

Title: Generating stationary axisymmetric solutions of 5D gravity.

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Abstract: I will discuss a solution generating technique that allows to generate stationary axisymmetric solutions of five-dimensional gravity, starting from static ones. This technique can be used to add angular momentum to static configurations. It can also be used to add KK-monopole charge to asymptotically flat five-dimensional solutions, thus generating geometries that interpolate between five-dimensional and four-dimensional solutions.

# Generating stationary axisymmetric solutions of 5D gravity

Stefano Giusto

University of Toronto



PI, September 18, 2007

Based on work with J. Ford, A. Peet and A. Saxena

S.G. and A. Saxena, [arXiv:0705.4484](https://arxiv.org/abs/0705.4484) [hep-th];

J. Ford, S.G., A. Peet and A. Saxena, [arXiv:0708.3823](https://arxiv.org/abs/0708.3823) [hep-th].

# Outline

- 1 Motivation
- 2 Review of known results
  - Static solutions
  - Stationary Solutions
  - $SL(3, \mathbb{R})$  invariance
- 3 Generating angular momentum
- 4 Generating KK-monopole charge
  - Applications
- 5 Summary



# Motivation

- Finding exact solutions to Einstein equations is hard.
- Most of the advances in our understanding of gravity hinge upon the knowledge of exact solutions.
- In  $D > 4$  there is a rich structure of black hole phases, and many new solutions to be discovered. An important testing ground for a theory of quantum gravity will be to explain this phase structure.
- String theory has already been successful in explaining a large part of this structure: microscopic derivation of black hole entropy, Hawking radiation, Gregory-Laflamme instability for black holes in KK spaces.

## Why we focus on the case of $D = 5$ ?

- It is non-trivial. There are black holes with different topologies:  
Myers-Perry Black Hole (topology  $S^3$ );  
Black-Ring (topology  $S^2 \times S^1$ ).
- It is close to being fully solved.  
In contrast to the case  $D \neq 5$ , where much less is known yet:  
Emparan, Harmark, Niarchos, Obers, Rodriguez.
- For simplicity, we consider vacuum solutions:

$$R_{\mu\nu} = 0$$



# Review of known results

## Emparan, Reall; Harmark

- Look at solutions which are asymptotically  $\mathbb{R}^{4,1}$ .  
The rotation group  $SO(4)$  has 2 commuting generators  
 $\implies$  2 axial symmetries:  $\frac{\partial}{\partial\phi}, \frac{\partial}{\partial\psi}$ .  
We assume that these symmetries are preserved by the full geometry.  
It has been shown (Hollands, Ishibashi, Wald) that b.h. in 5D need only 1 axial symmetry, but no solution with only 1 axial symmetry is known.
- Look at stationary solutions  $\implies \frac{\partial}{\partial t}$  is Killing.
- In total, 3 commuting Killing vectors:  $\frac{\partial}{\partial y^I} = \left\{ \frac{\partial}{\partial t}, \frac{\partial}{\partial\phi}, \frac{\partial}{\partial\psi} \right\}$ ,  $I=0,1,2$ .
- The 2D subspaces orthogonal to  $\frac{\partial}{\partial y^I}$  are integrable (Wald; Emparan, Reall)

$$\implies ds^2 = G_{IJ}(x^a) dy^I dy^J + g_{ab}(x^a) dx^a dx^b, \quad a,b=1,2$$

- Pick canonical coordinates on the 2D submanifolds.

Define  $r^2 = -\det G_{IJ}$ ,

there exists  $z$  s.t.  $g_{ab}dx^a dx^b = e^{2\nu(r,z)}(dr^2 + \Lambda(r,z)dz^2)$

$G^{IJ}R_{IJ} = 0 \implies \partial_r \Lambda = 0 \implies \Lambda = \Lambda(z) \implies \Lambda = 1$

by a redefinition of  $z$ .

Canonical form of the metric

$$ds^2 = G_{IJ}dy^I dy^J + e^{2\nu}(dr^2 + dz^2), \quad \det G_{IJ} = -r^2$$

- Define  $U = r\partial_r GG^{-1}$ ,  $V = r\partial_z GG^{-1}$

Equations of Motion

$$\partial_r U + \partial_z V = 0 \quad (1)$$

$$\partial_r \nu = -\frac{1}{2r} + \frac{1}{8r} \text{tr}(U^2 - V^2), \quad \partial_z \nu = \frac{1}{4r} \text{tr}(UV) \quad (2)$$

## Static solutions (Emparan, Reall)

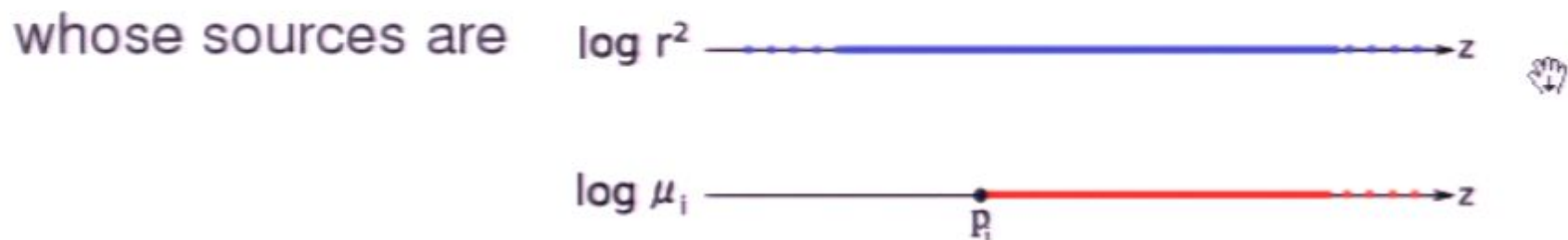
- Eq. (1) simplifies if  $G_{IJ}$  is diagonal:

$$G_{IJ} = G_I \delta_{IJ} \implies \square \log G_I = 0, \quad I=0,1,2$$

where  $\square = \partial_r^2 + \partial_z^2 + \frac{\partial_r}{r}$  is the Laplace operator for the metric  $ds_3^2 = dr^2 + dz^2 + r^2 d\phi^2$ , acting on  $\phi$ -independent functions.

- $\log G_I$  is a **harmonic** function on  $\mathbb{R}^3$ , with sources on the  $r = 0$  axis. It is a linear combination of:

$$\log r^2 \text{ and } \log \mu_i \text{ with } \mu_i = \sqrt{r^2 + (z - p_i)^2} - (z - p_i)$$



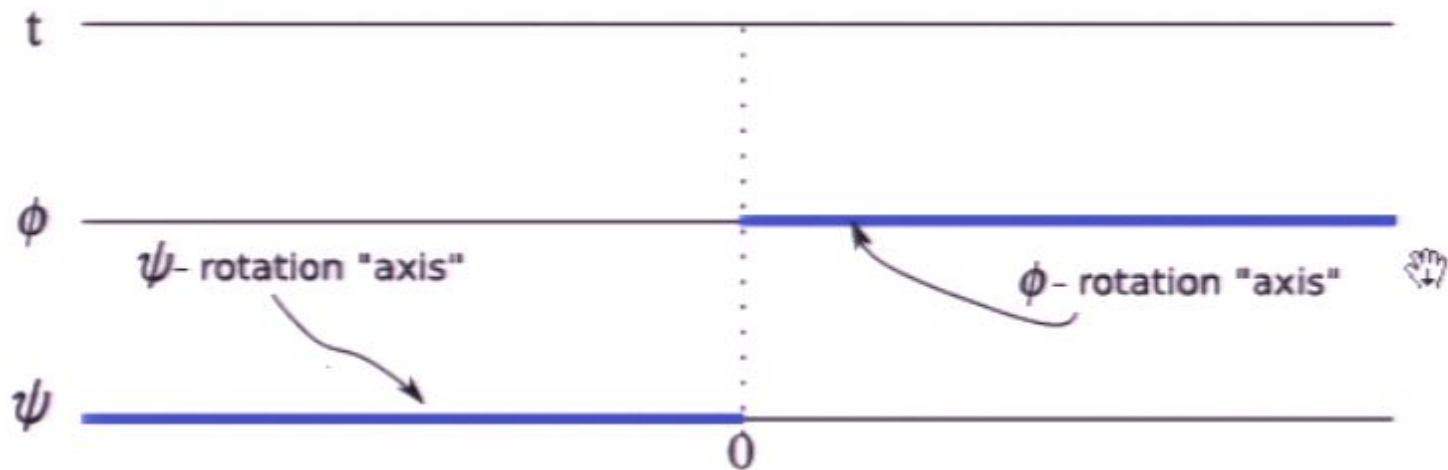
- The condition  $\det G = -r^2$  implies that the sources for  $\log G_I$  ( $I=0,1,2$ ) sum up to 1.



# Examples

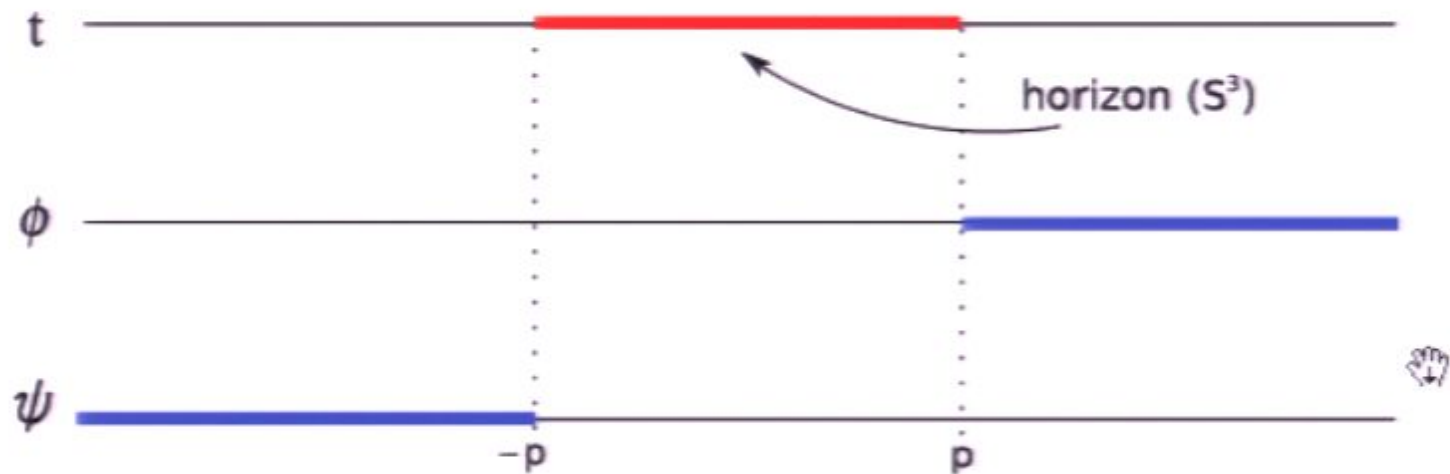
- 5D Minkowski space:

$$\log(-G_0) = 0, \quad \log G_1 = \log \mu_0, \quad \log G_2 = \log \frac{r^2}{\mu_0}$$



- 5D Schwarzschild Black-Hole:

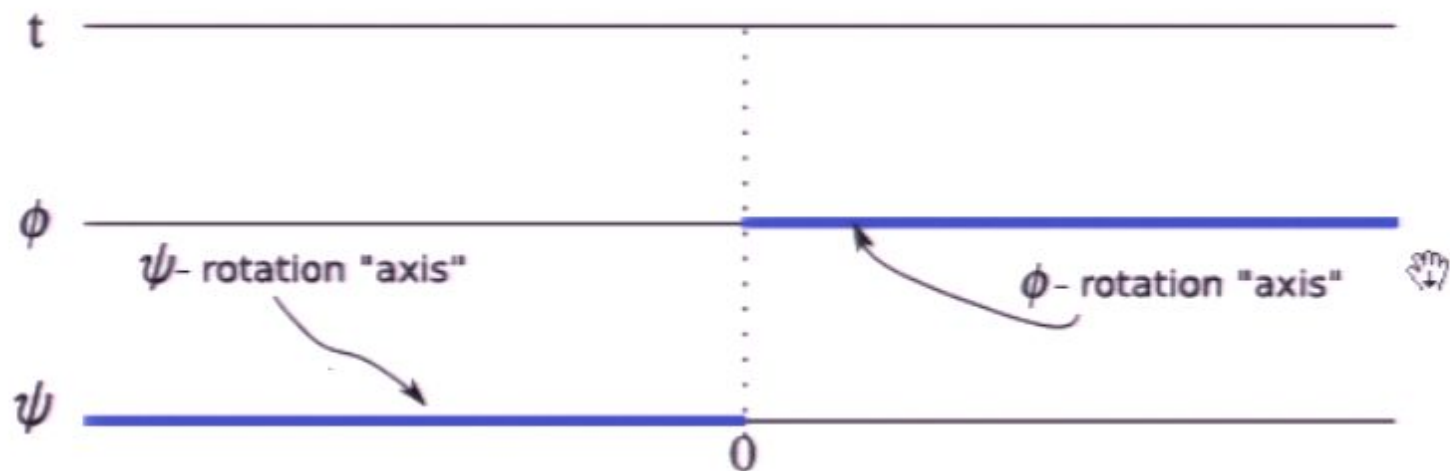
$$\log(-G_0) = \log \frac{\mu_{-p}}{\mu_p}, \quad \log G_1 = \log \mu_p, \quad \log G_2 = \log \frac{r^2}{\mu_{-p}}$$



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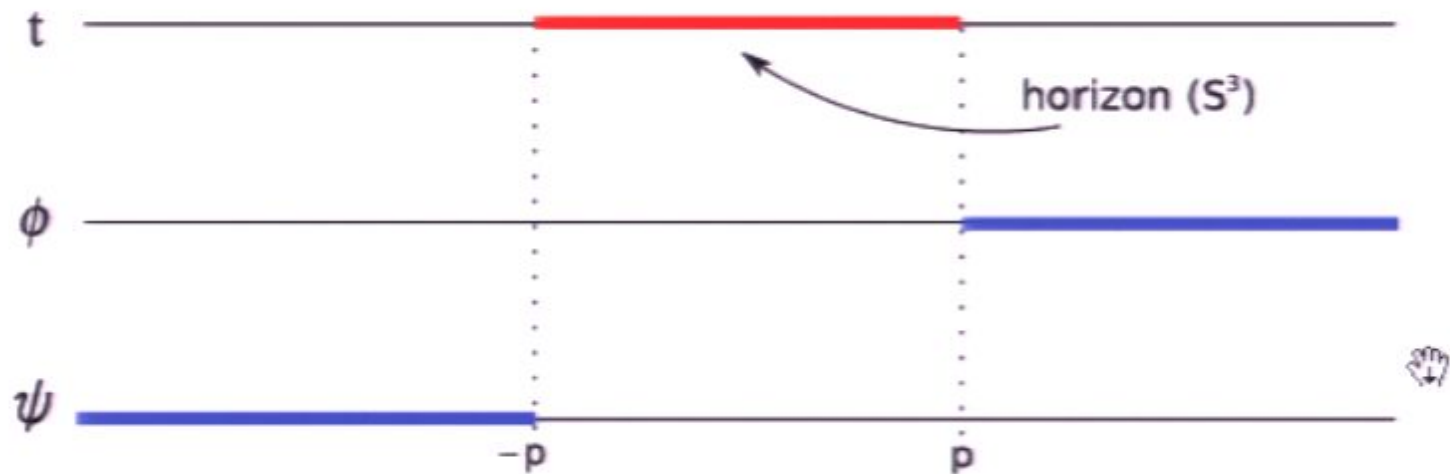
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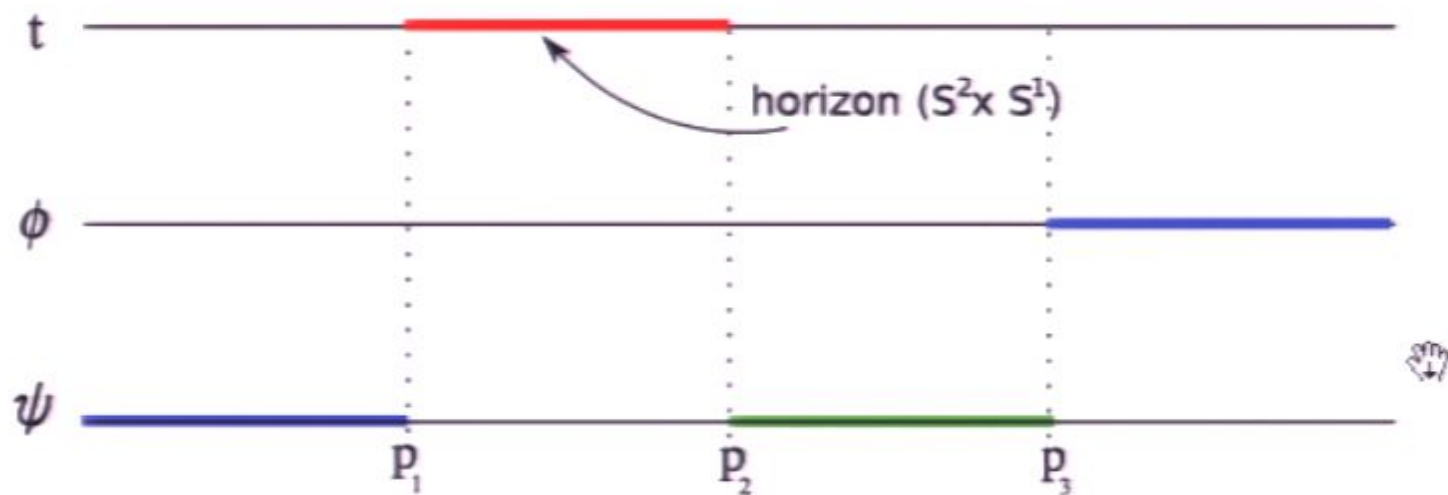
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- Static Black-Ring:

$$\log(-G_0) = \log \frac{\mu_{p_1}}{\mu_{p_2}}, \quad \log G_1 = \log \mu_{p_3}, \quad \log G_2 = \log \frac{r^2}{\mu_{p_1}} + \log \frac{\mu_{p_2}}{\mu_{p_3}}$$



# Stationary Solutions

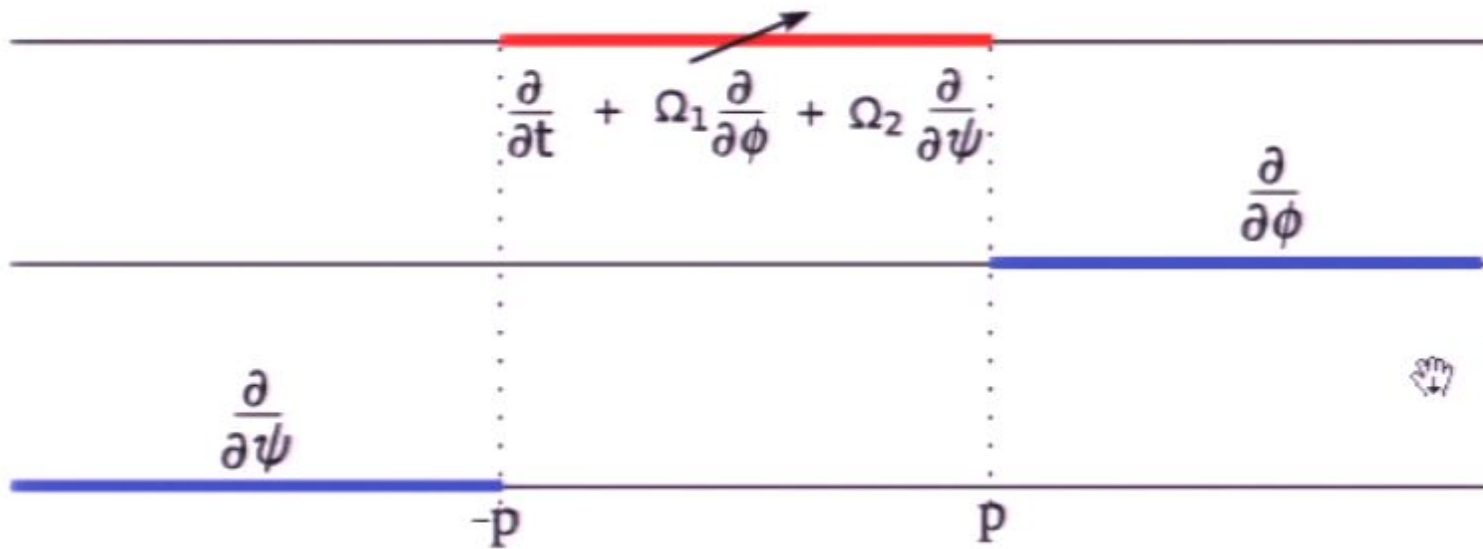
- The concept of **rod structure** can be generalized to non-static solutions (**Harmark**).
- $\det G = -r^2$  implies that on the  $r = 0$  axis  $\ker G \neq \{0\}$ .
- For regular solutions,  $\dim \ker G = 1$  for *generic*  $z$ .
- At isolated points  $z = p_i$ , one can have  $\dim \ker G = 2$ .
- Consider  $r = 0$  and  $p_i < z < p_{i+1}$ . There exists  $v_i$  s.t.  $G v_i = 0$ . It can be shown that  $v_i$  does not depend on  $z$ :

$$v_i = \Omega_i^{(0)} \frac{\partial}{\partial t} + \Omega_i^{(1)} \frac{\partial}{\partial \phi} + \Omega_i^{(2)} \frac{\partial}{\partial \psi} \quad \text{✎}$$

- The rod structure is defined as the collection of data  $\{[p_i, p_{i+1}], v_i\}$ .

# Example

- 5D Myers-Perry Black-Hole:



## Uniqueness Theorem (Hollands, Yazandjiev)

- Two stationary, asymptotically  $\mathbb{R}^{4,1}$ , vacuum solutions with 2 axial symmetries are identical if and only if their rod structures coincide.
- Problem: How to construct the solution with a given rod structure?
- Solve the coupled equations  $\partial_r(r\partial_r GG^{-1}) + \partial_z(r\partial_z GG^{-1}) = 0$ .
- This problem has been shown to be integrable (Belinsky, Zakharov; Pomeransky).
- In principle, the most general solution can be generated by an Inverse Scattering transformation.
- In practice, most solutions generated by IS have pathologies (singularities at the rod intersections).
- We propose a different solution, based on the  $SL(3, \mathbb{R})$  invariance of 5D GR.



## SL(3,ℝ) invariance (Maison)

- Consider a stationary solution in 5D, with a space-like Killing vector  $\frac{\partial}{\partial \xi^1}$  (and  $\xi^0 \equiv t$ ):

$$ds^2 = \lambda_{ab}(d\xi^a + \omega^a)(d\xi^b + \omega^b) + \frac{1}{\tau} ds_3^2, \quad \tau = -\det \lambda_{ab} \quad (a,b=1,2)$$

- The 1-forms on 3D space,  $\omega^a$ , can be dualized to scalars,  $V_a$ :

$$dV_a = -\tau \lambda_{ab} *_3 d\omega^b$$

- The scalars can be organized into a  $3 \times 3$  uni-modular symmetric matrix  $\chi$ :

$$\chi = \begin{pmatrix} \lambda_{ab} - \frac{V_a V_b}{\tau} & \frac{V_a}{\tau} \\ \frac{V_b}{\tau} & -\frac{1}{\tau} \end{pmatrix}$$

## Equations of Motion

$$d *_3 (\chi^{-1} d\chi) = 0, \quad R_{ij}^{(3)} = \frac{1}{4} \text{tr}(\chi^{-1} \partial_i \chi \chi^{-1} \partial_j \chi)$$

- The equations of motion are invariant under

$$\chi \rightarrow \chi' = N\chi N^T, \quad ds_3^2 \rightarrow ds_3^2 \quad \text{with} \quad N \in \text{SL}(3, \mathbb{R})$$

- What is the physical significance of the transformation  $N$ ?
- In general  $N$  changes the behavior at infinity. Need to identify the subgroup that preserves the asymptotic structure.

# $\mathbb{R}^{3,1} \times S^1$ asymptotics (Rasheed; Larsen)

- $ds^2 \approx -dt^2 + dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2) + d(x^5)^2$

- $\xi^1 \equiv x^5 \implies \chi \approx \eta_4 \equiv \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

- $N$  preserves the boundary conditions if

$$N\eta_4N^T = \eta_4 \Leftrightarrow N \in \text{SO}(2, 1)$$



SO(2,1) is generated by

$$\bullet N_\alpha = \begin{pmatrix} \cosh \alpha & \sinh \alpha & 0 \\ \sinh \alpha & \cosh \alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \implies \text{KK-momentum charge}$$

$$\bullet N_\beta = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cosh \beta & \sinh \beta \\ 0 & \sinh \beta & \cosh \beta \end{pmatrix} \implies \text{KK-monopole charge}$$

$$\bullet N_\gamma = \begin{pmatrix} \cos \gamma & 0 & -\sin \gamma \\ 0 & 1 & 0 \\ \sin \gamma & 0 & \cos \gamma \end{pmatrix} \implies \text{NUT-charge}$$





$\mathbb{R}^{4,1}$  asymptotics (S.G., Saxena)

- $ds^2 \approx -dt^2 + dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2 + \cos^2 \theta d\psi^2)$
- $\xi^1$  could be any linear combination of  $\phi$  and  $\psi$ . However, to have a non-trivial subgroup of  $SL(3, \mathbb{R})$  that preserves the asymptotic limit, one should take

$$\xi^1 = \ell(\psi + \phi) \quad \text{or} \quad \xi^1 = \ell(\psi - \phi)$$

- Let us make the first choice; we find

$$\chi \approx \eta_5 \equiv \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

- $\eta_5$  is related to  $\eta_4$  by an  $SL(3, \mathbb{R})$  transformation  $D$ :

$$\eta_5 = D^T \eta_4 D \quad \text{with} \quad D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

- The subgroup of  $SL(3, \mathbb{R})$  that preserves the asymptotic form of  $\chi$  is again isomorphic to  $SO(2, 1)$ :

$$M\eta_5 M^T = \eta_5 \Leftrightarrow M = D^T N D \text{ with } N \in SO(2, 1)$$

- A more careful analysis shows that  $\chi \approx \eta_5$  is sufficient to guarantee that the geometry is asymptotically  $\mathbb{R}^{4,1}$ .  
In particular, no terms of the form  $\cos 2\theta dt(d\psi - d\phi)$  are generated.
- In summary, the transformation

$$(\chi, ds_3^2) \xrightarrow{M} (\chi', ds_3^2)$$



connects 5D asymptotically flat solutions of pure gravity.


## A technical remark

- To construct the metric from the data  $(\chi', ds_3^2)$ , one needs to solve the duality equations for  $\omega'^a$ . In most cases, this can be computationally impractical.
- The e.o.m.  $d *_3 (\chi^{-1} d\chi) = 0$  allows one to define the matrix of 1-forms  $\kappa$ :

$$\chi^{-1} d\chi = *_3 d\kappa$$

- $\kappa$  encodes the information on the gauge fields  $\omega^a$ :

$$\omega^0 = -\kappa^0{}_2, \quad \omega^1 = -\kappa^1{}_2$$

- $\kappa$  transforms linearly under  $SL(3, \mathbb{R})$ : 

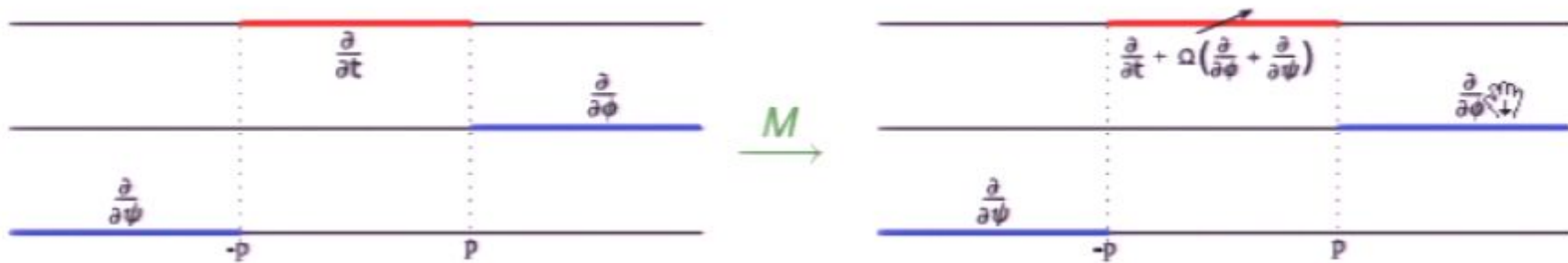
$$\kappa \rightarrow \kappa' = (M^T)^{-1} \kappa M^T$$

- No need to solve any differential equation, after the transformation



# Physical meaning of $M$

- Naively  $M$  has 3 parameters. However ...
- $M_\beta \equiv D^T N_\beta D \implies t \rightarrow t, \xi^1 \rightarrow e^{-\beta} \xi^1, x^i \rightarrow e^\beta x^i.$
- $M_s \equiv D^T N_{\beta(s)} N_{\alpha(s)} N_{\gamma(s)} D \implies t \rightarrow t + s \xi^1, \xi^1 \rightarrow \xi^1, x^i \rightarrow x^i.$
- Out of the 3 parameters of  $SO(2,1)$ , only 1 parameter is physical. Loosely speaking, it corresponds to add angular momentum along  $\psi + \phi$ .
- Example: action of  $M$  on 5D Schwarzschild b.h.



The result is the Myers-Perry b.h. with  $\Omega_1 = \Omega_2 = \Omega$ .

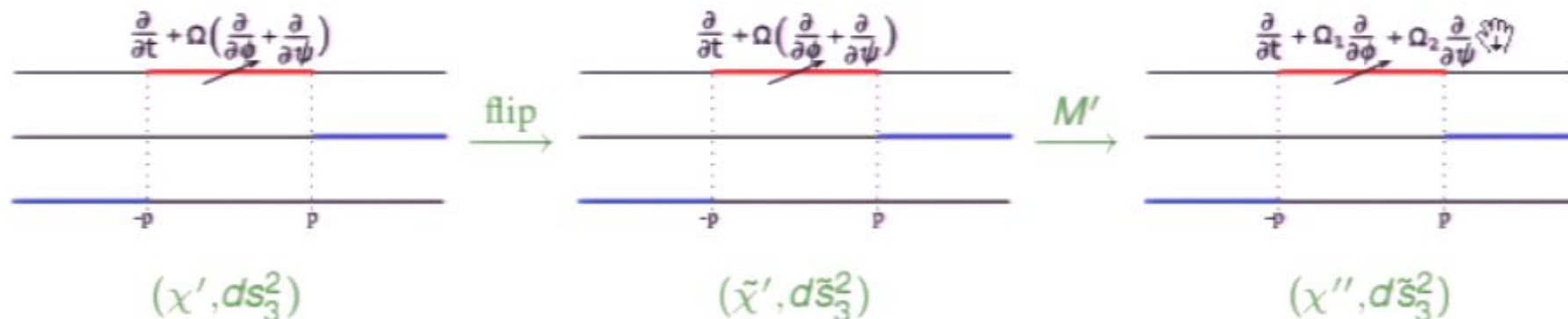


# The “flip”


- Can one generate the full MP solution ( $\Omega_1 \neq \Omega_2$ )?
- Till now, we have used only 1 axial symmetry  $\xi^1 = l(\psi + \phi)$ . We have another Killing vector, corresponding to  $\tilde{\xi}^1 = \tilde{l}(\psi - \phi)$ .
- Given the data  $(\chi, ds_3^2)$ , we can generate the data  $(\tilde{\chi}, d\tilde{s}_3^2)$ , corresponding to the *same* metric, by decomposing the metric with respect to  $\tilde{\xi}^1$ :

$$(\chi, ds_3^2) \xrightarrow{\text{flip}} (\tilde{\chi}, d\tilde{s}_3^2)$$

- Example: MP



# General conjecture

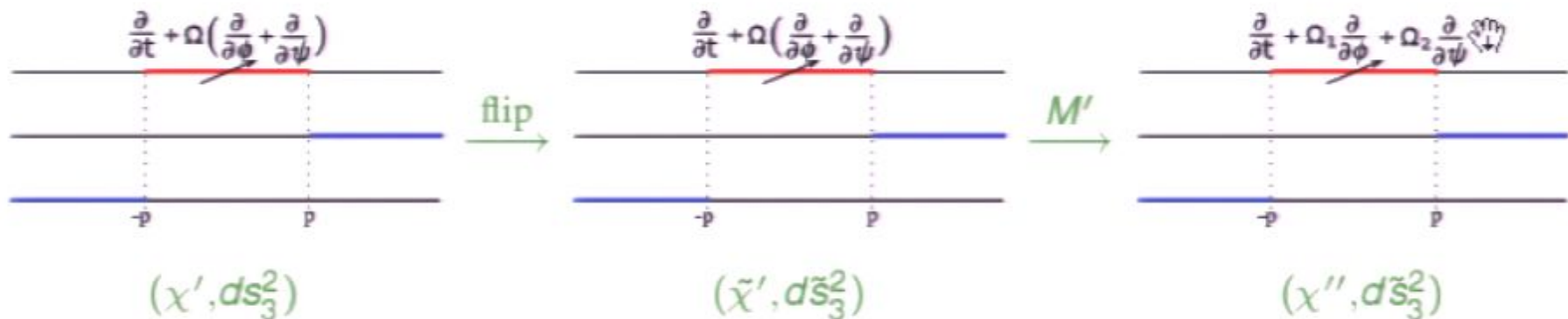
- In general we can prove that:  
If we start from a static 5D solution with  $N$  finite rods and act with  $M$ , we obtain a 5D stationary solution with **the same number of rods and the same rod positions**. **The eigenvectors** corresponding to the finite rods (both time-like and space-like) **are rotated**, by an amount that depends on  $M$  and the starting rod configuration.
- One can further act with a sequence of flips and  $M$ -transformations.
- **Conjecture: after  $2N$  steps, one generates the most general solution with  $N$  finite rods.** 
- The “flip” operation requires re-diagonalizing the metric and solving the new duality equations.  
This is computationally impractical, in most cases.

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## The 4D-5D connection (Ford, S.G., Peet, Saxena)

- The problem: Start from an asymptotically  $\mathbb{R}^{4,1}$  geometry. Construct a solution representing the 5D geometry at the center of a KK-monopole geometry.
- The resulting geometry is locally asymptotic to  $\mathbb{R}^{3,1} \times S^1$  (4D).
- It interpolates between a 4D ( $R_K \rightarrow 0$ ) and a 5D ( $R_K \rightarrow \infty$ ) geometry ( $R_K$  is the KK-monopole radius).
- Such geometries are at the basis of a remarkable connection between 4D and 5D partition functions, in cases in which the partition function is independent of  $R_K$  (extremal solutions).  
(Gaiotto, Strominger, Yin) 
- In the susy case, there is a systematic way to solve this problem. Add constants to harmonic functions.
- No general solution is known in the non-susy case.



- For axisymmetric vacuum solutions, the  $SL(3, \mathbb{R})$  transformation  $D$  provides a solution to the problem!
- We have seen that

$$\chi_{5D} \rightarrow \eta_5, \quad \chi_{4D} \rightarrow \eta_4, \quad \eta_4 = D\eta_5 D^T$$

- Then

$$\chi_{4D} = D\chi_{5D}D^T$$

gives a metric that interpolates between 4D and 5D.



# Examples

- $\mathbb{R}^{4,1} \xrightarrow{D}$  Gross-Perry monopole

$$ds_{5D}^2 = -dt^2 + V^{-1}(d\xi^1 + \ell \cos \theta d\phi)^2 + V^{-1} ds_3^2, \quad V = \frac{\ell}{r}$$

$$\chi_{5D} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & -V \end{pmatrix} \xrightarrow{D} \chi_{4D} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 - \frac{V}{2} & -\frac{V}{2} \\ 0 & -\frac{V}{2} & -(1 + \frac{V}{2}) \end{pmatrix}$$

$$ds_{4D}^2 = -dt^2 + \tilde{V}^{-1}(d\xi^1 + \frac{\ell}{2} \cos \theta d\phi)^2 + \tilde{V}^{-1} ds_3^2, \quad \tilde{V} = 1 + \frac{\ell}{2r}$$

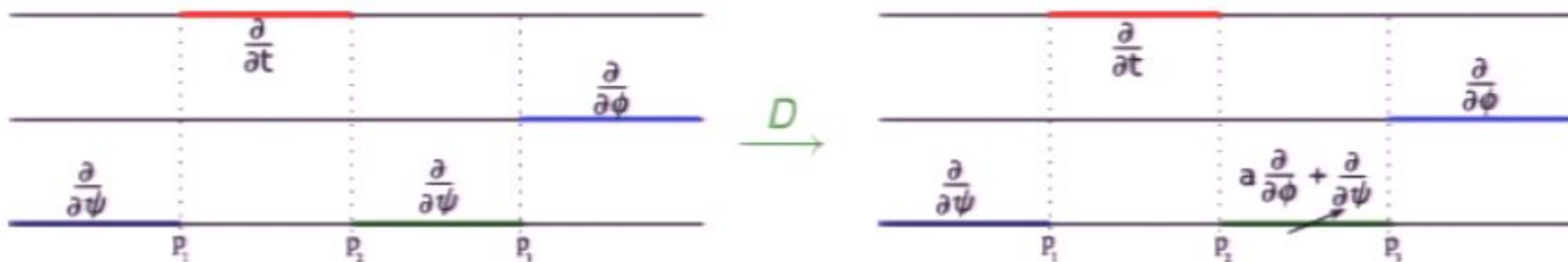
- The rod structures of  $ds_{5D}^2$  and  $ds_{4D}^2$  are identical (up to a change of coordinates).

- MP black hole  $\xrightarrow{D}$  Rasheed-Larsen geometry
- The Rasheed-Larsen geometry is a solution of KK gravity carrying KK-monopole charge, KK-momentum charge, and 4D angular momentum.
- It was first obtained by Rasheed, by applying an  $SO(2,1)$  transformation to  $Kerr \times S^1$ .
- It has the property that for  $R_K$  much greater than all other scales of the geometry it goes over to the 5D MP black hole.
- Our construction makes this last property obvious.



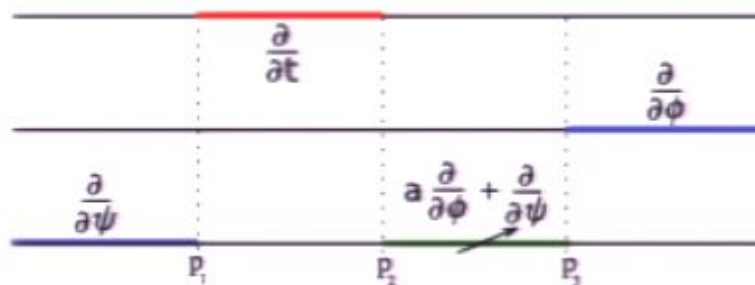
# BR in Taub-NUT

- Construct a Black Ring in Taub-NUT:




**Problem:** the final solution is not a Black Ring!

- Solution: Start from a 5D geometry with rod structure



and tune  $a$  in such a way that the finite space-like rod points along  $\frac{\partial}{\partial \psi}$  after the  $D$  action.

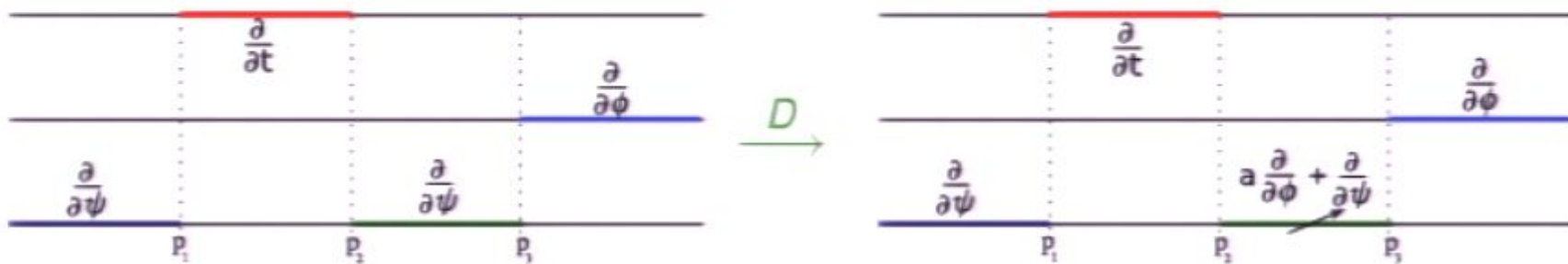


- The 5D geometry with this rod structure could be generated by a sequence of  $SL(3, \mathbb{R})$  transformations. In this case we found it more practical to use Inverse Scattering techniques.
- Technical remark: we have derived identities that allow to one compute  $\chi$  and  $\kappa$  for any solution generated by IS and reduce the problem to purely algebraic manipulations.
- As a result of this construction, we generate a new solution, representing a **static Black Ring in Taub-NUT**.
- This solution suffers from the same conical defect singularities as the static Black Ring in flat space.
- The regular solution representing a rotating Black Ring in  Taub-NUT can be generated in an analogous way (work in progress with **Camps, Emparan, Figueras, Saxena**).



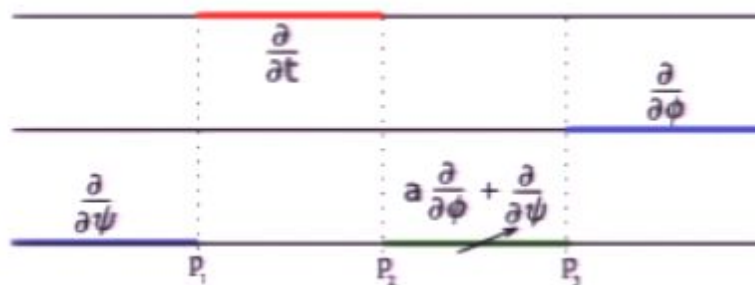
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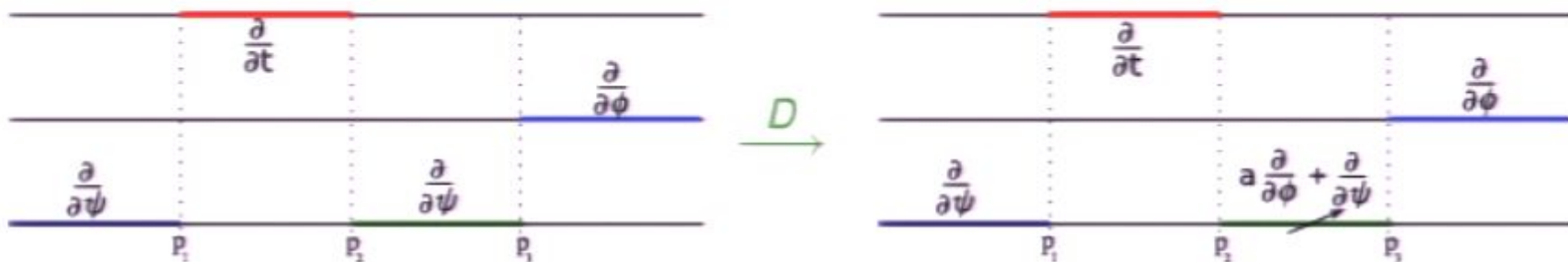


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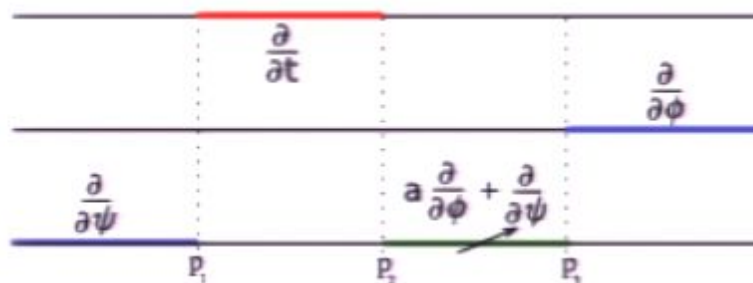
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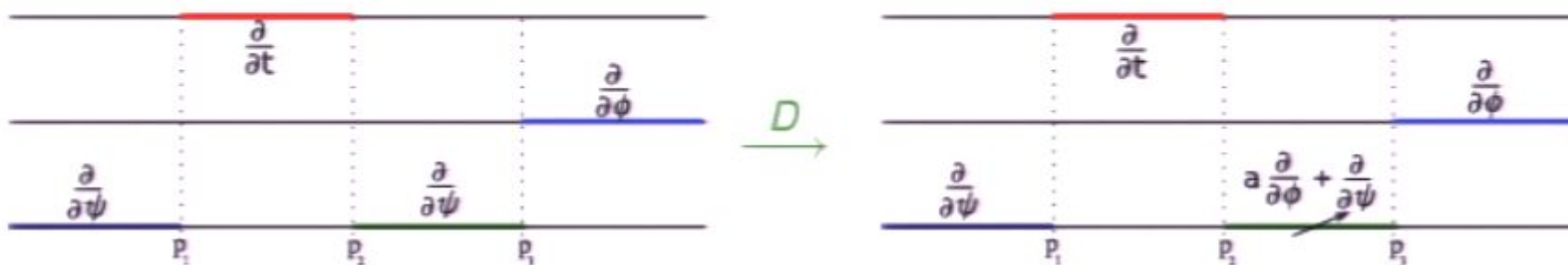
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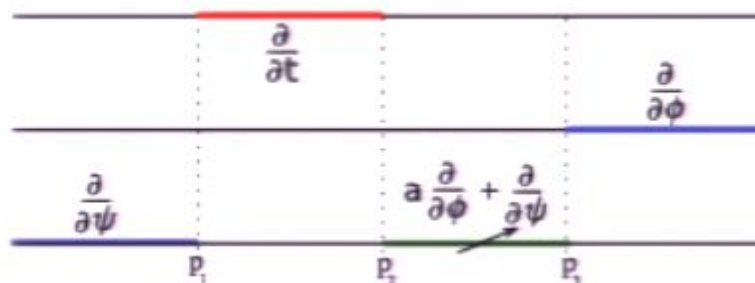
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and tune  $a$  in such a way that the finite space-like rod points along  $\frac{\partial}{\partial \psi}$  after the  $D$  action.



- The 5D geometry with this rod structure could be generated by a sequence of  $SL(3, \mathbb{R})$  transformations. In this case we found it more practical to use Inverse Scattering techniques.
- Technical remark: we have derived identities that allow to one compute  $\chi$  and  $\kappa$  for any solution generated by IS and reduce the problem to purely algebraic manipulations.
- As a result of this construction, we generate a new solution, representing a **static Black Ring in Taub-NUT**.
- This solution suffers from the same conical defect singularities as the static Black Ring in flat space.
- The regular solution representing a rotating Black Ring in  Taub-NUT can be generated in an analogous way (work in progress with **Camps, Emparan, Figueras, Saxena**).

## 4D non-susy microstates S.G., Ross, Saxena

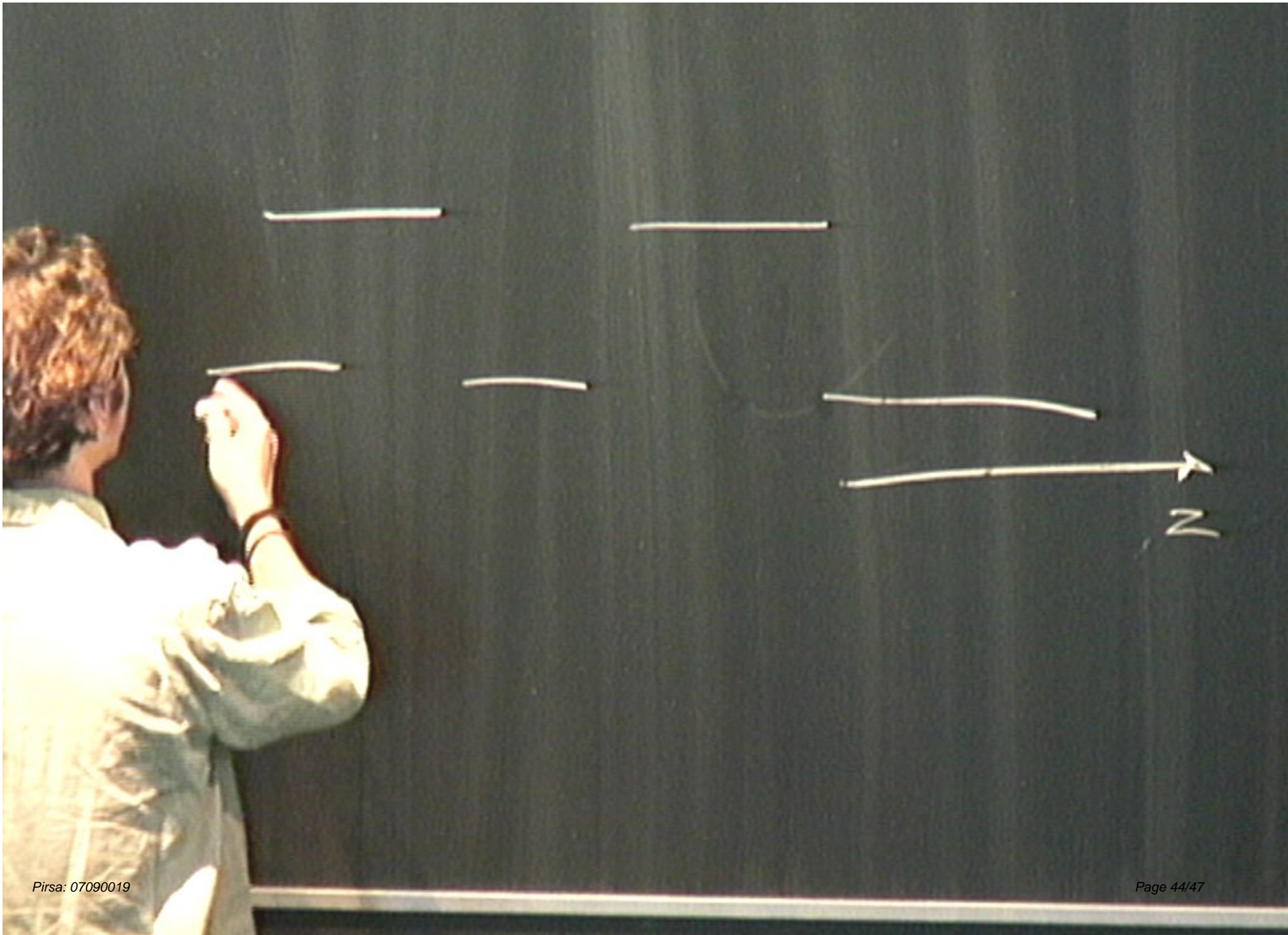
- Jejjala, Madden, Ross, Titchener have constructed regular, horizon-less geometries dual to some non-BPS microstates of the 5D black hole with D1-D5-P charges.
- The corresponding CFT states carry both left and right moving excitations.
- The geometries can be constructed by applying a chain of dualities to a certain vacuum “seed” solution (5D MP).
- By applying  $D$  to the vacuum seed, and applying the same chain of dualities, we have constructed new non-BPS geometries dual to microstates of the 4D black hole with D1-D5-P-KK charges.

# Summary

- We have presented a method to generate stationary axisymmetric solutions of 5D gravity.
- The method is based on the  $SL(3, \mathbb{R})$  invariance of the system.
- It is conjectured that the method generates all the 5D asymptotically flat solutions in this class.
- We have identified an  $SL(3, \mathbb{R})$  transformation  $D$  that connects 5D and 4D solutions of pure gravity.
- We have applied the  $D$  transformation to generate a new Black Ring in Taub-NUT.

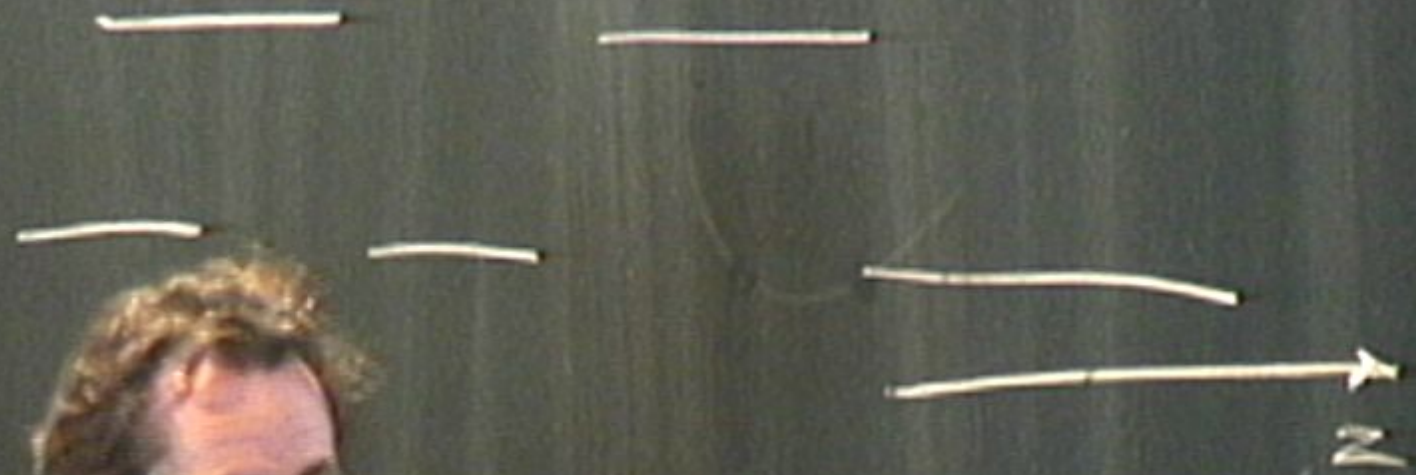








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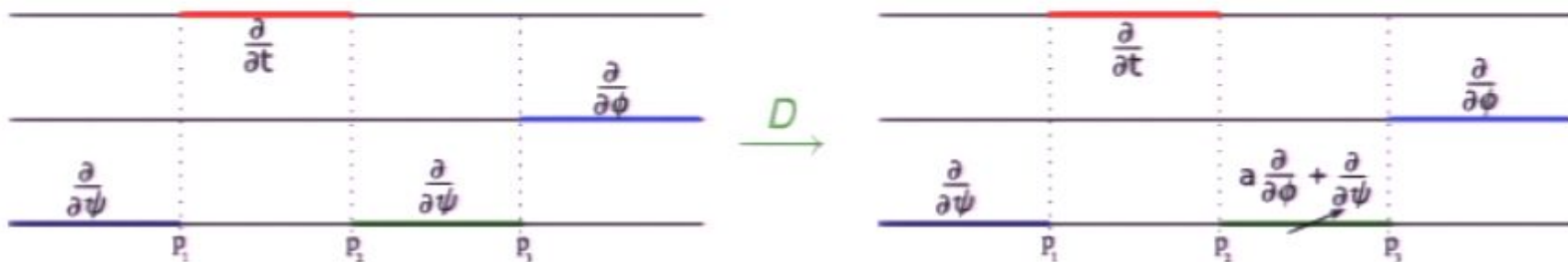


## 4D non-susy microstates S.G., Ross, Saxena

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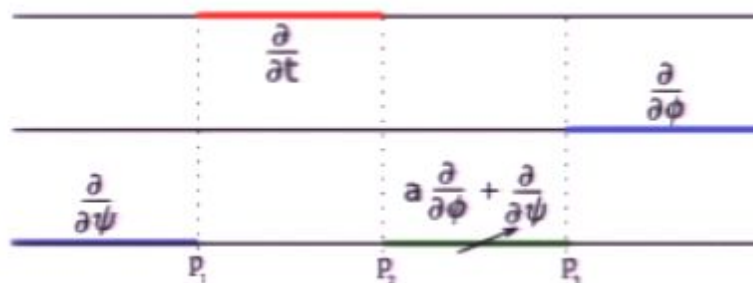
# BR in Taub-NUT

- Construct a Black Ring in Taub-NUT:



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