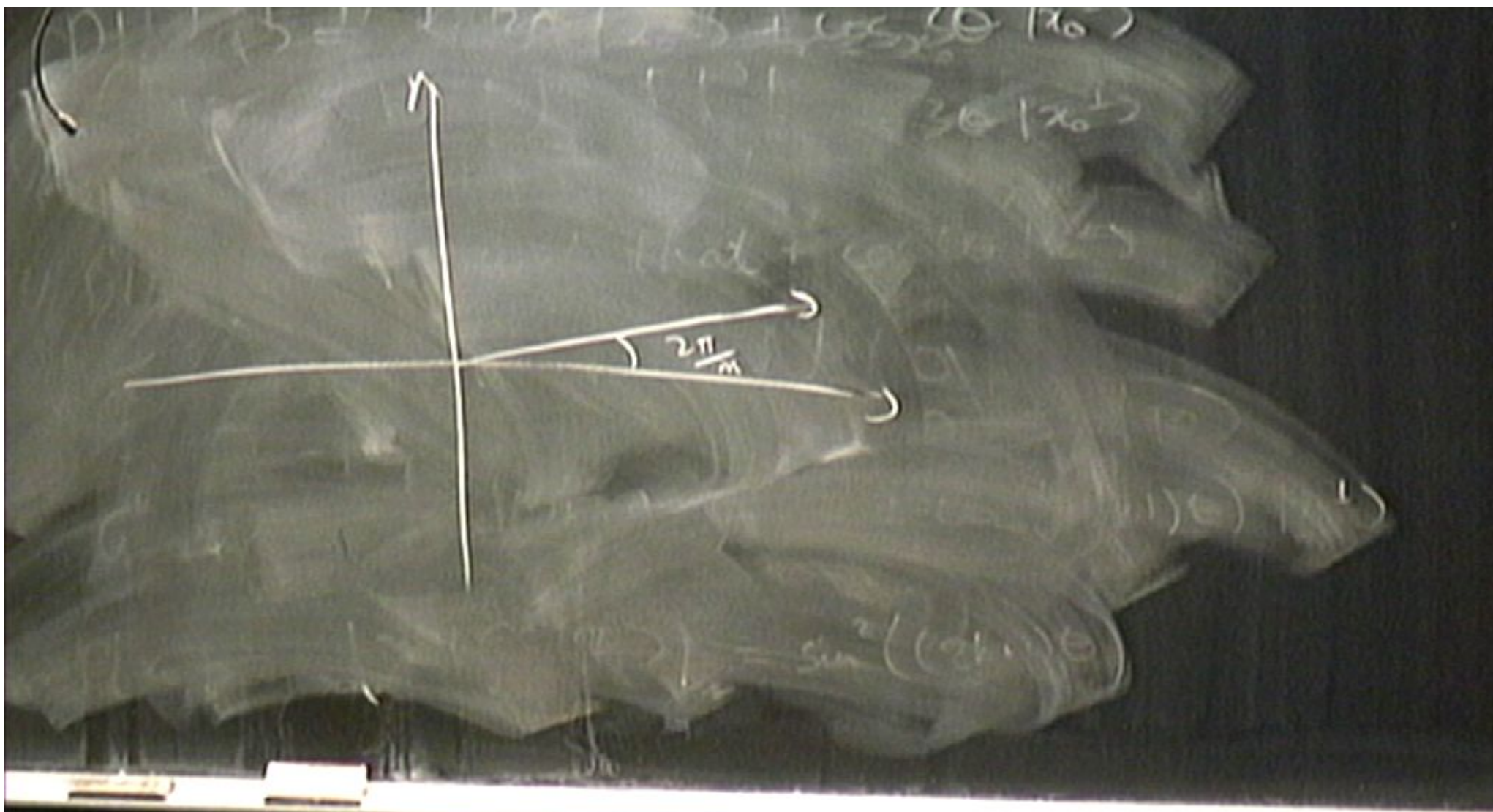
$$\sum_j e^{\left(\frac{2\pi i ry_j}{Q}\right)} = \sum_j \cos \frac{2\pi ry_j}{Q} + i \sin \frac{2\pi ry_j}{Q}$$



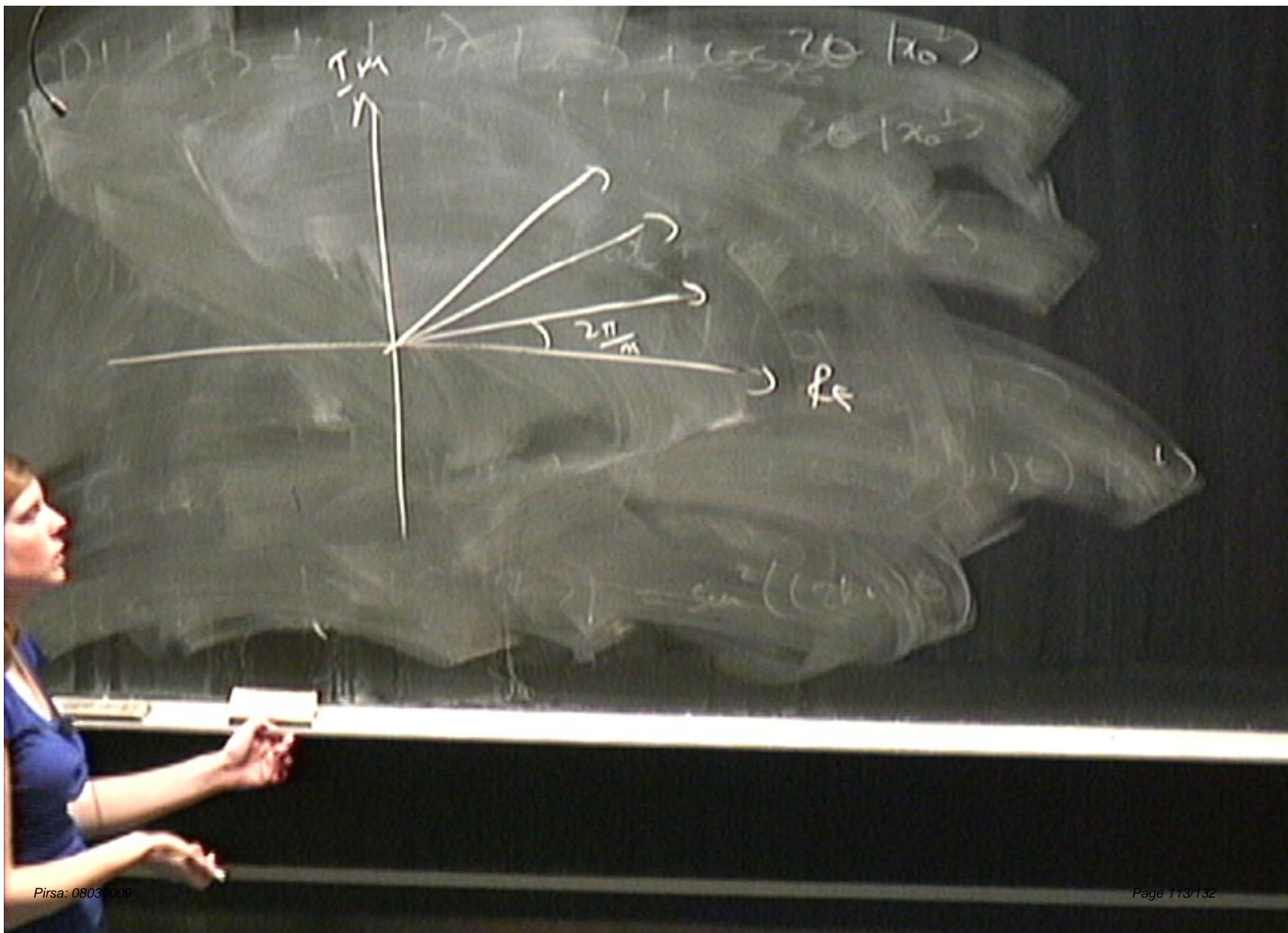
$\frac{ry}{Q}$  integer

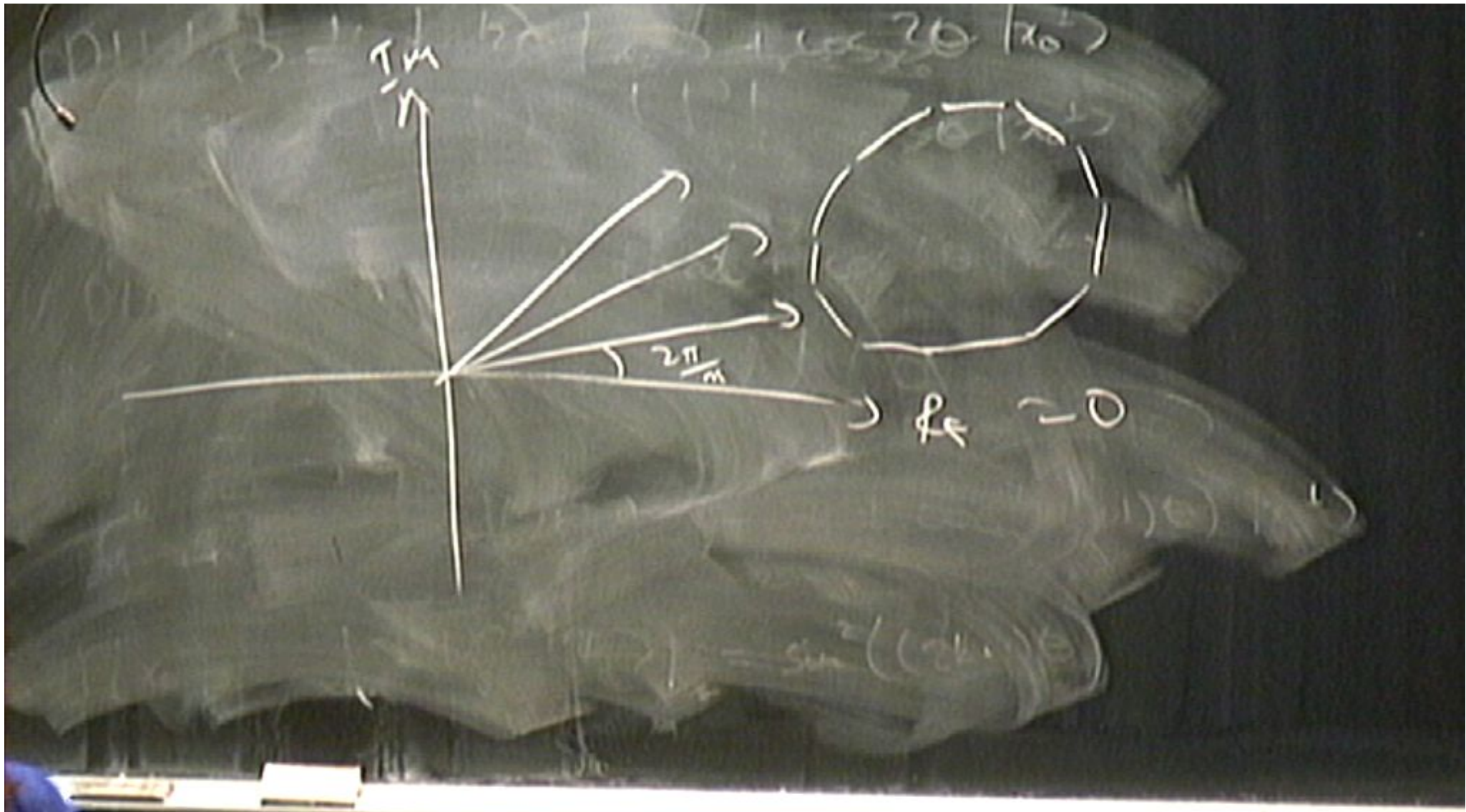
$$\Rightarrow \sum_{j=0}^{m-1} (e^{\frac{2\pi i ry}{Q}})^j = \sum_{j=0}^{m-1} (1)^j = m$$

$$\sum_j e\left(\frac{2\pi ry_j}{Q}\right) = \sum_j \cos \frac{2\pi ry_j}{m} + i \sin \frac{2\pi ry_j}{m}$$











$$\frac{1}{\sqrt{m}} \sum_{j=0}^{m-1} |x_0 + jr\rangle$$

$$U_{QR} |x\rangle$$

$$\hookrightarrow \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{m-1} \sum_{y=0}^{Q-1} (e^{2\pi i \frac{r}{Q}})^{(x_0 + jr)y} |y\rangle$$

$$= \frac{1}{\sqrt{mQ}} \sum_{y=0}^{Q-1} (e^{2\pi i \frac{r}{Q}})^{x_0 y} \left( \sum_{j=0}^{m-1} (e^{2\pi i \frac{r}{Q}})^{jy} \right) |y\rangle$$

$$\text{of } Q$$



$$\left( \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{Q-1} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i}{Q}})^{(x_0+j)y} |y\rangle \right)$$

$$= \frac{1}{\sqrt{mQ}} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i}{Q}})^{x_0 y} \left( \sum_{j=0}^{Q-1} (e^{\frac{2\pi i}{Q}})^{jy} \right) |y\rangle$$

$$\frac{ry}{Q} = k$$

$$\sum_j e^{\left(\frac{2\pi i r y_j}{Q}\right)j} = \sum_j \cos \frac{2\pi y_j}{m} + i \sin \frac{2\pi y_j}{m}$$



$$\left( \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{Q-1} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i y j}{Q}}) |y\rangle \right)$$

$$= \frac{1}{\sqrt{mQ}} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i y j}{Q}})^* \left( \sum_{j=0}^{Q-1} (e^{\frac{2\pi i y j}{Q}})^j \right) |y\rangle$$

$$y = 0, \dots, Q-1$$

$\frac{1}{Q} \sum_{j=0}^{Q-1} (e^{\frac{2\pi i y j}{Q}})^j = \sum_{j=0}^{Q-1} (1)^j = Q$

$$\sum_{j=0}^{Q-1} e^{\left(\frac{2\pi i y j}{Q}\right)^j} = \sum_{j=0}^{Q-1} \cos \frac{2\pi y j}{m} + i \sin \frac{2\pi y j}{m}$$



$$\hookrightarrow \frac{1}{\sqrt{m}} \frac{1}{\sqrt{Q}} \sum_{j=0}^{m-1} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i y j}{Q}})^j |y\rangle$$

$$= \frac{1}{\sqrt{mQ}} \sum_{y=0}^{Q-1} (e^{\frac{2\pi i y}{Q}})^j \left( \sum_{j=0}^{m-1} (e^{\frac{2\pi i y j}{Q}})^j \right) |y\rangle$$

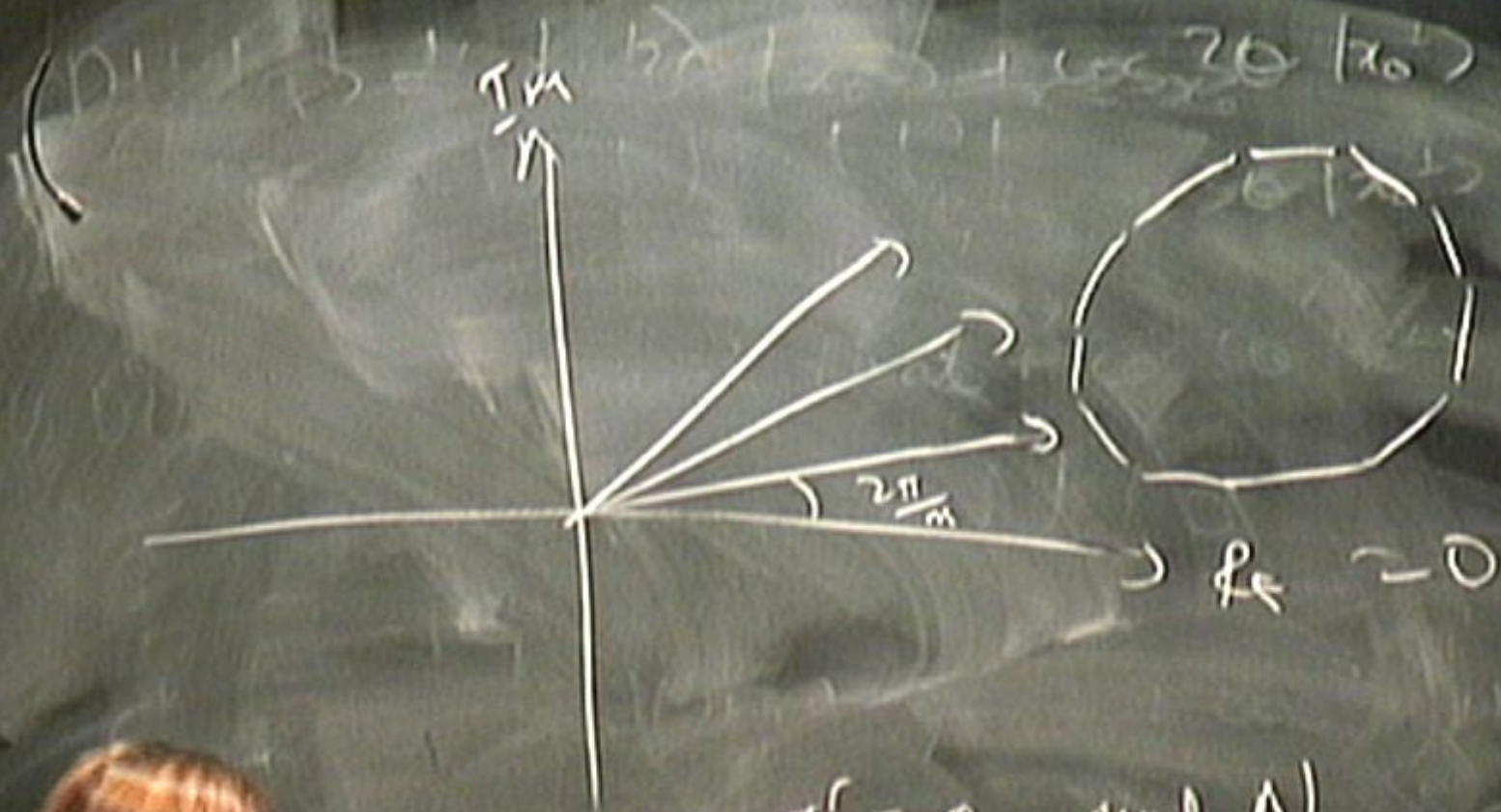
$$y = 0 \quad + \quad \frac{2\pi i y}{Q} \quad + \quad \frac{2\pi i y}{Q}$$

$\frac{r y}{Q}$  integer

$$\Rightarrow \sum_{j=0}^{m-1} (e^{\frac{2\pi i y j}{Q}})^j = \sum_{j=0}^{m-1} (1)^j = m$$

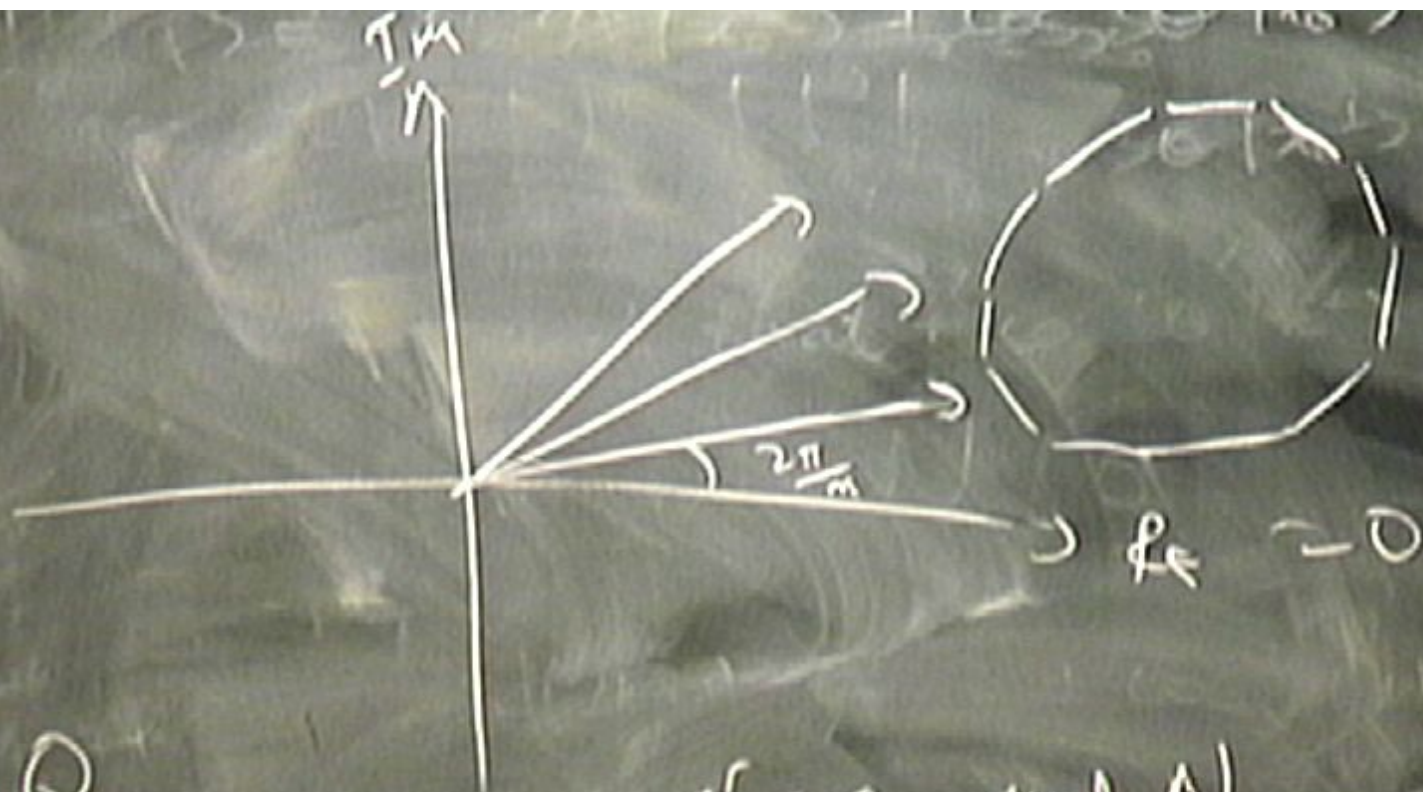
$$\sum_j e^{\left(\frac{2\pi i r y_j}{Q}\right)^j} = \sum_j \cos \frac{2\pi y_j}{m} + i \sin \frac{2\pi y_j}{m}$$





$$x^r = a \pmod{N}$$





$$\frac{Q}{r} = m$$

$$a^r = a \pmod{N}$$



$\frac{ry}{q}$  integer

$$\Rightarrow \sum_{j=0}^{n-1} \left( e^{\frac{2\pi i r y}{q}} \right)^j = \sum_{j=0}^{n-1} (1)^j = n$$

$$\sum_j e^{\left( \frac{2\pi i r y_j}{q} \right)} = \sum_j \cos$$

$\frac{ry}{a}$  integer

$$\Rightarrow \sum_{j=0}^{m-1} \left( e^{\frac{2\pi i ry}{a}} \right)^j = \sum_{j=0}^{m-1} (1)^j = m$$

$$\sum_j e\left(\frac{2\pi ry_j}{a}\right) = \sum_j \cos \frac{2\pi y_j}{m} + i \sin \frac{2\pi y_j}{m}$$



# Decoherence and Scalability

- Have assumed unitary transformations, in the presence of an environment this is not the case.
- Interactions with an environment partially corrupt the information encoded in quantum states.
- Fault-tolerant quantum computation possible if probability of single gate error is below a certain threshold level.
- Is there a scale at which the world stops behaving quantum mechanically?

$$\frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$$

$$\frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)$$



$$\frac{1}{\sqrt{2}} (|0\rangle + |1\rangle) |2\rangle$$

$$\frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) |2\rangle$$

$$\frac{1}{\sqrt{2}} (|0\rangle |2_0\rangle + |1\rangle |2_1\rangle)$$



$$\frac{1}{\sqrt{2}} (|0\rangle + |1\rangle) |2\rangle$$

$$\frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) |2\rangle$$

$$\frac{1}{\sqrt{2}} (|0\rangle |2_0\rangle + |1\rangle |2_1\rangle) \Rightarrow \rho = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$



$$\frac{1}{\sqrt{2}} (|0\rangle + |1\rangle) | \psi \rangle$$

$$\frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) | \psi \rangle$$

$$\begin{matrix} 000 \\ 010 \end{matrix}$$

$$\frac{1}{\sqrt{2}} (|0\rangle | \psi_0 \rangle + |1\rangle | \psi_1 \rangle) \Rightarrow \rho = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

# Summary

- By taking advantage of the laws of quantum mechanics, we can perform some information processing and communication tasks that are not possible classically.
  - Dense coding, teleportation, QKD
  - Quantum algorithms
- It is not possible to do EVERYTHING faster with a quantum computer! But by carefully using quantum parallelism and interference, it is possible to design some algorithms which are more powerful than any known classical ones.



# Open questions

- What are the class of problems for which a quantum computer can provide an improvement over classical computing?
  - Note that, in principle, a quantum computer can do anything a classical one can (without speed-up).
- What is it that makes a quantum computer more powerful? (Entanglement is not the full story...)
- Is quantum computing scalable?

## References

- Quantum Cryptography: N. Gisin, G. C. Ribordy, W. Tittel and H. Zbinden, “Quantum cryptography”, *Reviews of Modern Physics* **74**, 145 (2002)
- Quantum Information Processing: T. P. Spiller, W. J. Munro, S. D. Barrett and P. Kok, “An introduction to quantum information processing: applications and realizations”, *Contemporary Physics* **46**, 407 (2005)
- Shor’s algorithm for the man on the street:  
<http://scottaaronson.com/blog/?p=208>



