

Title: Volume Operator and Recoupling Theory

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Abstract:

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Recoupling Theory and the Volume Operator in Loop Quantum Gravity

Max Planck Institut
für Gravitationsphysik,
Golm near Potsdam, Germany



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Quantum Gravity in the Americas Workshop,

work in progress

T. Thiemann, D. Rideout

Waterloo 29/10/2004

Outline of this Talk

- Motivation
- LQG - Basics
 - ▶ Recoupling Schemes
- Volume Operator
 - ▶ Definition
 - ▶ Simplification of the Matrix Element Expression
- Applications (work in progress)
 - ▶ Numerical Studies
 - ▶ Triad Operators in LQG
 - Bounded or Unbounded? $\leftarrow$ Comparison to LQC
 - Coherent States
- Conclusions & Outlook

Motivation

$\hat{V}$ is crucial for various Parts of LQG

- Trick: Can treat negative powers of $\det q$ by rewriting as Poisson bracket...

$$H_E = \frac{1}{\kappa \sqrt{\det q}} \left[F_{ab}^j \epsilon_{jkl} E_k^a E_l^b \right] \quad F_{ab}^j = 2\partial_{[a} A_{b]}^j + \epsilon_{jkl} A_a^k A_b^l$$

► Identities: $\frac{\epsilon_{jkl} E_k^a E_l^b}{\kappa \sqrt{\det q}} = \text{sgn}(\det(e)) \epsilon^{abc} e_c^j$

$$e_c^j \propto \{A_c^j, V\} \propto \text{Tr} \left[\tau_j h_c \{h_c^{-1}, V\} \right]$$

where $V(R) = \int_R d^3x \sqrt{|\det q|}$

- (Spatial) Diffeomorphism Invariant (Complexifier) Coherent States

$$\begin{aligned} \Psi_{e \in E(\gamma)} &:= \left[\mathfrak{e}^{\frac{1}{\hbar} \hat{C}} \delta_{h_e} \right]_{G \ni h_e \rightarrow h_e^{\mathfrak{C}} \in G^{\mathfrak{C}}} \\ &= \sum_s \mathfrak{e}^{-t\lambda(s)} T_s(h_e^{\mathfrak{C}}) \langle T_s, \cdot \rangle_G \end{aligned}$$

LQG - Basics I

■ Classical Poisson Structure of ART

$$\left\{ A_a^i(x), E_j^b(y) \right\} = \kappa \delta_j^i \delta_a^b \delta^{(3)}(x, y) \longrightarrow \begin{array}{ll} \text{Electric Fields} & E_j(S) = \int_S *E_j \\ \text{Holonomies} & h_e = \mathcal{P} \exp \int_e A \end{array}$$

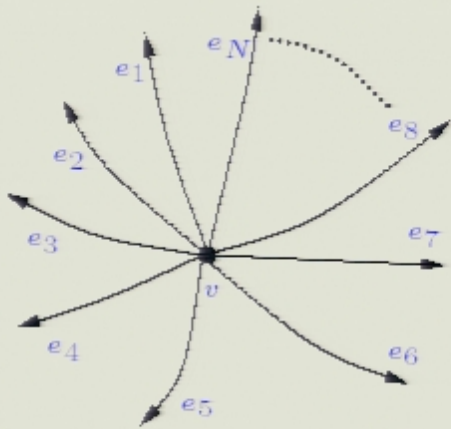
$$\begin{array}{llll} \text{■ Cylindrical Functions} & f_\gamma = f_\gamma[\{h_e\}_{e \in E(\gamma)}] & \mathcal{H} = L_2(f_\gamma, d\mu_\gamma) & \begin{array}{ll} \hat{E}_j(S) & \longleftrightarrow X_j \\ \hat{h}_e & \longleftrightarrow h_e \end{array} \end{array}$$

$$\text{■ Basis of } \mathcal{H} \text{ (Peter \& Weyl):} \quad \sqrt{2j+1} [\pi_j(h_e)]_{mn} =: \langle h_e \mid j \ m ; \ n \rangle \quad \text{--- SNF}$$

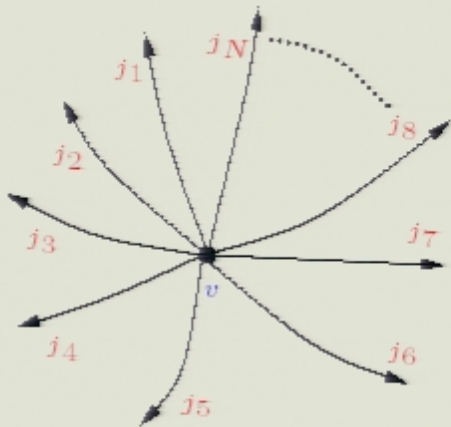
$$\blacktriangleright \text{Can replace} \quad -\frac{i}{2} X_j \mid j \ m ; \ n \rangle = J_j \mid j \ m ; \ n \rangle$$

Action of operators only containing X_j can be expressed as action of usual angular momentum operators acting on a spin system!

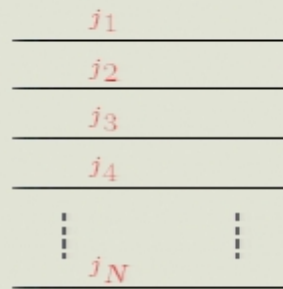
LQG - Basics II



LQG - Basics II

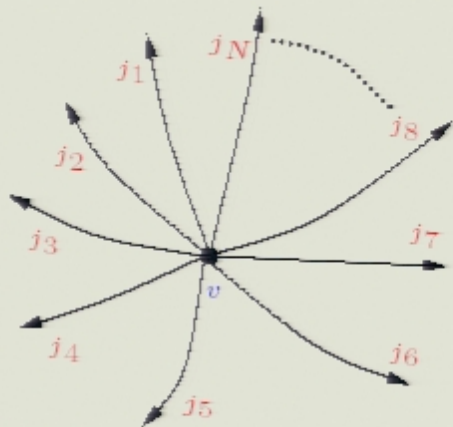


- Tensor Basis

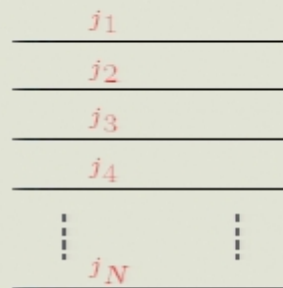


$$T_v = |j_1 m_1; n_1\rangle \otimes \dots \otimes |j_N m_N; n_N\rangle$$

LQG - Basics II



• Tensor Basis

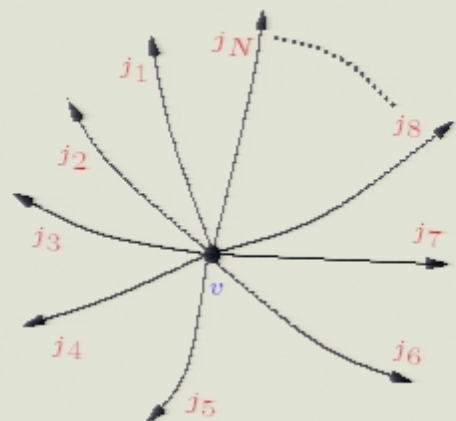


$$T_v = |j_1 m_1; n_1 \rangle \otimes \dots \otimes |j_N m_N; n_N \rangle$$

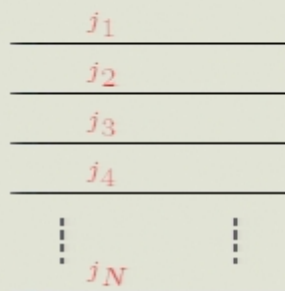
■ Decomposition

$$\pi_{j_1} \otimes \pi_{j_2} = \bigoplus_{j_{12}=|j_1-j_2|}^{j_1+j_2} \pi_{j_{12}}$$

LQG - Basics III: Recoupling Basis 1



• Tensor Basis

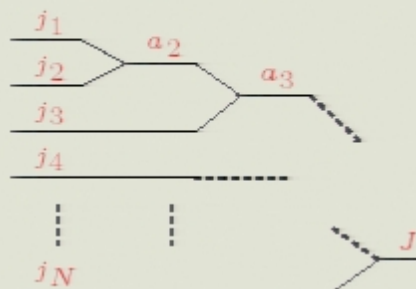


$$T_v = | j_1 m_1 ; n_1 > \otimes \dots \otimes | j_N m_N ; n_N >$$

■ Decomposition

$$\pi_{j_1} \otimes \pi_{j_2} = \bigoplus_{j_{12}=|j_1-j_2|}^{j_1+j_2} \pi_{j_{12}}$$

• Recoupling Basis



$$T_v = | a_2 a_3 \dots a_{N-1} J M ; \vec{j} \vec{n} >$$

LQG - Basics III: Recoupling Basis 2

- $T_v = | a_2(j_1 j_2) a_3(a_2 j_3) \dots a_{N-1}(a_{N-2} j_{N-1}) J(a_{N-1} j_N) M; \vec{j} \vec{n} \rangle$

diagonalizes

$$J_1, A_2 = J_1 + J_2, A_3 = A_2 + J_3, \dots, J = J_1 + \dots + J_2$$

The order of recoupling matters!

- $T'_v = | g_2(j_I j_J) g_3(g_2 j_1) \dots g_{I+2}(g_{I+1}, j_{I+1}) \dots g_{J+1}(g_J, j_{J+1}) \dots J(g_{N-1} j_N) M; \vec{j} \vec{n} \rangle$

diagonalizes

$$J_I, G_2 = J_I + J_J, G_3 = G_2 + J_1, \dots, J = J_1 + \dots + J_2$$

- Trafo between the different Bases: $3nj$ -Symbols

$$| \vec{g}(IJ) J M; \vec{n} \rangle = \sum_{\vec{a}(12)} \langle \vec{a}(12) J M; \vec{n} | \vec{g}(IJ) J M; \vec{n} \rangle | \vec{a}(12) J M; \vec{n} \rangle$$



LQG - Basics III: $3nj$ -Symbols in Terms of $6j$ -Symbols

$$\begin{aligned}
 & \langle \vec{g}(IJ) | \vec{g}'(12) \rangle = \\
 & = \sum_{h_2(j_I, j_1)} \langle g_2(j_I, j_J), g_3(g_2, j_1) | h_2(j_I, j_1), g_3(h_2, j_J) \rangle \\
 & \times \sum_{h_3(h_2, j_2)} \langle g_3(h_2, j_J), g_4(g_3, j_2) | h_3(h_2, j_2), g_4(h_3, j_J) \rangle \\
 & \vdots \\
 & \times \sum_{h_{I-1}(h_{I-2}, j_{I-2})} \langle g_{I-1}(h_{I-2}, j_J), g_I(g_{I-1}, j_{I-2}) | h_{I-1}(h_{I-2}, j_{I-2}), g_I(h_{I-1}, j_J) \rangle \\
 & \times \langle g_I(h_{I-1}, j_J), g_{I+1}(g_I, j_{I-1}) | g'_I(h_{I-1}, j_{I-1}), g_{I+1}(g'_I, j_J) \rangle \\
 & \times \langle g_{I+1}(g'_I, j_J), g_{I+2}(g_{I+1}, j_{I+1}) | g'_{I+1}(g'_I, j_{I+1}), g_{I+2}(g'_{I+1}, j_J) \rangle \\
 & \times \langle g_{I+2}(g'_{I+1}, j_J), g_{I+3}(g_{I+2}, j_{I+2}) | g'_{I+2}(g'_{I+1}, j_{I+2}), g_{I+3}(g'_{I+2}, j_J) \rangle \\
 & \vdots \\
 & \times \langle g_{J-1}(g'_{J-2}, j_J), g_J(g_{J-1}, j_{J-1}) | g'_{J-1}(g'_{J-2}, j_{J-1}), g_J(g'_{J-1}, j_J) \rangle \\
 & \times \langle h_2(j_I, j_1), h_3(h_2, j_2) | g'_2(j_1, j_2), h_3(g'_2, j_I) \rangle \\
 & \times \langle h_3(g'_2, j_I), h_4(h_3, j_3) | g'_3(g'_2, j_3), h_4(g'_3, j_I) \rangle \\
 & \times \langle h_4(g'_3, j_I), h_5(h_4, j_4) | g'_4(g'_3, j_4), h_5(g'_4, j_I) \rangle \\
 & \vdots \\
 & \times \langle h_{I-1}(g'_{I-2}, j_I), g'_I(h_{I-1}, j_{I-1}) | g'_{I-1}(g'_{I-2}, j_{I-1}), g'_I(g'_{I-1}, j_I) \rangle
 \end{aligned}$$

LQG - Basics III: $6j$ -Symbols

■ Definition

$$\begin{array}{c} j_1 \\ j_2 \\ j_3 \end{array} \begin{array}{c} \diagup \\ \diagdown \end{array} \begin{array}{c} j_{12} \\ \diagdown \\ \diagup \end{array} \begin{array}{c} \diagdown \\ \diagup \end{array} \begin{array}{c} J \end{array} = \sum_{j_{23}} \left\{ \begin{array}{ccc} j_1 & j_2 & j_{12} \\ j_3 & J & j_{23} \end{array} \right\} \begin{array}{c} j_1 \\ j_2 \\ j_3 \end{array} \begin{array}{c} \diagup \\ \diagdown \end{array} \begin{array}{c} \diagdown \\ \diagup \end{array} \begin{array}{c} j_{23} \\ \diagdown \\ \diagup \end{array} \begin{array}{c} J \end{array}$$

Volume Operator I: Definition

- Classical Volume Expression:

$$\begin{aligned} V(R) &= \int_R d^3x \sqrt{|\det q|} \\ &= \int_R d^3x \sqrt{\left| \frac{1}{3!} \epsilon_{abc} \epsilon^{ijk} E_i^a E_j^b E_k^c \right|} \end{aligned}$$

- According Operator in LQG

$$\hat{V}(R)_\gamma |\vec{a} J M ; \vec{n} \rangle = \sqrt{\left| \frac{i}{4} \sum_{I < J < K} \epsilon(I, J, K) \hat{q}_{IJK} \right|} |\vec{a} J M ; \vec{n} \rangle$$

$$\text{where } \hat{q}_{IJK} := [(J_{IJ})^2, (J_{JK})^2]$$

- Matrix Elements

$$\begin{aligned} \langle \vec{a} | \hat{q}_{IJK} | \vec{a}' \rangle &= \sum_{\vec{g}''(12)} \left[\sum_{\vec{g}(IJ)} g_2(IJ)(g_2(IJ) + 1) \langle \vec{g}(IJ) | \vec{g}'' \rangle \langle \vec{g}(IJ) | \vec{a} \rangle \times \right. \\ &\quad \times \sum_{\vec{g}(JK)} g_2(JK)(g_2(JK) + 1) \langle \vec{g}(JK) | \vec{g}'' \rangle \langle \vec{g}(JK) | \vec{a}' \rangle \left. \right] \\ &\quad - [\vec{a} \Longleftrightarrow \vec{a}'] \end{aligned}$$

Volume Operator II: Simplified Expression for the Matrix Element 1

■ Basic Structure:
$$\sum_{\vec{g}(IJ)} g_2(IJ) (g_2(IJ) + 1) \langle \vec{g}(IJ) | \vec{g}''(12) \rangle \langle \vec{g}(IJ) | \vec{a}(12) \rangle$$

■ Rewrite as 6j-Symbol
$$F(j_{12}, j'_{12}) = \sum_{j_{23}} (2j_{23} + 1) j_{23}(j_{23} + 1) \left\{ \begin{matrix} j_1 & j_2 & j_{12} \\ j_3 & j_4 & j_{23} \end{matrix} \right\} \left\{ \begin{matrix} j_1 & j_2 & j'_{12} \\ j_3 & j_4 & j_{23} \end{matrix} \right\}$$

■ Observation

$$a(a+1) = (-1)^{a+b+c} \left\{ \begin{matrix} a & b & c \\ 1 & c & b \end{matrix} \right\} X(b, c)^{\frac{1}{2}} + [(b+1) + c(c+1)]$$

Elliot Biedenharn Identity

■ Solution

$$\begin{aligned} F(j_{12}, j'_{12}) &:= \sum_{j_{23}} (2j_{23} + 1) j_{23}(j_{23} + 1) \left\{ \begin{matrix} j_1 & j_2 & j_{12} \\ j_3 & j_4 & j_{23} \end{matrix} \right\} \left\{ \begin{matrix} j_1 & j_2 & j'_{12} \\ j_3 & j_4 & j_{23} \end{matrix} \right\} = \\ &= \frac{1}{2} (-1)^{j_1+j_2+j_3+j_4+j_{12}+j'_{12}+1} X(j_1, j_4)^{\frac{1}{2}} \left\{ \begin{matrix} j_2 & j_1 & j_{12} \\ 1 & j'_{12} & j_1 \end{matrix} \right\} \left\{ \begin{matrix} j_3 & j_4 & j_{12} \\ 1 & j'_{12} & j_4 \end{matrix} \right\} \\ &\quad + \frac{j_1(j_1+1) + j_4(j_4+1)}{(2j_{12}+1)} \delta_{j_{12}j'_{12}} \end{aligned}$$

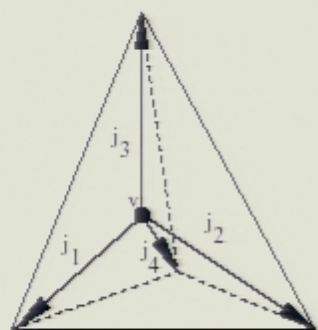
with $X(b, c) = 2b(2b+1)(2b+2)2c(2c+1)(2c+2)$.

Volume Operator II: Simplified Expression for the Matrix Element 2

$$\begin{aligned}
 \langle \vec{a} | \hat{q}_{IJK} | \vec{a}' \rangle &= \\
 &= \frac{1}{4} (-1)^{j_K + j_I + a_{I-1} + a_K} (-1)^{a_I - a'_I} (-1)^{\sum_{n=I+1}^{J-1} j_n} (-1)^{-\sum_{p=J+1}^{K-1} j_p} \times \\
 &\quad \times X(j_I, j_J)^{\frac{1}{2}} X(j_J, j_K)^{\frac{1}{2}} \sqrt{(2a_I + 1)(2a'_I + 1)} \sqrt{(2a_J + 1)(2a'_J + 1)} \times \\
 &\quad \times \left\{ \begin{matrix} a_{I-1} & j_I & a_I \\ 1 & a'_I & j_I \end{matrix} \right\} \left[\prod_{n=I+1}^{J-1} \sqrt{(2a'_n + 1)(2a_n + 1)} (-1)^{a'_{n-1} + a_{n-1} + 1} \left\{ \begin{matrix} j_n & a'_{n-1} & a'_n \\ 1 & a_n & a_{n-1} \end{matrix} \right\} \right] \times \\
 &\quad \times \left[\prod_{n=J+1}^{K-1} \sqrt{(2a'_n + 1)(2a_n + 1)} (-1)^{a'_{n-1} + a_{n-1} + 1} \left\{ \begin{matrix} j_n & a'_{n-1} & a'_n \\ 1 & a_n & a_{n-1} \end{matrix} \right\} \right] \left\{ \begin{matrix} a_K & j_K & a_{K-1} \\ 1 & a'_{K-1} & j_K \end{matrix} \right\} \times \\
 &\quad \times \left[(-1)^{a_J + a'_{J-1}} \left\{ \begin{matrix} a_J & j_J & a'_{J-1} \\ 1 & a_{J-1} & j_J \end{matrix} \right\} \left\{ \begin{matrix} a'_{J-1} & j_J & a'_J \\ 1 & a_J & j_J \end{matrix} \right\} \right. \\
 &\quad \left. - (-1)^{a_J + a_{J-1}} \left\{ \begin{matrix} a'_J & j_J & a'_{J-1} \\ 1 & a_{J-1} & j_J \end{matrix} \right\} \left\{ \begin{matrix} a_{J-1} & j_J & a'_J \\ 1 & a_J & j_J \end{matrix} \right\} \right] \times \\
 &\quad \times \prod_{n=2}^{I-1} \delta_{a_n a'_n} \prod_{n=K}^N \delta_{a_n a'_n}
 \end{aligned}$$

Application I: Numerical Studies 1

■ Gauge Invariant 4-Vertex



► Basis-States

$$T_v = \left| \underbrace{a_2(j_1 \ j_2)}_{j_{12}} \ a_3(a_2 \ j_3) \ J(a_3 \ j_4)=0 \ M=0; \ \vec{n} \right\rangle$$

► Gauge Invariance

$$J_1 + J_2 + J_3 + J_4 \stackrel{!}{=} 0$$

► Only $\hat{q}_{123}$ matters!

$$\langle j_{12} | \hat{q}_{123} | j_{12} - 1 \rangle =$$

$$= \frac{1}{\sqrt{(2j_{12}-1)(2j_{12}+1)}} \left[(j_1 + j_2 + j_{12} + 1)(-j_1 + j_2 + j_{12})(j_1 - j_2 + j_{12})(j_1 + j_2 - j_{12} + 1) \right. \\ \left. (j_3 + j_4 + j_{12} + 1)(-j_3 + j_4 + j_{12})(j_3 - j_4 + j_{12})(j_3 + j_4 - j_{12} + 1) \right]^{\frac{1}{2}}$$

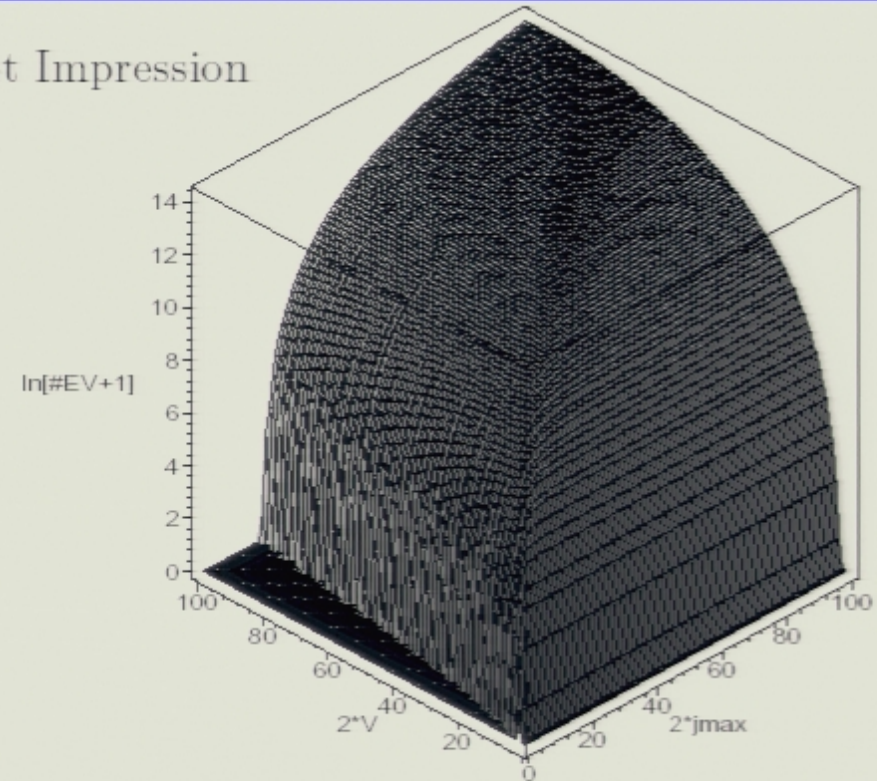
$$= - \langle j_{12} - 1 | \hat{q}_{123} | j_{12} \rangle$$

Application I: Numerical Studies 2

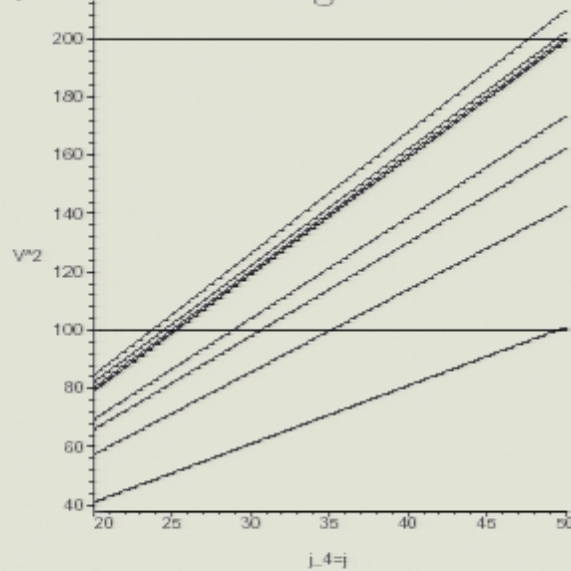
► Matrix Structure

$$A = \begin{pmatrix} 0 & -a_1 & 0 & \dots & \dots & 0 \\ a_1 & 0 & -a_2 & & & \\ 0 & a_2 & 0 & \ddots & & \\ \vdots & & \ddots & \ddots & \ddots & \\ \vdots & & & \ddots & \ddots & -a_{n-1} \\ 0 & \dots & \dots & \dots & a_{n-1} & 0 \end{pmatrix}$$

► First Impression

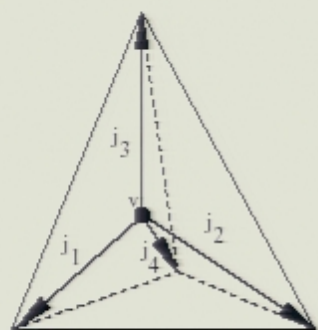


► First Few Eigenvalues



Application I: Numerical Studies 1

■ Gauge Invariant 4-Vertex



► Basis-States

$$T_v = \left| \underbrace{a_2(j_1 j_2)}_{j_{12}} a_3(a_2 j_3) J(a_3 j_4) = 0 \ M = 0; \vec{n} \right\rangle$$

► Gauge Invariance

$$J_1 + J_2 + J_3 + J_4 \stackrel{!}{=} 0$$

► Only $\hat{q}_{123}$ matters!

$$\langle j_{12} | \hat{q}_{123} | j_{12} - 1 \rangle =$$

$$= \frac{1}{\sqrt{(2j_{12}-1)(2j_{12}+1)}} \left[(j_1 + j_2 + j_{12} + 1)(-j_1 + j_2 + j_{12})(j_1 - j_2 + j_{12})(j_1 + j_2 - j_{12} + 1) \right. \\ \left. (j_3 + j_4 + j_{12} + 1)(-j_3 + j_4 + j_{12})(j_3 - j_4 + j_{12})(j_3 + j_4 - j_{12} + 1) \right]^{\frac{1}{2}}$$

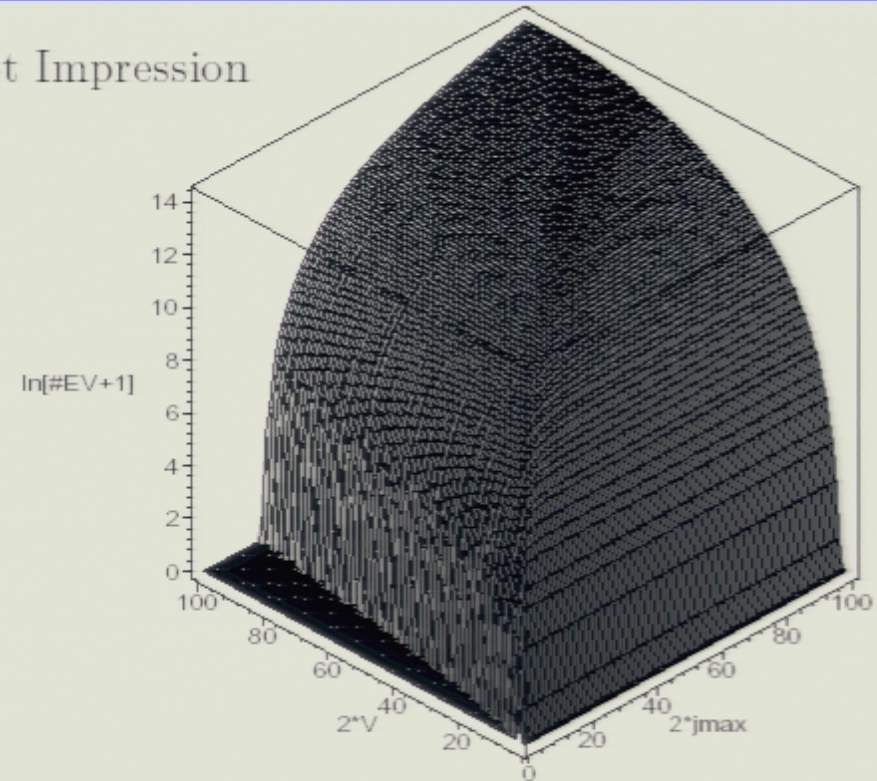
$$= - \langle j_{12} - 1 | \hat{q}_{123} | j_{12} \rangle$$

Application I: Numerical Studies 2

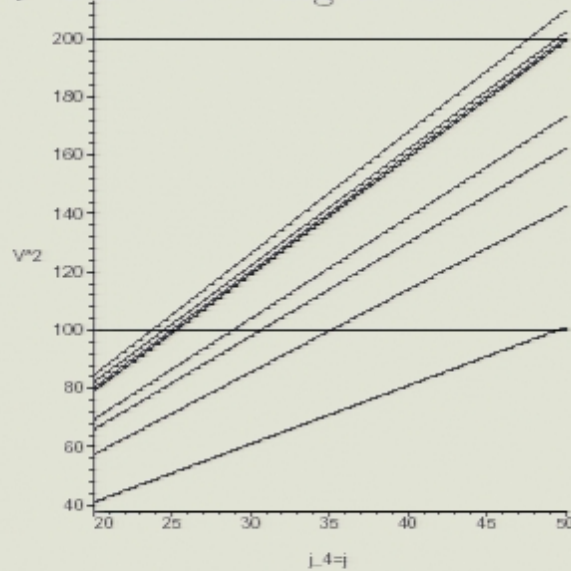
► Matrix Structure

$$A = \begin{pmatrix} 0 & -a_1 & 0 & \dots & \dots & 0 \\ a_1 & 0 & -a_2 & & & \\ 0 & a_2 & 0 & \ddots & & \\ \vdots & & \ddots & \ddots & \ddots & \\ \vdots & & & \ddots & \ddots & -a_{n-1} \\ 0 & \dots & \dots & \dots & a_{n-1} & 0 \end{pmatrix}$$

► First Impression



► First Few Eigenvalues



Application II: Triad Operators in LQG 1

- Classical: Euclidean Part of H

$$H_E = \frac{1}{\kappa \sqrt{\det q}} \left[F_{ab}^j \epsilon_{jkl} E_k^a E_l^b \right]$$

$$\begin{aligned} E_j^a &= \det(e) e_j^a \\ \frac{\epsilon_{jkl} E_k^a E_l^b}{\kappa \sqrt{\det q}} &= \text{sgn}(\det(e)) \epsilon^{abc} e_c^j \\ e_c^j &\propto \{A_c^j, V\} \propto \text{Tr} [\tau_j h_c \{h_c^{-1}, V\}] \end{aligned}$$

- Regularized Expression

$$H_E^\epsilon(N) \sim \sum_{\Delta \in T(\Sigma)} N(v(\Delta)) \epsilon^{IJK} \text{Tr} [h_{\alpha_{IJ}}(\Delta) h_{e_K}(\Delta) [h_{e_K}^{-1}(\Delta), \hat{V}]]$$

→ study operator

$$({}^{(r)}\hat{e}_K^k : = \text{Tr} [\tau_k h_K [h_K^{-1}, \hat{V}^r]])$$

- LQC: inverse Scale Factor

$$(\widehat{a^{-1}}) \propto \left(\sum_k \text{Tr} [\tau_k h_k \{h_k^{-1}, \sqrt{\hat{V}}\}] \right)^2 \rightarrow \text{Bounded Operator in Quantum Theory}$$

Application II: Triad Operators in LQG 2

■ What about LQG ??

► Holonomie Action $[\pi_{\frac{1}{2}}(\cdot)]_{AB} = \frac{1}{2} \left| \frac{1}{2} A ; B \right\rangle$

$$\begin{aligned} \frac{1}{2} \left| \frac{1}{2} A ; B \right\rangle \cdot \left| j m ; n \right\rangle = & \left[\frac{j + 2Bn + 1}{2(j + 1)} \right]^{\frac{1}{2}} \left\langle j m ; \frac{1}{2} A \left| j + \frac{1}{2} m + A \right\rangle \cdot \left| j + \frac{1}{2} m + A ; n + B \right\rangle \right. \\ & \left. \oplus (-2)B \left[\frac{j - 2Bn}{2j} \right]^{\frac{1}{2}} \left\langle j m ; \frac{1}{2} A \left| j - \frac{1}{2} m + A \right\rangle \cdot \left| j - \frac{1}{2} m + A ; n + B \right\rangle \right. \end{aligned}$$

Application II: Triad Operators in LQG 2

■ What about LQG ??

► Holonomie Action $[\pi_{\frac{1}{2}}(\cdot)]_{AB} = \frac{1}{2} \left| \frac{1}{2} A ; B \right\rangle$

$$\begin{aligned} \frac{1}{2} \left| \frac{1}{2} A ; B \right\rangle \cdot \left| j m ; n \right\rangle = & \left[\frac{j + 2Bn + 1}{2(j + 1)} \right]^{\frac{1}{2}} \left\langle j m ; \frac{1}{2} A \mid j + \frac{1}{2} m + A \right\rangle \cdot \left| j + \frac{1}{2} m + A ; n + B \right\rangle \\ & \oplus (-2)^B \left[\frac{j - 2Bn}{2j} \right]^{\frac{1}{2}} \left\langle j m ; \frac{1}{2} A \mid j - \frac{1}{2} m + A \right\rangle \cdot \left| j - \frac{1}{2} m + A ; n + B \right\rangle \end{aligned}$$

► 3-Vertex-Calculation

$$\begin{aligned} & \left\langle a_2(j_1 j_2) = j_3 \ J = 1 \ M' ; n_1 n_2 n_3 \mid {}^{(r)}\hat{e}_{K=3}^k \mid a_2(j_1 j_2) = j_3 \ J = 0 \ M ; n_1 n_2 n_3 \right\rangle = \\ & = C(M, M', k) \frac{\sqrt{j_3(j_3+1)}}{2j_3+1} \left[[(j_1 + j_2 + j_3 + 2)(-j_1 + j_2 + j_3 + 1)(j_1 - j_2 + j_3 + 1)(j_1 + j_2 - j_3)]^{\frac{r}{4}} \right. \\ & \quad \left. + [(j_1 + j_2 + j_3 + 1)(-j_1 + j_2 + j_3)(j_1 - j_2 + j_3)(j_1 + j_2 - j_3 + 1)]^{\frac{r}{4}} \right] \end{aligned}$$

Not Bounded!

Application II: Triad Operators in LQG 3

■ $U(1)^3$ -CS Calculation

► Study
$$\begin{aligned} {}^{(r)}\hat{e}_e^j(v) &= \text{Tr} \left[\tau_j \hat{h}_e \left[\hat{h}_e^{-1}, \hat{V}_v^r \right] \right] && \text{for } SU(2) \\ \hat{q}_e^j(v, r) &= \text{i} \hat{h}_e^j \left[(\hat{h}_e^j)^{-1}, \hat{V}_v^r \right] && \text{for } U(1)^3 \end{aligned}$$

► Charge Network States
$$T_c = \prod_{\substack{e_I \in E(v) \\ j=1,2,3}} [h_I^j(A)]^{n_I^j(c)} \quad \text{with } h_I^j(A) = e^{i\theta_I^j(A)}$$

► Coherent States
$$\Psi_{m,\gamma}^{(v)} = \prod_{\substack{e \in E(v) \\ j=1,2,3}} \sum_{n_e^j \in \mathbb{Z}} e^{-\frac{t(e)}{2} [n_e^j]^2} \left[h_e^j(Z(m)) h_e^j(A)^{-1} \right]^{n_e^j}$$

► Expectation Value
$$\left\langle \Psi_{m,\gamma}^{(v)} \mid \hat{q}_{e_k}^{jk}(v, r) \prod_{k=1}^M \mid \Psi_{m,\gamma}^{(v)} \right\rangle$$

is finite, no matter if peaked at classically singular ($E = 0$) configuration)

Conclusions & Outlook

- Simplified Volume Operator in Full Theory

- 1) Numerical Studies

- 2) Analytical Studies → Tools to check LQC and the question of singularity (dis-) appearance in the Full Theory

- Triad - Operator in General **not** necessarily **bounded** (3-vertex)

- on 0-volume Eigenstates → Calculation in $U(1)^3$ -CS shows finite behavior



- To Do:

- ▶ Further numerical studies

- ▶ Triad at 4-vertex?

- ▶ Re-Do $U(1)^3$ -Calculation for $SU(2)$

- ↪ Examine action of $\hat{H}_E$ in detail

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Application II: Triad Operators in LQG 1

- Classical: Euclidean Part of H

$$H_E = \frac{1}{\kappa \sqrt{\det q}} \left[F_{ab}^j \epsilon_{jkl} E_k^a E_l^b \right]$$

$$\begin{aligned} E_j^a &= \det(e) e_j^a \\ \frac{\epsilon_{jkl} E_k^a E_l^b}{\kappa \sqrt{\det q}} &= \text{sgn}(\det(e)) \epsilon^{abc} e_c^j \\ e_c^j &\propto \{A_c^j, V\} \propto \text{Tr} [\tau_j h_c \{h_c^{-1}, V\}] \end{aligned}$$

- Regularized Expression

$$H_E^\epsilon(N) \sim \sum_{\Delta \in T(\Sigma)} N(v(\Delta)) \epsilon^{IJK} \text{Tr} [h_{\alpha_{IJ}}(\Delta) h_{e_K}(\Delta) [h_{e_K}^{-1}(\Delta), \hat{V}]]$$

→ study operator

$$({}^r)\hat{e}_K^k : = \text{Tr} [\tau_k h_K [h_K^{-1}, \hat{V}^r]]$$

- LQC: inverse Scale Factor

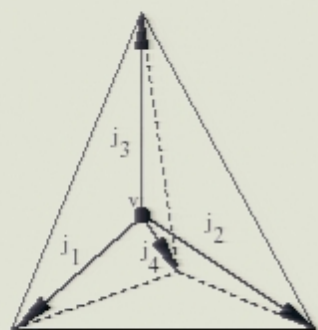
$$(\widehat{a^{-1}}) \propto \left(\sum_k \text{Tr} [\tau_k h_k \{h_k^{-1}, \sqrt{\hat{V}}\}] \right)^2 \rightarrow \text{Bounded Operator in Quantum Theory}$$

Volume Operator II: Simplified Expression for the Matrix Element 2

$$\begin{aligned}
 \langle \vec{a} | \hat{q}_{IJK} | \vec{a}' \rangle &= \\
 &= \frac{1}{4} (-1)^{j_K + j_I + a_{I-1} + a_K} (-1)^{a_I - a'_I} (-1)^{\sum_{n=I+1}^{J-1} j_n} (-1)^{-\sum_{p=J+1}^{K-1} j_p} \times \\
 &\quad \times X(j_I, j_J)^{\frac{1}{2}} X(j_J, j_K)^{\frac{1}{2}} \sqrt{(2a_I + 1)(2a'_I + 1)} \sqrt{(2a_J + 1)(2a'_J + 1)} \times \\
 &\quad \times \left\{ \begin{matrix} a_{I-1} & j_I & a_I \\ 1 & a'_I & j_I \end{matrix} \right\} \left[\prod_{n=I+1}^{J-1} \sqrt{(2a'_n + 1)(2a_n + 1)} (-1)^{a'_{n-1} + a_{n-1} + 1} \left\{ \begin{matrix} j_n & a'_{n-1} & a'_n \\ 1 & a_n & a_{n-1} \end{matrix} \right\} \right] \times \\
 &\quad \times \left[\prod_{n=J+1}^{K-1} \sqrt{(2a'_n + 1)(2a_n + 1)} (-1)^{a'_{n-1} + a_{n-1} + 1} \left\{ \begin{matrix} j_n & a'_{n-1} & a'_n \\ 1 & a_n & a_{n-1} \end{matrix} \right\} \right] \left\{ \begin{matrix} a_K & j_K & a_{K-1} \\ 1 & a'_{K-1} & j_K \end{matrix} \right\} \times \\
 &\quad \times \left[(-1)^{a_J + a'_{J-1}} \left\{ \begin{matrix} a_J & j_J & a'_{J-1} \\ 1 & a_{J-1} & j_J \end{matrix} \right\} \left\{ \begin{matrix} a'_{J-1} & j_J & a'_J \\ 1 & a_J & j_J \end{matrix} \right\} \right. \\
 &\quad \left. - (-1)^{a_J + a_{J-1}} \left\{ \begin{matrix} a'_J & j_J & a'_{J-1} \\ 1 & a_{J-1} & j_J \end{matrix} \right\} \left\{ \begin{matrix} a_{J-1} & j_J & a'_J \\ 1 & a_J & j_J \end{matrix} \right\} \right] \times \\
 &\quad \times \prod_{n=2}^{I-1} \delta_{a_n a'_n} \prod_{n=K}^N \delta_{a_n a'_n}
 \end{aligned}$$

Application I: Numerical Studies 1

■ Gauge Invariant 4-Vertex



► Basis-States

$$T_v = \left| \underbrace{a_2(j_1 \ j_2)}_{j_{12}} \ a_3(a_2 \ j_3) \ J(a_3 \ j_4)=0 \ M=0; \ \vec{n} \right\rangle$$

► Gauge Invariance

$$J_1 + J_2 + J_3 + J_4 \stackrel{!}{=} 0$$

► Only $\hat{q}_{123}$ matters!

$$\langle j_{12} | \hat{q}_{123} | j_{12} - 1 \rangle =$$

$$= \frac{1}{\sqrt{(2j_{12}-1)(2j_{12}+1)}} \left[(j_1 + j_2 + j_{12} + 1)(-j_1 + j_2 + j_{12})(j_1 - j_2 + j_{12})(j_1 + j_2 - j_{12} + 1) \right. \\ \left. (j_3 + j_4 + j_{12} + 1)(-j_3 + j_4 + j_{12})(j_3 - j_4 + j_{12})(j_3 + j_4 - j_{12} + 1) \right]^{\frac{1}{2}}$$

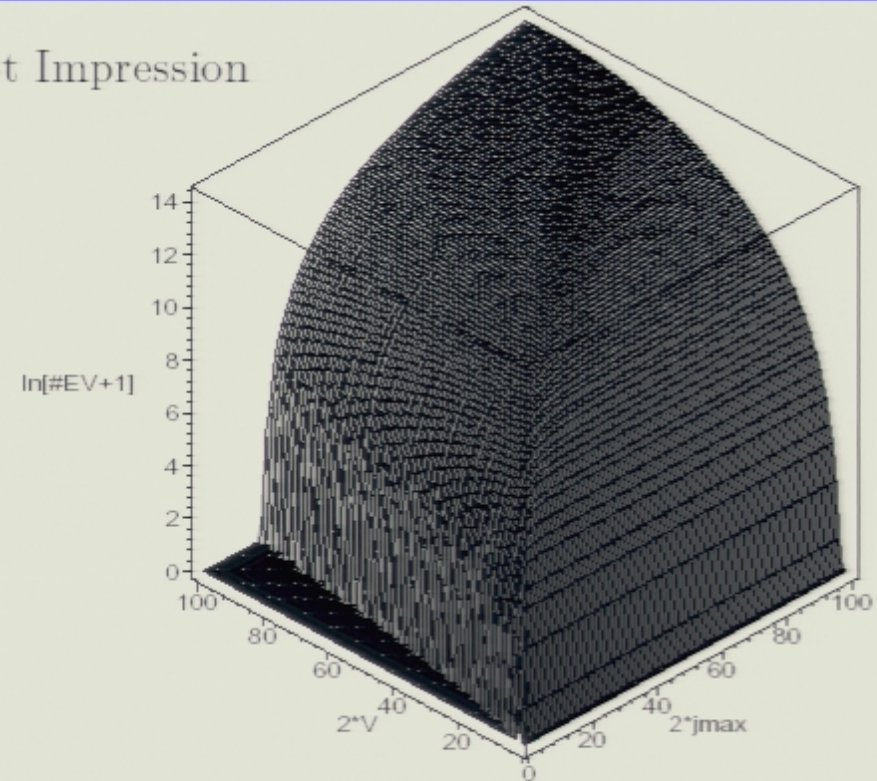
$$= - \langle j_{12} - 1 | \hat{q}_{123} | j_{12} \rangle$$

Application I: Numerical Studies 2

► Matrix Structure

$$A = \begin{pmatrix} 0 & -a_1 & 0 & \dots & \dots & 0 \\ a_1 & 0 & -a_2 & & & \\ 0 & a_2 & 0 & \ddots & & \\ \vdots & & \ddots & \ddots & \ddots & \\ \vdots & & & \ddots & \ddots & -a_{n-1} \\ 0 & \dots & \dots & \dots & a_{n-1} & 0 \end{pmatrix}$$

► First Impression



► First Few Eigenvalues

